

Summary of Chapter 2 : Machine Learning

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October 20, 2019



Outline

- 1 Overview
- 2 Supervised Learning
 - Rote Learning
 - Decision Trees
 - Learning in Bayesian Inference
- 3 Unsupervised Learning
 - Partition clustering
 - Hierarchical clustering
 - Density based clustering
 - Grid based clustering
- 4 Review



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Overview

■ What to learn?

Overview

- What to learn?
 - Learning denotes changes

Overview

- What to learn?
 - Learning denotes changes
- How to learn? – Key points

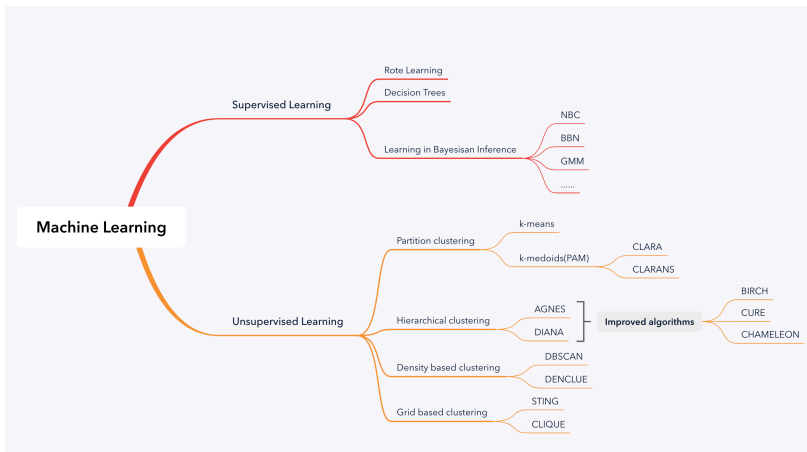
Overview

- What to learn?
 - Learning denotes changes
- How to learn? – Key points
 - Objectiveness

Overview

- What to learn?
 - Learning denotes changes
- How to learn? – Key points
 - Objectiveness
 - Optimization

Overview



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What and how to learn?

Learn a function to fit the data

- key points

What and how to learn?

Learn a function to fit the data

- key points
 - Function Structure

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 - Ockham's razor

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 - Function Structure
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 - Optimize the parameters
- learning methods

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- key points
 - Function Structure
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 - Optimize the parameters
- learning methods
 - data points : rote learning

What and how to learn?

Learn a function to fit the data

- key points
 - Function Structure
 - Ockham's razor
 - Optimize the parameters
- learning methods
 - data points : rote learning
 - implicit : decision trees, Bayesian Inference

Rote learning

- trade-off between saving states and computing

Rote learning

- trade-off between saving states and computing
- tune the search depth and evaluation function

Elements

Any discrete function

- non-leaf nodes : input variables

Elements

Any discrete function

- non-leaf nodes : input variables
- leaf nodes : output result

Elements

Any discrete function

- non-leaf nodes : input variables
- leaf nodes : output result
- edges : values of variables

Bases of choosing attributes

■ Informatino Gain (IG)

$$I\left(\frac{p}{p+n}, \frac{n}{p+n}\right) = -\frac{p}{p+n} \log_2 \frac{p}{p+n} - \frac{n}{p+n} \log_2 \frac{n}{p+n}$$

$$IG(A) = I\left(\frac{p}{p+n}, \frac{n}{p+n}\right) - remainder(A)$$

Bases of choosing attributes

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■ Minimum Description Length (MDL)

criterion : $complexity(f(x)) + accuracy(f(x))$

Problem and solution

■ overfitting

Problem and solution

- overfitting
- solution

Problem and solution

- overfitting
- solution
 - regularization term

Problem and solution

- overfitting
- solution
 - regularization term
 - post-prune

Bases

■ Foundation :

$$P(h|D) = \frac{P(D, h)}{P(D)} = \frac{P(D|h)P(h)}{P(D)}$$

Bases

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- $P(h)$: Prior probability
- $P(h|D)$: Posterior probability
- $P(D|h)$: Class-conditional probability

Bases

■ Foundation :

$$P(h|D) = \frac{P(D, h)}{P(D)} = \frac{P(D|h)P(h)}{P(D)}$$

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- $P(h|D)$: Posterior probability
- $P(D|h)$: Class-conditional probability

■ Criterion :

$$h_{MAP} = \operatorname{argmax}_h P(D|h)P(h)$$

Simplified form of class-conditional probability

■ Naive Bayesian Classifiers (NBC)

$$P(D|h) = P(d_1, \dots, d_n|h) = \prod_i P(d_i|h)$$

Simplified form of class-conditional probability

■ Naive Bayesian Classifiers (NBC)

$$P(D|h) = P(d_1, \dots, d_n|h) = \prod_i P(d_i|h)$$

■ Bayesian Belief Networks (BBN)

$$P(x_1, \dots, x_n) = \prod_{i=1}^n P(x_i | P(\text{Parents}(x_i)))$$

How to learn?

- fully observable variables : Conditional probability table (CPT)

How to learn?

