

Chapter-1

VECTOR ANALYSIS

$$A \cdot (B \times C) = C \cdot (A \times B) = B \cdot (C \times A)$$

$$A \times (B \times C) = B(A \cdot C) - C(A \cdot B)$$

Field: specify quantity in a particular region, that is known as field.

- i) Unit Vector
- ii) Distance Vector
- iii) Position Vector

Example: point P & Q are located at (0, 2, 4) & (-3, 1, 5). calculate a vector parallel to PQ with magnitude of 10.

Sol: $\vec{PQ} = -3\hat{i} - \hat{j} + \hat{k}$

(Unit vector is same for parallel vector which is to PQ)

$$\hat{PQ} = \frac{-3\hat{i} - \hat{j} + \hat{k}}{\sqrt{11}}$$

$$\text{parallel vector} = \frac{10}{\sqrt{11}}(-3\hat{i} - \hat{j} + \hat{k})$$

↳ Dot Product (Scalar product) $\Rightarrow \vec{A} \cdot \vec{B} = |\vec{A}| |\vec{B}| \cos \theta$

↳ Cross Product (Vector Product) $\Rightarrow \vec{A} \times \vec{B} = |\vec{A}| |\vec{B}| \sin \theta$

Coordinates System:

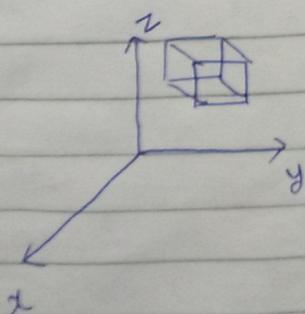
① Rectangular CS

② Cylindrical CS

③ Spherical CS

① Rectangular CS:

$$-\infty \leq x \leq \infty ; -\infty \leq y \leq \infty ; -\infty \leq z \leq \infty$$



Differ Displacement

$$d\vec{l} = dx \hat{i} + dy \hat{j} + dz \hat{k}$$

Differ Surface

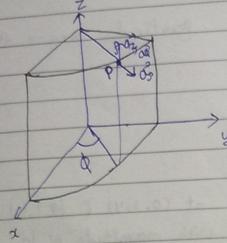
$$d\vec{s} = dy dz \hat{i} + dz dx \hat{j} + dx dy \hat{k}$$

Differ Volume

$$dV = dx dy dz$$

② Cylindrical CS:

there are three axis — \vec{Oz} , P , Z , ϕ
 ↓
 radius angle with the x -axis



$$0 \leq \rho \leq \infty$$

$$0 \leq \phi \leq 360^\circ$$

$$-\infty \leq z \leq \infty$$

$$\vec{A} = A_x \vec{O_x} + A_\phi \vec{O_\phi} + A_z \vec{O_z}$$

$$|\vec{A}| = \sqrt{A_x^2 + A_\phi^2 + A_z^2}$$

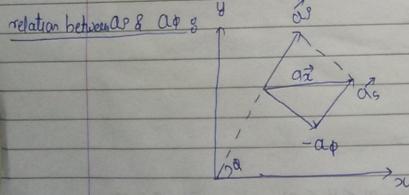
$$x = \rho \cos \phi$$

$$y = \rho \sin \phi$$

$$z = z$$

$$\rho = \sqrt{x^2 + y^2}$$

$$\phi = \tan^{-1}(y/x)$$



$$\Delta ABC, \sin \phi = \frac{AC}{BE}$$

$$BC = \sin \phi BE$$

$$= -\vec{O_\phi} \sin \phi$$

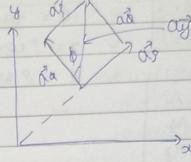
ΔCDE ,

$$\cos \phi = CD / DE$$

$$CD = DE \cos \phi$$

$$= \vec{O_\phi} \cos \phi$$

Similarly:



$$\Delta OBC; \cos \phi = \frac{CO}{BC}$$

$$\therefore CO = BC \cos \phi = \vec{O_\phi} \cos \phi$$

$$\Delta AOB; \sin \phi = \frac{AO}{AB}$$

$$\therefore AO = \vec{O_\phi} \cos \phi \sin \phi$$

$$\text{So, } AC = AO + OC$$

$$|\vec{AC}| = \cos \phi \vec{O_\phi} + \sin \phi \vec{O_y} \quad (2)$$

Multiplying eqn (1) with $\cos \phi$

$$\cos \phi \vec{O_x} = \cos \phi \vec{O_\phi} - \cos \phi \sin \phi \vec{O_y} \quad (4)$$

Multiplying eqn (2) with $\sin \phi$

$$\vec{O_y} \sin \phi = \cos \phi \sin \phi \vec{O_\phi} + \cos \phi \sin \phi \vec{O_x} \quad (5)$$

Adding (4) & (5)

$$\vec{O_x} = \cos \phi \vec{O_x} + \sin \phi \vec{O_y}$$

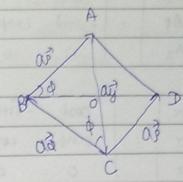
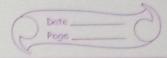
Sub. (4) & (5)

$$\vec{O_\phi} = \cos \phi \vec{O_y} - \sin \phi \vec{O_x}$$

$$\text{Rectangular CS: } \vec{A} = A_x \vec{O_x} + A_y \vec{O_y} + A_z \vec{O_z}$$

$$\text{Cylindrical CS: } \vec{A} = (\) \vec{O_\phi} + (\) \vec{O_x} + A_z \vec{O_z}$$

