

二叉搜索树

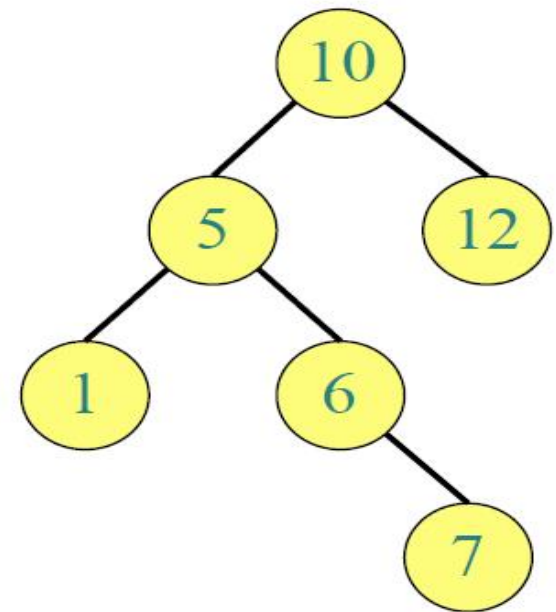
湖南大学信息科学与工程学院

Overview

- Runway reservation system (机场跑道预定系统) :
 - Definition
 - How to solve with lists (由一系列的飞机起飞时间节点组成)
- Binary Search Trees
 - Operations
- Readings: CLRS 10, 12.1-3



<http://izismile.com/tags/Gibraltar/>



Runway reservation system

- Problem definition:

- Single (**busy**) runway 单一跑道

- Reservations for landings 预定起飞时间

- maintain a set of future landing times

- a new request to land at time **t**

- add **t** to the set if no other landings are scheduled within < 3 minutes from **t**

- when a plane lands, removed from the set

- 当飞机起飞, 则把它的时间节点**t**从集合中删除



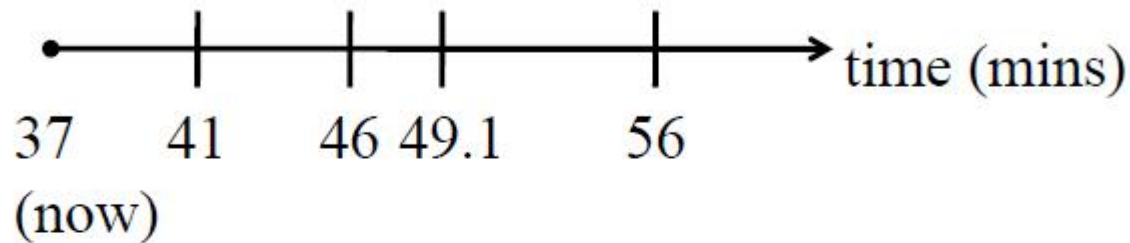
维护一个集合的
起飞时间节点

给定一个新的起
飞时间节点申请**t**

把**t**加入到集
合中: 新的
时间节点**t**与
其他所有时
间节点的间
隔小于3分
钟

Runway reservation system

- Example



- $R = (41, 46, 49.1, 56)$ 时间节点集合
- requests for time: 新时间节点请求
 - $44 \Rightarrow$ reject (46 in R) 拒绝
 - $53 \Rightarrow$ ok 允许
 - $20 \Rightarrow$ not allowed (already past) 不允许, 超过边界
- Ideas for efficient implementation ?

Some options

- Keep **R** as an unsorted list
 - Bad: takes linear time to search for collisions 缺点：需要线性时间来找冲突
 - Good: can insert **t** in $O(1)$ time 优点：插入为常量时间
- Keep **R** as a sorted array (resort after each insertion) 缺点：需要很多时间来插入时间节点
 - Bad: takes “a lot of” time to insert elements
 - Good: 3 minute check can be done in $O(\log n)$ time:
 - Using binary search, find* the smallest **i** such that $R[i] \geq t$ (next larger element)
 - Compare **t** to $R[i]$ and $R[i-1]$

下一个最大元素

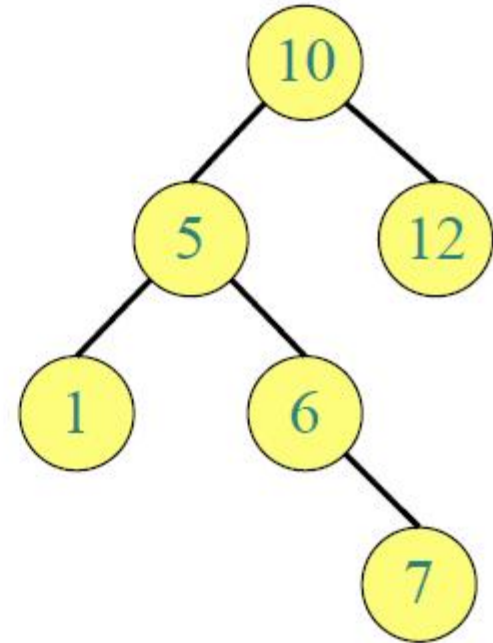
优点：检查3分钟时间冲突可以在对数时间内解决

Need: *fast* insertion into sorted list (sort of)

数组插入效率低，需要更快的插入算法及数据结构

Binary Search Tree (BSTs)

- Each node x has:
 - $\text{key}[x]$ 键值
 - Pointers: 节点指针、引用或索引
 - $\text{left}[x]$ 左节点
 - $\text{right}[x]$ 右节点
 - $\text{p}[x]$ 父节点



Binary Search Tree (BSTs)

- Property: for any node x : 属性: 对于每个节点
 - For all nodes y in the **left** subtree of x : 对于X的左子树的所有节点y

$$\text{key}[y] \leq \text{key}[x]$$

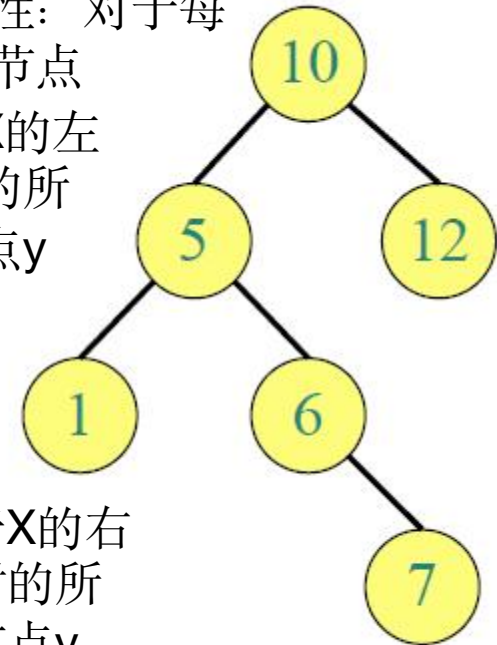
- For all nodes y in the **right** subtree of x :

$$\text{key}[y] \geq \text{key}[x]$$

- How are BSTs made ?

对于X的右子树的所有节点y

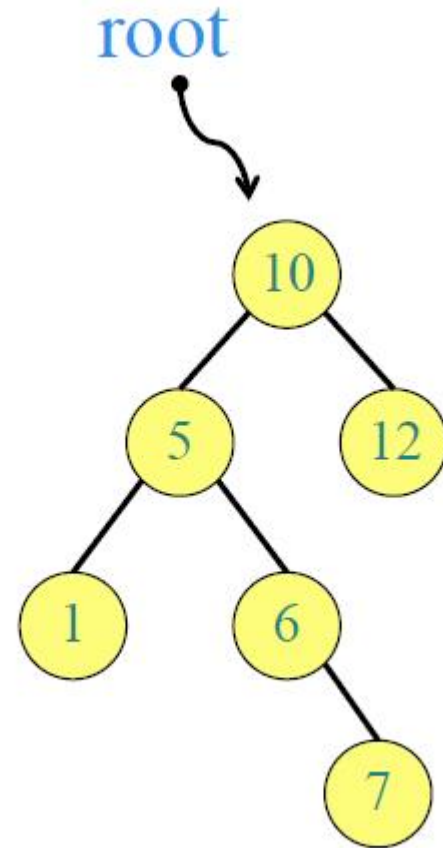
怎么构建二叉搜索树?



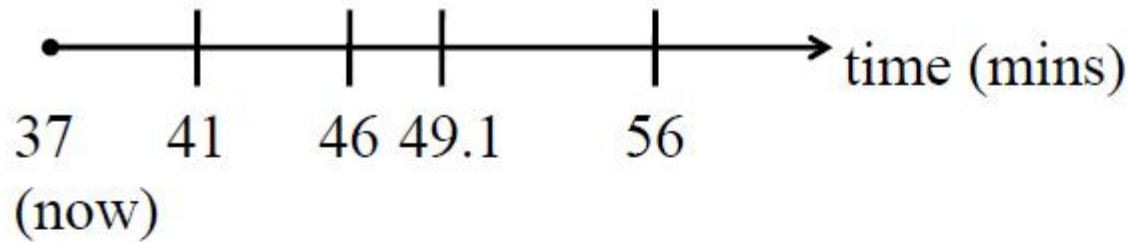
Growing BSTs

树的成长

- Insert 10
- Insert 12
- Insert 5
- Insert 1
- Insert 6
- Insert 7



BST as a data structure



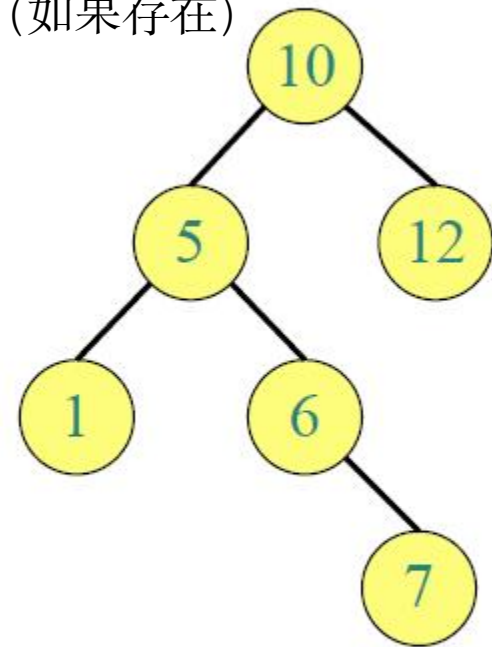
- **Operations:** 数据结构的操作
 - **insert(*k*):** inserts key *k* 插入: 插入给定键值*k*的节点
 - **search(*k*):** finds the node containing key *k* (if it exists) 搜索: 搜索包含键值*k*的节点 (如果存在)
 - **next-larger(*x*):** finds the next element after element *x* 下一个最大节点: 找出当前节点*x*的下一个最大节点
 - **minimum(*x*):** finds the minimum of the tree rooted at *x* 找最小节点: 找出当前节点*x*为根节点的子树的最小节点
 - **delete(*x*):** deletes node *x* 删除节点*x*

Search

Search(**k**): 搜索: 搜索包含键值**k**的节点 (如果存在)

- Recurse left or right until you find **k**, or get NIL

递归查找左节点或右节点,
直到找到**k**或者不在列表中为止



Search(7)

Search(8)

Next-larger

next-larger(x): 下一个最大节点: 找出当前节点x的下一个最大节点

- If $\text{right}[x] \neq \text{NIL}$ then
return minimum($\text{right}[x]$)

