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Lecture Support Vector Machines continued

PROF. LINDA SELLIE

SOME SLIDES FROM PROF. RANGAN



We can compare two hyperplanes by comparing their geometric margins.

Which hyperplane has a larger margin:

• Given the following data: $x^{(1)} = [3.2]$

$$\mathbf{x}^{(1)} = [3.2 \quad 4.7]$$
 $\mathbf{x}^{(2)} = [3.5 \quad 1.4]$
 $\mathbf{x}^{(3)} = [3. \quad 1.4]$

$$y^{(1)} = -1$$

 $y^{(2)} = 1$
 $y^{(3)} = 1$

What is the geometric margin for:

$$w_0 = 1/2 \quad \mathbf{w} = \begin{bmatrix} 2/3 \\ -1 \end{bmatrix}$$

$$y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + w_0) / ||\mathbf{w}||_2$$

$$(-1) \left([2/3 \ -1] \begin{bmatrix} 3.2 \\ 4.7 \end{bmatrix} + 1/2) \right) / \sqrt{4/9 + 1} = 1.7$$

$$(1)\left([2/3 -1]\begin{bmatrix} 3.5\\ 1.4 \end{bmatrix} + 1/2)\right)/\sqrt{4/9 + 1} = 1.2$$

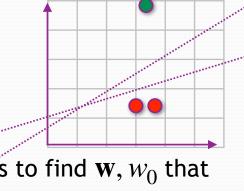
$$(1)$$
 $(2/3 -1]$ $\begin{bmatrix} 3 \\ 1.4 \end{bmatrix} + 1/2) / \sqrt{4/9 + 1}$

$$=0.9$$
 $\gamma_g = 0.9$

$$w_0 = 1 \qquad \mathbf{w} = \begin{bmatrix} 1/3 \\ -1 \end{bmatrix}$$

$$(-1)$$
 $\left([1/3 -1] \begin{bmatrix} 3.2 \\ 4.7 \end{bmatrix} + 1 \right) / \sqrt{1/9 + 1} = 2.5$

$$(1)\left(\begin{bmatrix} 1/3 & -1 \end{bmatrix} \begin{bmatrix} 3.5 \\ 1.4 \end{bmatrix} + 1\right) / \sqrt{1/9 + 1} = 0.7$$

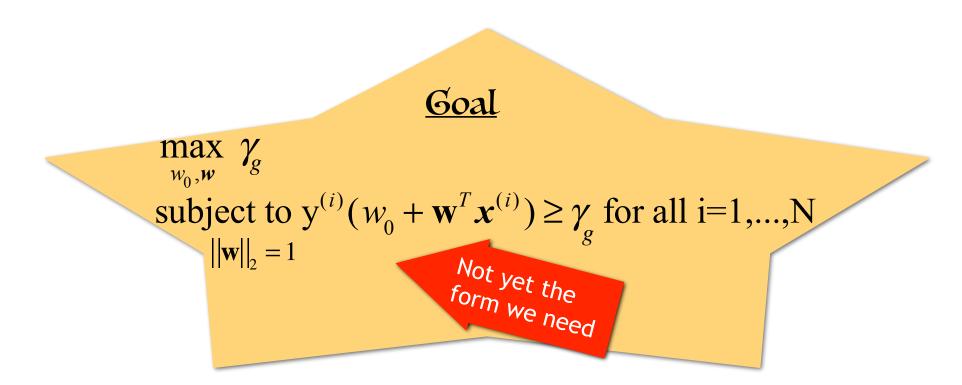


Goal is to find \mathbf{w} , w_0 that has the largest γ_g such that $y^{(i)}(\mathbf{w}^T\mathbf{x}^{(i)}+w_0)/\|\mathbf{w}\|_2 \geq \gamma_g$

$$\|\mathbf{y}^{(i)}(\mathbf{w}^T\mathbf{x}^{(i)} + w_0)/\|\mathbf{w}\|_2 \ge 0.9$$

$$y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + w_0) / \|\mathbf{w}\|_2 \ge 0.6$$

Objective function



Difficult to work with constraints that are not linear.

Let us write our objective function in a different way.

We want our constrained object function to return a unique \mathbf{w}, w_0

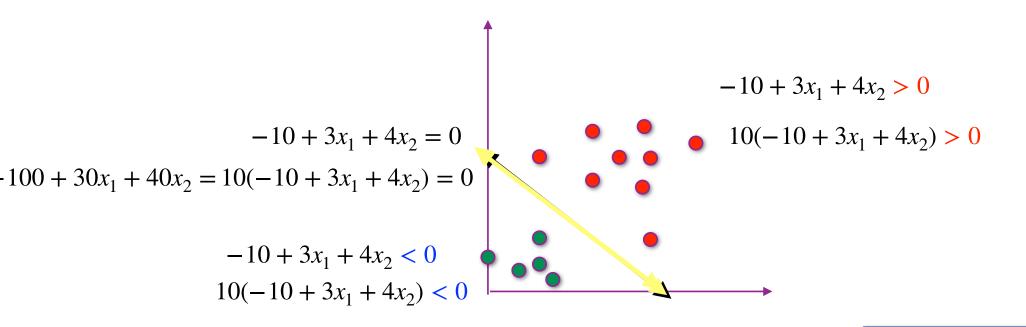
Crazy idea next!

