

Summary of Chapter 3

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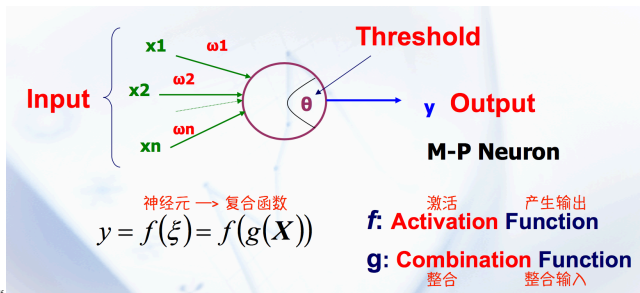
Outline

- 1 Overview
- 2 Feedforward Network
 - Perceptron
 - Deep Network
 - Self-Organizing Feature Map
- 3 Feedback Network
 - Hopfield Network
 - Long Short-Term Memory
- 4 Review

Outline

- 1 Overview
- 2 Feedforward Network
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 - Hopfield Network
 - Long Short-Term Memory
- 4 Review

Overview

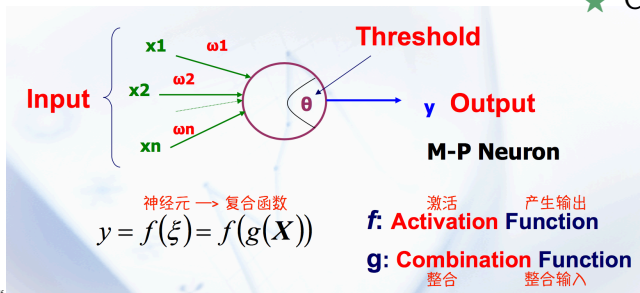


Neurons.pdf

Figure: Artificial Neuron

Overview

★ Connectionism

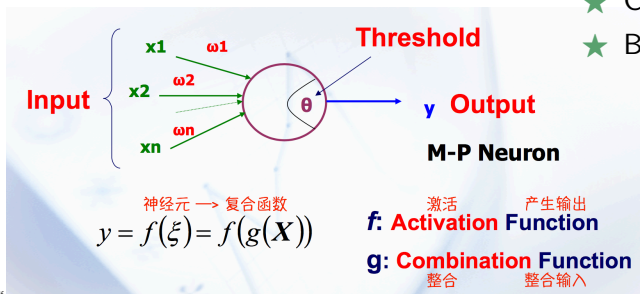


Neurons.pdf

Figure: Artificial Neuron

Overview

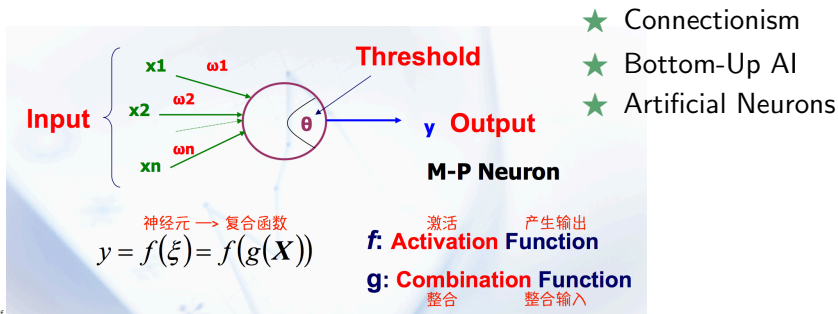
- ★ Connectionism
- ★ Bottom-Up AI



Neurons.pdf

Figure: Artificial Neuron

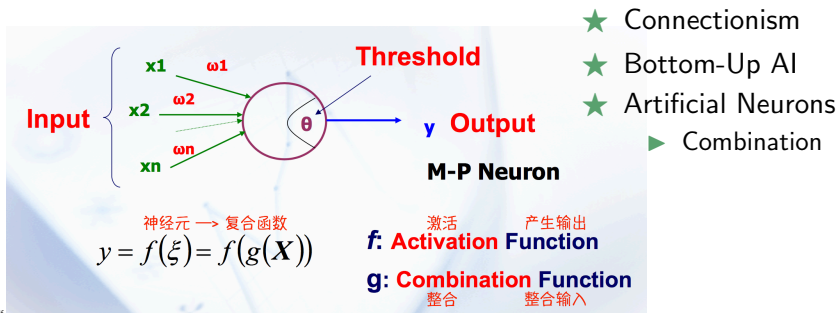
Overview



Neurons.pdf

Figure: Artificial Neuron

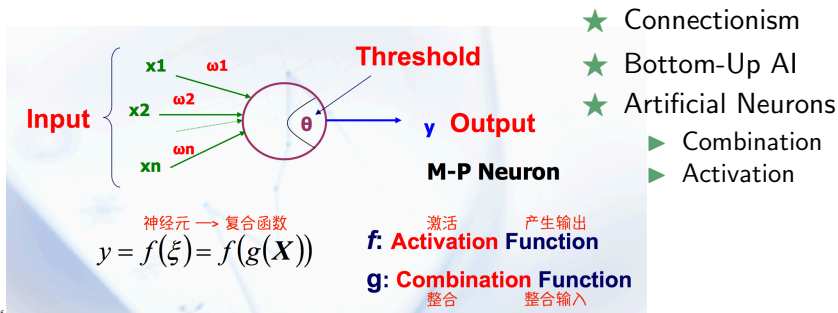
Overview



Neurons.pdf

Figure: Artificial Neuron

Overview



Neurons.pdf

Figure: Artificial Neuron

Overview

Main problems

■ Architecture

Overview

Main problems

- Architecture
 - feedforward (static)

