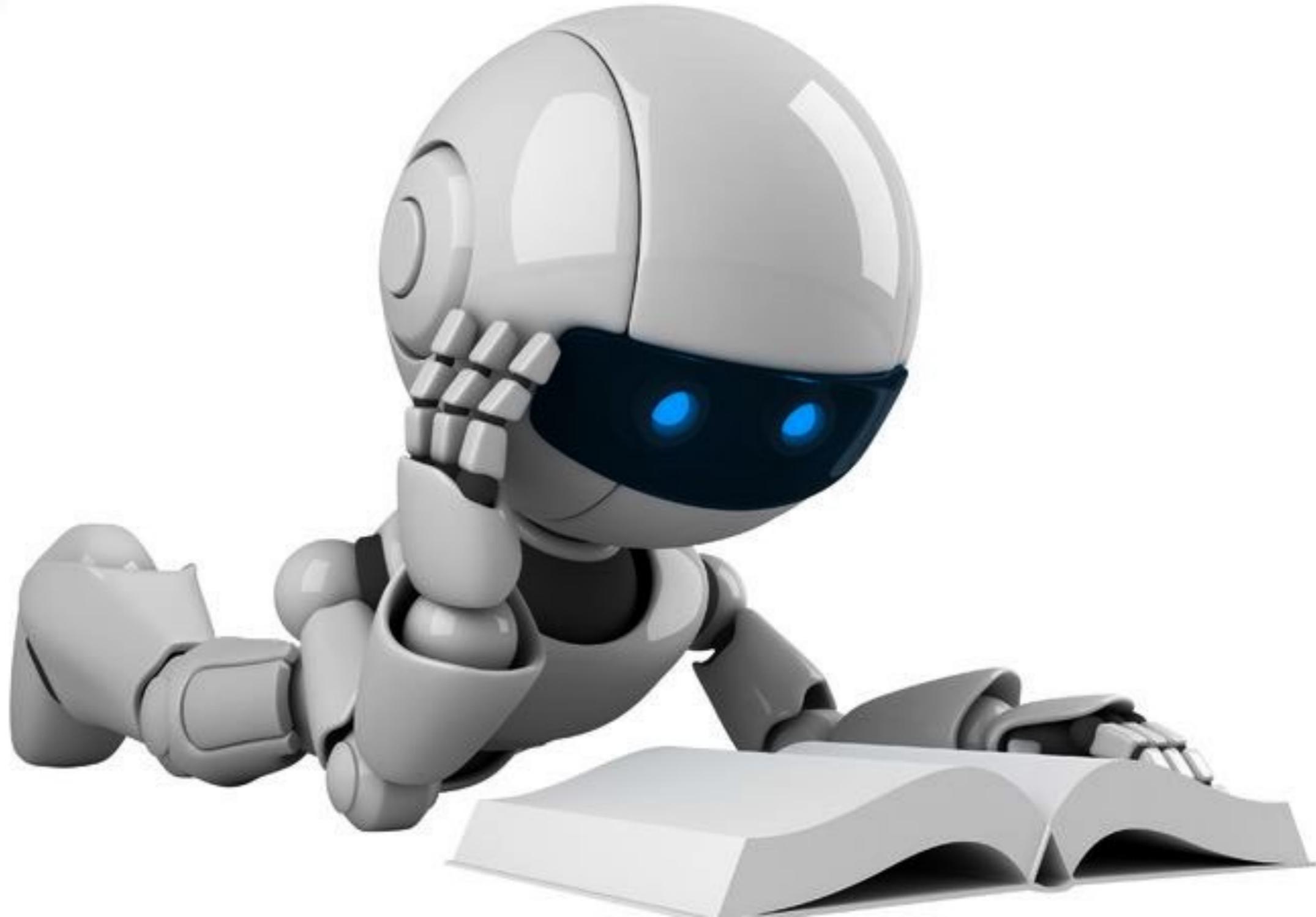


Recurrent Neural Networks

Bruno Gonçalves

www.bgoncalves.com

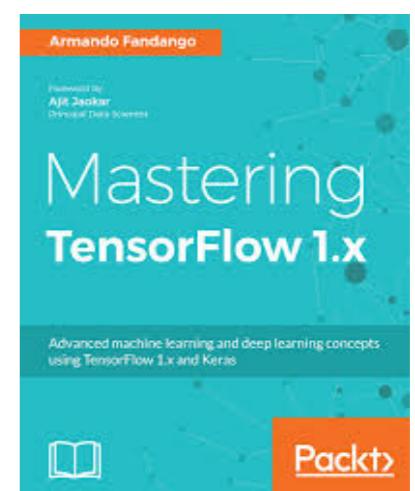
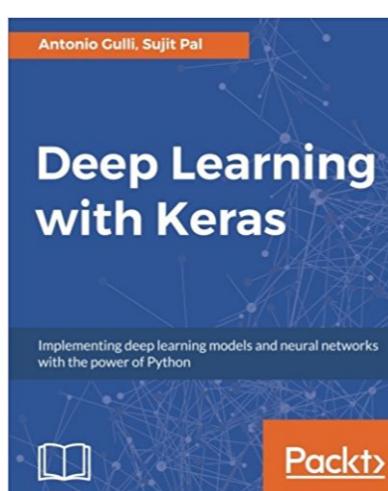
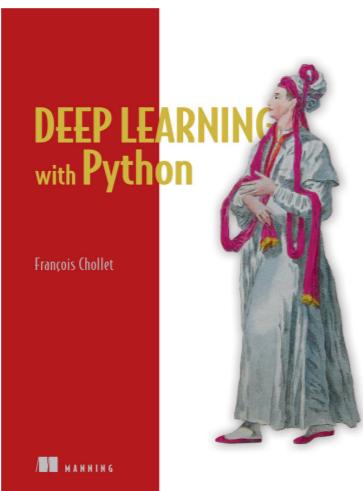
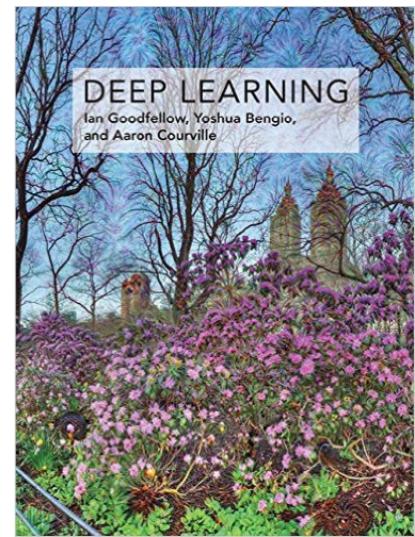
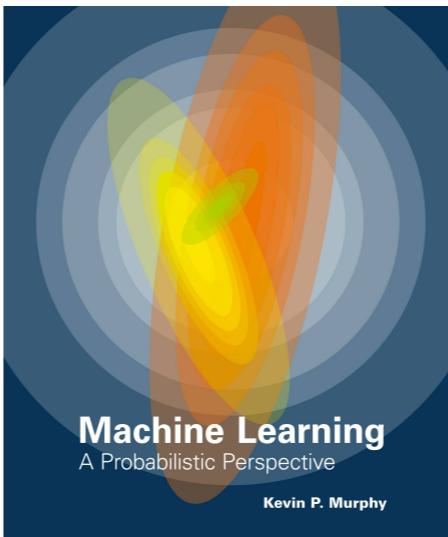
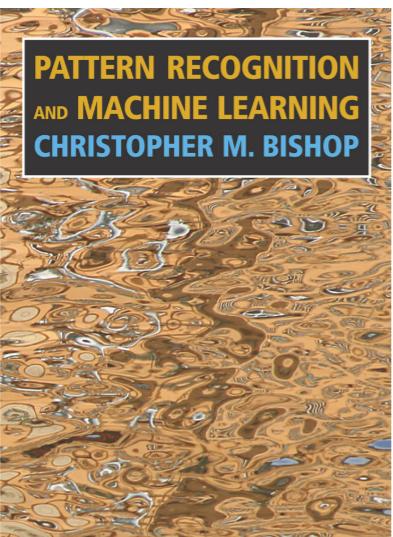
github.com/bmtgoncalves/RNN



Disclaimer

The views and opinions expressed in this article are those of the authors and do not necessarily reflect the official policy or position of my employer. The examples provided with this tutorial were chosen for their didactic value and are not meant to be representative of my day to day work.

References



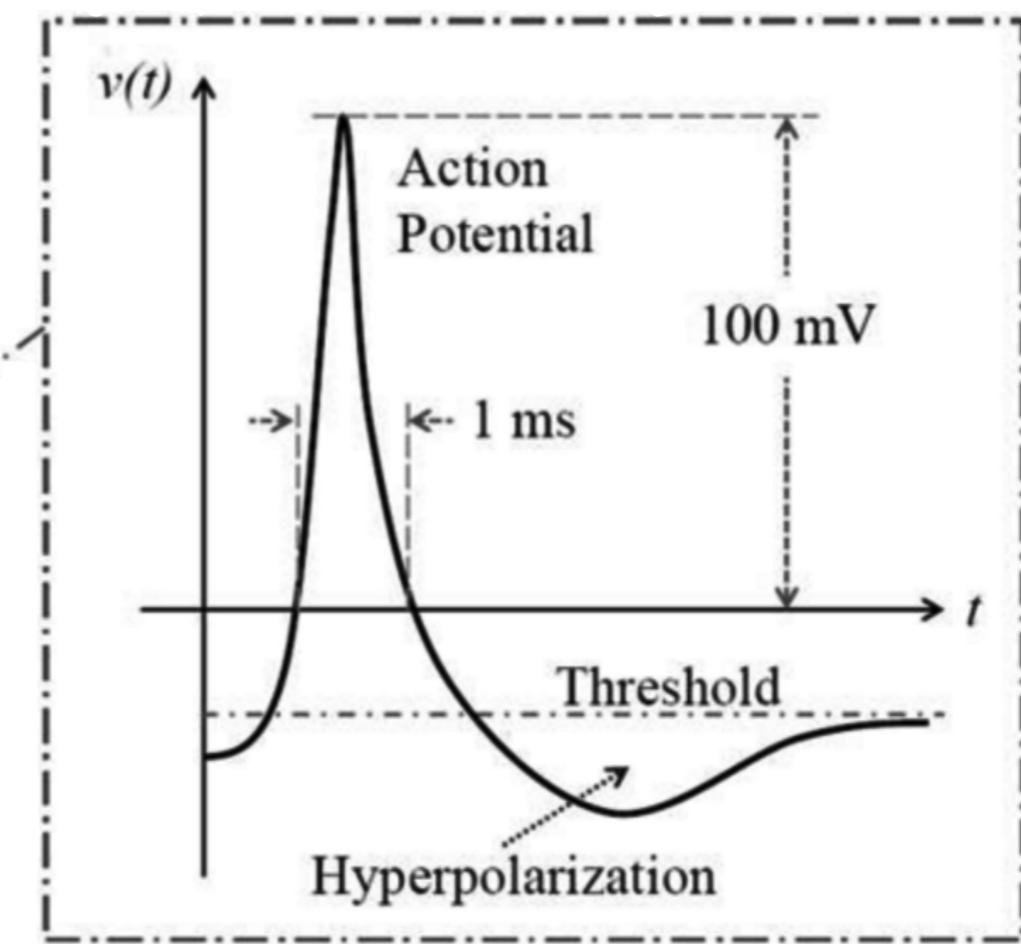
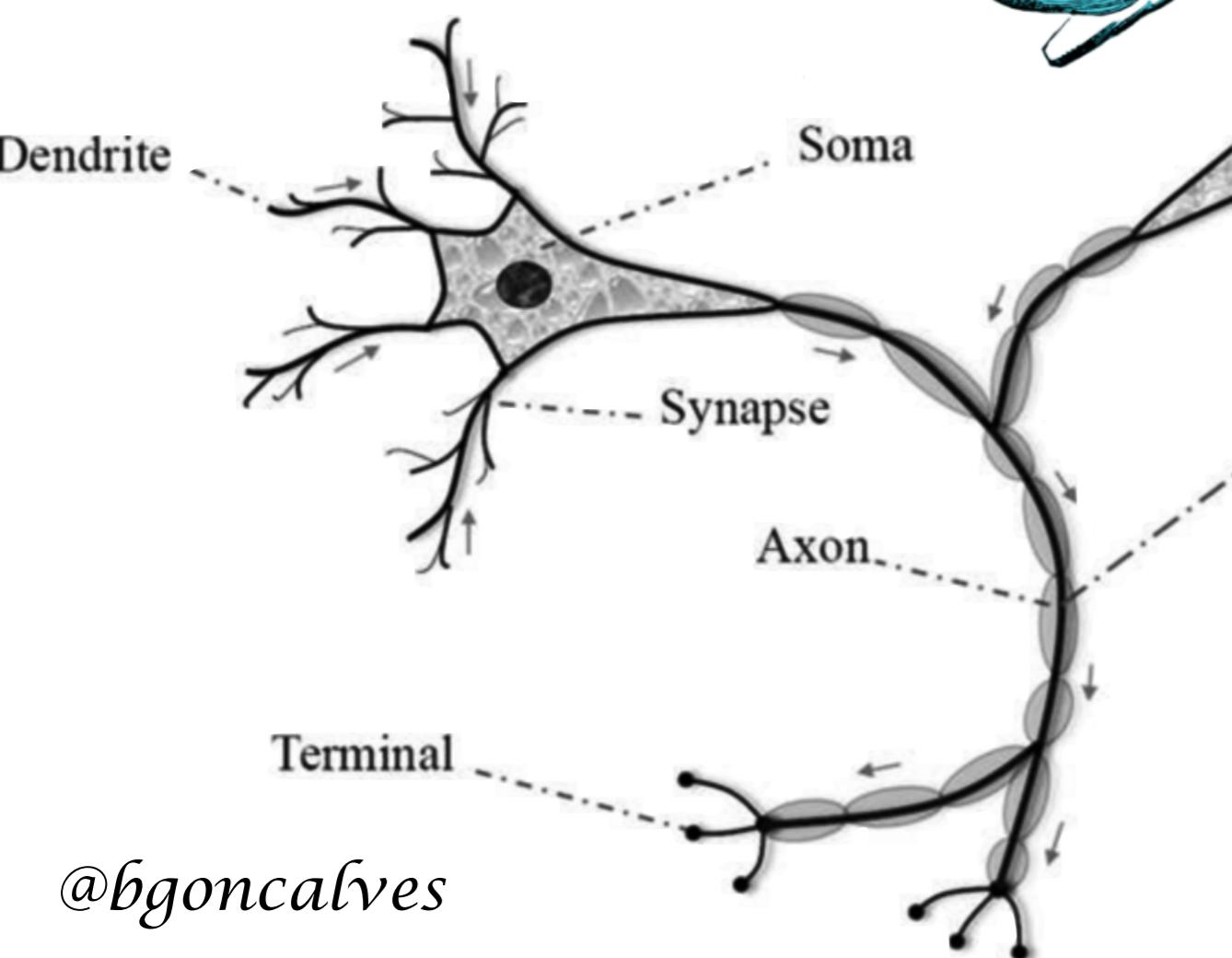
How the Brain “Works” (Cartoon version)



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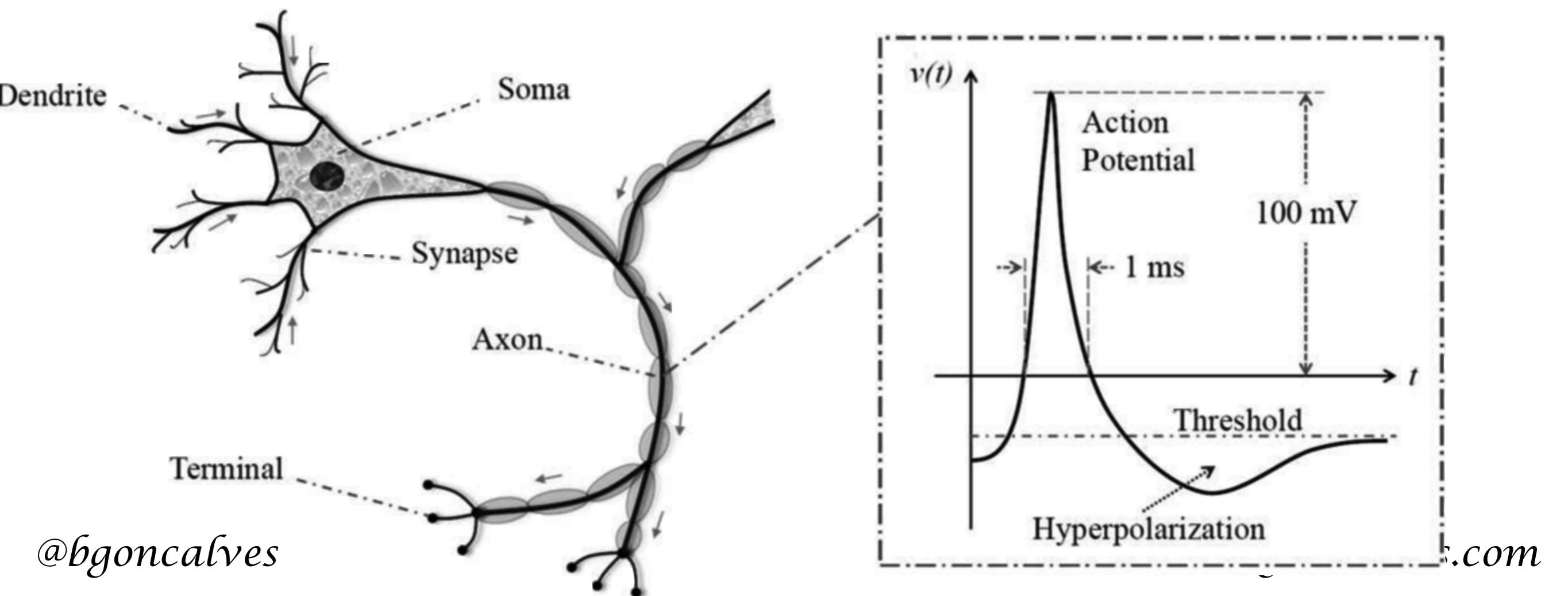


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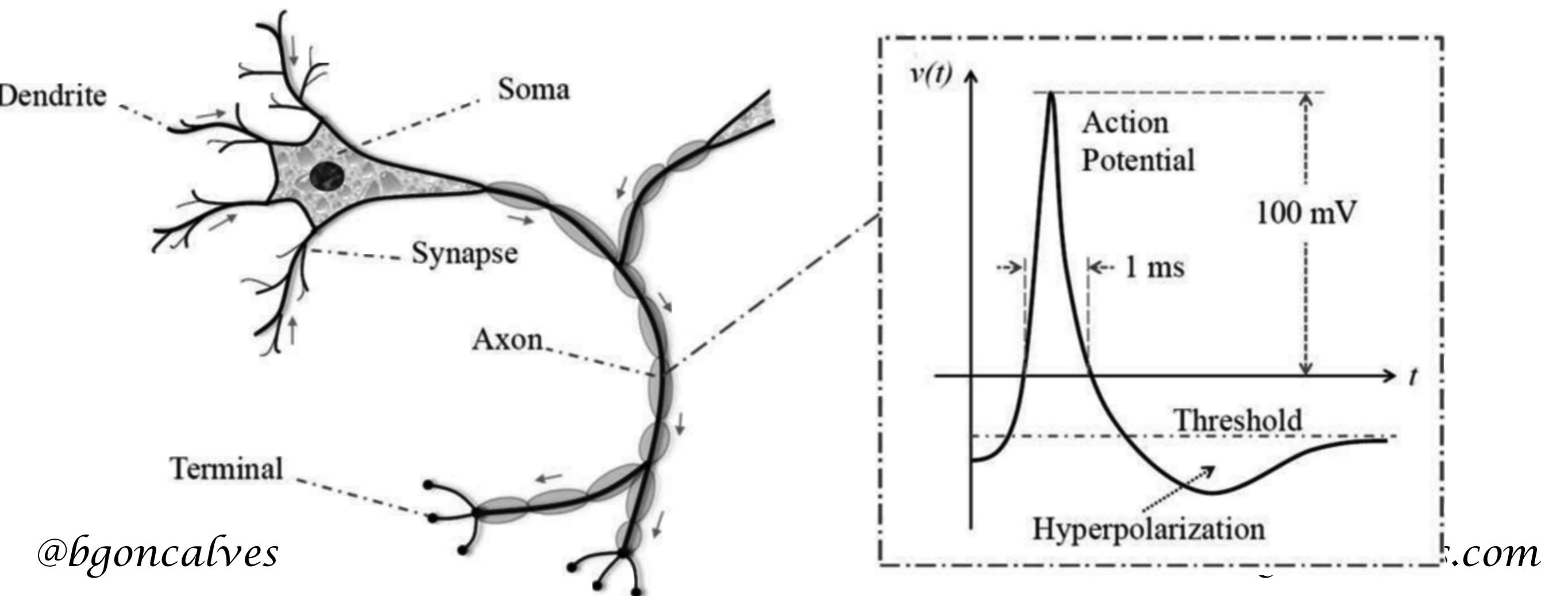
How the Brain “Works” (Cartoon version)

- Each neuron receives input from other neurons



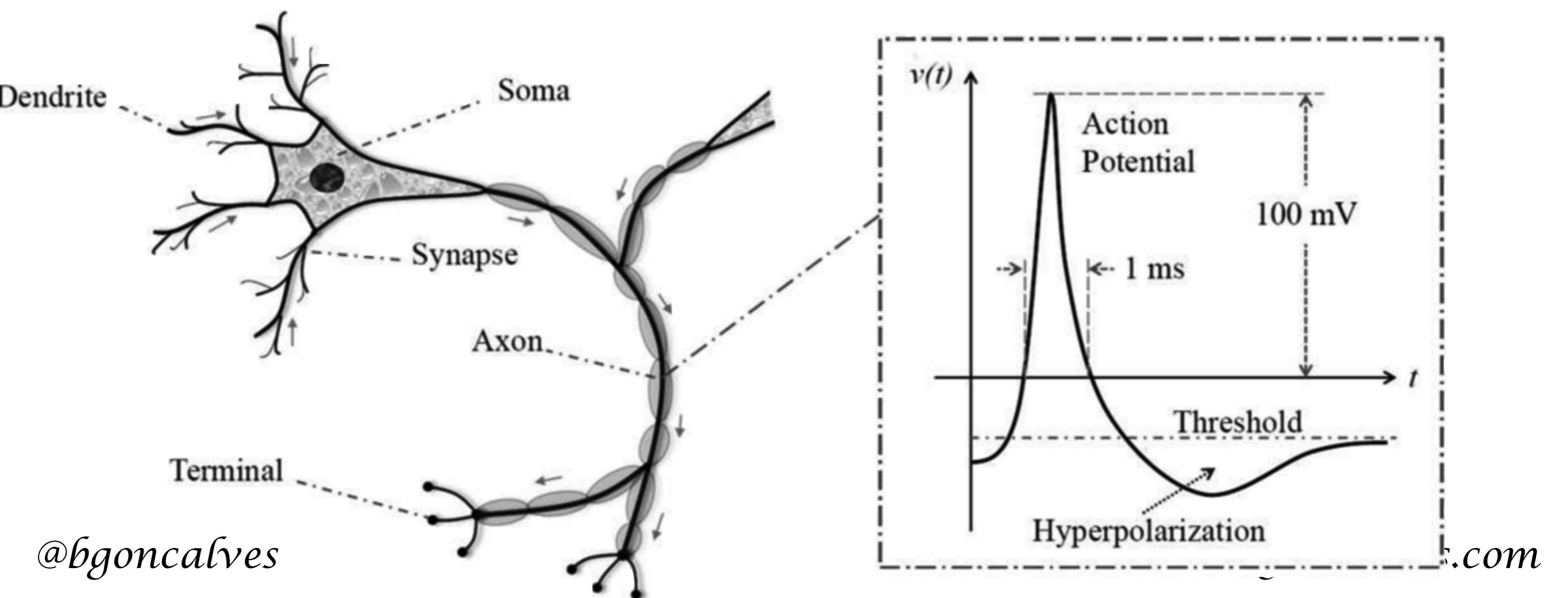
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- Each neuron receives input from other neurons
- 10^{11} neurons, each with 10^4 weights



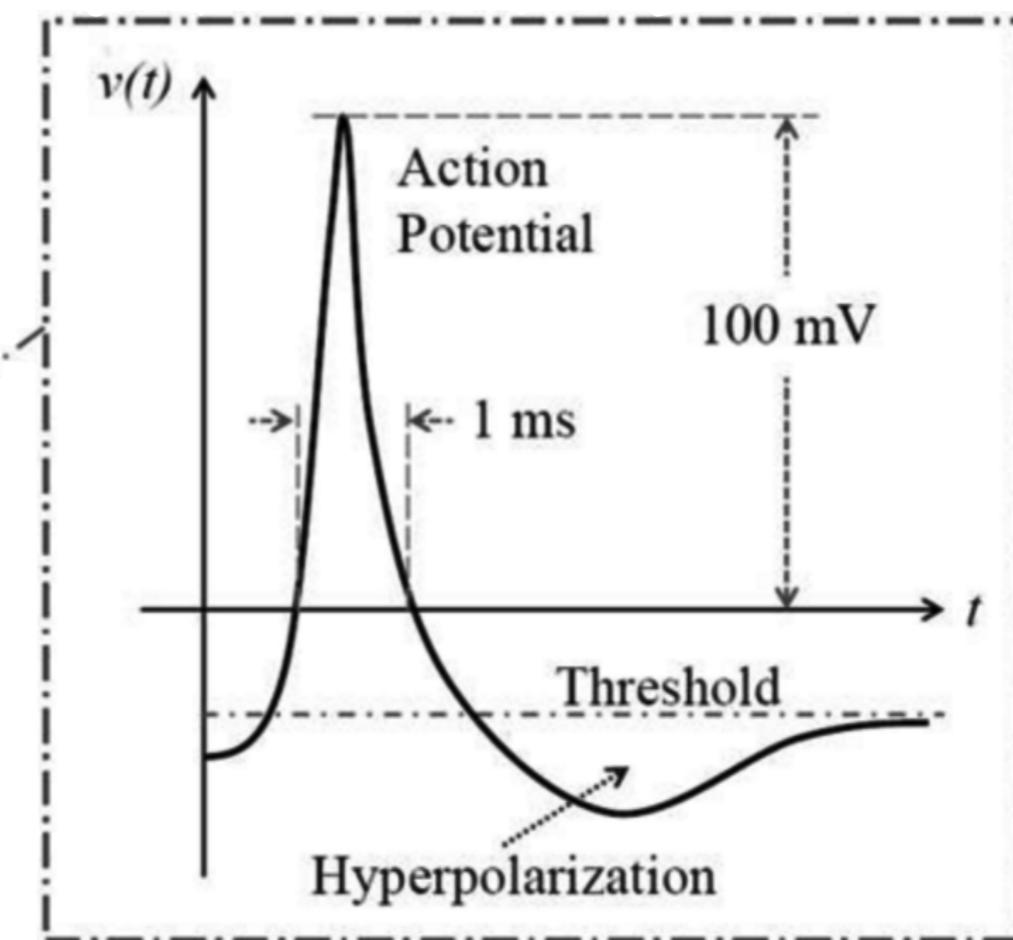
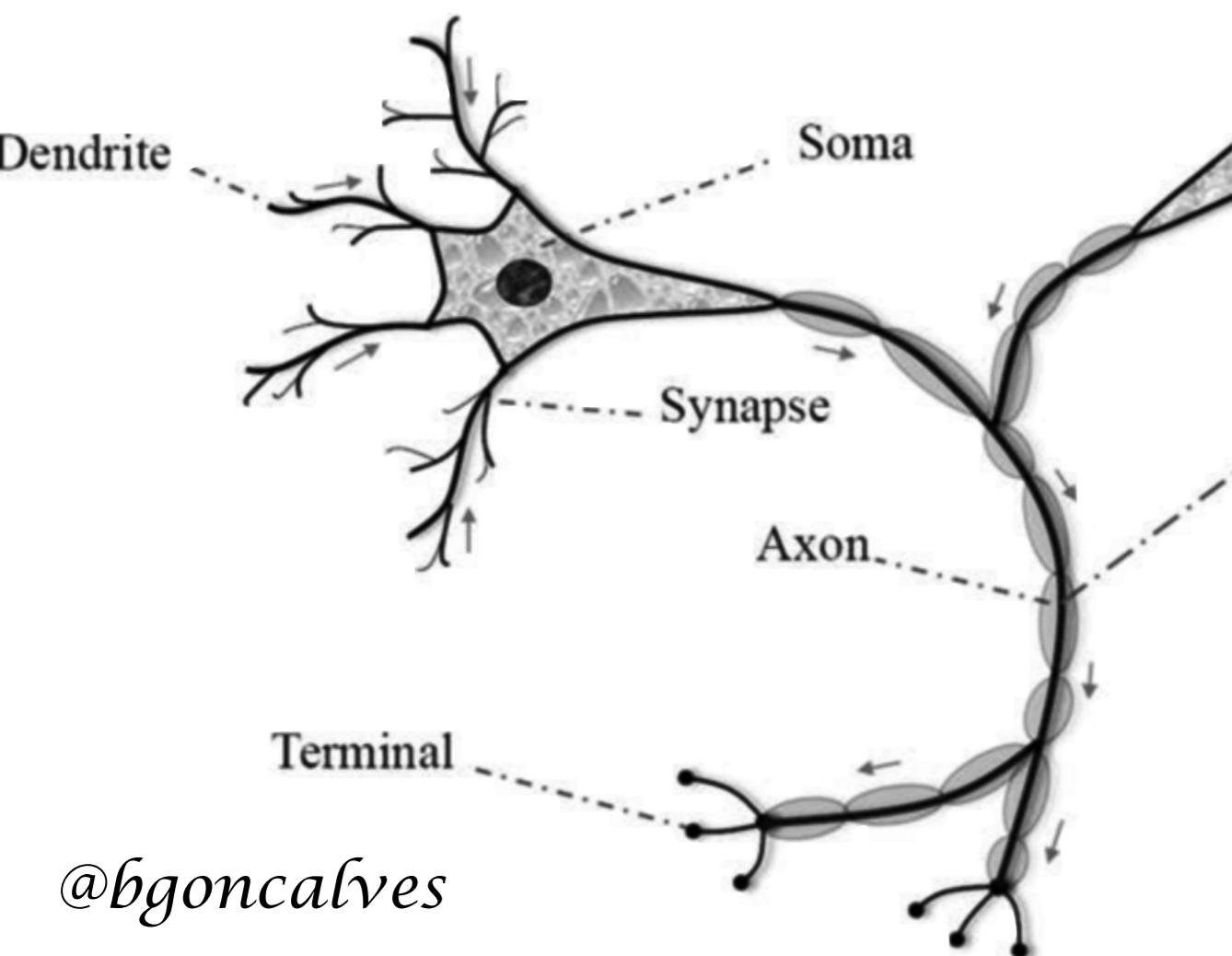
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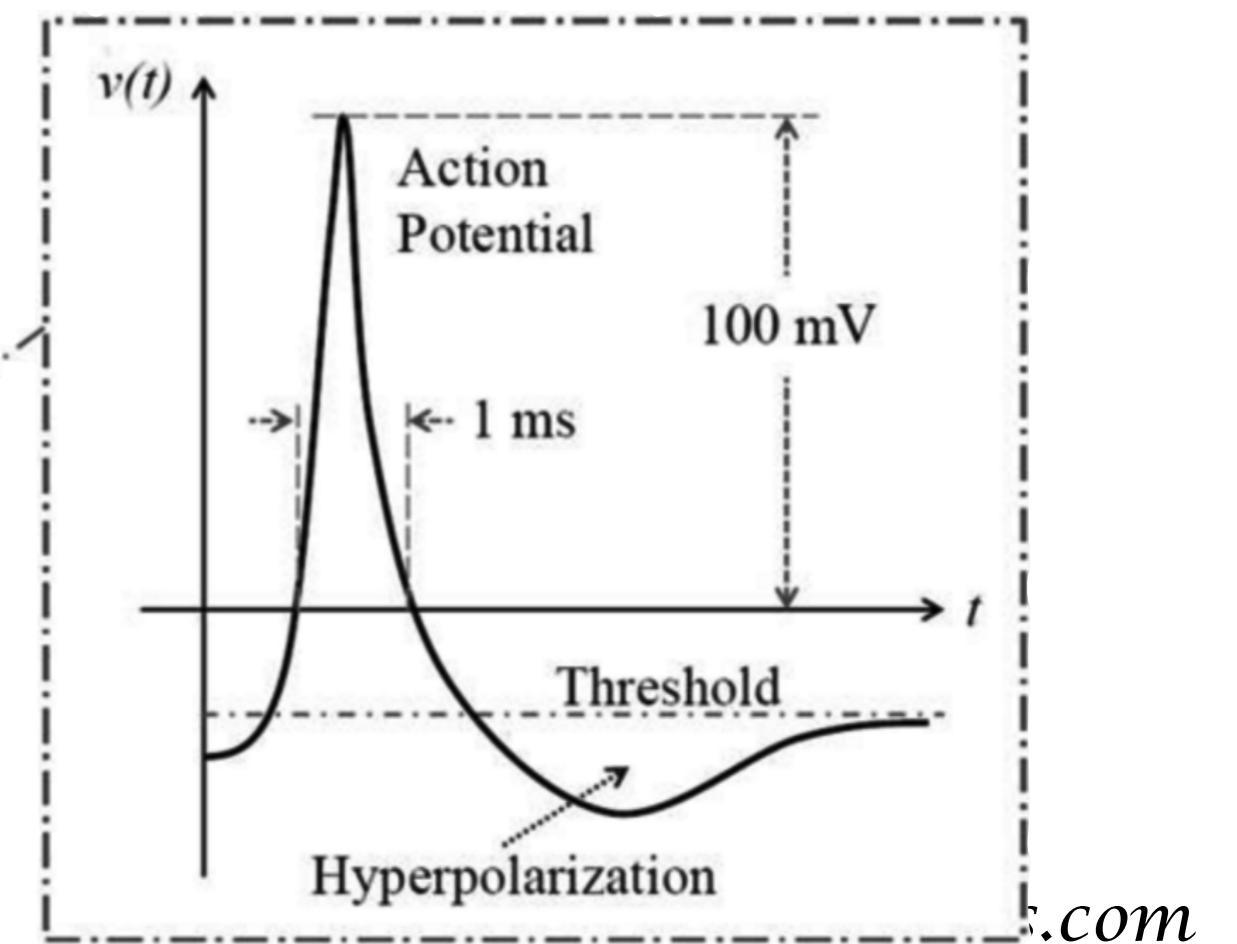
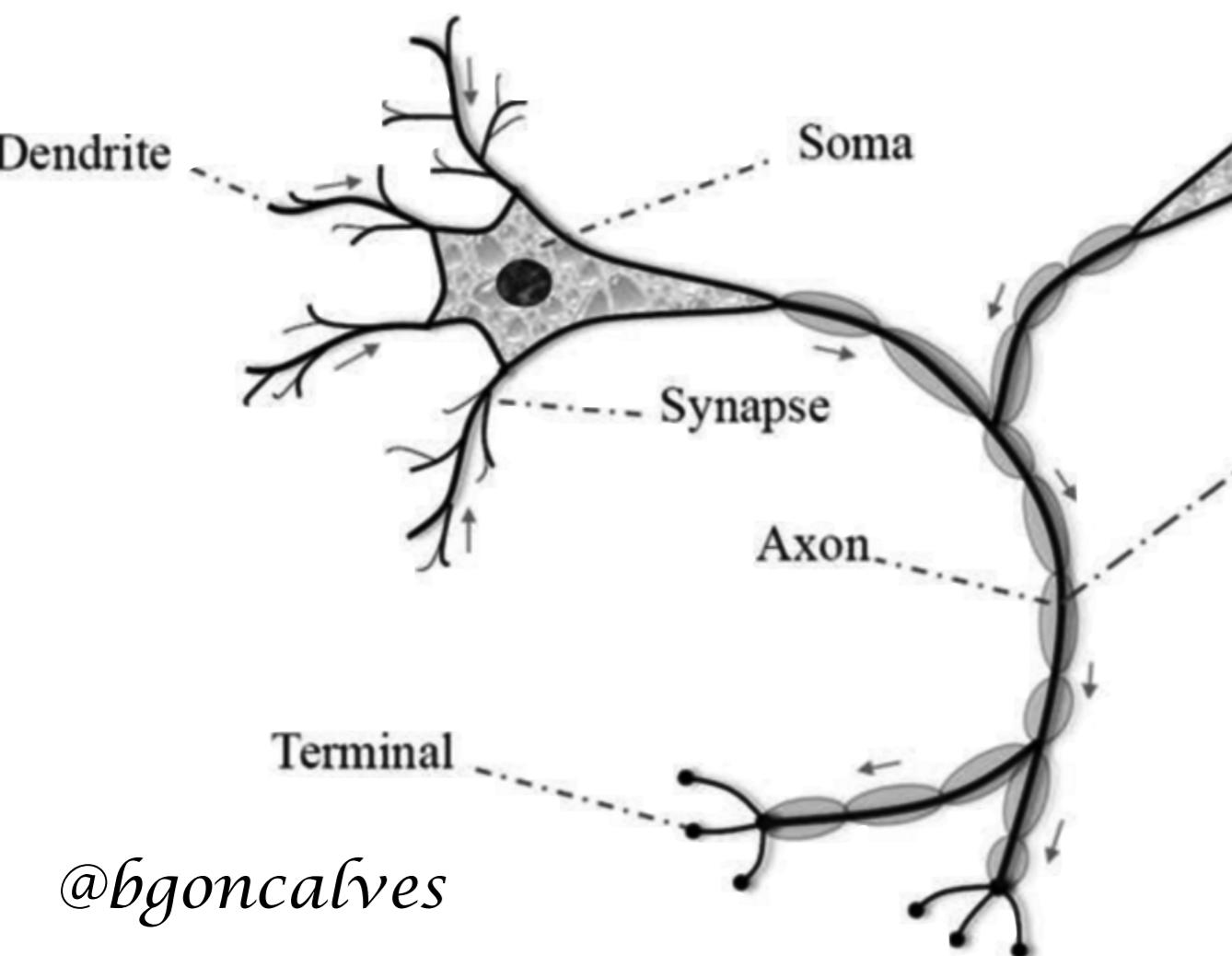
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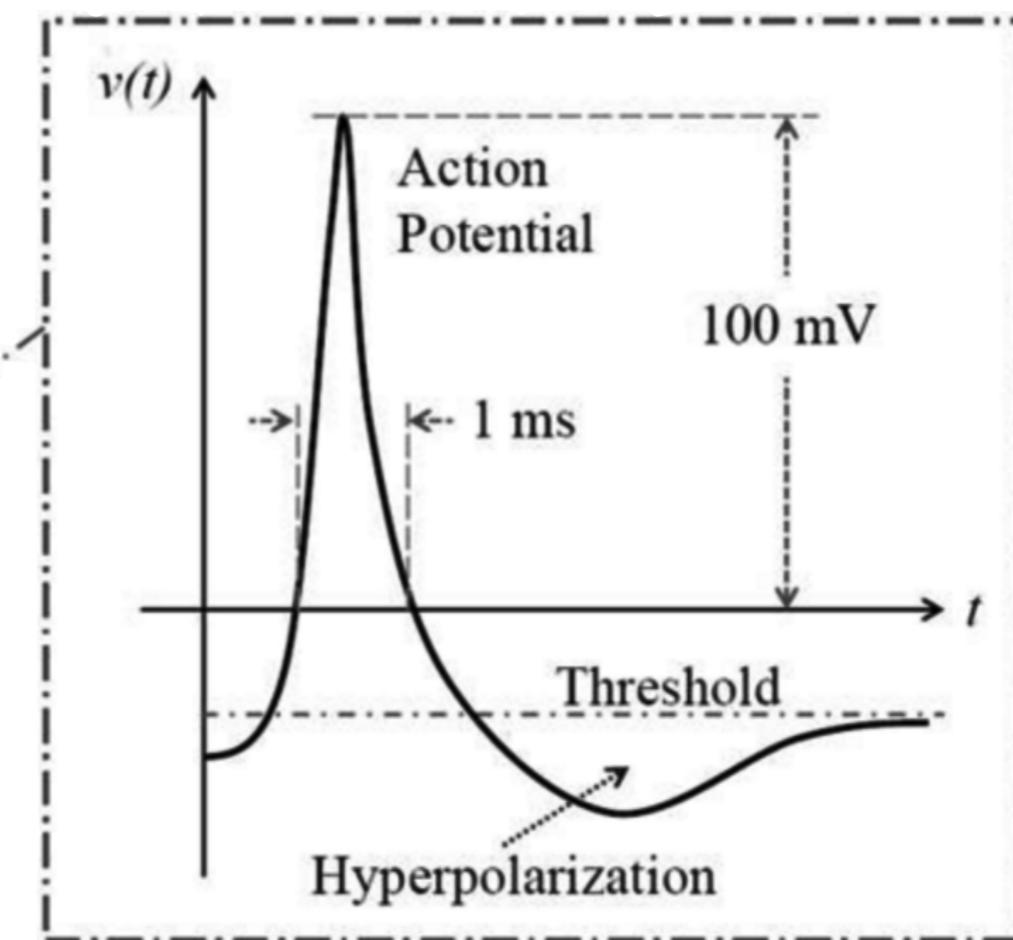
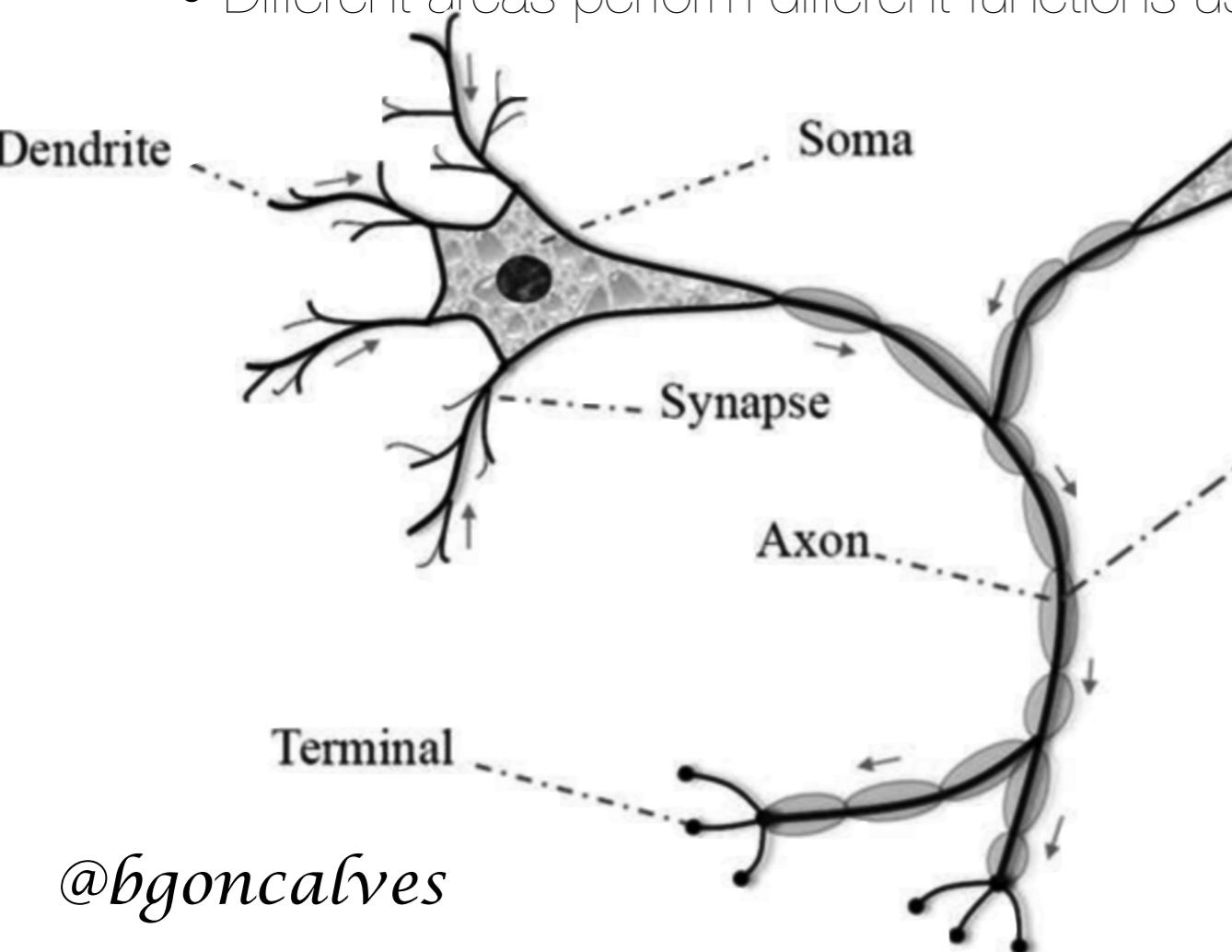
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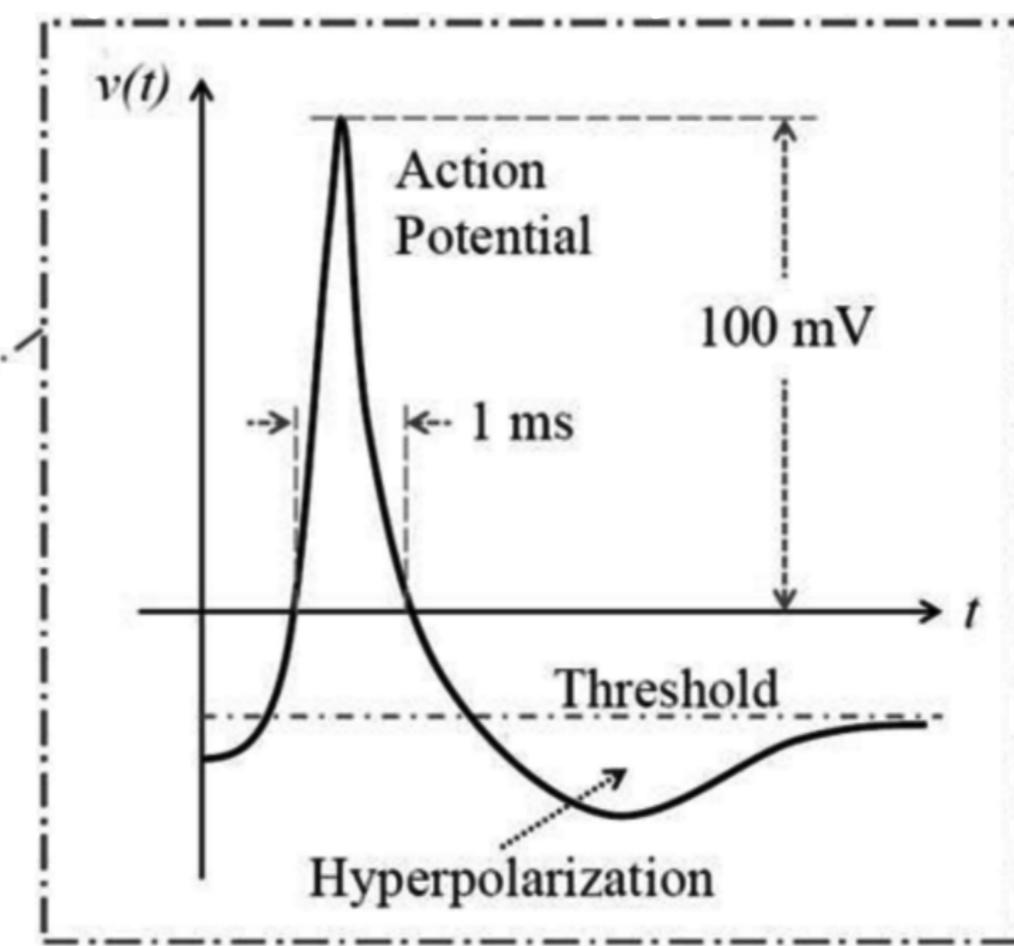
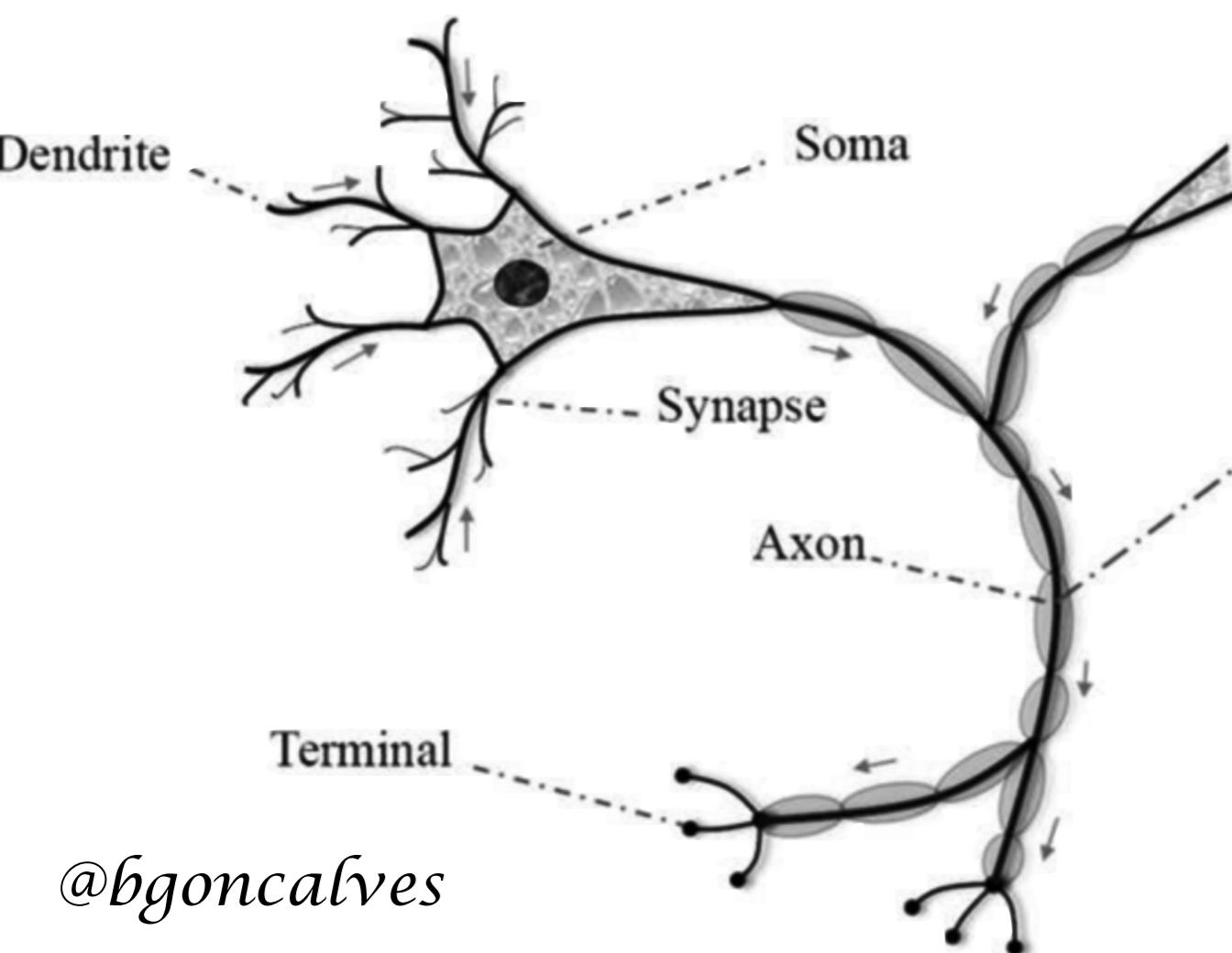


