UMCPC - Unimelb Competitive Programming Club

Week 4 Thursday Tutorial

Bellman-Ford Algorithm

- What is a graph?
 - (From MAST30011 Graph Theory)
 - A finite graph *G* consists of:
 - A finite set of *vertices* (*nodes*), denoted V(G)
 - A set E(G) of 2-elements subsets of V(G) called edges
 - o An edge {u, v} is denoted uv for short
 - Note that uv = vu denotes the same edge (only on undirected graph)
 - o If e = uv is an edge of a graph then
 - u and v are adjacent
 - e joins u and v
 - e is incident with u and v

Drawings of a graph

- Usually with circle denoting nodes, and line denoting edges
- Shape, size and position of such dots and lines are irrelevant

• Shortest path problem

- o Path A walk of the graph where no vertices are repeated
- Single-source shortest path (SSSP)
 - Computer shortest path from one source to any nodes in the graph
 - Breadth-first search (BFS) Only works on unweighted graph
 - Dijkstra's algorithm (will be taught in COMP20003/COMP20007)
 - **■** Bellman-Ford Algorithm
- o All Pairs Shortest Path
 - Floyd-Warshall Algorithm (will be taught in COMP20003/COMP20007)
- Negative Cycle
 - A cycle where the sum of the edges < 0
 - No *cheapest* path is defined You can loop in the cycle infinitely

Bellman-Ford - Algorithm

- (Run the algorithm on an example graph on board)
 - Example Graph
 Use graph from Algorithms in a Nutshell p.162
- (Show the algorithm in pseudo code from textbooks/wikipedia)

- dist[] array and pred[] array
- Initialization: all dist[] = inf, dist[s] = 0, all pred[] = -1
- Initialization
- Relaxations
- Negative Cycle detection

Bellman-Ford - Correctness

- After *ith* iteration, all nodes with *i* edges in their shortest path solution will have their correct distances computed.
- Every shortest path can only at maximum n 1 edges long
 (or unless there is a negative cycle, in which case the shortest is undefined)
- From above, you computer all shortest path in a graph by a maximum of *n* 1 iterations

• Bellman-Ford - Complexity

- O(V*E)
 - All edge relaxation in one iteration
 - Total of V-1 iterations performed on the graph
 - Hence (V-1)*E edges relaxation, O(V*E)

Early termination

 Can terminate with all values of dist[] remain unchanged after one full relaxation.

• Bellman-Ford v.s. Dijkstra

- Time Complexity
 - **Dijkstra (with Binary Heap) -** O((E+V)logV) More practical in competitions
 - **Dijkstra (with Fibonacci Heap)** O(E+VlogV) Best compelxity
 - Bellman-Ford O(V*E)
- Class of inputs
 - **Dijkstra** *Positive* graph only
 - **Bellman-Ford** Tolerant to *negative edges*, capability of detecting negative cycles

Problems

- https://uva.onlinejudge.org/index.php?option=onlinejudge&page=show_proble m&problem=499
- https://icpcarchive.ecs.baylor.edu/index.php?option=com_onlinejudge&Itemid
 =8&category=714&page=show_problem=5572

pure Bellman-Ford

■ Rough estimation of input complexity for the solution, unsolvable by