



# Boosted SVM for extracting rules from imbalanced data in application to prediction of the post-operative life expectancy in the lung cancer patients

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## ABSTRACT

In this paper, we present boosted SVM dedicated to solve imbalanced data problems. Proposed solution combines the benefits of using ensemble classifiers for uneven data together with cost-sensitive support vectors machines. Further, we present oracle-based approach for extracting decision rules from the boosted SVM. In the next step we examine the quality of the proposed method by comparing the performance with other algorithms which deal with imbalanced data. Finally, boosted SVM is used for medical application of predicting post-operative life expectancy in the lung cancer patients.

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## 1. Introduction

The main difficulty in learning classification models is the character of data. Usually, raw data gathered from many sources cannot be used directly in the training process due to various circumstances, i.e., missing values of some attributes [1], sequential nature of delivering data [2], or disproportions in class distribution [3]. In the literature, the third issue is known as *imbalanced data problem*. In general, each dataset with unequal class distribution can be considered as imbalanced. In practice, the problem of disproportion between classes occurs when the classifier trained with typical methods has a tendency to make decisions biased toward majority class. Extreme imbalance data problem is observed when the classifier trained using traditional methods is classifying all objects only to the majority class, independently on the vector of features. Applying techniques which deal with the problem of unequally distributed data is essential for learning decision models with high predictive accuracy.

The problem of imbalanced data is widely observed in medical decision making, particularly in post-operative risk evaluation domain. Considering the short period of planning (1 year) the

number of patients surviving the assumed interval is often significantly higher than the number of deceases. Moreover, the misclassification related to treating deceases as survivors is much more troublesome than the decision mistake made in opposite direction.

The second important issue connected to the problem of post-operative life expectancy prediction is the interpretability of the decision model. Using so-called “black box” models in the considered application is not recommended. It is mainly caused by the patient’s fear about being treated by machines with hidden and difficult-to-understand inference process and distrust among doctors of being supported by vaguely-working models. To dissipate the doubts it is necessary to propose a method to extract knowledge in the form of decision rules or trees from “black box” models.

The main goal of this paper is to propose a general decision model which obtains high predictive accuracy in case of imbalanced data and use this model for extraction of interpretable knowledge in the form of decision rules. The core of our proposition is a generalization of the learning task for SVM by introducing individual penalty parameters for each example, and then application of AdaBoost-like algorithm to learn ensemble of SVMs. We call this approach *boosted SVM* for imbalanced data. At the end, we apply *boosted SVM* as an oracle to re-label examples and use the new dataset for the rules induction in order to obtain an interpretable model.

Additionally, we aim at using thoracic surgery clinical diagnostics and treatment issues as an important application of the boosted

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SVM proposed in this paper. Our approach may contribute current clinical treatment twofold. First, to support decisions on patient selection for surgery made by clinicians. Second, to identify the cases of higher risk of patient's death after surgery by extracting decision rules.

The paper is organized as follows. In Section 2 we review approaches that are applied to imbalanced data and solutions used to extract rules from uninterpretable models. In Section 3 we present the ensemble SVM classifier (*boosted SVM*) for imbalanced data and describe the method of extracting decision rules from the model. Section 4 contains the results of an experiment showing the quality of the proposed approach for imbalanced data and presents post-operative life expectancy rules extracted using *boosted SVM*. This paper is briefly summarized in Section 5.

## 2. Related work

Typical methods used to learn classifiers are biased toward the majority class if they are trained with imbalanced data. Various techniques are used to deal with the stated problem which can be divided into three categories [3,4]:

- *Data level (external) approaches*, which use oversampling and undersampling techniques to equalize the number of instances from classes.
- *Algorithm level (internal) approaches*, which incorporate balancing techniques in training process.
- *Cost-sensitive solutions*, which use both data level transformations (by adding costs to instances) together with algorithm level modifications (by modifying the learning process to accept costs).

The first group of methods operates independently on the training procedure by modifying the class distribution, either by generating artificial samples or by eliminating non-informative examples. The most popular and commonly used sampling method is SMOTE (Synthetic Minority Over-sampling TEchnique) [5], which generates artificial examples situated on the path connecting two neighbours from minority class. Borderline-SMOTE is an extension of SMOTE, which incorporates in the sampling procedure only the minority data points located in the neighbourhood of the separating hyperplane [6]. On the other hand, non-informative majority examples can be eliminated to obtain more balanced data in the undersampling procedure. This type of methods is mainly used as a component of more sophisticated, internal approaches, and detection of non-informative examples is usually made by random selection, using K-NN algorithm [7] or with evolutionary algorithms [8].

The second group of methods solves the problem of uneven data directly during training phase, and it includes ensemble-based approaches which make use of under- and oversampling methods to construct diverse and balanced base classifiers. The most common approach in this group is SMOTEBOOST [9], that combines the benefits of boosting with multiple sampling procedure using SMOTE. Alternatively, synthetic data sampling can be included in the process of constructing bagging-based ensemble [10]. Some of ensemble solutions make use of undersampling techniques to construct class-unbiased base learners [11,12].

Other important group of inner methods uses granular computing techniques to solve the problem of uneven data [13–16]. The main feature of such approaches is knowledge-oriented decomposition of the main problem into parallel, balanced sub-problems, named *information granules*. *Active learning* solutions are also used

to deal with imbalanced data issue [17,18]. Originally, *active learning* was used to detect informative, unlabelled examples and query them about class values to create representative training set. Application of *active learning* techniques for imbalanced data is based on the assumption that the distribution of detected examples is significantly more equalized than the distribution of examples from the initial dataset. According to [17], the data points accumulated near the borderline tends to be more equalized than the points in the entire dataset.

The last group of methods assigns a weight to each element of the training set. In general, the process of weighting the examples is made to increase the significance of the minority observations at the expense of the majority class. Large set of cost-sensitive methods make use of ensemble classifiers which update the weights while constructing base learners. As a consequence, the weights related with minority examples are updated stronger than examples from majority class if they are misclassified by already constructed base classifiers. In this group we can distinguish mainly boosting-based approaches such as: AdaCost [19], CSB1, CSB2 [20], RareBoost [21], AdaC1, AdaC2, AdaC3 [22].

Cost-sensitive techniques are widely applied together with *Support Vector Machines* (SVM). The different misclassification costs for classes are considered in learning criterion to achieve soft margin unbiased toward majority class. The approaches differ in the manner of including cost values in penalization term of learning criterion to construct balanced SVM [23,24]. An interesting extension of typical cost-sensitive approaches is SVM with boosting proposed in [25].

In real-life applications, there are two major tasks to be solved: (i) prediction based on properties learned from data, and (ii) discovery of unknown properties from data. In the field of machine learning there are several successful approaches that achieve high predictive accuracy, e.g., neural networks and SVM. On the other hand, there are methods that allow to understand the considered phenomenon and they are easily interpretable by human, e.g., tree-based or rule-based models. Unfortunately, the methods with high predictive accuracy are hard to interpret and the understandable models performs poorly in the prediction task. Therefore, there arises a need to combine high predictive performance with interpretability of the model.

