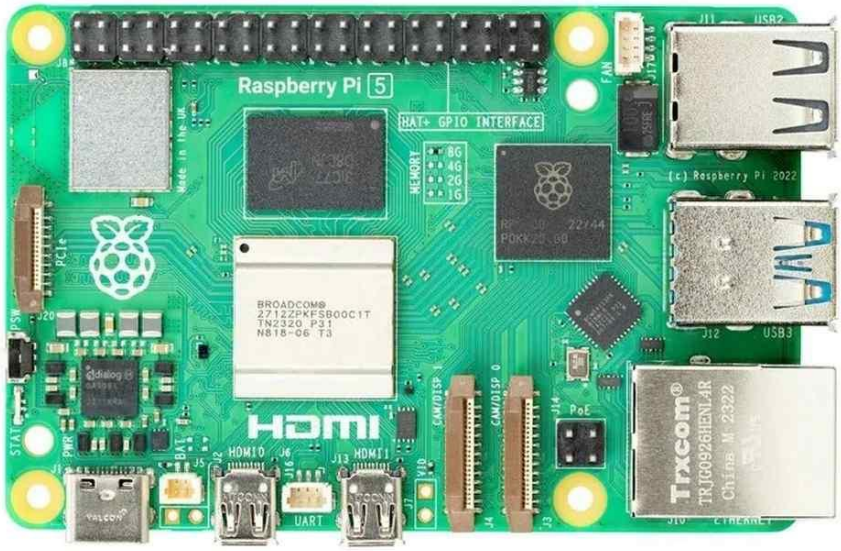
Raspberry Pi Tutorial

Using RPi.GPIO calls on a Raspberry Pi Model 5 or Bookworm OS



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Version 1.0

7th of March 2025

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Introduction

The Raspberry Pi Model 5 was introduced at the end of 2023. It only works with **Raspberry Pi Bookworm OS** or later.

However, the biggest impact for most developers is that the **RPi.GPIO** input/output library does not work on the **Raspberry Pi model 5** or on systems running **Bookworm**. This is because the **RPi Model 5** now has a separate chip called **RP1** for controlling I/O including the pins on the GPIO header (**j8**). In the case of Bookworm, the authors of **RPi/GPIO** have apparently not yet updated their software (this will no doubt change in the future). This means that hundreds of thousands of programs or maybe even millions of programs need to be modified to use one of the newer libraries such as **gpiod** or **lgpio**. The **RP1** chip also controls USB ports, Gigabyte Ethernet, MIPI Camera Controllers and Low Speed Peripherals compatible with earlier versions of the Raspberry Pi.

My own product, the **Raspberry Pi Internet Radio** is also such a program and would have meant a lot of work to convert all the GPIO routines to say **GPIOD** which does run on the RPi Model 5. So, I decided to write a simple interface called **GPIOconverter** which converts **RPi.GPIO** calls to one of the newer GPIO interfaces. This is a so-called **software shim**. See the following link for more information: **https://en.wikipedia.org/wiki/Shim_(computing)**. **GPIOD** was advocated as the best way forward however, at the time, I found that GPIOD was poorly documented and there didn't seem to be any examples of how to handle interrupts. This has improved since. I eventually settled on using the excellent **python3-lgpio** library for the **GPIOconverter** software. The architecture of the interface is shown below:

OUTPUT: User Program --> GPIO calls --> GPIOconverter --> LGPIO

INPUT: LGPIO events --> GPIOconverter --> User Program

The following illustration shows the location of the RPP1 I/O chip.

