

16-811 Homework 2

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Q1:

(a): See q1.py attached.

(b):

Interpolated value at $x = 0.3333333333333333$ is: 0.7165315560493046

Actual value at $x = 0.3333333333333333$ is: 0.7165313105737893

(c):

Interpolated value at $x = 0.05$ with $n = 2$ points is: 0.9976470588235294

Interpolated value at $x = 0.05$ with $n = 4$ points is: 0.9901364705882355

Interpolated value at $x = 0.05$ with $n = 40$ points is: 0.9615384615384615

Actual value at $x = 0.05$ is: 0.9615384615384615

(d):

Max error for $n = 2$ is: 0.5737522791671381

Max error for $n = 4$ is: 0.3853045754904466

Max error for $n = 6$ is: 0.48888096747915344

Max error for $n = 8$ is: 0.7319021780828148

Max error for $n = 10$ is: 1.1768940117150546

Max error for $n = 12$ is: 1.9694654921610955

Max error for $n = 14$ is: 3.381811520697178

Max error for $n = 16$ is: 5.913249213154253

Max error for $n = 18$ is: 10.479990230487914

Max error for $n = 20$ is: 18.768360900950597

Max error for $n = 40$ is: 8520.73984400868

We can observe that E_n increases as n increases. This makes sense because as n increases, we are using a higher order polynomial to fit the function that leads to oscillation in error near the edge of the interpolation interval, (ref: Runge's Phenomenon).

Q2: To ensure 6 decimal digit accuracy, the error should be at most $5 * 10^{-7}$.

In the case of linear interpolation:

For any $\bar{x} \in [x_i, x_{i+1}]$, $f(\bar{x})$ can be approximated with the polynomial of degree 1, given by $p_1(\bar{x})$,

Then the error $e_1(\bar{x})$ is given by:

$$e_1(\bar{x}) = \frac{f''(\xi)}{2!}(\bar{x} - x_i)(\bar{x} - x_{i+1})$$

Since $f(x) = \cos(x)$, $f''(x) = -\cos(x) \leq 1$

Therefore:

$$e_1(\bar{x}) = \frac{f''(\xi)}{2!}(\bar{x} - x_i)(\bar{x} - x_{i+1}) \leq \frac{1}{2!}(\bar{x} - x_i)(\bar{x} - x_{i+1})$$

Define the (uniform) interpolation interval length $x_{i+1} - x_i$ as h

Then we have:

$$(\bar{x} - x_i) \cdot (\bar{x} - x_{i+1}) \leq \frac{h}{2} \cdot \frac{h}{2} = \frac{h^2}{4}$$

Therefore:

$$e_1(\bar{x}) = \frac{f''(\xi)}{2!}(\bar{x} - x_i)(\bar{x} - x_{i+1}) \leq \frac{1}{2!} \cdot \frac{h^2}{4} = \frac{h^2}{8}$$

To ensure 6 decimal digit accuracy:

$$\frac{h^2}{8} < 5 * 10^{-7}$$

$$h < 2 * 10^{-3}$$

And since we are interpolating over the interval $[-\frac{\pi}{2}, \frac{3\pi}{2}]$, we need at least $2\pi/(2 * 10^{-3}) = 3142$ intervals (3143 points).

If we use quadratic interpolation, similarly:

$$e_2(\bar{x}) = \frac{f'''(\xi)}{3!}(\bar{x} - x_{i-1})(\bar{x} - x_i)(\bar{x} - x_{i+1})$$

Since $f(x) = \cos(x)$, $f'''(x) = \sin(x) \leq 1$

and consider the function $g(y) = (y - h) \cdot y \cdot (y + h)$:

$$g(-h) = g(0) = g(h) = 0$$

, therefore the function's maxima is at the point where $g'(y) = 0$. Solving the equation we get $y = \pm \frac{h}{\sqrt{3}}$

This gives

$$g(y) \leq \frac{2}{3} \cdot \frac{h^3}{\sqrt{3}}$$

Then we can get:

$$e_2(\bar{x}) = \frac{f'''(\xi)}{3!}(\bar{x} - x_{i-1})(\bar{x} - x_i)(\bar{x} - x_{i+1}) \leq \frac{1}{6} \cdot \frac{2}{3} \cdot \frac{h^3}{\sqrt{3}} = \frac{h^3}{9\sqrt{3}}$$

To ensure 6 decimal digit accuracy:

$$\frac{h^3}{9\sqrt{3}} < 5 * 10^{-7}$$

$$h < \sqrt[3]{7.7942} * 10^{-2}$$

And since we are interpolating over the interval $[-\frac{\pi}{2}, \frac{3\pi}{2}]$, we need at least $2\pi/(\sqrt[3]{7.7942} * 10^{-2}) = 317$ intervals (318 points).