Instead of requiring \mathbf{w} to be a unit vector (i.e. $\|\mathbf{w}\| = 1$), We will define the idea of a "functional margin" and require that to be 1.

Steps to understanding "functional margin":

- 1. Simple observation: rescaling the parameters doesn't change the decision boundary.
- 2. How to rescale the parameters/weights, so the functional margin is 1. We call these weights/parameters canonical weights.

Step 1. We can write a hyperplane in many ways



Pair share: Do we change the classification if we multiply $-10 + 3x_1 + 4x_2 = 0$ by 10?

Step 1 conclusion

Rescaling the parameters doesn't change the line (decision boundary)! $\mathbf{w}^T \mathbf{x} + w_0 = 0 = c \mathbf{w}^T \mathbf{x} + c w_0$

$$\mathbf{w}^T \mathbf{x} + w_0 = 0 = c \mathbf{w}^T \mathbf{x} + c w_0$$

Step 2

What is another way to constrain the problem so that we get a unique solution?

 $y^{(i)}(\mathbf{w}^T\mathbf{x}^{(i)} + w_0) = 1$ for the closest point to the hyperplane

The functional margin of (\mathbf{w}, w_0) with respect to <u>a point</u> $\mathbf{x}^{(i)}$ is

$$\gamma_f^{(i)} = y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + w_0)$$

The Functional margin of (\mathbf{w}, w_0) with respect to <u>a set</u> S is

$$\gamma_f = \min\{\gamma_f^{(1)}, \gamma_f^{(2)}, ..., \gamma_f^{(N)}\}$$

Step 2

: 1 Canonical weights

$$\gamma_f^{(2)} = (1) \left(\frac{3}{3} \frac{41}{3} \begin{bmatrix} 3 \\ 1 \end{bmatrix} - \frac{10}{3} \right)$$

$$= (1) \begin{pmatrix} 3 \\ 3 \end{bmatrix}$$

$$\gamma_f^{(1)} = (1) \left(\begin{bmatrix} 3 \\ 3 \end{bmatrix} + \begin{bmatrix} 1 \\ 2.5 \end{bmatrix} - \begin{bmatrix} 10 \\ 3 \end{bmatrix} \right)$$

$$= (1) \begin{pmatrix} 3 \\ 3 \end{bmatrix}$$

$$\gamma_f^{(N)} = (-1) \left(\begin{bmatrix} 3 \\ 3 \end{bmatrix} + \begin{bmatrix} 1 \\ 1 \end{bmatrix} - \begin{bmatrix} 10 \\ 3 \end{bmatrix} \right)$$

$$= (-1) \begin{pmatrix} -3 \end{bmatrix}$$

Functional margin of (\mathbf{w}, w_0) with respect to <u>a point</u> $\mathbf{x}^{(i)}$ is

$$\gamma_f^{(i)} = y^{(i)} (\mathbf{w}^T \mathbf{x}^{(i)} + \underline{w_0})$$

Functional margin of (\mathbf{w}, w_0) with respect to <u>a set</u> S is

$$\gamma_f = \min\{\gamma_f^{(1)}, \gamma_f^{(2)}, ..., \gamma_f^{(N)}\}$$

After scaling, the points closest to the decision boundary have:

- * functional margin of 1
- * Euclidean distance for this point is $\frac{1}{\|\mathbf{w}\|_2}$

$$\frac{1}{3}(-10 + 3x_1 + 4x_2) = 0$$

$$-10 + 3x_1 + 4x_2 = 0 = -10/3 + 3/3x_1 + 4/3x_2$$

(3,1)

(1, 2.5)

(1,1)

We can make γ_f = 1

The canonical weights

Step 2 conclusion

For any hyperplane that separates the data, we can make its functional margin any value we want.

Canonical weights are when the functional margin is 1 for the set of training examples

$$\min_{i} y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + w_0) = 1$$

Next: Many equivalent versions of our objective function

1)

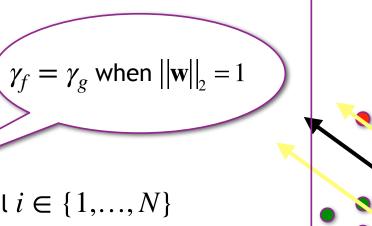
Constrained optimization problem:

$$\max_{\mathbf{w}, w_0} \gamma_g$$

Subject to
$$y^{(i)}(\mathbf{w}^T\mathbf{x}^{(i)} + w_0) \ge \gamma_g$$
 for all $i \in \{1,...,N\}$

$$||\mathbf{w}||_2 = 1$$

 $\|\mathbf{w}\|_2$



= Geometric margin

2)