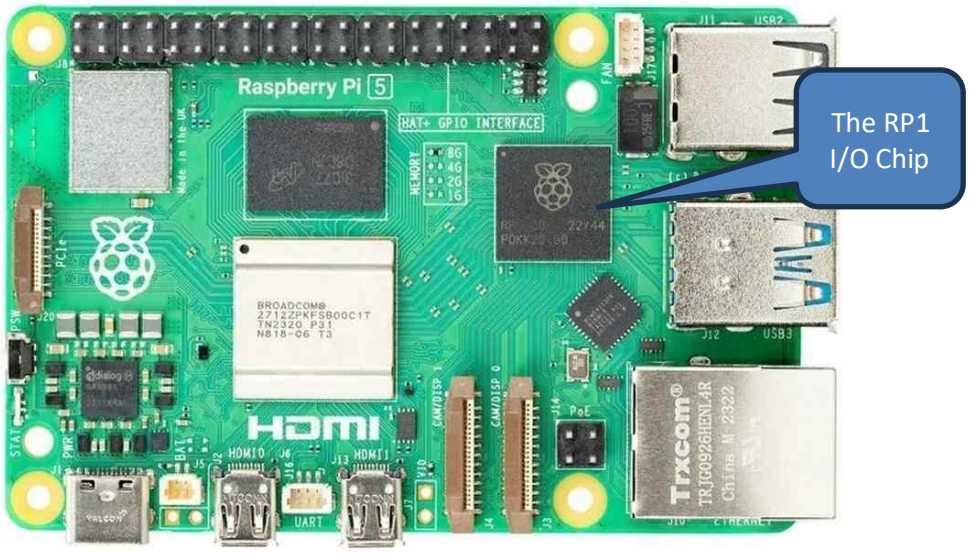

Figure 1 The Raspberry Pi Model 5 RP1 I/O chip

See *Appendix B - The RP1 general purpose I/O Chip* on page 12 for more information.

