

## Sln I-1 Spin Measurements

## Part I Solutions

$$a) \quad \hat{x} \cdot \vec{S} = \frac{\hbar}{2} \sigma_x \quad \sigma_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \checkmark$$

$$\hat{z} \cdot \vec{S} = \frac{\hbar}{2} \sigma_z \quad \sigma_z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$S_x + S_z = \hat{x} \cdot \vec{S} + \hat{z} \cdot \vec{S} = \frac{\hbar}{2} (\sigma_x + \sigma_z) = \frac{\hbar}{2} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$$

Eigenvalues are  $\frac{\hbar}{2} \times$  eigenvalues of  $\begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$ :

$$0 = \det \left( \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} - \lambda I \right) = (1-\lambda)(-1-\lambda) - 1$$

$$= -(1-\lambda^2) - 1 = \lambda^2 - 2 \Rightarrow \lambda = \pm\sqrt{2}$$

Thus, possible results are  $\pm\sqrt{2} \frac{\hbar}{2}$

b) The eigenvectors  $\begin{pmatrix} \alpha \\ \beta \end{pmatrix}$  obey

$$(1-\lambda)\alpha + \beta = 0$$

$$(1+m\sqrt{2})\alpha + \beta = 0$$

If the eigenvalue is  $m\frac{\hbar}{2}$ .

So, unnormalized, the state after measurement  $m\frac{\hbar}{2}$  is

$$\begin{pmatrix} 1 \\ 1-m\sqrt{2} \end{pmatrix}$$

So that

$$P_{S_x = \frac{\hbar}{2}} = \frac{1}{1 + (1-m\sqrt{2})^2} = \frac{1}{4 - 2\sqrt{2}m}$$

$$P_{S_x = -\frac{\hbar}{2}} = \frac{(1-m\sqrt{2})^2}{1 + (1-m\sqrt{2})^2} = \frac{3 - 2\sqrt{2}m}{4 - 2\sqrt{2}m}$$

after measuring  $S_x + S_z = m\frac{\hbar}{2}$ ,  $m = \pm 1$

## Section I: Involving Quantum Mechanics

## I -2 Electron Pressure

An electron is inside a sphere of radius  $R$ . What pressure  $P$  does it exert on the wall, if it is:

i) in the lowest S-state?

ii) in the lowest P-state? (Hint:  $\psi_1 \sim d\psi_0/d(kr)$ , solve approximately) ✓

Sln I-2

Sln: Solve Schroed to get  $E(R)$

• expand sphere by  $dR$

Work done is:  $dW = P dV = 4\pi R^2 P dR = -dE(R) = -\frac{dE(R)}{dR} dR$

Hence:  $P = -\frac{dE}{dR} \frac{1}{4\pi R^2} \quad (1)$

i) lowest S-state:  $\psi_0 \sim \frac{\sin kr}{kr}$  with  $\psi(R) = 0 \rightarrow kR = \pi$

Then:  $E = \frac{\hbar^2 k^2}{2m} = \frac{\pi^2 \hbar^2}{2m R^2}$

(2)  $\rightarrow \boxed{P = \frac{\pi^2 \hbar^2}{4m R^5}}$

ii) lowest P-state:  $\psi_1 \sim \frac{\cos(kr)}{kr} - \frac{\sin(kr)}{(kr)^2} \approx \frac{d\psi_0}{d(kr)}$

$\psi(R) = 0 \rightarrow kR \cot(kR) = 0$  solve by iteration,  $kR \approx 4.5$

$\rightarrow \boxed{P \approx (4.5)^5 \frac{\hbar^2}{4m R^5}}$

### I - 3 States and Observables of a System

Observable A has eigenstates  $|+\rangle$  and  $|-\rangle$ , where  $A|\pm\rangle = \pm 1|\pm\rangle$ . The Hamiltonian for this system is defined by  $\langle +|H|-\rangle = i\hbar\omega$ , and  $\langle +|H|+\rangle = \langle -|H|-\rangle = 0$ .

- Find the normalized eigenstates of H in terms of the states  $|+\rangle$ , and the corresponding eigenvalues.
- What are the matrix representations of A and H in the H eigenstates basis?
- Given that  $|\Psi(t=0)\rangle = |+\rangle$ , what is  $|\Psi(t)\rangle$  for any  $t$ ?
- Averaged over many identical experiments, what would one measure for the observables A and H when the system is in the state  $|\Psi(t)\rangle$ ?
- What is the probability of obtaining the result -1 in a measurement of A at time  $t$ ?
- At time  $t=10$ , for example, the Hamiltonian suddenly changes to  $H = \hbar\omega A$ . What will  $|\Psi(t)\rangle$  be at  $t=20$ ?

Sln I-3

a) In the  $| \pm \rangle$  basis  $\begin{pmatrix} + \\ - \end{pmatrix}$ :

$$H = \begin{pmatrix} 0 & i\hbar\omega \\ i\hbar\omega & 0 \end{pmatrix}$$

$$A = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \quad \text{then} \quad \text{sign inverted}$$

Eigenstates From  $\det(H - \epsilon I) = 0 \Rightarrow \epsilon^2 - \hbar^2\omega^2 = 0$   
 $\epsilon = \pm \hbar\omega$

$$\text{If } \epsilon = +\hbar\omega \quad \begin{pmatrix} -\hbar\omega & -i\hbar\omega \\ i\hbar\omega & -\hbar\omega \end{pmatrix} \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = 0 \Rightarrow \alpha + i\beta = 0$$

$$e_+ = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ i \end{pmatrix} \quad (\text{Normalized}) \quad |+\hbar\omega\rangle = \frac{|+\rangle + i|-\rangle}{\sqrt{2}}$$

$$\text{If } \epsilon = -\hbar\omega \quad \begin{pmatrix} \hbar\omega & -i\hbar\omega \\ i\hbar\omega & \hbar\omega \end{pmatrix} \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = 0 \Rightarrow \alpha - i\beta = 0$$

$$e_- = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -i \end{pmatrix} \quad (\text{Normalized}) \quad |-\hbar\omega\rangle = \frac{|+\rangle - i|-\rangle}{\sqrt{2}}$$

b)  $H e_+ = \hbar \omega e_+$   $\Rightarrow H = \begin{pmatrix} \hbar \omega & 0 \\ 0 & -\hbar \omega \end{pmatrix}$  in  $e_{\pm}$  basis 4 of 24  
 $H e_- = -\hbar \omega e_-$   $\langle e_n | H | e_m \rangle = \hbar \omega \delta_{nm}$  ;  $n, m = \pm$