$$\begin{bmatrix} A_\phi \\ A_x \\ A_y \\ A_z \end{bmatrix} = \begin{bmatrix} \cos \phi & \sin \phi & 0 \\ -\sin \phi & \cos \phi & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} A_\phi \\ A_x \\ A_y \\ A_z \end{bmatrix}$$



$$\begin{bmatrix} A_x \\ A_y \\ A_z \end{bmatrix} = \begin{bmatrix} \cos\phi & \sin\phi & 0 \\ -\sin\phi & \cos\phi & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} A_x \\ A_y \\ A_z \end{bmatrix}$$

$$r = \sqrt{x^2 + y^2}$$

$$\theta = \tan^{-1}(y/x); z=0$$

$$x = r \cos\phi$$

$$y = r \sin\phi$$

$$\begin{bmatrix} A_x \\ A_y \\ A_z \end{bmatrix} = \begin{bmatrix} \cos\phi & -\sin\phi & 0 \\ \sin\phi & \cos\phi & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} A_x \\ A_y \\ A_z \end{bmatrix}$$

Example Point (-2, 6, 3) and
 $\vec{A} = y \hat{a}_x + (x+z) \hat{a}_y$ express vector A in cylindrical coordinates.

Sol:

$A_x = y$	$x = -2$	$y = 6$	$z = 3$
$A_y = x+z$	$\rho = \sqrt{4+36} = \sqrt{40}$		
$A_z = 0$	$\phi = \tan^{-1}(-6/2) = -\tan^{-1}(3)$		
$A_\rho = y \cos\phi + (x+z) \sin\phi$	$\cos\phi = 6/\sqrt{40}$		
$A_\theta = -y \sin\phi + (x+z) \cos\phi$			
$A_z = A_2 = 0$			

$$A_\rho = r \sin\phi \cos\phi + (r \cos\phi \sin\phi) + z \sin\phi$$

$$A_\theta = -r \sin^2\phi + r \cos^2\phi + z \cos\phi$$

$$A_z = 0$$

So, $A_\rho = \frac{\sqrt{40}}{\sqrt{40}} \times \frac{6}{\sqrt{40}} \times -2 + \frac{\sqrt{40}}{\sqrt{40}} \times \frac{6}{\sqrt{40}} \times -2 + 3 \times \frac{6}{\sqrt{40}}$

$$= \frac{-36}{\sqrt{40}} + \frac{18}{\sqrt{40}} = \frac{-18}{\sqrt{40}} = -0.948$$

$$A_\theta = -\frac{\sqrt{40}}{\sqrt{40}} \times \frac{6}{\sqrt{40}} + \frac{\sqrt{40}}{\sqrt{40}} \times \frac{6}{\sqrt{40}} + 3 \times \frac{-2}{\sqrt{40}}$$

$$= \frac{-36+4-6}{\sqrt{40}} = \frac{-38}{\sqrt{40}} = -6.008$$

③ Spherical Coordinates System (Antenna)

$\rightarrow r, \phi, \theta \rightarrow$ angle wrt to z-axis (solid angle)
 \downarrow angle wrt to x-axis
 radius of sphere
 $\rightarrow 0 < r < \infty$
 $0 \leq \theta < \pi$
 $0 < \phi < 2\pi$

IL

$$r = \sqrt{x^2 + y^2 + z^2}$$

$$\theta = \tan^{-1}\left(\frac{\sqrt{x^2 + y^2}}{z}\right)$$

$$\phi = \tan^{-1}(y/x)$$

$$x = r \sin\theta \cos\phi ; y = r \sin\theta \sin\phi ; z = r \cos\theta$$

$$\begin{bmatrix} A_r \\ A_\theta \\ A_\phi \end{bmatrix} = \begin{bmatrix} \sin\theta \cos\phi & \sin\theta \sin\phi & \cos\theta \\ \cos\theta \cos\phi & \cos\theta \sin\phi & -\sin\theta \\ -\sin\phi & \cos\phi & 0 \end{bmatrix} \begin{bmatrix} A_x \\ A_y \\ A_z \end{bmatrix}$$

Example Sol: $A_r = \sin\theta \cos\phi A_x + \sin\theta \sin\phi A_y + \cos\theta A_z$

$$A_\theta = \cos\theta \cos\phi A_x + \cos\theta \sin\phi A_y - \sin\theta A_z$$

$$A_\phi = -\sin\theta A_x + \cos\theta A_z$$

$$A_x = 4 \quad A_z = 0 \quad A_y = (x+z)$$

Ex. Sol: $A_r = r \sin^2\theta \sin\phi \cos\phi + r \sin^2\theta \sin\phi \sin\phi + r \sin\theta \sin\theta \cos\phi$

$$A_\theta = r \sin\theta \cos\theta \sin\phi \cos\phi + r \cos^2\theta \sin\phi + r \sin\theta \sin\theta \sin\phi \cos\phi$$

$$A_\phi = -r \sin\theta \sin^2\phi \quad \text{---} \circ$$

So, $r = \sqrt{x^2 + y^2 + z^2} = \sqrt{4+36+9} = 7$

$$\tan\phi = -3 ; \sin\phi = 6/\sqrt{40} ; \cos\phi = -2/\sqrt{40}$$

$$\tan\theta = \frac{\sqrt{4+36}}{9} = \frac{\sqrt{40}}{9} ; \sin\theta = \frac{6}{\sqrt{40}} ; \cos\theta = \frac{4}{\sqrt{40}}$$

H.W. → spherical coordinates derivative

$$A_r = \frac{7}{40} \times \frac{40}{40} \times (-2) + \frac{7}{40} \times \frac{3 \times \sqrt{40}}{40} \times \frac{6}{\sqrt{40}}$$

