

Bryan Melanson

How to Learn
Data Structures
When your brain doesn't work

2021 \mathcal{BM}

Contents

1 Bitwise Operations	3
1.1 Operators	3
1.2 Common Operations	3
1.2.1 Set Bit	3
1.2.2 Clear Bit	3
1.2.3 Flip Bit	3
1.2.4 Clear	4
1.2.5 Little Endian to Big Endian	4
1.2.6 Big Endian to Little Endian	4
2 Array	5
2.1 Arrays in C	5
2.2 Static vs. Dynamic Arrays	5
2.2.1 Static Arrays	5
2.2.2 Dynamic Arrays	5
2.3 C Strings	6
3 Matrix	6
3.1 Normal Declaration	6
3.2 Dynamic Declaration	6
4 Linked List	6
4.1 Inserting	7
4.2 Deleting	7
5 Circular Linked List	7
5.1 Inserting	7
5.2 Deleting	7
6 Doubly Linked List	7
6.1 Inserting	8
6.2 Deleting	8
7 Binary Tree	8
7.1 Depth First Traversal	8
7.1.1 Pre-Order Traversal	8
7.1.2 In-Order Traversal	9
7.1.3 Post-Order Traversal	9
7.2 Breadth First Traversal	9

8 AVL Tree	10
9 Red-Black Tree	10
10 N-Ary Tree	10
11 Binary Search Tree	10
11.1 Searching	10
11.2 Inserting	11
12 B-Tree	12
13 Stack	12
13.1 Stack Array	12
13.2 Dynamic Stack Using Linked List	13
14 Queue	14
15 Heap	15
15.1 Maximum Heap	15
15.2 Minimum Heap	15
16 Hashes	15
16.1 Code	16
16.2 Hash Functions	17
16.2.1 Simple Hash Function for Strings	17
17 Graph	17

1 Bitwise Operations

1.1 Operators

Shift Left <<

Shift Right >>

Or |

And &

Invert ~

Exclusive Or ^

1.2 Common Operations

In each of the following cases, it should be noted that each byte in hex format is two digits (0x00). Therefore, moving a hex value by one byte is equivalent to shifting it 8 bits, or $0x00FF \ll 8 = 0xFF00$, and moving the hex value one space is half a byte, or 4 bits (a **nibble**).

1.2.1 Set Bit

To set the n th bit in value x , shift 1 (0x000000001) by n bits and AND them.

$$x \& (1 \ll n)$$

1.2.2 Clear Bit

To clear the n th bit in value x , shift 1 (0x000000001) by n bits and invert the ANDed value.

$$x \& \sim(1 \ll n)$$

1.2.3 Flip Bit

To flip the n th bit in value x , shift 1 (0x000000001) by n bits and XOR them.

$$x \wedge (1 \ll n)$$

1.2.4 Clear

To clear all values, AND the value with 0xFFFF.

$$x \ \& \ 0xFFFF$$

1.2.5 Little Endian to Big Endian

A little-endian system, in contrast, stores the least-significant byte at the smallest address.

Binary (Decimal: 149)	1	0	0	1	0	1	0	1
Bit weight	2^7	2^6	2^5	2^4	2^3	2^2	2^1	2^0
Bit position	MSB							LSB

In the case of the value 0x12345678, the **least significant byte** of this value 0x78 is stored in the lowest little Endian address, and subsequent bytes are stored in the next locations. The least significant byte can be considered the byte with the lowest value, when evaluated in typical bitwise fashion: 0x78563412

0x78 (0x004000)

0x56 (0x004001)

0x34 (0x004002)

0x12 (0x004003)

1.2.6 Big Endian to Little Endian

In a Big Endian representation of 0x12345678, the **most significant byte** (0x12) is stored at the lowest memory address: 0x12345678

0x12 (0x004000)

0x34 (0x004001)

0x56 (0x004002)

0x78 (0x004003)

To reverse these positions, the bytes can be isolated and bit-shifted by the appropriate number of bits to form the appropriate order.

```

(0x12345678 & 0x000000FF) << 24
(0x12345678 & 0x0000FF00) << 16
(0x12345678 & 0x00FF0000) << 8
(0x12345678 & 0xFF000000) >> 24

```

2 Array

Arrays are collections of same-type data items stored in a contiguous memory location. Knowing the data type, each element is located at an offset based on that data size. In other words, for `int data[]` the data at `data[1]` is located at `data[0] + sizeof(int)`.