- fully observable variables : Conditional probability table (CPT)
- only some observable : Multi-layer perceptron

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Fundamental task :

- Clustering (Similarity Measurement)

Key points :

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- Association Rule Mining

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- Similarity measurement
- Data set division

Overview

Fundamental task :

- Clustering (Similarity Measurement)
- Association Rule Mining

Key points :

- Similarity measurement
- Data set division
- Scalability

Partition clustering

■ Blind search

Partition clustering

- Blind search
- Heuristic search

Partition clustering

- Blind search
- Heuristic search
 - k-means algorithm

Partition clustering

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 - k-medoids algorithm (PAM)

Partition clustering

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Partition clustering

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 - CLARANS

k-means algorithm

$$J(X, v) = \sum_{i=1}^n \sum_{j=1}^k (u_{ik})^m \rho(d(x_i, v_j))$$

$O(tkn)$, local optimality, noises sensitive

k-medoids algorithm (PAM)

- Substitution cost :

$$C_{ih} = \sum_j C_{jih}$$

$O(tk(N - k)^2)$, Strong robustness

k-medoids algorithm (PAM)

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- Improved algorithms for large data set:

k-medoids algorithm (PAM)

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$$C_{ih} = \sum_j C_{jih}$$

$O(tk(N - k)^2)$, Strong robustness

- Improved algorithms for large data set:
 - CLARA : sampling

k-medoids algorithm (PAM)

- Substitution cost :

$$C_{ih} = \sum_j C_{jih}$$

$O(tk(N - k)^2)$, Strong robustness

- Improved algorithms for large data set:
 - CLARA : sampling
 - CLARANS : repetitive sampling

Hierarchical clustering

Overall methods :

- Bottom-up : AGNES

Problems and Solutions :

Hierarchical clustering

Overall methods :

- Bottom-up : AGNES
- Top-down : DIANA

Problems and Solutions :

Hierarchical clustering

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Problems and Solutions :

- False step sensitive

Hierarchical clustering

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 - CURE

Hierarchical clustering

Overall methods :

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Problems and Solutions :

- False step sensitive
- Improved algorithms
 - BIRCH
 - CURE
 - CHAMELEON

BIRCH

- Clustering feature (CF) :

$$CF = (N, LS, SS)$$

Additive

BIRCH

- Clustering feature (CF) :

$$CF = (N, LS, SS)$$

Additive

- CF Tree :

B,L,T

BIRCH

- Clustering feature (CF) :

$$CF = (N, LS, SS)$$

Additive

- CF Tree :

B,L,T

- Scales linearly ; order sensitive

CURE

Features :

- AGNES

CURE

Features :

- AGNES
- Representative data

CURE

Features :

- AGNES
- Representative data
- Shrunk toward the mean value

CURE

Features :

- AGNES
- Representative data
- Shrunk toward the mean value
- Random sampling for large scale

CHAMELEON

Dynamic modeling ; Graph based method

i Construct a sparse graph (KNN)

CHAMELEON

Dynamic modeling ; Graph based method

- i Construct a sparse graph (KNN)
- ii Partition the graph

CHAMELEON

Dynamic modeling ; Graph based method

- i Construct a sparse graph (KNN)
- ii Partition the graph
- iii Merge partitions

Density based clustering

Arbitrary shapes ; Noise handled ; Scan once

■ DBSCAN

Density based clustering

Arbitrary shapes ; Noise handled ; Scan once

- DBSCAN
- DENCLUE

DBSCAN

$$N_{Eps}(p) = \{q \in D | dist(p, q) \leq Eps\}$$

Parameters : Eps ; MinPts

- Directly density-reachable

DBSCAN

$$N_{Eps}(p) = \{q \in D | dist(p, q) \leq Eps\}$$

Parameters : Eps ; MinPts

- Directly density-reachable
- Density-reachable

DBSCAN

$$N_{Eps}(p) = \{q \in D | dist(p, q) \leq Eps\}$$

Parameters : Eps ; MinPts

- Directly density-reachable
- Density-reachable
- Density-connected

DENCLUE

■ Influence function

DENCLUE

- Influence function
 - Square wave

DENCLUE

- Influence function
 - Square wave
 - Gaussian

DENCLUE

- Influence function
 - Square wave
 - Gaussian
- Density function

DENCLUE

- Influence function
 - Square wave
 - Gaussian
- Density function
- Density attractor X^*

Grid-based clustering

Dense Grid Cell

- STING

Scale independent ; Non-diagonal boundary

Grid-based clustering

Dense Grid Cell

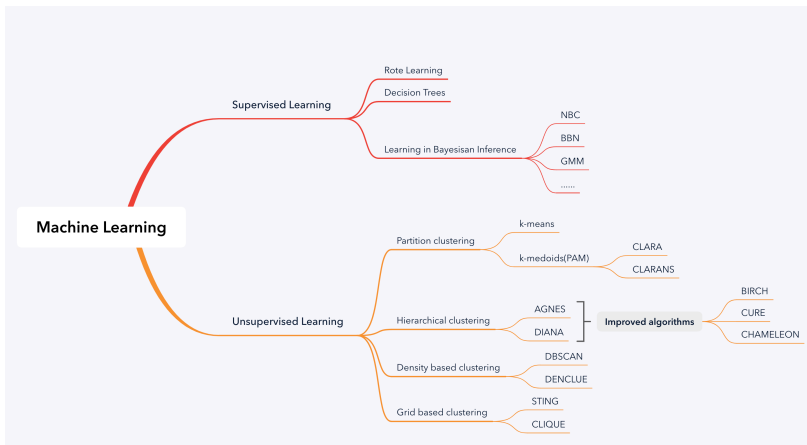
- STING
Scale independent ; Non-diagonal boundary
- CLIQUE
Dimension reduction

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Review



Thank you

Thank you for listening!