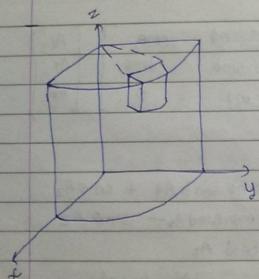
$$= -\frac{24}{7} + \frac{18}{7} = -\frac{6}{7}$$

$$A_\theta = \frac{7}{40} \times 2 \times (-2) \times \frac{3 \times \sqrt{40}}{40} + \frac{7}{40} \times \frac{9}{40} \times \frac{6}{\sqrt{40}}$$

$$= -\frac{72+63}{7\sqrt{40}} = -\frac{9}{7\sqrt{40}}$$

$$A_\phi = -\frac{7}{40} \times \frac{6}{40} \times \frac{40}{40} = -\frac{6\sqrt{40}}{7}$$

* cylindrical:



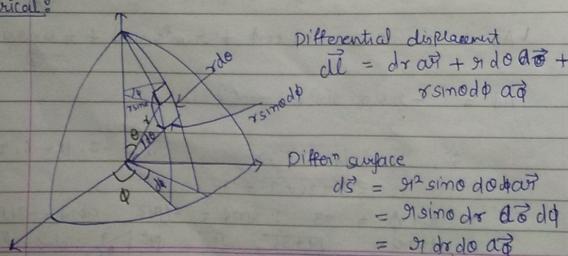
Differential Displacement:

$$d\vec{r} = dr \hat{a}_r + r d\theta \hat{a}_\theta + dz \hat{a}_z$$

$$d\vec{s} = r d\theta dz \hat{a}_\theta$$

$$dV = r d\theta dz dr$$

* spherical:



Differential displacement

$$d\vec{r} = dr \hat{a}_r + r d\theta \hat{a}_\theta + r \sin\theta d\phi \hat{a}_\phi$$

$$d\vec{s} = r^2 \sin\theta d\theta d\phi dr$$

$$= r \sin\theta dr d\theta d\phi$$

$$= r dr d\theta d\phi$$

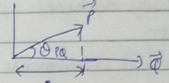
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Differential Volume $dV = r^2 \sin\theta dr d\theta d\phi$

(-) if we change radius of sphere.
 (+/-) what does it represent? → plane
 which type of coordinate sys is used if some scenario is given

* The component of \vec{P} along $\vec{\alpha}$ = $(\vec{P} \cdot \vec{\alpha}) \vec{\alpha} / |\vec{\alpha}|^2 = P_\alpha$



in spherical coordinates

$$\begin{bmatrix} A_r \\ A_\theta \\ A_\phi \end{bmatrix} = \begin{bmatrix} \sin\theta \cos\phi & \cos\theta \cos\phi & -\sin\phi \\ \sin\theta \sin\phi & \cos\theta \sin\phi & \cos\phi \\ \cos\theta & -\sin\theta & 0 \end{bmatrix} \begin{bmatrix} A_r \\ A_\theta \\ A_\phi \end{bmatrix}$$

chapter-2

Coulomb's Law and Electric field Intensity

- static charges \rightarrow electric field
- Uniform motion charge \rightarrow magnetic field

application: electric power transmission

x-ray machines

CRT

medical instruments (Medical)

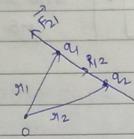
Electrochemical machines (industry)

separation of materials (agriculture)

Coulomb's law :

point charge q_1 & q_2

$$\vec{F} \propto \frac{q_1 q_2}{R^2}$$



$$F = K q_1 q_2$$

$$K = \frac{1}{4\pi\epsilon_0} = 9 \times 10^9 \text{ N m}^2/\text{C}^2$$

$$\epsilon_0 = 8.85 \times 10^{-12} \text{ F/m}$$

$$\vec{F}_{12} = \frac{q_1 q_2}{4\pi\epsilon_0 R^2} \vec{r}_{12}$$

$$R^2 = |\vec{r}_2 - \vec{r}_1|$$

$$R = |\vec{r}_{12}|$$

$$\vec{r}_{12} = \frac{\vec{r}_2 - \vec{r}_1}{|\vec{r}_{12}|} = \frac{(\vec{r}_2 - \vec{r}_1)}{R} = \frac{\vec{r}_2 - \vec{r}_1}{|\vec{r}_2 - \vec{r}_1|}$$

$$\text{so}, \vec{F}_{12} = \frac{q_1 q_2 (\vec{r}_2 - \vec{r}_1)}{4\pi\epsilon_0 R^3}$$

$$= \frac{q_1 q_2 (\vec{r}_2 - \vec{r}_1)}{4\pi\epsilon_0 |\vec{r}_2 - \vec{r}_1|^3}$$

- charges are static.

- Vacuum

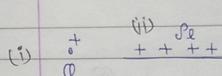
practically example: CRO, speakers, atoms (nuclear)

electric field intensity \vec{E} \approx force per unit charge when placed in the electric field. $\vec{E} = \frac{\vec{F}}{q} = \frac{q}{4\pi\epsilon_0 R^2} \vec{a}_R$

when $a_R > 0$ then direction of field & force will same.

$$\begin{aligned} \vec{E} &= \frac{q \vec{R}}{4\pi\epsilon_0 R^3} = \frac{q (\vec{r}_i - \vec{r}_k)}{4\pi\epsilon_0 |\vec{r}_i - \vec{r}_k|^3} \\ &= \frac{1}{4\pi\epsilon_0} \sum_{k=1}^N \frac{q_k (\vec{r}_i - \vec{r}_k)}{|\vec{r}_i - \vec{r}_k|^3} \end{aligned}$$

\vec{E} due to different charge distributions :



