

ItbToolkit-1.0

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# Chapter 1

## Data Structure Index

### 1.1 Data Structures

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## Chapter 2

# File Index

### 2.1 File List

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## Chapter 3

# Data Structure Documentation

### 3.1 Interp\_data Struct Reference

```
#include <src/interp_data.h>
```

#### Data Fields

- int **n**
- int **cur**
- double \* **x**
- double \* **y**
- double **max**
- double **min**
- gsl\_interp\_accel \* **acc**
- gsl\_interp \* **spline**

#### 3.1.1 Detailed Description

**Interp\_data** typedef structure

Used in inverting xi function to get eta

Definition at line 14 of file interp\_data.h.

#### 3.1.2 Field Documentation

##### 3.1.2.1 **gsl\_interp\_accel\* Interp\_data::acc**

minimum value op points to initialization

Definition at line 22 of file interp\_data.h.

##### 3.1.2.2 **int Interp\_data::cur**

Numbers of point to initialize spline procedure

Definition at line 17 of file interp\_data.h.

### 3.1.2.3 double Interp\_data::max

values of function in point x for spline initialization

Definition at line 20 of file `interp_data.h`.

### 3.1.2.4 double Interp\_data::min

maximum value of points to initialization

Definition at line 21 of file `interp_data.h`.

### 3.1.2.5 gsl\_interp\* Interp\_data::spline

LUT (look up table) for accelerating of interpolation

Definition at line 23 of file `interp_data.h`.

### 3.1.2.6 double\* Interp\_data::x

curvature of model for which we want interpolation

Definition at line 18 of file `interp_data.h`.

### 3.1.2.7 double\* Interp\_data::y

x points for spline initialization

Definition at line 19 of file `interp_data.h`.

The documentation for this struct was generated from the following file:

- [src/interp\\_data.h](#)

## 3.2 Ltb\_model Struct Reference

```
#include <src/ltb.h>
```

### Data Fields

- int **cur**
- size\_t [r\\_size](#)
- size\_t [t\\_size](#)
- gsl\_vector \* [r\\_vec](#)
- gsl\_vector \* [t\\_vec](#)
- gsl\_vector \* [tB\\_vec](#)
- gsl\_vector \* [E\\_vec](#)
- gsl\_vector \* [M\\_vec](#)
- gsl\_matrix \* [R\\_mat](#)
- double(\* [tB\\_fun](#))(double)
- double(\* [E\\_fun](#))(double)
- double(\* [M\\_fun](#))(double)
- double [tB\\_max](#)

### 3.2.1 Detailed Description

`Ltb_model` typedef struct Keeping all important information about specific LTB Model.

Definition at line 26 of file `ltb.h`.

### 3.2.2 Field Documentation

#### 3.2.2.1 `double(* Ltb_model::E_fun)(double)`

E function

Definition at line 38 of file `ltb.h`.

#### 3.2.2.2 `gsl_vector* Ltb_model::E_vec`

values of function E — `gsl_vector`

Definition at line 34 of file `ltb.h`.

#### 3.2.2.3 `double(* Ltb_model::M_fun)(double)`

M function

Definition at line 39 of file `ltb.h`.

#### 3.2.2.4 `gsl_vector* Ltb_model::M_vec`

values of function M — `gsl_vector`

Definition at line 35 of file `ltb.h`.

#### 3.2.2.5 `gsl_matrix* Ltb_model::R_mat`

Matrix of R (areal radius) — `gsl_matrix` of size `r_vec` x `r_mat`

Definition at line 36 of file `ltb.h`.

#### 3.2.2.6 `size_t Ltb_model::r_size`

Curvature of model values=-1,0,1 or -999 (error). Number of r points in model, size of `r_vec`.

Definition at line 29 of file `ltb.h`.

#### 3.2.2.7 `gsl_vector* Ltb_model::r_vec`

values of r — `gsl_vector`.

Definition at line 31 of file `ltb.h`.

#### 3.2.2.8 `size_t Ltb_model::t_size`

Number of t points in model. size of `t_vec`

Definition at line 30 of file `ltb.h`.

**3.2.2.9** `gsl_vector* Ltb_model::t_vec`

values of `t` — `gsl_vector`.

Definition at line 32 of file `ltb.h`.

**3.2.2.10** `double(* Ltb_model::tB_fun)(double)`

`tB` function

Definition at line 37 of file `ltb.h`.

**3.2.2.11** `double Ltb_model::tB_max`

maximum value of `tB` function, needed for normalization

Definition at line 40 of file `ltb.h`.

**3.2.2.12** `gsl_vector* Ltb_model::tB_vec`

values of function `t_{b}` — `gsl_vector`

Definition at line 33 of file `ltb.h`.

The documentation for this struct was generated from the following file:

- [src/ltb.h](#)

## Chapter 4

# File Documentation

### 4.1 src/gsl\_vector\_help\_functions.h File Reference

Custom extensions of `gsl_vector`, `gsl_matrix` from GSL library.

```
#include <string.h>
#include <gsl/gsl_errno.h>
#include <gsl/gsl_vector.h>
#include <gsl/gsl_matrix.h>
#include "ltb_error.h"
```

#### Macros

- `#define M(m, i, j) (gsl_matrix_get(m,i,j))`
- `#define MS(m, i, j, x) (gsl_matrix_set(m,i,j,x))`
- `#define V(v, i) (gsl_vector_get(v,i))`
- `#define VS(v, i, x) (gsl_vector_set(v,i,x))`

#### Functions

- `int gsl\_vector\_gen (gsl_vector *vec, unsigned int n, double min, double max)`  
*Generate  $n$  values from  $min$  to  $max$  and kept them in `gsl_vector` `vec`.*
- `int gsl\_vector\_gen\_fun (gsl_vector *vec, unsigned int n, gsl_vector *r, double(*f)(double))`  
*Generate  $n$  values of function  $f(r)$  and kept them in `gsl_vector` `vec`.*
- `int min (gsl_vector *vec, double x)`  
*If  $i$ th element of vector `vec` is greater than  $x$  -> set  $x$ .*
- `int max (gsl_vector *vec, double x)`  
*If  $i$ th element of vector `vec` is lesser than  $x$  -> set  $x$ .*
- `int gsl\_vector\_subtract (gsl_vector *a, gsl_vector *b)`  
*Subtraction of `gsl_vector`'s  $a=a-b$ .*
- `int gsl\_vector\_subtract\_out (gsl_vector *a, gsl_vector *b, gsl_vector *out)`  
*Subtraction of `gsl_vector`'s  $out=a-b$ .*
- `int gsl\_vector\_add\_constant\_out (gsl_vector *dest, gsl_vector *src, double x)`  
*Create new `gsl_vector`  $dest = src + x$ .*
- `int gsl\_vector\_set\_range (gsl_vector *vec, unsigned int min, unsigned int max, double val)`  
*Set value  $val$  in `vec` over indexes from  $min$  to  $max$ .*
- `int gsl\_vector\_load\_from\_file (gsl_vector *vec, char *fileName)`