40	55	63	17	22	68	89	97	89
0	1	2	3	4	5	6	7	8

2.1 Arrays in C

There is no index out-of-bound checking in C, so if access goes beyond the index boundaries of the array ($0-(n-1)$) there will be undefined behavior.

2.2 Static vs. Dynamic Arrays

Pointer and array accesses can be treated the same way in C, either by accessing the values by using the `[]` operator, or by incrementing the value of the pointer.

2.2.1 Static Arrays

In C, the size of an array should be decided at compile time by defining the array size either by declaring an array with size constraints such as `arr[10]` or by using `malloc` to define the required size. At run time this size will be used to allocate the required memory space.

2.2.2 Dynamic Arrays

In C++ an array can be passed a variable and the size can be determined for the memory allocation at run time.

2.3 C Strings

A C string is a pointer to an array of char data items which is terminated by the NULL character at the size limit. So, a char array of n items will contain data at elements $0-(n-1)$, while the value at n will be NULL. This allows for string operations to check for the boundary of memory space for the string object.

3 Matrix

The diagram shows a 3x3 matrix. Above the matrix, the word 'Columns' is written with a yellow arrow pointing down to the first column, which is labeled '[0]'. The other columns are labeled '[1]' and '[2]'. To the left of the matrix, the word 'Rows' is written with a green arrow pointing right to the first row, which is labeled '[0]'. The other rows are labeled '[1]' and '[2]'. The matrix contains the following values:

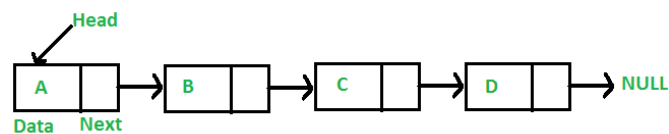
	[0]	[1]	[2]
[0]	1	2	3
[1]	4	5	6
[2]	7	8	9

3.1 Normal Declaration

3.2 Dynamic Declaration

4 Linked List

Unlike arrays, Linked Lists are dynamic and can grow by pointing to non-contiguous locations in memory using pointers. Extra memory is required when representing each pointer in the linked list, but it allows for easily inserting and deleting objects in the linked list.



Each node in the linked list consists of its data, and a pointer to the next object in the linked list. In the case that the head of the linked list is null.