$A e_+ = \frac{1}{\sqrt{2}}(-i) = e_-$   $\Rightarrow A = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$  in  $e_{\pm}$  basis  
 $A e_- = \frac{1}{\sqrt{2}}(i) = e_+$   $\langle e_n | A | e_m \rangle = (1 - \delta_{nm})$  ;  $n, m = \pm$

c)  $|\psi(t=0)\rangle = |+\rangle = \frac{|+\hbar\omega\rangle + |- \hbar\omega\rangle}{\sqrt{2}}$

$|\psi(t)\rangle = \frac{1}{\sqrt{2}}(|+\hbar\omega\rangle e^{-i\omega t} + |- \hbar\omega\rangle e^{i\omega t}) = \frac{e^{-i\omega t} + e^{i\omega t}}{2} |+\rangle + \frac{e^{-i\omega t} - e^{i\omega t}}{2} |-\rangle$   
 $= \cos \omega t |+\rangle + \sin \omega t |-\rangle$

d)  $\langle E \rangle = (\hbar\omega) \underbrace{\left| \frac{1}{\sqrt{2}} e^{-i\omega t} \right|^2}_{\frac{1}{2}} + (-\hbar\omega) \underbrace{\left| \frac{1}{\sqrt{2}} e^{i\omega t} \right|^2}_{\frac{1}{2}} = 0$

$\langle A \rangle = (+1) \cos^2 \omega t + (-1) \sin^2 \omega t = \cos^2 \omega t - \sin^2 \omega t = \cos 2\omega t$

e)  $P_{A=-1} = |\sin \omega t|^2 = \sin^2 \omega t$

f)  $|\psi(t=10)\rangle = \cos(10\omega) |+\rangle + \sin(10\omega) |-\rangle$

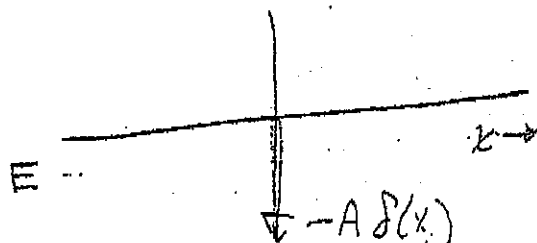
$|\psi(t=10)\rangle = \cos(10\omega) e^{-i10\omega} |+\rangle + \sin(10\omega) e^{i10\omega} |-\rangle$

$|\psi(t=20)\rangle = \cos(10\omega) e^{-i20\omega} |+\rangle + \sin(10\omega) e^{i20\omega} |-\rangle$

## I - 4 Sudden Change in Potential

For  $t < 0$ , an electron is in the ground state of the one dimensional potential  $V(x) = -A\delta(x)$ . At  $t=0$ , the potential suddenly changes to  $V(x) = -A'\delta(x)$ . What is the probability that the electron will be in the ground state of the potential  $V'$  for times  $t \gg 0$ ?

For:



We have  $-\frac{\hbar^2}{2m} \psi'' - A\delta(x) \psi = E \psi$

$$\psi'' + \frac{2mA}{\hbar^2} \delta(x) \psi = -\frac{2mE}{\hbar^2} \psi = k^2 \psi$$

For  $x \neq 0$ , this is  $\psi'' = k^2 \psi \Rightarrow \psi = \alpha e^{kx} + \beta e^{-kx}$

Boundary conditions: To be normalizable we require exponentially growing solution at  $x = \pm \infty$

$$\Rightarrow \psi(x) = \begin{cases} \alpha e^{-kx} & x > 0 \\ \beta e^{kx} & x < 0 \end{cases}$$

$\psi$  is continuous at  $x=0 \Rightarrow \alpha = \beta \Rightarrow \psi(x) = \alpha e^{-k|x|}$

$$\int_{-\epsilon}^{\epsilon} (\psi'' + \frac{2mA}{\hbar^2} \delta(x) \psi) dx = \int_{-\epsilon}^{\epsilon} k^2 \psi dx$$

$$(\psi/\epsilon) - (\psi/(-\epsilon)) + \frac{2mA}{\hbar^2} \psi(0) = 0$$

$$(-k\alpha) - (k\alpha) + \frac{2mA}{\hbar^2} \alpha = 0$$

$$\Rightarrow k = \frac{mA}{\hbar^2}$$

Normalizing:

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$$\begin{aligned} 1 &= \int_{-\infty}^{\infty} |\psi|^2 dx = \int_{-\infty}^{\infty} \alpha^2 e^{-2\alpha|x|} dx \\ &= 2\alpha^2 \int_0^{\infty} e^{-2\alpha x} dx \\ &= \frac{2\alpha^2}{2\alpha} \end{aligned}$$

$$\Rightarrow \alpha = \sqrt{k}$$

$$\Rightarrow \psi(x) = \sqrt{\frac{mA}{k^2}} e^{-\frac{mA}{k^2}|x|}$$

The probability is the square of the amplitude  $C$ :

$$P = |C|^2$$

$$C = \int dx \psi'^*(x) \psi(x)$$

$$= \int dx \sqrt{\frac{mA'}{k^2}} e^{-\frac{mA'}{k^2}|x|} \sqrt{\frac{mA}{k^2}} e^{-\frac{mA}{k^2}|x|}$$

$$= \frac{m}{k^2} \sqrt{A'A} \int dx e^{-\frac{m}{k^2}(A+A')|x|}$$

$$= \frac{m}{k^2} \sqrt{A'A} 2 \cdot \frac{1}{\frac{m}{k^2}(A+A')} = 2 \sqrt{\frac{AA'}{(A+A')^2}}$$

$$\Rightarrow P = 4 \frac{AA'}{(A+A')^2}$$

## Sh II - 1 Field of a Current Loop.

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a) Field of the loop  $\vec{B}$

