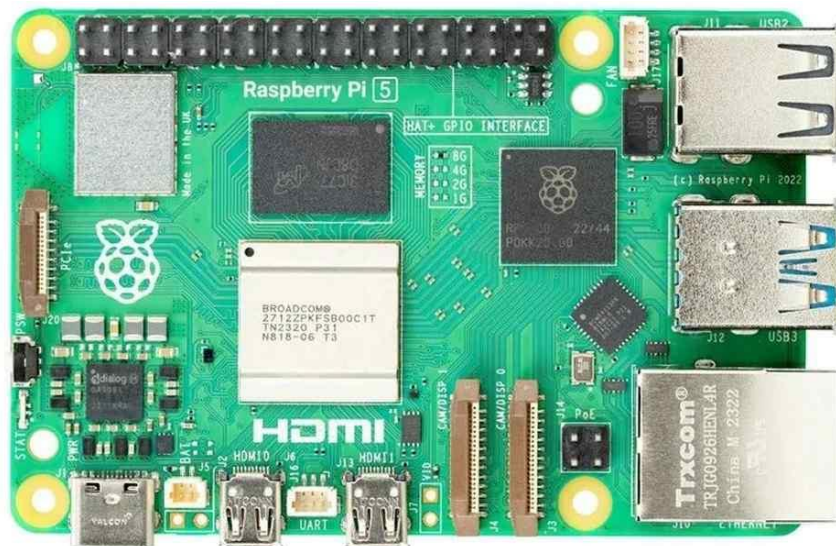


# Raspberry Pi

## Tutorial

Using RPi.GPIO calls on a Raspberry Pi  
Model 5 or Bookworm OS



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## Introduction

The Raspberry Pi Model 5 was introduced at the end of 2023. It only works with **Raspberry Pi Bookworm OS** or later.

However, the biggest impact for most developers is that the **RPi.GPIO** input/output library does not work on the **Raspberry Pi model 5**. This is because the **RPi Model 5** now has a separate chip called **RP1** for controlling I/O including the pins on the GPIO header (**j8**). This means that hundreds of thousands of programs or maybe even millions of programs need to be modified to use one of the newer libraries such as **gpiod** or **lgpio**. The **RP1** chip also controls USB ports, Gigabyte Ethernet, MIPI Camera Controllers and Low Speed Peripherals compatible with earlier versions of the Raspberry Pi.

My own product, the **Raspberry Pi Internet Radio** is also such a program and would have meant a lot of work to convert all the GPIO routines to say **GPIOD** which does run on the RPi Model 5. So, I decided to write a simple interface called **GPIOconverter** which converts **RPi GPIO** calls to one of the newer GPIO interfaces. This is a so-called **software shim**. See the following link for more information: [https://en.wikipedia.org/wiki/Shim\\_\(computing\)](https://en.wikipedia.org/wiki/Shim_(computing)). **GPIOD** was advocated as the best way forward however I found that **GPIOD** was poorly documented and there didn't seem to be any examples of how to handle interrupts. I eventually settled on using the excellent **python3-lgpio** library for the **GPIOconverter** software. The architecture of the interface is shown below:

**OUTPUT: User Program --> GPIO calls --> GPIOconverter --> LGPIO**

**INPUT: LGPIO events --> GPIOconverter --> User Program**

The following illustration shows the location of the RPP1 I/O chip.