- Load gsl\_vector vec from ascii file.*

  - int [gsl\\_write\\_mat](#) (gsl\_matrix \*matrix, char \*fileName, char \*header)

*Write gsl\_matrix matrix to ascii file fileName with header.*
- int [gsl\\_write\\_two\\_vec](#) (const gsl\_vector \*vec, const gsl\_vector \*vec2, char \*fileName)

*Write to vectors to file in two columns.*
- int [find\\_indices\\_leq](#) (const double \*data, const double x, unsigned int n, unsigned int start)

*Find first indices of array data less equal than x.*
- int [gsl\\_vector\\_find\\_indices\\_leq](#) (const gsl\_vector \*vec, const double x, unsigned int start)

*Find first indices of gsl\_vector vec less equal than x.*
- int [find\\_indices\\_geq](#) (const double \*data, const double x, unsigned int n, unsigned int start)

*Find first indices of array data greater equal than x.*
- int [gsl\\_vector\\_find\\_indices\\_geq](#) (const gsl\_vector \*vec, const double x, unsigned int start)

*Find first indices of gsl\_vector vec greater equal than x.*
- int [find\\_indices\\_range](#) (const double \*data, const double xa, const double xb, unsigned int n, unsigned int start, int \*ia, int \*ib)

*Find indices indices from range from xa to xb in array data.*
- int [gsl\\_vector\\_indices\\_range](#) (const gsl\_vector \*vec, const double xa, const double xb, unsigned int start, int \*ia, int \*ib)

*Find indices indices from range from xa to xb in gsl\_vector vec.*
- int [data\\_to\\_string](#) (double \*data, char \*format, unsigned int n, char \*out)

*Convert double array to string.*
- int [gsl\\_vector\\_to\\_string](#) (gsl\_vector \*vec, char \*format, char \*out)

*Convert gsl\_vector to string.*
- int [gsl\\_matrix\\_row\\_normalize](#) (gsl\_matrix \*mat)

*Normalize rows of matrix to 1.*

#### 4.1.1 Detailed Description

Custom extensions of `gsl_vector`, `gsl_matrix` from GSL library. Most of function from this file was used during testes. I only use functions for writing vectors and matrices and function for generating values from function ([gsl\\_vector\\_gen\\_fun\(\)](#) and [gsl\\_vector\\_gen\(\)](#))

Definition in file [gsl\\_vector\\_help\\_functions.h](#).

## 4.2 src/interp\_data.h File Reference

Structure and functions needed for interpolation  $\eta(x_i)$

```
#include <gsl/gsl_spline.h>
#include "ltb_error.h"
```

### Data Structures

- struct [Interp\\_data](#)

### Functions

- [Interp\\_data \\* interp\\_data\\_alloc](#) (double [max](#), double [min](#), unsigned int n, int cur, double(\*f)(double, int))
- Allocating Interp\_data.*
- void [interp\\_data\\_free](#) ([Interp\\_data](#) \*idata)



- Freeing [Interp\\_data](#) stuct.
- double [set\\_eta\\_max](#) (double xi\_max)  
Calculating max value for [Interp\\_data](#) structure.
- double [set\\_eta\\_min](#) (double xi\_min)  
Calculating min value for [Interp\\_data](#) structure.
- int [check\\_interp\\_data](#) ([Interp\\_data](#) \*eta\_interp, double xi\_min, double xi\_max, int cur)  
Check [Interp\\_data](#).

## Variables

- size\_t **eta\_n**
- double **dxi**  
Parameter used to calculate min and max value in [Interp\\_data](#). It telling how much bigger (lower) max (min) should be than max (min) value of xi. Used in [set\\_eta\\_max\(\)](#) and [set\\_eta\\_min\(\)](#) functions.

### 4.2.1 Detailed Description

Structure and functions needed for interpolation  $\eta(x_i)$

#### Author

Lukasz Matczynski

#### Copyright

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Definition in file [interp\\_data.h](#).

### 4.2.2 Function Documentation

**4.2.2.1** int [check\\_interp\\_data](#) ( [Interp\\_data](#) \* *eta\_interp*, double *xi\_min*, double *xi\_max*, int *cur* )

Check [Interp\\_data](#).

Return error if  $cur \neq eta\_interp \rightarrow cur$ ,  $xi\_min < eta\_interp \rightarrow min$  or  $xi\_max > eta\_interp \rightarrow max$

#### Parameters

in	<i>eta_interp</i>	— <a href="#">Interp_data</a> to check
in	<i>xi_min</i>	
in	<i>xi_max</i>	
in	<i>cur</i>	curvature parameter

Definition at line 137 of file [interp\\_data.c](#).

**4.2.2.2** [Interp\\_data\\*](#) [interp\\_data\\_alloc](#) ( double *max*, double *min*, unsigned int *n*, int *cur*, double(\*) (double, int) *f* )

Allocating [Interp\\_data](#).

**Parameters**

in	<i>max</i>	— maximum value of points to initialize spline function
in	<i>min</i>	— minimum value of points to initialize spline function
in	<i>n</i>	— number of points to initialize spline function
in	<i>cur</i>	curvature of model for which we want interpolate (xi)
in	<i>f</i>	pointer to function calculating eta

**Returns**

pointer to allocate [Interp\\_data](#) stuct or NULL pointer

Definition at line 7 of file `interp_data.c`.

**4.2.2.3 void interp\_data\_free ( Interp\_data \* idata )**

Freeing [Interp\\_data](#) stuct.

**Parameters**

in	<i>idata</i>	pointer to <a href="#">Interp_data</a> structure which we want to free
----	--------------	------------------------------------------------------------------------

Definition at line 77 of file `interp_data.c`.

**4.2.2.4 double set\_eta\_max ( double xi\_max )**

Calculating max value for [Interp\\_data](#) structure.

**Parameters**

in	<i>xi_max</i>	maximum value of xi
----	---------------	---------------------

Definition at line 103 of file `interp_data.c`.

**4.2.2.5 double set\_eta\_min ( double xi\_min )**

Calculating min value for [Interp\\_data](#) structure.

