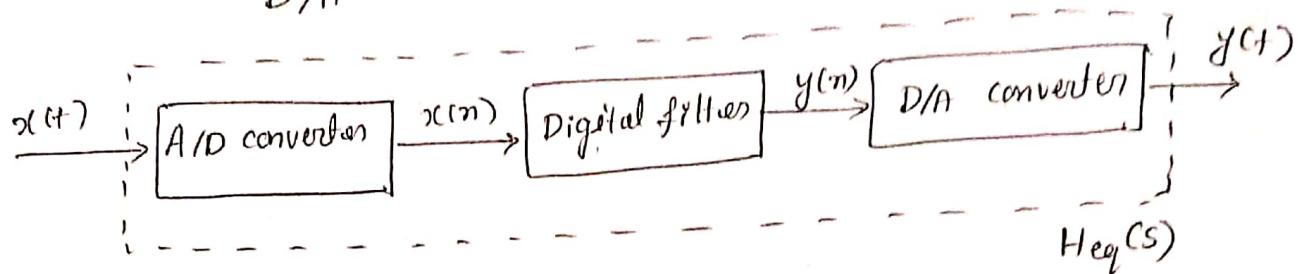


Digital filters

- * IIR / recursive filter
- * The Design of digital IIR filter is largely based on analog filter design techniques.
- * To simulate an analog filter
→ The digital filter is used in A/D - Digital filter D/A



- * $\{A/D - \text{Digital filter} - D/A\} = \underbrace{H_{eq}(S)}_{\hookrightarrow \text{analog filter}}$
- * Digital filter takes $x(n)$ & O/P's $y(n)$ i.e discrete-time sequences
→ Digital filter can be characterized by
 - unit sample response $h(n)$
 - system function $H(z)$ (BT)
 - A difference equation realization

Design procedure of a digital FIR filter

- 1) Selecting a method of transformation of a given analog filter to a digital filter having roughly the same ~~for~~ response.
- 2) Mapping the specifications of the digital FIR filter to equivalent specifications of an analog FIR filter.
- 3) Designing the analog FIR filter according to the mapped specifications.
- 4) Transforming the analog filter to an equivalent digital filter.

Mapping of an analog filter to a digital filter with approximately the same frequency response

- (i) The backward difference method $s = \frac{1-z^{-1}}{\tau}$
- (ii) The bilinear transformation.
- (iii) The impulse invariant transformation
- (iv) The matched -z transformation.

Backward difference Method $s =$

* $\boxed{A/D - H(z) - D/A} = H_{eq}$ \rightarrow analog filter in time domain

* Difference eqⁿ for same

$$\sum_{k=0}^N a_k \frac{d^k y(t)}{dt^k} = \sum_{k=0}^M b_k \frac{d^k x(t)}{dt^k}$$

taking laplace

$$\sum_{k=0}^N a_k s^k y(s) = \sum_{k=0}^M b_k s^k x(s)$$

$$\begin{aligned} H_{eq}(s) &= \frac{Y(s)}{X(s)} \\ &= \frac{\sum_{k=0}^M b_k s^k}{\sum_{k=0}^N a_k s^k} \end{aligned} \quad \rightarrow ①$$

1st order derivative

$$\nabla^{(1)} \{y(n)\} = \frac{[y(n) - y(n-1)]}{T} \quad \xleftrightarrow{zT} \frac{(1-z^{-1})}{T} y(z)$$

higher order = repetition of 1st order derivative.

$$\therefore \nabla^{(K)} \{y(n)\} \xleftrightarrow{zT} \left[\frac{1-z^{-1}}{T} \right]^K y(z)$$

$$\therefore H(z) = \frac{Y(z)}{X(z)}$$

$$= \frac{\sum_{k=0}^M b_k \left[\frac{1-z^{-1}}{\tau} \right]^k}{\sum_{k=0}^M a_k \left[\frac{1-z^{-1}}{\tau} \right]^k} \quad \rightarrow \textcircled{2}$$

by comparing ~~Eq~~ 1 & 2.

$$H(z) = H_a(s) \Big|_{s = \frac{1-z^{-1}}{\tau}}$$

$$s = \frac{1-z^{-1}}{\tau}$$

$$sT = 1 - z^{-1}$$

$$z^{-1} = 1 - sT$$

$$z = \frac{1}{1-sT}$$

$$\text{wkt } s = \sigma + j\omega$$

$$\therefore z = \frac{1}{1-\sigma T - j\omega T}$$

$$|z| = \frac{1}{\sqrt{[(1-\sigma T)^2 + (\omega T)^2]}}$$

OBSERVATION

$$(i) \sigma < 0 \Rightarrow |z| < 1$$

(i) if $\sigma < 0$ \Rightarrow All poles = Negative real parts

(ii) if H_a is stable \Rightarrow All poles will have magnitudes less than 1
ie $H(z)$ poles will have magnitudes less than 1

$$(iii) \text{ if } \sigma = 0$$

$$z = \frac{1}{1-j\omega T}$$

$$z - \frac{1}{2} = \frac{1}{1-j\omega T} - \frac{1}{2} = \frac{(1+j\omega T)}{2(1-j\omega T)}$$

$$|z - \frac{1}{2}| = \frac{1}{2}$$

i.e. $j\omega$ axis of the s -domain is a circle of radius 0.5
at $z = 0.5$ in the z domain

$$\Rightarrow j\omega \neq |z| = 1$$

i.e. $H(\omega)$ will be considerably distorted wrt $H(j\omega)$

\Rightarrow left-half of s -plane is mapped inside the circle.