GPIO Hardware Notes

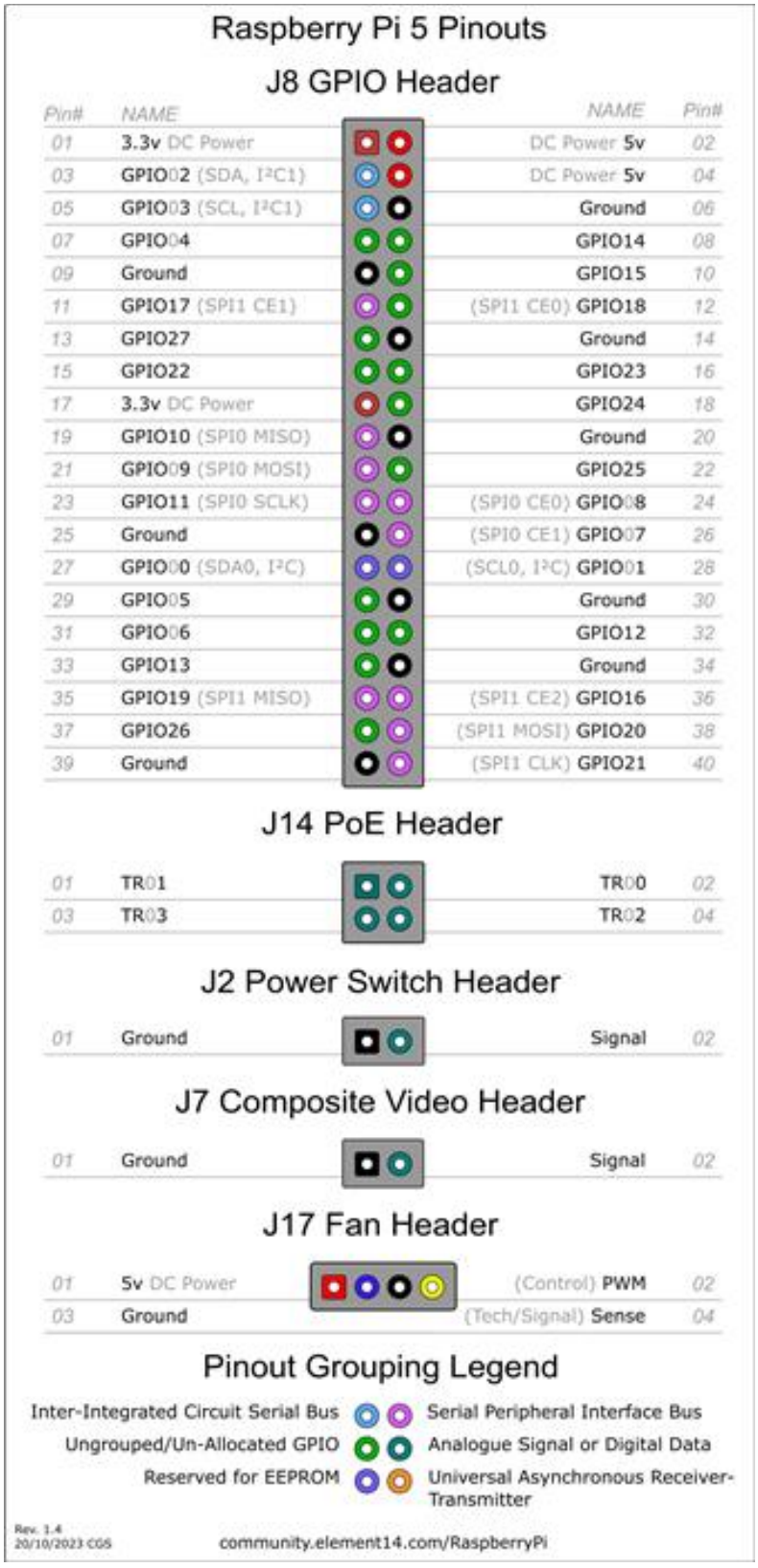

Figure 2 GPIO and other Headers Information

Conventions used in this tutorial

Installation of the radio program requires you to enter lines at the command line prompt. This requires you to log into the Raspberry PI as user '**pi**'. The default password is **raspberry**.

Note: Don't carry out any of the following commands just yet. They are just examples.

```
Raspberrypi login: pi
Password: raspberry
pi@raspberrypi:~$ Last login: Sun Apr  6 10:18:18 2014 from 192.168.2.100
pi@raspberrypi:~$
```

The prompt line is displayed ending with a **$** sign. The **pi@raspberrypi:~** string means user 'pi' on host machine called 'raspberrypi'. The ~ character means the user 'pi' home directory **/home/pi**. In this tutorial if you are required to do something as user **pi** then only the $ sign will be shown followed by the command as shown in the example below:

```
$ pinout
```

Some commands produce output which does not need to be shown. In such a case a ':' is used to indicate that some output has been omitted.

```
$ pinout
Description        : Raspberry Pi 5B rev 1.0
Revision           : c04170
: {Output ommited}
J8:
   3V3  (1) (2)  5V
 GPIO2  (3) (4)  5V
 GPIO3  (5) (6)  GND
 GPIO4  (7) (8)  GPIO14
   GND  (9) (10) GPIO15
GPIO17 (11) (12) GPIO18
GPIO27 (13) (14) GND
GPIO22 (15) (16) GPIO23
   3V3 (17) (18) GPIO24
GPIO10 (19) (20) GND
 GPIO9 (21) (22) GPIO25
GPIO11 (23) (24) GPIO8
   GND (25) (26) GPIO7
 GPIO0 (27) (28) GPIO1
 GPIO5 (29) (30) GND
 GPIO6 (31) (32) GPIO12
GPIO13 (33) (34) GND
GPIO19 (35) (36) GPIO16
GPIO26 (37) (38) GPIO20
   GND (39) (40) GPIO21
For further information, please refer to https://pinout.xyz/
```

END OF EXAMPLE COMMANDS.

Which OS works with my Raspberry Pi model

The following article contains a table showing which model Raspberry Pi's work with which Raspberry Pi OS:
https://en.wikipedia.org/wiki/Raspberry_Pi_OS

RPi.GPIO.py

The **GPIO.py code** is only for use with the **Raspberry Pi Model 5** or for earlier models such as the **Model 3B** or **4B** which are running the **Bookworm 32-bit OS** or later. The code is designed to intercept traditional GPIO calls and convert them to LGPIO calls. See:
https://abyz.me.uk/lg/py_lgpio.html

NOTE: On the **15th of March 2024** the **Raspberry Pi Foundation** released a new version of the **Bookworm** Operating System Firmware which completely broke the input functionality of the GPIO header pins on the **32-Bit** version of the OS. The **64-Bit** version is still OK at the time of writing. The error manifests itself as "Error: GPIO *nn* Failed to add edge detection" where *nn* is the GPIO number of the relevant pin. However, the **GPIO.py** program now supports the **gpiochip0** circuitry embedded in the BCM processor. Once **GPIOconverter** is enable it intercepts calls to **RPi.GPIO** and converts them to **lgpio** calls. This only works on **Bookworm** or later. Earlier versions of the OS such as **Bullseye** continue to use the legacy **RPi.GPIO** calls as normal.

