

Unfolding Tutorial

Top Workshop

Introduction



- Unfolding and long and complicated a procedure and too much to explain everything in one hour.
- Similarly, setting up and running a realistic unfolding is probably not going to be too useful with the limited time we have.
- Therefore, this tutorial is going to explain unfolding, from a practical point-of-view.
- I will explain the terminology that is used and explain the tests you need to perform in your analysis.
 - There are no stupid questions! Interrupt me and ask anything.
 - There will also be time for questions at the end.
- For a more pedagogical overview, see Baptise's talk: https://indico.cern.ch/event/794004/contributions/3326125/attachments/1802168/2939911/
 UnfoldingReview.pdf
- And for a walkthrough, see here: http://dpnc.unige.ch/~sfyrla/teaching/Statistics/
 handsOn4.html

What is Unfolding?



 Unfolding is more generally known as "deconvolution" where we have some signal f convoluted with some noise G to give some recorded data h.

$$f * G = h$$

- In particle physics f and h are generally discreet data in the form of binned histograms and G is a combination of detector smearing and acceptance effects.
- So unfolding is just the process of going from $h \rightarrow f$.
- When **f** and **h** are histograms (i.e. vectors of data), **G** has the form of a matrix and the process of going from $\mathbf{h} \to \mathbf{f}$ is an example of a matrix inversion problem.



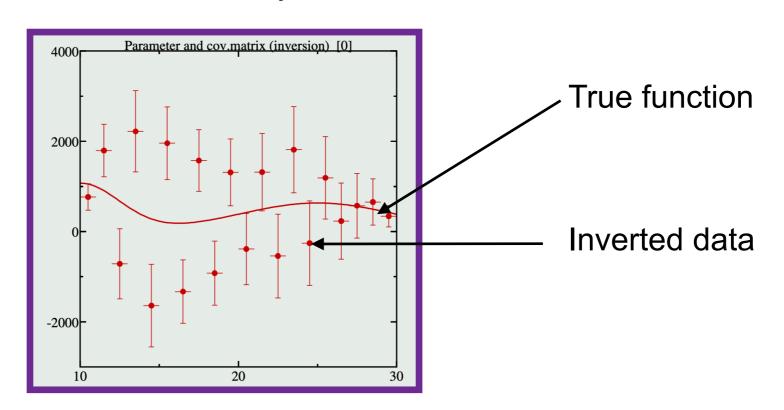
Why Matrix Inversion sucks



- We usually build this matrix (called the response matrix) from Monte Carlo (MC).
- So what happens if we invert the matrix and apply it to our data vector?

$$f = G^{-1}h$$
 $V_f = G^{-1} V_h (G^{-1})^T$

Basically, this:

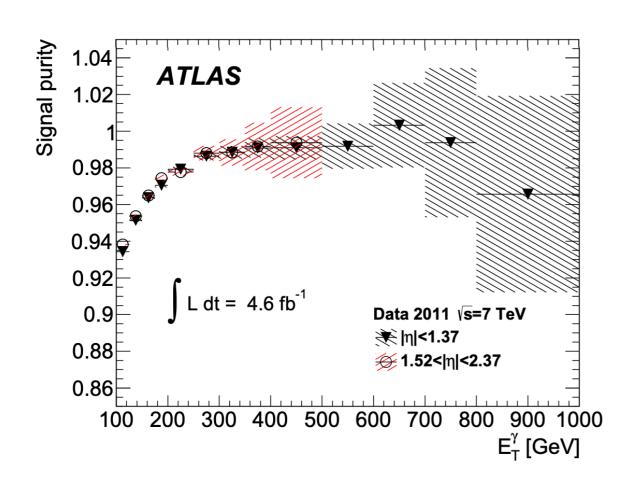


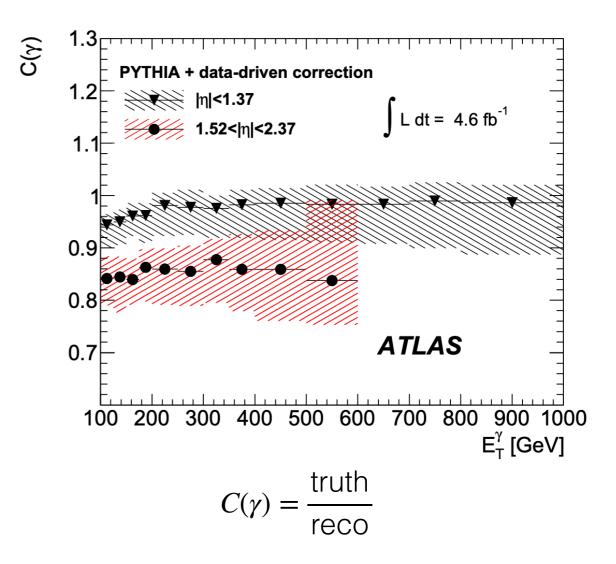
- Large anti-correlations in the covariance matrix allow this result (which actually agrees with the true function). What does that mean?
- It means that statistical fluctuations get amplified and you get stupid results. We need
 to dampen (regularise) these fluctuations somehow, and this is what almost all
 unfolding methods do.

Bin-by-bin unfolding



- The first method is the simplest but also the most limited in scope.
- It can only be used when "purity" is very high, i.e. most events at truth level do not migrate to different bins after detector effects.
- Correction factors are then used to correct the data to truth level.
- A simple method that has it's uses, but not often useful in top.

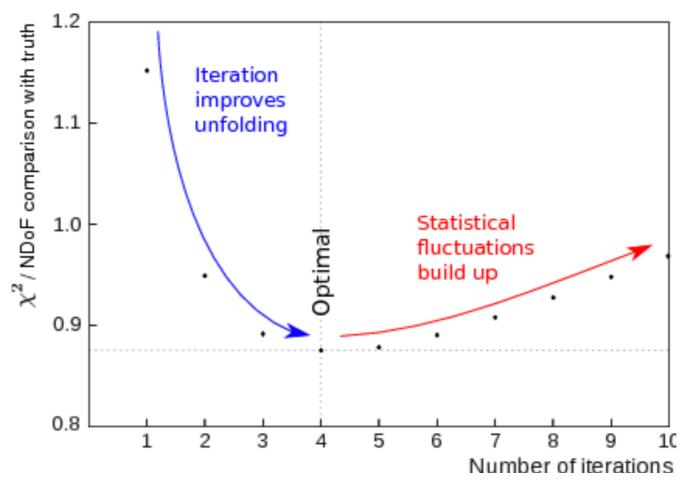




Iterative Bayesian Unfolding



- Far more commonly used is Bayesian Iterative Unfolding (IBU).
- In this unfolding method we use Bayes theorem recursively and use our truth distribution as a prior to control the harmonic oscillations.
- Has the slightly unusual feature that the more iterations you do, the weaker the regularisation.

