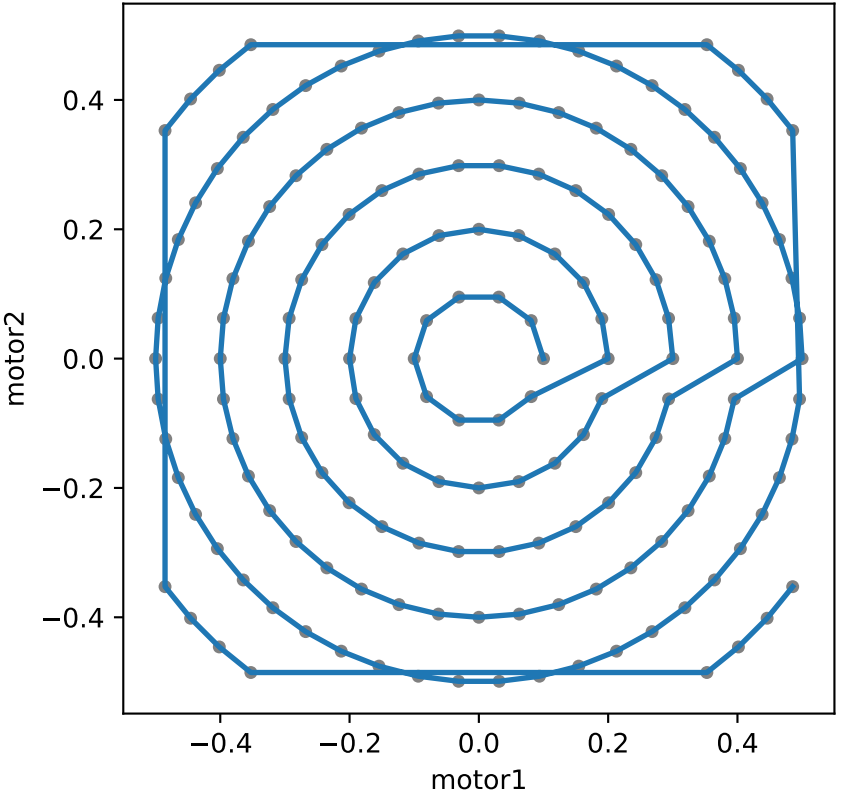
0.4
0.2
0.0
−0.2
−0.4
motor2
−0.4
−0.2
0.0
0.2
0.4
motor1