**Parameters**

in	<i>xi_min</i>	minimum value of xi
----	---------------	---------------------

Definition at line 120 of file `interp_data.c`.

**4.2.3 Variable Documentation****4.2.3.1 double dxi**

Parameter used to calculate min and max value in [Interp\\_data](#). It telling how much bigger (lower) max (min) should be than max (min) value of xi. Used in [set\\_eta\\_max\(\)](#) and [set\\_eta\\_min\(\)](#) functions.

Default numbers of points to initialize spline interpolation

**See Also**

[set\\_eta\\_max\(\)](#)  
[set\\_eta\\_min\(\)](#)

Definition at line 35 of file `interp_data.h`.

## 4.3 src/ltb.h File Reference

Ltb model function.

```
#include <stdio.h>
#include <stdlib.h>
#include <math.h>
#include <gsl/gsl_spline.h>
#include "ltb_error.h"
#include "gsl_vector_help_functions.h"
#include "phys_constant.h"
#include "interp_data.h"
#include <omp.h>
```

### Data Structures

- struct [Ltb\\_model](#)

### Functions

- int [set\\_cur](#) (const [gsl\\_vector](#) \*E\_vec, int \*cur)  
*Setting curvature of model.*
- int [cur\\_fun](#) (double E)  
*Calculate curvature from E.*
- double [Ricci\\_fun](#) (double E, double E\_r, double R, double R\_r)  
*Calculate single values of Ricci Tensor.*
- int [ltb\\_model\\_Ricci](#) ([Ltb\\_model](#) \*ltb, [gsl\\_vector](#) \*E\_r, [gsl\\_matrix](#) \*R\_r, [gsl\\_matrix](#) \*Ric)  
*Calculate matrix of Ricci Tensor values.*
- double [rho\\_fun](#) (double M\_r, double R, double R\_r)
- int [ltb\\_model\\_rho](#) ([Ltb\\_model](#) \*ltb, [gsl\\_vector](#) \*M\_r, [gsl\\_matrix](#) \*R\_r, [gsl\\_matrix](#) \*rho\_mat)  
*Calculate matrix of density in LTB model.*
- double [grr\\_sq\\_fun](#) (double R\_r, double E)  
*Calculate root square of radial part of LTB metrics.*
- int [ltb\\_model\\_grr\\_sq](#) ([gsl\\_vector](#) \*E, [gsl\\_matrix](#) \*R\_r, [gsl\\_matrix](#) \*grr\_sq)  
*Calculate matrix of root square of radial part of LTB model metrics .*
- double [exp\\_fun](#) (double R, double R\_r, double R\_t, double R\_rt)  
*Calculate expansion parameter in LTB model.*
- int [ltb\\_model\\_exp](#) ([Ltb\\_model](#) \*ltb, [gsl\\_matrix](#) \*R\_r, [gsl\\_matrix](#) \*R\_t, [gsl\\_matrix](#) \*R\_rt, [gsl\\_matrix](#) \*exp)  
*Calculate matrix of expansion parameters in LTB model.*
- int [get\\_chi](#) (int cur, [gsl\\_vector](#) \*E, [gsl\\_vector](#) \*chi\_vec)  
*Calculate vector of chi values.*
- double [fiFlat](#) (double eta)  
*Calculate values of fi in model with curvature = 0.*
- double [fiSpherical](#) (double eta)  
*Calculate values of fi in model with curvature > 0.*
- double [fiHyperbolic](#) (double eta)  
*Calculate values of fi in model with curvature < 0.*
- double [fi](#) (double eta, int cur)  
*Calculate values of fi.*
- double [xi\\_fun](#) (double tB, double M, double E, double t, int cur)  
*Calculet xi value using value of tB,M,E functions.*

- int [get\\_xi](#) (gsl\_vector \*tB, gsl\_vector \*M, gsl\_vector \*t, gsl\_vector \*E, int cur, gsl\_matrix \*xi\_mat)  
*Calculate xi matrix using values of tB, M, functions.*
- double [xiHyperbolic](#) (double eta)  
*Calculate xi value in model with curvature < 0.*
- double [xiFlat](#) (double eta)  
*Calculate values of xi in model with curvature = 0.*
- double [xiSpherical](#) (double eta)  
*Calculate values of xi in model with curvature > 0.*
- double [xi\\_fun\\_from\\_eta](#) (double eta, int cur)  
*Calculate values of xi.*
- [Interp\\_data](#) \* [interp\\_data\\_alloc\\_for\\_ltb](#) (const [Ltb\\_model](#) \*model, size\_t n)  
*Allocating interpolation data for specific [Ltb\\_model](#).*
- int [get\\_min\\_max\\_for\\_interp](#) (const [Ltb\\_model](#) \*model, double \*max, double \*min)  
*Finding value of max and min for [Interp\\_data](#).*
- double [eta\\_fun](#) (double xi, int cur, [Interp\\_data](#) \*eta\_interp)  
*Calculate values of eta from xi.*
- double [R\\_fun](#) (double M, double E, double eta, int cur)  
*Calculate R (areal radius) value.*
- [Ltb\\_model](#) \* [ltb\\_model\\_alloc](#) (size\_t \_r\_size, size\_t \_t\_size, double(\*M)(double), double(\*E)(double), double(\*tB)(double))  
*Allocating [Ltb\\_model](#) structure.*
- [Ltb\\_model](#) \* [ltb\\_model\\_alloc\\_from\\_vec](#) (gsl\_vector \*\_r\_vec, gsl\_vector \*\_t\_vec, double(\*M)(double), double(\*E)(double), double(\*tB)(double))  
*Allocating [Ltb\\_model](#) structure from r vector and t vector.*
- [Ltb\\_model](#) \* [ltb\\_model\\_cpy](#) ([Ltb\\_model](#) \*src)  
*Allocating [Ltb\\_model](#) making copy of src.*
- void [ltb\\_model\\_free](#) ([Ltb\\_model](#) \*model)  
*Freeing [Ltb\\_model](#) structure.*
- int [ltb\\_model\\_set\\_fun](#) ([Ltb\\_model](#) \*model)  
*Setting values of tB, M, E function for [Ltb\\_model](#) model.*
- int [ltb\\_model\\_set\\_R](#) ([Ltb\\_model](#) \*model, [Interp\\_data](#) \*eta\_interp)  
*Calculating matrix of function R(t,r)*
- int [ltb\\_model\\_write\\_fun](#) (const [Ltb\\_model](#) \*model, char \*file\_name)
- double [R\\_t\\_analytic\\_fun](#) (double R, double M, double E, int sgn)  
*Calculating partial derivative of R over t.*
- int [ltb\\_model\\_R\\_t](#) (const [Ltb\\_model](#) \*model, [Interp\\_data](#) \*eta\_interp, gsl\_matrix \*R\_t)  
*Calculating partial derivatives of R over t.*
- double [R\\_r\\_analytic\\_fun](#) (double R, double R\_t, double E, double E\_r, double M, double M\_r, double tB, double tB\_r, double t)  
*Calculating partial derivative of R over r.*
- int [ltb\\_model\\_R\\_r](#) (const [Ltb\\_model](#) \*model, const gsl\_matrix \*R\_t, const gsl\_vector \*E\_r\_vec, const gsl\_vector \*M\_r\_vec, const gsl\_vector \*tB\_r\_vec, gsl\_matrix \*R\_r)  
*Calculating value of partial derivatives of R over r.*
- double [R\\_rt\\_analytic\\_fun](#) (double R, double R\_r, double R\_t, double E\_r, double M, double M\_r)  
*Calculating value of partial mixed derivative of R over r and t.*
- int [ltb\\_model\\_R\\_rt](#) (const [Ltb\\_model](#) \*model, const gsl\_matrix \*R\_r, const gsl\_matrix \*R\_t, const gsl\_vector \*E\_r, const gsl\_vector \*M\_r, gsl\_matrix \*R\_rt)  
*Calculating value of partial mixed derivative of R over r and t.*

