

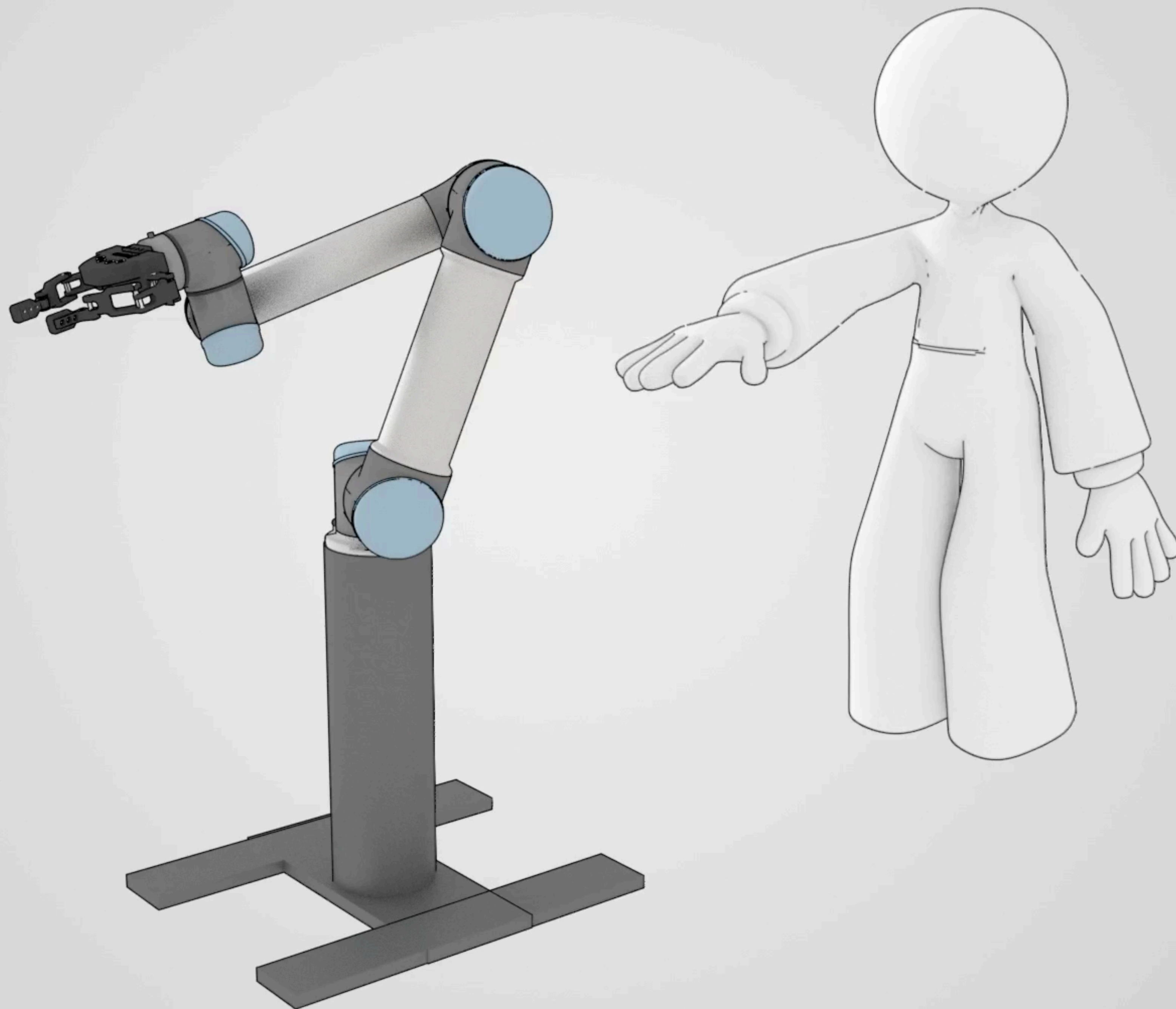
Research Thread 1: Human-in-the-Loop Teleoperation

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Thread 1 aims