Another formulation:

$$\max_{\mathbf{w}, w_0} \frac{\gamma_f}{\|\mathbf{w}\|_2} = r$$

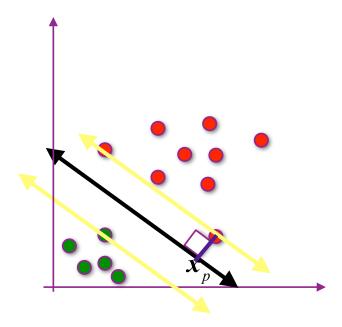
Subject to
$$y^{(i)}(\mathbf{w}^T\mathbf{x}^{(i)} + w_0) \ge \gamma_f$$
 for all $i \in \{1,...,N\}$



$$\frac{\gamma_f}{\|\mathbf{w}\|_2} = \gamma_g$$

$$2) \quad \max_{\mathbf{w}, w_0} \frac{\gamma_f}{\|\mathbf{w}\|_2} = r$$

Subject to
$$y^{(i)}(\mathbf{w}^T\mathbf{x}^{(i)} + w_0) \ge \gamma_f$$
 for all $i \in \{1,...,N\}$



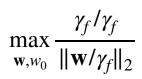
$$\max(\gamma/\gamma)/||\mathbf{w}/\gamma||_2$$

Canonical weights!!!

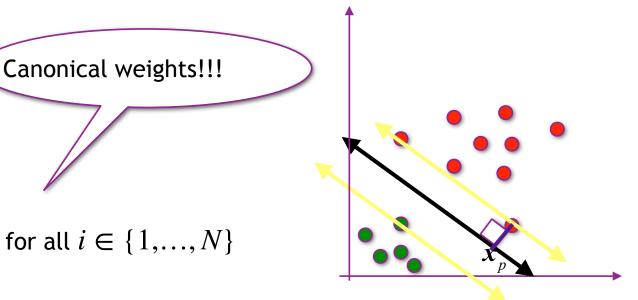
Idea: we can rescale our margin to anything we want by rescaling our coefficients notice that max $\frac{\gamma_f}{\gamma_f}$ equals max $\frac{\gamma_f}{\gamma_f}$

notice that
$$\max_{\mathbf{w}, w_0} \frac{\gamma_f}{\|\mathbf{w}\|_2}$$
 equals $\max_{\mathbf{w}, w_0} \frac{\gamma_f/\gamma_f}{\|\mathbf{w}/\gamma_f\|_2}$

Subject to
$$y^{(i)}(\frac{\mathbf{w}^T}{\gamma_f}\mathbf{x}^{(i)} + \frac{w_0}{\gamma_f}) \ge \frac{\gamma_f}{\gamma_f}$$
 for all $i \in \{1, ..., N\}$



Subject to
$$y^{(i)}(\frac{\mathbf{w}^T}{\gamma_f}\mathbf{x}^{(i)} + \frac{w_0}{\gamma_f}) \ge \frac{\gamma_f}{\gamma_f}$$
 for all $i \in \{1,...,N\}$

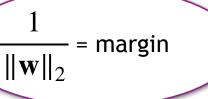


3) We set $w_0 := w_0/\gamma_f$, and $\mathbf{w} := \mathbf{w}/\gamma_f$ Notice we now want to $\max 1/\|\mathbf{w}\|_2$

Using this idea we rewrite the formula as

$$\max_{w_0, \mathbf{w}} 1/\|\mathbf{w}\|_2 \quad \text{now } \gamma = 1$$

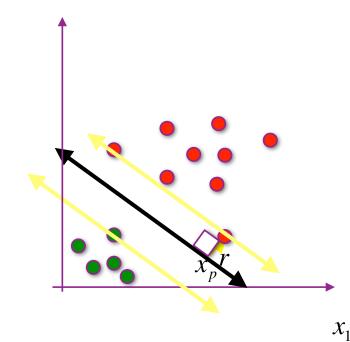
Subject to
$$y^{(i)}(w_0 + \mathbf{w}^T \mathbf{x}^{(i)}) \ge 1$$
 for all $i = 1, ..., N$



3) Constrained optimization problem:

$$\begin{aligned} &\max_{w_0,\mathbf{w}} 1/\|\mathbf{w}\|_2 \\ &\text{Subject to } y^{(i)}(w_0 + \mathbf{w}^T\mathbf{x}^{(i)}) \geq 1 \text{ for all } i=1,\dots,N \end{aligned}$$

4) Notice $\max 1/\|\mathbf{w}\|_2$ is the same as $\min \|\mathbf{w}\|_2$



Notice $\min \|\mathbf{w}\|_2$ is the same as $\min \|\mathbf{w}\|_2^2$

$$\min \|\mathbf{w}\|_2^2 = \min(w_1^2 + w_2^2 + \dots + w_d^2)$$

Subject to $y^{(i)}(w_0 + \mathbf{w}^T \mathbf{x}^{(i)}) \ge 1$ for all i = 1,...,N

Solvable in polynomial time!

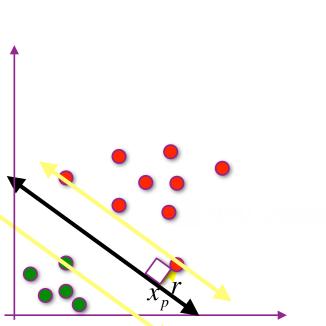
Objective function is convex and points satisfying constraints are convex

A constrained quaoratic optimization problem!

