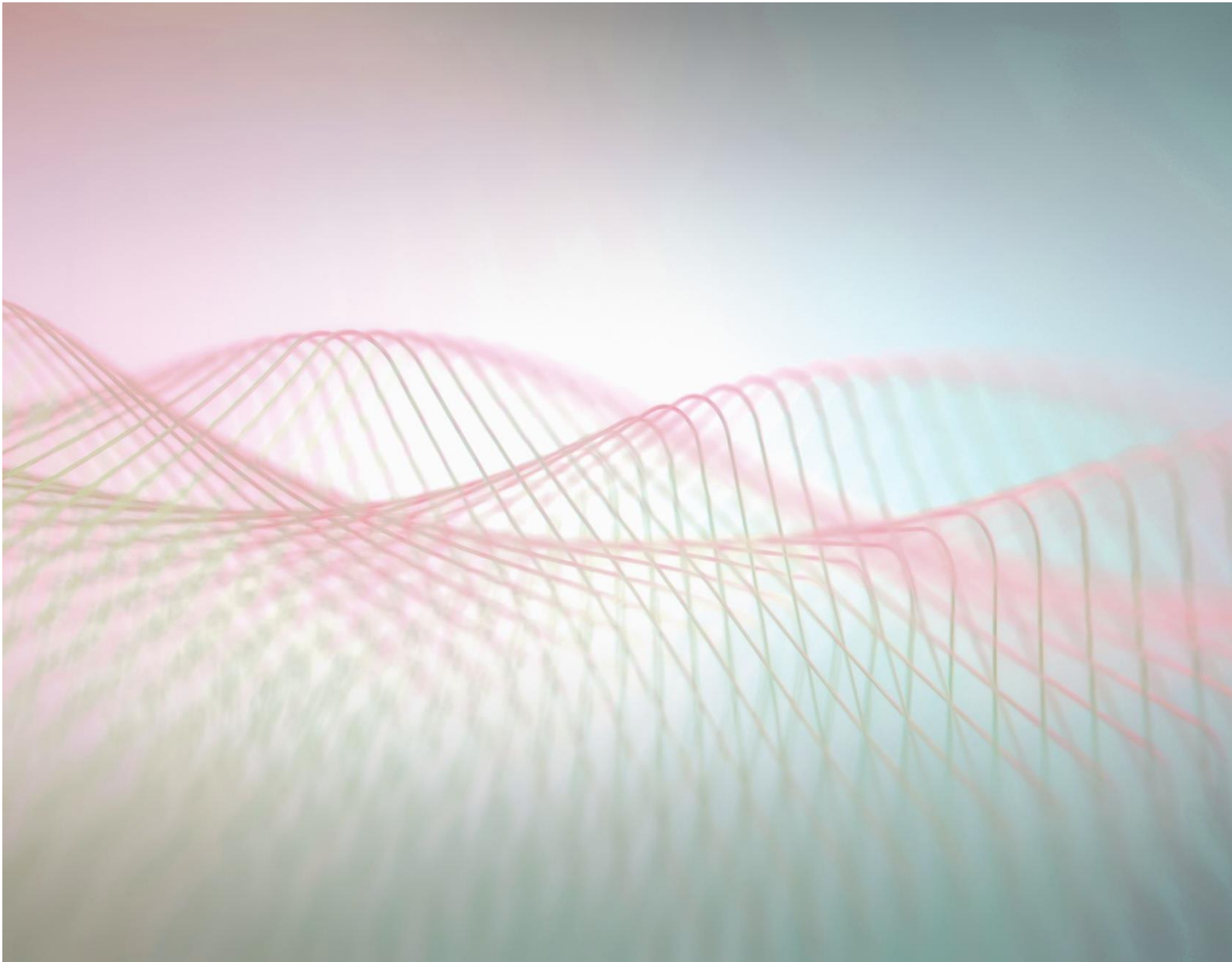




# MODEL-BASED SOFTWARE DEVELOPMENT

## LECTURE XIII. OUTLOOK

Dr. Mezei Gergely



# SIMULATION

# SIMULATION

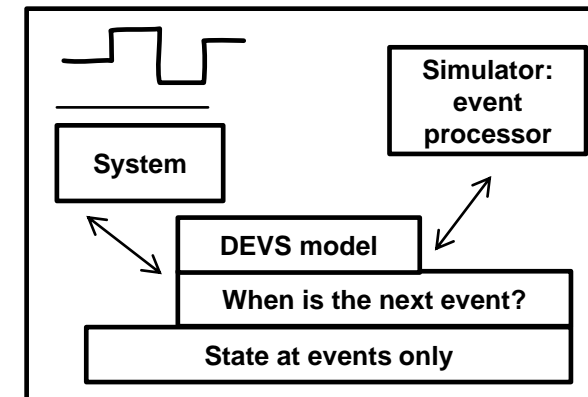
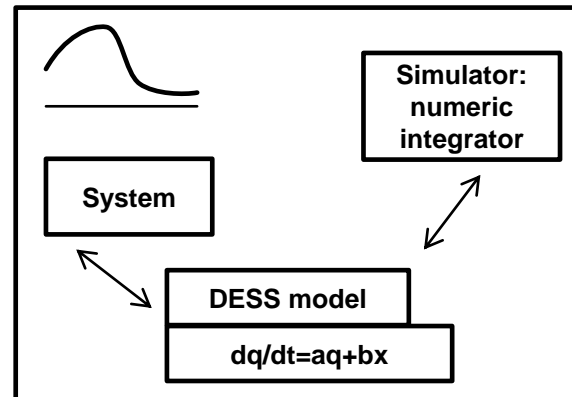
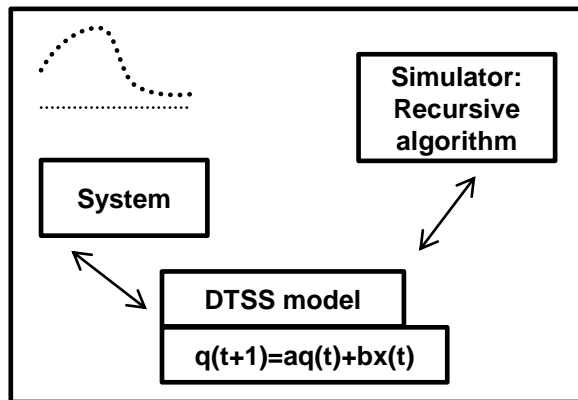
- To describe the dynamic operation of the model
- Basic question: does the system work according to the specification?
- Real systems are expensive to build and test, the models allow: running simulations without or before building the real system
- Proof (mathematical, automated, or other) that the system has the desired properties
- Purposes of use
  - Analysis: The system to be analyzed either exists or is being designed.  
We try to understand its behavioral characteristics
  - Conclusion: The system exists. We try to deduce its behavior from observations.
  - Design: The system is being designed, in the form in which it is modeled.  
We would like to make the best possible plan

## SIMULATE, ...

- ...if the physical system is impossible to build...
  - Simulate a collision of galaxies
- ... or costly...
  - Aircraft Airflow Simulation
- ... or unobservable...
  - Prediction, e.g. virus spread
- ... or measurement data-poor environment
  - E.g. adjusting traffic lights
  - It takes a long time to measure the throughput of each tried configuration

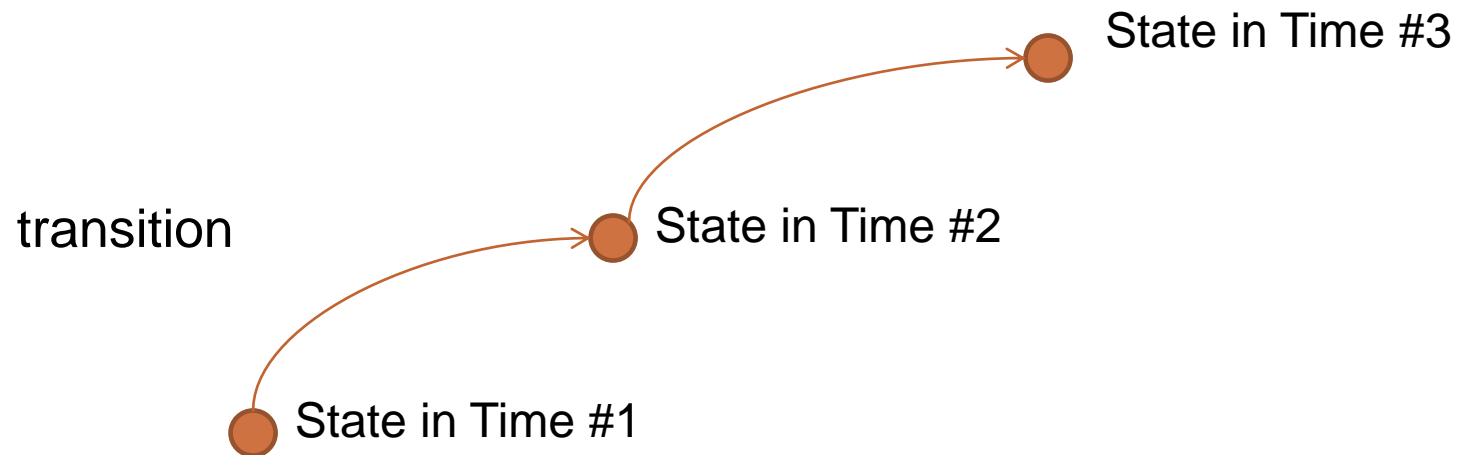
# SIMULATION FORMALISMS

- DTSS: discrete time
- DESS: continuous time
- DEVS: event-based



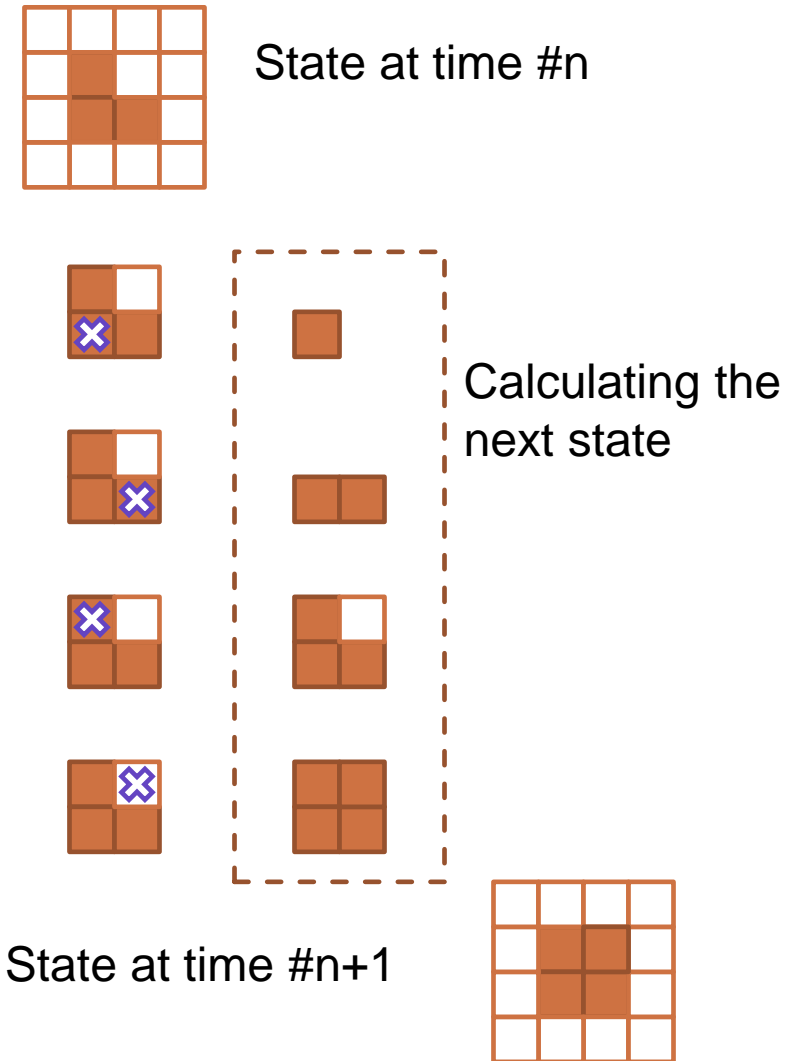
# DISCRETE-TIME SYSTEM SPECIFICATION (DTSS)

- Stepwise execution
  - Digital clock, time units
  - Works with any time unit (1 sec, 1 min, ...)
- State cannot change during a time unit



# EXAMPLE: CELLULAR AUTOMATON (GAME OF LIFE)

- Two dimensional grid (discrete space)
  - All grid cells represent a cell
  - The state of the cell is influenced by its neighbors (diagonal neighbors also count)
  - State examination at time steps
- Rules
  - A cell stays alive if it has 2 or 3 living neighbors
  - If the cell has more than 3 or less then 2 living neighbors, it dies
  - A dead cell come alive if it has exactly 3 living neighbors

