BLTouch: Auto Bed Leveling Sensor for 3D Printers

■ Smart V3.0 Highlights

■ Smart V2.0 and later versions highlights

Logic Voltage Free: 3.3V / 5V logic voltage free(default) **Long Stroke:** The stroke is up to 1.6mm longer than before.

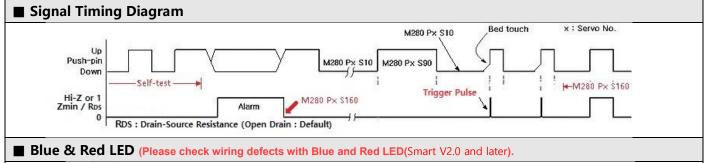
Blue & Red LED: Blue and Red LED for checking wiring defects. **Engineering plastic Push-pin:** Engineering plastic push-pin can be bent more easily than aluminum pins so that engineering plastic push-pin can be recovered well and the device can be protected.

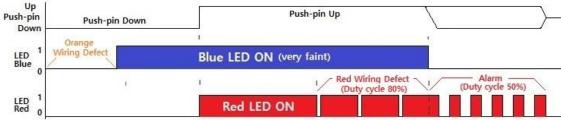
BLTouch – Smart V3.0 (Smart V3.0 produced since April 5th, 2019)							
BLTouch	Center Of PWM (Available PWM Rage ±20)	G-code	x: Servo Pin or No.				
Instruction		Marlin / Duet	Repetier	Smoothieware			
Push-pin Down(deploy)	650 us (10°)	M280 Px S10	M340 Px S650	M280 S3.3			
Alarm Release & Touch SW Mode(M119)	1165 us (60°)	M280 Px S60	M340 Px S1165	M280 S5.88			
Push-pin Up (Stow)	1475 us (90°)	M280 Px S90	M340 Px S1475	M280 S7.43			
Self-test (10 Times)	1780 us (120°)	M280 Px S120	M340 Px S1780	M280 S8.99			
5V Logic Zmin (Do not activate on 3.3V logic system)	1985 us (140°)	M280 Px S140	M340 Px S1985	M280 S10.01			
Logic voltage Free Zmin (default: open drain)	2090 us (150°)	M280 Px S150	M340 Px S2090	M280 S10.53			
Alarm Release & Push-pin UP	2190 us (160°)	M280 Px S160	M340 Px S2190	M280 S11.05			

- * Depending on your board, you can need to adjust the PWM range or Duty cycle.
- X 5V Logic Zmin (140°) for unusual board: High Signal is not weak. Stronger than V2.x
 - For example, Board with large capacity capacitor in end-stop input circuit(Melzi and some of the Creality3D, ANET board, etc.)
 - **☞** Do not activate 5V logic on 3.3V logic system without 3.3V logic conversion.

Specification		BLTouch CAD Dimension		
Voltage / Current	4.8 ~ 5.1 V	1. 18.0		
Current Maximum (Peak)	15mA 300mA	9.0		
Z Probe Output Open Drain VDS / ID	Logic Free (Open Drain: default) or 5V Max VDS = 5V / Max ID = 300mA	8 111		
PCB / Soldering	OSP / Lead Free			
Cable Length	150±5 mm (for retail)			
Weight	0.35oz (10g)	©78 40.3 40.5		
Wiring	3Pin: Brown (GND), Red (+5V) Orange (control signal) 2Pin: Black (GND) White (Zmin)	36.3 40~40.5 *45.7±0.5 46.6		
Case & Push-pin	Polycarbonate (PC)	<u> i</u> <u>i</u> <u>i</u> <u>i</u> <u>i</u> <u>i</u>		
Push-pin stroke	5.6 ~ 6.6 mm (If the stroke is large, push-pin may not deploy)	*: trigger position		

- * Additional power supply may be needed in case which your board does not supply enough amperage.
- X Electronic devices can be damaged or even destroyed if connected to the wrong side polarity.
- * Set Zmin pull-up on your firmware when using Logic Free (In most cases, it is already set up)
- X Depending on your type of 3D printer, you may need to remove or add some parts of the board.
- X In principle, Board with large capacitor on end stop input circuit is not supported. (You may need to remove the capacitor from your board.)
- X If noise, etc. interference is expected, you should use a anti-interference extension cable (Shielded or Twisted Cable).
- $\ensuremath{\mathbb{X}}$ Selling price and specifications are subject to change without prior notice.