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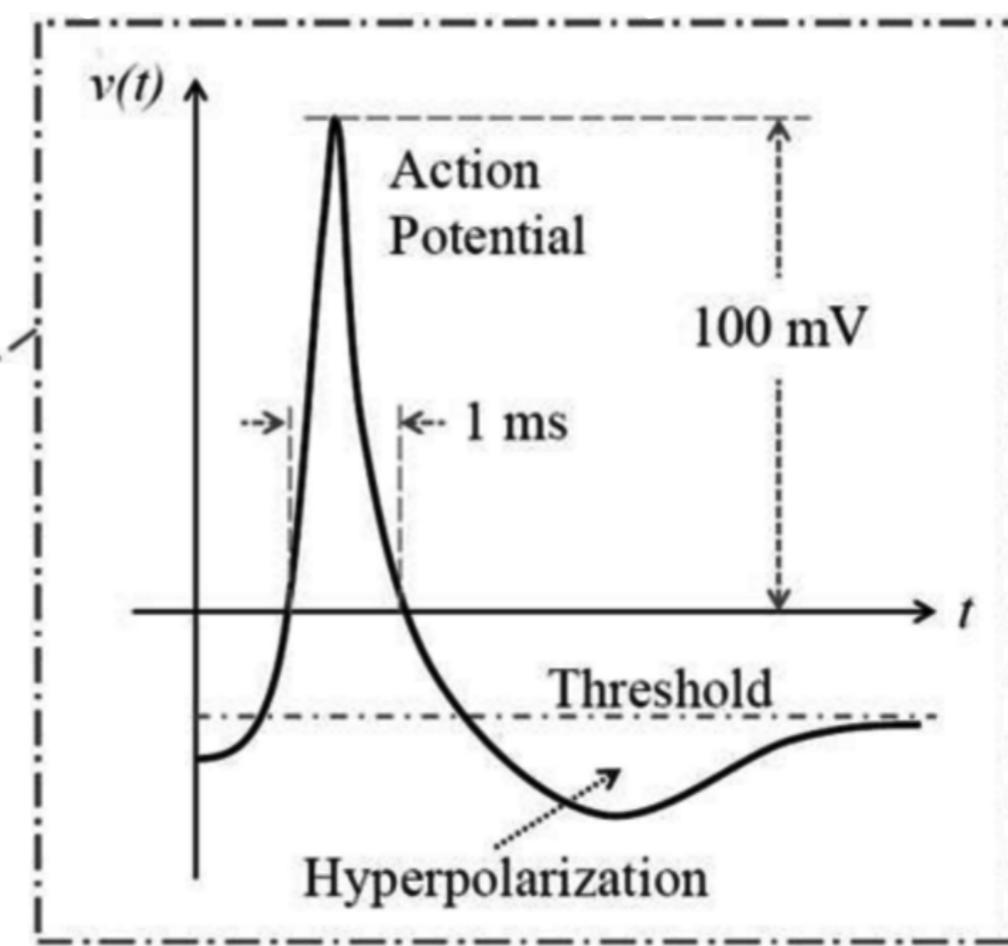
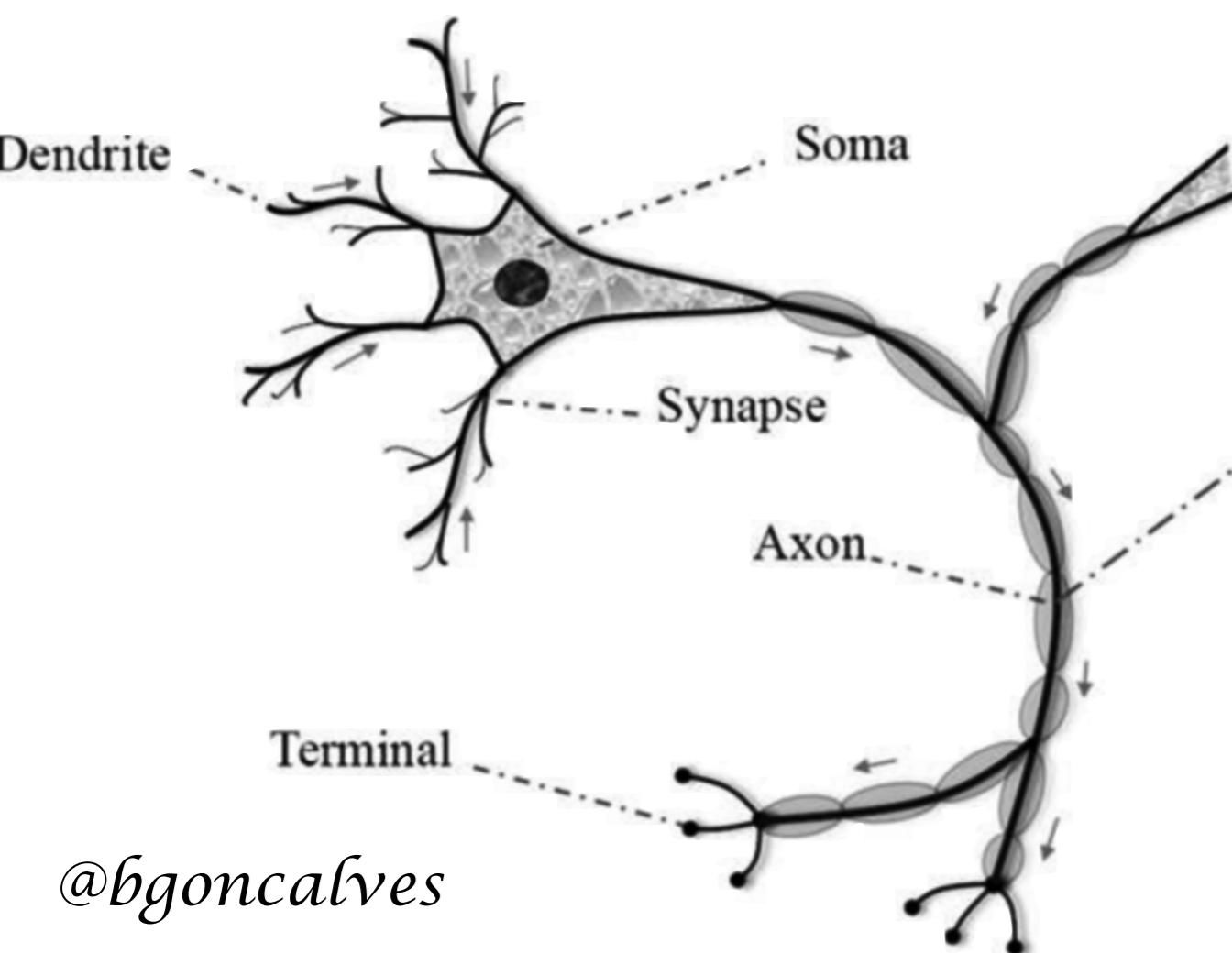
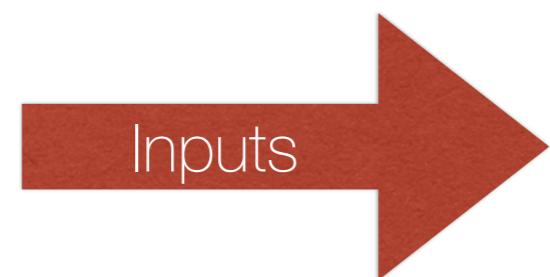
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- “neurons that fire together wire together” (Hebb)
- Different areas perform different functions using same structure (**Modularity**)



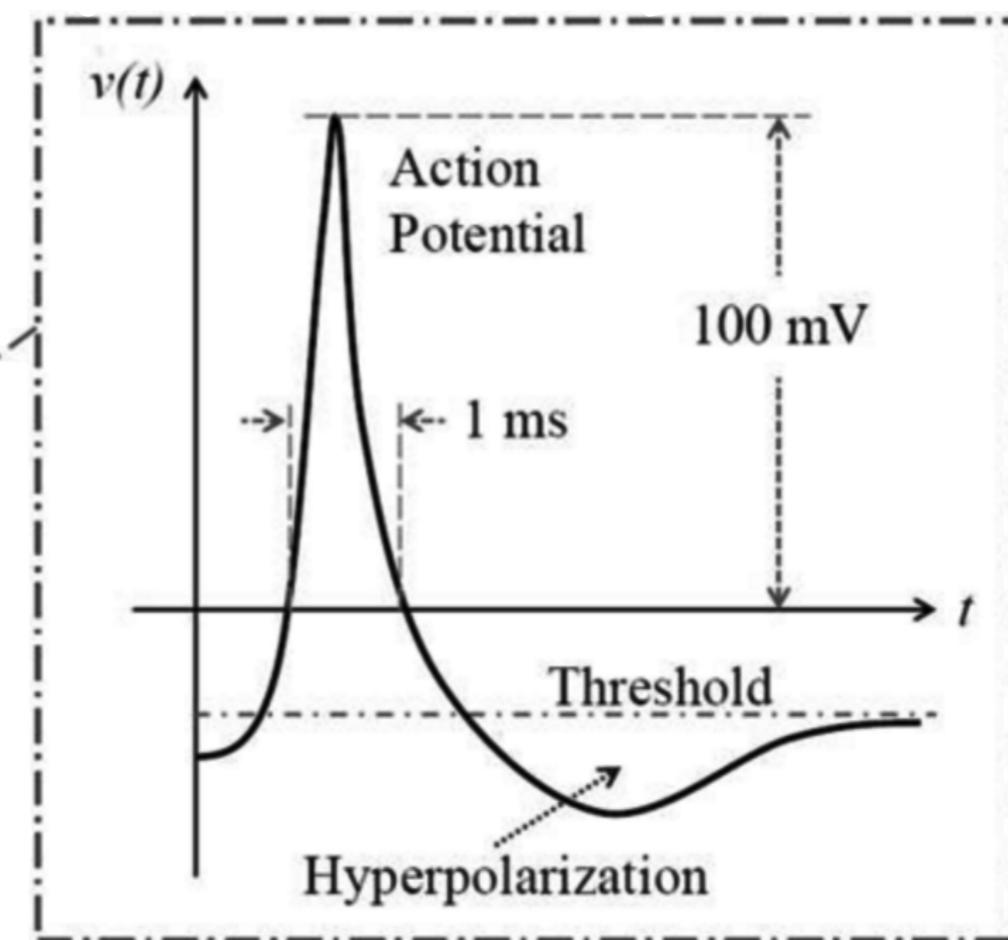
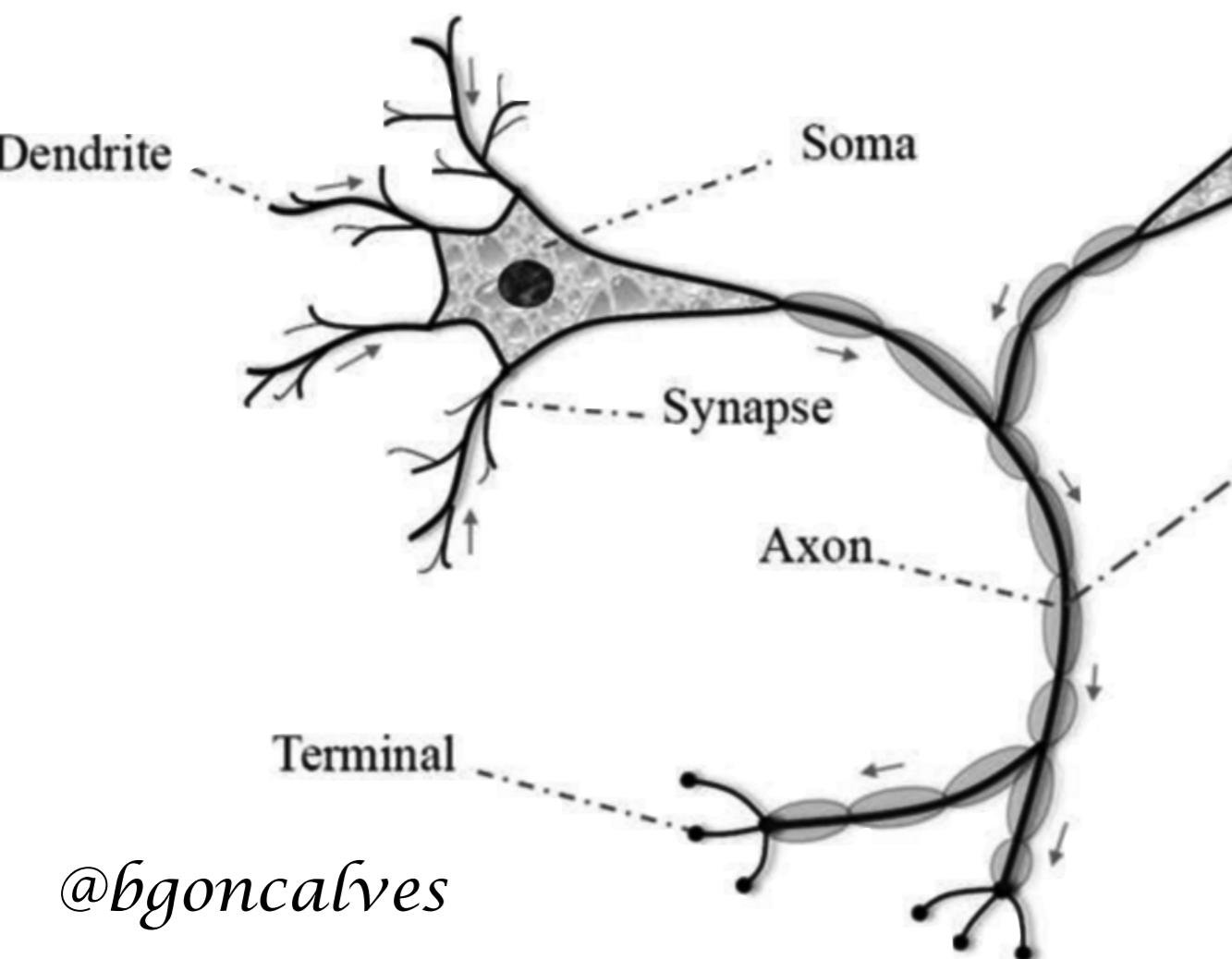
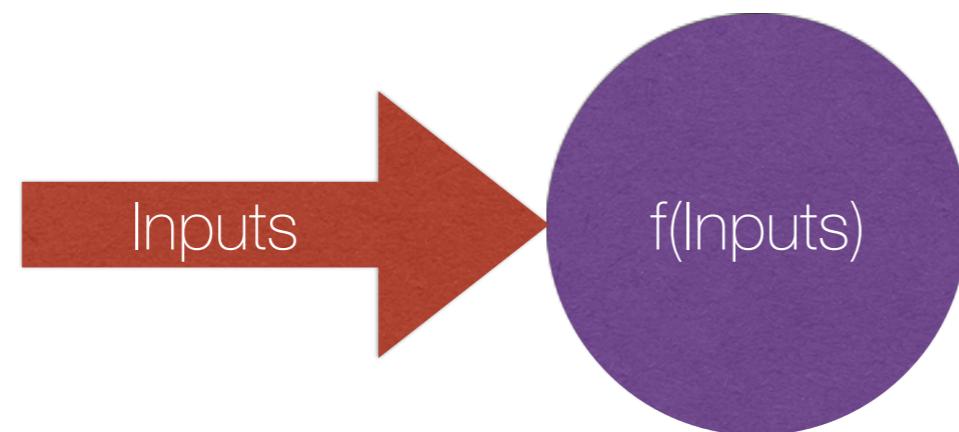
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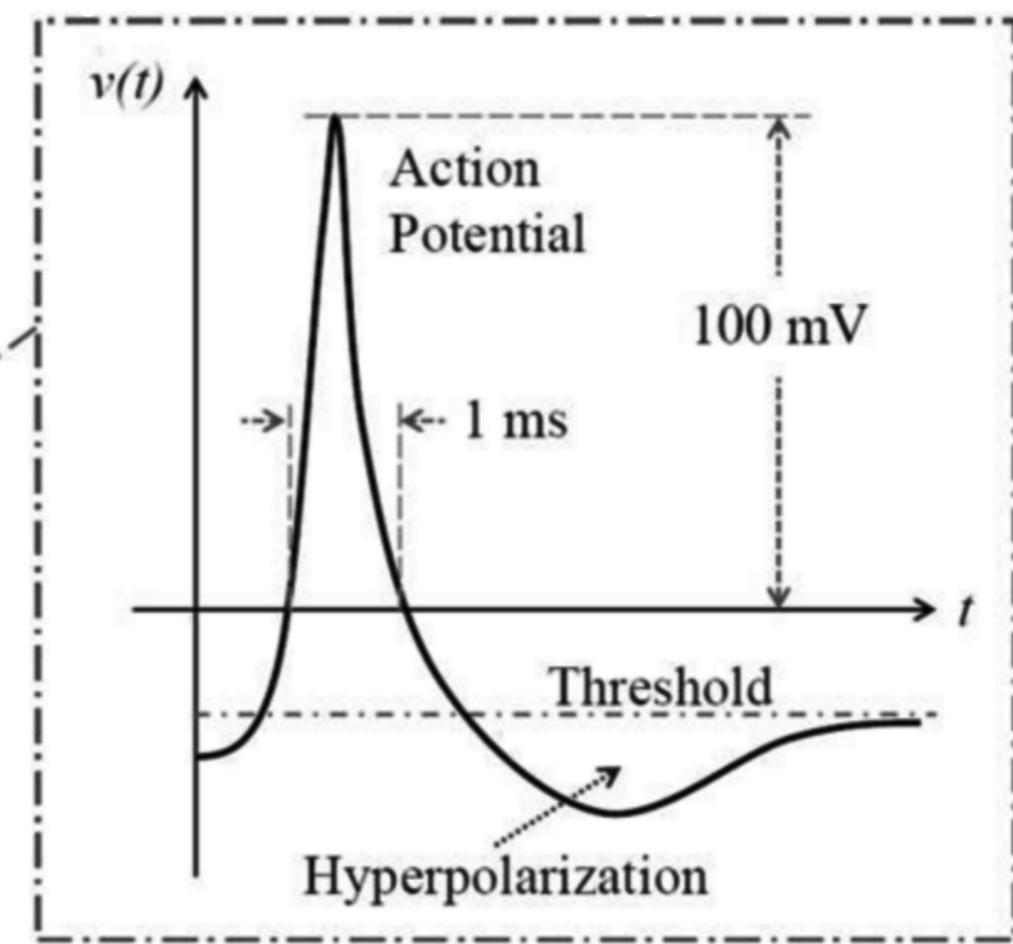
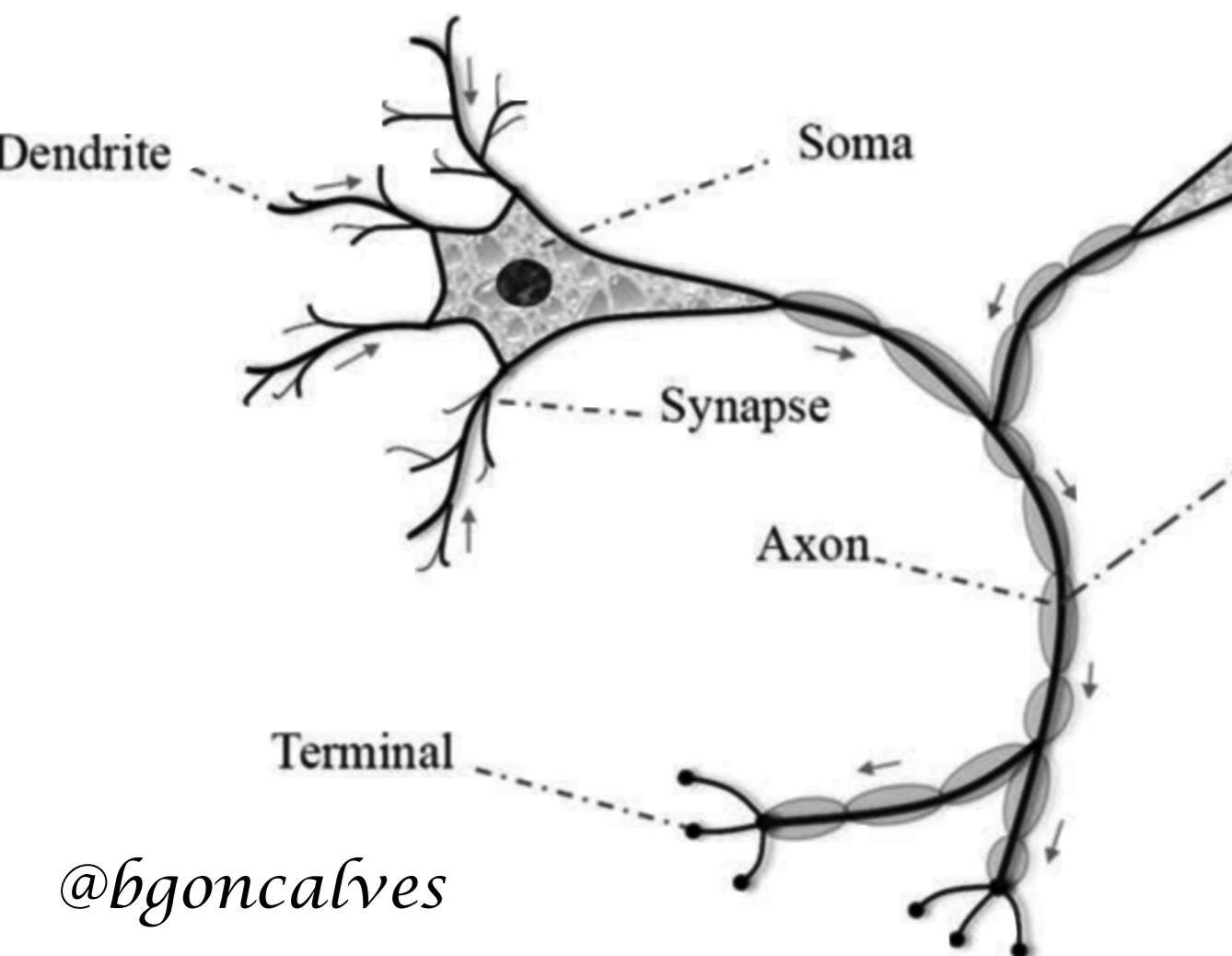
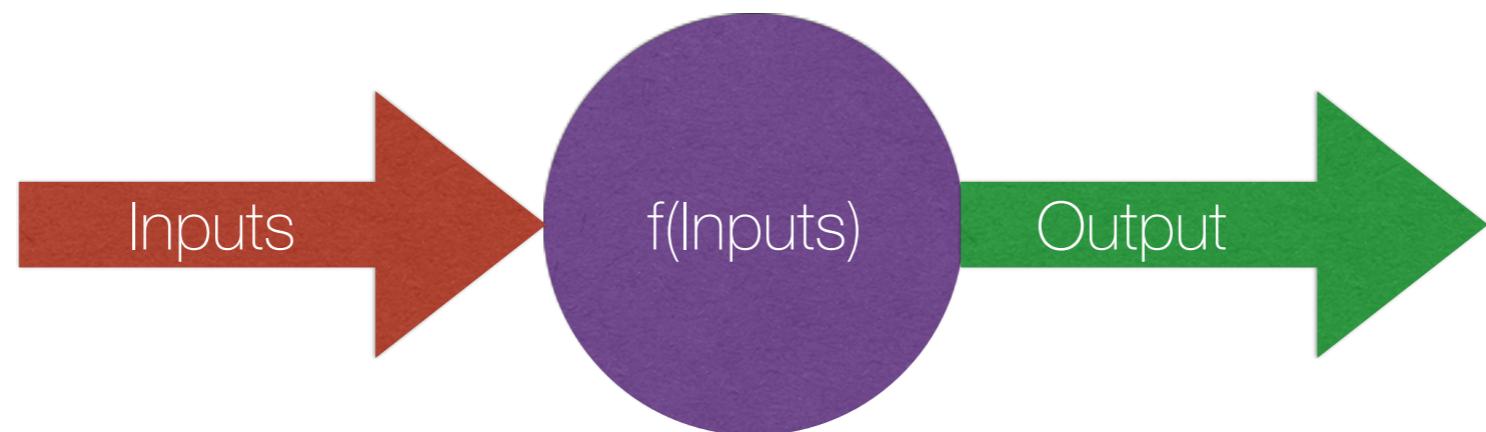
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Optimization Problem

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- Optimization Problems have 3 distinct pieces:



Optimization Problem

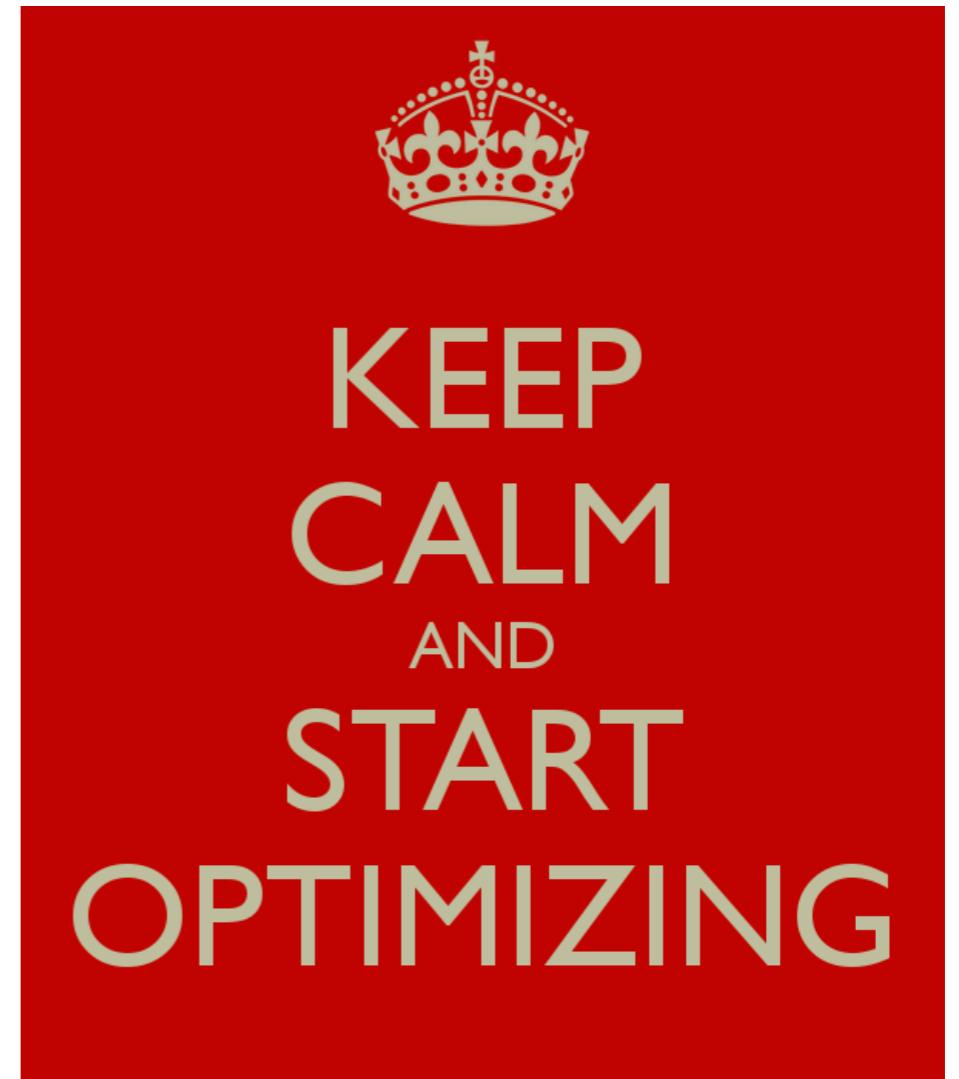
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Optimization Problem

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Neural Network

- The function to optimize

Prediction Error

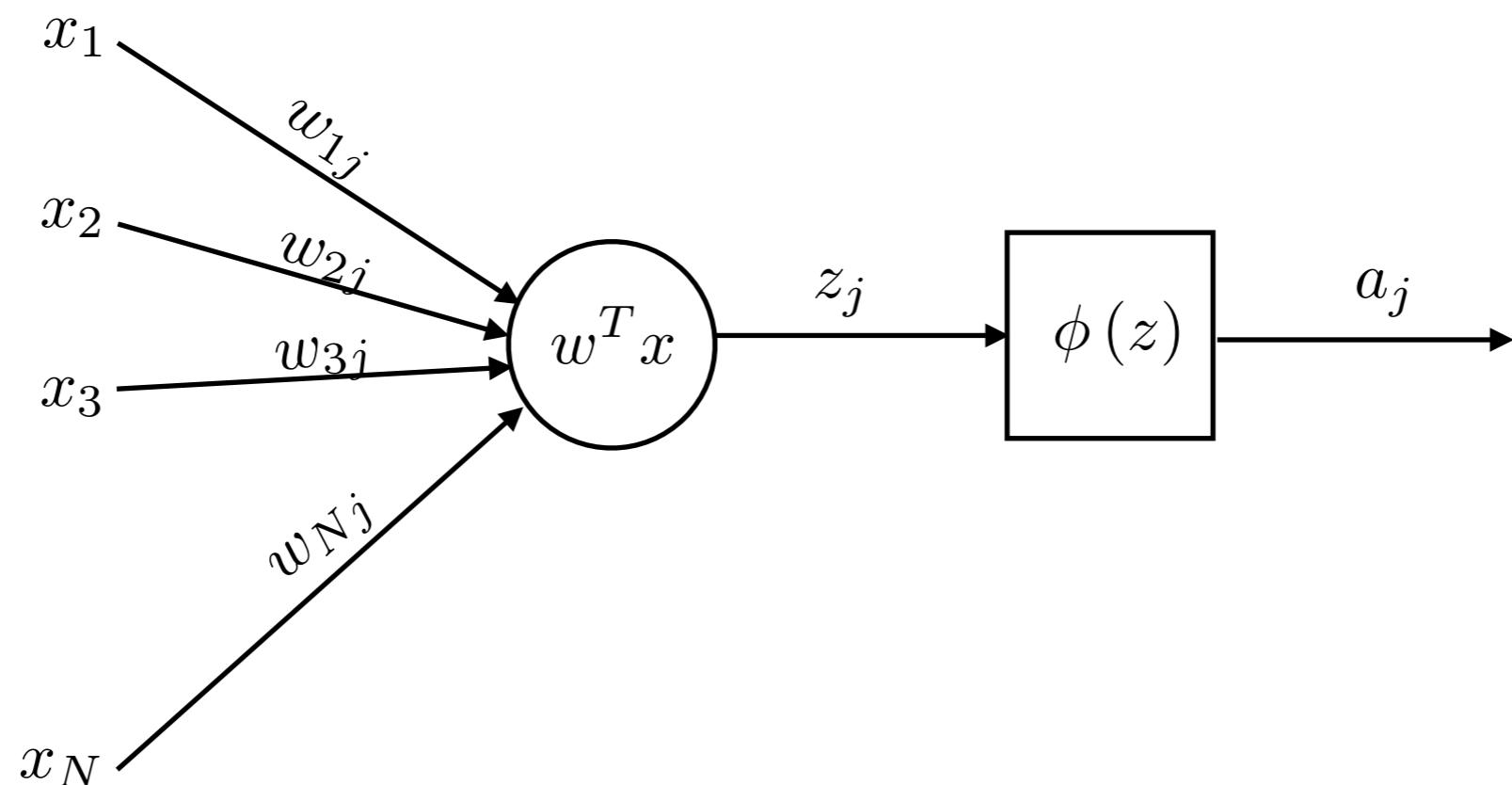
- The optimization algorithm

Gradient Descent

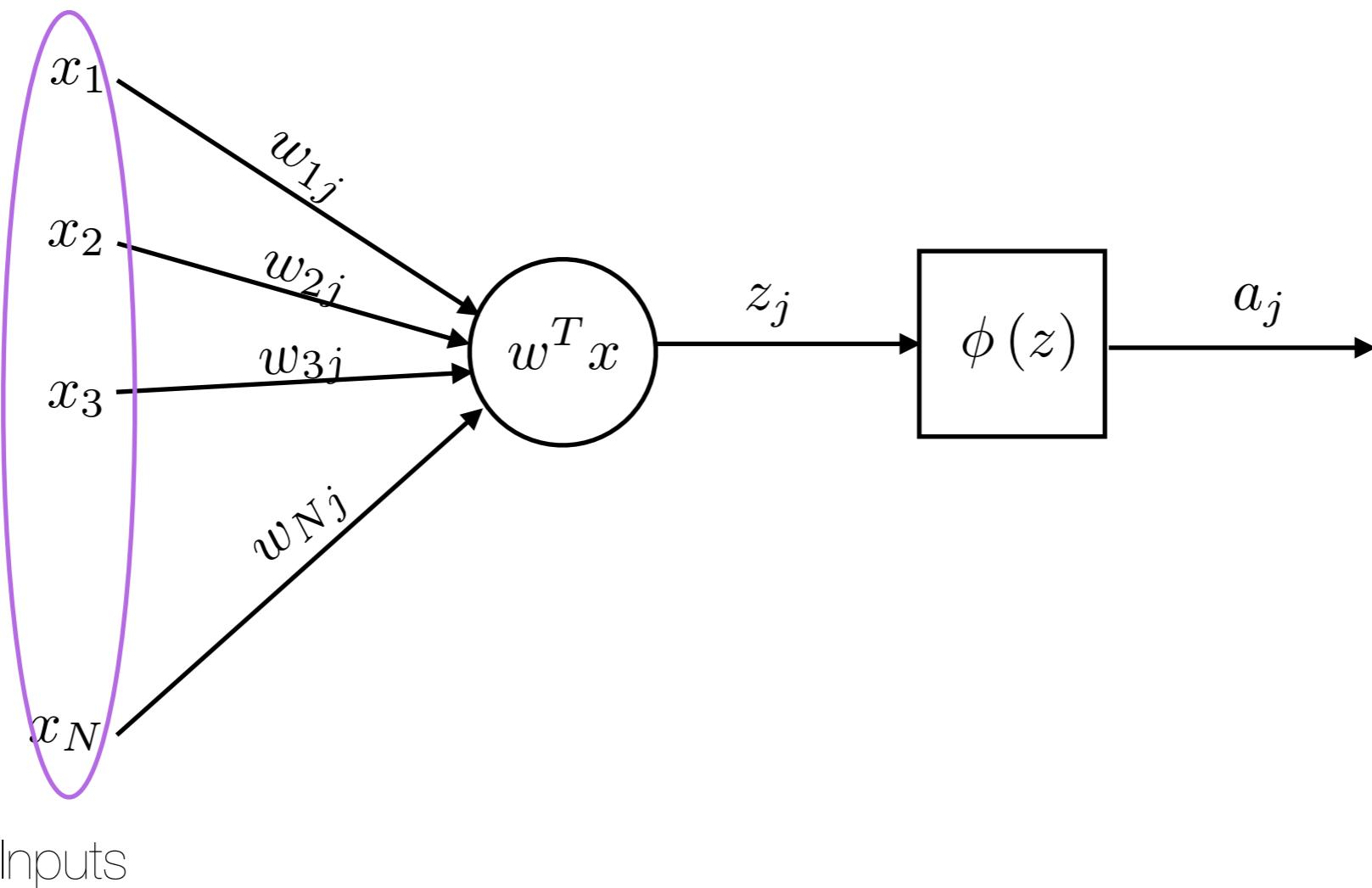


Artificial Neuron

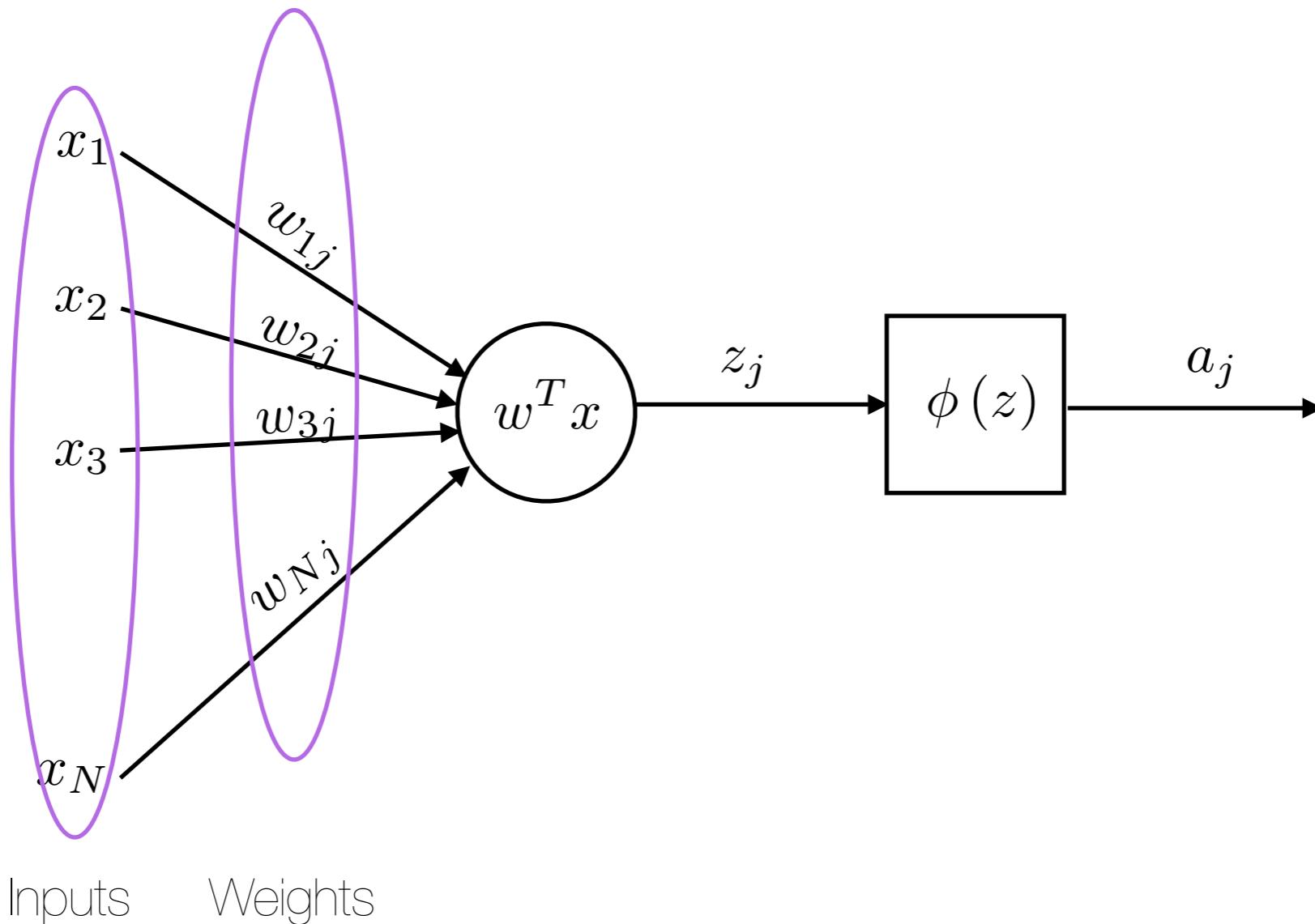
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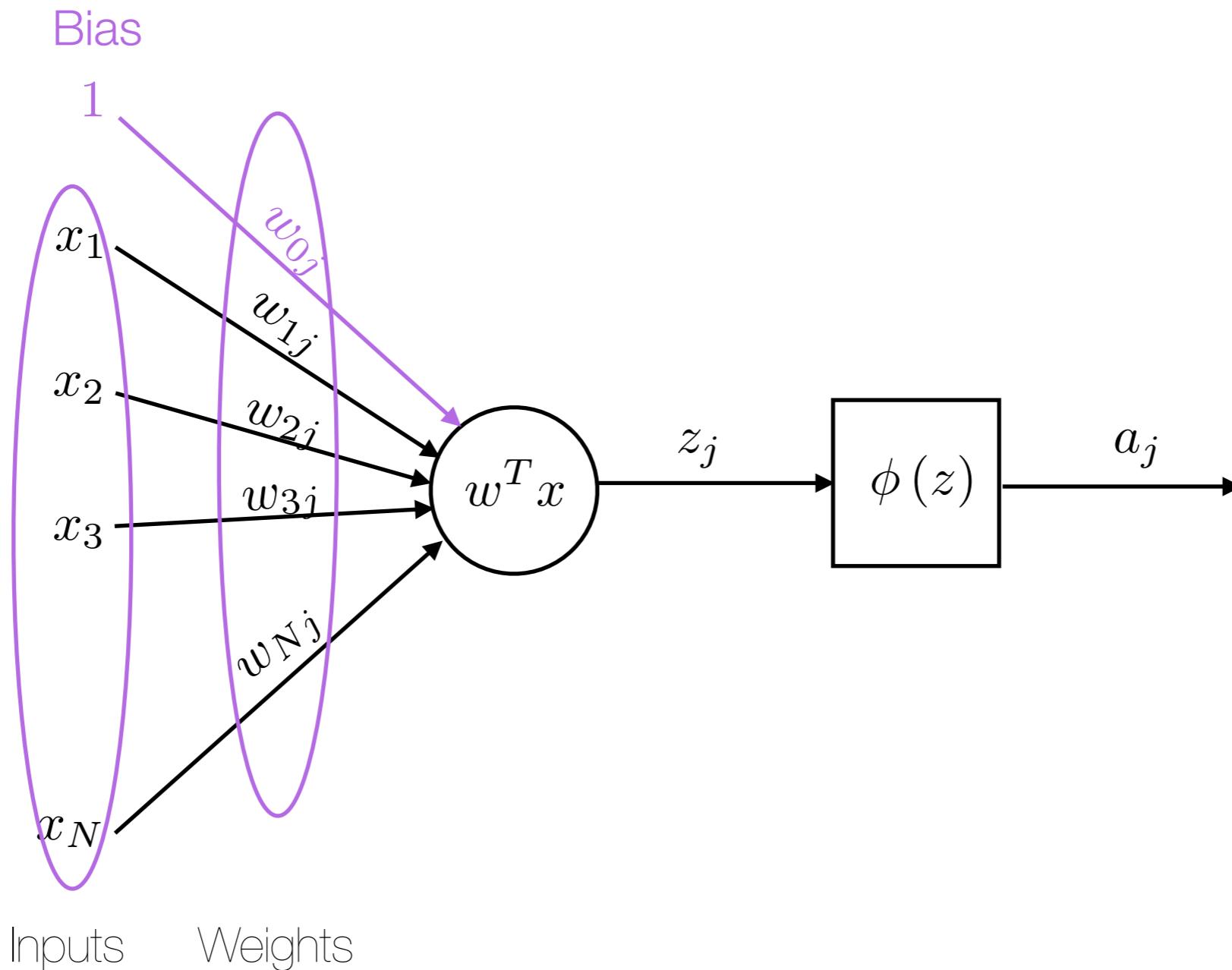
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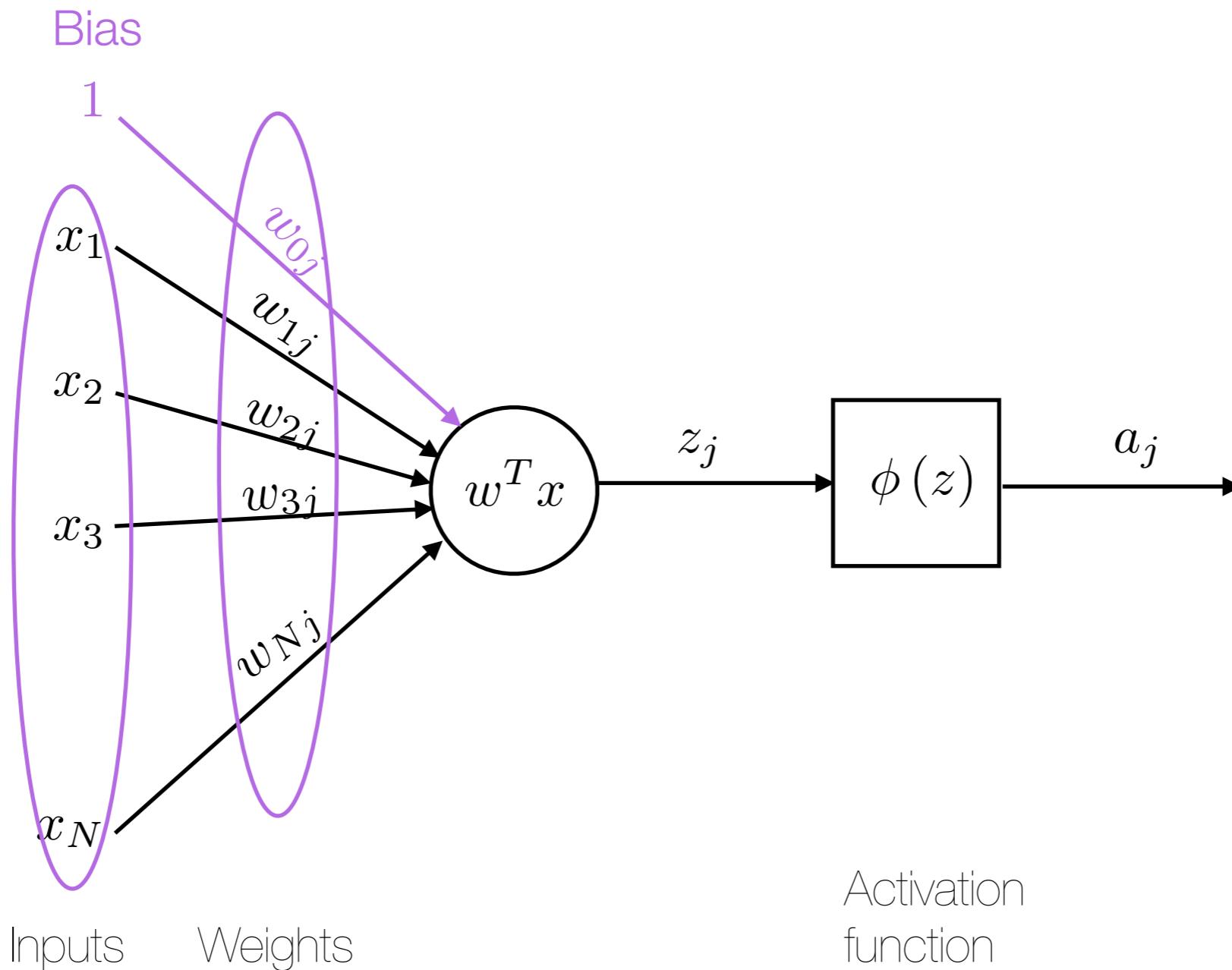
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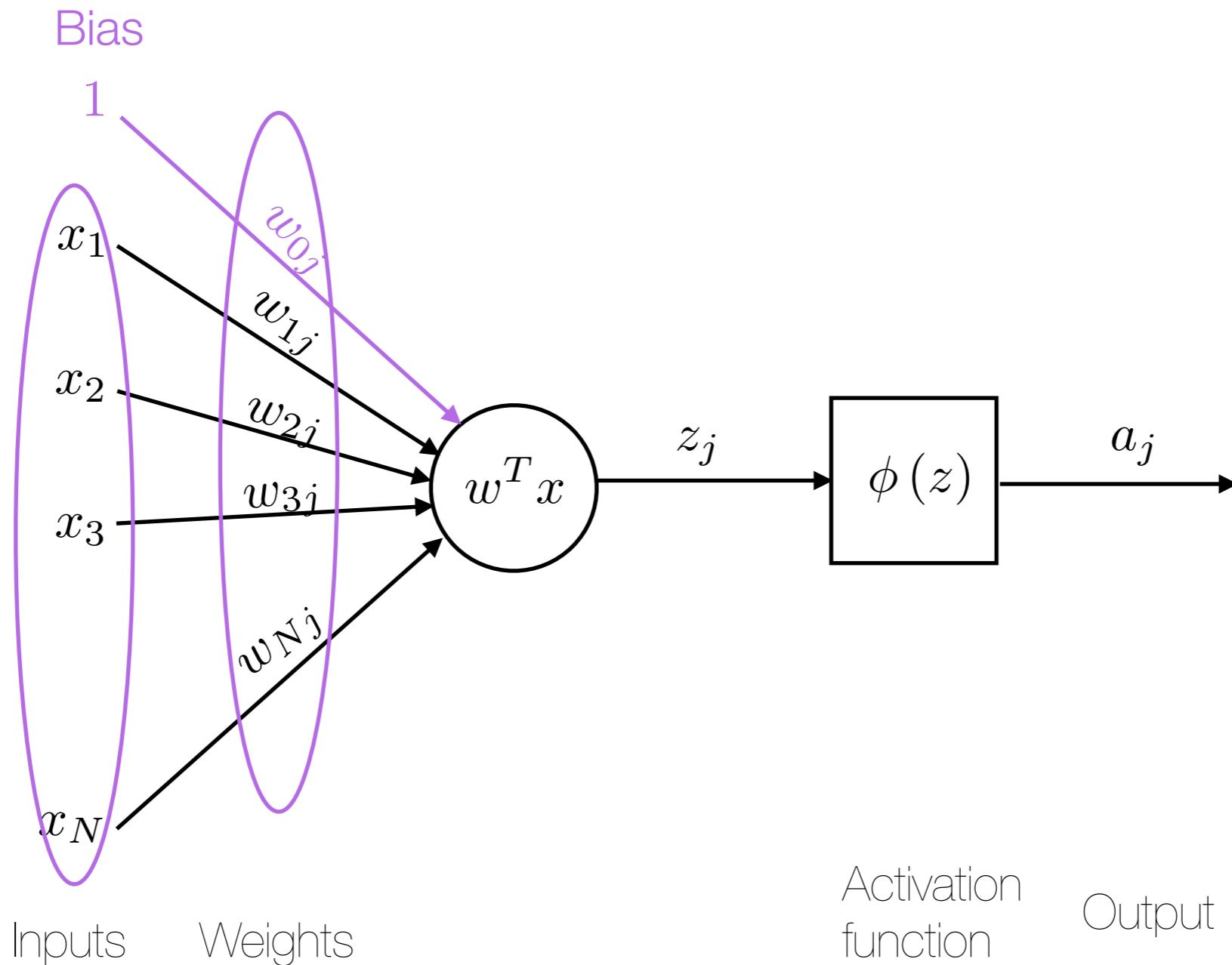
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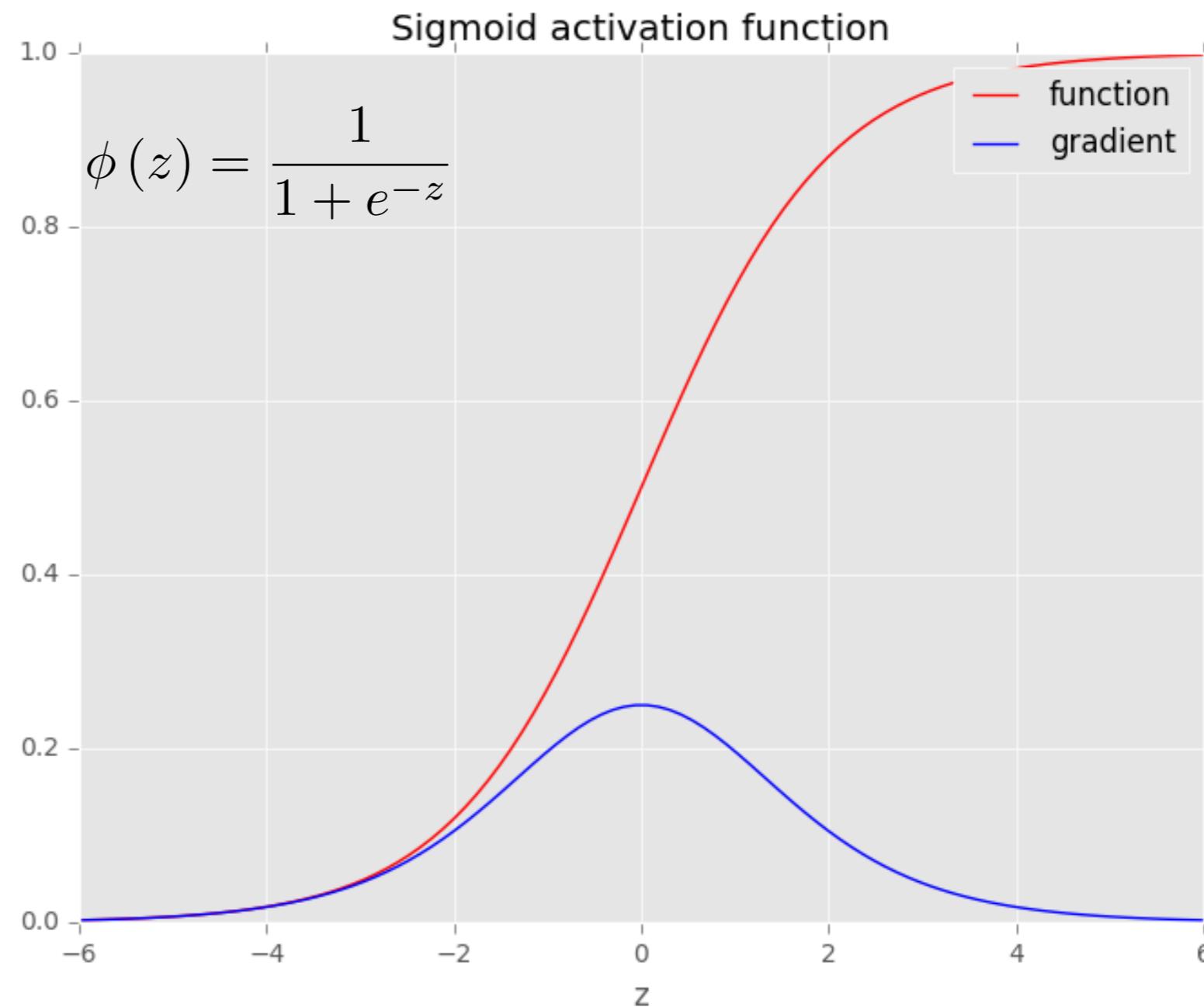


Artificial Neuron



Activation Function - Sigmoid

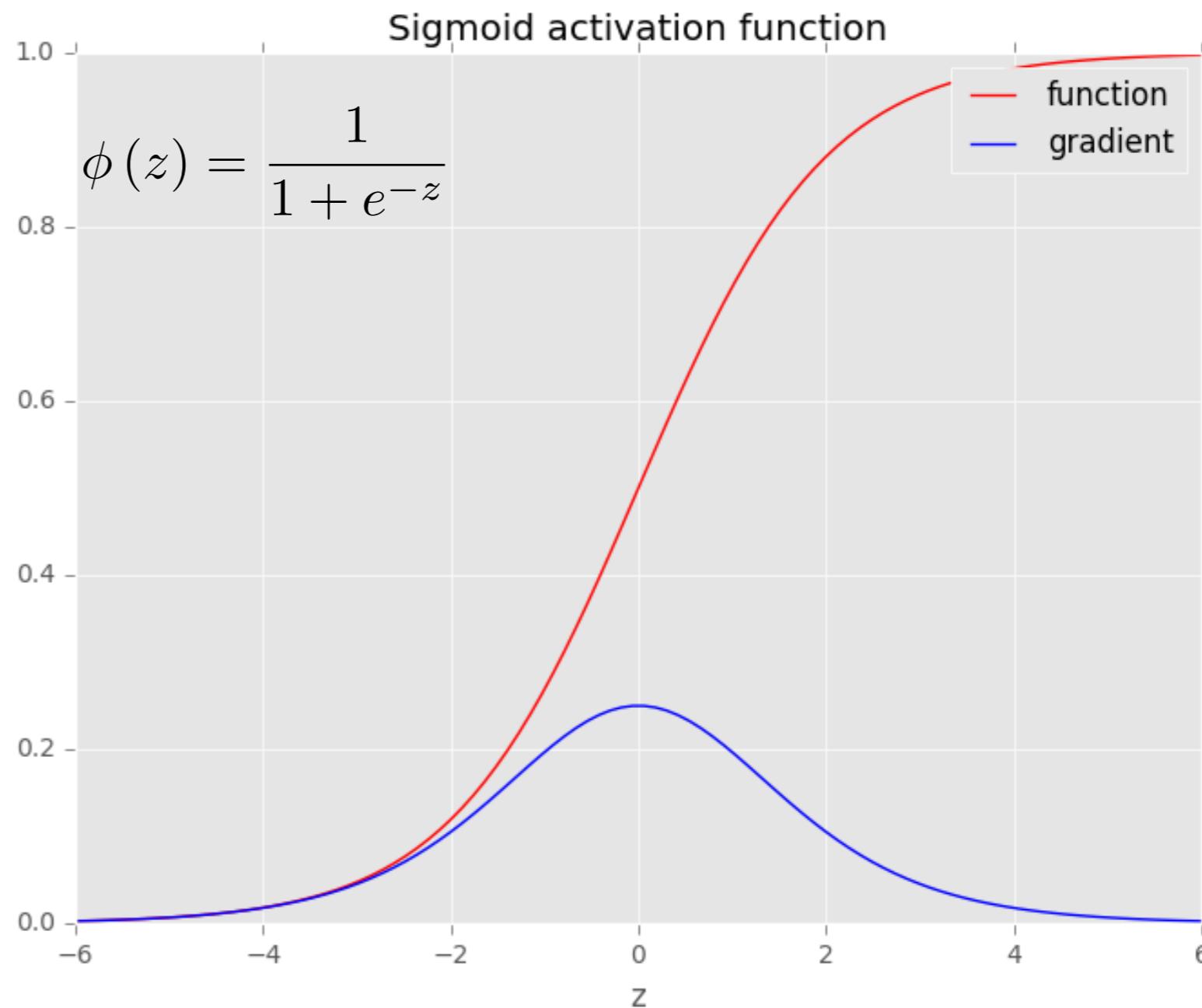
<http://github.com/bmtgoncalves/Neural-Networks>



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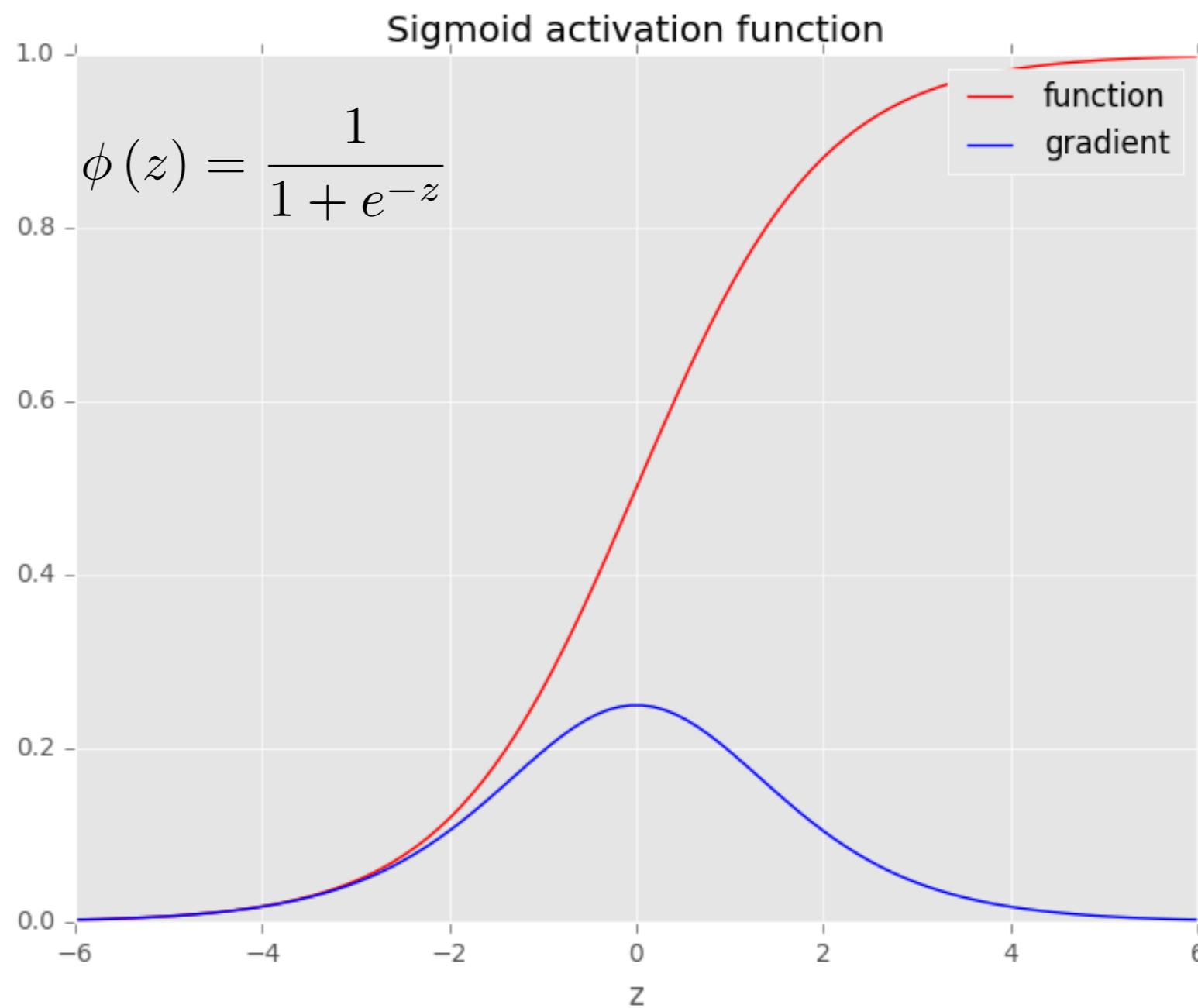
- Non-Linear function



