Cloud simulation

September 9, 2016

Abstract

Simulating the cloud from the client point of view. Assessment of the impact of different metrics. Recommendations for using cloud simulators. WARNING: figures in text might not be up to date.

1 Setup

1.1 Xp traces

 $274~\mathrm{xps}$

1.1.1 Schlouder

1.1.2 Applications

OMSSA (BoT CPU-intensive) and Montage (WF data-intensive). 3 usecases each.

Two differents provisioning Strategies: AFAP and ASAP.

1.1.3 Platform

Openstack-ICPS (private, homogeneous) BonFire (public, heterogeneous)

1.2 Simulations

1.2.1 Simulator

SimSchlouder/SCHIaaS/Simgrid

SimSchlouder reproducing Schlouder runs. Same input/output file.

1.2.2 Lab

1.2.3 Procedure

- 1. Real executions (xp) to test Schlouder and provisioning/scheduling strategies. Schlouder/SimSchlouder input:
 - Nodes: boottime prediction, amount limit, standard power
 - Tasks: walltime prediction

- 2. Normalization of xp traces (4 versions of schlouder, missing data)
- 3. Extraction of information about each xp:
 - Nodes: provisioning date, start date, end date, boottimes, instance type
 - Tasks: submission date, scheduling date, start date, end date, walltime, input time and size, runtime, output time and size, management time
- 4. Simulation of each xp, injecting different information from real xps
- 5. Comparison of Schlouder and SimSchlouder outputs (python)
- 6. Statistical analysis of all traces (R)
- 7. Close analysis of each outlier to understand the differences.

1.2.4 life-cycles and observed times

- Execution: $e \in E$
- Node of execution $e: n \in N_e$
- Task of execution $e: t \in T_e$
- Task handled by node $n: t \in T_n$
- The node running the task t is denoted $n_t \in N$
- v^R denotes the value v in the rality
- v^S denotes the value v in the simulation

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During the execution, the node are in the following states:

- 1. Future: Once the decision to start the node is made;
- 2. Pending: Once the node is requested to the cloud-kit;
- 3. Booting: Once the cloud-kit aknowledge the satisfaction of the request;
- 4. Idle: Once the node is ready to run tasks;
- 5. Busy: Once the node is running one task;
- 6. ShuttingDown: Once the termination of the node is aked to the cloud-kit;
- 7. Terminated: Once the node is terminated.

The observed times are:

- $uptime(n) = terminated_n booting_n$
- $boottime(n) = idle_n booting_n$

During the execution, the task are in the following states, each corresponding to one date:

- 1. Pending: Once they are subitted to the system;
- 2. Scheduled: Once the system decided on which node the taks should be executed:
- 3. Submitted: Once the task is sent to the worker node;
- 4. Inputting: Once the task begin to download its data;
- 5. Running: Once the task begin to computed;
- 6. Outputting: Once the task begin to upload its result;
- 7. Finished: Once the task is finished;
- 8. Complete: Once the system aknowledge the completion of the task.;

The observed times are:

- $walltime(t) = complete_t submitted_t$
- $inputtime(t) = running_t inputting_t$
- $runtime(t) = outputting_t running_t$
- $outputtime(t) = finished_t outputting_t$
- $managementtime(t) = walltime_t (inputtime_t + runtime_t + outputtime_t)$
- or $management time(t) = (input ting_t submitted_t) + (complete_t finished_t)$

2 Results

4 metrics $m \in M$ for each execution $e \in E$:

• uptime: amount of rented resources, cost

$$uptime(e) = \sum_{n \in N_e} uptime_n$$

• makespan: duration of the xp from the submission of the first task to the end of the last task, user experience

$$makespan(e) = max_{t \in T_e} complete_t$$

• usage: runtime / uptime, efficiency of the provisioning

$$usage(e) = \frac{\sum_{t \in T_e} walltime_t}{\sum_{n \in N_e} uptime_n}$$

• schederror: number of tasks that are not assigned to the same node in the simulation compared to the reality, accuracy of the scheduling decisions

$$schederror(e) = |t \forall t \in T/t_n^R \neq t_n^S|$$

Absolute errors are computed for each metric $m \in M$:

$$m.ae(e) = \frac{|m^S(e) - m^R(e)|}{m^R(e)}$$

Results are shown as frequencies and statistics (stat = min, mean, median, max) of absolute errors occurrences. Frequencies are weighted so that the two applications weight the same, and the two platforms weight alos the same (i.e. each couple application \times platform represents 1/4th of the frequencies).

