

Classical Mechanics I: Binary Scattering

$$a) L = \frac{1}{2} M_1 \dot{x}_1^2 + \frac{1}{2} M_2 \dot{x}_2^2 + \frac{1}{2} M_3 \dot{x}_3^2 + \frac{G M_1 M_2}{|x_1 - x_2|} + \frac{G M_1 M_3}{|x_1 - x_3|} + \frac{G M_2 M_3}{|x_2 - x_3|}$$

Now change variables: $(x_1, x_2, x_3) \rightarrow (R, \Gamma, \underline{s})$ where

$$R = M_1 x_1 + M_2 x_2, \Gamma = x_1 - x_2, \underline{s} = x_3 - R$$

$$\Rightarrow x_1 = R + \frac{M_2}{M_1 + M_2} \Gamma, x_2 = R - \frac{M_1}{M_1 + M_2} \Gamma, x_3 = R + \underline{s}.$$

$$\Rightarrow \frac{1}{2} M_1 \dot{x}_1^2 + \frac{1}{2} M_2 \dot{x}_2^2 = \frac{1}{2} (M_1 + M_2) \dot{R}^2 + \frac{1}{2} \mu \dot{\Gamma}^2, \mu \equiv \frac{M_1 M_2}{M_1 + M_2}$$

$$\text{Also, } \frac{1}{|x_1 - x_3|} = \frac{1}{|\underline{s} - \frac{M_2}{M_1 + M_2} \Gamma|} = \frac{1}{s} \left[1 + \frac{M_2}{M_1 + M_2} \frac{\Gamma \cdot \underline{s}}{s^2} + O\left(\frac{\Gamma}{s}\right)^2 \right]$$

$$\frac{1}{|x_2 - x_3|} = \frac{1}{|\underline{s} + \frac{M_1}{M_1 + M_2} \Gamma|} = \frac{1}{s} \left[1 - \frac{M_1}{M_1 + M_2} \frac{\Gamma \cdot \underline{s}}{s^2} + O\left(\frac{\Gamma}{s}\right)^2 \right]$$

$$\Rightarrow L = \frac{1}{2} (M_1 + M_2) \dot{R}^2 + \frac{1}{2} \mu \dot{\Gamma}^2 + \frac{1}{2} M_3 (\dot{R}^2 + 2 \dot{R} \cdot \dot{\underline{s}} + \dot{\underline{s}}^2) + \frac{G M_1 M_2}{r} + \frac{G (M_1 + M_2) M_3}{s} \left[1 + O\left(\frac{\Gamma}{s}\right)^2 \right]$$

Now perform Legendre transformation:

$$P_R \equiv \frac{\partial L}{\partial \dot{R}} = (M_1 + M_2) \dot{R} + M_3 (\dot{R} + \dot{\underline{s}})$$

$$P_\Gamma \equiv \frac{\partial L}{\partial \dot{\Gamma}} = \mu \dot{\Gamma}, \quad P_s \equiv \frac{\partial L}{\partial \dot{\underline{s}}} = M_3 (\dot{R} + \dot{\underline{s}})$$

$$\begin{aligned} h(R, \Gamma, \underline{s}, \dot{R}, \dot{\Gamma}, \dot{\underline{s}}) &\equiv \sum P \dot{q} - L = (M_1 + M_2 + M_3) \dot{R}^2 + 2 M_3 \dot{R} \cdot \dot{\underline{s}} + \mu \dot{\Gamma}^2 + M_3 \dot{\underline{s}}^2 - L \\ &= \frac{1}{2} (M_1 + M_2) \dot{R}^2 + \frac{1}{2} \mu \dot{\Gamma}^2 + \frac{1}{2} M_3 (\dot{R}^2 + 2 \dot{R} \cdot \dot{\underline{s}} + \dot{\underline{s}}^2) \\ &\quad - \frac{G M_1 M_2}{r} - \frac{G (M_1 + M_2) M_3}{s} \left[1 + O\left(\frac{\Gamma}{s}\right)^2 \right] \end{aligned}$$

$$\text{Now Solve } P(q, \dot{q}) \rightarrow \dot{q}(P, q): \quad \dot{R} = \frac{P_R - P_s}{M_1 + M_2}, \quad \dot{\Gamma} = \frac{P_\Gamma}{\mu}, \quad \dot{\underline{s}} = \frac{P_s}{M_3} + \frac{P_s - P_R}{M_1 + M_2}$$

$$\Rightarrow H(R, \Gamma, \underline{s}, P_R, P_\Gamma, P_s) = h(R, \Gamma, \underline{s}, \dot{R}(P_R), \dot{\Gamma}(P_\Gamma), \dot{\underline{s}}(P_s))$$

$$= \frac{1}{2} \frac{|P_R - P_s|^2}{(M_1 + M_2)^2} + \frac{P_\Gamma^2}{2\mu} + \frac{P_s^2}{2M_3} - \frac{G M_1 M_2}{r} - \frac{G (M_1 + M_2) M_3}{s} \left[1 + O\left(\frac{\Gamma}{s}\right)^2 \right]$$

Classical Mechanics I, continued.

- b) Note $H = H_r(r, p_r) + H_s(R, \epsilon, p_R, p_s)$ is separable where $H_r = \frac{p_r^2}{2\mu} - \frac{GM_1 M_2}{r}$ \therefore can solve for r -motion independent of R and ϵ . H_r is the Hamiltonian for the Kepler problem, \therefore the trajectories are conic sections $r(\phi) = \frac{a(1-e^2)}{1+e\cos\phi}$.