## Variables

- int **tB\_norm**
- unsigned int **chunk\_size**

### 4.3.1 Detailed Description

Ltb model function. Details(TODO)

#### Author

Lukasz Matczynski

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Definition in file [ltb.h](#).

### 4.3.2 Function Documentation

#### 4.3.2.1 int cur\_fun ( double *E* )

Calculate curvature from *E*.

##### Parameters

in	<i>E</i>	value of $E(r)$ function from LTB model
----	----------	-----------------------------------------

##### Returns

curvature parameter from set {-1,0,1}

Definition at line 170 of file ltb.c.

#### 4.3.2.2 double eta\_fun ( double *xi*, int *cur*, Interp\_data \* *eta\_interp* )

Calculate values of eta from *xi*.

If curvature (*cur* = 0) is flat — use analytic formula for  $\eta(x_i)$ . Otherwise use *eta\_interp* parameter for spline interpolation of  $\eta(x_i)$ . If *cur* != 0 && *eta\_interp* == NULL throw up error and return GSL\_NAN.

##### Parameters

in	<i>xi</i>	value of <i>xi</i>
in	<i>cur</i>	curvature parameter
in	<i>eta_interp</i>	<a href="#">Interp_data</a> needed for spline interpolation Using gsl spline interpolation

##### Returns

Single eta value.

Definition at line 423 of file ltb.c.

#### 4.3.2.3 double exp\_fun ( double *R*, double *R\_r*, double *R\_t*, double *R\_rt* )

Calculate expansion parameter in LTB model.

**Parameters**

in	$R_r$	partial derivative of areal radius $R$ ( $\frac{\partial R}{\partial r}$ ) in point $(t,r)$
in	$R_t$	partial derivative of areal radius $R$ ( $\frac{\partial R}{\partial t}$ ) in point $(t,r)$
in	$R_{rt}$	partial derivative of areal radius $R$ ( $\frac{\partial^2 R}{\partial r \partial t}$ ) in point $(t,r)$

**Returns**

single value of expansion parameter

Definition at line 113 of file Itb.c.

**4.3.2.4 double fi ( double eta, int cur )**

Calculate values of fi.

Depending on cur parameter choosing function to calculate  $fi(eta)$

**Parameters**

in	$eta$	value of eta
in	$cur$	curvature parameter

**Returns**

fi value

**See Also**

[fiFlat\(\)](#)  
[fiSpherical\(\)](#)  
[fiHyperbolic\(\)](#)

**4.3.2.5 double fiFlat ( double eta )**

Calculate values of fi in model with curvature = 0.

**Returns**

fi value

**See Also**

[fi\(\)](#)

Definition at line 276 of file Itb.c.

**4.3.2.6 double fiHyperbolic ( double eta )**

Calculate values of fi in model with curvature < 0.

**Returns**

fi value

**See Also**

[fi\(\)](#)

Definition at line 281 of file Itb.c.

4.3.2.7 double fiSpherical ( double *eta* )

Calculate values of fi in model with curvature  $> 0$ .

## Returns

fi value

## See Also

[fi\(\)](#)

Definition at line 271 of file ltb.c.

4.3.2.8 int get\_chi ( int *cur*, gsl\_vector \* *E*, gsl\_vector \* *chi\_vec* )

Calculate vector of chi values.

## Parameters

in	<i>cur</i>	curvature parameter
in	<i>E</i>	value of $E(r)$ LTB function
out	<i>chi_vec</i>	vector of chi values

## Returns

error code or GSL\_SUCCESS;

Definition at line 186 of file ltb.c.

4.3.2.9 int get\_min\_max\_for\_interp ( const Ltb\_model \* *model*, double \* *max*, double \* *min* )

Finding value of max and min for [Interp\\_data](#).

## Parameters

in	<i>model</i>	pointer to <a href="#">Ltb_model</a>
out	<i>max</i>	— max value of points to initialize spline procedure [out] min — min value of points to initialize spline procedure

## Returns

GSL\_SUCCESS or error code

Definition at line 344 of file ltb.c.

4.3.2.10 int get\_xi ( gsl\_vector \* *tB*, gsl\_vector \* *M*, gsl\_vector \* *t*, gsl\_vector \* *E*, int *cur*, gsl\_matrix \* *xi\_mat* )

Calculate xi matrix using values of *tB*, *M*, functions.

If *cur* parameter is not in  $\{-1, 0, 1\}$ , return GSL\_NAN and throw up error

## Parameters

in	$tB$	values of $tB$ function
in	$M$	values of $M$ function
in	$E$	values of $E$ function
in	$t$	values of time coordinates
out	$xi\_mat$	values of $xi$

**Returns**

GSL\_SUCESS or error code

**See Also**

[xi\\_fun\\_from\\_eta\(\)](#)

Definition at line 231 of file ltb.c.

**4.3.2.11 double grr\_sq\_fun ( double  $R_r$ , double  $E$  )**

Calculate root square of radial part of LTB metrics.

