

UNIVERSITY OF OXFORD

EXAMINATION

COMPUTER SCIENCE

Automata, Logic and Games

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Question 1

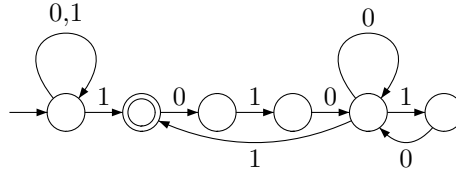
- (a) $\alpha \in L$ if and only if after some position k , α does not contain any occurrence of 11 and contains infinitely many occurrences of 101.

$\alpha \in \llbracket (0+1)^*.L' \rrbracket$ where L' is the language recognizing the words containing infinitely many 101 but containing no occurrence of 11.

Consider $\beta \in L'$, after each occurrence of 101 in β there must be a 0 (since 11 is not allowed). Moreover, between two occurrences of 1010, the only two possible sequences of symbols are 0 and 10, this corresponds to the regular expression $(0+10)^*$.

Therefore $L' = \llbracket (1010(0+10)^*)^\omega \rrbracket$ and $L = \llbracket (0+1)^*(1010(0+10)^*)^\omega \rrbracket$

The following Büchi-automaton recognizes this language:



- (b) Suppose that a deterministic automaton $A = (Q, \{0, 1\}, q_0, \delta, F)$ recognizes L . Then δ is a function and we can extend it to a function $Q \times \{0, 1\}^* \rightarrow Q$ returning the state reached after reading a given sequence of symbols from a given state.

A must accept $(101)^\omega$, therefore there is a word $w_1 \in \Sigma^*$ such that $\delta(q_0, w_1) \in F$, where w_1 is either $(101)^{n_1}$, $(101)^{n_1}1$ or $(101)^{n_1}10$ for some $n_1 \in \mathbb{N}$.

Again, A must accept $w_1.11(101)^\omega$ therefore, there is a word $w_2 \in \Sigma^*$ such that $\delta(q_0, w_1.11.w_2) \in F$, where w_2 is either $(101)^{n_2}$, $(101)^{n_2}1$ or $(101)^{n_2}10$ for some $n_2 \in \mathbb{N}$.

In this manner, we can create an infinite word $\alpha = w_1.11.w_2.11 \dots w_k.11 \dots$ which is recognized by A since the corresponding run passes infinitely through states in F . This is a contradiction, since α contains infinitely many 11 and therefore cannot belong to $L = L(A)$.

Question 2

We prove the result by contradiction. Suppose that $\phi(A, B)$, expressing that A and B have the same number of elements, is definable in S1S.

We define the S1S formula $\text{partition}(A, B, C)$ stating that the sets A , B and C form a partition of ω :

$$\begin{aligned} \text{partition}(A, B, C) = & \forall x.(x \in A \vee x \in B \vee x \in C) \\ & \wedge \forall y. \neg ((y \in A \wedge y \in B) \vee (y \in A \wedge y \in C) \vee (y \in B \wedge y \in C)) \end{aligned}$$

We define $\psi(X, Y)$ stating that after an occurrence of an element in Y there is no occurrence of an element in X :

$$\psi(X, Y) = \forall y. y \in Y \rightarrow (\forall x. x \geq y \rightarrow x \notin X)$$

We now consider the alphabet $\Sigma = \{0, 1\}^3$. An infinite word α on Σ is defined by three tracks characterized by the sets A , B and C :

$$\forall x \in \omega : \alpha(x) = \begin{pmatrix} [x \in A] \\ [x \in B] \\ [x \in C] \end{pmatrix}$$

We use the following notation:

$$a = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, b = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \text{ and } c = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

Then the following formula denotes the language $L = \{a^n b^n c^\omega | n \in \mathbb{N}\}$:

$$\text{partition}(A, B, C) \wedge \psi(A, B) \wedge \psi(B, C) \wedge \psi(A, C) \wedge (\exists z. z \in C)$$

Hence L is S1S definable and therefore there is a non-deterministic Büchi automaton recognizing L (by theorem 3.3 of the the lecture's notes).

This is a contradiction since L is not regular. Indeed, suppose that a Büchi-automaton A with m states recognizes L . Take $n > m$, then $a^n b^n c^\omega \in L$. After reading the first n symbols a , the automaton has visited twice a particular state. Suppose this state has been visited after reading a^i and after reading a^j with $i < j \leq n$. We know that $a^i b^i c^\omega \in L$. Since A is in the same state after reading a^i and a^j , we also have $a^j b^i c^\omega \in L$ too. This is a contradiction since $i < j$.

