COMP396

Meeting 5

Summary

- 1. Recall
- 2. Relevant Papers
- 3. Supporting Material
- 4. JSD
- 5. Code
- 6. What I don't understand yet?

Recall

- We had an overview of DIM objective functions
- Discussed points to focus on (i.e infograph and JSD)

Relevant Papers

- -LEARNING DEEP REPRESENTATIONS BY MUTUAL INFORMATION ESTIMATION AND MAXIMIZATION->https://arxiv.org/pdf/1808.06670.pdf
- -DEEP GRAPH INFOMAX: https://arxiv.org/pdf/1809.10341.pdf
- -INFOGRAPH: UNSUPERVISED AND SEMI-SUPERVISED GRAPH-LEVEL REPRESENTATION LEARNING VIA MUTUAL INFORMATION MAXIMIZATION->https://arxiv.org/pdf/1908.01000.pdf

Supporting Material

-Mean teachers are better role models: Weight-averaged consistency targets improve semi-supervised deep learning results-> https://arxiv.org/pdf/1703.01780.pdf

FASTGCN: FAST LEARNING WITH GRAPH CONVOLUTIONAL NETWORKS VIA IMPORTANCE SAMPLING-> https://arxiv.org/pdf/1801.10247.pdf

Mutual Information Neural Estimation->https://arxiv.org/pdf/1801.04062.pdf

f-GAN: Training Generative Neural Samplers using Variational Divergence Minimization https://arxiv.org/pdf/1606.00709.pdf

HOW POWERFUL ARE GRAPH NEURAL NETWORKS?

JSD

The mutual information estimator modeled by discriminator $T\psi$

$$I_{\phi,\psi}(h_{\phi}^{i}(G); H_{\phi}(G)) := \mathbb{E}_{\mathbb{P}}[-\operatorname{sp}(-T_{\phi,\psi}(\vec{h}_{\phi}^{i}(x), H_{\phi}(x)))] - \mathbb{E}_{\mathbb{P} \times \tilde{\mathbb{P}}}[\operatorname{sp}(T_{\phi,\psi}(\vec{h}_{\phi}^{i}(x'), H_{\phi}(x)))]$$
(5)

Unsupervised learning

h is the summarized patch representation centered at node u and $H\phi(G)$ is the global representation after applying READOUT.

$$\hat{\phi}, \hat{\psi} = \underset{\phi, \psi}{\operatorname{arg\,max}} \sum_{G \in \mathbf{G}} \frac{1}{|G|} \sum_{u \in G} I_{\phi, \psi}(\vec{h}_{\phi}^{u}; H_{\phi}(G)). \tag{4}$$

Here we use GIN:

Semi-supervised learning

$$L_{\text{total}} = \sum_{i=1}^{|\mathbb{G}^L|} L_{\text{supervised}}(y_{\phi}(G_i), o_i) + \sum_{j=1}^{|\mathbb{G}^L| + |\mathbb{G}^U|} L_{\text{unsupervised}}(h_{\varphi}(G_j); H_{\varphi}(G_j))$$
(7)

$$-\lambda \sum_{j=1}^{|\mathbb{G}^L|+|\mathbb{G}^U|} \frac{1}{|G_j|} \sum_{k=1}^K I(H_{\phi}^k(G_j); H_{\varphi}^k(G_j). \tag{8}$$

Code (setup)

https://colab.research.google.com/drive/1XC2H9SzhT7myepPNJO8WX0hoDBRuhFcV

NB: parameters are not correctly set as in the actual experiment

Materials & Resources

InfoGraph Code: https://github.com/fanyun-sun/InfoGraph

Deep Graph Infomax (Original): https://github.com/PetarV-/DGI

Deep Graph Infomax:

https://github.com/rusty1s/pytorch_geometric/blob/master/torch_geometric/nn/models/deep_graph_infomax.py

What I don't understand yet

- relationship between mean teacher and how mean teacher is used here (function) is ambiguous

To do:

Focus on global global (smiles + graph) + local global (node, readout) unsupervised DIM