

Rust and its usage as Python extensions

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Summary

1. Rust programming language introduction
2. Use of Rust extension codes into the **cdshealpix** Python package
3. **cdshealpix** deployment for Windows, MacOS and Linux

Part I: Rust programming language presentation

Rust Presentation

- ▶ Rust is a compiled system programming language (no garbage collector!)
- ▶ It tries to detect as much errors as possible statically (i.e. during the compilation)
- ▶ Therefore, it embeds some “rules” to guide/force you to code in a safety way
- ▶ These rules prevent your code to have segmentation faults, dereference null pointers, etc. . .

What are these “rules” about ?

The ownership concept

- ▶ At any time, a resource is owned by exactly one scope!
- ▶ When the resource goes out of its scope, it gets freed

The borrowing

- ▶ A scope (e.g. other methods) can borrow a resource: this is done by references
- ▶ Two types of borrowing: immutably (&, default behaviour) and mutably (&mut)
- ▶ When the reference goes out of the scope, the ownership is restored to the caller. The resource is not dropped
- ▶ At any time, you can either have:
 - ▶ one and only one mut ref to a resource
 - ▶ several immutable refs to the same resource

Lifetime annotation of references

- ▶ lifetime annotations ensure that referenced resources always outlive object instances that refer them.

Some Rust nice features

- ▶ The cargo package manager. All rust dependency libs (called **crates**) are written in a *Cargo.toml* configuration file at the root of the project.

```
[package]
name = "cdshealpix_python"
version = "0.1.10"
...
```

```
[dependencies]
# From github repo
cdshealpix = { git = 'https://github.com/
  cds-astro/cds-healpix-rust', branch = 'master' }
# or from crates.io
cdshealpix = "0.1.5"
```

- ▶ Safety: ownership, borrowing, lifetimes
- ▶ Performance:
 - ▶ No garbage collector but strong rules checked during the compilation! This force the programmer to code in a “safer” way, think about the reference lifetimes etc. . .
 - ▶ Zero-cost abstractions:
 - ▶ *Common collections* given by the standard library: Vec, HashMap
 - ▶ *Generics*: statically generation of Rust code auto-inlined by the compiler.
 - ▶ Iterators with *map*, *filter*, . . . , defined on them
 - ▶ Lambda functions (called *closures*)
 - ▶ *Object oriented*, Traits are java-like interfaces, no data attribute inheritance.
 - ▶ *Error handling*
 - ▶ Strong typing and type inference
- ▶ *Concurrency*: some primitives implemented in the std library: Mutexes, RWLocks, Atomics.
- ▶ See the well-explained *official documentation* and *Rust by examples* for more infos!

Where is Rust used and by who ?

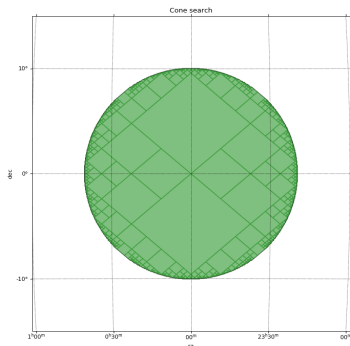
- ▶ Quite new: 1.0.0 released in 2015
- ▶ *Most Loved languages*. Rust is 1st, Kotlin 2nd, Python 3rd, . . . , C++ 22th. For the third year in a row **Rust** is the **most loved** language.
- ▶ Begin to be used in the game industry as a replacement for C++. See *here*.
- ▶ Over 70% of developers who work with Rust contribute to **open source** (*stackoverflow latest 2018 survey*)

Part II: use of Rust extension codes into the **cdshealpix** Python package

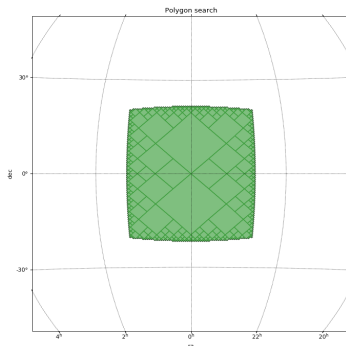
cdshealpix presentation

- ▶ HEALPix python package wrapping the *cdshealpix* Rust crate developed by FX Pineau.
- ▶ Provides `healpix_to_lonlat`, `lonlat_to_healpix`, `vertices`, `neighbours`, `cone_search`, `polygon_search` and `elliptical_cone_search` methods.