💥 Red wiring defect : When the BLTouch was disconnected and reconnected during normal operation. Unlike previous versions, it does not perform self-test even if wiring defects occur during printing.

■ Wiring:

: Soldering and firmware update might be needed in rare case				
	I can find a servo pin on my board.			
I	I can not find any Servo pin on my board.			
İ	I can not find Servo Pin on my board and click here #define SERVO0_PIN is not included in pins_YourMotherboard.h. Sanguinololu1.3a, Melzi, Ender-3, Anet, FlashForge, Azteeg X3, etc. ※ Depending on your type of 3D printer, you may need to remove or add some parts of the board.	□ () () () () () () () () () (
	32bit board			

■ Insert the following G-code into Slic3r or Cura

Depending on your board, you can choose between the following two.

Logic voltage free(default) mode (Recommended) ← Both 3.3V /5V Logic are available

M280 P0 S160; BLTouch alarm release

G4 P100; delay for BLTouch

G28; home

G29; auto bed leveling

If the nozzle is in contact with the bed after missing the trigger signal(A board with large capacity capacitor in end-stop input circuit, such as the Melzi).

M280 P0 S140 ← Only 5V Logic mode(Do not activate 5V logic on 3.3V logic system without 3.3V logic conversion)

G4 P2000; delay for BLTouch

M280 P0 S160; BLTouch alarm release

G4 P100; delay for BLTouch

G28; home

G29; auto bed leveling

Boards with large capacity capacitor in end-stop input circuit: Melzi and some of the Creality3D, ANET board, etc. (Select 1 if you have already removed the capacitor from your board)

■ Setting (e.g. Marlin firmware)

Please refer to other auto bed leveling setting documents (Youtube etc.).

// Choose a line of below lines and remove // at the start of the line

// set up at least 1

//#define AUTO_BED_LEVELING_3POINT //#define AUTO_BED_LEVELING_LINEAR #define AUTO_BED_LEVELING_BILINEAR //#define AUTO_BED_LEVELING_UBL //#define MESH_BED_LEVELING

#define SERVO_DELAY {300, 300, 300}

#define NUM_SERVOS 3

Marlin-bugfix-2.0.x Setting

```
https://github.com/MarlinFirmware/Marlin/archive/bugfix-2.0.x.zip
   Step 1: Copy the file below and overwrite at the Marlin folder. <== e.g. default
         Marlin-bugfix-2.0.x₩config₩default₩Configuration.h
         Marlin-bugfix-2.0.x\daggerconfig\default\Configuration_adv.h
   Step 2: Look at the Configuration.h at your previous firmware and edit Configuration.h at Marlin.
    Step 3: Check your 3D printer works well.
    Step 4: Please install your BLTouch.
   Step 5: Edit Configuration.h and Configuration_adv.h like below.
■ Configuration.h
#define USE_ZMIN_PLUG // a Z probe
#define ENDSTOPPULLUPS
                                       // BLTouch Smart V3.0 and Later
#define ENDSTOP_INTERRUPTS_FEATURE
#define Z_MIN_PROBE_USES_Z_MIN_ENDSTOP_PIN
#define BLTOUCH
#if ENABLED(BLTOUCH)
 //#define BLTOUCH_DELAY 500
                             // *option: Minimum Command delay (ms). Enable and increase if needed
 //#define BLTOUCH_FORCE_5V_MODE // only for 5V logic mode of Smart V3.0 : Do not remove // on 3.3V logic system
#define PROBING_HEATERS_OFF
                           // *option
#define PROBING_FANS_OFF
                           // *option
#define X_PROBE_OFFSET_FROM_EXTRUDER 0
                                       //Depend on your BLTouch installation value
                                       //Depend on your BLTouch installation value
#define Y PROBE OFFSET FROM EXTRUDER -22
#define Z_PROBE_OFFSET_FROM_EXTRUDER -2.35 //Depend on your BLTouch installation value
#define MIN_PROBE_EDGE 20
#define Z_CLEARANCE_DEPLOY_PROBE
                                 15
                                      // set up at least 15
#define Z_CLEARANCE_BETWEEN_PROBES 10
                                      // set up at least 10
```

