Deep Molecular Graph InfoMax

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Abstract

Machine learning has shown promise in tackling various problems in drug discovery; however, the shortage of annotated data is still a major obstacle to its success. To address this limitation, we introduce *Deep Molecular Graph InfoMax*, a framework for the completely unsupervised learning of molecular graph-level representations. Unlike previous work on graphs that leverage mutual information between homogeneous views of data, we focus on an approach that additionally utilizes auxiliary molecular descriptors and provides flexible objectives for better generalization. We demonstrate that our model is competitive with strong baselines when generating representations in the fully unsupervised setting.

1. Introduction

Traditional drug development is a complex, costly, and lengthy process that typically spans more than a decade (DiMasi et al., 2018). To this extent, machine learning techniques have been of particular interest in the application of several stages of the drug discovery pipeline, such as in prediction mechanisms and target identification. Recently, there have been significant advances in applying supervised graph neural networks (Bruna et al., 2014; Duvenaud et al., 2015; Gilmer et al., 2017; Schutt et al., 2016), which satisfy the rotational, translational and permutational invariances of molecules naturally, to property prediction tasks.

Indeed, representation learning has shown strong potential to address the shortcomings of conventional quantum mechanical simulations methods such as Density Function Theory (Capelle, 2006), used in both biological and materials science. It treats the problem of representing graph structure as a machine learning task itself by using a data-driven approach to learn embeddings (Hamilton et al., 2017). How-

School of Computer Science, McGill University Mila, Quebec Artificial Intelligence Institute ever, the tradeoff between accuracy and computational cost, and the limited amount of labeled training data remains a challenge. The latter is partly due to legal and privacy constraints on work with sensitive health records in the pharmaceutical industry. As such, learning good representations without relying on annotations is an essential step towards improving machine learning models for drug development.

Sun et al. (2020) proposed an unsupervised graph-level representation learning model termed InfoGraph. The impressive results of Deep InfoMax (Hjelm et al., 2018) motivated the creation of this model, which utilizes mutual information (MI) maximization for unsupervised learning between graph-level representations and the representations of substructures of different granularity. Inspired by this recent work on DIM and InfoGraph, we present a novel method for learning representations in an unsupervised manner between molecular graphs and Simplified Molecular-Input Line-Entry System (SMILES) strings based representations (Daylight Chemical Information Systems, 2019; Weininger, 1988). Our contributions can be summarized as follows:

- We propose learning efficient molecular representation via MI maximization between heterogeneous views of molecular data.
- We show that performing MI maximization between high-level representations can significantly enhance graph-level embeddings and surpass strong baselines on a property prediction task.

2. Related Work

Our framework builds upon recent research based on deep learning on molecular data, particularly graph representation learning.

A diverse set of work on molecular deep learning models has been presented to advance the drug discovery process. Early work involved fingerprinting methods, used in the training of neural networks, with one of the most prevalent techniques being the Extended Connectivity FingerPrinting (Rogers & Hahn, 2010). Later on, other architectures that directly operate on graphs such as neural fingerprints (Duvenaud et al., 2015) and molecular graph convolutions (Kearnes et al., 2016) emerged. These approaches have been

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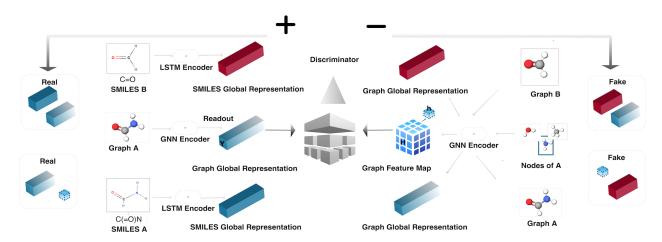


Figure 1. Model Architecture: Deep Molecular Graph InfoMax is a combination of both global mutual information maximization (left) and local mutual information maximization (right) schemes. The influence of both global and local objectives is determined by the choice of hyperparameters α and β .

included in the message passing neural networks (MPNNs) framework which consists of other supervised graph neural networks (Defferrard et al., 2016; Li et al., 2016).