In the literature, there are three main approaches to extract understandable rules from uninterpretable models with high predictive accuracy [26]. The first one, called *decompositional*, focuses on extracting rules from the structure of the trained model, e.g., from neural networks [27] or margin determined by SVM [28]. The second approach, called *pedagogical*, aims at generating examples from the trained model or to re-label training examples according to the trained model and then applying a method for rules extraction from data, e.g., using neural networks [29]. All other techniques which do not fall clearly into one of the above categories are called *eclectic*, e.g., rules extraction from SVM [30].

## 3. Boosted SVM for imbalanced data

### 3.1. SVM for imbalanced data

#### 3.1.1. Problem statement

Let  $\mathbf{x}$  be a  $M$ -dimensional vector of inputs,  $\mathbf{x} \in \mathcal{X}$ , and  $y$  – an output (or class label),  $y \in \{-1, 1\}$ . For given data  $S = \{\mathbf{x}_n, y_n\}_{n=1}^N$ , we are interested in finding a discriminative hyperplane of the following form:

$$H : \mathbf{a}^\top \phi(\mathbf{x}) + b = 0, \quad (1)$$

where  $\mathbf{a}$  is a vector of weights,  $\mathbf{a} \in \mathbb{R}^M$ ,  $\phi(\mathbf{x})$  denotes a fixed feature-space transformation, and  $b$  is bias,  $b \in \mathbb{R}$ .

The solution of the problem of determining adaptive parameters of the discriminative hyperplane is known as Support Vector Machines (SVM) [31]. The typical learning task for SVM is stated as follows:

$$\begin{array}{ll} \min_{\mathbf{a}, b} & Q(\mathbf{a}) = \frac{1}{2} \mathbf{a}^T \mathbf{a} + C \sum_{n=1}^N \xi_n \\ \text{s.t.} & y_n (\mathbf{a}^T \phi(\mathbf{x}_n) + b) \geq 1 - \xi_n \\ & \text{for all } n = 1, \dots, N \end{array} \quad (2)$$

where  $\xi_n$  are slack variables, such that  $\xi_n \geq 0$  for  $n = 1, \dots, N$ , and  $C$  is the parameter that controls the trade-off between the slack variable penalty and the margin,  $C > 0$ .

In the problems where data is well-balanced the SVM achieves high predictive accuracy. However, it may fail in case of imbalanced datasets. One of the possible solutions for this problem is to include cost-sensitivity of classes [32]. In other words, instead of one penalty parameter  $C$  there are two real-valued parameters  $C_+$  and  $C_-$ , namely, for minority and majority classes.<sup>1</sup> It is implemented by transforming the learning task for SVM into:

$$\begin{array}{ll} \min_{\mathbf{a}, b} & Q(\mathbf{a}) = \frac{1}{2} \mathbf{a}^T \mathbf{a} + C_+ \sum_{n \in \mathcal{N}_+} \xi_n + C_- \sum_{n \in \mathcal{N}_-} \xi_n \\ \text{s.t.} & y_n (\mathbf{a}^T \phi(\mathbf{x}_n) + b) \geq 1 - \xi_n \\ & \text{for all } n = 1, \dots, N \end{array} \quad (3)$$

where  $\mathcal{N}_+ = \{n \in \{1, \dots, N\} : y_n = 1\}$ , and  $\mathcal{N}_- = \{n \in \{1, \dots, N\} : y_n = -1\}$ .

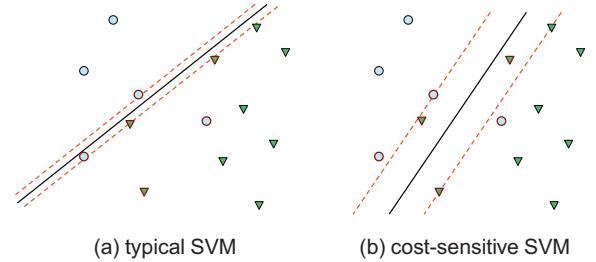
Further, we generalize the problem (3) by introducing individual penalty parameters  $w_n$  for each  $n$ th observation which yields:

$$\begin{array}{ll} \min_{\mathbf{a}, b} & Q(\mathbf{a}) = \frac{1}{2} \mathbf{a}^T \mathbf{a} + C \sum_{n=1}^N w_n \xi_n \\ \text{s.t.} & y_n (\mathbf{a}^T \phi(\mathbf{x}_n) + b) \geq 1 - \xi_n \\ & \text{for all } n = 1, \dots, N \end{array} \quad (4)$$

Because we have maintained the individual penalty parameter  $C$ , the penalty parameters  $w_n$  have to fulfill the following condition:

$$\sum_{n=1}^N w_n = N. \quad (5)$$

The introduction of  $\mathbf{w}$  allows to diversify the costs of misclassification not only between classes but also within classes. Further, we will use the penalty parameters  $\mathbf{w}$  in the boosting procedure during



**Fig. 1.** Optimal hyperplane for SVM trained on imbalanced dataset: (a) using the typical formulation (2), (b) using the cost-sensitive formulation (4). (a) Typical SVM. (b) Cost-sensitive SVM.

the classifiers construction. For the primal optimization problem (4) we get the following dual optimization problem<sup>2</sup>:

$$\begin{array}{ll} \min_{\lambda} & Q_D(\lambda) = \sum_{n=1}^N \lambda_n - \frac{1}{2} \sum_{i,j=1}^N \lambda_i \lambda_j y_i y_j k(\mathbf{x}_i, \mathbf{x}_j) \\ \text{s.t.} & 0 \leq \lambda_n \leq C w_n \\ & \sum_{n=1}^N \lambda_n y_n = 0 \\ & \text{for all } n = 1, \dots, N \end{array} \quad (6)$$

where  $\lambda$  is the vector of Lagrange multipliers.

The solution of the quadratic optimization task in the form (6) is optimal iff the matrix with the elements  $y_i y_j k(\mathbf{x}_i, \mathbf{x}_j)$  is semipositive-definite and for all  $n = 1, \dots, N$  the Kuhn-Tucker conditions are fulfilled:

$$\begin{aligned} \lambda_n &= 0, \\ 0 < \lambda_n &< C w_n, \\ \lambda_n &= C w_n. \end{aligned} \quad (7)$$

In practice, only some of the Lagrange multipliers  $\lambda_n$  will be nonzero and all examples for which  $\lambda_n \geq 0$  are called support vectors. Finally, the classification function is expressed by:

$$y(\mathbf{x}_i) = \text{sign} \left( \sum_{n \in \mathcal{SV}} y_n \lambda_n k(\mathbf{x}_n, \mathbf{x}_i) + b \right), \quad (8)$$

where  $\mathcal{SV}$  denotes the set of indices of the support vectors,  $\text{sign}(a)$  is a function that returns  $-1$  for  $a < 0$ , and  $1$  – otherwise, and the bias parameter is determined as follows:

$$b = \frac{1}{N_{\mathcal{SV}}} \sum_{n \in \mathcal{SV}} \left( y_n - \sum_{m \in \mathcal{SV}} \lambda_m y_m k(\mathbf{x}_n, \mathbf{x}_m) \right), \quad (9)$$

where  $N_{\mathcal{SV}}$  is the total number of the support vectors.