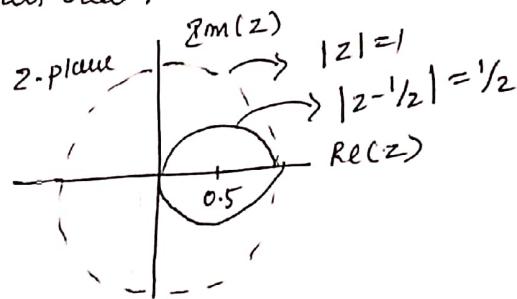
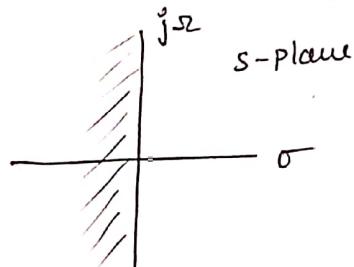
$$|z - 0.5| = 0.5 \text{ in the } z\text{-plane}$$

i.e. Right-half of z -plane at $z = 0.5$

\Rightarrow i.e. Analog Highpass filter cannot be mapped to
Digital HPF \because poles of Digital filter cannot lie
in the correct region.

\Rightarrow Backward difference method does not preserve the shape
of the frequency response ~~especially~~.

\therefore Rarely used in real.



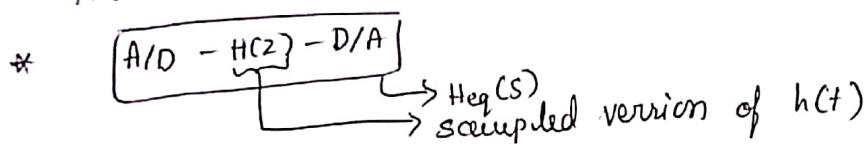
page
 $a_2 + a_3 + a_4$
2 problems

Objective of IIT is to develop an FIR filter TF whose impulse response is sampled version of $H_a(s)$. It preserves channel integrity if T is as small as possible. (3)

Impulse Invariant Transformation (IIT)

- * Impulse response of an analog filter is $h_a(t)$ $f_s \rightarrow$ high.

- * The unit sample response discrete-time filter $H(z)$



$$\begin{aligned} h(n) &= h_a(nT) \\ &= h_a(t) \Big|_{t=nT} \end{aligned}$$

$$H(z) = Z\{h(n)\}$$

Laplace transform $\xrightarrow{\text{Z-Transform}}$

$$Ls \quad e^{zT}$$

$$\Rightarrow H(z) = H(s) \Big|_{s=z}$$

it's short correct form.

$\Rightarrow H(z)$ can be obtained directly from $H_a(s)$ without intervening steps $h_a(t)$ & $h_a(nT)$

- * Analog transfer function with N different poles
S-domain transfer function written in partial fraction expansion form

$$H_a(s) = \sum_{i=1}^N \frac{C_i}{s-s_i} \longrightarrow ①$$

$$* \text{unit impulse response} \cdot h_a(t) = \sum_{i=1}^N C_i e^{s_i t}$$

$$\text{Sampled response} \cdot h_a(nT) = h(n) = \sum_{i=1}^N C_i e^{s_i nT}$$

$$\begin{aligned} * H(z) = Z\{h(n)\} &= Z \left\{ \sum_{i=1}^N C_i e^{s_i nT} \right\} \\ &= \sum_{n=0}^{\infty} h(n) z^{-n} \\ &= \sum_{n=0}^{\infty} h(n) z^{-n} = \sum_{n=0}^{\infty} \sum_{i=1}^N C_i e^{s_i nT} z^{-n} \end{aligned}$$

filter is assumed to be causal.

$$= \sum_{i=1}^N C_i \sum_{n=0}^{\infty} [e^{s_i T} z^{-1}]^n$$

$$= \sum_{i=1}^N C_i \frac{1}{1 - e^{s_i T} z^{-1}} \quad \rightarrow \textcircled{2}$$

By comparing \textcircled{1} & \textcircled{2}

$$\frac{1}{s - s_i} \Rightarrow \frac{1}{1 - e^{s_i T} z^{-1}} \quad \textcircled{3} \quad \frac{z}{z - e^{s_i T}}$$

OBSERVATION: (i) Analog pole at $s = s_i$ is mapped to a digital pole at $z_i = e^{s_i T}$

* Transformed $H(z)$ properties

(i) order is same as that of $H_a(s)$

(ii) poles are mapped according to

$$s_i \xrightarrow{T \mapsto} z_i = e^{s_i T}, \quad 1 \leq i \leq N$$

$$\text{i.e. } z = e^{sT} \quad (\text{digital} \Leftrightarrow \text{analog poles relation})$$

$$\text{WKT } z = re^{j\omega}$$

$$s = \sigma + j\omega$$

$$\therefore re^{j\omega} = e^{(\sigma+j\omega)T} = e^{\sigma T} e^{j\omega T}$$

$$\begin{aligned} r &= e^{\sigma T} \\ \omega &= e^{j\omega T} \end{aligned} \Rightarrow \boxed{\omega = \omega T}$$

- (a) $\sigma < 0 \Rightarrow 0 < \omega < 1$ L+ poles mapped inside the unit circle
 (b) $\sigma > 0 \Rightarrow \omega > 1$ R+ poles mapped outside the unit circle.
 (c) $\sigma = 0 \Rightarrow \omega = 1$ on unit circle. (jω axis = unit circle)

i.e. A stable analog filter $H_a(s)$ is transformed to a stable digital filter $H(z)$