Q3:

Denote $f(x) = x - \tan(x)$, then $f'(x) = 1 - \sec^2(x) = -\tan^2(x) \leq 0$

Since $\frac{3\pi}{2} < 7 < \frac{5\pi}{2}$ we can try to evaluate the value of $f(x)$ around these points.

Let's define $\pi_- = 3.14 < \pi$ and $\pi_+ = 3.1416 > \pi$:

$$f(\frac{3\pi_-}{2}) = -413.8778226538852 < 0$$

$$f(\frac{3\pi_+}{2}) = 90751.98186832224 > 0$$

$$f(7) = 6.128552017275681 > 0$$

$$f(\frac{5\pi_-}{2}) = -413.8778226538852 < 0$$

$$f(\frac{5\pi_+}{2}) = 54456.21567531984 > 0$$

By looking at the shape of $\tan(x)$, and the fact that $f'(x) = -\tan^2(x) = 1 - \frac{1}{\cos^2(x)} \leq 0$ and is continuous, we can say that there is only one root between $[\frac{3\pi_-}{2}, \frac{5\pi_-}{2}]$, and the first root less than 7 is less than $\frac{3\pi_-}{2}$.

Therefore, we start with $x_1 = \frac{3\pi_-}{2}$ and $x_2 = \frac{5\pi_-}{2}$, running our program (q3.py) gives:

$$root1 = 4.493409457909064$$

$$root2 = 7.7252518369377094$$

Since $root2 > 7$, therefore we find the solutions:

$$x_{low} = 4.493409457909064, x_{high} = 7.7252518369377094$$

Q4:

We can write $f(x)$ in the form of: $f(x) = (x - \xi)^2 \cdot g(x)$.

And denote

$$h(x) = \frac{f(x)}{f'(x)} = \frac{(x - \xi)^2 \cdot g(x)}{2(x - \xi)g(x) + (x - \xi)^2 g'(x)} = \frac{(x - \xi) \cdot g(x)}{2g(x) + (x - \xi)g'(x)}$$

Also we have:

$$\epsilon_n = \xi - x_n$$

$$\epsilon_{n+1} = \epsilon_n + h(\xi - \epsilon_n)$$

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$$

Then we evaluate

$$\lim_{n \rightarrow \infty} \frac{\epsilon_{n+1}}{\epsilon_n} = \lim_{n \rightarrow \infty} \frac{h(\xi - \epsilon_n)}{\epsilon_n} + 1 = \lim_{x \rightarrow \xi} \frac{h(x)}{\xi - x} + 1 = 1 - \lim_{x \rightarrow \xi} \frac{h(x)}{x - \xi} = 1 - \lim_{x \rightarrow \xi} \frac{g(x)}{2g(x)} = \frac{1}{2}$$

Therefore, the Newton's method now converges linearly.

Now for the iteration $x_{n+1} = x_n - 2 \frac{f(x_n)}{f'(x_n)}$:

now

$$h(x) = \frac{2f(x)}{f'(x)} = \frac{2(x - \xi) \cdot g(x)}{2g(x) + (x - \xi)g'(x)}$$

Similarly, we evaluate:

$$\lim_{n \rightarrow \infty} \frac{\epsilon_{n+1}}{\epsilon_n^2} = \lim_{n \rightarrow \infty} \frac{\epsilon_n + h(\xi - \epsilon_n)}{\epsilon_n^2} = \lim_{n \rightarrow \infty} \frac{\epsilon_n + h(x_n)}{\epsilon_n^2}$$

For the numerator:

$$\begin{aligned} \epsilon_n + h(x_n) &= \epsilon_n + \frac{2(x_n - \xi) \cdot g(x_n)}{2g(x_n) + (x_n - \xi)g'(x_n)} = \epsilon_n + \frac{-2\epsilon_n \cdot g(x_n)}{2g(x_n) + (x_n - \xi)g'(x_n)} \\ &= \frac{-2\epsilon_n \cdot g(x_n) + 2\epsilon_n g(x_n) - \epsilon^2 \cdot g'(x_n)}{2g(x_n) + (x_n - \xi)g'(x_n)} = \frac{-\epsilon^2 \cdot g'(x_n)}{2g(x_n) + (x_n - \xi)g'(x_n)} \end{aligned} \quad (1)$$

With this, let's go back to the original equation:

$$\lim_{n \rightarrow \infty} \frac{\epsilon_{n+1}}{\epsilon_n^2} = \lim_{n \rightarrow \infty} \frac{\epsilon_n + h(\xi - \epsilon_n)}{\epsilon_n^2} = \lim_{n \rightarrow \infty} \frac{\epsilon_n + h(x_n)}{\epsilon_n^2} = \lim_{x \rightarrow \xi} \frac{\frac{-\epsilon^2 \cdot g'(x)}{2g(x) + (x - \xi)g'(x)}}{\epsilon_n^2} = \frac{g'(\xi)}{2g(\xi)}$$

Therefore the iteration does converge quadratically.