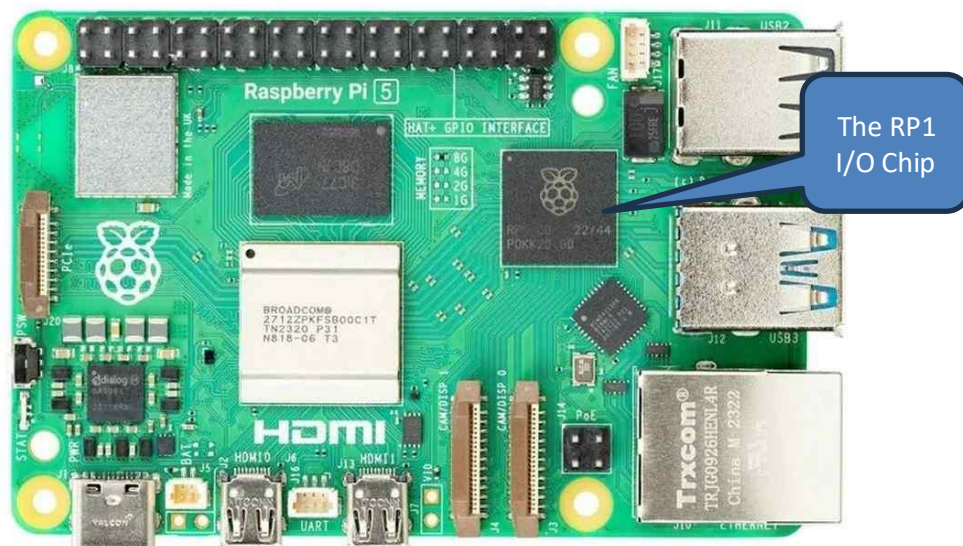
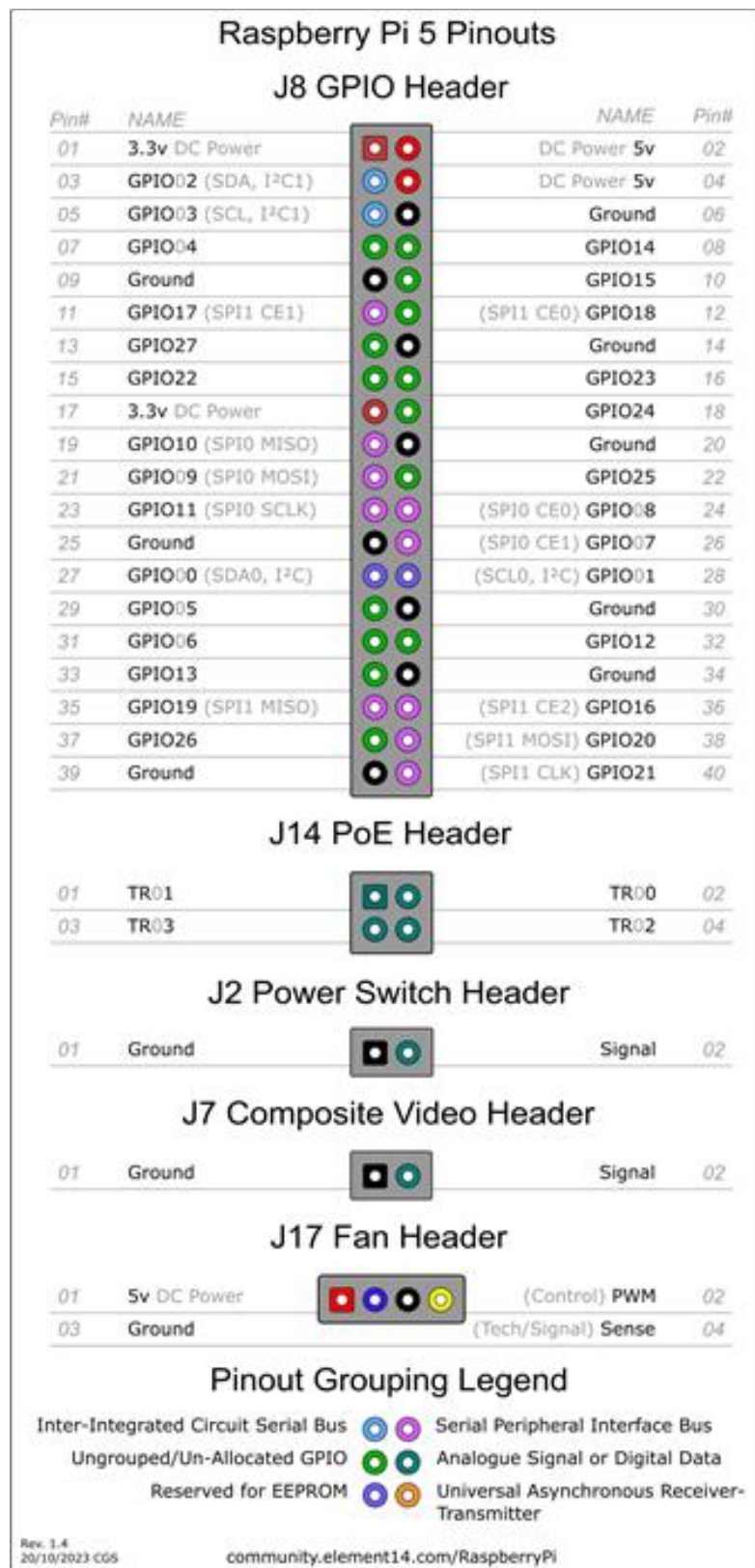