To compare absolute errors between set of simulations S and S' S being the reference:

- $\delta stat(m.ae(E)) = stat_{e \in E}(m.ae^{S'}(e)) stat_{e \in E}(m.ae^{S}(e))$
- $\Delta stat(m.ae(E)) = stat_{e \in E}(m.ae^{S'}(e) m.ae^{S}(e))$

2.1 Simulator accuracy

Best simulation we can do.

Assess the raw simulator accuracy, injecting all real-life hazards that can be captured: boottimes, walltimes and scheduling dates.

Scheduling dates allow to simulate some internal threaded mechanisms of Schlouder. Schlouder uses two threads: the node manager and the task manager. At settled intervals, the node manager interrupts the task manager to start and stop new nodes. This changes the state of nodes, which influence provisioning and scheduling decisions. However, simulating the exact moment of this interruption is utterly difficult, leading to differences between simulation and reality.

- \bullet uptime: 86% show less than 0.05 of absolute error, 92% less than 0.10, 2 simulations exceed 0.30, ranging from 0.00 to 0.50, for a mean of 0.025 and a median of 0.001
- makespan: 76% show less than 0.05 of absolute error, 90% less than 0.10, 0 simulations exceed 0.30, ranging from 0.00 to 0.62, for a mean of 0.042 and a median of 0.018
- usage: 59% show less than 0.05 of absolute error, 91% less than 0.10, 2 simulations exceed 0.30, ranging from 0.00 to 0.60, for a mean of 0.043 and a median of 0.002
- schederror: 70% show less than 0.05 of absolute error, 72% less than 0.10, 59 simulations exceed 0.30, ranging from 0.00 to 0.965, for a mean of 0.155 and a median of 0.000

If global metrics are quite accurately assessed by the simulator, the scheduling decisions can be very different between simulation and reality. One part of the explanation is that scheduling decisions are interdependent: any error leads to several others.

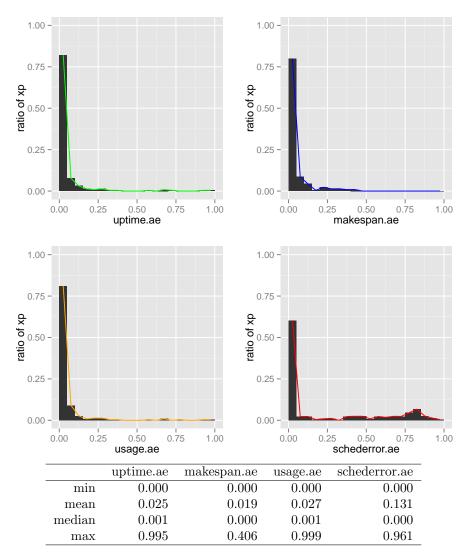


Figure 1: Frequencies and statistics about absolute error of best simulations (274 xp)

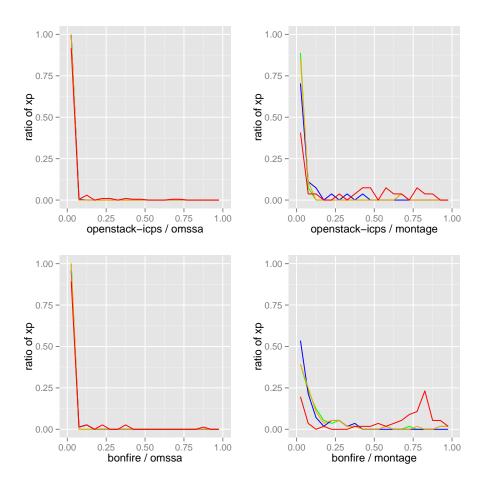


Figure 2: Absolute error frequencies of best simulations according to platforms and applications

2.2 Simulator accuracy according to platforms and applications

• openstack-icps / omssa (107 xp):

	uptime.ae	makespan.ae	usage.ae	schederror.ae
min	0.000	0.000	0.000	0.000
mean	0.001	0.001	0.001	0.024
median	0.000	0.000	0.001	0.000
max	0.029	0.079	0.028	0.749

All metrics are almost perfectly assessed (mean AR from 0.001 to 0.002) except scheduling error (mean 0.04 and max 0.75, 13% of xp show at least one error), leading to small makespan and usage errors.