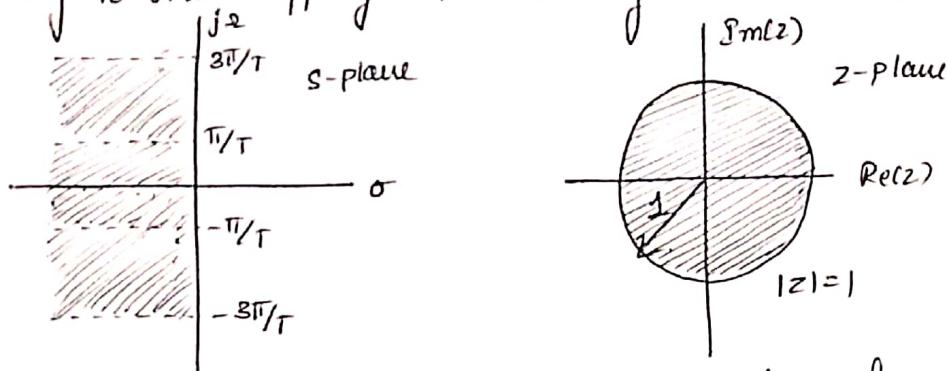
$$\omega = \omega T \Rightarrow \omega = \frac{\omega}{T} \Rightarrow -\frac{\pi}{T} \leq \omega \leq \frac{\pi}{T} \quad \textcircled{4} \quad (2q-1)\frac{\pi}{T} \leq \omega \leq (2q+1)\frac{\pi}{T}$$

$$-\frac{\pi}{T} \leq \omega \leq \frac{\pi}{T}$$

$$\Rightarrow (2q-1)\frac{\pi}{T} \leq \omega \leq (2q+1)\frac{\pi}{T} \Rightarrow q \text{ integer} \Rightarrow \omega \text{ to } \omega \text{ in many to one.}$$

(4)

\Rightarrow Many to one mapping ie aliasing due to sampling.



The impulse invariant transform from S-plane to the Z-plane

- Imaginary axis maps to the unit circle
- Strip $\frac{2\pi}{T}$ maps to the disk.

(iii) $H(\omega)$ & $H(z)$ are related by Sampling theorem.

\downarrow \downarrow

freq response of freq response of
digital filter analog filter.

$$H(z) = \frac{1}{T} \sum_{k=-\infty}^{\infty} h\left(\frac{\omega - 2\pi k}{T}\right)$$

Impulse Invariant Transformation :-

$$\frac{1}{(s+s_i^*)^m} \rightarrow \frac{(-1)^{m-1}}{(m-1)!} \frac{d^{m-1}}{ds_i^{m-1}} \frac{1}{1 - e^{-s_i T} z^{-1}}$$

$$\frac{s+a}{(s+a)^2 + b^2} \rightarrow \frac{1 - e^{-at} (\cos bt) z^{-1}}{1 - 2e^{-at} (\cos bt) z^{-1} + e^{-2at} z^{-2}}$$

$$\frac{b}{(s+a)^2 + b^2} \rightarrow \frac{e^{-at} (\sin bt) z^{-1}}{1 - 2e^{-at} (\cos bt) z^{-1} + e^{-2at} z^{-2}}$$

(5)

- * The analog transfer function, $H(s) = \frac{2}{s^2 + 3s + 2}$, determine $H(z)$ using inverse invariant transformation if (a) $T=1$ seconds
 (b) $T=0.1$ seconds

Soln

$$H(s) = \frac{2}{s^2 + 3s + 2} = \frac{2}{(s+1)(s+2)} = \frac{A}{s+1} + \frac{B}{s+2}$$

$$A = \left. \frac{2}{(s+1)(s+2)} \times (s+1) \right|_{s=-1} = \frac{+2}{-1+2} = \underline{\underline{2}}$$

$$B = \left. \frac{2}{(s+1)(s+2)} \times (s+2) \right|_{s=-2} = \frac{2}{-2+1} = \underline{\underline{-2}}$$

$$H(s) = \frac{2}{s+1} + \frac{-2}{s+2}$$

Wkt Impulse invariant transformation $\frac{A_i}{s+p_i} \rightarrow \frac{A_i}{1-e^{-p_i T} z^{-1}}$

by applying PIT on $H(s)$, $p_1=1$, $p_2=2$

$$H(z) = \frac{2}{1-e^{-1T} z^{-1}} + \frac{-2}{1-e^{-2T} z^{-1}}$$

(a) $T=1$ seconds

$$\begin{aligned} H(z) &= \frac{2}{1-e^{-1} z^{-1}} + \frac{-2}{1-e^{-2} z^{-1}} = \frac{2}{1-0.3679 z^{-1}} + \frac{-2}{1-0.1353 z^{-1}} \\ &= \frac{2(1-0.1353 z^{-1}) - 2(1-0.3679 z^{-1})}{(1-0.3679 z^{-1})(1-0.1353 z^{-1})} \\ &= \frac{2 - 0.2706 z^{-1} - 2 + 0.7358 z^{-1}}{1-0.1353 z^{-1}-0.3679 z^{-1}+0.0498 z^{-2}} = \frac{0.4652 z^{-1}}{1-0.5082 z^{-1}+0.0498 z^{-2}} \\ &= \frac{0.4652 z^{-1}}{z^{-2}(z^2 - 0.5082 z + 0.0498)} \\ &= \frac{0.4652 z}{z^2 - 0.5082 z + 0.0498} \end{aligned}$$