Overview

Main problems

■ Architecture

- feedforward (static)
- feedback (dynamic)

Overview

Main problems

- Architecture
 - feedforward (static)
 - feedback (dynamic)
- Learning Approach

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 - Incremental vs. Batch

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 - Incremental vs. Batch
 - Supervised vs. Unsupervised

Overview

Main problems

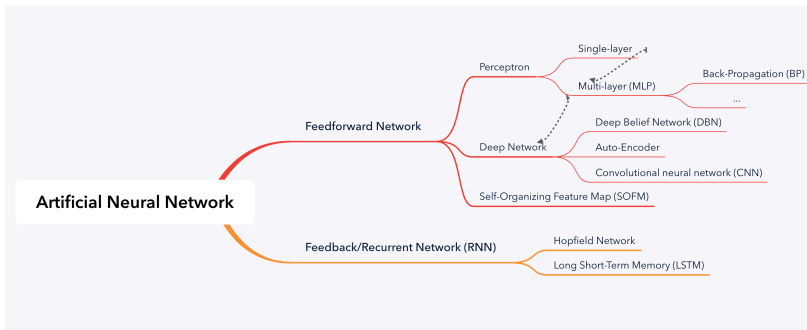
■ Architecture

- feedforward (static)
- feedback (dynamic)

■ Learning Approach

- Incremental vs. Batch
- Supervised vs. Unsupervised
- Error Correction vs. Hebbrian Learning vs. Competitive Learning

Overview



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Single-layer vs. Multi-layer

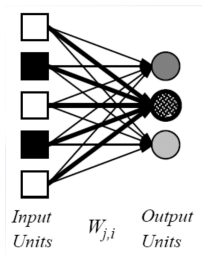


Figure: Single-layer Perceptron

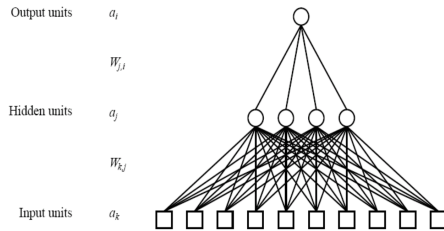


Figure: Multi-layer Perceptron

Single-layer vs. Multi-layer

- Single-layer : only linear functions

Single-layer vs. Multi-layer

- Single-layer : only linear functions
- Multi-layer : non-linear operations
hidden layer added
 - ▶ BP : Use sigmoid activation function

