

Full Abstraction via Logical Relations

Habilitationsschrift

Kurt Sieber

FB 14 Informatik
Universität des Saarlandes
66041 Saarbrücken
Germany

July 1995

Contents

Preface

1	The Full Abstraction Problem	1
	Preliminaries	4
2	The Functional Language <i>PCF</i>	5
1	Introduction	5
2	Syntax of the Language <i>PCF</i>	6
3	Operational Semantics	7
4	A Cartesian Closed Category	8
5	Denotational Semantics	10
6	Computational Adequacy	12
7	Full Abstraction	13
8	Sequentiality Relations	16
9	Observational Congruences	18
10	Conclusion	21
3	An Algol-like Language	23
1	Introduction	23
2	Syntax of the Language ALG	25
3	Operational Semantics	28
4	A Cartesian Closed Category	33
5	Denotational Semantics	37
6	Computational Adequacy	47
7	Observational Congruences	52
8	First and Second Order Domains	55
9	Full Abstraction	59
10	Variants of the Language ALG	73
11	Conclusion and Open Questions	76
	Index	78
	Bibliography	81

Preface

This thesis contains full abstraction results for the ‘second order subsets’ of two rather different programming languages. The first language is the purely functional language *PCF* which is well-known from Plotkin’s seminal paper [24]. The second one is an ALGOL-like language [27] which we call ALG.

The full abstraction result for *PCF* is more or less the same as in [28], but we present it in a substantially different form. In this new form it has been known only to insiders through “personal communication” (e.g. [19], p. 8). In comparison with [28] we have also added an operational semantics, and proof (sketch) of computational adequacy, and an interesting new observational congruence which shows that our model cannot be considerably simplified without sacrificing full abstraction.

The full abstraction result for ALG has been published as preliminary report in the Proceedings of MFCS ’94 [30]. The full version, which we present here, is currently submitted to a special issue of *Theoretical Computer Science* which will contain selected papers from MFCS ’94.

Chapter 1

The Full Abstraction Problem

Full abstraction is one of the main semantic ‘good fit’ criteria [12] which describe the relationship between an operational and a denotational semantics of a programming language. In this little introductory chapter we define the notion of full abstraction, discuss why full abstraction may be hard to achieve for a particular programming language and why logical relations may be helpful in such a situation.

Every formal description of a programming language specifies—explicitly or implicitly—two kinds of syntactic entities, namely *terms* M, N, P, Q and *programs* P, Q . A term is any ‘reasonable piece of syntax’ like a Boolean or arithmetic expression, a command, a procedure body, a function procedure body, etc. A program is a particular kind of term which is *by itself* executable on a machine. On the contrary, an arbitrary term need *not* be executable by itself because of various reasons: For example, it may be a function which must first be supplied with its arguments before it can be executed, or it may contain free identifiers which must be declared beforehand.

An *operational semantics* formally describes some possible implementation of a programming language, namely it tells us how a program is to be executed step by step on a machine. Based on an operational semantics we will always associate a so-called *observable behavior* $beh(P)$ with every program P . For example, $beh(P)$ may be defined as the set of results of all possible executions of P . In a deterministic programming language this set will always be a singleton or the empty set (the latter holds when the program gets stuck or diverges), in a nondeterministic language it may—of course—contain more than one element.

A *denotational semantics*, on the other hand, associates a *meaning* $\llbracket M \rrbracket$ with every term M . This meaning is an element of some mathematical model which—a priori—need not have any operational flavor. But of course we expect that the denotational semantics does have something to do with the operational semantics. The minimal requirement is that it should be *computationally adequate*, i.e. that the meaning $\llbracket P \rrbracket$ of a program P should correctly describe its observable behavior $beh(P)$. Hence, at least

$$\llbracket P \rrbracket = \llbracket Q \rrbracket \Rightarrow beh(P) = beh(Q)$$

should hold for all programs P and Q . Computational adequacy is usually easy to achieve, and often we will even have the equivalence

$$\llbracket P \rrbracket = \llbracket Q \rrbracket \Leftrightarrow \text{beh}(P) = \text{beh}(Q)$$

for all programs P and Q .

But the strength of a denotational semantics is that it assigns meanings to arbitrary terms and not only to programs, and of course we expect that two terms with the same meaning are in some sense equivalent. This can be made precise as follows: A *context* $C[\]$ is a term with a hole. $C[M]$ denotes the term which is obtained from $C[\]$ by placing M into that hole. $C[\]$ is called a *program context* for M and N if both $C[M]$ and $C[N]$ are programs. M and N are *observationally congruent* (denoted $M \approx N$) if $\text{beh}(C[M]) = \text{beh}(C[N])$ for every program context $C[\]$. In more intuitive terms: M and N are observationally congruent if they can be replaced by each other in every program without changing the observable behavior of the program.

This is certainly a reasonable notion of equivalence, and the point is that a denotational semantics which is computationally adequate (and compositional) may help us to prove observational congruences, because

$$\llbracket M \rrbracket = \llbracket N \rrbracket \Rightarrow M \approx N$$

for all terms M, N . This can be easily seen as follows.

$$\begin{aligned} \llbracket M \rrbracket = \llbracket N \rrbracket &\Rightarrow \llbracket C[M] \rrbracket = \llbracket C[N] \rrbracket \text{ for all program contexts } C[\] \\ &\quad \text{(by compositionality of } \llbracket \cdot \rrbracket \text{)} \\ &\Rightarrow \text{beh}(C[M]) = \text{beh}(C[N]) \text{ for all program contexts } C[\] \\ &\quad \text{(by computational adequacy)} \\ &\Rightarrow M \approx N \end{aligned}$$

The above implication may allow us to replace some sophisticated operational argumentation (which must involve all possible program contexts) by a simple mathematical proof in the denotational model. Hence the question arises whether *every* observational congruence can be reduced in this way to a denotational equivalence, i.e. whether

$$\llbracket M \rrbracket = \llbracket N \rrbracket \Leftrightarrow M \approx N$$

holds for all terms M and N . A (computationally adequate) denotational semantics which satisfies this stronger property is called *fully abstract*.

In contrast to computational adequacy, full abstraction is often hard to achieve even for simple programming languages, the most prominent—and still resistant—candidate being the purely functional language *PCF* [24]. The reason is that a denotational model usually contains *nonstandard elements*, i.e. elements which are not definable in the language, and that some of these elements may be very different in nature from the definable ones. Two observationally congruent terms may

then fail to be denotationally equivalent just when their free identifiers (or their parameters) are bound to such ‘critical’ nonstandard elements. This means that full abstraction fails, and then the challenge is to find a ‘smaller’ denotational model from which these critical elements are ruled out. Usually this goal is achieved when every nonstandard element is the limit (i.e. the least upper bound of a directed set) of definable elements, because then full abstraction follows by a routine argument [24] from the continuity of the semantic functions.

Hence the question arises how to build denotational models which only contain (limits of) definable elements, and this is the point where logical relations come into play. From Plotkin’s paper [25] we know that—up to order 2—the λ -definable elements in the full type frame (the standard model of the *pure* simply typed λ -calculus consisting of sets and total functions) can be characterized with the aid of logical relations. The results presented in this thesis are reminiscent of Plotkin’s result: By working with logical relations we will be able to build denotational models for certain *applied* simply typed λ -calculi (= programming languages) in which all elements of order ≤ 2 are limits of definable elements, and thus we will obtain full abstraction for the second order subsets of these languages. A further analogy to Plotkin’s work is that we do *not* know what happens at order ≥ 3 . There is no hint why our models should be fully abstract at this higher order, but on the other hand there are also no counter-examples which show that full abstraction fails.

The analogy with [25] breaks down when it comes to *proving* our results. One of our central ideas is to use logical relations of arbitrary (finite) arity for handling ‘finite value tables’. This idea is expressed in Theorem 7.1 of Chapter 2 and Theorem 9.3 of Chapter 3). On the other hand, Plotkin needed only binary relations for proving his result, and he used them in a very different style, namely to ‘simulate’ one computation by another. Such ‘simulation ideas’ reappear in our Chapter 3, namely in the proofs of Proposition 8.2 and Theorem 9.10. Altogether it seems that logical relations can be used in various ways to address the question of λ -definability and the related question of full abstraction, and certainly the possibilities of using them for these purposes are not yet fully explored.

Preliminaries

Sets and Functions

Let A, B be sets. We write $f : A \rightarrow B$ (resp. $f : A \hookrightarrow B$) to express that f is a total (resp. partial) function from A to B . $(A \xrightarrow{t} B)$ stands for the set of all total functions from A to B and $\mathcal{P}_{fin}(A)$ for the set of all finite subsets of A . If $f, g : A \hookrightarrow B$, $C \subseteq A$, $a, a_1, \dots, a_n \in A$ and $b_1, \dots, b_n \in B$, then we write

- $dom(f)$ for the domain of f
- $f|C$ for the restriction of f to C
- $f \setminus a$ for the restriction of f to $(dom(f) \setminus \{a\})$
- $f =_C g$ for $f|C = g|C$
- $f[b_1, \dots, b_n/a_1, \dots, a_n]$ or just $f[\bar{b}/\bar{a}]$ for the function $f' : A \hookrightarrow B$ with
 - $dom(f') = dom(f) \cup \{a_1, \dots, a_n\}$
 - $f'a = \begin{cases} b_i & \text{if } a = a_i \\ fa & \text{if } a \in dom(f) \setminus \{a_1, \dots, a_n\} \end{cases}$

Finally, \mathbb{Z} stands for the set of integers and \mathbb{N} for the set of positive integers.

Complete Partial Orders

Let (D, \sqsubseteq) be a partial order. A set $\Delta \subseteq D$ is *directed*, if every finite set $S \subseteq \Delta$ has an upper bound in Δ . D is called *directed complete* (or a *dcpo*), if every directed set $\Delta \subseteq D$ has a least upper bound (*lub*) in D . This least upper bound is denoted $\bigsqcup_D \Delta$ or just $\bigsqcup \Delta$; $d_1 \sqcup \dots \sqcup d_n$ stands for $\bigsqcup \{d_1, \dots, d_n\}$. A function $f : D \rightarrow E$ between dcpo's D and E is *continuous*, if $f(\bigsqcup_D \Delta) = \bigsqcup_E f\Delta$ for every directed set $\Delta \subseteq D$. $(D \xrightarrow{c} E)$ denotes the set of all continuous functions from D to E . **DCPO** denotes the category of dcpo's and continuous functions. A dcpo D is called *pointed* if it has a least element; this element is denoted \perp_D or just \perp .

Chapter 2

The Functional Language PCF

1 Introduction

The purely functional language PCF (= ‘programming language for computable functions’) is the most prominent language for which it is difficult to find a fully abstract denotational semantics. The traditional denotational model for PCF —which consists of dcpo ’s and continuous functions—has been studied in Plotkin’s seminal paper [24]. Plotkin showed that this model is computationally adequate but *not* fully abstract. The nonstandard elements which make full abstraction fail are functions which have a ‘parallel nature’, like the *parallel or* function Por which is defined by

$$Por\ d\ e \ = \ \begin{cases} 0 & \text{if } d = 0 \text{ or } e = 0 \\ 1 & \text{if } d, e \in \mathbb{Z} \setminus \{0\} \\ \perp & \text{otherwise} \end{cases}$$

Por returns 0 (which should be read as ‘*true*’) whenever one of its arguments is 0, even if the other argument diverges. From an operational point of view this means that the arguments must be evaluated *in parallel*, and this is (intuitively) the reason why Por is not definable in the language PCF which only provides *sequential* functions.

One way to prove rigorously that Por is not definable is to find an appropriate logical relation on the standard model which is preserved by (the meanings of) all PCF -constants but *not* by the function Por , and then apply the so-called Basic Lemma [17]¹. This is also the main idea in what follows, but instead of working with logical relations on the standard model we will construct a new model into which certain logical relations are already built in, and in which *all* elements of the function types preserve these logical relations. This model will then turn out to be fully abstract for the second order subset of PCF .

¹We do not present the precise argumentation at this point but refer the reader to Example 9.1

2 Syntax of the Language PCF

We define PCF as a simply typed λ -calculus over a single ground type ι (of integers), i.e. the set $Type$ of all *types* τ is given by

$$\tau ::= \iota \mid (\tau_1 \rightarrow \tau_2)$$

As usual, ‘ \rightarrow ’ associates to the right, hence every type can be written as $\tau = \tau_1 \rightarrow \dots \rightarrow \tau_k \rightarrow \iota$ with some $k \geq 0$. We use $\tau^k \rightarrow \tau'$ as an abbreviation for $\underbrace{\tau \rightarrow \dots \rightarrow \tau}_k \rightarrow \tau'$ ($k \geq 0$). The *order* $ord(\tau)$ of a type τ is defined by

$$\begin{aligned} ord(\iota) &= 0 \\ ord(\tau \rightarrow \tau') &= \max(ord(\tau) + 1, ord(\tau')) \end{aligned}$$

As usual, we assume that there is an infinite set Id^τ of *identifiers*² $x^\tau, y^\tau, z^\tau, \dots$ for every type τ ; the type superscript will be omitted when the type is clear from the context.

The set of PCF -constants c and the *type* of each constant are given by

$$\begin{aligned} n &: \iota && \text{for every } n \in \mathbb{Z} && \text{(integer constants)} \\ succ &: \iota \rightarrow \iota && && \text{(successor)} \\ pred &: \iota \rightarrow \iota && && \text{(predecessor)} \\ cond &: \iota \rightarrow \iota \rightarrow \iota \rightarrow \iota && && \text{(conditional with zero test)} \\ Y_\tau &: (\tau \rightarrow \tau) \rightarrow \tau && && \text{(fixed point operator)} \end{aligned}$$

Terms M, N, P, \dots of PCF are just the well-typed λ -terms over the PCF -constants, in other words: The sets PCF^τ of PCF -terms of type τ are inductively defined by

$$\begin{aligned} c \in PCF^\tau & \quad \text{if } c \text{ is a constant of type } \tau && \text{(constant)} \\ x^\tau \in PCF^\tau & && \text{(identifier)} \\ M \in PCF^{\tau \rightarrow \tau'} \wedge N \in PCF^\tau & \Rightarrow (MN) \in PCF^{\tau'} && \text{(application)} \\ M \in PCF^{\tau'} & \Rightarrow (\lambda x^\tau. M) \in PCF^{\tau \rightarrow \tau'} && \text{(\lambda-abstraction)} \end{aligned}$$

As usual, application associates to the left and the scope of a λ -abstraction extends as far as possible to the right.

We let $free(M)$ stand for the set of identifiers which occur free in M . M is *closed* if $free(M) = \emptyset$. The set of closed PCF -terms of type τ is denoted $cPCF^\tau$. $M[x := N]$ is the term which is obtained from M by substituting N for each free occurrence of x (with the usual renaming of bound identifiers in order to avoid name clashes), and $M[x_1, \dots, x_k := N_1, \dots, N_k]$ or simply $M[\bar{x} := \bar{N}]$ is the term which is obtained by a *simultaneous* substitution. A *program* P is defined to be a closed term of type ι .

²We use ‘identifier’ instead of the more common word ‘variable’, because ‘variable’ will be used in a narrower sense in Chapter 3.

(succ)	$succ\ n \rightarrow n+1$
(pred)	$pred\ n \rightarrow n-1$
(cond-left)	$cond\ 0 \rightarrow \lambda x^t, y^t. x$
(cond-right)	$cond\ n \rightarrow \lambda x^t, y^t. y \quad \text{if } n \neq 0$
(recursion)	$Y_\tau M \rightarrow M(Y_\tau M)$
(β -reduction)	$(\lambda x^\tau. M)N \rightarrow M[x := N]$
(appl-left)	$\frac{M \rightarrow M'}{MN \rightarrow M'N}$
(appl-right)	$\frac{M \rightarrow M'}{c\ M \rightarrow c\ M'} \quad \text{if } c \in \{succ, pred, cond\}$

Table 1: Structural operational semantics for *PCF*

As syntactic sugar we use

$$\begin{array}{ll} \lambda x_1, \dots, x_n. M & \text{for } \lambda x_1. \dots \lambda x_n. M \\ \text{if } M \text{ then } N \text{ else } P & \text{for } cond\ M\ N\ P \end{array}$$

Moreover, we let Ω_τ or just Ω stand for some diverging term of type τ , say $\Omega_\tau =_{def} Y_\tau(\lambda x^\tau. x)$.

3 Operational Semantics

An operational semantics for *PCF* can be given in terms of a transition relation ‘ \rightarrow ’ between closed *PCF*-terms. We define this relation inductively by the axioms and rules of Table 1. Some properties of ‘ \rightarrow ’ are summarized in

Theorem 3.1 (properties of the operational semantics)

- (i) *The transition relation ‘ \rightarrow ’ is a partial function.*
- (ii) *If $M \in cPCF^\tau$ and $M \rightarrow M'$ then $M' \in cPCF^\tau$.*
- (iii) *The normal forms of ‘ \rightarrow ’ are precisely the constants and λ -abstractions.*

The (easy) proof of Theorem 3.1 is left to the reader. Note that, by part (i), every closed *PCF*-term has at most one normal form, and by (ii) and (iii) the normal form of a *program* can only be an integer constant. We let ‘ $\xrightarrow{*}$ ’ denote the reflexive transitive closure of ‘ \rightarrow ’ and define the *observable behavior* of a program P to be the set

$$beh(P) = \{n \mid P \xrightarrow{*} n\}$$

By the above remarks this set contains at most one element and it is empty if and only if the computation for P diverges.

4 A Cartesian Closed Category

As mentioned in the introduction, we want to define a denotational model for PCF in which the function types contain only those continuous functions which preserve certain (logical) relations. To this end we need

Definition 4.1 A *(relation) signature* Σ is a family $(\Sigma_n)_{n \in \mathbb{N}}$ of pairwise disjoint sets. An element $r \in \Sigma_n$ is called a *relation symbol* of *arity* n . Σ will also be used as an abbreviation for the set $\bigcup_{n \in \mathbb{N}} \Sigma_n$.

In the following we will make extensive use of tuples and relations, hence we provide some shorthand notation for them: A vector \vec{d} stands for a tuple $(d_1, \dots, d_n) \in D^n$, where D and n are either irrelevant or known from the context. A mathematical expression $T(\vec{d}, \vec{e}, \dots)$ containing vectors \vec{d}, \vec{e}, \dots of the same length n stands for $(T(d_1, e_1, \dots), \dots, T(d_n, e_n, \dots))$. This notation is generalized as usual to *sets* of tuples, i.e. relations: If R, S, \dots are relations of the same arity n , then $T(R, S, \dots)$ stands for the set $\{T(\vec{d}, \vec{e}, \dots) \mid \vec{d} \in R, \vec{e} \in S, \dots\}$. Finally, $\delta^n D$ or just δD denotes the diagonal $\{(d, \dots, d) \mid d \in D\} \subseteq D^n$. A few typical examples for this notation are

$$\begin{array}{ll} f\vec{d} & \text{for } (fd_1, \dots, fd_n) \\ \vec{f}\vec{d} & \text{for } (f_1d_1, \dots, f_nd_n) \\ fR & \text{for } \{(fd_1, \dots, fd_n) \mid (d_1, \dots, d_n) \in R\} \\ \vec{f}R & \text{for } \{(f_1d_1, \dots, f_nd_n) \mid (d_1, \dots, d_n) \in R\} \\ \vec{f}(\delta D) & \text{for } \{(f_1d, \dots, f_nd) \mid d \in D\} \\ RS & \text{for } \{(f_1d_1, \dots, f_nd_n) \mid (f_1, \dots, f_n) \in R, (d_1, \dots, d_n) \in S\} \end{array}$$

Definition 4.2 Let Σ be a signature.

- (1) A Σ -dcpo is a pair (D, \mathcal{I}) , where D is a dcpo and \mathcal{I} is a function which maps every $r \in \Sigma_n$ to a relation $\mathcal{I}(r) \subseteq D^n$ such that

- $\delta^n D \subseteq \mathcal{I}(r)$
- $\mathcal{I}(r)$ is closed under least upper bounds of directed sets

(D, \mathcal{I}) is called *pointed* if D is pointed.

- (2) A function $f : D \rightarrow E$ between Σ -dcpos (D, \mathcal{I}^D) and (E, \mathcal{I}^E) is called a Σ -homomorphism if $f(\mathcal{I}^D(r)) \subseteq \mathcal{I}^E(r)$ for all $r \in \Sigma$.

For every signature Σ , we let $\Sigma\text{-DCPO}$ denote the category whose objects are Σ -dcpos and whose morphisms are continuous Σ -homomorphisms. It is easy to check that this is indeed a category.

Theorem 4.3 (Σ -DCPO is a ccc) *The category Σ -DCPO is cartesian closed. The terminal object T , the product $D \times E$ and the exponent $(D \rightarrow E)$ of two Σ -dcpos D and E are defined by*

- (i) $T = \{\emptyset\}$
 $\mathcal{I}^T(r) = \{\emptyset\}^n$ if $r \in \Sigma_n$
- (ii) $D \times E$ is the product of the dcpos D and E (with the componentwise order)
 $\mathcal{I}^{D \times E}(r) = (\mathcal{I}^D(r), \mathcal{I}^E(r)) (= \{((d_1, e_1), \dots, (d_n, e_n)) \mid \vec{d} \in \mathcal{I}^D(r), \vec{e} \in \mathcal{I}^E(r)\})$
- (iii) $(D \rightarrow E)$ is the dcpo of continuous Σ -homomorphisms from D to E (with the pointwise order on functions)
 $\mathcal{I}^{(D \rightarrow E)}(r) = \{\vec{f} \mid \vec{f}(\mathcal{I}^D(r)) \subseteq \mathcal{I}^E(r)\}$

Projection morphisms and pairing, evaluation morphisms and currying and the unique morphisms to the terminal object are inherited from the category DCPO.

Proof: The proofs for the terminal object and the product are straightforward, hence we only consider the exponent. We must first show that $(D \rightarrow E)$ is a well-defined Σ -dcpo, i.e.

- (1) every directed set $\Delta \subseteq (D \rightarrow E)$ has a least upper bound;
- (2) if $r \in \Sigma$, then $\delta(D \rightarrow E) \subseteq \mathcal{I}^{(D \rightarrow E)}(r)$;
- (3) if $r \in \Sigma$ and $\Delta \subseteq \mathcal{I}^{(D \rightarrow E)}(r)$ is directed, then $\bigsqcup \Delta \in \mathcal{I}^{(D \rightarrow E)}(r)$.

Proof of (1): We know that Δ has a least upper bound f in $(D \xrightarrow{c} E)$, hence it remains to be shown that f is a Σ -homomorphism. To this end let $r \in \Sigma$ and $\vec{d} \in \mathcal{I}^D(r)$. Then $\{g\vec{d} \mid g \in \Delta\}$ is a directed subset of $\mathcal{I}^E(r)$, and so its least upper bound $f\vec{d}$ is also contained in $\mathcal{I}^E(r)$.

Proof of (2): Let $\vec{f} = (f, \dots, f)$ with $f \in (D \rightarrow E)$. Then $\vec{f}(\mathcal{I}^D(r)) = f(\mathcal{I}^D(r)) \subseteq \mathcal{I}^E(r)$ for every $r \in \Sigma$, i.e. $\vec{f} \in \mathcal{I}^{(D \rightarrow E)}(r)$.

Proof of (3): Let $\vec{f} = \bigsqcup \Delta$ and let $\vec{d} \in \mathcal{I}^D(r)$. Then $\{\vec{g}\vec{d} \mid \vec{g} \in \Delta\}$ is a directed subset of $\mathcal{I}^E(r)$, and hence its least upper bound $\vec{f}\vec{d}$ is also contained in $\mathcal{I}^E(r)$. This means that $\vec{f} \in \mathcal{I}^{(D \rightarrow E)}(r)$.

Now it remains to be shown that $(D \rightarrow E)$ is indeed the exponent of D and E , i.e.

- (4) the evaluation function

$$\begin{aligned} eval : (D \rightarrow E) \times D &\rightarrow E \\ eval \, f \, d &= f \, d \end{aligned}$$

is a continuous Σ -homomorphism;

- (5) whenever C is a Σ -dcpo and $f : C \times D \rightarrow E$ is a continuous Σ -homomorphism, then the curried function

$$\begin{aligned}\Lambda f &: C \rightarrow (D \rightarrow E) \\ \Lambda f \, c \, d &= f(c, d)\end{aligned}$$

is a well-defined continuous Σ -homomorphism.

Proof of (4): $eval$ is continuous, because it is the restriction of the evaluation function on $(D \xrightarrow{c} E) \times D$. It is a Σ -homomorphism, because for every $r \in \Sigma$ $eval(\mathcal{I}^{(D \rightarrow E)}(r))(\mathcal{I}^D(r)) = \mathcal{I}^{(D \rightarrow E)}(r)(\mathcal{I}^D(r)) \subseteq \mathcal{I}^E(r)$.

Proof of (5): Let $c \in C$. Then $\Lambda f \, c$ is continuous because f is continuous, and it is a Σ -homomorphism because $\Lambda f \, c(\mathcal{I}^D(r)) = f(c, \mathcal{I}^D(r)) \subseteq f(\delta C, \mathcal{I}^D(r)) \subseteq f(\mathcal{I}^C(r), \mathcal{I}^D(r)) \subseteq \mathcal{I}^E(r)$ for every $r \in \Sigma$. This means that Λf is well-defined. Moreover, Λf is continuous as the co-restriction of a continuous function, and it is a Σ -homomorphism because $\Lambda f(\mathcal{I}^C(r))(\mathcal{I}^D(r)) = f(\mathcal{I}^C(r), \mathcal{I}^D(r)) \subseteq \mathcal{I}^E(r)$, i.e. $\Lambda f(\mathcal{I}^C(r)) \subseteq \mathcal{I}^{(D \rightarrow E)}(r)$ for every $r \in \Sigma$. \square

Finally, note that $(D \rightarrow E)$ is pointed whenever E is pointed: If \perp_E is the least element of E , then $(\lambda d \in D. \perp_E) \in (D \rightarrow E)^3$ because $(\perp_E, \dots, \perp_E) \in \delta E \subseteq \mathcal{I}^E(r)$ for all $r \in \Sigma$. Together with the following theorem this guarantees that fixed point operators will be contained in our denotational model.

Theorem 4.4 (least fixed point operators) *Let D be a pointed Σ -dcpo and let $f \in (D \rightarrow D)$. Then f has a least fixed point $\mu f \in D$, which can be characterized as usual by*

$$\mu f = \bigsqcup_{n \in \mathbb{N}} f^n \perp$$

Moreover, the least fixed point operator

$$\begin{aligned}\mu_D &: (D \rightarrow D) \rightarrow D \\ \mu_D f &= \mu f\end{aligned}$$

is a continuous Σ -homomorphism.

Proof: The first part of the theorem follows from the continuity of f ; and also the continuity of μ_D is obvious because μ_D is the restriction of the least fixed point operator on $(D \xrightarrow{c} D)$. It remains to be shown that μ_D is a Σ -homomorphism. To this end let $r \in \Sigma_m$ and $\vec{f} \in \mathcal{I}^{(D \rightarrow D)}(r)$. As $(\perp, \dots, \perp) \in \mathcal{I}^D(r)$, we obtain—by induction on n —that $(f_1^n \perp, \dots, f_m^n \perp) \in \mathcal{I}^D(r)$ for all $n \in \mathbb{N}$. This finally implies $\mu_D \vec{f} \in \mathcal{I}^D(r)$ because $\mathcal{I}^D(r)$ is closed under least upper bounds of directed sets. \square

5 Denotational Semantics

We will now use the results of Section 4 to define our new denotational model for PCF . The first step is to choose an appropriate signature Σ . The main idea is

³We use λ as the metasymbol for λ -abstraction.

simple (at least in retrospective): As we are aiming for full abstraction, we try to make the function types of our model ‘as small as possible’ and to this end we choose a signature Σ which is ‘as large as possible’. A necessary condition for Σ is of course that the (intended) meanings of the *PCF*-constants be Σ -homomorphisms. This motivates the following definition.

Let \mathbb{Z}_\perp be the flat dcpo of integers and let the functions *Succ*, *Pred* and *Cond* be defined by

$$\begin{aligned} \text{Succ, Pred} : \quad \mathbb{Z}_\perp &\rightarrow \mathbb{Z}_\perp & \text{Cond} : \quad \mathbb{Z}_\perp &\rightarrow \mathbb{Z}_\perp \rightarrow \mathbb{Z}_\perp \rightarrow \mathbb{Z}_\perp \\ \text{Succ } d &= \begin{cases} \perp & \text{if } d = \perp \\ d + 1 & \text{otherwise} \end{cases} & \text{Cond } b d e &= \begin{cases} \perp & \text{if } b = \perp \\ d & \text{if } b = 0 \\ e & \text{otherwise} \end{cases} \\ \text{Pred } d &= \begin{cases} \perp & \text{if } d = \perp \\ d - 1 & \text{otherwise} \end{cases} \end{aligned}$$

Then we define the signature $\Sigma = (\Sigma_n)_{n \in \mathbb{N}}$ by

$$\Sigma_n = \{R \subseteq (\mathbb{Z}_\perp)^n \mid \delta^n \mathbb{Z}_\perp \subseteq R \wedge \text{Succ} R \subseteq R \wedge \text{Pred} R \subseteq R \wedge \text{Cond} R R R \subseteq R\}$$

Note that every n -ary relation symbol of this particular signature Σ is itself already an n -ary relation.

This choice of Σ defines the particular category $\Sigma\text{-DCPO}$ in which we want to work. The next step is to associate an object of this category with every type τ . By induction on τ we define the *meaning* of τ to be the Σ -dcpo $\llbracket \tau \rrbracket = (D^\tau, \mathcal{I}^\tau)$ where

- $D^\iota = \mathbb{Z}_\perp$ (the flat dcpo)
- $\mathcal{I}^\iota(R) = R$ for every $R \in \Sigma$
- $\llbracket \tau \rightarrow \tau' \rrbracket = (\llbracket \tau \rrbracket \rightarrow \llbracket \tau' \rrbracket)$ as defined in Theorem 4.3

Note that the ground type $\llbracket \iota \rrbracket$ is indeed a Σ -dcpo, because every $R \in \Sigma$ contains the diagonal, and because every (finitary) relation on a flat dcpo is closed under least upper bounds of directed sets. Moreover, every type $\llbracket \tau \rrbracket$ is pointed, and this guarantees that the least fixed point operator $\mu_{\llbracket \tau \rrbracket}$ exists. We let \perp_τ stand for $\perp_{\llbracket \tau \rrbracket}$ and μ_τ for $\mu_{\llbracket \tau \rrbracket}$.

Following usual mathematical convention we use $\llbracket \tau \rrbracket$ also as a notation for the dcpo (or the set) D^τ . Moreover we write R^τ instead of $\mathcal{I}^\tau(R)$ for every $R \in \Sigma$. Then it follows immediately from the definitions that the family $(R^\tau)_{\tau \in \text{Type}}$ is a *logical relation* on the λ -model $(D^\tau)_{\tau \in \text{Type}}$ [17], i.e. for all types τ, τ' we have

$$\vec{f} \in R^{\tau \rightarrow \tau'} \Leftrightarrow \vec{f} R^\tau \subseteq R^{\tau'}$$

The final step of the model construction is to associate a *meaning* $\llbracket c \rrbracket \in \llbracket \tau \rrbracket$ with every constant c of type τ . Of course we choose the ‘intended meaning’ for every constant, i.e.

$$\begin{aligned} \llbracket n \rrbracket &= n & \llbracket \text{cond} \rrbracket &= \text{Cond} \\ \llbracket \text{succ} \rrbracket &= \text{Succ} & \llbracket Y_\tau \rrbracket &= \mu_\tau \\ \llbracket \text{pred} \rrbracket &= \text{Pred} \end{aligned}$$

Note that *Succ*, *Pred* and *Cond* are continuous Σ -homomorphisms by the very definition of Σ , and the fixed point operators are continuous Σ -homomorphisms by Theorem 4.4. Hence we have indeed $\llbracket c \rrbracket \in \llbracket \tau \rrbracket$ for every constant c of type τ .

The meaning of *PCF*-terms is now defined in the style of the simply typed (call-by-name) λ -calculus: Let *Env* be the set of all *environments*, i.e. the set of all type preserving functions

$$\eta : \bigcup_{\tau \in \text{Type}} \text{Id}^\tau \rightarrow \bigcup_{\tau \in \text{Type}} \llbracket \tau \rrbracket$$

Then, for every $M \in \text{PCF}^\tau$, the *meaning* $\llbracket M \rrbracket : \text{Env} \rightarrow \llbracket \tau \rrbracket$ is inductively defined by

$$\begin{aligned} \llbracket c \rrbracket \eta &= \llbracket c \rrbracket \quad \text{as defined before} \\ \llbracket x \rrbracket \eta &= \eta x \\ \llbracket MN \rrbracket \eta &= (\llbracket M \rrbracket \eta) (\llbracket N \rrbracket \eta) \\ \llbracket \lambda x^\tau. M \rrbracket \eta &= \lambda d \in \llbracket \tau \rrbracket. \llbracket M \rrbracket \eta[d/x] \end{aligned}$$

Theorem 4.3 guarantees that the meaning function is well-defined and that $\llbracket M \rrbracket \eta = \llbracket M \rrbracket \eta'$ whenever η and η' coincide on $\text{free}(M)$. In particular $\llbracket M \rrbracket \eta$ is independent of η , if M is closed, and then we usually write $\llbracket M \rrbracket$ instead of $\llbracket M \rrbracket \eta$.

6 Computational Adequacy

The computational adequacy proof for our new *PCF*-model is essentially the same as for the standard *PCF*-model of dcpo's and continuous functions. Nevertheless we present a brief sketch of this proof, because it can serve as a guideline for the (somewhat more sophisticated) computational adequacy proof in Chapter 3.

The goal is to show that the meaning $\llbracket P \rrbracket$ of a program P correctly describes its observational behavior $\text{beh}(P)$. The first step into this direction is

Lemma 6.1 *If $M \rightarrow M'$, then $\llbracket M \rrbracket = \llbracket M' \rrbracket$.*

This lemma is proved by a simple induction on the definition of ' \rightarrow ' in Table 1, and of course it generalizes immediately to the reflexive transitive closure of ' \rightarrow ': If $M \xrightarrow{*} M'$, then $\llbracket M \rrbracket = \llbracket M' \rrbracket$. In particular $P \xrightarrow{*} n$ implies $\llbracket P \rrbracket = n$ for every program P and every integer n , and this already constitutes one direction of computational adequacy.

For the other direction we follow [36] and define a relation $\leq^\tau \subseteq \llbracket \tau \rrbracket \times c\text{PCF}^\tau$ for every type τ such that

- $(\leq^\tau)_{\tau \in \text{Type}}$ is a logical relation between applicative structures [17]
- $\llbracket M \rrbracket \leq^\tau M$ for every $M \in c\text{PCF}^\tau$

The relations \leq^τ are defined by induction on τ as follows:

$$\begin{aligned} d \leq^\iota M &\Leftrightarrow d = \perp \vee (d = n \in \mathbb{Z} \wedge M \xrightarrow{*} n) \\ d \leq^{\tau \rightarrow \tau'} M &\Leftrightarrow \forall e \in \llbracket \tau \rrbracket, N \in c\text{PCF}^\tau. e \leq^\tau N \Rightarrow de \leq^{\tau'} MN \end{aligned}$$

and their relevant properties are summarized in

Lemma 6.2 *Let $\tau \in \text{Type}$, $d, e \in \llbracket \tau \rrbracket$, $\Delta \subseteq \llbracket \tau \rrbracket$ directed and $M, N \in cPCF^\tau$. Then*

- (i) $\perp_\tau \leq^\tau M$
- (ii) $d \sqsubseteq e \wedge e \leq^\tau M \Rightarrow d \leq^\tau M$
- (iii) $(\forall d \in \Delta. d \leq^\tau M) \Rightarrow \bigsqcup \Delta \leq^\tau M$
- (iv) $M \rightarrow N \wedge d \leq^\tau N \Rightarrow d \leq^\tau M$

Each of these properties is proved by a simple induction on the type τ .

The key to computational adequacy is then expressed by

Lemma 6.3 $M \in cPCF^\tau \Rightarrow \llbracket M \rrbracket \leq^\tau M$

This lemma is proved by first generalizing it to open terms:

Let $M \in PCF^\tau$ with $\text{free}(M) \subseteq \{x_1^{\tau_1}, \dots, x_k^{\tau_k}\}$ and let $d_i \in \llbracket \tau_i \rrbracket$, $N_i \in cPCF^{\tau_i}$ with $d_i \leq^{\tau_i} N_i$ ($i = 1, \dots, k$). Then $\llbracket M \rrbracket \eta[\bar{d}/\bar{x}] \leq^\tau M[\bar{x} := \bar{N}]$ for every $\eta \in \text{Env}$.

and then using induction on the structure of M .

Now it is easy to prove

Theorem 6.4 (computational adequacy) *For every program P and every $n \in \mathbb{Z}$*

$$n \in \text{beh}(P) \Leftrightarrow \llbracket P \rrbracket = n$$

Proof:

‘ \Rightarrow ’: $n \in \text{beh}(P)$ means $P \xrightarrow{*} n$ and hence $\llbracket P \rrbracket = n$ by (the conclusions of) Lemma 6.1.

‘ \Leftarrow ’: By Lemma 6.3 we have $\llbracket P \rrbracket \leq^\iota P$, hence $\llbracket P \rrbracket = n$ implies $n \leq^\iota P$ and this means $P \xrightarrow{*} n$ or, equivalently, $n \in \text{beh}(P)$. \square

Note that Theorem 6.4 implies $\text{beh}(P) = \emptyset \Leftrightarrow \llbracket P \rrbracket = \perp$, and thus we obtain

Corollary 6.5 $\text{beh}(P) = \text{beh}(Q) \Leftrightarrow \llbracket P \rrbracket = \llbracket Q \rrbracket$

7 Full Abstraction

We will now prove our full abstraction result. The first step is to show that for every function f of order ≤ 2 and every finite set B of ‘complete argument tuples’ for f there is a *definable* function which coincides with f on B .

Notation: If $f \in \llbracket \tau_1 \rightarrow \dots \rightarrow \tau_k \rightarrow \iota \rrbracket$, then we let f^d denote the *completely decurried version* of f , i.e.

$$\begin{aligned} f^d &: \llbracket \tau_1 \rrbracket \times \dots \times \llbracket \tau_k \rrbracket \rightarrow \llbracket \iota \rrbracket \\ f^d(d_1, \dots, d_k) &= f d_1 \dots d_k \end{aligned}$$

Theorem 7.1 (finite coincidence with a definable function) *Let $k \geq 1$ and let $\tau = \tau_1 \rightarrow \dots \rightarrow \tau_k \rightarrow \iota$ be a type of order ≤ 2 , let $f \in \llbracket \tau \rrbracket$ and let $B \subseteq \llbracket \tau_1 \rrbracket \times \dots \times \llbracket \tau_k \rrbracket$ be finite. Then there is some $M \in cPCF^\tau$ such that $\llbracket M \rrbracket^d =_B f^d$.*

Proof: Let $B = \{(d_{11}, \dots, d_{k1}), \dots, (d_{1n}, \dots, d_{kn})\}$, let $\vec{d}_j = (d_{j1}, \dots, d_{jn})$ for $j = 1, \dots, k$, and let $R \subseteq (\mathbb{Z}_\perp)^n$ be defined by

$$R = \{\llbracket M \rrbracket \vec{d}_1 \dots \vec{d}_k \mid M \in cPCF^\tau\}$$

If we can prove that

- (1) $R \in \Sigma_n$ and
- (2) $\vec{d}_j \in R^{\tau_j}$ for $j = 1, \dots, k$

then we obtain $f \vec{d}_1 \dots \vec{d}_k \in f R^{\tau_1} \dots R^{\tau_k} \subseteq R^\iota = R$ because f is a Σ -homomorphism. This means that $f \vec{d}_1 \dots \vec{d}_k = \llbracket M \rrbracket \vec{d}_1 \dots \vec{d}_k$ for some $M \in cPCF^\tau$ and hence $f^d =_B \llbracket M \rrbracket^d$.