Question 3

(a) Let us define the following two operators:

$$A \oplus B \triangleq (A \vee B) \wedge \neg(A \wedge B)$$

$$A \leftrightarrow B \triangleq \neg(A \oplus B)$$

Then the following formula $\phi(X, Y, Z)$ expresses that the numbers a, b and c represented respectively by the finite sets X, Y and Z are related by the equation $a + b = c$:

$$\begin{aligned} \phi(X, Y, Z) &= \exists R. 0 \notin R \\ &\wedge \forall b. b \in Z \leftrightarrow [(b \in X) \oplus (b \in Y) \oplus (b \in R)] \\ &\wedge \forall b. s \ b \in R \leftrightarrow [(b \in X) \wedge (b \in Y)] \vee [(b \in X) \wedge (b \in R)] \vee [(b \in Y) \wedge (b \in R)] \end{aligned}$$

The first line states that there is a set R defining the value of the reminder for every step of the binary addition. $0 \notin R$ means that there is no reminder for the computation of the digit 0 of c . The second line defines how the semi-addition is done and the third line defines how the reminder is calculated at every step.

- (b) For any first-order formula ψ over the structure $(\omega, +)$, we can construct an equivalent S1S formula $F(\psi)$ as follow:

Let x, y and z be first order variables, we define corresponding second order μ -calculus variables X, Y and Z . F is defined recursively as follow:

$$\begin{aligned} F(\psi_1 \wedge \psi_2) &= F(\psi_1) \wedge F(\psi_2) \\ F(\psi_1 \vee \psi_2) &= F(\psi_1) \vee F(\psi_2) \\ F(\neg\psi) &= \neg F(\psi) \\ F(\forall x.\psi) &= \forall X.F(\psi) \\ F(\exists x.\psi) &= \exists X.F(\psi) \\ F(x + y = z) &= \phi(X, Y, Z) \\ F(x) &= X \end{aligned}$$

Moreover for any constant $n \in \omega$ we define $F(n)$ as the set of numbers corresponding to the position of 1's in the binary representation of n :

$$F(n) = \{k \in \mathbb{N} \mid \text{the } k^{\text{th}} \text{ binary digit in the binary representation of } n \text{ is a } 1\}$$

A Presburger arithmetic formula $\phi(x_1, \dots, x_n)$ can be transformed into the S1S formula $F(\phi(x_1, \dots, x_n)) = \psi(X_1, \dots, X_n)$. From this S1S formula, we can construct the Büchi automaton A_ψ defines in slide 3-17 of the lecture's note. The language recognized by this automaton is not empty if and only if the formula ψ is satisfiable. Hence, since non-emptiness is decidable for Büchi automata (theorem 1.6), Presburger arithmetic is decidable.

- (c) What we proved is that when we encode numbers into sets, we can decide whether the second-order variable X, Y and Z encode numbers satisfying the relation $x + y = z$.

But if x, y and z are first-order variables then the natural number addition $x + y = z$ on these first-order variables is not definable in S1S.

Question 4

See answer on the attached sheets.

Question 5

(a) We define the following two functions:

$$\begin{aligned}\Phi(X, Z) &= [a]((Z \vee \langle b \rangle t) \wedge X) \\ \phi(X) &= \mu Z. \Phi(X, Z)\end{aligned}$$

Let us first do some preliminary computations:

– We have:

$$\begin{aligned}\|\mu^0 Z. \Phi(S, Z)\|_\emptyset^T &= \emptyset \\ \|\mu^1 Z. \Phi(S, Z)\|_\emptyset^T &= \|[a](\underbrace{\langle b \rangle t}_{\{1\}})\|_\emptyset^T = \{2\} \\ \|\mu^2 Z. \Phi(S, Z)\|_\emptyset^T &= \|[a](\underbrace{\{2\} \vee \{1\}}_{\{1,2\}})\|_\emptyset^T = \{1, 2\} \\ \|\mu^3 Z. \Phi(S, Z)\|_\emptyset^T &= \|[a](\{1, 2\} \vee \{1\})\|_\emptyset^T = \{1, 2\}\end{aligned}$$

therefore:

$$\|\phi(S)\|_\emptyset^T = \|\mu Z. \Phi(S, Z)\|_\emptyset^T = \{1, 2\} \quad (1)$$