Perceptron

Multi-layer ► BP Network

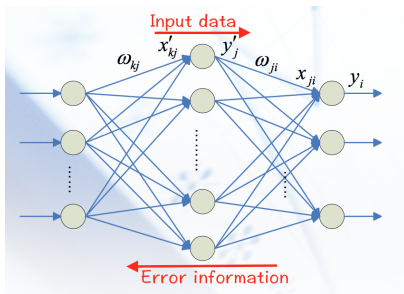


Figure: BP Structure

Multi-layer ► BP Network

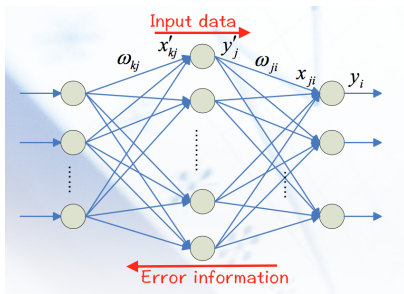


Figure: BP Structure

- objectiveness (measuring criterion)
 - *MSE* :

$$e(\omega) = \frac{1}{2} \sum_{i=1}^n [d_i - y_i]^2$$

Multi-layer ► BP Network

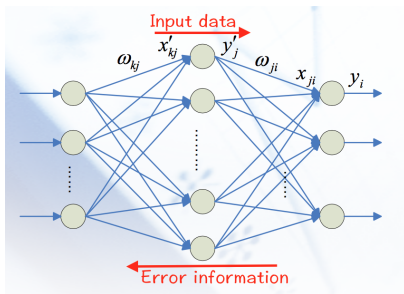


Figure: BP Structure

- objectiveness (measuring criterion)
 - *MSE* :

$$e(\omega) = \frac{1}{2} \sum_{i=1}^n [d_i - y_i]^2$$

- optimization
 - *Gradient Descent* :

$$\omega = \omega - \eta \frac{\partial e}{\partial \omega}$$

Multi-layer ► BP Network

Problems : (especially for deeper layers)

- Diffusion of Gradient → *early layers not trained well*

Multi-layer ► BP Network

Problems : (especially for deeper layers)

- Diffusion of Gradient → *early layers not trained well*
- Supervised learning → *not enough labeled data*

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Deep Belief Network (DBN)

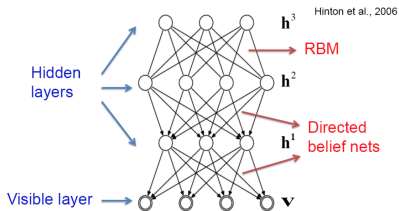
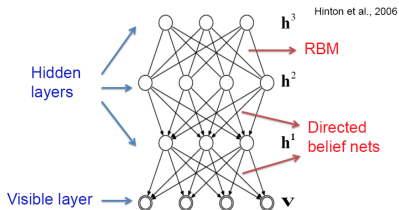


Figure: DBN Structure

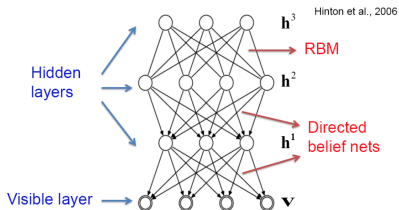
Deep Belief Network (DBN)



■ Key points :

Figure: DBN Structure

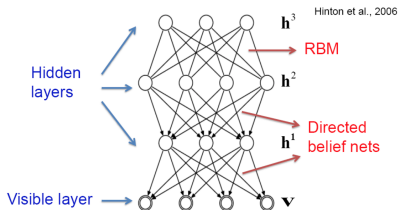
Deep Belief Network (DBN)



- Key points :
 - Unsupervised pre-learning

Figure: DBN Structure

Deep Belief Network (DBN)



■ Key points :

- Unsupervised pre-learning
- Greedy layer-wise training

Figure: DBN Structure

Deep Belief Network (DBN)