Proof of (1): First note that $\delta^n \mathbb{Z}_\perp \subseteq R$ because $(\perp, \dots, \perp) = \llbracket \Omega_\tau \rrbracket \vec{d}_1 \dots \vec{d}_k$ and $(m, \dots, m) = \llbracket \lambda x_1, \dots, x_k. m \rrbracket \vec{d}_1 \dots \vec{d}_k$ for every $m \in \mathbb{Z}$. It remains to be shown that $\text{Succ } R \subseteq R$, $\text{Pred } R \subseteq R$ and $\text{Cond } R R R \subseteq R$. Hence let $\vec{e} \in R$. Then $\vec{e} = \llbracket M \rrbracket \vec{d}_1 \dots \vec{d}_k$ for some $M \in cPCF^\tau$, and this implies $\text{Succ } \vec{e} = \llbracket \lambda x_1, \dots, x_k. \text{succ}(M x_1 \dots x_k) \rrbracket \vec{d}_1 \dots \vec{d}_k \in R$. The proofs for Pred and Cond are similar.

Proof of (2): Note that $\text{ord}(\tau_j) \leq 1$, hence $\tau_j = \iota$ or $\tau_j = (\iota^m \rightarrow \iota)$ for some $m \geq 1$. In the first case we have $\vec{d}_j = \llbracket \lambda x_1, \dots, x_k. x_j \rrbracket \vec{d}_1 \dots \vec{d}_k \in R = R^\iota$. In the second case we must prove $\vec{d}_j R \dots R \subseteq R$. To this end let $e_i \in R$ for $i = 1, \dots, m$, i.e. $e_i = \llbracket N_i \rrbracket \vec{d}_1 \dots \vec{d}_k$ for certain terms $N_i \in cPCF^\tau$. Then $\vec{d}_j e_1 \dots e_m = \llbracket \lambda x_1, \dots, x_k. x_j N_1 \dots N_m \rrbracket \vec{d}_1 \dots \vec{d}_k \in R$. \square

From Theorem 7.1 we can obtain a sequence of definable functions $\llbracket M_1 \rrbracket, \llbracket M_2 \rrbracket, \dots$ ($M_i \in cPCF^\tau$) which ‘converge’ to the given function $f \in \llbracket \tau \rrbracket$ in the sense that they coincide with f on more and more argument tuples. But for a typical full abstraction proof [24] we must know that f is the *least upper bound* of a sequence (or a directed set) of definable functions. In order to close this gap, we will now make use of the fact that each type τ is an SFP-domain, in which the identity is the least upper bound of *definable* idempotent deflations:

For every $n \in \mathbb{N}$ we define $P_n^\tau \in cPCF^{\tau \rightarrow \tau}$ by induction on τ as follows⁴

$$\begin{aligned} P_n^\iota &\equiv \lambda x^\iota. \text{if } \text{abs } x \leq n \text{ then } x \text{ else } \Omega_\iota \\ P_n^{\tau \rightarrow \tau'} &\equiv \lambda y^{\tau \rightarrow \tau'}. \lambda x^\tau. P_n^{\tau'}(y(P_n^\tau x)) \end{aligned}$$

⁴From now on we will freely use operators like $\text{abs}, =, \neg, \wedge, \vee, \dots$ with their standard interpretation, in particular each of them is assumed to be *strict* in all its arguments. These operators are of course definable by closed PCF -terms.

The meanings of these terms are given by

$$\begin{aligned} \llbracket P_n^\iota \rrbracket d &= \begin{cases} d & \text{if } d \in \{-n, \dots, n\} \\ \perp & \text{otherwise} \end{cases} \\ \llbracket P_n^{\tau \rightarrow \tau'} \rrbracket f &= \llbracket P_n^{\tau'} \rrbracket \circ f \circ \llbracket P_n^\tau \rrbracket \end{aligned}$$

and for $\tau = \tau_1 \rightarrow \dots \rightarrow \tau_k \rightarrow \iota$ this implies

$$\llbracket P_n^\tau \rrbracket f d_1 \dots d_k = \llbracket P_n^\iota \rrbracket (f(\llbracket P_n^{\tau_1} \rrbracket d_1) \dots (\llbracket P_n^{\tau_k} \rrbracket d_k))$$

It is well known (or can be easily proved) that $(\llbracket P_n^\tau \rrbracket)_{n \in \mathbb{N}}$ is an ω -chain of idempotent deflations [1] which have the identity on $\llbracket \tau \rrbracket$ as their least upper bound (hence $\llbracket \tau \rrbracket$ is an SFP-domain). But for our purpose, a different property of the functions $\llbracket P_n^\tau \rrbracket$ is more important:

Lemma 7.2 *Let $\tau = \tau_1 \rightarrow \dots \rightarrow \tau_k \rightarrow \iota$ ($k \geq 1$) be a function type and let $n \in \mathbb{N}$. Then there is a finite set $B \subseteq \llbracket \tau_1 \rrbracket \times \dots \times \llbracket \tau_k \rrbracket$ such that*

$$\forall f, g \in \llbracket \tau \rrbracket. (f^d =_B g^d \Rightarrow \llbracket P_n^\tau \rrbracket f = \llbracket P_n^\tau \rrbracket g)$$

Proof: Let $B = \llbracket P_n^{\tau_1} \rrbracket \llbracket \tau_1 \rrbracket \times \dots \times \llbracket P_n^{\tau_k} \rrbracket \llbracket \tau_k \rrbracket$. Then B is a finite set, because each of the deflations $\llbracket P_n^{\tau_j} \rrbracket$ has finite image. Now let $f, g \in \llbracket \tau \rrbracket$ with $f^d =_B g^d$. Then

$$\begin{aligned} \llbracket P_n^\tau \rrbracket f d_1 \dots d_k &= \llbracket P_n^\iota \rrbracket (f(\llbracket P_n^{\tau_1} \rrbracket d_1) \dots (\llbracket P_n^{\tau_k} \rrbracket d_k)) \\ &= \llbracket P_n^\iota \rrbracket (f^d(\llbracket P_n^{\tau_1} \rrbracket d_1, \dots, \llbracket P_n^{\tau_k} \rrbracket d_k)) \\ &= \llbracket P_n^\iota \rrbracket (g^d(\llbracket P_n^{\tau_1} \rrbracket d_1, \dots, \llbracket P_n^{\tau_k} \rrbracket d_k)) \\ &= \llbracket P_n^\iota \rrbracket (g(\llbracket P_n^{\tau_1} \rrbracket d_1) \dots (\llbracket P_n^{\tau_k} \rrbracket d_k)) \\ &= \llbracket P_n^\tau \rrbracket g d_1 \dots d_k \end{aligned}$$

for all $(d_1, \dots, d_k) \in \llbracket \tau_1 \rrbracket \times \dots \times \llbracket \tau_k \rrbracket$, and this means $\llbracket P_n^\tau \rrbracket f = \llbracket P_n^\tau \rrbracket g$. \square

Now we combine Theorem 7.1 and Lemma 7.2 to obtain

Theorem 7.3 (approximation by definable functions) *Let τ be a type of order ≤ 2 . Then every element in $\llbracket \tau \rrbracket$ is the least upper bound of an ω -chain of definable elements.*

Proof: If $\tau = \iota$, then every element is itself definable. Hence let $f \in \llbracket \tau \rrbracket$ where $\tau = \tau_1 \rightarrow \dots \rightarrow \tau_k \rightarrow \iota$ is of order 1 or 2. By Lemma 7.2 we can choose finite sets $B_n \subseteq \llbracket \tau_1 \rrbracket \times \dots \times \llbracket \tau_k \rrbracket$ such that $\llbracket P_n^\tau \rrbracket f = \llbracket P_n^\tau \rrbracket g$ whenever $f^d =_{B_n} g^d$, and by Theorem 7.1 we can choose terms $M_n \in cPCF^\tau$ such that $\llbracket M_n \rrbracket^d =_{B_n} f^d$. This implies $\llbracket P_n^\tau \rrbracket f = \llbracket P_n^\tau \rrbracket \llbracket M_n \rrbracket = \llbracket P_n^\tau M_n \rrbracket$ for every $n \in \mathbb{N}$, and hence $f = \bigsqcup_{n \in \mathbb{N}} \llbracket P_n^\tau \rrbracket f = \bigsqcup_{n \in \mathbb{N}} \llbracket P_n^\tau M_n \rrbracket$. \square

From Theorem 7.3 we obtain our full abstraction result by the usual argumentation:

Theorem 7.4 (full abstraction) *Let τ be a type of order ≤ 3 and let $M_1, M_2 \in cPCF^\tau$. Then*

$$\llbracket M_1 \rrbracket = \llbracket M_2 \rrbracket \Leftrightarrow M_1 \approx M_2$$

Proof: Only ‘ \Leftarrow ’ remains to be proved. Let $\tau = \tau_1 \rightarrow \dots \rightarrow \tau_k \rightarrow \iota$ ($k \geq 0$) and assume that $\llbracket M_1 \rrbracket \neq \llbracket M_2 \rrbracket$, i.e. there are $d_j \in \llbracket \tau_j \rrbracket$ for $j = 1, \dots, k$ such that

$$\llbracket M_1 \rrbracket d_1 \dots d_k \neq \llbracket M_2 \rrbracket d_1 \dots d_k$$

By Theorem 7.3, every d_j is the least upper bound of a directed set of definable elements in $\llbracket \tau_j \rrbracket$, hence the continuity of $\llbracket M_1 \rrbracket$ and $\llbracket M_2 \rrbracket$ implies that there are terms $N_j \in cPCF^{\tau_j}$ ($j = 1, \dots, k$) with

$$\llbracket M_1 N_1 \dots N_k \rrbracket \neq \llbracket M_2 N_1 \dots N_k \rrbracket$$

Thus we have found a program context $C[\]$ with $\llbracket C[M_1] \rrbracket \neq \llbracket C[M_2] \rrbracket$. This implies $beh(C[M_1]) \neq beh(C[M_2])$ and hence $M_1 \not\approx M_2$. \square

We have formulated Theorem 7.4 for *closed* terms of order ≤ 3 . Instead, we could have used *open* terms of order ≤ 2 whose only free identifiers are of order ≤ 2 . In any case the main role is played by identifiers of order ≤ 2 ; that’s why we speak of ‘full abstraction for the second order subset’.

8 Sequentiality Relations

So far we have worked with a rather ‘indirect’ definition of our signature Σ via the functions *Succ*, *Pred* and *Cond*. This definition was appropriate for the full abstraction proof, but for proving concrete observational congruences we prefer a more concrete description which we will now present.

Definition 8.1 For every $n \in \mathbb{N}$ and every pair of sets $A \subseteq B \subseteq \{1, \dots, n\}$ let $S_{A,B}^n \subseteq (\mathbb{Z}_\perp)^n$ be defined by

$$S_{A,B}^n = \{(d_1, \dots, d_n) \in (\mathbb{Z}_\perp)^n \mid (\exists i \in A. d_i = \perp) \vee (\forall i, j \in B. d_i = d_j)\}$$

An n -ary relation $R \subseteq (\mathbb{Z}_\perp)^n$ is called a *sequentiality relation* if it is an intersection of relations of the form $S_{A,B}^n$.

Note that—for every n —there are only finitely many relations of the form $S_{A,B}^n$, hence there are only finitely many sequentiality relations of arity n , and each of them is a *finite* intersection of relations $S_{A,B}^n$.

Theorem 8.2 (concrete description of the signature Σ)

$$R \in \Sigma \Leftrightarrow R \text{ is a sequentiality relation}$$

Proof:

‘ \Leftarrow ’: Per definition of Σ it is sufficient to consider the special case $R = S_{A,B}^n$. In this case $\delta^n(\mathbb{Z}_\perp) \subseteq R$ holds per definition, and $Succ\ R \subseteq R$, $Pred\ R \subseteq R$ follow immediately from the strictness of $Succ$ and $Pred$. In order to see that also $Cond\ R\ R\ R \subseteq R$, let $\vec{b}, \vec{d}, \vec{e} \in R$ and $\vec{u} = Cond\ \vec{b}\ \vec{d}\ \vec{e}$. If $b_i = \perp$ for some $i \in A$, then $u_i = Cond\ b_i\ d_i\ e_i = \perp$, hence $\vec{u} \in R$. Otherwise, $b_i = b_j \neq \perp$ for all $i, j \in B$, hence either $u_i = d_i$ for all $i \in B$ or $u_i = e_i$ for all $i \in B$, and in both cases it follows again that $\vec{u} \in R$ (because $\vec{d} \in R$ and $\vec{e} \in R$).

‘ \Rightarrow ’: Let $R \in \Sigma_n$ and let S be the intersection of all $S_{A,B}^n$ which contain R . We must prove that $S \subseteq R$. Hence let $\vec{d} \in S$. We will show that for every $C \subseteq \{1, \dots, n\}$ there is some $\vec{e} \in R$ such that $d_i = e_i$ for all $i \in C$. Setting $C = \{1, \dots, n\}$ then yields $\vec{d} = \vec{e} \in R$. The proof is by induction on the size of C . If $C = \{i\}$ is a singleton then we choose $\vec{e} = (d_i, \dots, d_i)$. Otherwise we distinguish two cases.

Case 1: $d_i \neq \perp$ for all $i \in C$

Let $T = \{\vec{v} \in (\mathbb{Z}_\perp)^n \mid v_i \neq \perp \text{ for all } i \in C\}$. Every $\vec{v} \in T$ defines an equivalence relation $\sim_{\vec{v}}$ on C by: $i \sim_{\vec{v}} j \Leftrightarrow v_i = v_j$. Now let $\vec{u} \in R \cap T$ be such that $\sim_{\vec{u}}$ is minimal in $\{\sim_{\vec{v}} \mid \vec{v} \in R \cap T\}$, i.e. such that no other $\vec{v} \in R \cap T$ is ‘finer’ than \vec{u} (\vec{u} exists because $R \cap T \supseteq \delta^n \mathbb{Z} \neq \emptyset$). We will show that $R \subseteq S_{B,B}^n$ for every equivalence class B of $\sim_{\vec{u}}$.

Let $i \in C$, let $B = \{j \in C \mid u_j = u_i\}$ be the $\sim_{\vec{u}}$ -equivalence class of i , and assume that $\vec{v} \in R \setminus S_{B,B}^n$. Then $v_j \neq \perp$ for all $j \in B$ and $v_j \neq v_k$ for some pair of indices $j, k \in B$. This allows us to find some $\vec{w} \in R \cap T$ which is finer than \vec{u} , namely: Let $n \in \mathbb{Z} \setminus \{u_i \mid i \in C\}$ and let $\vec{w} = \llbracket M \rrbracket \vec{u}\ \vec{v}$, where

$$M \equiv \lambda x^t, y^t. \text{if } x = u_i \text{ then if } y = v_j \text{ then } n \text{ else } x \text{ else } x$$

Then $\vec{w} \in \llbracket M \rrbracket R\ R \subseteq R$, and a straightforward case distinction shows that $\vec{w} \in T$ with $\sim_{\vec{w}} \subset \sim_{\vec{u}}$ (because the equivalence class B of $\sim_{\vec{u}}$ is split into two equivalence classes of $\sim_{\vec{w}}$). This contradicts the minimality of $\sim_{\vec{u}}$, hence the assumption was wrong and $R \subseteq S_{B,B}^n$ is proved.

It follows that $S \subseteq S_{B,B}^n$, hence $\vec{d} \in S_{B,B}^n$ for all equivalence classes B of $\sim_{\vec{u}}$. This implies $\sim_{\vec{u}} \subseteq \sim_{\vec{d}}$ because $d_i \neq \perp$ for all $i \in C$. But then it is easy to find some $N \in cPCF^\iota$ such that $d_i = \llbracket N \rrbracket u_i$ for all $i \in C$, and this means that we can choose $\vec{e} = \llbracket N \rrbracket \vec{u} \in \llbracket N \rrbracket R \subseteq R$.

Case 2: $d_i = \perp$ for some $i \in C$

If $R \not\subseteq S_{C \setminus \{i\}, C}^n$, then there is some $\vec{u} \in R$ such that $u_j \neq \perp$ for all $j \in C \setminus \{i\}$ and $u_k \neq u_i$ for some $k \in C \setminus \{i\}$. By induction hypothesis there are $\vec{v}, \vec{w} \in R$ with

$$v_j = d_j \text{ for all } j \in C \setminus \{i\} \quad \text{and} \quad w_j = d_j \text{ for all } j \in C \setminus \{k\}$$

These two vectors can be ‘merged’ by a closed PCF -term. Let $\vec{e} = \llbracket M \rrbracket \vec{u}\ \vec{v}\ \vec{w}$, where

$$M \equiv \lambda x^t, y^t, z^t. \text{if } x = u_k \text{ then } y \text{ else } z$$

Then $\vec{e} \in \llbracket M \rrbracket R R R \subseteq R$, and it is easy to see that $e_i = d_i$ for all $i \in C$.

If $R \subseteq S_{C \setminus \{i\}, C}^n$, then $S \subseteq S_{C \setminus \{i\}, C}^n$ and hence $\vec{d} \in S_{C \setminus \{i\}, C}^n$. As $d_i = \perp$, this implies $d_k = \perp$ for some $k \in C \setminus \{i\}$. With that new index k we define $\vec{v}, \vec{w} \in R$ as before. If $v_i = \perp (= d_i)$, then we can clearly choose $\vec{e} = \vec{v} \in R$. Otherwise we let $\vec{e} = \llbracket M \rrbracket \vec{v} \vec{w}$, where

$$M \equiv \lambda x^\iota, y^\iota. \text{if } x = v_i \text{ then } y \text{ else } x$$

Then, once again, $\vec{e} \in \llbracket M \rrbracket R R \subseteq R$ and a straightforward case distinction shows $e_i = d_i$ for all $i \in C$. \square

9 Observational Congruences

Theorem 8.2 helps us to show that certain functions or—more generally—functions with certain properties cannot be contained in our model, and this will in turn allow us to prove certain observational congruences. We present some examples.

Example 9.1 There is *no* function $f \in \llbracket \iota \rightarrow \iota \rightarrow \iota \rrbracket$ with

$$\begin{array}{rclcl} f & \perp & 0 & = & 0 \\ f & 0 & \perp & = & 0 \\ f & 1 & 1 & = & 1 \end{array}$$

Proof: Let $R = S_{\{1,2\}, \{1,2,3\}}^3$. Then the argument columns $(\perp, 0, 1)$ and $(0, \perp, 1)$ are contained in R , but the result column $(0, 0, 1)$ is not contained in R . This shows that a function f which satisfies these equations cannot be a Σ -homomorphism, hence it cannot be contained in $\llbracket \iota \rightarrow \iota \rightarrow \iota \rrbracket$. \square

Note that in particular the *parallel or* function Por is ruled out by Example 9.1. Moreover, the result of Example 9.1 can be easily cast into an observational congruence. Consider the closed *PCF*-term

$$\text{POR_TEST} \equiv \lambda y^{\iota \rightarrow \iota \rightarrow \iota}. \text{if } y \Omega 0 \wedge y 0 \Omega \wedge \neg y 1 1 \text{ then } 0 \text{ else } \Omega$$

Then $\llbracket \text{POR_TEST} \rrbracket f$ can only be 0 if f satisfies the equations in Example 9.2. As such a function f does not exist in $\llbracket \iota \rightarrow \iota \rightarrow \iota \rrbracket$ we have proved $\llbracket \text{POR_TEST} \rrbracket = \perp$ and hence

$$\text{POR_TEST} \approx \Omega$$

Example 9.2 There is *no* function $g \in \llbracket \iota \rightarrow \iota \rightarrow \iota \rightarrow \iota \rrbracket$ with

$$\begin{array}{rclcl} g & \perp & 0 & 1 & = & 0 \\ g & 1 & \perp & 0 & = & 0 \\ g & 0 & 1 & \perp & = & 1 \end{array}$$

Proof: Let $R = S_{\{1,2,3\},\{1,2,3\}}^3$. Then the argument columns $(\perp, 1, 0)$, $(0, \perp, 1)$ and $(1, 0, \perp)$ are contained in R , but the result column $(0, 0, 1)$ is not contained in R . This shows that a function g which satisfies these equations cannot be a Σ -homomorphism, hence it cannot be contained in $\llbracket \iota \rightarrow \iota \rightarrow \iota \rightarrow \iota \rrbracket$. \square

The standard model for PCF does contain a function g which satisfies the above equations, and the least such function is known as the *Berry-Plotkin function* or *Gustave's function*. It is one of the simplest examples of a stable function [?] which is not definable by a closed PCF -term.

We continue with a second order example. A whole series of such examples, known as the *Curien monsters*, are contained in [?]. We consider the last (and most difficult) one of them. We use the familiar notation for step functions, defined by

$$(d_1 \Rightarrow \dots \Rightarrow d_k \Rightarrow e) u_1 \dots u_k = \begin{cases} e & \text{if } u_i \sqsupseteq d_i \text{ for } i = 1, \dots, k \\ \perp & \text{otherwise} \end{cases}$$

Example 9.3 Let $g_1 = (\perp \Rightarrow 1 \Rightarrow 0) \sqcup (1 \Rightarrow 0 \Rightarrow 0)$, $g_2 = (0 \Rightarrow \perp \Rightarrow 0)$, $g_3 = (\perp \Rightarrow 0 \Rightarrow 0)$ and $g_4 = \perp_{\iota \rightarrow \iota \rightarrow \iota}$. Then no function $f \in \llbracket (\iota \rightarrow \iota \rightarrow \iota) \rightarrow \iota \rrbracket$ satisfies

$$\begin{aligned} f \ g_1 &= 0 \\ f \ g_2 &= 0 \\ f \ g_3 &= 0 \\ f \ g_4 &= \perp \end{aligned}$$

Proof: Let R be the sequentiality relation defined by

$$R^\iota = S_{\{1,2\},\{1,2\}}^4 \cap S_{\{1,3\},\{1,3\}}^4 \cap S_{\{1,2,3\},\{1,2,3,4\}}^4$$

The result column $(0, 0, 0, \perp)$ is *not* in $S_{\{1,2,3\},\{1,2,3,4\}}^4 \supseteq R^\iota$, hence we must only convince ourselves that (g_1, \dots, g_4) is in $R^{\iota \rightarrow \iota \rightarrow \iota}$. Assume that $g_i u_i v_i = d_i$ for $i = 1, \dots, 4$, where $(d_1, \dots, d_4) \notin R^\iota$. Per definition of the functions g_i this is only possible when $(d_1, \dots, d_4) = (0, 0, 0, \perp)$, and then one of the following two cases must occur:

$$\begin{aligned} (u_1, \dots, u_4) &\sqsupseteq (\perp, 0, \perp, \perp) \quad \text{and} \quad (v_1, \dots, v_4) \sqsupseteq (1, \perp, 0, \perp) \\ (u_1, \dots, u_4) &\sqsupseteq (1, 0, \perp, \perp) \quad \text{and} \quad (v_1, \dots, v_4) \sqsupseteq (0, \perp, 0, \perp) \end{aligned}$$

In the first case $(v_1, \dots, v_4) \notin S_{\{1,3\},\{1,3\}}^4 \supseteq R^\iota$ and in the second case $(u_1, \dots, u_4) \notin S_{\{1,2\},\{1,2\}}^4 \supseteq R^\iota$. Thus we have proved $(g_1, \dots, g_4) \in R^{\iota \rightarrow \iota \rightarrow \iota}$. \square

Of course, this example can also be cast into an observational congruence. Let $G_i \in cPCF^{\iota \rightarrow \iota \rightarrow \iota}$ ($i = 1, \dots, 4$) such that $\llbracket G_i \rrbracket = g_i$, say

$$G_1 \equiv \lambda x^\iota. y^\iota. \text{if } \neg y \text{ then } 0 \text{ else if } \neg x \text{ then } 0 \text{ else } \Omega$$

etc., and let y be an identifier of type $(\iota \rightarrow \iota \rightarrow \iota) \rightarrow \iota$. Then

$$\llbracket \lambda y. \text{if } y \ G_1 \wedge y \ G_2 \wedge y \ G_3 \text{ then } 0 \text{ else } \Omega \rrbracket = \llbracket \lambda y. \text{if } y \ G_4 \text{ then } 0 \text{ else } \Omega \rrbracket$$

and this implies

$$\lambda y. \text{if } y G_1 \wedge y G_2 \wedge y G_3 \text{ then } 0 \text{ else } \Omega \approx \lambda y. \text{if } y G_4 \text{ then } 0 \text{ else } \Omega$$

We conclude this section with a sophisticated example in which infinitely many relations are needed to prove a *single* observational congruence.

Example 9.4 Let $g \in \llbracket \iota \rightarrow \iota \rightarrow \iota \rightarrow \iota \rrbracket$ be defined by

$$g \, n \, i \, j = \begin{cases} i & \text{if } 1 \leq j \leq n \wedge j \neq i \\ \perp & \text{otherwise} \end{cases}$$

and $test \in \llbracket \iota \rightarrow ((\iota \rightarrow \iota) \rightarrow \iota) \rightarrow \iota \rrbracket$ by

$$test \, n \, f = \begin{cases} \bigwedge_{i=1}^n f(g \, n \, i) & \text{if } n \geq 2 \\ \perp & \text{otherwise} \end{cases}$$

Finally, let TEST be a closed PCF-term with $\llbracket \text{TEST} \rrbracket = test$ (such a term can be programmed with a simple recursion). Then

$$\llbracket \lambda x^\iota, y^{(\iota \rightarrow \iota) \rightarrow \iota}. \text{if TEST } x \, y \text{ then } 0 \text{ else } y \, \Omega \rrbracket = \llbracket \lambda x^\iota, y^{(\iota \rightarrow \iota) \rightarrow \iota}. y \, \Omega \rrbracket$$

Proof: We must show that both sides coincide on all $n \in \llbracket \iota \rrbracket$ and $f \in \llbracket (\iota \rightarrow \iota) \rightarrow \iota \rrbracket$. The only critical case is $test \, n \, f = 0$ which occurs when $n \geq 2$ and $f(g \, n \, i) = 0$ for $i = 1, \dots, n$. Let $R = S_{\{1, \dots, n\}, \{1, \dots, n+1\}}^{n+1}$. If we can prove $(g \, n \, 1, \dots, g \, n \, n, \perp) \in R^{\iota \rightarrow \iota}$, then $(f(g \, n \, 1), \dots, f(g \, n \, n), f \, \perp) \in R^\iota = R$, hence $f \, \perp = 0$, and the equivalence holds.

Hence let $(d_1, \dots, d_{n+1}) \in R^\iota = R$. If $d_i = \perp$ or $d_i \notin \{1, \dots, n\}$ for some $i \in \{1, \dots, n\}$ then $g \, n \, i \, d_i = \perp$. Otherwise $d_1 = \dots = d_{n+1} = j$ for some $j \in \{1, \dots, n\}$ which implies $g \, n \, j \, d_j = g \, n \, j \, j = \perp$. In both cases $(g \, n \, 1 \, d_1, \dots, g \, n \, n \, d_n, \perp \, d_{n+1}) \in R^\iota = R$, and this concludes the proof. \square

Note that the number n in the definition of the above relation R is given by the value which we bind to x and not by the equivalence itself. This means that we have used infinitely many relations for proving a single observational congruence, and we will now show that finitely many relations are indeed not sufficient. To be more precise, let $\bar{\Sigma}$ be some finite sub-signature of Σ , and replace Σ by $\bar{\Sigma}$ in our model construction. This yields a new model which is still computationally adequate for PCF (by the same proof as before) but in which the above equivalence fails. In order to see this, let g be defined as before, let n be the maximal arity of a relation $R \in \bar{\Sigma}$, and let $f = \bigsqcup_{i=1}^n (g \, n \, i \Rightarrow 0) \in (\llbracket \iota \rightarrow \iota \rrbracket \xrightarrow{c} \llbracket \iota \rrbracket)$. If we can show that f is a $\bar{\Sigma}$ -homomorphism, then f is contained in the new model, and then the above equivalence fails because $test \, n \, f = 0$ and $f \, \perp = \perp$.

To begin with, let $\hat{f} = \bigsqcup_{i=1}^n (g \, n \, i \, 1 \Rightarrow \dots \Rightarrow g \, n \, i \, n \Rightarrow 0)$, i.e.

$$\begin{aligned} \hat{f} &= (\perp \Rightarrow 1 \Rightarrow \dots \Rightarrow 1 \Rightarrow 0) \quad \sqcup \\ &\quad (2 \Rightarrow \perp \Rightarrow \dots \Rightarrow 2 \Rightarrow 0) \quad \sqcup \\ &\quad \vdots \\ &\quad (n \Rightarrow n \Rightarrow \dots \Rightarrow \perp \Rightarrow 0) \end{aligned}$$

\hat{f} is a well-defined continuous function, and we want to prove that it is a $\bar{\Sigma}$ -homomorphism. As it is a first order function, it suffices to show that it preserves all relations of the form $S_{A,B}^m$ with $m \leq n$ and $A, B \subseteq \{1, \dots, m\}$. Hence let $\vec{d}_1, \dots, \vec{d}_n \in S_{A,B}^m$ and let $\vec{e} = \hat{f}\vec{d}_1 \dots \vec{d}_n$. If $A = B$, then $\vec{e} \in S_{A,B}^m$ because $e_i \in \{\perp, 0\}$ for all $i \in B$ by the very definition of \hat{f} . Hence we are left with the case $A \subset B$. For every $j \in \{1, \dots, n\}$ let $A_j = \{i \in A \mid d_{ji} = \perp\}$, and let $J = \{j \in \{1, \dots, n\} \mid A_j \neq \emptyset\}$. Then—per definition of $S_{A,B}^m$ —every \vec{d}_j with $j \in \{1, \dots, n\} \setminus J$ is constant on B .

Case 1: $J = \emptyset$

Then all \vec{d}_j ($j = 1, \dots, n$) are constant on B , hence \vec{e} is constant on B .

Case 2: J contains only a single element j

As $A_j \neq \emptyset$, there is some $i \in A$ with $d_{ji} = \perp$. On the other hand, \vec{d}_k is constant on B for all $k \neq j$. This implies $(d_{1i}, \dots, d_{ni}) \sqsubseteq (d_{1h}, \dots, d_{nh})$ for all $h \in B$, and hence also $e_i \sqsubseteq e_h$ by monotonicity of \hat{f} . This means that either $e_i = \perp$ or \vec{e} is constant on B .

Case 3: J contains at least two elements

If there are two sets A_j, A_k ($j, k \in J, j \neq k$) which contain a common element $i \in A$, then $d_{ji} = d_{ki} = \perp$ and hence $e_i = \perp$ per definition of \hat{f} .

Otherwise the sets A_j ($j \in J$) are pairwise disjoint and nonempty, and we have $\bigcup_{j \in J} A_j \subseteq A \subset B \subseteq \{1, \dots, n\}$. This means that J itself must be smaller than $\{1, \dots, n\}$, hence we can choose indices $j \in \{1, \dots, n\} \setminus J$, $k, l \in J$ with $k \neq l$ and $h \in A_k$, $i \in A_l$. Then $d_{kh} = d_{li} = \perp$ and $d_{jh} = d_{ji}$ because \vec{d}_j is constant on B , hence either $e_i = \perp$ or $e_h = \perp$ per definition of \hat{f} .

Thus we have proved $\vec{e} \in S_{A,B}^m$ in all cases, i.e. \hat{f} is indeed a $\bar{\Sigma}$ -homomorphism. But then f is also a $\bar{\Sigma}$ -homomorphism because $fh = \hat{f}(h1) \dots (hn)$ for all functions $h \in [\iota \rightarrow \iota]$.

10 Conclusion

We have presented a denotational model for the language PCF which is fully abstract for the second order subset of PCF . In contrast to our original presentation in [28] we have *not* used an extensional collapse to construct this model, but instead we have first introduced the cartesian closed category of Σ -dcpo's and continuous Σ -homomorphisms in which the model could then be easily defined.

It is still an open question whether our model is fully abstract for the full language PCF . In the meantime, O'Hearn and Riecke [19] have generalized our logical relation approach to PCF by using so-called *Kripke logical relations of varying arity* which were first introduced by Jung and Tiuryn [6] to provide a new characterization of λ -definability. With the aid of these much more complicated logical relations they do get full abstraction for the full language PCF , but an example of a concrete observational congruence where these new relations are superior to our ordinary

logical relations is still missing.

Chapter 3

An Algol-like Language

1 Introduction

Another class of programming languages for which full abstraction is hard to achieve are imperative languages with local variables or—more specifically—ALGOL-like languages. In traditional denotational models for such languages [2, 3, 18], so-called *marked store models* [13], the critical nonstandard elements are those functions which have ‘access’ to an unbounded number of locations. We briefly sketch the definition of such a model in order to obtain some hints how better models can be constructed:

Let Loc be some infinite set, whose elements l are called *locations*, let $\mathcal{P}_{fin}(Loc)$ be the set of finite subsets of Loc and let $next : \mathcal{P}_{fin}(Loc) \rightarrow Loc$ be a function with $next(L) \notin L$ for all $L \in \mathcal{P}_{fin}(Loc)$. We define a *marked store* to be a partial function $ms : Loc \hookrightarrow \mathbb{Z}$ whose domain $dom(ms)$ is finite. We think of $dom(ms)$ as the set of locations which are marked as active, $ms\,l$ as the contents of location l , and $next(dom(ms))$ as the first ‘free’ location, i.e. the one to be allocated next.¹ The meaning of a block with a local variable declaration can then be defined by²

$$\llbracket \text{new } x \text{ in } M \text{ end} \rrbracket_{\eta\,ms} = \begin{cases} \perp & \text{if } \llbracket M \rrbracket_{\eta[l/x]}(ms[0/l]) = \perp \\ ms' \setminus l & \text{if } \llbracket M \rrbracket_{\eta[l/x]}(ms[0/l]) = ms' \neq \perp \end{cases}$$

where $l = next(dom(ms))$. This definition simply imitates an operational semantics: Upon block entry the first free location l is bound to the local variable x , marked as active and set to the initial value 0. Then the block body M is executed and—if it terminates—the location l is finally deallocated by removing it from the domain of the resulting store ms' . Now consider the block³

$$B \equiv \text{new } x \text{ in } y; \text{ if } !x = 0 \text{ then } \Omega \text{ end}$$

¹Of course there are innumerable variants of this idea, e.g. a marked store can be represented as a pair (L, s) with a *total* function s , or the mark L can be introduced as part of the *environment* η . The reader may be assured that the problems which we illustrate here appear *mutatis mutandis* for such alternative definitions.

²In ALGOL 60 syntax such a block is written as **begin integer** x ; M **end**.

³We use the ML-notation $!x$ for explicitly dereferencing a variable x .

which contains a call of some global parameterless procedure y . It is easy to argue informally (and it will be rigorously proved in Section 7) that B is observationally congruent to the always diverging command Ω : Due to the static scope rule in ALGOL-like languages, the global procedure y does not have access to the local variable x , hence—if the call of y terminates at all—the variable x will still contain its initial value 0 after the call, and this makes the block diverge. On the other hand, B is *not* denotationally equivalent to Ω : Let $\eta y = f$ where f is the function which sets all active locations to 1, i.e.

$$f\ ms = ms' \text{ with } \text{dom}(ms') = \text{dom}(ms) \text{ and } ms' l = 1 \text{ for all } l \in \text{dom}(ms)$$

Then even the new location which is bound to the local variable x will be set to 1 (because it is active when y is called) and this implies $\llbracket B \rrbracket \eta \neq \llbracket \Omega \rrbracket \eta$. Thus we have shown that every model which contains the above function f (and the traditional models do contain this function) fails to be fully abstract.

It is clear which lesson we have to learn from this example if we want to achieve full abstraction: We must define a model in which every function only has access to some fixed finite set of locations (in contrast to the above function f), and we must carefully choose the new location which we bind to a local variable, so that the functions which are bound to the global procedure identifiers do not have access to it. This means in particular that we must somehow formalize the notion of ‘access’. For first order procedures, it is easy to give an *ad hoc* definition (cf. Theorem 8.1), but when it comes to second order then we need a more systematic approach—and this is the point where (logical) relations come again into play.

The idea to use relations for constructing models of ALGOL-like languages originates with [13], but the particular model which was presented there, failed to be fully abstract because the set of relations was too small. The idea was resumed in [21] and [29] with larger sets of relations, thus leading to improved models in which all the known test equivalences [13, 8, 21] for ALGOL-like languages could be validated, but a full abstraction proof for these models was still missing. Here we will present such a proof for (a slight variant of) the model in [29].

It should be mentioned that O’Hearn and Tennent’s motivation for using logical relations in [21] is somewhat different from ours. Their intention was to transfer Reynolds’ concept of ‘relational parametricity’ [11] from polymorphic languages to ALGOL-like languages, because they see a close relationship between information hiding through type variables (in a polymorphic language) and information hiding through local variables. Our view, which we have already explained in Chapter 1, is much more technical: We simply try to exploit the close relationship between full abstraction and λ -definability, which we have already used in Chapter 2 to obtain a fully abstract model for the second order subset of *PCF*.

Let us now briefly review the main concepts of an ALGOL-like language: Due to [27, 5, 34, 8] it should be a simply typed, statically scoped call-by-name language which obeys the so-called *stack discipline*. The latter means that a location never survives the block in which it has been allocated; this is considered as a semantic principle and not as a matter of implementation. Finally, there should be a clear

distinction between locations and storable values, and also between commands and expressions: Commands alter the store but do not return values, expressions return values but do not have (permanent) side effects on the store.

In order to obtain our full abstraction result we had to include one somewhat unusual feature in our particular ALGOL-like language ALG, namely the so-called *snap back effect* which goes back to a suggestion of J.C. Reynolds': Inside the body of a function procedure, assignments to global variables are allowed, but after each call of such a procedure the store 'snaps back' to the contents which it had before the call, i.e. only a *temporary* side effect is caused by such an assignment. We will allow the snap back effect to occur in arbitrary (integer) expressions. For an ALGOL-like language *without* snap back, our model definitely *fails* to be fully abstract, but our general techniques may well be suited for constructing a (different) fully abstract model for such an alternative language (Section 10). This is subject to further research.