Activation Function - Sigmoid

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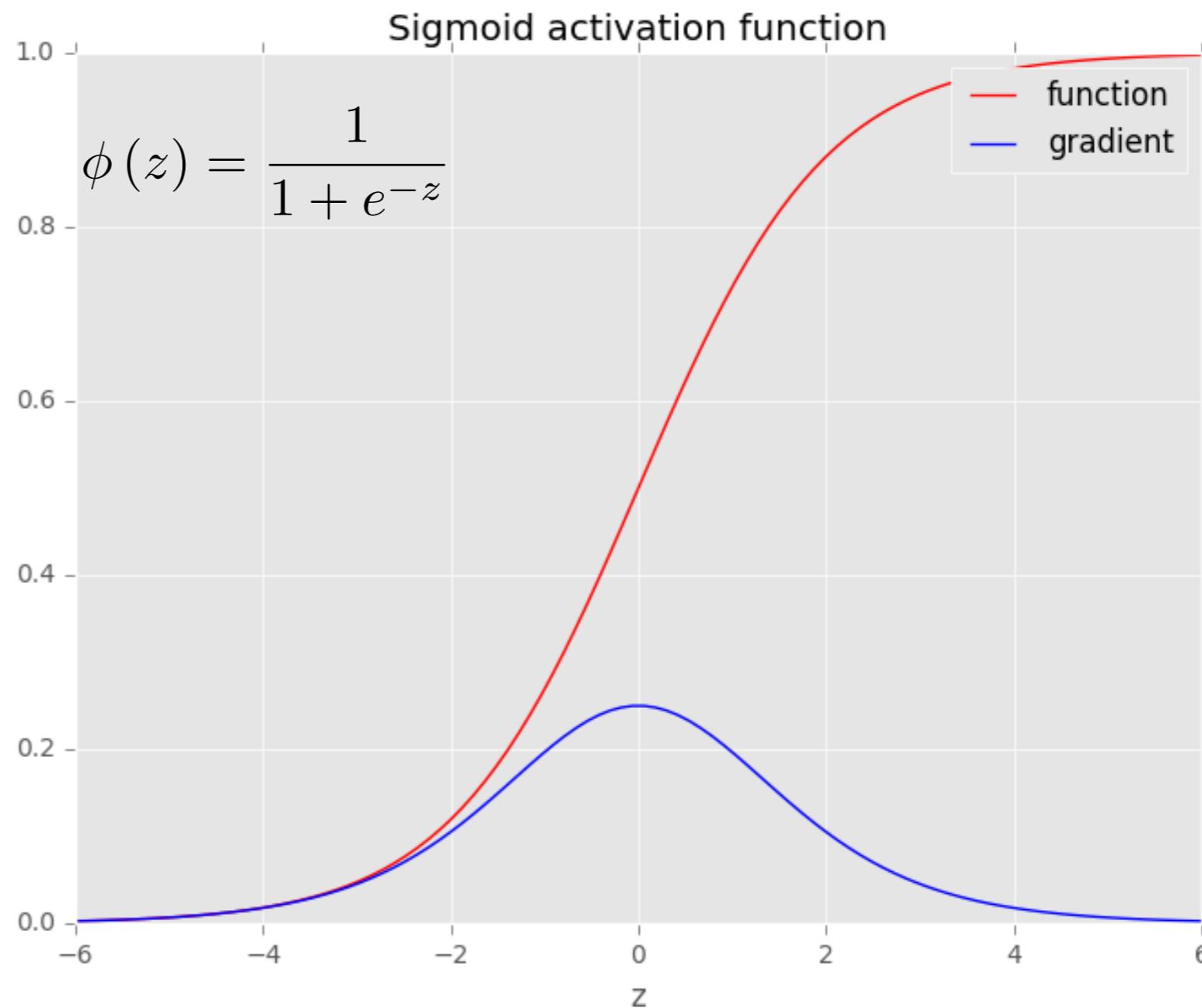
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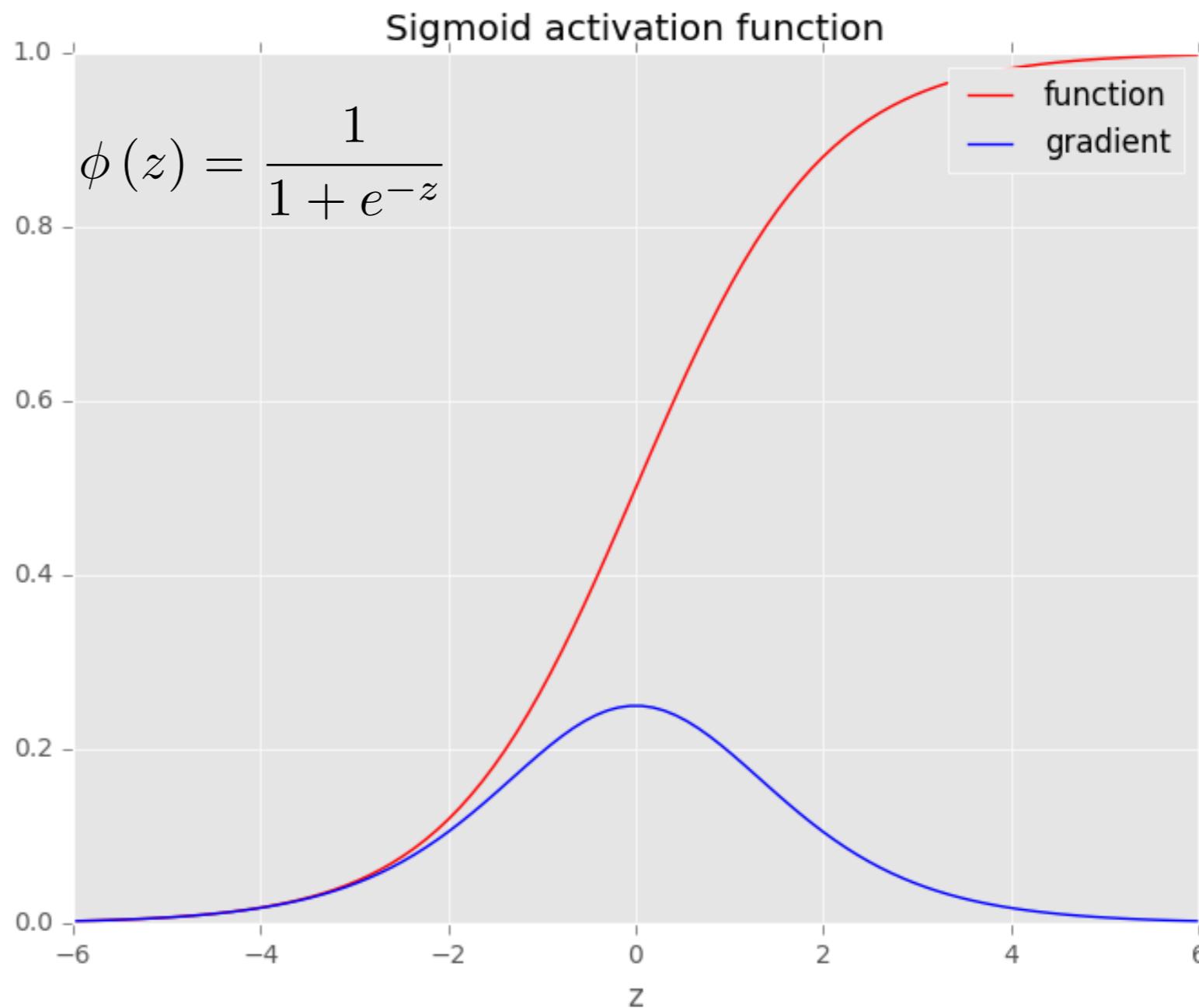
- non-decreasing



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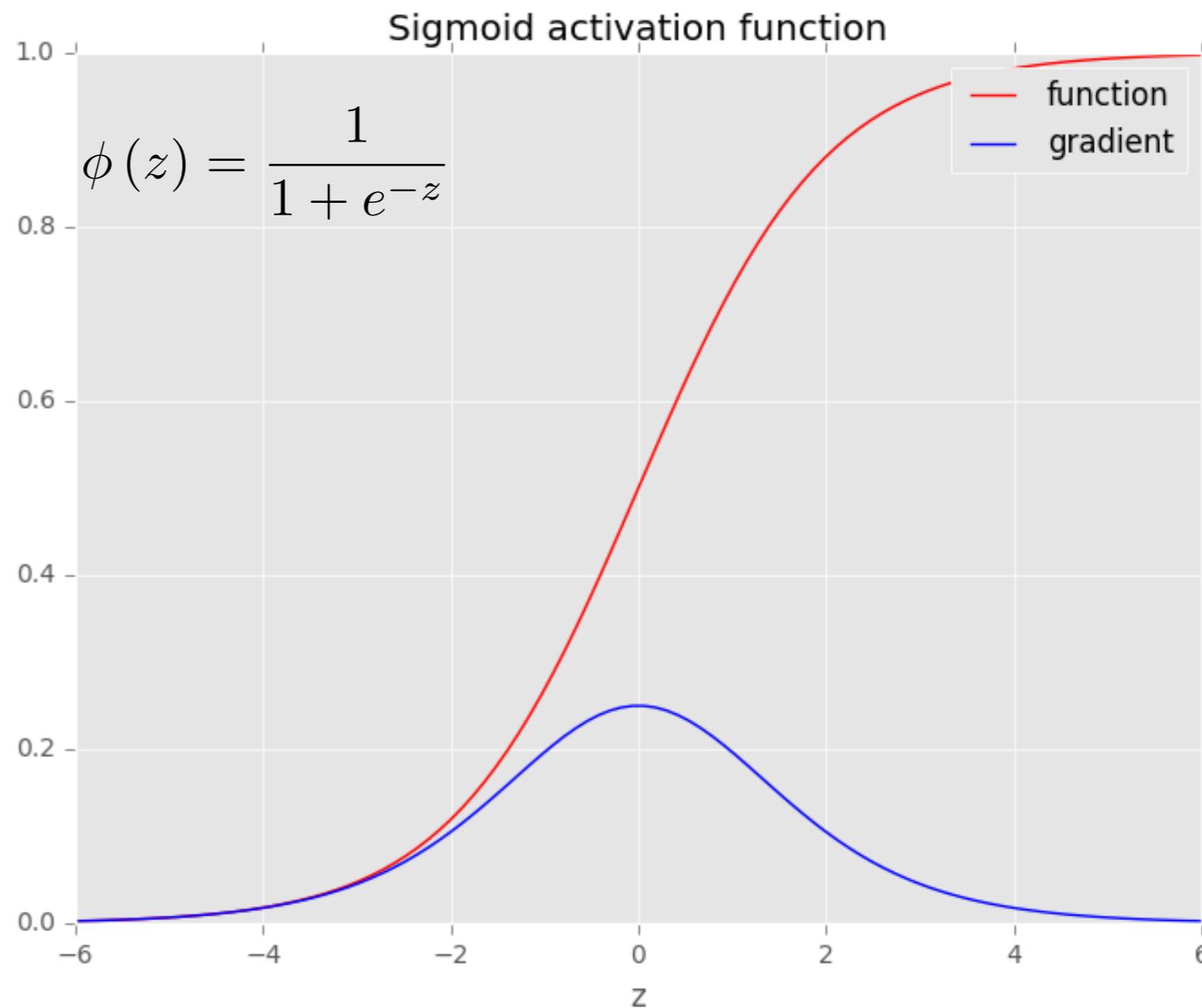
- Non-Linear function
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- Compute new sets of features



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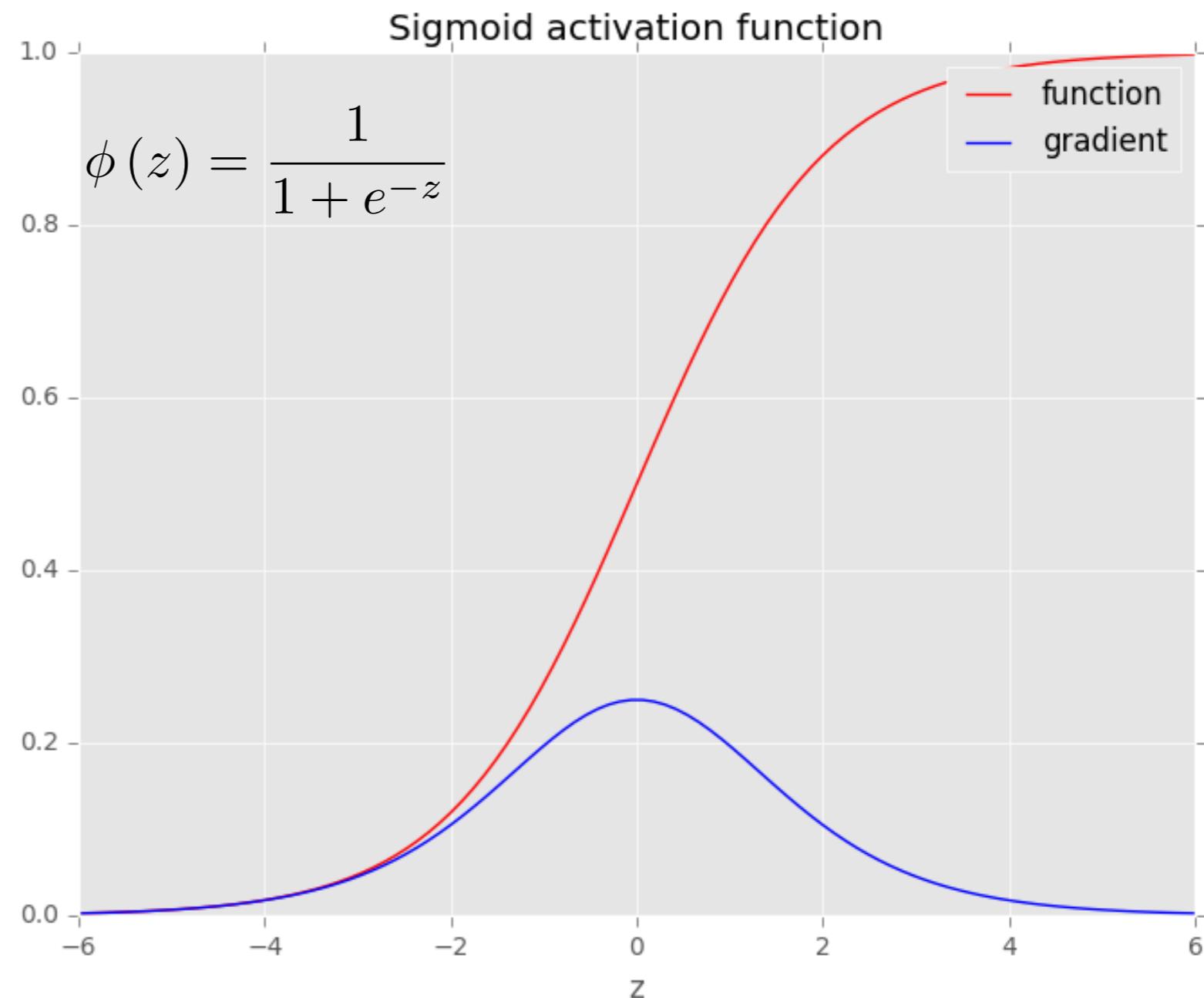
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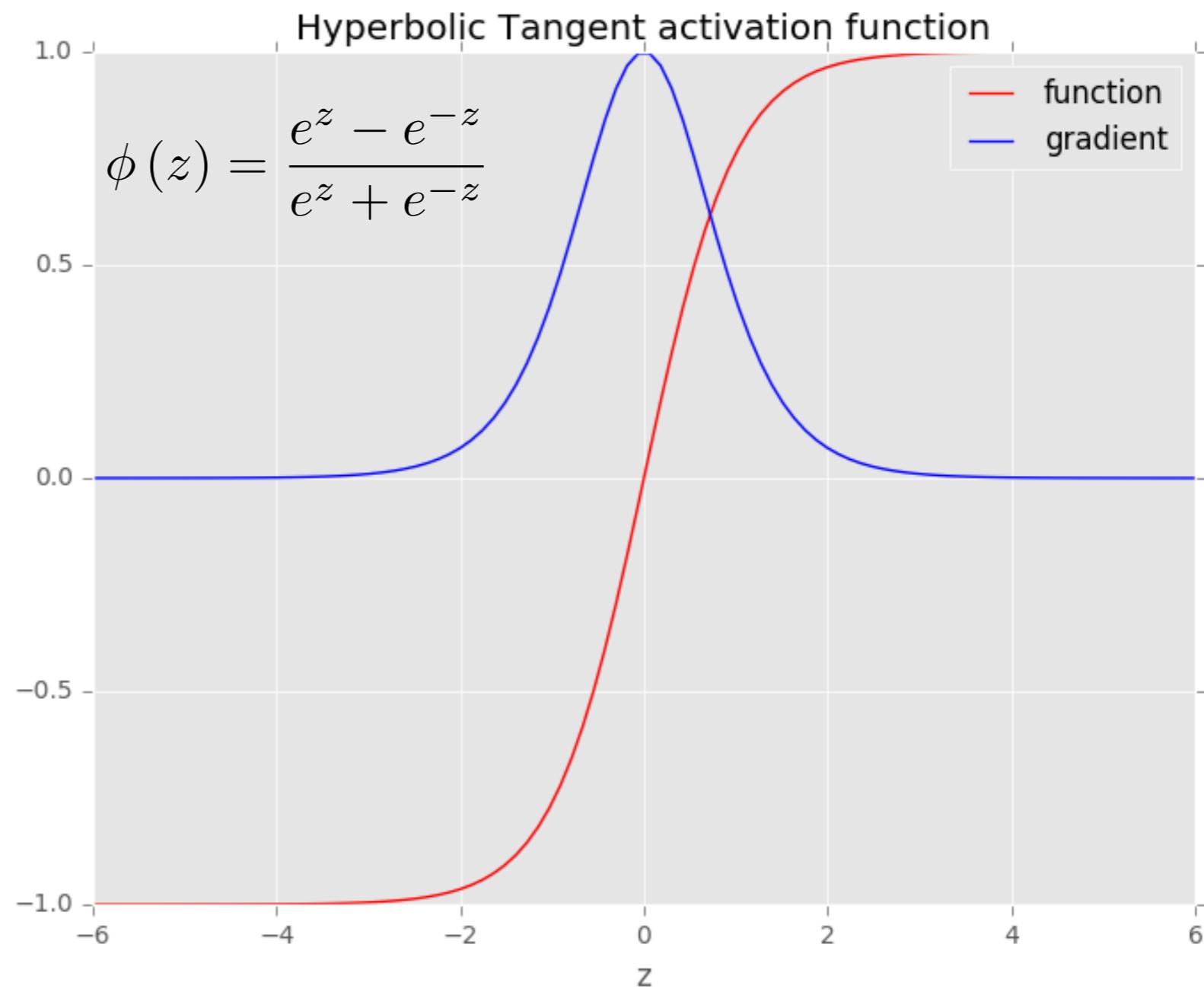
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- Non-Linear function
- Differentiable
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- Perhaps the **most common**



Activation Function - tanh

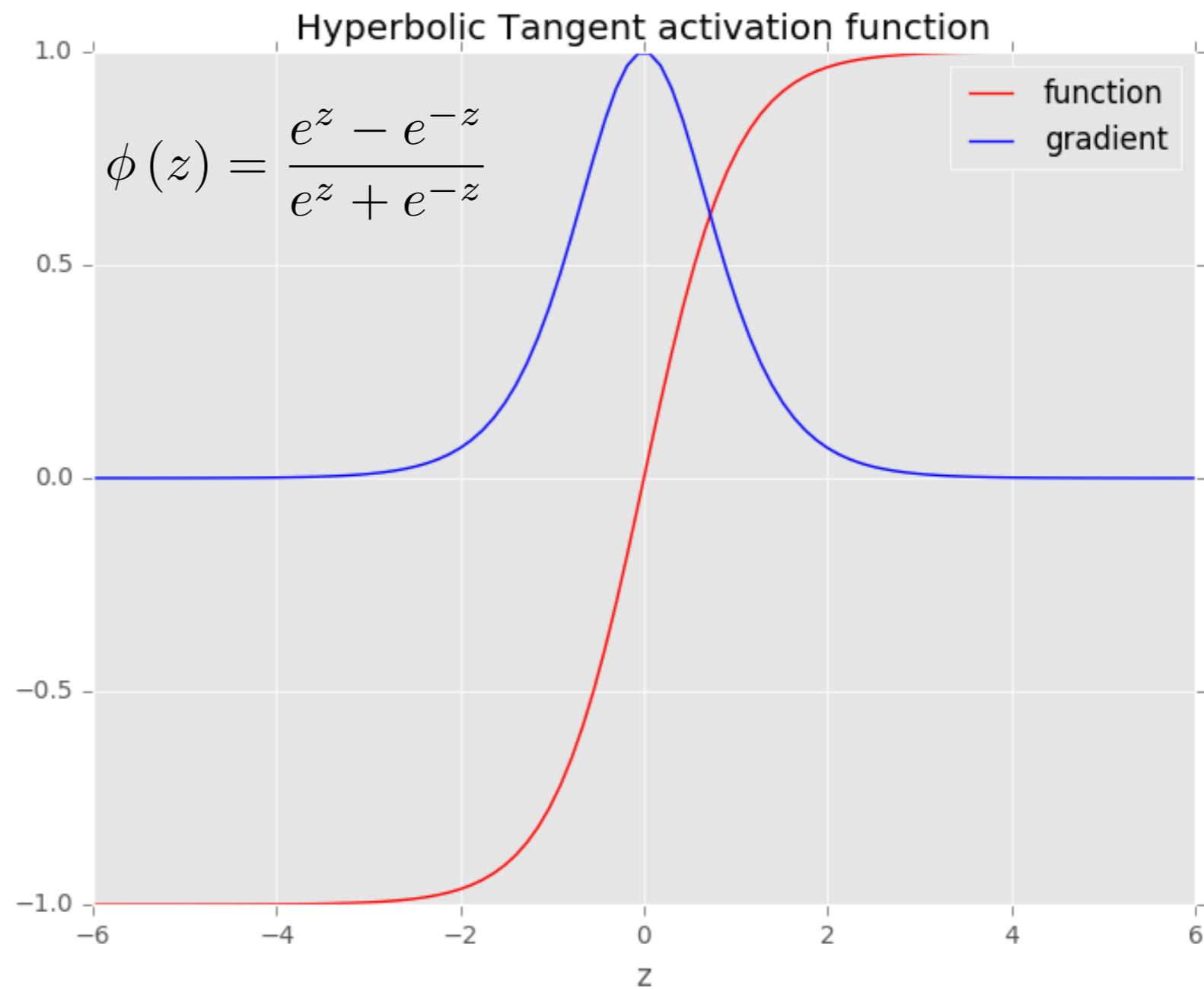
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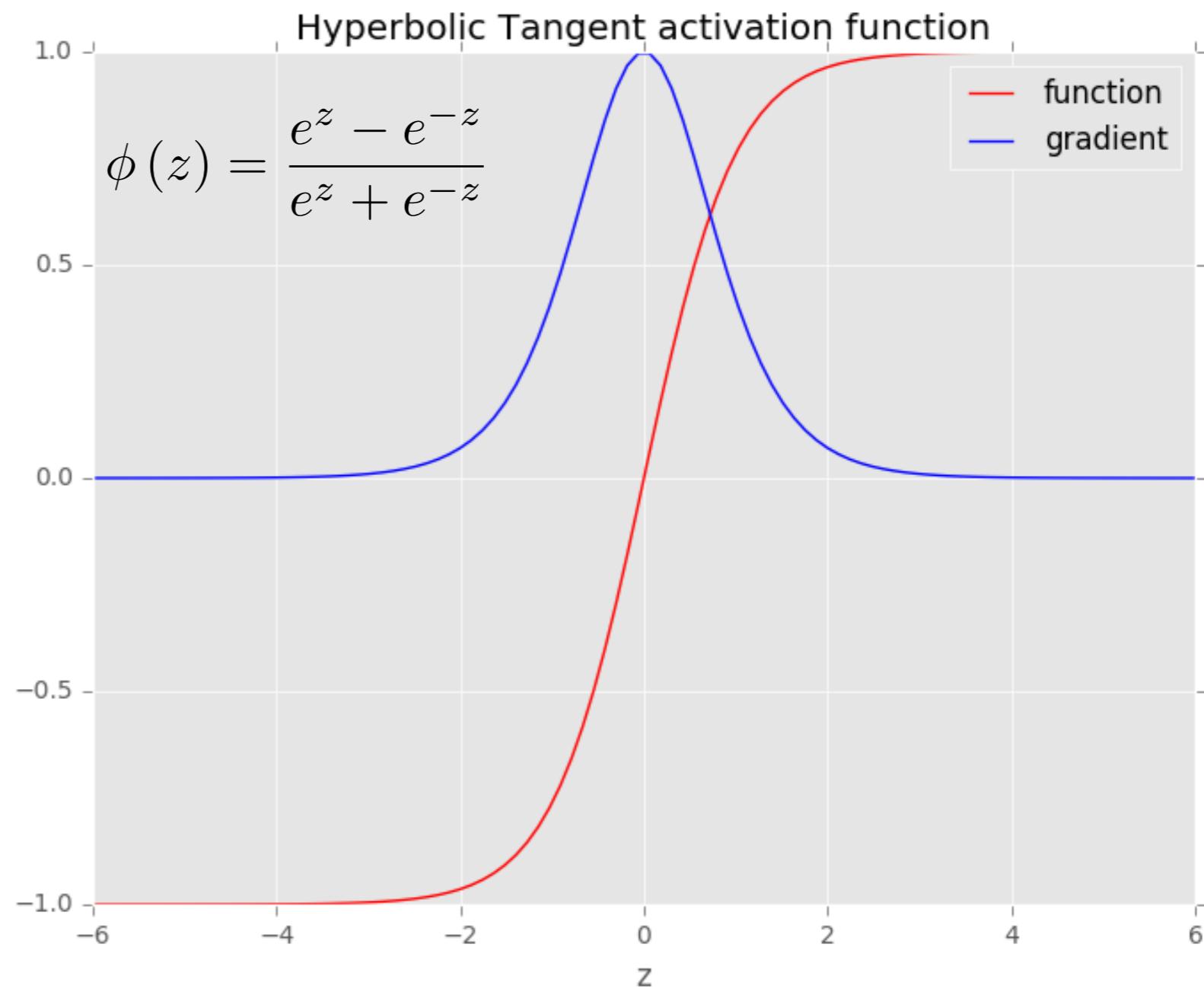


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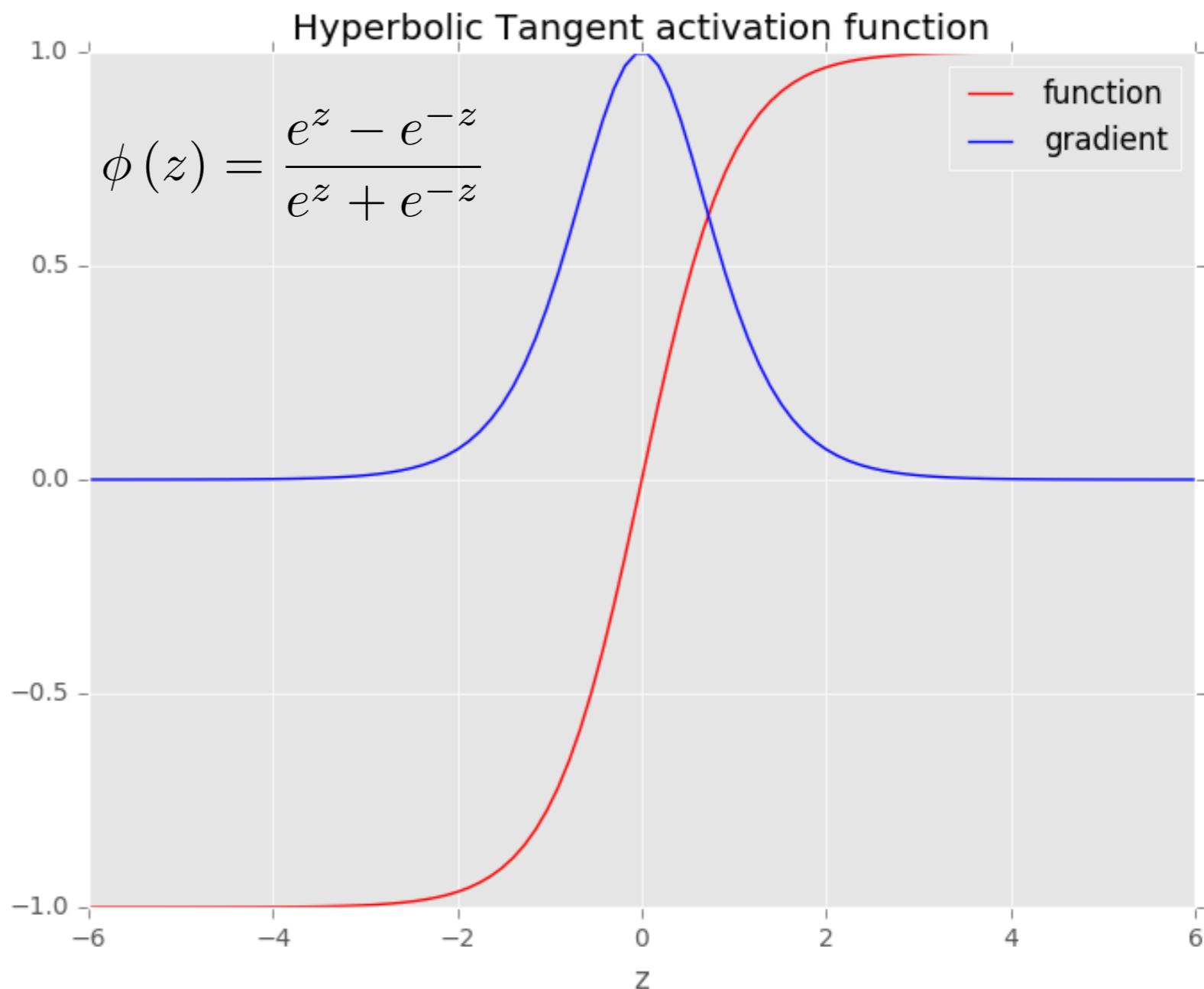
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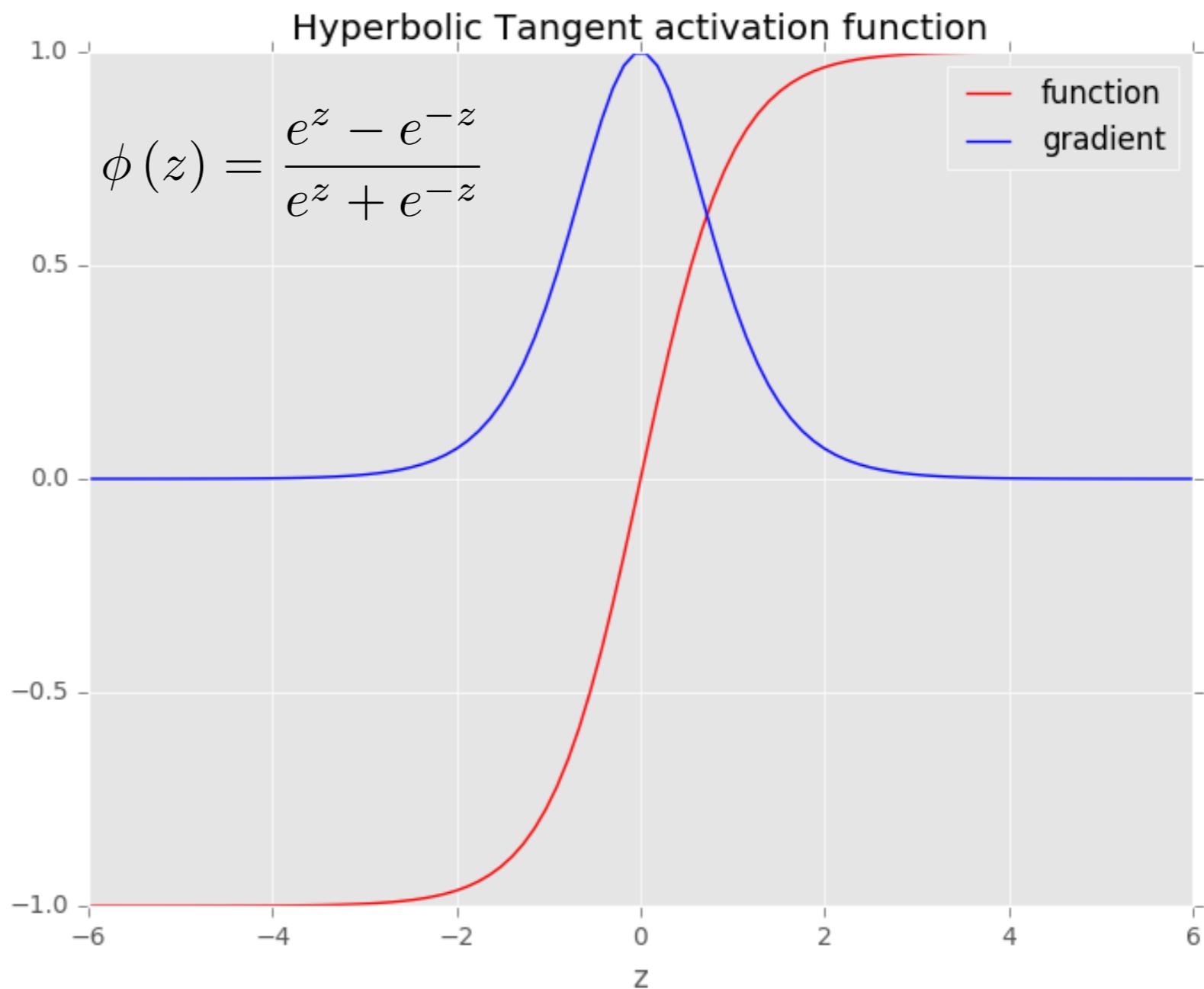
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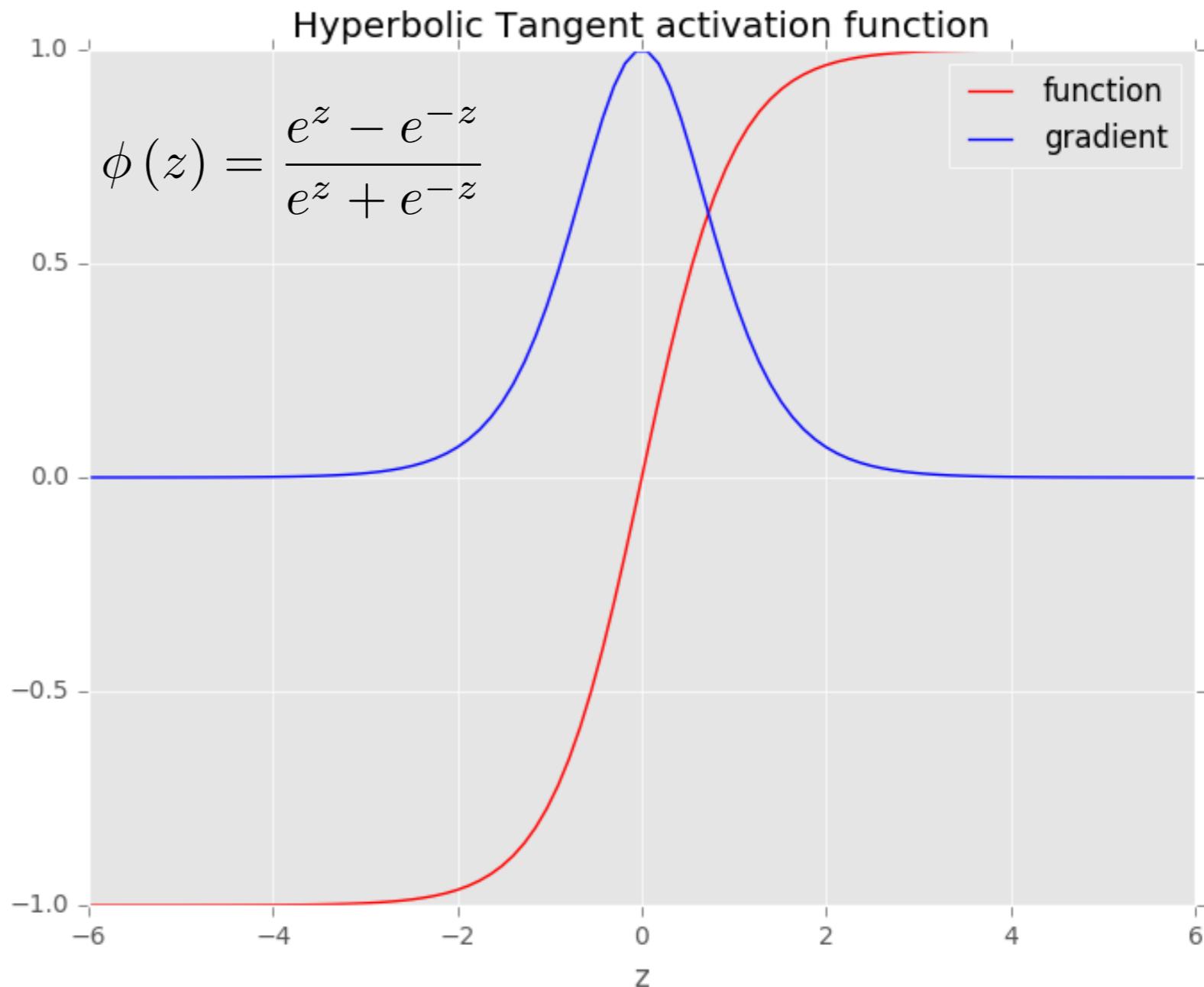
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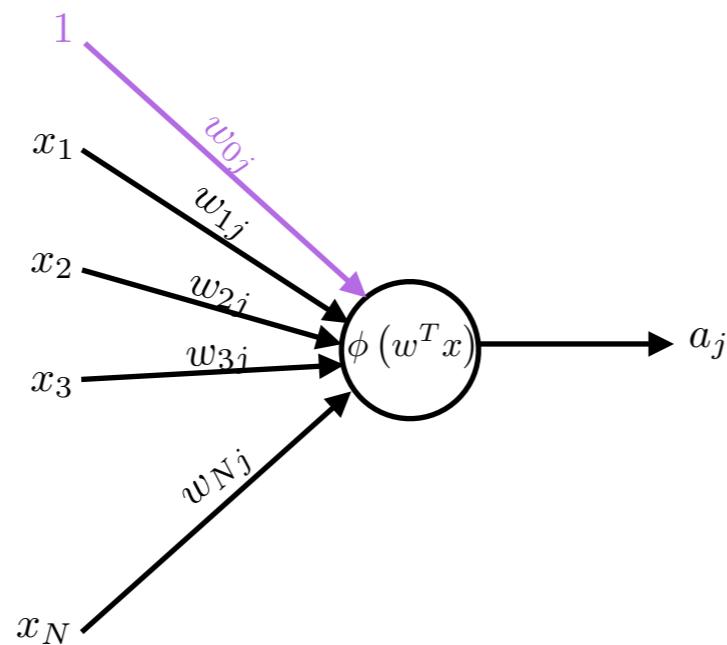
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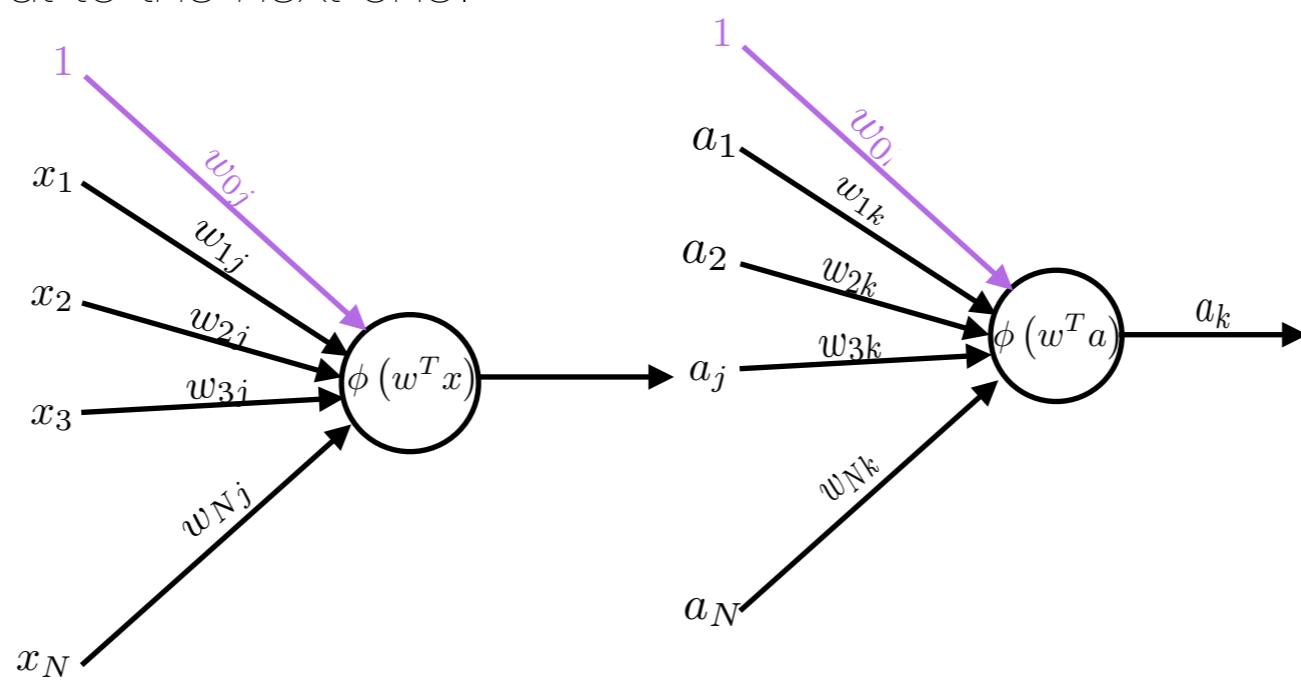
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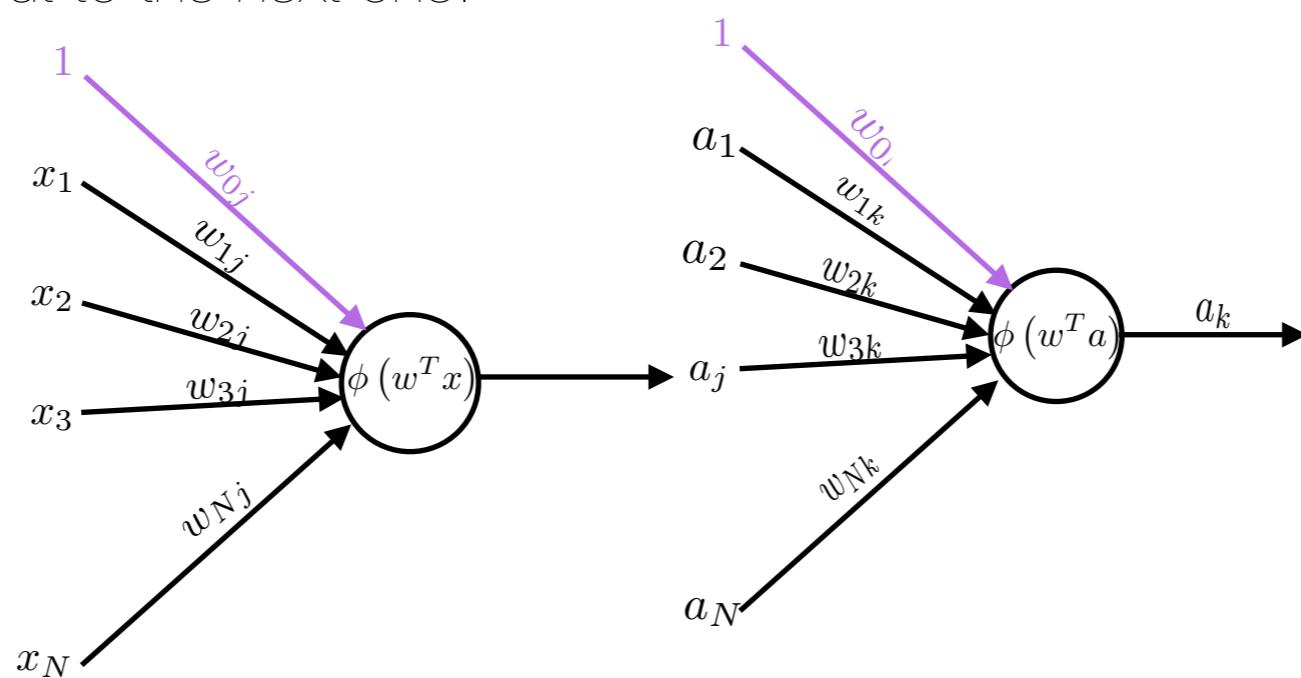
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- But how can we propagate back the errors and update the weights?