– moreover:

$$\begin{aligned}\|\mu^0 Z. \Phi(\{1, 2\}, Z)\|_\emptyset^T &= \emptyset \\ \|\mu^1 Z. \Phi(\{1, 2\}, Z)\|_\emptyset^T &= \|[a](\{1\} \wedge \{1, 2\})\|_\emptyset^T = \|[a](\{1\})\|_\emptyset^T = \{2\} \\ \|\mu^2 Z. \Phi(\{1, 2\}, Z)\|_\emptyset^T &= \|[a](\{2\} \vee \{1\}) \wedge \{1, 2\}\|_\emptyset^T = \|[a](\{1, 2\})\|_\emptyset^T = \{1, 2\} \\ \|\mu^3 Z. \Phi(\{1, 2\}, Z)\|_\emptyset^T &= \|[a](\{1, 2\} \vee \{1\}) \wedge \{1, 2\}\|_\emptyset^T = \|[a](\{1, 2\})\|_\emptyset^T = \{1, 2\}\end{aligned}$$

therefore:

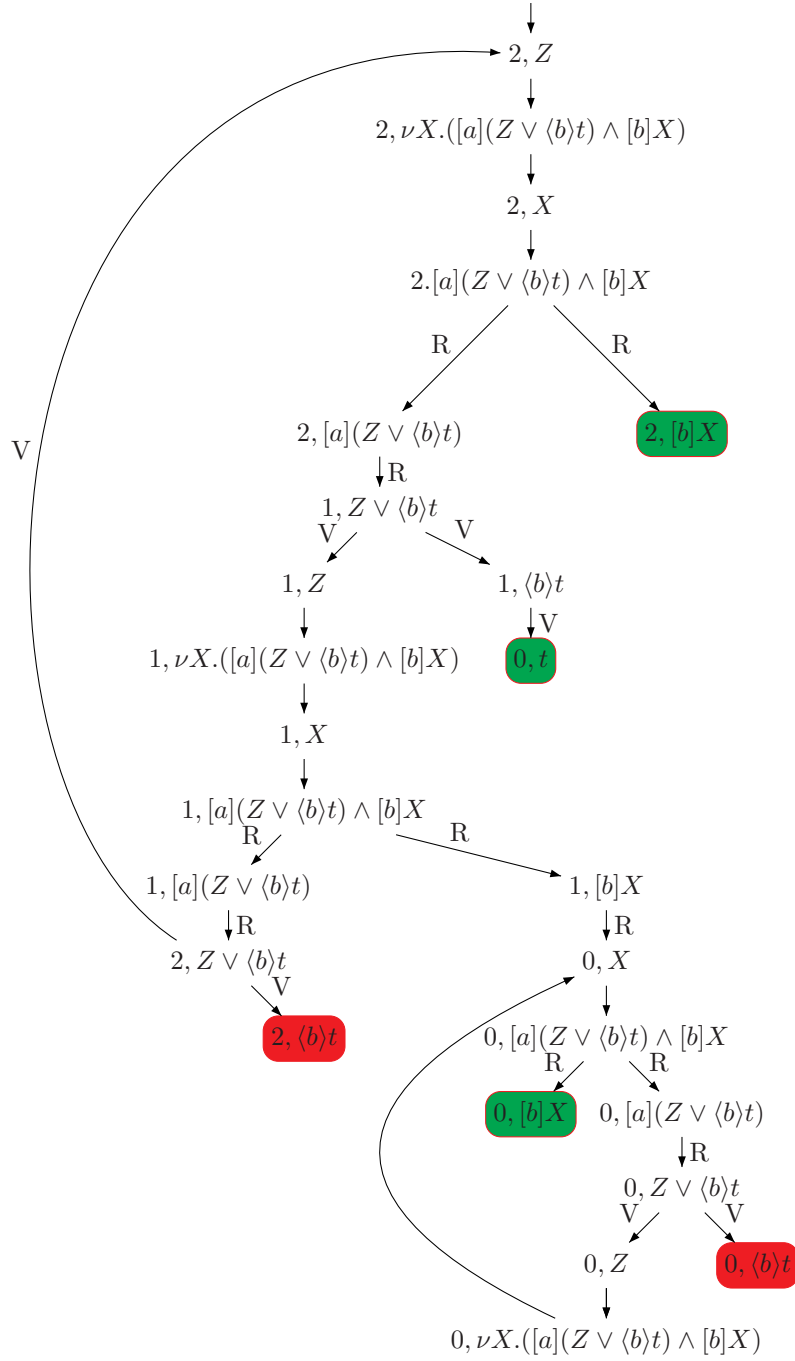
$$\|\phi(\{1, 2\})\|_\emptyset^T = \|\mu Z. \Phi(\{1, 2\}, Z)\|_\emptyset^T = \{1, 2\} \quad (2)$$

