

Pouyan Navard

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About Me

PhD hacker turning pixels into intelligence—2D/3D generative AI, CVPR-grade diffusion & 3D vision. PhD wraps May 2025, ready to start June 2025. Actively seeking full-time AI/ML roles where cutting-edge research ships to production.

Education

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| PhD | The Ohio State University (OSU) , Computer Science | Feb 2021 – May 2025 |
| | <ul style="list-style-type: none">• Focus: computer vision• GPA: 3.85 | |
| MSc | The Ohio State University (OSU) , Computer Science | Sept 2021 – Dec 2023 |
| | <ul style="list-style-type: none">• Non-Thesis degree obtained through my PhD, GPA: 3.75 | |
| BSc | University of Isfahan , Computer Vision | Sept 2014 – Sept 2018 |
| | <ul style="list-style-type: none">• Thesis: 3D Reconstruction using Structure from Motion• GPA: 3.60 | |

Publications

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| KnobGen: Controlling the Sophistication of Artwork in Sketch-Based Diffusion Models | March 2025 Nashville, USA |
| Pouyan Navard , Amin Karimi Monsefi, Mengxi Zhou, Wei-Lun Chao, Alper Yilmaz, Rajiv Ramnath | |
| CVPR - AI for Creative Visual Content Generation Editing and Understanding (CVEU) Workshop | |
| SegFormer3D: an Efficient Transformer for 3D Medical Image Segmentation | Feb 2025 Seattle, USA |
| Pouyan Navard , Shehan Perera, Alper Yilmaz | |
| CVPR - Workshop on Domain adaptation, Explainability, Fairness in AI for Medical Image Analysis | |
| A Probabilistic-based Drift Correction Module for Visual Inertial SLAMs | Oct 2024 Las Vegas, USA |
| Pouyan Navard , Alper Yilmaz | |
| The International Archives of the Photogrammetry, Remote Sensing and Spatial Information Sciences | |
| Assessing the effects of georeferencing error in a vertical comparison study of GDEMs | June 2021 |
| Masoud Babadi, Saeed Nadi, Pouyan Navard , Mohammad Moein Sheikholeslami, Mohammad Samiei, Vahid Sadeghi | |
| International Journal of Remote Sensing | |

Experience

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| Path Robotics Inc. , Computer Vision Research Scientist Intern | Columbus, OH Nov 2024 - April 2025 |
| <ul style="list-style-type: none">• Photorealistic image generation of 3D objects using 3D diffusion model• Conditional image generation (text, material, texture map)• Active learning on out-of-distribution samples• World model for autonomous robotics | |
| Photogrammetric Computer Vision Lab (PCVLab) , Graduate Research Assistant | Columbus, OH Feb 2021 – May 2025 |
| <ul style="list-style-type: none">• 3D medical image understanding (segmentation, classification)• 3D image probabilistic distributional reasoning & representation learning• 3D image self-supervised training | |
| Center for Automotive Research , Simultaneous Localization and Mapping (SLAM) team lead | Columbus, OH |

- Leading the Ohio State University's SLAM team at General Motors SAE Autodrive Challenge
- Engineered a SLAM pipeline optimized for narrow FOV LiDARs
- Robust localization and mapping in geometrically constrained environments.

Oct 2022- May 2023

Projects

Fine-grained Material Control for Diffusion-based Image Generation

Path Robotics Inc

- Introduced a *three stage* method for controlling the material during image generation:
- First stage: generate a provisional image with uncontrolled material with text-prompt
- Second stage: generate material hint given the provisional image and target material
- Third stage: using text-material conditioning using ControlNet to generate the foreground object
- Reduced the cost of data collection.

Deep-Neural World Model for Autonomous Robots.

Path Robotics Inc

- Developed end-to-end ML-ops pipeline—automated data processing, PyTorch-Lightning training and Hydra configuration.
- **3x** faster experimentation with the devised streamlined pipeline.
- Multi-modal state representation for robot-learning using Graph Neural Network.

3D Ultrasound Image Understanding.

PCVLab


- 3D ultrasound medical image representation learning robust to extreme noise (motion blur, diffuse reverberation etc)
- Foundational model for multi-modal ultrasound data, ocular (eye) and echocardiogram (heart) 3D image sequence
- Achieved expert-level performance with sensitivity of **98%** percent in detecting the class of interest

Visual SLAM in GPS-Denied and Low-Texture Environments.

PCVLab

- Devised Multivariate Gaussian based probabilistic module for visual inertial navigation methods such as VINS-MONO
- software engineering computer vision pipeline into Augmented Reality (AR) system.

Awards and Honors

- [Robert E. Altenhofen Memorial Scholarship Award](#) 
- Graduate Student Travel Awards

ISPRS, 2022

OSU, 2025

Services

Invited Reviewer: CVPR, ECCV, ICCV, ICLR, AVSS, ACCV, SIBGRAPI

2023-2025

Invited Talk: Intro to Diffusion Probabilistic Models

OSU, 2025

Co-mentorship: Co-mentored along my advisor and collaborated with and lead junior PhD students

PCVLab, 2025

Distributed Parallel Computing: Streamline large scale high performance (multi-gpu) pipeline and configs PCVLab, 2024-2025

Technologies

Technologies: PyTorch, GenAI, TensorFlow, Numpy, Scipy, Hydra, MLOps, Blender, VLM, Diffusion Model

Languages: C++, Python