

# Project 3: Implement a planning search

## Research report

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**Implementation** The loading & unloading actions, level-sum heuristics, and problem 1-3 were implemented in `my_air_cargo_problem.py`. The methods required to build the planning graph algorithm were implemented in `my_planning_graph.py`. The implementation was tested using the provided unit tests.

The different algorithms together with problem 1-3 were compared using `run_analysis.py`. The results were stored in `search_result.json` and further processed with the ipython notebook `analyze_results.ipynb`.

**Analysis of the results** All searches except the breadth first search yielded the same path length for the individual problems (cf. table 1). The optimal plans for the problems (cf listing 1, 2 & 3) was taken from the A\* search with the planning graph and level-sum heuristics.

The planning graph implementation took exceptionally long, probably due to a not optimized implementation and the small size of the problems. The overhead of the planning graph does not out weight the uniformed searches. In general the A\* search with the level sum heuristics performed best. The depth first search found not the optimal solutions, due to its tendency to get stuck in local minimum, when not further expanding certain trees, it is a poor choice for these kind of planning problems.

Table 1: Overview of all results

| Algorithm                           | Air Cargo | Expansions | Goal tests | New nodes | Plan length | Time elapsed |
|-------------------------------------|-----------|------------|------------|-----------|-------------|--------------|
| astar_search-h_ignore_preconditions | Problem 1 | 41         | 43         | 170       | 6           | 0.0523106    |
|                                     | Problem 2 | 1450       | 1452       | 13303     | 9           | 5.33969      |
|                                     | Problem 3 | 5040       | 5042       | 44763     | 12          | 20.5908      |
| astar_search-h_pg_levelsum          | Problem 1 | 11         | 13         | 50        | 6           | 0.673669     |
|                                     | Problem 2 | 86         | 88         | 841       | 9           | 58.2366      |
|                                     | Problem 3 | 365        | 367        | 3345      | 12          | 387.304      |
| breadth_first_search-               | Problem 1 | 43         | 56         | 180       | 6           | 0.0424407    |
|                                     | Problem 2 | 3346       | 4612       | 30534     | 9           | 15.8045      |
|                                     | Problem 3 | 14120      | 17673      | 123927    | 12          | 110.124      |
| depth_first_graph_search-           | Problem 1 | 12         | 13         | 48        | 12          | 0.014013     |
|                                     | Problem 2 | 107        | 108        | 959       | 105         | 0.398715     |
|                                     | Problem 3 | 3752       | 3753       | 30138     | 293         | 17.9365      |
| uniform_cost_search-                | Problem 1 | 55         | 57         | 224       | 6           | 0.0514757    |
|                                     | Problem 2 | 4853       | 4855       | 44041     | 9           | 14.3754      |
|                                     | Problem 3 | 18236      | 18238      | 158317    | 12          | 61.8446      |

Listing 1: Plan for Problem 1

```
Load(C1, P1, SFO)
Fly(P1, SFO, JFK)
Load(C2, P2, JFK)
Fly(P2, JFK, SFO)
Unload(C1, P1, JFK)
Unload(C2, P2, SFO)
```

Listing 2: Plan for Problem 2

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Load(C1, P1, SFO)  
Fly(P1, SFO, JFK)  
Load(C2, P2, JFK)  
Fly(P2, JFK, SFO)  
Load(C3, P3, ATL)  
Fly(P3, ATL, SFO)  
Unload(C3, P3, SFO)  
Unload(C2, P2, SFO)  
Unload(C1, P1, JFK)

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Listing 3: Plan for Problem 3

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Load(C2, P2, JFK)  
Fly(P2, JFK, ORD)  
Load(C4, P2, ORD)  
Fly(P2, ORD, SFO)  
Load(C1, P1, SFO)  
Fly(P1, SFO, ATL)  
Load(C3, P1, ATL)  
Fly(P1, ATL, JFK)  
Unload(C4, P2, SFO)  
Unload(C3, P1, JFK)  
Unload(C2, P2, SFO)  
Unload(C1, P1, JFK)

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