Point charge Line charge

Unit: (C) (C/m)

surface charge

(C/m²)

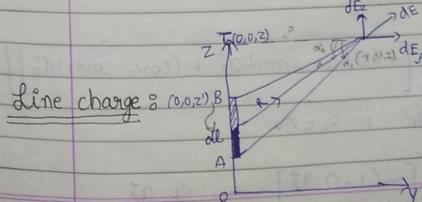
volume charge

(C/m³)

$$dQ = \rho_s dL \Rightarrow Q = \int_L \frac{\rho_s dl}{4\pi\epsilon_0 R^2} \vec{a}_R \rightarrow E = \int_L \frac{\rho_s dl}{4\pi\epsilon_0 R^2} \vec{a}_R$$

$$dQ = \rho_s ds \Rightarrow Q = \int_A \frac{\rho_s ds}{4\pi\epsilon_0 R^2} \vec{a}_R \rightarrow E = \int_A \frac{\rho_s ds}{4\pi\epsilon_0 R^2} \vec{a}_R$$

$$dQ = \rho_v dV \Rightarrow Q = \int_V \frac{\rho_v dV}{4\pi\epsilon_0 R^2} \vec{a}_R \rightarrow E = \int_V \frac{\rho_v dV}{4\pi\epsilon_0 R^2} \vec{a}_R$$



Line charge $\approx \rho_s L$

$dE_x = \frac{\rho_s L}{4\pi\epsilon_0 R^2} \vec{a}_x$

$dE_y = \frac{\rho_s L}{4\pi\epsilon_0 R^2} \vec{a}_y$

$dE_z = \frac{\rho_s L}{4\pi\epsilon_0 R^2} \vec{a}_z$

$E_x = \int \frac{\rho_s L}{4\pi\epsilon_0 R^2} \vec{a}_x$

$E_y = \int \frac{\rho_s L}{4\pi\epsilon_0 R^2} \vec{a}_y$

$E_z = \int \frac{\rho_s L}{4\pi\epsilon_0 R^2} \vec{a}_z$

$E = \sqrt{E_x^2 + E_y^2 + E_z^2}$

$\theta = \tan^{-1} \frac{E_y}{E_x}$

$\phi = \tan^{-1} \frac{E_z}{E_x}$

$\psi = \tan^{-1} \frac{E_y}{E_z}$

$\alpha = \sin^{-1} \frac{E_z}{E}$

$\beta = \sin^{-1} \frac{E_y}{E}$

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$\zeta = \cos^{-1} \frac{E_x}{E}$

$\eta = \cos^{-1} \frac{E_z}{E}$

$\theta = \cos^{-1} \frac{E_x}{E}$

$\phi = \cos^{-1} \frac{E_z}{E}$

$\psi = \cos^{-1} \frac{E_y}{E}$

$\alpha = \cos^{-1} \frac{E_y}{E}$

$\beta = \cos^{-1} \frac{E_z}{E}$

$\gamma = \cos^{-1} \frac{E_x}{E}$

$\delta = \cos^{-1} \frac{E_z}{E}$

$\epsilon = \cos^{-1} \frac{E_y}{E}$

$\zeta = \cos^{-1} \frac{E_x}{E}$

$\eta = \cos^{-1} \frac{E_z}{E}$

$\theta = \cos^{-1} \frac{E_x}{E}$

$\phi = \cos^{-1} \frac{E_z}{E}$

$\psi = \cos^{-1} \frac{E_y}{E}$

$\alpha = \cos^{-1} \frac{E_y}{E}$

$\beta = \cos^{-1} \frac{E_z}{E}$

$\gamma = \cos^{-1} \frac{E_x}{E}$

$\delta = \cos^{-1} \frac{E_z}{E}$

$\epsilon = \cos^{-1} \frac{E_y}{E}$

$\$

$$d\phi = \rho dz = \rho dz - \text{①} \quad [\text{because } dz \text{ is on } z\text{-axis}]$$

$$Q = \int_{z_0}^{z_0} \rho dz \quad \text{②}$$

from the figure

$$dz = dz' \quad \text{③}$$

$$\vec{R} = (0, 0, z') + (x, y, z)$$

$$= x\hat{x} + y\hat{y} + (z - z')\hat{z} \quad \text{④}$$

$$\vec{R} = \rho\hat{r} + (z - z')\hat{z} \quad \text{⑤}$$

$$R^2 = x^2 + y^2 + (z - z')^2 = \rho^2 + (z - z')^2 \quad \text{⑥}$$

$$\vec{a}_R = \frac{\rho\hat{r} + (z - z')\hat{z}}{[\rho^2 + (z - z')^2]^{3/2}} \quad \text{⑦}$$

$$\vec{E} = \frac{\rho_L}{4\pi\epsilon_0} \int \frac{\rho\hat{r} + (z - z')\hat{z}}{[\rho^2 + (z - z')^2]^{3/2}} dz' \quad \text{⑧}$$

$$\text{from the figure } \frac{\rho}{R} = \cos\alpha$$

$$R = \rho \sec\alpha$$

$$[\rho^2 + (z - z')^2]^{1/2} = \rho \sec\alpha \quad \text{⑨}$$

$$\text{also, } z' = \rho T - \rho \tan\alpha$$

$$dz' = -\rho \sec^2\alpha dx \quad \text{⑩}$$

sub. in equation ⑧

$$\vec{E} = -\frac{\rho_L}{4\pi\epsilon_0} \int_{x_1}^{x_2} \frac{\rho \sec^3\alpha [\hat{a}_\rho \cos\alpha + \hat{a}_z \sin\alpha]}{\rho^2 \sec^3\alpha} dx$$