As another unusual feature we have included a *parallel conditional*. This operator often plays a prominent role in full abstraction proofs [24], but here it does *not*. If we remove it from ALG then we can still obtain a (different) fully abstract model with the same techniques as before (Section 10). The interesting point about the parallel conditional is that it may allow us to simplify our model definition, namely to use only relations of arity ≤ 2 , even of a very particular shape (Conjecture 11.1). This would not only increase the 'tastefulness' of our denotational model but it would also bring us closer to O'Hearn and Tennent's parametric functor model [21]. Hence it may finally turn out that their model is also fully abstract for the second order subset of ALG.

2 Syntax of the Language ALG

In the spirit of [7, 27] we define our ALGOL-like language ALG as a subset of a simply typed λ -calculus. Its *types* τ are given by the grammar

$$\begin{aligned}\tau &::= loc \mid \sigma \\ \sigma &::= \theta \mid (\tau \rightarrow \sigma) \\ \theta &::= iexp \mid cmd\end{aligned}$$

loc stands for 'location', *iexp* for 'integer expression' and *cmd* for 'command'. We let *Type* denote the set of all types. The types $\sigma (\neq loc)$ are called *procedure types*. As usual, ' \rightarrow ' associates to the right, hence every procedure type can be written as $\sigma = \tau_1 \rightarrow \dots \rightarrow \tau_k \rightarrow \theta$ with some $k \geq 0$. We use $\tau^k \rightarrow \sigma$ as an abbreviation for $\underbrace{\tau \rightarrow \dots \rightarrow \tau}_k \rightarrow \sigma$ ($k \geq 0$). The *order* $ord(\tau)$ of a type τ is defined by

$$\begin{aligned}ord(loc) &= 0 \\ ord(\theta) &= 1 \\ ord(\tau \rightarrow \sigma) &= \max(ord(\tau) + 1, ord(\sigma))\end{aligned}$$

It may come as a surprise that we assign the order 1 to the ground (!) types *ie xp* and *cmd*. This does make sense, because—semantically—elements of type *ie xp* and *cmd* will be *functions* which have the current store as an implicit parameter; in particular, elements of type *ie xp* will be *thunks* in terms of the ALGOL jargon.⁴ From an operational point of view this means that parameters of type *ie xp* (and *cmd*) are *called by name*, i.e. they are handled by β -reduction. Thus we follow the view that call-by-name should be the main parameter passing mechanism for an ALGOL-like language. In addition we have parameters of type *loc*; they have been added as a mere convenience because we anyways need identifiers of type *loc* as local variables. Intuitively they may be considered as *reference parameters*, but technically they can also be handled by β -reduction because the only terms of type *loc* are location constants and variables.

As usual, we assume that there is an infinite set Id^τ of *identifiers* $x^\tau, y^\tau, z^\tau, \dots$ for every type τ ; the type superscripts will be omitted when the type is clear from the context. Identifiers of procedure type σ are called *procedure identifiers*, those of type *loc* are called *location identifiers* or *variables*. This means that we use the word ‘variable’ in the sense of imperative programming languages and not in the (more general) sense of the λ -calculus. We will preferably use y, z, \dots as procedure identifiers and x, x', \dots as variables (or as generics for arbitrary identifiers).

The set of ALG-constants c and the *type* of each constant are defined by

$l :$	<i>loc</i>	for every $l \in Loc$	(location constants)
$n :$	<i>ie xp</i>	for every $n \in \mathbb{Z}$	(integer constants)
$succ, pred :$	<i>ie xp</i>	\rightarrow <i>ie xp</i>	(successor and predecessor)
$cont :$	<i>loc</i>	\rightarrow <i>ie xp</i>	(dereferencing)
$asgn :$	<i>loc</i>	\rightarrow <i>ie xp</i> \rightarrow <i>cmd</i>	(assignment)
$skip :$	<i>cmd</i>		(empty command)
$cond_\theta :$	<i>ie xp</i>	$\rightarrow \theta \rightarrow \theta \rightarrow \theta$	(conditional with zero test)
$seq_\theta :$	<i>cmd</i>	$\rightarrow \theta \rightarrow \theta$	(sequencing)
$new_\theta :$	$(loc \rightarrow \theta)$	$\rightarrow \theta$	(<i>new</i> -operator)
$Y_\sigma :$	$(\sigma \rightarrow \sigma)$	$\rightarrow \sigma$	(fixed point operator)
$pcond :$	<i>ie xp</i>	\rightarrow <i>ie xp</i> \rightarrow <i>ie xp</i> \rightarrow <i>ie xp</i>	(parallel conditional with zero test)

Terms M, N, P, \dots of ALG are just the well-typed λ -terms over the ALG-constants with the restriction that the body of a λ -abstraction must not be of type *loc*, in other words: The sets ALG^τ of ALG-terms of type τ are inductively defined by

$c \in ALG^\tau$	if c is a constant of type τ	(constant)
$x^\tau \in ALG^\tau$		(identifier)
$M \in ALG^{\tau \rightarrow \sigma} \wedge N \in ALG^\tau \Rightarrow (MN) \in ALG^\sigma$		(application)
$M \in ALG^\sigma \Rightarrow (\lambda x^\tau. M) \in ALG^{\tau \rightarrow \sigma}$		(λ -abstraction)

⁴Put another way, *cmd* and *ie xp* are the types of parameterless procedures and function procedures, corresponding to the ML-types $(unit \rightarrow unit)$ and $(unit \rightarrow int)$, and thus it is reasonable to assign the order 1 to them.

As usual, application associates to the left and the scope of a λ -abstraction extends as far as possible to the right.

We let $locns(M)$ stand for the set of locations which occur (as constants) in M and $free(M)$ for the set of identifiers which occur free in M . M is *closed* if $free(M) = \emptyset$. $M[x := N]$ is the term which is obtained from M by substituting N for each free occurrence of x (with the usual renaming of bound identifiers in order to avoid name clashes), and $M[x_1, \dots, x_k := N_1, \dots, N_k]$ or simply $M[\bar{x} := \bar{N}]$ is the term which is obtained by a *simultaneous* substitution. As further notation we use

$$\begin{aligned} \text{ALG}_L^\tau &= \{M \in \text{ALG}^\tau \mid locns(M) \subseteq L\} \\ c\text{-ALG}^\tau &= \{M \in \text{ALG}^\tau \mid free(M) = \emptyset\} \\ c\text{-ALG}_L^\tau &= \{M \in \text{ALG}^\tau \mid free(M) = \emptyset \wedge locns(M) \subseteq L\} \end{aligned}$$

where L ranges over finite subsets of Loc .

Finally, we define a *program* to be a term $P \in c\text{-ALG}_\emptyset^{iexp}$. Note that location constants (which may be thought of as explicit storage addresses) must not occur in programs at all. Terms with location constants will be useful for defining the operational semantics; besides that they will play a technical role in the full abstraction proof.

We conclude this section by introducing some syntactic sugar. First, we generalize conditional, sequencing and *new*-operators to arbitrary procedure types: If $\sigma = \tau_1 \rightarrow \dots \rightarrow \tau_k \rightarrow \theta$ ($k \geq 1$), then we let

$$\begin{aligned} cond_\sigma &=_{def} \lambda y^{iexp}, z_1^\sigma, z_2^\sigma, x_1^{\tau_1}, \dots, x_k^{\tau_k}. cond_\theta y (z_1 x_1 \dots x_k) (z_2 x_1 \dots x_k) \\ seq_\sigma &=_{def} \lambda y^{cmd}, z^\sigma, x_1^{\tau_1}, \dots, x_k^{\tau_k}. seq_\theta y (z x_1 \dots x_k) \\ new_\sigma &=_{def} \lambda y^{loc \rightarrow \sigma}, x_1^{\tau_1}, \dots, x_k^{\tau_k}. new_\theta (\lambda x^{loc}. y x x_1 \dots x_k) \end{aligned}$$

Besides that, we introduce some notation which looks more familiar for imperative languages, namely

$$\begin{aligned} !M &=_{def} cont M \\ M := N &=_{def} asgn M N \\ M; N &=_{def} seq_\sigma M N \\ \text{if } M \text{ then } N \text{ else } P &=_{def} cond_\sigma M N P \\ \text{new } x \text{ in } M \text{ end} &=_{def} new_\sigma (\lambda x^{loc}. M) \\ \text{proc } y^\sigma: M \text{ in } N \text{ end} &=_{def} (\lambda y^\sigma. N) (Y_\sigma (\lambda y^\sigma. M)) \\ \text{if } M \text{ then } N &=_{def} \text{if } M \text{ then } N \text{ else skip} \\ \text{new } x_1, \dots, x_n \text{ in } M \text{ end} &=_{def} \text{new } x_1 \text{ in } \dots \text{new } x_n \text{ in } M \text{ end } \dots \text{end} \end{aligned}$$

In each case we insist that the term on the right hand side be already well-typed. Note that some of these constructs are defined more generally than in traditional imperative languages because σ ranges over arbitrary procedure types. Finally we let Ω_σ or just Ω stand for a diverging term of type σ , say $\Omega_\sigma =_{def} Y_\sigma (\lambda y^\sigma. y)$.

3 Operational Semantics

In this section we define a structural operational semantics [26] for our language ALG, i.e. we define a transition relation ‘ \rightarrow ’ on a set of (machine) configurations. Our definition of configurations is somewhat unusual, because the language ALG is not single threaded.

In a *single threaded* language, a configuration can be defined to be a pair (M, ms) where—intuitively— ms is the current (marked) store and M is the term to be evaluated next. For the language ALG, single threadedness fails because of the snap back effect and the parallel conditional. The snap back effect forces us to keep book of *earlier* stores into which the computation might snap back after the evaluation of an integer expression. The parallel conditional forces us to make copies of the *current* store, because we do not want to allow any interaction between computations which run in parallel, hence we insist that each argument of the parallel conditional works on its own ‘private’ copy of the store. In order to handle both features together we define the set of *configurations* K by

$$\begin{aligned} K ::= & (M, ms) \mid \\ & succ\ K \mid pred\ K \mid \\ & (asgn\ l\ K, ms) \mid (cond_{\theta} KMN, ms) \mid \\ & seq_{\theta} KM \mid dealloc_{\theta} l\ K \mid \\ & pcond K_1 K_2 K_3 \end{aligned}$$

where M and N are *closed* terms.

The rules for deriving transition steps between configurations are presented in Table 1. An auxiliary transition relation ‘ \rightarrow ’ between closed ALG-terms is defined in Table 2. We explicitly distinguish between ‘ \rightarrow ’ and ‘ \rightarrow ’ in order to emphasize that the operational semantics of an ALGOL-like language is naturally separated into two layers [27, 8, 9, 35]: ‘ \rightarrow ’ describes the purely functional layer, in which the only transition steps are β -reduction and recursion unfolding. ‘ \rightarrow ’ describes the imperative layer, where transition steps can depend on the store and/or change the store. The only connection between the two layers is given by the (interaction)-rule of Table 2.

In the (context)-rule we make use of so-called evaluation contexts [35]. In our setting, an *evaluation context* E is a particular ‘configuration with at least one hole’ defined by

$$\begin{aligned} E ::= & succ\ [\] \mid pred\ [\] \mid \\ & (asgn\ l\ [\], ms) \mid (cond_{\theta} [\]MN, ms) \mid \\ & seq_{\theta} [\]M \mid dealloc_{\theta} l\ [\] \mid \\ & pcond\ [\][\][\] \mid \\ & pcond\ [\][\](n, ms) \mid pcond\ [\](n, ms)[\] \mid \\ & pcond\ [\](n, ms)(n', ms') \quad \text{with } n \neq n' \end{aligned}$$

(succ-init)	$(succ\ M, ms) \rightarrow succ\ (M, ms)$
(succ-exec)	$succ\ (n, ms) \rightarrow (n+1, ms)$
(pred-init)	$(pred\ M, ms) \rightarrow pred\ (M, ms)$
(pred-exec)	$pred\ (n, ms) \rightarrow (n-1, ms)$
(cont)	$(cont\ l, ms) \rightarrow (ms\ l, ms) \text{ if } l \in dom(ms)$
(asgn-init)	$(asgn\ l\ M, ms) \rightarrow (asgn\ l\ (M, ms), ms)$
(asgn-exec)	$(asgn\ l\ (n, ms'), ms) \rightarrow (skip, ms[n/l]) \text{ if } l \in dom(ms)$
(cond-init)	$(cond_{\theta} MNP, ms) \rightarrow (cond_{\theta}(M, ms)NP, ms)$
(cond-left)	$(cond_{\theta}(0, ms')NP, ms) \rightarrow (N, ms)$
(cond-right)	$(cond_{\theta}(n, ms')NP, ms) \rightarrow (P, ms) \text{ if } n \neq 0$
(seq-init)	$(seq_{\theta} MN, ms) \rightarrow seq_{\theta}(M, ms)N$
(seq-finish)	$seq_{\theta}(skip, ms)N \rightarrow (N, ms)$
(new-init)	$(new_{\theta} M, ms) \rightarrow dealloc_{\theta} l\ (Ml, ms[0/l]) \text{ if } l = next(dom(ms))$
(new-finish)	$dealloc_{\theta} l\ (c, ms) \rightarrow (c, ms \setminus l) \text{ if } l \in dom(ms)$
(pcond-init)	$(pcond MNP, ms) \rightarrow pcond\ (M, ms)\ (N, ms)\ (P, ms)$
(pcond-left)	$pcond\ (0, ms)\ K_1 K_2 \rightarrow K_1$
(pcond-right)	$pcond\ (n, ms)\ K_1 K_2 \rightarrow K_2 \text{ if } n \neq 0$
(pcond-par)	$pcond\ K\ (n, ms)\ (n, ms') \rightarrow (n, ms)$
(context)	$\frac{K_i \rightarrow K'_i \text{ for } i = 1, \dots, n}{E[K_1, \dots, K_n] \rightarrow E[K'_1, \dots, K'_n]}$

Table 1: Rules for ‘ \rightarrow ’

As usual, $[]$ specifies a hole, and $E[K_1, \dots, K_n]$ denotes the configuration which is obtained by filling K_1, \dots, K_n into the n holes of E . The intuition (expressed by the (context)-rule) is that an evaluation context E enforces the parallel evaluation of the configurations K_1, \dots, K_n which are placed in its holes.

With the aid of the transition relation ‘ \rightarrow ’ we define the *observable behavior* of a program P to be the set

$$beh(P) = \{ n \mid (P, ms_{init}) \xrightarrow{*} (n, ms_{init}) \}$$

where ms_{init} is the (unique) marked store with $dom(ms_{init}) = \emptyset$ and ‘ $\xrightarrow{*}$ ’ denotes the reflexive transitive closure of ‘ \rightarrow ’. We will see below, that $beh(P)$ contains at most one element and that $beh(P) = \emptyset$ if and only if the computation for (P, ms_{init}) diverges. But first we give a small example to illustrate this somewhat unusual operational semantics and in particular to illustrate the snap back effect.

(β -reduction)	$(\lambda x^\tau. M)N \rightarrow M[x := N]$
(recursion)	$Y_\sigma M \rightarrow M(Y_\sigma M)$
(application)	$\frac{M \rightarrow M'}{MN \rightarrow M'N}$
(interaction)	$\frac{M \rightarrow M'}{(M, ms) \rightarrow (M', ms)}$

Table 2: Rules for ‘ \rightarrow ’ and interaction

Example 3.1 Consider the program

$$\begin{aligned}
P &\equiv \text{new } x \text{ in if } x := 1; !x \text{ then } 1 \text{ else } !x \text{ end} \\
&\equiv \text{new}_{iexp}(\lambda x^{loc}. \text{cond}_{iexp}(\text{seq}_{iexp}(\text{asgn } x \ 1) (\text{cont } x)) \ 1 (\text{cont } x))
\end{aligned}$$

We show that $(P, ms_{init}) \xrightarrow{*} (0, ms_{init})$. Let $l = \text{next}(\emptyset)$ and let $[l : n]$ denote the marked store ms with $\text{dom}(ms) = \{l\}$ and $ms \ l = n$. Then

$$\begin{aligned}
(P, ms_{init}) &\rightarrow \text{dealloc } l ((\lambda x. \text{cond}(\text{seq}(\text{asgn } x \ 1) (\text{cont } x)) \ 1 (\text{cont } x)) \ l, [l : 0]) \\
&\rightarrow \text{dealloc } l (\text{cond}(\text{seq}(\text{asgn } l \ 1) (\text{cont } l)) \ 1 (\text{cont } l), [l : 0]) \\
&\rightarrow \text{dealloc } l (\text{cond}(\text{seq}(\text{asgn } l \ 1) (\text{cont } l), [l : 0]) \ 1 (\text{cont } l), [l : 0]) \\
&\xrightarrow{*} \text{dealloc } l (\text{cond}(1, [l : 1]) \ 1 (\text{cont } l), [l : 0]) \\
&\rightarrow \text{dealloc } l (\text{cont } l, [l : 0]) \\
&\rightarrow \text{dealloc } l (0, [l : 0]) \\
&\rightarrow (0, ms_{init})
\end{aligned}$$

where ‘ $\xrightarrow{*}$ ’ follows by the (context)-rule from

$$\begin{aligned}
(\text{seq}(\text{asgn } l \ 1) (\text{cont } l), [l : 0]) &\rightarrow \text{seq}(\text{asgn } l \ 1, [l : 0]) (\text{cont } l) \\
&\rightarrow \text{seq}(\text{asgn } l \ (1, [l : 0]), [l : 0]) (\text{cont } l) \\
&\rightarrow \text{seq}(\text{skip}, [l : 1]) (\text{cont } l) \\
&\rightarrow (\text{cont } l, [l : 1]) \\
&\rightarrow (1, [l : 1])
\end{aligned}$$

Note that the marked store $[l : 0]$ is duplicated in the third step of the computation and that the first copy of $[l : 0]$ is changed to $[l : 1]$ by the evaluation of $\text{seq}(\text{asgn } l \ 1) (\text{cont } l)$. But then the computation *snaps back* to (the second copy of) $[l : 0]$, and thus the evaluation of $\text{cont } l$ finally delivers 0.

We conclude this section by proving some useful properties of our operational semantics, in particular we want to show that “computations do not get stuck”. To this end we will prove that all configurations which occur during the evaluation of a program have a certain reasonable shape: For $\theta \in \{iexp, cmd\}$ and $L \in \mathcal{P}_{fin}(Loc)$ we define the sets $Conf_L^\theta$ inductively by

- $M \in c\text{-ALG}_L^\theta \wedge \text{dom}(ms) = L \Rightarrow (M, ms) \in \text{Conf}_L^\theta$
- $K \in \text{Conf}_L^{\text{ieexp}} \Rightarrow \text{succ } K, \text{pred } K \in \text{Conf}_L^{\text{ieexp}}$
- $K \in \text{Conf}_L^{\text{ieexp}} \wedge l \in L \wedge \text{dom}(ms) = L \Rightarrow (\text{asgn } l \ K, ms) \in \text{Conf}_L^{\text{cmd}}$
- $K \in \text{Conf}_L^{\text{ieexp}} \wedge M, N \in c\text{-ALG}_L^\theta \wedge \text{dom}(ms) = L$
 $\Rightarrow (\text{cond}_\theta KMN, ms) \in \text{Conf}_L^\theta$
- $K \in \text{Conf}_L^{\text{cmd}} \wedge M \in c\text{-ALG}_L^\theta \Rightarrow \text{seq}_\theta KM \in \text{Conf}_L^\theta$
- $K \in \text{Conf}_L^\theta \wedge l \in L \Rightarrow \text{dealloc}_\theta l \ K \in \text{Conf}_{L \setminus \{l\}}^\theta$
- $K_1, K_2, K_3 \in \text{Conf}_L^{\text{ieexp}} \Rightarrow \text{pcond } K_1 K_2 K_3 \in \text{Conf}_L^{\text{ieexp}}$

We say that a configuration is *consistent* if it is contained in one of the sets Conf_L^θ . Intuitively, a consistent configuration is ‘well-typed’ and does not contain any *dangling references* [15, 14]. The latter means that every location which occurs in a consistent configuration is ‘active’ in the sense that it is contained in the domain of the corresponding marked store and hence a computation will never get stuck because of the restriction ‘ $l \in \text{dom}(ms)$ ’ in the rules (cont) or (asgn-exec). This is just a particular instance of

Theorem 3.2 (properties of the operational semantics)

- (i) *The transition relations ‘ \rightarrow ’ and ‘ \rightarrow ’ are partial functions.*
- (ii) *If $M \in c\text{-ALG}_L^\tau$ and $M \rightarrow M'$ then $M' \in c\text{-ALG}_L^\tau$.
If $K \in \text{Conf}_L^\theta$ and $K \rightarrow K'$ then $K' \in \text{Conf}_L^\theta$.*
- (iii) *$K \in \text{Conf}_L^{\text{ieexp}}$ is in normal form iff it is of the form (n, ms) .
 $K \in \text{Conf}_L^{\text{cmd}}$ is in normal form iff it is of the form (skip, ms) .*

(i) means that all computations are deterministic, (ii) means that transition steps preserve types and consistency, and together with (iii) this implies that each computation which starts with a consistent configuration $K \in \text{Conf}_L^\theta$ either diverges or terminates with a ‘proper result’ $(c, ms) \in \text{Conf}_L^\theta$. As $(P, ms_{\text{init}}) \in \text{Conf}_\emptyset^{\text{ieexp}}$ for every program P , this implies in particular that the evaluation of a program can never get stuck; it either diverges or terminates with a unique result of the form (n, ms_{init}) . Note that the final configuration (n, ms_{init}) does not contain any garbage, because our operational semantics explicitly follows the stack discipline: Every location which is allocated upon block entry by rule (new-init) is eventually deallocated upon block exit by rule (new-finish), and thus—in contrast to the situation in a call-by-value language [15, 14]—a location never survives the block in which it has been allocated.

Proof:

(i) is omitted. It is a routine argumentation about the applicability of rules.

(ii) The first part is obvious, because a transition step $M \rightarrow M'$ cannot create any new location constants. The second part is proved by induction on the derivation of $K \rightarrow K'$. We consider a few cases in which locations play a role; the proofs for the remaining cases are absolutely straightforward.

Case 1: $K \equiv (\text{asgn } l(n, ms'), ms) \rightarrow K' \equiv (\text{skip}, ms[n/l])$ by rule (asgn-exec)

Then $l \in \text{dom}(ms)$ and we obtain

$$\begin{aligned} K \in \text{Conf}_L^{\text{cmd}} &\Rightarrow \text{dom}(ms) = L \\ &\Rightarrow \text{dom}(ms[n/l]) = L \\ &\Rightarrow K' \in \text{Conf}_L^{\text{cmd}} \end{aligned}$$

Case 2: $K \equiv (\text{new}_\theta M, ms) \rightarrow K' \equiv \text{dealloc}_\theta l(Ml, ms[0/l])$ by rule (new-init)

Here we have $l = \text{next}(\text{dom}(ms))$ and thus we obtain

$$\begin{aligned} K \in \text{Conf}_L^\theta &\Rightarrow M \in c\text{-ALG}_L^{\text{loc} \rightarrow \theta} \wedge \text{dom}(ms) = L \quad (\text{hence } l \notin L) \\ &\Rightarrow Ml \in c\text{-ALG}_{L \cup \{l\}}^\theta \wedge \text{dom}(ms[0/l]) = L \cup \{l\} \\ &\Rightarrow (Ml, ms[0/l]) \in \text{Conf}_{L \cup \{l\}}^\theta \\ &\Rightarrow K' \in \text{Conf}_{(L \cup \{l\}) \setminus \{l\}}^\theta = \text{Conf}_L^\theta \end{aligned}$$

Case 3: $K \equiv \text{dealloc}_\theta l(c, ms) \rightarrow K' \equiv (c, ms \setminus l)$ by rule (new-finish)

Again $l \in \text{dom}(ms)$ and hence

$$\begin{aligned} K \in \text{Conf}_L^\theta &\Rightarrow \text{dom}(ms) = L \cup \{l\} \wedge l \notin L \\ &\Rightarrow \text{dom}(ms \setminus l) = L \\ &\Rightarrow K' \in \text{Conf}_L^\theta \end{aligned}$$

(iii) The ‘if’-parts are obvious from the rules; ‘only if’ is proved by induction on the structure of K : Assume that $K \in \text{Conf}_L^\theta$ is *not* of the form (n, ms) or (skip, ms) .

Case 1: $K \equiv (M, ms)$

From the definition of Conf_L^θ it follows that $M \in c\text{-ALG}_L^\theta$ and $\text{dom}(ms) = L$. By assumption, M is not a constant, and as θ is a ground type, M cannot be a λ -abstraction as well, hence it must be an application which can be written as $M \equiv M_0 M_1 \dots M_k$ ($k \geq 1$) where M_0 is *not* an application. If M_0 is a λ -abstraction or a fixed point operator, then $M \rightarrow M'$ for some $M' \in c\text{-ALG}_L^\theta$, hence $K \rightarrow (M', ms)$. Otherwise, M_0 must be a constant $c \neq Y_\sigma$, and then one of the (init)-rules applies in each case. For example, if $M_0 \equiv \text{asgn}$, then K must be of the form $(\text{asgn } l M_2, ms)$ with $l \in L = \text{dom}(ms)$, hence $K \rightarrow (\text{asgn } l(M_2, ms), ms)$ by rule (asgn-init). The argumentation for the remaining constants is similar.

Case 2: $K \equiv E[K']$, where E does not start with ‘pcond’

If $K' \rightarrow K''$ then $K \rightarrow E[K'']$ by the (context)-rule. If K' is in normal form, then one

of the other rules of Table 1 can be applied. For example, if $E \equiv (\text{asgn } l \mid, ms)$, then $K' \in \text{Conf}_L^{\text{iecp}}$ and $l \in L = \text{dom}(ms)$, hence $K' \equiv (n, ms')$ by induction hypothesis and this implies $K \equiv (\text{asgn } l \mid (n, ms'), ms) \rightarrow (\text{skip}, ms[n/l])$. The argumentation for the remaining evaluation contexts is similar.

Case 3: $K \equiv \text{pcond} K_1 K_2 K_3$

Here either the (context)-rule or one of the (pcond)-rules can be applied, depending on which of the configurations K_1, K_2, K_3 are in normal form. \square

4 A Cartesian Closed Category

In this section we define the general framework for our denotational semantics. The intuition is, that every function in the denotational model should only have access to some fixed finite set of locations. Hence we would like to identify—for every type τ and every $L \in \mathcal{P}_{\text{fin}}(\text{Loc})$ —a dcpo $\llbracket \tau \rrbracket_L$ of ‘elements of type τ which only have access to L ’ and then define $\llbracket \tau \rrbracket$ as the union of the dcpos $\llbracket \tau \rrbracket_L$. This is the motivation for

Definition 4.1 Let (W, \leq) be a directed set (of ‘worlds’ w).

- (1) A *W*-locally complete partial order (*W*-lcpo) is a partial order (D, \sqsubseteq) together with a family of subsets $(D_w)_{w \in W}$ such that $D = \bigcup_{w \in W} D_w$ and for all $v, w \in W$

- $v \leq w \Rightarrow D_v \subseteq D_w$
- if $\Delta \subseteq D_w$ is directed, then $\bigsqcup_D \Delta$ exists and is contained in D_w (hence it is also the lub in D_w , i.e. (D_w, \sqsubseteq) is a dcpo)

D is called *pointed*, if it has a least element which is contained in all D_w .

- (2) A function $f : D \rightarrow E$ between *W*-lcpos D and E is called *locally continuous* if $(f \mid D_w) \in (D_w \xrightarrow{c} E_w)$ for every $w \in W$.

Note that every finite subset S of a *W*-lcpo D is entirely contained in one of the dcpos D_w , because W is directed and $v \leq w$ implies $D_v \subseteq D_w$. This implies in turn that every locally continuous function $f : D \rightarrow E$ is monotone on the whole of D .

For every directed set W , we let **W-LCPO** denote the category whose objects are *W*-lcpos and whose morphisms are locally continuous functions. It can be easily checked that this is indeed a category.

Theorem 4.2 (W-LCPO is a ccc) *The category W-LCPO is cartesian closed. The terminal object T , the product $D \times E$ and the exponent $(D \rightarrow E)$ of two W-lcpos D and E are defined by*

- (i) $T_w = \{\emptyset\}$
 $T = \{\emptyset\}$

- (ii) $(D \times E)_w = D_w \times E_w$
 $D \times E = \bigcup_{w \in W} (D \times E)_w$ with the componentwise order on pairs
- (iii) $(D \rightarrow E)_w = \{f : D \rightarrow E \mid \forall v \geq w. (f \upharpoonright D_v) \in (D_v \xrightarrow{c} E_v)\}$
 $(D \rightarrow E) = \bigcup_{w \in W} (D \rightarrow E)_w$ with the pointwise order on functions

Projection morphisms and pairing, evaluation morphisms and currying and the unique morphisms to the terminal object are defined as usual.

The experienced reader certainly realizes the similarity with a functor category, in particular (iii) looks like functor exponentiation [33]. Indeed, a W -lcpo D can be considered as a functor from the category W to the category **DCPO** of dcpo's and continuous functions, which maps every morphism $f : v \rightarrow w$ in W to the inclusion map $i : D_v \rightarrow D_w$ (which is continuous, because $\bigsqcup_{D_v} \Delta = \bigsqcup_D \Delta = \bigsqcup_{D_w} \Delta$ for every directed set $\Delta \subseteq D_v$). The locally continuous functions between two W -lcpos then correspond exactly to the natural transformations between the functors, and exponentiation in W -**LCPO** corresponds to functor exponentiation. Hence W -**LCPO** can be identified with a full subcategory of the functor category $(W \Rightarrow \mathbf{DCPO})$ which has the same terminal object, products and exponents as $(W \Rightarrow \mathbf{DCPO})$ itself.

We omit the proof of Theorem 4.2, because the category W -**LCPO** is anyways not sufficient for our purposes. We are again aiming for a denotational model in which the function types $\llbracket \tau \rightarrow \sigma \rrbracket$ contain only those locally continuous functions which preserve certain (logical) relations. To this end we must add 'relation structure' to the W -lcpos and then refine the definition of the exponent $(D \rightarrow E)$.

Definition 4.3 A W -sorted (relation) signature is a family $\Sigma = (\Sigma_n^w)_{w \in W, n \in \mathbb{N}}$ of sets Σ_n^w such that for all $m, n \in \mathbb{N}$ and $v, w \in W$

- $m \neq n \Rightarrow \Sigma_m^v \cap \Sigma_n^w = \emptyset$
- $v \leq w \Rightarrow \Sigma_n^v \supseteq \Sigma_n^w$

An element $r \in \Sigma_n$ is called a *relation symbol* of *arity* n . We use the abbreviations

$$\Sigma_n =_{\text{def}} \bigcup_{w \in W} \Sigma_n^w, \quad \Sigma^w =_{\text{def}} \bigcup_{n \in \mathbb{N}} \Sigma_n^w, \quad \Sigma =_{\text{def}} \bigcup_{n \in \mathbb{N}} \Sigma_n$$

Definition 4.4 Let Σ be a W -sorted signature.

- (1) A W - Σ -lcpo is a pair (D, \mathcal{I}) , where D is a W -lcpo and \mathcal{I} is a function which maps every $r \in \Sigma_n$ to a relation $\mathcal{I}(r) \subseteq D^n$ such that for all $w \in W$

- $r \in \Sigma^w \Rightarrow \delta^n D_w \subseteq \mathcal{I}(r)$
- $\mathcal{I}(r) \cap D_w^n$ is closed under least upper bounds of directed sets

(D, \mathcal{I}) is called *pointed* if the underlying W -lcpo D is pointed.

- (2) A function $f : D \rightarrow E$ between W - Σ -lcpos (D, \mathcal{I}^D) and (E, \mathcal{I}^E) is called a Σ -homomorphism if $f(\mathcal{I}^D(r)) \subseteq \mathcal{I}^E(r)$ for all $r \in \Sigma$.

For every directed set W and W -sorted signature Σ , we let W - Σ -**LCPO** denote the category whose objects are W - Σ -lcpos and whose morphisms are locally continuous Σ -homomorphisms. Again, it can be easily checked that this is a category.

Theorem 4.5 (W - Σ -LCPO** is a ccc)** *The category W - Σ -**LCPO** is cartesian closed. The terminal object T , the product $D \times E$ and the exponent $(D \rightarrow E)$ of two W - Σ -lcpos D and E are defined by*

- (i) $T_w = \{\emptyset\}$
 $T = \{\emptyset\}$
 $\mathcal{I}^T(r) = \{\emptyset\}^n$ if $r \in \Sigma_n$
- (ii) $(D \times E)_w = D_w \times E_w$
 $D \times E = \bigcup_{w \in W} (D \times E)_w$ with the componentwise order on pairs
 $\mathcal{I}^{D \times E}(r) = (\mathcal{I}^D(r), \mathcal{I}^E(r)) = \{((d_1, e_1), \dots, (d_n, e_n)) \mid \vec{d} \in \mathcal{I}^D(r), \vec{e} \in \mathcal{I}^E(r)\}$
- (iii) $(D \rightarrow E)_w = \{f : D \rightarrow E \mid \forall v \geq w. (f \upharpoonright D_v) \in (D_v \xrightarrow{c} E_v) \wedge \forall r \in \Sigma^w. f(\mathcal{I}^D(r)) \subseteq \mathcal{I}^E(r)\}$
 $(D \rightarrow E) = \bigcup_{w \in W} (D \rightarrow E)_w$ with the pointwise order on functions
 $\mathcal{I}^{(D \rightarrow E)}(r) = \{\vec{f} \mid \vec{f}(\mathcal{I}^D(r)) \subseteq \mathcal{I}^E(r)\}$

Projection morphisms and pairing, evaluation morphisms and currying and the unique morphisms to the terminal object are defined as usual.

Proof: The proofs for the terminal object and the product are straightforward, hence we only consider the exponent. We must first show that $(D \rightarrow E)$ is a well-defined W - Σ -lcpo. Obviously, $(D \rightarrow E)$ is a partial order and $v \leq w$ implies $(D \rightarrow E)_v \subseteq (D \rightarrow E)_w$, because $\Sigma^v \supseteq \Sigma^w$ in this case. For the remaining steps it is sufficient to prove that for all $w \in W$ and $r \in \Sigma_n$

- (1) if $\Delta \subseteq (D \rightarrow E)_w$ is directed, then $f : D \rightarrow E$ with $fd = \bigsqcup \Delta d$ is a well-defined function in $(D \rightarrow E)_w$ (hence it is the lub of Δ in D);
- (2) if $r \in \Sigma^w$ then $\delta^n(D \rightarrow E)_w \subseteq \mathcal{I}^{(D \rightarrow E)}(r)$;
- (3) if $\Delta \subseteq \mathcal{I}^{(D \rightarrow E)}(r) \cap (D \rightarrow E)_w^n$ is directed, then $\bigsqcup \Delta \in \mathcal{I}^{(D \rightarrow E)}(r)$.

Proof of (1): Let $\Delta \subseteq (D \rightarrow E)_w$ be directed and let $d \in D$. As W is directed, we may assume that $d \in D_v$ for some $v \geq w$, hence Δd is a directed subset of E_v and thus $\bigsqcup \Delta d \in E_v \subseteq E$ exists. This shows that $f : D \rightarrow E$ is well-defined and that $f(D_v) \subseteq E_v$ for all $v \geq w$. Moreover, the restriction $f \upharpoonright D_v$ is continuous for every $v \geq w$, because it is the pointwise lub of the continuous functions $g \upharpoonright D_v$ with $g \in \Delta$. Finally, if $\vec{d} \in \mathcal{I}^D(r)$ for some $r \in \Sigma^w$, then there is some $v \geq w$

such that $d_1, \dots, d_n \in D_v$, hence $g \vec{d} \in \mathcal{I}^E(r) \cap E_v^n$ for all $g \in \Delta$ and thus also $f \vec{d} = \bigsqcup_{g \in \Delta} g \vec{d} \in \mathcal{I}^E(r)$. This concludes the proof that $f \in (D \rightarrow E)_w$.

Proof of (2): If $r \in \Sigma^w$ and $f \in (D \rightarrow E)_w$, then $f(\mathcal{I}^D(r)) \subseteq \mathcal{I}^E(r)$, hence $(f, \dots, f) \in \mathcal{I}^{(D \rightarrow E)}(r)$.

Proof of (3): Let $\Delta \subseteq \mathcal{I}^{(D \rightarrow E)}(r) \cap (D \rightarrow E)_w^n$ be directed and let $\vec{f} = \bigsqcup \Delta$. For every $\vec{d} \in \mathcal{I}^D(r)$ there is some $v \geq w$ with $d_1, \dots, d_n \in D_v$, hence $\vec{g} \vec{d} \in \mathcal{I}^E(r) \cap E_v^n$ for every $\vec{g} \in \Delta$ and thus also $\vec{f} \vec{d} = \bigsqcup_{\vec{g} \in \Delta} \vec{g} \vec{d} \in \mathcal{I}^E(r)$.

This concludes the proof that $(D \rightarrow E)$ is a W - Σ -lcpo. It remains to be shown that it is indeed the exponent of D and E in the category W - Σ -lcpo. To this end it is sufficient to prove that

(4) the function

$$\begin{aligned} eval : (D \rightarrow E) \times D &\rightarrow E \\ eval f d &= f d \end{aligned}$$

is a locally continuous Σ -homomorphism, and

(5) if C is a W - Σ -lcpo and $f : C \times D \rightarrow E$ is a locally continuous Σ -homomorphism, then the function

$$\begin{aligned} \Lambda f : C &\rightarrow (D \rightarrow E) \\ \Lambda f c d &= f(c, d) \end{aligned}$$

is well-defined and is a locally continuous Σ -homomorphism.

Proof of (4): For every $w \in W$, $eval((D \rightarrow E)_w \times D_w) = (D \rightarrow E)_w D_w \subseteq E_w$, and the restriction of $eval$ to $(D \rightarrow E)_w \times D_w$ is continuous, because lub's are defined pointwise on $(D \rightarrow E)_w$ and because every $f \in (D \rightarrow E)_w$ is continuous on D_w . Moreover, $eval(\mathcal{I}^{(D \rightarrow E) \times D}(r)) = eval(\mathcal{I}^{(D \rightarrow E)}(r), \mathcal{I}^D(r)) = \mathcal{I}^{(D \rightarrow E)}(r) (\mathcal{I}^D(r)) \subseteq \mathcal{I}^E(r)$ for every $r \in \Sigma$.