Deep Graph InfoMax (DGI) (Velickovic et al., 2018) and InfoGraph (Sun et al., 2020) are two notable unsupervised graph representation learning approaches that have been recently proposed. The former is a node-level learning technique that relies on applying the objective function between patch representations and corresponding high-level summaries of graphs, whereas the latter focuses on learning graph-level representations in both unsupervised and semi-supervised scenarios via mutual-information maximization.

Similar to InfoGraph, we propose an unsupervised algorithm to learn graph-level representations of molecules. However, in contrast to InfoGraph, our method not only offers the flexibility to focus on the global structure of the graph representation, but it also incorporates representations of auxiliary molecular descriptors.

3. Proposed Method

In this section, we discuss the intuition behind our framework and formulate the problem of learning representations for molecular graphs. Then, we expose the unsupervised learning setup of graph-level representations that focuses on utilizing high-level representations of heterogeneous views of molecular data. We then outline the setting based on maximizing the multual information (MI) between representations of subsets of the graph, such as the nodes, and the information content of the entire graph.

3.1. Model Intuition

Given a dataset of multiple different molecules represented as both graphs $G = \{G_1, G_2, ...\}$ and SMILES $S = \{S_1, S_2, ...\}$, our objective is to learn meaningful embeddings by utilizing the gradients from the discriminators to help train their respective encoder's network.

Each graph representation, with n total number of nodes, is composed of a set of node embeddings h such that $H = \{h_1, h_2, ...h_n\}$ denotes the summary representation of all nodes/patch representations of the graph. The feature vector of a molecular SMILES based representation or graph is expressed as Y. In the case that entirely prioritizes global information content, our model maximizes MI by discriminating the summarized graph representation from the global SMILES representation. Equivalently, in the localized version, the discriminator is trained to distinguish the summarized graph representation from its node representations. We implement our framework with the encoders and discriminators specified in the subsection below.

3.2. Encoders and Discriminators

SMILES Strings Encoder The Simplified Molecular-Input Line-Entry System (SMILES) is a string-based representation of molecules that was introduced in the late 1980s and represents a universal standard for many software applications. Numerous studies have demonstrated the effectiveness of models based on SMILES fed to neural networks such as RNNs (Goh & N. Hodas; Wu et al., 2018). In order to enforce permutational invariance and uniqueness, we use the canonicalized representation of the molecule's SMILES representation as a 1-hot-encoding input to an LSTM en-

coder network. The LSTM is used both as part the DMGI framework, but also as a competitive baseline (i.e, as an LSTM autoencoder) in order to gauge the quality of our model.

Graph Model Encoder As in InfoGraph, we choose a Message Passing Neural Networks (MPNNs) (enn-s2) introduced by Gilmer et al. (2017) as our main graph encoder. On an undirected graph G = (V, E) with node features x_v , edge features e_{vw} and a neighborhood defined as N(v), a message passing process is composed of two phases, a messaging phase (1) and (2) a readout phase (3). The general message passing phase is defined by the following formula:

$$\mathbf{m}_v^{t+1} = \sum_{w \in N(v)} \mathbf{M}_t(\mathbf{h}_v^t, \mathbf{h}_w^t, \mathbf{e}_{vw}) \tag{1}$$

$$\mathbf{h}_{v}^{t+1} = \mathbf{U}_{t}(\mathbf{h}_{v}^{t}, \mathbf{m}_{v}^{t+1}),$$
 (2)

where the message \mathbf{m}_v^{t+1} is the transition function that propagates information and \mathbf{h}_v^t denotes the hidden states that are updated for T iterations. The readout phase (3), which is computed with a readout function R, generates a representation of the entire graph based on node and edge hidden representations.

$$\hat{\mathbf{y}} = \mathbf{R}\Big(\{h_v^t | \mathbf{v}\epsilon G\}\Big). \tag{3}$$

The (enn-s2s) MPNN variation is constructed with the continuous edge network message function, a gated recurrent unit (Chung et al., 2014) update function, and a Set2Set (Vinyals & S. Bengio, 2015) readout operator. The power of this encoder can be attributed to the inclusion of edge attributes which is an essential feature for molecules.

