Python Path Finding with Breadth First Search

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Surabaya, date, 30 March 2019

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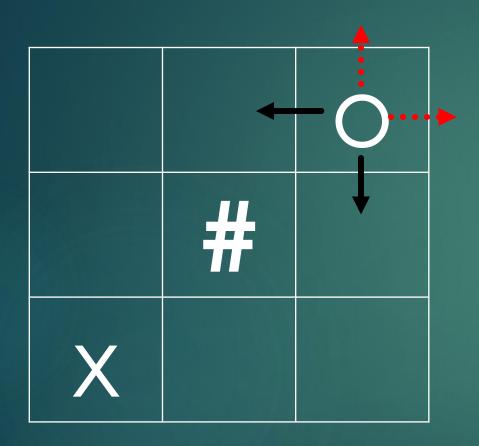
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Theorem and Abstraction

- Breadth-first search (BFS) is an algorithm for traversing or searching <u>tree</u> or <u>graph</u> data structures. It starts at the tree root (or some arbitrary node of a graph, sometimes referred to as a 'search key'), and explores all of the neighbor nodes at the present depth prior to moving on to the nodes at the next depth level.
- ▶ It uses the opposite strategy as depth-first search, which instead explores the highest-depth nodes first before being forced to backtrack and expand shallower nodes.
- ▶ BFS and its application in finding connected components of graphs were invented in 1945 by Konrad Zuse, in his (rejected) Ph.D. thesis on the <u>Plankalkül</u> programming language, but this was not published until 1972. It was reinvented in 1959 by Edward F. Moore, who used it to find the shortest path out of a maze and later developed by C. Y. Lee into a wire routing algorithm (published 1961).
- Source : https://en.wikipedia.org/wiki/Breadth-first_search

Explanation and Analysis

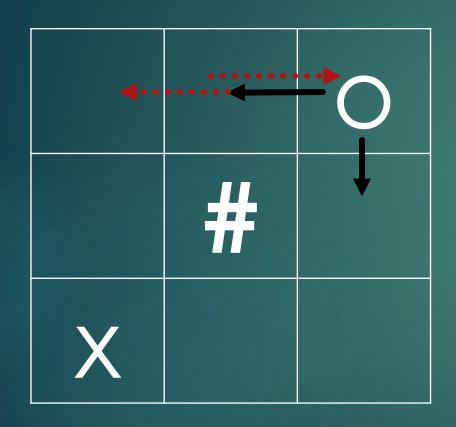


For example we drawing 3x3 grid, and let we say # is an obstacle, 'o' is starting point and 'x' is the goal. What we'll do is create all the possibility moves.

First move, the valid moves we can do is we go to the left or we go down.

Because if we try to go right or up, those are not valid moves so we're not gonna add them to the queue. So when we're checking if we reach this destination and we're only checking the valid moves there's no point to checking moves outside of the range

Explanation and Analysis



So we have two possible moves, left and down. So in our queue we're gonna add left and down:

[L,D]

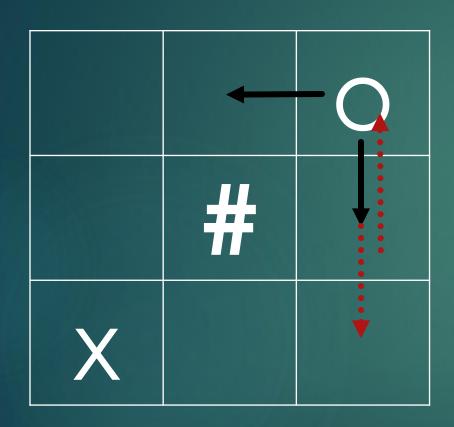
So now, we repeat the process, we'll dequeue L (left),

[D]

Now we're at L,look at the blue arrow, we're looking at this move. We can go right or left, so two moves we're gonna add to queueu

[D, LL,LR]

Explanation and Analysis



And then look at down moves, we'll dequeue down

[LL,LR]

The possible moves is we can go down or up, so two moves we're gonna add to queue

[LL,LR,DD,DU]

Just continue repeating this process and we're gonna get a move that's either equal to [LLDDD] or [DDLLL] each of this are only five moves, so either path is valid to go and that how we're gonna generate the path to find our point.

Source Code Analysis

Program Documentation

- Our Program Purpose is to help user to find path in a labyrinth / maze.
- We use 1 main function and 6 support function (buatLabirin, poscount, validMove, endPoint, changePath, and printMap)
- To make the model of the labyrinth, open the source code then edit the labyrinth inside the buatlabirin function.
- ► The output of the program will be steps the should be taken and the map with the path or "No. Valid path"
- S means endpoint and M means startpoint

1. buatLabirin()

We use this function to model our labyrinth. The datatype of the labyrinth is list []. List[] is a python datatype collection that allows duplicated member.

