

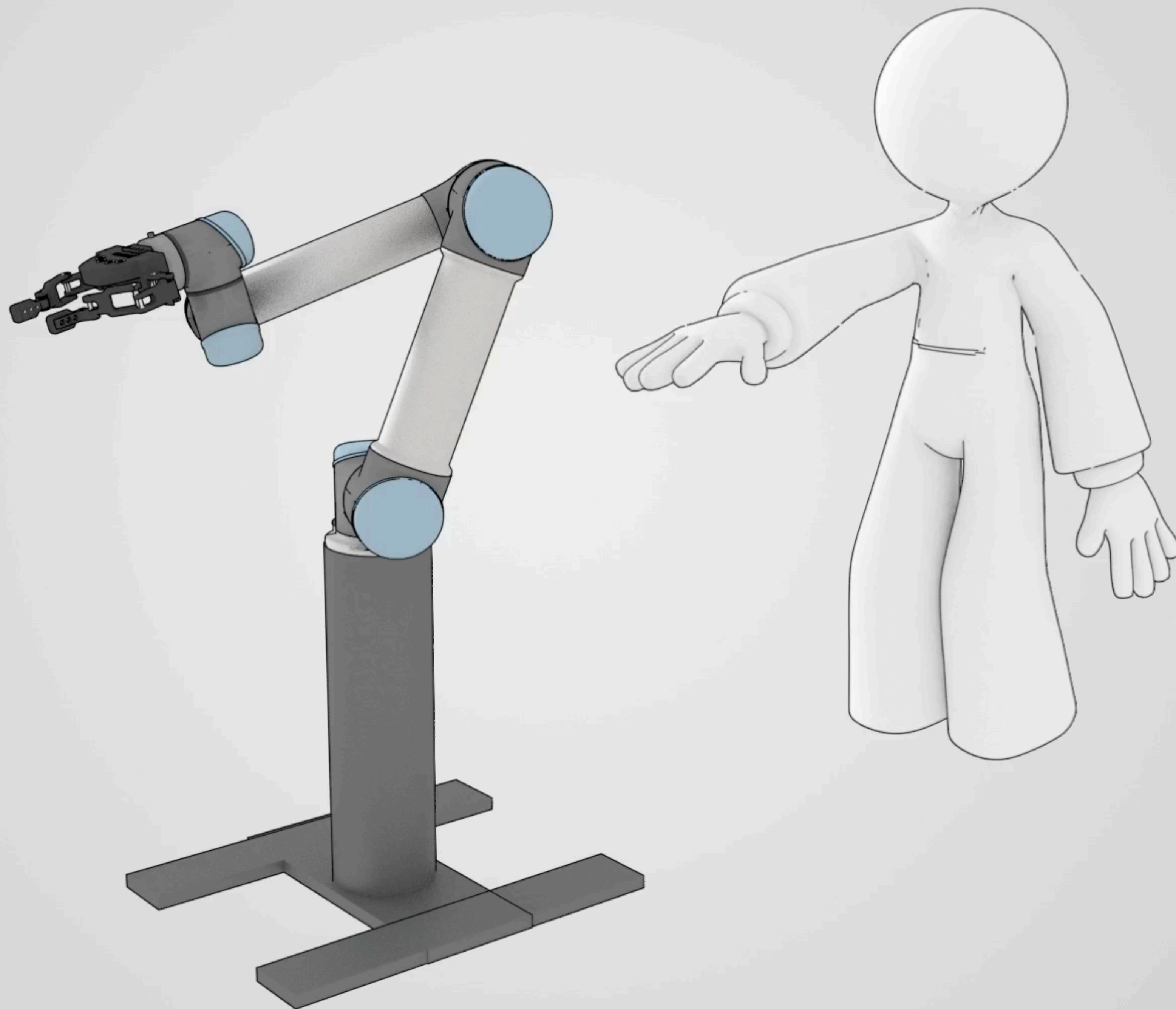
Research Thread 1:

Making Collaborative Robots Easy to Use

BEST PAPER AWARD

A large red circle with a dark gray number '1' in the center.