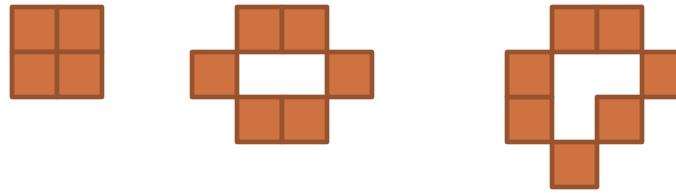


# BEHAVIORS

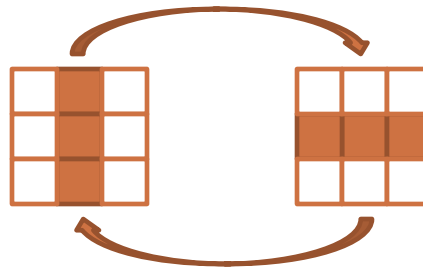
- Behaviors
  1. The pattern dies out quickly
  2. The pattern becomes periodic
  3. Chaotic behavior
  4. Unpredictable, not periodic, but shows regular patterns

## EXAMPLE PATTERNS

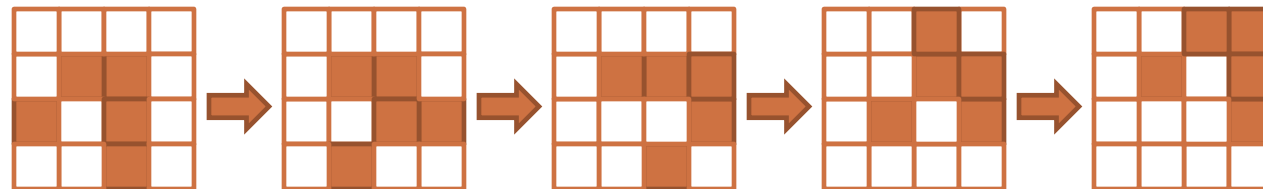
- Stable patterns



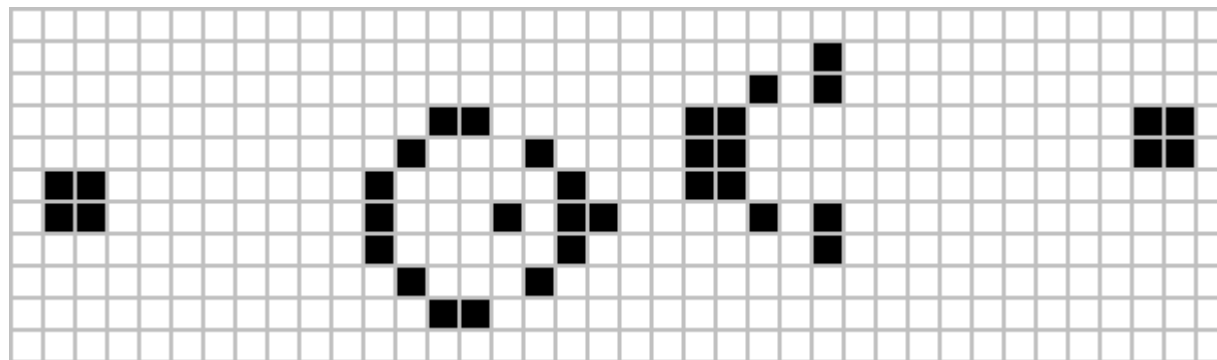
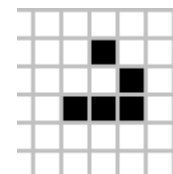
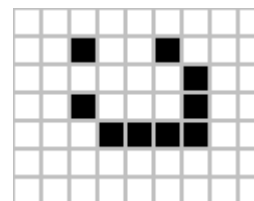
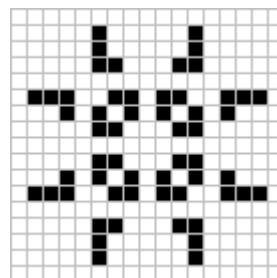
- Oscillating pattern:



- Moving pattern:

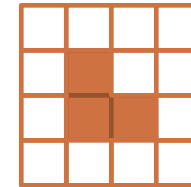


# FURTHER EXAMPLES

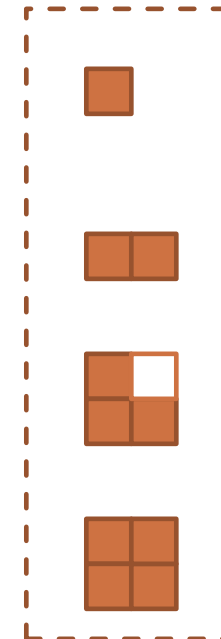
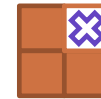
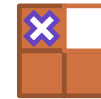
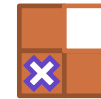


# SIMULATION MECHANISM

1. We examine all cells in all steps
2. We apply the state transition rules for each of them at the same time
3. We save the next state of the cells
4. We update the global state and increment the timer

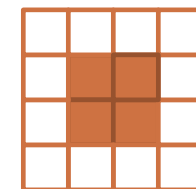


Global state at time #n



Next state

Global state at time #n+1

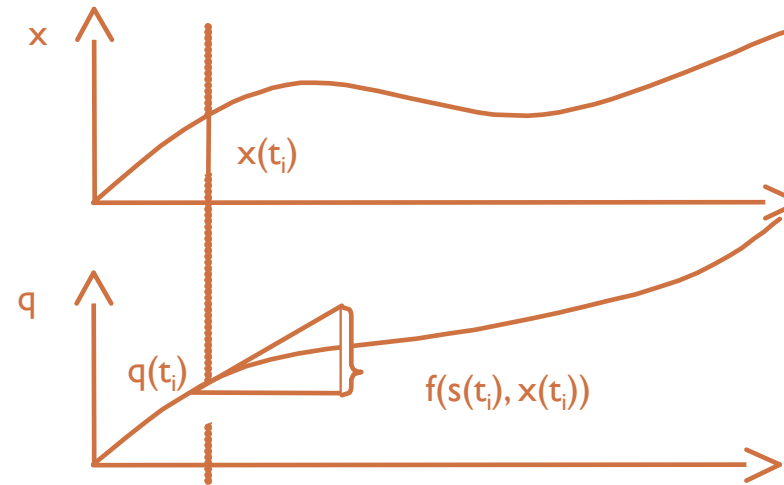


## DTSS – STATE CHANGES

- Transition function:  $\delta(\mathbf{q}, \mathbf{x})$
- Output function:  $\lambda(\mathbf{q}, \mathbf{x})$
- State trajectory:  $\mathbf{q}(t+1) = \delta(\mathbf{q}(t), \mathbf{x}(t))$
- Output trajectory:  $\mathbf{y}(t) = \lambda(\mathbf{q}(t), \mathbf{x}(t))$

# DIFFERENTIAL EQUATION SYSTEM SPECIFICATION (DESS)

- The time is not discrete, but continuous
- We use derivation function instead of a state transition function
  - Instead of the “next state” we focus on the amount of change



# DESS – FORMALISM

- Input:  $dq(t)/dt = x(t)$
- Output:  $y(t) = q(t)$  (current state)
- We use first-order differential equation for more than one variable:

$$d q_1(t)/dt = f_1(q_1(t), q_2(t), \dots, q_n(t), x_1(t), x_2(t), \dots, x_m(t))$$

$$d q_2(t)/dt = f_2(q_1(t), q_2(t), \dots, q_n(t), x_1(t), x_2(t), \dots, x_m(t))$$

...

$$d q_n(t)/dt = f_n(q_1(t), q_2(t), \dots, q_n(t), x_1(t), x_2(t), \dots, x_m(t))$$

- Challenge:
  - In a given  $t_i$  time, we know only  $dq_i/dt$  (steepness)
  - Next point is a  $t_{i+1}$  time and an interval  $[t_i, t_{i+1}]$  associated
  - *The value of  $t_{i+1}$  must be calculated without knowing the elements of  $[t_i, t_{i+1}]$  (only  $t_i$  is known)*
- We use numerical integration methods

# MANUFACTURING

- Tasks
  - Order materials
  - Store materials
  - Manufacture product
  - Quality management
- The process is event-driven
  - Order if the stock is almost empty
  - Quality insurance after manufacture
  - ...
- DTSS/DESS
  - Can be used, but not efficient
  - *Event-based timing would be better*

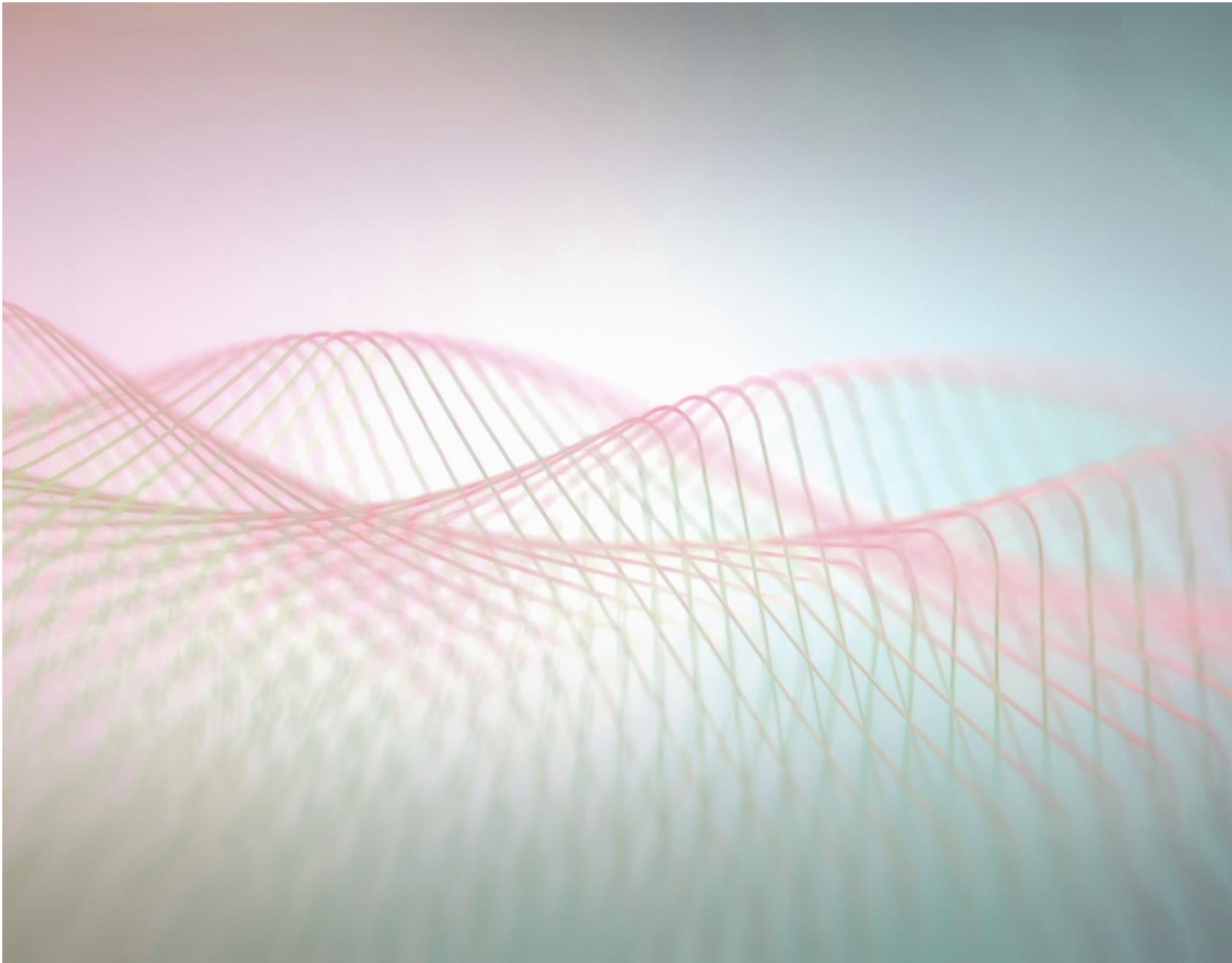


# CELLULAR AUTOMATON - ISSUES

- State transition is calculated and applied on all components
  - Most of the cells do not change at all
  - E.g. dead regions will not raise from dead
- Idea: liveness state changes can be handled as events
  - How can we find cells to observe?
  - Basic idea
    - State transition marks cells which change their states
    - Only the neighbor cells of the marked ones are to be observed

# DEVS

- Discrete Event System
  - The system is built up from components, which may interact each other
  - The components interact each other via messages referred to as events
  - The system can have different states, which are discrete
  - The state changes are always triggered by events



# MULTI-LAYER DYNAMIC METAMODELLING

# MULTILAYER METAMODELLING

- The evolution of concepts
  - At the beginning, we have *something...*
  - ... refined through several steps....
  - ... leading to concrete products



My Black Thunder  
Price: 260.000Ft

# MULTILAYER METAMODELING

- Modeling the manufacturing workflow
  - Based on prototypes, using many intermediate steps
  - We refine concepts step by step
    - Abstract and concrete components co-exists and my refer to each other
  - “Living”, evolving domain specific languages
    - Agile-style methodology
    - Branching along refinements instead of versioning
- Validated refinement

# DMLA BOOTSTRAP

- Bootstrap – core elements
  - Classifier (class)
  - Slot (field)
  - Operation (method)
  - Annotation (annotation, constraint)
  - Contract (interface)