Proof of (5): Let $f : C \times D \rightarrow E$ be a locally continuous Σ -homomorphism, let $w \in W$ and $c \in C_w$. If $v \geq w$, then $\Lambda f c D_v = f(\{c\} \times D_v) \subseteq f(C_v \times D_v) \subseteq E_v$ and $\Lambda f c \upharpoonright D_v$ is continuous because $f \upharpoonright C_v \times D_v$ is continuous. Moreover, $\Lambda f c (\mathcal{I}^D(r)) = f(c, \mathcal{I}^D(r)) \subseteq f(\delta C_w, \mathcal{I}^D(r)) \subseteq f(\mathcal{I}^C(r), \mathcal{I}^D(r)) \subseteq f(\mathcal{I}^{C \times D}(r)) \subseteq \mathcal{I}^E(r)$ for all $r \in \Sigma^w$. This shows that $\Lambda f c \in (D \rightarrow E)_w$. Hence Λf is a well-defined function which maps C_w to $(D \rightarrow E)_w$ for every $w \in W$. The restriction of Λf to each C_w is continuous, because f is continuous on $C_w \times \{d\}$ for every $d \in D$ and because lub's are defined pointwise on $(D \rightarrow E)_w$. Finally, $\Lambda f(\mathcal{I}^C(r)) (\mathcal{I}^D(r)) = f(\mathcal{I}^C(r), \mathcal{I}^D(r)) = f(\mathcal{I}^{C \times D}(r)) \subseteq \mathcal{I}^E(r)$, i.e. $\Lambda f(\mathcal{I}^C(r)) \subseteq \mathcal{I}^{(D \rightarrow E)}(r)$ for every $r \in \Sigma$. \square

We finally remark that $(D \rightarrow E)$ is pointed whenever E is pointed: If \perp_E is the least element of E , then $(\lambda d \in D. \perp_E) \in (D \rightarrow E)_w$ for all $w \in W$ because $\perp_E \in E_w$ for all $w \in W$ and $(\perp_E, \dots, \perp_E) \in \bigcap_{w \in W} \delta^n E_w \subseteq \mathcal{I}^E(r)$ for all $r \in \Sigma$. Together with the following theorem this guarantees that enough fixed point operators will be contained in our denotational model.

Theorem 4.6 (least fixed point operators) *Let D be a pointed W - Σ -lcpo and let $f \in (D \rightarrow D)$. Then f has a least fixed point $\mu f \in D$, which can be characterized as usual by*

$$\mu f = \bigsqcup_{n \in \mathbb{N}} f^n \perp$$

Moreover, the least fixed point operator

$$\begin{aligned} \mu_D : (D \rightarrow D) &\rightarrow D \\ \mu_D f &= \mu f \end{aligned}$$

is a locally continuous Σ -homomorphism.

Proof: Let $f \in (D \rightarrow D)_w$. As $(f \mid D_w) \in (D_w \xrightarrow{c} D_w)$, we know that $\bigsqcup_{n \in \mathbb{N}} f^n \perp$ exists and is the least fixed point of f in D_w . But then it is also its least fixed point in D , because—by monotonicity of f — $f^n \perp \sqsubseteq d$ for every other fixed point d . This shows already that μ_D maps $(D \rightarrow D)_w$ to D_w for every $w \in W$. Moreover, μ_D is continuous on every $(D \rightarrow D)_w$ because it is the pointwise lub of the functions $\lambda f. f^n \perp$ ($n \in \mathbb{N}$), which are continuous on $(D \rightarrow D)_w$ by Theorem 4.5. Finally, let $r \in \Sigma_m$ and $\vec{f} \in \mathcal{I}^{(D \rightarrow D)}(r)$. Then $f_1, \dots, f_m \in D_w$ for some $w \in W$, hence—by induction on n — $(f_1^n \perp, \dots, f_m^n \perp) \in \mathcal{I}^D(r) \cap D_w^m$ for all $n \in \mathbb{N}$, and this implies $\mu_D \vec{f} \in \mathcal{I}^D(r)$. \square

W - Σ -**LCPO** is the category in which we will define our denotational model (with an appropriate choice of W and Σ). It has a certain similarity with a category of ‘parametric functors and natural transformations’ [21], and indeed we succeeded to prove a connection: Let \mathcal{D} be the reflexive graph with vertex category **DCPO** as defined in [21]. Then—for every W -sorted signature Σ —we can define a reflexive graph \mathcal{W} with vertex category W such that W - Σ -**LCPO** can be identified with a full subcategory of the parametric functor category $(\mathcal{W} \Rightarrow \mathcal{D})$ which has the same terminal object, products and exponents as $(\mathcal{W} \Rightarrow \mathcal{D})$ itself. We do not want to elaborate on this any further because it seems like a purely technical insight.

5 Denotational Semantics

We will now use the techniques of Section 4 to define a denotational semantics for **ALG**. Of course we choose

$$(W, \leq) = (\mathcal{P}_{fin}(Loc), \subseteq)$$

as the directed set of worlds, but the question remains how to define a W -sorted signature Σ which serves our purposes. The basic idea is the same as for our *PCF*-model in Chapter 2: In order to achieve full abstraction we try to keep the denotational model ‘as small as possible’ and to this end we try to make the relation signature ‘as large as possible’. For the purely functional language *PCF* this was easy to achieve. We simply used *all* relations on the flat ground type of integers which are preserved by the meanings of the first order *PCF*-constants. This worked out,

because all relations on a flat dcpo are automatically closed under lub's of directed sets (as required in Definition 4.4) and because the only higher order *PCF*-constants are fixed point operators. For the imperative language ALG the situation is more difficult, because the ground types $\llbracket iexp \rrbracket$ and $\llbracket cmd \rrbracket$ will certainly be *not* flat. Thus, in order to transfer the ideas of Chapter 2 to the ALG setting, we first introduce an additional semantic layer of flat dcpo's *below* the ground types $\llbracket iexp \rrbracket$ and $\llbracket cmd \rrbracket$, and on this new layer we define certain auxiliary functions, which are closely related to the intended meanings of the ALG-constants.

To begin with, we define the set *Stores* of *stores* s by

$$\begin{aligned} Stores &= \bigcup_{L \in W} Stores_L \quad \text{where} \\ Stores_L &= \{s : Loc \rightarrow \mathbb{Z} \mid \forall l \in Loc \setminus L. sl = 0\} \end{aligned}$$

Note that a store s —in contrast to a marked store ms —is a *total* function which delivers 0 for all but finitely many locations. Working with total instead of partial functions is a technical trick which makes our denotational semantics somewhat simpler.

Now let $\Gamma = \{loc, int, sto\}$, where *int* (= ‘integer’) and *sto* (= ‘store’) are auxiliary symbols. We use $sto \Rightarrow int$ and $sto \Rightarrow sto$ as alternative notation for *iexp* and *cmd*. For every $\gamma \in \Gamma$ we define a dcpo D^γ by

$$\begin{aligned} D^{loc} &= Loc && \text{(discrete dcpo)} \\ D^{int} &= \mathbb{Z}_\perp, \quad D^{sto} = Stores_\perp && \text{(flat dcpo's)} \end{aligned}$$

We write \perp_γ for the bottom element of D^γ (if we want to be precise about γ) and id_γ for the identity on D^γ . The set *AUX* of *auxiliary functions* is then defined by

$$AUX = \{Const_n, Succ, Pred, Cont, Asgn, Cond_\gamma, Pcond \mid n \in \mathbb{Z}, \gamma \neq loc\}$$

where

$$\begin{aligned} - \quad Const_n &: D^{sto} \rightarrow D^{int} \\ Const_n s &= \begin{cases} \perp & \text{if } s = \perp \\ n & \text{otherwise} \end{cases} \\ - \quad Succ &: D^{int} \rightarrow D^{int} \\ Succ d &= \begin{cases} \perp & \text{if } d = \perp \\ d + 1 & \text{otherwise} \end{cases} \\ - \quad Pred &: D^{int} \rightarrow D^{int} \\ Pred d &= \begin{cases} \perp & \text{if } d = \perp \\ d - 1 & \text{otherwise} \end{cases} \\ - \quad Cont &: D^{loc} \rightarrow D^{sto} \rightarrow D^{int} \\ Cont l s &= \begin{cases} \perp & \text{if } s = \perp \\ sl & \text{otherwise} \end{cases} \end{aligned}$$

$$\begin{aligned}
- \text{Asgn} : & \quad D^{loc} \rightarrow D^{int} \rightarrow D^{sto} \rightarrow D^{sto} \\
\text{Asgn } l \, d \, s = & \quad \begin{cases} \perp & \text{if } d = \perp \text{ or } s = \perp \\ s[d/l] & \text{otherwise} \end{cases} \\
- \text{Cond}_\gamma : & \quad D^{int} \rightarrow D^\gamma \rightarrow D^\gamma \rightarrow D^\gamma \\
\text{Cond}_\gamma \, b \, d_1 \, d_2 = & \quad \begin{cases} \perp & \text{if } b = \perp \\ d_1 & \text{if } b = 0 \\ d_2 & \text{otherwise} \end{cases} \\
- \text{Pcond} : & \quad D^{int} \rightarrow D^{int} \rightarrow D^{int} \rightarrow D^{int} \\
\text{Pcond } b \, d_1 \, d_2 = & \quad \begin{cases} \perp & \text{if } b = \perp \text{ and } d_1 \neq d_2 \\ d_1 & \text{if } b = 0 \\ d_2 & \text{otherwise} \end{cases}
\end{aligned}$$

With the aid of these auxiliary functions we can now define the signature Σ . The relation symbols of Σ are so-called ground relations. A *ground relation* of *arity* n is simply a triple $R = (R^\gamma)_{\gamma \in \Gamma}$ such that $R^\gamma \subseteq (D^\gamma)^n$ for every $\gamma \in \Gamma$. We say that a function $f : D^{\gamma_1} \rightarrow \dots \rightarrow D^{\gamma_k} \rightarrow D^\gamma$ *preserves* the ground relation R if $f R^{\gamma_1} \dots R^{\gamma_k} \subseteq R^\gamma$. Finally we let $\Sigma = (\Sigma_n^L)_{L \in W, n \in \mathbb{N}}$ where Σ_n^L is the set of all ground relations R of arity n such that

- (a) every $f \in \text{AUX}$ preserves R
- (b) $\delta^n(\text{Loc} \setminus L') \subseteq R^{loc}$ for some $L' \in W$ with $L \cap L' = \emptyset$
(i.e. R^{loc} contains a cofinite part of the diagonal $\delta^n \text{Loc}$ which includes $\delta^n L$)
- (c) $(\perp_{sto}, \dots, \perp_{sto}) \in R^{sto}$
(and hence $(\perp_{int}, \dots, \perp_{int}) \in R^{int}$ by (a))

Note that Σ is indeed a W -sorted signature, because $L \subseteq L'$ implies $\Sigma_n^L \supseteq \Sigma_n^{L'}$. The motivation for choosing this particular signature Σ is as follows: Condition (a) will guarantee that $\llbracket n \rrbracket, \llbracket succ \rrbracket, \llbracket pred \rrbracket, \llbracket cont \rrbracket, \llbracket asgn \rrbracket, \llbracket cond_\theta \rrbracket$ and $\llbracket pcond \rrbracket$ are Σ -homomorphisms. Together with (b) this will imply that every $R \in \Sigma^L$ is preserved by the functions $\llbracket cont \rrbracket l$ and $\llbracket asgn \rrbracket l$ not only for all $l \in L$ but also for all but finitely many $l \notin L$. The latter will play a role in the proof that the meanings of the *new*-operators are Σ -homomorphisms. Finally, (c) will be needed for handling the fixed point operators. Altogether these are the necessary conditions for Σ , if we want to define a denotational semantics for ALG in the category $W\text{-}\Sigma\text{-LCPO}$. This means that we have indeed chosen the ‘largest possible’ signature Σ for our purposes, and thus we can hope for a full abstraction proof along the lines of Chapter 2.

With the definition of W and Σ we have fixed the category in which we want to define our denotational model. The next step is to associate an object of this category with each type. For every type τ we define a $W\text{-}\Sigma\text{-lcpo}$ $\llbracket \tau \rrbracket = (D^\tau, \mathcal{I}^\tau)$ by

$$\begin{aligned}
- D_L^{loc} &= L \\
D^{loc} &= \text{Loc} \quad (\text{as before}) \\
\mathcal{I}^{loc}(R) &= R^{loc}
\end{aligned}$$

- $D_L^{sto \Rightarrow \gamma} = \{f : D^{sto} \rightarrow D^\gamma \mid fR^{sto} \subseteq R^\gamma \text{ for all } R \in \Sigma^L\}$
 $D^{sto \Rightarrow \gamma} = \bigcup_{L \in W} D_L^{sto \Rightarrow \gamma}$ with the pointwise order on functions
- $\mathcal{I}^{sto \Rightarrow \gamma}(R) = \{\vec{f} \in (D^{sto \Rightarrow \gamma})^n \mid \vec{f}R^{sto} \subseteq R^\gamma\}$ if $R \in \Sigma_n$
- $\llbracket \tau \rightarrow \sigma \rrbracket = (\llbracket \tau \rrbracket \rightarrow \llbracket \sigma \rrbracket)$ as defined in Theorem 4.5

It can be easily checked that the first two clauses indeed define W - Σ -lcpos, in particular $D_L^{sto \Rightarrow \gamma}$ is always closed under lub's of directed sets, because every R^γ is (trivially) closed under lub's of directed sets. Note also that $\llbracket \sigma \rrbracket$ is pointed for every procedure type σ (by a straightforward induction on σ). We write \perp_σ for the bottom element of $\llbracket \sigma \rrbracket$ and id_σ for the identity on $\llbracket \sigma \rrbracket$.

The reader may have realized that the ground types $\llbracket iexp \rrbracket = \llbracket sto \Rightarrow int \rrbracket$ and $\llbracket cmd \rrbracket = \llbracket sto \Rightarrow sto \rrbracket$ have a certain similarity with our function types (Theorem 4.5) in that they consist of relation preserving functions. Hence the question may arise whether our model definition can be simplified by introducing *sto* and *int* as ground types and defining *iexp* and *cmd* as function types $(sto \rightarrow int)$ and $(sto \rightarrow sto)$. Unfortunately this is *not* possible. There is no way to define a W - Σ -lcpo $\llbracket sto \rrbracket$ such that $\llbracket cmd \rrbracket$ (as defined above) coincides with the exponent $(\llbracket sto \rrbracket \rightarrow \llbracket sto \rrbracket)$. O'Hearn and Tennent have occasionally used 'contra-exponentiation' instead of ordinary exponentiation to overcome this difficulty [32, 20], but for our purposes it doesn't seem worth to introduce such an extra concept; the above ad hoc definition of $\llbracket iexp \rrbracket$ and $\llbracket cmd \rrbracket$ is entirely sufficient.

We follow usual mathematical convention and use $\llbracket \tau \rrbracket$ not only as a notation for the W - Σ -lcpo $(D^\tau, \mathcal{I}^\tau)$ but also for the underlying W -lcpo (or the partial order or the set) D^τ , hence $\llbracket \tau \rrbracket_L$ denotes the dcpo D_L^τ . Moreover, we use R^τ as an abbreviation for $\mathcal{I}^\tau(R)$. As immediate consequences of the definitions in Section 4 we then obtain the following 'reasoning principles' which will be frequently used throughout the rest of the chapter.

- (1) $\llbracket \tau \rightarrow \sigma \rrbracket_L \llbracket \tau \rrbracket_{L'} \subseteq \llbracket \sigma \rrbracket_{L'}$ whenever $L \subseteq L'$
- (2) $fR^\tau \subseteq R^\sigma$ whenever $f \in \llbracket \tau \rightarrow \sigma \rrbracket_L$ and $R \in \Sigma^L$
- (3) $R^{\tau \rightarrow \sigma} = \{\vec{f} \in \llbracket \tau \rightarrow \sigma \rrbracket^n \mid \vec{f}R^\tau \subseteq R^\sigma\}$ whenever $R \in \Sigma_n$

Reasoning principle (1) is equivalent to

$$(1') \quad \llbracket \tau \rightarrow \sigma \rrbracket_L \llbracket \tau \rrbracket_{L'} \subseteq \llbracket \sigma \rrbracket_{L \cup L'} \text{ for all } L, L' \in W$$

which can be rephrased in more intuitive terms as

‘A procedure call fd can only have access to those locations to which either the procedure $f \in \llbracket \tau \rightarrow \sigma \rrbracket$ or the parameter $d \in \llbracket \tau \rrbracket$ has access.’

For (2) we do not (yet) have such an intuitive formulation, because our current definition of the sets Σ^L is very technical, but we will come back to this in a moment. (3) means that the family $(R^\tau)_{\tau \in Type}$ is a logical relation [17] for every $R \in \Sigma$.

We finally define the *support* of an element $d \in \llbracket \tau \rrbracket$ to be the set

$$\text{supp}(d) = \bigcap \{L \mid d \in \llbracket \tau \rrbracket_L\}$$

One may wonder whether $d \in \llbracket \tau \rrbracket_{\text{supp}(d)}$, i.e. whether there is a *smallest* set L with $d \in \llbracket \tau \rrbracket_L$. We have not examined this question, as it is irrelevant for our purposes.

As mentioned above, we are not yet satisfied with our current, rather technical characterization of the signature Σ . It is well suited for the full abstraction proof (especially for the proof of Theorem 9.3), but for other purposes—like proofs of particular observational congruences—a more concrete description of Σ would certainly be useful. Unfortunately we have not found a (tasteful) concrete description of the full signature Σ , but instead we have identified the following ‘sub-signature’, which seems to be sufficient for proving all observational congruences (cf. Section 7 and Conjecture 11.1).

Definition 5.1 Let $L \in W$. An n -ary ground relation R is called *L -definable*, if there is a relation $R_L \subseteq (L \xrightarrow{t} \mathbb{Z})^n$ such that

- $R^{\text{sto}} = \{\perp\}^n \cup \{\vec{s} \in \text{Stores}^n \mid (\vec{s} \upharpoonright L) \in R_L \wedge \vec{s}(\delta^n(\text{Loc} \setminus L)) \subseteq \delta^n \mathbb{Z}\}$
- $R^{\text{int}} = \delta^n D^{\text{int}}$
- $R^{\text{loc}} = \{\vec{l} \in (D^{\text{loc}})^n \mid \text{Cont } \vec{l} R^{\text{sto}} \subseteq R^{\text{int}} \wedge \text{Asgn } \vec{l} R^{\text{int}} R^{\text{sto}} \subseteq R^{\text{sto}}\}$

Note that every L -definable ground relation R is uniquely determined by R^{sto} or even by R_L . We let DEF_n^L denote the set of all L -definable ground relations of arity n and $\text{OUT}_n^L = \bigcup_{L' \in W \wedge L \cap L' = \emptyset} \text{DEF}_n^{L'}$ the set of those which are definable outside L . Note that $\text{OUT}_n^L \supseteq \text{OUT}_n^{L'}$ whenever $L \subseteq L'$, hence $\text{OUT} = (\text{OUT}_n^L)_{L \in W, n \in \mathbb{N}}$ is itself a W -sorted signature.

Theorem 5.2 (a sub-signature of Σ) $\text{OUT}_n^L \subseteq \Sigma_n^L$ for every $L \in W$ and $n \in \mathbb{N}$.

Proof: Let $R \in \text{DEF}_n^{L'}$ for some $L' \in W$ with $L \cap L' = \emptyset$. Then $(\perp, \dots, \perp) \in R^{\text{sto}}$, and it is easy to see that every function $f \in \text{AUX}$ preserves R . Hence it is sufficient to show that $\delta^n(\text{Loc} \setminus L') \subseteq R^{\text{loc}}$.

Let $l \in \text{Loc} \setminus L'$, let $\vec{s} \in R^{\text{sto}}$, $\vec{d} \in R^{\text{int}}$, $\vec{e} = \text{Cont } l \vec{s}$ and $\vec{t} = \text{Asgn } l \vec{d} \vec{s}$. If $\vec{s} = (\perp, \dots, \perp)$, then $\vec{e} = (\perp, \dots, \perp) \in R^{\text{int}}$. Otherwise $\vec{e} = \vec{s}l \in \delta^n \mathbb{Z} \subseteq R^{\text{int}}$. If $\vec{d} = (\perp, \dots, \perp)$ or $\vec{s} = (\perp, \dots, \perp)$, then $\vec{t} = (\perp, \dots, \perp) \in R^{\text{sto}}$. Otherwise $(\vec{t} \upharpoonright L') = (\vec{s} \upharpoonright L') \in R_{L'}$, $\vec{t}l = \vec{d} \in \delta^n \mathbb{Z}$ and $\vec{t}l' = \vec{s}l' \in \delta^n \mathbb{Z}$ for all $l' \in \text{Loc} \setminus L'$ with $l' \neq l$, hence again $\vec{t} \in R^{\text{sto}}$. Thus we have proved that $\text{Cont } l R^{\text{sto}} \subseteq R^{\text{int}}$ and $\text{Asgn } l R^{\text{int}} R^{\text{sto}} \subseteq R^{\text{sto}}$, i.e. $(l, \dots, l) \in R^{\text{loc}}$. \square

As immediate consequences of Theorem 5.2 we obtain

- $f R^{\text{sto}} \subseteq R^\gamma$ whenever $f \in \llbracket \text{sto} \Rightarrow \gamma \rrbracket_L$ and $R \in \text{OUT}^L$
- $f R^\tau \subseteq R^\sigma$ whenever $f \in \llbracket \tau \rightarrow \sigma \rrbracket_L$ and $R \in \text{OUT}^L$

In more intuitive terms both can be summarized as

‘A procedure $f \in \llbracket \sigma \rrbracket_L$ preserves all relations which are definable outside L .’

This is the most important reasoning principle for proving observational congruences (Section 7) as well as other, more general properties of our denotational model like Theorem 5.3 below. A particular instance of this reasoning principle is obtained by permutations of locations: Let $\varphi : Loc \rightarrow Loc$ be a *finite permutation*, i.e. a bijective function whose ‘support’ $Supp(\varphi) =_{def} \{l \in Loc \mid \varphi l \neq l\}$ is finite. Then we define $R_\varphi \in DEF_2^{Supp(\varphi)}$ by

$$R_\varphi^{sto} = \{\perp\}^2 \cup \{(s, s \circ \varphi) \mid s \in Stores\}$$

In order to see that R_φ is indeed $Supp(\varphi)$ -definable, note that it can be rewritten as

$$R_\varphi^{sto} = \{\perp\}^2 \cup \{\vec{s} \in Stores^2 \mid \forall l \in Supp(\varphi). s_1(\varphi l) = s_2 l \wedge s_1 =_{Loc \setminus Supp(\varphi)} s_2\}$$

and that $\varphi(Supp(\varphi)) = Supp(\varphi)$. If we finally let $Fix(L)$ denote the set of all finite permutations $\varphi : Loc \rightarrow Loc$ which leave the locations of L fixed (i.e. those with $L \cap Supp(\varphi) = \emptyset$), then we have

$$\varphi \in Fix(L) \Rightarrow R_\varphi \in OUT_2^L$$

We will now make use of these new relations in order to prove some important properties of the domains $\llbracket \sigma \rrbracket$ with $ord(\sigma) = 1$. But first we extend the notation for function application, function coincidence and for the variant of a function to bottom elements by defining

$$\begin{aligned} \perp_{sto} l &= \perp_{int} && \text{for all } l \in Loc \\ \perp_{sto} =_L \perp_{sto} &&& \text{for all } L \in W \\ s[d/l] &= \perp_{sto} && \text{if } s = \perp_{sto} \text{ or } d = \perp_{int} \end{aligned}$$

Theorem 5.3 (properties of the first order domains) *Let $L \in W$, $s, s' \in Stores$, $l_1, \dots, l_m \in Loc$ ($m \geq 0$) and $\varphi \in Fix(L)$. Then*

- (i) *If $f \in \llbracket \theta \rrbracket$, then $f\perp = \perp$.*
- (ii) *If $f \in \llbracket iexp \rrbracket_L$, then $s =_L s' \Rightarrow fs = fs'$.*
- (iii) *If $f \in \llbracket cmd \rrbracket_L$, then $fs \neq \perp \Rightarrow fs =_{Loc \setminus L} s$ and $s =_L s' \Rightarrow fs =_L fs'$.*
- (iv) *If $f \in \llbracket loc^m \rightarrow iexp \rrbracket_L$, then $f(\varphi l_1) \dots (\varphi l_m) s = fl_1 \dots l_m(s \circ \varphi)$.*
- (v) *If $f \in \llbracket loc^m \rightarrow cmd \rrbracket_L$, then $f(\varphi l_1) \dots (\varphi l_m) s = (fl_1 \dots l_m(s \circ \varphi)) \circ \varphi^{-1}$.*

Note that by (ii) and (iii), a function $f \in \llbracket \theta \rrbracket_L$ is uniquely determined by its restriction $f|_{Stores_L}$. Intuitively, (ii) means that $f \in \llbracket iexp \rrbracket_L$ cannot read on locations outside L , (iii) means that $f \in \llbracket cmd \rrbracket_L$ can neither read nor write outside L and (iv) and (v) mean that a function $f \in \llbracket loc^m \rightarrow \theta \rrbracket_L$ behaves uniformly on locations outside L . Taking into account that two stores can only be different on a finite set of locations, we can reformulate (ii) and (iii) as

(ii') If $f \in \llbracket iexp \rrbracket_L$ and $l \in Loc \setminus L$, then $f(s[n/l]) = fs$ for all $n \in \mathbb{Z}$.

(iii') If $f \in \llbracket cmd \rrbracket_L$ and $l \in Loc \setminus L$, then $f(s[n/l]) = (fs)[n/l]$ for all $n \in \mathbb{Z}$.

Proof: We prove (i), (iii) and (v), the proofs for (ii) and (iv) are similar.

(i) Let $\theta = sto \Rightarrow \gamma$ and $f \in \llbracket \theta \rrbracket_L$. Consider the unary ground relation R with $R^{loc} = Loc$, $R^{sto} = \{\perp_{sto}\}$ and $R^{int} = \{\perp_{int}\}$. R is clearly preserved by all $f \in AUX$ and $\delta^1 Loc \subseteq R^{loc}$, hence $R \in \Sigma^L$. This implies $fR^{sto} \subseteq R^\gamma$ and hence $f\perp_{sto} = \perp_\gamma$.

(iii) Let $f \in \llbracket cmd \rrbracket_L$.

If $s \in Stores$ and $l \in Loc \setminus L$, then let $R \in DEF_1^{\{l\}}$ be defined by $R^{sto} = \{\perp\} \cup \{t \in Stores \mid tl = sl\}$. Clearly $s \in R^{sto}$ and $fR^{sto} \subseteq R^{sto}$ because $R \in OUT^L$. This implies $fs \in R^{sto}$, hence $fs = \perp$ or $fsl = sl$. Thus we have proved that $fs \neq \perp$ implies $fs =_{Loc \setminus L} s$.

If $s, s' \in Stores$ with $s =_L s'$, then there is some $L' \in W$ with $L \cap L' = \emptyset$ and $s =_{Loc \setminus L'} s'$. Let $R \in DEF_2^{L'}$ with $R^{sto} = \{\perp\}^2 \cup \{\bar{t} \in Stores^2 \mid t_1 =_{Loc \setminus L'} t_2\}$. Then $(s, s') \in R^{sto}$ and $fR^{sto} \subseteq R^{sto}$ because $R \in OUT^L$. This implies $(fs, fs') \in R^{sto}$, hence $fs =_L fs'$.

(v) Let $f \in \llbracket loc^m \rightarrow cmd \rrbracket_L$. We know that $R_\varphi \in OUT_2^L$, and it is easy to see that $(\varphi l, l) \in R_\varphi^{loc}$ for all $l \in Loc$, hence $(f(\varphi l_1) \dots (\varphi l_m) s, fl_1 \dots l_m(s \circ \varphi)) \in fR_\varphi^{loc} \dots R_\varphi^{loc} R_\varphi^{sto} \subseteq R_\varphi^{sto}$, i.e. $f(\varphi l_1) \dots (\varphi l_m) s = (fl_1 \dots l_m(s \circ \varphi)) \circ \varphi^{-1}$. \square

We now conclude the definition of the denotational semantics by assigning meanings to the constants. We make extensive use of the auxiliary functions in the following definition. This does not only lead to a compact notation but it will also be helpful for later purposes. For every ALG-constant c we define the *meaning* $\llbracket c \rrbracket$ by

$$\begin{array}{ll}
\llbracket l \rrbracket \in D^{loc} & \llbracket n \rrbracket : D^{sto} \rightarrow D^{int} \\
\llbracket l \rrbracket = l & \llbracket n \rrbracket = Const_n \\
\llbracket succ \rrbracket : \llbracket iexp \rrbracket \rightarrow D^{sto} \rightarrow D^{int} & \llbracket pred \rrbracket : \llbracket iexp \rrbracket \rightarrow D^{sto} \rightarrow D^{int} \\
\llbracket succ \rrbracket fs = Succ(fs) & \llbracket pred \rrbracket fs = Pred(fs) \\
\llbracket cont \rrbracket : \llbracket loc \rrbracket \rightarrow D^{sto} \rightarrow D^{int} & \llbracket asgn \rrbracket : \llbracket loc \rrbracket \rightarrow \llbracket iexp \rrbracket \rightarrow D^{sto} \rightarrow D^{sto} \\
\llbracket cont \rrbracket = Cont & \llbracket asgn \rrbracket lfs = Asgn l(fs) s \\
\llbracket skip \rrbracket : D^{sto} \rightarrow D^{sto} & \\
\llbracket skip \rrbracket s = s & \\
\llbracket cond_{sto \Rightarrow \gamma} \rrbracket : \llbracket iexp \rrbracket \rightarrow \llbracket sto \Rightarrow \gamma \rrbracket \rightarrow \llbracket sto \Rightarrow \gamma \rrbracket \rightarrow D^{sto} \rightarrow D^\gamma & \\
\llbracket cond_{sto \Rightarrow \gamma} \rrbracket bfgs = Cond_\gamma(bs)(fs)(gs) & \\
\llbracket seq_{sto \Rightarrow \gamma} \rrbracket : \llbracket cmd \rrbracket \rightarrow \llbracket sto \Rightarrow \gamma \rrbracket \rightarrow D^{sto} \rightarrow D^\gamma & \\
\llbracket seq_{sto \Rightarrow \gamma} \rrbracket fgs = g(fs) &
\end{array}$$

$$\begin{aligned}
& \llbracket new_{iexp} \rrbracket : \llbracket loc \rightarrow iexp \rrbracket \rightarrow D^{sto} \rightarrow D^{int} \\
& \llbracket new_{iexp} \rrbracket fs = fl(Asgn\ l\ 0\ s) \quad \text{with } l = next(supp(f)) \\
& \llbracket new_{cmd} \rrbracket : \llbracket loc \rightarrow cmd \rrbracket \rightarrow D^{sto} \rightarrow D^{sto} \\
& \llbracket new_{cmd} \rrbracket fs = Asgn\ l\ (Cont\ l\ s)(fl(Asgn\ l\ 0\ s)) \quad \text{with } l = next(supp(f)) \\
& \llbracket Y_\sigma \rrbracket : \llbracket \sigma \rightarrow \sigma \rrbracket \rightarrow \llbracket \sigma \rrbracket \\
& \llbracket Y_\sigma \rrbracket = \mu_{\llbracket \sigma \rrbracket} \\
& \llbracket pcond \rrbracket : \llbracket iexp \rrbracket \rightarrow \llbracket iexp \rrbracket \rightarrow \llbracket iexp \rrbracket \rightarrow D^{sto} \rightarrow D^{int} \\
& \llbracket pcond \rrbracket bfg\ s = Pcond(bs)(fs)(gs)
\end{aligned}$$

Note that the fixed point operators $\mu_{\llbracket \sigma \rrbracket}$ are (well-defined) locally continuous Σ -homomorphisms by Theorem 4.6, hence $\llbracket Y_\sigma \rrbracket \in \llbracket (\sigma \rightarrow \sigma) \rightarrow \sigma \rrbracket_\emptyset$ for every procedure type σ . The meanings of the other constants are also well-defined, but it remains to be proved that they are ‘contained in the model’, i.e. that $\llbracket c \rrbracket \in \llbracket \tau \rrbracket$ for every constant c of type τ . The first step into this direction is to show that the particular choice of l in the clauses for $\llbracket new_{iexp} \rrbracket$ and $\llbracket new_{cmd} \rrbracket$ does not play a role, i.e. instead of $l = next(supp(f))$ we can use any arbitrary location $l \notin supp(f)$.

Proposition 5.4 *For every $l \in Loc \setminus supp(f)$ we have*

$$\begin{aligned}
\llbracket new_{iexp} \rrbracket fs &= fl(s[0/l]) \\
\llbracket new_{cmd} \rrbracket fs &= (fl(s[0/l]))[sl/l]
\end{aligned}$$

Proof: We only consider $\llbracket new_{cmd} \rrbracket$, the proof for $\llbracket new_{iexp} \rrbracket$ is similar. Let $L \in W$ be such that $f \in \llbracket loc \rightarrow cmd \rrbracket_L$, let $l_1, l_2 \in Loc \setminus L$ and let φ be the *transposition* of l_1 and l_2 , i.e. the permutation which only interchanges l_1 and l_2 . Then we obtain

$$\begin{aligned}
fl(s[0/l_1]) &=_{L \cup \{l_1\}} fl(s[0/l_1][0/l_2]) \\
&\quad \text{by Theorem 5.3 (iii), because } fl_1 \in \llbracket cmd \rrbracket_{L \cup \{l_1\}} \\
&= (fl_2(s[0/l_1][0/l_2])) \circ \varphi \\
&\quad \text{by Theorem 5.3 (v), because } \varphi = \varphi^{-1} \\
&=_L fl_2(s[0/l_1][0/l_2]) \\
&\quad \text{because } \varphi \in Fix(L) \\
&=_{L \cup \{l_2\}} fl_2(s[0/l_2]) \\
&\quad \text{by Theorem 5.3 (iii), because } fl_2 \in \llbracket cmd \rrbracket_{L \cup \{l_2\}}
\end{aligned}$$

This implies $(fl_1(s[0/l_1]))[sl_1/l_1] =_L (fl_2(s[0/l_2]))[sl_2/l_2]$ and if they are different from \perp , then they both coincide with s on $Loc \setminus L$ by Theorem 5.3 (iii), hence they are equal in any case.

Now let $l_1, l_2 \in Loc \setminus supp(f)$, say $l_1 = next(supp(f))$. Then there are $L_1, L_2 \in W$ with $f \in \llbracket loc \rightarrow cmd \rrbracket_{L_i}$ and $l_i \in Loc \setminus L_i$ for $i = 1, 2$, and by choosing some arbitrary $l \in Loc \setminus (L_1 \cup L_2)$ we obtain $\llbracket new_{cmd} \rrbracket fs = (fl_1(s[0/l_1]))[sl_1/l_1] = (fl(s[0/l]))[sl/l] = (fl_2(s[0/l_2]))[sl_2/l_2]$. \square

Proposition 5.4 captures the ‘operational intuition’ that the particular choice of the new location which we bind to a local variable does not play a role, and thus it already gives us some confidence into our denotational semantics. Indeed, Proposition 5.4 will be needed for the computational adequacy as well as for the full abstraction of our denotational model.

As to computational adequacy, note that there is a gap between the operational and the denotational definition of a ‘new’ location l . In the operational semantics we work with *marked* stores ms and we let $l = \text{next}(\text{dom}(ms))$ in rule (new-init), i.e. we choose l to be the ‘first location which is not marked as active’. In the denotational semantics we work with ordinary stores and we let $l = \text{next}(\text{supp}(f))$ where f corresponds to the body of the block in which the local variable is declared, i.e. we choose l to be the ‘first location to which the body of the block does not have access’. This gap can be closed if we know that the denotational definition is independent of l as long as $l \notin \text{supp}(f)$ and that $\text{supp}(f) \subseteq \text{dom}(ms)$, i.e. that the body of the block can only have access to locations which are marked as active.

While these considerations about computational adequacy are somewhat technical (and could perhaps be avoided by an alternative definition of the denotational semantics), the role of Proposition 5.4 for full abstraction is more significant. If the particular choice of l in the definition of $\llbracket \text{new}_\theta \rrbracket$ *did* play a role, then the meaning of a block with two local variables could depend on the order in which these local variables are declared. This means that certain observational congruences (e.g. Example 7.3) would not be provable in our denotational semantics and thus full abstraction would indeed fail.

We continue with a purely technical lemma.

Lemma 5.5 *Let $L \in W, k \in \mathbb{N}$ and let $f : \llbracket \tau_1 \rrbracket \rightarrow \dots \rightarrow \llbracket \tau_k \rrbracket \rightarrow D^{\text{sto}} \rightarrow D^\gamma$. If*

- (1) $f R^{\tau_1} \dots R^{\tau_k} R^{\text{sto}} \subseteq R^\gamma$ *for every $R \in \Sigma^L$ and*
- (2) $f d_1 \dots d_{j-1}$ *is continuous on $\llbracket \tau_j \rrbracket_{L'}$ for all $j \in \{1, \dots, k\}$, $(d_1, \dots, d_{j-1}) \in \llbracket \tau_1 \rrbracket \times \dots \times \llbracket \tau_{j-1} \rrbracket$ and $L' \in W$*

then $f \in \llbracket \tau_1 \rightarrow \dots \rightarrow \tau_k \rightarrow \text{sto} \Rightarrow \gamma \rrbracket_L$.

Proof: By induction on k .

$k = 0$:

If $f R^{\text{sto}} \subseteq R^\gamma$ for all $R \in \Sigma^L$, then $f \in \llbracket \text{sto} \Rightarrow \gamma \rrbracket_L$ per definition.

$k > 0$:

Assume that (1) and (2) hold for f . If $L' \in W, L \subseteq L'$ and $d_1 \in \llbracket \tau_1 \rrbracket_{L'}$, then we obtain for all $R \in \Sigma_n^{L'}$

$$f d_1 R^{\tau_2} \dots R^{\tau_k} R^{\text{sto}} \subseteq f (\delta^n \llbracket \tau_1 \rrbracket_{L'}) R^{\tau_2} \dots R^{\tau_k} R^{\text{sto}} \subseteq f R^{\tau_1} \dots R^{\tau_k} R^{\text{sto}} \subseteq R^\gamma$$

This means that (1) holds for $f d_1$ with L' instead of L , and of course (2) also holds for $f d_1$. Hence $f d_1 \in \llbracket \tau_2 \rightarrow \dots \rightarrow \tau_k \rightarrow \text{sto} \Rightarrow \gamma \rrbracket_{L'}$ by induction hypothesis,

i.e. we have proved $f(\llbracket \tau_1 \rrbracket_{L'}) \subseteq \llbracket \tau_2 \rightarrow \dots \rightarrow \tau_k \rightarrow sto \Rightarrow \gamma \rrbracket_{L'}$ for all $L' \supseteq L$ and thus also $f \llbracket \tau_1 \rrbracket \subseteq \llbracket \tau_2 \rightarrow \dots \rightarrow \tau_k \rightarrow sto \Rightarrow \gamma \rrbracket$. But then (1) means that $f R^{\tau_1} \subseteq R^{\tau_2 \rightarrow \dots \rightarrow \tau_k \rightarrow sto \Rightarrow \gamma}$ for every $R \in \Sigma^L$ and from (2) we know in particular that f itself is continuous on all $\llbracket \tau_1 \rrbracket_{L'}$. Hence $f \in \llbracket \tau_1 \rightarrow \dots \rightarrow \tau_k \rightarrow sto \Rightarrow \gamma \rrbracket_L$. \square

Now we are ready to prove

Proposition 5.6 *If c is a constant of procedure type σ , then $\llbracket c \rrbracket \in \llbracket \sigma \rrbracket_\emptyset$.*

Proof: We only consider two sample cases, namely $c \equiv \text{asgn}$ as a routine case and $c \equiv \text{new}_{cmd}$ as the most interesting case.