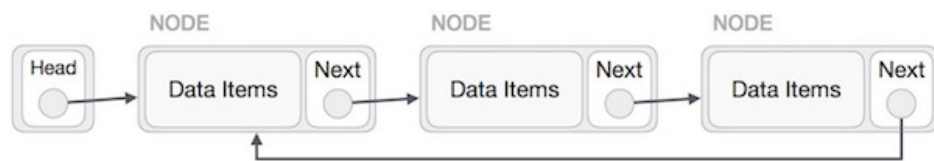
4.1 Inserting

4.2 Deleting

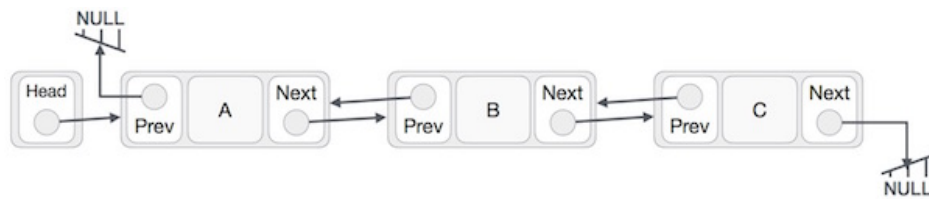
5 Circular Linked List

5.1 Inserting

5.2 Deleting



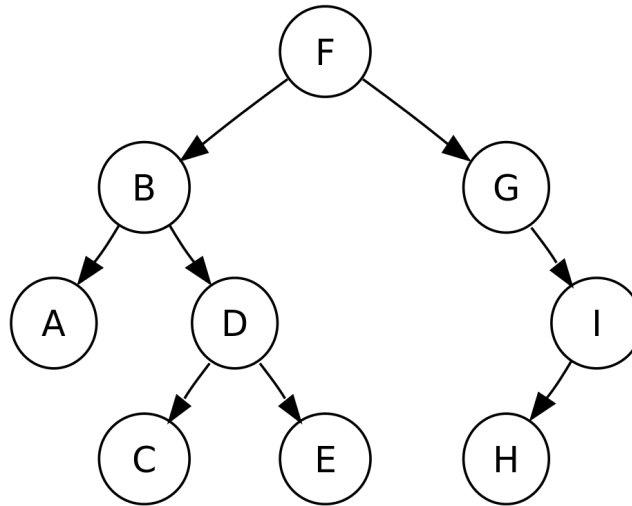
6 Doubly Linked List



6.1 Inserting

6.2 Deleting

7 Binary Tree



A Binary Tree is any tree organized in which each node, or **root** has at most two children, or **leaves**, hence *binary*, designated left and right.

7.1 Depth First Traversal

Depth First Traversal traverses the tree to its extents before backtracking and completing the traversal. It will explore until it reaches nodes with no children before moving to the nearest neighbor. The order of traversal can be categorized into **Pre-Order**, **In-Order** and **Post-Order** which determine which order the nodes (*Left, right, center*) are visited.

7.1.1 Pre-Order Traversal

```
void pre_order(struct Node* n) {  
    // print n->value  
  
    if (n->left)  
        pre_order(n->left);  
}
```

```
        if (n->right)
            pre_order(n->right);
    }
```

7.1.2 In-Order Traversal

```
void in_order(struct Node* n) {
    if (n->left)
        pre_order(n->left);

    // print n->value

    if (n->right)
        pre_order(n->right);
}
```

7.1.3 Post-Order Traversal

```
void post_order(struct Node* n) {
    if (n->left)
        pre_order(n->left);

    if (n->right)
        pre_order(n->right);

    // print n->value
}
```

7.2 Breadth First Traversal

Breadth first traversal traverses a tree by visiting all nodes at a given height, before descending the depth of the tree.

```
def bfs(self):
    queue = Queue()
    queue.put(self)

    while not queue.empty():
        current_node = queue.get()
```

```
print(current_node.value)

if current_node.left_child:
    queue.put(current_node.left_child)

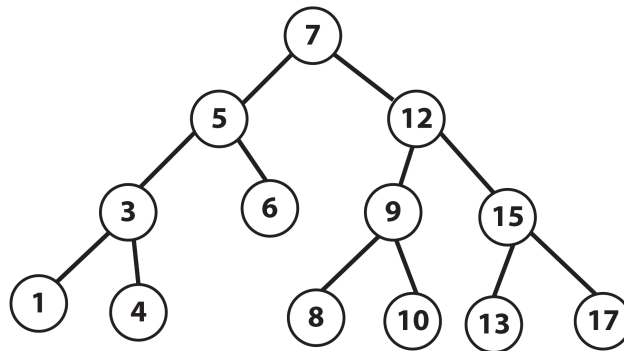
if current_node.right_child:
    queue.put(current_node.right_child)
```

8 AVL Tree

9 Red-Black Tree

10 N-Ary Tree

11 Binary Search Tree



A Binary Search Tree is one in which the value of the node stored on the left is less than the value of root, and the value of the node on the right is greater than the value of the root. By organizing a tree in this way, values can easily be found using a similar method as binary search which eliminates half of the remaining possibilities at each step.