**Parameters**

in	$R_r$	partial derivative of areal radius $R ( \frac{\partial R}{\partial r} )$ in point $(t,r)$
in	$E$	value of $E(r)$ LTB function

**Returns**

value or sqrt of radial part of LTB metrics

Definition at line 76 of file ltb.c.

**4.3.2.12 Interp\_data\* interp\_data\_alloc\_for\_ltb ( const Ltb\_model \*  $model$ , size\_t  $n$  )**

Allocating interpolation data for specific [Ltb\\_model](#).

**Parameters**

in	$model$	pointer to <a href="#">Ltb_model</a>
in	$n$	numbers of point to initialize spline

**Returns**

pointer to Interp\_data\* (or null pointer)

Definition at line 396 of file ltb.c.

**4.3.2.13 Ltb\_model\* ltb\_model\_alloc ( size\_t  $r\_size$ , size\_t  $t\_size$ , double(\*)( $double$ )  $M$ , double(\*)( $double$ )  $E$ , double(\*)( $double$ )  $tB$  )**

Allocating [Ltb\\_model](#) structure.

$r\_size$  and  $t\_size$  have to be  $> 0$  otherwise throw up error and return NULL ptr. If can't allocate any of [Ltb\\_model](#) pointers return NULL.



## Parameters

in	<code>_r_size</code>	number of $r$ points (radial coordinates)
in	<code>_t_size</code>	number of $t$ points (time coordinates)
in	$M$	pointer to $M(r)$ function
in	$E$	pointer to $E(r)$ function
in	$tB$	pointer to $tB(r)$ function

## Returns

pointer to [Ltb\\_model](#)

## See Also

[ltb\\_model\\_alloc\\_from\\_vec\(\)](#)  
[ltb\\_model\\_cpy\(\)](#)

Definition at line 519 of file ltb.c.

**4.3.2.14** `Ltb_model* ltb_model_alloc_from_vec ( gsl_vector * _r_vec, gsl_vector * _t_vec, double(*)(double)  $M$ , double(*)(double)  $E$ , double(*)(double)  $tB$  )`

Allocating [Ltb\\_model](#) structure from  $r$  vector and  $t$  vector.

After allocating [Ltb\\_model](#) with [ltb\\_model\\_alloc\(\)](#) function (with  $r$  parameter equal to `_r_vec->size` and  $t$  parameter to `_t_vec->size`) copy `_r_vec` and `_t_vec` to [Ltb\\_model](#) `r_vec` and `t_vec`. If copying data fail throw up error and return null.

## Parameters

in	<code>_r_vec</code>	vector of $r$ values (radial coordinate)
in	<code>_t_vec</code>	vector of $t$ values (time coordinate)
in	$M$	pointer to $M(r)$ function
in	$E$	pointer to $E(r)$ function
in	$tB$	pointer to $tB(r)$ function

## Returns

pointer to [Ltb\\_model](#)

## See Also

[ltb\\_model\\_alloc\(\)](#)  
[ltb\\_model\\_cpy\(\)](#)

Definition at line 597 of file ltb.c.

**4.3.2.15** `Ltb_model* ltb_model_cpy ( Ltb_model * src )`

Allocating [Ltb\\_model](#) making copy of `src`.

Allocate [Ltb\\_model](#) with [ltb\\_model\\_alloc\(\)](#) function, after this copying of data from [Ltb\\_model](#) `*src` to newly created. If copying of any data fail throw up error and return NULL.

## Parameters

in	<i>src</i>	<a href="#">Ltb_model</a> to copy
----	------------	-----------------------------------

## Returns

pointer to [Ltb\\_model](#)

## See Also

[ltb\\_model\\_alloc\\_from\\_vec\(\)](#)  
[ltb\\_model\\_alloc\(\)](#)

Definition at line 634 of file ltb.c.

**4.3.2.16** `int ltb_model_exp ( Ltb_model * ltb, gsl_matrix * R_r, gsl_matrix * R_t, gsl_matrix * R_rt, gsl_matrix * exp )`

Calculate matrix of expansion parameters in LTB model.

## Parameters

in	<i>ltb</i>	pointer to <a href="#">Ltb_model</a> (using <code>ltb-&gt;R_mat</code> )
in	<i>R_r</i>	partial derivative of areal radius $R$ ( $\frac{\partial R}{\partial r}$ ) in point $(t,r)$
in	<i>R_t</i>	partial derivative of areal radius $R$ ( $\frac{\partial R}{\partial t}$ ) in point $(t,r)$
in	<i>R_rt</i>	partial derivative of areal radius $R$ ( $\frac{\partial^2 R}{\partial r \partial t}$ ) in point $(t,r)$
out	<i>exp</i>	matrix of expansion parameters

## Returns

error code or `GSL_SUCCESS`;

## See Also

`expansion_fun()`

Definition at line 119 of file ltb.c.

**4.3.2.17** `void ltb_model_free ( Ltb_model * model )`

Freeing [Ltb\\_model](#) structure.

## Parameters

in	<i>model</i>	pointer to <a href="#">Ltb_model</a>
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Definition at line 689 of file ltb.c.

**4.3.2.18** `int ltb_model_grr_sq ( gsl_vector * E, gsl_matrix * R_r, gsl_matrix * grr_sq )`

Calculate matrix of root square of radial part of LTB model metrics .

## Parameters

---

in	$E$	value of $E(r)$ LTB function
in	$R_r$	partial derivative of areal radius $R$ ( $\frac{\partial R}{\partial r}$ ) in point $(t,r)$
out	$matrix$	of $grr\_sq$ values

**Returns**

error code or GSL\_SUCCESS;

**See Also**

[grr\\_sq\\_fun\(\)](#)

Definition at line 87 of file ltb.c.

**4.3.2.19** `int ltb_model_R_r ( const Ltb_model * model, const gsl_matrix * R_t, const gsl_vector * E_r_vec, const gsl_vector * M_r_vec, const gsl_vector * tB_r_vec, gsl_matrix * R_r )`

Calculating value of partial derivatives of  $R$  over  $r$ .

**Parameters**

in	$R$	areal radius value
in	$R_t$	partial derivative of $R$ over $t$
in	$E$	LTB $E(r)$ function
in	$E_r$	derivative of $E(r)$ function
in	$M$	LTB $M(r)$ function
in	$M_r$	derivative of $M(r)$ function
in	$tB$	LTB $tB(r)$ function
in	$tB_r$	derivative of $tB(r)$ function
out	$R_r$	matrix of partial derivative of $R$ over $r$

**Returns**

GSL\_SUCCESS or error code

**See Also**

`ltb_model_R_r_analytic_fun()`

Definition at line 910 of file ltb.c.