We can compute the fixpoint approximants for $\|\nu X. \phi(X)\|_\emptyset^T$:

$$\begin{aligned}\|\nu^0 X. \phi(X)\|_\emptyset^T &= S \\ \|\nu^1 X. \phi(X)\|_\emptyset^T &= \|\phi(S)\|_\emptyset^T = \{1, 2\} \quad (\text{equation 1}) \\ \|\nu^2 X. \phi(X)\|_\emptyset^T &= \|\phi(\{1, 2\})\|_\emptyset^T = \{1, 2\} \quad (\text{equation 2})\end{aligned}$$

Hence $\|\nu X. \phi(X)\|_\emptyset^T = \{1, 2\}$.

- (b) The following graph describes the game $\mathcal{G}_0^T(2, \mu Z. \nu X. ([a](Z \vee \langle b \rangle t) \wedge [b]X))$:
 $2, \mu Z. \nu X. ([a](Z \vee \langle b \rangle t) \wedge [b]X)$



The **green** position correspond to the verifier's winning positions, the **red** positions correspond to the refuter's winning position.

We recall theorem 5.2 from the notes:

Theorem 1 1. $s \models_V^T \phi$ iff player V has as history-free winning strategy for $\mathcal{G}_V^T(s, \phi)$

2. $s \not\models_V^T \phi$ iff player R has as history-free winning strategy for $\mathcal{G}_V^T(s, \phi)$

V has a history-free winning strategy for $\mathcal{G}_0^T(2, \mu Z. \nu X. ([a](Z \vee \langle b \rangle t) \wedge [b]X))$ consisting in choosing the position “1, $\langle b \rangle t$ ” when the game is at position “1, $Z \vee \langle b \rangle t$ ”. Hence $2 \models \mu Z. \nu X. ([a](Z \vee \langle b \rangle t) \wedge [b]X)$.

Question 6

(a)

$$\begin{aligned} \alpha \models \mathbf{X}\phi \rightarrow \mathbf{X}\psi &\iff (\alpha \models \mathbf{X}\phi) \implies (\alpha \models \mathbf{X}\psi) \\ &\iff (\alpha^1 \models \phi) \implies (\alpha^1 \models \psi) \\ &\iff \alpha^1 \models (\phi \rightarrow \psi) \\ &\iff \alpha \models \mathbf{X}(\phi \rightarrow \psi) \end{aligned}$$

(b)

$$\begin{aligned} \alpha \models \phi \mathbf{R} \psi &\iff \forall k \geq 0. (\alpha^k \models \psi \vee \exists i : 0 \leq i < k. \alpha^i \models \phi) \\ &\iff \left[\alpha \models \psi \vee \overbrace{\exists i : 0 \leq i < 0. \alpha^i \models \phi}^{\text{false}} \right] \quad (k = 0) \\ &\quad \wedge \underbrace{\forall k > 0. (\alpha^k \models \psi \vee \exists i : 0 \leq i < k. \alpha^i \models \phi)}_A \\ &\iff \alpha \models \psi \wedge [(A \wedge \alpha \models \psi) \vee (A \wedge \alpha \not\models \psi)] \quad (3) \end{aligned}$$

– Since

$$\alpha \models \phi \implies [\forall k > 0. \exists i : 0 \leq i < k. \alpha^i \models \phi] \equiv A$$

we have $(A \wedge \alpha \models \psi) \equiv \alpha \models \phi$.