# DMLA - DYNAMISM

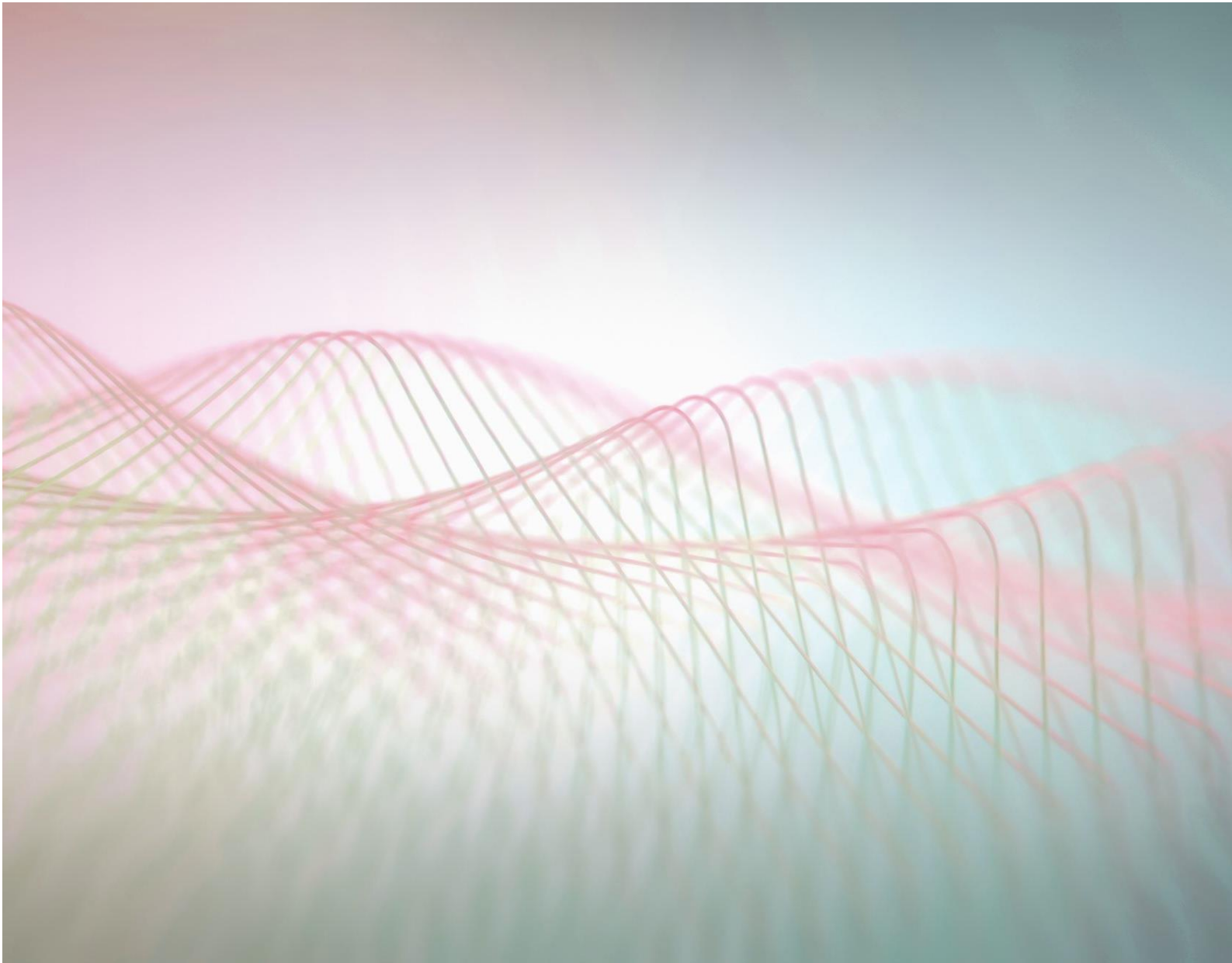
- Customizable type constraint
  - Type-, Cardinality constraint (annotation)
- Customizable validation
  - Refinement rules are not wired
  - Key: operation = AST built from entities
    - Operation is data → can be changed
- Customizable behavior
  - Operation that rewrote another operation
  - (Self-healing code?)

# DMLA

- GraalVM + Truffle
  - Interpreter, not compiler (dynamism)
  - Operation  $\Leftrightarrow$  AST
- Custom, hand written parser, CAAS
- LSP

# DMLA - REFINEMENT

- Stepwise refinement
  - Refinement chain for Entities, Slots and Annotations
  - Slot division
- Model is not a snapshot
  - Model contains all design decisions, branches
  - Step back is always possible

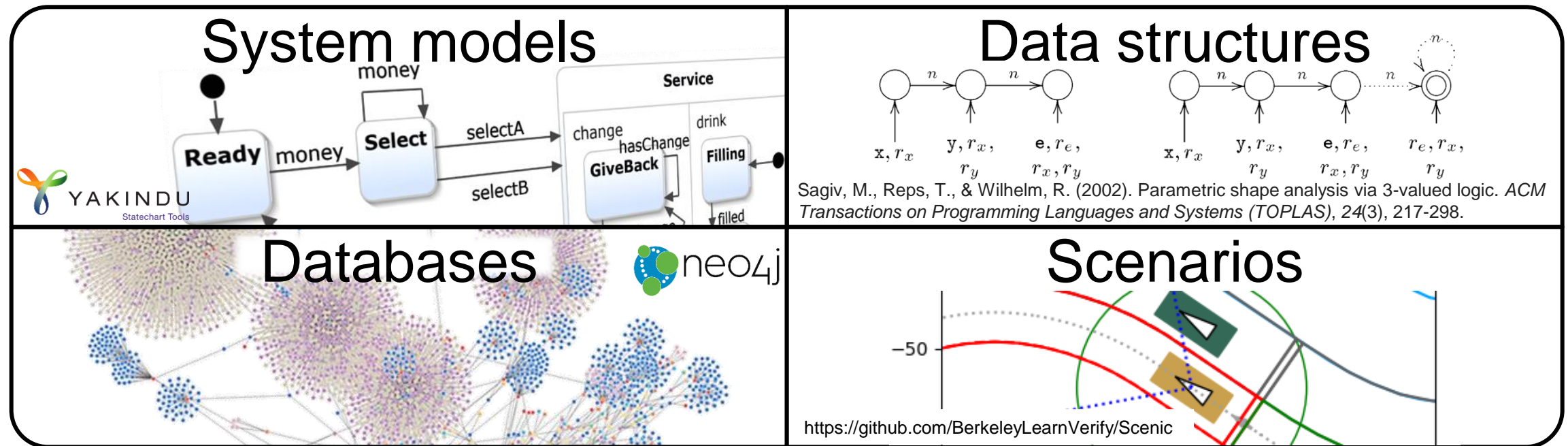


# Automated Model Generation Techniques

Challenges of **CoREDiSc**

# Modeling with Graphs

- Graphs are widely used in software engineering



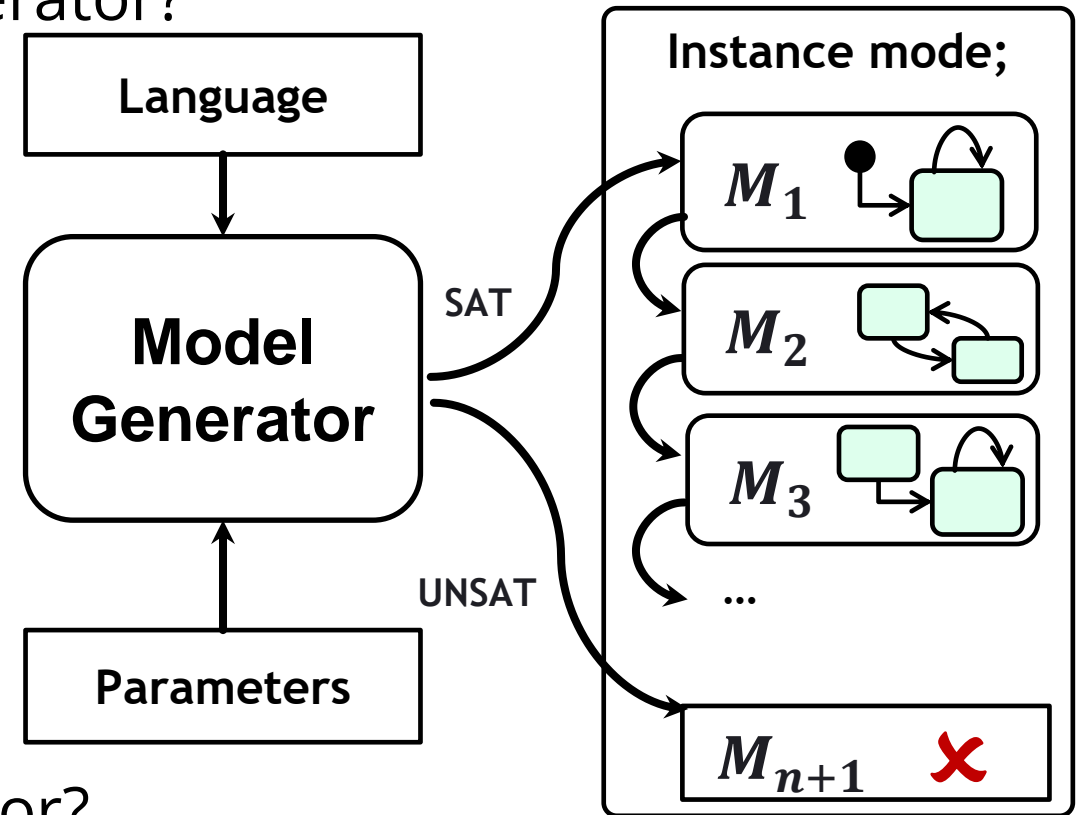
- Testing, benchmarking, generative architecture → graphs

Goal: (Consistent | Realistic | Diverse | Scalable) generation!

# Arcitecture of generators

- What is the architecture of an ideal generator?

1. Input: Language specification  
*We are generating the instances of this language*
2. Input: Parameters  
*We can characterize the wanted models*
3. Output: Models  
*Sequence of models*
4. Output: Inconsistency  
*If there is no such model, we should prove it*



- What are the properties of such generator?

# Consistency

- A generator is consistent, if it can generate models that satisfies all well-formedness constraints.
- A generator is complete, if it can generate all valid models.
- Well-formedness constraints are complex logic predicates (e.g. OCL or graph patterns)
- We need to use logic solvers



CO  
Consistent

# Realistic

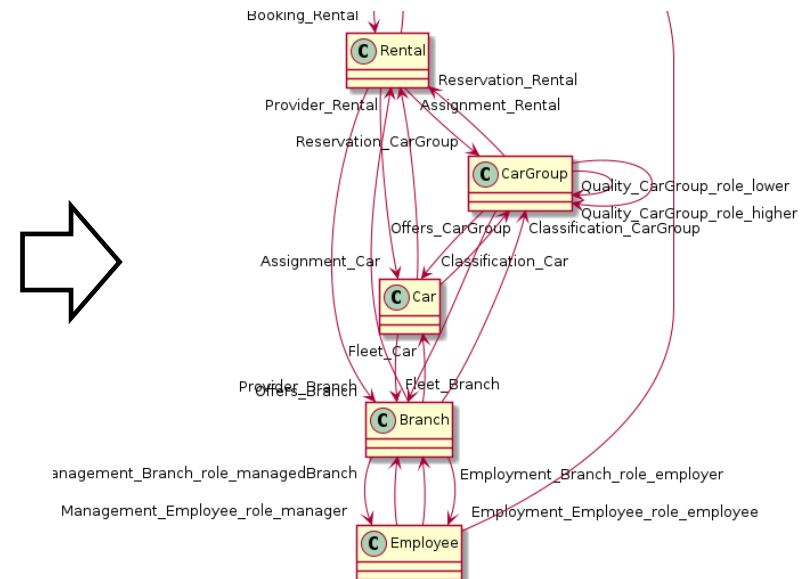
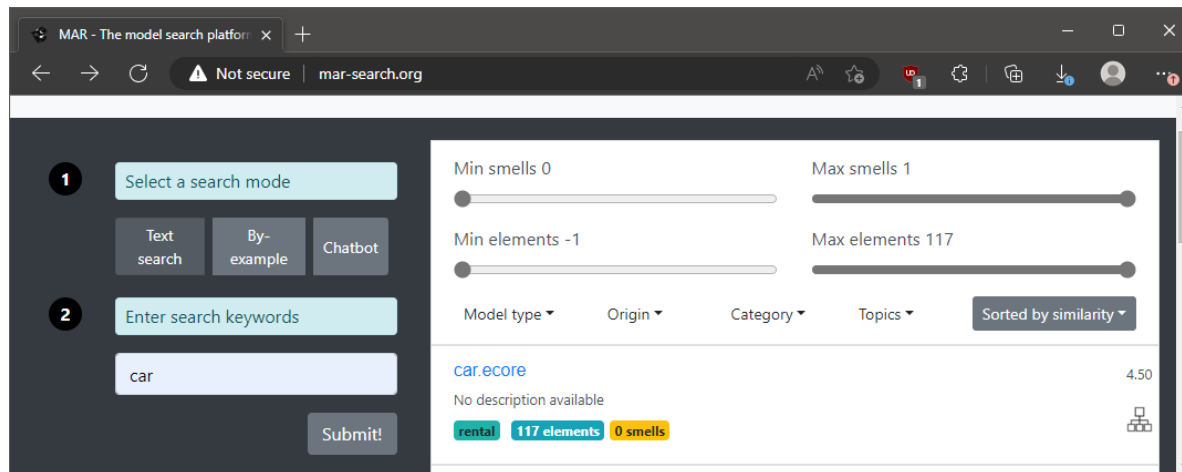
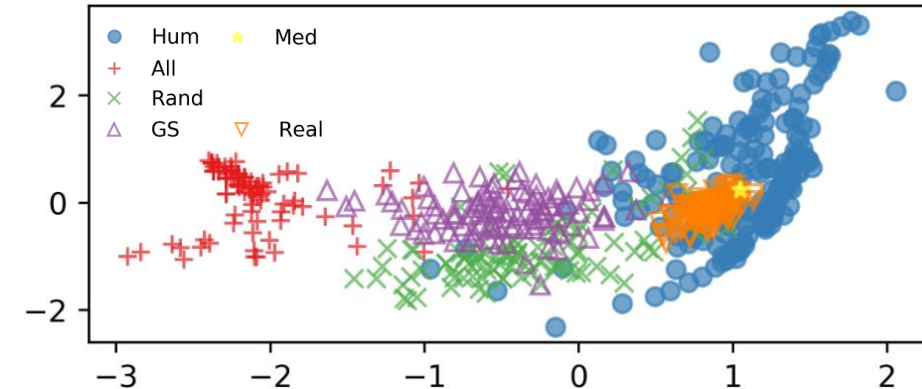
- A model generator is realistic, if the generated models are indistinguishable from real ones.