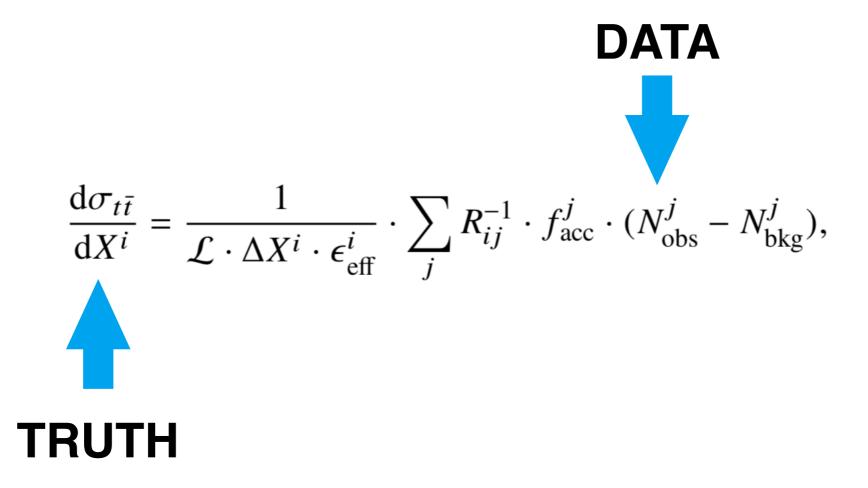


Finding the optimal stopping point is an important feature of using IBU.

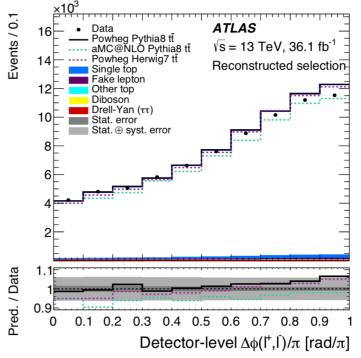


$$\frac{\mathrm{d}\sigma_{t\bar{t}}}{\mathrm{d}X^{i}} = \frac{1}{\mathcal{L} \cdot \Delta X^{i} \cdot \epsilon_{\mathrm{eff}}^{i}} \cdot \sum_{j} R_{ij}^{-1} \cdot f_{\mathrm{acc}}^{j} \cdot (N_{\mathrm{obs}}^{j} - N_{\mathrm{bkg}}^{j}),$$





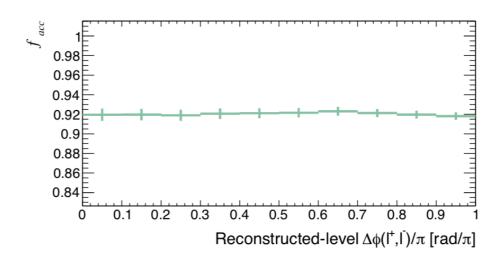




$$\frac{\mathrm{d}\sigma_{t\bar{t}}}{\mathrm{d}X^{i}} = \frac{1}{\mathcal{L} \cdot \Delta X^{i} \cdot \epsilon_{\mathrm{eff}}^{i}} \cdot \sum_{j} R_{ij}^{-1} \cdot f_{\mathrm{acc}}^{j} \cdot (N_{\mathrm{obs}}^{j} - N_{\mathrm{bkg}}^{j}),$$

Step 1: Subtract background events.



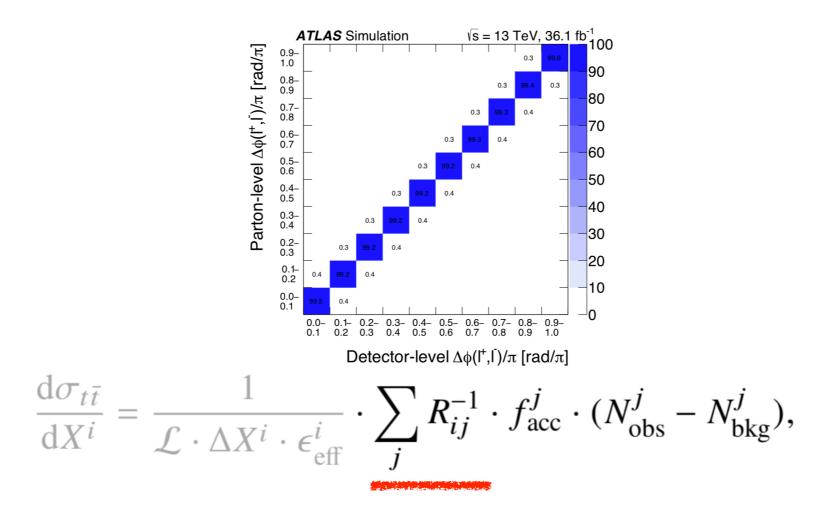


$$\frac{\mathrm{d}\sigma_{t\bar{t}}}{\mathrm{d}X^{i}} = \frac{1}{\mathcal{L} \cdot \Delta X^{i} \cdot \epsilon_{\mathrm{eff}}^{i}} \cdot \sum_{j} R_{ij}^{-1} \cdot f_{\mathrm{acc}}^{j} \cdot (N_{\mathrm{obs}}^{j} - N_{\mathrm{bkg}}^{j}),$$

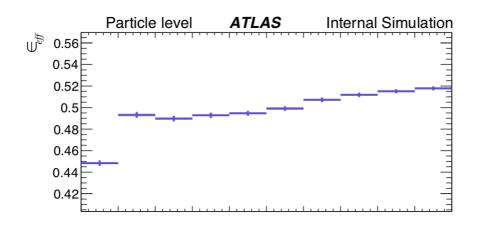
- Step 1: Subtract background events.
- Step 2: Correct for "non-fiducial" events that are in the Reco-level but aren't in truth.