to make using collaborative robots very very easy for non-experts by combining **end-user programming, shared control, learning.**



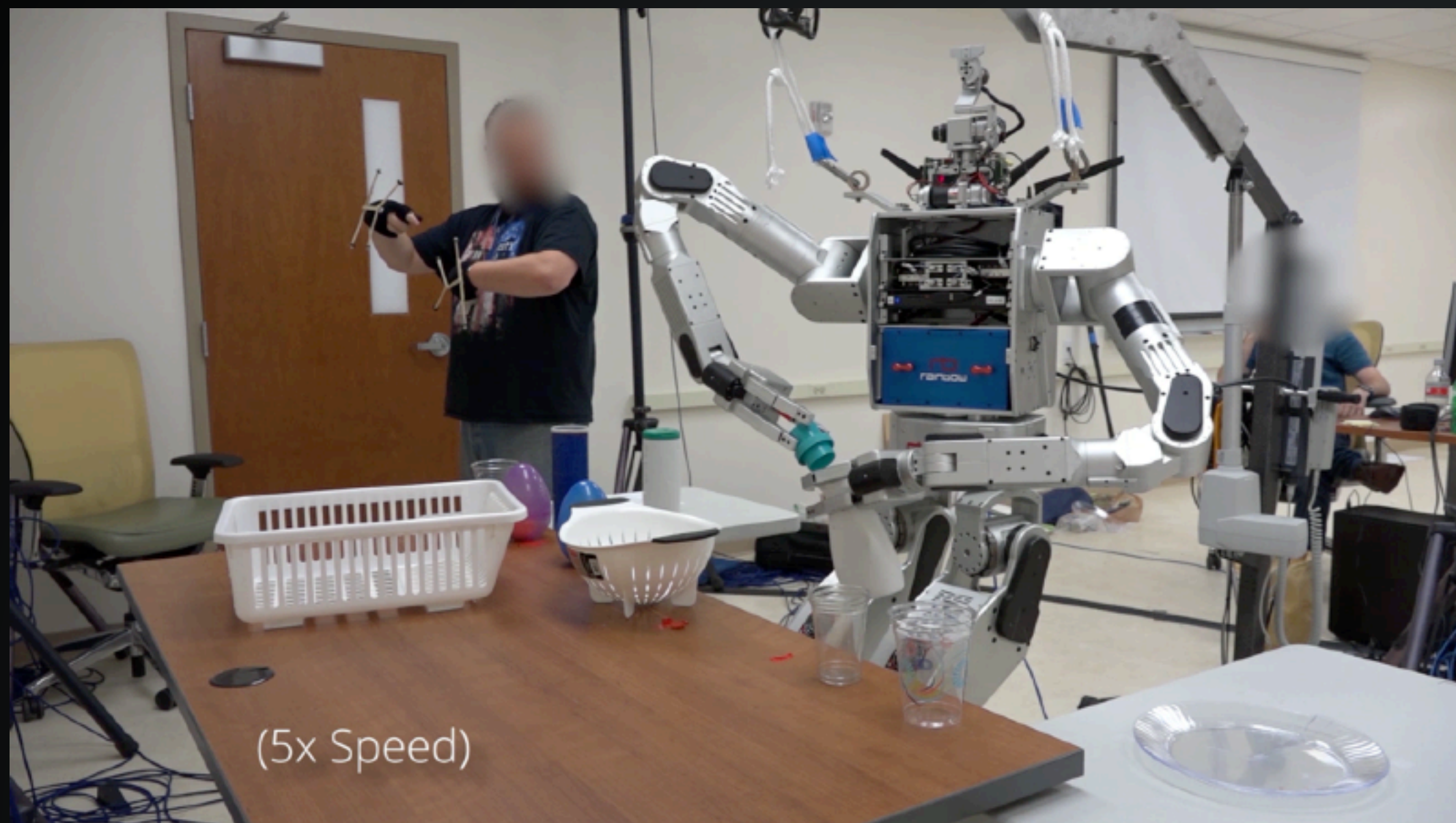