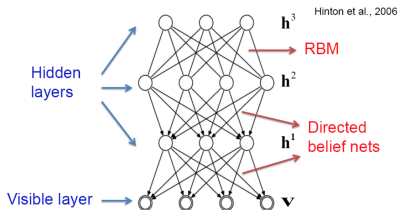


Figure: DBN Structure

- Key points :
 - Unsupervised pre-learning
 - Greedy layer-wise training
 - Use softmax for output layer

Deep Belief Network (DBN)

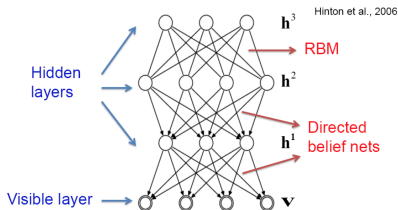


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- objectiveness : MLE

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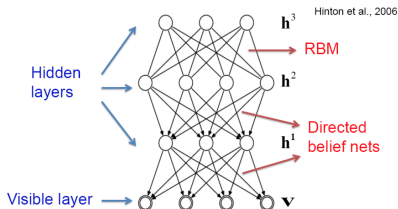


Figure: DBN Structure

- Key points :
 - Unsupervised pre-learning
 - Greedy layer-wise training
 - Use softmax for output layer
- objectiveness : MLE
- optimization : Gradient Ascent

DBN ► Bases

Statistical distribution

- random variable for each neuron

$$P(v, h^1, h^2, \dots, h^l) = P(v|h^1)P(h^1|h^2) \dots P(h^{l-2}|h^{l-1})P(h^{l-1}, h^l)$$

$$P(h^i|h^{i+1}) = \prod_{j=1}^{n^i} P(h_j^i|h^{i+1})$$

DBN ► Bases

Statistical distribution

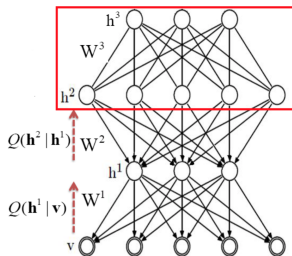
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- RBM for distribution between layers

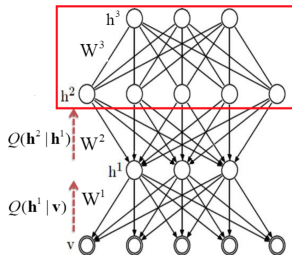
DBN ► Training



Layer-wise Training of DBN.png

Figure: Greedy Layer-wise Training

DBN ► Training

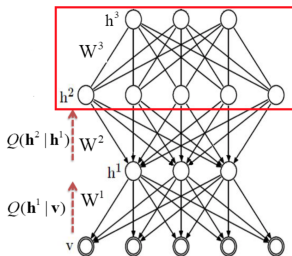


Layer-wise Training of DBN.png

■ Greedy Layer-wise Training

Figure: Greedy Layer-wise Training

DBN ► Training

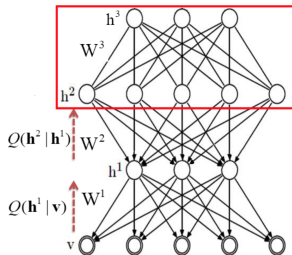


Layer-wise Training of DBN.png

- Greedy Layer-wise Training
 - i construct a RBM with v and h^1

Figure: Greedy Layer-wise Training

DBN ► Training



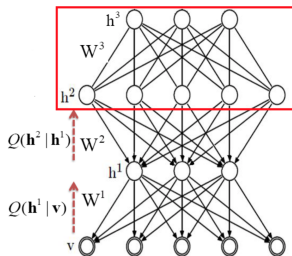
Layer-wise Training of DBN.png

■ Greedy Layer-wise Training

- i construct a RBM with v and h^1
- ii form a new RBM with h^1 and h^2

Figure: Greedy Layer-wise Training

DBN ► Training



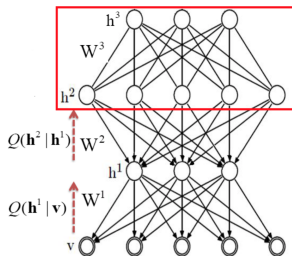
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■ Greedy Layer-wise Training

- i construct a RBM with v and h^1
- ii form a new RBM with h^1 and h^2
- iii continued...