$$f_{\text{acc}}^{j} = \frac{\text{reco}_{j} \wedge \text{truth}_{j}}{\text{reco}_{j}}$$





- Step 1: Subtract background events.
- Step 2: Correct for "non-fiducial" events that are in the Reco-level but aren't in truth.
- Step 3: Remove the detector smearing.



$$\epsilon_{\text{eff}}^{j} = \frac{\text{truth}_{j}}{\text{reco}_{j} \wedge \text{truth}_{j}}$$

$$\frac{\mathrm{d}\sigma_{t\bar{t}}}{\mathrm{d}X^{i}} = \frac{1}{\mathcal{L} \cdot \Delta X^{i} \cdot \epsilon_{\mathrm{eff}}^{i}} \cdot \sum_{j} R_{ij}^{-1} \cdot f_{\mathrm{acc}}^{j} \cdot (N_{\mathrm{obs}}^{j} - N_{\mathrm{bkg}}^{j}),$$

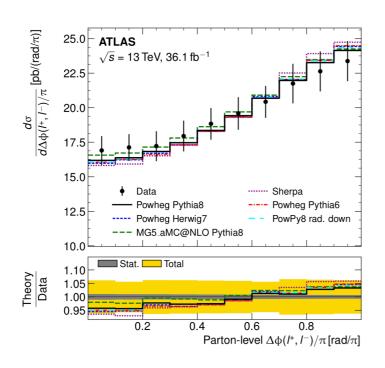
- Step 1: Subtract background events.
- Step 2: Correct for "non-fiducial" events that are in the Reco-level but aren't in truth.
- Step 3: Remove the detector smearing.
- Step 4.1: Extrapolate to your truth phase-space.



$$\frac{\mathrm{d}\sigma_{t\bar{t}}}{\mathrm{d}X^{i}} = \frac{1}{\mathcal{L}\cdot\Delta X^{i}\cdot\epsilon_{\mathrm{eff}}^{i}}\cdot\sum_{j}R_{ij}^{-1}\cdot f_{\mathrm{acc}}^{j}\cdot(N_{\mathrm{obs}}^{j}-N_{\mathrm{bkg}}^{j}),$$

- Step 1: Subtract background events.
- Step 2: Correct for "non-fiducial" events that are in the Reco-level but aren't in truth.
- Step 3: Remove the detector smearing.
- Step 4.1: Extrapolate to your truth phase-space.
- Step 4.2: Convert event count to cross-section.





$$\frac{\mathrm{d}\sigma_{t\bar{t}}}{\mathrm{d}X^{i}} = \frac{1}{\mathcal{L} \cdot \Delta X^{i} \cdot \epsilon_{\mathrm{eff}}^{i}} \cdot \sum_{j} R_{ij}^{-1} \cdot f_{\mathrm{acc}}^{j} \cdot (N_{\mathrm{obs}}^{j} - N_{\mathrm{bkg}}^{j}),$$

- Step 1: Subtract background events.
- Step 2: Correct for "non-fiducial" events that are in the Reco-level but aren't in truth.
- Step 3: Remove the detector smearing.
- Step 4.1: Extrapolate to your truth phase-space.
- Step 4.2: Convert event count to cross-section.
- Step 5: Profit!

AND THE PROPERTY OF THE PARTY O

The Code



- Most common code that is used is called "RooUnfold".
- Almost all of the unfolding frameworks that exist in the top group are based on it (with the notable exception of FBU) and usually they are just complicated python wrappers.
- https://svnsrv.desy.de/public/unfolding/RooUnfold/trunk/
 make sure to get trunk.
- ROOT does have it's own unfolding class, called TUnfold, which is commonly used by CMS (implements a more frequentist type of unfolding).
- In the end it doesn't matter too much, most (but not all) of the unfolding methods do
 the same thing and the recipe + tests are essentially the same.

The Code



```
response = RooUnfoldResponse(hist_reco, hist_truth, migration_matrix)
unfold_bayes = RooUnfoldBayes(response, hist_reco, 4, False)
hist_result = unfold_bayes.Hreco().Clone(random_name)
```

$$\frac{\mathrm{d}\sigma_{t\bar{t}}}{\mathrm{d}X^{i}} = \frac{1}{\mathcal{L} \cdot \Delta X^{i} \cdot \epsilon_{\mathrm{eff}}^{i}} \cdot \sum_{j} R_{ij}^{-1} \cdot f_{\mathrm{acc}}^{j} \cdot (N_{\mathrm{obs}}^{j} - N_{\mathrm{bkg}}^{j}),$$

- RooUnfoldResponse is a class that basically implements R_{ij}^{-1}
- However, the code will also try to do $f_{
 m acc}^j$ and $\epsilon_{
 m eff}^i$ for you, you shouldn't let it!
- An easy way to prevent this is to simply build the response matrix as follows:

```
response = RooUnfoldResponse(mig_matrix.ProjectionX(), mig_matrix.ProjectionY(), mig_matrix)
```

- This way, RooUnfold simply thinks that $f_{
 m acc}^j$ are $\epsilon_{
 m eff}^i$ equal to 1 for all bins.
- You then obviously have to apply these bin-by-bin corrections yourself.