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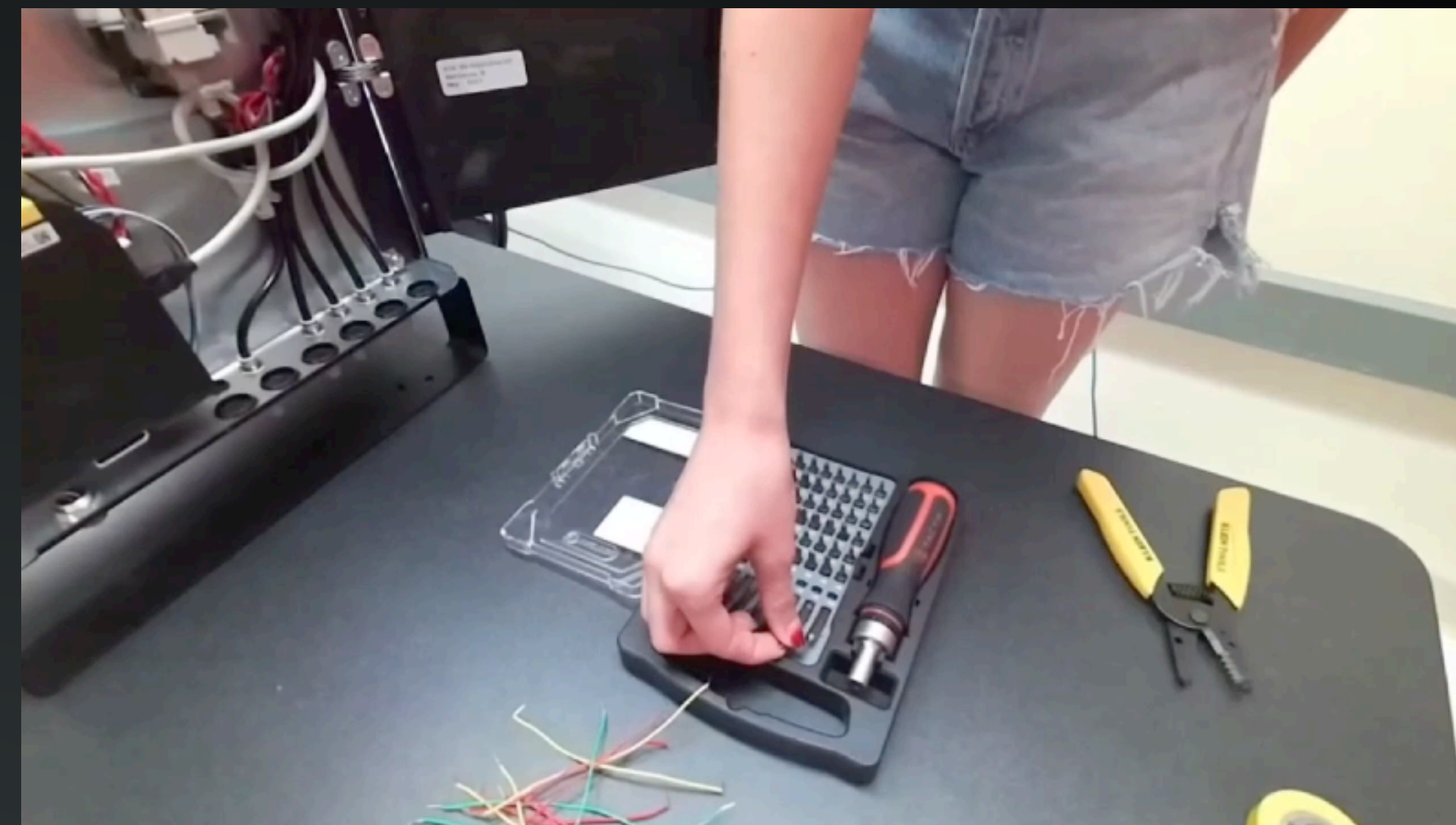


Research Thread 1: Human-in-the-Loop Teleoperation

