





# Research Thread 2: Low-Code/No-Code Robot Programming

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2



Thread 2 integrates **end-user programming** and **program synthesis** methods to build expert and non-expert tools for robot programming.



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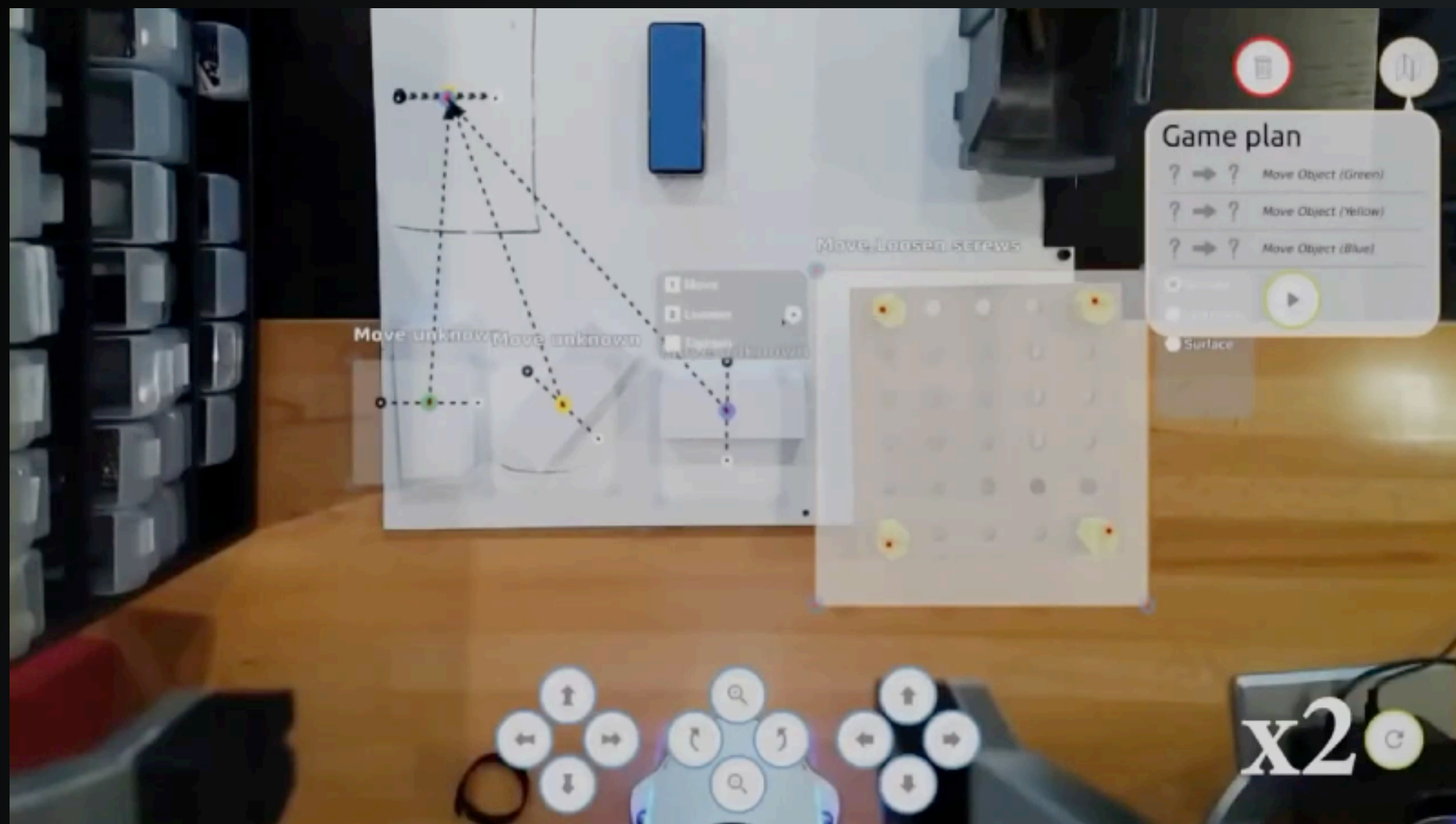