11.1 Searching

```
bool contains(Node* curr, int value) {
    if (curr->data == value) { return true; }
```

```

    else if (value < curr->value) {
        if (curr->left) {
            return contains(curr->left, value);
        }
    } else {
        if (curr->right) {
            return contains(curr->right, value);
        }
    }
}

```

11.2 Inserting

To maintain the structure rules of the Binary Search Tree after insertion, the leaves of each node must be evaluated and the next route determined until a non-null spot that meets the criteria is determined. If the the current value of the node is greater than the value to be inserted, it will attempt to insert on the left if the left is currently null. If the left is not null, it will recursively evaluate the left node in the same way.

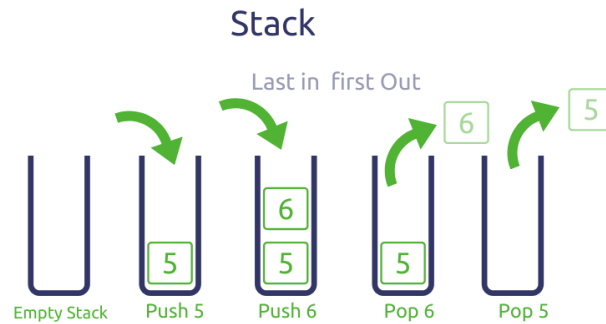
```

void insert(Node* new, Node* curr, int value) {
    if (value <= curr->value) {
        if (curr->left == NULL) {
            curr->left = new;
        } else {
            insert(curr->left, value);
        }
    } else {
        if (curr->right == NULL) {
            curr->right = new;
        } else {
            insert(curr->right, value);
        }
    }
}

```

12 B-Tree

13 Stack



13.1 Stack Array

A struct can be created which tracks the index of the top, and holds the allocated array. When popping a value, the array index should be wiped with a null value and top decremented. If the top index is out of range, it should throw an error to indicate a stack underflow.

```
/*
 * Stack implementation using array in C
 */

#define CAPACITY 100

typedef struct stack {
    int top;
    arr[CAPACITY];
} stack;

// Function to push a new element in stack
void push(stack* s, int val)
{
    s->arr[s->top++] = val;
}

// Function to pop element from top of stack
int pop(stack* s)
{
    if (top < 0) return -1;
```

```
    return s->arr[s->top--];  
}
```

13.2 Dynamic Stack Using Linked List

When the size of the array is not known and allocating a static array of its capacity may be wasteful, Linked Lists can be used to connect the items on the stack. When popping an object, the node pointer should be stored in a temporary pointer, then free'd once the new top is the old node's next pointer.

```
/*  
 * Stack implementation using linked list in C  
 */  
  
// Define stack node structure  
// The variable also instantiates this as a global  
struct stack {  
    int data;  
    struct stack *next;  
} *top;  
  
// Function to push a new element in stack.  
void push(int element)  
{  
    // Create a new node and push to stack  
    struct stack* newNode = malloc(sizeof(struct stack));  
  
    // Assign data to new node in stack  
    newNode->data = element;  
  
    // Next element after new node should be current top element  
    newNode->next = top;  
  
    // Make sure new node is always at top  
    top = newNode;  
}  
  
// Function to pop element from top of stack.  
int pop()  
{  
    // Check stack underflow  
    if (!top)
```

```

{
    printf("Stack is empty.\n");
    return -1;
}
// Hold pointer to node to be removed
stack* old = top;

int data = 0;

// Copy data from stack's top element
data = old->data;

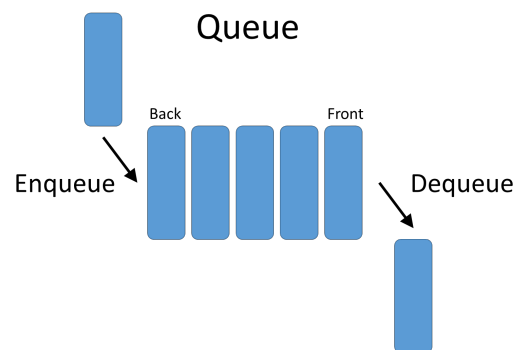
// Move top to its next element
top = old->next;

free(old);

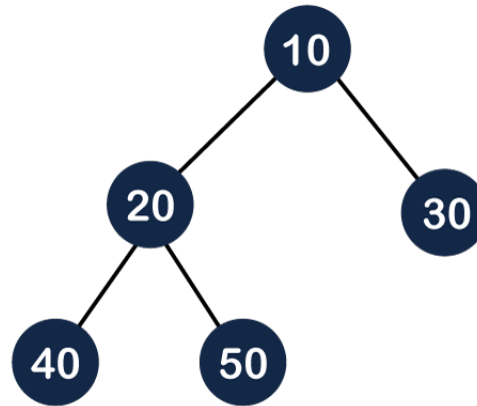
return data;
}