In the literature, there are several training algorithms for SVM like *chunking* [33], *Osuna's algorithm* [34], and *Sequential Minimal Optimization* (SMO) [35] with its modification [36]. Further, we will use SMO algorithm for solving the optimization task (6).

The difference between solutions of different SVM formulations is presented in Fig. 1. For the imbalanced data the solution of the typical formulation of SVM (2) has a tendency

<sup>1</sup> We use the following convention. The data points within the minority class are called *positive examples*, i.e.,  $y = 1$ , while data with majority class label,  $y = -1$  – *negative examples*.

<sup>2</sup> In the following formulation, we have already applied the kernel trick, i.e., we have replaced the inner product with the kernel function,  $\phi(\mathbf{x}_i)^T \phi(\mathbf{x}_j) = k(\mathbf{x}_i, \mathbf{x}_j)$ .

to move towards examples from the majority class (Fig. 1a). Application of different values of penalty parameters for positive and negative examples prevents this undesirable phenomenon (Fig. 1b).

### 3.1.2. Weights determination

The crucial issue in the optimization task (6) is the determination of penalty weights  $\mathbf{w}$ . In our studies we use the following weights' values:

$$w_n = \begin{cases} \frac{N}{2N_+}, & \text{for } n \in \mathcal{N}_+ \\ \frac{N}{2N_-}, & \text{for } n \in \mathcal{N}_- \end{cases} \quad (10)$$

where  $N_+$ , and  $N_-$  are cardinalities of the sets  $\mathcal{N}_+$ , and  $\mathcal{N}_-$ , respectively. The values (10) fulfil the equations:

$$\sum_{n \in \mathcal{N}_+} w_n = \sum_{n \in \mathcal{N}_-} w_n = \frac{N}{2}, \quad (11)$$

and thus the condition (5) is also fulfilled. Such fashion of defining weights solves only the problem of between-class imbalancedness, without distinguishing weight values within the class. To solve this issue we propose boosted algorithm to determine the different weight values and make use of (10) only in the process of weights initialization.

### 3.2. Boosted SVM for imbalanced data

Ensemble classifiers are usually used to improve the prediction accuracy of so called *weak learners*. In this work, we propose boosted SVM to solve inner and between-class imbalanced data problems. In this considered case, ensemble approach is used to determine the weights' values in SVM learning criterion during external sequential error minimization in boosting loop. The training procedure of boosting SVM is performed in two alternating steps: by solving optimization problem (6) for fixed values of  $\mathbf{w}$ , and by iterative updating  $\mathbf{w}$  in external optimization process of exponential error:

$$E_{\text{exp},lmb} = \frac{1}{N_+} \sum_{n \in \mathcal{N}_+} \exp(-y_n f_k(\mathbf{x}_n)) + \frac{1}{N_-} \sum_{n \in \mathcal{N}_-} \exp(-y_n f_k(\mathbf{x}_n)), \quad (12)$$

where  $f_k(\mathbf{x}_n)$  is the linear combination of  $k$  base classifiers  $h_l(\mathbf{x}_n)$ <sup>3</sup>:

$$f_k(\mathbf{x}) = \frac{1}{2} \sum_{l=1}^k c_l h_l(\mathbf{x}_n), \quad (13)$$

where  $c_l$  is the weight of  $l$ th base classifier  $h_l$ ,  $l = 1, \dots, k$ .

### 3.2.1. Boosting framework for imbalanced data – external procedure

**Algorithm 1** (General boosting algorithm for imbalanced data).

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**Input** :  $\mathcal{S}$ : training set,  $\mathcal{S}_{\text{val}}$ : validation set,  $\mathcal{Y} = \{-1, 1\}$ : set of class labels,  $K$ : number of iterations

**Output**: Boosted classifier for imbalanced data:

$$H(\mathbf{x}) = \arg \max_{y \in \mathcal{Y}} \sum_{k=1}^{K_{\text{final}}} c_k I(h_k(\mathbf{x}) = y)$$

```

1 Initialize:  $D_1(n) \leftarrow 1/N$  for  $n \in \{1, \dots, N\}$  ;
2  $G \leftarrow 0$ ;
3  $K_{\text{final}} \leftarrow 1$ ;
4 for  $k = 1 \rightarrow K$  do
5   Train base learner  $h_k$  by minimizing error  $e_k$  given by (14);
6   Calculate  $e_k$  on  $\mathcal{S}$  achieved by  $h_k$ ;
7   if  $e_k < 0.5$  then
8      $c_k \leftarrow \ln \frac{1-e_k}{e_k}$ ;
9     Calculate Gmean value  $g_k$  on  $\mathcal{S}_{\text{val}}$  achieved by  $H_k(\mathbf{x}) = \arg \max_{y \in \mathcal{Y}} \sum_{l=1}^k c_l I(h_l(\mathbf{x}) = y)$  ;
10    if  $g_k > G$  then
11       $G \leftarrow g_k$ ;
12       $K_{\text{final}} \leftarrow k$ ;
13    end
14    Update:
15     $D_{k+1}(n) \leftarrow D_k(n) \exp(c_k I(h_k(\mathbf{x}_n) \neq y_n))$  ;
16    Normalize:  $D_{k+1}(n) \leftarrow \frac{D_{k+1}(n)}{\sum_{n=1}^N D_{k+1}(n)}$  ;
17  else
18     $c_k \leftarrow 0$ ;
19    Initialize:  $D_1(n) \leftarrow 1/N$  ;
20    Change parameters for training base classifiers ;
21 end
```

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**Algorithm 1** presents general boosting method for imbalanced data that minimizes exponential error function given by (12). In the first step the initial values for the distribution (data weighting coefficients)  $D_1(n)$  are equal  $1/N$ . Next, the values of boosting coefficient are iteratively updated in the following manner. First, base learner  $h_k$  is built by minimizing weighted error function:

$$e_k = \frac{E_{\text{lmb}}}{(1/N_+) \sum_{n \in \mathcal{N}_+} D_k(n) + (1/N_-) \sum_{n \in \mathcal{N}_-} D_k(n)} \quad (14)$$

where  $E_{\text{lmb}}$  is equal:

$$E_{\text{lmb}} = \frac{1}{N_+} \sum_{n \in \mathcal{N}_+} D_k(n) I(h_k(\mathbf{x}_n) \neq y_n) + \frac{1}{N_-} \sum_{n \in \mathcal{N}_-} D_k(n) I(h_k(\mathbf{x}_n) \neq y_n), \quad (15)$$

where  $I(\cdot)$  denotes the indicator function.