At $\phi=0$ and $\phi=\pi$ the motion is entirely tangential,

$$p_r = \frac{L}{r} e_\phi \text{ for } r = a(1 \pm e)$$

$$\therefore E = H_r = \frac{p_r^2}{2\mu} - \frac{GM_1 M_2}{r} = \frac{L^2}{2\mu r^2} - \frac{GM_1 M_2}{r} \text{ for } r = a(1 \pm e)$$

$$\Rightarrow r^2 + \frac{2GM_1 M_2}{E} r - \frac{L^2}{2\mu E} = 0 \Rightarrow r = -\left(\frac{GM_1 M_2}{2E}\right) \pm \left[\left(\frac{GM_1 M_2}{2E}\right)^2 + \frac{L^2}{2\mu E}\right]^{1/2}$$

$$\Rightarrow \boxed{a = -\frac{GM_1 M_2}{2E}, e = \left[1 + \frac{2EL^2}{\mu(GM_1 M_2)^2}\right]^{1/2}}$$

- c) $\frac{\partial H}{\partial R} = 0 \Rightarrow \frac{d p_R}{dt} = 0$ where $p_R = (M_1 + M_2)\dot{R} + M_3(\dot{R} + \dot{\epsilon}) = M_1 \dot{x}_1 + M_2 \dot{x}_2 + M_3 \dot{x}_3$
 $\therefore R$ -motion is simple; choose $p_R = 0$ without loss of generality.

$$\Rightarrow H_s = \frac{p_s^2}{2\mu_s} - \frac{G(M_1 + M_2)M_3}{s} \text{ where } \boxed{\frac{1}{\mu_s} = \frac{1}{M_1 + M_2} + \frac{1}{M_3}}$$

This has the same form as H_r , therefore the s -motion is also Keplerian. Explicitly,

$$\frac{dp_s}{dt} = -\frac{\partial H}{\partial s} = -\frac{G(M_1 + M_2)M_3}{s^2} \underline{s}; p_s = \mu_s \dot{s} \Rightarrow \frac{dp_s}{dt} = \mu_s \ddot{s}$$

$$\Rightarrow \frac{d^2 s}{dt^2} = -\frac{G(M_1 + M_2 + M_3)}{s^2} \underline{s}$$

We can get the Kepler parameters a_s and e_s by comparing $E_s = H_s(p_R=0)$ with part b).

$$\therefore \boxed{a_s = -\frac{G(M_1 + M_2)M_3}{2E_s}, e_s = \left[1 + \frac{2E_s L_s^2}{\mu_s (G(M_1 + M_2)M_3)^2}\right]^{1/2}}$$

$$[\text{note } (M_1 + M_2)M_3 = (M_1 + M_2 + M_3)\mu_s]$$

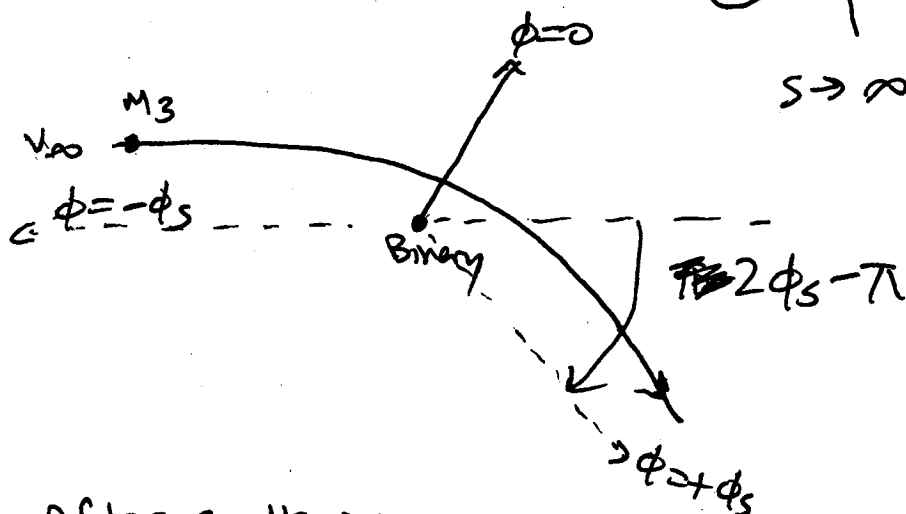
Classical Mechanics I, continued

d) Initially, $\dot{\underline{S}} = v_{\infty} \underline{e}_x$ (\underline{e}_x is arbitrary) $\Rightarrow \underline{r}_S = \mu_S v_{\infty} \underline{e}_x$.

$$S(\phi) = \frac{a_s(1-e_s^2)}{1+e_s \cos \phi}$$



$$S \rightarrow \infty \Rightarrow \cos \phi_s = -\frac{1}{e_s}$$



After scattering,

$$\dot{\underline{S}} = v_{\infty} [\underline{e}_x \cos(2\phi_s - \pi) - \underline{e}_y \sin(2\phi_s - \pi)]$$

$$\cos(2\phi_s - \pi) = -\cos 2\phi_s = 1 - 2\cos^2 \phi_s = 1 - \frac{2}{e_s^2}$$

$$\sin(2\phi_s - \pi) = -\sin 2\phi_s = -2\sin \phi_s \cos \phi_s = \frac{2}{e_s} \sqrt{1 - \frac{1}{e_s^2}}$$

$$\therefore \Delta \underline{r}_S = \underline{r}_S(t \rightarrow \infty) - \underline{r}_S(t \rightarrow -\infty) = \mu_S v_{\infty} \left[-\frac{2}{e_s^2} \underline{e}_x - \frac{2}{e_s} \sqrt{1 - \frac{1}{e_s^2}} \underline{e}_y \right]$$