CO  
Consistent

RE  
Realistic

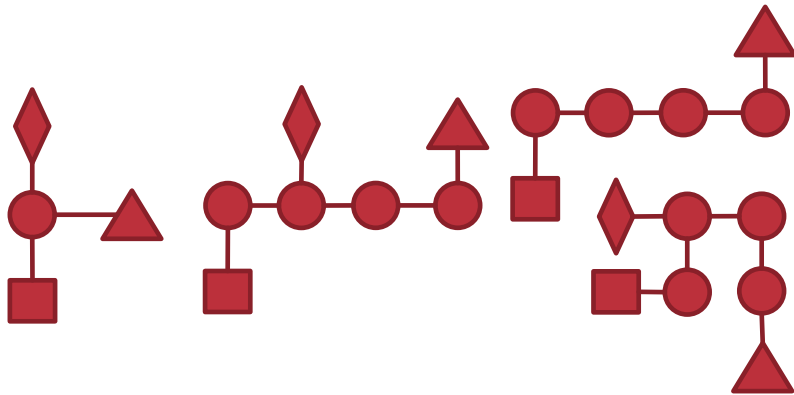
# Realistic

- How to measure the realistic nature
  - Graph Solver: network science (degree distribution), during generation, we measure and control
  - AI-based solutions
- How to get real models?
  - IP issues, model repositories are important (<http://mar-search.org/>)



# Diversity

- Models are not symmetric
- Generated models are different from each other.
- How to measure diversity?
  - E.g., count the different kind of subgraphs

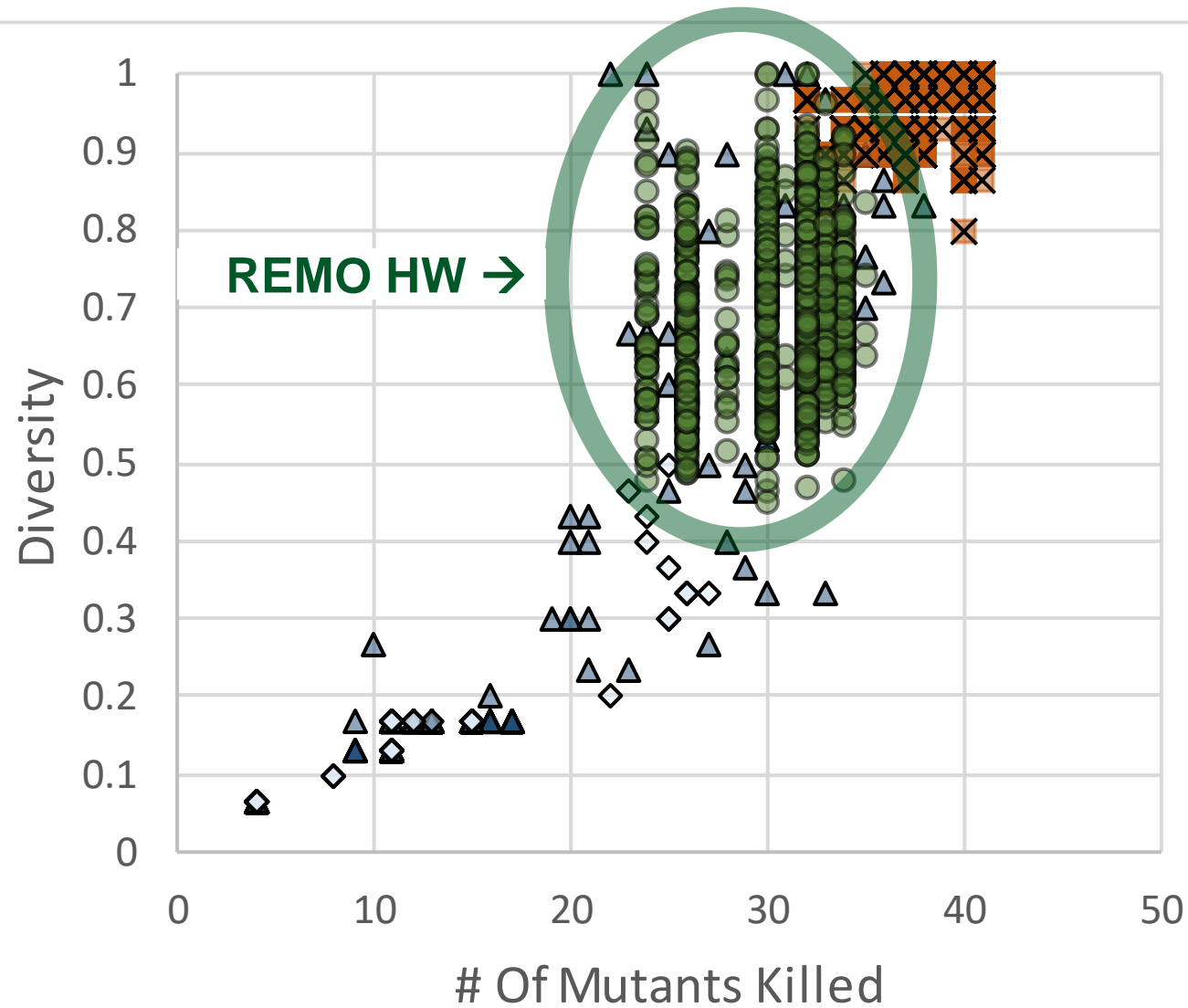


- The more the better

CO  
Consistent

RE  
Realistic

DI  
Diverse



- △ Alloy; $s=0$
- ◇ Alloy; $s=20$
- ✕ GS; $r=1$
- Human

How to compare  
**diversity**  
**test coverage?**



Used different solvers,  
compared the result

- **Takeaway 1:**  
SAT < Human < Graph Solver
- **Takeaway 2:** Correlation

# Scalability

- A generator is scalable, if it is able
  - To generate large models
  - To generate a lot of models
- Co/RE/DI is hard
  - Scalability issues (Sc--)
  - Or reduce others (Co-- RE-- DI--)

CO  
Consistent

RE  
Realistic

DI  
Diverse

SC  
Scalable

# Some measurements for graph solvers

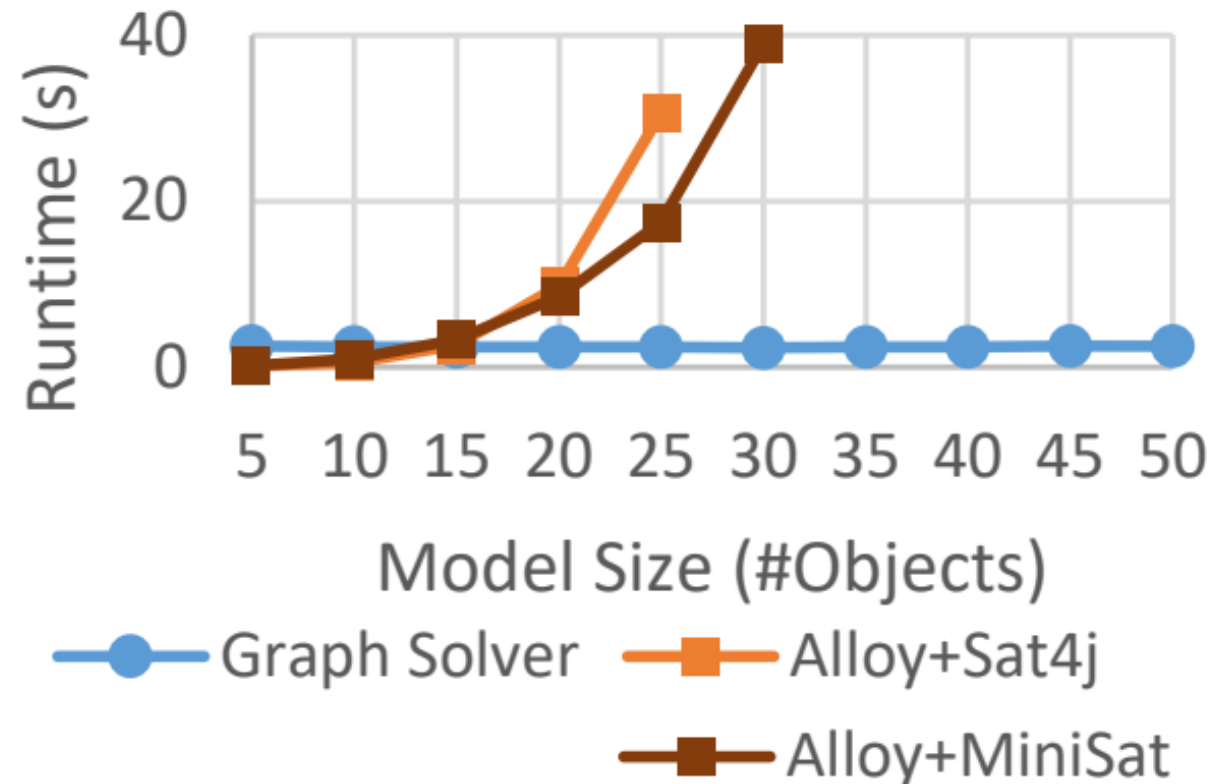
## Max size

	Largest model (#Objects)		
	Graph Solver	Sat4J	MiniSat
FAM+WF	6250	58	61
FAM-WF	7000	87	92
Yak+WF	1000	–	–
Yak-WF	7250	86	90
FS	4750	87	89
Ecore	2000	38	41

FAM: Industrial, Avionics  
 FS: File System example of

Yakindu: Industrial,  
 Statemachine  
 Ecore: Metamodelling  
 language

## Runtime comparison



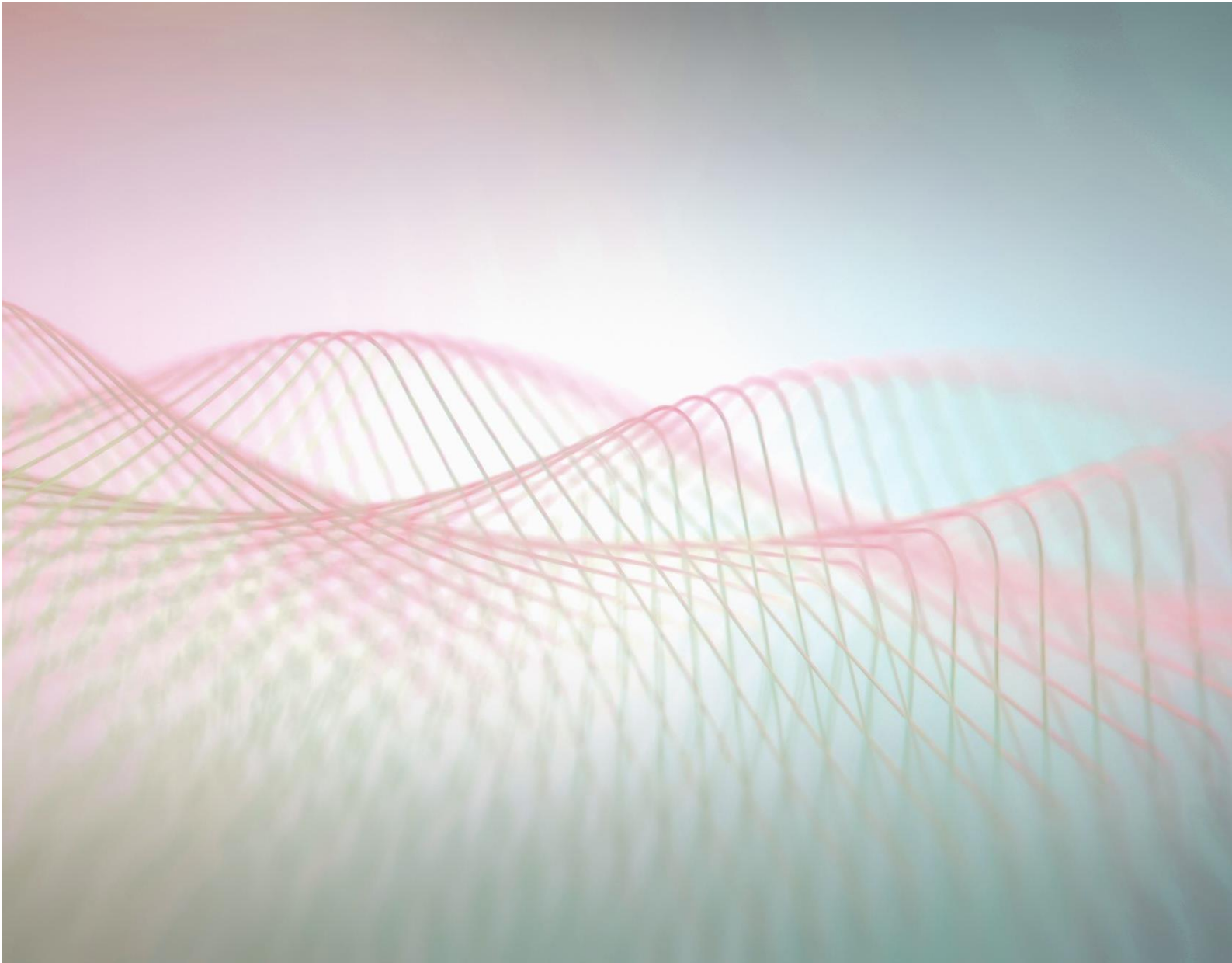
## (Consistent | Realistic | Diverse | Scalable) generation!