- infinite line of charge

$$\vec{E} = -\frac{\rho_L}{4\pi\epsilon_0} \left[-(\sin\alpha_2 - \sin\alpha_1)\hat{a}_\rho + (\cos\alpha_2 - \cos\alpha_1)\hat{a}_z \right]$$

$$\text{when } \alpha_2 = 90^\circ, \alpha_1 = 90^\circ$$

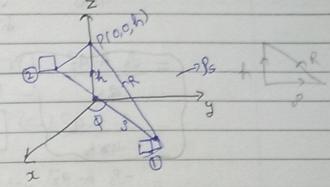
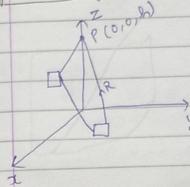
$$\vec{E} = -\frac{\rho_L}{4\pi\epsilon_0} \left[-(1+1)\hat{a}_\rho \right] = \frac{\rho_L}{4\pi\epsilon_0} \hat{a}_z$$

where $\rho_L \rightarrow \text{line charge}$

$\rho \rightarrow \text{radius of cylinder}$

$\epsilon_0 \rightarrow \text{perm of space}$

Surface charge σ



$$d\phi = \sigma_s dS \quad \text{①}$$

$$\vec{E} = \int \frac{\sigma_s dS \vec{a}_R}{4\pi\epsilon_0 R^2}$$

$$d\vec{E} = \frac{d\phi}{4\pi\epsilon_0 R^2} \vec{a}_R \quad \text{②}$$

$$\vec{R} = -\rho\hat{a}_\rho + h\hat{a}_z$$

$$|\vec{R}| = \sqrt{\rho^2 + h^2}$$

$$\vec{a}_R = \vec{R} = -\frac{\rho\hat{a}_\rho + h\hat{a}_z}{\sqrt{\rho^2 + h^2}}$$

$$d\phi = \sigma_s dS = \sigma_s \rho d\theta d\phi$$

sub. in eqn ②

[$d\theta$ cancelled because for every $d\theta$ vector, there will always be $-d\theta$]

$$d\vec{E} = \frac{\sigma_s \rho d\theta d\phi}{4\pi\epsilon_0} \cdot \frac{-\rho\hat{a}_\rho + h\hat{a}_z}{(\rho^2 + h^2)^{3/2}} \quad \text{⑨}$$

$$d\vec{E} = \frac{\sigma_s \rho d\theta d\phi h\hat{a}_z}{4\pi\epsilon_0 (\rho^2 + h^2)^{3/2}} \quad \text{⑩}$$

by integration:

$$\vec{E} = \frac{\sigma_s h \hat{a}_z}{4\pi\epsilon_0} \int_0^{2\pi} \int_0^{\infty} \frac{\rho d\rho d\phi}{(\rho^2 + h^2)^{3/2}} \quad \text{⑪}$$

$$\begin{aligned}
 &= \frac{\rho_s \cdot h \cdot \vec{a}_z}{4\pi\epsilon_0} \times 2\pi \int_0^\infty \frac{\rho \, d\rho}{(\rho^2 + h^2)^{3/2}} \\
 &= \frac{\rho_s \cdot h \cdot \vec{a}_z}{4\pi\epsilon_0} \times 2\pi \int_0^\infty \frac{d\rho}{2\rho^2 h^2} \\
 &= \frac{\rho_s \cdot h \cdot \vec{a}_z}{4\epsilon_0} \left[\frac{x^{-1/2} + 1}{1 - 1/2} \right]_0^\infty \\
 &= \frac{\rho_s \cdot h \cdot \vec{a}_z}{4\epsilon_0} (-2) \left[\frac{x^{-1/2}}{h^2} \right]_0^\infty \\
 &= -\frac{\rho_s \cdot h \cdot \vec{a}_z}{2\epsilon_0} \times \frac{1}{h}
 \end{aligned}$$

$\vec{E} = \frac{\rho_s \cdot \vec{a}_z}{2\epsilon_0}$

is valid when $h > 0$

* $\vec{E} = \frac{\rho_s \cdot \vec{a}_n}{2\epsilon_0}$ Normal vector / Unit vector to the surface

Example A circular ring of radius 'a' carries a uniform charge ρ_s C/m & is placed on the x-y plane with axis the same as z-axis.

(i) Show that $\vec{E}(0, 0, h) = \frac{\rho_s \cdot a \cdot h}{2\epsilon_0 [a^2 + h^2]^{3/2}} \cdot \vec{a}_z$

(ii) What values of h gives the max value of \vec{E}

(iii) If the total charge on the ring is Q . find

\vec{E} as $a \rightarrow 0$

$$\begin{aligned}
 d\vec{E} &= \frac{d\Phi \vec{a}_z}{4\pi\epsilon_0 r^2} \\
 d\Phi &= \frac{d\Phi \cdot a \cdot \rho_s}{dL} \cdot a \cdot \rho_s \\
 dE &= \frac{\rho_s \cdot a \cdot dz}{4\pi\epsilon_0 [a^2 + h^2]^{3/2}}
 \end{aligned}$$

$$\vec{E} = \frac{\rho_s \cdot a \cdot h \cdot \vec{a}_z}{4\pi\epsilon_0 [a^2 + h^2]^{3/2}}$$