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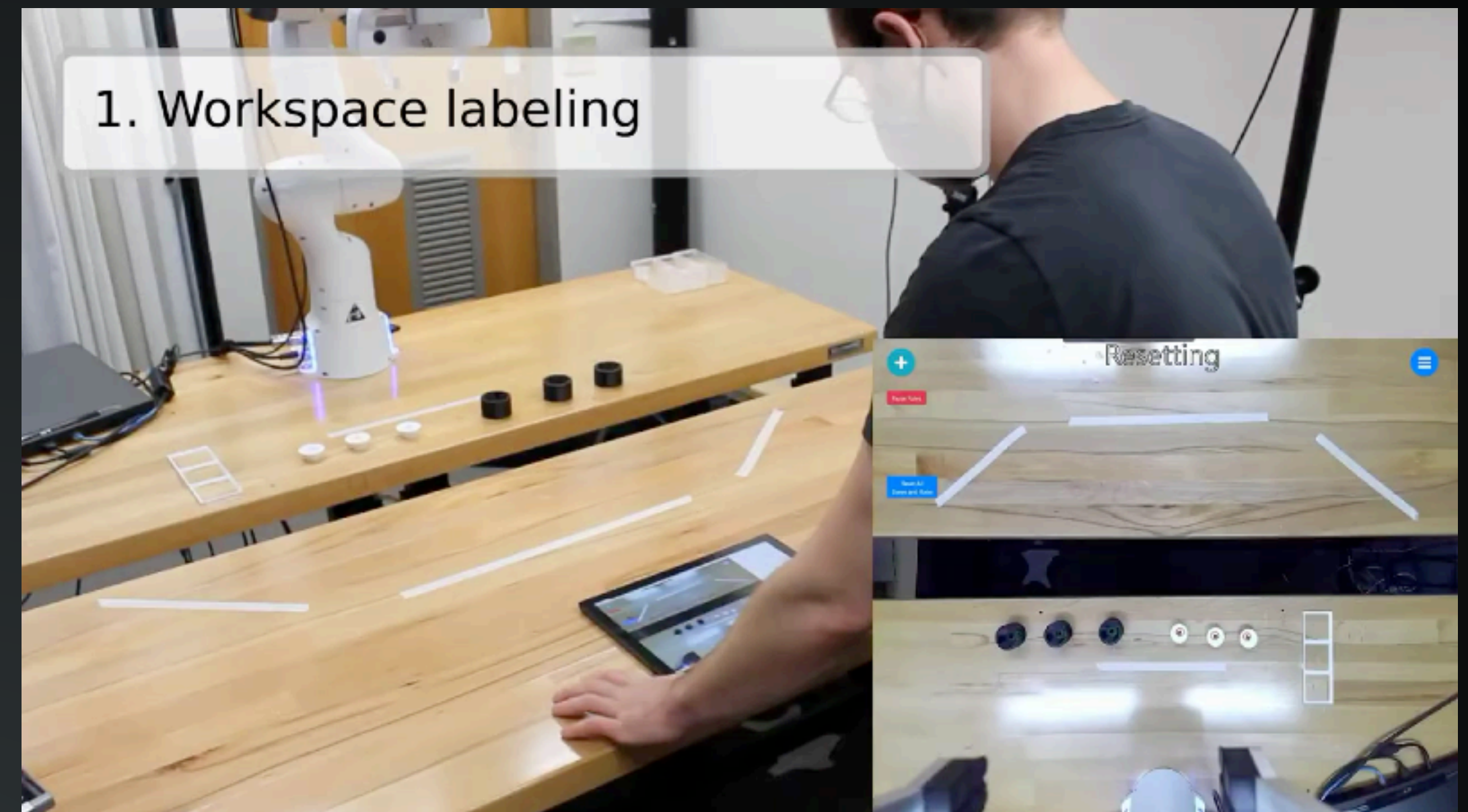
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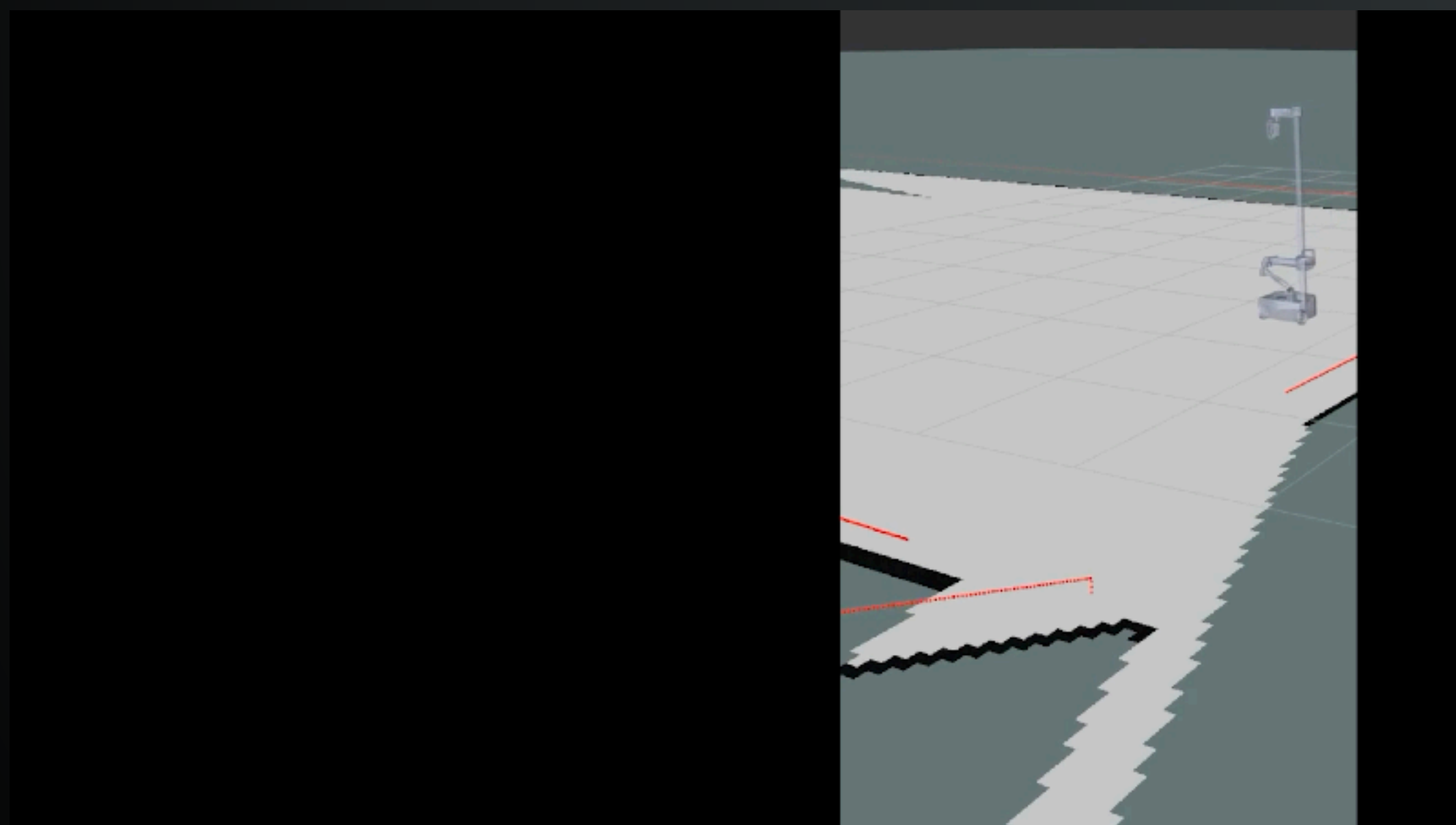