We looked at each single case of scheduling error and all those errors comes from ambiguities in the scheduling algorithms.

This is a first limitation of simulation: Whenever heuristics lead to several equivalent solutions, the decision is made by the implementation and relies on data structures (e.g. selection of the first encountered suitable solution) or clocks (e.g. the solution differs from a second to the next, which depends on threads activations and timers). While we made sure to use the same structures and timers, some clocks-related events can not be captured nor simulated: Processing the nodes and tasks queues for scheduling and provisioning decisions take time. Consequently, if those decisions rely on clock, they change during the decision process in reality, as clocks advance by itself, but not in simulation, as clocks advance only explicitly.

Thus, the simulation is not mistaken, but only different from reality. Actually, the decisions made by the simulator are exactly those that one can expect, while the decisions made by the real scheduler are sometimes difficult to understand.

Filtering the xps showing clocks-related issues (16 xps), the results are perfect: all metrics present a mean AR of 0.001, and a max of 0.003 for uptimes, 0.011 for makespan, and 0.002 for usage.

The less accurate simulation shows a makespan absolute error of 0.010. Acutally, the makespan of the simulation is 94s, whereas it is 95s in reality. This small difference is due to one lag between two consecutive tasks in the middle of the simulation. Such lags are not captured by our simulation workflow.

This shows that, providing that one can inject the right information, the only limitation of our simulator are micro clock-related hazards.

• openstack-icps / montage (36 xps):

	uptime.ae	makespan.ae	usage.ae	schederror.ae
min	0.000	0.000	0.000	0.000
mean	0.034	0.058	0.043	0.307
median	0.000	0.002	0.011	0.258
max	0.665	0.406	0.664	0.851

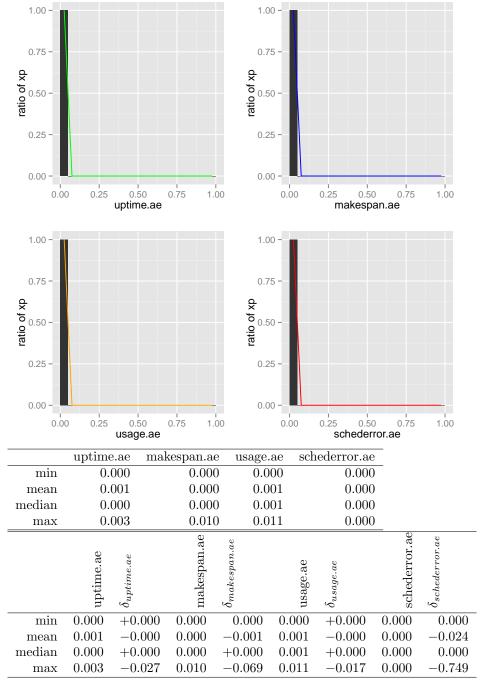


Figure 3: Frequencies and statistics about absolute error of best simulations for openstack-icps / ommssa, without scheduling error cases (91 xps)

	uptime.ae	$\delta_{uptime.ae}$	makespan.ae	$\delta_{makespan.ae}$	usage.ae	$\delta_{usage.ae}$	schederror.ae	$\delta_{schederror.ae}$
min	0.000	+0.000	0.000	+0.000	0.000	+0.000	0.000	0.000
mean	0.034	+0.033	0.058	+0.057	0.043	+0.042	0.307	+0.283
median	0.000	+0.000	0.002	+0.002	0.011	+0.010	0.258	+0.258
max	0.665	+0.635	0.406	+0.327	0.664	+0.636	0.851	+0.102

With a work-flow, scheduling errors are more numerous (AR mean of 0.24 for a max of 0.79), leading to less accurate assessments of uptime, makespan and usage (mean AR of 0.01, 0.05, and 0.01), that is ten times more than with a BoT.

First, montage has much more tasks (from 43 to 1672) than omssa (from 33 to 223). Consequently, queues are much longer, which increases the clock-related issues.

BoT scheduling are actually made offline (i.e. scheduling decisions are taken before any actual execution), while WF scheduling implies decisions during the execution, every time dependencies are satisfied. Those decisions rely on the system state (predicted end date of nodes for instance). Consequently, divergences between simulation and reality have more important impacts.