Figure: Greedy Layer-wise Training

DBN ► Training



Layer-wise Training of DBN.png

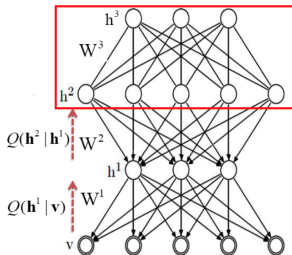
■ Greedy Layer-wise Training

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■ Fine-tuning

Figure: Greedy Layer-wise Training

DBN ► Training



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Figure: Greedy Layer-wise Training

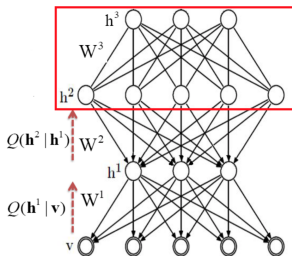
■ Greedy Layer-wise Training

- i construct a RBM with v and h^1
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- iii continued...

■ Fine-tuning

- Generative (unsupervised):
Up-down algorithm

DBN ► Training



Layer-wise Training of DBN.png

Figure: Greedy Layer-wise Training

■ Greedy Layer-wise Training

- construct a RBM with v and h^1
- form a new RBM with h^1 and h^2
- continued...

■ Fine-tuning

- Generative (unsupervised):
Up-down algorithm
- Discriminative (supervised):
Back propagation

Auto-encoder

■ Bases

Auto-encoder

- Bases
 - Encoder

Auto-encoder

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 - Decoder

Auto-encoder

- Bases
 - Encoder
 - Decoder
- AutoEncoder vs. RBM

Auto-encoder

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- AutoEncoder vs. RBM
 - AutoEncoder : reconstruct each training data

Auto-encoder

■ Bases

- Encoder
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■ AutoEncoder vs. RBM

- AutoEncoder : reconstruct each training data
- RBM : reconstruct distribution of data

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SOFM

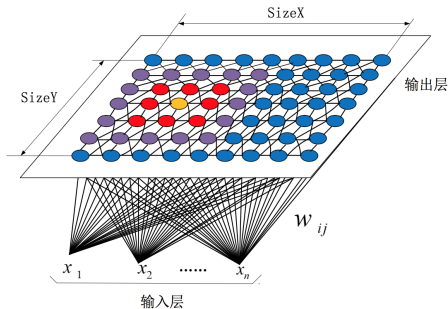
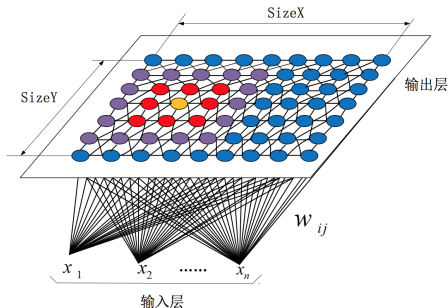