Backward Propagation of Errors (BackProp)

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- BackProp operates in two phases:
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 - Update the weights
- The error at the output is a **weighted average difference** between predicted output and the observed one.
- For inner layers there is no “real output”!

Loss Functions

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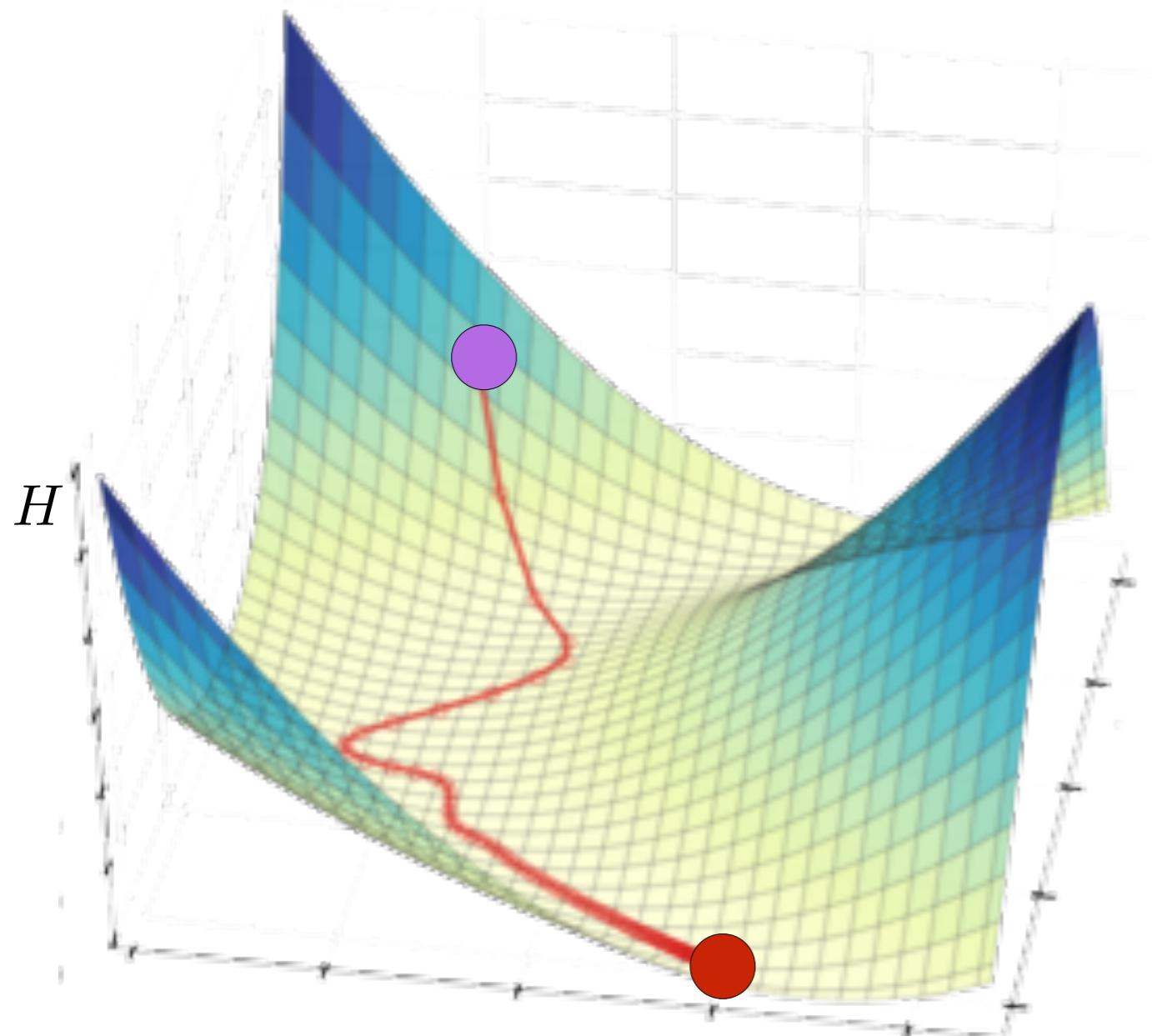
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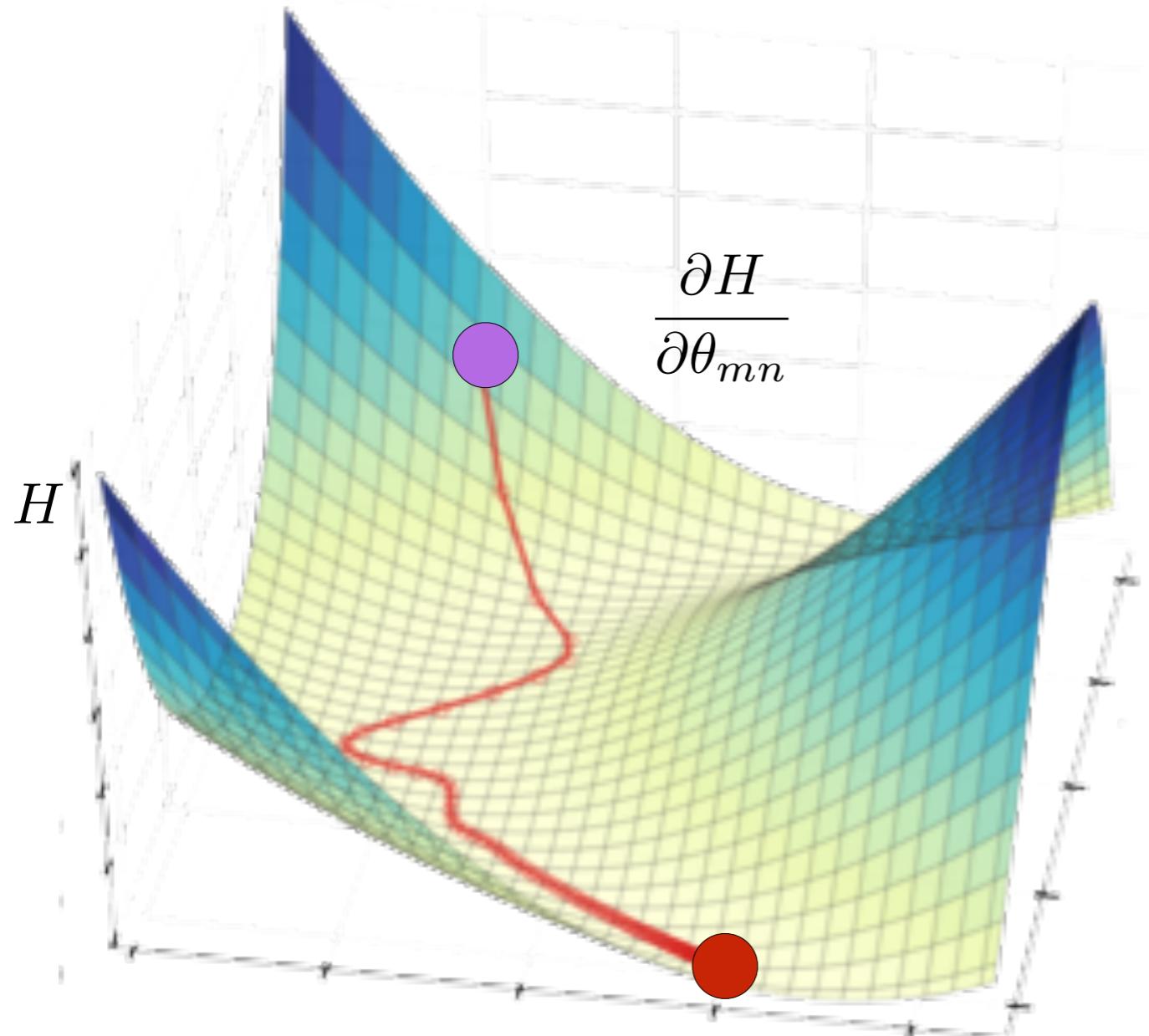
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The **Cross Entropy** is complementary to **sigmoid** activation in the output layer and improves its stability.

Gradient Descent

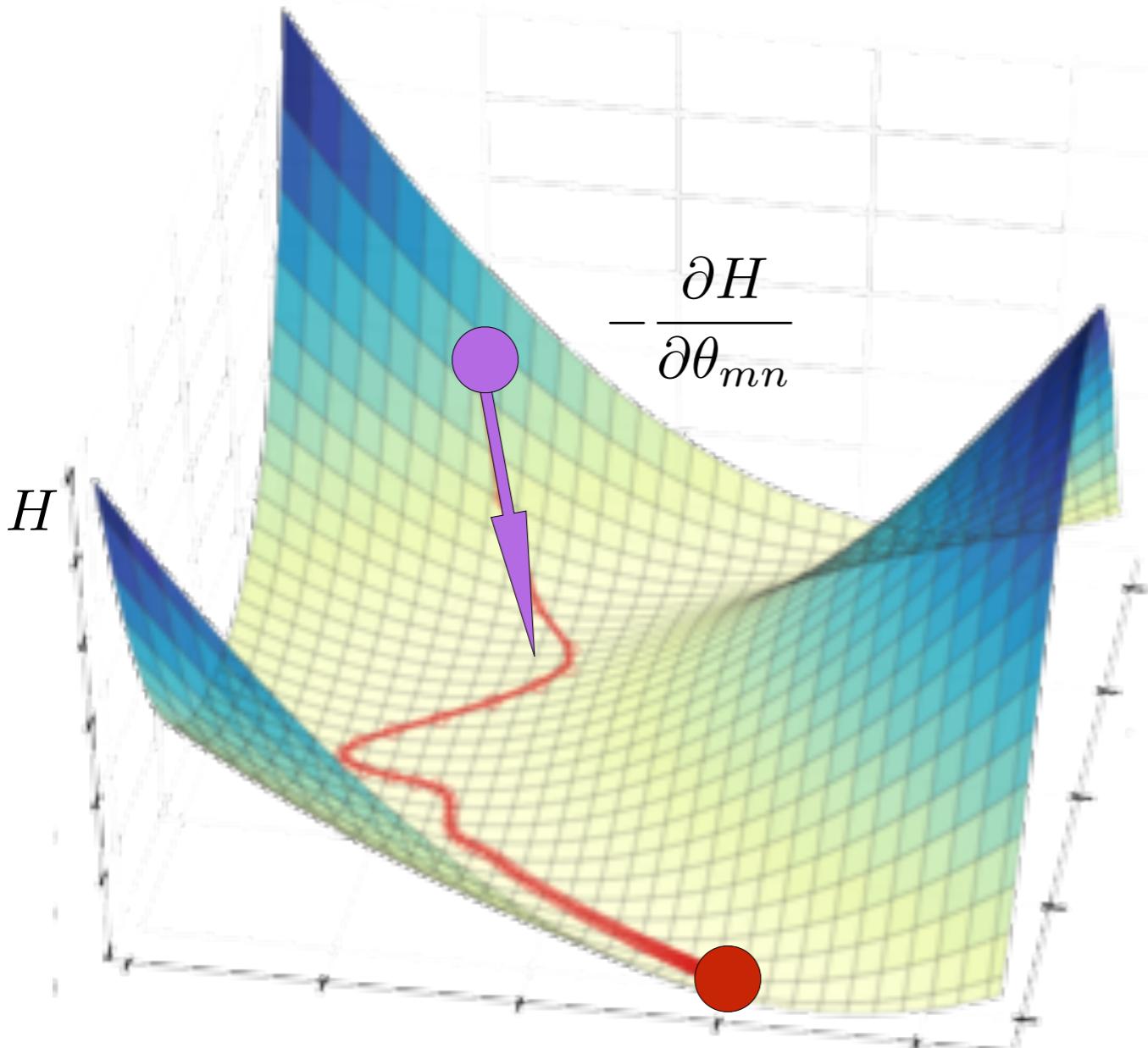


Gradient Descent



- Find the gradient for each training batch

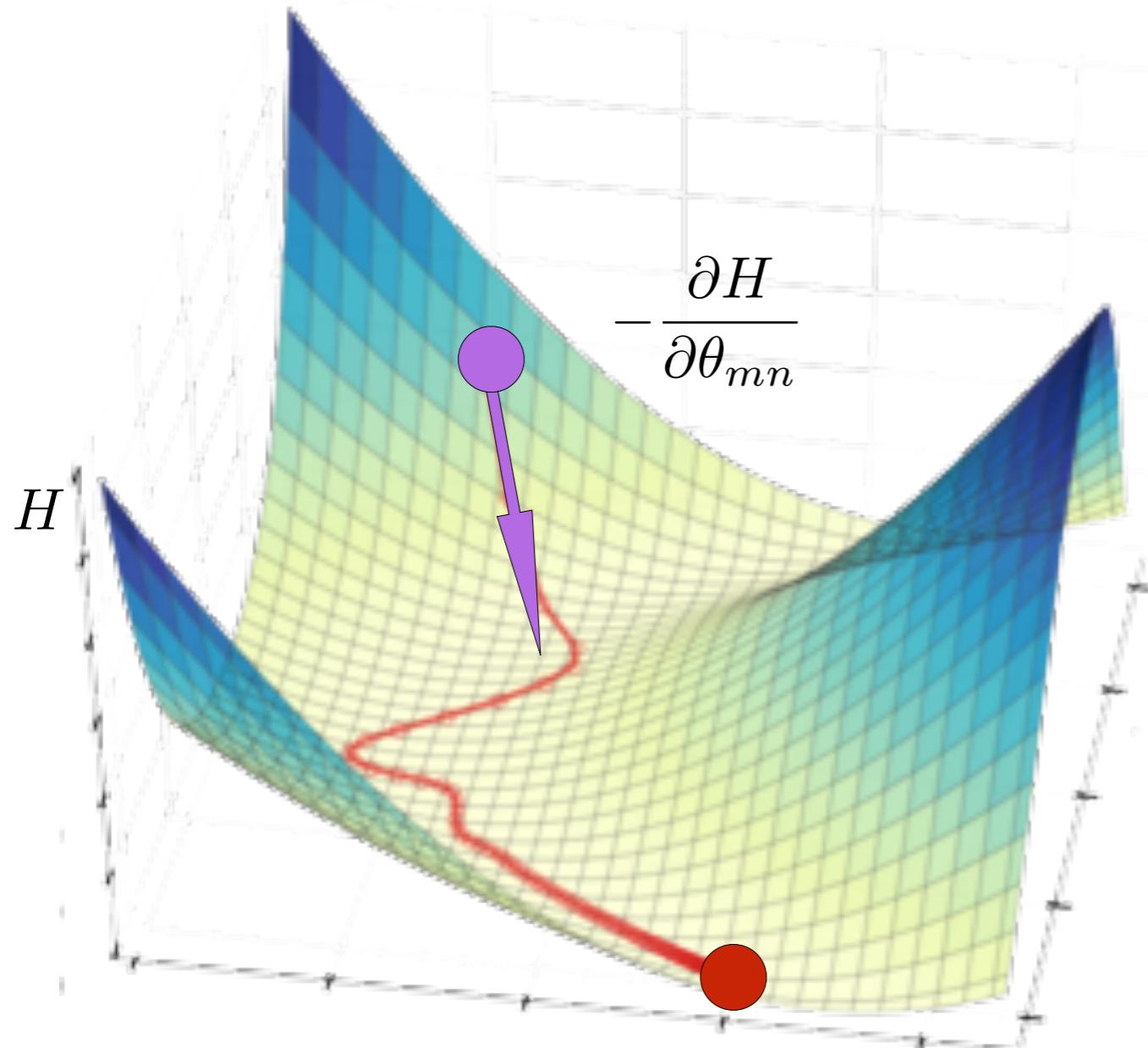
Gradient Descent



- Find the gradient for each training batch
- Take a step **downhill** along the direction of the gradient

$$\theta_{mn} \leftarrow \theta_{mn} - \alpha \frac{\partial H}{\partial \theta_{mn}}$$

Gradient Descent



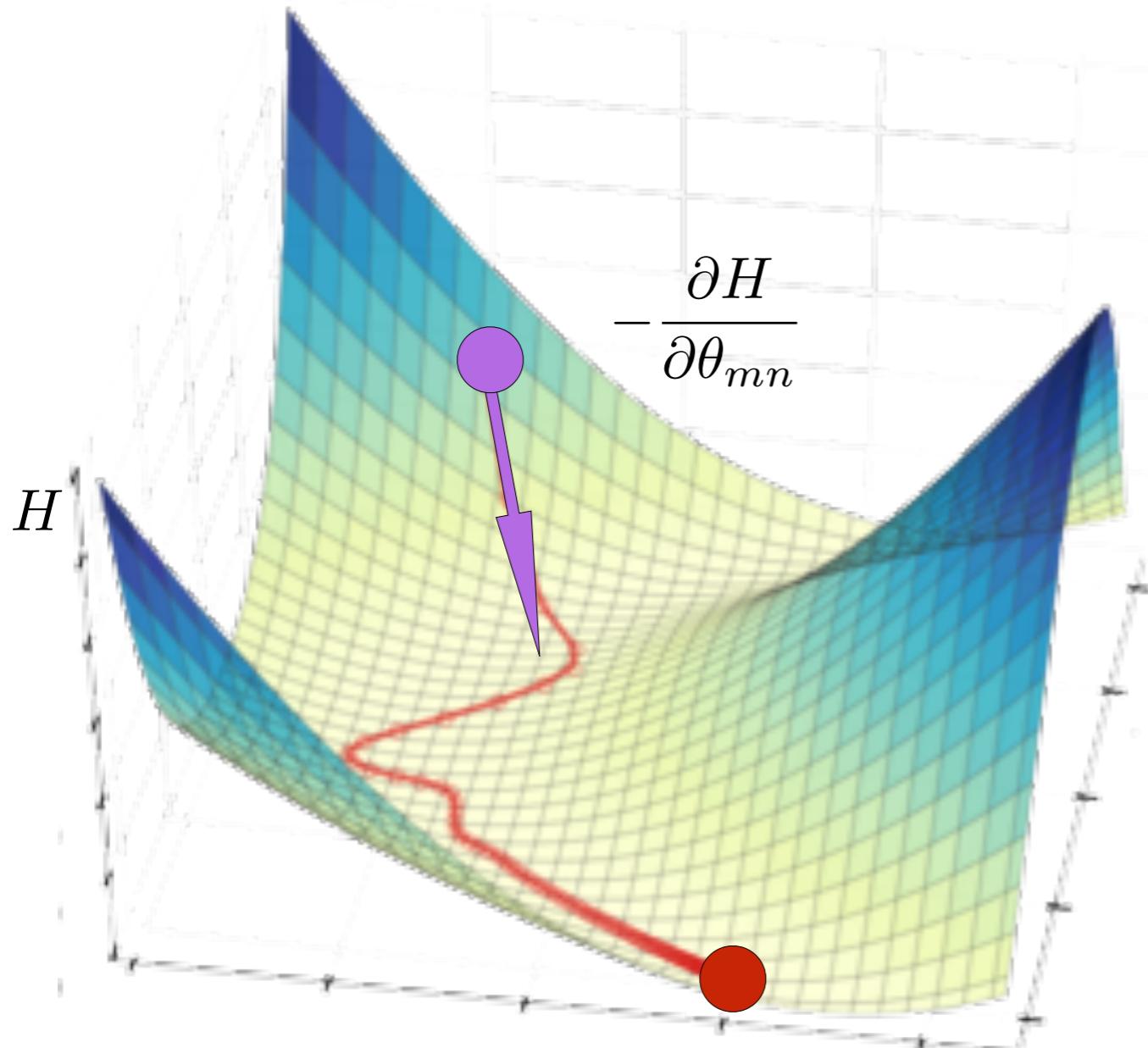
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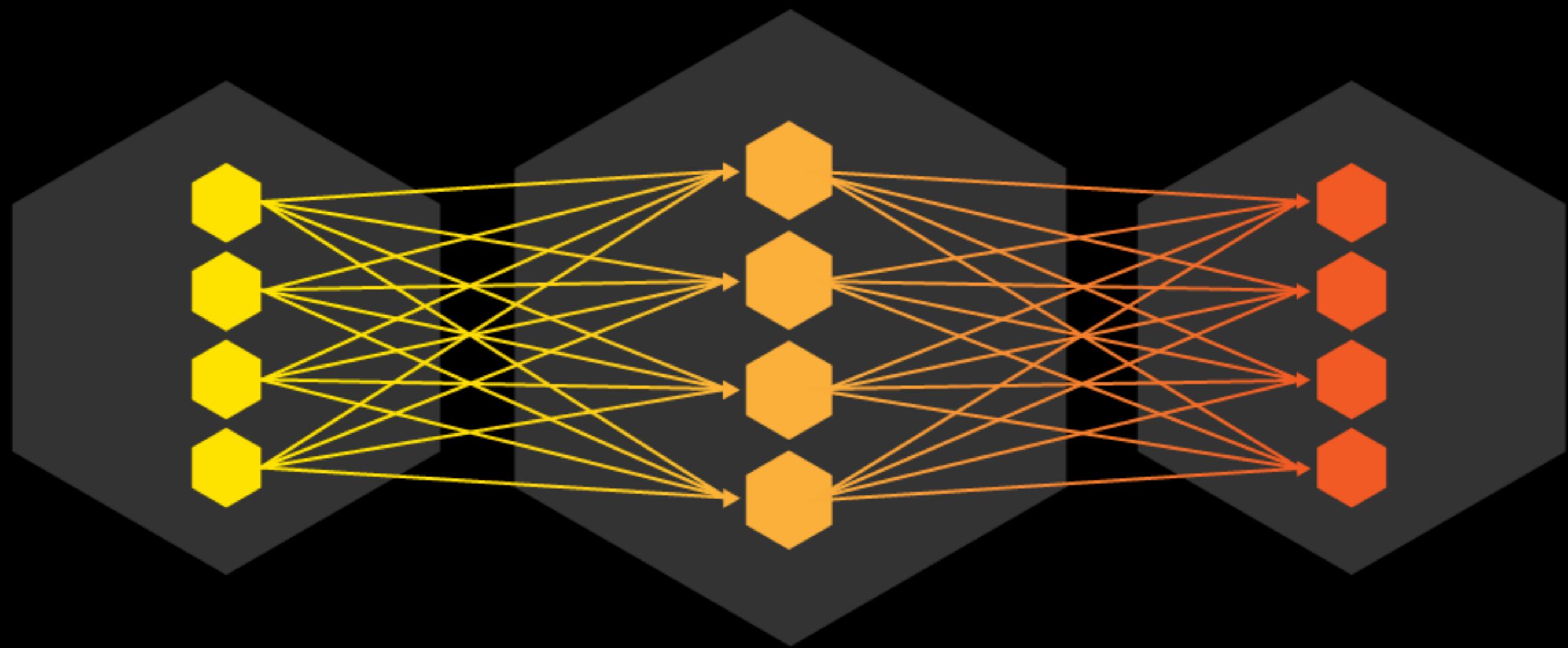
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 - Repeat until "convergence".



INPUT TERMS

FEATURES
PREDICTIONS
ATTRIBUTES
PREDICTABLE VARIABLES

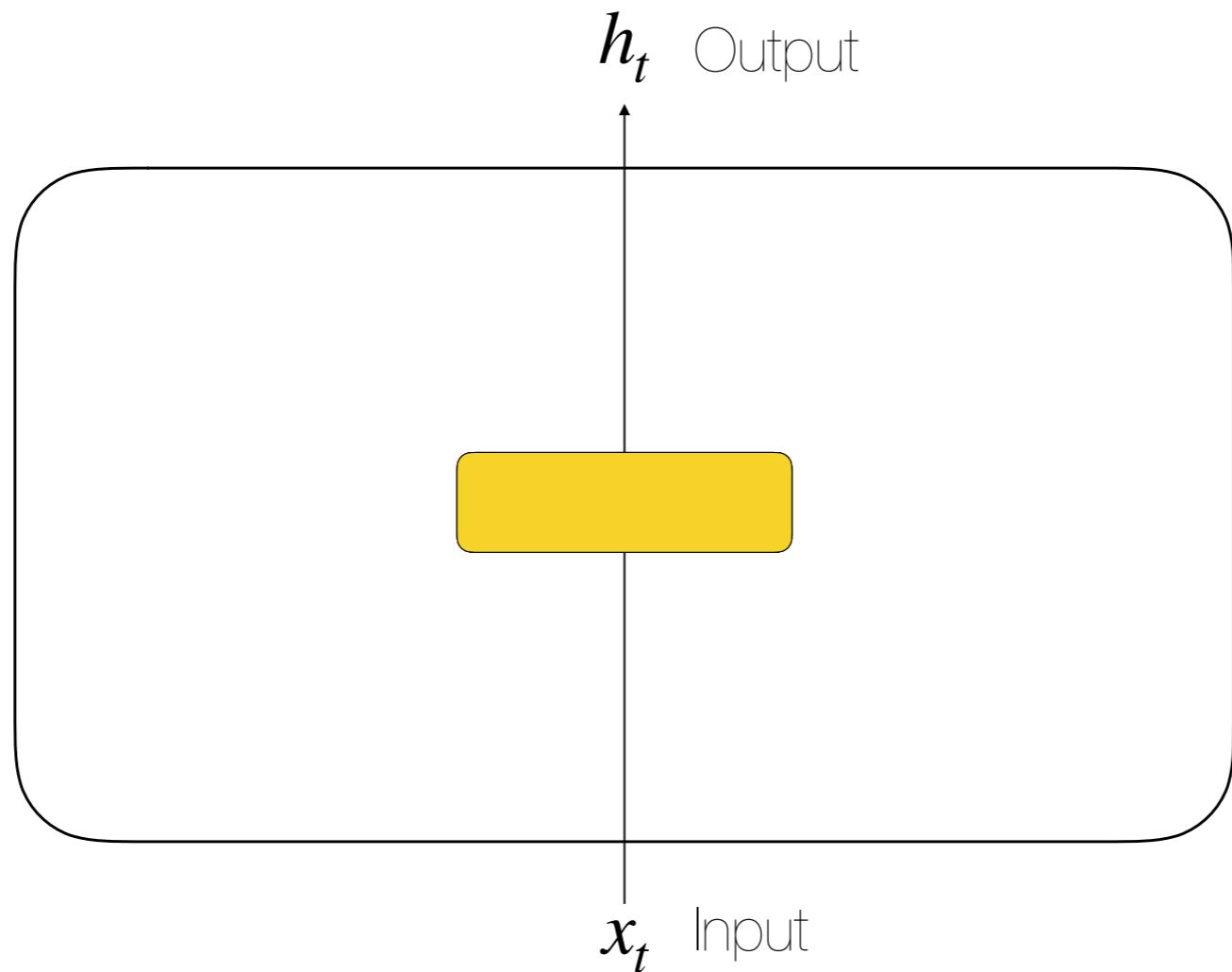
MACHINE

ALGORITHMS
TECHNIQUES
MODELS

OUTPUT TERMS

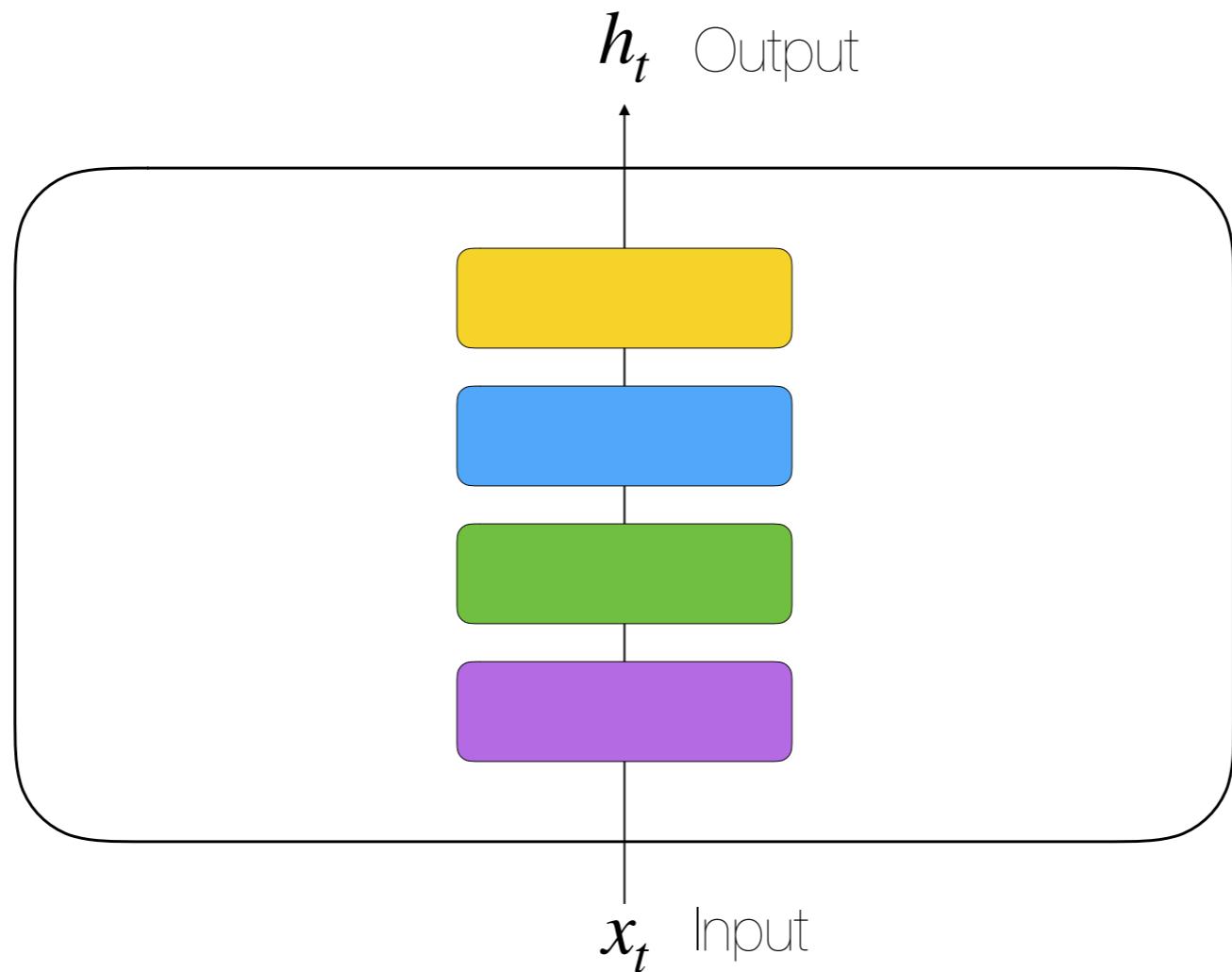
CLASSES
RESPONSES
TARGETS
DEPENDANT VARIABLES