The Code

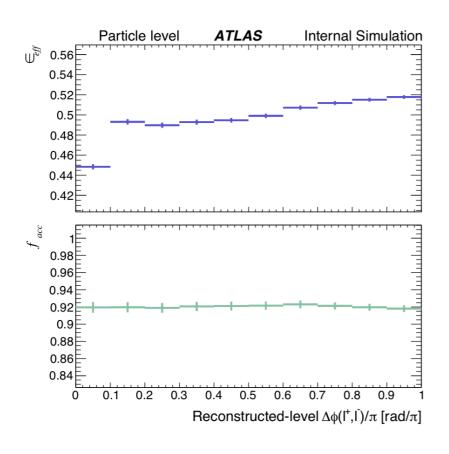


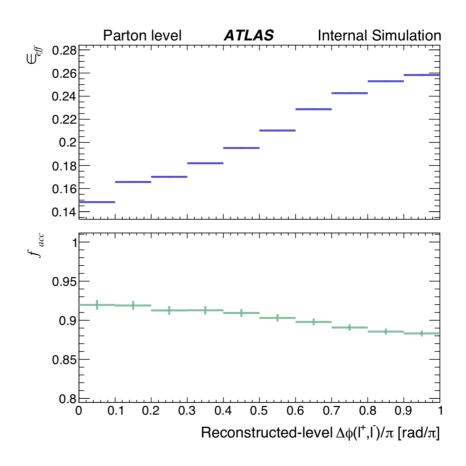
```
unfold_bayes = RooUnfoldBayes(response, hist_reco, iterations)
unfold_svd = RooUnfoldBayes(response, hist_reco, kterm)
unfold_bin = RooUnfoldBayes(response, hist_reco)
unfold_t = RooUnfoldTUnfold(response, hist_reco)
unfold_inv = RooUnfoldInvert(response, hist_reco)
```

- RooUnfold allows you to easily switch between several different unfolding options, but all other methods are the same (i.e. getting your histograms, setting error options etc).
- One of the main reasons we like RooUnfold as a tool!

Particle vs. Parton







- From the efficiency and acceptance plots you can really see the difference between parton level in a full phase-space and particle level in a fiducial phase-space.
- In particle level, the acceptance is mostly flat (since our particle and reco level leptons are very very similar) and the extrapolation is also no large (meaning our fiducial phasespace is similar in "size" to our reco one).
- In parton level you can see the extrapolation is much larger, and there are more efficiency effects (since parton leptons are not "dressed").



- The pull of an observable tells you two things:
 - If your results are biased
 - → If your uncertainties are correct
- The pull is constructed by:

$$pull = \frac{obs. - exp.}{\sigma(obs.)}$$

- If σ(obs.) is gaussian, then the pull (if calculated for many statistically independent pseudo-experiments) should take the form of a normal distribution, where the parameters can be interpreted in the following way:
 - \rightarrow μ = 0: unbiased results, μ != 0, probably some bias
 - $\rightarrow \sigma$ = 1: errors correctly estimated, σ < (>) 1 errors are over (under) estimated.
- It is generally a good idea to have pulls with $\mu = 0$ and $\sigma = 1$, but it's not the end of the world if they don't, you will just need to apply a correction based on your pull tests.



- The pull of an observable tells you two things:
 - If your results are biased
 - → If your uncertainties are correct
- The pull is constructed by:

$$pull = \frac{obs. - exp.}{\sigma(obs.)}$$

- If σ(obs.) is gaussian, then the pull (if calculated for many statistically independent pseudo-experiments) should take the form of a normal distribution, where the parameters can be interpreted in the following way:
 - \rightarrow μ = 0: unbiased results, μ != 0, probably some bias
 - $\rightarrow \sigma$ = 1: errors correctly estimated, σ < (>) 1 errors are over (under) estimated.
- It is generally a good idea to have pulls with $\mu = 0$ and $\sigma = 1$, but it's not the end of the world if they don't, you will just need to apply a correction based on your pull tests.



- The pull of an observable tells
 - If your results are biased
 - If your uncertainties are cor
- The pull is constructed by:

- Best calculated from pseudo-experiments yourself.
- RooUnfold does have some options (and the error on the histogram bin it returns isn't bad for a first look).

$$pull = \frac{obs. - exp.}{\sigma(obs.)}$$

- If σ (obs.) is gaussian, then the pull (if calculated for many statistically independent pseudo-experiments) should take the form of a normal distribution, where the parameters can be interpreted in the following way:
 - \rightarrow μ = 0: unbiased results, μ != 0, probably some bias
 - \rightarrow σ = 1: errors correctly estimated, σ < (>) 1 errors are over (under) estimated.
- It is generally a good idea to have pulls with $\mu = 0$ and $\sigma = 1$, but it's not the end of the world if they don't, you will just need to apply a correction based on your pull tests.



- The pull of an observable tells
 - → If your results are biased
 - If your uncertainties are cor
- The pull is constructed by:

- Best calculated from pseudo-experiments yourself.
- RooUnfold does have some options (and the error on the histogram bin it returns isn't bad for a first look).

$$pull = \frac{obs. - exp.}{\sigma(obs.)}$$

• If σ(obs.) is gaussian, then the pull (if calculated for many statistically independent pseudo-experiments) should take the form of a normal distribution, where the

	X	$\frac{\mathrm{d}\sigma_{t\bar{t}}}{\mathrm{d}X} \left[\frac{\mathrm{pb}}{\mathrm{GeV}} \right]$	$\frac{1}{\sigma_{t\bar{t}}} \frac{\mathrm{d}\sigma_{t\bar{t}}}{\mathrm{d}X} \left[\frac{1}{\mathrm{GeV}} \right]$	Stat. (abs.)	Stat. (norm.)	Syst. (abs.)	Syst. (norm.)	
	$p_{\mathrm{T}}(t) \; [\mathrm{GeV}]$			[%]	[%]	[%]	[%]	
	0 - 70	7.1	0.371	± 1.8	± 1.7	+11 -11	+4 -3.2	
•	70 - 150	9.9	0.515	± 1.3	± 1.2	+10 -11	+2.3 - 2.7	d of
1	150 - 250	4.61	0.239	± 1.8	± 1.7	+7 - 8	+2.1 - 2.0	11
•	250 - 400	0.97	0.051	± 3.4	± 3.3	+7 -9	+10 -11	"
†	400 - 1000	0.042	0.0022	± 10	± 9	+40 -40	+40 -40	



```
hist_result = unfold_bayes.Hreco(option).Clone(random_name)
```

• When retrieving the histogram from RooUnfold, there are several error options:

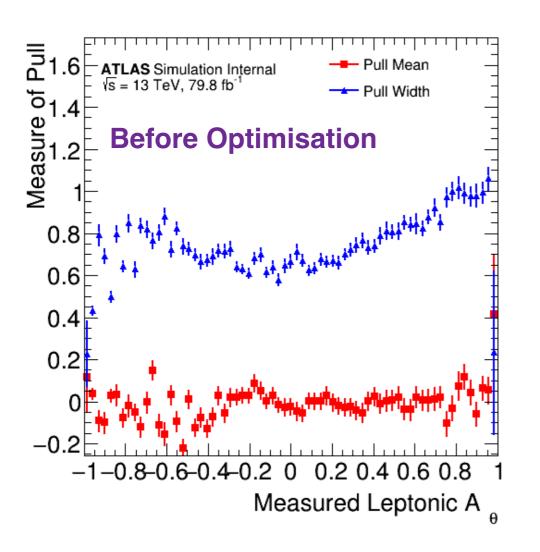
Creates reconstructed distribution. Error calculation varies by withError:

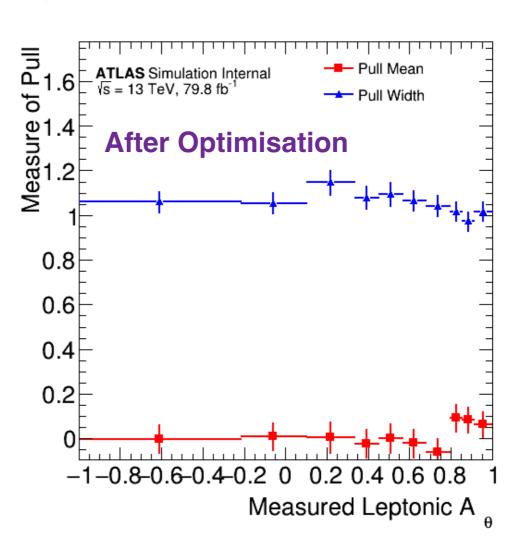
- 0: No errors
- 1: Errors from the square root of the diagonals of the covariance matrix given by the unfolding
- 2: Errors from the square root of of the covariance matrix given by the unfolding
- 3: Errors from the square root of the covariance matrix from the variation of the results in toy MC tests
- Personally, I've never fully trusted these options and usually calculate covariance matrices myself (out of the scope of this tutorial but please ask about it, we have many examples to help you).
- But they should be fine for first tests (at least, option 1 is usually exactly what it says).

Binning Optimisation



- Pull tests can also be used to help you optimise your binning.
- Here is an example from the Deadcone analysis:



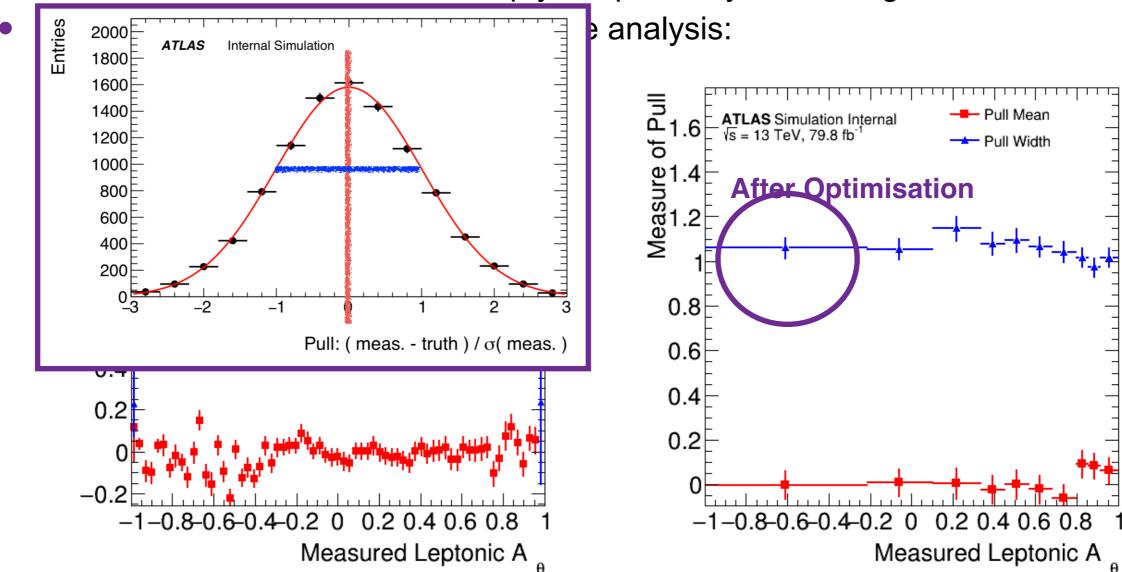


- With a large number of bins, there are obvious biases and underestimated uncertainties.
- After optimisation for the number and width of bins, things look far more reasonable.

Binning Optimisation



Pull tests can also be used to help you optimise your binning.

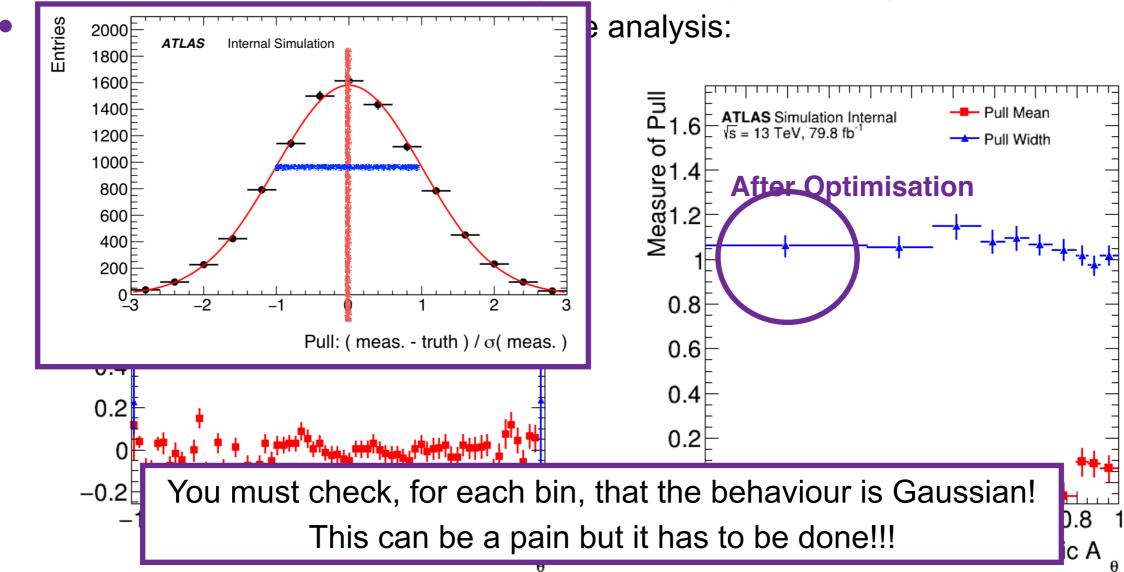


- With a large number of bins, there are obvious biases and underestimated uncertainties.
- After optimisation for the number and width of bins, things look far more reasonable.

