











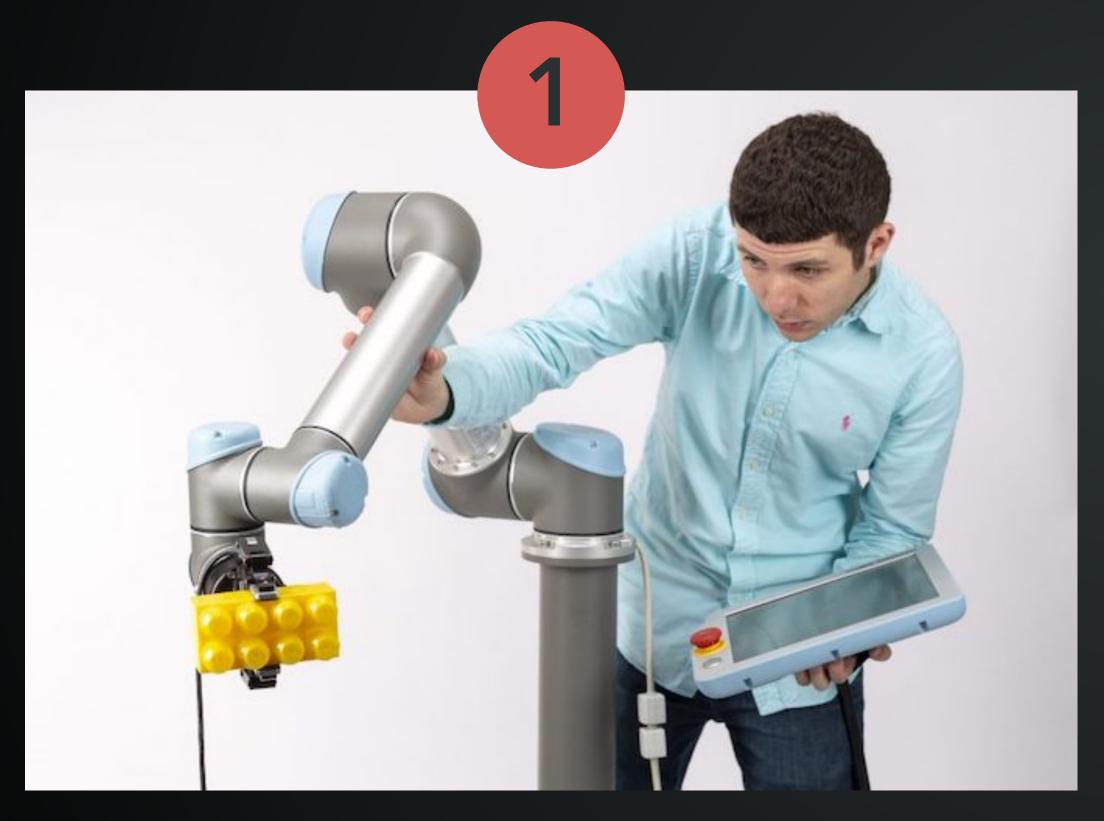




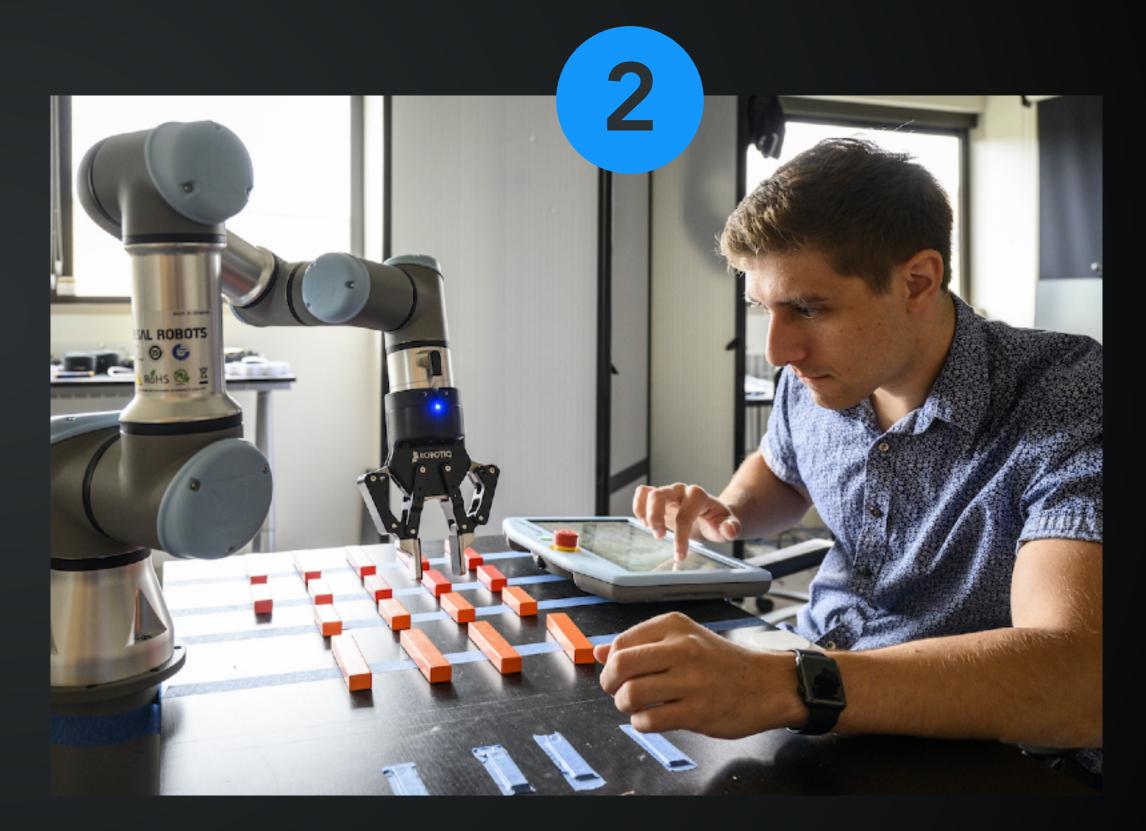
In collaborative robotics, my research aims to build **1 human-in-the-loop** robotic systems and 2 low-code/no-code programming tools that help overcome automation bottlenecks and improve efficiency, ergonomics.

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Thread 1: Human-in-the-loop teleoperation, control