Feed Forward Networks



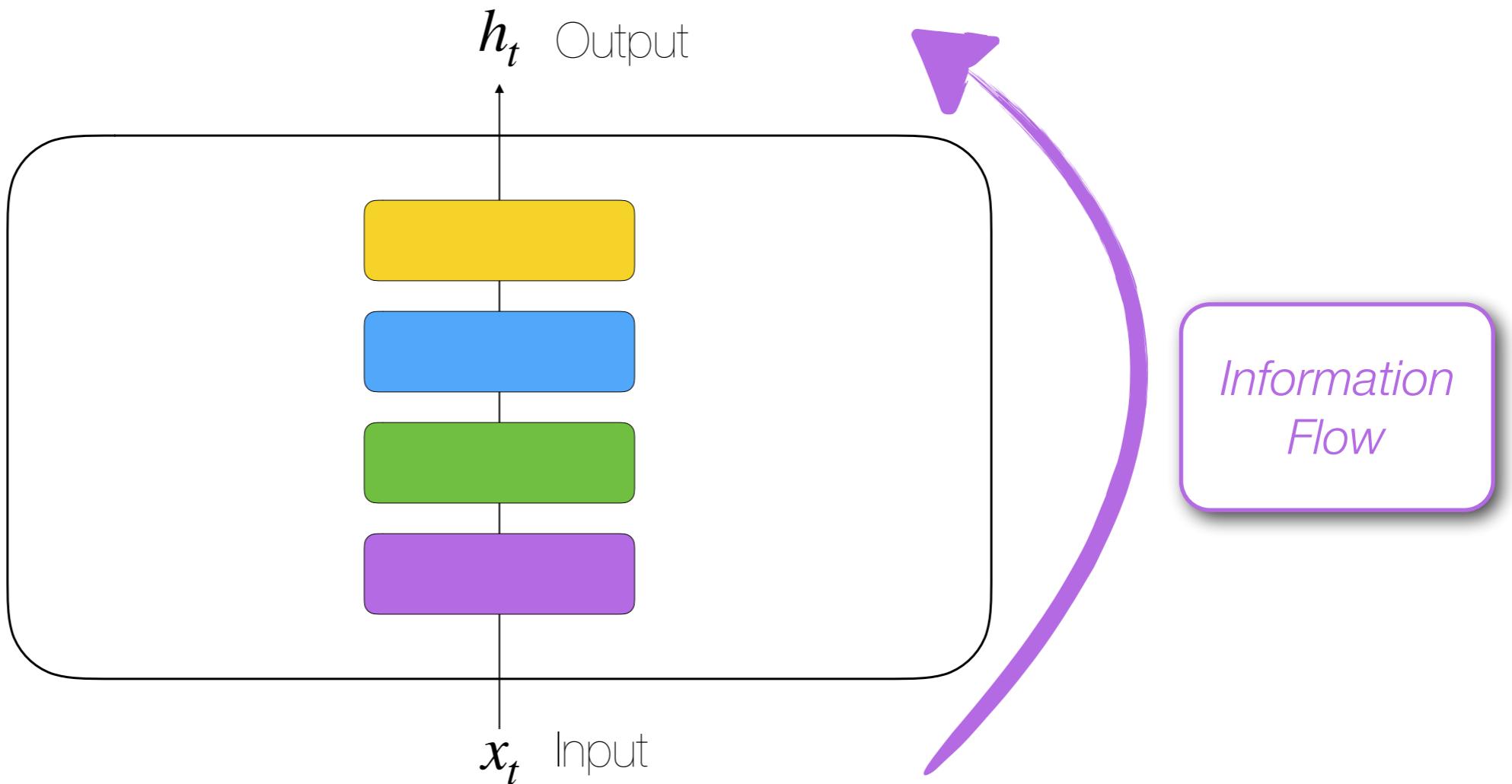
$$h_t = f(x_t)$$

Feed Forward Networks



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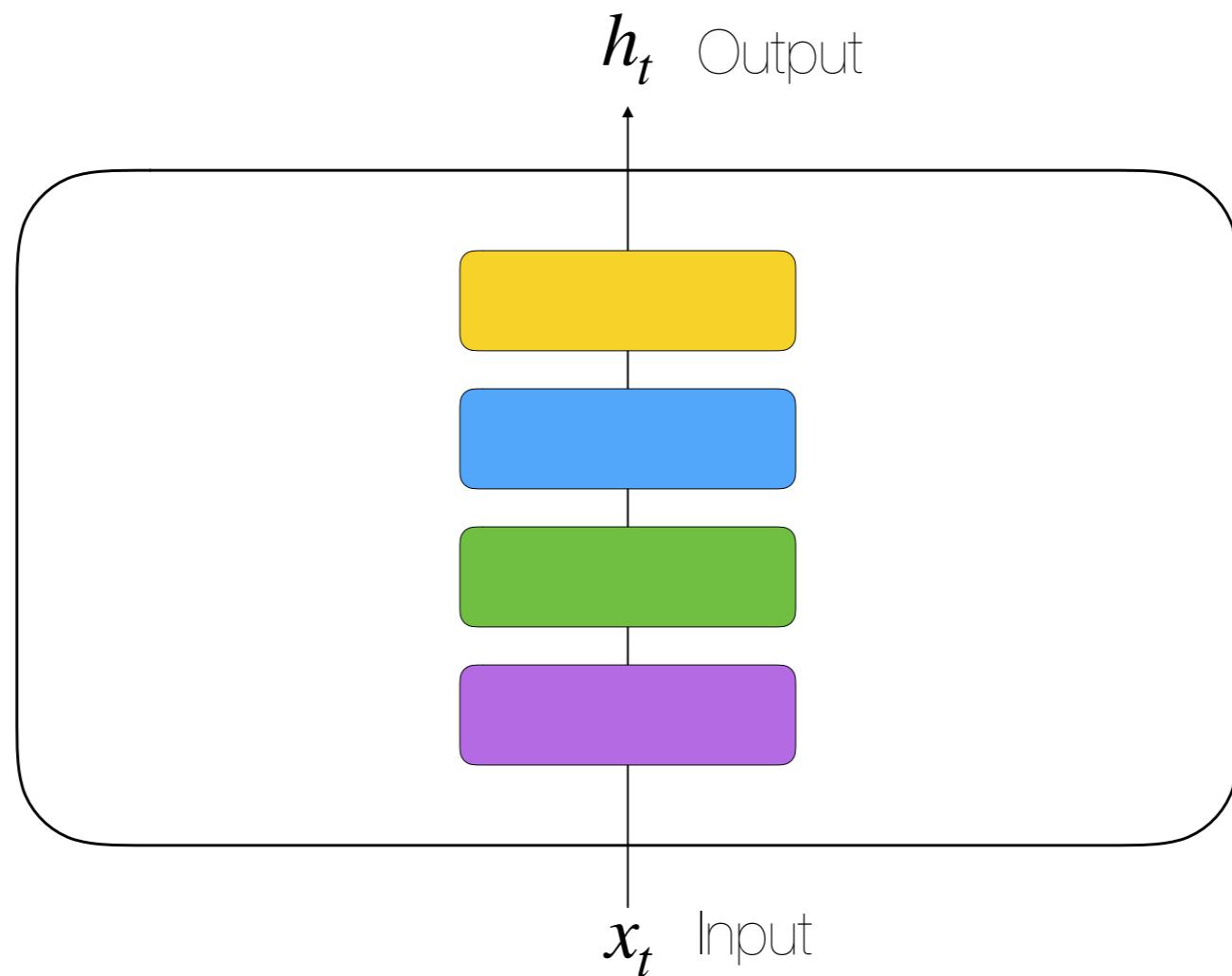
Feed Forward Networks



$$h_t = f(x_t)$$

Information
Flow

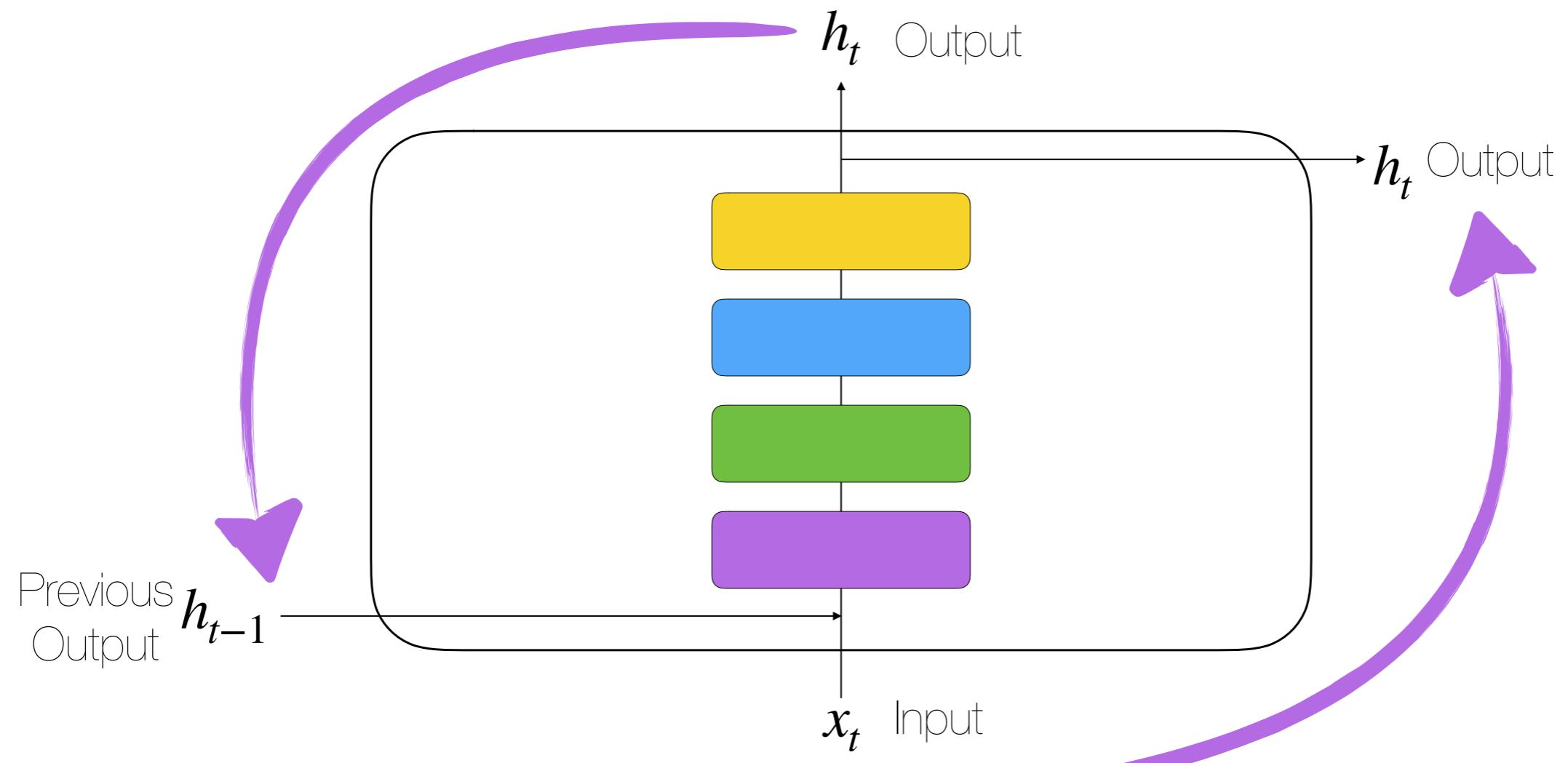
Recurrent Neural Network (RNN)



$$h_t = f(x_t)$$

Information
Flow

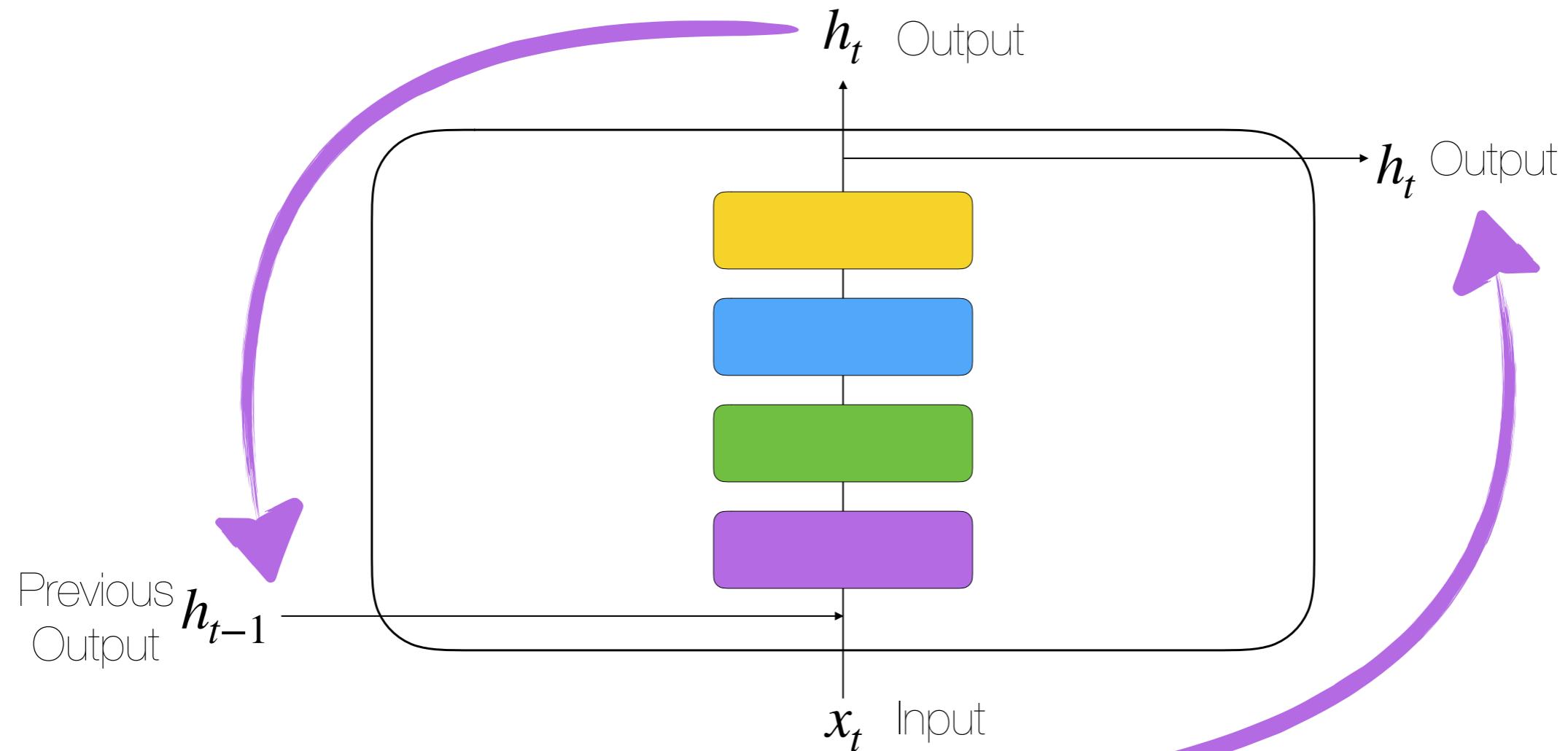
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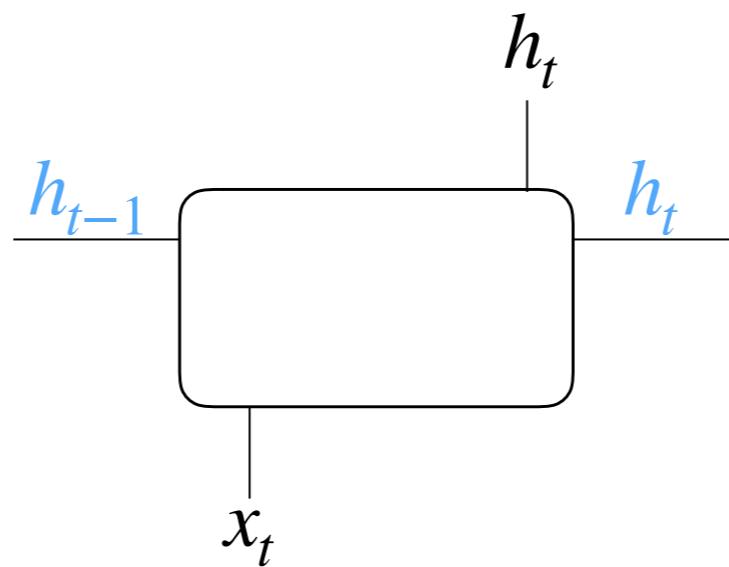
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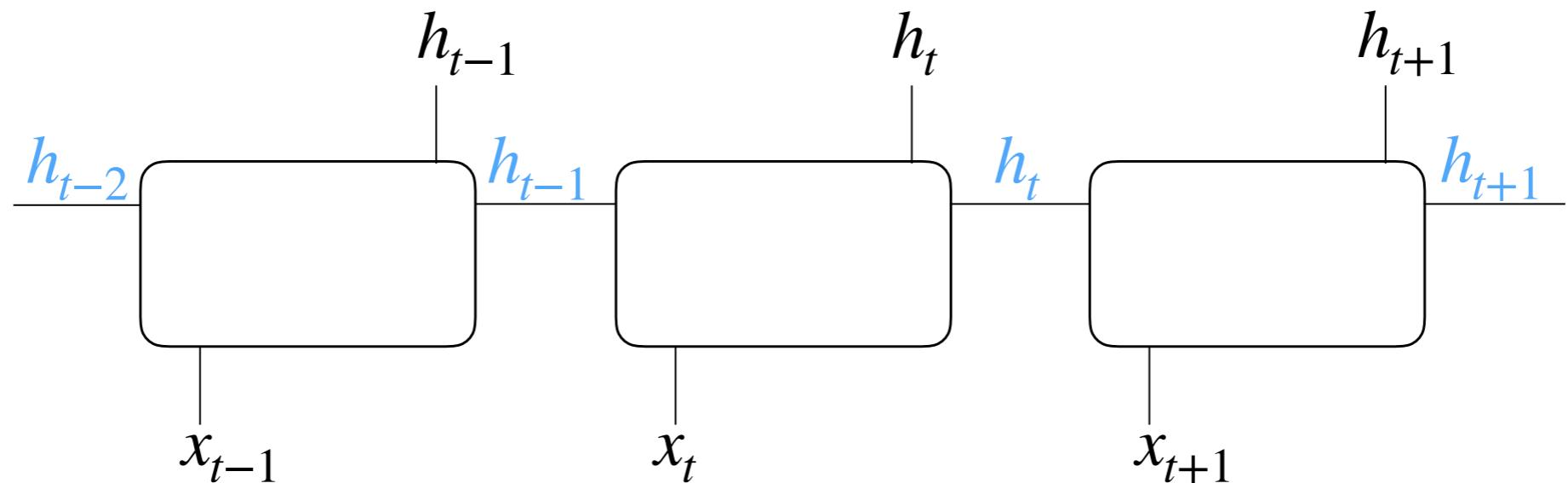
$$h_t = f(x_t, h_{t-1})$$

Recurrent Neural Network (RNN)



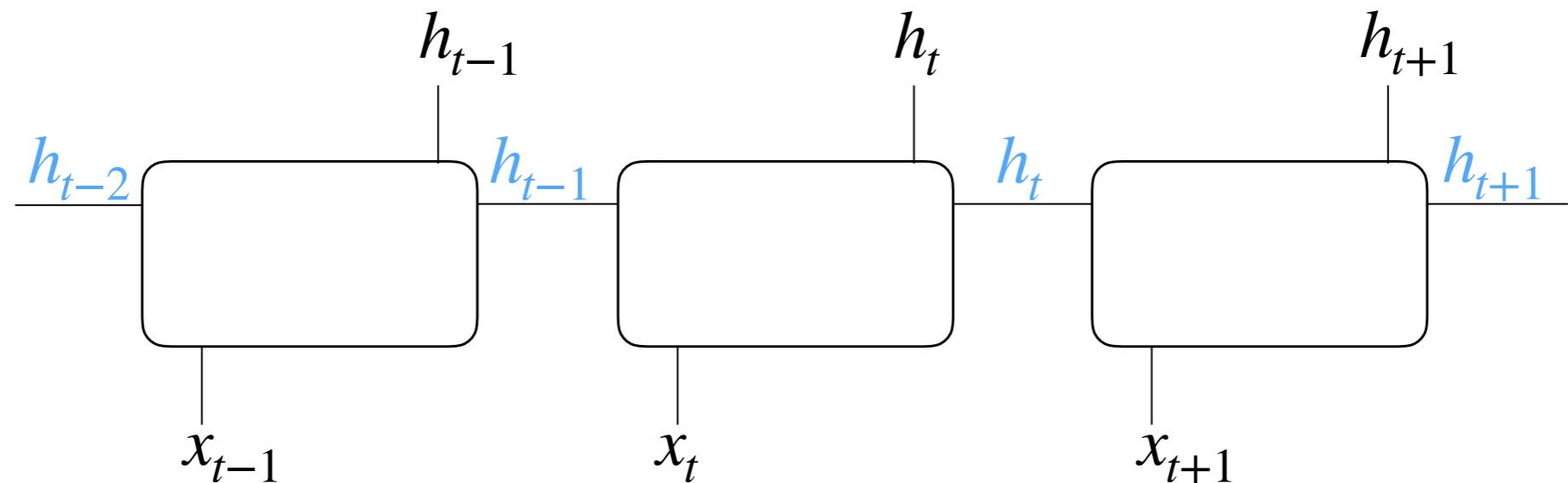
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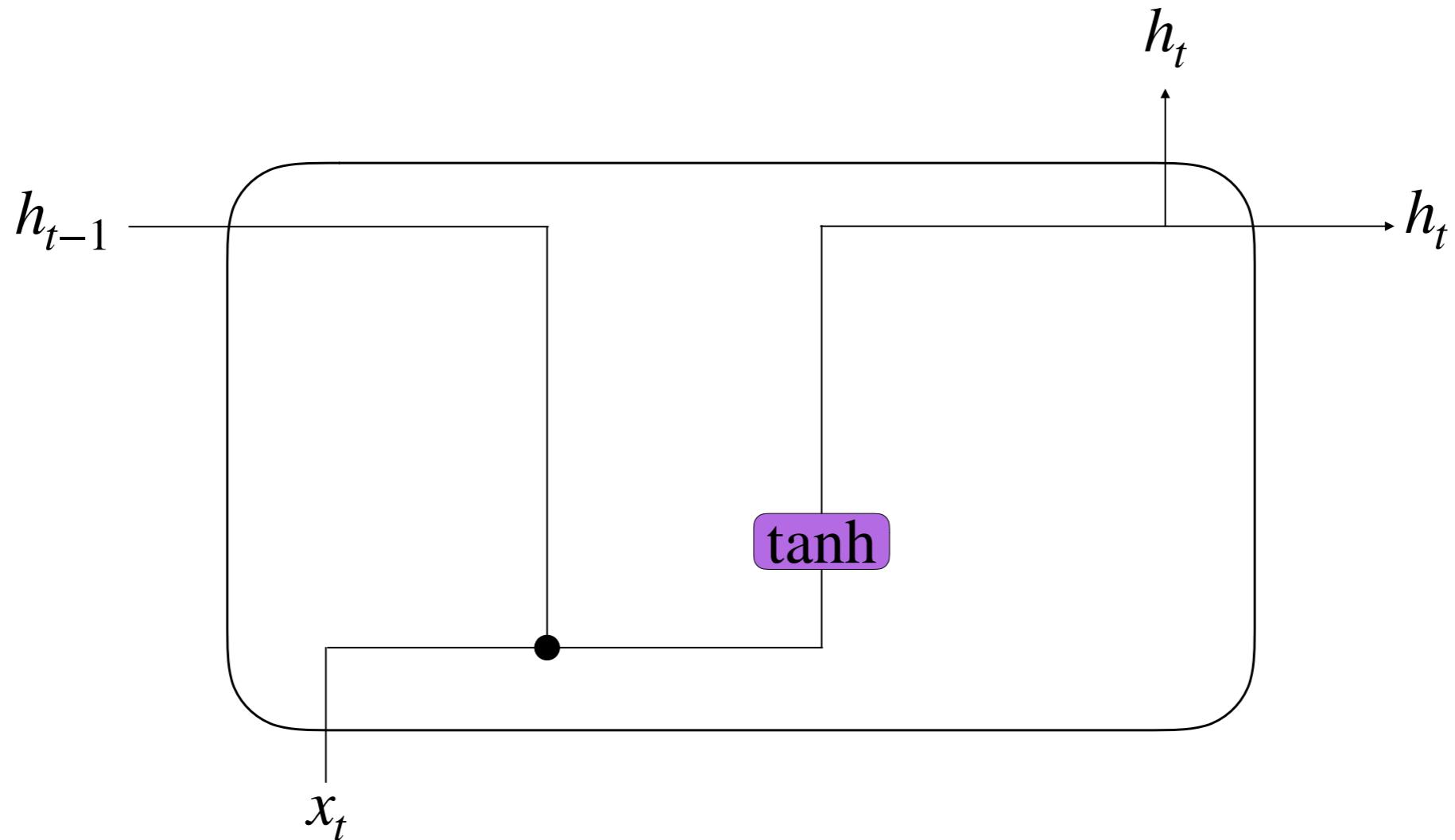


Recurrent Neural Network (RNN)

- Each output depends (implicitly) on all previous **outputs**.
- Input sequences generate output sequences (**seq2seq**)

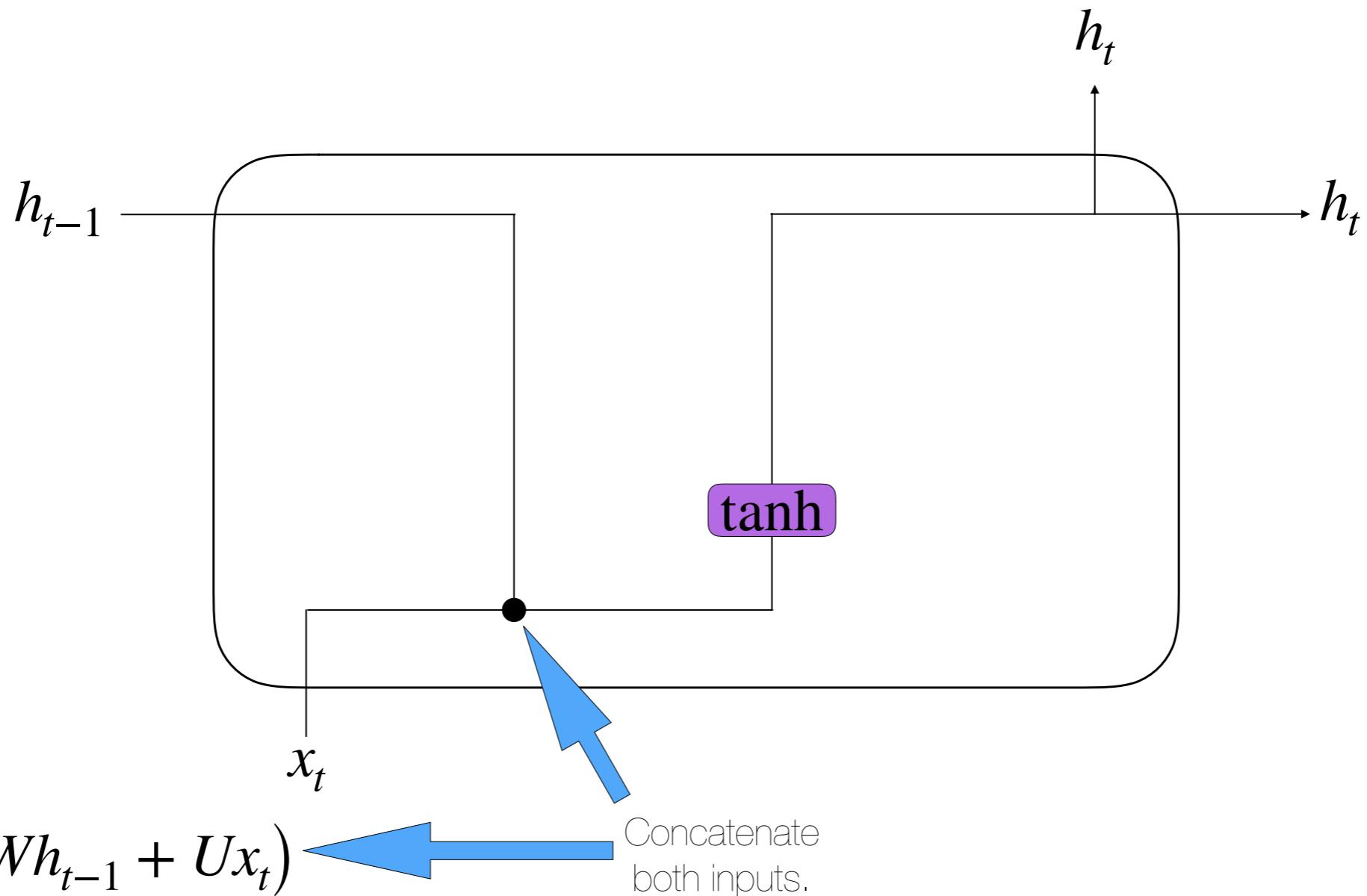


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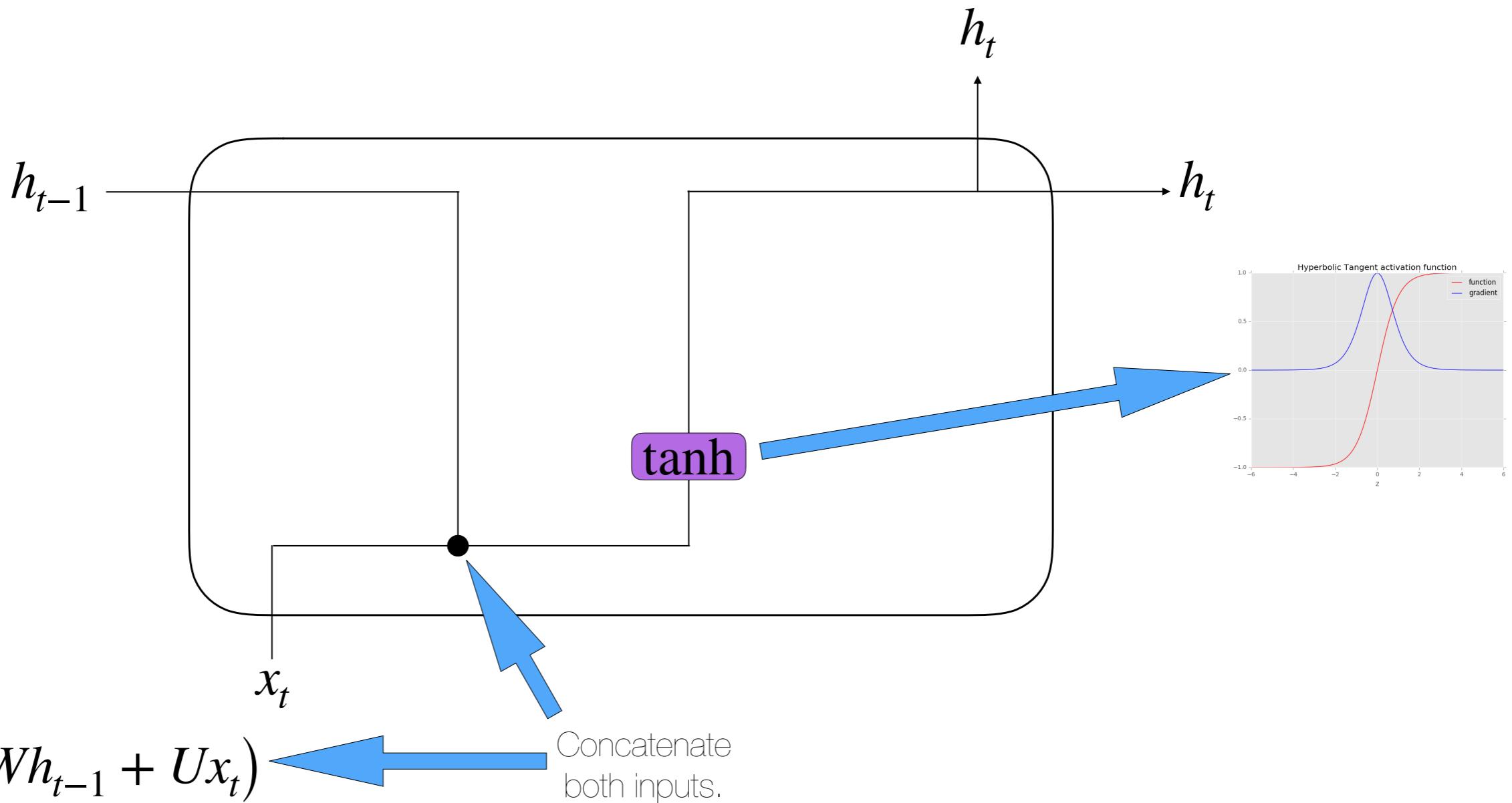


$$h_t = \tanh (Wh_{t-1} + Ux_t)$$

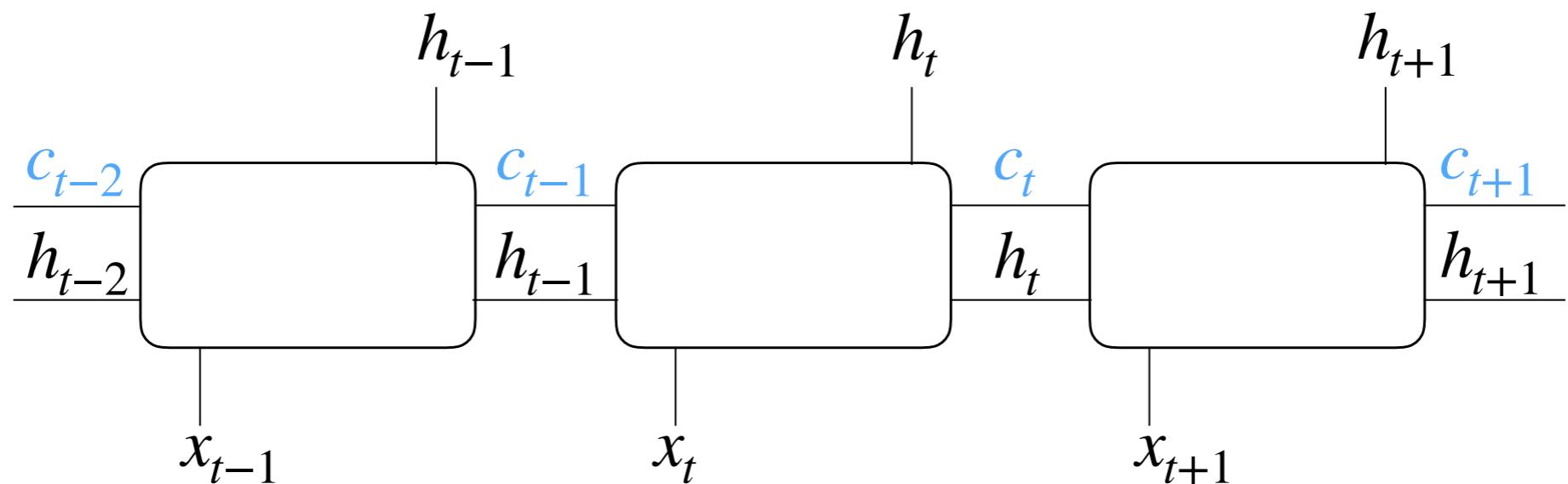
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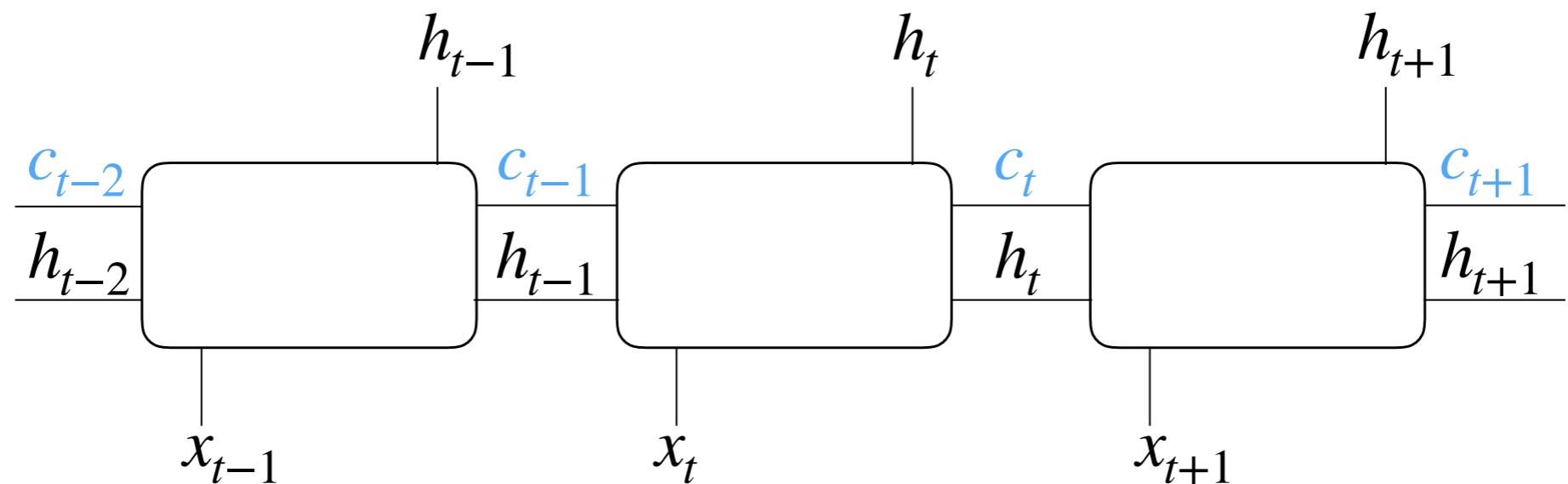


Long-Short Term Memory (LSTM)



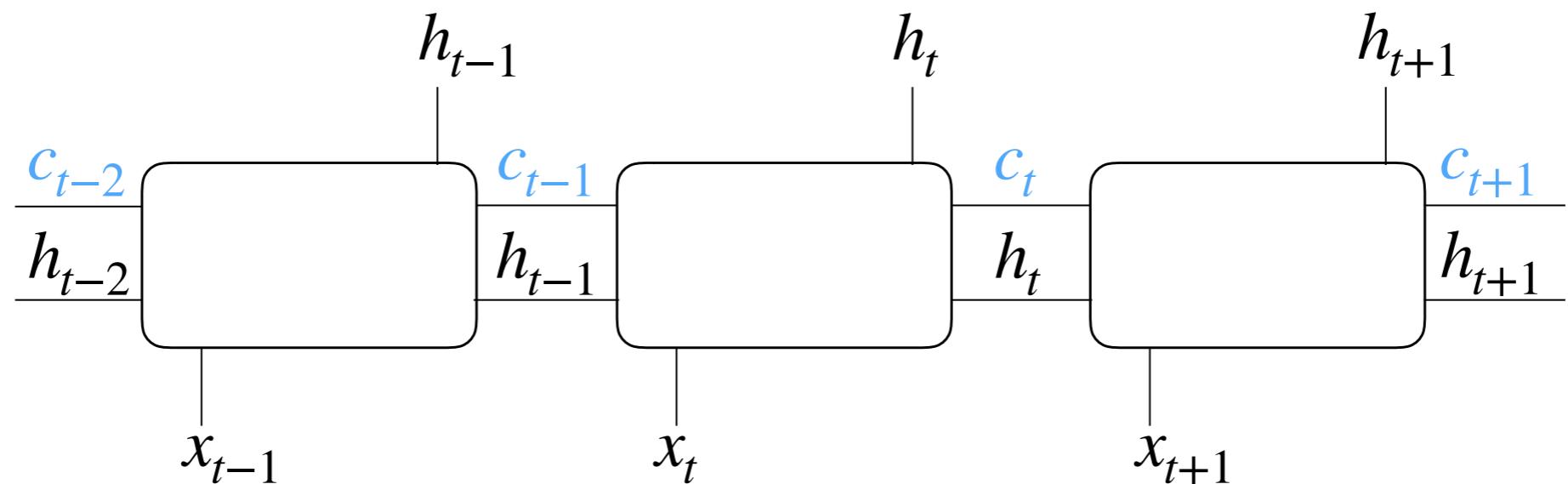
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- What if we want to keep explicit information about previous states (**memory**)?