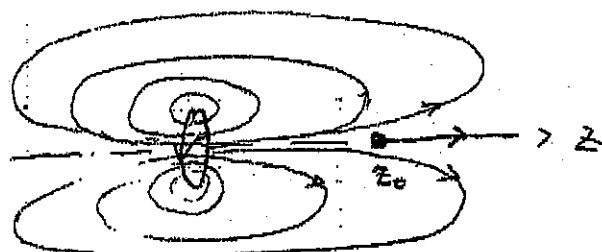
Biot S.

$$d\vec{B} = \frac{\mu_0}{4\pi} \frac{I d\vec{l} \times \vec{r}}{r^3}$$



$$\boxed{B = \frac{\mu_0}{4\pi} \frac{2\pi b}{(b^2 + z_0^2)} \frac{b}{\sqrt{b^2 + z_0^2}} = \frac{\mu_0 I b^2}{2 \sqrt{b^2 + z_0^2}} \hat{z}}$$

b)



c) Small  $\Delta y$  off axis

Use:  $\text{div } \vec{B} = 0 = \frac{\partial B_x}{\partial x} + \frac{\partial B_y}{\partial y} + \frac{\partial B_z}{\partial z}$

Note: from b) the cylindrical symmetry

$$\rightarrow \text{use } \nabla_{\text{cyl}} \cdot \vec{B} = 0 = \frac{1}{r} \frac{\partial}{\partial r}(r B_r) + \underbrace{\frac{1}{r} \frac{\partial B_\phi}{\partial \phi}}_0 + \frac{\partial B_z}{\partial z}$$

$r = \Delta y$  :  $\frac{1}{\Delta y} \frac{\partial}{\partial y}(\Delta y B_y) \approx \frac{\partial B_y}{\partial y}$   
small

$$\boxed{B_y = \frac{\partial B_z}{\partial y} \Delta y = - \frac{\partial B_z}{\partial z} \Delta y = \frac{3}{4} \mu_0 \frac{I b^2 \Delta y}{\sqrt{b^2 + z_0^2}} \frac{2 z_0}{\sqrt{b^2 + z_0^2}}}$$

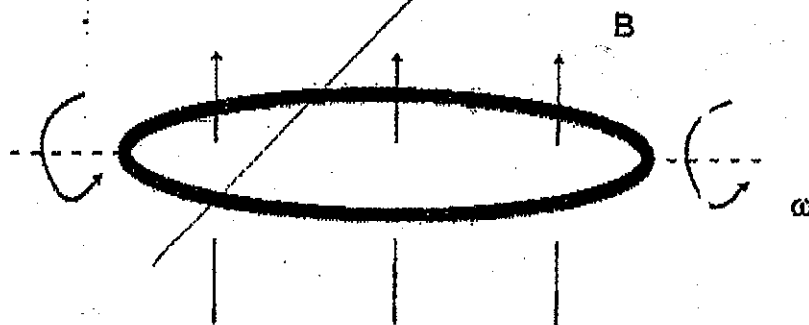
direction  $+\hat{y}$

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## II - 2 Rotating Ring

A metal ring rotates in a weak homogeneous magnetic field  $B$  around an axis perpendicular to  $B$ , see sketch. Due to Joule heat dissipation it slows down to  $\omega_0 e^{-1}$  in a time  $\tau$  from its initial value  $\omega_0$ .

Calculate  $\tau$  for a ring made from a round wire of a metal with resistivity  $\eta$  ( $\Omega \cdot m$ ) and density  $\rho$  ( $g/cm^3$ ). Neglect self induction and assume that only a small amount of energy is lost in one revolution.



Sln II-2

Flux  $\neq 0$ :  $\phi = B \cdot \pi a^2 = B \pi a^2 \cos \omega_0 t$

Faraday:  $\mathcal{E} = - \frac{d\phi}{dt} = -B \pi a^2 \sin \omega_0 t \approx IR$   
 ( $a$  is radius of loop)

with  $R = \eta \frac{2\pi a}{\pi b^2}$  ( $b$  is radius of wire)

kin. E  $E = \frac{1}{2} \theta \omega^2$  with mom of inertia  $\theta$

$\theta = \int r^2 dm = \int_0^{2\pi} (a \sin \theta)^2 d\ell \cdot \pi b^2 \rho$

$\theta = a^3 \pi b^2 \rho \int_0^{2\pi} \sin^2 \theta d\theta = \pi^2 a^3 b^2 \rho$

note:  $\theta = \frac{ma^2}{2}$

$d\ell = a d\theta$   
 $dm = \pi b^2 \rho d\ell$

E conservation:  $\frac{d}{dt} \frac{ma^2}{4} \omega^2 = - \langle I^2 R \rangle = - \frac{B^2 \pi^2 a^4 \omega^2}{2R} = \left\langle \frac{dE}{dt} \right\rangle$

Diff eq:  $\theta \omega \dot{\omega} = - \frac{B^2 \pi^2 a^4 \omega^2}{2R}$

Sln:  $\omega = \omega_0 \exp \left( - \frac{B^2 \pi^2 a^4}{2R\theta} t \right)$

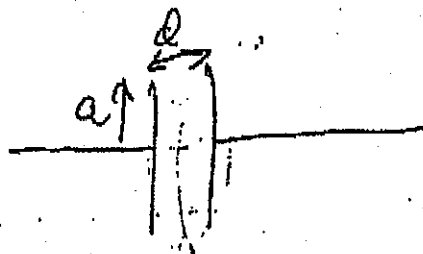
$\tau = \frac{2R\theta}{B^2 \pi^2 a^4} = \frac{2\eta \frac{2a}{b^2} \cdot \pi^2 a^3 b^2 \rho}{B^2} = \frac{4\eta \rho}{B^2}$



# Capacitance at H.F. (3)

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II-3



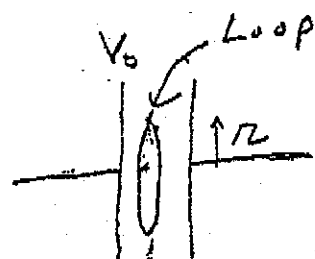
DC capacitance is  $C_0$   
 $V = V_0 e^{i\omega t}$

(a) Electric field?