Cone Search



Polygon Search



cdshealpix: How does the binding works ?

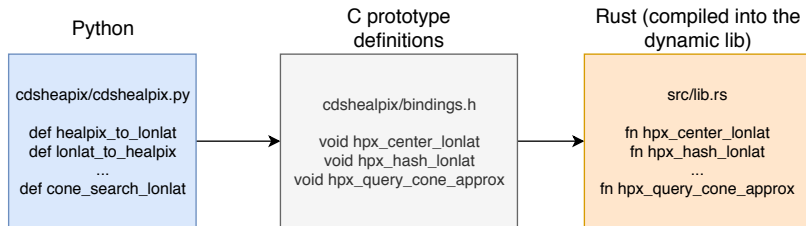


Figure 1: Python -> C -> Rust bindings

- ▶ Python sees Rust code the same way as C
- ▶ Rust functions can be **externed** as if it would be C. This is what we use for Python to call Rust functions!

cdshealpix: Python interface

- ▶ Use of *CFFI* (C Foreign Function Interface for Python) to load the dynamic library compiled (.so or .pyd for Windows) with cargo (Rust compiler)
- ▶ This is done as soon as the user imports something from **cdshealpix** (in the `__init__.py` file).

Content of cdshealpix/_init_.py

```
import os
import sys
from cffi import FFI

ffi = FFI()
# Open and read the C function prototypes
with open(
    os.path.join(
        os.path.dirname(__file__),
        "bindings.h"
    ),
    "r") as f_in:
    ffi.cdef(f_in.read())

# Open the dynamic library generated by setuptools_rust
dyn_lib_path = find_dynamic_lib_file()
lib = ffi.dlopen(dyn_lib_path)
```

cdshealpix: Python interface

- ▶ Then **lib** and **ffi** can be imported in cdshealpix/cdshealpix.py

```
# Beginning of cdshealpix.py
```

```
from . import lib, ffi
```

- ▶ To call Rust code, just run:

```
lib.<rust_method>(args...)
```

cdshealpix examples: lonlat_to_healpix

- ▶ Let's dive into how **lonlat_to_healpix** is wrapped around **hpx_hash_lonlat**
- ▶ **lonlat_to_healpix** in cdshealpix/cdshealpix.py

```
def lonlat_to_healpix(lon, lat, depth):  
    # Handle zero dim lon, lat array cases  
    lon = np.atleast_1d(lon.to_value(u.rad)).ravel()  
    lat = np.atleast_1d(lat.to_value(u.rad)).ravel()  
  
    if lon.shape != lat.shape:  
        raise ValueError("The number of longitudes does \  
        not match with the number of latitudes given")
```

```
num_ipixels = lon.shape[0]
# We know the size of the returned HEALPix cells
# So we allocate an array from the Python code side
ipixels = np.zeros(num_ipixels, dtype=np.uint64)
# Dynamic library call
lib.hpx_hash_lonlat(
    # depth
    depth,
    # num of ipixels
    num_ipixels,
    # lon, lat
    ffi.cast("const double*", lon.ctypes.data),
    ffi.cast("const double*", lat.ctypes.data),
    # result
    ffi.cast("uint64_t*", ipixels.ctypes.data)
)

return ipixels
```


- ▶ C `hpx_hash_lonlat` prototype defined in `cdshealpix/bindings.h`

```
void hpx_hash_lonlat(  
  uint8_t depth,  
  uint32_t num_coords,  
  const double* lon,  
  const double* lat,  
  uint64_t* ipixels);
```

Rust hpx_hash_lonlat in src/lib.rs

```
#[no_mangle]
pub extern "C" fn hpx_hash_lonlat(
    depth: u8,
    num_coords: u32,
    lon: *const f64, lat: *const f64,
    ipixels: *mut u64,
) {
    let num_coords = num_coords as usize;

    let lon = to_slice(lon, num_coords);
    let lat = to_slice(lat, num_coords);
    let ipix = to_slice_mut(ipixels, num_coords);

    let layer = get_or_create(depth);
    for i in 0..num_coords {
        ipix[i] = layer.hash(lon[i], lat[i]);
    }
}
```