<sup>3</sup> Constant 1/2 is used for convenience to prove that presented boosting method minimizes sequentially the exponential error function.

**Table 1**  
A confusion matrix.

	Predicted positive	Predicted negative
Actual positive	TP ( <i>True positive</i> )	FN ( <i>False negative</i> )
Actual negative	FP ( <i>False positive</i> )	TN ( <i>True negative</i> )

The problem of uneven data is solved by proposing weighted error function with different misclassification costs,  $1/N_+$  and  $1/N_-$ , for positive and negative examples respectively.

The value of  $e_k$  is calculated on the training data  $S$  and is further used to compute coefficient  $c_k$  of  $k$ th base learner. Finally, the data weights are updated using typical AdaBoost [37] procedure to increase the significance of misclassified examples.

Additionally, basing on boosting SVM training procedure described in [25], we select only the subset of base classifiers with the highest geometric mean (*Gmean*) value. *Gmean* is one of the most commonly used quality rates for imbalanced data and is described by equation:

$$Gmean = \sqrt{TP_{rate} \cdot TN_{rate}}, \quad (16)$$

where  $TN_{rate}$  is specificity rate (or simply true negative rate) defined by:

$$TN_{rate} = \frac{TN}{TN + FP}, \quad (17)$$

and  $TP_{rate}$  is sensitivity rate (true positive rate) and described by the following equation:

$$TP_{rate} = \frac{TP}{TP + FN} \quad (18)$$

True positive ( $TP$ ), false negative ( $FN$ ), false positive ( $FP$ ) and true negative ( $TN$ ) are situated in confusion matrix (see Table 1), which illustrates prediction tendencies of considered classifier.

### 3.2.2. Why does it work?

The training procedure sequentially minimizes exponential error described by Eq. (12) and maximizes *Gmean* in parallel. The process of maximization of *Gmean* value is performed simply by selecting subsequence of base classifiers performing best on validation set  $S_{val}$ . The justification for sequential minimization of (12) is more complex and will be discussed below.

We assume that the training process in boosting loop is reduced to estimation  $c_1, \dots, c_k$  and base classifiers  $h_1, \dots, h_k$  by minimizing error function (12). The optimization process is made sequentially, therefore in each iteration values  $c_1, \dots, c_{k-1}$ , and base learners  $h_1, \dots, h_{k-1}$  are fixed and the process of estimation is made with respect to  $c_k$  and  $h_k$ . Exponential error function (12) can be presented in the following form:

$$\begin{aligned} E_{exp,imb} &= \frac{1}{N_+} \sum_{n \in \mathcal{N}_+} \exp \left( -y_n f_{k-1}(\mathbf{x}_n) - \frac{1}{2} y_n c_k h_k(\mathbf{x}_n) \right) \\ &\quad + \frac{1}{N_-} \sum_{n \in \mathcal{N}_-} \exp \left( -y_n f_{k-1}(\mathbf{x}_n) - \frac{1}{2} y_n c_k h_k(\mathbf{x}_n) \right) \\ &= \frac{1}{N_+} \sum_{n \in \mathcal{N}_+} D_k(n) \exp \left( -\frac{1}{2} y_n c_k h_k(\mathbf{x}_n) \right) \\ &\quad + \frac{1}{N_-} \sum_{n \in \mathcal{N}_-} D_k(n) \exp \left( -\frac{1}{2} y_n c_k h_k(\mathbf{x}_n) \right), \end{aligned} \quad (19)$$

where  $D_k(n) = \exp(-y_n f_{k-1}(\mathbf{x}_n))$  is a constant value, because it is independent on  $c_k$  and  $h_k$ . Next, we assume that  $\mathcal{T}_+$  represents total number of positive examples classified correctly by  $h_k$  and  $\mathcal{F}_+$  the

rest, misclassified positive examples. Analogously, we denote cardinalities of correctly and incorrectly classified negative examples by  $\mathcal{T}_-$  and  $\mathcal{F}_-$ , respectively. Hence, we can rewrite error function in the following form:

$$\begin{aligned} E_{exp,imb} &= \frac{1}{N_+} \exp \left( -\frac{c_k}{2} \right) \sum_{n \in \mathcal{T}_+} D_k(n) + \frac{1}{N_+} \exp \left( \frac{c_k}{2} \right) \sum_{n \in \mathcal{F}_+} D_k(n) \\ &\quad + \frac{1}{N_-} \exp \left( -\frac{c_k}{2} \right) \sum_{n \in \mathcal{T}_-} D_k(n) + \frac{1}{N_-} \exp \left( \frac{c_k}{2} \right) \sum_{n \in \mathcal{F}_-} D_k(n). \end{aligned} \quad (20)$$

Minimizing exponential error with respect to  $c_k$  gives:

$$\exp(c_k^*) = \frac{(1/N_+) \sum_{n \in \mathcal{T}_+} D_k(n) + (1/N_-) \sum_{n \in \mathcal{T}_-} D_k(n)}{(1/N_+) \sum_{n \in \mathcal{F}_+} D_k(n) + (1/N_-) \sum_{n \in \mathcal{F}_-} D_k(n)}. \quad (21)$$

Making use of the fact:

$$\begin{aligned} &\frac{1}{N_+} \sum_{n \in \mathcal{T}_+} D_k(n) + \frac{1}{N_-} \sum_{n \in \mathcal{T}_-} D_k(n) \\ &= \frac{1}{N_+} \left( \sum_{n \in \mathcal{N}_+} D_k(n) - \sum_{n \in \mathcal{F}_+} D_k(n) \right) \\ &\quad + \frac{1}{N_-} \left( \sum_{n \in \mathcal{N}_-} D_k(n) - \sum_{n \in \mathcal{F}_-} D_k(n) \right), \end{aligned} \quad (22)$$

and putting  $e_k$  given by Eq. (14) to (21) we get:

$$\exp(c_k^*) = \frac{1 - e_k}{e_k} \quad (23)$$

Taking logarithm on both sides we gain formula for calculating optimal value of  $c_k$  (see step 8, Algorithm 1).