(b) $T=0.1$ seconds ($T<1$)

$$\begin{aligned} H(z) &= \frac{2}{1-e^{-0.1} z^{-1}} + \frac{-2}{1-e^{-0.2} z^{-1}} = \frac{2}{1-0.9048 z^{-1}} + \frac{-2}{1-0.8187 z^{-1}} \\ &= \frac{2(1-0.8187 z^{-1}) - 2(1-0.9048 z^{-1})}{(1-0.9048 z^{-1})(1-0.8187 z^{-1})} \end{aligned}$$

$$\begin{aligned}
 &= \frac{-1.6374 z^{-1} - 2 + 1.8096 z^{-1}}{1 - 0.8187 z^{-1} - 0.9048 z^{-1} + 0.7408 z^{-2}} \\
 &= \frac{0.1722 z^{-1}}{1 - 1.7235 z^{-1} + 0.7408 z^{-2}} \\
 &= \frac{0.1722 z}{z^2 - 1.7235 z + 0.7408}
 \end{aligned}$$

⑥ If $T < 1$ i.e. compute magnitude normalized transfer function $H_N(z)$.

$$\begin{aligned}
 H_N(z) &= T \times H(z) \\
 &= 0.1 \times H(z) = 0.1 \times \frac{0.1722 z^{-1}}{1 - 1.7235 z^{-1} + 0.7408 z^{-2}} \\
 &= \frac{0.01722 z^{-1}}{1 - 1.7235 z^{-1} + 0.7408 z^{-2}} \\
 &= 0.1 \times H(z) = 0.1 \times \frac{0.1722 z}{z^2 - 1.7235 z + 0.7408} \\
 &= \frac{0.01722 z}{z^2 - 1.7235 z + 0.7408}
 \end{aligned}$$

⑦ Convert the analog filter with system transfer function,

$$H(s) = \frac{s+0.1}{(s+0.1)^2 + 9}$$

into a digital IIR filter by means of the PPM.

Solⁿ

$$H(s) = \frac{s+0.1}{(s+0.1)^2 + 9} = \frac{s+0.1}{(s+0.1)^2 + 8^2}$$

$$\text{Wkt } \frac{(s+a)}{(s+a)^2 + b^2} \Rightarrow \frac{1 - e^{-aT} (\cos bT) z^{-1}}{1 - 2e^{-aT} (\cos bT) z^{-1} + e^{-2aT} z^{-2}}$$

$$H(z) = \frac{1 - e^{-0.1T} (\cos 3T) z^{-1}}{1 - 2e^{-0.1T} (\cos 3T) z^{-1} + e^{-2 \times 0.1T} z^{-2}}$$

$$\begin{aligned}
 T = 1 \Rightarrow H(z) &= \frac{1 - e^{-0.1} (\cos 3) z^{-1}}{1 - 2e^{-0.1} (\cos 3) z^{-1} + e^{-0.2} z^{-2}} \\
 &= \frac{1 + 0.8958 z^{-1}}{1 + 1.7916 z^{-1} + 0.8187 z^{-2}}
 \end{aligned}$$

$$H(z) = \frac{z^2 + 0.8958 z}{z^2 + 1.7916 z + 0.8187}$$

Bilinear Transformation

It is a conformal mapping that transforms imaginary axis of S-plane into unit circle in z-plane only once, thus avoiding aliasing. (6)

- * used for transforming an analog filter to a digital filter
- * P+ uses trapezoidal rule for integrating a continuous time function.

- * P+ is defined by $S = \frac{2}{T} \left[\frac{1 - z^{-1}}{1 + z^{-1}} \right]$

Let considering the derivative (1st order differential eqn of an analog sys)

$$\frac{dy(t)}{dt} = x(t)$$

taking LT

$$S Y(s) = X(s) \rightarrow ①$$

- * $y(t)$ with the limits $(n-1)T$ & nT

T = Sampling period.

$$\therefore \int_{(n-1)T}^{nT} \frac{dy(t)}{dt} dt = \int_{(n-1)T}^{nT} x(t) dt$$

$$y(nT) - y[(n-1)T] = \int_{(n-1)T}^{nT} x(t) dt$$

$$\int_{(n-1)T}^{nT} x(t) dt = \left[\frac{x(nT) + x[(n-1)T]}{2} \right] T$$

$$y(nT) - y[(n-1)T] = \left[\frac{x(nT) + x[(n-1)T]}{2} \right] T$$

$$y(n) - y(n-1) = \left[\frac{x(n) + x(n-1)}{2} \right] T$$

Taking z-transform of the above eqn

$$Y(z) - z^{-1}Y(z) = \left[\frac{x(z) + z^{-1}x(z)}{2} \right] T$$

$$Y(z)(1 - z^{-1}) = \left[\frac{1 + z^{-1}}{2} \right] T x(z)$$

$$\frac{x(z)}{Y(z)} = \frac{2}{T} \left[\frac{1 - z^{-1}}{1 + z^{-1}} \right] \rightarrow ②$$

by trapezoidal rule. It states that if T is small the area (integral) can be approximated by the mean height of $x(t)$ b/w the 2 limits & then multiplying by the width.

by comparing eqn ① & ②

$$S = \frac{2}{T} \left[\frac{1 - z^{-1}}{1 + z^{-1}} \right] \rightarrow ③$$

My transformation from Z to S is

$$\frac{ST}{2} = \frac{1 - z^{-1}}{1 + z^{-1}}$$

$$\frac{ST}{2} + z^{-1} \frac{ST}{2} = 1 - z^{-1}$$

$$z^{-1} + z^{-1} \frac{ST}{2} = 1 - \frac{ST}{2}$$

$$z^{-1} \left(1 + \frac{ST}{2} \right) = \cancel{1 - \frac{ST}{2}} \quad 1 - \frac{ST}{2}$$

$$z^{-1} = \frac{1 - \frac{ST}{2}}{1 + \frac{ST}{2}}$$

$$z = \boxed{\frac{1 + \frac{ST}{2}}{s - \frac{ST}{2}}} \rightarrow ④$$

$$S = \frac{2}{T} \left[\frac{1 - z^{-1}}{1 + z^{-1}} \right]$$

$$S = \frac{2}{T} \left[\frac{z-1}{z+1} \right]$$

Relation b/w Analog & digital filter poles
in Bilinear transformation.