Installation

There are two methods of installing **GPIOconverter** software:

1) Install as a systemwide package usually in **/usr/lib/python3/dist-packages/RPi**
2) In the project directory as your GPIO program as a local package

Method 1 means that only your local **RP.GPIO** program(s) installation will be using **GPIOconverter**. All other GPIO programs will use the standard GPIO library in **/usr/lib/python3/dist-packages/RPi**

Building and installing the GPIOconverter package

The software is installed from the GPIOconverter package (gpioconverter_1.0_all.deb). To build it carry out the following procedure:

Install the python3-lgpio package

The **GPIOconverter** package requires the **python3-lgpio** module. Log into the Raspberry Pi and install the **python3-lgpio** package

```
sudo apt install python3-lgpio
```

Downloading GPIOconverter from GitHub

Now clone the **GPIOconverter** software to your home directory and run:

```
cd
git clone https://github.com/bobrathbone/GPIOconverter
```

Build the GPIOconverter package

```
cd GPIOconverter
chmod +x build.sh
./build.sh
```

The build script will now create the **GPIOconverter** package. Towards the end of the build you will be asked if you wish to check the package with Lintian. This is only used by developers so - Answer n

```
Check using Lintian y/n: n
```

Installing the GPIOconverter package

At the end of the run the build script will display the instruction to install the package using **dpkg** installer as shown below:

```
Install the **gpioconverter_1.0_all.deb** package with the following
command:
sudo dpkg -i gpioconverter_1.0_all.deb
```

Installation to a local directory

It may well be that you only wish to install the package **GPIOconverter** software in a specific project directory leaving the rest of the system unaffected. If so, you do not need to create the package but only copy the main files to your project directory.

Create a sub-directory called RPi in the directory where your GPIO code is installed For example codein directory **/usr/share/myproject**:

```
cd /usr/share/myproject
mkdir RPi
cp /home/<user>/GPIOconverter/RPi/GPIO.py /usr/share/myproject/RPi/.
```

Where **<user>** is your log in name (usually 'pi')

Enabling GPIO.py

If running on a **Raspberry Pi model 5** or if running **Bookworm (32-bit)** or later. Example:

```
touch /usr/share/myproject/RPi/__init__.py
```

The above instruction will cause the code using the GPIO calls to see directory **RPi** as a package. For earlier models such as the 3B or 4 disable the package unless running on **Bookworm 32-bit OS** using the instruction below:

```
rm /usr/share/myproject/RPi/__init__.py
```

NOTE: The first part of the above procedure is not necessary if you installed the software from the Debian package (**gpioconverter_1.0_all.deb**) as the installation process does this for you.

Known Issues

GPIO.setwarnings call limitations

The call **GPIO.setwarnings(True|False)** is currently not implemented in a compatible manner in **lgpio**. The **lgpio** package does not have the equivalent of **GPIO.setwarnings** but has the **lgpio.exceptions** call which can be set to True or False. So, the **setwarnings** call can either be ignored or be used to enable and disable **lgpio** exceptions. Set **IGNORE_WARNINGS** to **True** at the beginning of the **GPIO.py** program to prevent **lgpio exceptions** or control this with the **GPIO.setwarnings** call.

Using GPIOconverter with Rotary Encoders

There is a lot of Python software for Rotary Encoders which was originally written by Ben Buxton in 2011. You may find that the Rotary Encoder is sluggish and misses a high number of turns. In the case of the Ben Buxton code this can be corrected by changing the **HALF_STEP** flag from **False** to **True**.

```
# Enable this to emit codes twice per step.
# HALF_STEP == True: emits a code at 00 and 11
# HALF_STEP == False: emits a code at 00 only
HALF_STEP      = True
STATE_TAB = HALF_TAB if HALF_STEP else FULL_TAB
```

Fortunately, the above change doesn't seem to affect operation when running the code using the standard **RPi.GPIO** calls on say a Raspberry Pi Model 4B.

Support

It is not possible to provide support for the standard **RPi.GPIO library** as literally hundreds of thousands of programs are using **RPi.GPIO** routines. The code is provided as is and without any warranties or "fit for purpose" etc. However, do contact bob@bobrahbone.com or raise an issue on https://github.com/bobrathbone/GPIOconverter for any errors or missing features in **GPIOconverter**.