For instance, the worst case shows a very large amount of scheduling errors (0.954). A close examination of this case shown that the simulation behave as expected: After the first dependencies were satisfied, three newly ready tasks t1, t2, and t3 were scheduled on the node n. However in reality, scheduling takes time. During this time, the last task scheduled to node n was completed between the scheduling of t2 and t3, but before t1 were actually submitted to n. This lead to mistakingly set the state of node n to idle, impacting the scheduling decision of t3.

Those kind of complex and unforeseeable events are actually frequent when confronted to reality. However, they are utterly difficult to detect (1672 jobs were scheduled for the presented case). Comparing real execution with simulation allow the detection of such case, without having to look at each scheduling decision.

the last task assigned to node n was completed during the scheduling of the tasks which dependencies were satisfied first. But those tasks were intended to This completion lead Schlouder to mistake the state of the

• bonfire / omssa (75 xp):

	uptime.ae	makespan.ae	usage.ae	schederror.ae
min	0.000	0.000	0.000	0.000
mean	0.002	0.009	0.005	0.032
median	0.001	0.004	0.004	0.000
max	0.044	0.134	0.047	0.857

	uptime.ae	$\delta_{uptime.ae}$	makespan.ae	$\delta_{makespan.ae}$	usage.ae	$\delta_{usage.ae}$	schederror.ae	$\delta_{schederror.ae}$
min	0.000	+0.000	0.000	+0.000	0.000	+0.000	0.000	0.000
mean	0.002	+0.002	0.009	+0.008	0.005	+0.003	0.032	+0.008
median	0.001	+0.001	0.004	+0.004	0.004	+0.003	0.000	0.000
max	0.044	+0.015	0.134	+0.054	0.047	+0.019	0.857	+0.108

On a public shared heterogeneous cloud, scheduling errors are more numerous (AR mean of 0.03 for a max of 0.86), leading to less accurate assessments of uptime, makespan and usage (mean AR of 0.005, 0.045, and 0.053).

More interesting, usage are never perfectly assessed: 16% of xp show less than 0.05 of AR, while 86% show an AR between 0.05 and 0.10

This show the impacts of public heterogeneous platforms on simulation accuracy: It is not possible to precisely simulate the vm-to-pm scheduling algorithm of public cloud, as they are generally not public, and their decisions impacts performances, as one can not predict the power of the VM one get.

• bonfire / montage (56 xp):

	uptime	ae mal	kespan.a	e usage.	ae sch	ederror.ae)	
min	0.000		0.00	0.001 0.00		0.000		
mean	0.1	138	0.082		39	0.572		
median	0.0	081	$0.048 \qquad 0.07$		78	0.742		
max	0.0	995	0.375 0.99		99	0.961		
	uptime.ae	$\delta_{uptime.ae}$	makespan.ae	$\delta_{makespan.ae}$	usage.ae	$\delta_{usage.ae}$	schederror.ae	$\delta_{schederror.ae}$
min	0.000	+0.000	0.000	+0.000	0.000	+0.000	0.000	0.000
mean	0.002	+0.002	0.009	+0.008	0.005	+0.003	0.032	+0.008
median	0.001	+0.001	0.004	+0.004	0.004	+0.003	0.000	0.000
max	0.044	+0.015	0.134	+0.054	0.047	+0.019	0.857	+0.108

On a public shared heterogeneous cloud, scheduling errors are even more numerous (AR mean of 0.48 for a max of 0.96), leading to less accurate assessments of uptime, makespan and usage (mean AR of 0.10, 0.115, and 0.48).

This is simply explained by the cumulation of inaccuracies from both platform and applications.

2.3 Boottime impacts

Assessing the impact of efficient boottimes simulation.

Same simulations, without injecting the boottimes observations. Thus, boottimes are only predictions, based on linear regressions of previously observed boottimes.

The worst case show a makespan ae of 0.816 (3141s instead of 17076s). This is due to boottimes on BonFire that were completely of charts: 5 boots were normal (ranging from 232s to 311s), the 17 others ranged from 3281s to 11084s. Whereas BonFire were intended to deliver 22 simultaneous VMs, only 5 were available at the time of the experiment. Instead of refusing the following 17 VMs, the provisioning system of BonFire put them in pending state, waiting for the delivered ones to stop. The VMs being provisioned for one hour, following the 5 normal boots, 5 boots took approximatively 1 hour, then 5 other boots took 2 hours, and 5 another more took 3 hours. Finally, 2 boots took 1 hour after the last dependencies were satsified.