$dQ = \rho_L \, dL = \rho_L (a \, d\phi)$ $\therefore \vec{a}_z = \vec{R}/|\vec{R}| \therefore \vec{R} = h\vec{a}_z - a\vec{a}_\phi$
 $\int dE = \int \frac{\rho_L a \, d\phi}{4\pi\epsilon_0} \cdot \frac{ha_z - a \cdot a_\phi}{(a^2 + h^2)^{3/2}}$
 $E = \frac{\rho_L \cdot a \cdot ha_z}{4\pi\epsilon_0 (a^2 + h^2)^{3/2}} \int d\phi = \frac{\rho_L a^2 h}{4\pi\epsilon_0 (a^2 + h^2)^{3/2}} \vec{a}_z$
(iii) $\frac{dE}{dh} = 0$
 $\frac{\rho_L a \cdot h}{2\epsilon_0} \frac{d}{dh} \left[\frac{h}{(a^2 + h^2)^{3/2}} \right] = 0$
 $(a^2 + h^2)^{3/2} \times 1 - h \times \frac{3}{2} (a^2 + h^2)^{1/2} \cdot 2h = 0$
 $(a^2 + h^2)^3 - 3h^2 = 0$
 $a^2 = gh^2$
 $h = \pm a\sqrt{g}$

(iii) $Q = \int \rho_L \, dL$ (Point charge)
 $= \frac{1}{2} \rho_s \cdot 2\pi a$
 $\rho_L = \frac{Q}{2\pi a}$
so, $\vec{E} = \frac{Q}{4\pi\epsilon_0 R^2} \cdot \vec{a}_z$

Example: the finite sheet $0 \leq y \leq 1$ on the $z=0$ plane has a charge density $\rho_s = 2y(x^2 + y^2 + 25)^{3/2}$ nC/m²; find (a) total charge on sheet; (b) electric field at $(0, 0, 5)$; (c) the force experienced by a -1mC charge located at $(0, 0, 5)$.

So, $\int_S \rho_s \, ds$
 $= \int_0^1 \int_0^1 x(x^2 + y^2 + 25)^{3/2} \, dx \cdot y \, dy$

$$\begin{aligned} &= \frac{1}{2} \int_0^1 y dy \left[(y^2 + 25 + 1)^{5/2} - (y^2 + 25 + 0)^{5/2} \right] \\ &= \frac{1}{5} \times \frac{1}{2} \left[(27)^{5/2} - (26)^{5/2} - (26)^{5/2} + (25)^{5/2} \right] \\ &= 33.15 \text{ mC} \end{aligned}$$

(b) $E = \int \frac{\rho_s ds}{4\pi\epsilon_0 r^3} \vec{r}$

$$\begin{aligned} \vec{r} &= (0, 0, 5) - (x, y, 0) = (-x, -y, 5) \\ E &= \int_0^1 \int_0^1 \frac{1}{4\pi\epsilon_0} \frac{1}{(x^2 + y^2 + 25)^{3/2}} (-x a_x - y a_y + 5 a_z) dx dy \\ &= 9 \left[\frac{-1}{6}, \frac{-1}{6}, \frac{5}{4} \right] = (-1.5, -1.5, 11.25) \frac{V}{m} \end{aligned}$$

(c) $F = qE$
 $= 1 \text{ mC} (-1.5, -1.5, 11.25) \frac{V}{m}$
 $= (1.5, 1.5, 11.25) \text{ MN}$

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ELECTRIC FLUX DENSITY, GAUSS LAW & DIVERGENCE

flux: lines coming out of a point / surface
 electric lines \rightarrow electric field intensity flux

EFD (electric field density) = electric field
 Area

$\vec{D} = \epsilon_0 \vec{E} \rightarrow$ electric field intensity
 \downarrow permittivity

flux density

$$\Phi = \int \vec{D} \cdot d\vec{s}$$

Weber = C/m^2
 lines from a charge which passes through a surface in which the charge is enclosed.

- \vec{D} is function of charge distribution but is independent of medium.

as $D = \epsilon_0 E \Rightarrow$ all the formulas of D is independent so and dependent on E .

Ex:

Determine \vec{D} at $(4, 0, 3)$ if there is a point charge $-5\pi \text{ mC}$ at $(4, 0, 0)$ and a line charge $8\pi \text{ mC/m}$ along y -axis.

Sol:

$$E(\text{Point charge}) = \vec{E}_1 = \frac{q}{4\pi\epsilon_0 R^2} \hat{a}_z$$

$$\begin{aligned} \vec{R} &= (4, 0, 3) - (4, 0, 0) \\ &= (0, 0, 3) \end{aligned} \quad = \frac{-5\pi \times 10^{-3}}{4\pi\epsilon_0 \times 9} \frac{(0, 0, 3)}{3}$$

$$D = \epsilon_0 E$$

Gauss law :

- when symmetry is presence

Gauss's law is basically a way to find the electric field intensity, provided symmetry exists.

: advantage of gauss's law over coulomb's law \Rightarrow reduced complexity while showing solving and finding electric field intensity.

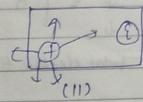
$$\Phi = \frac{Q_{enc}}{\epsilon_0}$$



flux would be zero when:

\hookrightarrow charge is zero

\hookrightarrow equal no. of pos. and neg. charges are there



fig(i) & fig(ii); flux is same.

$$\Phi = \text{Enclosed}$$

$$\Phi = \oint_S d\Phi = \oint_S \vec{D} \cdot d\vec{s} \quad \text{--- (2)}$$

$$d\text{Enclosed} = \oint_S \vec{D} \cdot d\vec{s}$$

Gauss's law in integral form :

$$\oint_S \vec{D} \cdot d\vec{s} = \oint_S \vec{B} \cdot d\vec{s} \quad \text{--- (3)}$$