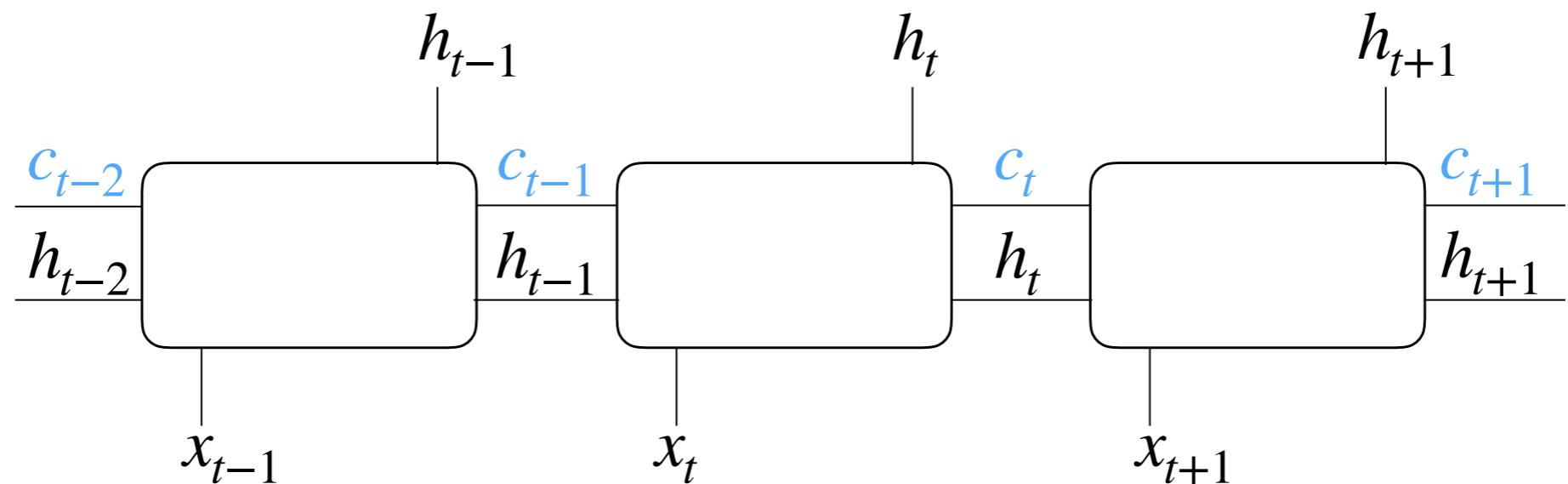
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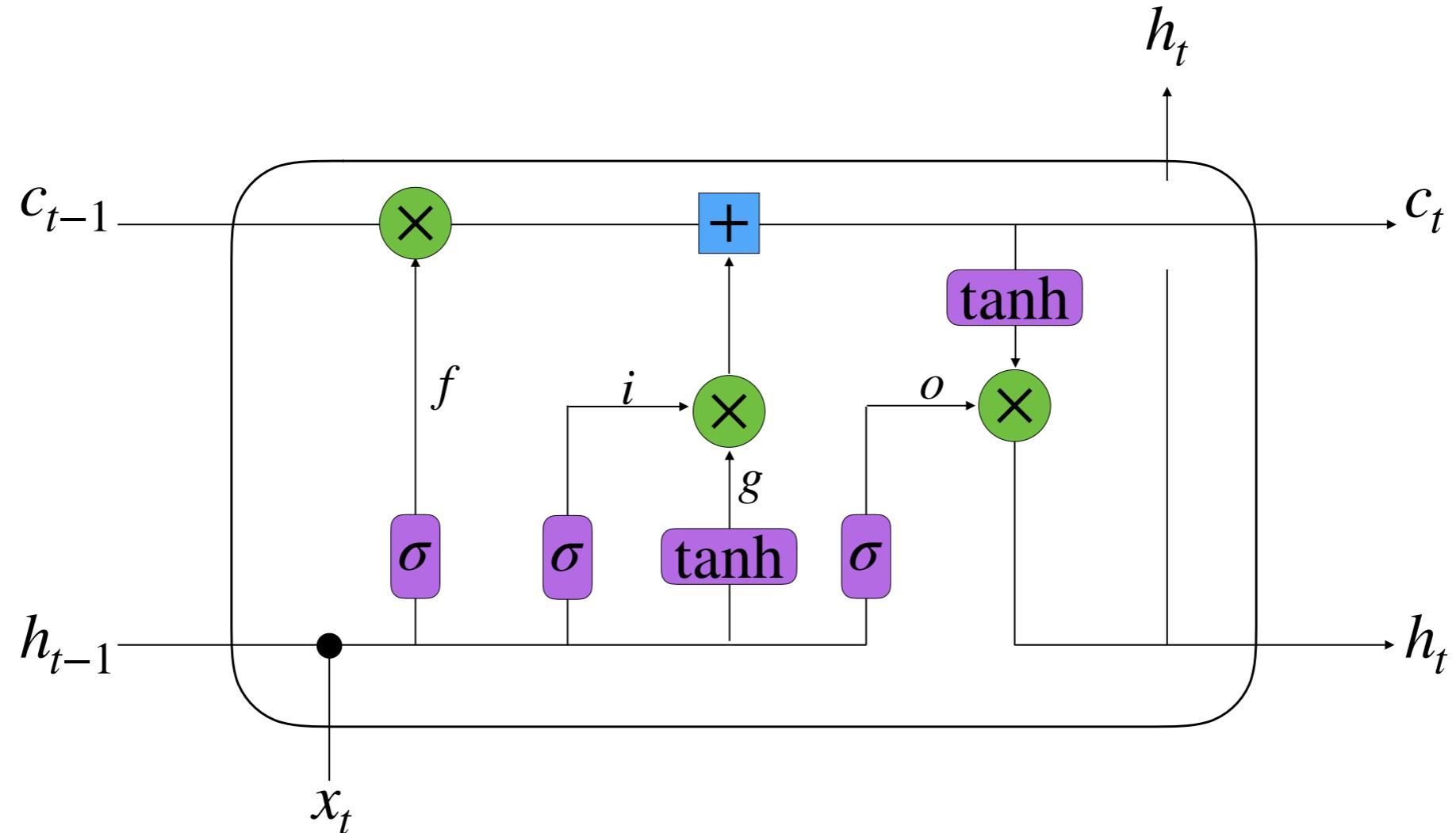
Long-Short Term Memory (LSTM)

- What if we want to keep explicit information about previous states (**memory**)?
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- LSTMs were first introduced in **1997** by Hochreiter and Schmidhuber



Long-Short Term Memory (LSTM)

-  Element wise addition
-  Element wise multiplication
-  1 minus the input



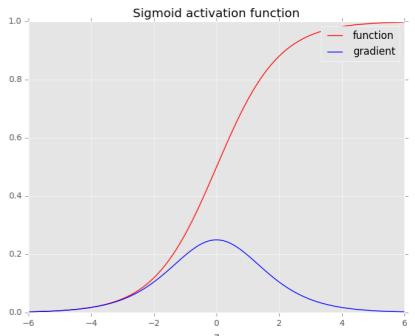
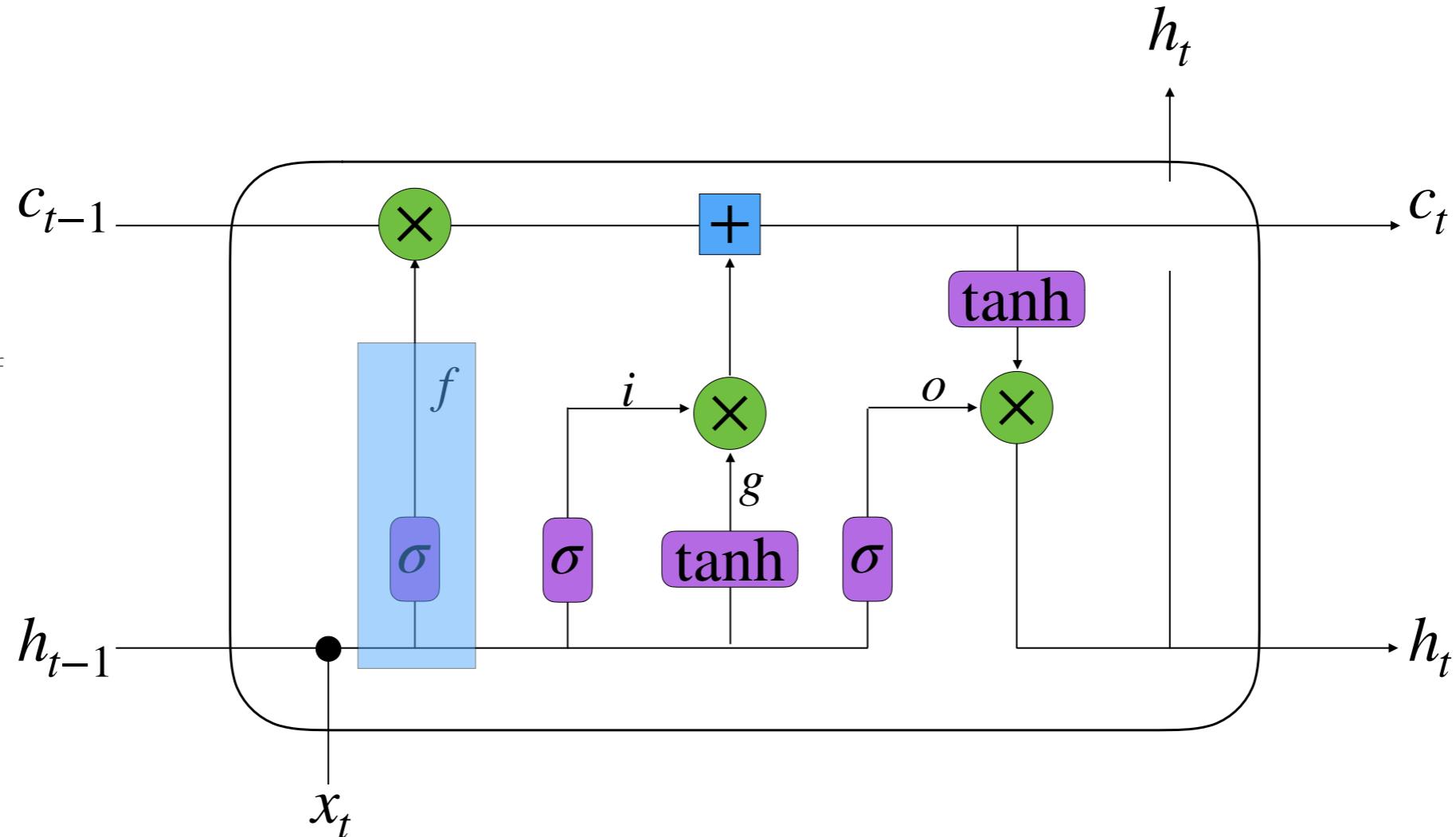
$$f = \sigma(W_f h_{t-1} + U_f x_t) \quad g = \tanh(W_g h_{t-1} + U_g x_t)$$

$$i = \sigma(W_i h_{t-1} + U_i x_t) \quad c_t = (c_{t-1} \otimes f) + (g \otimes i)$$

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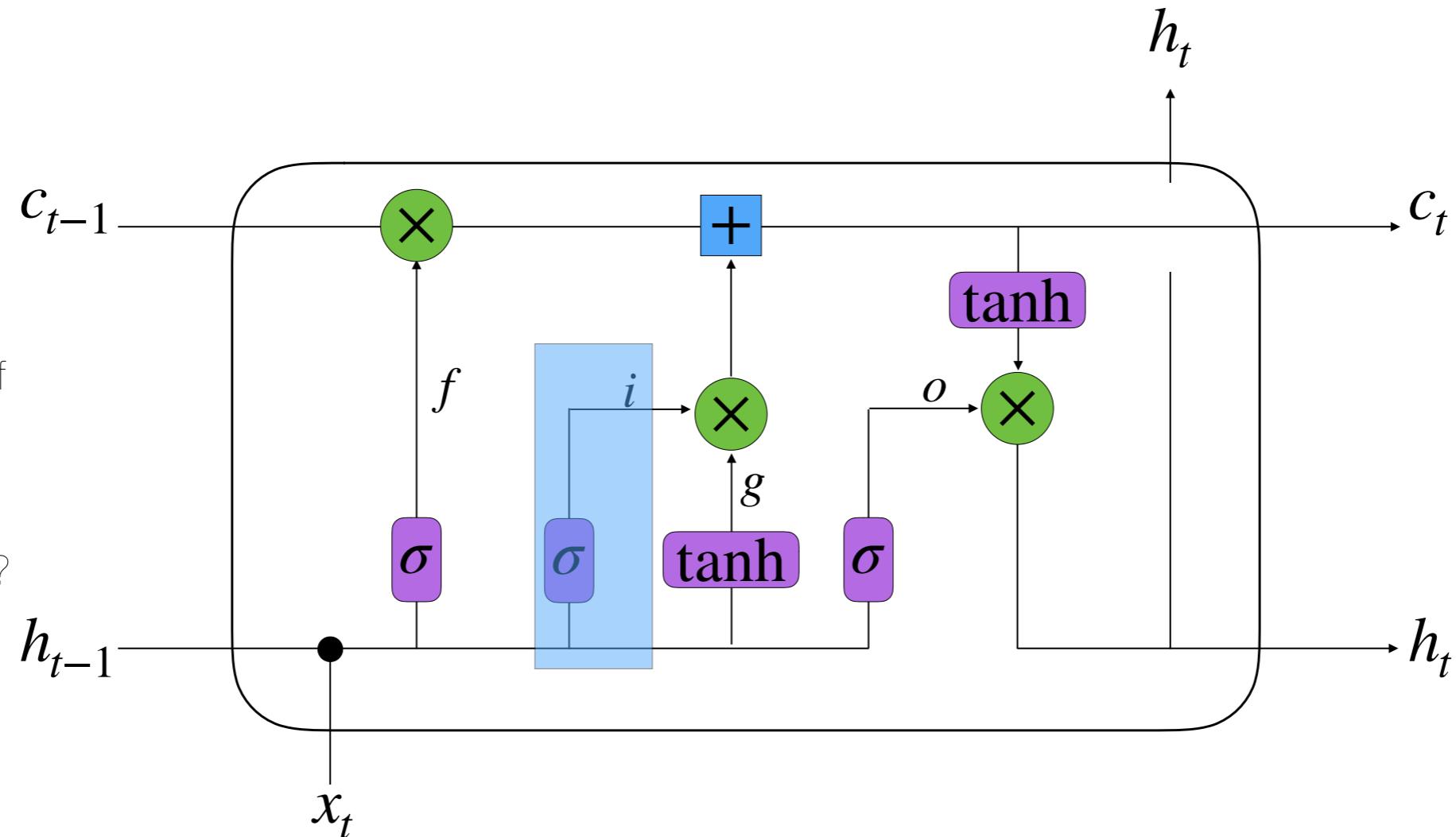
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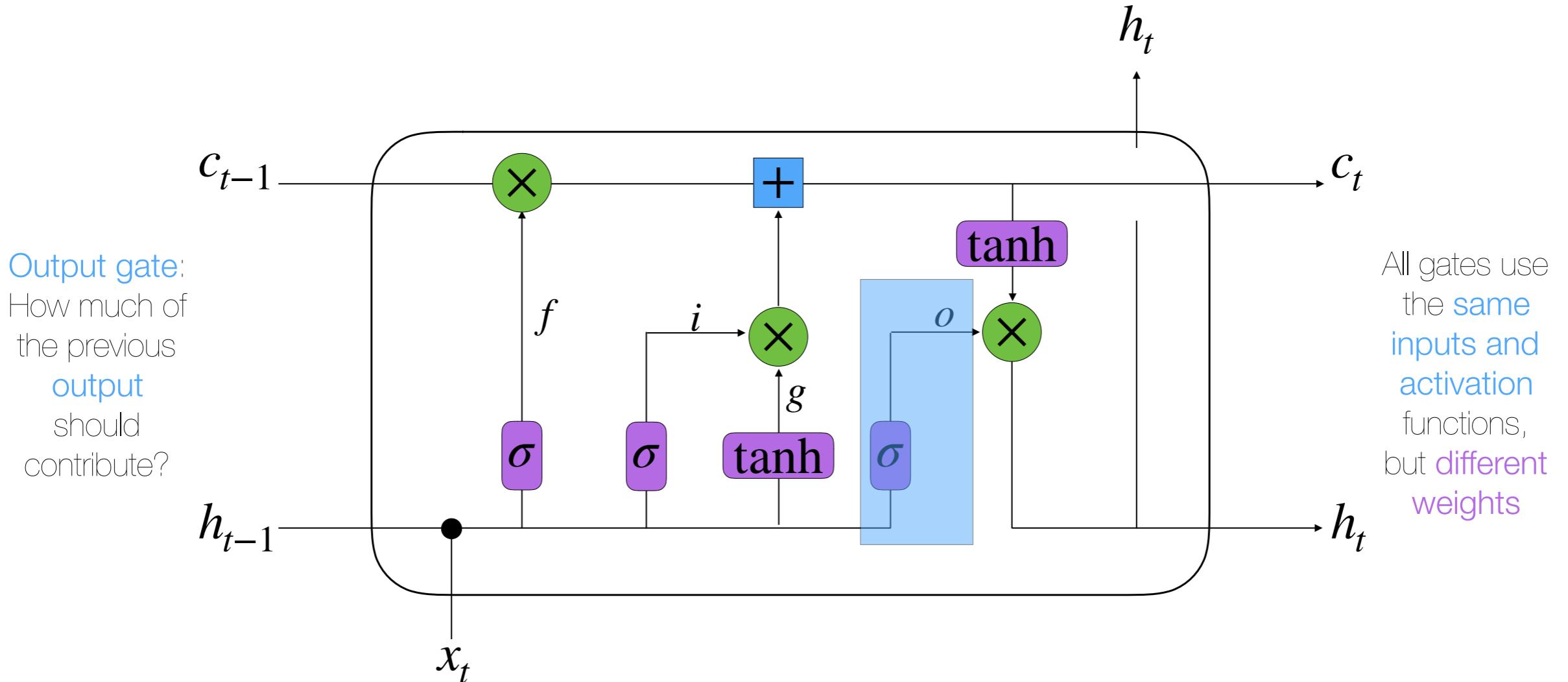
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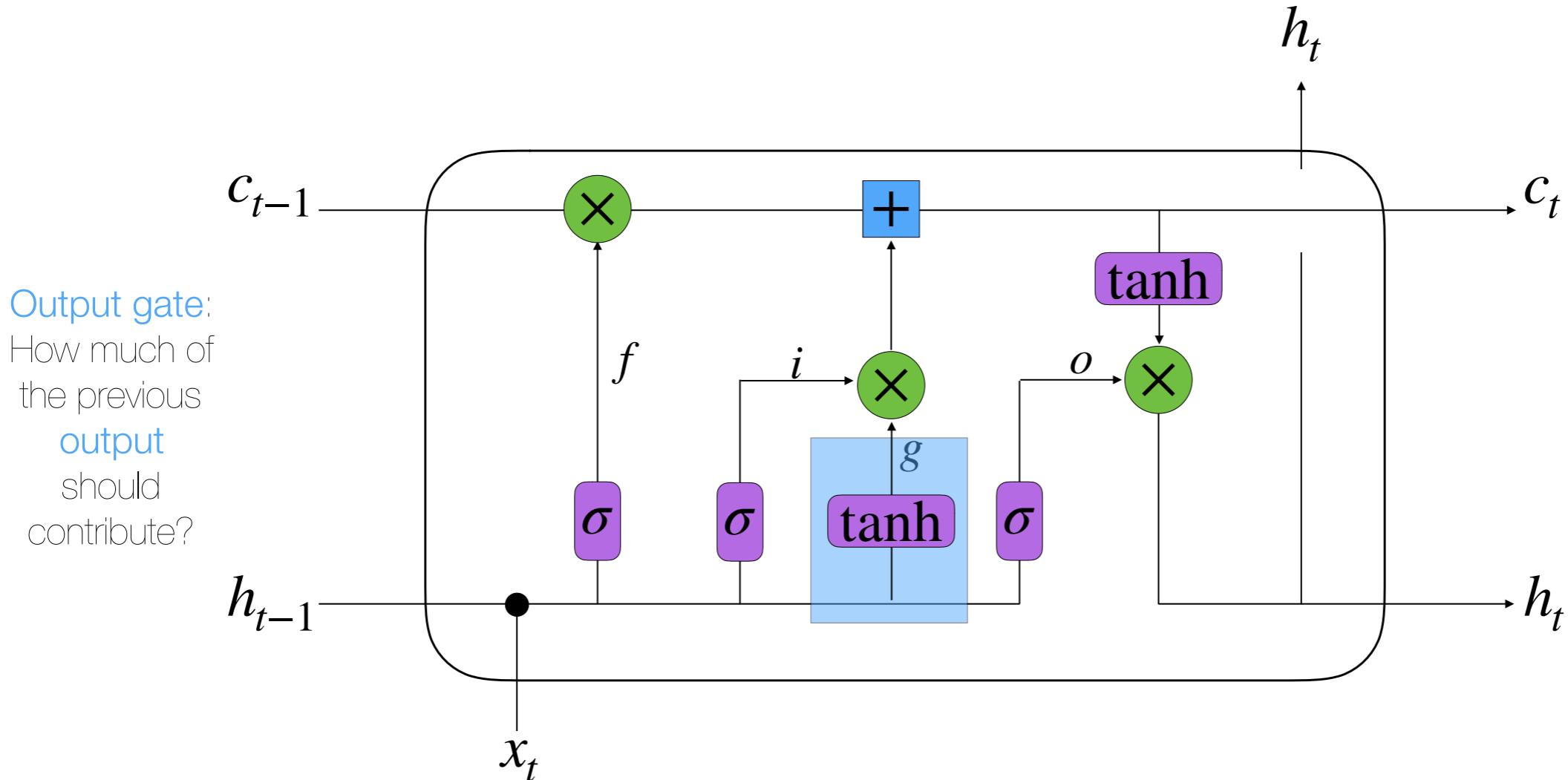
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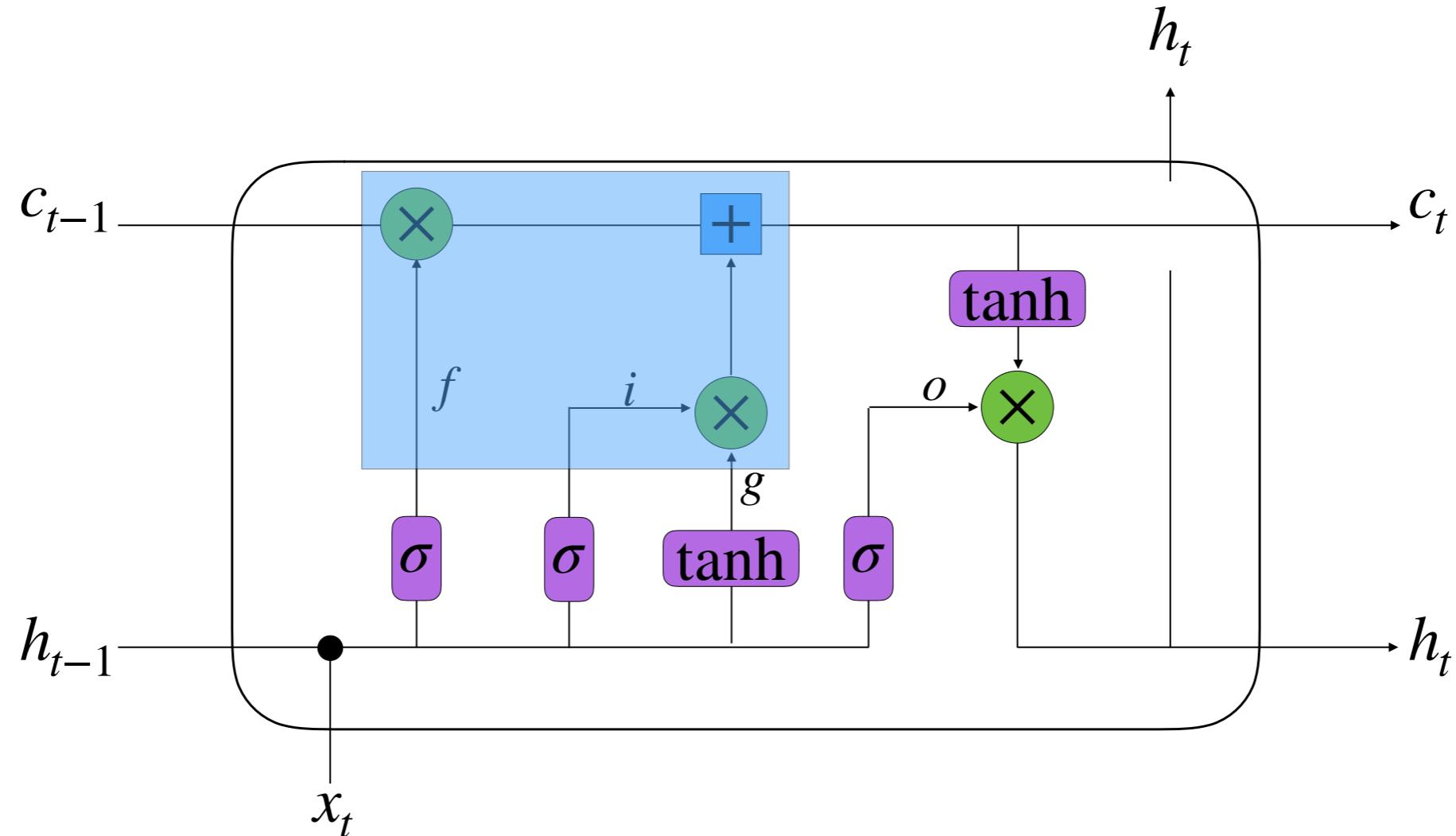
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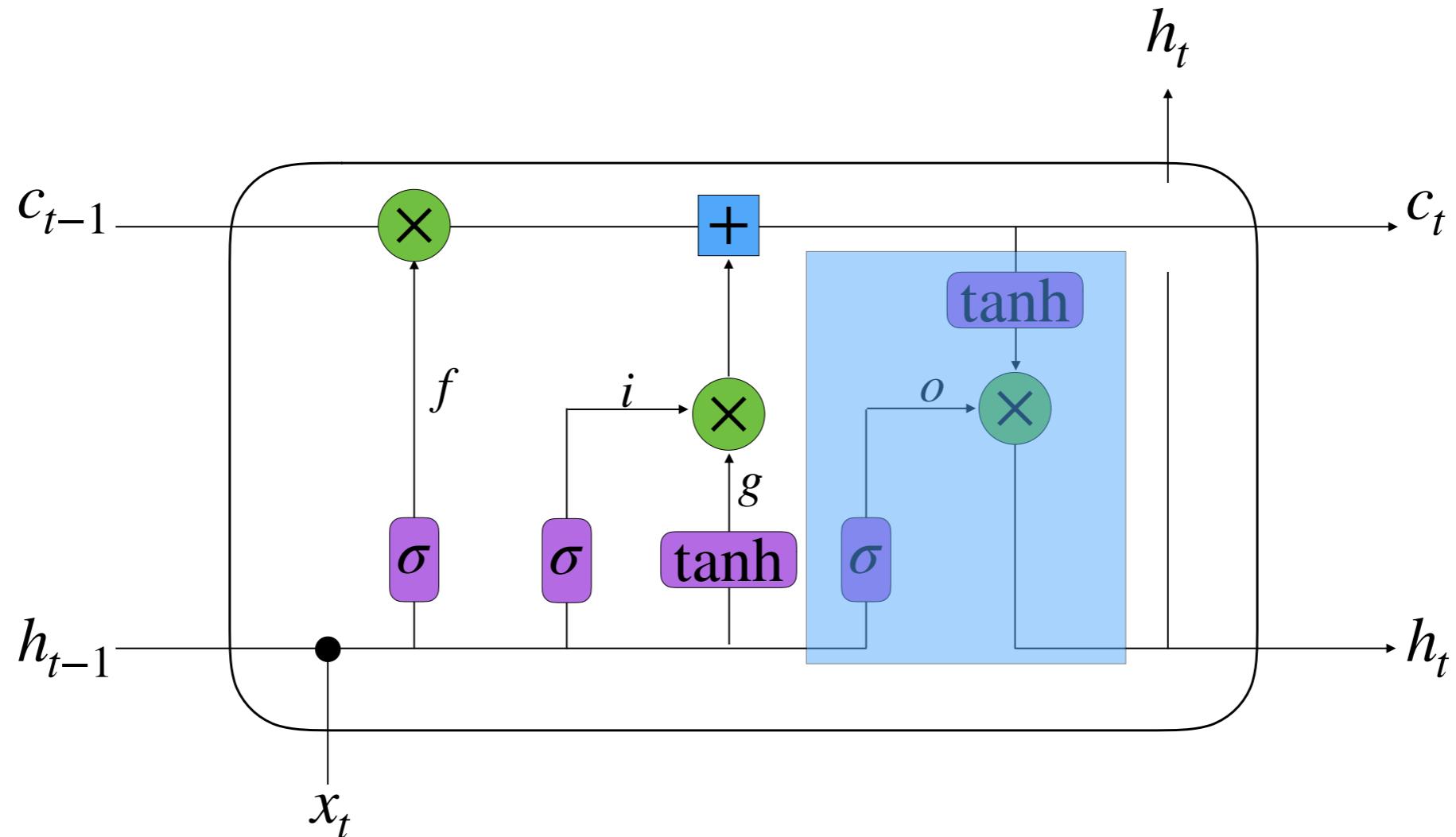
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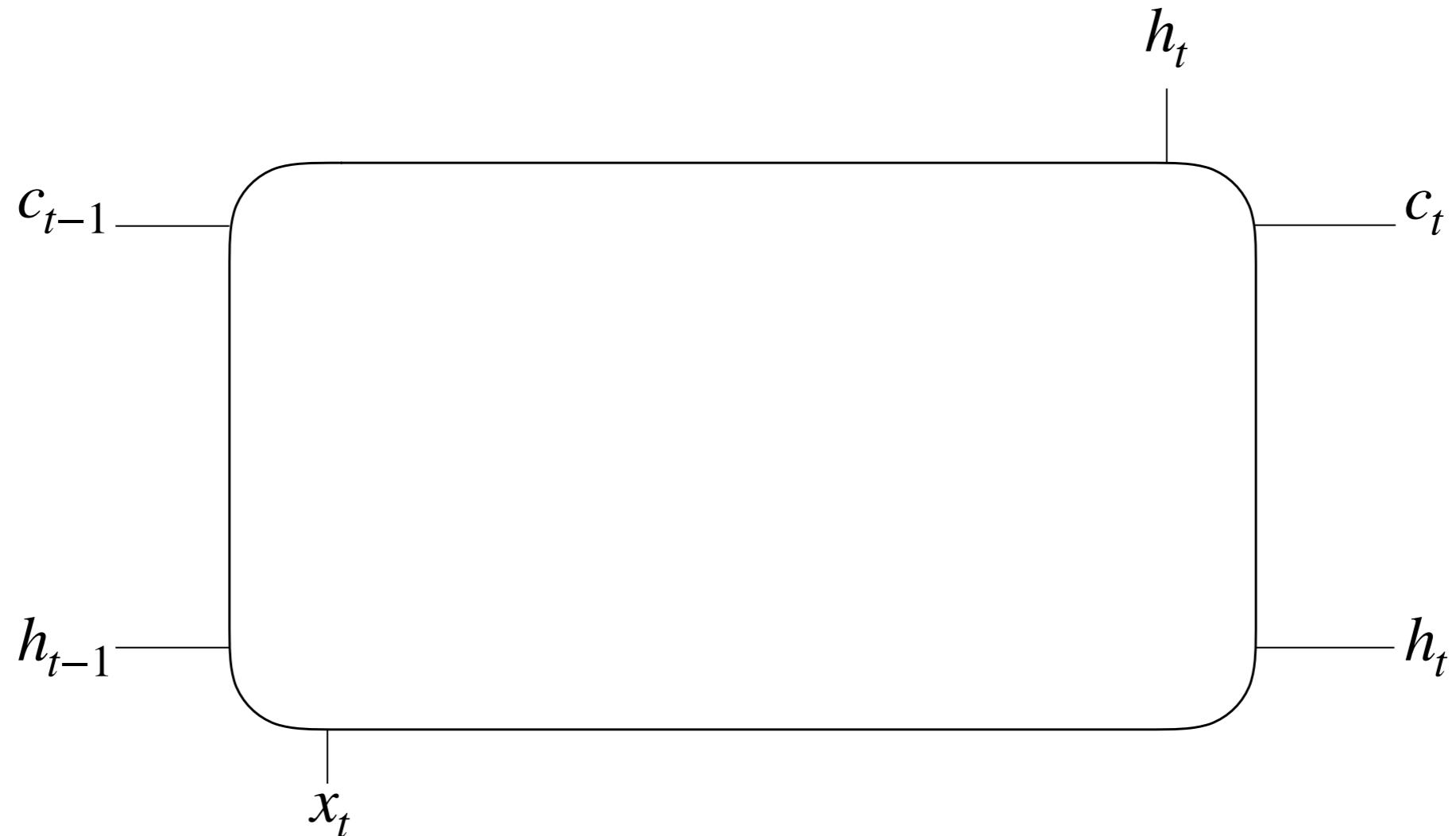
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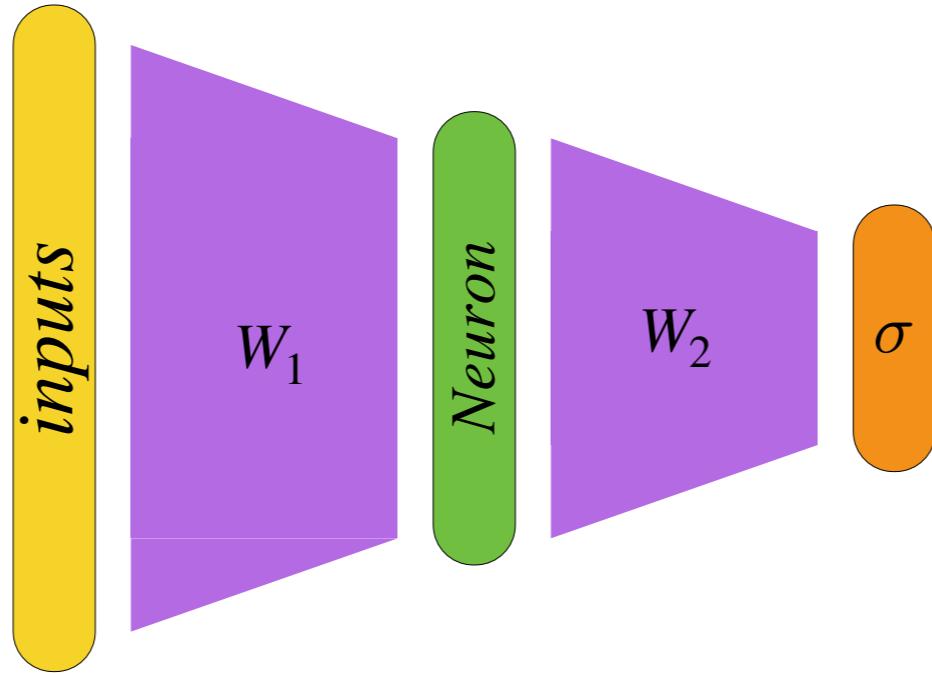
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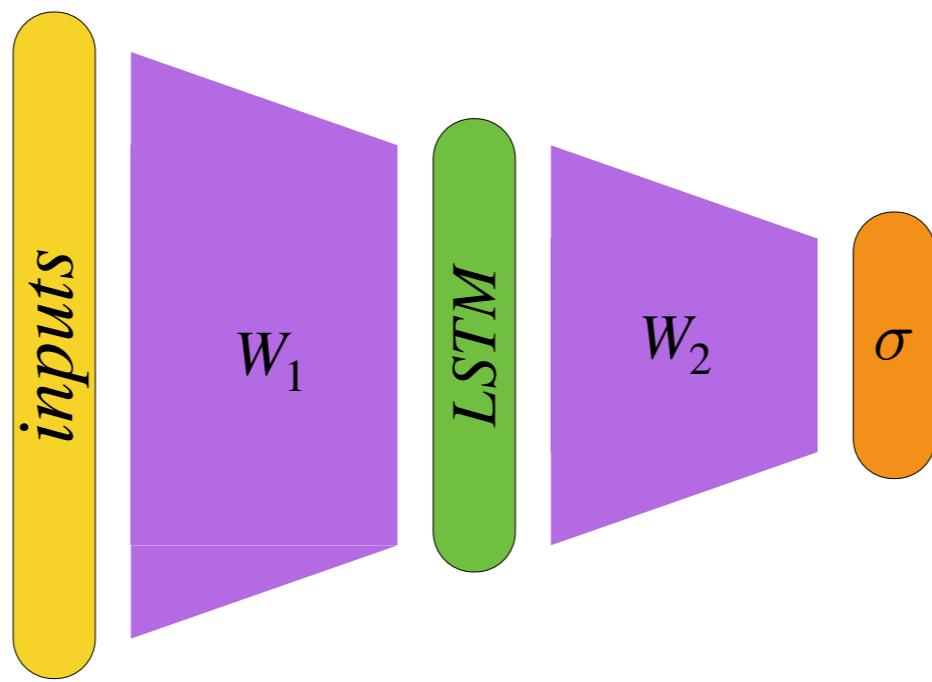
Neural Networks?