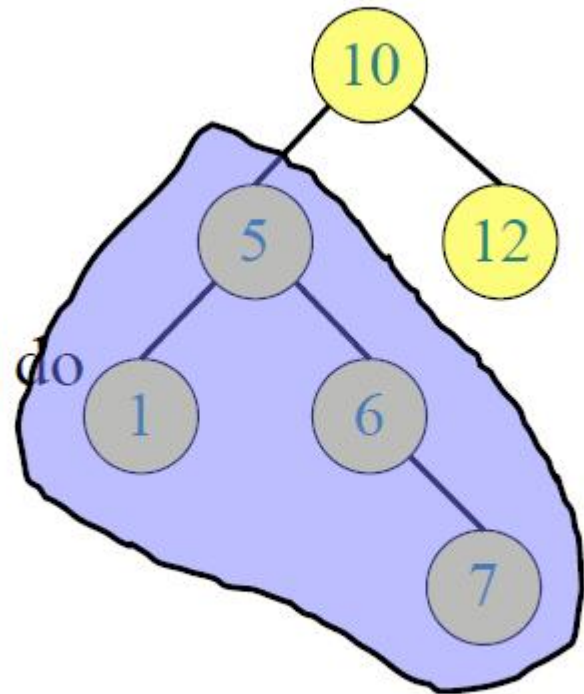
- Otherwise

$y \leftarrow p[x]$

While $y \neq \text{NIL}$ and $x = \text{right}[y]$ do

- $x \leftarrow y$
- $y \leftarrow p[y]$

Return y



next-larger(5)

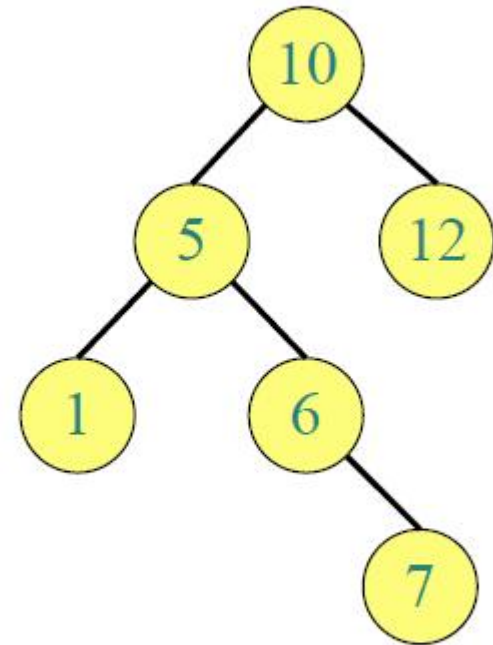
next-larger(7)

Minimum

找最小节点：找出当前节点x为根节点的子树的最小节点

Minimum(x)

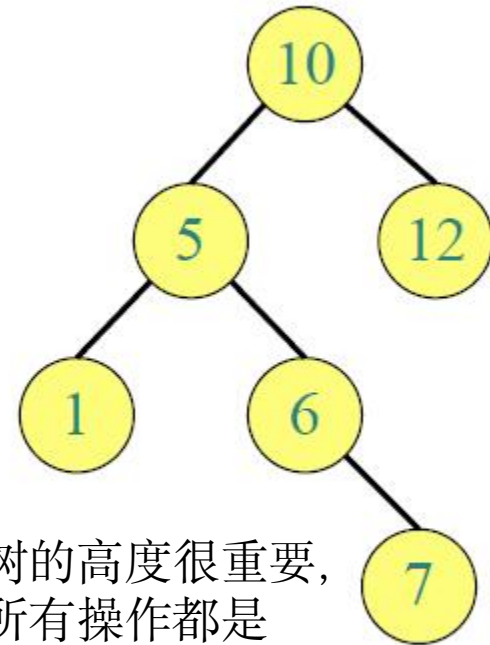
- While left[x] ≠ NIL do
 $x \leftarrow \text{left}[x]$
- Return x



minimum(5)

Analysis

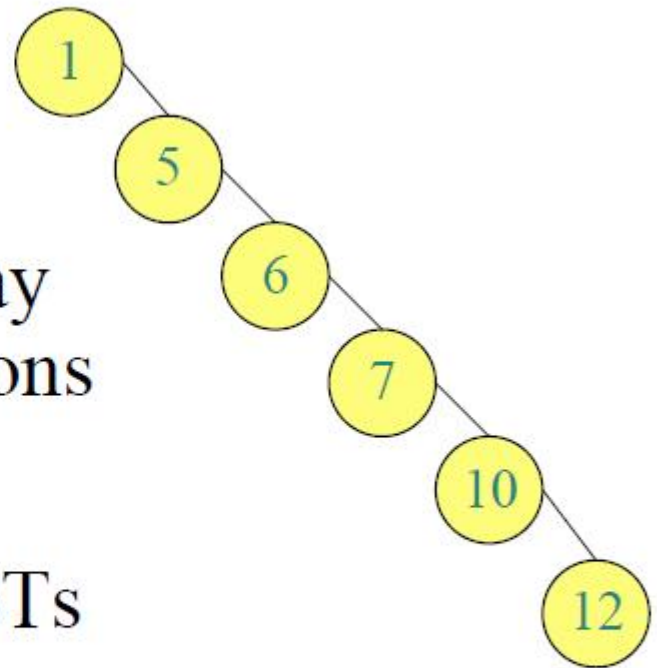
- We have seen insertion, search, minimum, etc.
- How much time does any of this take ?
- Worst case: $O(\text{height})$
=> height really important
- After we insert n elements, what is the worst possible BST height ?
当插入完 n 个元素后，可能的最差二叉搜索树的高度是多少？



树的高度很重要，
所有操作都是
 $O(n)$

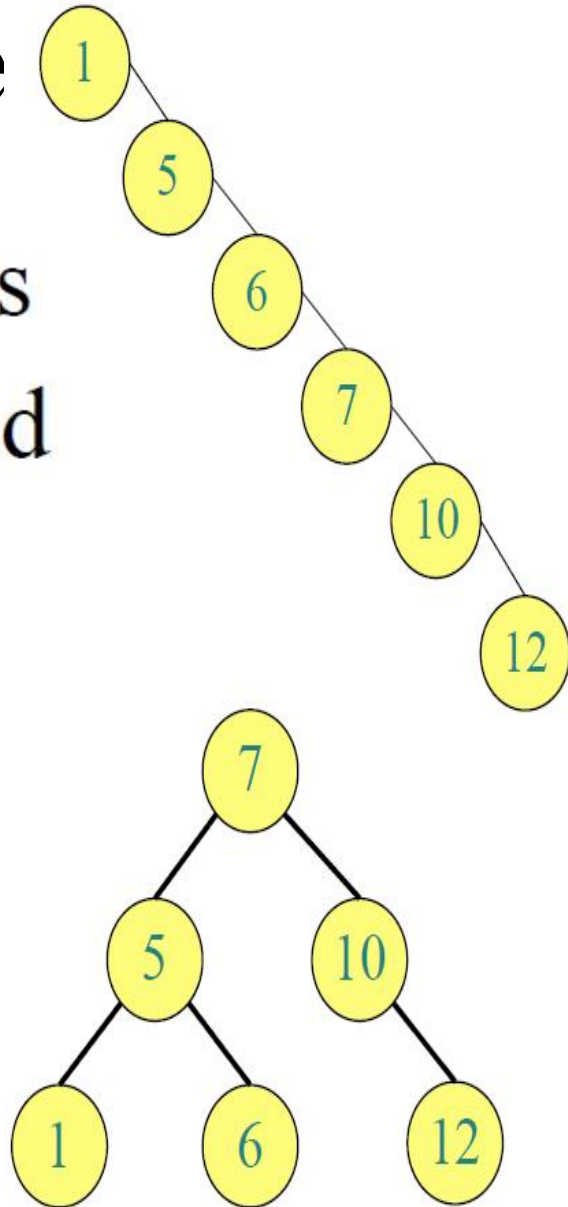
Analysis

- $n-1$
- So, still $O(n)$ for the runway reservation system operations
- Next lecture: **balanced** BSTs
- Readings: CLRS 13.1-2



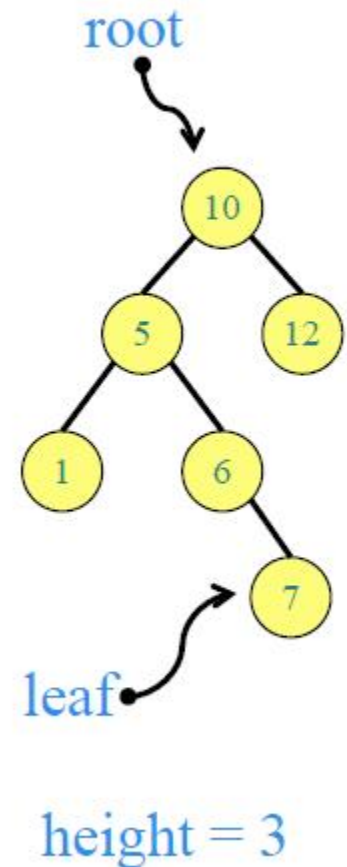
Lecture Overview

- Review: Binary Search Trees
- Importance of being balanced
- Balanced BSTs
 - AVL trees
 - definition
 - rotations, insert



Binary Search Trees (BSTs)

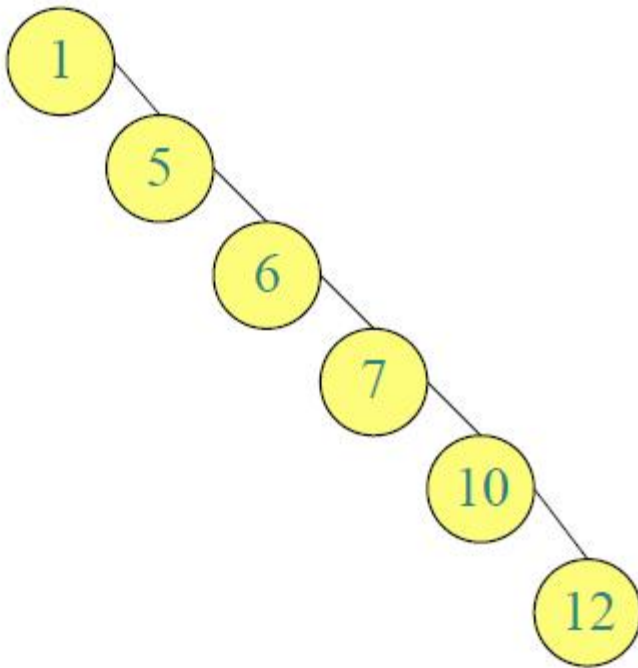
- Each node x has:
 - $\text{key}[x]$
 - Pointers: $\text{left}[x]$, $\text{right}[x]$, $p[x]$
- Property: for any node x :
 - For all nodes y in the **left** subtree of x :
 $\text{key}[y] \leq \text{key}[x]$
 - For all nodes y in the **right** subtree of x :
 $\text{key}[y] \geq \text{key}[x]$



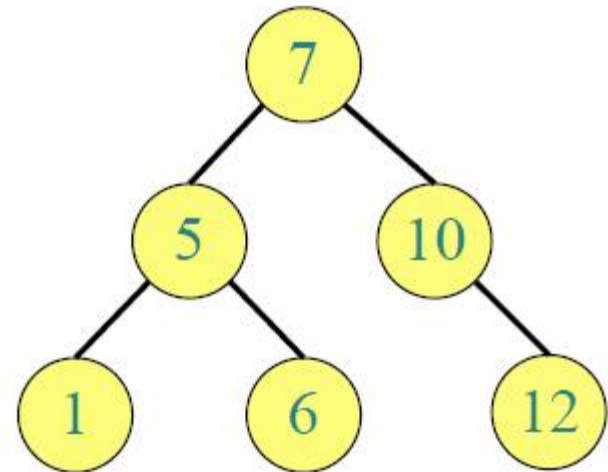
The importance of being balanced

for n nodes:

平衡树的高度非常的关键



$$h = \Theta(n)$$

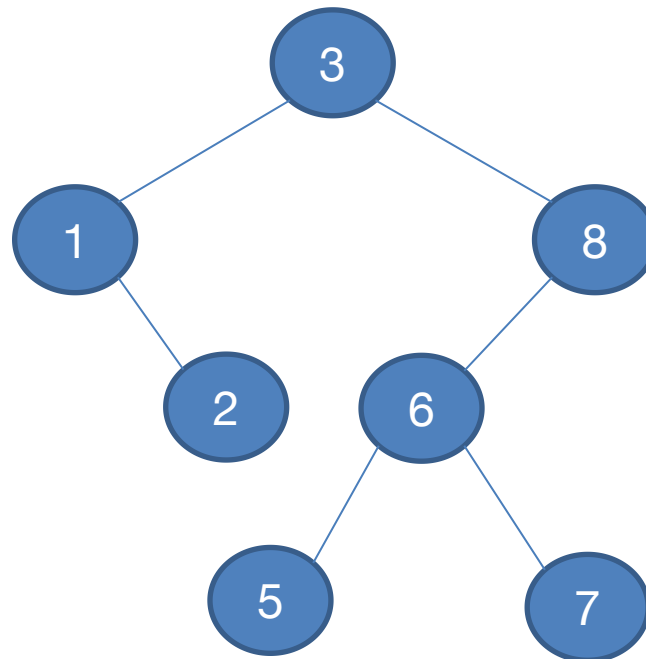


$$h = \Theta(\log n)$$

BST Sort

- Given an array A, build a BST for A
- Do an inorder tree walk(中序遍历)

3	1	8	2	6	7	5
---	---	---	---	---	---	---



Time Complexity

- Given an array A, build a BST for A ($\Omega(n \log n)$)
- Do an inorder tree walk ($O(n)$)

Relation to Quick Sort

- Comparisons in BST Sort are the same to comparisons in Quick Sort

3	1	8	2	6	7	5
---	---	---	---	---	---	---

- We can randomize BST Sort
- Randomized BST Sort have the same time complexity to randomized Quick Sort

Balanced BST Strategy

平衡的二叉搜索树的策略

给所有的节点增加一些额外的信息

- **Augment** every node with some data

- Define a local **invariant** on data 给每个本地节点的信息
定义一个不变式

- Show (prove) that invariant guarantees $\Theta(\log n)$ height 证明每个本地节点的不变式可以保证树的高度为 $\Theta(\log n)$

- Design algorithms to maintain data and the invariant 设计算法来维持额外的节点信息和不变式



AVL Trees: Definition

[Adelson-Velskii and Landis'62]

- **Data:** for every node, maintain its height (“augmentation”)

信息：对于每一个节点，维护它的高度（“增加物”）

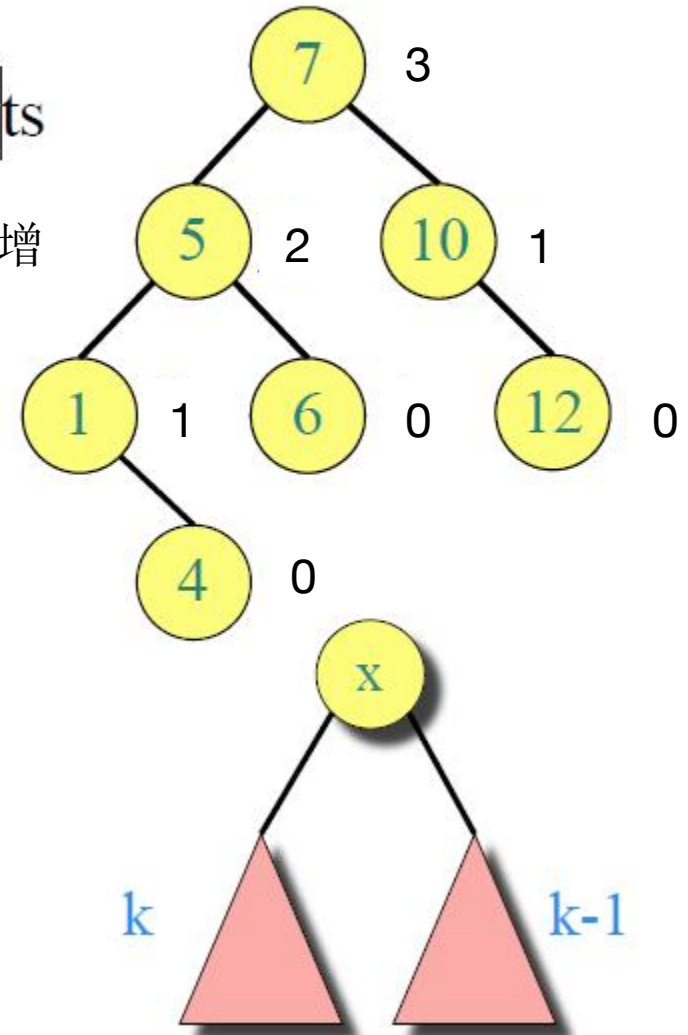
- Leaves have height 0 叶节点高度为0

- NIL has “height” -1

空节点高度为-1

不变式：对于每一个节点，左子树与右子树的高度差为1

- **Invariant:** for every node x , the heights of its left child and right child differ by at most 1



AVL trees have height $\Theta(\log n)$

Invariant: for every node x , the heights of its left child and right child differ by at most 1

- Let n_h be the minimum number of nodes of an AVL tree of height h

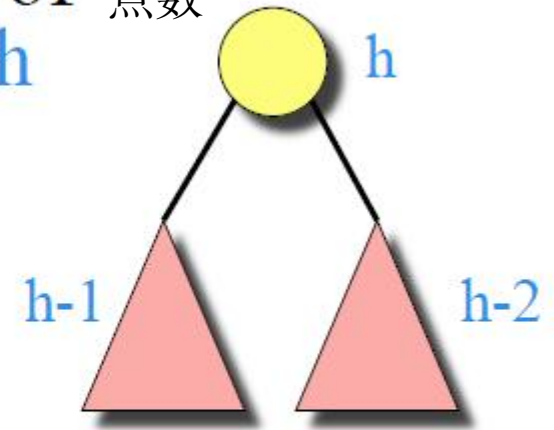
一系列高度为 h 的子平衡树当中的最小的节点数

- We have $n_h \geq 1 + n_{h-1} + n_{h-2}$

$$\Rightarrow n_h > 2n_{h-2}$$

$$\Rightarrow n_h > 2^{h/2}$$

$$\Rightarrow h < 2 \lg n_h$$

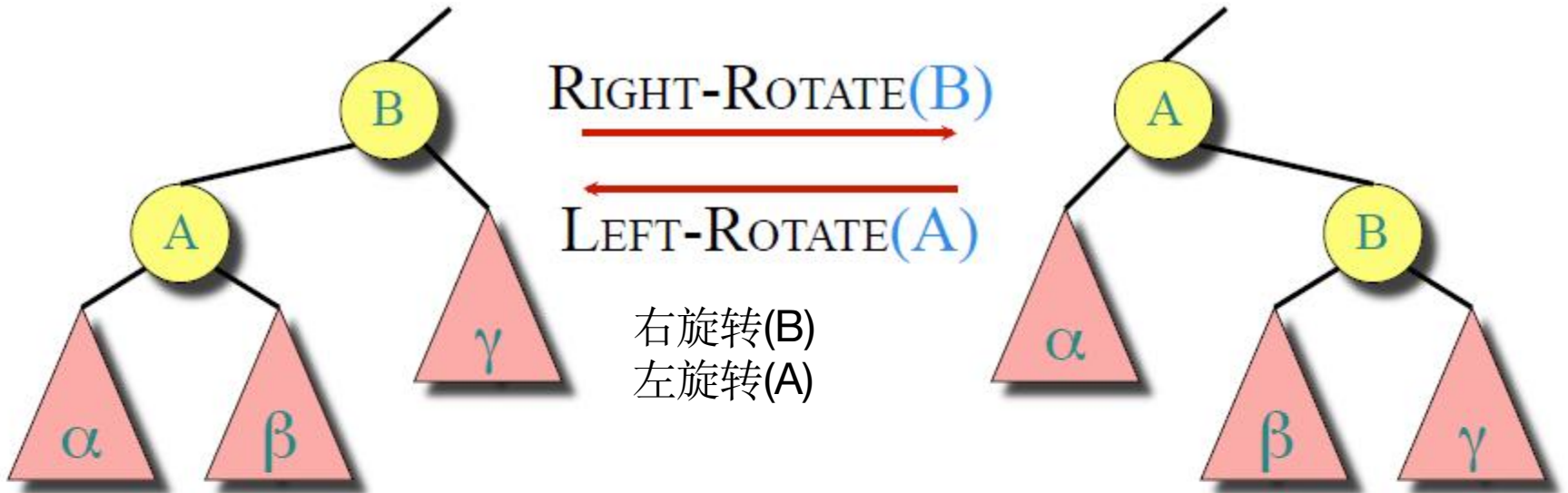


- The constant “2” can be improved

每个节点满足不变式的话，上面证明了整棵树的高度必然是 $\Theta(\log n)$ ，下一步是怎样来维护每个节点的不变式？

How can we maintain the invariant ?

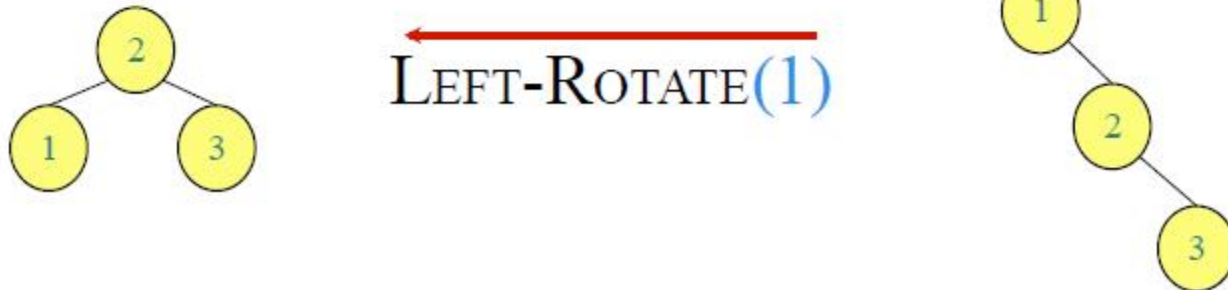
Rotations



Rotations maintain the inorder ordering of keys:

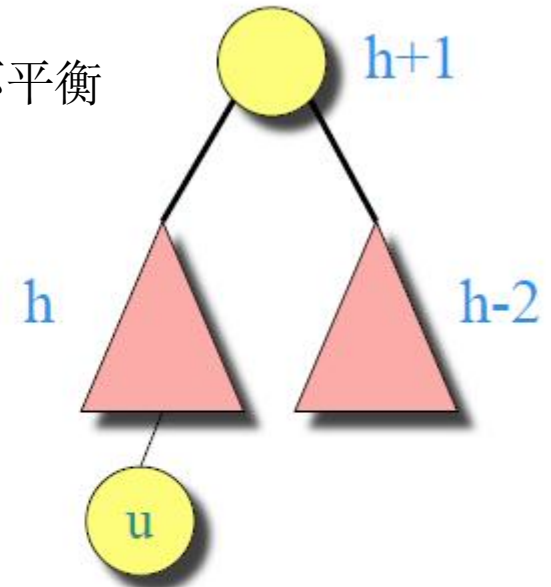
$$\bullet a \in \alpha, b \in \beta, c \in \gamma \Rightarrow a \leq A \leq b \leq B \leq c.$$

旋转前后节点的键值的排序没有变化



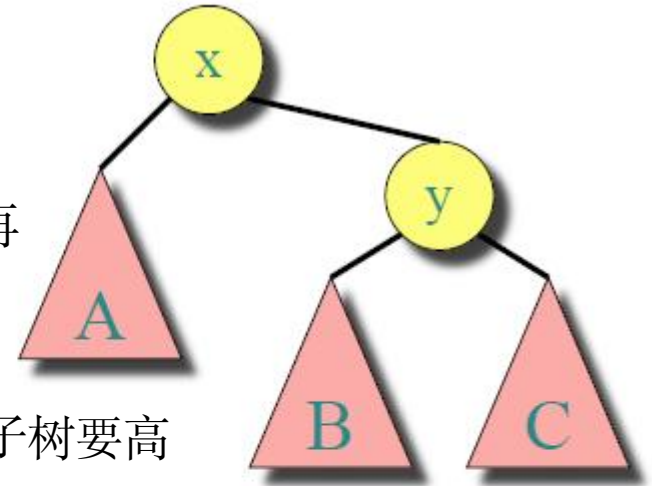
Insertions

- Insert new node **u** as in the simple BST 插入一个新的节点可能导致不平衡
 - Can create imbalance
- Work your way up the tree, restoring the balance
- Similar issue/solution when deleting a node

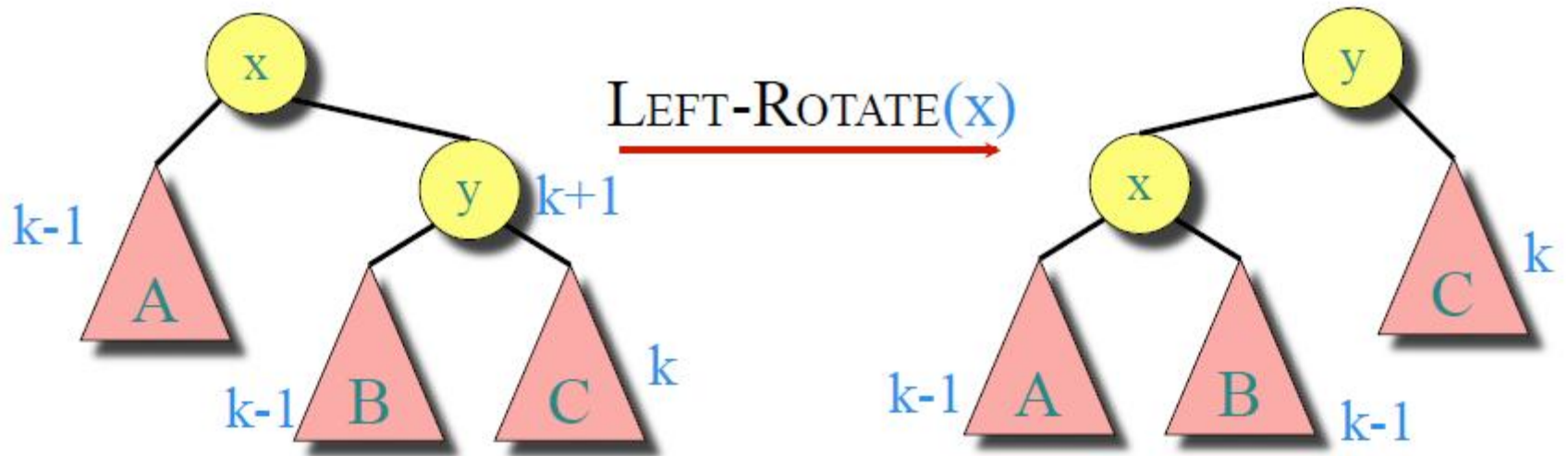


Balancing

- Let **x** be the lowest “violating” node
node 使X节点是最低的违反属性的节点
 - We will fix the subtree of **x** and move up
先修复X为根节点的子树，再一步步往上修复
- Assume the right child of **x** is deeper than the left child of **x** (**x** is “right-heavy”) 右高：假设x右子树比左子树要高
- Scenarios: 可能出现3种情况
 - Case 1: Right child **y** of **x** is right-heavy
X的右节点y是右高
 - Case 2: Right child **y** of **x** is balanced
X的右节点y是平衡的
 - Case 3: Right child **y** of **x** is left-heavy
X的右节点y是左高