This impulse is given to the binary:

$$\Delta(M_1 \dot{\underline{x}}_1 + M_2 \dot{\underline{x}}_2) = (M_1 + M_2) \Delta \dot{\underline{B}} = -\Delta \underline{r}_S$$

\therefore the binary recoils (in its initial rest frame) with velocity

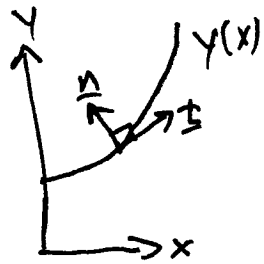
$$\dot{\underline{B}} = \frac{-\Delta \underline{r}_S}{M_1 + M_2} = \frac{2\mu_S v_{\infty}}{M_1 + M_2} \left[\frac{1}{e_s^2} \underline{e}_x + \frac{1}{e_s} \sqrt{1 - \frac{1}{e_s^2}} \underline{e}_y \right]$$

\therefore the final speed is

$$\dot{R} = \frac{2\mu_S v_{\infty}}{M_1 + M_2} \cdot \frac{1}{e_s} = \frac{2\mu_S v_{\infty}}{e_s (M_1 + M_2)} = \boxed{\frac{2M_3 v_{\infty}}{e_s (M_1 + M_2 + M_3)}}$$

Classical Mechanics II: Rolling Disk

Will need tangent and normal vectors to the curve:



$$\underline{t} = \frac{dx}{ds} \underline{e}_x + \frac{dy}{ds} \underline{e}_y, \quad ds = dx \sqrt{1 + (dy/dx)^2}$$

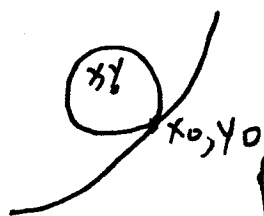
$$y = a \cosh(x/a) \Rightarrow \frac{dy}{dx} = \sinh(x/a) \Rightarrow ds = dx \cosh(x/a)$$

$$\Rightarrow \underline{t} = \frac{1}{\cosh(x_0/a)} \underline{e}_x + \tanh(x_0/a) \underline{e}_y \equiv t_x \underline{e}_x + t_y \underline{e}_y,$$

$$\underline{n} = -t_y \underline{e}_x + t_x \underline{e}_y$$

- a) Need to express (x, y) on curve to ϕ : rolling without slipping $\Rightarrow ds = R d\phi \Rightarrow R\phi = \int_0^{x_0} dx \cosh(x/a) = a \sinh(x_0/a)$
 $\phi = \frac{a}{R} \sinh(x_0/a), \quad x_0 = a \sinh^{-1}(\frac{R\phi}{a}), \quad y_0 = a \cosh(x_0/a) = \sqrt{a^2 + R^2 \phi^2}.$

Use subscript 0 to denote coordinates of contact point.



$$\underline{x} = \underline{x}_0 + \underline{n} R \quad t_x = \frac{1}{\cosh(x_0/a)} = \frac{a}{y_0} = \frac{a}{\sqrt{a^2 + R^2 \phi^2}}$$

$$t_y = \frac{\sinh(x_0/a)}{\cosh(x_0/a)} = \frac{R\phi}{a} t_x = \frac{R\phi}{\sqrt{a^2 + R^2 \phi^2}}$$

\Rightarrow The center of the disk has coordinates

$$\boxed{\begin{aligned} x &= x_0 + R n_x = x_0 - R t_y = a \sinh^{-1}\left(\frac{R\phi}{a}\right) - \frac{R^2 \phi}{\sqrt{a^2 + R^2 \phi^2}} \\ y &= y_0 + R n_y = y_0 + R t_x = \sqrt{a^2 + R^2 \phi^2} + \frac{a R}{\sqrt{a^2 + R^2 \phi^2}} \end{aligned}}$$

b) $L = \frac{1}{2} M (\dot{x}^2 + \dot{y}^2) + \frac{1}{2} I \dot{\phi}^2 - mgy$; $\dot{x} = \frac{dx}{d\phi} \dot{\phi}$, $\dot{y} = \frac{dy}{d\phi} \dot{\phi}$, $I = \frac{1}{2} MR^2$

$$\phi = \frac{a}{R} \sinh \frac{x_0}{a} \Rightarrow \frac{d\phi}{dx_0} = \frac{1}{R} \cosh \frac{x_0}{a} = \frac{y_0}{aR} = \frac{\sqrt{a^2 + R^2 \phi^2}}{aR}$$

$$\Rightarrow \frac{dx}{d\phi} = \frac{aR}{\sqrt{a^2 + R^2 \phi^2}} - \frac{R^2}{\sqrt{a^2 + R^2 \phi^2}} + \frac{R^4 \phi^2}{(a^2 + R^2 \phi^2)^{3/2}} = \frac{aR}{\sqrt{a^2 + R^2 \phi^2}} \left[1 - \frac{aR}{a^2 + R^2 \phi^2} \right]$$

$$\frac{dy}{d\phi} = \frac{R^2 \phi}{\sqrt{a^2 + R^2 \phi^2}} \left[1 - \frac{aR}{a^2 + R^2 \phi^2} \right] \Rightarrow \left(\frac{dx}{d\phi} \right)^2 + \left(\frac{dy}{d\phi} \right)^2 = R^2 D^2$$

$$\Rightarrow \boxed{\begin{aligned} L &= \frac{1}{2} MR^2 \dot{\phi}^2 (D^2 + \frac{1}{2}) - mg \left(\sqrt{a^2 + R^2 \phi^2} + \frac{aR}{\sqrt{a^2 + R^2 \phi^2}} \right) \\ D &\equiv 1 - \frac{aR}{a^2 + R^2 \phi^2} \end{aligned}}$$