Figure 1 The Raspberry Pi Model 5 RP1 I/O chip

See *Appendix B - The RP1 general purpose I/O Chip* on page 9 for more information.

## GPIO Hardware Notes



## Conventions used in this tutorial

Installation of the radio program requires you to enter lines at the command line prompt. This requires you to log into the Raspberry PI as user '**pi**'. The default password is **raspberrypi**.



**Note:** Don't carry out any of the following commands just yet. They are just examples.

```
Raspberrypi login: pi
Password: raspberrypi
pi@raspberrypi:~$ Last login: Sun Apr  6 10:18:18 2014 from 192.168.2.100
pi@raspberrypi:~$
```

The prompt line is displayed ending with a \$ sign. The **pi@raspberrypi:~** string means user 'pi' on host machine called 'raspberrypi'. The ~ character means the user 'pi' home directory **/home/pi**. In this tutorial if you are required to do something as user **pi** then only the \$ sign will be shown followed by the command as shown in the example below:

```
$ pinout
```

Some commands produce output which does not need to be shown. In such a case a ':' is used to indicate that some output has been omitted.

```
$ pinout
Description      : Raspberry Pi 5B rev 1.0
Revision         : c04170
: {Output omitted}
J8:
  3V3  (1) (2)  5V
  GPIO2 (3) (4)  5V
  GPIO3 (5) (6)  GND
  GPIO4 (7) (8)  GPIO14
  GND   (9) (10) GPIO15
  GPIO17 (11) (12) GPIO18
  GPIO27 (13) (14) GND
  GPIO22 (15) (16) GPIO23
  3V3   (17) (18) GPIO24
  GPIO10 (19) (20) GND
  GPIO9  (21) (22) GPIO25
  GPIO11 (23) (24) GPIO8
  GND    (25) (26) GPIO7
  GPIO0  (27) (28) GPIO1
  GPIO5  (29) (30) GND
  GPIO6  (31) (32) GPIO12
  GPIO13 (33) (34) GND
  GPIO19 (35) (36) GPIO16
  GPIO26 (37) (38) GPIO20
  GND    (39) (40) GPIO21
For further information, please refer to https://pinout.xyz/
```

END OF EXAMPLE COMMANDS.

## Which OS works with my Raspberry Pi model

The following article contains a table showing which model Raspberry Pi's work with which Raspberry Pi OS:

[https://en.wikipedia.org/wiki/Raspberry\\_Pi\\_OS](https://en.wikipedia.org/wiki/Raspberry_Pi_OS)

## RPi/GPIO.py

The **GPIO.py** code is only for use with the **Raspberry Pi Model 5** or for earlier models such as the **Model 3B** or **4B** which are running the **Bookworm OS** or later. The code is designed to intercept traditional GPIO calls and convert them to LGPIO calls. See: [https://abyz.me.uk/lg/py\\_lgpio.html](https://abyz.me.uk/lg/py_lgpio.html)



**NOTE:** On the 15<sup>th</sup> of March 2024 the **Raspberry Pi Foundation** released a new version of the **Bookworm** Operating System Firmware which completely broke the input functionality of the GPIO header pins. The error manifests itself as "Error: GPIO *nn* Failed to add edge detection" where *nn* is the GPIO number of the relevant pin. This means that it became necessary to either install **Bullseye OS** or to install an older release of **Bookworm** from December 2023 which has older firmware. However, the **GPIO.py** program now supports the **gpiochip0** circuitry embedded in the BCM processor. Once **GPIOconverter** is enable it intercepts calls to RPi.GPIO and converts them to **lgpio** calls. This only works on **Bookworm** or later. Earlier versions of the OS such as Bullseye continue to use the normal **RPi.GPIO** calls as normal.