**4.3.2.20** `int ltb_model_R_rt ( const Ltb_model * model, const gsl_matrix * R_r, const gsl_matrix * R_t, const gsl_vector * E_r, const gsl_vector * M_r, gsl_matrix * R_rt )`

Calculating value of partial mixed derivative of  $R$  over  $r$  and  $t$ .

**Parameters**

in	$model$	pointer to <a href="#">Ltb_model</a>
in	$R_r$	partial derivative of $R$ over $t$
in	$R_t$	partial derivative of $R$ over $t$
in	$E_r$	derivative of $E(r)$ function

in	$M_r$	derivative of $M(r)$ function
out	$R_{rt}$	matrix of mixed partial derivative

**Returns**

GSL\_SUCCESS or error code

**See Also**

[R\\_rt\\_analytic\\_fun\(\)](#)

Definition at line 955 of file ltb.c.

4.3.2.21 `int ltb_model_R_t ( const Ltb_model * model, Interp_data * eta_interp, gsl_matrix * R_t )`

Calculating partial derivatives of  $R$  over  $t$ .

**Parameters**

in	$model$	pointer to <a href="#">Ltb_model</a>
in	$eta\_interp$	pointer to <a href="#">Interp_data</a> needed for calculating sign of derivative.
out	$R_t$	matrix of derivatives

**Returns**

GSL\_SUCCESS or error code

**See Also**

[R\\_t\\_analytic\\_fun\(\)](#)

Definition at line 860 of file ltb.c.

4.3.2.22 `int ltb_model_rho ( Ltb_model * ltb, gsl_vector * M_r, gsl_matrix * R_r, gsl_matrix * rho_mat )`

Calculate matrix of density in LTB model.

All pointers should be allocated otherwise return GSL\_EFAULT. All matrix should have equals dimensions all vector should have size equal matrices second dimension otherwise return GSL\_EBADLEN.

**Parameters**

in	$ltb$	pointer to <a href="#">Ltb_model</a> (using <code>ltb-&gt;R_mat</code> )
in	$M_r$	first derivative of $M(r)$ function in point $r$
in	$R_r$	partial derivative of areal radius $R ( \frac{\partial R}{\partial r} )$ in point $(t,r)$
out	$\rho\_mat$	matrix of density

**Returns**

error code or GSL\_SUCCESS;

**See Also**

[rho\\_fun\(\)](#)

Definition at line 47 of file ltb.c.

#### 4.3.2.23 int ltb\_model\_Ricci ( Ltb\_model \* ltb, gsl\_vector \* E\_r, gsl\_matrix \* R\_r, gsl\_matrix \* Ric )

Calculate matrix of Ricci Tensor values.

All pointers should be allocated otherwise return GSL\_EFAULT. All matrix should have equals dimensions all vector should have size equal matrices second dimension otherwise return GSL\_EBADLEN.

##### Parameters

in	<i>ltb</i>	pointer to <a href="#">Ltb_model</a> (using <code>ltb-&gt;R_mat</code> )
in	<i>E_r</i>	first derivative of E
in	<i>R_r</i>	partial derivative over r of R
out	<i>Ric</i>	pointer to Ricci matrix

##### Returns

error code or GSL\_SUCCESS;

##### See Also

[Ricci\\_fun\(\)](#)

Definition at line 13 of file ltb.c.

#### 4.3.2.24 int ltb\_model\_set\_fun ( Ltb\_model \* model )

Setting values of tB, M, E function for [Ltb\\_model](#) model.

Calculating values of LTB functions (*M*, *E*, *tB*) using pointers to function `model->M_fun`, `model->E_fun`, `model->tB_fun`. If one of this pointers is NULL return GSL\_EFAULT. Calculated values are stored in [Ltb\\_model](#) `gsl_vectors` (`M_vec`, `E_vec` and `tB_vec`). For *tB* is calculate `model->tB_max` if global parameter `tB_norm` is set values in `tB_vec` will be normalized (`gsl_vector_max(tB_vec) == 0`). Depending on `E_vec` curvature parameter is calculated ( $E < 0 - \text{cur} = 1$ ,  $E > 0 - \text{cur} = -1$ ,  $E == 0 \text{ cur} = 0$ , otherwise error will be throw up and `cur == -999`).

##### Parameters

in	<i>model</i>	pointer to <a href="#">Ltb_model</a>
----	--------------	--------------------------------------

##### Returns

GSL\_SUCCESS or error code

##### See Also

[ltb\\_model\\_alloc\(\)](#)  
[ltb\\_model\\_set\\_R](#)

Definition at line 730 of file ltb.c.

#### 4.3.2.25 int ltb\_model\_set\_R ( Ltb\_model \* model, Interp\_data \* eta\_interp )

Calculating matrix of function  $R(t,r)$

`eta_interp` pointer is needed to calculate *eta* in curved model. If you only interested in flat model you can pass NULL in place of `eta_interp`.

**Parameters**

in	<i>model</i>	pointer to <a href="#">Ltb_model</a>
in	<i>eta_interp</i>	pointer to Inter_data structure

**Returns**

GSL\_SUCCESS or error code

**See Also**

[ltb\\_model\\_set\\_fun\(\)](#)  
[ltb\\_model\\_alloc\(\)](#)

Definition at line 472 of file ltb.c.

4.3.2.26 `int ltb_model_write_fun ( const Ltb_model * model, char * file_name )`

Write basis function E,tB,M of [Ltb\\_model](#) model to ascii file file\_name

Writing to file content of *r\_vec*, *M\_vec*, *E\_vec*, *tB\_vec* in four columns.

**Parameters**

in	<i>model</i>	pointer to <a href="#">Ltb_model</a> with functions to write
in	<i>file_name</i>	name of file

**Returns**

GSL\_SUCCESS or error code

**See Also**

[ltb\\_model\\_write\\_fun\(\)](#)

Definition at line 793 of file ltb.c.

4.3.2.27 `double R_fun ( double M, double E, double eta, int cur )`

Calculate *R* (areal radius) value.

**Parameters**

in	<i>M</i>	value of <i>M(r)</i> function
in	<i>E</i>	value of <i>E(r)</i> function
in	<i>tB</i>	value of <i>tB(r)</i> function
in	<i>eta</i>	value of eta
in	<i>cur</i>	value of curvature parameter

**Returns**

value of R

**See Also**

[ltb\\_model\\_set\\_R\(\)](#)

Definition at line 454 of file ltb.c.