– Moreover,

$$\begin{aligned} A \wedge \alpha \not\models \phi &\implies \forall k > 0. (\alpha^k \models \psi \vee \exists i : 0 < i < k. \alpha^i \models \phi) \\ &\stackrel{k \leftarrow k-1}{\iff} \forall k \geq 0. (\alpha^{k+1} \models \psi \vee \exists i : 0 < i < k+1. \alpha^i \models \phi) \\ &\stackrel{i \leftarrow i-1}{\iff} \forall k \geq 0. (\alpha^{k+1} \models \psi \vee \exists i : 0 \leq i < k. \alpha^{i+1} \models \phi) \\ &\iff \forall k \geq 0. ((\alpha^1)^k \models \psi \vee \exists i : 0 \leq i < k. (\alpha^1)^i \models \phi) \\ &\stackrel{R \text{ def.}}{\iff} \alpha^1 \models \phi \mathbf{R} \psi \\ &\implies \alpha \models \mathbf{X}(\phi \mathbf{R} \psi) \end{aligned}$$

By plugging these two results into equation 3 we obtain the desired result:

$$\alpha \models \phi \mathbf{R} \psi \implies \alpha \models \psi \wedge [\alpha \models \phi \vee \alpha \models \mathbf{X}(\phi \mathbf{R} \psi)]$$

(c) We first prove the identity $\mathbf{f} \mathbf{R} \phi = \mathbf{G}\phi$:

$$\begin{aligned} \alpha \models \mathbf{f} \mathbf{R} \phi &\iff \forall k \geq 0. \alpha^k \models \phi \vee \exists i : 0 \leq i < k : \alpha^i \models \mathbf{f} \\ &\iff \forall k \geq 0. \alpha^k \models \phi \\ &\iff \alpha \models \mathbf{G}\phi \end{aligned}$$

Hence:

$$\begin{aligned} \mathbf{f} \mathbf{R} (\phi \wedge \mathbf{X}\phi) \rightarrow (\phi \rightarrow \mathbf{f} \mathbf{R}\phi) &\equiv \mathbf{G}(\phi \wedge \mathbf{X}\phi) \rightarrow (\phi \rightarrow \mathbf{G}\phi) \\ &\equiv \mathbf{G}\phi \rightarrow (\phi \rightarrow \mathbf{G}\phi) \\ &\equiv (\mathbf{G}\phi \wedge \phi) \rightarrow (\mathbf{G}\phi) \\ &\equiv \mathbf{G}\phi \rightarrow (\mathbf{G}\phi) \\ &\equiv \mathbf{true} \end{aligned}$$

(d) **Claim:** $\phi \mathbf{R} \psi \equiv \mathbf{G}(\neg\phi \wedge \psi) \vee (\neg\phi \wedge \psi)\mathbf{U}(\phi \wedge \psi)$

Proof: We first note that $\phi \mathbf{R} \psi \equiv [(\phi \mathbf{R} \psi) \wedge \mathbf{G}\neg\phi] \vee [(\phi \mathbf{R} \psi) \wedge \mathbf{F}\phi]$

– We have $(\phi \mathbf{R} \psi) \wedge \mathbf{G}\neg\phi \equiv \mathbf{G}(\neg\phi \wedge \psi)$, indeed:

$$\begin{aligned} \alpha \models (\phi \mathbf{R} \psi) \wedge \mathbf{G}\neg\phi &\iff (\forall k \geq 0. \alpha^k \models \psi \vee \exists i : 0 \leq i < k. \alpha^i \models \phi) \wedge (\forall l \geq 0 : \alpha^l \models \neg\phi) \\ &\iff \forall k \geq 0 : (\alpha^k \models \psi \wedge \forall l \geq 0 : \alpha^l \models \neg\phi) \\ &\quad \vee \underbrace{[(\exists i : 0 \leq i < k. \alpha^i \models \phi) \wedge (\forall l \geq 0 : \alpha^l \models \neg\phi)]}_{\text{false}} \\ &\iff \forall k \geq 0 : \alpha^k \models \psi \wedge \forall l \geq 0 : \alpha^l \models \neg\phi \\ &\iff \alpha \models \mathbf{G}(\neg\phi \wedge \psi) \end{aligned}$$

– moreover $(\phi \mathbf{R} \psi) \wedge \mathbf{F}\phi \equiv (\neg\phi \wedge \psi)\mathbf{U}(\phi \wedge \psi)$, indeed:

$$\begin{aligned} \alpha \models (\phi \mathbf{R} \psi) \wedge \mathbf{F}\phi &\iff (\forall k \geq 0 : \alpha^k \models \psi \vee \exists i : 0 \leq i < k : \alpha^i \models \phi) \\ &\quad \wedge (\exists i_0. \alpha^{i_0} \models \phi \wedge \forall j < i_0 : \alpha^j \models \neg\phi) \\ &\iff \exists i_0. \alpha^{i_0} \models \phi \wedge (\forall j < i_0 : \alpha^j \models \neg\phi) \\ &\quad \wedge (\forall k \geq 0 : \alpha^k \models \psi \vee \exists i : 0 \leq i < k : \alpha^i \models \phi) \\ &\iff \exists i_0. \alpha^{i_0} \models \phi \wedge (\forall j < i_0 : \alpha^j \models \neg\phi) \\ &\quad \wedge (\forall k < i_0 : \alpha^k \models \psi \vee \exists i : 0 \leq i < k : \alpha^i \models \phi) \\ &\quad \wedge (\alpha^{i_0} \models \psi \vee \exists i : 0 \leq i < i_0 : \alpha^i \models \phi) \\ &\quad \wedge (\forall k > i_0 : \alpha^k \models \psi \vee \exists i : 0 \leq i < k : \alpha^i \models \phi) \\ &\iff \exists i_0. \alpha^{i_0} \models \phi \wedge (\forall j < i_0 : \alpha^j \models \neg\phi) \end{aligned}$$

$$\begin{aligned}
& \wedge \forall k < i_0 : \alpha^k \models \psi \\
& \wedge \alpha^{i_0} \models \psi \\
& \wedge (\forall k > i_0 : \alpha^k \models \psi \vee \exists i : 0 \leq i < k : \alpha^i \models \phi) \\
\iff & \exists i_0. \alpha^{i_0} \models \phi \wedge (\forall j < i_0 : \alpha^j \models \neg \phi) \\
& \wedge \forall k < i_0 : \alpha^k \models \psi \\
& \wedge \alpha^{i_0} \models \psi \\
& \wedge \forall k > i_0. \\
& \quad [(\alpha^{i_0} \models \phi \wedge \alpha^k \models \psi) \vee \underbrace{(\alpha^{i_0} \models \phi \wedge \exists i : 0 \leq i < k : \alpha^i \models \phi)}_{\alpha^{i_0} \models \phi}] \\
\iff & \exists i_0. \alpha^{i_0} \models \phi \wedge (\forall j < i_0 : \alpha^j \models \neg \phi) \\
& \wedge \forall k < i_0 : \alpha^k \models \psi \\
& \wedge \alpha^{i_0} \models \psi \\
& \wedge \underbrace{(\alpha^{i_0} \models \phi \wedge \forall k > i_0. \alpha^k \models \psi) \vee \alpha^{i_0} \models \phi}_{\alpha^{i_0} \models \phi} \\
\iff & \exists i_0. (\forall j < i_0 : \alpha^j \models \neg \phi) \wedge (\forall k < i_0 : \alpha^k \models \psi) \\
& \wedge \alpha^{i_0} \models (\psi \wedge \phi) \\
\iff & \exists i_0. \forall j < i_0 : \alpha^j \models \neg \phi \wedge \psi \\
& \wedge \alpha^{i_0} \models (\psi \wedge \phi) \\
\iff & \alpha \models (\neg \phi \wedge \psi) \mathbf{U}(\phi \wedge \psi)
\end{aligned}$$

■

Question 7

Suppose that a formula ϕ has a model. Then there is a transition system $T = \langle S, \rightarrow, \rho \rangle$ and a state $r \in S$ such that $r \models_T \phi$.

- The model T can be unwound into a tree rooted at r : the graph of the transition system is browsed from r in a breadth-first search manner, every time we reach an edge $s \rightarrow t$ where t has already been visited, we replace the edge $s \rightarrow t$ by an edge pointing to a newly created tree obtained by unwinding the LTS at state t . This process clearly removes all the cycles in the graph, hence the resulting model is a tree but possibly with an infinite depth.

It is also obvious that s satisfies ϕ in this new model: for a given state, the possible outcomes are the same in the two models.

- We need to prove that the resulting tree has a bounded width.

We achieve this by assuming with no proof that the small model property is true for the modal μ -calculus.

The small model property states that if a formula has a model then it has a model with finite number of states.

By unwinding the finite model, we obtain a tree model with possibly infinite depth (if there are loops in the finite model) but with a bounded width. Indeed, the unwinding process preserves the number of outgoing edges for a node: there may be infinitely many copies of a node but for all these copies, the number of outgoing edges is the same as the original node. The number of outgoing edges for a node is clearly bounded by $|S| \cdot |\mathcal{L}|$ where \mathcal{L} is the labeling set.