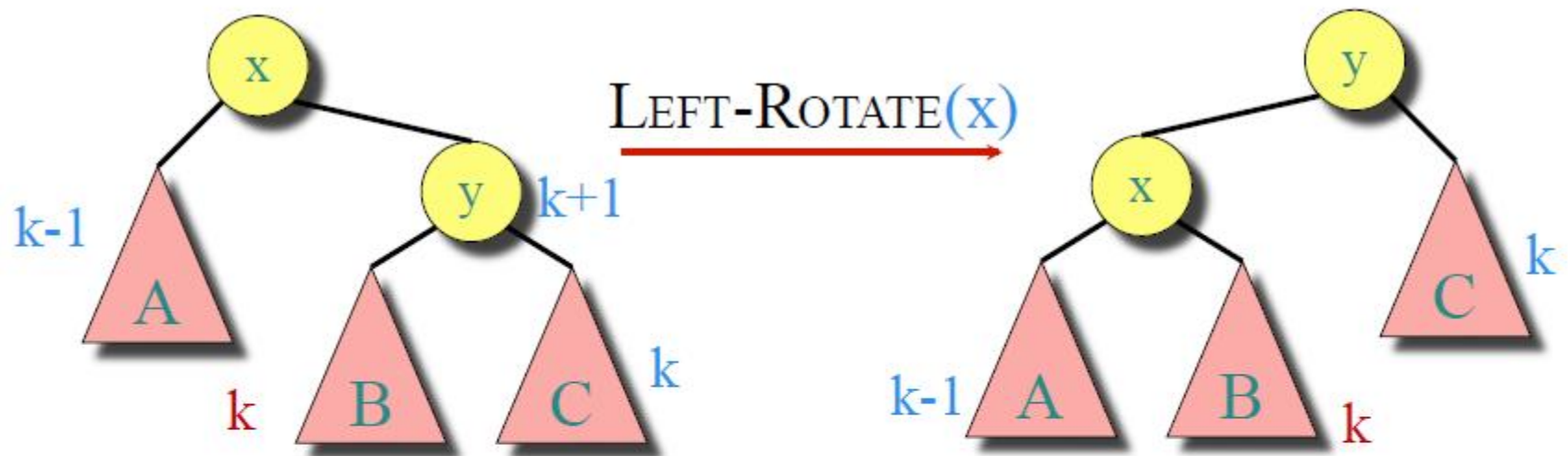


Case 1: y is right-heavy



x 的右节点 y 是右高

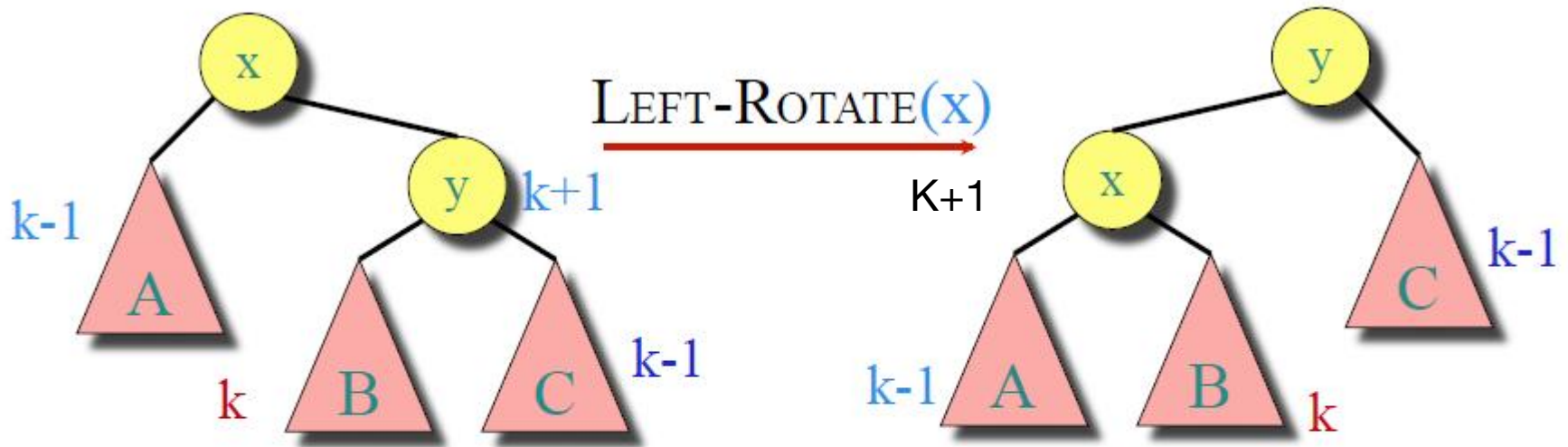
Case 2: y is balanced



x 的右节点 y 是平衡的

Same as Case 1

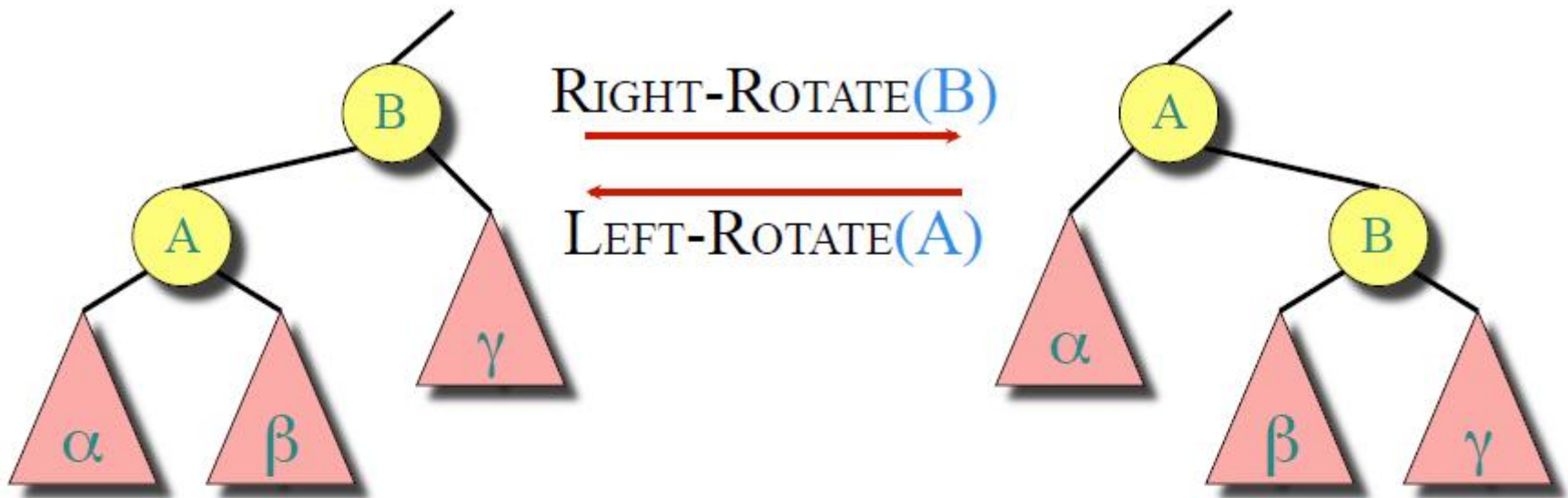
Case 3: y is left-heavy



x的右节点y是左高

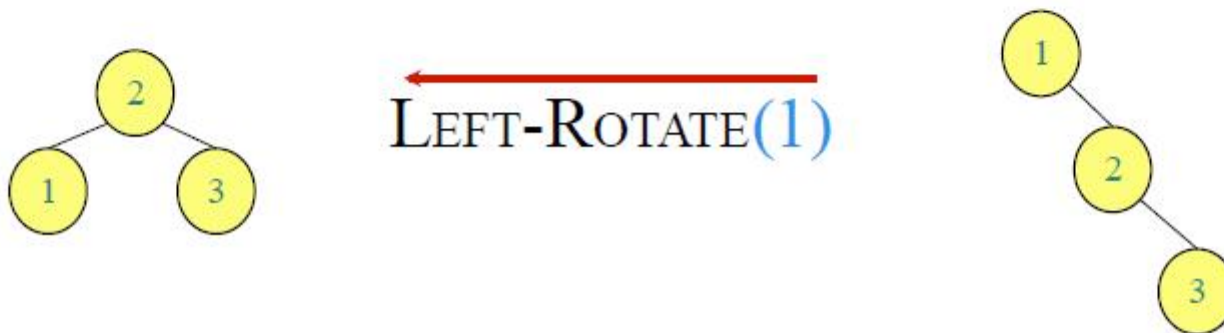
Need to do more ...

Rotations

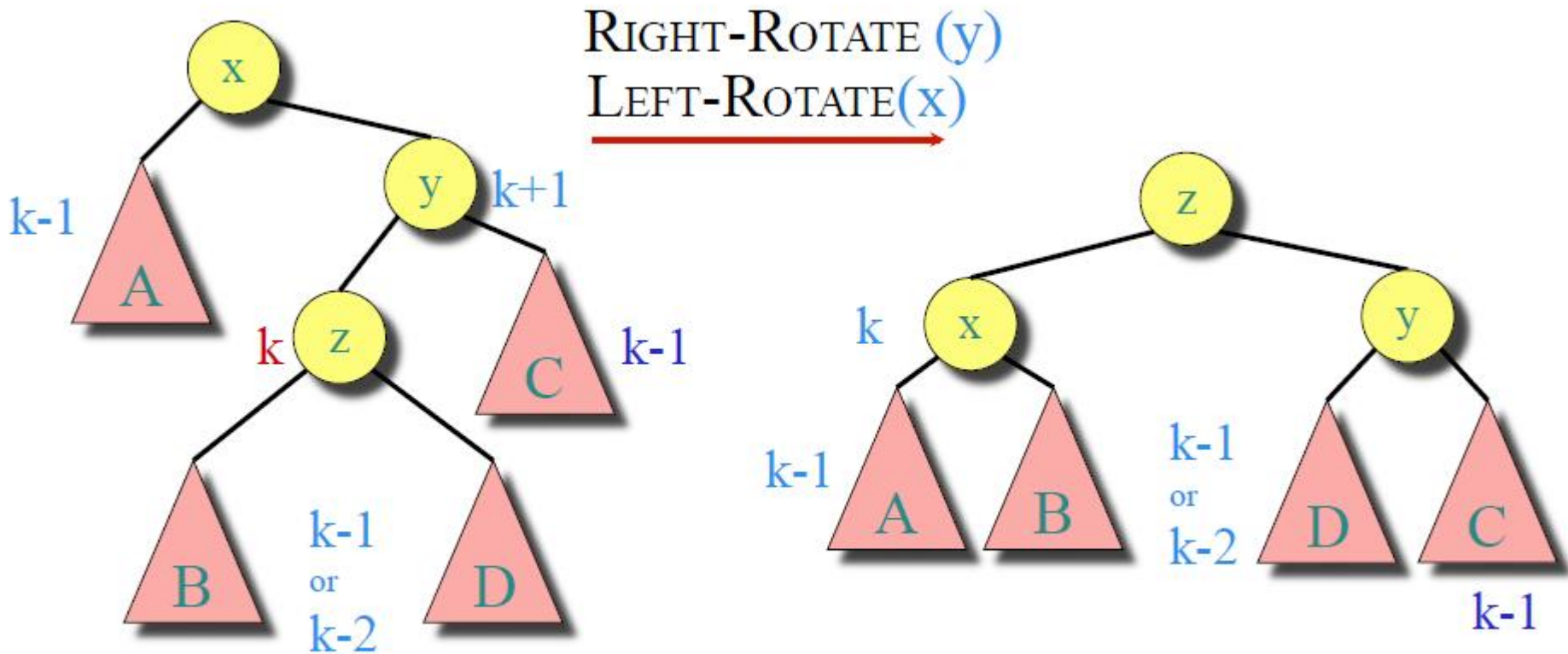


Rotations maintain the inorder ordering of keys:

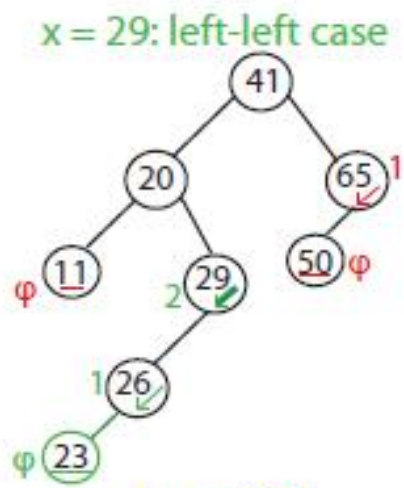
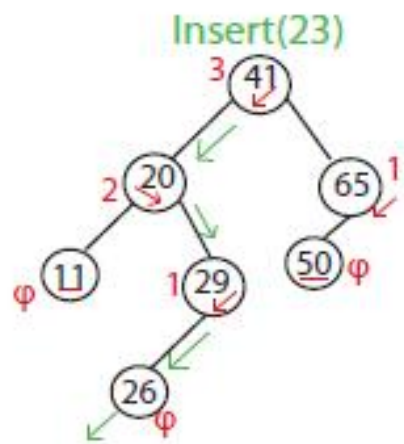
- $a \in \alpha, b \in \beta, c \in \gamma \Rightarrow a \leq A \leq b \leq B \leq c.$



Case 3: y is left-heavy



And we are done!

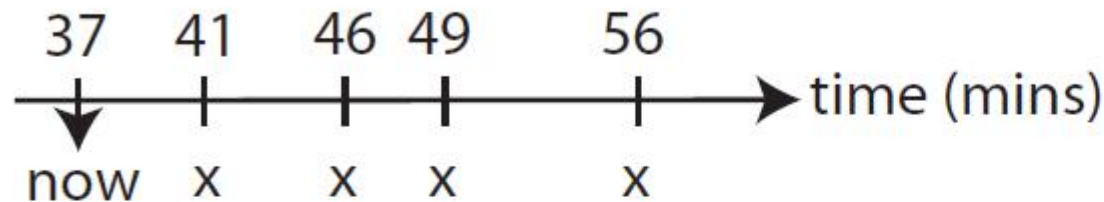


Conclusions

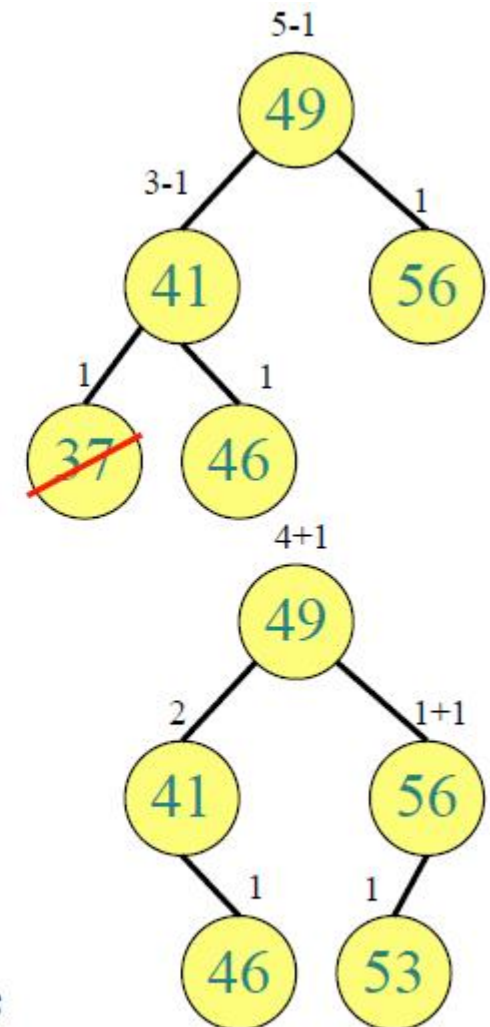
- Can maintain balanced BSTs in $O(\log n)$ time per insertion
- Search etc take $O(\log n)$ time

BST for runway reservation system

- $R = (37, 41, 46, 49, 56)$ current landing times



- remove t from the set when a plane lands
 $R = (41, 46, 49, 56)$
- add new t to the set if no other landings are scheduled within < 3 minutes from t
 - $44 \Rightarrow$ reject (46 in R)
 - $53 \Rightarrow$ ok
- delete, insert, conflict checking take $O(h)$, where h is the height of the tree