Case 1: $c \equiv \text{asgn}$

If $R \in \Sigma (= \Sigma^\emptyset)$, then $\llbracket \text{asgn} \rrbracket R^{loc} R^{iexp} R^{sto} \subseteq \text{Asgn } R^{loc} (R^{iexp} R^{sto}) R^{sto} \subseteq \text{Asgn } R^{loc} R^{int} R^{sto} \subseteq R^{sto}$. The function $\llbracket \text{asgn} \rrbracket$ itself is continuous and it is easy to see that $\llbracket \text{asgn} \rrbracket l$ is continuous on $\llbracket iexp \rrbracket_L$ for all $l \in D^{loc}$ and $L \in W$. Hence Lemma 5.5 implies $\llbracket \text{asgn} \rrbracket \in \llbracket loc \rightarrow iexp \rightarrow cmd \rrbracket_\emptyset$.

Case 2: $c \equiv \text{new}_{cmd}$

Let $R \in \Sigma$, $\vec{f} \in R^{loc \rightarrow cmd}$ and $\vec{s} \in R^{sto}$. Let $L \in W$ with $f_1, \dots, f_n \in \llbracket loc \rightarrow cmd \rrbracket_L$ and $l \in Loc \setminus L$ with $(l, \dots, l) \in R^{loc}$. Then, by Proposition 5.4,

$$\begin{aligned} \llbracket \text{new}_{cmd} \rrbracket \vec{f} \vec{s} &= \text{Asgn } l (\text{Cont } l \vec{s}) (\vec{f} l (\text{Asgn } l 0 \vec{s})) \\ &\in \text{Asgn } R^{loc} (\text{Cont } R^{loc} R^{sto}) (R^{loc \rightarrow cmd} R^{loc} (\text{Asgn } R^{loc} R^{int} R^{sto})) \\ &\subseteq \text{Asgn } R^{loc} R^{int} (R^{cmd} R^{sto}) \\ &\subseteq R^{sto} \end{aligned}$$

Now let $L' \in W$. By choosing some $l \in Loc \setminus L'$ we obtain by Proposition 5.4: $\llbracket \text{new}_{cmd} \rrbracket f = \lambda s \in Stores. \text{Asgn } l (\text{Cont } s l) (\vec{f} l (\text{Asgn } l 0 s))$ for all $f \in \llbracket loc \rightarrow cmd \rrbracket_{L'}$. This shows that $\llbracket \text{new}_{cmd} \rrbracket$ is continuous on $\llbracket loc \rightarrow cmd \rrbracket_L$ and hence $\llbracket \text{new}_{cmd} \rrbracket \in \llbracket (loc \rightarrow cmd) \rightarrow cmd \rrbracket_\emptyset$ by Lemma 5.5. \square

Theorem 4.5 and Proposition 5.6 allow us to define the meaning of ALG-terms in the style of the simply typed λ -calculus, more precisely: Let Env be the set of all *environments*, i.e. the set of all type preserving functions

$$\eta : \bigcup_{\tau \in Type} Id^\tau \rightarrow \bigcup_{\tau \in Type} \llbracket \tau \rrbracket$$

Then, for every $M \in \text{ALG}^\tau$, the *meaning* $\llbracket M \rrbracket : Env \rightarrow \llbracket \tau \rrbracket$ is inductively defined by

$$\begin{aligned} \llbracket c \rrbracket \eta &= \llbracket c \rrbracket \quad \text{as defined before} \\ \llbracket x \rrbracket \eta &= \eta x \\ \llbracket MN \rrbracket \eta &= (\llbracket M \rrbracket \eta) (\llbracket N \rrbracket \eta) \\ \llbracket \lambda x^\tau. M \rrbracket \eta &= \lambda d \in \llbracket \tau \rrbracket. \llbracket M \rrbracket \eta[d/x] \end{aligned}$$

As usual, $\llbracket M \rrbracket \eta$ only depends on the restriction of η to $free(M)$; in particular it is independent of η , if M is closed, and then we usually write $\llbracket M \rrbracket$ instead of $\llbracket M \rrbracket \eta$.

Proposition 5.7

- (i) If $M \in \text{ALG}_L^\tau$ and $\eta x^{\tau'} \in \llbracket \tau' \rrbracket_L$ for every $x^{\tau'} \in \text{free}(M)$, then $\llbracket M \rrbracket \eta \in \llbracket \tau \rrbracket_L$.
- (ii) If $M \in c\text{-ALG}_L^\tau$, then $\llbracket M \rrbracket \in \llbracket \tau \rrbracket_L$.

Part (ii) captures our intuition that a closed ALG-term has only access to those locations which explicitly occur in it and *not* to those which are temporarily bound to its local variables. An open term may (of course) also have access to the locations which are bound to its free variables and it may have ‘indirect’ access to additional locations via the functions which are bound to its free procedure identifiers.

Proof: Of course it is sufficient to prove (i). For location free terms we can apply general principles: For every constant c of procedure type σ the meaning $\llbracket c \rrbracket \in \llbracket \sigma \rrbracket_\emptyset$ can be considered as a morphism from the terminal object T to the object $\llbracket \sigma \rrbracket$, hence—by the categorical semantics of the λ -calculus [4]—the meaning of a term $M \in \text{ALG}_\emptyset^\tau$ with $\text{free}(M) = \{x_1^{\tau_1}, \dots, x_k^{\tau_k}\}$ is a morphism from $\llbracket \tau_1 \rrbracket \times \dots \times \llbracket \tau_k \rrbracket$ to $\llbracket \tau \rrbracket$, i.e. it maps $\llbracket \tau_1 \rrbracket_L \times \dots \times \llbracket \tau_k \rrbracket_L$ to $\llbracket \tau \rrbracket_L$. The generalization to terms *with* locations is straightforward. \square

We conclude this section by explicitly presenting the meaning of a block with a local variable declaration. Remember that **new x in M end** is syntactic sugar for $\text{new}_\theta(\lambda x^{\text{loc}}. M)$, if M is of type θ . Thus we obtain

$$\begin{aligned} \llbracket \text{new } x \text{ in } M \text{ end} \rrbracket \eta s &= \llbracket M \rrbracket \eta[l/x] s[0/l] && \text{if } M \in \text{ALG}^{\text{exp}} \\ \llbracket \text{new } x \text{ in } M \text{ end} \rrbracket \eta s &= (\llbracket M \rrbracket \eta[l/x] s[0/l]) [s l/l] && \text{if } M \in \text{ALG}^{\text{cmd}} \end{aligned}$$

where, by Proposition 5.4, l is an *arbitrary* location in $\text{Loc} \setminus \text{supp}(\llbracket \lambda x. M \rrbracket \eta)$. The possibility to choose l freely from an infinite set will be important in the following sections, because we will often need a location which is different from finitely many given ones. In such cases we sometimes briefly say that we choose a *new* location and leave it to the reader to spell out precisely what is meant by ‘new’ in a particular case.

6 Computational Adequacy

In this section we will show that our denotational semantics is *computationally adequate*. Computational adequacy means [12] that the observable behavior $\text{beh}(P)$ of a program P can be (easily) derived from its denotational meaning $\llbracket P \rrbracket$. Concretely, we will show that for every $n \in \mathbb{Z}$

$$n \in \text{beh}(P) \iff \llbracket P \rrbracket s_{\text{init}} = n$$

where s_{init} is the constant 0 store, i.e. the (unique) store in Stores_\emptyset . This implies that $\text{beh}(P)$ contains at most one element (as we know already from Theorem 3.2) and that $\text{beh}(P) = \emptyset \iff \llbracket P \rrbracket s_{\text{init}} = \perp$.

We begin with ‘ \Rightarrow ’ which is the easier direction. For a purely functional language, this direction is usually proved by showing that each transition step of the operational semantics preserves the denotational meaning of terms [4, 36]. This is also the main idea for our proof, but as our transition relation ‘ \rightarrow ’ works on configurations as opposed to terms, we will first extend our meaning function: For every marked store ms we define $\overline{ms} \in Stores$ by

$$\overline{ms} \ l = \begin{cases} ms \ l & \text{if } l \in \text{dom}(ms) \\ 0 & \text{otherwise} \end{cases}$$

and for every *consistent* configuration $K \in Conf_L^{sto \Rightarrow \gamma}$ we define its *meaning* $\llbracket K \rrbracket \in D^\gamma$ inductively by

- $\llbracket (M, ms) \rrbracket = \llbracket M \rrbracket \overline{ms}$
- $\llbracket succ \ K \rrbracket = Succ \ \llbracket K \rrbracket$
- $\llbracket pred \ K \rrbracket = Pred \ \llbracket K \rrbracket$
- $\llbracket (asgn \ l \ K, ms) \rrbracket = Asgn \ l \ \llbracket K \rrbracket \ \overline{ms}$
- $\llbracket (cond_{sto \Rightarrow \gamma} \ KMN, ms) \rrbracket = Cond_\gamma \ \llbracket K \rrbracket \ (\llbracket M \rrbracket \ \overline{ms}) \ (\llbracket N \rrbracket \ \overline{ms})$
- $\llbracket seq_\theta \ KM \rrbracket = \llbracket M \rrbracket \ \llbracket K \rrbracket$
- $\llbracket dealloc_{iecp} \ l \ K \rrbracket = \llbracket K \rrbracket$
- $\llbracket dealloc_{cmd} \ l \ K \rrbracket = Asgn \ l \ 0 \ \llbracket K \rrbracket$
- $\llbracket pcond \ K_1 K_2 K_3 \rrbracket = Pcond \ \llbracket K_1 \rrbracket \ \llbracket K_2 \rrbracket \ \llbracket K_3 \rrbracket$

Lemma 6.1 *Every transition step is meaning-preserving, i.e.*

- (i) $M \rightarrow M'$ implies $\llbracket M \rrbracket = \llbracket M' \rrbracket$ for closed terms M, M'
- (ii) $K \rightarrow K'$ implies $\llbracket K \rrbracket = \llbracket K' \rrbracket$ for consistent configurations K, K'

Proof: (i) is obvious; (ii) is proved by induction on the derivation of $K \rightarrow K'$. We consider a few sample cases in which locations play a role.

Case 1: $K \equiv (asgn \ l \ (n, ms'), ms) \rightarrow K' \equiv (skip, ms[n/l])$ by rule (asgn-exec)

Then $\llbracket K \rrbracket = Asgn \ l \ \llbracket (n, ms') \rrbracket \ \overline{ms} = \overline{ms}[n/l] = \overline{ms[n/l]} = \llbracket skip \rrbracket \ \overline{ms[n/l]} = \llbracket K' \rrbracket$

Case 2: $K \equiv (new_{cmd} \ M, ms) \rightarrow K' \equiv dealloc_{cmd} \ l \ (Ml, ms[0/l])$ by rule (new-init)

Let $K \in Conf_L^{cmd}$. Then $M \in c\text{-ALG}_L^{loc \rightarrow cmd}$, $\text{dom}(ms) = L$ and $l = \text{next}(\text{dom}(ms))$,

hence $l \notin L \supseteq \text{supp}(\llbracket M \rrbracket)$ and thus we obtain

$$\begin{aligned}
\llbracket K \rrbracket &= \llbracket \text{new}_{cmd} M \rrbracket \overline{ms} \\
&= \text{Asgn } l \ (Cont \ l \ \overline{ms}) \ (\llbracket M \rrbracket \ l \ (\text{Asgn } l \ 0 \ \overline{ms})) \\
&= \text{Asgn } l \ 0 \ (\llbracket Ml \rrbracket \ (\overline{ms}[0/l])) \\
&= \text{Asgn } l \ 0 \ (\llbracket Ml \rrbracket \ (\overline{ms}[0/l])) \\
&= \text{Asgn } l \ 0 \ (\llbracket (Ml, ms[0/l]) \rrbracket) \\
&= \llbracket K' \rrbracket
\end{aligned}$$

Case 3: $K \equiv \text{dealloc}_{cmd} \ l \ (skip, ms) \rightarrow K' \equiv (skip, ms \setminus l)$ by rule (new-finish)

Then $\llbracket K \rrbracket = \text{Asgn } l \ 0 \ (\llbracket (skip, ms) \rrbracket) = \overline{ms}[0/l] = \overline{ms} \setminus l = \llbracket skip \rrbracket \overline{ms} \setminus l = \llbracket K' \rrbracket \quad \square$

Lemma 6.1 will deliver the ‘ \Rightarrow ’-part of computational adequacy. The usual approach for proving the ‘ \Leftarrow ’-part [36] is to define a relation $\leq^\tau \subseteq \llbracket \tau \rrbracket \times c\text{-ALG}^\tau$ for every type τ such that

- $(\leq^\tau)_{\tau \in \text{Type}}$ is a logical relation between applicative structures [17]
- $\llbracket M \rrbracket \leq^\tau M$ for every $M \in c\text{-ALG}^\tau$

In our setting it is more natural to define a relation $\leq_L^\tau \subseteq \llbracket \tau \rrbracket_L \times c\text{-ALG}_L^\tau$ for every type τ and every $L \in W$ such that

- $(\leq^\tau)_{\tau \in \text{Type}, L \in W}$ is a *Kripke* logical relation between applicative structures [17]
- $\llbracket M \rrbracket \leq_L^\tau M$ for every $M \in c\text{-ALG}_L^\tau$

The relations \leq_L^τ are defined by induction on τ as follows

$$\begin{aligned}
l &\leq_L^{loc} l' \Leftrightarrow l = l' \\
f &\leq_L^{exp} M \Leftrightarrow \forall L' \supseteq L, s \in \text{Stores}, n \in \mathbb{Z}. fs = n \Rightarrow \exists ms. (M, s \mid L') \xrightarrow{*} (n, ms) \\
f &\leq_L^{cmd} M \Leftrightarrow \forall L' \supseteq L, s, s' \in \text{Stores}. fs = s' \Rightarrow (M, s \mid L') \xrightarrow{*} (skip, s' \mid L') \\
f &\leq_L^{\tau \rightarrow \sigma} M \Leftrightarrow \forall L' \supseteq L, d \in \llbracket \tau \rrbracket_{L'}, P \in c\text{-ALG}_{L'}^\tau. d \leq_{L'}^\tau P \Rightarrow fd \leq_{L'}^\sigma MP
\end{aligned}$$

Lemma 6.2 *Let σ be a procedure type, let $L \in W$, $f, g \in \llbracket \sigma \rrbracket_L$, $\Delta \subseteq \llbracket \sigma \rrbracket_L$ directed and $M, N \in c\text{-ALG}_L^\sigma$. Then*

- (i) $\perp_\sigma \leq_L^\sigma M$
- (ii) $f \sqsubseteq g \wedge g \leq_L^\sigma M \Rightarrow f \leq_L^\sigma M$
- (iii) $(\forall f \in \Delta. f \leq_L^\sigma M) \Rightarrow \bigsqcup \Delta \leq_L^\sigma M$
- (iv) $M \rightarrow N \wedge f \leq_L^\sigma N \Rightarrow f \leq_L^\sigma M$

Proof: All the proofs are simple inductions on σ .

- (i) holds vacuously for ground types, and the induction step is obvious.

- (ii) For $\sigma = iexp$ note that $f \sqsubseteq g \wedge fs = n$ implies $gs = n$; similarly for $\sigma = cmd$. For $\sigma = (\tau \rightarrow \sigma')$ note that $f \sqsubseteq g \wedge gd \leq_{L'}^{\sigma'} MP$ implies $fd \leq_{L'}^{\sigma'} MP$ by induction hypothesis.
- (iii) For $\sigma = iexp$ note that $(\sqcup \Delta)s = n$ implies $fs = n$ for some $f \in \Delta$; similarly for $\sigma = cmd$. For $\sigma = (\tau \rightarrow \sigma')$ note that $(\forall f \in \Delta. fd \leq_{L'}^{\sigma'} MP)$ implies $(\sqcup \Delta)d = \sqcup \Delta d \leq_{L'}^{\sigma'} MP$ by induction hypothesis.
- (iv) For $\sigma = iexp$ note that $M \rightarrow N \wedge (N, s | L') \xrightarrow{*} (n, ms)$ implies $(M, s | L') \rightarrow (N, s | L') \xrightarrow{*} (n, ms)$; similarly for $\sigma = cmd$. For $\sigma = (\tau \rightarrow \sigma')$ note that $M \rightarrow N \wedge fd \leq_{L'}^{\sigma'} NP$ implies $fd \leq_{L'}^{\sigma'} MP$ by induction hypothesis (because $MP \rightarrow NP$). \square

Lemma 6.3 $M \in c\text{-ALG}_L^\tau \Rightarrow \llbracket M \rrbracket \leq_L^\tau M$

Proof: As usual [36] this assertion is first generalized to open terms:

Let $M \in \text{ALG}_L^\tau$ with $\text{free}(M) \subseteq \{x_1^{\tau_1}, \dots, x_k^{\tau_k}\}$ and let $d_i \in \llbracket \tau_i \rrbracket_L$, $N_i \in c\text{-ALG}_L^{\tau_i}$ with $d_i \leq_L^{\tau_i} N_i$ ($i = 1, \dots, k$). Then $\llbracket M \rrbracket \eta[\bar{d}/\bar{x}] \leq_L^\tau M[\bar{x} := \bar{N}]$ for every $\eta \in \text{Env}$.

This generalized assertion is proved by induction on the structure of M .

Case 1: M constant of type loc

Then $M \equiv l \in L$ and $\llbracket M \rrbracket \eta[\bar{d}/\bar{x}] = l \leq_L^{loc} l \equiv M[\bar{x}/\bar{N}]$.

Case 2: M constant of procedure type σ

It must be proved that $\llbracket M \rrbracket \leq_L^\sigma M$ for *all* $L \in W$. To this end it is sufficient to prove $\llbracket M \rrbracket \leq_\emptyset^\sigma M$, because \leq_\emptyset^σ is the strongest relation among all \leq_L^σ . We consider a few sample cases.

- (i) $M \equiv cont : loc \rightarrow iexp$

Let $L \in W$, $d \in \llbracket loc \rrbracket_L$ and $l \in c\text{-ALG}_L^{loc} = L$ with $d \leq_L^{loc} l$. Then $d = l$, hence we must prove $\llbracket cont \rrbracket l \leq_L^{iexp} cont l$. Let $L' \supseteq L$, $s \in \text{Stores}$ and $n \in \mathbb{Z}$ with $\llbracket cont \rrbracket l s = n$. Then $sl = n$, and as $l \in L'$ we obtain $(cont l, s | L') \rightarrow (n, s | L')$.

- (ii) $M \equiv asgn : loc \rightarrow iexp \rightarrow cmd$

Let L, d and l be as in (i). Further let $L' \supseteq L$, $f \in \llbracket iexp \rrbracket_{L'}$ and $N \in c\text{-ALG}_{L'}^{iexp}$ with $f \leq_{L'}^{iexp} N$. Then we must prove $\llbracket asgn \rrbracket l f \leq_{L'}^{cmd} asgn l N$. Let $L'' \supseteq L'$ and $s, s' \in \text{Stores}$ with $\llbracket asgn \rrbracket l fs = s'$. Then there is some $n \in \mathbb{Z}$ with $fs = n$ and $s' = s[n/l]$, and as $f \leq_{L'}^{iexp} N$ we know that $(N, s | L'') \xrightarrow{*} (n, ms)$ for some marked store ms . As $l \in L''$, this finally implies $(asgn l N, s | L'') \rightarrow (asgn l (N, s | L''), s | L'') \xrightarrow{*} (asgn l (n, ms), s | L'') \rightarrow (skip, s' | L'')$.

(iii) $M \equiv \text{new}_{cmd} : (loc \rightarrow cmd) \rightarrow cmd$

Let $L \in W$, $f \in \llbracket loc \rightarrow cmd \rrbracket_L$ and $N \in c\text{-ALG}_L^{loc \rightarrow cmd}$ with $f \leq_L^{loc \rightarrow cmd} N$. We must prove $\llbracket \text{new}_{cmd} \rrbracket f \leq_L^{cmd} \text{new}_{cmd} N$. Let $L' \supseteq L$ and $s, s' \in \text{Stores}$ with $\llbracket \text{new}_{cmd} \rrbracket fs = s'$. Let $l = \text{next}(L')$, hence $l \notin L' \supseteq L \supseteq \text{supp}(f)$. Then there is some $s'' \in \text{Stores}$ with $fl(s[0/l]) = s''$ and $s' = s''[sl/l]$. As $fl \leq_{L \cup \{l\}}^{cmd} Nl$, we know that $(Nl, s[0/l] \mid L' \cup \{l\}) \xrightarrow{*} (\text{skip}, s'' \mid L' \cup \{l\})$ and from this we obtain $(\text{new}_{cmd} N, s \mid L') \rightarrow \text{dealloc}_{cmd} l (Nl, (s \mid L') [0/l]) \equiv \text{dealloc}_{cmd} l (Nl, s[0/l] \mid L' \cup \{l\}) \xrightarrow{*} \text{dealloc}_{cmd} (\text{skip}, s'' \mid L' \cup \{l\}) \rightarrow (\text{skip}, s'' \mid L') \equiv (\text{skip}, s' \mid L')$.

(iv) $M \equiv Y_\sigma : (\sigma \rightarrow \sigma) \rightarrow \sigma$

Let $L \in W$, $f \in \llbracket \sigma \rightarrow \sigma \rrbracket_L$ and $N \in c\text{-ALG}_L^{\sigma \rightarrow \sigma}$ with $f \leq_L^{\sigma \rightarrow \sigma} N$. We first prove by induction on n that $f^n \perp_\sigma \leq_L^\sigma Y_\sigma N$.

$n = 0$: $f^0 \perp = \perp \leq_L^\sigma Y_\sigma N$ holds by Lemma 6.2 (i).

$n > 0$: Let $f^{n-1} \perp \leq_L^\sigma Y_\sigma N$. Then $f^n \perp = f(f^{n-1} \perp) \leq_L^\sigma N(Y_\sigma N)$ because $f \leq_L^{\sigma \rightarrow \sigma} N$, and from this we obtain $f^n \perp \leq_L^\sigma Y_\sigma N$ by Lemma 6.2 (iv), because $Y_\sigma N \rightarrow_\triangleright N(Y_\sigma N)$.

Now $\Delta = \{f^n \perp \mid n \in \mathbb{N}\}$ is a directed set in $\llbracket \sigma \rrbracket_L$, and thus we finally obtain $\llbracket Y_\sigma \rrbracket f = \bigsqcup \Delta \leq_L^\sigma Y_\sigma N$ by Lemma 6.2 (iii).

Case 3: $M \equiv x_i^{\tau_i}$ for some $i \in \{1, \dots, k\}$

Then $\llbracket M \rrbracket \eta[\bar{d}/\bar{x}] = d_i \leq_L^{\tau_i} N_i \equiv M[\bar{x} := \bar{N}]$.

Case 4: $M \equiv PQ$ with $P \in \text{ALG}_L^{\tau \rightarrow \sigma}$ and $Q \in \text{ALG}_L^\tau$

As $\text{free}(P), \text{free}(Q) \subseteq \{x_1^{\tau_1}, \dots, x_k^{\tau_k}\}$ we have $\llbracket P \rrbracket \eta[\bar{d}/\bar{x}] \leq_L^{\tau \rightarrow \sigma} P[\bar{x} := \bar{N}]$ and $\llbracket Q \rrbracket \eta[\bar{d}/\bar{x}] \leq_L^\tau Q[\bar{x} := \bar{N}]$, hence also $\llbracket M \rrbracket \eta[\bar{d}/\bar{x}] = (\llbracket P \rrbracket \eta[\bar{d}/\bar{x}]) (\llbracket Q \rrbracket \eta[\bar{d}/\bar{x}]) \leq_L^\sigma P[\bar{x} := \bar{N}] (Q[\bar{x} := \bar{N}]) \equiv M[\bar{x} := \bar{N}]$ per definition of $\leq_L^{\tau \rightarrow \sigma}$.

Case 5: $M \equiv \lambda y^\tau. P$ with $P \in \text{ALG}_L^\sigma$

Without loss of generality we may assume that $y^\tau \notin \{x_1^{\tau_1}, \dots, x_k^{\tau_k}\}$. We must prove $\llbracket M \rrbracket \eta[\bar{d}/\bar{x}] \leq_L^{\tau \rightarrow \sigma} M[\bar{x} := \bar{N}]$. Hence let $L' \supseteq L$, $e \in \llbracket \tau \rrbracket_{L'}$ and $Q \in c\text{-ALG}_{L'}^\tau$ with $e \leq_{L'}^\tau Q$. Then $\llbracket M \rrbracket \eta[\bar{d}/\bar{x}] e = \llbracket P \rrbracket \eta[\bar{d}, e/\bar{x}, y]$ and $M[\bar{x} := \bar{N}] Q \equiv (\lambda y. P[\bar{x} := \bar{N}]) Q \rightarrow_\triangleright P[\bar{x}, y := \bar{N}, Q]$. As $P \in \text{ALG}_{L'}^\sigma$ and $\text{free}(P) \subseteq \{x_1^{\tau_1}, \dots, x_k^{\tau_k}, y^\tau\}$, we obtain $\llbracket P \rrbracket \eta[\bar{d}, e/\bar{x}, y] \leq_{L'}^\sigma P[\bar{x}, y := \bar{N}, Q]$ by induction hypothesis, and this finally implies $\llbracket M \rrbracket \eta[\bar{d}/\bar{x}] e \leq_{L'}^\sigma M[\bar{x} := \bar{N}] Q$ by Lemma 6.2 (iv). \square

Theorem 6.4 (computational adequacy) *For every program P and every $n \in \mathbb{Z}$*

$$n \in \text{beh}(P) \Leftrightarrow \llbracket P \rrbracket s_{\text{init}} = n$$

Proof:

$$\begin{aligned}
\text{'}\Rightarrow\text{'}: \quad n \in \text{beh}(P) &\Rightarrow (P, ms_{init}) \xrightarrow{*} (n, ms_{init}) && \text{per definition of } \text{beh}(P) \\
&\Rightarrow \llbracket (P, ms_{init}) \rrbracket = \llbracket (n, ms_{init}) \rrbracket && \text{by Lemma 6.1} \\
&\Rightarrow \llbracket P \rrbracket s_{init} = \llbracket n \rrbracket s_{init} && \text{because } \overline{ms_{init}} = s_{init} \\
&\Rightarrow \llbracket P \rrbracket s_{init} = n
\end{aligned}$$

‘ \Leftarrow ’: By Lemma 6.3 we have $\llbracket P \rrbracket \leq_{\emptyset}^{exp} P$, hence

$$\begin{aligned}
\llbracket P \rrbracket s_{init} = n &\Rightarrow \exists ms. (P, ms_{init}) \xrightarrow{*} (n, ms) && \text{because } ms_{init} = s_{init} \mid \emptyset \\
&\Rightarrow (P, ms_{init}) \xrightarrow{*} (n, ms_{init}) && \text{by Theorem 3.2 (ii)} \\
&\Rightarrow n \in \text{beh}(P)
\end{aligned}$$

□

7 Observational Congruences

In this section we will illustrate by a series of examples how to prove particular observational congruences with the aid of our denotational semantics. Most of the examples have already appeared in the literature [13, 8, 21], some of them originally served as *counter*-examples for earlier denotational models of ALGOL-like languages, i.e. they were used to prove that these models are *not* fully abstract [13, 8].

We will no longer slavishly stick to the ALG-syntax, but freely use operators like $+$, $-$, $*$, **div**, *abs*, $=$, \geq , \neg , \wedge , \vee , \dots with their standard interpretation, in particular each of them is assumed to be *strict* in all its arguments. These operators are of course definable by closed ALG-terms.

The intuitive idea behind all our examples is that a global procedure cannot have access to a local variable. The corresponding formal argumentation in the denotational model works as follows: If f is the function which is bound to a global procedure identifier y^σ , then there is some $L \in W$ such that $f \in \llbracket \sigma \rrbracket_L$ and we may assume that all locations l_1, \dots, l_n which are bound to the local variables are *not* contained in L . The desired semantic equality then usually follows by applying Theorem 5.3 (in the case of a first order procedure) or by choosing some appropriate $\{l_1, \dots, l_n\}$ -definable ground relation R and exploiting the fact that f preserves (the logical relation induced by) R .

Example 7.1 $\llbracket \text{new } x \text{ in } M \text{ end}; y^\sigma \rrbracket = \llbracket \text{new } x \text{ in } M; y^\sigma \text{ end} \rrbracket$

Proof: Let $\eta \in Env$, $s \in Stores$ and $L \in W$ with $\eta y \in \llbracket \sigma \rrbracket_L$. If $\sigma = cmd$, then

$$\begin{aligned}
\llbracket \text{new } x \text{ in } M \text{ end}; y \rrbracket \eta s &= \eta y (\llbracket M \rrbracket \eta[l/x] (s[0/l]) [s l/l]) \\
&\quad \text{for some new location } l \notin L \\
&= (\eta y (\llbracket M \rrbracket \eta[l/x] (s[0/l]))) [s l/l] \\
&\quad \text{by Theorem 5.3 (iii')} \\
&= (\llbracket M; y \rrbracket \eta[l/x] (s[0/l])) [s l/l] \\
&= \llbracket \text{new } x \text{ in } M; y \text{ end} \rrbracket \eta s
\end{aligned}$$

The proof for $\sigma = iexp$ is similar and the generalization to arbitrary procedure types σ is a routine calculation in the λ -calculus (remember that sequencing and *new*-operators for higher types have been introduced as syntactic sugar). \square

The intuition for Example 7.1 is that the global procedure y cannot read on the local variable x , hence it does not matter whether y is inside or outside the scope of the local variable. As an immediate consequence of Example 7.1 we obtain

$$\llbracket \text{new } x \text{ in } x := n; y \text{ end} \rrbracket = \llbracket \text{new } x \text{ in } x := n \text{ end}; y \rrbracket = \llbracket \text{skip}; y \rrbracket = \llbracket y \rrbracket$$

which is essentially Example 1 in [13].

Example 7.2 $\llbracket y^{cmd}; \text{new } x \text{ in } M \text{ end} \rrbracket = \llbracket \text{new } x \text{ in } y^{cmd}; M \text{ end} \rrbracket$

Proof: We only consider the case $M \in \text{ALG}^{cmd}$. Let $\eta \in Env$, $s \in Stores$ and $L \in W$ with $\eta y \in \llbracket cmd \rrbracket_L$. Then

$$\begin{aligned} \llbracket y; \text{new } x \text{ in } M \text{ end} \rrbracket \eta s &= \llbracket \text{new } x \text{ in } M \text{ end} \rrbracket \eta (\eta y s) \\ &= (\llbracket M \rrbracket \eta[l/x] ((\eta y s) [0/l]) [\eta y s l/l]) \\ &\quad \text{for some new location } l \notin L \\ &= (\llbracket M \rrbracket \eta[l/x] (\eta y (s [0/l]))) [s l/l] \\ &\quad \text{by Theorem 5.3 (iii) and (iii')} \\ &= (\llbracket y; M \rrbracket \eta[l/x] (s [0/l])) [s l/l] \\ &= \llbracket \text{new } x \text{ in } y; M \text{ end} \rrbracket \eta s \end{aligned}$$

\square The intuition for Example 7.2 is that the global procedure y can

neither read nor write on the local variable x , hence moving the procedure call of y into the scope of the local variable has no influence on the computation of y or M . As an immediate consequence of Example 7.2 we obtain

$$\llbracket \text{new } x \text{ in } y; \text{if } !x = 0 \text{ then } \Omega \text{ end} \rrbracket = \llbracket y; \text{new } x \text{ in if } !x = 0 \text{ then } \Omega \text{ end} \rrbracket = \llbracket \Omega \rrbracket$$

which is essentially Example 2 in [13].

Example 7.3 $\llbracket \text{new } x, x' \text{ in } M \text{ end} \rrbracket = \llbracket \text{new } x', x \text{ in } M \text{ end} \rrbracket$

Proof: For $M \in \text{ALG}^{cmd}$ we obtain

$$\begin{aligned} \llbracket \text{new } x, x' \text{ in } M \text{ end} \rrbracket \eta s &= \llbracket M \rrbracket \eta[l/x][l'/x'] (s [0/l][0/l']) [s l/l][s l'/l'] \\ &\quad \text{where } l, l' \in Loc \setminus \text{supp}(\llbracket \lambda x. M \rrbracket \eta) \text{ and } l \neq l' \\ &= \llbracket \text{new } x', x \text{ in } M \text{ end} \rrbracket \eta s \end{aligned}$$

and similarly for $M \in \text{ALG}^{iexp}$. The generalization to $M \in \text{ALG}^\sigma$ is routine. \square

Example 7.3 is a generalization of Example 3 in [13]. Note that it is *not* an α -conversion, because we do not rename x and x' inside the block body M . The crucial point is, that it does not matter which location we bind to the first local variable and which to the second.

Example 7.4 $\llbracket \text{new } x \text{ in } y^{cmd \rightarrow cmd}(x := !x + 1); \text{ if } !x \geq 0 \text{ then } \Omega \text{ end} \rrbracket = \llbracket \Omega \rrbracket$

Proof: Let $\eta \in Env$, $s \in Stores$ and $L \in W$ with $\eta y \in \llbracket cmd \rightarrow cmd \rrbracket_L$. We may assume that the location l which is bound to the local variable x is not contained in L . If we now choose $R \in DEF_1^{\{l\}}$ with $R^{sto} = \{\perp\} \cup \{t \in Stores \mid tl \geq 0\}$, then we have $s[0/l] \in R^{sto}$ and $\llbracket x := !x + 1 \rrbracket \eta[l/x] \in R^{cmd}$. Hence the store $t = \llbracket y(x := !x + 1) \rrbracket \eta[l/x](s[0/l])$ is contained in $\eta y R^{cmd} R^{sto} \subseteq R^{sto}$, i.e. $t = \perp$ or $tl \geq 0$, and this easily implies the desired equality. \square

Example 7.4 is similar to Example 4 in [13]. It illustrates “a form of *representational abstraction*, which is one of the main themes of modern programming methodology” [21], in particular of object oriented programming: The local variable x may be considered as the *instance variable* of a *counter object* which is initially set to 0 and which can only be accessed through a single *method*, namely through the parameterless procedure⁵ $x := !x + 1$. Although we do not know how often this method is used by the *client* y , we can be sure that the *representation invariant* $!x \geq 0$ of the counter object will be preserved, and this finally implies that the whole block must diverge.

Example 7.5 For $i = 1, 2$ let

$$M_i \equiv \text{new } x \text{ in } y^{cmd \rightarrow iexp \rightarrow iexp}(x := !x + i) (!x \text{ div } i) \text{ end}$$

Then $\llbracket M_1 \rrbracket = \llbracket M_2 \rrbracket$.

Proof: Let $\eta \in Env$, $s \in Stores$ and $L \in W$ with $\eta y \in \llbracket cmd \rightarrow iexp \rightarrow iexp \rrbracket_L$. Again we may assume that the new location l is not contained in L . We choose $R \in DEF_2^{\{l\}}$ with $R^{sto} = \{\perp\}^2 \cup \{\vec{s} \in Stores^2 \mid s_2 l = 2 * s_1 l \wedge s_1 =_{Loc \setminus \{l\}} s_2\}$. Then we have $(s[0/l], s[0/l]) \in R^{sto}$, $(\llbracket x := !x + 1 \rrbracket \eta[l/x], \llbracket x := !x + 2 \rrbracket \eta[l/x]) \in R^{cmd}$ and $(\llbracket !x \text{ div } 1 \rrbracket \eta[l/x], \llbracket !x \text{ div } 2 \rrbracket \eta[l/x]) \in R^{iexp}$. Hence the pair (d_1, d_2) with $d_i = \llbracket y(x := !x + i) (!x \text{ div } i) \rrbracket \eta[l/x](s[0/l])$ is contained in $\eta y R^{cmd} R^{iexp} R^{sto} \subseteq R^{int} = \delta^2 D^{int}$, i.e. $d_1 = d_2$, and this proves the equality. \square

Example 7.5 is a variant of Example 7 in [13]. It shows that “there is more to representational abstraction than preservation of invariants” [21]. Again, the local variable x may be considered as the instance variable of a counter object, which now has two methods, namely one which increases the counter and one which reads the counter. M_1 and M_2 use two different internal representations of such a counter object, and the observational congruence between M_1 and M_2 shows that the client y cannot distinguish between these different internal representations. This is an instance of *representation independence* [21, 16].

Example 7.6 $\llbracket \text{new } x \text{ in } x := 1; y^{iexp \rightarrow iexp}(!x) \text{ end} \rrbracket = \llbracket y^{iexp \rightarrow iexp} 1 \rrbracket$

⁵Note that ALG is a full fledged call-by-name λ -calculus, hence—in contrast to ALGOL 60—there is no need to introduce a name for the procedure $x := !x + 1$ and—in contrast to the call-by-value language ML—there is no need to explicitly delay evaluation of $x := !x + 1$ with the aid of a λ -abstraction.

Proof: Let $\eta \in Env$, $s \in Stores$ and let L and l as usual. Let $R \in DEF_2^{\{l\}}$ be defined by $R^{sto} = \{\perp\}^2 \cup \{\vec{s} \in Stores^2 \mid s_1 l = 1 \wedge s_1 =_{Loc \setminus \{l\}} s_2\}$. Then $(s [1/l], s) \in R^{sto}$ and $(\llbracket !x \rrbracket \eta [l/x], \llbracket 1 \rrbracket \eta) \in R^{iexp}$. Hence the pair $(d_1, d_2) = (\llbracket y (!x) \rrbracket \eta [l/x] (s [1/l]), \llbracket y 1 \rrbracket \eta s)$ is contained in $\eta y R^{iexp} R^{sto} \in R^{int} = \delta^2 D^{int}$, i.e. $d_1 = d_2$ and this easily implies the equality. \square

Example 7.6 was presented in [8]. Note that the simpler term $(x := 1; y (!x))$ is *not* observationally congruent to $y 1$, because $!x$ is a name parameter and the function procedure y may have a temporary side effect on the global variable x before it uses its parameter. Hence it is indeed necessary for the example that x is a *local* variable.

Example 7.7 $\llbracket y^{\sigma \rightarrow cmd} z^\sigma \rrbracket = \llbracket \text{new } x \text{ in } y(x := !x + 1; z) \text{ end} \rrbracket$

Proof: We only consider $\sigma = cmd$. Let $\eta \in Env$, $s \in Stores$ and $L \in W$ with $\eta y \in \llbracket cmd \rightarrow cmd \rrbracket_L$ and $\eta z \in \llbracket cmd \rrbracket_L$, and let $l \in Loc \setminus L$. We choose $R \in DEF_2^{\{l\}}$ with $R^{sto} = \{\perp\}^2 \cup \{\vec{s} \in Stores^2 \mid s_1 =_{Loc \setminus \{l\}} s_2\}$. Then we obtain $(s, s [0/l]) \in R^{sto}$ and $(\eta z, \llbracket x := !x + 1; z \rrbracket \eta [l/x]) \in R^{cmd}$, because $s_1 =_{Loc \setminus \{l\}} s_2$ implies $\eta z s_1 =_{Loc \setminus \{l\}} \eta z s_2 =_{Loc \setminus \{l\}} \llbracket x := !x + 1; z \rrbracket \eta [l/x] s_2$ by Theorem 5.3 (iii'). Hence the pair $(t_1, t_2) = (\llbracket y z \rrbracket \eta s, \llbracket y(x := !x + 1; z) \rrbracket \eta [l/x] (s [0/l]))$ is contained in $\eta y R^{cmd} R^{sto} \subseteq R^{cmd} R^{sto} \subseteq R^{sto}$, i.e. $t_1 =_{Loc \setminus \{l\}} t_2$. This implies $t_1 = t_2[s l/l]$ because $t_1 l = s l$ by Theorem 5.3 (iii), and thus the equality is proved. \square

The intuition for Example 7.7 is that the local variable x counts the procedure calls of z during the computation of $y z$ (occasionally the counter may snap back, namely when z is called inside an integer expression). The equivalence shows that adding such a counter has no influence on the procedure call $y z$. Example 7.7 will play a role in the full abstraction proof.