For optimization process with respect to base classifier  $h_k$ , we present error function in the following manner:

$$\begin{aligned} E_{exp,imb} &= \left( \exp \left( -\frac{c_k}{2} \right) + \exp \left( \frac{c_k}{2} \right) \right) \\ &\quad \times \left( \frac{1}{N_+} \sum_{n \in \mathcal{N}_+} D_k(n) I(h_k(\mathbf{x}_n) \neq y_n) \right. \\ &\quad \left. + \frac{1}{N_-} \sum_{n \in \mathcal{N}_-} D_k(n) I(h_k(\mathbf{x}_n) \neq y_n) \right) + \exp \left( -\frac{c_k}{2} \right) \\ &\quad \times \left( \frac{1}{N_+} \sum_{n \in \mathcal{N}_+} D_k(n) + \frac{1}{N_-} \sum_{n \in \mathcal{N}_-} D_k(n) \right) \end{aligned} \quad (24)$$

It can be noticed, that the minimization of exponential error respecting  $h_k$  is reduced to minimization of the error function given by Eq. (15), because the second term in the sum is constant and the value of  $(\exp(-c_k/2) + \exp(c_k/2))$  does not affect the location of the minimum. In step 5 (Algorithm 1) the optimal classifier is constructed by minimization of (14), which is normalized value of error given by (15).

### 3.3. SVM as base learner – internal procedure

Algorithm 1 presents general procedure of sequential minimizing exponential error function given by Eq. (12). In previous

subsection we have shown that the process of building each of base learners is performed by minimization of the weighted error function given by (15). The problem of error function minimization is stated theoretically, because  $S$  is a sample taken from the entire data space. Optimizing error only on training set may result in overfitting. In this work we present boosted SVM for imbalanced data (further named *BoostingSVM-IB*) and the theoretical problem formulation will be transformed into optimization task presented in (6). For each boosting iteration penalty parameters  $w_n^{(k)}$  in (6) are set in the following fashion:

$$w_n^{(k)} = \begin{cases} \frac{N}{2N_+} D_k(n) & \text{for } n \in \mathcal{N}_+ \\ \frac{N}{2N_-} D_k(n) & \text{for } n \in \mathcal{N}_- \end{cases} \quad (25)$$

Kth SVM base learner is built by solving optimization problem (6) with actual  $w_n^{(k)}$  penalty values.

### 3.4. Rules extraction from boosted SVM for imbalanced data

In the previous section we have outlined the boosted SVM, an ensemble of SVM classifiers. Additionally, we have justified that it works in case of imbalanced datasets. Hence, we will use this model for decision rules induction.

#### Algorithm 2 (Rules extraction process using BoostingSVM-IB).

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**Input :**  $S$ : training set,  $H(\mathbf{x})$ : *BoostingSVM-IB* classifier  
**Output:**  $\mathcal{R}$ : set of decision rules

- 1  $\tilde{S} \leftarrow \emptyset$ ;
- 2 Train  $H(\mathbf{x})$  on  $S$  with optimal parameters;
- 3 **foreach**  $(\mathbf{x}_n, y_n) \in S$  **do**
- 4      $\tilde{y}_n \leftarrow H(\mathbf{x}_n)$ ;
- 5      $\tilde{S} \leftarrow \tilde{S} \cup \{(\mathbf{x}_n, \tilde{y}_n)\}$ ;
- 6 **end**
- 7 Construct set of decision rules  $\mathcal{R}$  from  $\tilde{S}$  using rules inducer;

---

Once the proposed model obtains high predictive accuracy, it seems proper to use it as an oracle for re-labelling examples. The procedure of extracting rules is presented in Algorithm 2. In the first step we train boosted SVM,  $H(\mathbf{x})$ , on entire training set  $S$ .<sup>4</sup> Next, each example is re-labelled with output  $\tilde{y}_n$  returned by  $H(\mathbf{x})$  ( $\tilde{S}$  denotes dataset after re-labelling procedure). Finally, set of decision rules is obtained by applying a rules inducer, e.g., RIPPER algorithm [38]. This is a typical application of the *pedagogical approach*.

## 4. Experiments

The main issue of this paper is to propose the novel *BoostingSVM-IB* algorithm for imbalanced data which is further used in the rule extraction. Therefore, we perform two experiments. First, the performance of the boosted SVM is examined on a set of 44 benchmark imbalanced datasets respecting *Gmean* value criterion. Second, the proposed approach with boosted SVM and rules extraction is applied to the prediction of the post-operative life expectancy in the lung cancer patients.

### 4.1. Benchmark datasets

In the first experiment we aim at evaluating predictive performance of the proposed boosted SVM. Stratified cross-validation

**Table 2**  
Characteristic of datasets used in experiment [4].

Dataset	# Inst.	# Attr.	%P	%N	Imb <sub>rate</sub>
Glass1	214	9	35.51	64.49	1.82
Ecoli0vs1	220	7	35.00	65.00	1.86
Wisconsin	683	9	35.00	65.00	1.86
Pima	768	8	34.84	66.16	1.90
Iris0	150	4	33.33	66.67	2.00
Glass0	214	9	32.71	67.29	2.06
Yeast1	1484	8	28.91	71.09	2.46
Vehicle1	846	18	28.37	71.63	2.52
Vehicle2	846	18	28.37	71.63	2.52
Vehicle3	846	18	28.37	71.63	2.52
Haberman	306	3	27.42	73.58	2.68
Glass0123vs456	214	9	23.83	76.17	3.19
Vehicle0	846	18	23.64	76.36	3.23
Ecoli1	336	7	22.92	77.08	3.36
New-thyroid2	215	5	16.89	83.11	4.92
New-thyroid1	215	5	16.28	83.72	5.14
Ecoli2	336	7	15.48	84.52	5.46
Segment0	2308	19	14.26	85.74	6.01
Glass6	214	9	13.55	86.45	6.38
Yeast3	1484	8	10.98	89.02	8.11
Ecoli3	336	7	10.88	89.77	8.77
Page-blocks0	5472	10	10.23	89.77	8.77
Yeast2vs4	514	8	9.92	90.08	9.08
Yeast05679vs4	528	8	9.66	90.34	9.35
Vowel0	988	13	9.01	90.99	10.10
Glass016vs2	192	9	8.89	91.11	10.29
Glass2	214	9	8.78	91.22	10.39
Ecoli4	336	7	6.74	93.26	13.84
Yeast1vs7	459	8	6.72	93.28	13.87
Shuttle0vs4	1829	9	6.72	93.28	13.87
Glass4	214	9	6.07	93.93	15.47
Page-blocks13vs2	472	10	5.93	94.07	15.85
Abalone9vs18	731	8	5.65	94.25	16.68
Glass016vs5	184	9	4.89	95.11	19.44
Shuttle2vs4	129	9	4.65	95.35	20.5
Yeast1458vs7	693	8	4.33	96.67	22.10
Glass5	214	9	4.20	95.80	22.81
Yeast2vs8	482	8	4.15	95.85	23.10
Yeast4	1484	8	3.43	96.57	28.41
Yeast1289vs7	947	8	3.17	96.83	30.56
Yeast5	1484	8	2.96	97.04	32.78
Ecoli0137vs26	281	7	2.49	97.51	39.15
Yeast6	1484	8	2.49	97.51	39.15
Abalone9	4174	8	0.77	99.23	128.87

is used as a research methodology in the experiment. The *BoostingSVM-IB* algorithm was implemented in *KEEL Software* [39,40] for comparative analysis with other methods dedicated for imbalanced problems.