Marlin 1.1.x(1.1.9) Setting

```
https://github.com/MarlinFirmware/Marlin/archive/1.1.x.zip
   Step 1: Copy the file below and overwrite at the Marlin folder. <== e.g. Delta
          Marlin\wexample_configurations\wdelta\wedgeneric\wConfiguration.h
          Marlin\wexample_configurations\wdelta\wgeneric\wConfiguration_adv.h
   Step 2: Look at the Configuration.h at your previous firmware and edit Configuration.h at Marlin 1.1.x
   Step 3: Check your 3D printer works well.
   Step 4: Please install your BLTouch.
   Step 5: Edit Configuration.h and Configuration_adv.h like below.
■ Configuration.h
#define USE_ZMIN_PLUG // a Z probe
#define ENDSTOPPULLUPS
                                          // BLTouch Smart V3.0 and Later
#define ENDSTOP_INTERRUPTS_FEATURE
#define Z_MIN_PROBE_USES_Z_MIN_ENDSTOP_PIN
//#define Z_MIN_PROBE_ENDSTOP
//#define FIX_MOUNTED_PROBE
#define BLTOUCH
#if ENABLED(BLTOUCH)
 #define BLTOUCH_DELAY 100
                             // *option
#endif
#define PROBING_HEATERS_OFF
                             // *option
#define PROBING_FANS_OFF
                             // *option
#define X_PROBE_OFFSET_FROM_EXTRUDER 0
                                           //Depend on your BLTouch installation value
#define Y_PROBE_OFFSET_FROM_EXTRUDER -22
                                           //Depend on your BLTouch installation value
#define Z_PROBE_OFFSET_FROM_EXTRUDER -2.35 //Depend on your BLTouch installation value
#define MIN_PROBE_EDGE 20
```

// Choose a line of below lines and remove // at the start of the line //#define AUTO_BED_LEVELING_3POINT

//#define AUTO_BED_LEVELING_LINEAR #define AUTO_BED_LEVELING_BILINEAR

//#define AUTO_BED_LEVELING_UBL //#define MESH_BED_LEVELING

//#define Z_PROBE_ALLEN_KEY

#define SERVO_DELAY {300, 300, 300}

Previous Versions before Marlin RC7

■ Configuration.h

```
const bool Z_MIN_ENDSTOP_INVERTING = false;
//====== Z Probe Options ===========
//#define Z_MIN_PROBE_ENDSTOP
                                  // *RC4 ~ RC6
#define Z_MIN_PROBE_USES_Z_MIN_ENDSTOP_PIN
                                  // *RC4 ~ RC6
#define AUTO_BED_LEVELING_FEATURE
#define X_PROBE_OFFSET_FROM_EXTRUDER 20
                                  //Your BLTouch X_PROBE_OFFSET_FROM_EXTRUDE
#define Y PROBE OFFSET FROM EXTRUDER -20
                                  //Your BLTouch Y PROBE OFFSET FROM EXTRUDE
                                  //Your BLTouch Z_PROBE_OFFSET_FROM_EXTRUDE
#define Z_PROBE_OFFSET_FROM_EXTRUDER -1.0
#define Z_SAFE_HOMING
#define NUM SERVOS 3
#define SERVO_ENDSTOP_ANGLES {{0,0}, {0,0}, {10,90}}
                                       // 10=deploy, 90=retract
//#define DEACTIVATE_SERVOS_AFTER_MOVE
```