Binning Optimisation



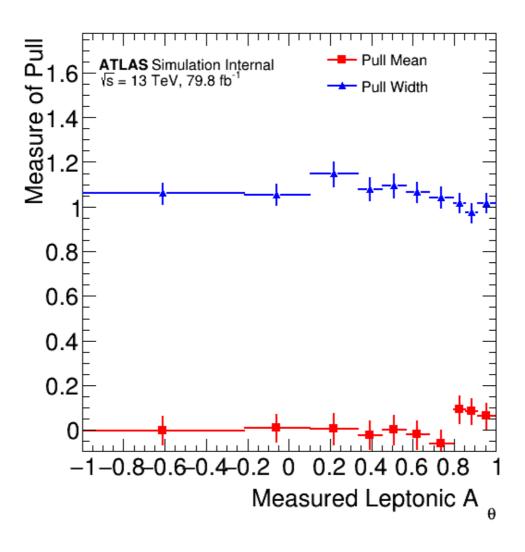
Pull tests can also be used to help you optimise your binning.



- With a large number of bins, there are obvious biases and underestimated uncertainties.
- After optimisation for the number and width of bins, things look far more reasonable.



- We ran 300 statistically independent pseudo-experiments for this binning optimisation test.
- Do we keep optimising until all the blue markers are a at 1 and red markers are at zero?

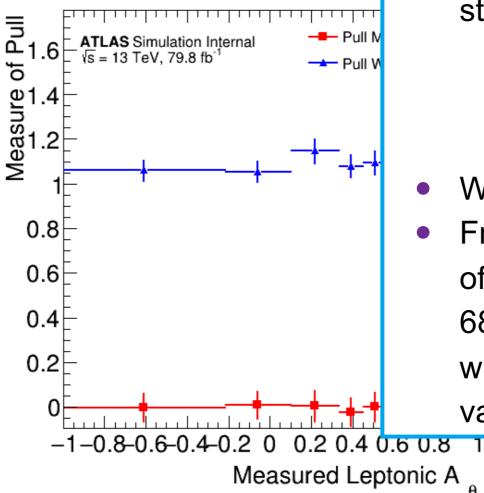




 We ran 300 statistically independent pseudo-experiments for this binning optimisation test.

Do we keep optimising until all the blue markers are a at 1 and red markers are at

zero?



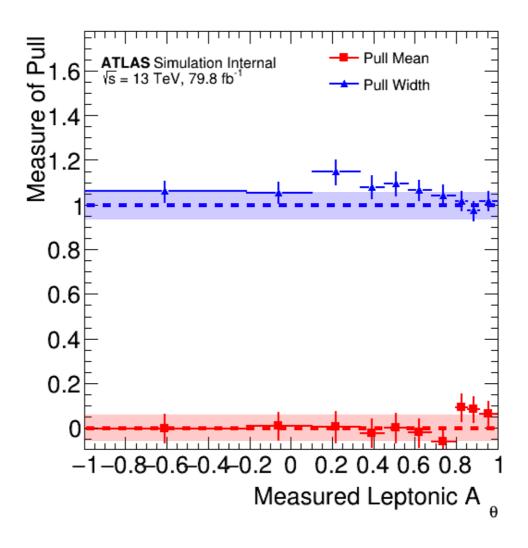
 We have 300 pseudo experiments, so we have a statistical uncertainty of:

$$\frac{1}{\sqrt{300}} * 100 = 5.8\%$$

- We also have 10 bins.
- From a pure frequentist point of view, we expect that only 68% (i.e. 7) of the bins lie within 5.8% of their expected values.

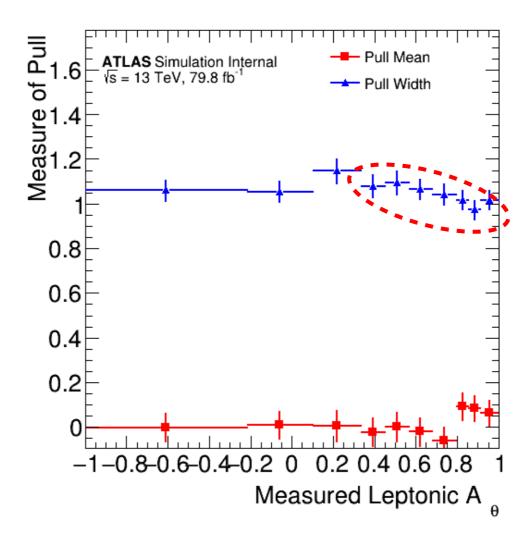


• So, from a purely statistical counting point of view, the below binning looks like it's (just about) reasonable. There are only 3/4 blue markers outside of the range, and only three red markers, which is what we expect (this is just a basic χ^2 test).