By definition,  $E = \text{Volts/m} = \frac{V_0 e^{i\omega t}}{d}$

(b) Magnetic field between plates?

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 \left( \int_S \vec{J} \cdot d\vec{S} + \epsilon_0 \frac{\partial \Phi_E}{\partial t} \right)$$



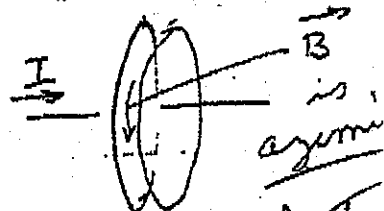
$$B \cdot 2\pi r = \mu_0 \epsilon_0 \frac{\partial E}{\partial t} \cdot \pi r^2$$

$$B = \frac{\mu_0 \epsilon_0 r}{2} \frac{\partial E}{\partial t}$$

$$B = \frac{\mu_0 \epsilon_0 r}{2} \frac{V_0}{d} (i\omega) e^{i\omega t}$$

$$\vec{J} = 0$$

$$\left[ \frac{\partial \vec{E}}{\partial t} \neq 0 \right]$$



(c) First order correction to electric field?

$$\text{Now } \nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$\vec{E} = (0, 0, E_z)$$

X cap.

$$\frac{\partial E_z}{\partial y} = \frac{\partial E_z}{\partial z} = -\frac{\partial B_x}{\partial t}$$

(appropriate on y axis)  
 where  $B = (B_x, 0, 0)$

$$\therefore \frac{\partial E_z}{\partial y} = -\frac{\partial B_x}{\partial t}$$

$$\text{where } B_x = \frac{\mu_0 \epsilon_0 r}{2} \frac{V_0}{d} (i\omega) e^{i\omega t}$$

$$\therefore \frac{\partial E_z}{\partial y} = + \frac{\mu_0 \epsilon_0}{2} \frac{V_0}{d} \omega^2 y e^{i\omega t} \Rightarrow E_z = \frac{\mu_0 \epsilon_0}{2} \frac{V_0}{d} \frac{\omega^2 y^2}{2} e^{i\omega t}$$

(d) Charge density (net) on plates

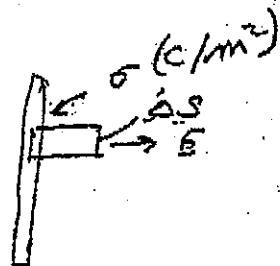
$$E = E_0 + E_{\text{con}} = \frac{V_0}{d} e^{i\omega t} \left[ 1 + \frac{\mu_0 \epsilon_0 \omega^2 r^2}{4} \right]$$

From Gauss's law

$$\int E \cdot dS = \frac{q_{\text{enc}}}{\epsilon_0}$$

$$E \cdot \Delta S = \frac{\sigma \Delta S}{\epsilon_0}$$

$$E = \sigma / \epsilon_0$$



$$\therefore \sigma = E \epsilon_0$$

$$\sigma = \frac{V_0}{d} \epsilon_0 e^{i\omega t} \left[ 1 + \frac{\mu_0 \epsilon_0 \omega^2 r^2}{4} \right]$$

(e) Effective capacitance

$$C = \frac{Q}{V} \quad \text{where } Q = \iint \sigma(r) dS = \int_0^a \sigma(r) \cdot 2\pi r dr$$

$$Q = \frac{V_0}{d} \epsilon_0 e^{i\omega t} \pi a^2$$

$$+ \frac{V_0}{d} \epsilon_0 e^{i\omega t} \frac{\mu_0 \epsilon_0 \omega^2}{4} \cdot 2\pi \int_0^a r^3 dr$$

$\underbrace{\int_0^a r^3 dr}_{a^4/4}$

$$C = \frac{Q}{V_0 e^{i\omega t}} = \frac{\epsilon_0 \pi a^2}{d} + \frac{\epsilon_0 (\mu_0 \epsilon_0 \omega^2)}{d} \cdot \frac{\pi a^4}{4}$$

$$C = \frac{\epsilon_0 \pi a^2}{d} \left[ 1 + \frac{\mu_0 \epsilon_0 \omega^2 a^2}{8} \right]$$

parallel  
plates

II-4

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(a) on y axis, only  $\pm 2Q$  zero is at  $y > a$ , by inspection.

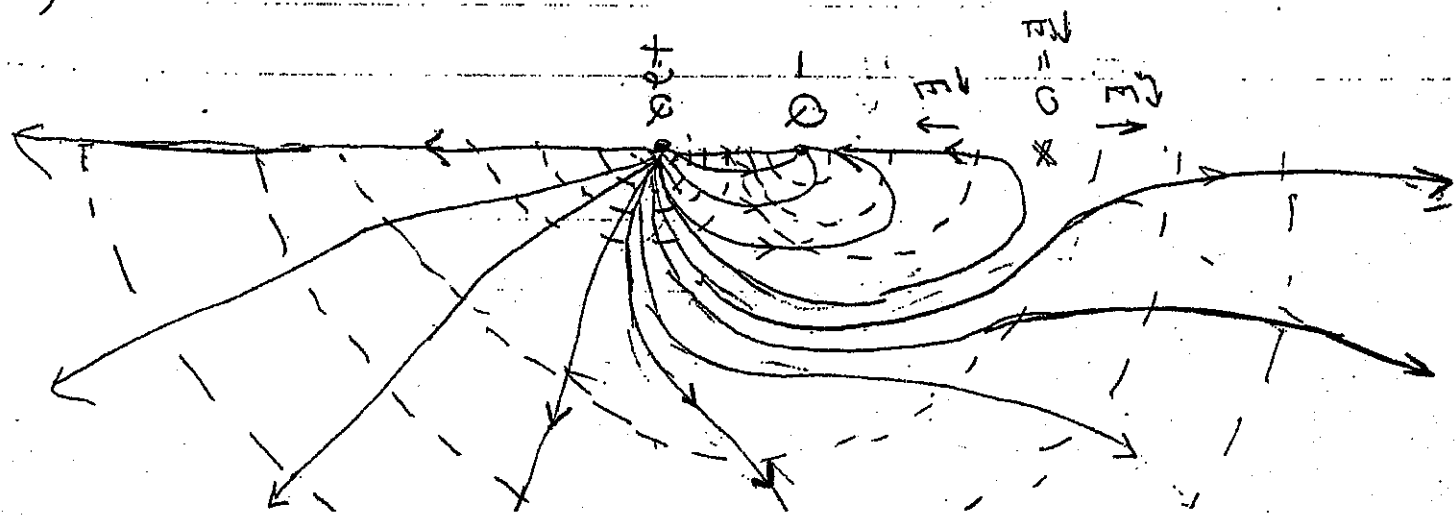
$$\frac{2Q}{y^2} - \frac{Q}{(y-a)^2} = 0 \Rightarrow y^2 - 4ay + 2a^2$$