1

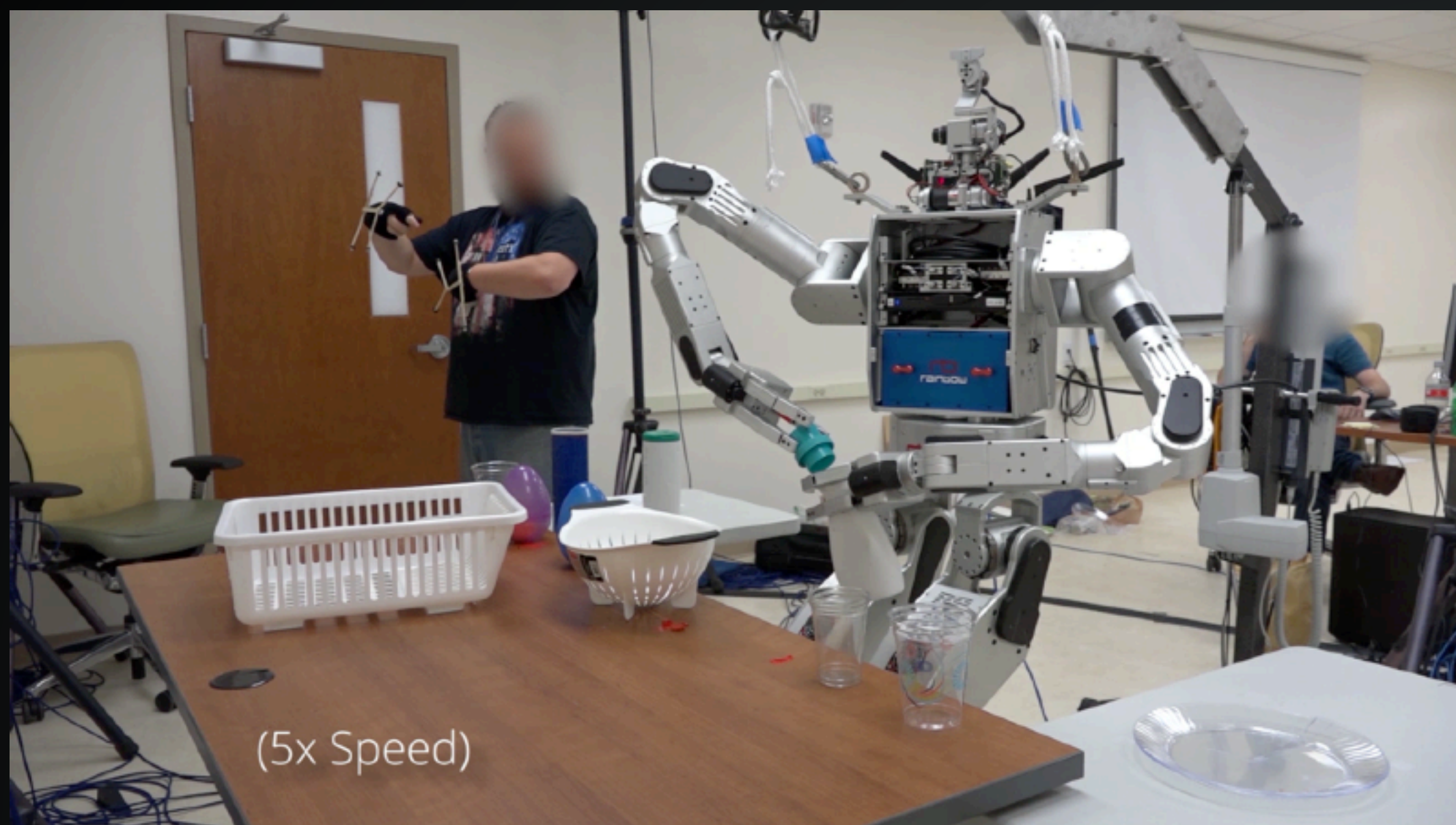


1



Research Thread 1: Making Collaborative Robots Easy to Use

HRI 2018 BEST PAPER AWARD
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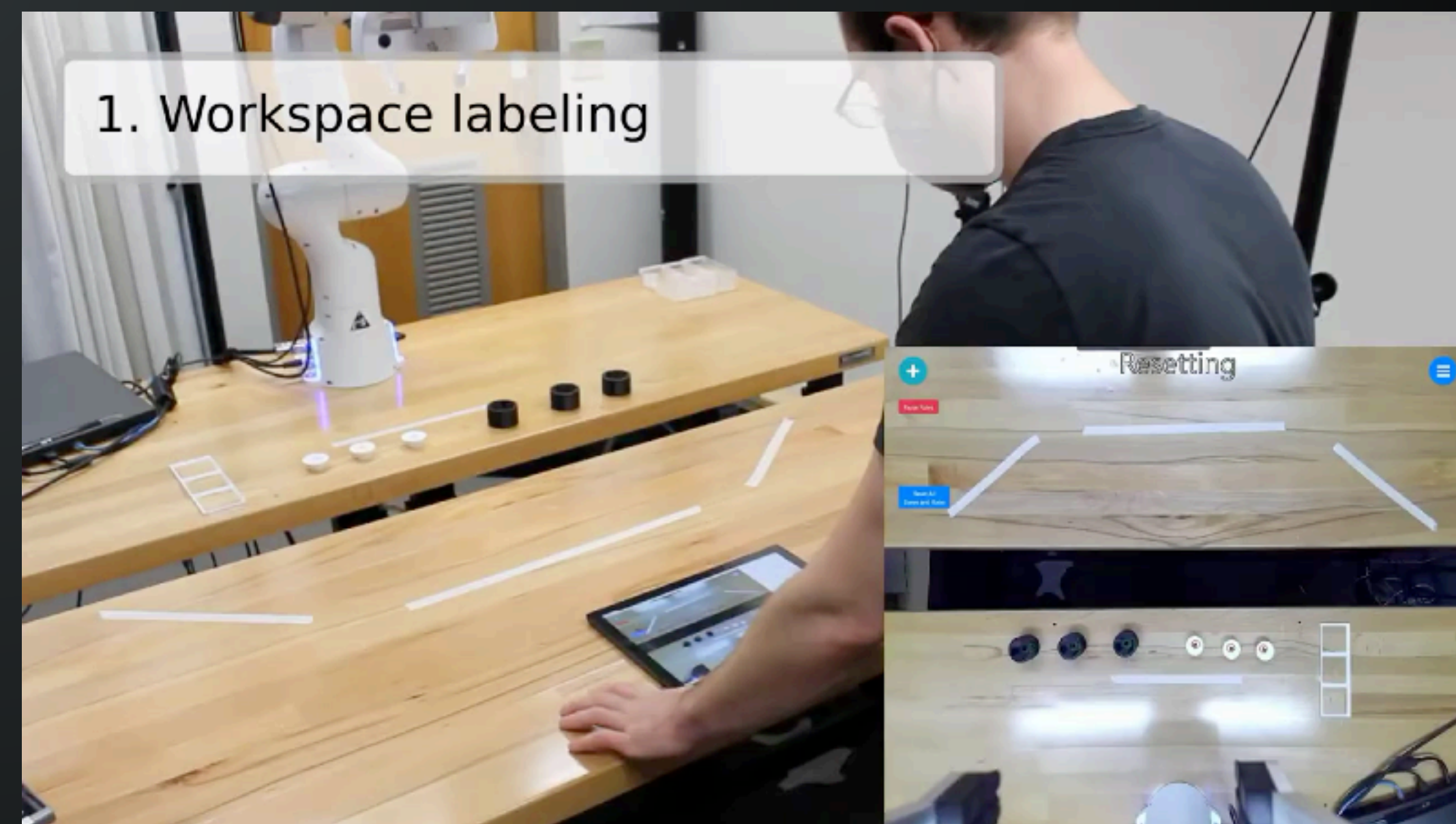
Shared-control-based bimanual teleoperation



Corrective shared control for highly variable tasks



Task-level authoring for highly variable tasks



Trigger-action-based plans for human-robot collaboration