8 First and Second Order Domains

As a preparation for the full abstraction proof in Section 9 we will now prove some further properties of our denotational semantics, in particular we will take a closer look at types of order ≤ 2 . The following theorem presents an alternative description of the domains $\llbracket \sigma \rrbracket_L$ with $ord(\sigma) = 1$. This description is more concrete than the original one in that it does no longer refer to the signature Σ .

Theorem 8.1 (concrete description of the first order domains) *Let $L \in W$. Then*

- (i) $\llbracket iexp \rrbracket_L = \{f: D^{sto} \rightarrow D^{int} \mid f \perp = \perp \wedge \forall s, s' \in Stores. s =_L s' \Rightarrow fs = fs'\}$
- (ii) $\llbracket cmd \rrbracket_L = \{f: D^{sto} \rightarrow D^{sto} \mid f \perp = \perp$
 $\wedge \forall s \in Stores. fs \neq \perp \Rightarrow fs =_{Loc \setminus L} s$
 $\wedge \forall s, s' \in Stores. s =_L s' \Rightarrow fs =_L fs'\}$

- (iii) $\llbracket loc^m \rightarrow iexp \rrbracket_L = \{ f: Loc \rightarrow \dots \rightarrow Loc \rightarrow \llbracket iexp \rrbracket \mid$
 $\forall l_1, \dots, l_m \in Loc, s \in Stores, \varphi \in Fix(L).$
 $fl_1 \dots l_m \in \llbracket iexp \rrbracket_{L \cup \{l_1, \dots, l_m\}}$
 $\wedge f(\varphi l_1) \dots (\varphi l_m) s = fl_1 \dots l_m (s \circ \varphi) \}$
- (iv) $\llbracket loc^m \rightarrow cmd \rrbracket_L = \{ f: Loc \rightarrow \dots \rightarrow Loc \rightarrow \llbracket cmd \rrbracket \mid$
 $\forall l_1, \dots, l_m \in Loc, s \in Stores, \varphi \in Fix(L).$
 $fl_1 \dots l_m \in \llbracket cmd \rrbracket_{L \cup \{l_1, \dots, l_m\}}$
 $\wedge f(\varphi l_1) \dots (\varphi l_m) s = (fl_1 \dots l_m (s \circ \varphi)) \circ \varphi^{-1} \}$

Proof: In each case only ‘ \supseteq ’ must be proved, because ‘ \subseteq ’ already follows from Theorem 5.3. We consider (ii) and (iv), the proofs for (i) and (iii) are similar.

(ii) Let f be in the set on the right hand side. Per definition of $\llbracket cmd \rrbracket_L$ we must only show that f preserves all $R \in \Sigma^L$. Hence let $R \in \Sigma_n^L$ and $\vec{s} \in R^{sto}$. Because of the first and third condition for f there is some $M \in c\text{-ALG}_L^{cmd}$ (consisting of tests and assignments over location constants in L) such that $s =_L s_i$ implies $\llbracket M \rrbracket s =_L f s_i$ for all $s \in Stores$ and $i \in \{1, \dots, n\}$. This means in particular $\llbracket M \rrbracket s_i =_L f s_i$ for $i = 1, \dots, n$, hence either $\llbracket M \rrbracket s_i = \perp = f s_i$ or $\llbracket M \rrbracket s_i =_{Loc \setminus L} s_i =_{Loc \setminus L} f s_i$ by the second condition for f , and this implies again $\llbracket M \rrbracket s_i = f s_i$. Thus we have proved $f \vec{s} = \llbracket M \rrbracket \vec{s} \in \llbracket M \rrbracket R^{sto} \subseteq R^{sto}$.

(iv) Let f be in the set on the right hand side. Again it is sufficient to show that f preserves all $R \in \Sigma^L$ (local continuity is not an issue, because $\llbracket loc \rrbracket$ is ordered discretely). Hence let $R \in \Sigma_n^L$, $\vec{l}_1, \dots, \vec{l}_m \in R^{loc}$ and $\vec{s} \in R^{sto}$. We define a relation \sim on Loc^m by

$$(l_1, \dots, l_m) \sim (l'_1, \dots, l'_m) \Leftrightarrow \exists \varphi \in Fix(L). \forall i \in \{1, \dots, m\}. \varphi l_i = l'_i$$

Obviously, \sim is an equivalence relation on Loc^m (because $Fix(L)$ is a group with respect to function composition), and the equivalence class of a tuple (l_1, \dots, l_m) is uniquely determined by the two sets $\{(i, j) \in \{1, \dots, m\}^2 \mid l_i = l_j\}$ and $\{(i, l) \in \{1, \dots, m\} \times L \mid l_i = l\}$. Hence, with the aid of the term $EQ =_{def} \lambda x, x'. x := !x' + 1; !x = !x' \in \text{ALG}_\emptyset^{loc^2 \rightarrow iexp}$ which tests the equality of locations, it is easy to construct a term $CLASS \in c\text{-ALG}_L^{loc^m \rightarrow iexp}$ which determines the \sim -equivalence class of a tuple in Loc^m , i.e.

$$\llbracket CLASS \rrbracket l_1 \dots l_m s = \llbracket CLASS \rrbracket l'_1 \dots l'_m s \Leftrightarrow (l_1, \dots, l_m) \sim (l'_1, \dots, l'_m)$$

for all $l_1, \dots, l_m, l'_1, \dots, l'_m \in Loc$ and $s \in Stores$.

Now let eq be one of the \sim -equivalence classes. We will first construct a term $N_{eq} \in c\text{-ALG}_L^{loc^m \rightarrow cmd}$ such that

$$\llbracket N_{eq} \rrbracket l_{1i} \dots l_{mi} s_i = fl_{1i} \dots l_{mi} s_i \quad \text{whenever } (l_{1i}, \dots, l_{mi}) \in eq$$

Without loss of generality we may assume $eq = \{(l_{11}, \dots, l_{m1}), \dots, (l_{1k}, \dots, l_{mk})\}$ for some $k \leq n$. Then there are functions $\varphi_i \in Fix(L)$ such that $(l_{1i}, \dots, l_{mi}) =$

$(\varphi_i l_{11}, \dots, \varphi_i l_{m1})$ for $i = 1, \dots, k$. Since $fl_{11} \dots l_{m1} \in \llbracket cmd \rrbracket_{L \cup \{l_{11}, \dots, l_{m1}\}}$, we can first choose some $M \in c\text{-ALG}_{L \cup \{l_{11}, \dots, l_{m1}\}}^{cmd}$ as in the proof of (ii), such that $\llbracket M \rrbracket$ and $fl_{11} \dots l_{m1}$ coincide on the finitely many stores $s_i \circ \varphi_i$, $i = 1, \dots, k$, and from M we can easily construct a term $N_{eq} \in c\text{-ALG}_L^{loc^m \rightarrow cmd}$ with $\llbracket N_{eq} \rrbracket l_{11} \dots l_{m1} = \llbracket M \rrbracket$. Thus we obtain indeed

$$\begin{aligned} \llbracket N_{eq} \rrbracket l_{1i} \dots l_{mi} s_i &= (\llbracket N_{eq} \rrbracket l_{11} \dots l_{m1} (s_i \circ \varphi_i)) \circ \varphi_i^{-1} \\ &= (\llbracket M \rrbracket (s_i \circ \varphi_i)) \circ \varphi_i^{-1} \\ &= (fl_{11} \dots l_{m1} (s_i \circ \varphi_i)) \circ \varphi_i^{-1} \\ &= fl_{1i} \dots l_{mi} s_i \end{aligned}$$

for $i = 1, \dots, k$. Finally, we can use the term $CLASS$ for branching between the various N_{eq} and thus obtain a term $N \in c\text{-ALG}_L^{loc^m \rightarrow cmd}$ such that $\llbracket N \rrbracket l_{1i} \dots l_{mi} s_i = fl_{1i} \dots l_{mi} s_i$ for all $i \in \{1, \dots, n\}$. This means $f \vec{l} \vec{s} = \llbracket N \rrbracket \vec{l} \vec{s} \in R^{sto}$. \square

For second order types we do not have such a concrete description of all the domains $\llbracket \sigma \rrbracket_L$ as for the first order types. Instead, the following proposition presents only one particular example, namely the domain $\llbracket cmd \rightarrow cmd \rrbracket_\emptyset$. It is meant as a warm-up exercise for Section 9, because it anticipates certain techniques which will reappear in the full abstraction proof in a (much) more complicated form.

Proposition 8.2 *For $m \geq n \geq 0$ let $f_{m,n} = \llbracket \lambda z^{cmd}. \text{if } z^m; 0 \text{ then } z^n \rrbracket$ where $z^0 \equiv \text{skip}$ and $z^k \equiv \underbrace{z; \dots; z}_k$ if $k > 0$. Then $\llbracket cmd \rightarrow cmd \rrbracket_\emptyset = \{\perp\} \cup \{f_{m,n} \mid m \geq n \geq 0\}$.*

Proof: Choose some arbitrary $l \in Loc$ and define

$$\begin{aligned} inc_{<i} &= \llbracket \text{if } !l < i \text{ then } l := !l + 1 \text{ else } \Omega \rrbracket \quad \text{for every } i \in \mathbb{N} \\ inc_{<\infty} &= \llbracket l := !l + 1 \rrbracket \end{aligned}$$

Then $inc_{<0} \sqsubset inc_{<1} \sqsubset \dots$ is an ω -chain in $\llbracket cmd \rrbracket_{\{l\}}$ which has $inc_{<\infty}$ as its least upper bound. Now let $f \in \llbracket cmd \rightarrow cmd \rrbracket_\emptyset$. Define

$$\begin{aligned} m &= \text{card} \{i \in \mathbb{N} \mid f inc_{<i} s_0 = \perp\} \in \mathbb{N} \cup \{\infty\} \\ n &= f inc_{<\infty} s_0 l \in \mathbb{Z}_\perp \end{aligned}$$

where s_0 is some arbitrary store with $s_0 l = 0$. Note that m and n are independent of the particular choice of s_0 because $f inc_{<i} \in \llbracket cmd \rrbracket_{\{l\}}$ for every $i \in \mathbb{N} \cup \{\infty\}$. Moreover, $n \in \mathbb{Z}$ whenever $m \in \mathbb{N}$ because of the monotonicity of f . We will show that

$$\begin{aligned} f &= \perp && \text{if } m = \infty \\ m \geq n \geq 0 \wedge f &= f_{m,n} && \text{if } m \in \mathbb{N} \end{aligned}$$

To this end let $g \in \llbracket cmd \rrbracket$ and $s \in Stores$. Then there is some $L \in W$ with $l \in L$ and $g \in \llbracket cmd \rrbracket_L$. The intuition is, that the computation of $f g s$ can be simulated by the computation of $f inc_{<k} (s [0/l])$ for some appropriate $k \in \mathbb{N} \cup \{\infty\}$, and

that this simulation can be expressed by one of our logical relations. We choose $k = \sup \{i \in \mathbb{N} \mid g^i s \neq \perp\}$ and we define $R \in DEF_2^L$ by

$$R^{sto} = \{\perp\}^2 \cup \{\vec{s} \in Stores^2 \mid \exists i \in \mathbb{N}. i \leq k \wedge s_1 l = i \wedge s_2 =_L g^i s \wedge s_1 =_{Loc \setminus L} s_2\}$$

Then $(s[0/l], s) = (s[0/l], g^0 s) \in R^{sto}$ and it is easy to see that $(inc_{<k}, g) \in R^{cmd}$. This implies $(f inc_{<k}(s[0/l]), fg s) \in f R^{cmd} R^{sto} \subseteq R^{sto}$. If $m = \infty$, then we have $f inc_{<k}(s[0/l]) = \perp$, hence also $fg s = \perp$. Thus we have proved $f = \perp$ in this case. If $m \in \mathbb{N}$, then

$$\begin{aligned} fg s = \perp &\Leftrightarrow f inc_{<k}(s[0/l]) = \perp \\ &\Leftrightarrow k < m \quad \text{per definition of } m \\ &\Leftrightarrow g^m s = \perp \quad \text{per definition of } k \end{aligned}$$

and

$$\begin{aligned} fg s \neq \perp &\Rightarrow \exists i \in \mathbb{N}. f inc_{<k}(s[0/l]) l = i \wedge fg s =_L g^i s \\ &\Rightarrow n \in \mathbb{N} \wedge fg s =_L g^n s \quad \text{because } i \text{ can only be } n \\ &\Rightarrow n \in \mathbb{N} \wedge fg s = g^n s \quad \text{because } fg \text{ and } g^n \text{ are in } \llbracket cmd \rrbracket_L \end{aligned}$$

Thus we have proved

$$fg s = \begin{cases} \perp & \text{if } g^m s = \perp \\ g^n s \neq \perp & \text{if } g^m s \neq \perp \end{cases}$$

for all $g \in \llbracket cmd \rrbracket$ and $s \in Stores$. This implies $m \geq n$ and $f = f_{m,n}$. \square

Note that by Proposition 8.2 the domain $\llbracket cmd \rightarrow cmd \rrbracket_\emptyset$ consists of infinitely many descending chains $f_{n,n} \sqsupset f_{n+1,n} \sqsupset \dots$ which only meet in the bottom element; the maximal elements of this domain are the ‘Church numerals’ $f_{n,n} = \llbracket \lambda z. z^n \rrbracket$. If we define $p_i : \llbracket cmd \rightarrow cmd \rrbracket_\emptyset \rightarrow \llbracket cmd \rightarrow cmd \rrbracket_\emptyset$ for all $i \in \mathbb{N}$ by

$$p_i f = \begin{cases} f & \text{if } f = f_{m,n} \text{ for some } m, n \leq i \\ \perp & \text{otherwise} \end{cases}$$

then $p_0 \sqsubset p_1 \sqsubset \dots$ is an ω -chain of idempotent deflations [1] which have the identity as their least upper bound, i.e. $\llbracket cmd \rightarrow cmd \rrbracket_\emptyset$ is an SFP object [23]. But a different property of the functions p_i is more interesting for us: With the notation from the above proof we can reformulate the definition of p_i as

$$p_i f = \begin{cases} \perp & \text{if } f inc_{<i} s_0 l = \perp \\ f_{m,n} & \text{if } f inc_{<i} s_0 l \neq \perp, \\ & m = \text{card} \{j < i \mid f inc_{<j} s_0 l = \perp\} \text{ and } n = f inc_{<\infty} s_0 l \end{cases}$$

This shows that $p_i f$ is uniquely determined by the finitely many values $f inc_{<j} s_0 l$ with $j \in \{0, \dots, i, \infty\}$. Such functions will be called ‘finitely determined’ in Section 9, and sequences of finitely determined functions which have the identity as their least upper bound will play a prominent role in the full abstraction proof.

We conclude this section with a technical lemma.

Lemma 8.3 Let $\varphi : Loc \rightarrow Loc$ be a finite permutation and let $R_\varphi \in DEF_2^{Supp(\varphi)}$ as in Section 5. Then there is a term $SWAP_\varphi^\sigma \in c\text{-ALG}_{Supp(\varphi)}^{\sigma \rightarrow \sigma}$ for every procedure type σ , such that R_φ^σ is the graph of $\llbracket SWAP_\varphi^\sigma \rrbracket$ and $\llbracket SWAP_\varphi^\sigma \rrbracket \circ \llbracket SWAP_{\varphi^{-1}}^\sigma \rrbracket = \text{id}_\sigma$.

Proof: It is easy to construct $SWAP_\varphi \in c\text{-ALG}_{Supp(\varphi)}^{cmd}$ such that $\llbracket SWAP_\varphi \rrbracket s l = s(\varphi l)$ for all $s \in Stores$ and $l \in Loc$, i.e. such that R_φ^{sto} is the graph of $\llbracket SWAP_\varphi \rrbracket$. By induction on σ we then define $SWAP_\varphi^\sigma \in c\text{-ALG}_{Supp(\varphi)}^{\sigma \rightarrow \sigma}$ by

$$\begin{aligned} SWAP_\varphi^{iexp} &\equiv \lambda y^{iexp}. SWAP_{\varphi^{-1}}; y \\ SWAP_\varphi^{cmd} &\equiv \lambda y^{cmd}. SWAP_{\varphi^{-1}}; y; SWAP_\varphi \\ SWAP_\varphi^{loc \rightarrow \sigma} &\equiv \lambda y^{loc \rightarrow \sigma}. \lambda x^{loc}. \\ &\quad \text{if } EQ\ x\ l'_1 \text{ then } SWAP_\varphi^\sigma(y\ l_1) \text{ else} \\ &\quad \vdots \\ &\quad \text{if } EQ\ x\ l'_n \text{ then } SWAP_\varphi^\sigma(y\ l_n) \text{ else } SWAP_\varphi^\sigma(y\ x) \\ &\quad \text{where } EQ =_{def} \lambda x, x'. x := !x' + 1; !x = !x' \text{ tests the equality} \\ &\quad \text{on locations, } \{l_1, \dots, l_n\} = Supp(\varphi) \text{ and } l'_i = \varphi l_i \text{ for } i = 1, \dots, n \\ SWAP_\varphi^{\sigma \rightarrow \sigma'} &\equiv \lambda y^{\sigma \rightarrow \sigma'}. \lambda z^\sigma. SWAP_\varphi^{\sigma'}(y\ (SWAP_{\varphi^{-1}}^\sigma z)) \end{aligned}$$

A straightforward induction on σ shows that every $\llbracket SWAP_\varphi^\sigma \rrbracket$ has the desired properties. \square

9 Full Abstraction

We will now present our full abstraction proof. The overall structure of the proof is the same as for PCF in Chapter 2: In the first part we show that for every function $f \in \llbracket \sigma \rrbracket_L$ with $ord(\sigma) \leq 2$ and every finite set B of argument tuples for f there is a term $M \in c\text{-ALG}_L^\tau$ such that $\llbracket M \rrbracket$ and f coincide on B . As in Chapter 2 we will prove this result by using “logical relations which have large arity and are reminiscent of value tables” [6]. As a preparation we prove a technical lemma which allows us to ‘fill up’ a ground relation with a cofinite part of the diagonal $\delta^n Loc$.

Definition 9.1 Let R be an n -ary ground relation with $R^{sto}(\delta^n(Loc \setminus L)) \subseteq R^{int}$. Then the L -closure of R is defined to be the ground relation S with

$$\begin{aligned} - S^{int} &= R^{int}, \\ - S^{loc} &= R^{loc} \cup \delta^n(Loc \setminus L) \\ - S^{sto} &= \{\vec{s} \in (D^{sto})^n \mid \exists \vec{t} \in R^{sto}. \vec{s} =_L \vec{t} \wedge \vec{s}(\delta^n(Loc \setminus L)) \subseteq R^{int}\} \end{aligned}$$

Note that R is ‘contained’ in its L -closure S , i.e. $R^\gamma \subseteq S^\gamma$ for every $\gamma \in \Gamma$.

Lemma 9.2 Let R be an n -ary ground relation with $R^{sto}(\delta^n(Loc \setminus L)) \subseteq R^{int}$ and $R^{loc} \subseteq L^n$. Then every function $f \in AUX$, which preserves R , also preserves the L -closure of R .

Proof: Let $f \in AUX$ preserve R , and let S denote the L -closure of R . We show that f preserves S .

Case 1: $f = \text{Const}_m$

If $\vec{s} \in S^{sto}$ and $\vec{t} \in R^{sto}$ with $\vec{s} =_L \vec{t}$, then $\text{Const}_m \vec{s} = \text{Const}_m \vec{t} \in R^{int} = S^{int}$.

Case 2: $f \in \{\text{Succ}, \text{Pred}, \text{Cond}_{int}, \text{Pcond}\}$

Obvious, because $S^{int} = R^{int}$.

Case 3: $f = \text{Cond}_{sto}$

First note that $\text{Cond}_{sto} d s t l = \text{Cond}_{int} d (s l) (t l)$ for all $d \in D^{int}$, $s, t \in D^{sto}$ and $l \in \text{Loc}$. Now let $\vec{d} \in S^{int} = R^{int}$, $\vec{s}, \vec{t} \in S^{sto}$ and $\vec{u}, \vec{v} \in R^{sto}$ with $\vec{s} =_L \vec{u}$ and $\vec{t} =_L \vec{v}$. Then $\text{Cond}_{sto} \vec{d} \vec{s} \vec{t} =_L \text{Cond}_{sto} \vec{d} \vec{u} \vec{v} \in R^{sto}$ because $\text{Cond}_{int} \vec{d} (\vec{s} l) (\vec{t} l) = \text{Cond}_{int} \vec{d} (\vec{u} l) (\vec{v} l)$ for all $l \in L$, and $\text{Cond}_{sto} \vec{d} \vec{s} \vec{t} l = \text{Cond}_{int} \vec{d} (\vec{s} l) (\vec{t} l) \in \text{Cond}_{int} R^{int} R^{int} R^{int} \subseteq R^{int}$ for all $l \in \text{Loc} \setminus L$. This proves $\text{Cond}_{sto} \vec{d} \vec{s} \vec{t} \in S^{sto}$.

Case 4: $f = \text{Cont}$

Let $\vec{l} \in S^{loc}$, $\vec{s} \in S^{sto}$ and $\vec{t} \in R^{sto}$ with $\vec{s} =_L \vec{t}$. If $\vec{l} \in R^{loc} \subseteq L^n$, then $\text{Cont} \vec{l} \vec{s} = \vec{s} \vec{l} = \vec{t} \vec{l} = \text{Cont} \vec{l} \vec{t} \in R^{int} = S^{int}$. If $\vec{l} \in \delta^n(\text{Loc} \setminus L)$, then $\text{Cont} \vec{l} \vec{s} = \vec{s} \vec{l} \in R^{int} = S^{int}$ per definition of S^{sto} .

Case 5: $f = \text{Asgn}$

Let $\vec{l} \in S^{loc}$, $\vec{d} \in S^{int}$, $\vec{s} \in S^{sto}$, $\vec{t} \in R^{sto}$ with $\vec{s} =_L \vec{t}$ and let $\vec{u} = \text{Asgn} \vec{l} \vec{d} \vec{s}$. If $\vec{l} \in R^{loc} \subseteq L^n$, then $\vec{u} =_L \text{Asgn} \vec{l} \vec{d} \vec{t} \in R^{sto}$, because $\text{Asgn} \vec{l} \vec{d} \in (\llbracket \text{cmd} \rrbracket_L)^n$, and $\vec{u} l = \vec{s} l \in R^{int}$ for every $l \in \text{Loc} \setminus L$, hence $\vec{u} \in S^{sto}$. If $\vec{l} = (l, \dots, l) \in \delta^n(\text{Loc} \setminus L)$, then $\vec{u} =_L \vec{s} =_L \vec{t} \in R^{sto}$, $\vec{u} l = \vec{d} \in S^{int} = R^{int}$ and $\vec{u} l' = \vec{s} l' \in R^{int}$ for all $l' \in \text{Loc} \setminus (L \cup \{l\})$, hence again $\vec{u} \in S^{sto}$. \square

Notation: If $f \in \llbracket \tau_1 \rightarrow \dots \rightarrow \tau_k \rightarrow sto \Rightarrow \gamma \rrbracket$, then we let f^d denote the *completely decurried version* of f , i.e.

$$\begin{aligned} f^d &: \llbracket \tau_1 \rrbracket \times \dots \times \llbracket \tau_k \rrbracket \times D^{sto} \rightarrow D^\gamma \\ f^d(d_1, \dots, d_k, s) &= f d_1 \dots d_k s \end{aligned}$$

Theorem 9.3 (finite coincidence with a definable function) *Let $L \in W$ and $\sigma = \tau_1 \rightarrow \dots \rightarrow \tau_k \rightarrow \theta$ ($k \geq 0$) with $\text{ord}(\sigma) \leq 2$. Let $f \in \llbracket \sigma \rrbracket_L$ and let $B \subseteq \llbracket \tau_1 \rrbracket \times \dots \times \llbracket \tau_k \rrbracket \times D^{sto}$ be finite. Then there is some $M \in c\text{-ALG}_L^\sigma$ with $\llbracket M \rrbracket^d =_B f^d$.*

Proof: Let $B = \{(d_{11}, \dots, d_{k1}, s_1), \dots, (d_{1n}, \dots, d_{kn}, s_n)\}$, let $\vec{d}_j = (d_{j1}, \dots, d_{jn})$ for $j = 1, \dots, k$, $\vec{s} = (s_1, \dots, s_n)$ and let R be the n -ary ground relation with

$$\begin{aligned} - R^{loc} &= \{\vec{d}_j \mid \tau_j = \text{loc}\} \cup \delta^n L \\ - R^\gamma &= \{\llbracket M \rrbracket \vec{d}_1 \dots \vec{d}_k \vec{s} \mid M \in c\text{-ALG}_L^{\tau_1 \rightarrow \dots \rightarrow \tau_k \rightarrow sto \Rightarrow \gamma}\} \quad \text{for } \gamma = \text{int}, \text{sto} \end{aligned}$$

Then we must prove that $f \vec{d}_1 \dots \vec{d}_k \vec{s} \in R^\gamma$ (if $\theta = sto \Rightarrow \gamma$). As a first step we show that every $g \in AUX$ preserves R .

Case 1: $g = \text{Const}_m$

Let $\vec{t} \in R^{sto}$, i.e. $\vec{t} = \llbracket M \rrbracket \vec{d}_1 \dots \vec{d}_k \vec{s}$ for some $M \in c\text{-ALG}_L^{\tau_1 \rightarrow \dots \rightarrow \tau_k \rightarrow cmd}$. Then $\text{Const}_m \vec{t} = \llbracket \lambda x_1, \dots, x_k. Mx_1 \dots x_k; m \rrbracket \vec{d}_1 \dots \vec{d}_k \vec{s} \in R^{int}$.

Case 2: $g = \text{Succ}$ (similarly for Pred , Cond_γ and Pcond)

Let $\vec{e} \in R^{int}$, i.e. $\vec{e} = \llbracket M \rrbracket \vec{d}_1 \dots \vec{d}_k \vec{s}$ for some $M \in c\text{-ALG}_L^{\tau_1 \rightarrow \dots \rightarrow \tau_k \rightarrow iexp}$. Then $\text{Succ} \vec{e} = \llbracket \lambda x_1, \dots, x_k. \text{succ}(Mx_1 \dots x_k) \rrbracket \vec{d}_1 \dots \vec{d}_k \vec{s} \in R^{int}$.

Case 3: $g = \text{Cont}$

Let $\vec{l} \in R^{loc}$ and $\vec{t} = \llbracket M \rrbracket \vec{d}_1 \dots \vec{d}_k \vec{s} \in R^{sto}$. If $\vec{l} = \vec{d}_j$ with $\tau_j = loc$, then let $P \equiv \lambda x_1, \dots, x_k. Mx_1 \dots x_k; !x_j$, and if $\vec{l} = (l, \dots, l) \in \delta^n L$, then let $P \equiv \lambda x_1, \dots, x_k. Mx_1 \dots x_k; !l$. In both cases $\text{Cont} \vec{l} \vec{t} = \llbracket P \rrbracket \vec{d}_1 \dots \vec{d}_k \vec{s} \in R^{int}$.

Case 4: $g = \text{Asgn}$

Let $\vec{l} \in R^{loc}$, $\vec{e} = \llbracket M \rrbracket \vec{d}_1 \dots \vec{d}_k \vec{s} \in R^{int}$ and $\vec{t} = \llbracket N \rrbracket \vec{d}_1 \dots \vec{d}_k \vec{s} \in R^{sto}$. If $\vec{l} = \vec{d}_j$ with $\tau_j = loc$, then $\text{Asgn} \vec{l} \vec{e} \vec{t} = \llbracket P \rrbracket \vec{d}_1 \dots \vec{d}_k \vec{s}$, where

$$P \equiv \lambda x_1, \dots, x_k. \text{new } x \text{ in } x := Mx_1 \dots x_k; Nx_1 \dots x_k; x_j := !x \text{ end}$$

Intuitively, P works as follows: First, $Mx_1 \dots x_k$ is evaluated and the result \vec{e} is stored into the local variable x . After evaluation of $Mx_1 \dots x_k$ the computation snaps back to \vec{s} , and then \vec{t} is computed by evaluating $Nx_1 \dots x_k$. Finally, \vec{t} is updated to $\vec{t}[\vec{e}/\vec{l}]$ by the assignment $x_j := !x$. The precise argumentation is as follows.

$$\begin{aligned} & \llbracket P \rrbracket \vec{d}_1 \dots \vec{d}_k \vec{s} \\ &= (\llbracket x := Mx_1 \dots x_k; Nx_1 \dots x_k; x_j := !x \rrbracket \vec{\eta}[l/x] (\vec{s}[0/l])) [\vec{s}l/l] \\ & \quad \text{where } l \text{ is some new location and } \vec{\eta} \in Env^n \text{ with } \vec{\eta}x_i = \vec{d}_i \text{ for } i = 1, \dots, k \\ &= (\llbracket Nx_1 \dots x_k; x_j := !x \rrbracket \vec{\eta}[l/x] (\vec{s}[\vec{e}/l])) [\vec{s}l/l] \\ & \quad \text{because } l \text{ is new and hence } \llbracket M \rrbracket \vec{d}_1 \dots \vec{d}_k (\vec{s}[0/l]) = \llbracket M \rrbracket \vec{d}_1 \dots \vec{d}_k \vec{s} = \vec{e} \\ &= (\llbracket x_j := !x \rrbracket \vec{\eta}[l/x] (\vec{t}[\vec{e}/l])) [\vec{s}l/l] \\ & \quad \text{because } l \text{ is new and hence } \llbracket N \rrbracket \vec{d}_1 \dots \vec{d}_k (\vec{s}[\vec{e}/l]) = \vec{t}[\vec{e}/l] \\ &= \vec{t}[\vec{e}/l] [\vec{e}/\vec{l}] [\vec{s}l/l] \\ &= \vec{t}[\vec{e}/\vec{l}] \quad \text{because } l \text{ is new and hence } \vec{s}l = \vec{t}l \\ &= \text{Asgn} \vec{l} \vec{e} \vec{t} \end{aligned}$$

If $\vec{l} = (l, \dots, l) \in \delta^n L$, then we replace the assignment $x_j := !x$ in P by $l := !x$. Thus we obtain again $\text{Asgn} \vec{l} \vec{e} \vec{t} = \llbracket P \rrbracket \vec{d}_1 \dots \vec{d}_k \vec{s}$, i.e. $\text{Asgn} \vec{l} \vec{e} \vec{t} \in R^{sto}$ in both cases.

So far we have shown that every $g \in AUX$ preserves R . Now let $L' \supseteq L$ be such that $\vec{d}_j \in (\llbracket \tau_j \rrbracket_{L'})^n$ for $j = 1, \dots, k$ and $\vec{s} \in (\text{Stores}_{L'})^n$. Then $R^{sto}(\delta^n(\text{Loc} \setminus L')) = \text{Const}_0 R^{sto} \subseteq R^{int}$, hence we can define the L' -closure S of R . By Lemma 9.2, every $g \in AUX$ preserves S , moreover $\delta^n(\text{Loc} \setminus (L' \setminus L)) \subseteq S^{loc}$ because $\delta^n L \subseteq R^{loc}$, and

finally $(\perp, \dots, \perp) \in S^{sto}$ because $(\perp, \dots, \perp) = \llbracket \lambda x_1, \dots, x_k. \Omega \rrbracket \vec{d}_1 \dots \vec{d}_k \vec{s} \in R^{sto}$. Altogether this proves $S \in \Sigma^L$ and hence f preserves S .

If we can now show that $\vec{d}_j \in S^{\tau_j}$ for $j = 1, \dots, k$, then we obtain $f \vec{d}_1 \dots \vec{d}_k \vec{s} \in f S^{\tau_1} \dots S^{\tau_k} R^{sto} \subseteq f S^{\tau_1} \dots S^{\tau_k} S^{sto} \subseteq S^\gamma$. For $\gamma = int$ this already concludes the proof, because $S^{int} = R^{int}$. For $\gamma = sto$ we first obtain $f \vec{d}_1 \dots \vec{d}_k \vec{s} =_{L'} \vec{t}$ for some $\vec{t} \in R^{sto}$, and then $f \vec{d}_1 \dots \vec{d}_k \vec{s} =_{Loc \setminus L'} \vec{s} =_{Loc \setminus L'} \vec{t}$ implies $f \vec{d}_1 \dots \vec{d}_k \vec{s} = \vec{t} \in R^{sto}$.

Hence let $j \in \{1, \dots, k\}$. If $\tau_j = loc$, then $\vec{d}_j \in R^{loc} \subseteq S^{loc}$. As τ_j is a type of order ≤ 1 , we are left with the case $\tau_j = loc^m \rightarrow \theta$ ($m \geq 0$). In order to keep the notation simple, we consider only one particular case, namely $\tau_j = loc \rightarrow cmd$:

Let $\vec{l} \in S^{loc}, \vec{t} \in S^{sto}, \vec{u} \in R^{sto}$ with $\vec{t} =_{L'} \vec{u}$ and let $M \in c\text{-ALG}_L^{\tau_1 \rightarrow \dots \rightarrow \tau_k \rightarrow cmd}$ with $\vec{u} = \llbracket M \rrbracket \vec{d}_1 \dots \vec{d}_k \vec{s}$. If $\vec{l} = \vec{d}_i$ with $\tau_i = loc$, then $\vec{d}_j \vec{l} \vec{t} =_{L'} \vec{d}_j \vec{l} \vec{u}$ because $\vec{d}_j \vec{l} \in (\llbracket cmd \rrbracket_{L'})^n$, hence $\vec{d}_j \vec{l} \vec{t} =_{L'} \llbracket \lambda x_1, \dots, x_k. M x_1 \dots x_k; x_j x_i \rrbracket \vec{d}_1 \dots \vec{d}_k \vec{s} \in R^{sto}$, and moreover $\vec{d}_j \vec{l} \vec{t} l = \vec{t} l \in R^{int}$ for all $l \in Loc \setminus L'$. This proves $\vec{d}_j \vec{l} \vec{t} \in S^{sto}$. If $\vec{l} = (l, \dots, l) \in \delta^n L$, then we replace $x_j x_i$ by $x_j l$ in the above term and thus obtain again $\vec{d}_j \vec{l} \vec{t} \in S^{sto}$. Hence we are left with the case $\vec{l} = (l, \dots, l) \in \delta^n (Loc \setminus L')$:

As $\vec{t} \in S^{sto}$, we have $\vec{t} l \in R^{int}$, i.e. there is some $N \in c\text{-ALG}_L^{\tau_1 \rightarrow \dots \rightarrow \tau_k \rightarrow iexp}$ with $\vec{t} l = \llbracket N \rrbracket \vec{d}_1 \dots \vec{d}_k \vec{s}$. Now we define

$$\begin{aligned} P &\equiv \lambda x_1, \dots, x_k. \mathbf{new\ } x \mathbf{\ in\ } x := N x_1 \dots x_k; M x_1 \dots x_k; x_j x \mathbf{\ end} \\ Q &\equiv \lambda x_1, \dots, x_k. \mathbf{new\ } x \mathbf{\ in\ } x := N x_1 \dots x_k; M x_1 \dots x_k; x_j x; !x \mathbf{\ end} \end{aligned}$$

We may assume that our particular location $l \in Loc \setminus L'$ is bound to the local variable x , hence we obtain

$$\begin{aligned} \llbracket P \rrbracket \vec{d}_1 \dots \vec{d}_k \vec{s} &= (\llbracket x := N x_1 \dots x_k; M x_1 \dots x_k; x_j x \rrbracket \vec{\eta} \vec{s}) [0/l] \\ &\quad \text{where } \vec{\eta} \in Env^n \text{ with } \vec{\eta} x_i = \vec{d}_i \text{ for } i = 1, \dots, k \text{ and } \vec{\eta} x = (l, \dots, l) \\ &=_{L'} \llbracket x := N x_1 \dots x_k; M x_1 \dots x_k; x_j x \rrbracket \vec{\eta} \vec{s} \\ &= \llbracket M x_1 \dots x_k; x_j x \rrbracket \vec{\eta} (\vec{s} [\vec{t} l / l]) \\ &= \llbracket x_j x \rrbracket \vec{\eta} (\vec{u} [\vec{t} l / l]) \\ &\quad \text{because } \llbracket M \rrbracket \vec{d}_1 \dots \vec{d}_k (\vec{s} [\vec{t} l / l]) = \vec{u} [\vec{t} l / l] \text{ by Theorem 5.3 (iii')} \\ &= \vec{d}_j l (\vec{u} [\vec{t} l / l]) \\ &=_{L'} \vec{d}_j l \vec{t} \quad \text{because } \vec{d}_j l \in (\llbracket cmd \rrbracket_{L' \cup \{l\}})^n \text{ and } \vec{t} =_{L' \cup \{l\}} \vec{u} [\vec{t} l / l] \end{aligned}$$

This shows that $\vec{d}_j l \vec{t} =_{L'} \llbracket P \rrbracket \vec{d}_1 \dots \vec{d}_k \vec{s} \in R^{sto}$ and similarly we can prove $\vec{d}_j l \vec{t} l = \llbracket Q \rrbracket \vec{d}_1 \dots \vec{d}_k \vec{s} \in R^{int}$. Moreover, if $l' \in Loc \setminus (L' \cup \{l\})$, then $\vec{d}_j l \vec{t} l' = \vec{t} l' \in R^{int}$ because $\vec{d}_j l \in (\llbracket cmd \rrbracket_{L' \cup \{l\}})^n$. Thus we have shown that $\vec{d}_j l \vec{t} \in S^{sto}$, and this concludes the proof. \square

From Theorem 9.3 we can obtain a sequence of definable functions $\llbracket M_1 \rrbracket, \llbracket M_2 \rrbracket, \dots$ ($M_i \in c\text{-ALG}_L^\sigma$) which ‘converge’ to the given function $f \in \llbracket \sigma \rrbracket_L$ in the sense that they coincide with f on more and more argument tuples. But for a typical full

abstraction proof [24] we must know that f is the *least upper bound* of a sequence (or a directed set) of definable functions. In Chapter 2 we succeeded to close the gap between these two kinds of ‘convergence’ by showing that the meaning of each type is an SFP object, in which the identity is the lub of an ω -chain of *definable* idempotent deflations. But a closer look at the full abstraction proof in Chapter 2 reveals that we did not really need to know that these definable functions are idempotent or that they have finite image. Instead we only used the fact that they are ‘finitely determined’ in the sense of the following definition.

Definition 9.4 Let D_i, E_i ($i = 1, 2$) be sets, let $F_i \subseteq (D_i \xrightarrow{t} E_i)$ and $p \in (F_1 \xrightarrow{t} F_2)$.