Conclusion

- ▶ Quite readable and only few lines of code:
 1. Some test exceptions
 2. One numpy array allocation
 3. The call to the dynamic library (some casts to match the C prototype)
- ▶ Whenever it is possible (size of the returned HEALPix cell array known) one should always allocate memory content in the Python side because it is auto garbage collected!
- ▶ \Rightarrow No need to think about free the content!
- ▶ If memory has to be allocated by the dynamic library \Rightarrow do not forget to call later the lib to deallocate the memory space! Let's see another example to illustrate that case !

cdshealpix examples: cone_search_lonlat

- ▶ The Python-side code does not know how much HEALPix cells will be returned by **hpx_query_cone_search**
- ▶ Thus, allocation must necessary be done in the Rust-side

Rust hpx_query_cone_search in src/lib.rs

```
#[no_mangle]
pub extern "C" fn hpx_query_cone_approx(
    depth: u8, delta_depth: u8,
    lon: f64, lat: f64, radius: f64
) -> *const PyBMOCell {
    let bmoc = cone_coverage_approx_custom(
        depth, delta_depth, lon, lat, radius,
    );

    let cells: Vec<BMOCell> = to_bmoc_cell_array(bmoc);
    let len = cells.len() as u32;
    // Allocation here
    let bmoc = Box::new(PyBMOCell { len, cells });
    // Returns a raw pointer to a struct containing
    // * the num of HEALPix cells
    // * the array of cells
    Box::into_raw(bmoc)
}
```

- ▶ Deallocation can only be done in the Rust side too!
- ▶ Thus, Python-side must call this method

```
#[no_mangle]
pub extern "C" fn bmoc_free(ptr: *mut PyBMOC) {
    if !ptr.is_null() {
        unsafe {
            Box::from_raw(ptr)
            // Drop the content of the PyBMOC here.
        };
    }
}
```

- ▶ If not called, we would have memory leaks.

- ▶ This is something the Python user should not bother to do!
- ▶ Solution: wraps the result of **hpx_query_cone_approx** structure into a class

```
class ConeSearchLonLat(object):  
    def __init__(self, d, delta_d, lon, lat, r):  
        self.data = lib.hpx_query_cone_approx(  
            d, depth_d, lon, lat, r  
        )  
  
    def __enter__(self):  
        return self  
  
    # Called when garbage collected  
    def __del__(self):  
        lib.bmoc_free(self.data)  
        self.data = None
```

`cone_search_lonlat` in `cdshealpix/cdshealpix.py`

```
def cone_search_lonlat(lon, lat, radius,
    depth, delta_depth):
    # Exceptions handling
    ...

    lon = lon.to_value(u.rad)
    lat = lat.to_value(u.rad)
    radius = radius.to_value(u.rad)

    cone = ConeSearchLonLat(
        depth, depth_delta,
        lon, lat, radius)
    return cone.data
```


Part III: **cdshealpix** deployment for Windows, MacOS and Linux

Setuptools_rust

- ▶ setuptools_rust package is used to:
 1. Build the dynamic library (need cargo compiled installed)
 2. Pack all the python files contained **cdshealpix/** + the dynamic library into a wheel

Content of the setup.py

```
setup(...  
    rust_extensions=[RustExtension(  
        # Package name  
        "cdshealpix.cdshealpix",  
        # The path to the Cargo.toml.  
        # Contains the dependencies of the Rust side code  
        'Cargo.toml',  
        # CFFI bindings  
        binding=Binding.NoBinding,  
        # --release option for cargo  
        debug=False)],  
    ...)
```

- ▶ `python setup.py build_wheel/install` will build the wheel into a `.whl` file for the host architecture (resp. install `cdshealpix` into your local machine)

Travis-CI

- ▶ Travis-CI is used for testing and deploying the wheels for Linux and MacOS
- ▶ The *.travis.yml* contains 2 stages: a testing & a deployment one
- ▶ Each stage is divided into jobs responsible for testing (resp. deploying) **cdshealpix** for a specific platform and python version.
- ▶ Deployment jobs use *cibuildwheel* tool. cibuildwheel uses docker with manylinux32/64bits images for generating the wheels for linux.
- ▶ See the script for deploying the wheels for linux/macos *here*.

Questions ?