Source files

The software is stored on **GitHub** at https://github.com/bobrathbone/GPIOconverter or is available as an archive (tar) for download from:
https://bobrathbone.com/raspberrypi/packages/GPIOconverter.tar.gz

The GPIO.py shim software

The **GPIO.py** file uses the Python 3 LGPIO library (python3-lgpio) to handle calls to and from the RP1 i/o chip. More information on LGPIO see: https://abyz.me.uk/lg/py_lgpio.html

Python code examples will be found at: https://abyz.me.uk/lg/examples.html#Python%20lgpio

The test_pwm.py program

The **test_pwm.py** program tests the **PWM** (Pulse-Width Modulation) function of **RPi.GPIO** which, which is a technique for creating variable-width pulses to encode or modulate a signal. PWM is used in many applications, including power supplies, DC-DC switching regulators, and DC motor control or in this case to brighten and dim a LED. To use it, amend the "led = 16" statement in the source code The test_pym.py program

First edit the **test_pwm.py** file and change the led GPIO setting to the the GPIO number you are using for the test.

```
# Change the following values to suit your system
Led = 16          # Led GPIO for mode BCM
```

Now run the program. The selected LED should brighten and dim. Press Ctrl-C to end the test.

```
cd /usr/share/myproject/RPi
./test_pwm.py
```

Note: If you are only using **GPIOconverter** in a local project directory then it is necessary to first copy **test_pwm.py** to it and run it from there as shown in the following example.

```
cd /usr/share/myproject
cp RPi/test_pwm.py .
./test_pwm.py
```

The above isn't necessary if you installed the **GPIOconverter** package as previously shown.

The test_group.py program

The **test_group.py** program is a simple test program used to test the **RPi.GPIO group** functions.

First edit the **test_group.py** file and change the list of GPIOs in **chan_list** parameter to change the GPIO list that you are using for the test.

```
chan_list = [18,16,17,4]        # Group GPIOs for mode BCM
chan_list_board = [12,36,11,7]  # Group GPIOs for mode BOARD
```

If you are using mode **GPIO.BOARD** then also edit the **chan_list_board** definition. The mapping between **GPIO.BCM** and **GPIO.BOARD** will be found in the **pins** definition in **RPi.GPIO.py**

```
# pins is the mapping between GPIO.BOARD and GPIO.BCM. Format Pin:GPIO
pins = {
         3:2, 5:3, 7:4, 8:14, 10:15, 11:17, 12:18, 13:27, 15:22, 16:23,
18:24, 19:10,
         21:9, 22:25, 23:11, 24:8, 26:7, 27:0, 28:1, 29:5, 31:6, 32:12,
33:13, 35:19,
         36:16, 37:26, 38:20, 40:21,
       }
```

The program first flashes a single LED as configured by the **led** parameter and then switches alternate LEDs on and off as defined in **chan_list** and the

Appendix A Licences

The software and documentation for this project is released under the GNU General Public Licence.

The GNU General Public License (GNU GPL or GPL) is the most widely used free software license, which guarantees end users (individuals, organizations, companies) the freedoms to use, study, share (copy), and modify the software. Software that ensures that these rights are retained is called free software. The license was originally written by Richard Stallman of the Free Software Foundation (FSF) for the GNU project.

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Acknowledgements

The people at https://abyz.me.uk/lg/index.html. who produced the **lgpio** package. No individuals are mentioned by name on their Web site but whoever they are, they have made an excellent product for General Purpose Input Output control on Linux Single Board Computers such as the Raspberry Pi Model 5 with extremely professional documentation. My compliments.

The GitHub member known only by the handle **fgmnts** who kindly implemented PWM support in **GPIOconverter**. See https://github.com/fgmnts

Appendix B - The RP1 general purpose I/O Chip

The RP1 general purpose I/O chip is a 12×12mm, 0.65mm-pitch BGA southbridge, which provides the majority of the I/O capabilities for Raspberry Pi 5.