- (1) $B \subseteq D_1$ is called a *determining set* for p , if $f =_B g$ implies $pf = pg$ for all $f, g \in F_1$. p is called *finitely determined* if it has a finite determining set.
- (2) $\hat{p} \in (D_2 \xrightarrow{t} D_1)$ is called a *determining function* for p , if $f(\hat{p}d) = g(\hat{p}d)$ implies $pf d = pg d$ for all $f, g \in F_1$ and $d \in D_2$. p is called *locally determined* if it has a determining function.

Finitely determined functions are those which we need for the full abstraction proof, but sometimes it is very difficult to prove ‘directly’ that a particular function is finitely determined. Hence we use locally determined functions to construct new finitely determined functions from given ones. This is possible by

Lemma 9.5 Let D_i, E_i, F_i ($i = 0, 1, 2$) as before, $p \in (F_1 \xrightarrow{t} F_2)$ and $q \in (F_0 \xrightarrow{t} F_1)$.

- (i) If p and q are locally determined, then $p \circ q$ is locally determined.
- (ii) If q is finitely determined, then $p \circ q$ is finitely determined.
- (iii) If p is finitely determined and q is locally determined, then $p \circ q$ is finitely determined.

Proof:

(i) Let \hat{p}, \hat{q} be determining functions for p and q . Then $f(\hat{q}(\hat{p}d)) = g(\hat{q}(\hat{p}d)) \Rightarrow qf(\hat{p}d) = qg(\hat{p}d) \Rightarrow p(qf)d = p(qg)d$ for all $d \in D_2$ and $f, g \in F_0$. This shows that $\hat{q} \circ \hat{p}$ is a determining function for $p \circ q$.

(ii) Clearly every determining set for q is also a determining set for $p \circ q$.

(iii) Let B be a (finite) determining set for p and let \hat{q} be a determining function for q . Then $f =_{\hat{q}B} g \Rightarrow f \circ \hat{q} =_B g \circ \hat{q} \Rightarrow qf =_B qg \Rightarrow p(qf) = p(qg)$ for all $f, g \in F_0$. This shows that $\hat{q}B$ is a (finite) determining set for $p \circ q$. \square

Notation: Let σ, σ' be procedure types and let $p \in ([\sigma] \xrightarrow{t} [\sigma'])$. Then we let p^D denote the corresponding function on the completely decurried types, i.e.

$$\begin{aligned} p^D &: [\sigma]^d \rightarrow [\sigma']^d \\ p^D f^d &= (pf)^d \end{aligned}$$

Note that $(p \circ q)^D = p^D \circ q^D$, if $q \in ([\sigma] \xrightarrow{t} [\sigma'])$ and $p \in ([\sigma'] \xrightarrow{t} [\sigma''])$.

Definition 9.6 Let σ, σ' be procedure types and let $L \in W$.

- (1) An *L-FD-sequence* on σ is a sequence of terms $P_n \in c\text{-ALG}_L^{\sigma \rightarrow \sigma}$ such that $(\llbracket P_n \rrbracket)_{n \in \mathbb{N}}$ is an ω -chain with $\bigsqcup_{n \in \mathbb{N}} \llbracket P_n \rrbracket = \text{id}_\sigma$ and $\llbracket P_n \rrbracket^D \mid (\llbracket \sigma \rrbracket_L)^d$ is finitely determined for every $n \in \mathbb{N}$. σ is called an *L-FD-type* if there is an *L-FD-sequence* on σ .
- (2) An *L-section-retraction-pair* (or *L-SR-pair*) between σ and σ' is a pair of terms $S \in c\text{-ALG}_L^{\sigma \rightarrow \sigma'}$, $R \in c\text{-ALG}_L^{\sigma' \rightarrow \sigma}$ such that $\llbracket R \rrbracket \circ \llbracket S \rrbracket = \text{id}_\sigma$ and $\llbracket S \rrbracket^D$ is locally determined. σ is called an *L-retract* of σ' (notation: $\sigma \triangleleft_L \sigma'$) if there is an *L-SR-pair* between σ and σ' .

Note that *L-retracts* are closely related to ordinary retracts [1, 4]: If (S, R) is an *L-SR-pair* between the types σ and σ' , then $(\llbracket S \rrbracket \mid \llbracket \sigma \rrbracket_L, \llbracket R \rrbracket \mid \llbracket \sigma' \rrbracket_L)$ is an (ordinary) s-r-pair between the dcpos $\llbracket \sigma \rrbracket_L$ and $\llbracket \sigma' \rrbracket_L$.

Our ultimate goal is to prove that every procedure type σ with $\text{ord}(\sigma) \leq 2$ is an *L-FD-type*, whenever $L \neq \emptyset$. But—as mentioned before—it is sometimes very difficult to prove directly that particular functions are finitely determined. This is the point where *L-retracts* come in:

Theorem 9.7 (L-retracts of L-FD-types) *Every L-retract of an L-FD-type is an L-FD-type.*

Proof: Let $(P_n)_{n \in \mathbb{N}}$ be an *L-FD-sequence* on σ and let (S, R) be an *L-SR-pair* between σ' and σ . For every $n \in \mathbb{N}$ let $P'_n \equiv \lambda y^{\sigma'}. R(P_n(Sy)) \in c\text{-ALG}_L^{\sigma' \rightarrow \sigma'}$. By monotonicity of $\llbracket R \rrbracket$, the functions $\llbracket P'_n \rrbracket$ form an ω -chain, and by its local continuity $\bigsqcup_{n \in \mathbb{N}} \llbracket P'_n \rrbracket = \bigsqcup_{n \in \mathbb{N}} \llbracket R \rrbracket \circ \llbracket P_n \rrbracket \circ \llbracket S \rrbracket = \llbracket R \rrbracket \circ (\bigsqcup_{n \in \mathbb{N}} \llbracket P_n \rrbracket) \circ \llbracket S \rrbracket = \llbracket R \rrbracket \circ \text{id}_\sigma \circ \llbracket S \rrbracket = \text{id}_{\sigma'}$. Moreover, by Lemma 9.5 (ii) and (iii), the functions $\llbracket P'_n \rrbracket^D \mid (\llbracket \sigma' \rrbracket_L)^d = (\llbracket R \rrbracket^D) \mid (\llbracket \sigma \rrbracket_L)^d \circ \llbracket P_n \rrbracket^D \mid (\llbracket \sigma \rrbracket_L)^d \circ \llbracket S \rrbracket^D \mid (\llbracket \sigma' \rrbracket_L)^d$ are finitely determined. This proves that $(P'_n)_{n \in \mathbb{N}}$ is an *L-FD-sequence* on σ' . \square

In order to make good use of Theorem 9.7 we will now provide some ‘recipes’ for obtaining *L-retracts*. First note that \triangleleft_L is a preorder for every $L \in W$, because procedure types and *L-SR-pairs* form a category: The morphisms from σ to σ' are the *L-SR-pairs* between σ and σ' ; the identity morphism on σ is $(\lambda y^\sigma. y, \lambda y^\sigma. y)$; the composition of two morphisms (S, R) from σ to σ' and (S', R') from σ' to σ'' is $(\lambda y^\sigma. S'(Sy), \lambda y^{\sigma''}. R'(R'y))$. Note that $(\llbracket S' \rrbracket \circ \llbracket S \rrbracket)^D = \llbracket S' \rrbracket^D \circ \llbracket S \rrbracket^D$ is indeed locally determined by Lemma 9.5 (i). In order to obtain some more interesting facts about the relations \triangleleft_L we need the following technical lemma.

Lemma 9.8

- (i) Let $\sigma = \tau_1 \rightarrow \dots \rightarrow \tau_k \rightarrow \theta$ and $\sigma' = \tau_{m+1} \rightarrow \dots \rightarrow \tau_k \rightarrow \theta$ for some $m \geq 0$, let $p_i \in (\llbracket \tau \rrbracket \xrightarrow{t} \llbracket \tau_i \rrbracket)$ for $i = 1, \dots, m$ and let $p \in (\llbracket \sigma \rrbracket \xrightarrow{t} \llbracket \tau \rightarrow \sigma' \rrbracket)$ with

$$pfd = f(p_1d) \dots (p_md) \quad \text{for all } f \in \llbracket \sigma \rrbracket, d \in \llbracket \tau \rrbracket$$

Then p^D is locally determined.

(ii) Let $q \in (\llbracket \sigma' \rrbracket \xrightarrow{t} \llbracket \sigma \rrbracket)$ and let $p \in (\llbracket \tau \rightarrow \sigma' \rrbracket \xrightarrow{t} \llbracket \tau \rightarrow \sigma \rrbracket)$ with

$$pf = q \circ f \quad \text{for all } f \in \llbracket \tau \rightarrow \sigma' \rrbracket$$

Then p^D is locally determined, if q^D is locally determined.

Proof:

(i) For all $d \in \llbracket \tau \rrbracket$ and all $(d_{m+1}, \dots, d_k, s) \in \llbracket \tau_{m+1} \rrbracket \times \dots \times \llbracket \tau_k \rrbracket \times D^{sto}$ we have $p^D f^d(d, d_{m+1}, \dots, d_k, s) = p f d d_{m+1} \dots d_k s = f^d(p_1 d, \dots, p_m d, d_{m+1}, \dots, d_k, s)$. This shows that $\langle p_1, \dots, p_m \rangle \circ fst, snd \rangle$ is a determining function for p^D .

(ii) For all $d \in \llbracket \tau \rrbracket$ and all $(d_1, \dots, d_k, s) \in \llbracket \tau_1 \rrbracket \times \dots \times \llbracket \tau_k \rrbracket \times D^{sto}$ we have $p^D f^d(d, d_1, \dots, d_k, s) = p f d d_1 \dots d_k s = q(fd) d_1 \dots d_k s = q^D(fd)^d(d_1, \dots, d_k, s)$. Now let \hat{q} be a determining function for q^D . Then we obtain

$$\begin{aligned} f^d(d, \hat{q}(d_1, \dots, d_k, s)) &= g^d(d, \hat{q}(d_1, \dots, d_k, s)) \\ &\Rightarrow (fd)^d(\hat{q}(d_1, \dots, d_k, s)) = (gd)^d(\hat{q}(d_1, \dots, d_k, s)) \\ &\Rightarrow q^D(fd)^d(d_1, \dots, d_k, s) = q^D(gd)^d(d_1, \dots, d_k, s) \\ &\Rightarrow p^D f^d(d, d_1, \dots, d_k, s) = p^D g^d(d, d_1, \dots, d_k, s) \end{aligned}$$

This shows that $\langle fst, \hat{q} \circ snd \rangle$ is a determining function for p^D . \square

Lemma 9.9 Let $L \in W$. Then⁶

- (i) $\sigma \triangleleft_L \sigma'$ implies $\tau \rightarrow \sigma \triangleleft_L \tau \rightarrow \sigma'$ and $\sigma \rightarrow \sigma'' \triangleleft_L \sigma' \rightarrow \sigma''$
- (ii) $L \neq \emptyset$ implies $iepx \triangleleft_L cmd$
- (iii) $\sigma \triangleleft_L loc \rightarrow \sigma$
- (iv) $\sigma \rightarrow \sigma \rightarrow \sigma' \triangleleft_L (loc \rightarrow \sigma) \rightarrow \sigma'$
- (v) $\tau \rightarrow \tau' \rightarrow \sigma \triangleleft_L \tau' \rightarrow \tau \rightarrow \sigma$

The condition $L \neq \emptyset$ is necessary in (ii), because—by Theorem 8.1— $\llbracket iexp \rrbracket_\emptyset$ is isomorphic to \mathbb{Z}_\perp and $\llbracket cmd \rrbracket_\emptyset$ is isomorphic to $\{\perp, \top\}$, hence $\llbracket iexp \rrbracket_\emptyset$ cannot be a retract of $\llbracket cmd \rrbracket_\emptyset$.

Proof:

(i) Let (S, R) be an L -SR-pair between σ and σ' and define

$$\begin{aligned} \bar{R} &\equiv \lambda y^{\tau \rightarrow \sigma'}. \lambda z^\tau. R(yz) & \bar{S} &\equiv \lambda y^{\tau \rightarrow \sigma}. \lambda z^\tau. S(yz) \\ \tilde{R} &\equiv \lambda y^{\sigma' \rightarrow \sigma''}. \lambda z^\sigma. y(Sz) & \tilde{S} &\equiv \lambda y^{\sigma \rightarrow \sigma''}. \lambda z^{\sigma'}. y(Rz) \end{aligned}$$

$\llbracket \bar{S} \rrbracket^D$ is locally determined by Lemma 9.8 (ii), because $\llbracket S \rrbracket^D$ is locally determined and $\llbracket \bar{S} \rrbracket f = \llbracket S \rrbracket \circ f$ for all $f \in \llbracket \tau \rightarrow \sigma \rrbracket$. $\llbracket \tilde{S} \rrbracket^D$ is locally determined by Lemma 9.8 (i), because $\llbracket \tilde{S} \rrbracket fg = f(\llbracket R \rrbracket g)$ for all $f \in \llbracket \sigma \rightarrow \sigma'' \rrbracket$ and $g \in \llbracket \sigma' \rrbracket$. Moreover, $\llbracket \bar{R}(\bar{S}y)z \rrbracket =$

⁶If we had product types in ALG, then we could replace (iv) by $\sigma \times \sigma \triangleleft_L loc \rightarrow \sigma$ and (v) by $\tau \times \tau' \triangleleft_L \tau' \times \tau$.

$\llbracket R(\bar{S}yz) \rrbracket = \llbracket R(S(yz)) \rrbracket = \llbracket yz \rrbracket$ shows that $\llbracket \bar{R}(\bar{S}y) \rrbracket = \llbracket y \rrbracket$, and $\llbracket \tilde{R}(\tilde{S}y)z \rrbracket = \llbracket \tilde{S}y(Sz) \rrbracket = \llbracket y(R(Sz)) \rrbracket = \llbracket yz \rrbracket$ shows that $\llbracket \tilde{R}(\tilde{S}y) \rrbracket = \llbracket y \rrbracket$.

(ii) Let $l \in L$, let $R \equiv \lambda y^{cmd}. y; !l$ and $S \equiv \lambda y^{iexp}. l := y$. For all $f \in \llbracket iexp \rrbracket$ and $s \in D^{sto}$ we have $\llbracket S \rrbracket fs = s[fs/l]$, hence $\llbracket S \rrbracket^D = \llbracket S \rrbracket$ is locally determined with determining function id_{sto} . Moreover, $\llbracket R(Sy) \rrbracket = \llbracket Sy; !l \rrbracket = \llbracket l := y; !l \rrbracket = \llbracket y \rrbracket$.

(iii) Let $R \equiv \lambda y^{loc \rightarrow \sigma}. \text{new } x \text{ in } yx \text{ end}$ and $S \equiv \lambda y^\sigma. \lambda x^{loc}. y$. Then $\llbracket S \rrbracket^D$ is locally determined by Lemma 9.8 (i), because $\llbracket S \rrbracket fl = f$ for all $f \in \llbracket \sigma \rrbracket$ and $l \in \llbracket loc \rrbracket$. Moreover, $\llbracket R(Sy) \rrbracket = \llbracket \text{new } x \text{ in } Syx \text{ end} \rrbracket = \llbracket \text{new } x \text{ in } y \text{ end} \rrbracket = \llbracket y \rrbracket$.

(iv) Let $R \equiv \lambda y^{(loc \rightarrow \sigma) \rightarrow \sigma'}. \lambda z_1^\sigma, z_2^\sigma. y(\lambda x^{loc}. \text{if } !x = 0 \text{ then } z_1 \text{ else } z_2)$ and $S \equiv \lambda y^{\sigma \rightarrow \sigma \rightarrow \sigma'}. \lambda z^{loc \rightarrow \sigma}. y(\text{new } x \text{ in } x := 0; zx \text{ end})(\text{new } x \text{ in } x := 1; zx \text{ end})$. Then $\llbracket S \rrbracket^D$ is locally determined by Lemma 9.8 (i) and

$$\begin{aligned} \llbracket R(Sy) z_1 z_2 \rrbracket &= \llbracket Sy(\lambda x. \text{if } !x = 0 \text{ then } z_1 \text{ else } z_2) \rrbracket \\ &= \llbracket y(\text{new } x \text{ in } x := 0; \text{if } !x = 0 \text{ then } z_1 \text{ else } z_2 \text{ end}) \\ &\quad (\text{new } x \text{ in } x := 1; \text{if } !x = 0 \text{ then } z_1 \text{ else } z_2 \text{ end}) \rrbracket \\ &= \llbracket y(\text{new } x \text{ in } x := 0; z_1 \text{ end})(\text{new } x \text{ in } x := 1; z_2 \text{ end}) \rrbracket \\ &= \llbracket y z_1 z_2 \rrbracket \quad \text{by the remark after Example 7.1} \end{aligned}$$

hence $\llbracket R(Sy) \rrbracket = \llbracket y \rrbracket$.

(v) $R \equiv \lambda y^{\tau' \rightarrow \tau \rightarrow \sigma}. \lambda z_1^\tau, z_2^{\tau'}. y z_2 z_1$ and $S \equiv \lambda y^{\tau \rightarrow \tau' \rightarrow \sigma}. \lambda z_1^{\tau'}, z_2^\tau. y z_2 z_1$ define (even) an isomorphism, and obviously $\llbracket S \rrbracket^D$ is locally determined. \square

Theorem 9.10 (L-FD-types) *Let σ be a procedure type with $\text{ord}(\sigma) \leq 2$ and let $L \neq \emptyset$. Then σ is an L-FD-type.*

Proof: We will prove that

- (1) $loc^m \rightarrow cmd$ is an L-FD-type for every $m \geq 0$, $L \neq \emptyset$
- (2) $(loc^m \rightarrow cmd) \rightarrow cmd$ is an L-FD-type for every $m \geq 0$, $L \neq \emptyset$
- (3) $(loc \rightarrow \sigma)$ is an L-FD-type for all $L \neq \emptyset$, if σ is an L-FD-type for all $L \neq \emptyset$

From (1) we obtain by Theorem 9.7 that all first order types are L-FD-types, because $loc^m \rightarrow iexp \triangleleft_L loc^m \rightarrow cmd$ by Lemma 9.9 (i) and (ii). From (2) we obtain, again by Theorem 9.7, that $\sigma_1 \rightarrow \dots \rightarrow \sigma_k \rightarrow \theta$ is an L-FD-type, provided that all σ_i are first order types, namely: If $\sigma_i = loc^{m_i} \rightarrow \theta_i$ and $m = \max\{m_1, \dots, m_k\}$, then $\sigma_1 \rightarrow \dots \rightarrow \sigma_k \rightarrow \theta \triangleleft_L (loc^m \rightarrow cmd)^k \rightarrow \theta \triangleleft_L (loc^{m+k-1} \rightarrow cmd) \rightarrow cmd$ by Lemma 9.9 (i)–(iv). Together with (3) this implies that all types of the form $loc^m \rightarrow \sigma_1 \rightarrow \dots \rightarrow \sigma_k \rightarrow \theta$ with first order types σ_i are L-FD-types. But from these we obtain any arbitrary second order type by a permutation of the parameter types, hence another application of Theorem 9.7 combined with Lemma 9.9 (v) shows that all second order types are L-FD-types.

Proof of (1): Let $\sigma = loc^m \rightarrow cmd$ and $L \in W$. We will show that $(P_{n,L}^\sigma)_{n \in \mathbb{N}}$ with

$$P_{n,L}^\sigma \equiv \lambda y^\sigma. \lambda x_1^{loc}, \dots, x_m^{loc}. \\ \mathbf{proc} \ z: \mathbf{if} \ \bigwedge_{i=1}^m \text{abs}(!x_i) \leq n \wedge \bigwedge_{l \in L} \text{abs}(!l) \leq n \mathbf{then} \text{skip} \mathbf{else} \ \Omega \\ \mathbf{in} \ z; y \ x_1 \dots x_m; z \mathbf{end}$$

is an L -FD-sequence on σ with the additional property that, for every $n \in \mathbb{N}$, $\llbracket P_{n,L}^\sigma \rrbracket$ is idempotent and $\llbracket P_{n,L}^\sigma \rrbracket (\llbracket \sigma \rrbracket_L)$ is finite (hence $\llbracket \sigma \rrbracket_L$ is an SFP object). To this end we define $p_{n,L'}^{sto} \in \llbracket cmd \rrbracket_{L'}$ for every $n \in \mathbb{N}$ and $L' \in W$ by

$$p_{n,L'}^{sto} s = \begin{cases} s & \text{if } sL' \subseteq \{-n, \dots, n\} \\ \perp & \text{otherwise} \end{cases}$$

Clearly, for every $L' \in W$, $(p_{n,L'}^{sto})_{n \in \mathbb{N}}$ is an ω -chain of idempotent functions in $\llbracket cmd \rrbracket_{L'}$ such that $\bigsqcup_{n \in \mathbb{N}} p_{n,L'}^{sto} = \llbracket skip \rrbracket$ and $p_{n,L'}^{sto}(\text{Stores}_{L'})$ is finite for every $n \in \mathbb{N}$. Now note that

$$\llbracket P_{n,L}^\sigma \rrbracket f l_1 \dots l_m = p_{n,L \cup \{l_1, \dots, l_m\}}^{sto} \circ (f l_1 \dots l_m) \circ p_{n,L \cup \{l_1, \dots, l_m\}}^{sto}$$

for all $f \in \llbracket \sigma \rrbracket$ and $l_1, \dots, l_m \in Loc$. This implies immediately that $(\llbracket P_{n,L}^\sigma \rrbracket)_{n \in \mathbb{N}}$ is an ω -chain of idempotent functions with $\bigsqcup_{n \in \mathbb{N}} \llbracket P_{n,L}^\sigma \rrbracket = \text{id}_\sigma$. It remains to be shown that, for every $n \in \mathbb{N}$, $\llbracket P_{n,L}^\sigma \rrbracket^D \mid (\llbracket \sigma \rrbracket_L)^d$ is finitely determined and that $\llbracket P_{n,L}^\sigma \rrbracket (\llbracket \sigma \rrbracket_L)$ is finite.

To this end let $f \in \llbracket \sigma \rrbracket_L$ and $l_1, \dots, l_m \in Loc$. By Theorem 5.3, $\llbracket P_{n,L}^\sigma \rrbracket f l_1 \dots l_m \in \llbracket cmd \rrbracket_{L \cup \{l_1, \dots, l_m\}}$ is uniquely determined by its restriction to $\text{Stores}_{L \cup \{l_1, \dots, l_m\}}$ and hence also by the restriction of $f l_1 \dots l_m$ to $p_{n,L \cup \{l_1, \dots, l_m\}}^{sto}(\text{Stores}_{L \cup \{l_1, \dots, l_m\}}) \setminus \{\perp\}$. This means that

$$A = \{(l_1, \dots, l_m, s) \mid l_1, \dots, l_m \in Loc \wedge s \in p_{n,L \cup \{l_1, \dots, l_m\}}^{sto}(\text{Stores}_{L \cup \{l_1, \dots, l_m\}}) \setminus \{\perp\}\}$$

is a determining set for $\llbracket P_{n,L}^\sigma \rrbracket^D \mid (\llbracket \sigma \rrbracket_L)^d$. In order to obtain a *finite* determining set we define an equivalence relation \sim on A by

$$(l_1, \dots, l_m, s) \sim (l'_1, \dots, l'_m, s') \Leftrightarrow \exists \varphi \in \text{Fix}(L). \forall i \in \{1, \dots, m\}. \varphi l_i = l'_i \wedge s = s' \circ \varphi$$

This equivalence relation has finite index, because the equivalence class of an element (l_1, \dots, l_m, s) is uniquely determined by the sets $\{(i, j) \in \{1, \dots, m\}^2 \mid l_i = l_j\}$ and $\{(l, i) \in L \times \{1, \dots, m\} \mid l = l_i\}$, the function $(s \mid L) \in (L \xrightarrow{t} \{-n, \dots, n\})$ and the tuple $(s l_1, \dots, s l_m) \in \{-n, \dots, n\}^m$. Moreover, the restriction of f^d to any equivalence class is uniquely determined by its value for one representative of the class, because $f^d(\varphi l_1, \dots, \varphi l_m, s \circ \varphi^{-1}) = f(\varphi l_1) \dots (\varphi l_m) (s \circ \varphi^{-1}) = (f l_1 \dots l_m s) \circ \varphi^{-1} = f^d(l_1, \dots, l_m, s) \circ \varphi^{-1}$ by Theorem 5.3 (v). Thus, every representation system B for \sim is a finite determining set for $\llbracket P_{n,L}^\sigma \rrbracket^D \mid (\llbracket \sigma \rrbracket_L)^d$. Finally note that $(\llbracket P_{n,L}^\sigma \rrbracket f)^d =_B (\llbracket P_{n,L}^\sigma \rrbracket g)^d$ implies $\llbracket P_{n,L}^\sigma \rrbracket f = \llbracket P_{n,L}^\sigma \rrbracket (\llbracket P_{n,L}^\sigma \rrbracket f) = \llbracket P_{n,L}^\sigma \rrbracket (\llbracket P_{n,L}^\sigma \rrbracket g) = \llbracket P_{n,L}^\sigma \rrbracket g$ for all $f, g \in \llbracket \sigma \rrbracket_L$, i.e. $\llbracket P_{n,L}^\sigma \rrbracket f$ is uniquely determined by the finite value table

$$(\llbracket P_{n,L}^\sigma \rrbracket f l_1 \dots l_m s)_{(l_1, \dots, l_m, s) \in B}$$

The set of all such value tables is finite, because the possible entries for any element $(l_1, \dots, l_m, s) \in B$ can only range over the finite set $p_{n, L \cup \{l_1, \dots, l_m\}}^{sto}(Stores_{L \cup \{l_1, \dots, l_m\}})$. This shows that $\llbracket P_{n, L}^\sigma \rrbracket(\llbracket \sigma \rrbracket_L)$ is finite.

Proof of (2): Let $\sigma' = (loc^m \rightarrow cmd) \rightarrow cmd$ and $L \in W$. We continue to use the notation from the proof of (1), in particular σ stands for $loc^m \rightarrow cmd$.

The first idea which comes to mind for defining an L -FD-sequence on σ' is to imitate the definition of idempotent deflations [1] in *PCF* (Section 7 of Chapter 2), i.e. to define

$$P_{n, L}^{\sigma'} \stackrel{?}{=} \lambda y^{\sigma'}. \lambda z^\sigma. P_{n, L}^{cmd}(y(P_{n, L}^\sigma z))$$

Unfortunately this idea is too naive: As the elements of $\llbracket \sigma' \rrbracket_L$ cannot be considered as functions from $\llbracket \sigma \rrbracket_L$ to $\llbracket cmd \rrbracket_L$ (but also map $\llbracket \sigma \rrbracket_{L'}$ to $\llbracket cmd \rrbracket_{L'}$ for all $L' \supseteq L$), we cannot really expect that this simple *PCF*-approach carries over to *ALG*, and indeed it turns out that the functions $\llbracket P_{n, L}^{\sigma'} \rrbracket^D \mid (\llbracket \sigma' \rrbracket_L)^d$ are *not* finitely determined (nor do they have finite image). Somewhat to our own surprise, this problem can already be solved by using a slightly modified definition, namely

$$P_{n, L}^{\sigma'} \equiv \lambda y^{\sigma'}. \lambda z^\sigma. \mathbf{new} \ x \ \mathbf{in} \ P_{n, L}^{cmd}(y(\mathbf{if} \ !x < n \ \mathbf{then} \ x := !x + 1; P_{n, L}^\sigma z \ \mathbf{else} \ \Omega)) \ \mathbf{end}$$

The difference to the first definition is, that we now use a local variable x to count the procedure calls of z (as in Example 7.7) and that we let $P_{n, L}^{\sigma'} y z$ diverge as soon as the number of these procedure calls exceeds n . We will show that these new terms $P_{n, L}^{\sigma'}$ indeed define an L -FD-sequence on σ' .

Clearly, $P_{n, L}^{\sigma'} \in c\text{-ALG}_L^{\sigma' \rightarrow \sigma'}$ and $(\llbracket P_{n, L}^{\sigma'} \rrbracket)_{n \in \mathbb{N}}$ is an ω -chain with $\bigsqcup_{n \in \mathbb{N}} \llbracket P_{n, L}^{\sigma'} \rrbracket = \llbracket \lambda y. \lambda z. \mathbf{new} \ x \ \mathbf{in} \ y(x := !x + 1; z) \ \mathbf{end} \rrbracket = \llbracket \lambda y. \lambda z. y z \rrbracket = \text{id}_{\sigma'}$, where the second equality holds by Example 7.7. The hard part is to show that $\llbracket P_{n, L}^{\sigma'} \rrbracket^D \mid (\llbracket \sigma' \rrbracket_L)^d$ is finitely determined for every $n \in \mathbb{N}$:

Let A and \sim be defined as before. As the set A/\sim of all \sim -equivalence classes eq is finite, we may encode a word $w \in (A/\sim)^*$ as an integer and thus store it into a location. We use $eq.w$ to denote the concatenation of eq and w and $|w|$ to denote the length of w and—in order to simplify notation—we do not explicitly distinguish between a word w and its code. Below we will use an element $eq \in A/\sim$ as a(n incomplete) description of a procedure call of some fixed procedure $g \in \llbracket \sigma \rrbracket$, hence a word $w \in (A/\sim)^*$ stands for a sequence of such procedure calls.

Now let $Seq_{<n} = \{w \in (A/\sim)^* \mid |w| < n\}$ and let $l \in Loc \setminus L$. For every function $\Phi : Seq_{<n} \rightarrow \llbracket P_{n, L}^\sigma \rrbracket(\llbracket \sigma \rrbracket_L)$ we define $c_\Phi \in \llbracket \sigma \rrbracket_{L \cup \{l\}}$ by

$$c_\Phi l_1 \dots l_m s = \begin{cases} \Phi(sl) l_1 \dots l_m (s[class \ l_1 \dots l_m s. sl/l]) & \text{if } sl \in Seq_{<n} \\ \perp & \text{otherwise} \end{cases}$$

where $class \in \llbracket loc^m \rightarrow iexp \rrbracket_L$ is such that

$$class \ l_1 \dots l_m s = \begin{cases} eq & \text{if } (l_1, \dots, l_m, s) \in eq \\ \perp & \text{if } (l_1, \dots, l_m, s) \notin A \end{cases}$$

for all $l_1, \dots, l_m \in Loc$, $s \in Stores_{L \cup \{l_1, \dots, l_m\}}$. Note that by Theorem 8.1 (i) and (iii) such a function *class* exists and is uniquely determined. Moreover, each c_Φ is indeed in $\llbracket \sigma \rrbracket_{L \cup \{l\}}$, because it is defined by a finite case distinction on the contents of l from the function *class* and the functions $\Phi(w) \in \llbracket \sigma \rrbracket_L$ ($w \in Seq_{<n}$). To obtain some intuition for these functions, note that each c_Φ uses the location l to keep a record of its own history of procedure calls and diverges as soon as the recorded history becomes longer than n . The role of the index Φ is to describe how a call of c_Φ depends on the previously recorded history.

From the proof of (1) we know that $\llbracket P_{n,L}^\sigma \rrbracket(\llbracket \sigma \rrbracket_L)$ and $p_{n,L}^{sto}(Stores_L)$ are finite, hence the set

$$C = \{(c_\Phi, s[\varepsilon/l]) \mid \Phi : Seq_{<n} \rightarrow \llbracket P_{n,L}^\sigma \rrbracket(\llbracket \sigma \rrbracket_L) \wedge s \in p_{n,L}^{sto}(Stores_L) \setminus \{\perp\}\}$$

is also finite, and we will prove that it is a determining set for $\llbracket P_{n,L}^{\sigma'} \rrbracket^D \mid (\llbracket \sigma' \rrbracket_L)^d$. More precisely, we will show that for every $(g, s) \in \llbracket \sigma \rrbracket \times Stores$ there is some $(c_\Phi, s'[\varepsilon/l]) \in C$ such that $fc_\Phi(s'[\varepsilon/l]) = f'c_\Phi(s'[\varepsilon/l]) \Rightarrow \llbracket P_{n,L}^{\sigma'} \rrbracket fgs = \llbracket P_{n,L}^{\sigma'} \rrbracket f'gs$ whenever $f, f' \in \llbracket \sigma' \rrbracket_L$ (i.e. $\llbracket P_{n,L}^{\sigma'} \rrbracket^D \mid (\llbracket \sigma' \rrbracket_L)^d$ is not only finitely determined but also locally determined). The intuition for the proof is, that the computation of $\llbracket P_{n,L}^{\sigma'} \rrbracket fgs$ can be simulated by the computation of $fc_\Phi(s'[\varepsilon/l])$ for some appropriate Φ and s' . **This is a surprising fact** and we consider it as **one of the central points of the whole full abstraction proof**. Note that, although every single function $g \in \llbracket \sigma \rrbracket$ can only have access to finitely many locations $l_1, \dots, l_k \in Loc \setminus L$, there is *no upper bound* on the number k of these locations. Moreover, the values which are stored in l_1, \dots, l_k during the computation of $\llbracket P_{n,L}^{\sigma'} \rrbracket fgs$ can in no way be controlled by $\llbracket P_{n,L}^{\sigma'} \rrbracket f$, i.e. the simulation must cope with *arbitrarily large* values in l_1, \dots, l_k . On the other hand there are only *finitely many* functions c_Φ , which only use a *single* location $l \in Loc \setminus L$ and, by their very definition, can only store *finitely many* different values in l , namely the words w with $|w| \leq n$. Altogether this means that there is no hope for a naive simulation, which uses some direct encoding of the values in l_1, \dots, l_k into the contents of l . The trick is to use an ‘indirect encoding’ which is based on histories of procedure calls. This encoding will now be defined.

Let $g \in \llbracket \sigma \rrbracket$ and $s \in Stores$. The idempotence of $\llbracket P_{n,L}^\sigma \rrbracket$ implies that $\llbracket P_{n,L}^{\sigma'} \rrbracket fgs = \llbracket P_{n,L}^{\sigma'} \rrbracket f(\llbracket P_{n,L}^\sigma \rrbracket g)s$ for all $f \in \llbracket \sigma' \rrbracket$, hence we may assume that g itself is already contained in $\llbracket P_{n,L}^\sigma \rrbracket \llbracket \sigma \rrbracket$. Now let $l_1, \dots, l_k \in Loc \setminus L$ be such that $g \in \llbracket \sigma \rrbracket_{L \cup \{l_1, \dots, l_k\}}$, $s \in Stores_{L \cup \{l_1, \dots, l_k\}}$ and $l \in \{l_1, \dots, l_k\}$. For every equivalence class $eq \in A/\sim$ and every $i \in \{1, \dots, k\}$ we define $g_i^{eq} : \mathbb{Z}_\perp^k \rightarrow \mathbb{Z}_\perp$ by

$$g_i^{eq}(d_1, \dots, d_k) = g l'_1 \dots l'_m (t[d_1/l_1] \dots [d_k/l_k]) l_i \\ \text{where } (l'_1, \dots, l'_m, t) \in eq \text{ and } l'_1, \dots, l'_m \notin \{l_1, \dots, l_k\}$$

In order to see that the functions g_i^{eq} are well-defined, first note that every eq does indeed contain a tuple (l'_1, \dots, l'_m, t) with $l'_1, \dots, l'_m \notin \{l_1, \dots, l_k\}$. Moreover, if we have two such tuples in the same equivalence class eq , then we may assume that the corresponding permutation φ in the definition of \sim is contained in $Fix(L \cup \{l_1, \dots, l_k\})$

and then Theorem 5.3 (v) implies $g(\varphi l'_1) \dots (\varphi l'_m) ((t \circ \varphi^{-1}) [d_1/l_1] \dots [d_k/l_k]) l_i = g(\varphi l'_1) \dots (\varphi l'_m) ((t [d_1/l_1] \dots [d_k/l_k]) \circ \varphi^{-1}) l_i = g l'_1 \dots l'_m (t [d_1/l_1] \dots [d_k/l_k]) (\varphi^{-1} l_i) = g l'_1 \dots l'_m (t [d_1/l_1] \dots [d_k/l_k]) l_i$, i.e. both tuples lead to the same result.

Finally we define a value $d_i^w \in \mathbb{Z}_\perp$ for every $w \in (A/\sim)^*$ and $i \in \{1, \dots, k\}$ by

$$\begin{aligned} - d_i^\varepsilon &= s l_i \\ - d_i^{eq.w} &= g_i^{eq}(d_1^w, \dots, d_k^w) \end{aligned}$$

Intuitively, d_i^w is the current contents of the location l_i , if w describes the history of procedure calls of g (and if the initial contents of l_1, \dots, l_k is given by s). The above argumentation has shown that the values d_i^w are uniquely determined by the (incomplete) description w , hence w is indeed an ‘indirect encoding’ of the current contents of l_1, \dots, l_k . Moreover, the counter x in the definition of $P_{n,L}^{\sigma'}$ will guarantee that the sequence of procedure calls of g will never become longer than n , hence we will need only words w of length $\leq n$ for the encoding.

Now we are ready to choose the appropriate function c_Φ which will make our simulation work. Let $\Phi : Seq_{<n} \rightarrow \llbracket P_{n,L}^{\sigma'} \rrbracket(\llbracket \sigma \rrbracket_L)$ be such that

$$\begin{aligned} \Phi(w) l'_1 \dots l'_m t &=_{L \cup \{l'_1, \dots, l'_m\}} g l'_1 \dots l'_m (t [d_1^w/l_1] \dots [d_k^w/l_k]) \\ &\text{for all } l'_1, \dots, l'_m \in Loc \setminus \{l_1, \dots, l_k\}, t \in Stores \end{aligned}$$

It follows easily from Theorem 8.1 (ii) and (iv) that the function Φ exists and is uniquely determined. To obtain some intuition for Φ , note that the procedure calls $\Phi(w) l'_1 \dots l'_m$ and $g l'_1 \dots l'_m$ have the same effect on $L \cup \{l'_1, \dots, l'_m\}$, provided that w describes the history of procedure calls of g . Hence $c_\Phi l'_1 \dots l'_m$ indeed simulates $g l'_1 \dots l'_m$ in the following sense: First it reads the word w from the location l , then it behaves like $\Phi(w) l'_1 \dots l'_m$, i.e. it acts like $g l'_1 \dots l'_m$ on $L \cup \{l'_1, \dots, l'_m\}$, and finally it extends the contents w of l by the description eq of the current procedure call. The last step guarantees that the contents $eq.w$ of l after the call of c_Φ encodes the contents $d_1^{eq.w}, \dots, d_k^{eq.w}$ of l_1, \dots, l_k after the call of g . Of course, all this is only a vague intuition, which will now be replaced by a mathematically rigorous proof. In particular, our intuitive understanding of a ‘simulation’ will be expressed by an appropriate logical relation.