Q5:

(a): See q5.py attached.

(b): The roots for this polynomial are:

$$x_1 = 3.0, x_2 = 1.0 + 2j, x_3 = 1.0 - 2j$$

where $j = \sqrt{-1}$

Q6:

(a):

$$xp(x) = x^4 - 4x^3 + 6x^2 - 4x$$

$$p(x) = x^3 - 4x^2 + 6x - 4$$

$$x^2q(x) = x^4 + 2x^3 - 8x^2$$

$$xq(x) = x^3 + 2x^2 - 8x$$

$$q(x) = x^2 + 2x - 8$$

Construct the equation with the Q matrix from the coefficients:

$$Q\bar{x} = \begin{bmatrix} 1 & -4 & 6 & -4 & 0 \\ 0 & 1 & -4 & 6 & -4 \\ 1 & 2 & -8 & 0 & 0 \\ 0 & 1 & 2 & -8 & 0 \\ 0 & 0 & 1 & 2 & -8 \end{bmatrix} \begin{bmatrix} x^4 \\ x^3 \\ x^2 \\ x^1 \\ 1 \end{bmatrix}$$

If $p(x)$ and $q(x)$ share a common root, there should be some $\bar{x} \neq \mathbf{0}$ that satisfies $Q\bar{x} = 0$

Equivalently means:

$$\det(Q) = 0$$

Using program (q6.py), we can get $\det(Q) = 0$, therefore $p(x)$ and $q(x)$ share a common root.

(b):

To apply the ratio method, we construct Q_1 and Q_2 by removing rows and columns from Q :

$$Q_1 = \begin{bmatrix} -4 & 6 & -4 & 0 \\ 1 & -4 & 6 & -4 \\ 2 & -8 & 0 & 0 \\ 1 & 2 & -8 & 0 \end{bmatrix}$$

$$Q_2 = \begin{bmatrix} 1 & 6 & -4 & 0 \\ 0 & -4 & 6 & -4 \\ 1 & -8 & 0 & 0 \\ 0 & 2 & -8 & 0 \end{bmatrix}$$

The common root is given by $x = \frac{-\det(Q_1)}{\det(Q_2)} = 2$

Q7:

(a):

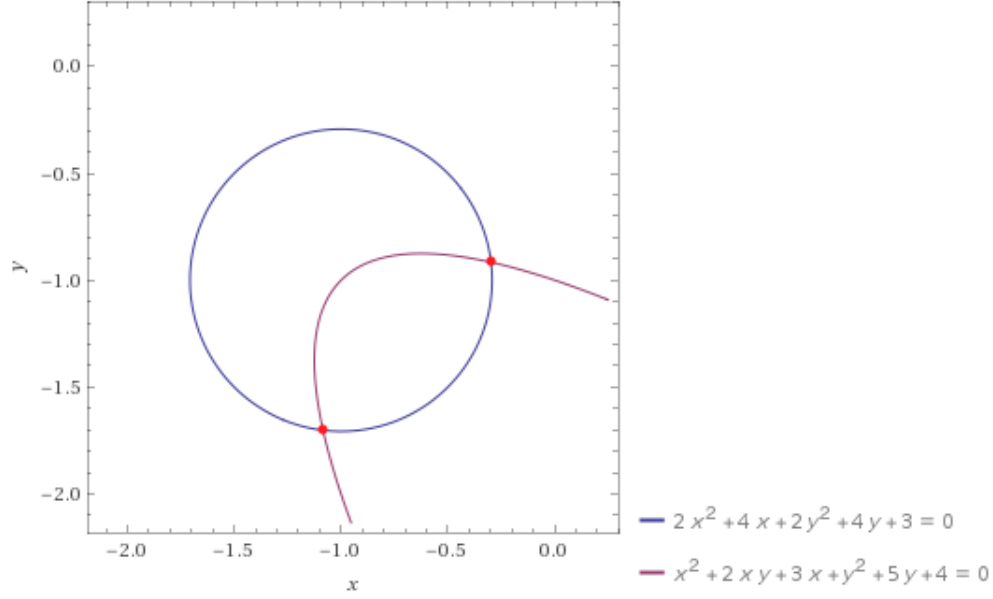


Figure 1: Contours of $p(x, y) = 0$ and $q(x, y) = 0$

(b):