Example Hard-Margin SVM

 (x^{T},y) : ((1, 2.5),1), ((2, 2),1), ((3,1),1),...,((0, 0.75),-1), ((1,1),-1)

The constrained quadratic optimization function is:



$$\min_{w_0, \mathbf{w}} \|\mathbf{w}\|_2^2 = w_1^2 + w_2^2$$
subject to (1) $\left(w_0 + \mathbf{w}^T \begin{bmatrix} 1 \\ 2.5 \end{bmatrix}\right) \ge 1$

$$(1) \left(w_0 + \mathbf{w}^T \begin{bmatrix} 2 \\ 2 \end{bmatrix}\right) \ge 1$$

$$\vdots$$

$$(-1) \left(w_0 + \mathbf{w}^T \begin{bmatrix} 1 \\ 1 \end{bmatrix}\right) \ge 1$$

Example Hard-Margin SVM

 (x^{T},y) : ((1, 2.5),1), ((2, 2),1), ((3,1),1),...,((0, 0.75),-1), ((1,1),-1)

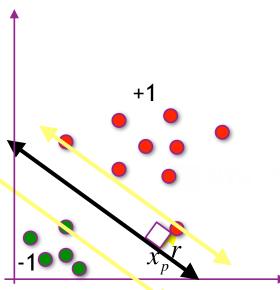
The optimal hyperplane is: $\mathbf{w} = (1,4/3)^T$, $\mathbf{w}_0 = -10/3$

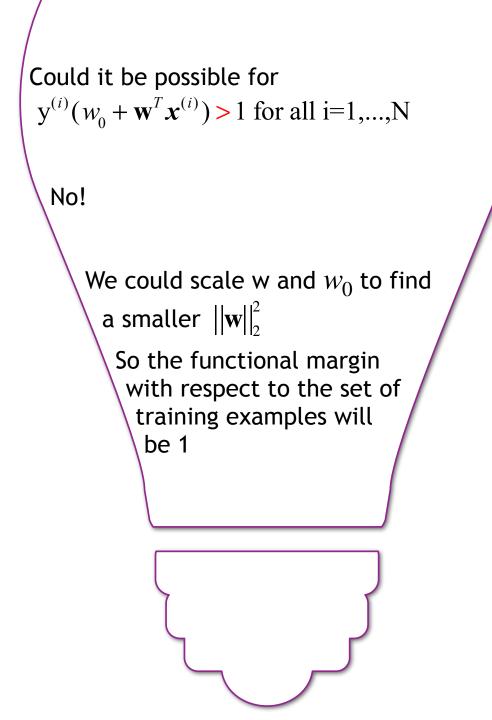
•
$$f(\mathbf{x}) = (1,4/3)\mathbf{x} - 10/3$$

- Predict +1 if $f(\mathbf{x}) > 0$
- Predict -1 if $f(\mathbf{x}) < 0$

Two types of training data:

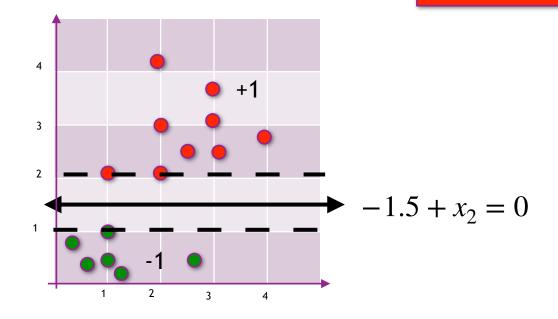
- $y^{(i)}(\mathbf{w}^T\mathbf{x}^{(i)} + w_0) = 1$. Points on the margin called support vectors
- $y^{(i)}(\mathbf{w}^T\mathbf{x}^{(i)} + w_0) > 1$. If we remove these points, the solution doesn't change





Hard margin example

Pair share: How can modify our decision boundary to have a functional margin of 1?

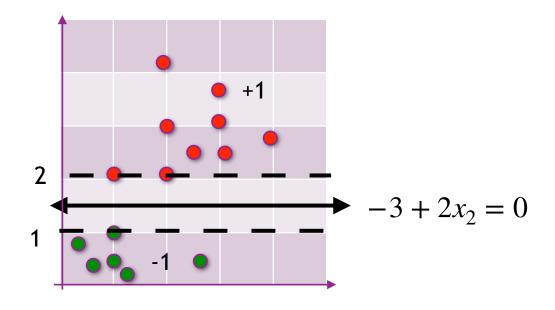


Decision boundary is $\mathbf{w} = [0,1]^T$, $w_0 = -1.5$

Is this the form we wanted?

