Basel Mostafa

https://github.com/bmostafa340

EDUCATION

California Institute of Technology

Pasadena, CA

Bachelor's of Science in Computer Science; GPA: 4.13 Sep. 2019 - Present (Jun. 2023)

Cupertino High School

Cupertino, CA High School Diploma; SAT: 1550; GPA: 4.00 Aug. 2015 - Jun. 2019

EXPERIENCE

Cosmic Dawn Center

Copenhagen, Denmark

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Undergraduate Summer Research Fellow Jun. 2020 - Sep. 2020

• Built an automated data processing pipeline for analyzing and visualizing the results of incorporating an additional temperature-like parameter in the computation of galaxy properties. Wrote a Makefile to automatically update dependencies as necessary while minimizing execution of unnecessary subprocesses and maintaining a simple UI.

• Used data chunking and hashing to quickly process multi-GB data files while minimizing computational expense.

Caltech Robotics Team

Pasadena, CA

Software Team Member

Sep. 2019 - Jan. 2020

o Optimized object detection neural network speed on CPU for autonomous submarine; achieved 36% speedup with minimal loss of precision over CRT's previous vision system by enabling int-8 weight quantization, AVX, and SSE.

• Used OpenCV to follow an underwater cart through a stream of images as seen by a moving submarine.

CHS Robotics Team Cupertino, CA

Project Coordinator, Mechanical Designer, Mentor

Sep. 2015 - Mar. 2019

- Led the design and fabrication of multiple mechanisms for a semi-autonomous robot in the FRC 2019 season.
- Primary designer of a ball shooter, animatronic, and robot drivetrain for R&D 2017-18. Contributed to the design of a climbing mechanism used for the FRC 2018 build season.
- Led the design and fabrication of Sparky for the FTC 2016-17 build season, for which we won the Inspire Award.
- Mentored middle school students through the FLL lego robotics experience for two years.

Projects

- TeenyBASIC Compiler: Compiles a simplified version of BASIC in O(n) time on the parse tree size, optimized to pre-evaluate constant expressions, replace multiplication with bit shifts where possible, and maximize register use.
- Python Rubik's Cube Solver: Optimal smarter brute force 2x2x2 Rubik's Cube solver reduces the number of cubes to be considered by up to 2 billion fold as compared to naive BFS. Greedy corners first 3x3x3 Rubik's Cube solver achieves 150 quarter turn solutions in a few seconds on average.
- Ph 11 Hurdles: Simulated hourly flight delays during SFO's 9/19 construction as a queue scheduling problem, with flight and runway data elements designed to reflect real-world conditions for Hurdle 1. Modeled the relationship between rinderpest seroprevalence, wildebeest population, fire frequency, and tree density on the Serengeti using rate-based analysis and simulation as a synchronous cellular automaton for Hurdle 2.
- **DAMMIT:** Collaborated in a team of three using git to create a top-down monster survival game using JavaFX. Used OOP principles of inheritance and polymorphism to build a consistent and intuitive software architecture.

Programming Skills

- Coursework: Data Structures, Learning Systems, Intro to Computing Systems, Decidability and Tractability, Intro to C/C++, Calculus of One and Multiple Variables, Linear Algebra, Ordinary Differential Equations.
- Languages: Python, Java, C, C++

Tools: Linux, Git, NumPy, Matplotlib, Solidworks

AWARDS

• Eagle Rank, Tombrello Fellowship