The performance of *BoostingSVM-IB* method is examined using 44 benchmark imbalanced datasets available in *KEEL* tool and on website.<sup>5</sup> Multiclass datasets are modified to obtain two-class imbalanced data by merging some of possible class values [4]. Detailed description of the datasets is presented in Table 2, where **# Inst.** denotes total number of instances, **# Attr.** is the number of attributes in dataset, **%P** and **%N** represent percentage of positive and negative examples, respectively, and **Imb<sub>rate</sub>** is the ratio between negative and positive examples.

The quality of *BoostingSVM-IB* (**BSI**) method was compared with other methods working in imbalanced fashion:

- **SVM (SVM):** SVM trained using SMO.
- **SVM +SMOTE (SSVM):** SVM trained on data oversampled by SMOTE.

<sup>4</sup> The proposed method is invariant on classifier, so *strong learners* can be used instead.

<sup>5</sup> <http://www.keel.es/dataset.php>

**Table 3**

Results of Wilcoxon test made between **BSI** and the strongest methods from Tables 4 and 5.

Methods	R <sup>+</sup>	R <sup>-</sup>	Hypothesis ( $\alpha = 0.05$ )	p-Value
<b>BSI vs. UB</b>	715.0	275.0	rejected for <b>BSI</b>	0.01007
<b>BSI vs. RUS</b>	709.0	281.0	rejected for <b>BSI</b>	0.01231
<b>BSI vs. SSVM</b>	779.0	167.0	rejected for <b>BSI</b>	0.00021

- **SMOTEBoostSVM (SBSVM)**: Boosted SVM which uses SMOTE to generate artificial samples before constructing each of base classifiers.
- **C-SVM (CSVN)**: Cost-sensitive SVM described in details in [24,41].
- **AdaCost (AdaC)**: Cost-sensitive, ensemble classifier, in which the misclassification cost for minority class is higher than the misclassification cost for majority class [19].
- **SMOTEBoost (SBO)**: Modified AdaBoost algorithm, in which base classifiers are constructed using SMOTE synthetic sampling [9].
- **RUSBoost (RUS)**: Extension of SMOTEBoost approach, which uses additional undersampling in each boosting iteration [42].
- **SMOTEBagging (SB)**: Bagging method, which uses SMOTE to oversample dataset before constructing each of base classifiers [10].
- **UnderBagging (UB)**: Bagging method, which randomly undersamples dataset before constructing each of base classifiers [12].

Two groups of methods were selected for the analysis: SVM-based methods which deal with the problem of imbalanced data and ensemble based approaches presented and evaluated in [4]. In the first group of methods we have distinguished approaches which modify SVM classifier to enable adjusting to unequal data distribution. Additionally, we included simple SVM trained with SMO to compare the results with the method dedicated to be used for balanced data. The second group of methods is composed of ensemble techniques which achieved the highest results in empirical studies carried out in [4].

The detailed results are presented in Table 4 (**BSI** was compared with other SVM-based solutions) and in Table 5 (similar comparison was made for ensemble-based approaches). The highest average *Gmean* value was achieved by **BSI** method in both cases. For further analysis we used *Wilcoxon* non-parametric statistical test to investigate the differences in between results obtained by **BSI** and three other methods with the highest *Gmean* value: **UB**, **RUS** and **SSVM**. The results for the sum of positive and negative ranks and p-value for each pairwise comparison are presented in Table 3. Assuming the level of significance at 0.05 hypothesis about median equality were rejected for all pairs, what practically means that **BSI** significantly outperforms other considered methods.

#### 4.2. Thoracic surgery dataset

One of the main clinical decision problems in thoracic surgery (TS) is the appropriate patient selection for surgery, taking into account risk and benefits for a patient, both in short term (e.g., post-operative complications, including 30-days mortality) and also under longer term perspective (e.g., 1-year or 5-year survival). Traditional methods aim at incorporating standard statistical modelling, based on Kaplan–Meier survival curves, hierarchical statistical models, multivariable logistic regression or Cox proportional hazards regression [43–46]. Particular sets of predictors and their relative importance in post-operative survival or complications prediction are reported as results suggested by standard statistical software packages, while other authors formulate explicit regression-type models [47] or develop web-based applications, like Thoracoscore [48–50] one of the standard-like TS risk stratification scoring systems. Taking into account the limitations of both classic statistical approaches and hospital datasets,

which are often incomplete, due to missing values of attributes and unknown survivals for prospective analysis, and also – aiming at increasing not only formal prediction accuracy (which can easily be high with heavily imbalanced data) but also other performance measures like *AUC* or *Gmean*, other multivariable approaches have been proposed for the TS domain. Those include data mining and machine learning procedures for standardizing TS data analysis and report generation [51,52], as well as applications based on particular techniques, like decision trees [53,54] or artificial neural networks [55,56].

#### 4.2.1. Dataset description

In this chapter we report application of the proposed approach in modelling surgical risk for real-life clinical data from Thoracic Surgery domain. The data was collected retrospectively at Wrocław Thoracic Surgery Centre for over 1200 consecutive patients who underwent major lung resections for primary lung cancer in the years 2007–2011. The Centre is associated with the Department of Thoracic Surgery of the Medical University of Wrocław and Lower-Silesian Centre for Pulmonary Diseases, Poland, while the research database constitutes a part of the National Lung Cancer Registry, administered by the Institute of Tuberculosis and Pulmonary Diseases in Warsaw, Poland. The main dataset included 139 predictors, of which 36 from pre-operative, 37 from peri-operative, and 46 (including 17 pathology-related) from post-operative periods.

In this paper, we make use of the *BoostingSVM-IB* method to extract decision rules for the problem of 1-year survival period basing on the vector of attributes composed of 36 from pre-operative features.

#### 4.2.2. Features selection

First, the feature selection method was applied to evaluate the worth of each attribute. According to [57] this step is recommended in medical decision problems with imbalanced data. We used information gain criterion [58] at this stage, which resulted in reducing the number of features from 36 to 16 attributes. Features selected for further analysis are described in Table 6. Attributes *PRE4*, *PRE5* and *AGE* are numeric, *PRE14*, *DGN* and *PRE6* are nominal and the rest of features are binary.<sup>6</sup>

In the next step examples with missing values are eliminated from data.<sup>7</sup> The final dataset used in the experiment was composed of 470 examples and the imbalanced rate equalled 5.71.