\hookrightarrow prove

$$\vec{E} = \frac{Q}{4\pi\epsilon_0 s^2} \vec{a}_r$$

$$\vec{D} = \epsilon_0 \vec{E}$$

$$\vec{D} = \frac{Q \vec{a}_r}{4\pi s^2}$$

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$$D_s = \frac{Q a^2}{4\pi a^2}$$

$$ds = r^2 \sin\theta d\phi d\theta \quad \text{differential surface}$$

$$\text{So, } D_s \cdot ds = \frac{Q}{4\pi a^2} \cdot a^2 \sin\theta d\phi d\theta$$

by integrating

$$= \int_0^\pi \int_0^{2\pi} \frac{Q}{4\pi} \sin\theta d\phi d\theta$$

$$= \frac{Q}{4\pi} \times 2\pi \int_0^\pi \sin\theta d\theta$$

$$\int_S \vec{D} \cdot d\vec{s} = \frac{Q}{2} [\cos 0]_0^\pi = \frac{Q}{2} [1+1] = Q$$

(Enclosed) of electric flux crossing the surface as Q is enclosed in the surface.

Application of Gauss's law :

$$Q = \oint_S \vec{D} \cdot d\vec{s}$$

for find the total charge

\hookrightarrow $d\vec{s}$ either normal and tangential to the surface

normal $\rightarrow 0^\circ$

tangential $\rightarrow 90^\circ$

\hookrightarrow whether symmetry exist or not.

① Point charge :

radius of sphere = a

$$\text{total charge } Q = \oint_S D_s \cdot d\vec{s} \quad \vec{a} \cdot \vec{b} = ab \cos 0^\circ - ab \cos 90^\circ$$

ds is the normal to the sphere surface always

$$= \oint_S D_s \cdot ds$$

sph

$$= D_s \oint dS$$

$$= D_s \oint r^2 \sin\theta d\phi d\theta$$

$$= D_s \cdot r^2 \int_0^\pi \sin\theta d\theta \cdot 2\pi$$

$$= D_s \cdot r^2 \cdot 2\pi [-\cos\theta]_0^\pi$$

$$Q = 4\pi r^2 D_s$$

$$D_s = \frac{Q}{4\pi r^2}$$

flux density $\vec{D} = \frac{Q}{4\pi r^2} \hat{ar}$

field intensity $\vec{E} = \frac{Q}{4\pi \epsilon_0 r^2} \hat{ar}$

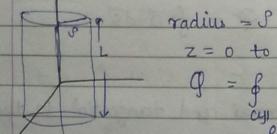
Conditions - field is symmetrical & radially directed outwards

② Line charges

- cylindrical surface

- $d\phi$ components is available

$$\vec{D} = \vec{D}_p \vec{dS}$$



radius = r

$z = 0$ to $z = L$

$$Q = \oint D_s \cdot d\vec{S}$$

cup

$$= \int_{\text{side}} D_s d\vec{S} + \int_{\text{top}} D_s d\vec{S} + \int_{\text{bottom}} D_s d\vec{S}$$

con 90° con 90°

$$Q = \int_{\text{side}} D_s d\vec{S} = D_s \int_{\text{side}} d\vec{S}$$

$$= D_s \cdot P \int_0^L dz$$

$$= D_s \cdot P \cdot 2\pi \int_0^L dz$$

$$Q = D_s \cdot P (2\pi L)$$

$$D_s = \frac{Q}{P 2\pi L}$$

$$Q = P_L \cdot L$$

$$D_s = \frac{P_L}{2\pi P} \rightarrow \text{electric field density}$$

$$E_p = \frac{P_L}{2\pi \epsilon_0 P} \text{ electric field intensity}$$

$$\Rightarrow \Phi = Q_{\text{closed}} = \vec{E} \cdot \vec{S} = E_s \cos\theta$$

when $\theta = 0$, Φ_{\max}

$\theta = 90^\circ$, Φ_{\min}

③ CO-axial wire?

inner radius = a

outer radius = b

$P_s \rightarrow$ charge distribution on outer surface of inner cord.



To when $a < r < b$

$$Q = D_s \cdot 2\pi r L \quad \text{--- (1)}$$

$$\text{inner conductor } Q = \int_{z=0}^L \int_{r=a}^b P_s a d\phi dz = 2\pi a L P_s \quad \text{--- (2)}$$

$$(1) = (2)$$

$$D_s \cdot 2\pi r L = 2\pi a L P_s$$

$$D_s = \frac{a P_s}{r}$$

$$\vec{D}_s = \frac{a P_s}{r} \hat{ar} \quad a < r < b$$

$$\text{charge per unit length } P_s = \frac{P_L}{2\pi a}$$

$$\vec{D}_s = \frac{a P_L}{2\pi a} \hat{ar} \quad \text{same as line charge}$$

$$\nabla = \frac{\partial \vec{a}_x}{\partial x} + \frac{\partial \vec{a}_y}{\partial y} + \frac{\partial \vec{a}_z}{\partial z}$$

- The divergence of \vec{A} at a given point P is the constant flux per unit volume at the volume about P .
 $\text{div } \vec{A} = \nabla \cdot \vec{A} = \lim_{\Delta V \rightarrow 0} \frac{\oint_S \vec{A} \cdot d\vec{s}}{\Delta V}$
- Divergence of the vector field \vec{A} at a given point as a measure of how much the field diverges or emanates from the point.