$$\text{WKT } S = \sigma + j\omega$$

$$Z = r e^{j\omega}$$

$$\therefore \sigma + j\omega = \frac{2}{T} \left[\frac{r e^{j\omega} - 1}{r e^{j\omega} + 1} \right] = \frac{2}{T} \left[\frac{r(\cos\omega + j\sin\omega) - 1}{r(\cos\omega + j\sin\omega) + 1} \right]$$

$$= \frac{2}{T} \left[\frac{(r\cos\omega - 1) + j r\sin\omega}{(r\cos\omega + 1) + j r\sin\omega} \right]$$

$$= \frac{2}{T} \frac{(r\cos\omega - 1) + j r\sin\omega}{(r\cos\omega + 1) + j r\sin\omega} \times \frac{(r\cos\omega + 1) + j r\sin\omega}{(r\cos\omega + 1) + j r\sin\omega}$$

by Rationalizing

$$= \frac{2}{T} \frac{r^2 (\cos^2\omega + \sin^2\omega) - 1 + j 2r\sin\omega}{r^2 (\cos^2\omega + \sin^2\omega) + 1 + 2r\cos\omega}$$

$$= \frac{2}{T} \left[\frac{r^2 - 1 + j 2r\sin\omega}{r^2 + 1 + 2r\cos\omega} \right]$$

Separate real & imaginary.

(7)

$$\sigma + j\omega = \frac{2}{T} \left[\frac{\gamma^2 - 1}{1 + \gamma^2 + 2\gamma \cos \omega} + j \frac{2\gamma \sin \omega}{1 + \gamma^2 + 2\gamma \cos \omega} \right]$$

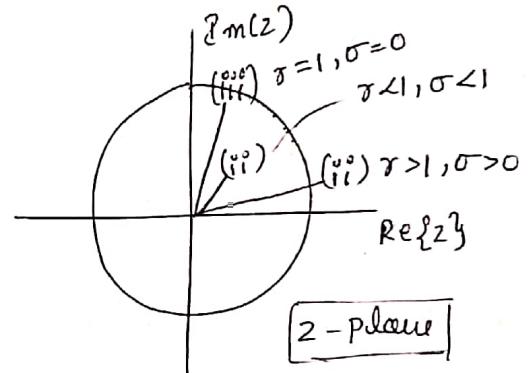
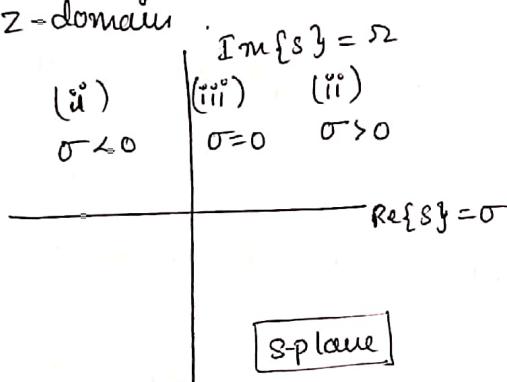
$$\therefore \sigma = \frac{2}{T} \left[\frac{\gamma^2 - 1}{1 + \gamma^2 + 2\gamma \cos \omega} \right]$$

$$\omega = \frac{2}{T} \left[\frac{2\gamma \sin \omega}{1 + \gamma^2 + 2\gamma \cos \omega} \right]$$

(i) if $\gamma < 1 \Rightarrow \sigma < 0$ ie LHS of the S-plane is mapped inside the circle $|z| = 1$

(ii) if $\gamma > 1 \Rightarrow \sigma > 0$ ie RHS of the S-plane is mapped outside the circle $|z| = 1$

(iii) if $\gamma = 1$ we get $\sigma = 0$ ie the imaginary axis in the S-domain is mapped to the circle of unit radius at $z = 0$ in the Z-domain.



OBSERVATION :

\Rightarrow Bilinear transformation preserves the stability of the transformed filter.

$$\Rightarrow \gamma = 1 \Rightarrow \sigma = 0$$

$$\omega = \frac{2}{T} \left[\frac{2 \sin \omega}{1 + 1 + 2 \cos \omega} \right]$$

$$= \frac{2}{T} \left[\frac{2 \sin \omega}{1 + \cos \omega} \right] = \frac{2}{T} \left[\frac{2 \sin \omega / 2 \cos \omega / 2}{2 \cos^2 \omega / 2} \right]$$

$$\boxed{\omega = \frac{2}{T} \tan \frac{\omega}{2}}$$

analog frequency

$$\tan^{-1} \left(\frac{\omega T}{2} \right) = \omega / 2$$

$$\boxed{\therefore \omega = 2 \tan^{-1} \frac{\omega T}{2}}$$

digital domain frequency.

- * Digital-domain frequency ω is warped with respect to the analog frequency s_2
 - warping function $\Rightarrow 2 \tan^{-1} \left(\frac{s_2 T}{2} \right)$
 - analog frequencies $s_2 = \pm \infty$ are mapped to digital frequencies $\omega = \pm \pi$
 - \therefore frequency mapping is not aliased.
ie Relationship b/w s_2 & ω is one-to-one
 - \therefore Bilinear transformation is adequate for all filter types.