Classical Mechanics II - continued

c) For $R^2 \phi^2 \ll a^2$, $D \approx D_0 \equiv 1 - \frac{R}{a}$, and

$$Y \approx a \left(1 + \frac{1}{2} \frac{R^2 \phi^2}{a^2}\right) + R \left(1 - \frac{1}{2} \frac{R^2 \phi^2}{a^2}\right) = a + R + \frac{1}{2} \frac{R^2 \phi^2}{a} D_0$$

$$\Rightarrow L \approx \frac{1}{2} M R^2 (D_0^2 + \frac{1}{2}) \dot{\phi}^2 - mg(a+R) - \frac{1}{2} mg \frac{R^2 D_0}{a} \phi^2$$

or $L = \frac{1}{2} A \dot{\phi}^2 - \frac{1}{2} B \phi^2 + \text{constant}$, simple harmonic oscillator

$$A \ddot{\phi} = -B \phi \Rightarrow \boxed{\omega^2} = \frac{B}{A} = \frac{mg R^2 D_0}{\frac{1}{2} M R^2 (D_0^2 + \frac{1}{2})} = \frac{g}{a} \frac{D_0}{D_0^2 + \frac{1}{2}}, D_0 = 1 - \frac{R}{a}$$

d) $m \ddot{\mathbf{x}} = -mg \mathbf{e}_y + N \mathbf{n} + T \mathbf{t}$ where N, T = normal and tangential contact forces

$$\ddot{\mathbf{x}} = \frac{d}{dt} \left(\frac{d\mathbf{x}}{d\phi} \dot{\phi} \right) = \frac{d\mathbf{x}}{d\phi} \ddot{\phi} + \frac{d^2\mathbf{x}}{d\phi^2} \dot{\phi}^2 \quad (\dot{\phi} \neq 0)$$

$$\ddot{\mathbf{y}} = \frac{d}{dt} \left(\frac{d\mathbf{y}}{d\phi} \dot{\phi} \right) = \frac{d\mathbf{y}}{d\phi} \ddot{\phi} + \frac{d^2\mathbf{y}}{d\phi^2} \dot{\phi}^2$$

$$m \ddot{\mathbf{x}} = n_x N + t_x T = -t_y N + t_x T$$

$$m \ddot{\mathbf{y}} = n_y N + t_y T - mg = t_x N + t_y T - mg$$

$$\begin{pmatrix} -t_y & t_x \\ t_x & t_y \end{pmatrix} \begin{pmatrix} N \\ T \end{pmatrix} = m \begin{pmatrix} \ddot{\mathbf{x}} \\ \ddot{\mathbf{y}} + g \end{pmatrix} = m \begin{pmatrix} \frac{d\mathbf{x}}{d\phi} \ddot{\phi} \\ \frac{d\mathbf{y}}{d\phi} \ddot{\phi} + g \end{pmatrix}. \quad \begin{pmatrix} -t_y & t_x \\ t_x & t_y \end{pmatrix}^{-1} = \begin{pmatrix} -t_y & t_x \\ t_x & t_y \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} N \\ T \end{pmatrix} = m \begin{pmatrix} -t_y & t_x \\ t_x & t_y \end{pmatrix} \begin{pmatrix} \frac{d\mathbf{x}}{d\phi} \ddot{\phi} \\ \frac{d\mathbf{y}}{d\phi} \ddot{\phi} + g \end{pmatrix} \quad t_x = \frac{a}{\sqrt{a^2 + R^2 \phi^2}}, t_y = \frac{R \phi}{\sqrt{a^2 + R^2 \phi^2}}$$

$$\frac{N}{m} = - \frac{a^2 R^2 \phi D}{a^2 + R^2 \phi^2} \ddot{\phi} + \frac{a R^2 \phi D}{a^2 + R^2 \phi^2} \ddot{\phi} + \frac{a g}{\sqrt{a^2 + R^2 \phi^2}} = \frac{g a}{\sqrt{a^2 + R^2 \phi^2}}$$

$$\frac{T}{m} = \frac{a^2 R D}{a^2 + R^2 \phi^2} \ddot{\phi} + \frac{R^3 \phi^2 D}{a^2 + R^2 \phi^2} \ddot{\phi} + \frac{g R \phi}{\sqrt{a^2 + R^2 \phi^2}} = R D \ddot{\phi} + \frac{g R \phi}{\sqrt{a^2 + R^2 \phi^2}}$$

Now, for $R \phi \ll a$, $\ddot{\phi} = -\omega^2 \phi$ with ω^2 from part c) above

$$\Rightarrow \frac{T}{m} = R \phi \left(\frac{g}{a} - \omega^2 D_0 \right) = \frac{g}{a} R \phi \left(1 - \frac{D_0^2}{D_0^2 + \frac{1}{2}} \right) = \frac{g}{a} \frac{R \phi}{2 D_0^2 + 1}$$

$$\therefore \boxed{N \approx mg \left(1 - \frac{1}{2} \frac{R^2 \phi^2}{a^2} \right), T \approx mg \frac{R}{a} \frac{\phi}{2 D_0^2 + 1} \left[1 + O\left(\frac{R^2 \phi^2}{a^2}\right) \right]}$$

$$[D_0 = 1 - \frac{R}{a}]$$

e) The disk slips if $T > \mu N$

$$mg \frac{R}{a} \frac{\phi}{2 D_0^2 + 1} > \frac{1}{2} mg \quad \text{or} \quad \frac{R \phi}{a} > D_0^2 + \frac{1}{2}$$

Since we assume $\frac{R \phi}{a} \ll 1$, the disk will not slip.