- What combination is needed for different tasks?
  - Test generation
  - Performance evaluation
  - Representative examples
  - Fair homework
  - Cheat detection
  - Optimization

# Summary

- Model generation is hard
- Different properties: (Consistent | Realistic | Diverse | Scalable)
- We are developing one!
  - Homeworks
  - Railway
  - Avionic architecture
  - Testing self-driving vehicles
    - ESA
    - NAVY
- Video: <https://youtu.be/fUopeDFIUKA>
- Open source tool: <https://github.com/graphs4value/refinery>



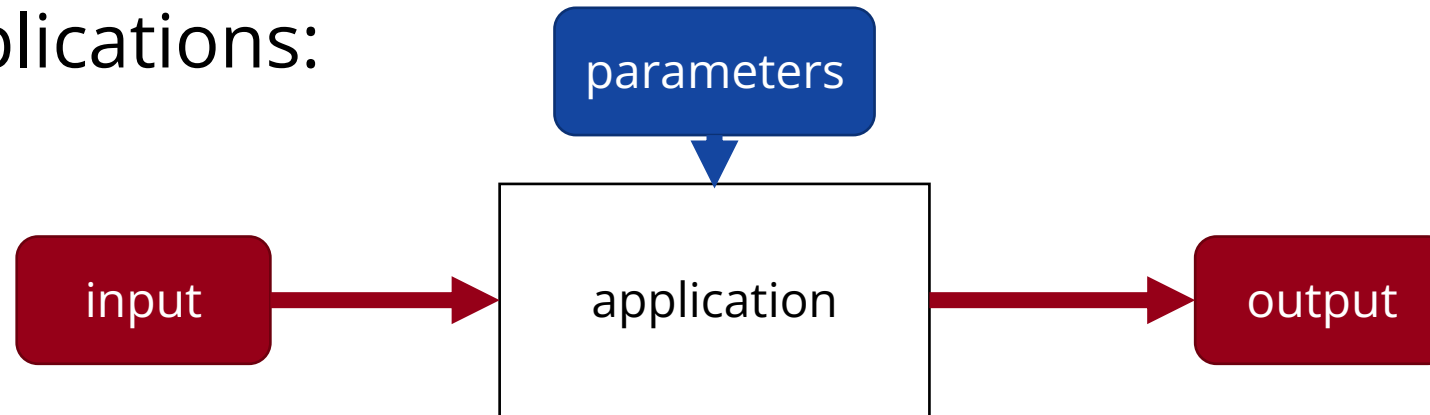


# Models and AI

Neuro-Symbolic Reasoning

# AI Applications

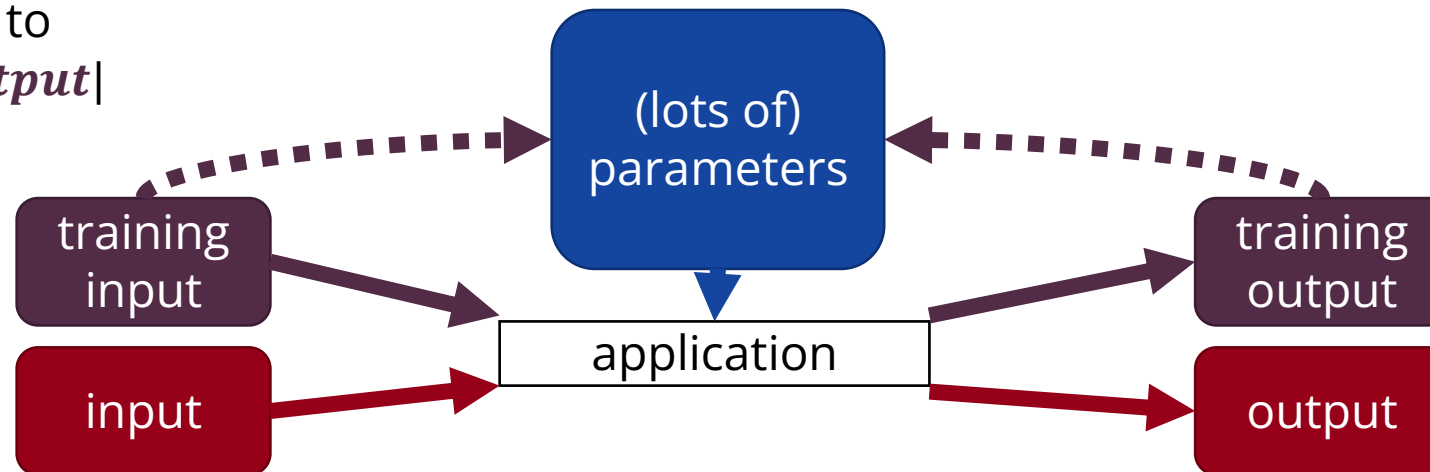
- Normal applications:



- AI apps: requirements + manual work → data + power

- calculate *parameters* to
- $\min |\text{app}(\text{input}) - \text{output}|$
- wrt. a cost function

If training, validation, and runtime data is similar, it should work.

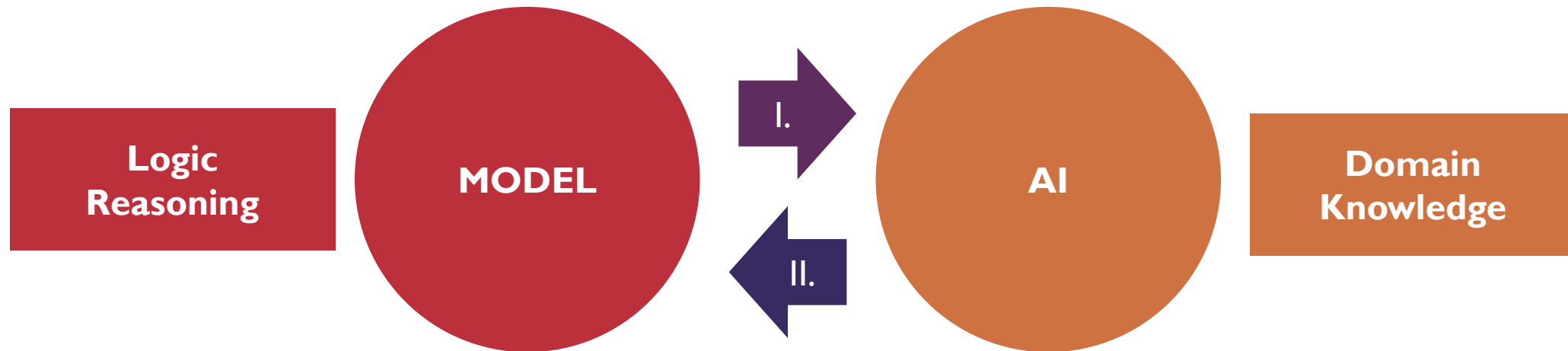


# CRITICAL AI APPLICATION

- AI-based applications are widely used
- Even in safety critical domains
- However, AI-based applications
  - do not have the same kind of guarantees for trustworthiness
  - need novel testing/verification techniques

# MODELS AND AI APPLICATIONS

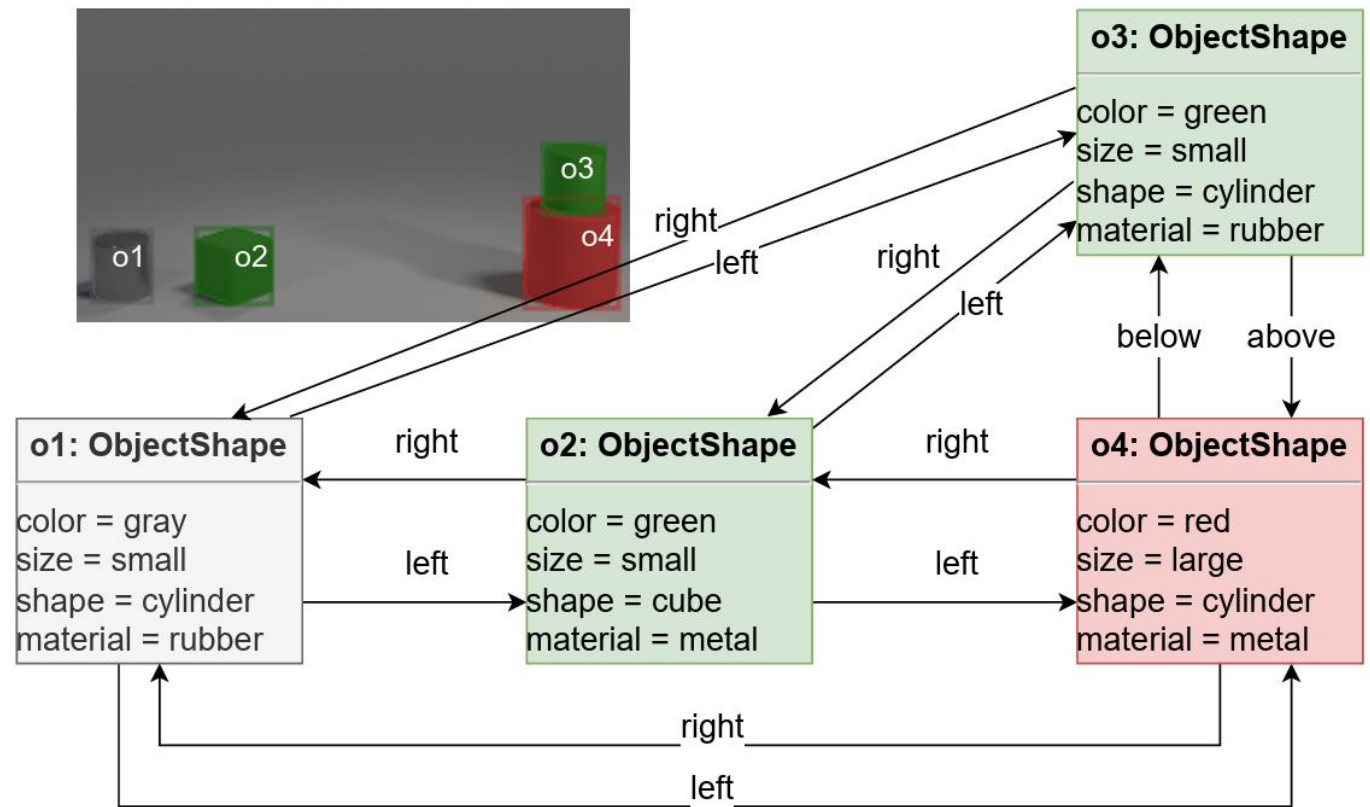
- Model expected behavior
- and model diversity
- to improve the reliability of AI applications



- We can **capture either**: (I.) coverage or (II.) random errors

# HOW TO MODEL THE OUTPUT OF THE AI

- **Clevr**: visual question answering
- Ask all the questions
- Store it in a model
- We can answer the questions from the model, if we are smart enough

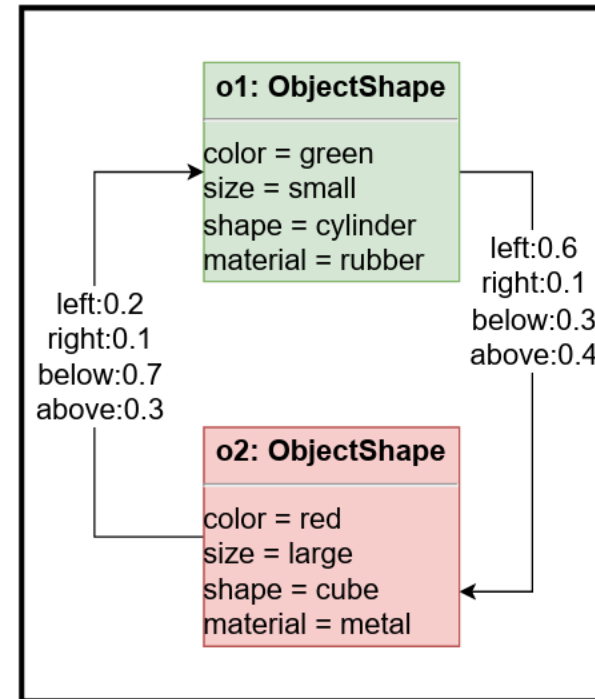


# UNCERTAINTY IN MODELS

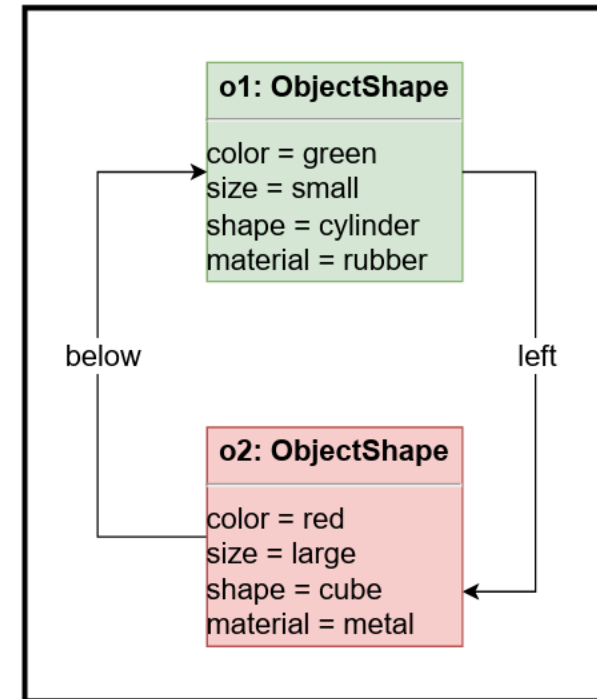
- AI applications cannot do logic reasoning with relations
  - But they can cheat with high probability
  - Lot of logic inconsistencies!
- AI applications provide weights for the answers
  - Those weights can be interpreted as confidence in answer
  - Lots of logic uncertainties!
- store uncertainties in the model explicitly.