Re-write the functions in terms of y :

$$p(y) = 2y^2 + 4y + (2x^2 + 4x + 3)$$

$$q(y) = y^2 + (2x + 5)y + (x^2 + 3x + 4)$$

Then we get:

$$yp(y) = 2y^3 + 4y^2 + (2x^2 + 4x + 3)y$$

$$yq(y) = y^3 + (2x + 5)y^2 + (x^2 + 3x + 4)y$$

Similar to (a), we construct the matrix Q :

$$Q = \begin{bmatrix} 2 & 4 & 2x^2 + 4x + 3 & 0 \\ 0 & 2 & 4 & 2x^2 + 4x + 3 \\ 1 & 2x + 5 & x^2 + 3x + 4 & 0 \\ 0 & 1 & 2x + 5 & x^2 + 3x + 4 \end{bmatrix}$$

Using WolframAlpha to solve $\det(Q)$:

$$\det(Q) = 16x^4 + 80x^3 + 144x^2 + 100x + 19$$

Solving $\det(Q) = 0$ we get two real roots and two imaginary roots, only consider the real roots:

$$x_1 = -1.08406$$

$$x_2 = -0.297907$$

So these are the x-values of the two intersection points of the two contours, putting them back into $p(x, y)$ and $q(x, y)$:

$$y_1 = -1.70209$$

$$y_2 = -0.915941$$

Therefore the two intersection points of the two contours are:

$$(x_1, y_1) = (-1.08406, -1.70209)$$

$$(x_2, y_2) = (-0.297907, -0.915941)$$

(c):

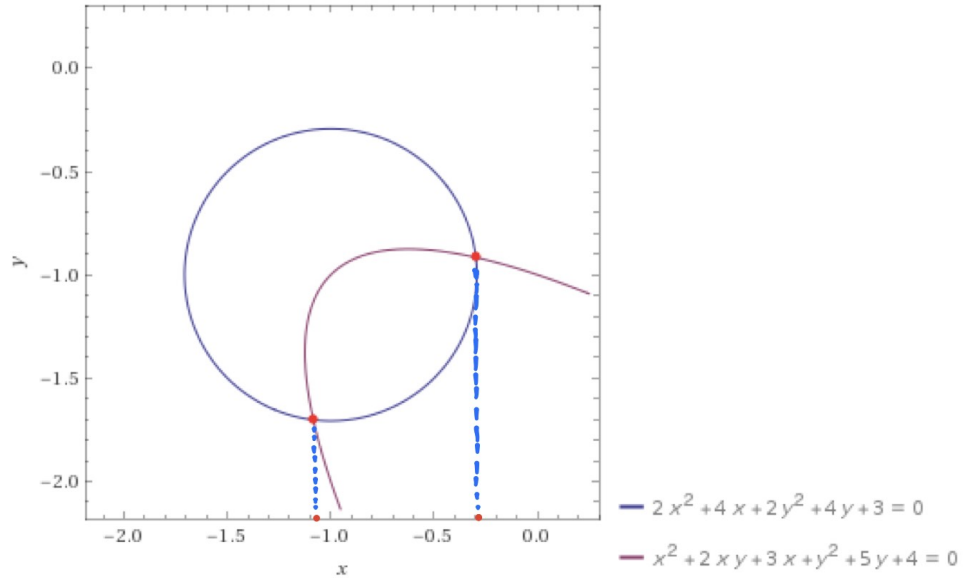


Figure 2: Contours of $p(x, y) = 0$ and $q(x, y) = 0$

Q8:

(a): We define two vectors $\vec{ij} = (x^{(j)} - x^{(i)}, y^{(j)} - y^{(i)})$ and $\vec{ik} = (x^{(k)} - x^{(i)}, y^{(k)} - y^{(i)})$, in fact \vec{ij} and \vec{ik} can be visualized as the two edges of the triangle formed by the three points.

Then for any point $p = (x, y)$ falls within the triangle, the vector \vec{ip} can be expressed a linear combination of \vec{ij} and \vec{ik} , with constraints on the coefficients:

$$\vec{ip} = (x - x^{(i)}, y - y^{(i)}) = \alpha * \vec{ij} + \beta * \vec{ik}$$

where

$$0 \leq \alpha \leq 1$$

$$0 \leq \beta \leq 1$$

$$\alpha + \beta \leq 1$$

Therefore, we can write the system of linear equations as:

$$\begin{bmatrix} x^{(j)} - x^{(i)} & x^{(k)} - x^{(i)} \\ y^{(j)} - y^{(i)} & y^{(k)} - y^{(i)} \end{bmatrix} \begin{bmatrix} \alpha \\ \beta \end{bmatrix} = \begin{bmatrix} x - x^{(i)} \\ y - y^{(i)} \end{bmatrix}$$

with constraints:

$$0 \leq \alpha \leq 1$$

$$0 \leq \beta \leq 1$$

$$\alpha + \beta \leq 1$$

(b):

I have not solved this problem yet...