Electromagnetism : Electromagnetic waves E. Bertschinger

a) $\partial^\nu F_{\mu\nu} = \partial^\nu (\partial_\mu A_\nu - \partial_\nu A_\mu) = \partial_\mu (\partial^\nu A_\nu) - \square A_\mu = -4\pi J_\mu$

Applying the Lorentz gauge condition $\partial^\nu A_\nu = \partial_\nu A^\nu = 0$ gives the desired wave equation $\square A^\mu = +4\pi J^\mu$

The Lorentz gauge condition does not completely fix A_μ because we can add $\partial_\mu \psi$ where $\psi(x)$ is a scalar field

satisfying $\square \psi = 0$. Adding this term has no effect on the Lorentz gauge condition $[\partial^\nu (A_\nu + \partial_\nu \psi)] = \partial^\nu A_\nu + \square \psi$ or on the electromagnetic field: $F_{\mu\nu} = \partial_\mu (A_\nu + \partial_\nu \psi) - \partial_\nu (A_\mu + \partial_\mu \psi) = \partial_\mu A_\nu - \partial_\nu A_\mu$

b) The point charge corresponds to a current density

$$J^\mu(x, t) = (q, q \underline{v}_q) \delta^3(\underline{x} - \underline{x}_q(t)) \text{ where } \underline{v}_q = d\underline{x}_q/dt$$

In the radiative solution, we cannot immediately use the delta function, because t_r depends on \underline{x} , hence $\underline{x}_q(t_r)$ depends on \underline{x} . We work around this problem by introducing another integral (time) with its own delta function

$$A^\mu = q \int d^3x' \frac{(1, \underline{v}_q)}{|\underline{x} - \underline{x}'|} \delta^3(\underline{x}' - \underline{x}_q(t_r)) , \quad t_r = t - |\underline{x} - \underline{x}'|$$

$$= q \int dt' \int d^3x' \frac{(1, \underline{v}_q(t'))}{|\underline{x} - \underline{x}'|} \delta^3(\underline{x}' - \underline{x}_q(t')) \delta(t' - t + |\underline{x} - \underline{x}'|)$$

$$= q \int dt' \frac{(1, \underline{v}_q(t'))}{|\underline{x} - \underline{x}_q(t')|} \delta(t' - t + |\underline{x} - \underline{x}_q(t')|) \quad \text{Now we can } \int d^3x' !$$

Now we use the relation $\delta(f(t')) = \frac{1}{|df/dt'|} \delta(t' - \dots)$

$$\text{with } \frac{d}{dt'} [t' - t + |\underline{x} - \underline{x}_q(t')|] = 1 - \underline{n} \cdot \underline{v}_q(t'), \quad \underline{n} \equiv \frac{\underline{x} - \underline{x}_q(t')}{|\underline{x} - \underline{x}_q(t')|}$$

$$\downarrow$$

$$A^\mu = \left[\frac{q(1, \underline{v}_q)}{|\underline{x} - \underline{x}_q| (1 - \underline{n} \cdot \underline{v}_q)} \right]_{\text{ret}} = \left[\frac{q(1, \underline{v}_q)}{R - \underline{B} \cdot \underline{v}_q} \right]_{\text{ret}}, \quad \underline{B} \equiv \underline{x} - \underline{x}_q$$

ret means evaluate \underline{x}_q and \underline{v}_q at retarded time.

E & M

Problem 1

a) Start w. Maxwell eqs inside the waveguide

$$\nabla \cdot \mathbf{E} = 0$$

$$\nabla \cdot \mathbf{B} = 0$$

$$\nabla \times \mathbf{E} = -\frac{1}{c} \dot{\mathbf{B}}$$

$$\nabla \times \mathbf{B} = \frac{1}{c} \dot{\mathbf{E}}$$

Looking for solutions of the form
 $\mathbf{E}, \mathbf{B} \propto e^{-i\omega t + i k x} \mathbf{f}(x)$

Consider TE modes, $E_{||} = 0$

$$\nabla \times (\nabla \times \mathbf{B}) = \frac{1}{c} \nabla \times \dot{\mathbf{E}} = -\frac{1}{c^2} \ddot{\mathbf{B}}$$

$$\nabla(\nabla \cdot \mathbf{B}) - \nabla^2 \mathbf{B} = \frac{\omega^2}{c^2} \mathbf{B}$$

• for $B_{||}$ have $\nabla_{\perp}^2 B_{||} = \left(k^2 - \frac{\omega^2}{c^2}\right) B_{||}$

Boundary condition $\frac{\partial B_{||}}{\partial n}$ follows from the property of ideal conductor, $E_{||} = 0$ together with $\frac{1}{c} \dot{\mathbf{E}} = \nabla \times \mathbf{B}$