- * Frequency warping.
 - \Rightarrow consider LPF having ripples in both the bands.
 - \Rightarrow The frequency warping introduced by the bilinear transformation.
 - \therefore necessary to prewarp the specifications of the analog filter.

- * Design a LP Digital filter with passband & stopband edge frequencies w_p & w_s .
 - convert these frequencies to corresponding analog-domain band-edge frequencies s_p^1 & s_s^1
$$s_p^1 = \frac{2}{T} \tan \left(\frac{\omega_p}{2} \right)$$

$$s_s^1 = \frac{2}{T} \tan \left(\frac{\omega_s}{2} \right)$$
 - using s_p^1 & s_s^1 design the analog filter $H(s)$
 - obtain the required Digital lowpass filter by using the bilinear transformation on the analog filter.

(iii) $H(s) \rightarrow H(z)$ using $s = \frac{2}{T} \left[\frac{1-z^{-1}}{1+z^{-1}} \right]$ with $T=1\text{sec}$

- ~~(*)~~
- NOTE : (i) The value of T used is immaterial as long as it is same in both (analog & digital) ($T=1\text{sec}$)
- (ii) Prewarping is done in the beginning of the design,
Bilinear transformation is performed in the end.

Warping & Prewarping

→ Relation b/w analog frequency (ω) & digital frequency (ω)

$$\omega = \frac{2}{T} \tan \frac{\omega_2}{2}$$

⇒ for smaller values of ω , exist linear relationship b/w ω & ω_2

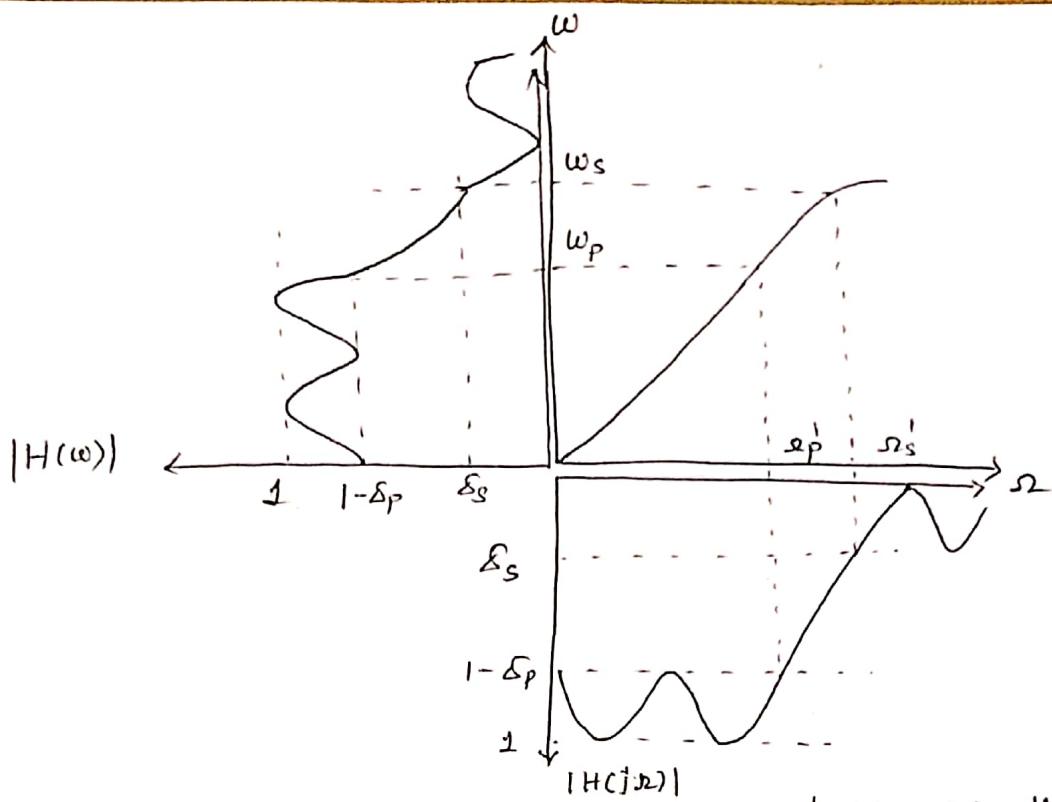
⇒ for large values of ω , the relationship is non linear
" this non-linearity introduces distortion in the frequency axis, this is known as warping effect"

⇒ This effect compresses the magnitude & phase response at high frequencies.

→ Non-linear compression at high frequencies can be compensated

⇒ when the desired magnitude response is piece-wise constant over frequency, can be compensated by introducing a suitable prescaling (⑦) prewarping the critical frequencies by using the formula

$$\omega = \frac{2}{T} \tan \frac{\omega_2}{2}$$



mapping of an analog LPF to digital LPF via the Bilinear Transformation

- ④ A digital LPF is required to meet the following specifications
- (i) monotonic passband & stopband.
 - (ii) -3.01 dB cutoff frequency of 0.5π rad.
 - (iii) Stopband attenuation of atleast 15 dB at 0.75π rad.
- Find the system function $H(z)$ & the difference equation realization. Verify the design by checking for the passband & stopband specifications.