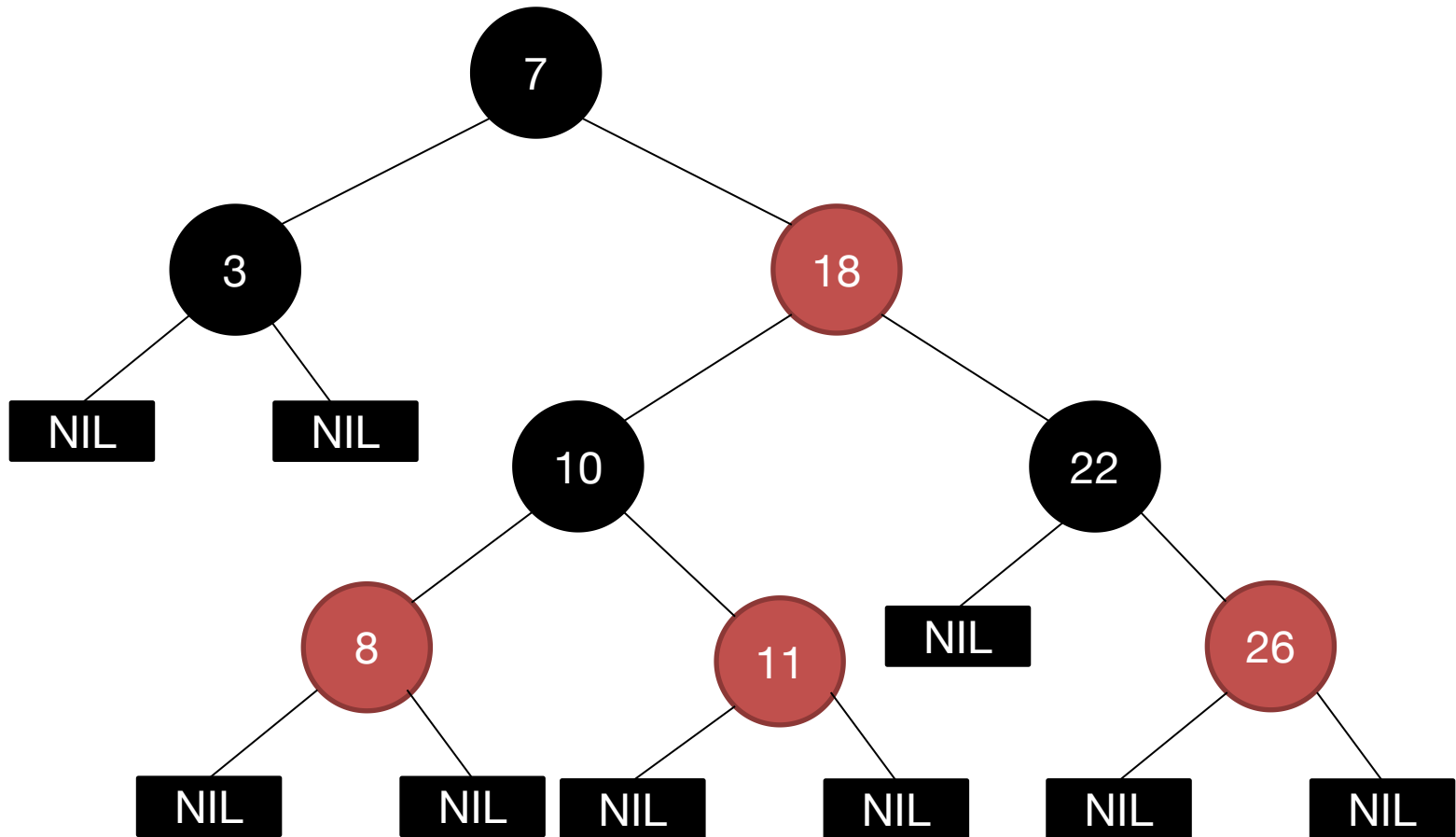
Balanced Search Trees ...

- AVL trees (Adelson-Velsii and Landis 1962)
- Red-black trees (see CLRS 13)
- Splay trees (Sleator and Tarjan 1985)
- Scapegoat trees (Galperin and Rivest 1993)
- Treaps (Seidel and Aragon 1996)
-

Red-black Tree

- BST structure with extra color, satisfying :
 1. Every node is either black or red;
 2. Root and leaves are all black, and all leaves are NIL;
 3. Red nodes' parents are black;
 4. The paths from a node x to all its descendant leaves have the same number of black nodes.

Example



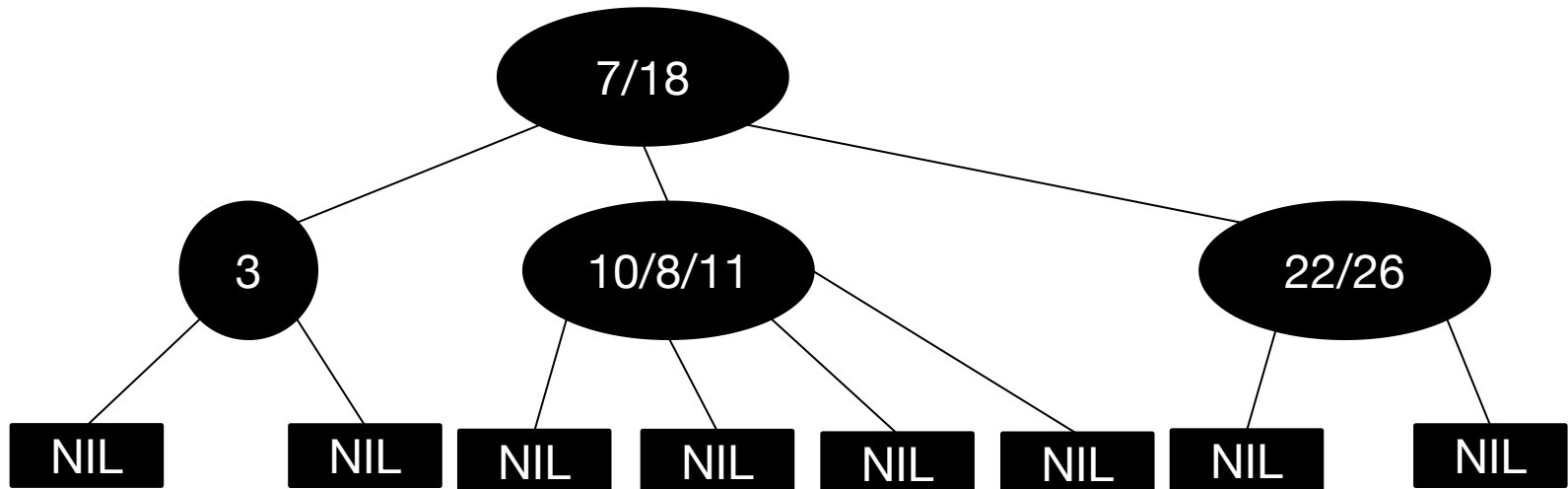
Red-black Tree

- In Red-black tree, the same number of black nodes in all paths from a node x to all its descendant leaves have are called the *black height* of x
- Supposed that there are n nodes, there are $n+1$ leaves in a red-black tree(Proved in induction)

Height of Red-Black Tree

- The height of a red-black tree is smaller than $2\log(n+1)=O(\log n)$
- Proof: Merge red node with its black parent. Then, the tree becomes a 2-3-4 tree, where each node have 2, 3 or 4 children and all leaves have the same depth that is black height h' .

Example for Proof

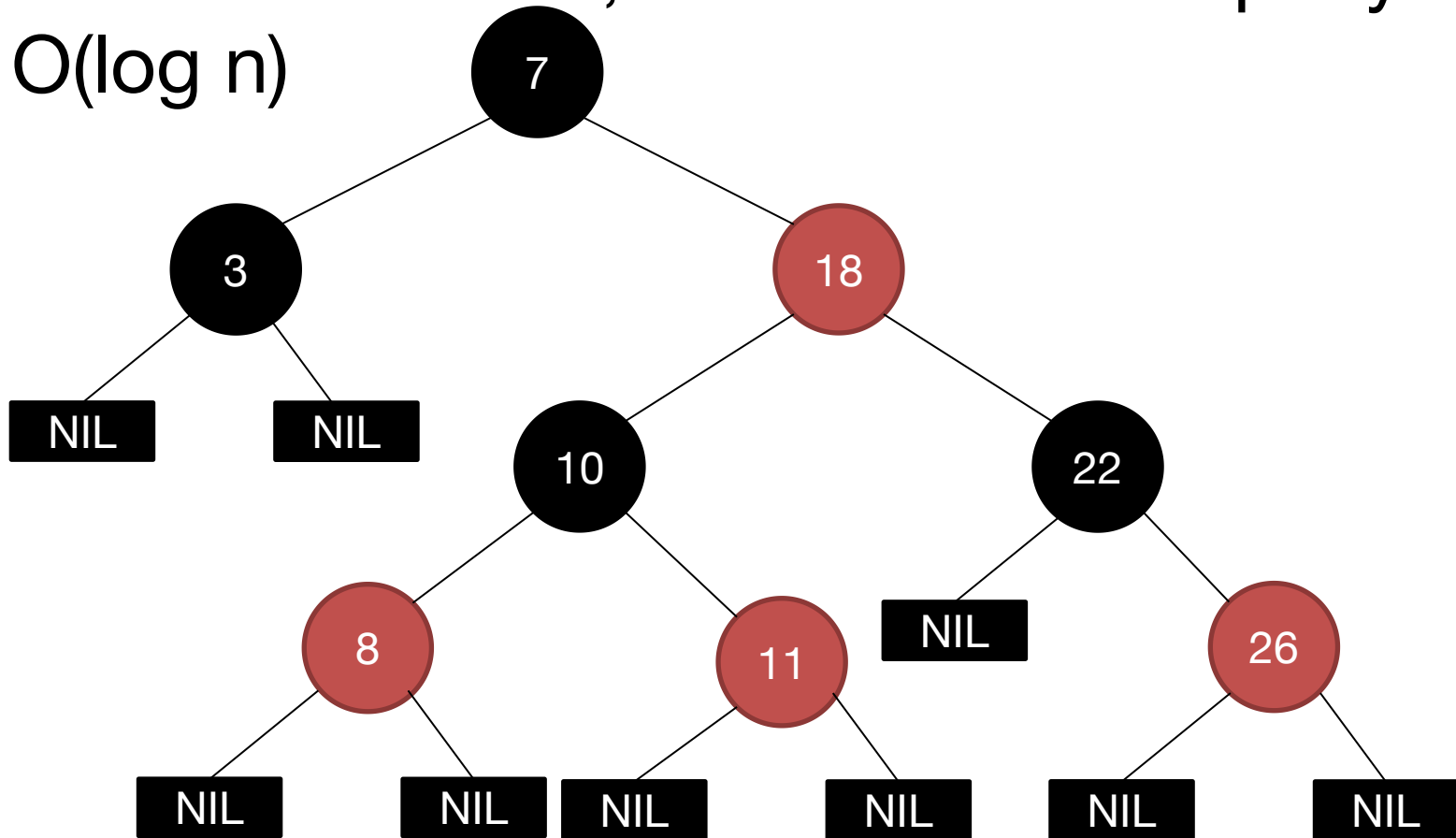


Height of Red-Black Tree

- The height of a red-black tree is smaller than $2\log(n+1)=O(\log n)$
- Proof: $2^{h'} \leq \#leaves \leq 4^{h'} \Rightarrow 2^{h'} \leq n + 1 \Rightarrow h' \leq \log(n + 1)$
- Hence, the height of a red-black tree h is smaller than $2h'$, so $h \leq 2\log(n + 1)$