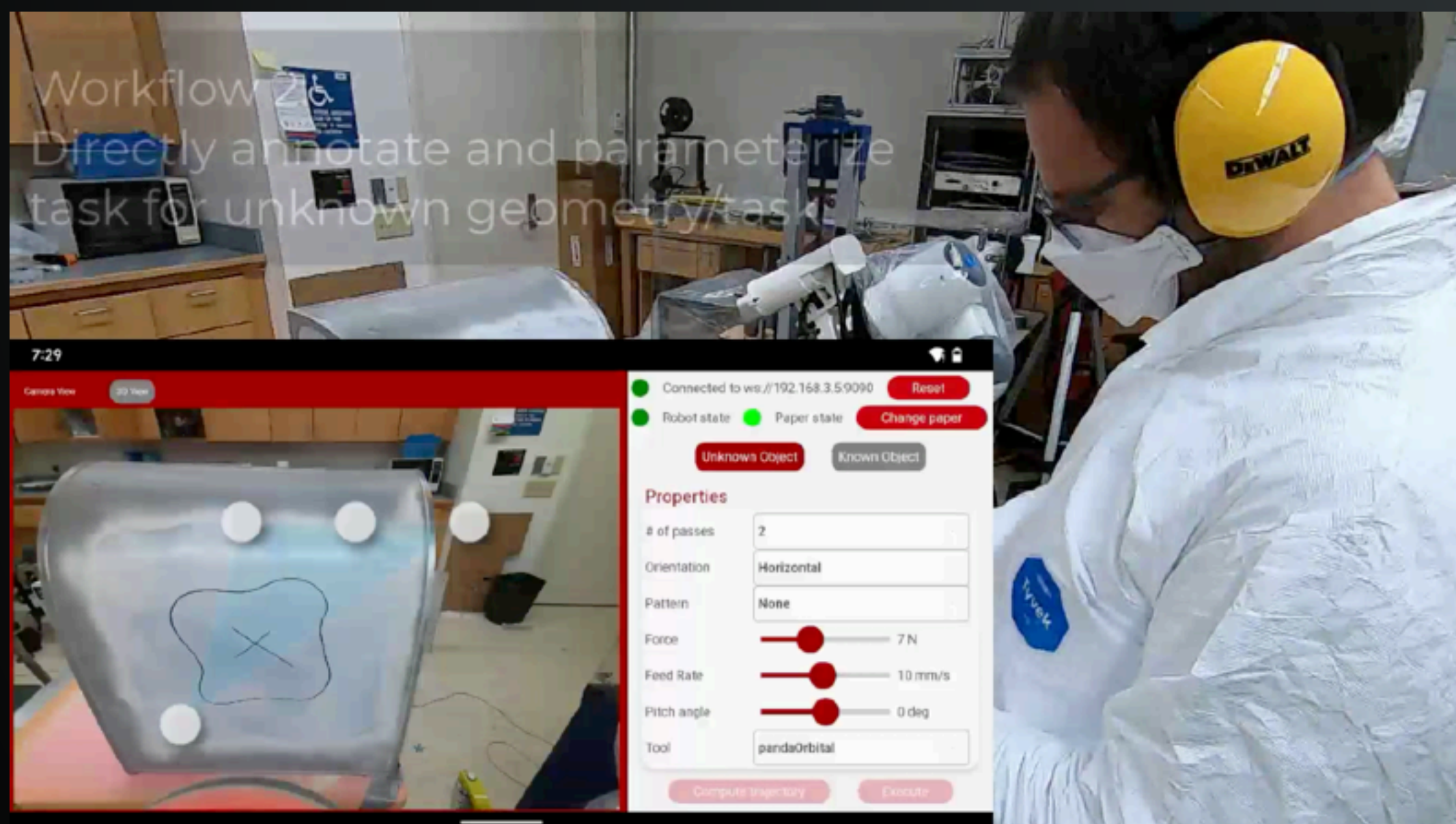
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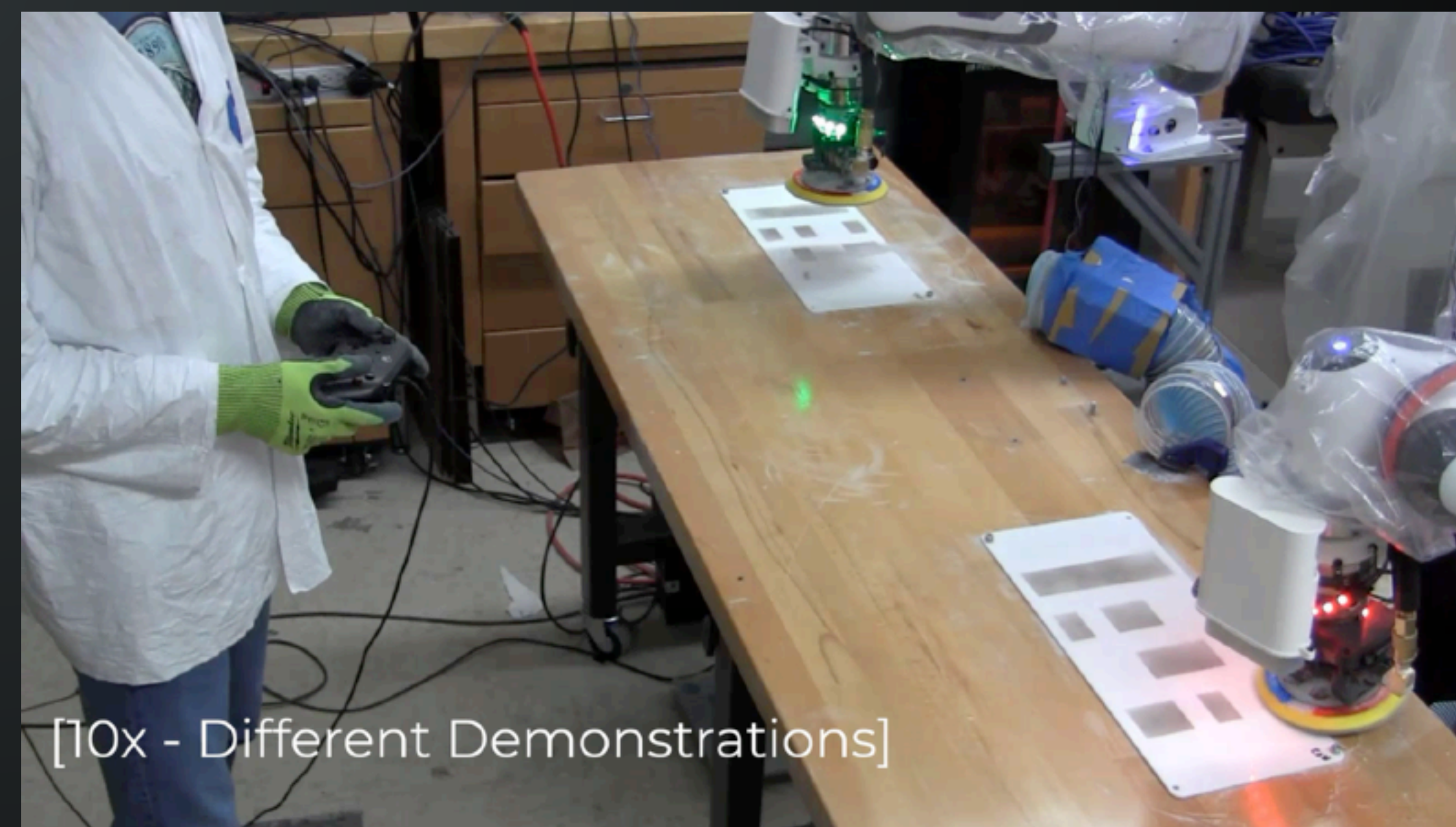
Shared-control-based bimanual teleoperation



Robotic camera-based remote monitoring/collaboration



Corrective shared control for highly variable tasks



Corrective multi-robot shared control