This illustrates that defective clouds can not be efficiently simulated without proper information capture. However, once captured, this kind of defection is perfectly simulated by SchIaaS. Consequently, it can be used to assess behavior and robustness of solutions facing these defections.

Some case are surprisingly improved without the real boot times injection: For instance, one xp shows a real makespan of 25788s, for 35106s with boot times injection and 24266s without.

2.3.1 No-threads

Injection of: real boot times and some times due to Schlouder internal threads, such as lapses after a node become ready and the start of the first job.

Assess the impact of efficient internal threads simulation

2.3.2 Communications

Injection of: real boot times, some times due to Schlouder internal threads, such as lapses after a node become ready and the start of the first job, and, real runtimes and real data size for jobs input and output communications.

Assess the impact of efficient communications

2.3.3 Prediction

Injection of nothing from the real xp, except the xp description as submitted to schlouder.

Assess the efficiency of using a simulator as a predictor of a cloud.

3 Open-science

```
git clone https://git.unistra.fr/gossa/schlouder-traces.git
git clone https://scm.gforge.inria.fr/anonscm/git/schiaas/schiaas.git
cd schiaas
cmake .
make
cd lab
./lap.py -p2 setup/simschlouder/validation.cfg
cd setup/simschlouder/validation-results
```

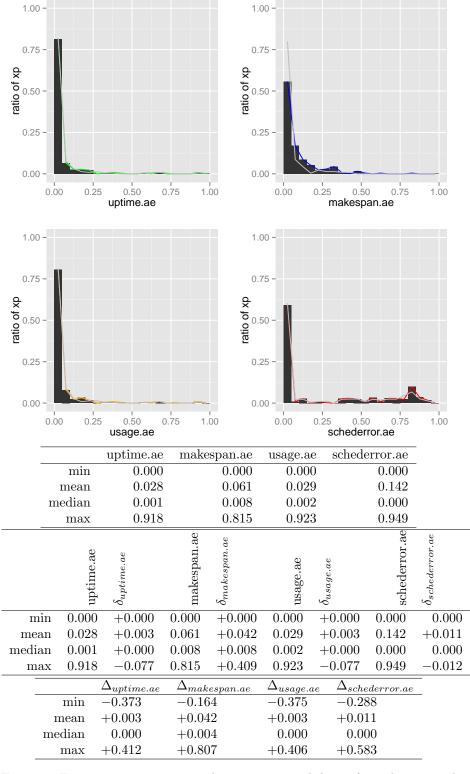


Figure 4: Frequencies, statistics, and comparison with best of simulations with no real boot times injection

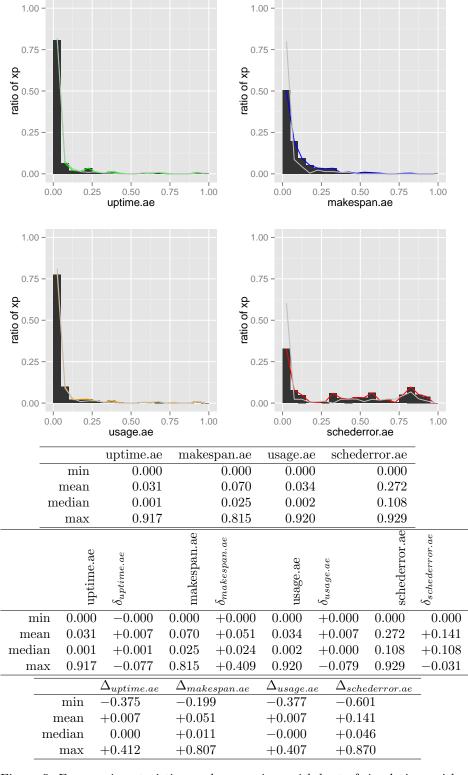


Figure 5: Frequencies, statistics, and comparison with best of simulations with no real thread times injection