#### 4.2.3. Method evaluation

Basing on the results from previous experiment we examined the quality of methods **UB**, **RUS**, **SSVM** and **BSI** for the problem of predicting post-operative life expectancy (see Table 7). Research methodology was the same as in the benchmark datasets experiment. According to *Gmean* criterion **BSI** method performed slightly better than the other three algorithms. Comparable results were achieved by **UB** but this ensemble technique has tendency to overbalance, what can be observed in higher values of *TP<sub>rate</sub>* and lower accuracy. Analysis of the results gathered in Tables 4, 5 and 7 leads to the conclusion that the most appropriate method for further rule extraction is **BSI**.

**BSI** is a highly uninterpretable classifier because it combines two “difficult to understand” models: SVM and ensembles. The oracle method for generating decision rules seems to be the best solution

<sup>6</sup> T(rue) if a symptom or clinical condition occurs, (F)alse otherwise

<sup>7</sup> The simplest method of dealing with missing values is proposed because the goal of this work is to present the novel approach for dealing with imbalanced data problem and extracting decision rules with oracle approach in the application of thoracic post-operative life expectancy, not to solve the problem itself.

**Table 4**

Detailed test results table for SVM-based methods vs. *BoostingSVM-IB*.

Dataset	SVM	SSVM	SBSVM	CSVM	BSI
Glass1	0.0	55.7	69.3	71.4	74.2
Ecoli0vs1	<b>98.7</b>	98.3	83.3	97.0	98.3
Wisconsin	96.9	<b>97.6</b>	95.7	94.6	97.3
Pima	69.6	75.3	74.4	73.2	74.6
Iris0	<b>100.0</b>	<b>100.0</b>	<b>100.0</b>	<b>100.0</b>	<b>100.0</b>
Glass0	48.1	70.7	74.8	77.4	77.8
Yeast1	45.2	70.6	70.3	71.6	72.5
Vehicle1	54.1	79.0	82.7	83.0	84.1
Vehicle2	93.8	95.0	<b>98.4</b>	97.4	98.1
Vehicle3	39.1	76.7	81.7	82.1	82.0
Haberman	0.0	55.3	62.0	62.4	64.2
Glass0123vs456	88.3	89.4	89.3	89.3	91.4
Vehicle0	95.0	96.5	96.5	<b>97.8</b>	97.1
Ecoli1	82.8	89.7	88.9	88.0	90.1
New-thyroid2	79.3	98.9	97.1	97.7	98.0
New-thyroid1	77.5	98.6	98.0	99.4	99.2
Ecoli2	77.2	91.1	92.4	91.9	92.2
Segment0	99.1	99.3	99.4	99.5	<b>99.8</b>
Glass6	84.4	89.5	86.9	88.8	88.6
Yeast3	76.5	91.8	89.8	90.7	91.9
Ecoli3	41.1	89.4	86.7	83.8	89.0
Page-blocks0	65.5	95.4	96.3	96.0	97.8
Yeast2vs4	74.0	89.4	87.1	88.3	89.2
Yeast05679vs4	0.0	79.5	75.1	74.2	79.1
Vowel0	97.1	98.8	<b>100.0</b>	<b>100.0</b>	<b>100.0</b>
Glass016vs2	0.0	56.2	57.5	61.9	<b>76.7</b>
Glass2	0.0	57.1	57.6	78.0	81.2
Ecoli4	80.6	92.4	88.0	88.6	92.6
Shuttle0vs4	99.6	99.6	99.6	99.6	99.6
Yeast1vs7	0.0	75.1	54.3	69.1	<b>79.4</b>
Glass4	39.2	90.7	82.2	86.6	92.9
Page-blocks13vs2	70.2	90.6	90.2	93.4	93.4
Abalone9vs18	0.0	87.1	72.1	86.0	89.9
Glass016vs5	0.0	95.0	87.4	81.2	98.3
Shuttle2vs4	90.9	99.6	91.3	91.3	91.3
Yeast1458vs7	0.0	63.8	66.6	57.3	66.4
Glass5	0.0	94.2	74.4	81.3	<b>99.0</b>
Yeast2vs8	74.1	76.7	74.1	61.0	79.6
Yeast4	0.0	81.2	62.0	77.3	81.4
Yeast1289vs7	0.0	69.7	18.2	62.6	73.3
Yeast5	21.3	96.6	84.6	94.0	94.8
Ecoli0137vs26	84.2	87.5	<b>96.7</b>	74.6	83.9
Yeast6	0.0	87.6	71.3	86.4	88.9
Abalone9	0.0	68.4	17.6	61.2	76.6
Average	51.0	85.0	80.0	83.8	<b>87.9</b>

The best results for each dataset are bolded.

because of the high quality of **BSI** and independence on learning process and simplicity of the approach.

**Table 7** shows the results obtained by typical rule extraction method named RIPPER (also named **JRip**) algorithm. It can be observed (see **Table 7**) that applying **JRip** alone for the medical problem resulted in constructing only one decision rule (*Risk1Y=F*), according to which each example should be classified to the majority class ( $TP_{rate} = 0.00$ ,  $TN_{rate} = 100.00$ ). Detecting cases in which patient dies in 1 year period is crucial in post-operative risk management domain. Therefore, it is essential to extract decision rules that covers minority examples, even at the expense of high accuracy decreases in majority class. **Table 7** contains also the results obtained by using relabelling technique with **BSI** as oracle before extracting rules by **JRip** (**JRip + BSI**). Results achieved by **JRip** trained using relabelled data were comparable with results gained by **BSI**, which means that the rules imitates the uninterpretable model at a satisfactory level.

#### 4.2.4. Extracted rules

The process of extracting rules using **BSI** as an oracle resulted in generating 9 decision rules presented in **Table 8**. In the machine learning literature, in order to evaluate induced rules coverage and

**Table 5**

Detailed test results table for ensemble-based methods vs. *BoostingSVM-IB*.