Poscount(labirin)

Function that will calculate the maximal steps that could be taken. It counts the number of white space plus M (start point) and S (end point)

ValidMove(labirin, langkah)

The purpose of this function is to check whether a move that is just taken is valid or not. Valid means the present move is not outside the maze and not on the "#" (obstacle) sign. If the move is valid, the function will return true, but if the move is invalid, the function will return false.

```
import queue
def validMove(labirin, langkah):
    for j, row in enumerate(labirin):
        for i,col in enumerate(row):
            if col == "M":
                x1 = i
                v1 = i
                break
    x = x1
    y = y1
    #print(y)
    for i in langkah:
            V -= 1
        elif i == "D":
        elif i == "R":
            x += 1
    if not (0 \le x < len(labirin[0]) and 0 \le y < len(labirin)):
        #print("FALSE")
        return False
    elif labirin[v][x] == "#":
```

changePath(labirin,lang kah)

ChangePath function is a function that gives + sign to some points at the labyrinth as the symbol that those points are parts of the path.

```
#Memberikan tanda + pada jalan yang dipilih
def changePath(labirin, langkah):
    for j, row in enumerate(labirin):
        for i,col in enumerate(row):
            if col == "M":
                x1 = i
                y1 = j
                break
    v = v1
    #print(x)
    #print(y)
    for i in langkah:
        if i == "U":
            v -= 1
        elif i == "D":
            v += 1
        elif i == "L":
        elif i == "R":
            x += 1
        if labirin[v][x] != "S":
            labirin[y][x] = "+"
    return labirin
```

EndPoint(labirin,langkah)

► This function purpose is to check whether the present moves collection has reached the destination or not. If the present collection of moves has reached the destination, the function will print the moves collection and call changePath and printMap function.

```
def endPoint(labirin, langkah):
    for j, row in enumerate(labirin):
        for i,col in enumerate(row):
            if col == "M":
                x1 = i
                v1 = 1
                break
    #print(x)
    #print(y)
    for i in langkah:
            x += 1
    if labirin[y][x] == "S":
        changePath(labirin,langkah)
        print("langkah yang didapat " + langkah)
        printMap(labirin)
        return True
    #print("Tidak sampai")
    return False
```

PrintMap(labirin)

With this function we can print the labyrinth model with the path that is choosen.

```
#Mencetak labirin beserta path yang dipilih

def printMap(labirin):

for j, row in enumerate(labirin):

for i, col in enumerate(row):

print(col + " "_end="")

print()

print()
```

Main

- ► This is the main function of our program. in this function we create the queue (FIFO) that will collect possible moves from the BFS. We also create a variabel that will contain the steps that we took.
- ▶ The logic of the function:
- While the present move has not reached the destination (letter S) POP the queue, then add it to present move variable

```
#1. Membuat labirin
         labirin = buatLabirin()
         #2. Membuat Queue untuk BFS
         bfs = queue.Queue()
         bfs.put("")
         #3. Membuat variabel untuk menyimpan
         #kemungkinan langkah
         posstep =
         totstep = poscount(labirin)
         print(totstep)
         #Proses pencarian Jalur
         while not endPoint(labirin_posstep):
             if len(posstep) > totstep:
                 print("no Valid Path")
                 exit(2)
             posstep = bfs.get()
145
             for direction in ["U","D","L","R"]:
                 choice = posstep + direction
                 if validMove(labirin_choice):
                     bfs.put(choice)
```

Main

- List the next possible moves (choice variable contains the next possible moves)
- If the next possible moves is valid, push it to the queue
- Repeat this logic until we found the path
- ▶ If there is no valid path (when the quantity of steps that have been taken is greater than the number of vertex, (in this case the white space element + S>destination +M>start point)) the program will print " no valid path and exit with exit code (2)

```
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145
             for direction in ["U","D","L","R"]:
                 choice = posstep + direction
                 if validMove(labirin_choice):
                     bfs.put(choice)
```

Example 1 (labyrinth that has valid path)

From the result, we can see that we need 7 steps to reach the destination (S). and the steps are down > down > down > left > left > up

```
labirin.append(["#", "#", "M", "#"])
labirin.append(["#", " ", " ", "#"])
labirin.append([" ", "#", " ", "#"])
labirin.append(["S", "#", " ", "#"])
labirin.append([" ", " ", " ", "#"])
labirin.append(["#", "#", "#", "#"])
```

```
langkah yang didapat DDDDLLU
# # M #
# + #
S # + #
+ + + #
# # # #

Process finished with exit code 0
```

```
/mnt/510c764a-8824-48a9-89b5-6c8791f8
no Valid Path
Process finished with exit code 2
```

Example 2 (Labyrinth without valid path)

- From the labyrinth we can know if there is no valid path to the destination
- ► The result of the program is no valid path because the number of steps that has been taken is greater than the maximal step that could be taken.