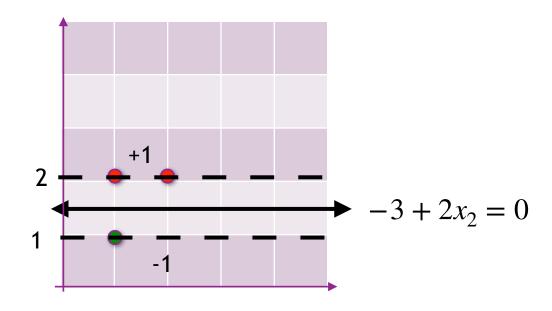
The support vectors are supposed to have a functional margin of 1: $y^{(i)}(\mathbf{w}^T\mathbf{x}^{(i)} + w_0) = 1$

Approach taken in this slide is from CMU 18-661

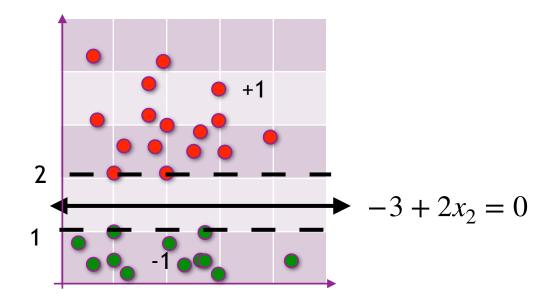


Decision boundary is $\mathbf{w} = [0,2]^T$, $w_0 = -3$ The support vectors have a functional margin of 1: $y^{(i)}(\mathbf{w}^T\mathbf{x}^{(i)} + w_0) = 1$

Approach taken in this slide is from CMU 18-661



The boundary doesn't change if I remove points with a functional margin > 1



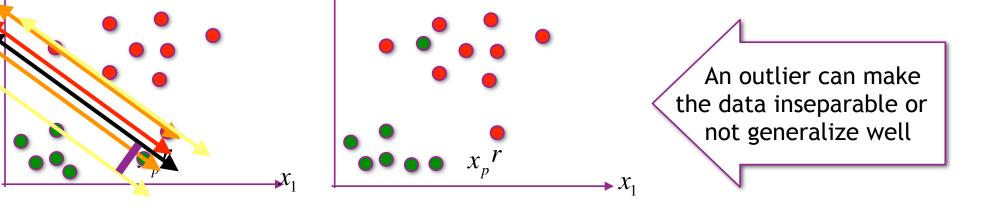
The solution doesn't change if I add points whose functional margin is ≥ 1

Outline

- □ Notation change, intuition, and finding how to compare hyperplanes mathematically how do compare hyperplanes to find the one with the maximum margin. Can we turn this way of comparing hyperplanes into an objective function
- □Support vector machines
 - ★ hard margin find the constrained objective function when the data is linearly separable
- ★ Dealing with non-linear data "Soft" margins for SVM New constrained objective function for the case where the data is not linearly separable
- ★ Pegasos algorithm. Optimizer for soft margin SVM
- ★ Dealing with non-linear data feature transformation with the kernel trick Show two popular feature maps

Non-Linear Data

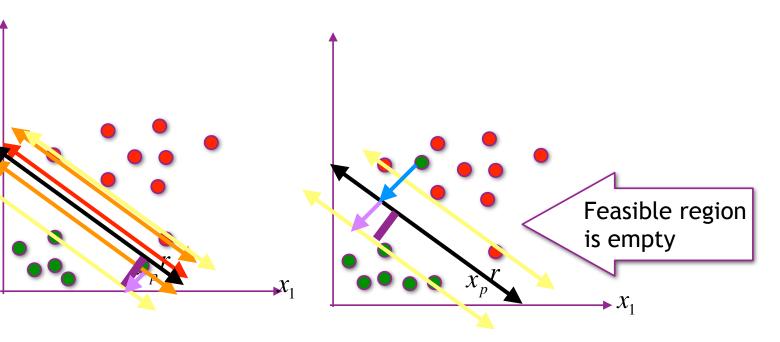
- 1. Soft margin
- 2. Transform features vector \mathbf{x} into a new feature space $\Phi(\mathbf{x})$



What if the data isn't linearly separable

WE CAN MAKE OUR MODEL MORE FLEXIBLE BY ADDING A COST FUNCTION FOR THE POINTS THAT ARE MISCLASSIFIED

Soft-Margin SVM



How can we still find find the optimal hyperplane where we allow for a few points to either be misclassified or within the margin?

We could incur a $\cos \xi^{(i)}$ for how far the $x^{(i)}$ is away from the margin.

We will create a slack variable $\boldsymbol{\xi}^{(i)}$ for each training example $\mathbf{x}^{(i)}$

The hyperplane must satisfy

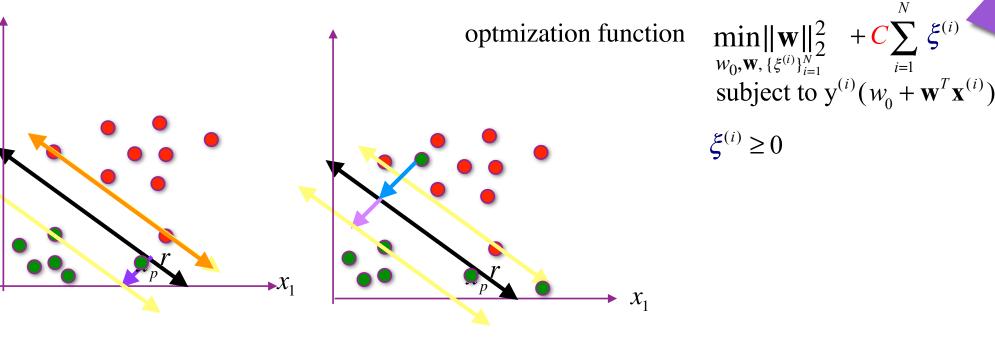
$$y^{(i)}(\mathbf{w}^T\mathbf{x}^{(i)} + w_0) \ge 1 - \xi^{(i)}$$

$$\xi^{(i)} =$$
What function should we use for

Which cost function?