SOL

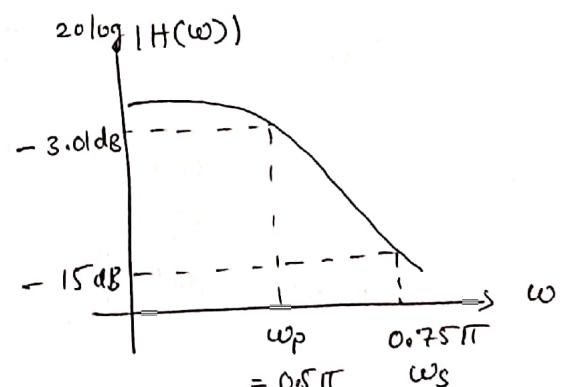
Step 1 : Prework

$$\omega_p = 0.5\pi \text{ rad} \quad \omega_s = 0.75\pi \text{ rad}$$

$$T = 1 \text{ sec}$$

$$\Omega_p^1 = \frac{2}{T} \tan\left(\frac{\omega_p}{2}\right) = 2 \tan\left(\frac{0.5\pi}{2}\right) = 2 \text{ rad/s}$$

$$\Omega_s^1 = \frac{2}{T} \tan\left(\frac{\omega_s}{2}\right) = 2 \tan\left(\frac{0.75\pi}{2}\right) = 4.8282 \text{ rad/s}$$



Step - 2 : Analog filter design [Butterworth]

$$\begin{aligned}
 N &= \log \left[\frac{\frac{10^{-0.1 A_{\text{pinkdB}}}}{10^{-0.1 A_{\text{in dB}}}} - 1}{2 \log \frac{\omega_p}{\omega_s}} \right] \\
 &= \frac{\log \left[\frac{10^{0.1 \times -3.01}}{10^{0.1 \times -15}} - 1 \right]}{2 \log \left[\frac{2}{4.8282} \right]} = \frac{\log \left[\frac{0.9998}{30.62} \right]}{2 \log \left(\frac{2}{4.8282} \right)} \\
 &= 1.9418 \\
 &\approx 2 \quad \boxed{\therefore N = 2}
 \end{aligned}$$

$$H_2(s) = \frac{1}{s^2 + \sqrt{2}s + 1}$$

$$\omega_n = \omega_m \omega_p = 2.000 \text{ rad/s}$$

$$H_a(s) = H_2(s) \Big|_{s \rightarrow \frac{s}{\omega_n}} = \frac{s}{2}$$

$$(7) \quad \omega_c = \frac{\omega_p}{\left[10^{-0.1 A_{\text{pinkdB}}} - 1 \right]^{1/2N}}$$

$$= \frac{1}{\left(\frac{s}{2}\right)^2 + \sqrt{2}\left(\frac{s}{2}\right) + 1}$$

$$H_a(s) = \frac{4}{s^2 + 2\sqrt{2}s + 4}$$

Step - 3 : obtain $H(z)$ by bilinear transformation ($T=1$)

$$\begin{aligned}
 H(z) &= H_a(s) \Big|_{s \rightarrow \frac{2}{T} \left[\frac{1-z^{-1}}{1+z^{-1}} \right]} \\
 &= \frac{4}{\left(2 \left[\frac{1-z^{-1}}{1+z^{-1}} \right] \right)^2 + 2\sqrt{2} \left(2 \left[\frac{1-z^{-1}}{1+z^{-1}} \right] \right) + 4} \\
 &= \frac{(1+z^{-1})^2}{3.4142 + 0.5858 z^{-2}}
 \end{aligned}$$

(9)

$$\text{Verification : } z = \sigma e^{j\omega} \quad \tau = 1$$

$$H(z) = H(e^{j\omega}) = H(\omega) = \frac{(1 + e^{-j\omega})^2}{3.4142 + 0.5858 e^{-j2\omega}}$$

$$= \frac{(1 + \cos \omega - j \sin \omega)^2}{3.4142 + 0.5858 \cos 2\omega - j 0.5858 \sin 2\omega}$$

$$|H(z)| = \frac{(1 + \cos \omega)^2 + \sin^2 \omega}{\sqrt{(0.5858 \cos 2\omega + 3.4142)^2 + (0.5858 \sin 2\omega)^2}}$$

$$\omega = 0.5\pi$$

- (10)
- * Convert the analog filter with system function $H(s)$ into digital filter using bilinear transformation $H(s) = \frac{s+0.3}{(s+0.3)^2 + 16}$, $T = 0.5$

$$\underline{S_0[10]} \quad H(s) = \frac{s+0.3}{(s+0.3)^2 + 16} = \frac{s+0.3}{s^2 + 0.6s + 16.09}$$

$$= \frac{s+0.3}{s^2 + 0.6s + 16.09}$$

Bilinear transformation to get $H(z)$ from $H(s)$

$$s = \frac{2}{T} \frac{1-z^{-1}}{1+z^{-1}}$$

$$H(z) = \frac{2/T \frac{1-z^{-1}}{1+z^{-1}} + 0.3}{\left(\frac{2}{T} \left[\frac{1-z^{-1}}{1+z^{-1}}\right]\right)^2 + 0.6 \left(\frac{2(1-z^{-1})}{T(1+z^{-1})}\right) + 16.09}$$

$$= \frac{2/T \left(\frac{1-z^{-1}}{1+z^{-1}}\right) + 0.3}{\frac{4(1-z^{-1})^2}{T^2(1+z^{-1})^2} + \frac{1.2 \left[1-z^{-1}\right]}{T(1+z^{-1})} + 16.09}$$

$$= \frac{\frac{2(1-z^{-1}) + 0.3T(1+z^{-1})}{T(1+z^{-1})}}{4(1-z^{-1})^2 + 1.2T(1-z^{-1})T(1+z^{-1}) + 16.09T^2(1+z^{-1})}$$

$$= \frac{\left[2(1-z^{-1}) + 0.3T(1+z^{-1})\right] (T(1+z^{-1}))}{4(1-z^{-1})^2 + 1.2T(1-z^{-2}) + 16.09T^2(1+z^{-1})}$$