$$y = (2 \pm \sqrt{2}) a$$

$y \approx 0.6 a, 3.4 a$   
excluded

(b) One half of field lines from  $2Q$  must terminate on  $-Q$ . These will be the field lines starting in directions closest to that of the direction to  $-Q$ , i.e. those with  $\theta < 90^\circ$ . For  $\theta > 90^\circ$ , lines terminate at  $\infty$ .

(c)



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## Section III: Involving Statistical Mechanics and Thermodynamics

### III - 1 Heat Capacity

Consider a solid piece of material containing  $N$  nuclei of spin 1, which do not interact. Each nucleus can be in  $m = 0$  or  $\pm 1$  state. Due to the internal electric field in the solid the  $m = \pm 1$  states have the same energy  $\epsilon > 0$ , while  $m = 0$  has energy 0.

Deduce the entropy of the  $N$  nuclei as a function of temperature, and give the heat capacity for  $\epsilon/kT \ll 1$ .

Sln III - 1

Sln: Part. fn:  $Z = \sum e^{-\frac{\epsilon}{kT}} = (1 + 2e^{-\frac{\epsilon}{kT}})^N$

$$F = -kT \ln Z = -NkT \ln(1 + 2e^{-\frac{\epsilon}{kT}})$$

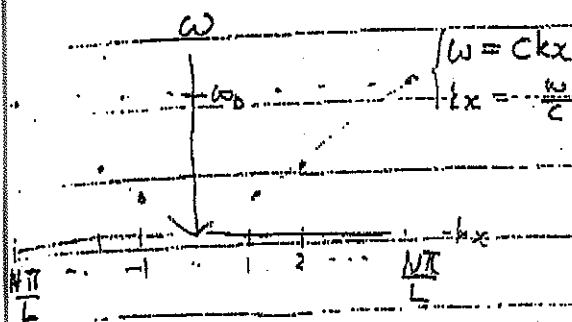
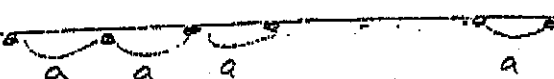
$$S = -\left(\frac{\partial F}{\partial N}\right)_{T,N} \quad S = -\frac{\partial F}{\partial T} = Nk \ln(1 + 2e^{-\frac{\epsilon}{kT}}) + \frac{2N\epsilon}{T} \frac{e^{-\frac{\epsilon}{kT}}}{(1 + 2e^{-\frac{\epsilon}{kT}})}$$

$$E = U = TS \quad U = \frac{2N\epsilon e^{-\frac{\epsilon}{kT}}}{(1 + 2e^{-\frac{\epsilon}{kT}})} \approx \frac{2N\epsilon}{3} \left(1 - \frac{\epsilon}{3kT}\right) \quad \text{for } \frac{\epsilon}{kT} \ll 1$$

$$C = \frac{\partial U}{\partial T} = \frac{2N\epsilon^2}{3} \frac{1}{9kT^2} = \frac{2}{9} Nk \left(\frac{\epsilon}{kT}\right)^2$$

-4.

$$L = Na$$



N-values

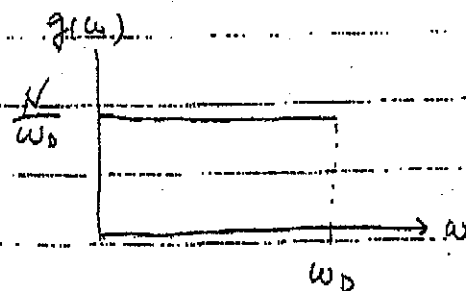
(a)  $\frac{N}{2}$  - allowed values for  $0 \leq kx \leq \frac{N\pi}{L}$

$$\therefore g(k) = \left(\frac{N}{2}\right) / \left(\frac{N\pi}{L}\right) = \frac{L}{2\pi} \quad \text{for positive \& negative}$$

(b)  $g(\omega) \Delta\omega = 2g(k) \Delta kx$

$$\therefore g(\omega) = 2g(k) \cdot \frac{\Delta kx}{\Delta\omega} = 2\left(\frac{L}{2\pi}\right) \cdot \frac{1}{c} = \frac{L}{\pi c}$$

(c)  $\omega_D = c|kx|_{\max} = c\left(\frac{N\pi}{L}\right) \Leftrightarrow \frac{L}{c} = \frac{N\pi}{\omega_D}$