Figure: SOFM structure

SOFM



- Fundamental idea
Dimensionality reduction

Figure: SOFM structure

SOFM

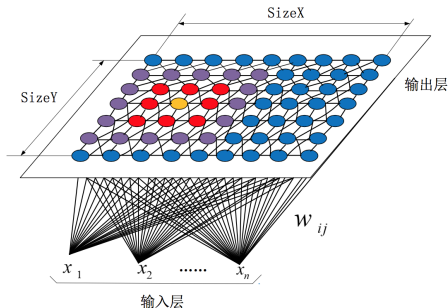


Figure: SOFM structure

- Fundamental idea
Dimensionality reduction
- Principles

SOFM

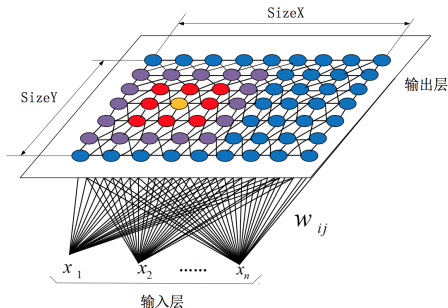


Figure: SOFM structure

- Fundamental idea
Dimensionality reduction
- Principles
 - Self-reinforcing

SOFM

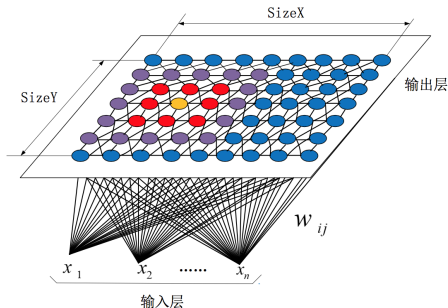


Figure: SOFM structure

- Fundamental idea
 - Dimensionality reduction
- Principles
 - Self-reinforcing
 - Competition

SOFM

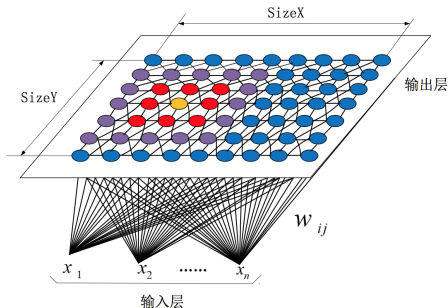


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- Fundamental idea
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Feedback (Recurrent) Network (RNN)

(1) Stable feedback network

Feedback (Recurrent) Network (RNN)

(1) Stable feedback network

► Hopfield Network

Feedback (Recurrent) Network (RNN)

(1) Stable feedback network

▶ Hopfield Network

(2) Sequential feedback network \longleftrightarrow Deep Network

Feedback (Recurrent) Network (RNN)

(1) Stable feedback network

- ▶ Hopfield Network

(2) Sequential feedback network \longleftrightarrow Deep Network

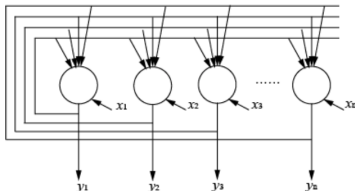
- ▶ LSTM

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Hopfield Network

Bases

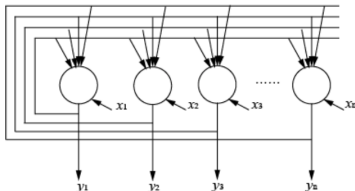


Network.png

Figure: Hopfield Network Structure

Bases

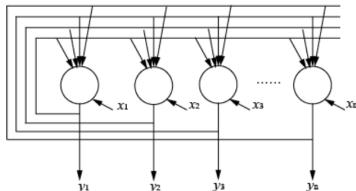
■ Full link network



Network.png

Figure: Hopfield Network Structure

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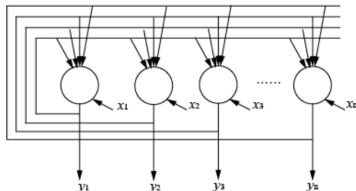


Network.png

- Full link network
- Training method :
change network state

Figure: Hopfield Network Structure

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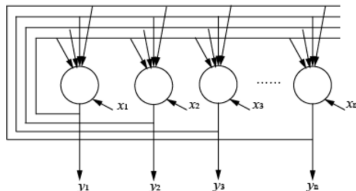


Network.png

- Full link network
- Training method :
change network state
 - ▶ asynchronous

Figure: Hopfield Network Structure

Bases



Network.png

- Full link network
- Training method :
change network state
 - ▶ asynchronous
 - ▶ synchronous

Figure: Hopfield Network Structure

Energy Function



$$E = -\frac{1}{2} \sum_{i=0}^n \sum_{j=0}^n \omega_{ij} s_i s_j \quad \left(- \sum_{i=1}^n I_i s_i \right)$$

Energy Function



$$E = -\frac{1}{2} \sum_{i=0}^n \sum_{j=0}^n \omega_{ij} s_i s_j \quad \left(- \sum_{i=1}^n I_i s_i \right)$$