Discriminators Both graph and SMILES string-based descriptor discriminators are implemented as feed-forward neural networks.

3.3. Objective Function

We select the Jensen Shannon Divergence (JSD) estimator as the main objective function of our model. The generic formula of the JSD we will be following throughout the rest of the paper is:

$$\begin{aligned} & \max I^{JSD}\left(X;Y\right) := \max D_{JS}\left(P\left(X,Y\right) || P\left(X\right) P\left(Y\right)\right) \\ & = \max \left(2\log 2 + E_{p\left(x,y\right)}\left[-\operatorname{sp}\left(-\operatorname{T}\left(x,y\right)\right)\right] \end{aligned} \tag{4}$$

$$-E_{p(x)p(y)} \left[\operatorname{sp} \left(\operatorname{T} \left(x^{'}, y \right) \right) \right] \right), \tag{5}$$

where sp denotes the softplus function. Here, we maximize the lower bound on the JSD the divergence, where T is the discriminator, x is an input sampled from P and $x^{'}$ is the negative input pair. More specifically, we generate useful representations by training the discriminator T to estimate the JSD divergence and train the encoder to minimize this estimate. Similarly to InfoGraph, negative samples are generated by permuting the batch.

3.4. Global Mutual Information Maximization

Our model architecture is illustrated in Figure 1, where the global MI maximization is on the left of the discriminator. We can express the global objective function as:

$$\max_{\phi\omega_{1}} I_{\phi\omega_{1}} \left(Y_{1\phi} \left(G \right); Y_{2\phi} \left(S \right) \right). \tag{6}$$

Let I denote the mathematical notation of mutual information between the global representation Y_1 and Y_2 after applying the readout operations of the graph (G) and LSTM (S) encoders, respectively.

3.5. Local Mutual Information Maximization

The local MI maximization approach illustrated on the right of Figure 1 is equivalent to InfoGraph and DIM methodology to some extent. Here, I designates the mutual information between the patch representation h centered at an arbitrary node of G and the global representation Y after applying the readout operation.

$$\max_{\phi\omega} \sum_{G \in G} \frac{1}{|G|} I_{\phi\omega}(h_{\phi}(G); Y_{\phi}(G)). \tag{7}$$

We note that most, if not all existing graph representation learning work on MI maximization, present the local MI maximization as a more robust, or suitable objective than global or combinations of global and local objectives.

3.6. Deep Molecular Graph InfoMax

As the generic version of our model, we define the complete objective for DMGI below:

$$\alpha \max_{\phi\omega_1} I_{\phi\omega_1}(Y_{1\phi}(G); Y_{2\phi}(S))$$

$$+ \beta \max_{\phi\omega_2} \sum_{G \in G} \frac{1}{|G|} I_{\phi\omega_2}(h_{\phi}(G); Y_{\phi}(G)). \tag{8}$$

where α and β are hyper-parameters for the global and local objectives, respectively. Both α and β are arbitrarily set to 0.5 in our experiments. Similarly to DIM, integrating the hyper-parameters allows us to exercise control over the information, either locally or globally. However, in contrast to DIM, we do not impose structural constraints on high-level representations with prior matching.

Table 1. Mean absolute error (MAE) accuracy results on QM9 molecular property prediction regression task. We compare our model with an LSTM autoencoder (LSTM-AE), and InfoGraph which is the same as DMGI-Local. DMGI-Global refers to the global mutual information maximization objective as the name implies, and DMGI denotes the generic model with parameters α and β arbitrarily set to 0.5 each.