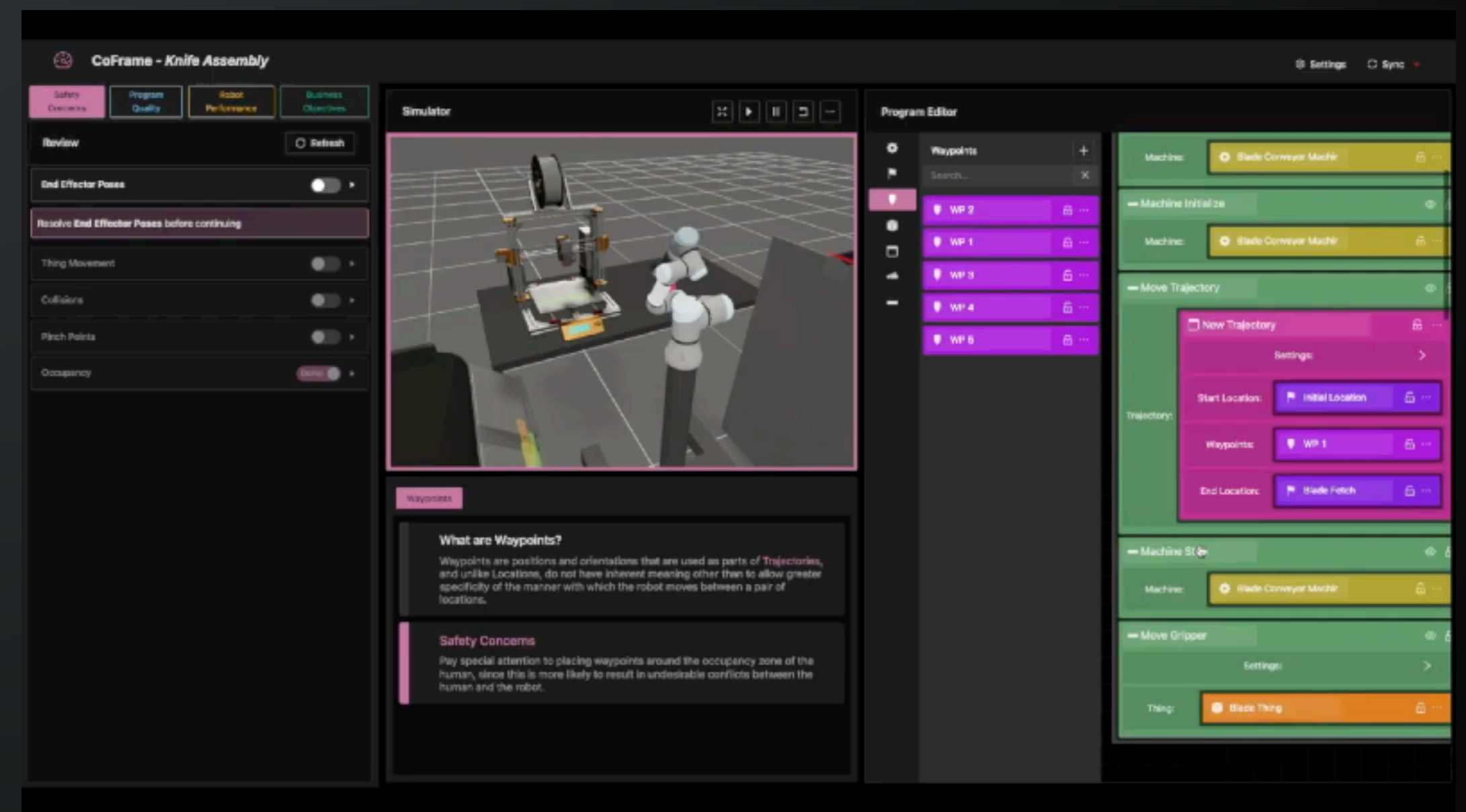
Task-level authoring for highly variable tasks



Trigger-action-based plans for human-robot collaboration



Program synthesis from multimodal input



Real-time program analysis feedback