■ Stability condition

$$\omega_{ij} = \begin{cases} \omega_{ji} & i \neq j \\ 0 & i = j \end{cases}$$

Application

- Associative memory (CRM)
 - ▶ each local minimum represents one memorized data

Application

- Associative memory (CRM)
 - ▶ each local minimum represents one memorized data
- Combinatorial Optimization
 - ▶ TSP

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Back-Propagation Through Time (BPTT)

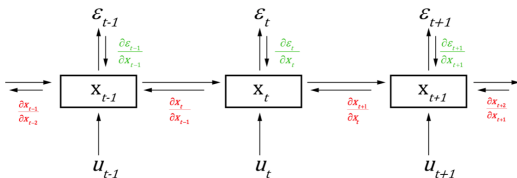


Figure: BPTT Structure

Back-Propagation Through Time (BPTT)

■ Problems

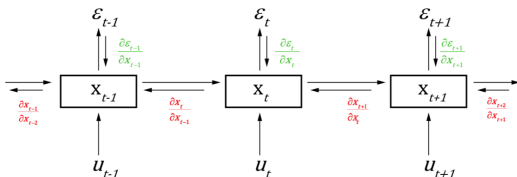


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Back-Propagation Through Time (BPTT)

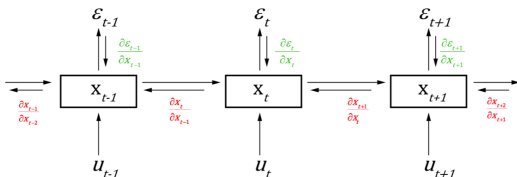


Figure: BPTT Structure

Problems

- Gradient Vanishing

Back-Propagation Through Time (BPTT)

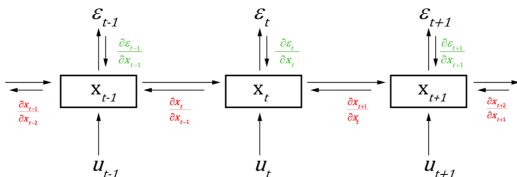


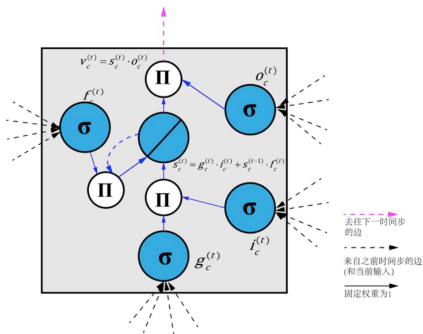
Figure: BPTT Structure

Problems

- Gradient Vanishing
- Gradient Exploding

Long Short-Term Memory

LSTM Memory Cell

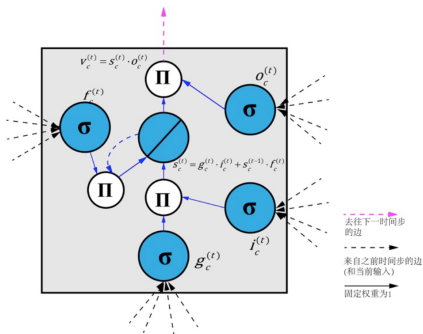


cell.png

Figure: LSTM Memory Cell

LSTM Memory Cell

- Internal state (constant error carousel):
kernel, linear activation function, self-cycling edge (weight fixed to 1)

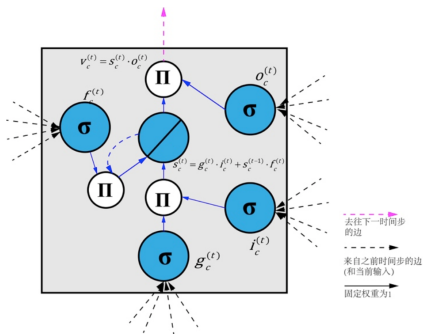


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Figure: LSTM Memory Cell

Long Short-Term Memory

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- Input node :
receive earlier signals