**partial models:**

**true | false | error | unknown**

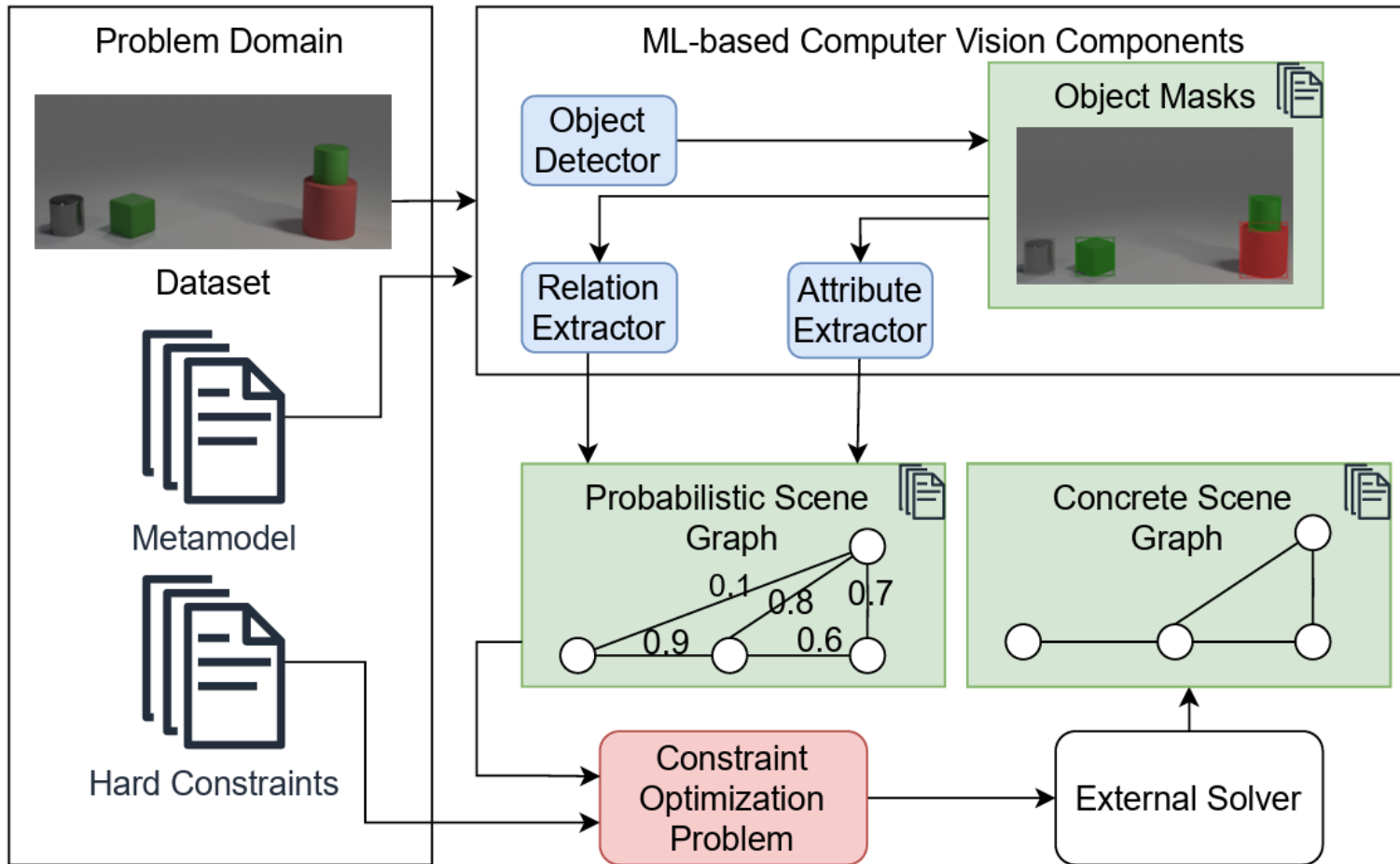


(a)



(b)

# AI IMPROVEMENT WITH MODEL GENERATION



## Results:

- + **Consistent** models
- + Extra **constraints**
- + Better **accuracy**
- Lower **performance**



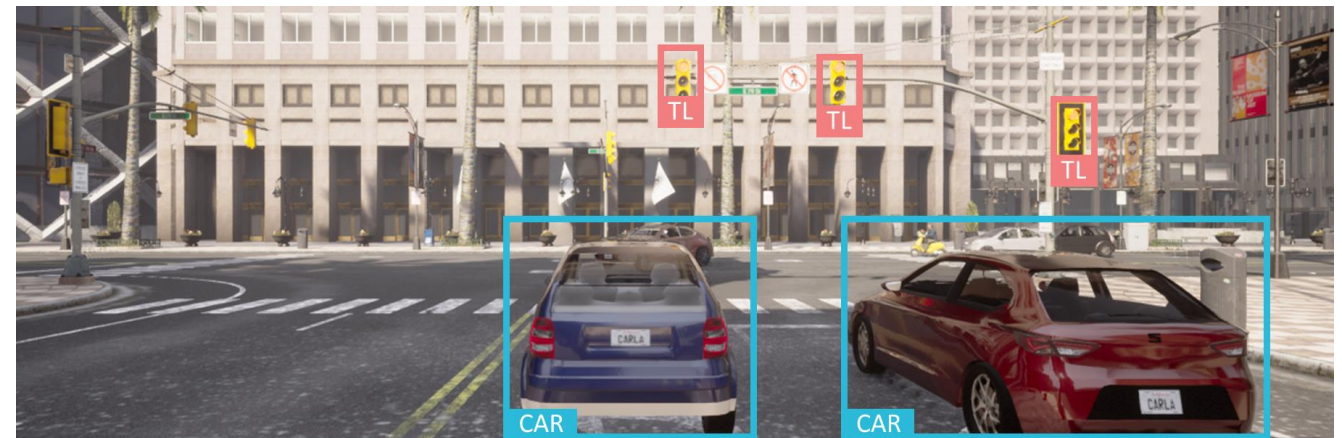
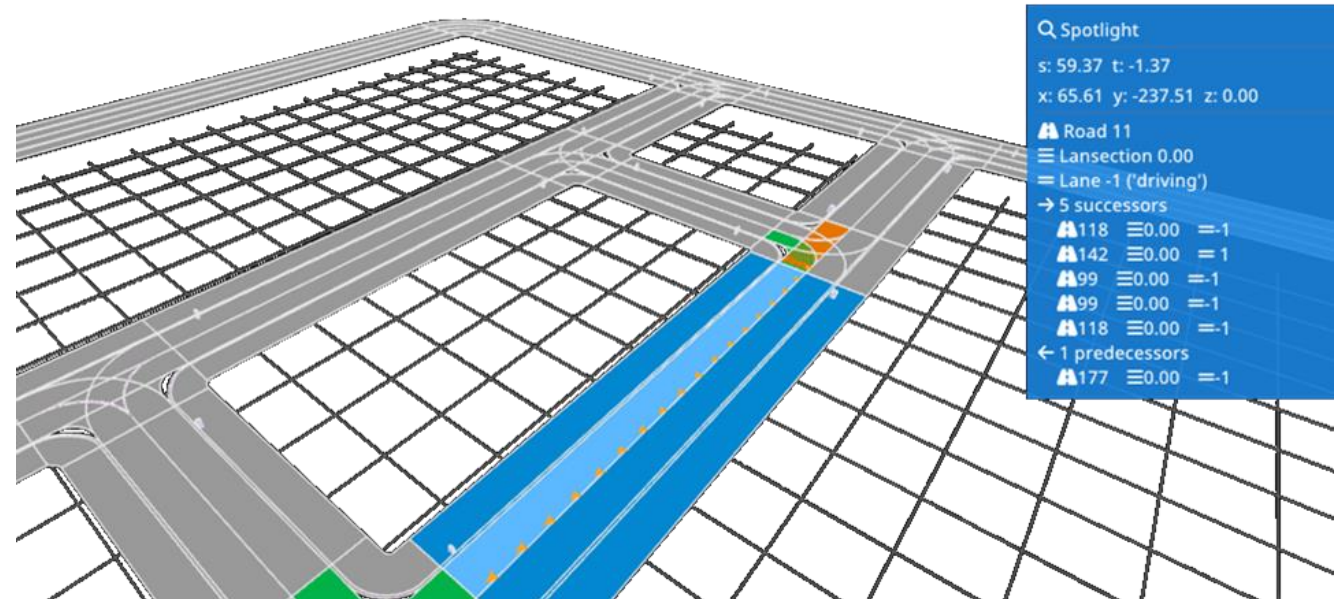
# EXAMPLE PROJECT APPLICATION: VAMPIR

## Input:

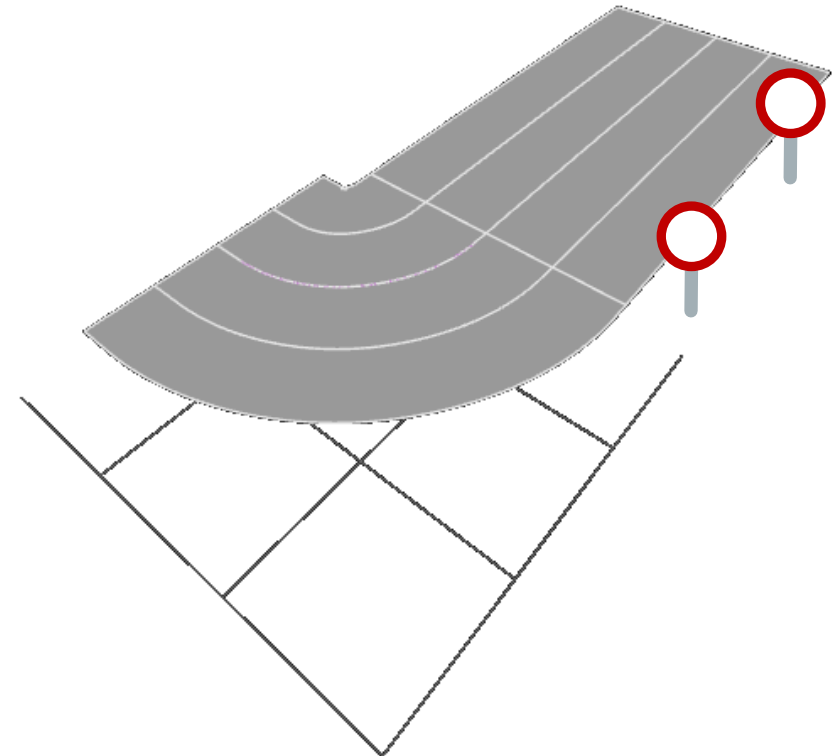
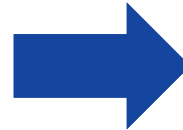
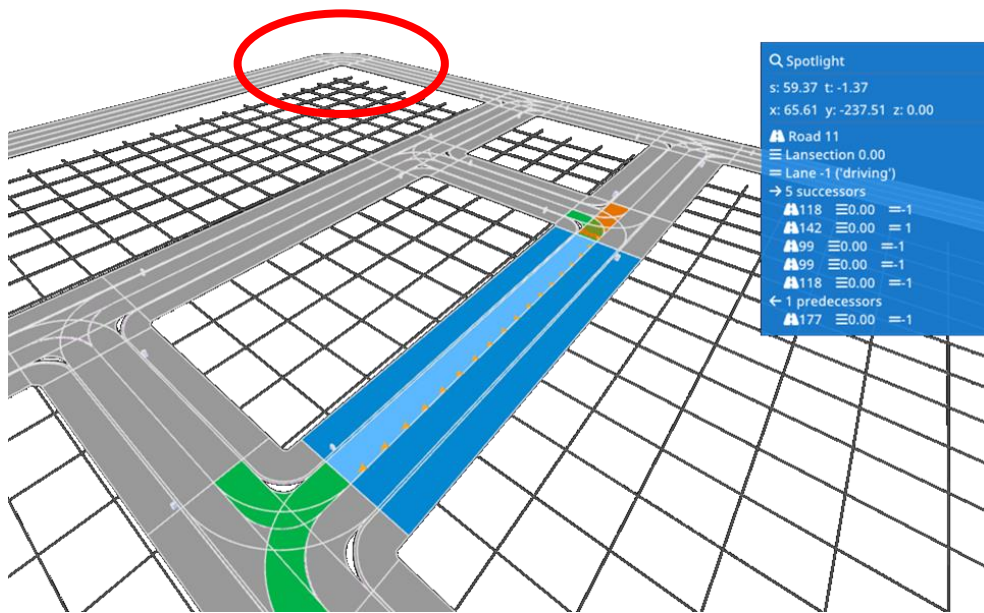
- GNSS position + HD-Map
- AI sensor output