4.3.2.28 `double R_r_analytic_fun ( double R, double R_t, double E, double E_r, double M, double M_r, double tB, double tB_r, double t )`

Calculating partial derivative of  $R$  over  $r$ .

**Parameters**

in	$R$	areal radius value
in	$M$	value of $M(r)$ function
in	$E$	value of $E(r)$ function
in	$sgn$	sign of derivative (have to be calculated separately)

**Returns**

Partial derivative of  $R$  over  $r$

**See Also**

[ltb\\_model\\_R\\_r\(\)](#)

Definition at line 894 of file ltb.c.

**4.3.2.29** `double R_rt_analytic_fun ( double  $R$ , double  $R_r$ , double  $R_t$ , double  $E_r$ , double  $M$ , double  $M_r$  )`

Calculating value of partial mixed derivative of  $R$  over  $r$  and  $t$ .

**Parameters**

in	$R$	areal radius value
in	$R_r$	partial derivative of $R$ over $t$
in	$R_t$	partial derivative of $R$ over $t$
in	$E_r$	derivative of $E(r)$ function
in	$M$	$LTB M(r)$ function
in	$M_r$	derivative of $M(r)$ function

**Returns**

value of partial mixed derivative of  $R$  over  $r$  and  $t$

**See Also**

[ltb\\_model\\_R\\_rt\(\)](#)

Definition at line 950 of file ltb.c.

**4.3.2.30** `double R_t_analytic_fun ( double  $R$ , double  $M$ , double  $E$ , int  $sgn$  )`

Calculating partial derivative of  $R$  over  $t$ .

**Parameters**

in	$R$	areal radius value
in	$M$	value of $M(r)$ function
in	$E$	value of $E(r)$ function
in	$sgn$	sign of derivative (have to be calculated separately)

**Returns**

Partial derivative of  $R$  over  $t$

**See Also**

[ltb\\_model\\_R\\_t\(\)](#)

Definition at line 822 of file ltb.c.



4.3.2.31 double rho\_fun ( double *M\_r*, double *R*, double *R\_r* )

Calculate density in point (*t*,*r*).

Calculate density using equation [?] :

$$\rho = \frac{M_{,r}}{4\pi R^2 R_{,r}}$$

## Parameters

<i>M_r</i>	first derivative of <i>M(r)</i> function in point <i>r</i>
<i>R</i>	value of areal radius in point ( <i>t</i> , <i>r</i> )
<i>R_r</i>	partial derivative of areal radius <i>R</i> ( $\frac{\partial R}{\partial r}$ ) in point ( <i>t</i> , <i>r</i> )

## Returns

value of density

## See Also

[lrb\\_model\\_rho\(\)](#)

Definition at line 42 of file lrb.c.

4.3.2.32 double Ricci\_fun ( double *E*, double *E\_r*, double *R*, double *R\_r* )

Calculate single values of Ricci Tensor.

## Parameters

in	<i>E</i>	value of LTB <i>E(r)</i> function
in	<i>E_r</i>	first derivative of <i>E</i>
in	<i>R</i>	areal radius
in	<i>R_r</i>	partial derivative over <i>r</i> of <i>R</i>

## Returns

value of Ricci Tensor (double)

Definition at line 8 of file lrb.c.

4.3.2.33 int set\_cur ( const gsl\_vector \* *E\_vec*, int \* *cur* )

Setting curvature of model.

Checking all values of *E* *gsl\_vector* If all values have the same sign set *cur* parameter and return *GSL\_SUCCESS*.  
If *E* values have different sign set *cur* parameter to error value -999 and return *LTB\_ECURV*.

## Parameters

in	<i>E</i>	vector of values of <i>E(r)</i> LTB function
out	<i>cur</i>	curvature parameter

## Returns

*GSL\_SUCCESS* or *LTB\_ECURV*

## See Also

[set\\_cur\(\)](#)

Definition at line 152 of file lrb.c.

#### 4.3.2.34 double xi\_fun ( double *tB*, double *M*, double *E*, double *t*, int *cur* )

Calculates xi value using value of *tB*, *M*, *E* functions.

##### Parameters

in	<i>tB</i>	value of <i>tB</i> function
in	<i>M</i>	value of <i>M</i> function
in	<i>E</i>	value of <i>E</i> function
in	<i>t</i>	value of time coordinate
in	<i>cur</i>	curvature parameter

##### Returns

value of xi

Definition at line 210 of file *ltb.c*.

#### 4.3.2.35 double xi\_fun\_from\_eta ( double *eta*, int *cur* )

Calculate values of xi.

Depending on *cur* parameter choosing function to calculate *xi(eta)*

##### Parameters

in	<i>eta</i>	value of eta
in	<i>cur</i>	curvature parameter

##### Returns

fi value

##### See Also

[xiFlat\(\)](#)  
[xiSpherical\(\)](#)  
[xiHyperbolic\(\)](#)

Definition at line 307 of file *ltb.c*.

#### 4.3.2.36 double xiFlat ( double *eta* )

Calculate values of xi in model with curvature = 0.

##### Returns

xi value

##### See Also

[xi\\_fun\\_from\\_eta\(\)](#)

Definition at line 328 of file *ltb.c*.

#### 4.3.2.37 double xiHyperbolic ( double *eta* )

Calculate xi value in model with curvature  $< 0$ .

##### Returns

xi value

##### See Also

[xi\\_fun\\_from\\_eta\(\)](#)

Definition at line 333 of file l**tb**.c.

#### 4.3.2.38 double xiSpherical ( double *eta* )

Calculate values of xi in model with curvature  $> 0$ .

##### Returns

xi value

##### See Also

[xi\\_fun\\_from\\_eta\(\)](#)

Definition at line 338 of file l**tb**.c.

## 4.4 src/l**tb**\_error.h File Reference

Errors Handling macros and functions.

```
#include <gsl/gsl_errno.h>
#include <gsl/gsl_nan.h>
```

### Macros

- `#define CHECK_STAT(status)`
- `#define CHECK_PTR(stptr, errno)`
- `#define CHECK_M_DIM(m1, m2, reason)`
- `#define CHECK_SIZE(s1, s2, reason)`

### Enumerations

- `enum { LTB_ECURV = 100, LTB_EEFUN = 101 }`

#### 4.4.1 Detailed Description

Errors Handling macros and functions.

Definition in file [l\*\*tb\*\*\\_error.h](#).