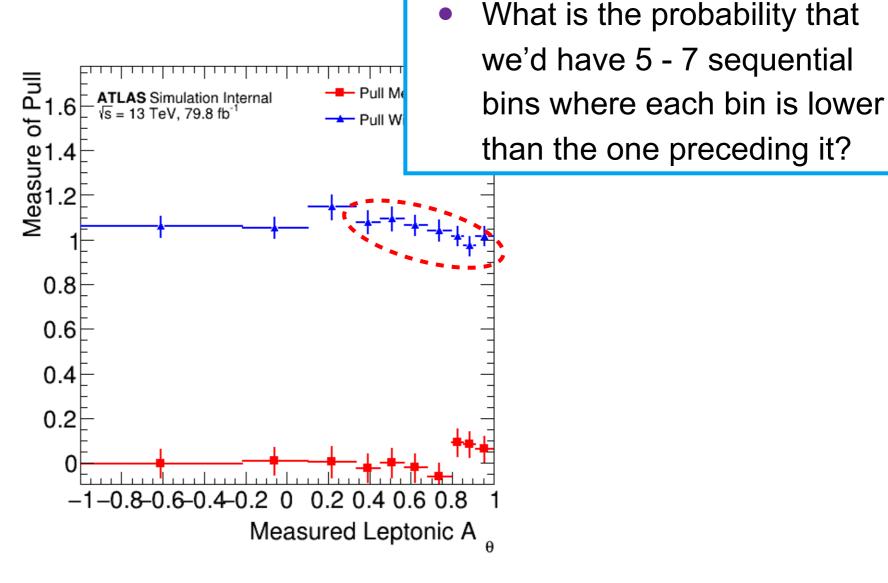
- So, from a purely statistical counting point of view, the below binning looks like it's (just about) reasonable. There are only 3/4 blue markers outside of the range, and only three red markers, which is what we expect (this is just a basic χ^2 test).
- But what about this?





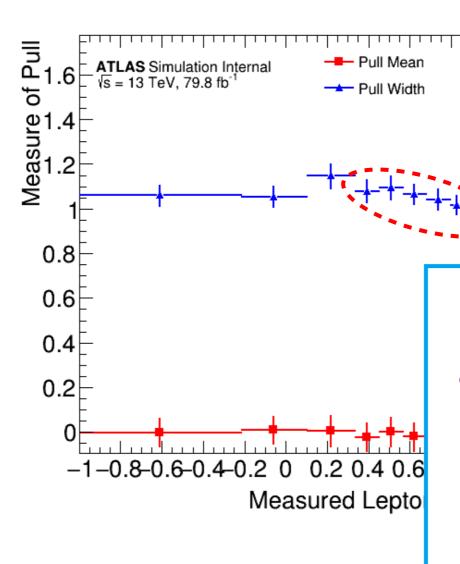
• So, from a purely statistical counting point of view, the below binning looks like it's (just about) reasonable. There are only 3/4 blue markers outside of the range, and only three red markers, which is what we expect (this is just a basic χ^2 test)

But what about this?





- So, from a purely statistical counting point of view, the below binning looks like it's (just about) reasonable. There are only 3/4 blue markers outside of the range, and only three red markers, which is what we expect (this is just a basic χ^2 test)
- But what about this?

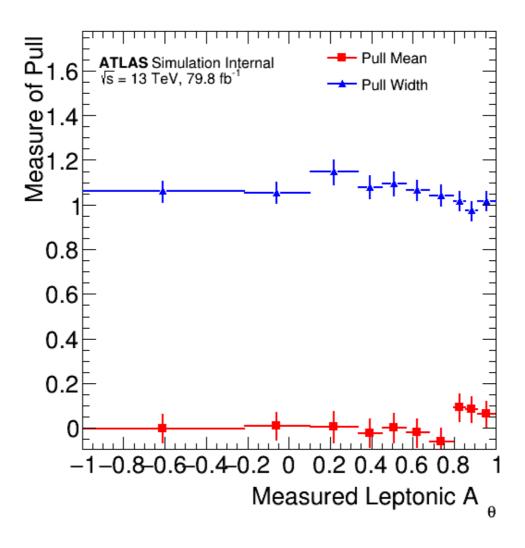


$$\frac{1}{2} * \frac{1}{2} * \frac{1}{2} * \frac{1}{2} * \frac{1}{2} = 0.03$$

Since 0.03 < 0.05 (the p-value for 2σ), we'd consider this a significant trend that shouldn't be attributed to random chance.

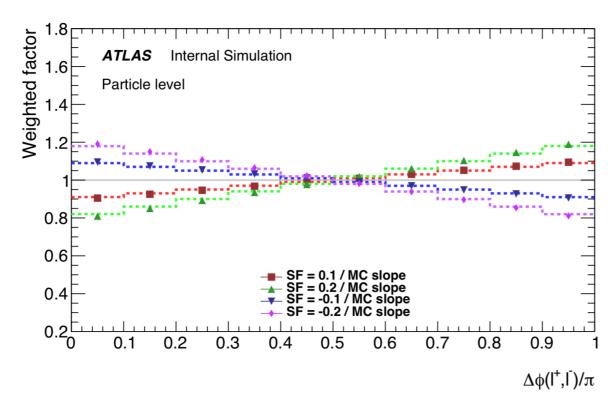


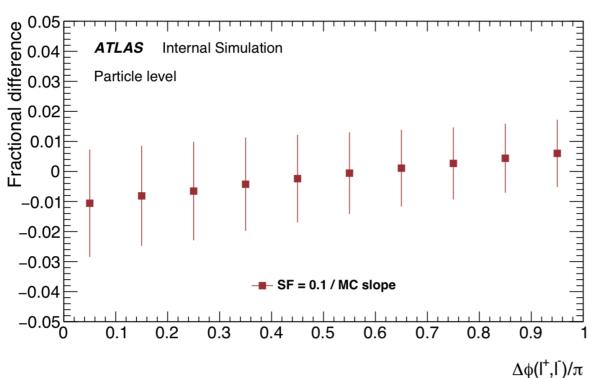
- Summary on this is, think about each test you do and if it makes statistical sense!
 - \Longrightarrow Don't blindly try to make all your bins have exactly a pull μ = 0, σ = 1.
 - Don't assume just because things are inside an uncertainty band that they're fine, this hides important shape effects!