Dataset	AdaC	SBO	RUS	SB	UB	BSI
Glass1	78.9	<b>80.1</b>	78.2	75.2	76.5	74.2
Ecoli0vs1	97.0	97.0	97.7	98.3	98.0	98.3
Wisconsin	97.2	96.3	95.9	96.4	96.3	97.3
Pima	71.6	74.4	73.3	<b>76.1</b>	76.0	74.6
Iris0	99.0	99.0	99.0	98.0	99.0	<b>100.0</b>
Glass0	81.5	81.5	<b>85.6</b>	82.7	82.9	77.8
Yeast1	64.6	70.7	70.6	72.9	72.2	72.5
Vehicle1	79.5	74.4	74.0	77.1	77.6	84.1
Vehicle2	98.1	97.7	97.6	97.0	95.9	98.1
Vehicle3	76.7	73.9	77.5	75.6	79.0	82.0
Haberman	56.0	63.0	62.6	65.6	66.2	64.2
Glass0123vs456	92.3	90.3	91.0	92.3	90.5	91.4
Vehicle0	97.7	96.3	96.0	96.4	95.3	97.1
Ecoli1	89.1	87.8	<b>91.2</b>	90.3	90.4	90.1
New-thyroid2	95.7	96.9	95.5	96.6	94.9	98.0
New-thyroid1	94.6	98.3	97.7	97.5	96.6	99.2
Ecoli2	88.1	90.4	88.4	88.0	89.5	92.2
Segment0	98.2	99.6	99.1	99.3	98.9	<b>99.8</b>
Glass6	88.7	83.5	91.3	<b>92.1</b>	89.7	88.6
Yeast3	89.2	89.3	91.6	<b>94.1</b>	93.1	91.9
Ecoli3	82.2	81.5	87.1	86.9	89.0	89.0
Page-blocks0	<b>99.8</b>	99.7	97.0	99.0	97.0	97.8
Yeast2vs4	91.9	87.7	91.3	90.2	<b>95.4</b>	89.2
Yeast05679vs4	78.1	77.3	<b>84.4</b>	79.7	79.1	79.1
Vowel0	97.0	99.1	95.8	98.6	94.8	<b>100.0</b>
Glass016vs2	55.6	60.6	59.8	66.0	73.3	<b>76.7</b>
Glass2	71.9	76.9	70.4	<b>83.6</b>	77.0	81.2
Ecoli4	92.7	88.0	92.6	92.9	88.7	92.6
Shuttle0vs4	<b>100.0</b>	<b>100.0</b>	<b>100.0</b>	<b>100.0</b>	<b>100.0</b>	99.6
Yeast1vs7	70.1	63.2	73.5	65.2	74.5	<b>79.4</b>
Glass4	88.1	91.9	92.7	88.0	85.7	92.9
Page-blocks13vs2	79.7	93.4	95.0	95.6	<b>96.0</b>	93.4
Abalone9vs18	69.0	78.3	78.5	78.0	77.3	89.9
Glass016vs5	86.4	92.9	<b>98.9</b>	85.4	94.1	98.3
Shuttle2vs4	91.3	<b>100.0</b>	<b>100.0</b>	<b>100.0</b>	<b>100.0</b>	91.3
Yeast1458vs7	42.1	43.8	61.9	54.6	64.2	66.4
Glass5	97.3	98.3	86.7	92.0	94.7	<b>99.0</b>
Yeast2vs8	49.8	73.7	77.1	<b>79.7</b>	76.2	79.6
Yeast4	69.5	66.0	82.2	74.7	84.8	81.4
Yeast1289vs7	57.7	59.5	<b>74.5</b>	58.1	71.5	73.3
Yeast5	87.5	90.9	96.0	96.3	95.8	94.8
Ecoli0137vs26	81.5	83.0	81.2	83.1	75.4	83.9
Yeast6	67.8	80.2	83.7	82.4	87.0	88.9
Abalone9	17.5	17.6	68.5	38.7	69.0	76.6
Average	80.9	82.8	86.0	84.8	86.3	<b>87.9</b>

The best results for each dataset are bolded.

**Table 6**

Characteristic of selected pre-operative features.

ID	Description	InfoGain
PRE14	T in clinical TNM (size of the original tumour, from OC11 (smallest) to OC14 (largest))	0.029
DGN	Diagnosis (specific combination of ICD-10 codes for primary and secondary as well multiple tumours if any)	0.013
PRE4	Forced vital capacity (FVC)	0.008
PRE7	Pain (pre-surgery)	0.008
AGE	Age at surgery	0.008
PRE6	Performance status (Zubrod scale)	0.007
PRE11	Weakness (pre-surgery)	0.004
PRE9	Dyspnoea (pre-surgery)	0.004
PRE10	Cough (pre-surgery)	0.003
PRE8	Haemoptysis (pre-surgery)	0.003
PRE25	PAD (peripheral arterial diseases)	0.003
PRE19	MI up to 6 months	0.003
PRE5	Volume that has been exhaled at the end of the first second of forced expiration (FEV1)	0.002
PRE32	Asthma	0.002
PRE30	Smoking	0.002
PRE17	Type 2 DM (diabetes mellitus)	0.002
Risk1Y	1 year survival period ((T)rue value if died)	

**Table 7**  
Results for thoracic surgery data.

Method	TP <sub>rate</sub>	TN <sub>rate</sub>	Gmean
<b>UB</b>	<b>68.57</b>	61.75	65.07
<b>RUS</b>	52.85	65.50	58.84
<b>SSVM</b>	57.14	68.25	62.45
<b>BSI</b>	60.00	72.00	<b>65.73</b>
<b>JRip</b>	0.00	<b>100.00</b>	0.00
<b>JRip + BSI</b>	60.00	70.00	64.81

The best results for each dataset are bolded.

**Table 8**  
Rules extracted from thoracic surgery data.

Rules	Coverage	Accuracy
(DGN = DGN5) => Risk1Yr = T	0.03	0.47
(PRE14 = OC14) => Risk1Yr = T	0.04	0.41
(PRE17 = T) and (PRE30 = T) and (AGE > = 57) => Risk1Yr = T	0.05	0.38
(PRE11 = T) and (PRE5 < = 2.16) and (PRE4 > = 2.44) => Risk1Yr = T	0.05	0.35
(PRE9 = T) and (AGE > = 54) and (PRE5 < = 66.4) => Risk1Yr = T	0.05	0.35
(PRE14 = OC13) => Risk1Yr = T	0.04	0.32
(DGN = DGN2) and (PRE30 = T) and (PRE14 = OC12) and (PRE5 < = 3.72) => Risk1Yr = T	0.04	0.30
(PRE8 = T) and (PRE30 = T) and (PRE4 < = 3.52) => Risk1Yr = T	0.08	0.26
OTHERWISE => Risk1Yr = F	0.62	0.97

accuracy measures are typically used. The coverage measure determines the percentage of examples covered by rule on average while the accuracy measure expresses the relative frequency of examples satisfying the complete rule among those satisfying only the antecedent. The accuracy for rules combined with the minority class was from 0.26 to 0.47. Each of the rules covered from 3% to 8% of the training data. Remaining subspace of features covered 62% of examples with accuracy of 97% for the majority class.

Results show that it is possible to identify cases of higher risk of patient's death after surgery by applying oracle-based approach combined with boosted SVM method. Extracted rules together with coverage and accuracy values give important information about patients suffering special treatment due to high risk of death. It is also important to highlight, that patients uncovered by the minority rules in 97% of cases will survive the considered survival period.

## 5. Conclusions

In this paper, we have proposed a novel boosted SVM method for imbalanced data problem which was further used for rules extraction. We have evaluated the quality of the proposed approach by comparing it with other solutions dedicated for imbalanced data problem. Next, we have used the proposed method to solve the problem for prediction of the post-operative life expectancy in the lung cancer patients. We have shown that our approach can be successfully applied to the problem by making additional experimental comparison on real-life dataset. Finally, we extracted decision rules using oracle-based approach.

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