*
$$\frac{\partial D_x}{\partial x} + \frac{\partial D_y}{\partial y} + \frac{\partial D_z}{\partial z} = \frac{\oint_S \vec{D} \cdot d\vec{s}}{\Delta V} = \frac{\Phi}{\Delta V}$$

 (volume is shrinking) $= \lim_{\Delta V \rightarrow 0} \frac{\oint_S \vec{D} \cdot d\vec{s}}{\Delta V} = \lim_{\Delta V \rightarrow 0} \frac{\Phi}{\Delta V}$
 $= \lim_{\Delta V \rightarrow 0} \rho_V$

- "divergence" of any vector \vec{A} , outflow of flux from a closed surface as volume shrinks. results obtained as scalar.

$$\text{div } \vec{A} = \lim_{\Delta V \rightarrow 0} \frac{\oint_S \vec{A} \cdot d\vec{s}}{\Delta V}$$

rectangular: $\text{div } \vec{B} = \frac{\partial D_x}{\partial x} + \frac{\partial D_y}{\partial y} + \frac{\partial D_z}{\partial z}$

cylindrical: $\text{div } \vec{B} = \frac{1}{r} \frac{\partial (r D_\phi)}{\partial r} + \frac{1}{r^2} \frac{\partial D_\phi}{\partial \phi} + \frac{\partial D_z}{\partial z}$

spherical: $\text{div } \vec{B} = \frac{1}{r^2} \frac{\partial (r^2 D_r)}{\partial r} + \frac{1}{r^2 \sin \theta} \frac{\partial (r^2 D_\theta)}{\partial \theta} + \frac{1}{r^2 \sin^2 \theta} \frac{\partial D_\phi}{\partial \phi}$

Ex 8 - Find $\text{div } \vec{B}$ at the origin if

Sol:
$$\vec{B} = e^{-x} \sin y \vec{a}_x - e^{-x} \cos y \vec{a}_y + 2z \vec{a}_z$$

$$\text{div } \vec{B} = -e^{-x} \sin y + e^{-x} \cos y + 2$$

$$= 2$$

Maxwell's first equation:

- for only electrostatics

$$\text{div } \vec{D} = \frac{\partial D_x}{\partial x} + \frac{\partial D_y}{\partial y} + \frac{\partial D_z}{\partial z}$$

$$= \lim_{\Delta V \rightarrow 0} \frac{\oint_S \vec{D} \cdot d\vec{s}}{\Delta V}$$

$$\text{div } \vec{D} = \rho_V - Q$$

↳ it's also called Point form of Gauss law / Differential eqn form of Gauss' law
 * Gauss law \leftarrow integral form of Maxwell 1st eqn
 charge enclosed by the surface = flux

vector operator ∇ :

$$\nabla = \frac{\partial \vec{a}_x}{\partial x} + \frac{\partial \vec{a}_y}{\partial y} + \frac{\partial \vec{a}_z}{\partial z}$$

$$\nabla \cdot \vec{D} = (\quad) (D_x \vec{a}_x + D_y \vec{a}_y + D_z \vec{a}_z)$$

$$\text{div } \vec{D} = \frac{\partial D_x}{\partial x} + \frac{\partial D_y}{\partial y} + \frac{\partial D_z}{\partial z}$$

Divergence theorem:

Gauss law $\Phi = \oint_S \vec{D} \cdot d\vec{s}$

$$\int_C \rho_V dV = \oint_S \vec{D} \cdot d\vec{s}$$

$$\int \nabla \cdot \vec{D} dV = \oint_S \vec{D} \cdot d\vec{s}$$

II Divergence theorem: the integral of normal component of any vector field over a closed surface is equal to the integral of the divergence of this vector field through out the volume enclosed by the closed surface.

Chm - Given a vector, proved divergence surface

Example: A non-uniform surface charge density of $\frac{5\rho}{\rho^2+1} \text{ nC/m}^2$ lies in the plane $z=2$; where

$$\rho_s = \begin{cases} 5\rho/\rho^2+1 & ; \rho \leq 5 \\ 0 & ; \rho > 5 \end{cases}$$

How much electric flux leaves the circular region $\rho \leq 5$ at $z=2$:

Sol:

$$\Phi = \oint \vec{E} \cdot d\vec{s}$$

$$\Rightarrow \Phi = \int d\Omega$$

$$= \int \rho_s \cdot ds$$

$$= \int \rho_s \cdot \rho d\rho d\phi$$

$$= \int_0^{2\pi} \int_0^5 \frac{5\rho^2}{\rho^2+1} d\rho d\phi$$

$$= 2\pi \cdot 5 \int_0^5 \frac{\rho^2+1-1}{1+\rho^2} d\rho$$

$$= 10\pi \left[\rho - \tan^{-1}\rho \right]_0^5$$

$$= 10\pi [5 - \tan^{-1}(5)]$$

$$= 113.39 \text{ nC/m}^2$$

Example: Given that $\vec{D} = z \rho \cos^2\phi \hat{a}_z \text{ C/m}^2$ calculate the charge density at $(1, \pi/4, 3)$

the total charge enclosed by the cylinder of radius $\rho = 1 \text{ m}$ with $-2 \leq z \leq 2 \text{ m}$

Sol:

$$\rho_v = \nabla \cdot \vec{D}$$

$$x = \rho \cos\phi = \frac{1}{\sqrt{2}}$$

$$y = \rho \sin\phi = \frac{1}{\sqrt{2}}y$$

$$= \rho \cos^2\phi$$

$$= \rho \cdot \cos^2(\pi/4) = 1/2 \text{ C/m}^3$$

V/V

$$\Phi = \oint \rho_v dV$$

$$= \int_2^2 \int_0^{2\pi} \int_0^1 \rho^2 d\phi dz d\rho$$

$$= \frac{1}{2} \times \frac{\pi}{4} \int_2^2 \int_0^1 \rho^2 d\rho dz$$

$$= \frac{\pi}{8} (\rho^3)_0^1 \int_2^2 dz$$

$$= \frac{\pi}{8} \times \frac{1}{3} (2+2) = \frac{\pi}{4}$$

=