Insert into (b),

$$g(\omega) = \frac{1}{\pi} \frac{N\pi}{\omega_D} = \frac{N}{\omega_D}$$

$$U = \int_0^{\omega_D} \left( \frac{N\hbar\omega}{2} + N\hbar\omega \cdot \frac{1}{e^{\hbar\omega/kT} - 1} \right) g(\omega) d\omega$$

$$\bar{\epsilon} = \frac{\hbar\omega}{2} + \frac{\hbar\omega}{e^{\hbar\omega/kT} - 1}$$

$$\frac{\hbar\omega}{kT} = x$$

$$(e) \quad \frac{1}{\omega_D} \int_0^{\omega_D} \frac{N\hbar\omega}{2} \frac{N}{\omega_D} d\omega$$

$$+ \int_0^{\infty} \frac{(NkT)x}{e^x - 1} \cdot \frac{N}{\omega_D} dx \quad \frac{kT}{\hbar}$$

$$\pi^2/6$$

$$= \frac{N^2\hbar}{2\omega_D} \frac{\omega^2}{2} \Big|_0^{\omega_D} + \frac{\pi^2}{6} \cdot NkBT \cdot \frac{1}{\omega_D} \cdot \frac{kT}{\hbar}$$

$$= \frac{1}{4} N^2(\hbar\omega_D) + \frac{\pi^2}{6} \frac{N^2 \cdot (kBT)^2}{\hbar\omega_D}$$

for  $T \rightarrow 0$ , the first term last; Zero Point Term

$$(f) \quad C_v = \frac{\partial U}{\partial T} = \frac{\pi^2}{6} \frac{N^2}{\hbar\omega_D} \cdot 2k_B^2 T$$

$$= \frac{\pi^2 N^2}{3(\hbar\omega_D)} k_B^2 T //$$

### III - 3 Cooling by relaxing B field.

At low temperatures one can cool further by reducing the magnetic field penetrating a paramagnetic substance. Assume  $M = a(T) \cdot B$ , i.e. the magnetization is linear proportional to the B field applied. Find the temperature change  $\Delta T$  for a magnetic field decrease  $\Delta B$  in a thermally isolated sample of heat capacity  $c_B$  at constant B.

Sln III-3

Sln: Suppose  $M = a(T) \cdot B$

we have  $dU = T dS + B dM$

thermal isolated:  $\Delta S = 0$

Then:  $\Delta T = \left. \frac{\partial T}{\partial H} \right|_S \Delta H$

$$d(U - BM) = T dS - M dB$$

$$\frac{\partial^2 (U - BM)}{\partial S \partial B} = \left. \frac{\partial T}{\partial B} \right|_S = - \left. \frac{\partial M}{\partial S} \right|_B \quad (\text{Maxwell})$$

$$\rightarrow \Delta T = - \left. \frac{\partial M}{\partial S} \right|_B \Delta B = - \left. \frac{\partial M}{\partial T} \right|_B \left. \frac{\partial S}{\partial T} \right|_B \Delta B$$

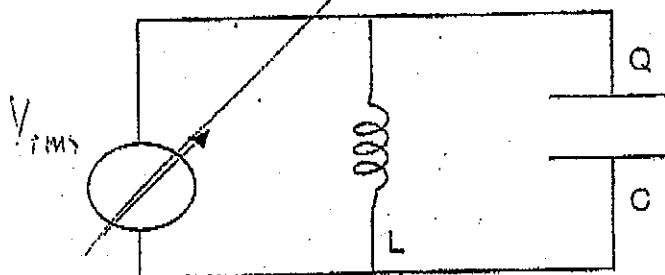
$$\Delta T = \frac{- \frac{\partial a}{\partial T} \cdot B \Delta B}{c_B / T} = - \frac{T}{c_B} \frac{da}{dT} B \Delta B$$

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### III - <sup>4</sup> LC Thermometer

By measuring the noise (rms) voltage across a capacitor in parallel with an inductor one can determine the temperature,  $T$ . Find the relation between  $T$  and  $V_{rms} = \langle \delta V^2 \rangle^{1/2}$ .

Start with a Hamiltonian involving  $Q$ .



Sln III - 4

Sln:  $H = \frac{1}{2} L \left( \frac{dQ}{dt} \right)^2 + \frac{Q^2}{2C} \rightarrow \text{harm. osc } \omega = \frac{1}{\sqrt{LC}}$

$$E_n = \hbar \omega \left( n + \frac{1}{2} \right)$$

in circuit

$$U = \langle E \rangle = \frac{\sum E_n e^{-E_n/kT}}{\sum e^{-E_n/kT}} = \frac{\hbar \omega}{2} + \frac{\hbar \omega}{e^{\hbar \omega/kT} - 1}$$

or

$$U/L = \left\langle \frac{CV^2}{2} \right\rangle = \left\langle \frac{L I^2}{2} \right\rangle$$

$$\begin{aligned} \langle V^2 \rangle &= \frac{\hbar \omega}{C} \left\{ \frac{e^{-\hbar \omega/2}}{e^{-\hbar \omega/2} + e^{-3\hbar \omega/2} + \dots} \right\} \\ &= \frac{\hbar \omega}{2C} \cosh \left( \frac{\hbar \omega}{2kT} \right) \end{aligned}$$

Class limit:  $kT \gg \hbar \omega$ :  $\boxed{\langle V^2 \rangle = \frac{\hbar T}{C}}$

Other ~  $kT \ll \hbar \omega$ :  $\langle V^2 \rangle = \frac{\hbar \omega}{2C}$



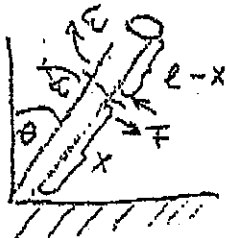
## Section IV: Classical Physics of Mechanics

## IV - 1 Chimney Breaking Point

A thin uniform brick chimney falls, pivoted by its low end. Consider the flexion stress at a section through the chimney and calculate the likely point of rupture.

Let  $N - I$

Let:



Ch. rotates:  $\frac{M L^2}{3} \ddot{\theta} = Mg \frac{L}{2} \sin \theta$

$$\Rightarrow \ddot{\theta} = \frac{3g \sin \theta}{2L}$$

Consider lower portion  $x$ :  $\frac{M x^2}{3} \ddot{\theta} = Mg \frac{x^2}{2L} + \cancel{xF} - \tau$   
shear force internal flexion torque at  $x$

Rotation of upper portion about its Centre of mass:  $\frac{M(L-x)^2}{12L} \ddot{\theta} = \frac{(L-x)}{2} F + \tau$