SHOULD ALL THE POINTS BE CHARGED, OR ONLY THOSE THAT ARE INSIDE THE MARGIN OR INCORRECTLY CLASSIFIED?

Soft-Margin SVM



C is a tunable parameter. Gives relative importance of the error term

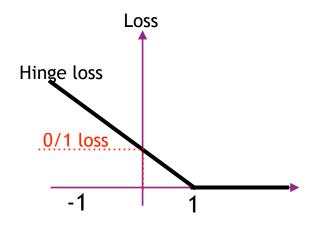
subject to
$$y^{(i)}(w_0 + \mathbf{w}^T \mathbf{x}^{(i)}) \ge 1 - \xi^{(i)}$$
 for all $i = 1,...,N$

$$\xi^{(i)} \geq 0$$

$$\boldsymbol{\xi}^{(i)} = \begin{cases} 0 & y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + w_0) \ge 1\\ 1 - y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + w_0) & otherwise \end{cases}$$

Hinge Loss

Introduced one slack variable $\xi^{(i)}$ for each training example.



$$\boldsymbol{\xi}^{(i)} = \begin{cases} 0 & y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + w_0) \ge 1\\ 1 - y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + w_0) & otherwise \end{cases}$$

0-1 loss: No penalty if correctly classified. Cost of 1 for incorrectly classified points

Hinge loss: Penalty upper bounds 0/1 loss

- Penalizes correct predictions that are too close to the margin
- Penalty linearly increases for incorrect predictions (and close correct predictions)
 No penalty on correct predictions that are far away from the margin

optmization function

$$\min_{w_0, \mathbf{w}, \{\xi^{(i)}\}_{i=1}^N} 2 + C \sum_{i=1}^N \xi^{(i)}$$

subject to
$$\mathbf{y}^{(i)}(w_0 + \mathbf{w}^T \mathbf{x}^{(i)}) \ge 1 - \boldsymbol{\xi}^{(i)}$$

 $\xi^{(i)} \geq 0$

Pair share: What do you know about the functional margin for **x** if:

1)
$$\xi \ge 1$$

2)
$$0 < \xi < 1$$

3) $\xi = 0$

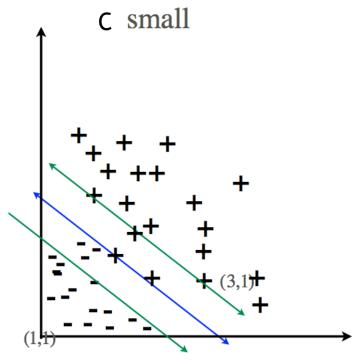
3)
$$\xi = 0$$

Pair share: Do you think that $\sum_{i=1}^{N} \xi^{(i)}$ is an upper bound on the number of training errors (i.e. number of points misclassified incorrectly)?

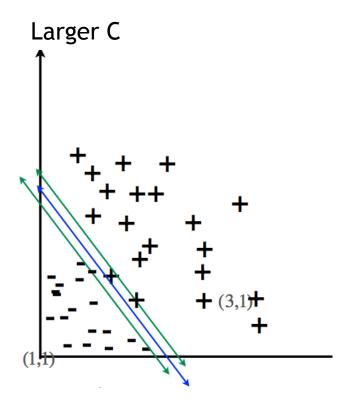
Pair share:

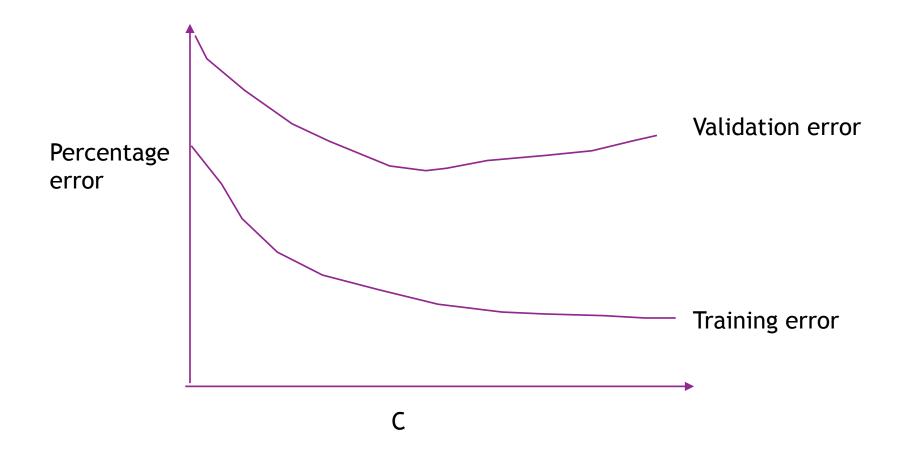
1) What happens to the margin if I make C large?