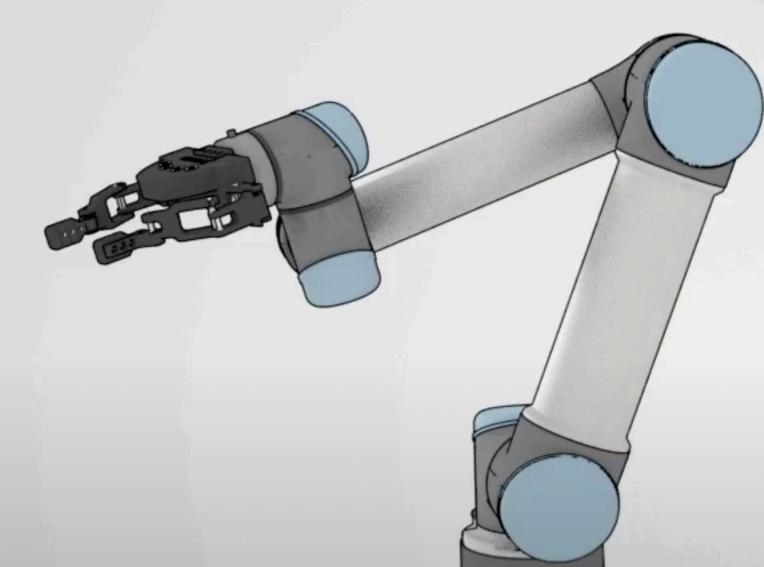


Thread 2: Low-code/No-code programming

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Thread 1 aims to make using collaborative robots very very easy for non-experts by combining enduser programming, shared control, learning.





Research Thread 1: Human-in-the-Loop Teleoperation

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