To this end let $s' = p_{n,L}^{sto}(s[0/l_1] \dots [0/l_k]) \in p_{n,L}^{sto}(Stores_L)$. We must show that $\llbracket P_{n,L}^{\sigma'} \rrbracket f g s$ is uniquely determined by $f c_\Phi(s'[\varepsilon/l])$. First note that $\llbracket P_{n,L}^{\sigma'} \rrbracket f g s = (\llbracket P_{n,L}^{cmd} \rrbracket (f g') (s[0/l'])) [s'/l']$, where l' is new, say $l' \notin L \cup \{l_1, \dots, l_k\}$, and $g' \in \llbracket \sigma \rrbracket_{L \cup \{l_1, \dots, l_k, l'\}}$ is defined by

$$g' l'_1 \dots l'_m t = \begin{cases} g l'_1 \dots l'_m (t [t l' + 1/l']) & \text{if } t l' < n \\ \perp & \text{otherwise} \end{cases}$$

Now let $S \in DEF_2^{\{l_1, \dots, l_k, l'\}} \subseteq OUT_2^L$ be defined by

$$\begin{aligned} S^{sto} = \{\perp\}^2 \cup \{ \vec{t} \in Stores^2 \mid \exists w \in (A/\sim)^*. t_1 l = w \wedge t_2 l' = |w| \leq n \wedge \\ \forall i \in \{1, \dots, k\}. t_2 l_i = d_i^w \wedge t_1 =_{Loc \setminus \{l_1, \dots, l_k, l'\}} t_2 \} \end{aligned}$$

Clearly, $(s[0/l_1] \dots [0/l_k][\varepsilon/l], s[0/l']) \in S^{sto}$, and if we can prove $(c_\Phi, g') \in S^\sigma$, then we obtain

$$(\llbracket P_{n,L}^{cmd} \rrbracket (fc_\Phi)(s[0/l_1] \dots [0/l_k][\varepsilon/l]), \llbracket P_{n,L}^{cmd} \rrbracket (fg')(s[0/l'])) \in S^{sto}$$

for all $f \in \llbracket \sigma \rrbracket_L$, because $\llbracket P_{n,L}^{cmd} \rrbracket \circ f$ is also in $\llbracket \sigma \rrbracket_L$. The left hand side of this pair equals $p_{n,L}^{sto}(fc_\Phi(s'[\varepsilon/l]))$ and the right hand side uniquely determines $\llbracket P_{n,L}^{\sigma'} \rrbracket fg s$. As S^{sto} is a partial function, this implies that $\llbracket P_{n,L}^{\sigma'} \rrbracket fg s$ is indeed uniquely determined by $fc_\Phi(s'[\varepsilon/l])$.

It remains to be shown that $(c_\Phi, g') \in S^\sigma$. It can be easily seen that $S^{loc} = \delta^2(Loc \setminus \{l_1, \dots, l_k, l'\})$, hence we must prove $(c_\Phi l'_1 \dots l'_m, g' l'_1 \dots l'_m) \in S^{cmd}$ for all $l'_1, \dots, l'_m \in Loc \setminus \{l_1, \dots, l_k, l'\}$. To this end let $(t_1, t_2) \in S^{sto} \setminus \{\perp\}^2$. Then there is some $w \in (A/\sim)^*$ with $t_1 l = w$, $t_2 l' = |w| \leq n$, $t_2 l_i = d_i^w$ for $i = 1, \dots, k$ and $t_1 =_{Loc \setminus \{l_1, \dots, l_k, l'\}} t_2$. If $t_1, t_2 \notin p_{n, L \cup \{l'_1, \dots, l'_m\}}^{sto}(Stores)$ then $c_\Phi l'_1 \dots l'_m t_1 = \perp$ because $class l'_1 \dots l'_m t_1 = \perp$, and $g' l'_1 \dots l'_m t_2 = \perp$ because $g \in \llbracket P_{n,L}^\sigma \rrbracket \llbracket \sigma \rrbracket$. If $|w| = n$ then $c_\Phi l'_1 \dots l'_m t_1 = \perp$ because $t_1 l = w \notin Seq_{<n}$, and $g' l'_1 \dots l'_m t_2 = \perp$ because $t_2 l' = |w| = n$. Hence we have $(c_\Phi l'_1 \dots l'_m t_1, g' l'_1 \dots l'_m t_2) = (\perp, \perp) \in S^{sto}$ in both cases. The only remaining case is $t_1, t_2 \in p_{n, L \cup \{l'_1, \dots, l'_m\}}^{sto}(Stores) \wedge |w| < n$. Then there is some $eq \in A/\sim$ with $class l'_1 \dots l'_m t_1 = eq$ and we obtain

$$\begin{aligned} g' l'_1 \dots l'_m t_2 &= g l'_1 \dots l'_m (t_2[t_2 l' + 1/l']) \\ &\quad \text{because } t_2 l' = |w| < n \\ &=_{L \cup \{l_1, \dots, l_k, l'_1, \dots, l'_m\}} g l'_1 \dots l'_m (t_1[d_1^w/l_1, \dots, d_k^w/l_k]) \\ &\quad \text{because } t_2[t_2 l' + 1/l'] =_{Loc \setminus \{l'\}} t_1[d_1^w/l_1, \dots, d_k^w/l_k] \\ &=_{L \cup \{l'_1, \dots, l'_m\}} \Phi(w) l'_1 \dots l'_m t_1 \\ &\quad \text{per definition of } \Phi \\ &=_{L \cup \{l'_1, \dots, l'_m\}} \Phi(w) l'_1 \dots l'_m (t_1[eq.w/l]) \\ &\quad \text{because } t_1 =_{L \cup \{l'_1, \dots, l'_m\}} t_1[eq.w/l] \\ &= c_\Phi l'_1 \dots l'_m t_1 \\ &\quad \text{because } class l'_1 \dots l'_m t_1 = eq \wedge t_1 l = w \end{aligned}$$

If $g' l'_1 \dots l'_m t_2 = c_\Phi l'_1 \dots l'_m t_1 = \perp$ then we are done, otherwise note that

$$\begin{aligned} - c_\Phi l'_1 \dots l'_m t_1 l &= eq.w \\ - g' l'_1 \dots l'_m t_2 l' &= t_2 l' + 1 = |eq.w| \\ - g' l'_1 \dots l'_m t_2 l_i &= g l'_1 \dots l'_m (t_1[d_1^w/l_1] \dots [d_k^w/l_k]) l_i = g_i^{eq}(d_1^w, \dots, d_k^w) = d_i^{eq.w} \\ &\quad \text{for every } i \in \{1, \dots, k\} \\ - g' l'_1 \dots l'_m t_2 &\text{ and } c_\Phi l'_1 \dots l'_m t_1 \text{ coincide on } Loc \setminus \{l_1, \dots, l_k, l'_1, \dots, l'_m, l'\} \end{aligned}$$

The latter observation implies that $g' l'_1 \dots l'_m t_2$ and $c_\Phi l'_1 \dots l'_m t_1$ even coincide on $Loc \setminus \{l_1, \dots, l_k, l'\}$. Altogether this proves $(c_\Phi l'_1 \dots l'_m t_1, g' l'_1 \dots l'_m t_2) \in S^{sto}$ and thus concludes the proof of (2).

Proof of (3): Let $\sigma' = loc \rightarrow \sigma$ and $L \in W$, $L \neq \emptyset$.

We choose some location $l \in Loc \setminus L$. By assumption, there are an L -FD-sequence $(P_{n,L}^\sigma)_{n \in \mathbb{N}}$ and an $(L \cup \{l\})$ -FD-sequence $(P_{n,L \cup \{l\}}^\sigma)_{n \in \mathbb{N}}$ on σ . For every $n \in \mathbb{N}$ let $P_{n,L \cup \{x\}}^\sigma \in \text{ALG}_L^{\sigma \rightarrow \sigma}$ be the term which is obtained from $P_{n,L \cup \{l\}}^\sigma$ by substituting a fresh variable x for the location constant l , and let $P_{n,L}^{\sigma'} \in c\text{-ALG}_L^{\sigma' \rightarrow \sigma'}$ be defined by

$$P_{n,L}^{\sigma'} \equiv \lambda y^{\sigma'}. \lambda x^{loc}. \mathbf{if} \bigvee_{l' \in L} EQ \ x \ l' \ \mathbf{then} \ P_{n,L}^\sigma(yx) \ \mathbf{else} \ P_{n,L \cup \{x\}}^\sigma(yx)$$

where $EQ \in c\text{-ALG}_\emptyset^{loc^2 \rightarrow iexp}$ is the equality on locations and $y^{\sigma'}$ is some fresh identifier. Let $f \in \llbracket \sigma' \rrbracket$. Then

$$\llbracket P_{n,L}^{\sigma'} \rrbracket f \ l' = \begin{cases} \llbracket P_{n,L}^\sigma \rrbracket (f \ l') & \text{if } l' \in L \\ \llbracket P_{n,L \cup \{l\}}^\sigma \rrbracket (f \ l) & \text{if } l' = l \end{cases}$$

and for $l' \notin L \cup \{l\}$ we conclude by Lemma 8.3 that

$$\begin{aligned} \llbracket P_{n,L}^{\sigma'} \rrbracket f \ l' &= \llbracket SWAP_{(l')}^\sigma \rrbracket (\llbracket P_{n,L}^\sigma \rrbracket (\llbracket SWAP_{(l')}^{\sigma'} \rrbracket f) \ l) \\ &= \llbracket SWAP_{(l')}^\sigma \rrbracket (\llbracket P_{n,L \cup \{l\}}^\sigma \rrbracket (\llbracket SWAP_{(l')}^{\sigma'} \rrbracket f \ l)) \end{aligned}$$

where (l') denotes the transposition of l and l' . From these equations it follows easily that $(\llbracket P_{n,L}^{\sigma'} \rrbracket)_{n \in \mathbb{N}}$ is an ω -chain with $\bigsqcup_{n \in \mathbb{N}} \llbracket P_{n,L}^{\sigma'} \rrbracket = \text{id}_{\sigma'}$.

It remains to be shown that $\llbracket P_{n,L}^{\sigma'} \rrbracket^D \mid (\llbracket \sigma' \rrbracket_L)^d$ is finitely determined for all $n \in \mathbb{N}$. Let $f \in \llbracket \sigma' \rrbracket_L$. Then $\llbracket SWAP_{(l')}^{\sigma'} \rrbracket f = f$ whenever $l' \in Loc \setminus L$ and thus we obtain from the above equations

$$\llbracket P_{n,L}^{\sigma'} \rrbracket f \ l' = \begin{cases} \llbracket P_{n,L}^\sigma \rrbracket (f \ l') & \text{if } l' \in L \\ \llbracket SWAP_{(l')}^\sigma \rrbracket (\llbracket P_{n,L \cup \{l\}}^\sigma \rrbracket (f \ l)) & \text{if } l' \notin L \end{cases}$$

Now let B and B' be finite determining sets for the functions $\llbracket P_{n,L}^\sigma \rrbracket^D \mid (\llbracket \sigma \rrbracket_L)^d$ and $\llbracket P_{n,L \cup \{l\}}^\sigma \rrbracket^D \mid (\llbracket \sigma \rrbracket_{L \cup \{l\}})^d$. Then, for every $l' \in L$, $(\llbracket P_{n,L}^\sigma \rrbracket (f \ l'))^d = \llbracket P_{n,L}^\sigma \rrbracket^D (f \ l')^d$ is uniquely determined by $(f \ l')^d \mid B$ and $(\llbracket P_{n,L \cup \{l\}}^\sigma \rrbracket (f \ l))^d = \llbracket P_{n,L \cup \{l\}}^\sigma \rrbracket^D (f \ l)^d$ is uniquely determined by $(f \ l)^d \mid B'$. Thus it follows from the above equation that $\llbracket P_{n,L}^{\sigma'} \rrbracket^D f^d = (\llbracket P_{n,L}^{\sigma'} \rrbracket f)^d$ is uniquely determined by $f^d \mid (L \times B) \cup (\{l\} \times B')$, i.e. $\llbracket P_{n,L}^{\sigma'} \rrbracket^D$ is indeed finitely determined. \square

We conjecture that the restriction $L \neq \emptyset$ can be dropped from Theorem 9.10 and that *all* the domains $\llbracket \sigma \rrbracket_L$ with $\text{ord}(\sigma) \leq 2$ are SFP objects (as we already know for $\sigma = loc^m \rightarrow cmd$). But the only way to prove this would be to *directly* construct L -FD-sequences for all types of order ≤ 2 in order to avoid applications of Lemma 9.9 (where the restriction $L \neq \emptyset$ comes from) and Theorem 9.7 (where the idempotence of functions gets lost). We preferred to take the *indirect* way via L -retracts, because it allowed us to restrict the tricky encoding in the proof of Theorem 9.10 to types of the form $(loc^m \rightarrow cmd) \rightarrow cmd$, and because we consider the use of L -retracts as an interesting technique in its own.

We are now ready to prove full abstraction.

Theorem 9.11 (approximation by definable functions) *Let σ be a procedure type of order 1 or 2 and let $L \neq \emptyset$. Then every $f \in \llbracket \sigma \rrbracket_L$ is the least upper bound of an ω -chain of definable functions $\llbracket M \rrbracket$ with $M \in c\text{-ALG}_L^\sigma$.*

Proof: Let $(P_n)_{n \in \mathbb{N}}$ be an L -FD-sequence on σ , and for every $n \in \mathbb{N}$ let B_n be a finite determining set for $(\llbracket P_n \rrbracket)^D \mid (\llbracket \sigma \rrbracket_L)^d$. By Theorem 9.3 there are terms $M_n \in c\text{-ALG}_L^\sigma$ with $\llbracket M_n \rrbracket^d =_{B_n} f^d$, hence $\llbracket P_n M_n \rrbracket^d = \llbracket P_n \rrbracket^D \llbracket M_n \rrbracket^d = \llbracket P_n \rrbracket^D f^d = (\llbracket P_n \rrbracket f)^d$ for every $n \in \mathbb{N}$. This implies $f = \bigsqcup_{n \in \mathbb{N}} \llbracket P_n \rrbracket f = \bigsqcup_{n \in \mathbb{N}} \llbracket P_n M_n \rrbracket$. \square

Now we obtain our full abstraction result by the usual argumentation [24]:

Theorem 9.12 (full abstraction) *Let σ be a type of order ≤ 3 and let $M_1, M_2 \in c\text{-ALG}_\emptyset^\sigma$. Then*

$$\llbracket M_1 \rrbracket = \llbracket M_2 \rrbracket \Leftrightarrow M_1 \approx M_2$$

Proof: Only ‘ \Leftarrow ’ remains to be proved. Let $\sigma = \tau_1 \rightarrow \dots \rightarrow \tau_k \rightarrow \theta$ ($k \geq 0$) and assume that $\llbracket M_1 \rrbracket \neq \llbracket M_2 \rrbracket$, i.e. there are $d_j \in \llbracket \tau_j \rrbracket$ for $j = 1, \dots, k$ and $s \in \text{Stores}$ such that

$$\llbracket M_1 \rrbracket d_1 \dots d_k s \neq \llbracket M_2 \rrbracket d_1 \dots d_k s$$

Let $L \neq \emptyset$ be such that $d_j \in \llbracket \tau_j \rrbracket_L$ for $j = 1, \dots, k$. By Theorem 9.11, every d_j is the least upper bound of a directed set of definable elements in $\llbracket \tau_j \rrbracket_L$ (for $\tau_j = \text{loc}$, d_j is itself definable), hence the local continuity of $\llbracket M_1 \rrbracket$ and $\llbracket M_2 \rrbracket$ implies that there are $N_j \in c\text{-ALG}_L^{\tau_j}$ with

$$\llbracket M_1 N_1 \dots N_k \rrbracket s \neq \llbracket M_2 N_1 \dots N_k \rrbracket s$$

From this, it is easy to construct a program context $C[\]$ with $\llbracket C[M_1] \rrbracket \neq \llbracket C[M_2] \rrbracket$. Hence $M_1 \not\approx M_2$. \square

We have formulated Theorem 9.12 for *closed* terms of order ≤ 3 . Instead, we could have used *open* terms of order ≤ 2 whose only free identifiers are of order ≤ 2 . In any case the main role is played by procedure identifiers of order ≤ 2 ; that’s why we speak of ‘full abstraction for the second order subset’.

10 Variants of the Language ALG

We have included some features in our language ALG which are not typical for an ALGOL-like language, hence it seems worth to discuss whether they can be removed or whether some further ones can be added.

Removing the parallel conditional

The observant reader may have realized that the parallel conditional did not really play a role in our full abstraction proof, and indeed it can be removed from the language ALG without any difficulties:

Let ALG^{seq} be the *sequential subset* of ALG , which is obtained from ALG by removing the constant $pcond$. If we replace AUX by $AUX \setminus \{Pcond\}$ in the definition of the signature Σ , then we obtain a new signature Σ^{seq} which is strictly greater than Σ , in particular it contains ground relations which are similar to the *sequentiality relations* of Chapter 2. One such example is the ground relation R with

- $R^{loc} = \delta^3 Loc$
- $R^\gamma = \{\vec{d} \in (D^\gamma)^3 \mid d_1 = \perp \vee d_2 = \perp \vee d_1 = d_2 = d_3\} \quad \text{for } \gamma = int, sto$

which is contained in $(\Sigma^{seq})^L$ for all $L \in W$ (as can be easily checked). If we replace Σ by Σ^{seq} in the construction of our denotational model, then we obtain a ‘smaller’ model which is computationally adequate and fully abstract for the language ALG^{seq} . This can be proved exactly as before, because we have never made any real use of the parallel conditional in the proofs of computational adequacy and full abstraction. In the new model we can validate additional denotational equivalences like

$$\llbracket y \text{ skip } \Omega + y \Omega \text{ skip} \rrbracket = \llbracket 2 * y \Omega \Omega \rrbracket$$

where $y : cmd \rightarrow cmd \rightarrow iexp$. This is a variant of Example 9.1 in Chapter 2, and it can be validated similarly: Let $\eta \in Env$, $s \in Stores$ and let R be defined as above. Then $(\llbracket skip \rrbracket, \llbracket \Omega \rrbracket, \llbracket \Omega \rrbracket) \in R^{cmd}$, $(\llbracket \Omega \rrbracket, \llbracket skip \rrbracket, \llbracket \Omega \rrbracket) \in R^{cmd}$ and $(s, s, s) \in R^{sto}$, hence $(\llbracket y \text{ skip } \Omega \rrbracket \eta s, \llbracket y \Omega \text{ skip} \rrbracket \eta s, \llbracket y \Omega \Omega \rrbracket \eta s) \in \eta y R^{cmd} R^{cmd} R^{sto} \subseteq R^{int}$. This means that one of the first two components must be \perp or all three must be equal, and in both cases the above equality follows easily.

Note that—for the first time in this chapter—we have used a relation of arity greater than 2 for proving an observational congruence. Indeed, it can be shown that *no binary relation* works for this example, and similar examples show that there is *no upper bound at all* on the arity of relations which are needed for proving observational congruences in ALG^{seq} . This is in contrast to ALG itself, where binary relations seem to be sufficient (cf. Sections 7 and 11).

Removing the snap back effect

In contrast to the parallel conditional, the snap back effect does play an important role in our full abstraction proof, and it is not (yet) clear whether we can obtain a fully abstract model without it.

First note that there are at least two (significantly) different options for a language without snap back, namely

- a language ALG^{-se} in which integer expressions have *no* side effects at all [8, 9], not even temporary ones,
- a language ALG^{+se} in which integer expressions may have *permanent* side effects [35].

ALG^{-se} can be defined by removing the constant seq_{iexp} from ALG . As it is a subset of ALG , its observational congruence relation can only be coarser than the ALG -congruence, and indeed it is *strictly* coarser, as is illustrated by the terms

$$M_i \equiv \mathbf{new} \ x \ \mathbf{in} \ y^{cmd \rightarrow cmd} (x := 1; x' := i); \mathbf{if} \ !x = 1 \ \mathbf{then} \ \Omega \ \mathbf{end} \quad (i = 1, 2)$$

In ALG^{-se} we have $M_1 \approx M_2$ by the following (somewhat informal) argumentation: If we start M_1 and M_2 in the same initial store, then it only depends on this store (and not on the particular parameter) whether the procedure y ignores its parameter or whether it calls its parameter at least once. In the first case it is obvious that M_1 and M_2 either both diverge or terminate with the same result. In the second case the local variable x contains 1 after $y(x := 1; x' := 1)$ and also after $y(x := 1; x' := 2)$, because the global procedure y has no access to x *and* because the contents of x cannot snap back to 0. Hence M_1 and M_2 both diverge in this case. In ALG itself we have $M_1 \not\approx M_2$ because M_1 and M_2 can be distinguished by the program context $C[\] \equiv \mathbf{new} \ x' \ \mathbf{in} \ \mathbf{proc} \ y^{cmd \rightarrow cmd} : \lambda z^{cmd}. x' := (z; !x') \ \mathbf{in} \ [\]; !x' \ \mathbf{end} \ \mathbf{end}$.

ALG^{+se} can be defined to have the same syntax as ALG^{seq} (the parallel conditional does not make sense if integer expressions can have permanent side effects) but of course it must have a rather different operational and denotational semantics, in particular $\llbracket iexp \rrbracket$ must consist of functions from D^{sto} to $D^{sto} \times D^{int}$. The two observational congruence relations of ALG^{seq} and ALG^{+se} are incomparable: On the one hand, the above terms M_1 and M_2 are observationally congruent in ALG^{+se} (with the same argumentation as before) but not in ALG^{seq} . On the other hand there are trivial examples of ALG^{seq} -congruences which do not hold in ALG^{+se} , e.g. $(x := 0; 1) \approx 1$.

As to finding fully abstract semantics, both ALG^{-se} and ALG^{+se} seem to create new problems. Although ALG^{-se} is just a syntactic restriction of ALG , we cannot use the same trick as for ALG^{seq} in order to obtain a larger signature (and thus a ‘smaller’ model), because AUX does not contain an auxiliary function which corresponds to the constant seq_{iexp} . Hence, if there is an appropriate signature at all for ALG^{-se} , new ideas seem to be necessary for defining it. For ALG^{+se} it is of course necessary to restructure the whole denotational model before searching for an appropriate signature. Some first steps which we have made into this direction seem to suggest that ALG^{+se} is more promising than ALG^{-se} .

Removing reference parameters

We have included parameters of type *loc* as a matter of convenience, but they are not important for our full abstraction result. Only some minor changes are necessary if we want to remove them from ALG : Of course ‘ $\mathbf{new} \ x \ \mathbf{in} \ \dots \ \mathbf{end}$ ’ can no longer be considered as syntactic sugar; it must be introduced as an extra binding mechanism. Besides that we must only insist that environments η are injective on the set Id^{loc} because sharing between location identifiers is no longer possible in the restricted language. At some points the full abstraction proof must be carried out with more care in order to avoid redundant λ -abstractions (with reference parameters) in the

distinguishing contexts (cf. [31]), but all in all it will even become simpler because some nasty case distinctions will disappear (especially in the proof of Theorem 9.3).

Adding value parameters

It should be no problem to add parameters of type *int* to ALG, i.e. to introduce call-by-value as an additional parameter passing mechanism (at ground type level). We conjecture that they can be handled similarly as the parameters of type *loc*.

11 Conclusion and Open Questions

We have defined a denotational semantics for an ALGOL-like language, and we have proved that it is fully abstract for the second order subset of that language. Our denotational model satisfies the usual ‘goodness’ criteria, namely it is defined in a cartesian closed category, it is syntax-independent and—despite of its rather technical definition—it allows us to give rigorous and simple proofs for all the test equivalences which have been proposed in the literature. The simplicity of these equivalence proofs is partially due to the fact that they are all based on relations of arity ≤ 2 from the sub-signature *OUT*. This leads us to

Conjecture 11.1 *Theorem 9.12 remains valid, if we use a smaller signature for our model construction, namely the signature $\bar{\Sigma}$ with*

$$\bar{\Sigma}_1^L = OUT_1^L \cup \{(\{\perp_{int}\}, \{\perp_{sto}\}, Loc)\} \quad \bar{\Sigma}_2^L = OUT_2^L \quad \bar{\Sigma}_n^L = \emptyset \text{ for } n > 2$$

From our efforts to construct counter-examples, we have already gained some evidence that Conjecture 11.1 really holds. This would increase the ‘tastefulness’ of our model, because *OUT* (and hence $\bar{\Sigma}$) is defined more concretely than the original signature Σ . Moreover we would come closer to O’Hearn and Tennent’s parametric functor model [21], and so it could finally turn out that their model is also fully abstract for the second order subset of ALG. Therefore we consider Conjecture 11.1 as a worthwhile subject of further research.

The most obvious open question is of course, whether our model is fully abstract for the full language ALG and not only for the second order subset. We believe that the answer is negative: Our intuition is that a global procedure acts on a local variable like a pure λ -term and hence the full abstraction problem for ALG should be closely related to the definability problem in the pure (simply typed) λ -calculus. From [10] it follows that (at least for a finite ground type) the λ -definable functions of order 3 cannot be characterized by logical relations, and so we expect that full abstraction for our ALG-model also fails (already) at order 3. In order to repair this, one might try to use ‘Kripke logical relations of varying arity’ [6, 19] instead of our finitary logical relations, but this would certainly lead to a terribly difficult model construction and it is questionable whether such a model would provide any new insights into the nature of local variables. Hence we think that our ‘full abstraction

for the second order subset' is indeed the best result which one may expect at the current state of the art.

One may finally wonder whether our techniques can be transferred to call-by-value (i.e. ML-like as opposed to ALGOL-like) languages [22]. This is a question which we have not yet investigated. Although the observations in [22] indicate that additional problems might come up in the call-by-value setting, we are confident that at least our main ideas will be helpful.

Index

- $(A \xrightarrow{t} B)$, 4
- $(D \xrightarrow{c} E)$, 4
- $(d_1 \Rightarrow \dots \Rightarrow d_k \Rightarrow e)$, 19
- $C[M]$, 2
- L -closure, 59
- L -definable ground relation, 41
- L -retract, 64
- L -section-retraction-pair, 64
- $M \approx N$, 2
- $M[\bar{x} := \bar{N}]$, 6, 27
- $M[x := N]$, 6, 27
- $M[x_1, \dots, x_k := N_1, \dots, N_k]$, 6, 27
- R^τ , 11, 40
- R^φ , 42
- R_L , 41
- $S_{A,B}^n$, 16
- W - Σ -lcpo, 34
- W - Σ -**LCPO**, 35
- W -lcpo, 33
- W -locally complete partial order, 33
- W -sorted (relation) signature, 34
- W -**LCPO**, 33
- $Asgn$, 39
- AUX , 38
- c - ALG^τ , 27
- c - ALG_L^τ , 27
- $cPCF^\tau$, 6
- $Cond$, 11
- $Cond_\gamma$, 39
- $Conf_L^\theta$, 30
- $Const_n$, 38
- $Cont$, 38
- DEF_n^L , 41
- Env , 12, 46
- ALG^τ , 26
- ALG_L^τ , 27
- Γ , 38
- Id^τ , 6, 26
- Loc , 23
- $\sqcup \Delta$, 4
- $\sqcup_D \Delta$, 4
- Ω , 7
- Ω_τ , 7
- OUT_n^L , 41
- $Pcond$, 39
- $\mathcal{P}_{fin}(A)$, 4
- Por , 5
- $Pred$, 11, 38
- Σ -dcpo, 8
- Σ -homomorphism, 8, 35
- Σ -**DCPO**, 8
- $Stores$, 38
- $Stores_L$, 38
- $Succ$, 11, 38
- $Supp(\varphi)$, 42
- $SWAP_\varphi^\sigma$, 59
- PCF^τ , 6
- $Type$, 6, 25
- \leq^τ , 12
- \leq_L^τ , 49
- $\xrightarrow{*}$, 7, 29
- $beh(P)$, 1, 7, 29
- \perp , 4
- \perp_D , 4
- \perp_γ , 38
- \perp_σ , 40
- \perp_τ , 11
- $\rightarrow_\triangleright$, 28
- δD , 8
- $\delta^n D$, 8
- $dom(f)$, 4
- μf , 10

- μ_D , 10
- μ_τ , 11
- $free(M)$, 6, 27
- id_γ , 38
- id_σ , 40
- int , 38
- λ -model, 11
- $locns(M)$, 27
- $\llbracket K \rrbracket$, 48
- $\llbracket M \rrbracket$, 1, 12
- $\llbracket \tau \rrbracket$, 11, 39, 40
- $\llbracket \tau \rrbracket_L$, 40
- $\llbracket c \rrbracket$, 11, 43
- ms_{init} , 29
- $next$, 23
- $ord(\tau)$, 6, 25
- \overline{ms} , 48
- \rightarrow , 7, 28
- $\sigma \triangleleft_L \sigma'$, 64
- $sto \Rightarrow int$, 38
- $sto \Rightarrow sto$, 38
- sto , 38
- $supp(d)$, 41
- $f =_C g$, 4
- $f \mid C$, 4
- $f \setminus a$, 4
- $f : A \hookrightarrow B$, 4
- $f : A \rightarrow B$, 4
- $f[\bar{b}/\bar{a}]$, 4
- $f[b_1, \dots, b_n/a_1, \dots, a_n]$, 4
- f^d , 13, 60
- p^D , 63
- s_{init} , 47
- L -FD-sequence, 64
- L -FD-type, 64
- L -SR-pair, 64
- DCPO**, 4
- applicative structure, 12
- arity
 - of a ground relation, 39
 - of a relation symbol, 8, 34
- auxiliary function, 38
- Berry-Plotkin function, 19
- call by name, 26
- client, 54
- closed term, 6, 27
- completely decurried, 13, 60
- computationally adequate, 1, 47
- configuration, 28
- consistent configuration, 31
- constants
 - of **ALG**, 26
 - of **PCF**, 6
- context, 2
- continuous, 4
- Curien monsters, 19
- dangling reference, 31
- dcpo, 4
- denotational semantics, 1
- determining function, 63
- determining set, 63
- directed, 4
- directed complete, 4
- environment, 12, 46
- evaluation context, 28
- finite permutation, 42
- finitely determined, 63
- free, 6, 27
- fully abstract, 2
- ground relation, 39
- Gustave's function, 19
- identifier, 6, 26
- instance variable, 54
- Kripke logical relation, 49
- least upper bound, 4
- locally continuous, 33
- locally determined, 63
- location, 23
- location identifier, 26
- logical relation, 11, 12
- lub, 4

- marked store, 23
- marked store model, 23
- meaning
 - of a *PCF*-constant, 11
 - of a *PCF*-term, 12
 - of a *PCF*-type, 11
 - of a configuration, 48
 - of a term, 1
 - of an ALG-constant, 43
 - of an ALG-term, 46
 - of an ALG-type, 39
- method, 54
- new location, 47
- nonstandard element, 2
- object, 54
- observable behavior, 1
 - of a *PCF*-program, 7
 - of an ALG-program, 29
- observationally congruent, 2
- operational semantics, 1
- order
 - of a *PCF*-type, 6
 - of an ALG-type, 25
- parallel conditional, 25
- parallel or, 5
- permanent side effect, 74
- pointed
 - W - Σ -lcpo, 34
 - W -lcpo, 33
 - Σ -dcpo, 8
 - dcpo, 4
- preserve, 39
- procedure identifier, 26
- procedure type, 25
- program context, 2
- programs, 1
 - of ALG, 27
 - of *PCF*, 6
- reference parameter, 26
- relation signature, 8
- relation symbol, 8, 34
- representation independence, 54
- representation invariant, 54
- representational abstraction, 54
- sequentiality relation, 16
- signature, 8
- simultaneous substitution, 6, 27
- single threaded, 28
- snap back effect, 25
- stable function, 19
- stack discipline, 24
- step function, 19
- store, 38
- substitution, 6, 27
- support, 41
- terms, 1
 - of ALG, 26
 - of *PCF*, 6
- thunk, 26
- transition relation
 - for ALG, 28
 - for *PCF*, 7
- transposition, 44
- type
 - of a *PCF*-constant, 6
 - of a *PCF*-term, 6
 - of an ALG-constant, 26
 - of an ALG-term, 26
 - of an identifier, 6
- types
 - of ALG, 25
 - of *PCF*, 6
- variable, 26

Bibliography

- [1] Samson Abramsky and Achim Jung. Domain theory. In S. Abramsky, D. M. Gabbay, and T. S. E. Maibaum, editors, *Handbook of Logic in Computer Science*, volume III, pages 1–168. Oxford University Press, 1995.
- [2] Jaco de Bakker. *Mathematical Theory of Program Correctness*. International Series in Computer Science. Prentice Hall, 1980.
- [3] Michael J. C. Gordon. *The Denotational Description of Programming Languages*. Springer-Verlag, 1979.
- [4] Carl A. Gunter. *Semantics of Programming Languages: Structures and Techniques*. Foundations of Computing Series. MIT Press, 1992.
- [5] Joseph Y. Halpern, Albert R. Meyer, and Boris A. Trakhtenbrot. The semantics of local storage, or what makes the free-list free? In *11th Annual ACM Symposium on Principles of Programming Languages*, pages 245–257, 1984.
- [6] Achim Jung and Jerzy Tiuryn. A new characterization of lambda definability. In *Proc. Int'l Conf. on Typed Lambda Calculi and Applications (TLCA)*, Springer LNCS 664, pages 230–244, Utrecht, The Netherlands, March 1993.
- [7] Peter J. Landin. A correspondence between Algol 60 and Church's lambda notation. *Comm. ACM*, 8:89–101, 158–165, 1965.
- [8] Arthur F. Lent. The category of functors from state shapes to bottomless cpos is adequate for block structure. Master's thesis, M.I.T., Cambridge, February 1992.
- [9] Arthur F. Lent. The category of functors from state shapes to bottomless cpos is adequate for block structure. In *Proc. ACM SIGPLAN Workshop on State in Programming Languages* (available as Technical Report YALEU/DCS/RR-968, Yale University), pages 101–119, Copenhagen, Denmark, 1993.
- [10] Ralph Loader. The undecidability of λ -definability. In M. Zeleny, editor, *The Church Festschrift*. CSLI/University of Chicago Press, 1994.
- [11] QingMing Ma and John C. Reynolds. Types, abstraction and parametric polymorphism. In S. Brookes, M. Main, A. Melton, M. Mislove, and D. Schmidt,

- editors, *Proc. 7th Conf. on Mathematical Foundations of Programming Semantics*, Springer LNCS 598, pages 1–40, Pittsburgh, March 1991.
- [12] Albert R. Meyer. Semantical paradigms: Notes for an invited lecture, with two appendices by Stavros Cosmadakis. In *Proc. 3rd IEEE Symp. on Logic in Computer Science*, pages 236–253, Edinburgh, 1988.
 - [13] Albert R. Meyer and Kurt Sieber. Towards fully abstract semantics for local variables: Preliminary report. In *Proc. 15th Annual ACM Symp. on Principles of Programming Languages*, pages 191–203, San Diego, 1988.
 - [14] Robin Milner and Mads Tofte. *Commentary on Standard ML*. MIT Press, 1991.
 - [15] Robin Milner, Mads Tofte, and Robert Harper. *The Definition of Standard ML*. MIT Press, 1990.
 - [16] John C. Mitchell. Representation independence and data abstraction (Preliminary version). In *Proc. 13th Annual ACM Symp. on Principles of Programming Languages*, pages 263–276, St. Petersburg, Florida, 1986.
 - [17] John C. Mitchell. Type systems for programming languages. In J. van Leeuwen, editor, *Handbook of Theoretical Computer Science, volume B*, chapter 8, pages 365–458. North-Holland, 1990.
 - [18] Hanne Riis Nielson and Flemming Nielson. *Semantics with Applications: A Formal Introduction*. Wiley Professional Computing. Wiley, 1992.
 - [19] Peter W. O’Hearn and Jon G. Riecke. Kripke logical relations and PCF. *Information and Computation*, 120(1):107–116, July 1995.
 - [20] Peter W. O’Hearn and Robert D. Tennent. Semantics of local variables. In M. P. Fourman, P. T. Johnstone, and A. M. Pitts, editors, *Proc. LMS Symposium on Applications of Categories in Computer Science, Durham 1991*, LMS Lecture Note Series 177, pages 217–238. Cambridge University Press, 1992.
 - [21] Peter W. O’Hearn and Robert D. Tennent. Relational parametricity and local variables. In *Proc. 20th Annual ACM Symposium on Principles of Programming Languages*, pages 171–184, Charleston, 1993.
 - [22] Andrew M. Pitts and Ian D. B. Stark. Observable properties of higher order functions that dynamically create local names, or: What’s *new*? In Andrzej M. Borzyszkowski and Stefan Sokołowski, editors, *Proc. 18th International Symposium on Mathematical Foundations of Computer Science*, Springer LNCS 711, pages 122–141, 1993.
 - [23] Gordon D. Plotkin. A powerdomain construction. *SIAM Journal on Computing*, 5(3):452–487, September 1976.

- [24] Gordon D. Plotkin. LCF considered as a programming language. *Theoretical Computer Science*, 5:223–256, 1977.
- [25] Gordon D. Plotkin. Lambda-definability in the full type hierarchy. In J.P. Seldin and J.R. Hindley, editors, *To H. B. Curry: Essays on Combinatory Logic, Lambda Calculus and Formalism*, pages 363–374. Academic Press, 1980.
- [26] Gordon D. Plotkin. A structural approach to operational semantics. Technical Report DAIMI FN-19, Aarhus University, Computer Science Department, Denmark, 1981.
- [27] John C. Reynolds. The essence of ALGOL. In J. deBakker and van Vliet, editors, *Int’l. Symp. Algorithmic Languages*, pages 345–372. IFIP, North-Holland, 1981.
- [28] Kurt Sieber. Reasoning about sequential functions via logical relations. In M. P. Fourman, P. T. Johnstone, and A. M. Pitts, editors, *Proc. LMS Symposium on Applications of Categories in Computer Science, Durham 1991*, LMS Lecture Note Series 177, pages 258–269. Cambridge University Press, 1992.
- [29] Kurt Sieber. New steps towards full abstraction for local variables. In *Proc. ACM SIGPLAN Workshop on State in Programming Languages* (available as Technical Report YALEU/DCS/RR-968, Yale University), pages 88–100, Copenhagen, Denmark, 1993.
- [30] Kurt Sieber. Full abstraction for the second order subset of an ALGOL-like language. In *Mathematical Foundations of Computer Science (MFCS)*, Springer LNCS 841, pages 608–617, Košice, Slovakia, August 1994.
- [31] Allen Stoughton. Mechanizing logical relations. In S. Brookes et al., editors, *Proc. 9th Int’l Conf. Mathematical Foundations of Programming Semantics*, Springer LNCS 802, pages 359–377, New Orleans, 1993.
- [32] Robert D. Tennent. Semantical analysis of specification logic. *Information and Computation*, 85:135–162, 1990.
- [33] Robert D. Tennent. *Semantics of Programming Languages*. International Series in Computer Science. Prentice Hall, 1991.
- [34] Boris A. Trakhtenbrot, Joseph Y. Halpern, and Albert R. Meyer. From denotational to operational and axiomatic semantics for ALGOL-like languages: an overview. In Edmund Clarke and Dexter Kozen, editors, *Proc. Logics of Programs*, Spriger LNCS 164, pages 474–500, Pittsburgh, 1983.
- [35] Stephen Weeks and Matthias Felleisen. On the orthogonality of assignments and procedures in Algol. In *Proc. 20th Annual ACM Symposium on Principles of Programming Languages*, pages 57–70, Charleston, 1993.
- [36] Glynn Winskel. *Formal Semantics of Programming languages*. Foundations of Computing Series. MIT Press, 1993.