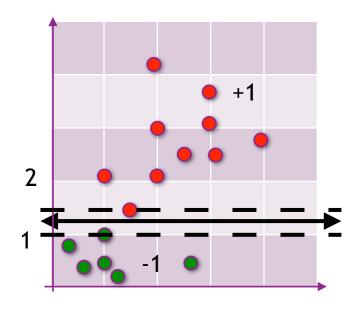
2) What happens to the margin if I make C small?



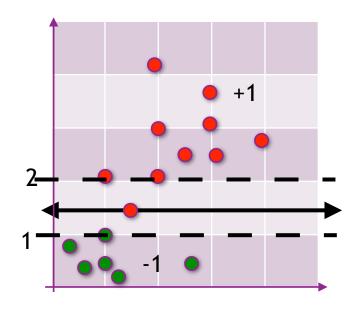
What if $C = \infty$?







Our margin becomes smaller if we have an outlier



$$\min_{w_0, \mathbf{w}, \{\xi^{(i)}\}_{i=1}^N} + C \sum_{i=1}^N \xi^{(i)}$$

subject to
$$y^{(i)}(w_0 + \mathbf{w}^T \mathbf{x}^{(i)}) \ge 1 - \xi^{(i)}$$

Approach taken in this slide is from CMU 18-661

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Simplifying our objective function

Rewriting our SVM objective function

$$\min_{\substack{w_0, \mathbf{w}, \{\xi^{(i)}\}_{i=1}^N \\ \text{subject to } \mathbf{y}^{(i)}(\mathbf{w}_0 + \mathbf{w}^T\mathbf{x}^{(i)}) \ge 1 - \xi^{(i)}} \begin{cases} \text{Same as: } \xi^{(i)} \ge 1 - y^{(i)}(\mathbf{w}^T\mathbf{x}^{(i)} + w_0) \\ \xi^{(i)} \ge 0 \end{cases}$$

Our SVM objective function with hinge loss:

Setting
$$\lambda = 1/C$$

$$\min_{\mathbf{w}, w_0} \frac{\lambda}{2} \|\mathbf{w}\|_2^2 + \sum_{i=1}^{N} \max\left(0, 1 - y^{(i)}(\mathbf{w}^T\mathbf{x}^{(i)} + w_0)\right) \left(\text{Since } \xi^{(i)} \text{ is as small as possible} \right)$$
 hinge Loss

A balance between loss function and regularizer.

^{*}In our optimizer, we will ignore the intercept term to make things easier

Our objective function is convex but not differentiable

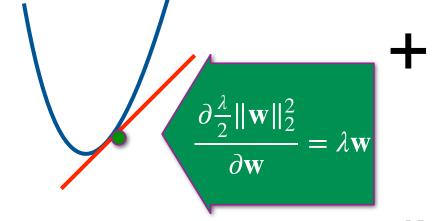
We can use a sub-gradient. Derivation is beyond the scope of course.

Derivative

Sub-derivative of the hinge loss

$$\frac{\lambda}{2} \|\mathbf{w}\|_2^2$$

hinge loss =
$$\max(0, 1 - y^{(i)}\mathbf{w}^T\mathbf{x})$$



$$\frac{\partial \text{hinge loss}}{\partial \mathbf{w}} = -y^{(i)}\mathbf{x}^{(i)}$$

$$\frac{\partial \text{hinge loss}}{\partial \mathbf{w}} = 0$$

$$J(\mathbf{w}) = \frac{\lambda}{2} ||\mathbf{w}||_2^2 + \sum_{i=1}^{N} \max \left(0, 1 - y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + w_0)\right)$$

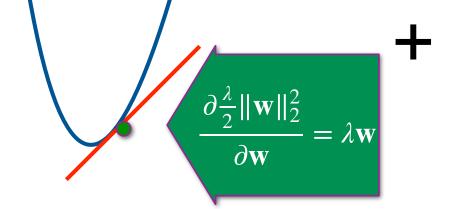
$$\nabla J(\mathbf{w}) = \lambda \mathbf{w} + \begin{cases} 0 & \text{if } y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + \mathbf{w}_0) \ge 1 \\ -y^{(i)} \mathbf{x}^{(i)} & \text{otherwise} \end{cases}$$

Derivative

Sub-derivative of the hinge loss

$$\frac{\lambda}{2} \|\mathbf{w}\|_2^2$$

hinge loss =
$$\max(0, 1 - y^{(i)}\mathbf{w}^T\mathbf{x})$$



$$\frac{\partial \text{hinge loss}}{\partial \mathbf{w}} = -y^{(i)} \mathbf{x}^{(i)}$$