$$\boxed{T = 0.5}$$

$$H(z) = \frac{\left[2(1-z^{-1}) + 0.3 \times 0.5(1+z^{-1})\right] (0.5(1+z^{-1}))}{4(1-z^{-1})^2 + 1.2 \times 0.5(1-z^{-2}) + 16.09 (0.5)^2 (1-z^{-1})}$$

$$= \frac{1(1-z^{-1})(1+z^{-1}) + 0.075(1+z^{-1})(1+z^{-1})}{4(1-z^{-1}+z^{-2}) + 0.6(1-z^{-2}) + 4.0225(1+2z^{-1}+z^{-2})}$$

$$= \frac{1-z^{-1}+z^{-1}-z^{-2} + 0.075(1+2z^{-1}+z^{-2})}{4-8z^{-1}+4z^{-2}+0.6-0.6z^{-2}+4.0255+8.0450z^{-1}+4.0225z^{-2}}$$

$$= \frac{1.075 + 0.15z^{-1} - 0.925z^{-2}}{8.6225 + 0.045z^{-1} + 7.4225z^{-2}}$$

$$= \frac{\frac{1.075}{8.6225} + \frac{0.15}{8.6225}z^{-1} - \frac{0.925}{8.6225}z^{-2}}{1 + \frac{0.045}{8.6225}z^{-1} - \frac{7.4225}{8.6225}z^{-2}}$$

$$H(z) = \frac{0.1247 + 0.0174z^{-1} - 0.1073z^{-2}}{1 + 0.0052z^{-1} + 0.8608z^{-2}}$$

$$H(z) = \frac{0.1247z^2 + 0.0174z - 0.1073}{z^2 + 0.0052z + 0.8608}$$

(Q1)

* Design a Butterworth digital FIR lowpass filter using impulse invariant transformation by taking $T = 1$ second, to satisfy the following specifications.

$$0.707 \leq |H(e^{j\omega})| \leq 1.0 ; \text{ for } 0 \leq \omega \leq 0.3\pi$$

$$|H(e^{j\omega})| \leq 0.2 ; \text{ for } 0.75\pi \leq \omega \leq \pi$$

Sol:

$$\omega_p = 0.3\pi \text{ rad/samples}$$

$$\omega_s = 0.75\pi \text{ rad/samples}$$

$$A_p = 0.707$$

$$A_s = 0.2$$

$T = 1$ second (Sampling time period)

for Impulse Invariant transformation.

$$\omega_p = \frac{\omega_p}{T} = \frac{0.3\pi}{1} = 0.9425 \text{ rad/second}$$

$$\omega_s = \frac{\omega_s}{T} = \frac{0.75\pi}{1} = 2.3562 \text{ rad/second}$$

$$N = \frac{\log \left[\frac{1/A_s^2 - 1}{1/A_p^2 - 1} \right]}{2 \log \left(\frac{\omega_s}{\omega_p} \right)} = \frac{\log \left[\frac{1/0.2^2 - 1}{1/0.707^2 - 1} \right]}{2 \log \left(\frac{0.9425}{2.3562} \right)} = \underline{\underline{1.7339}}$$

i.e $\boxed{N = 2}$

WKT

$$H(s) = \frac{1}{s^2 + 1.4142s + 1}$$

$$K = \frac{N}{2} = \frac{2}{2} = 1$$

$$= \frac{A}{2} = 2, 1$$

★ Design a Butterworth digital IIR lowpass filter using bilinear transformation by taking $T = 0.1$ second, to satisfy the following specifications.

Passband ripple ≤ 4.436 dB

Stop -1dB attenuation ≥ 20 dB

$$\omega_p = 0.35\pi \text{ rad/samples}$$

$$\omega_s = 0.7\pi \text{ rad/sample}$$

Soln for bilinear transformation

$$\omega_p = \frac{2}{T} \tan \left(\frac{\omega_p}{2} \right)$$

$$= \frac{2}{0.1} \tan \left(\frac{0.35\pi}{2} \right) = \frac{2}{0.1} \tan 0.35\pi$$

$$= 12.2560 \text{ rad/second}$$

$$\omega_s = \frac{2}{T} \tan \left(\frac{\omega_s}{2} \right) = \frac{2}{0.1} \tan \left(\frac{0.7\pi}{2} \right) = 39.2522 \text{ rad/second.}$$

$$N = \frac{\log \left[\frac{10^{-0.1 \times -4.436}}{10^{-0.1 \times -20}} - 1 \right]}{2 \log \frac{\omega_s}{\omega_p}} = \frac{\log \left[\frac{10^{-0.1 \times -4.436}}{10^{-0.1 \times -20}} - 1 \right]}{2 \log \left(\frac{39.2522}{12.2560} \right)} = 1.7267 = 2$$

ie N = 2

$$\therefore H(s) = \frac{1}{s^2 + 1.4142s + 1}$$

$$H(s) \Big|_{s=s/\omega_c} \Rightarrow \frac{\omega_s = \omega_p}{\left[10^{-0.1 \times -4.436} - 1 \right]^{1/2} N} = \omega_c = \frac{39.2522}{\left[10^{-0.1 \times -20} - 1 \right]^{1/4}} = 12.4439 \text{ rad/sec}$$

$$H(s) \Big|_{s \rightarrow \frac{s}{12.4439}} = \frac{1}{\left(\frac{s}{12.4439} \right)^2 + 1.4142 \left(\frac{s}{12.4439} \right) + 1}$$

$$= \frac{154.8506 (112.6769)}{s^2 + 17.5982s + 154.8506}$$

$$= \frac{s^2 + 15.0115s + 112.6769}{s^2 + 17.5982s + 154.8506}$$