Search Red-black Tree

- Search as in BST, and the cost of query is $O(\log n)$



Insert Red-black Tree

- The cost of update is $O(\log n)$

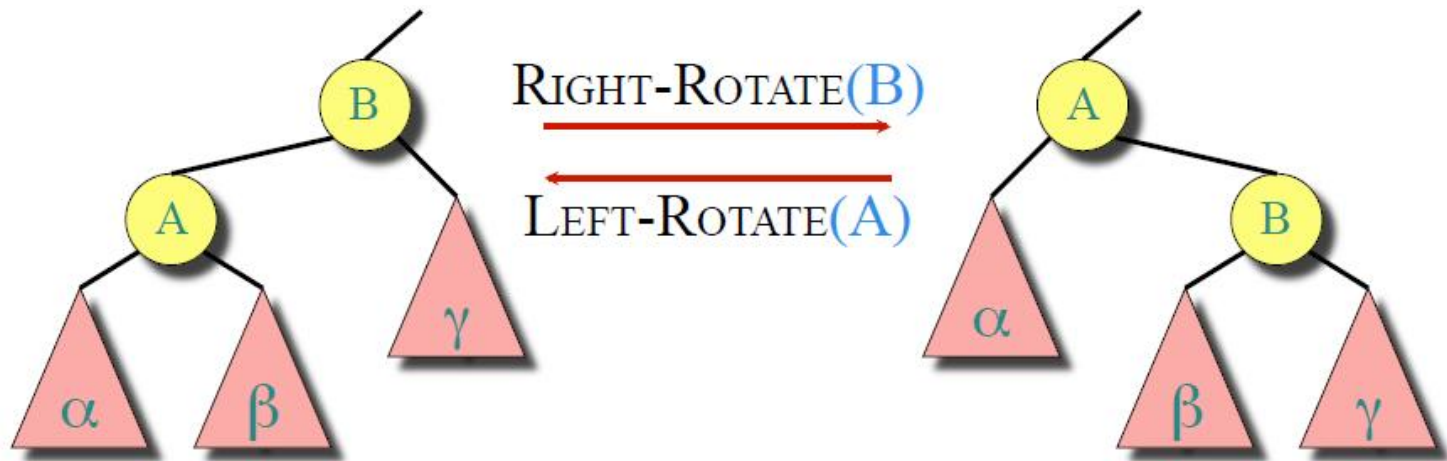
RB-INSERT(T, z)

```
1   $y = T.nil$ 
2   $x = T.root$ 
3  while  $x \neq T.nil$ 
4       $y = x$ 
5      if  $z.key < x.key$ 
6           $x = x.left$ 
7      else  $x = x.right$ 
8   $z.p = y$ 
9  if  $y == T.nil$ 
10      $T.root = z$ 
11 elseif  $z.key < y.key$ 
12      $y.left = z$ 
13 else  $y.right = z$ 
14  $z.left = T.nil$ 
15  $z.right = T.nil$ 
16  $z.color = RED$ 
17 RB-INSERT-FIXUP( $T, z$ )
```

RB-INSERT-FIXUP(T, z)

```
1  while  $z.p.color == RED$ 
2      if  $z.p == z.p.p.left$ 
3           $y = z.p.p.right$ 
4          if  $y.color == RED$ 
5               $z.p.color = BLACK$  // case 1
6               $y.color = BLACK$  // case 1
7               $z.p.p.color = RED$  // case 1
8               $z = z.p.p$  // case 1
9          else if  $z == z.p.p.right$ 
10              $z = z.p$  // case 2
11             LEFT-ROTATE( $T, z$ ) // case 2
12              $z.p.color = BLACK$  // case 3
13              $z.p.p.color = RED$  // case 3
14             RIGHT-ROTATE( $T, z.p.p$ ) // case 3
15         else (same as then clause
16             with “right” and “left” exchanged)
17      $T.root.color = BLACK$ 
```

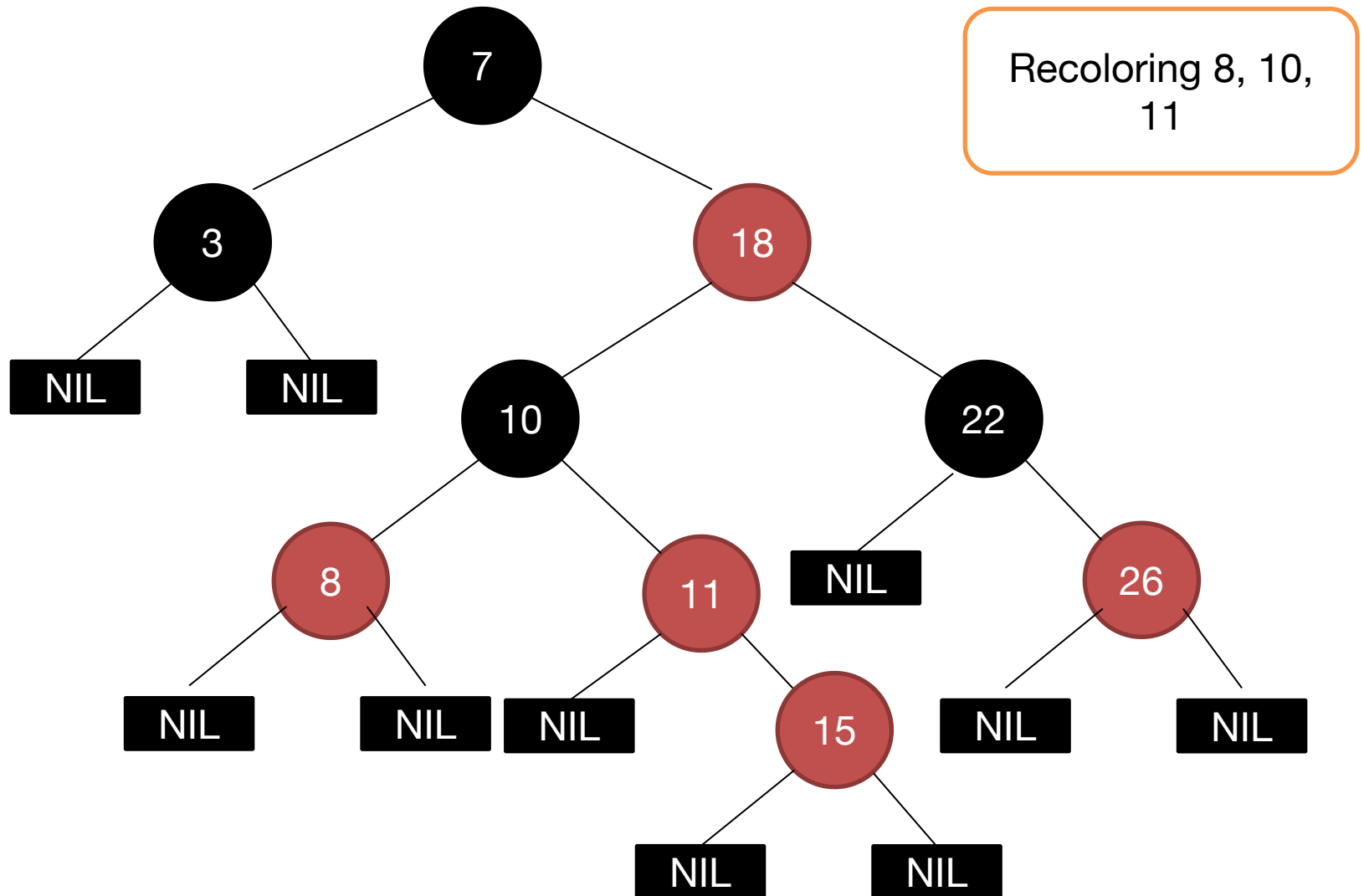
Left and Right Rotations



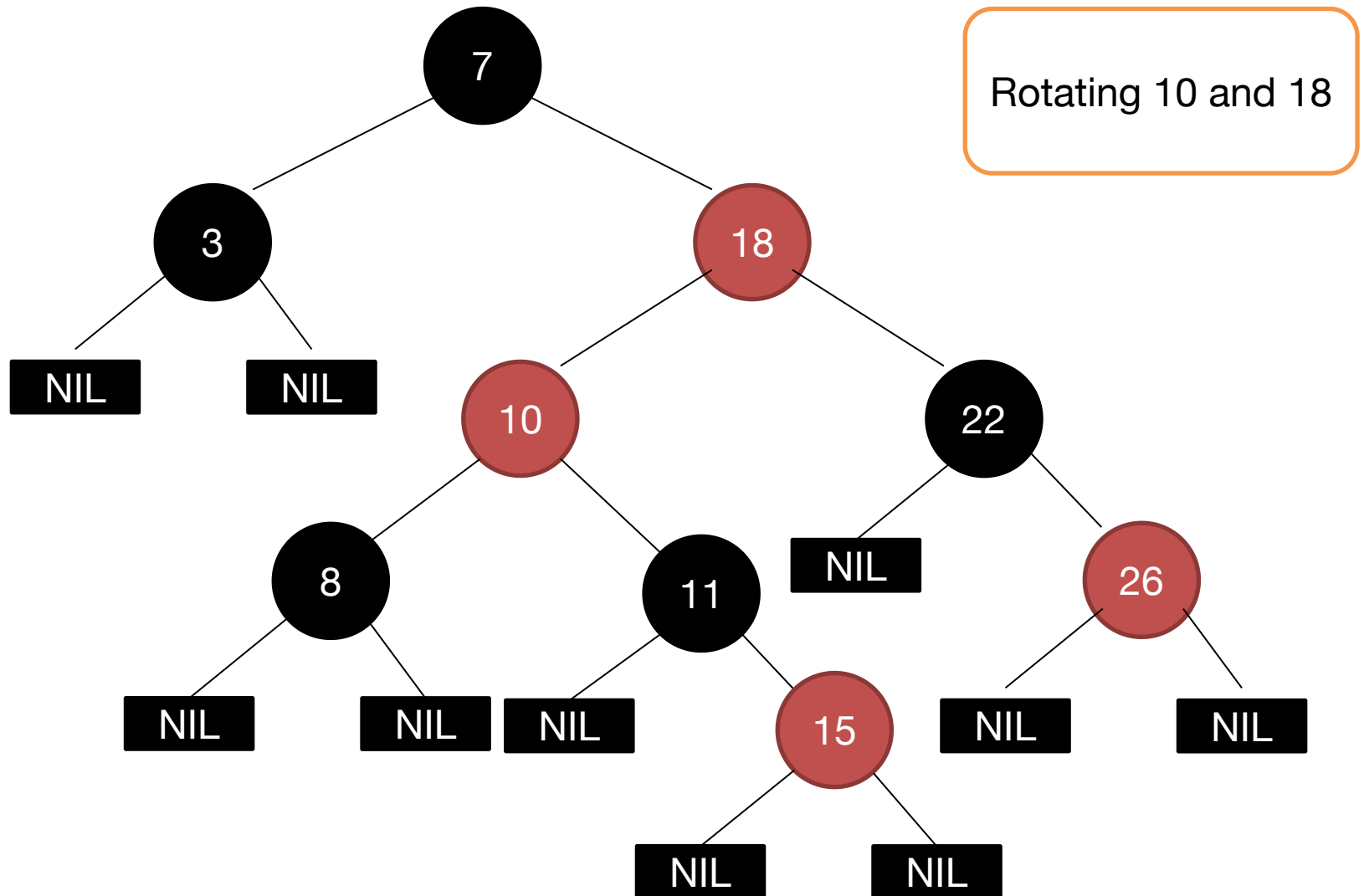
Rotations maintain the inorder ordering of keys:

- $a \in \alpha, b \in \beta, c \in \gamma \Rightarrow a \leq A \leq b \leq B \leq c.$