## Output:

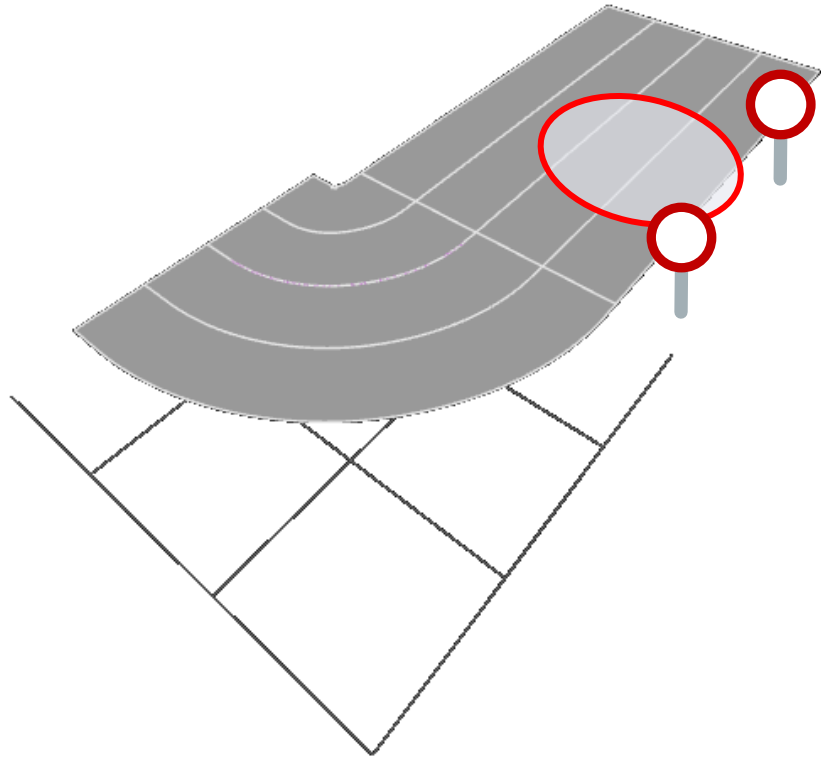
- Level 1 > Scene interpretation
- Level 2 > Safety and accuracy
- Level 3 > Improved GNSS accuracy



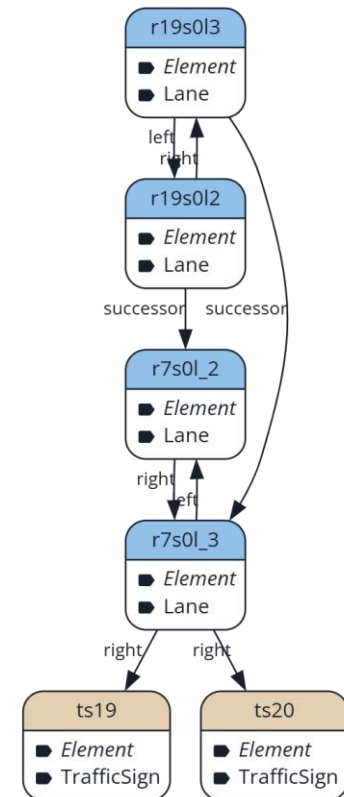
# ESA EXAMPLE: MAP EXTRACTION



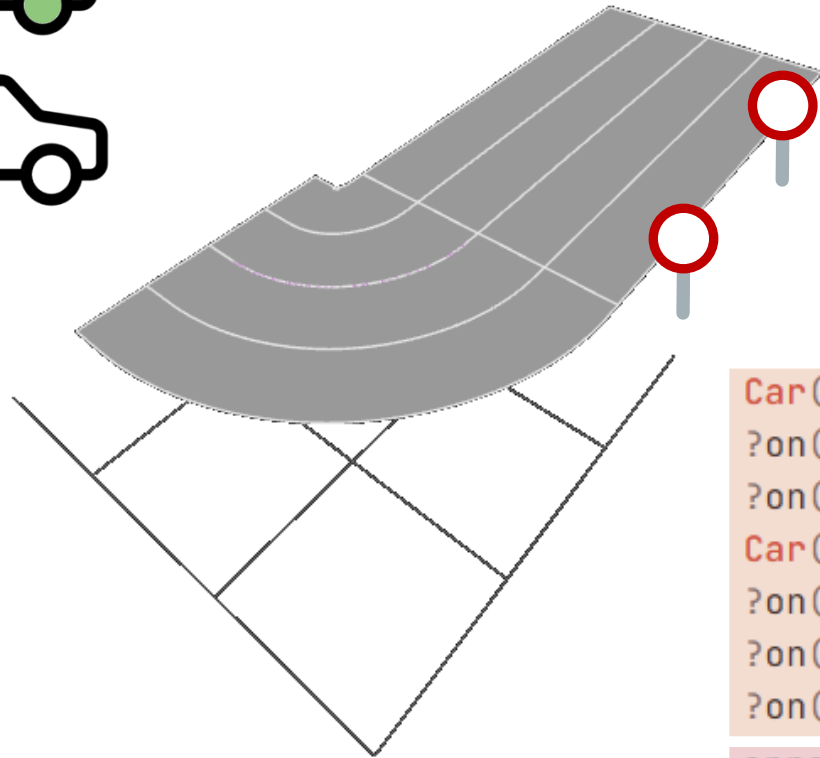
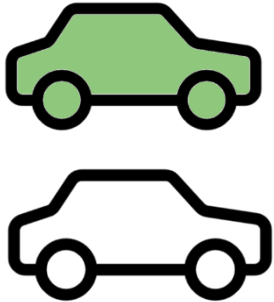
# ESA EXAMPLE: MAP TO TOPOLOGY



- Capture the topology of the environment
- Objects (lanes, traffic signs) and relations (successor, left, right)



# ESA EXAMPLE: AI OBSERVATIONS



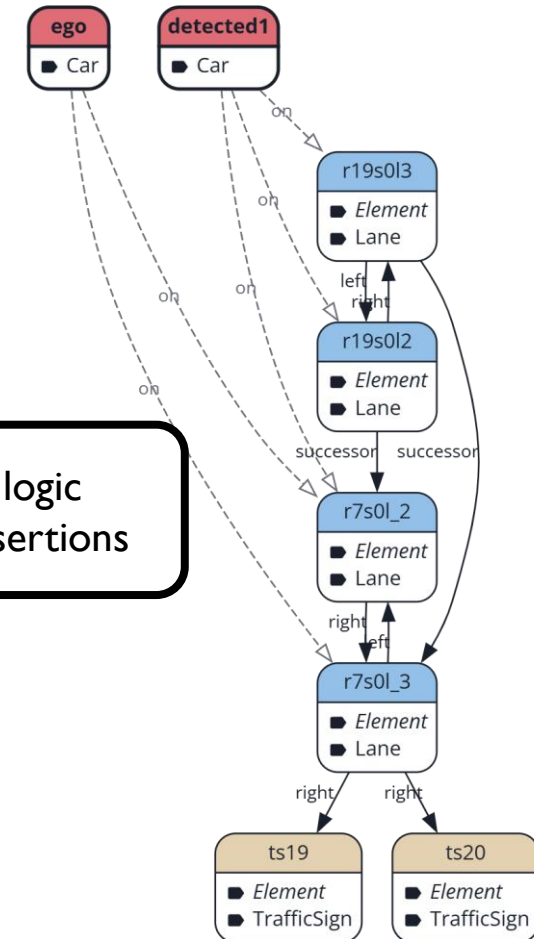
```
Car(ego).
?on(ego,r7s0l_2).
?on(ego,r7s0l_3).
Car(detected1).
?on(detected1,r19s0l2).
?on(detected1,r19s0l3).
?on(detected1,r7s0l_2).

error notLeft(l1, l2) ↔
  on(ego, l1),
  on(detected1, l2),
  !left(l1,l2).
```