```

14 Queue



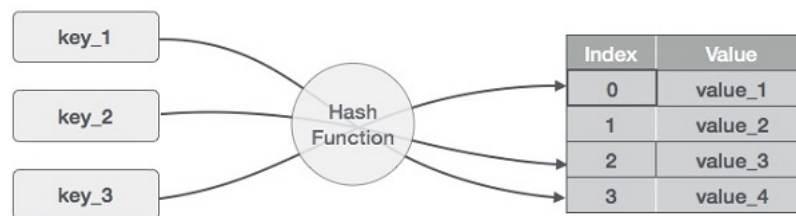
15 Heap



15.1 Maximum Heap

15.2 Minimum Heap

16 Hashes



A hash map combines features of a static array and a linked list, without being bound by issues such as inserting new values in a size-defined array, or searching for values in a linked list. A hash map has a preallocated buffer, and uses the value of the data to be inserted to generate a key, or index by hashing it. If a hash is properly defined, there will be no hash collisions, and data with an identical value will be stored in the identical spot in the hash map. This way, a value need only be calculated once, then stored in the hash map. Instead of generating the value again by calculation, the value can be retrieved from the hash map by visiting the pre-determined index.

The **Hash Set** is a hash map which stores no repeated values.

16.1 Code

```
int hash(int key) {
    int r = key % SIZE;
    return r < 0 ? r + SIZE : r;
}

void insert(int *values, int key, int value) {
    int index = hash(key);
    while (values[index]) {
        index++;
        index %= SIZE;
    }
    keys[index] = key;
    values[index] = value;
}

int search(int *keys, int *values, int key) {
    int index = hash(key);
    while (values[index]) {
        if (keys[index] == key) {
            return values[index];
        }
        index++;
        index %= SIZE;
    }
    return 0;
}

/* The requested value is checked for, in each step of the loop
   then the hash map is populated with the value if it doesn't
   already exist. This means the check will take O(n) */

int* main(int* nums, int numsSize, int target) {
    int keys[SIZE];
    int values[SIZE] = {0};
    for (int i = 0; i < numsSize; i++) {
        int complements = target - nums[i];
        int value = search(keys, values, complements);
        if (value) {
            int *indices = (int *) malloc(sizeof(int) * 2);
            indices[0] = value - 1;
            indices[1] = i;
            return indices;
        }
    }
}
```

```

    }
    insert(keys, values, nums[i], i + 1);
}
return NULL;
}

```

16.2 Hash Functions

16.2.1 Simple Hash Function for Strings

```

int hash_function(char* key) {
    int hash = toupper(key[0]) - 'A';
    /* Subtracting 'A' sets the index of alpha characters
       starting with 0 for 'A'. 'A' is 0, 'B' is 1, etc. */
    return hash % SIZE; // Constrain to the array size
}

```

If a collision occurs, linked lists can point to values with this same index. A good hash value would distribute values evenly across the map.

17 Graph

