Bradley Seamons

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Education

UC BERKELEY, Berkeley, CA (August 2017 - May 2021)

Mechanical Engineering Major, Electrical Engineering and Computer Science Minor - 3.3 GPA

Relevant Courses: Thermodynamics, Solid Mechanics, Manufacturing and Tolerancing, Orthopedic Biomechanics, Dynamic Systems and Feedback, Data Structures and Algorithms, Electronics for the Internet of Things, Fluid Mechanics, Dynamics

Clubs: Hispanic Engineers and Scientists, EnableTech, Space Enterprises at Berkeley

Skills and Abilities

Solidworks, Fusion 360, MATLAB, AutoCAD, Java, JavaScript, HTML, CSS, Python, C++, Arduino, C, PLC, Node.js

Work Experience

Hardware Engineering Intern, General Motors (Summer 2020)- Warren, MI

- Worked on vision systems used in lane-keep assist technology.
  - Standardized camera software used in testing to allow for easy access to camera data.
  - Developed algorithm to determine where lane edge is based off road reflectors.
  - Implemented ladder logic for car response to road lane markers disappearing.
  - Troubleshot cameras causing inconsistent results in testing.
- Led a gear study to help the company improve quality of pinions used in 2 transmissions being produced.
  - Wrote PLC programs to automate measurement of key dimensions on parts allowing operators to run multiple parts.
  - Wrote a Python script to extract data from system logs and produce part summary produced each shift.
  - Developed internal Java Agent framework utilized across the company testing machines.
- Volunteered to assist at an assembly plant for a week.
  - Helped assemble over 750 vehicles by operating the station where the car chassis and frame are bolted together.

Software Engineering Intern, Phoenix Deventures (Summer 2019)- Morgan Hill, CA

- Wrote a program in C to automate testing of needles on the company tensile testing machine.
  - Reduced the need for human supervision since the only manual part of the test is swapping out the needle.
- Developed the algorithm that controls the robots used to package company parts produced in company clean rooms.
  - Implemented logic resulting in a increase in output of 10% more parts per day
- Wrote a Python script that automates the creation of Engineering Change Order reports for new company parts.
  - Distributed program to company computers to standardize the report format.

Tutor, UC Berkeley Engineering Center (March 2019-Present)- Berkeley, CA

- Tutored students one on one in Calculus, Physics, and Mechanical Engineering classes.
- Adapted to working remotely during COVID-19 pandemic by moving tutoring online to Google Hangouts.

Projects

JARL- Just Another Robotic Limb

- Used Fusion 360 to design the 3 axis prosthetic arm that can be operated by a quadriplegic patient.
- Utilized MATLAB optimization tools to optimize reinforcements needed in parts.
- Wrote Arduino code that can move fingers to close around differently shaped objects.
- Developed the Android app that runs on takes user input and sends commands to Arduino on arm.

Item-Eyes

- Developed user interface for Item-Eyes app, an app that allows users to keep track of receipts.
- Used Ionic and Cordova with the Node.js platform to develop a web based app using JavaScript, HTML, and CSS.

Tablut

- Used Java to implement the Tablut game, a chess-like board game.
- Developed an AI that found moves using the mini-max algorithm, and was able to quickly force a win in 4 moves if possible due to effective alpha-beta pruning.

Gitlet

- Developed a clone of git with Java.
- Used serialization to store needed data to maintain state of git repository between commands.

Leadership

Enable Tech Board Member (2018-Present)

- Mentored new members in Arduino software and hardware.
- Met with a quadripleic patient once a month for feedback on the progressing design of JARL.