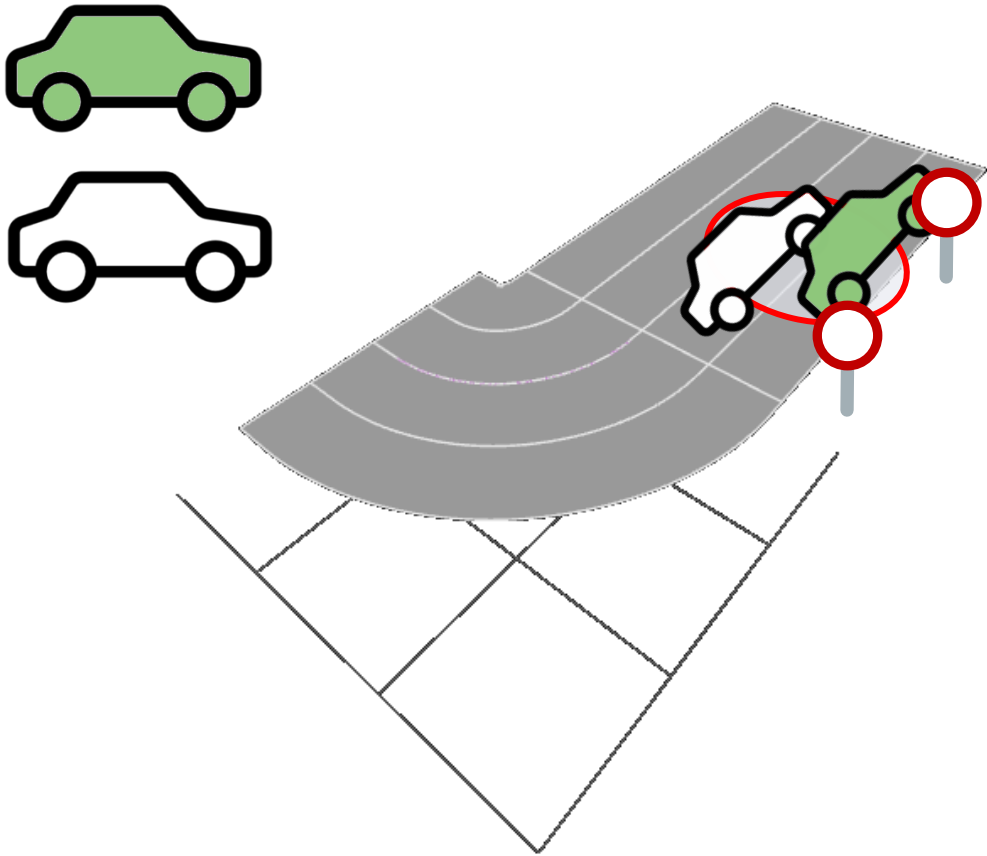
logic  
predicates

logic  
assertions

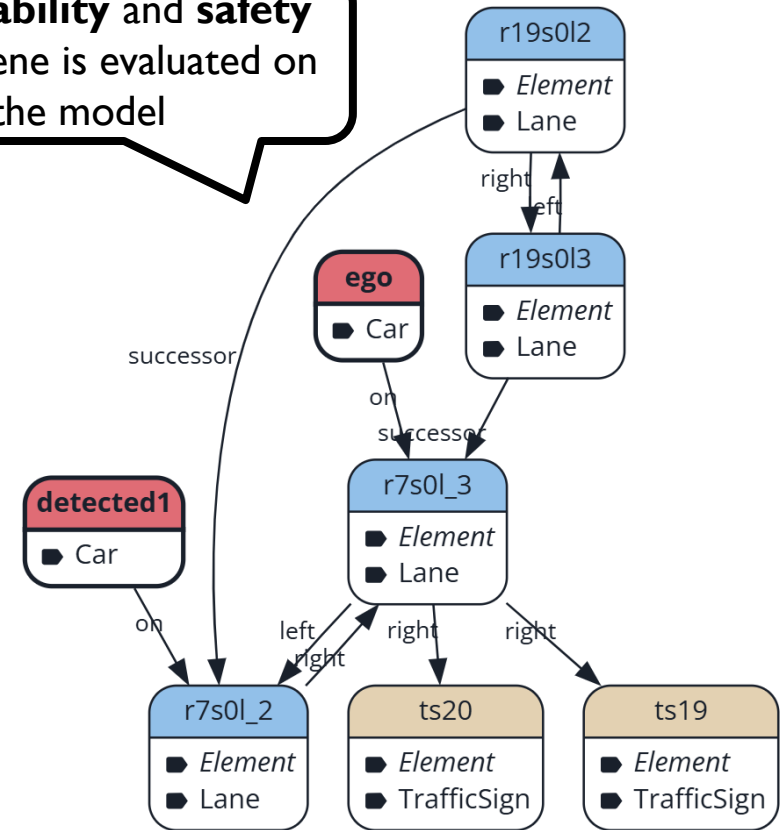
Detected car must be on the left



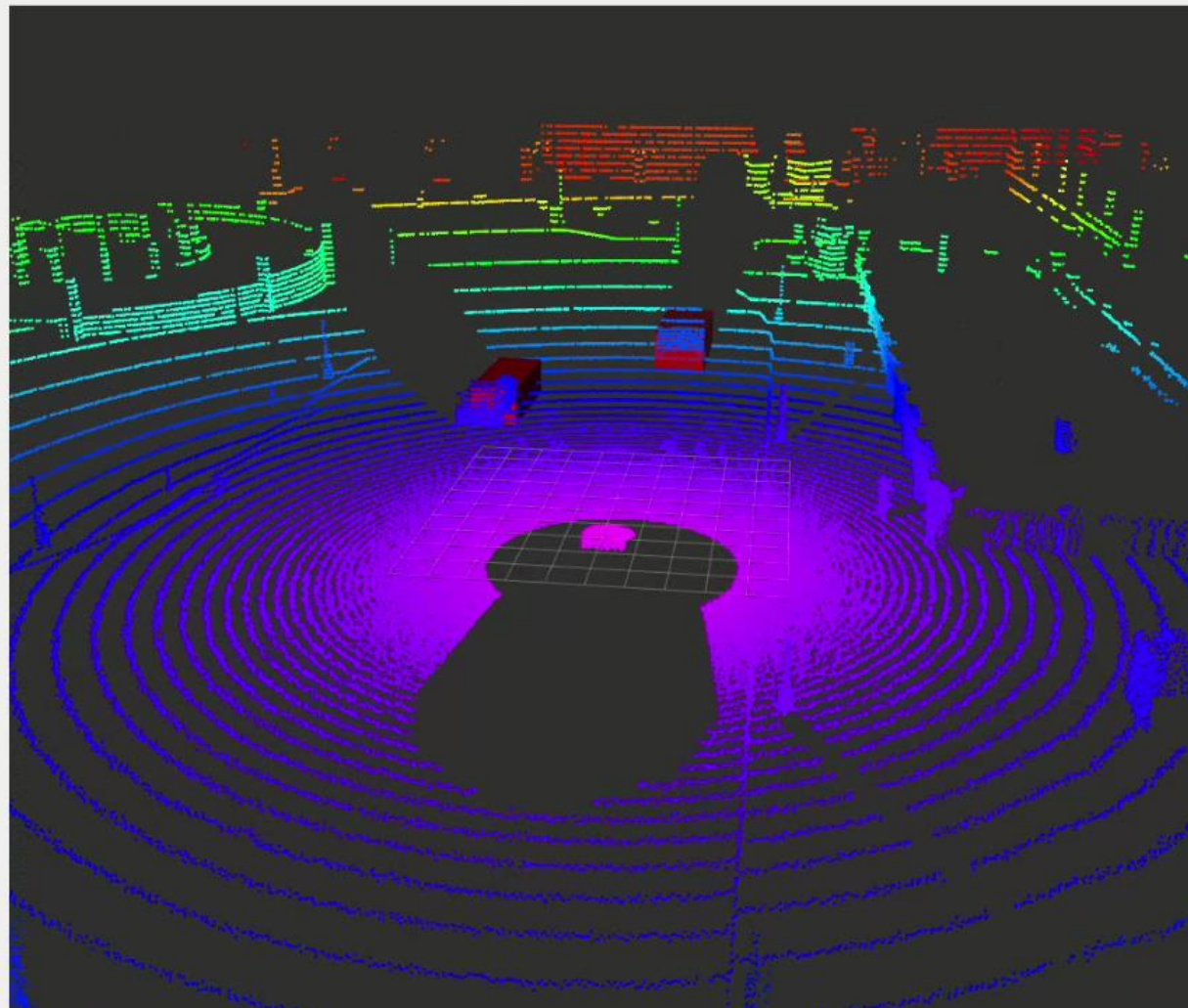
# ESA EXAMPLE: SCENE RECONSTRUCTION



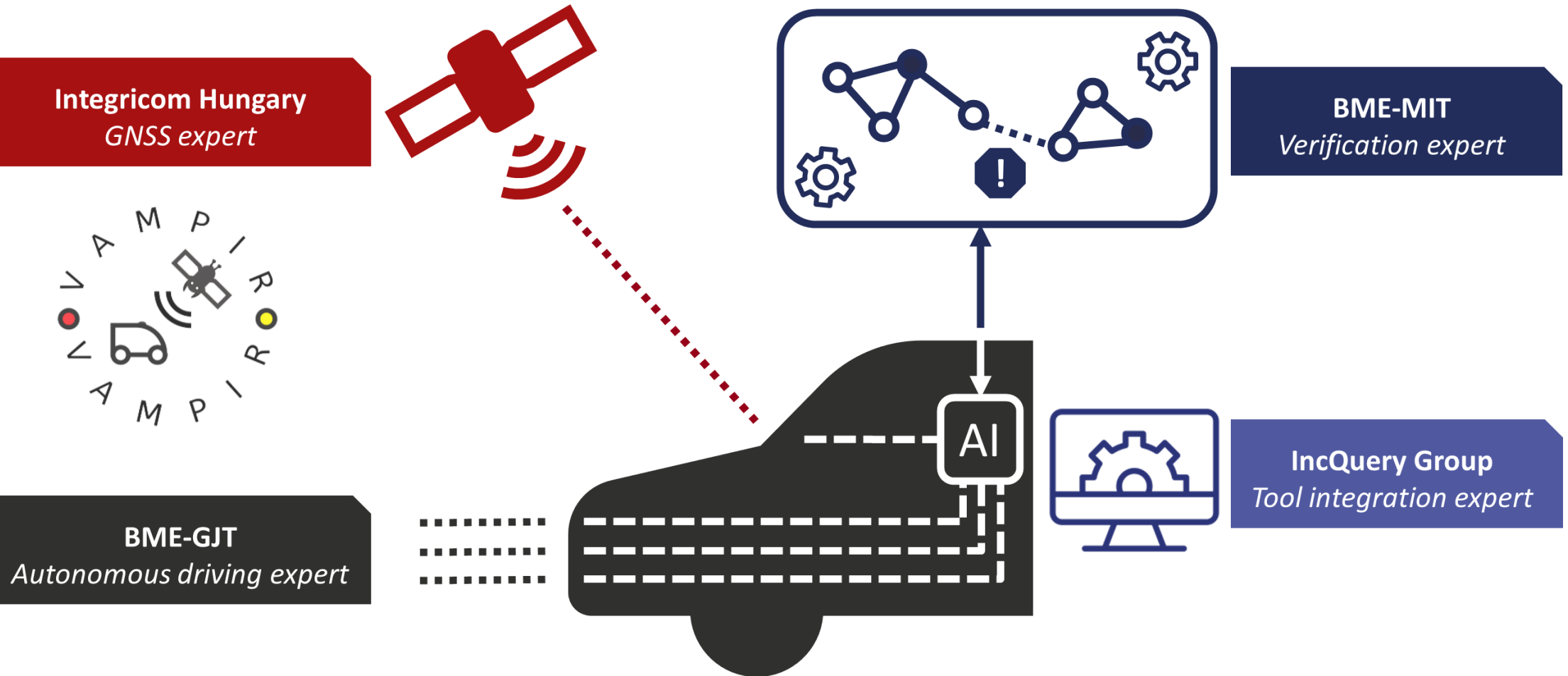
The **reliability** and **safety** of the scene is evaluated on the model



# SENSORS

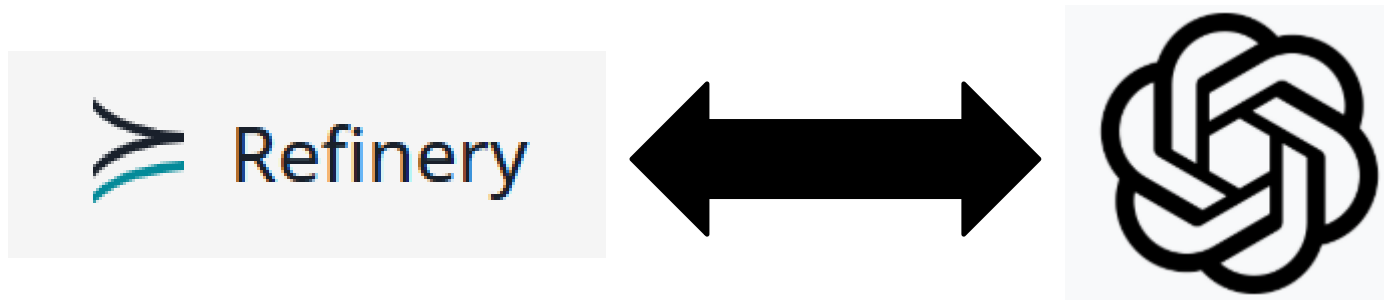


PARTNERS



# TEXTUAL AI → REFINERY

- DEMO



Refinery

localhost:1313/#/1/KLUv\_SBK7QEAFANjbGFzcyBQZXJzb24gewogICBmYXRoZXJtb30KCnNjb3BIIG5vZGUGPSAyMC4uMzAuAwBAwDV5AcQMAw==

Refinery DEV

<> CODE

GRAPH

TABLE

AI

class Person {  
 Person father  
 Person mother  
}

scope node = 20..30

< EL

GENERATED AT 23:23:32 (0)

GENERATED AT 23:24:14 (0)

GENERATED AT 23:25:20 (0)

GENERATED AT 23:26:03 (0)

GENERATED AT 23:30:37 >

```
graph TD
    RichardII[Richard II] -- mother --> JoanKent[Joan Kent]
    RichardII -- father --> EdwardIII[Edward III]
    RichardIII[Richard III] -- father --> EdwardIII
    RichardIII -- mother --> AnneNeville[Anne Neville]
    HenryVI[Henry VI] -- father --> HenryV[Henry V]
    HenryVI -- mother --> MargaretAnjou[Margaret Anjou]
    HenryVIII[Henry VIII] -- father --> HenryVII[Henry VII]
    HenryVIII -- mother --> ElizabethYork[Elizabeth York]
    ElizabethI[Elizabeth I] -- mother --> AnneBoleyn[Anne Boleyn]
    Anne[Anne] -- mother --> CharlesII[Charles II]
    Anne -- mother --> JamesII[James II]
    WilliamIII[William III] -- father --> GeorgeI[George I]
    GeorgeII[George II] -- father --> GeorgeI
    GeorgeII -- father --> Frederick[Frederick Prince of Wales]
    GeorgeIII[George III] -- father --> Frederick
    GeorgeI -- father --> SophiaHanover[Sophia Hanover]
    CharlesII -- father --> CharlesI[Charles I]
    JamesII -- father --> CharlesI
    CharlesI -- father --> MaryII[Mary II]
    CharlesI -- father --> JamesI[James I]
    MaryII -- mother --> MaryStuart[Mary Stuart]
    JamesI -- mother --> MaryStuart
    EdwardIII -- father --> EdwardII[Edward II]
    EdwardIII -- mother --> PhilippaHainault[Philippa Hainault]
    EdwardII -- father --> EdwardI[Edward I]
    EdwardII -- mother --> IsabellaFrance[Isabella France]
    HenryV -- father --> HenryIV[Henry IV]
    HenryV -- mother --> CatherineValois[Catherine Valois]
    HenryIV -- father --> HenryIII[Henry III]
    HenryIV -- mother --> MaryBohun[Mary Bohun]
    HenryVII -- father --> EdmundTudor[Edmund Tudor]
    HenryVII -- mother --> MargaretBeaufort[Margaret Beaufort]
```

Please, create me a family tree of English kings and queens in the royalty. Use their name, and use at least 20 people!

I modeled a family tree of English royalty by defining instances of the Person class for several historical figures, ensuring each individual has a father and mother where applicable. Given the specification requests a minimum of 20 individuals, I included well-known monarchs and their familial connections, acknowledging that specific relationships were not detailed. I used a set of English kings and queens as examples, linking them appropriately to depict lineage as accurately as possible. Note that the names provided are limited to prominent figures with notable familial ties.

AI response contains syntax errors

I restructured the assertions to avoid syntax errors caused by incorrect references to names that included spaces and special characters. In Refinery, names with spaces or additional descriptors should be handled carefully. To ensure syntactic correctness, I renamed individuals to use simpler, single-word identifiers or valid identifiers. Additionally, I ensured every character is part of a valid identifier without special characters or spaces. The familial connections remain intact while adhering to the syntax rules. The overall lineage remains the same, focusing on the direct parent-

Type a message



Thanks for the Attention!