For TM modes, similarly, have $\nabla_{\perp}^2 E_{||} = \left(k^2 - \frac{\omega^2}{c^2}\right) E_{||}$ with boundary condition $E_{||} = 0$

To prove that this exhausts all modes, suppose that $E_{||} = B_{||} = 0$. Then, from Maxwell eqs, $\mathbf{E}_{\perp} = \nabla_{\perp} \Phi$, $\nabla_{\perp}^2 \Phi = 0 \rightarrow \Phi = 0$ and similarly, $B_{\perp} = 0$

Solution

Quantum Mechanics Hydrogen Like Atoms

1

a) $\vec{L}\psi = 0$

$$-\frac{\hbar^2}{2m} \left(\frac{\partial^2}{\partial r^2} + \frac{2}{r} \frac{\partial}{\partial r} \right) e^{-\beta r} - \frac{e^2}{r} e^{-\beta r} = E e^{-\beta r}$$

$$-\frac{\hbar^2}{2m} \left(\beta^2 - \frac{2\beta}{r} \right) - \frac{e^2}{r} = E$$

$$E = -\frac{\hbar^2}{2m} \beta^2 \quad \frac{\hbar^2}{m} \beta = e^2$$

$$\text{so } \beta = \frac{me^2}{\hbar^2} \quad E = -\frac{\hbar^2}{2m} \frac{me^4}{\hbar^4} = -\frac{1}{2} \frac{me^4}{\hbar^2}$$

b) $\psi = N e^{-\beta r}$

$$1 = 4\pi N^2 \int_0^{\infty} e^{-2\beta r} r^2 dr$$

$$1 = 4\pi N^2 \frac{2}{(2\beta)^3} \quad 1 = \frac{\pi N^2}{\beta^3} \quad N = \left(\frac{\beta^3}{\pi} \right)^{1/2}$$

$$\beta_T = \frac{me^2}{\hbar^2} \quad \beta_{He} = 2 \frac{me^2}{\hbar^2}$$

$$B_T = B$$

$$B_{He} = 2B$$

Solution

2

$$\psi_T(r) = \left(\frac{\beta_T^3}{\pi} \right)^{1/2} e^{-\beta_T r} = \left(\frac{\beta^3}{\pi} \right)^{1/2} e^{-\beta r}$$

$$\psi_{He}(r) = \left(\frac{\beta_{He}^3}{\pi} \right)^{1/2} e^{-\beta_{He} r} = \left(\frac{8\beta^3}{\pi} \right)^{1/2} e^{-2\beta r}$$

$$\text{Overlap} = 4\pi \int_0^\infty r^2 dr \left(\frac{\beta^3}{\pi} \right)^{1/2} \left(\frac{8\beta^3}{\pi} \right)^{1/2} e^{-3\beta r}$$

$$= 4 \cdot 8^{1/2} \beta^3 \int_0^\infty r^2 dr e^{-3\beta r}$$

$$= 4 \cdot 8^{1/2} \beta^3 \frac{2}{(3\beta)^3} = \frac{8 \cdot 8^{1/2}}{3^3}$$

$$\text{probability} = \frac{8^3}{3^6} = .7023$$

$$c) \quad L^2 Y_m^1 = 2\hbar^2 Y_m^1$$

~~$$\frac{\hbar^2}{2m} \frac{d^2}{dr^2} \left(\frac{1}{r} \right) + \frac{\hbar^2}{2m} \frac{d^2}{dr^2} \left(\frac{1}{r} \right) e^{-\beta r} = E \left(\frac{1}{r} \right) e^{-\beta r}$$~~

~~$$\frac{\hbar^2}{2m} \frac{d^2}{dr^2} \left(\frac{1}{r} \right) + \frac{\hbar^2}{2m} \frac{d^2}{dr^2} \left(\frac{1}{r} \right) e^{-\beta r} = E \left(\frac{1}{r} \right) e^{-\beta r}$$~~

$$\left(-\frac{\hbar^2}{2m} \left(\frac{\partial^2}{\partial r^2} + \frac{2}{r} \frac{\partial}{\partial r} \right) + \frac{1}{2m} \frac{1}{r^2} \right) r e^{-\tilde{\beta} r} - \frac{e^2}{r} r e^{-\tilde{\beta} r} = E r e^{-\tilde{\beta} r}$$

$$-\frac{\hbar^2}{2m} \left(-2\tilde{\beta} + r\tilde{\beta}^2 + \frac{2}{r} (1 - \tilde{\beta}r) \right) + \frac{\hbar^2}{mr} - e^2 = Er$$

$$\frac{1}{r} : -\frac{\hbar^2}{m} + \frac{\hbar^2}{m} = 0 \quad \checkmark$$

$$r^0 : 2\frac{\hbar^2}{m} \tilde{\beta} - e^2 = 0 \quad \tilde{\beta} = \frac{me^2}{2\hbar^2}$$

$$E = -\frac{\hbar^2}{2m} \tilde{\beta}^2 = -\frac{\hbar^2}{2m} \frac{m^2 e^4}{4\hbar^4} = -\frac{me^4}{8\hbar^2}$$