Solve 3 eq:

$$F = \frac{Mg \sin \theta (L-x)}{L^2(2+x)} \left\{ \frac{(L-x)^2}{4} - x^2 \right\}$$

$$\tau = \frac{M x (L-x)^2 g \sin \theta}{4 L^2}$$

Since the chimney is thin width  $w$ :  ~~$\tau \gg F$  is dominant~~

Breaking at  $\tau_{\max}$   $\frac{d\tau}{dx} = (L-x)^2 - 2x(L-x) = 0$   
 $L^2 - 2Lx + x^2 - 2Lx + 2x^2 = 0$   
 $L^2 - 4Lx + 3x^2 = 0$   
 $L^2 - \frac{4}{3}Lx + \frac{1}{3}x^2 = 0$   
 $x_{1/2} = \left\{ \frac{2}{3} \pm \sqrt{\left(\frac{2}{3}\right)^2 + \frac{1}{3}} \right\} L$   
 $= \frac{1}{2} L$

# Sln IV-2 Jet Engines

## 1. Jet Engines

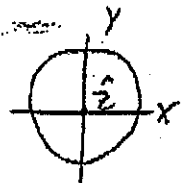
- a. The mass of area flowing into the intake per unit time is  $\dot{m} = \frac{dm}{dt} = v_i \rho A$ .
- b. The force applied to the engine equal to the momentum transferred to the air per unit time (Newton's Second Law),  $F = \dot{m}(v_e - v_i) = \dot{m}\Delta v$ . The power output of the engine is the energy output per unit time,  $P = \dot{E} = \dot{m}\Delta v v_i$ .
- c. The kinetic energy increase per unit time of the air flowing in is  $\dot{E}_{kin} = \frac{1}{2} \dot{m}(v_e^2 - v_i^2)$ .
- d. The propulsive efficiency  $\eta_p$  is the ratio of the power output of the engine  $P$  to the energy increase per unit time of the gas  $\dot{E}_{kin}$ .

$$\eta_p = \frac{\dot{m} v_i \Delta v}{\frac{1}{2} \dot{m} (v_e^2 - v_i^2)} = \frac{2}{2 + \frac{\Delta v}{v_i}}$$

- e. The mass flow is now  $\dot{m}' = v_i \rho A'$ . The force is the same as in part b,  $(v_e - v_i) = \alpha(v'_e - v_i)$ ; in order to achieve the same power output, more air is moved at a lower velocity. The propulsive efficiency is then

$$\eta_p = \frac{\dot{m}' v_i \Delta v'}{\frac{1}{2} \dot{m}' (v_e'^2 - v_i^2)} = \frac{2}{2 + \frac{\Delta v'}{v_i}} = \frac{2}{2 + \frac{\Delta v}{\alpha v_i}}$$

For a loop:



21 Aug. 1995

$$I = \frac{M}{2\pi R} \delta(R\frac{1}{2} - r) \delta(-z) \quad (1)$$

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$$I_{xx} = \int R d\theta \frac{M}{2\pi R} (R^2 - R^2 \cos^2 \theta)$$

$$= \frac{MR^2}{2\pi} \int_0^{2\pi} \sin^2 \theta d\theta$$

A trig identity:

$$\sin^2 \theta = \frac{1}{4} (e^{2i\theta} - 2 + e^{-2i\theta}) = \frac{1}{2} - \frac{1}{2} \cos 2\theta$$

$$I_{xx} = \frac{MR^2}{2\pi} \left( \frac{1}{2} \right) \int_0^{2\pi} (1 - \cos 2\theta) d\theta$$

$$= \frac{MR^2}{4\pi} \left( 2\pi - \frac{1}{2} \int_0^{2\pi} \cos 2\theta d\theta \right) = \frac{MR^2}{2}$$

$$I_{xx} = I_{yy}$$

$$I_{zz} = \int_0^{2\pi} R d\theta \frac{M}{2\pi R} R^2 = MR^2$$

$$I_{xy} = \int_0^{2\pi} R d\theta \frac{M}{2\pi R} (-xy)$$

$$= -\frac{M}{2\pi} \int_0^{2\pi} \sin \theta \cos \theta d\theta = +\frac{M}{2\pi} \int_0^{2\pi} \cos \theta d(\sin \theta)$$

$$= \frac{M}{2\pi} \left[ \frac{1}{2} \sin^2 \theta \right]_0^{2\pi} = 0$$

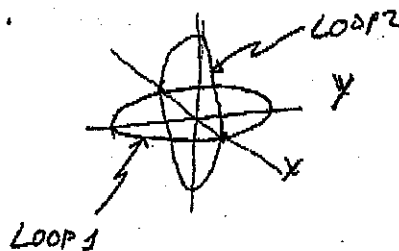
$$I_{zz} = \frac{1}{2} (I_{xx} + I_{yy}) = I_{zz} = n$$

For loop 1:

$$I_{xx,1} = I_{yy,1} = \frac{MR^2}{2}$$

$$I_{zz,1} = MR$$

$$I_{xy,1} = I_{xz,1} = I_{yz,1} = 0$$



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For loop 2:

$$I_{xx,2} = I_{zz,2} = \frac{MR^2}{2}$$

$$I_{yy,2} = MR^2$$

Then,  $I_{xx} = MR^2$  since  $I = I_1 + I_2$

$$I_{yy} = \frac{3}{2} MR^2$$

$$I_{zz} = \frac{3}{2} MR^2$$

all others are zero.

Principal axes:  $\hat{x}$ ,  $\hat{y}$  and  $\hat{z}$

"By symmetry" not an acceptable answer.

$$c) \frac{d\vec{L}}{dt} + \vec{\omega} \times \vec{L} = \vec{N}$$

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$$L_i = I_{ij} \omega_j$$

$$I = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 3/2 & 0 \\ 0 & 0 & 3/2 \end{pmatrix} MR^2$$

$$\vec{L} = \begin{pmatrix} 1 & 3/2 \\ & 3/2 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \frac{MR^2 \omega_0}{\sqrt{2}}$$

$$= \begin{pmatrix} 1 \\ 3/2 \\ 0 \end{pmatrix} \frac{MR^2 \omega_0}{\sqrt{2}}$$

$\vec{N}$  is fixed such that  $\frac{d\vec{L}}{dt} = 0$

$$\Rightarrow \vec{N} = \vec{\omega} \times \vec{L}$$

$$= \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ 1 & 1 & 0 \\ 3/2 & 3/2 & 0 \end{vmatrix} \left( \frac{MR^2 \omega_0}{\sqrt{2}} \right) \left( \frac{\omega_0}{\sqrt{2}} \right)$$

$$= \frac{MR^2 \omega_0^2}{2} \begin{pmatrix} 0 \\ 0 \\ 3/2 - 1 \end{pmatrix} = \frac{MR^2 \omega_0^2}{4} \hat{z}$$

d) For no net torque,

IV-3 cont (4)

$$\frac{d\vec{L}}{dt} + \vec{\omega} \times \vec{L} = 0$$

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~~$\sum \dot{\omega}_i I_i = \sum \dot{\omega}_i$~~