TARGET	LSTM-AE	INFOGRAPH	DMGI-GLOBAL	DMGI
MU	1.2639	0.8231	0.8168	0.8450
ALPHA	5.0834	2.2483	1.8585	2.5098
Номо	0.0169	0.0108	0.0111	0.0106
Lumo	0.0380	0.0153	0.0154	0.0150
GAP	0.0357	0.0182	0.0194	0.0184
R2	204.9099	52.3440	42.4115	46.4030
ZVPE	0.0239	0.0052	0.0050	0.0047
U	24.4618	11.4668	10.3556	11.9785
U0	30.9940	11.6948	9.8761	12.1456
H	22.7233	11.3416	10.0502	12.0853
G	28.8239	11.5395	9.9134	11.2979
Cv	2.6136	1.1697	0.7131	1.0836

4. Experiments and Analysis

In this section, we empirically evaluate the performance of our model on a molecular property prediction task.

4.1. Dataset and Setup

We use the Quantum Machine 9 (QM9) dataset (Ramakrishnan et al., 2014; Ruddigkeit et al., 2012) as our benchmark. It is composed of 134k molecules which are modeled using Density Functional Theory, and their properties are related to atomization energies, fundamental vibration frequency, states of electrons and measures of spatial distributions of the molecules (Gilmer et al., 2017).

All graph and LSTM based models are implemented using the PyTorch Geometric (Fey & Lenssen, 2019) and PyTorch (Paszke et al., 2017) deep learning libraries.

4.2. Results and Discussion

Table 1 shows the results of the QM9 property prediction task. We observe that DMGI-Global outperforms all other unsupervised learning methods on 8 out of 12 target properties. More specifically, the methodology with the global objective distinctly achieves a lower MAE on all targets related to atomization energies (U, U0, H, G), spatial distributions of electrons in a molecule (alpha, R2) and the heat capacity (Cv). We find that the results obtained for properties related to fundamental vibrations of the molecule (HOMO, LUMO, and gap) are slightly better with local or combined objectives of our framework.

Property prediction is a complex task; however, our results demonstrate that prioritizing global structure can be

more suitable in some scenarios. It is possible that the model based on the local objective discards, or misinterprets edge attributes as noise. Further analysis will need to be conducted in future work, in order to determine an exact theoretical explanation.

5. Conclusion

In this paper, we presented Deep Molecular Graph Info-Max, an unsupervised representation learning technique to learn graph-level embeddings of molecules of arbitrary sizes. Through our experiments involving the QM9 benchmark dataset, we demonstrated that our framework surpasses two strong baselines, namely an LSTM autoencoder and Info-Graph. Although our experiments are task-specific, they still demonstrate the effectiveness of the introduced method, and prove that it is a methodology worth investigating.

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6. Appendix

6.1. Model Configuration

Our SMILES-based text encoding is composed of 19 different characters for QM9, and the largest molecule size (i.e 26) is the maximum length of characters fed to the LSTM. In the case of the graph encoding, the input representation at the node level consists of different atomic properties such as the atomic nuclear charge, the hybridization state, and the features at the edge level consists of the number of bonds.

We use Infograph and the PyTorch Geometric QM9 intialization implementations as basis for constructing our model. For all of the tasks, we first standardize the target values using Scikit-learn StandardScaler (Pedregosa et al., 2011), so that all targets have a mean of zero and unit variance.

All of our models are trained with the Adam optimizer (Kingma & Ba, 2014) for 10 epochs, at a constant learning rate of 1e-3, and a batch of size 64. The performance of our models are assessed on a molecular property prediction task with 16000 molecules (due to resource contsraints), where we use the embeddings learned on the completely unsupervised setting. We train a kernel ridge regression classifier with 50% of the samples, select a Laplacian kernel, and set alpha to 10^{-3} . For each model, we evaluate the performance on 25% of the data and report the mean absolute error on the test set (i.e remaining samples).