Stress Tests





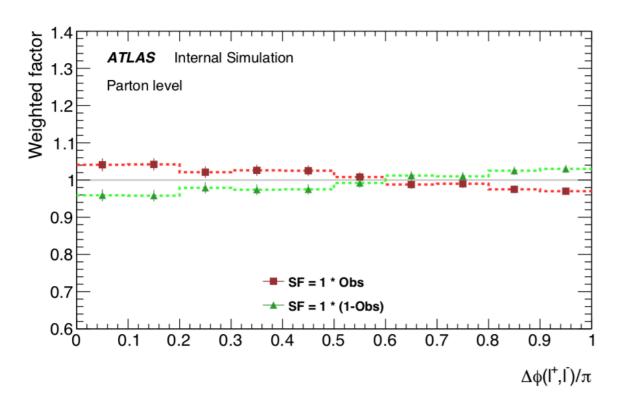


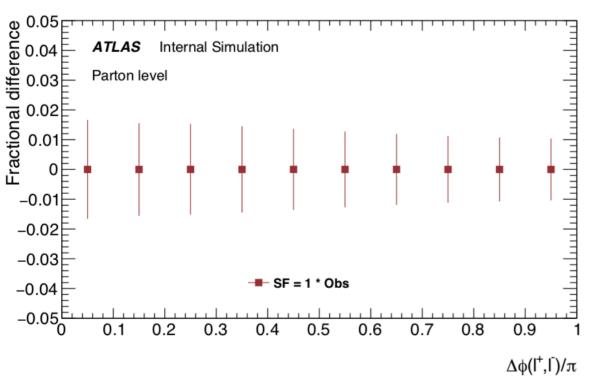
$$S_i = 1 + C \cdot \frac{(\text{Data}_i - \text{MC}_i)}{\text{Data}_i}$$

- Reweight your truth spectra with some function (usually a linear slope).
- Unfold your reweighed reco level distribution and see if you recover that slope.
- The point of this test isn't really to get perfect closure, it's to stress the unfolding and see where it breaks down.
- Other functions may be more appropriate for your analysis (curves, bumps etc.)

Stress Tests





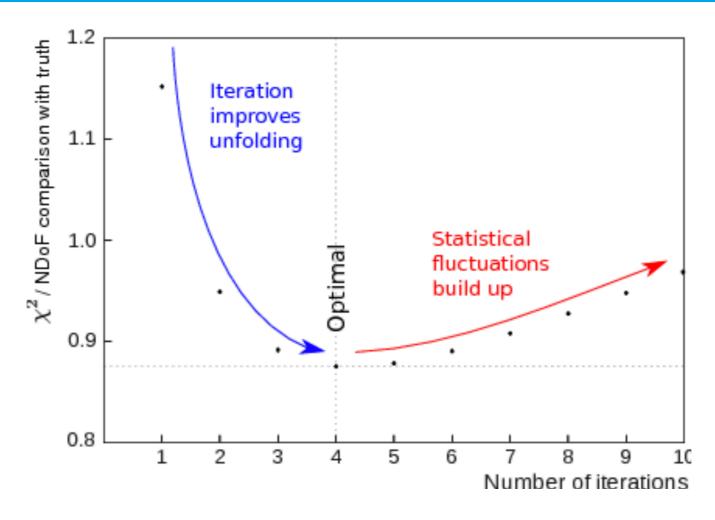


$$S_i = 1 + C \cdot \frac{(\text{Data}_i - \text{MC}_i)}{\text{Data}_i}$$

- You can also reweight your truth spectra with the observed Data/MC at reco level.
- This is as close as you can get to saying "can I unfold my data in an unbiased way?"
- If this test doesn't close, not the end of the world, but you will have to either change the binning/number of iterations or accept a bias correction on your measurement.

Optimising Iterations (IBU)

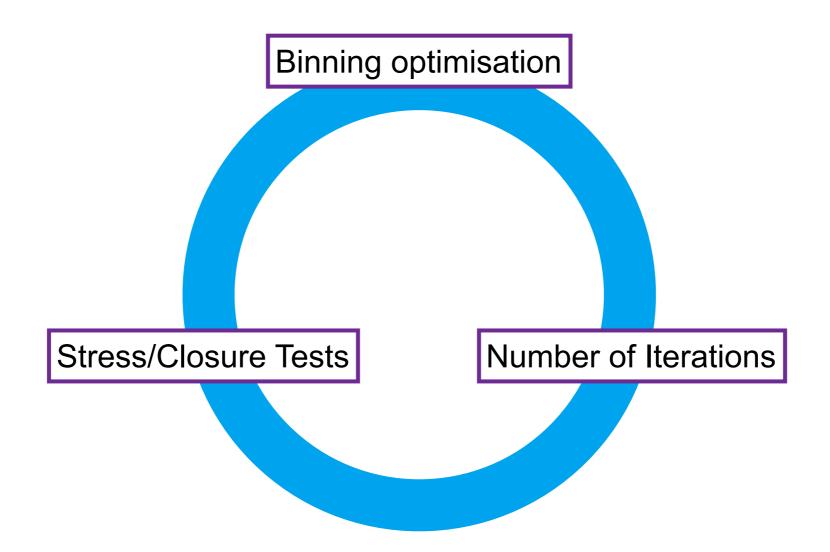




- Many ways one can determine this, but a Chi2 test is as good as any.
- As a general rule, you want as few iterations as possible in order to minimise the statistical uncertainties.
- You will almost never get a plot as helpful as this one, the changes tend to be quite subtle, but it's usually possible to identify a minima (often between 2 and 4 iterations).

Optimising Iterations (IBU)





- Binning optimisation, number of iterations, stress-tests, closure tests, these are all somewhat inter-dependent, and it's not possible to say "do this one first, then this one" so you will need to use a bit of physics intuition.
- Are small bins the most important to you? If so then optimise that first. If stat
 uncertainty matters most, optimise the number of iterations first etc.

Unfolding Experts in Top



 If you have any unfolding questions, the following people have frameworks of RooUnfold or FBU implemented and currently running:

Jay Howarth (IBU spin): Manchester

Federica Fabbri (IBU I+jets xsec): Glasgow

→ Tom Neep (IBU ttbb): Birmingham

Clement Helsens (FBU CA): Somewhere

Chris Pollard (FBU b-frag): Somewhere

→ Baptiste Ravina (IBU ttZ): Sheffield

Maria Costa (IBU t-chan): Valencia

- Non-exhaustive list, just people I know that are currently working on unfolding frameworks (biased by who I know).
- Any of them will be happy to help you with your unfolding questions, or you can always contact your sub-conveners.
- We now also have a mailing list for unfolding questions:

atlas-phys-top-unfolding