~~$\frac{d}{dt}$~~

$$L_x = \omega_x I_x \quad \text{etc}$$

Then

$$\dot{\omega}_x I_x + \omega_y L_z - \omega_z L_y = 0$$

$$\dot{\omega}_x I_x + \omega_y \omega_z I_z - \omega_z \omega_y I_y = 0$$

---

$$\dot{\omega}_x I_x + \omega_y \omega_z (I_z - I_y) = 0$$

$$\dot{\omega}_y I_y + \omega_z \omega_x (I_x - I_z) = 0$$

$$\dot{\omega}_z I_z + \omega_x \omega_y (I_y - I_x) = 0$$

For  $I_x = MR^2$

$$I_y = \frac{3}{2} MR^2$$

$$I_z = \frac{3}{2} MR^2$$

$$\cancel{\dot{\omega}_x I_x} + \omega_y \omega_z \dot{\omega}_x = 0 \quad (I_z - I_y = 0)$$

$$\omega_y \left(\frac{3}{2}\right) + \omega_z \omega_x \left(-\frac{1}{2}\right) = 0$$

$$\omega_z \left(\frac{3}{2}\right) + \omega_x \omega_y \left(\frac{1}{2}\right) = 0$$

$$3\omega_x = \omega_z \frac{L_0}{I_x}$$

IV 3 con't

(5)

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$$\text{at } t=0, \quad \vec{L} = L_0 \hat{x} = I_x \omega_{x0} / \sqrt{2}$$

$$\Rightarrow \omega_{x0} = \frac{L_0}{MR^2 / \sqrt{2}}$$

$$\dot{\omega}_x = 0 \Rightarrow \omega_x \text{ remain constant}$$

$$3\dot{\omega}_y + \omega_z \omega_{x0} = 0$$

$$3\dot{\omega}_z + \omega_y \omega_{x0} = 0$$

$$3\ddot{\omega}_z + \dot{\omega}_y \omega_{x0} = 0$$

$$\omega_z(0) = 0$$

$$\omega_y(0) = \frac{L_0}{\sqrt{2} MR^2}$$

$$-\frac{3\ddot{\omega}_z}{\omega_{x0}} = \dot{\omega}_y$$

$$\Rightarrow \omega_y(t) = \omega_y(0) \cos \frac{\omega_{x0}}{3} t$$

and

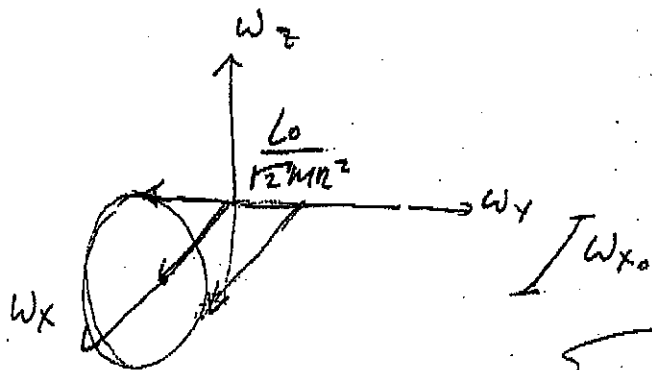
$$\Rightarrow 3 \left( -\frac{3\ddot{\omega}_z}{\omega_{x0}} \right) - \omega_z \omega_{x0} = 0$$

$$\ddot{\omega}_z + \frac{\omega_{x0}^2}{9} \omega_z = 0$$

$$\Rightarrow \omega_z(t) = \omega_z(0) \cos \frac{\omega_{x0}}{3} t$$

$$\ddot{\omega}_y + \frac{\omega_{x0}^2}{9} \omega_y = 0 \Rightarrow \omega_y(t) = \frac{L_0}{\sqrt{2} MR^2} \cos \left( \frac{\omega_{x0}}{3} t \right)$$

$$\omega_z(t) = \frac{L_0}{\sqrt{2} MR^2} \sin \left( \frac{\omega_{x0}}{3} t \right)$$



$\vec{\omega}$  precesses around  $\hat{x}$  with frequency

$$\frac{L_0}{\sqrt{2} MR^2}; \omega_x = \frac{L_0}{\sqrt{2} MR^2}$$

# Soln IV-4 Relativity

$$(a) \quad E^2 = p^2 c^2 + m^2 c^4$$

$$E_{\pi} = m_{\pi} c^2$$

$$E_{\mu} = c \sqrt{m_{\mu}^2 c^2 + p_{\mu}^2}$$

$$E_{\nu} = |p_{\nu}| c = |p_{\mu}| c$$

$$m_{\pi} c^2 = c \sqrt{m_{\mu}^2 c^2 + p_{\mu}^2} + |p_{\mu}| c$$

$$(m_{\pi} c - |p_{\mu}|)^2 = m_{\mu}^2 c^2 + p_{\mu}^2$$

$$|p_{\mu}| = \frac{m_{\pi}^2 - m_{\mu}^2}{2 m_{\pi}} = m_{\pi} \gamma v$$

$$(c) \quad E_{\mu} = \frac{m_{\pi}^2 + m_{\mu}^2}{2 m_{\pi}} = m_{\pi} \gamma c^2$$

$$p/E = v/c^2$$

$$\boxed{v = \frac{|p| c^2}{E}} = \frac{m_{\pi}^2 - m_{\mu}^2}{m_{\pi}^2 + m_{\mu}^2} c$$