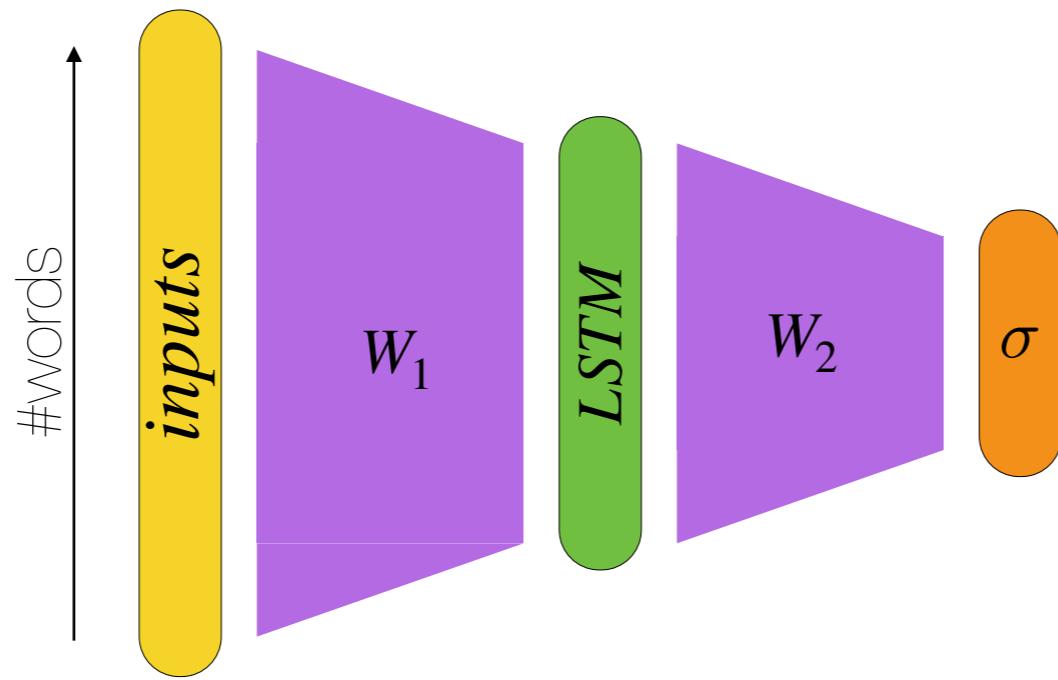
Using LSTMs



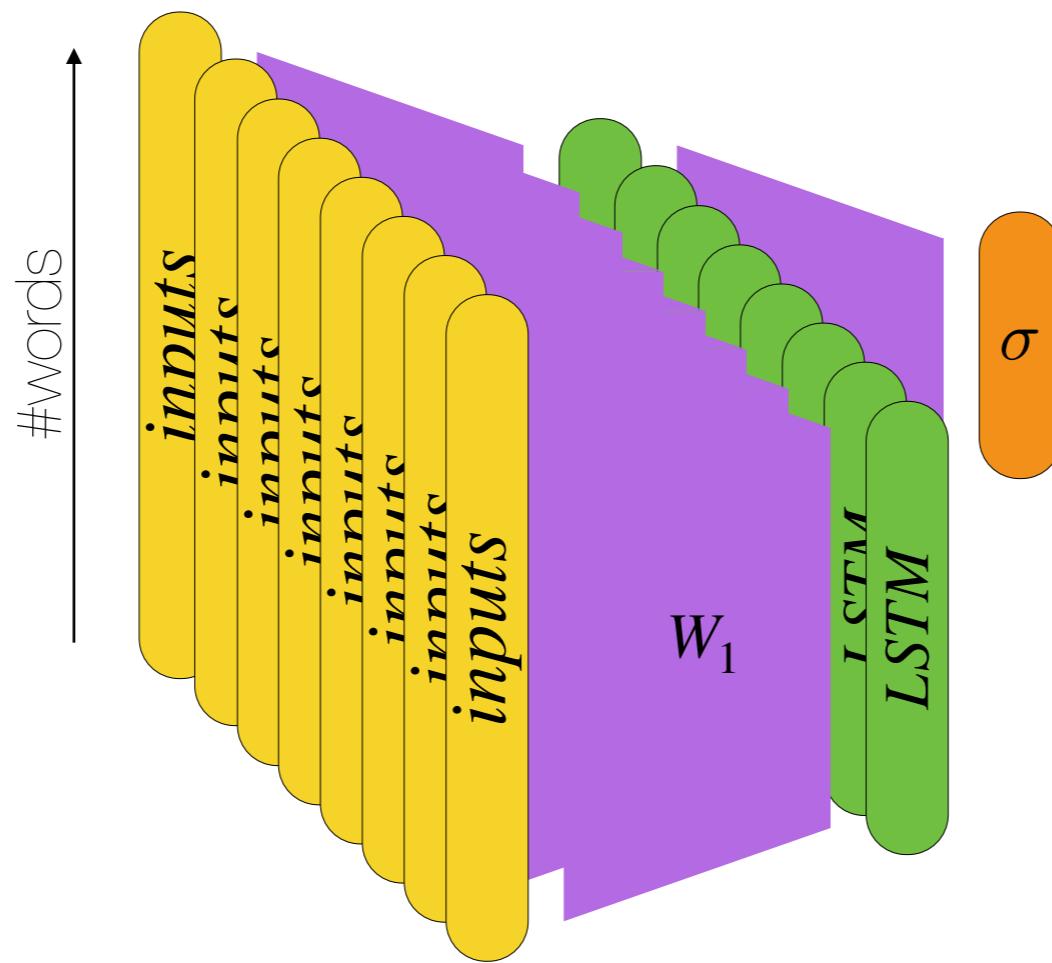
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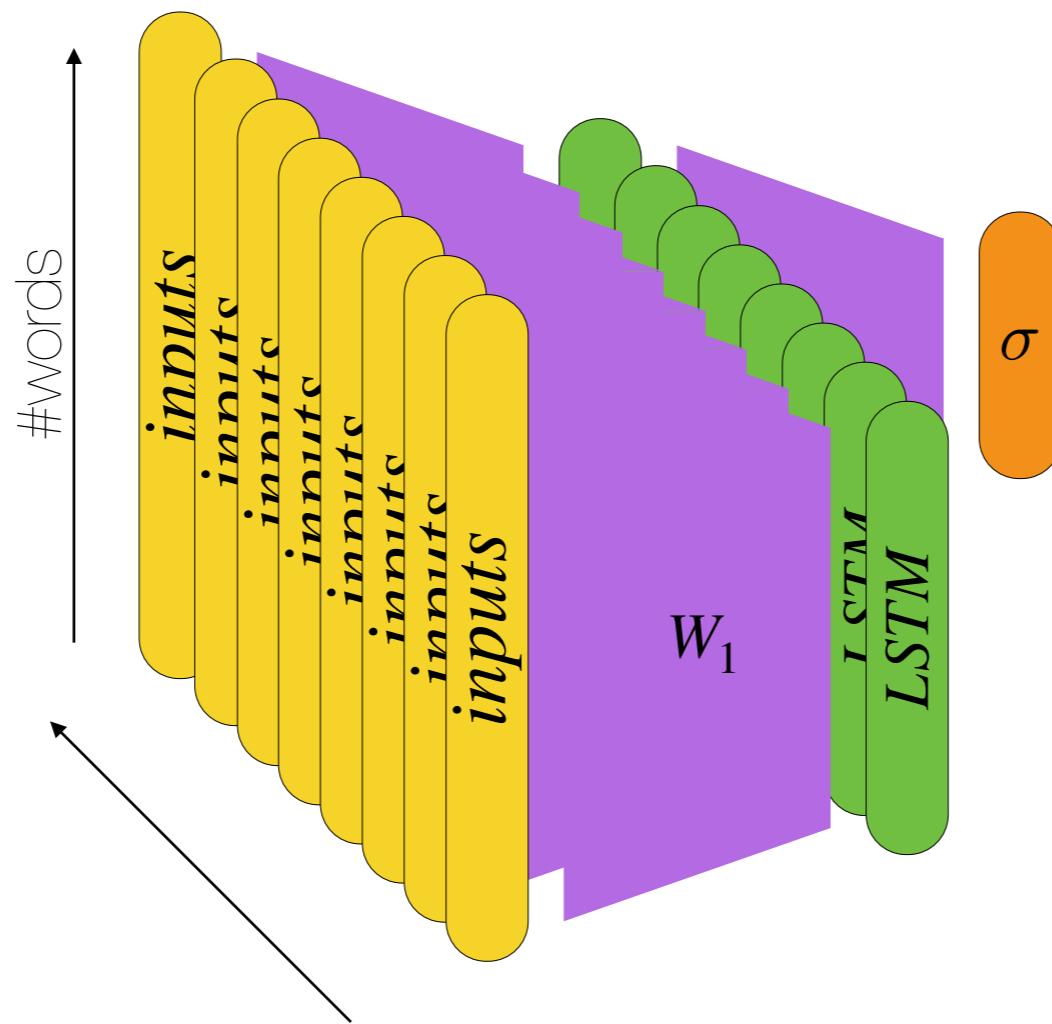
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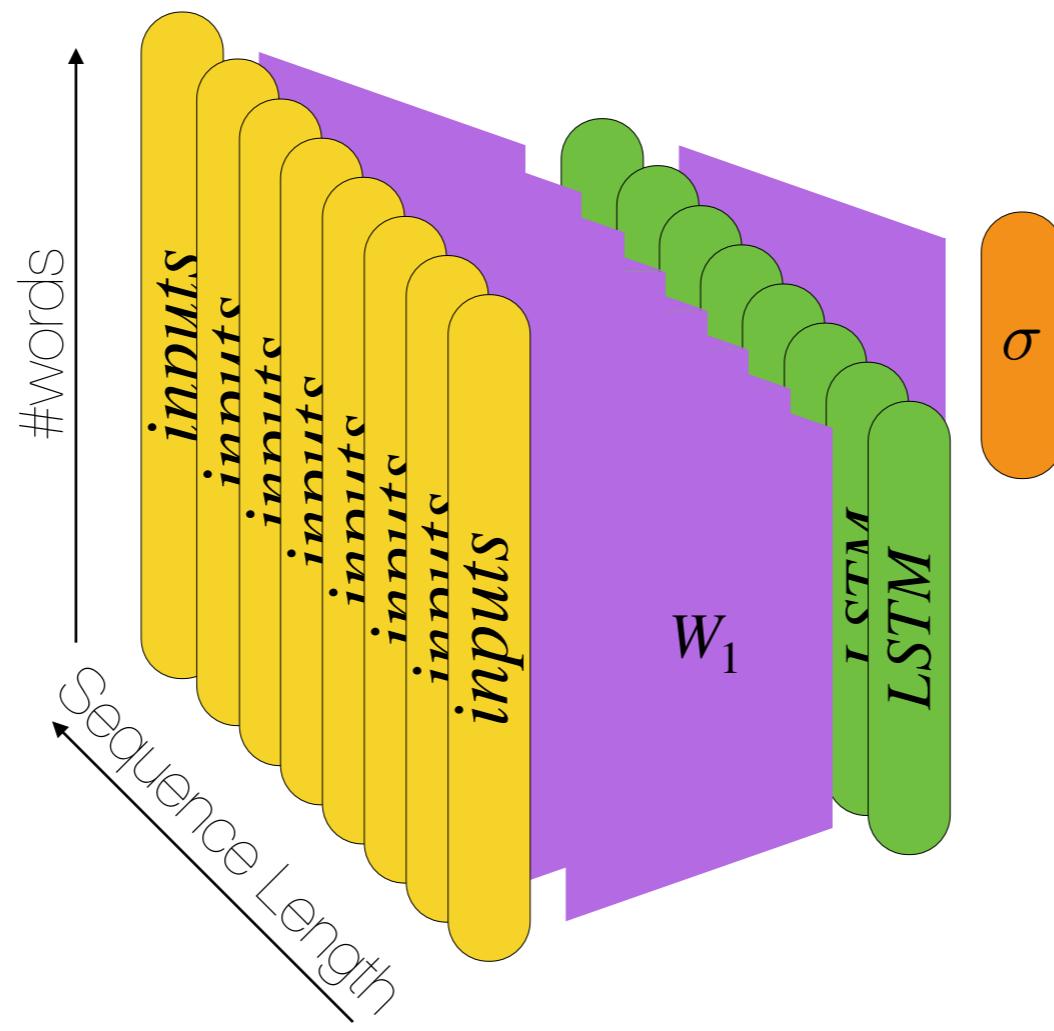
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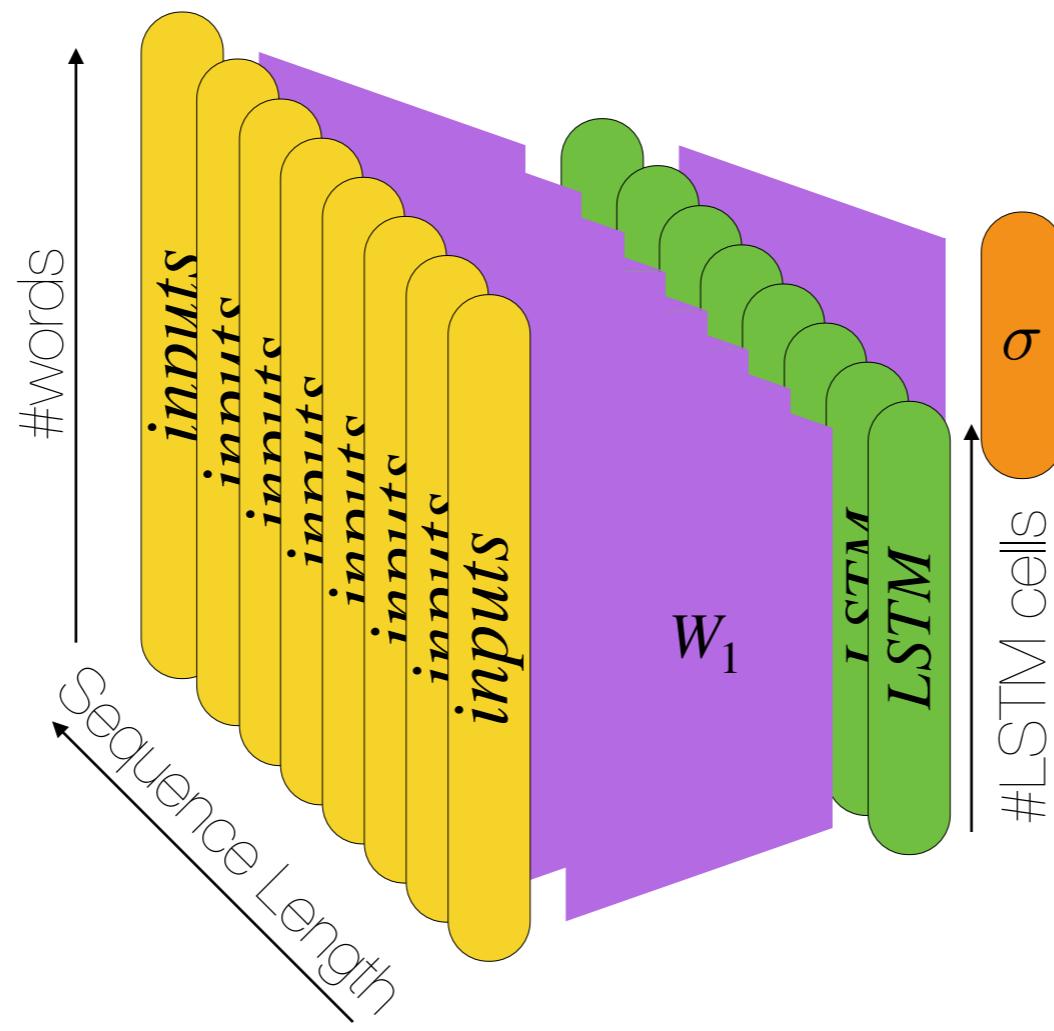
Using LSTMs



Using LSTMs



Using LSTMs



Applications

Applications

- Language Modeling and Prediction

Applications

- Language Modeling and Prediction
- Speech Recognition

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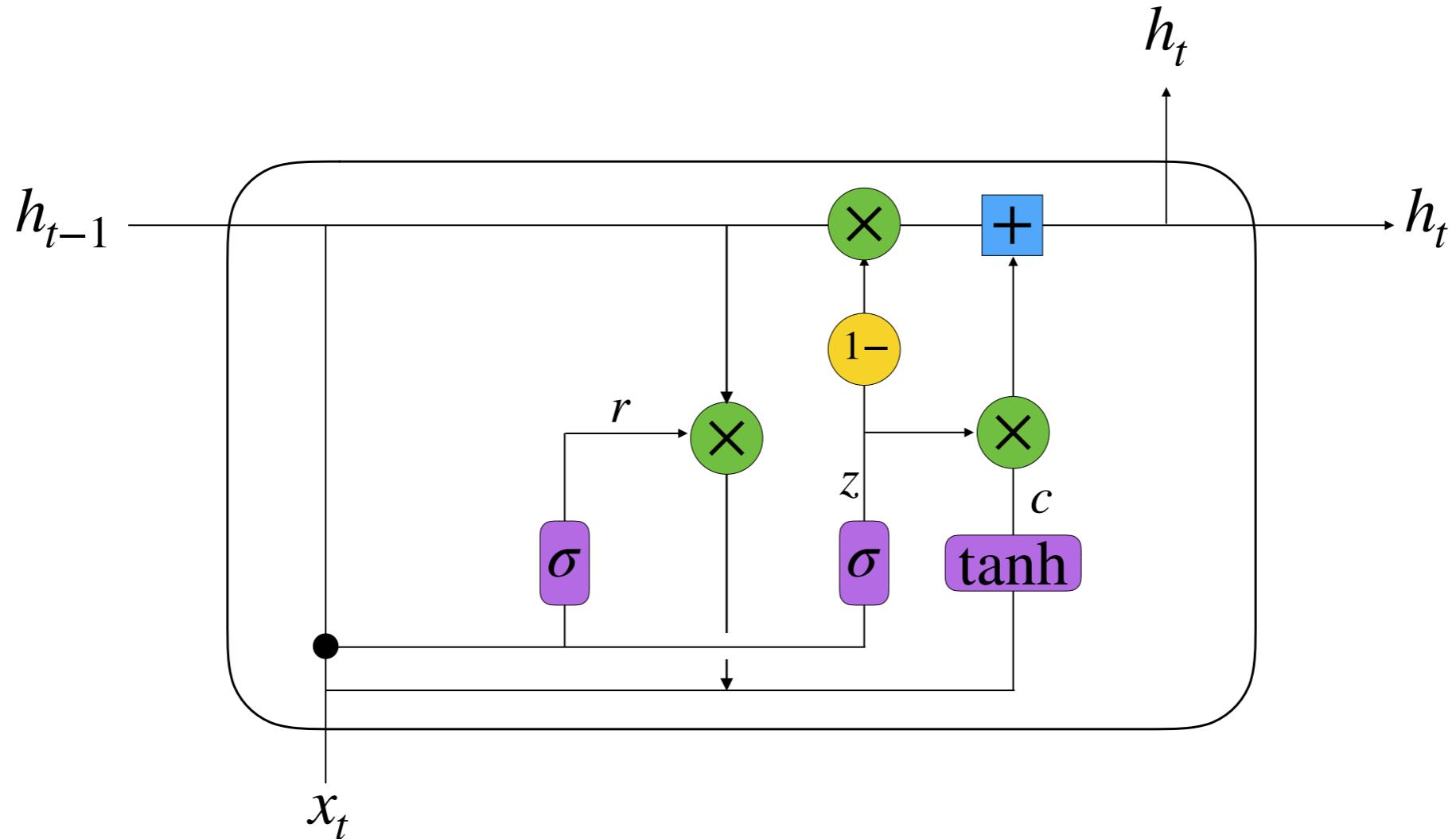
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- [Similar performance](#) to LSTM in some applications, [better performance](#) for [smaller datasets](#).

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-  Element wise addition
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$$z = \sigma(W_z h_{t-1} + U_z x_t)$$

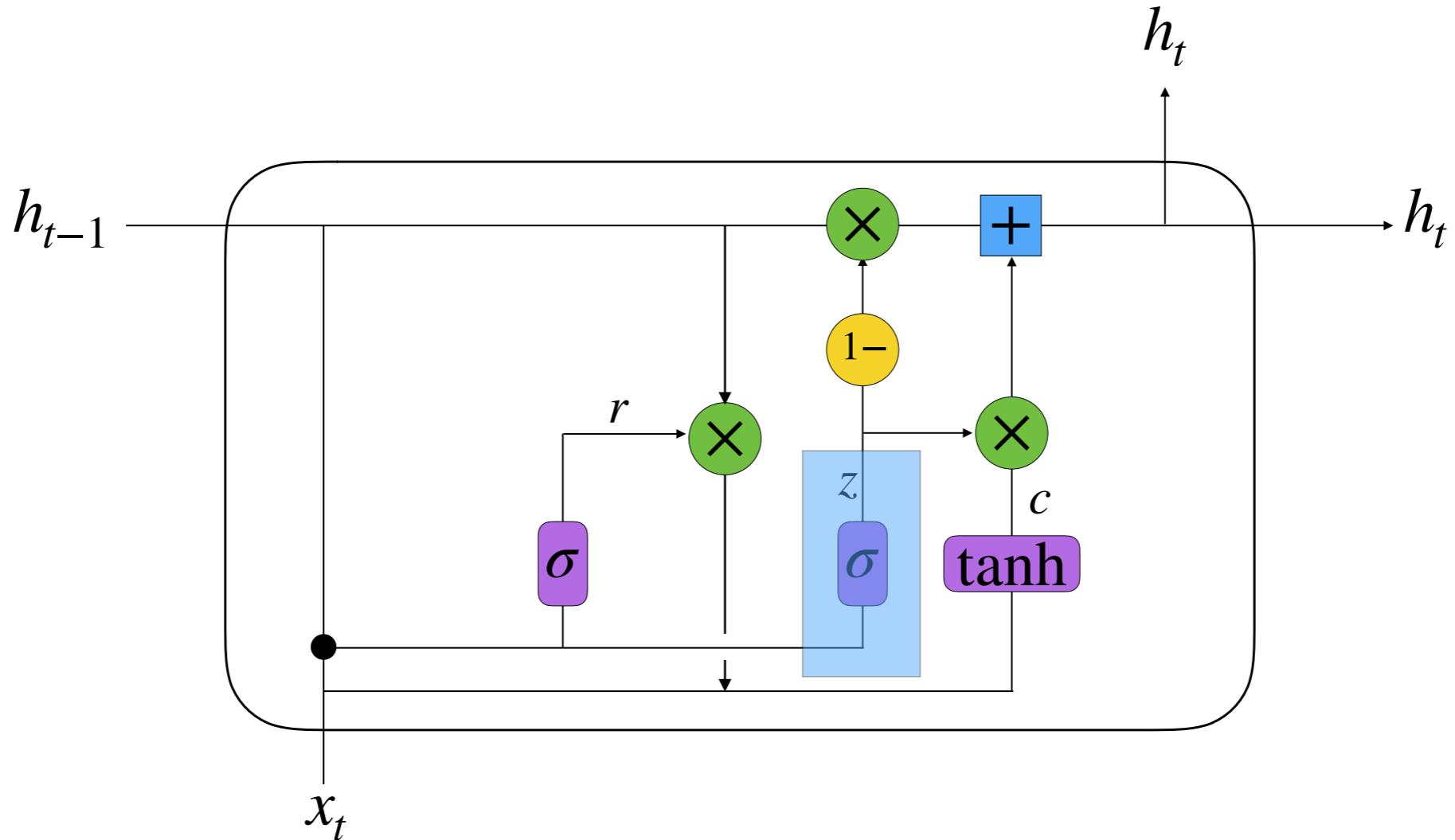
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Update gate:

How much of
the previous
state should
be kept?

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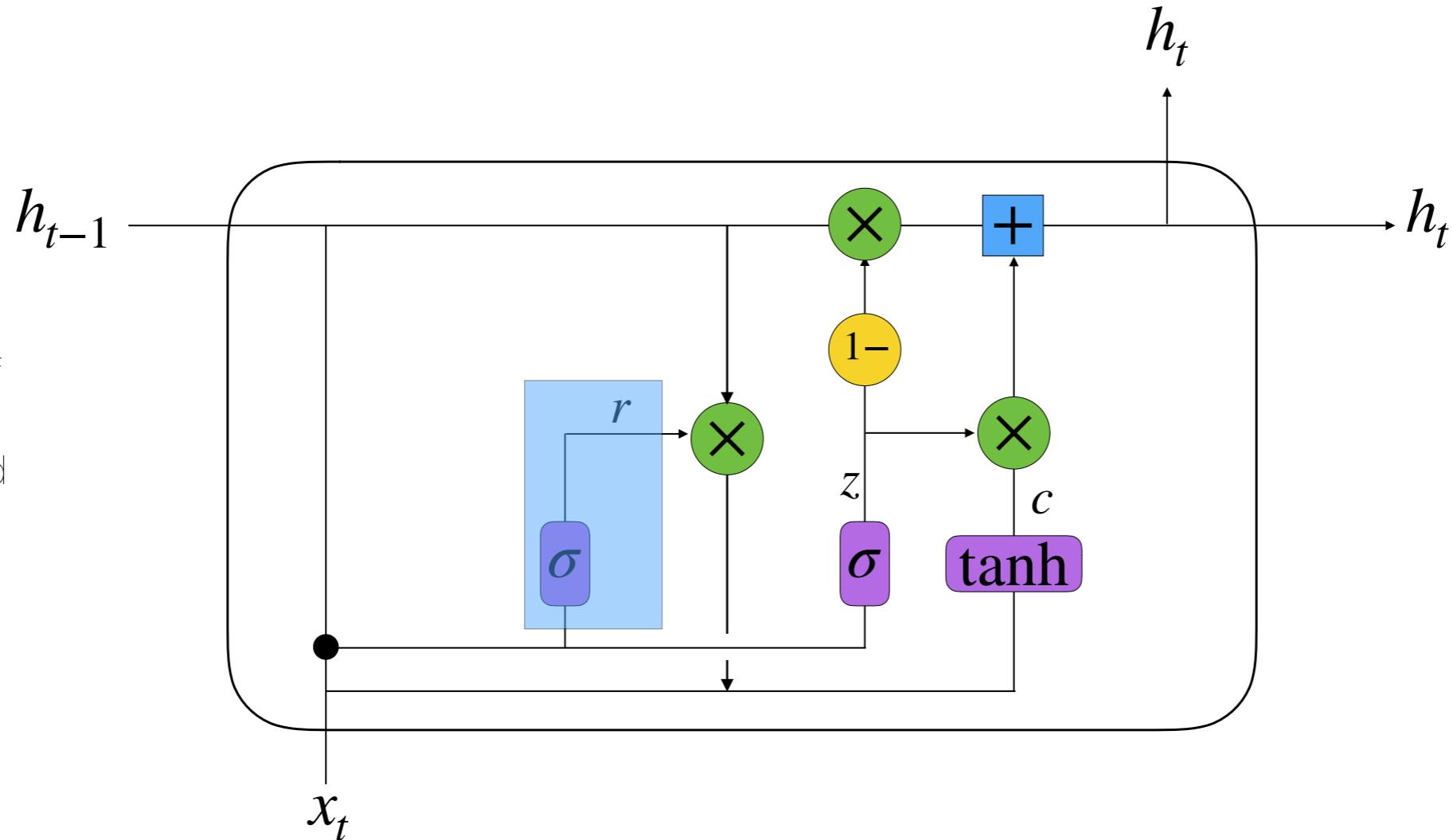
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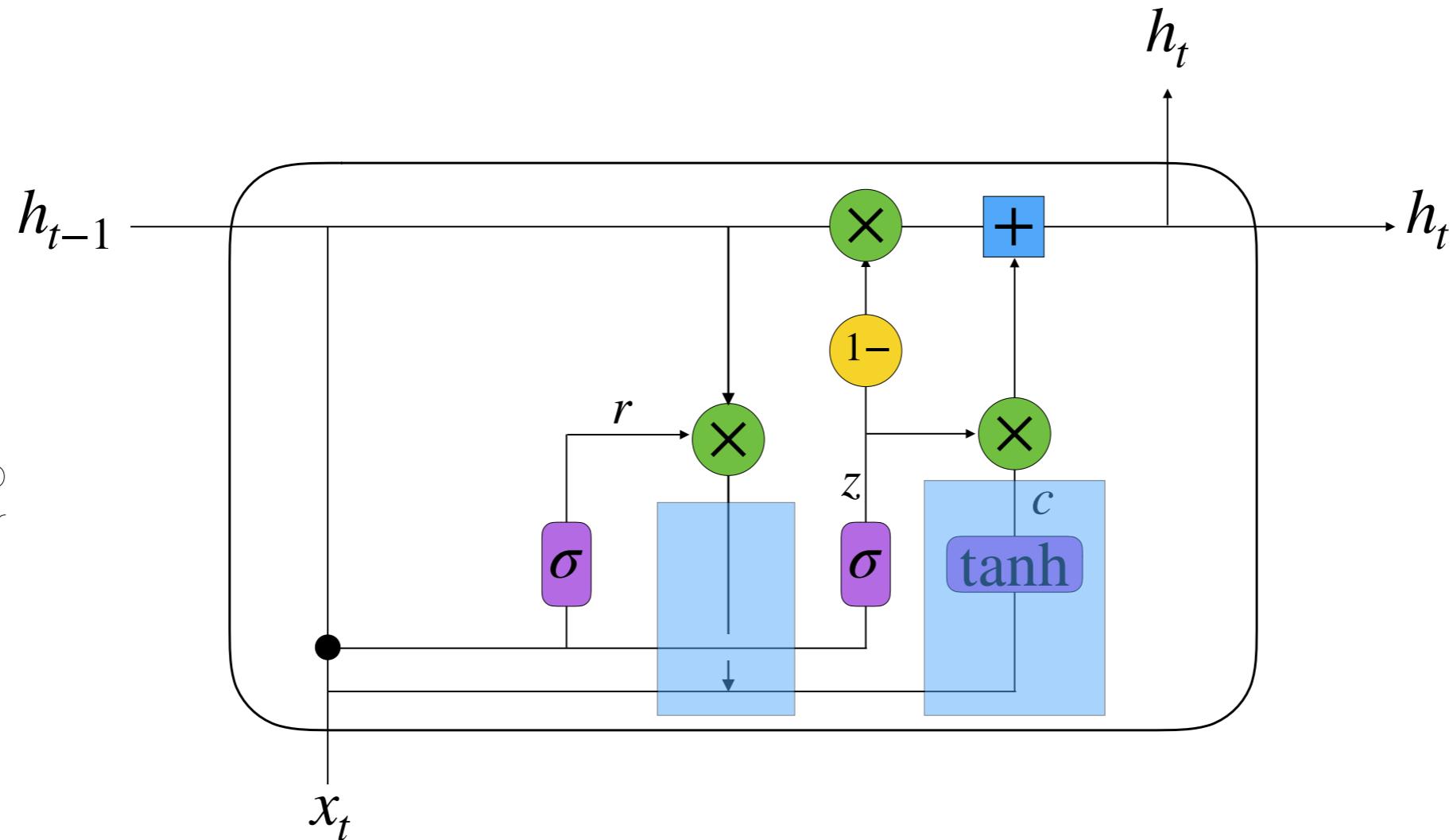
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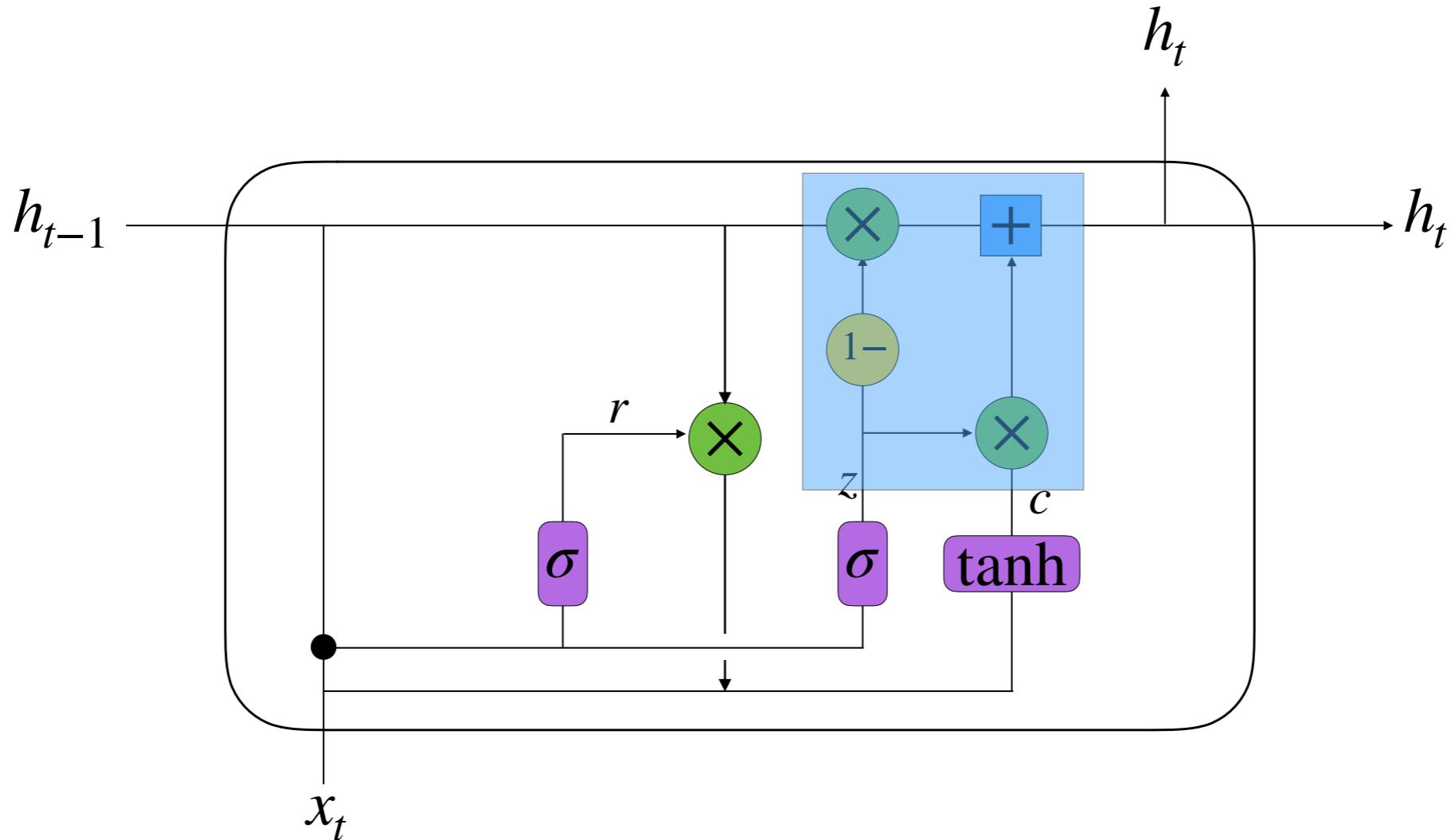
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Output:
Combine all available information.

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My name is _____.

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Mary had a little lamb whose fleece was white as snow.

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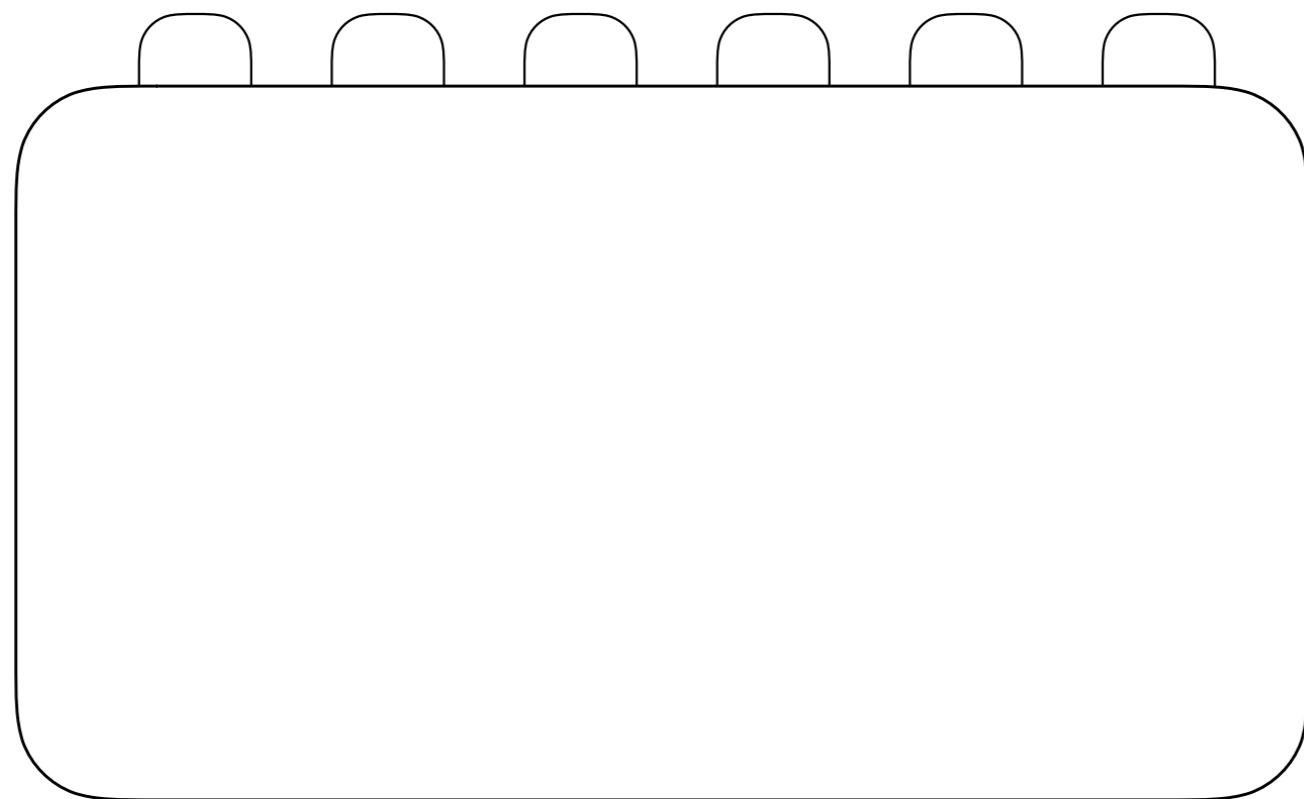
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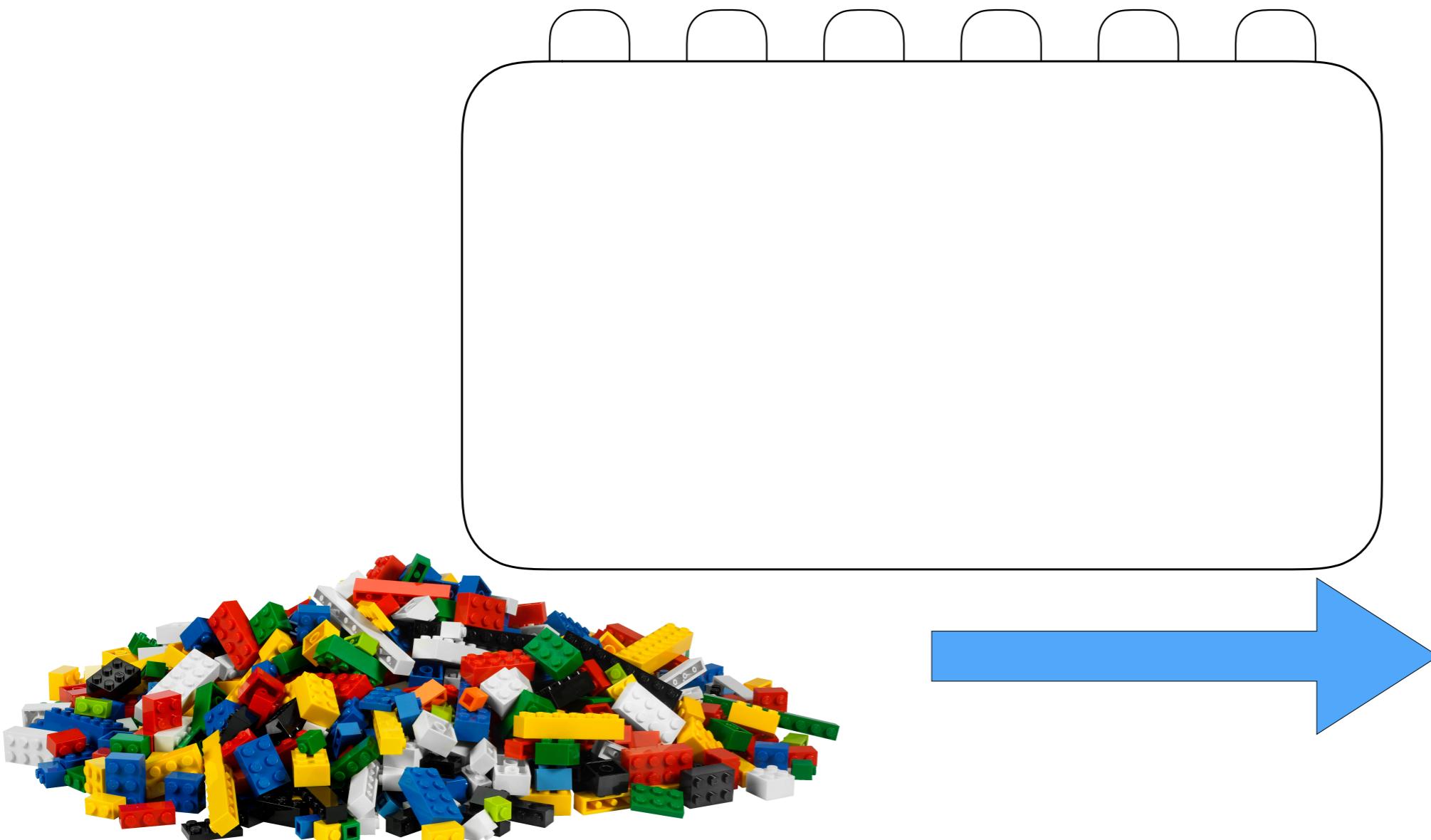
- Supervised learning model

Input Sequence	Output
Mary had a little	lamb
had a little lamb	whose
a little lamb whose	fleece
little lamb whose fleece	was
lamb whose fleece was	white
whose fleece was white	as
fleece was white as	snow

Or legos?



Or legos?



Or legos?

<https://keras.io>



Keras

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www.bgoncalves.com

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 - `Activation(activation)` - Same as the activation option to `Dense`, can also be used to pass `TensorFlow` or `Theano` operations directly.
 - `SimpleRNN(units, input_shape, activation='tanh', use_bias=True, dropout=0.0, return_sequences=False)`
 - `GRU(units, input_shape, activation='tanh', use_bias=True, dropout=0.0, return_sequences=False)`
 - `LSTM(units, input_shape, activation='tanh', use_bias=True, dropout=0.0, return_sequences=False)`

Keras

<https://keras.io>

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- `model.summary()` - Output a textual representation of the model

github.com/bmtgoncalves/RNN