Quantum Mechanics II Solution

a) Expand $|\psi\rangle$ in the energy eigenstates

$$|\psi\rangle = \sum_a \langle E_a | \psi \rangle |E_a\rangle$$

$$\langle \psi | H | \psi \rangle = \sum_a E_a |\langle E_a | \psi \rangle|^2$$

$$p_a \equiv |\langle E_a | \psi \rangle|^2 \quad \sum_a p_a = 1 \quad p_a \geq 0$$

$$\langle \psi | H | \psi \rangle = \sum_a p_a E_a = \text{average } E$$

average is always bigger than smallest

$$E_0 \leq \langle \psi | H | \psi \rangle$$

b) $\psi(x) = N \sin(\pi x/L) \quad 0 \leq x \leq L$

$$N^2 \int_0^L \sin^2 \frac{\pi x}{L} dx = N^2 \frac{L}{2} = 1 \quad N = \sqrt{\frac{2}{L}}$$

$$\psi(x) = \sqrt{\frac{2}{L}} \sin(\pi x/L)$$

$$\langle \psi | H | \psi \rangle = \langle \psi | H_0 | \psi \rangle + \langle \psi | V | \psi \rangle$$

ψ is an eigenstate of H_0

$$\langle \psi | H_0 | \psi \rangle = \frac{\hbar^2}{2m} \frac{\pi^2}{L^2}$$

$$\langle \psi | V | \psi \rangle = \int_a^L V_0 \frac{2}{L} \sin^2\left(\frac{\pi x}{L}\right) dx$$

$$\frac{\pi x}{L} = y$$

$$\langle \psi | V | \psi \rangle = \frac{2V_0}{L} \int_{\frac{\pi a}{L}}^{\pi} \sin^2 y \frac{L dy}{\pi} = \frac{2V_0}{\pi} \int_{\frac{\pi a}{L}}^{\pi} \sin^2 y dy$$

$$\langle \psi | H | \psi \rangle = \frac{\hbar^2}{2m} \frac{\pi^2}{L^2} + \frac{2V_0}{\pi} \int_{\frac{\pi a}{L}}^{\pi} \sin^2 y dy$$

$$\text{Take } \frac{d}{dL} : -\frac{\hbar^2 \pi^2}{m L^3} + \frac{2V_0}{\pi} \left(-\sin^2 \frac{\pi a}{L} \right) \left(-\frac{\pi a}{L^2} \right) = 0$$

3.

$$\frac{\hbar^2 \pi^2}{mL} = 2V_0 a \sin^2\left(\frac{\pi a}{L}\right)$$

$$L = a + \Delta$$

$$\frac{\hbar^2 \pi^2}{2mV_0 a (a + \Delta)} = \sin^2\left(\frac{\pi}{1 + \Delta/a}\right)$$

$$\approx \sin^2 \pi (1 - \Delta/a)$$

$$\frac{\hbar^2 \pi^2}{2mV_0 a^2} \approx \frac{\pi \Delta}{a}$$

$$\Delta \approx \frac{\hbar^2 \pi}{2ma V_0}$$

$$\langle \psi | H | \psi \rangle = \frac{\hbar^2 \pi^2}{2mL^2} + \frac{2V_0}{\pi} \int_{\frac{\pi a}{L}}^{\pi} \sin^2 y \, dy$$

$$\frac{\pi a}{L} = \frac{\pi}{1 + \Delta/a} \approx \pi (1 - \Delta/a)$$

\int is of order Δ^3

$$\frac{\hbar^2 \pi^2}{2m(a+\Delta)^2} = \frac{\hbar^2 \pi^2}{2ma^2} \frac{1}{(1+\Delta/a)^2}$$

$$\approx \frac{\hbar^2 \pi^2}{2ma^2} \left(1 - \frac{2\Delta}{a}\right)$$

PHYSICAL ADSORPTION

FIRST DO THE BULK GAS. USE $N_{\text{BULK}} = N$ FOR BREVITY

$$\epsilon = \frac{p_x^2 + p_y^2 + p_z^2}{2m}$$

$$Z(N, T, V) = \frac{1}{N! (\hbar)^{3N}} \left[\int_{-\infty}^{\infty} e^{-\frac{p_x^2}{2mkT}} dp_x \right]^{3N} V^N = \frac{(2\pi mkT)^{\frac{3N}{2}} V^N}{N! (\hbar)^{3N}}$$
$$\sqrt{mkT} \sqrt{2\pi} \underbrace{\frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{-s^2/2} ds}_1$$

USE $N! \approx (N/e)^N$

$$Z(N, T, V) \approx \left\{ \frac{e}{N} \frac{1}{\hbar^3} (2\pi mkT)^{3/2} V \right\}^N$$

$$F = -kT \ln Z = -NkT \ln \left\{ \frac{e}{N} \frac{1}{\hbar^3} (2\pi mkT)^{3/2} \frac{V}{N} \right\}$$

$$\mu = \left. \frac{\partial F}{\partial N} \right|_{T, V} = -kT \ln \left\{ \frac{e}{N} \frac{1}{\hbar^3} (2\pi mkT)^{3/2} \frac{V}{N} \right\} - NkT \underbrace{\frac{\{ \} (-1/N)}{\{ \}}}_{+kT}$$

NOW DO THE SURFACE. AGAIN USE $N_{\text{SURFACE}} = N$ TEMPORARILY

$$\epsilon = -E_0 + \frac{p_x^2 + p_y^2}{2m}$$

$$Z(N, T, A) = \frac{1}{N! \hbar^{2N}} \left[e^{E_0/kT} \underbrace{\left(\int_{-\infty}^{\infty} e^{-p_x^2/2mkT} dp_x \right)^2}_{(2\pi mkT)} A \right]^N$$

$$Z(N, T, A) = \frac{1}{N! \hbar^{2N}} \left[e^{E_0/kT} 2\pi mkT A \right]^N \approx \left\{ \frac{e}{N} (2\pi mkT) \frac{A}{N} e^{E_0/kT} \right\}^N$$

$$F = -kT \ln Z = -NkT \ln \left\{ \frac{e}{h^2} (2\pi mkT) \frac{A}{N} e^{E_0/kT} \right\}^N$$

$$\mu = -kT \ln \left\{ \frac{e}{h^2} (2\pi mkT) \frac{A}{N} e^{E_0/kT} \right\} + kT$$