Sub-gradient: Linear global underestimate at this point

$$J(\mathbf{w}) = \frac{\lambda}{2} \|\mathbf{w}\|_{2}^{2} + \sum_{i=1}^{N} \max(0, 1 - y^{(i)}(\mathbf{w}^{T}\mathbf{x}^{(i)} + w_{0}))$$

$$\nabla J(\mathbf{w}) = \lambda \mathbf{w} + \begin{cases} 0 & \text{if } y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + \mathbf{w}_0) \ge 1 \\ -y^{(i)} \mathbf{x}^{(i)} & \text{otherwise} \end{cases}$$

$$J(\mathbf{w}) = \frac{\lambda}{2} \|\mathbf{w}\|_{2}^{2} + \sum_{i=1}^{N} \max\left(0, 1 - y^{(i)}(\mathbf{w}^{T}\mathbf{x}^{(i)} + w_{0})\right)$$
regularizer hinge Loss

$$\mathbf{subgradient}(\mathbf{w}) = \begin{cases} \lambda \mathbf{w} & \text{if } y^{(i)}(\mathbf{w}^T\mathbf{x}^{(i)}) \geq 1 \\ \lambda \mathbf{w} - y^{(i)}\mathbf{x}^{(i)} & \text{otherwise} \end{cases}$$

"We did not incorporate a bias term in any of our experiments. We found that including an un-regularized bias term does not significantly change the predictive performance for any of the data sets used. Furthermore, most methods we compare to, including [21, 24, 37, 18], do not incorporate a bias term either. Nonetheless, there are clearly learning problems where the incorporation of the bias term could be beneficial." /https://www.cs.huji.ac.il/w~shais/papers/ShalevSiSrCo10.pdf

To keep it simple, we will not include a bias unit.

If N is large, batch gradient is slow

We will use stochastic sub-gradient descent with an adaptive learning rate

Stochastic Gradient Descent

```
\begin{aligned} \mathbf{w} &= \text{random initialization} \\ \text{For } \mathbf{t} &= 1,2,...,T \text{:} \\ \text{Pick a random training example } (\mathbf{x}^{(i)},y^{(i)}) \\ &\# \hat{J}(\mathbf{w}) = \frac{\lambda}{2} \|\mathbf{w}\|_2^2 + \max\left(0,1-y^{(i)}(\mathbf{w}^T\mathbf{x}^{(i)})\right) \\ &\# \text{Use only one training example in objective function, N=1} \\ &\mathbf{w} &= \mathbf{w} - \alpha \, \nabla \hat{J}(\mathbf{w}) \end{aligned}
```

The Pegasos Algorithm

$$subgradient(w) = \begin{cases} \lambda w & \text{if } y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)}) \ge 1 \\ \lambda \mathbf{w} - y^{(i)} \mathbf{x}^{(i)} & \text{otherwise} \end{cases}$$

if
$$y^{(i)}(\mathbf{w}^T\mathbf{x}^{(i)}) \ge 1$$

otherwise

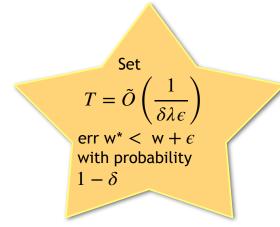
w = random initialization

For t = 1, 2, ..., T:

Pick a random training example $(\mathbf{x}^{(i)}, y^{(i)})$

Decrease the learning rate every iteration of the algorithm

Update the parameters by moving a small amount in the opposite direction of the sub gradient

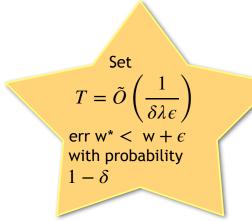


To keep it simple, we will not include a bias unit.

The Pegasos Algorithm

$$\text{subgradient}(\mathbf{w}) = \begin{cases} \lambda \mathbf{w} & \text{if } y^{(i)}(\mathbf{w}^T\mathbf{x}^{(i)}) \geq 1 \\ \lambda \mathbf{w} - y^{(i)}\mathbf{x}^{(i)} & \text{otherwise} \end{cases}$$

w = random initialization For t = 1,2,...,T: Pick a random training example $(\mathbf{x}^{(i)}, y^{(i)})$ $\alpha = \frac{1}{1-\alpha}$



if
$$y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)}) \ge 1$$

 $\mathbf{w} = \mathbf{w} - \alpha \lambda \mathbf{w} \text{ # weight decay}$
else
 $\mathbf{w} = \mathbf{w} - \alpha (\lambda \mathbf{w} - y^{(i)} \mathbf{x}^{(i)})$

Pair share: If α is small enough, will the function converge to a minimum value if enough iterations occur?

To keep it simple, we will not include a bias unit.

Modified Pegasos for Homework

```
W = 0, t = 0
For iter = 1,2,...,num_iters:
     For j = 1, 2, ..., N:
             t=t+1
             \alpha = \frac{1}{\lambda \cdot t}
             if \mathbf{y}^{(j)}(\mathbf{w}^T\mathbf{x}^{(j)}) \geq 1
                   \mathbf{w} = \mathbf{w} - \alpha \lambda \mathbf{w} # weight decay
            else
                 \mathbf{w} = \mathbf{w} - \alpha(\lambda \mathbf{w} - \mathbf{y}^{(j)} \mathbf{x}^{(j)})
```