## Installation

### Pre-requisites

Install package **python3-lgpio**

```
$ sudo apt install python3-lgpio
```

Don't include the "\$" sign in the command you enter.

### Downloading GPIOconverter

Log into the Raspberry Pi Model 5 and clone the **GPIOconverter** software and run:

```
$ cd
$ git clone https://github.com/bobrathbone/GPIOconverter
```

### Installation

Create a sub-directory called RPi in the directory where your GPIO code is installed. For example, for code in directory **/usr/share/radio**:

```
$ cd /usr/share/radio
$ mkdir RPi
```



Now copy **GPIO.py** to **/usr/share/radio**

```
$ cp <source>/GPIO.py /usr/share/radio/RPi/.
```

## Enabling GPIO.py

For a Raspberry Pi model 5 only or earlier models running Bookworm OS. For example, for code found in the **/usr/share/radio/** directory:

```
$ touch /usr/share/radio/RPi/__init__.py
```

The instruction above will cause the code using the GPIO calls to see directory RPi as a package.

For earlier models such as the 3B or 4B disable the package:

```
$ rm /usr/share/radio/RPi/__init__.py
```

## Known Issues

### GPIO.setwarnings call ignored

The call **GPIO.setwarnings(True|False)** is currently ignored.

### Using GPIOconverter with Rotary Encoders

There is a lot of Python software for Rotary Encoders which was originally written by Ben Buxton in 2011. You may find that the Rotary Encoder is sluggish and misses a high number of turns. In the case of the Ben Buxton code this can be corrected by changing the **HALF\_STEP** flag from **False** to **True**.

```
# Enable this to emit codes twice per step.  
# HALF_STEP == True: emits a code at 00 and 11  
# HALF_STEP == False: emits a code at 00 only  
HALF_STEP = True  
STATE_TAB = HALF_TAB if HALF_STEP else FULL_TAB
```

Fortunately, the above change doesn't seem to affect operation when running the code using the standard **RPi.GPIO** calls on say a Raspberry Pi Model 4B.

## Support

It is not possible to provide support for the standard GPIO library as literally hundreds of thousands of programs are using GPIO routines. The code is provided as is and without any warranties or "fit for purpose" etc. However, do contact [bob@bobrahbone.com](mailto:bob@bobrahbone.com) for any errors or missing features in **GPIOconverter** on **Raspberry Pi Model 5 only**.

## Source files

The software is stored on **GitHub** at <https://github.com/bobrathbone/GPIOconverter> or is available as an archive (tar) for download from:

<https://bobrathbone.com/raspberrypi/packages/GPIOconverter.tar.gz>

The **GPIO.py** file uses the Python 3 LGPIO library (python3-lgpio) to handle calls to and from the RP1 i/o chip. More information on LGPIO see: [https://abyz.me.uk/lg/py\\_lgpio.html](https://abyz.me.uk/lg/py_lgpio.html)

Python code examples will be found at: <https://abyz.me.uk/lg/examples.html#Python%20lgpio>

## Appendix A Licences

The software and documentation for this project is released under the GNU General Public Licence.

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## Acknowledgements

The people at <https://abyz.me.uk/lg/index.html>. No individuals are mentioned by name on their Web site but who ever they are, they have made an excellent product for General Purpose Input Output control on Linux Single Board Computers such as the Raspberry Pi Model 5 with extremely professional documentation. My compliments.



## Appendix B - The RP1 general purpose I/O Chip

The RP1 general purpose I/O chip is a 12×12mm, 0.65mm-pitch BGA southbridge, which provides the majority of the I/O capabilities for Raspberry Pi 5.