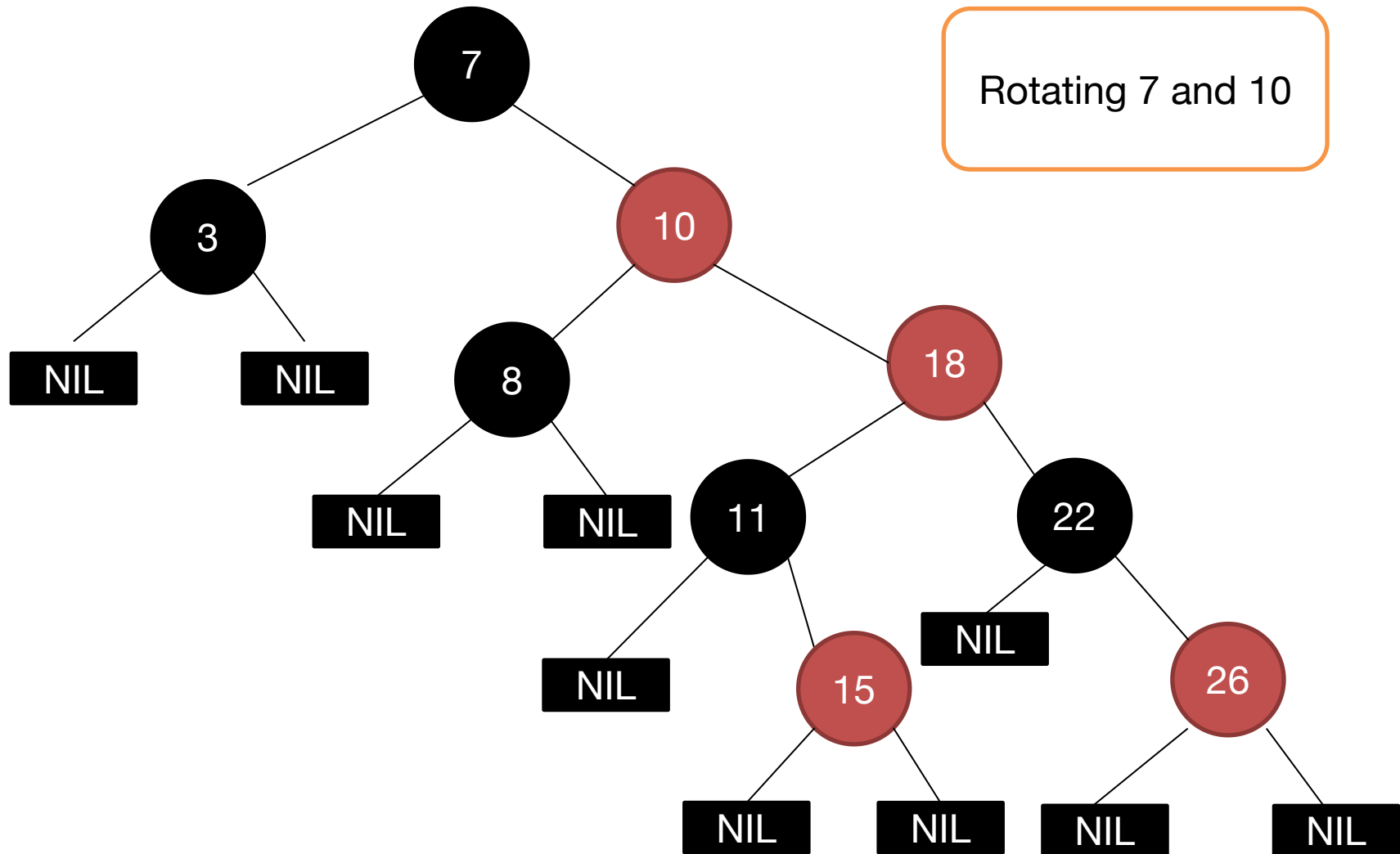
Example Insert 15



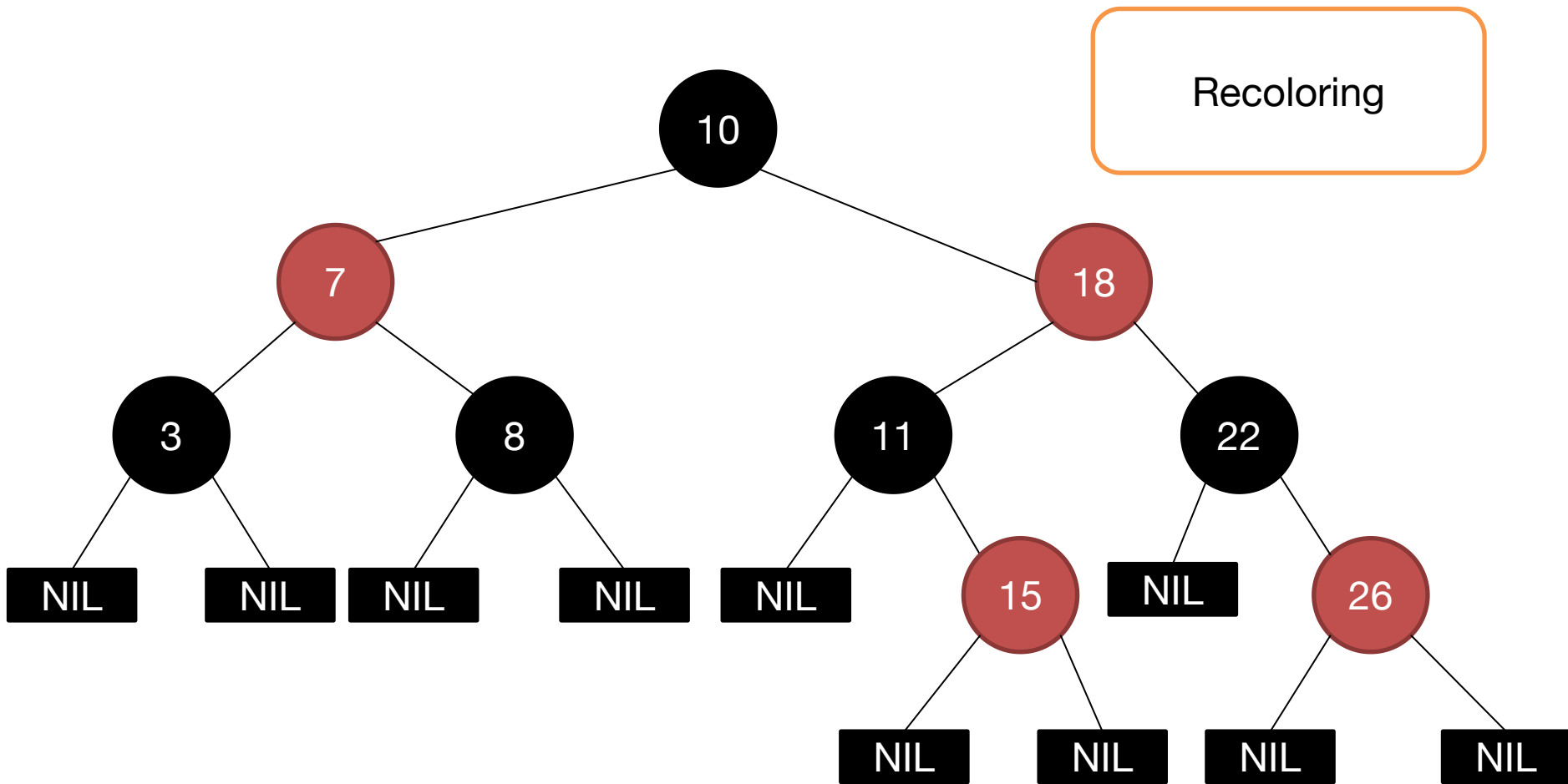
Example Insert 15



Example Insert 15

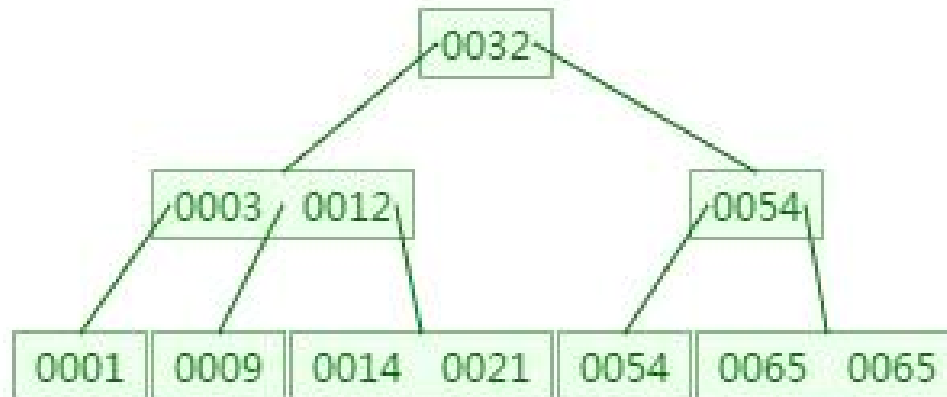


Example Insert 15



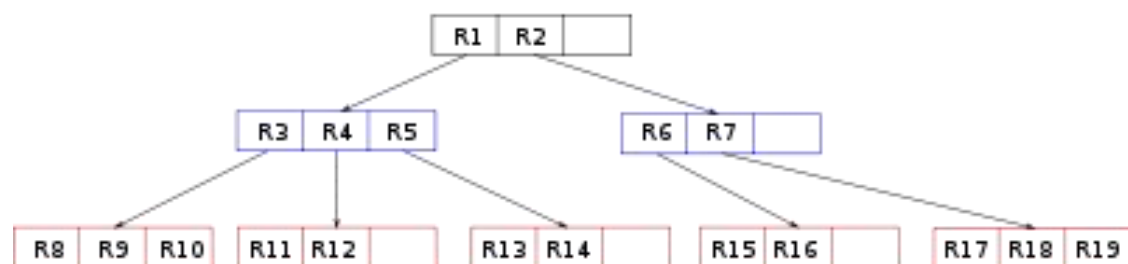
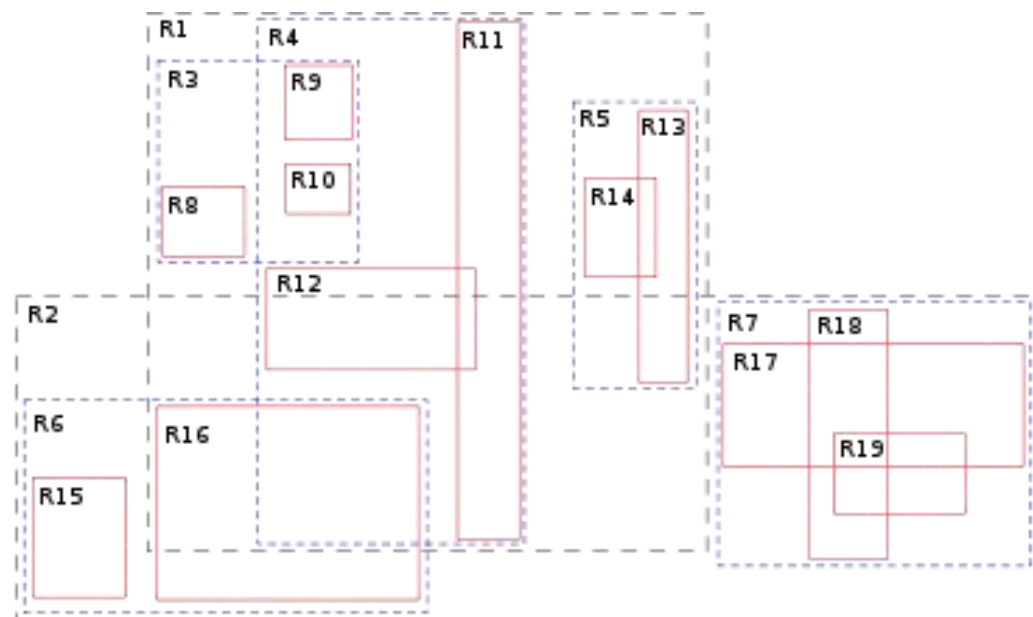
B-Tree

- In B-trees, internal (non-leaf) nodes can have a variable number of child nodes within the pre-defined range $[m/2, m]$.



R-Tree

- R-trees are tree data structures used for spatial access methods, i.e., for indexing multi-dimensional information such as geographical coordinates, rectangles or polygons.



Signature Tree

- signature pointed to by the corresponding leaf node.