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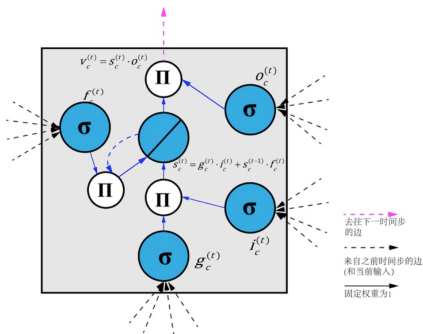
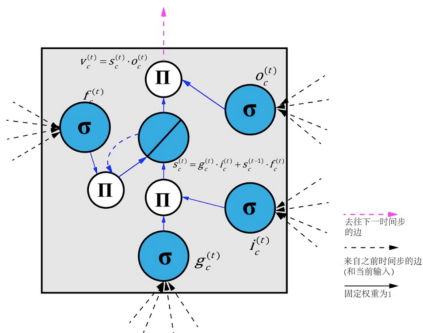


Figure: LSTM Memory Cell

- Internal state (constant error carousel):
kernel, linear activation function, self-cycling edge (weight fixed to 1)
- Input node :
receive earlier signals
- Input gate :
same as Input node, control result of input

Long Short-Term Memory

LSTM Memory Cell



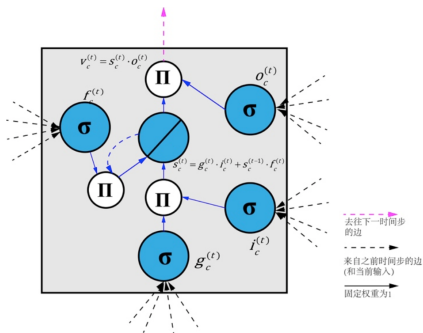
cell.png

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Long Short-Term Memory

LSTM Memory Cell

- Forget gate :
eliminate previous internal state value

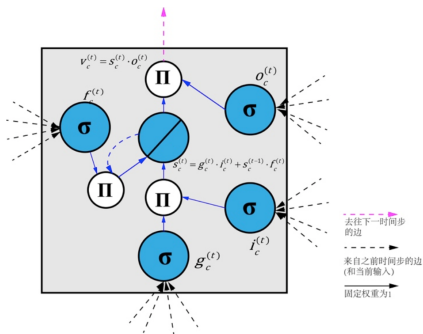


cell.png

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Long Short-Term Memory

LSTM Memory Cell

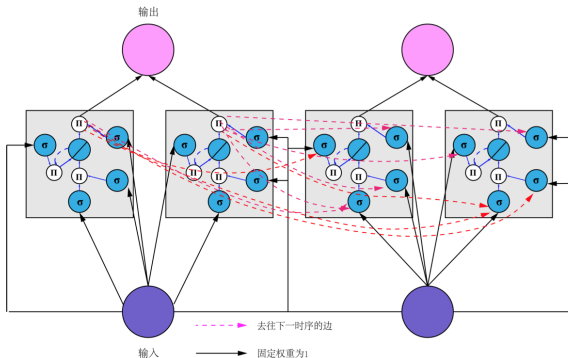


cell.png

- Forget gate :
eliminate previous internal state value
- Output gate :
control result of output

Figure: LSTM Memory Cell

LSTM Structure



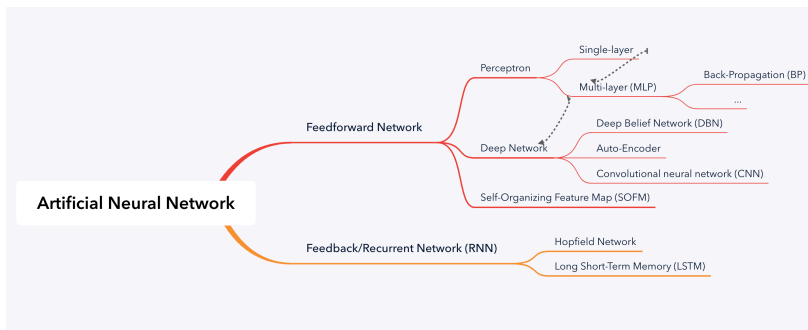
structure.png

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