NOW SET $\mu_{\text{BULK}} = \mu_{\text{SURFACE}}$ AND USE

$$N_{\text{BULK}}/V \equiv n, \quad N_{\text{SURFACE}}/A \equiv \sigma$$

$$\ln \left\{ \frac{e}{h^2} (2\pi mkT)^{3/2} \frac{1}{n} \right\} = \ln \left\{ \frac{e}{h^2} (2\pi mkT) \frac{1}{\sigma} e^{E_0/kT} \right\}$$

$$\frac{1}{h} \sqrt{2\pi mkT} \frac{1}{n} = e^{E_0/kT} \frac{1}{\sigma}$$

$$\underline{\underline{\sigma(n, T) = n e^{\frac{E_0/kT}{\frac{h}{\sqrt{2\pi mkT}}}}}}$$

Tom Greytak

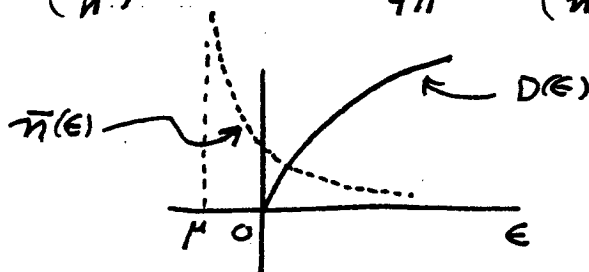
BOSE-EINSTEIN CONDENSATION

a) $D(k) = (2S+1) \frac{V}{(2\pi)^3}$ AND $E = \frac{\hbar^2 k^2}{2m}$

$$\#(\epsilon) = D(k) \frac{4}{3} \pi k^3 = D(k) \frac{4\pi}{3} \left(\frac{2m\epsilon}{\hbar^2} \right)^{3/2}$$

$$D(\epsilon) = \frac{d\#}{d\epsilon} = 2\pi D(k) \left(\frac{2m}{\hbar^2} \right)^{3/2} \epsilon^{1/2} = \frac{2S+1}{4\pi^2} V \left(\frac{2m}{\hbar^2} \right)^{3/2} \epsilon^{1/2}$$

$$\bar{n}(\epsilon) = \frac{1}{e^{\frac{\epsilon - \mu}{kT}} - 1}$$



$$N = \int_0^{\infty} \frac{D(\epsilon)}{e^{(\epsilon - \mu)/kT} - 1} d\epsilon \Rightarrow \mu \leq 0 \text{ OR } \int_0^{\infty} \text{DIVERGES}$$

μ BECOMES PINNED AT $\mu = 0$
AT $T = T_c$

$$N = \frac{2S+1}{4\pi^2} \left(\frac{2m}{\hbar^2} \right)^{3/2} V \int_0^{\infty} \frac{\epsilon^{1/2}}{e^{\epsilon/kT} - 1} d\epsilon = \frac{2S+1}{4\pi^2} \left(\frac{2mkT}{\hbar^2} \right)^{3/2} V \underbrace{\int_0^{\infty} \frac{x^{1/2}}{e^x - 1} dx}_{\equiv I_c}$$

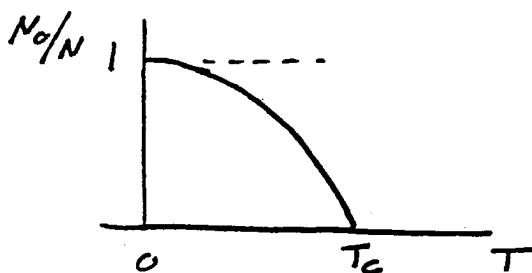
$$\frac{4\pi^2 n}{(2S+1) I_c} = \left(\frac{2mkT_c}{\hbar^2} \right)^{3/2} \Rightarrow \underline{\underline{kT_c = \frac{\hbar^2}{2m} \left(\frac{4\pi^2 n}{(2S+1) I_c} \right)^{2/3}}}$$

NOTE THAT kT_c IS EQUAL TO THE ENERGY OF
A SINGLE PARTICLE WITH A WAVEVECTOR COMPARABLE
TO OVER THE MEAN SPACING BETWEEN PARTICLES

b) BELOW T_c $\bar{n}(\epsilon)$ WITH $\mu=0$ APPLIES TO ALL STATES EXCEPT THE GROUND STATE. THUS

$$N = N_0(T) + \underbrace{\frac{2S+1}{4\pi^2} \left(\frac{2m kT}{\hbar^2} \right)^{3/2} V}_{\frac{n}{\left(\frac{2m kT_c}{\hbar^2} \right)^{3/2}}} I_c \quad \text{FROM LAST LINE IN a)}$$

$$N = N_0(T) + \underbrace{\frac{nV}{N}}_{\left(\frac{T}{T_c} \right)^{3/2}} \Rightarrow \underline{\underline{\frac{N_0(T)}{N} = 1 - \left(\frac{T}{T_c} \right)^{3/2}}}$$



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