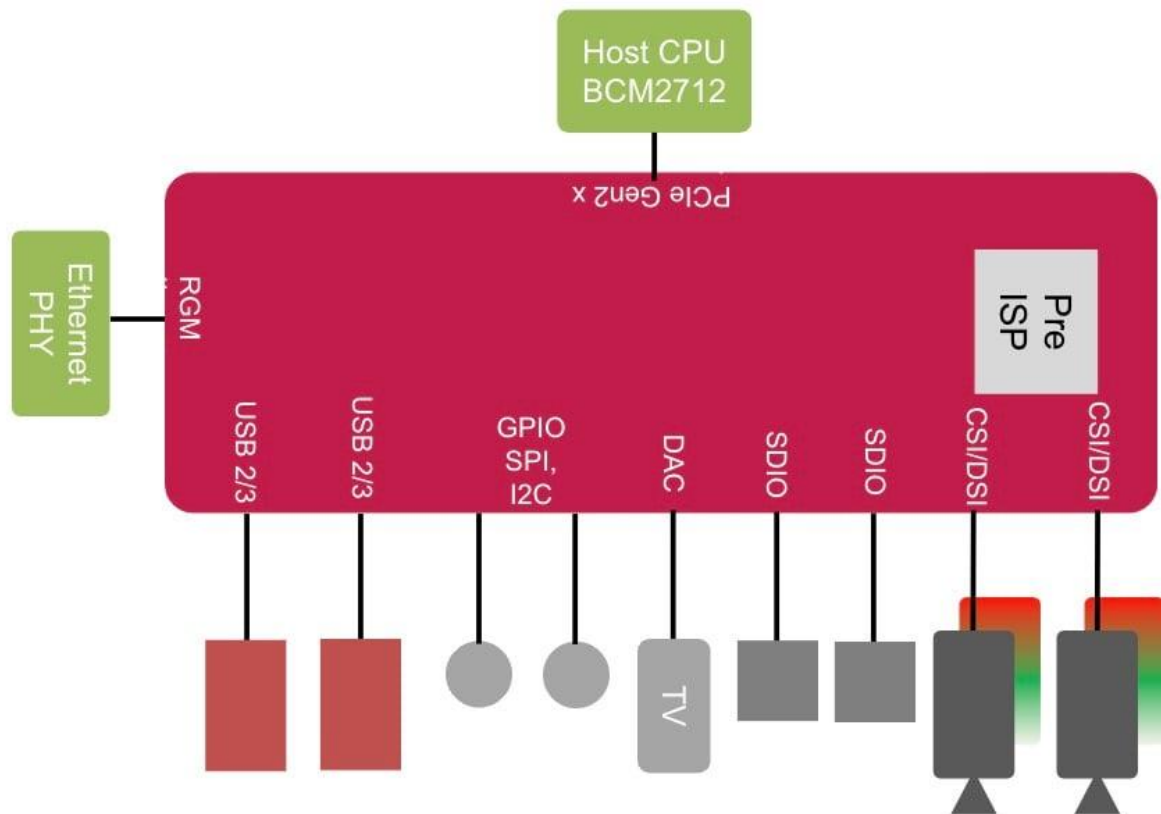


Figure 3 The RP1 General Purpose I/O Chip

The RPi chip provides:

- 4-lane PCIe 2.0 endpoint
- Gigabit Ethernet MAC
- 2× USB 3 host controllers
  - Each has 1× USB 3 and 1× USB 2 port
  - More than twice the usable USB bandwidth vs. Raspberry Pi 4
- 2× SDIO ports/eMMC (not used on Raspberry Pi 5)
- 2× MIPI transceivers (4-lane, supporting DSI and CSI-2)
- Video DAC (3-channel, supporting PAL/NTSC and VGA)
  - Only one channel (composite) used on Raspberry Pi 5
- Low-speed peripherals (SPI, UART, I2C, PWM, GPIO, I2S)
- Delta-sigma PWM audio out

More information on RP1 can be found in the RP1 Peripherals document.

See <https://datasheets.raspberrypi.com/rp1/rp1-peripherals.pdf>

## Glossary

<b>BGA</b>	Ball Grid Array – A popular surface mount for Integrated Circuits (ICs)
<b>CSI</b>	Camera Serial Interface
<b>DAC</b>	Digital to Analogue Converter (In this case for audio output cards)
<b>DSI</b>	Display Serial Interface
<b>GND</b>	Ground, 0 Volts
<b>GPIO</b>	General Purpose IO (On the Raspberry Pi)
<b>I2C</b>	Two-wire serial communication protocol
<b>I2S</b>	Electrical serial bus for connecting digital audio devices
<b>RP1</b>	Input Output Controller Chip for Raspberry Pi Model 5 peripherals
<b>SPI</b>	Serial Peripheral Interface – Interface us between digital components
<b>USB</b>	Universal Serial Bus