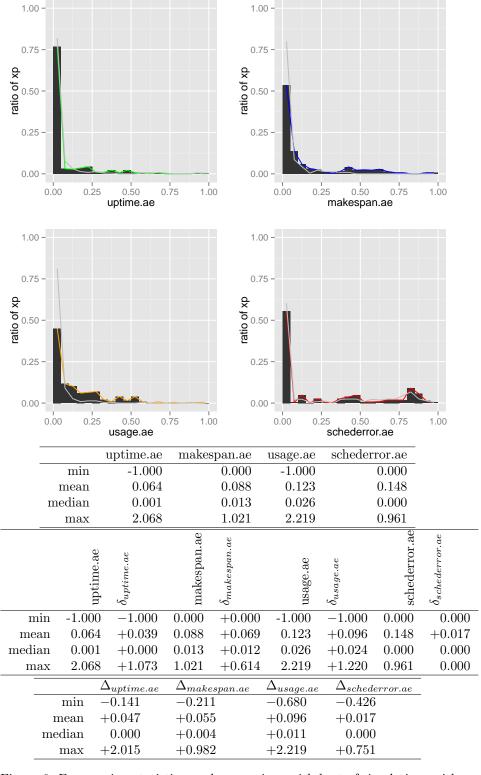


Figure 6: Frequencies, statistics, and comparison with best of simulations with simulation of communications

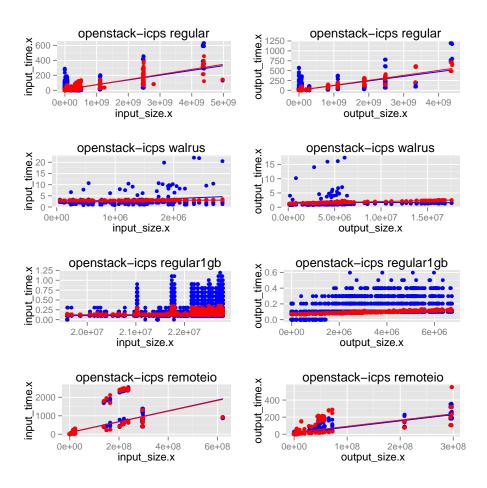


Figure 7: Linear regressions of communication times vs. data size, according to platform, storage, and communication direction on openstack-icps

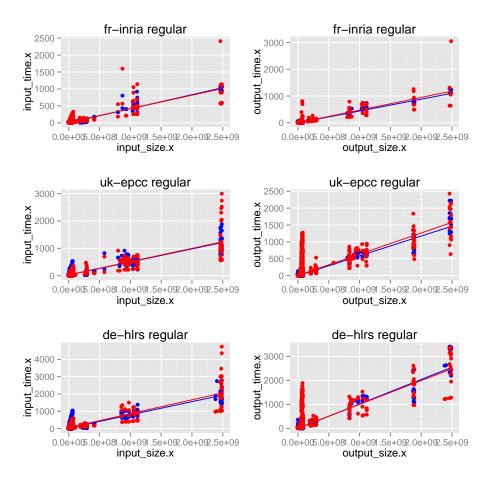


Figure 8: Linear regressions of communication times vs. data size, according to platform, storage, and communication direction on BonFire

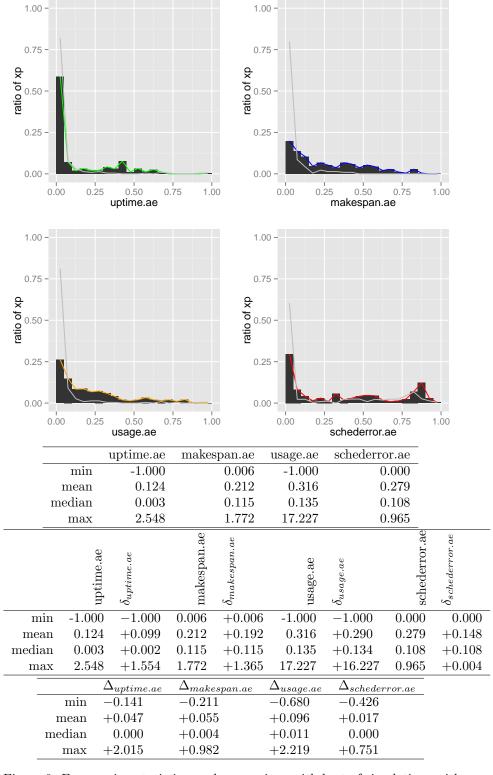


Figure 9: Frequencies, statistics, and comparison with best of simulations with no injection