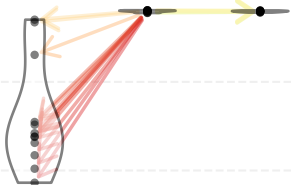
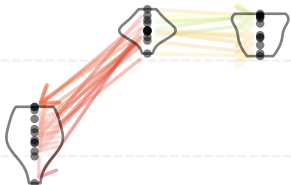


Policy evaluations on sim S

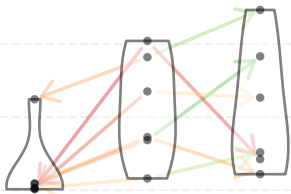
Pendulum



Reacher



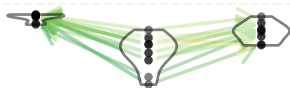
Lunar Lander


 $\pi_T \xleftarrow{\text{naive}} \pi_S \xrightarrow{\text{ours}} \pi_T^\psi$ 

Policy evaluations on sim T

Rewards

400  
300  
200



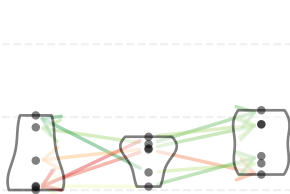
Rewards

300  
200



Rewards

200  
100  
0


 $\pi_T \xleftarrow{\text{naive}} \pi_S \xrightarrow{\text{ours}} \pi_T^\psi$