## 4.4.2 Macro Definition Documentation

### 4.4.2.1 #define CHECK\_M\_DIM( *m1*, *m2*, *reason* )

**Value:**

```
if (m1->size1 != m2->size1 || m1->size2 != m2->size2){ \
    gsl_error(reason, __FILE__, __LINE__, GSL_EBADLEN); \
    return GSL_EBADLEN; \
}
```

Checking if two matrices have the same shape

Definition at line 37 of file ltb\_error.h.

### 4.4.2.2 #define CHECK\_PTR( *stptr*, *errno* )

**Value:**

```
if(!stptr){ \
    gsl_error ("Bad pointer", __FILE__, __LINE__, errno) ; \
    return errno; \
}
```

Checking pointer macro - if pointer is NULL return specific error errno

Definition at line 30 of file ltb\_error.h.

### 4.4.2.3 #define CHECK\_SIZE( *s1*, *s2*, *reason* )

**Value:**

```
if (s1 != s2){ \
    gsl_error(reason, __FILE__, __LINE__, GSL_EBADLEN); \
    return GSL_EBADLEN; \
}
```

Checking if two values differ

Definition at line 44 of file ltb\_error.h.

### 4.4.2.4 #define CHECK\_STAT( *status* )

**Value:**

```
if(status){ \
    return status; \
}
```

Checking status macro - if status is > 0 then return status

Definition at line 23 of file ltb\_error.h.

## 4.4.3 Enumeration Type Documentation

### 4.4.3.1 anonymous enum

Ltb erro codes

Enumerator

***LTB\_ECURV*** Wrong value of curvature

***LTB\_EEFUN***  $E(r) < -0.5$  metric degeneration

Definition at line 15 of file ltb\_error.h.

## 4.5 src/ltb\_integrate.h File Reference

Functions for integrating.

```
#include <gsl/gsl_matrix.h>
#include "ltb_error.h"
```

### Functions

- [int gsl\\_matrix\\_integrate\\_trap\\_range](#) (const [gsl\\_matrix](#) \*mat, double dr, unsigned int rstart, unsigned int rstop, unsigned int tstart, unsigned int tstop, [gsl\\_matrix](#) \*integral)  
*Integrate using trapezoid method points kept in [gsl\\_matrix](#).*

### 4.5.1 Detailed Description

Functions for integrating. Details(TODO)

#### Author

Lukasz Matczynski

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Definition in file [ltb\\_integrate.h](#).

### 4.5.2 Function Documentation

**4.5.2.1** [int gsl\\_matrix\\_integrate\\_trap\\_range](#) ( const [gsl\\_matrix](#) \* mat, double dr, unsigned int rstart, unsigned int rstop, unsigned int tstart, unsigned int tstop, [gsl\\_matrix](#) \* integral )

Integrate using trapezoid method points kept in [gsl\\_matrix](#).

This function is needed for calculating radial proper length  $d(t,r)$ . To get it we must integrate points in rows of [grr\\_sq](#) matrix ([ltb\\_model\\_grr\\_sq\(\)](#) ). To integrate I'm using trapezoid method:

$$\int_a^b f(x)dx \approx \frac{h}{2} \sum_{i=1}^n (f(x_i) + f(x_{i+1}))$$

Where  $h$  size of integration interval. When  $r$  dimension of matrix [grr\\_sq](#) is  $n$  we calculate  $n$  integrals

$$\int_{m[0]}^{m[0]} f(x)dx, \int_{m[0]}^{m[1]} f(x)dx, \dots, \int_{m[0]}^{m[n-1]} f(x)dx$$

Where  $m[i]$  are matrix elements. First of this integrals is always 0.

**Parameters**

in	<i>mat</i>	matrix to integrate
in	<i>dr</i>	size of integration interval
in	<i>rstart</i>	element of row from which start to integrate
in	<i>rstop</i>	element of row on which stop integrating
in	<i>tstart</i>	row from which start to integrate
in	<i>tstop</i>	row on which stop integrating
out	<i>integral</i>	matrix where result of integration is kept

**See Also**

[ltb\\_model\\_grr\\_sq\(\)](#)

Definition at line 3 of file `ltb_integrate.c`.

## 4.6 src/macros.h File Reference

Additional helpful macros.

### 4.6.1 Detailed Description

Additional helpful macros.

Definition in file [macros.h](#).

## 4.7 src/phys\_constant.h File Reference

Physics constant.

```
#include "macros.h"
```

**Macros**

- `#define G_DEF 6.67300e-11 * 1.98892e40 / 3.08568025e25 / (299792458.0*299792458.0)`  
*Default G parameter  $c=1$ ,  $Gpc / 10^4 10M_{\{sun\}}$ .*
- `#define H_0_DEF 100.0 / 299792.458 * 1000`  
*Default Hubble parameter  $c=1$  units  $Gpc * h^{-1}$ .*
- `#define C_DEF 299792458.0;`  
*Default  $c$  — speed of light.*

**Functions**

- void [export\\_phys\\_const](#) (char \*file\_name)  
*Write physical constant to file.*
- void [set\\_phys\\_const](#) (double G\_in, double H\_0\_in, double c\_in)  
*Set physical constant.*

## Variables

- static const double `pi` = 3.14159265
- double `G_grav`
- double `H_0`
- double `c`
- static const double `Gyr_per_Gpc` = 3.08568025e16 / 299792458.0 / (365.25\*24.0\*3600.0)

*Gyr/Gpc value Parameter used to conver time values to distance values.*

### 4.7.1 Detailed Description

Physics constant.

Definition in file `phys_constant.h`.

### 4.7.2 Function Documentation

#### 4.7.2.1 void export\_phys\_const ( char \* file\_name )

Write physical constant to file.

Parameters

<code>in</code>	<code>file</code>	
-----------------	-------------------	--

Definition at line 8 of file `phys_constant.c`.

#### 4.7.2.2 void set\_phys\_const ( double G\_in, double H\_0\_in, double c\_in )

Set physical constant.

Parameters

<code>in</code>	<code>G_in</code>	Gravity Const.
<code>in</code>	<code>H_0_in</code>	actual value of Hubbel Parameter
<code>in</code>	<code>c_in</code>	speed of light

Definition at line 20 of file `phys_constant.c`.

### 4.7.3 Variable Documentation

#### 4.7.3.1 double c

c speed of light

Definition at line 6 of file `phys_constant.c`.

#### 4.7.3.2 double G\_grav

Gravity constant G

Definition at line 4 of file `phys_constant.c`.

#### 4.7.3.3 double H\_0

Hubbel parameter

Definition at line 5 of file `phys_constant.c`.

4.7.3.4 `const double pi = 3.14159265` `[static]`

pi constant

Definition at line 10 of file `phys_constant.h`.



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