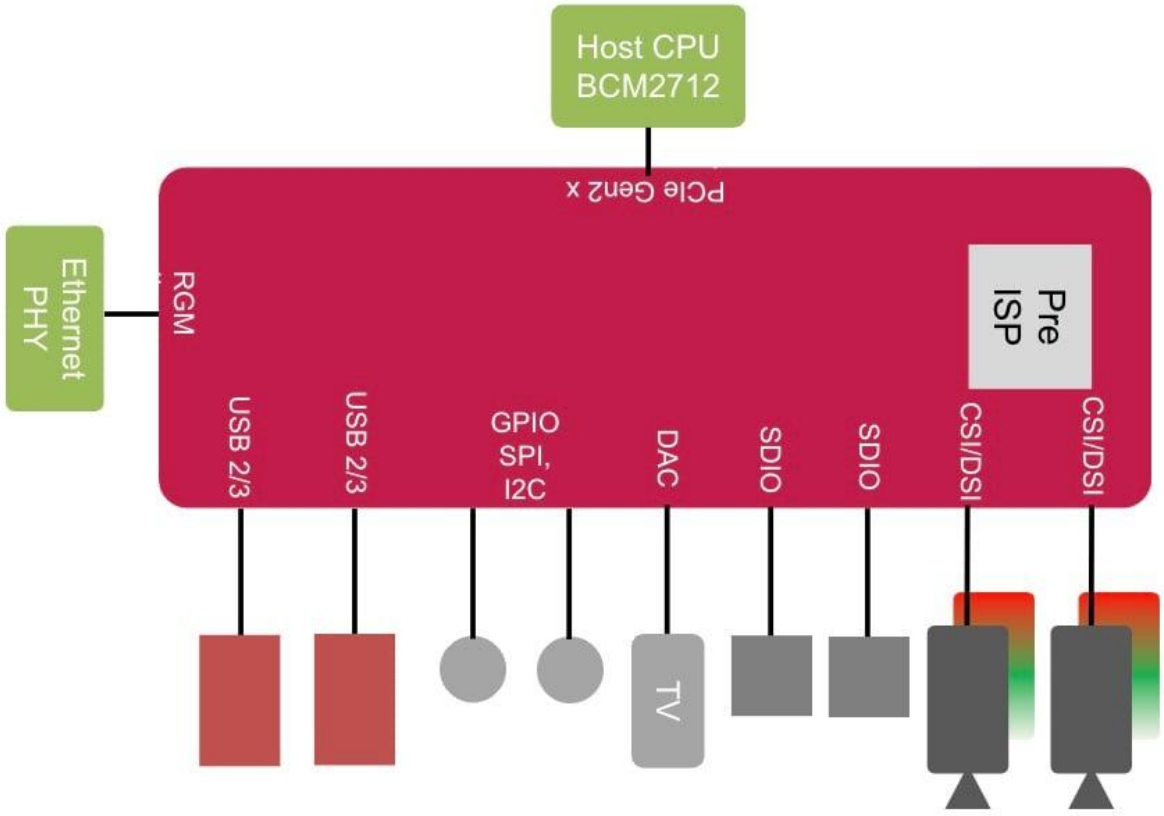

Figure 3 The RP1 General Purpose I/O Chip

The RPi chip provides:

- 4-lane PCIe 2.0 endpoint
- Gigabit Ethernet MAC
- 2× USB 3 host controllers
    - Each has 1× USB 3 and 1× USB 2 port
    - More than twice the usable USB bandwidth vs. Raspberry Pi 4
- 2× SDIO ports/eMMC (not used on Raspberry Pi 5)
- 2× MIPI transceivers (4-lane, supporting DSI and CSI-2)
- Video DAC (3-channel, supporting PAL/NTSC and VGA)
    - Only one channel (composite) used on Raspberry Pi 5
- Low-speed peripherals (SPI, UART, I2C, PWM, GPIO, I2S)
- Delta-sigma PWM audio out

More information on RP1 can be found in the RP1 Peripherals document.
See https://datasheets.raspberrypi.com/rp1/rp1-peripherals.pdf

Glossary

BGA Ball Grid Array – A popular surface mount for Integrated Circuits (ICs)

CSI Camera Serial Interface

DAC Digital to Analogue Converter (In this case for audio output cards)

DSI Display Serial Interface

GND Ground, 0 Volts

GPIO General Purpose IO (On the Raspberry PI)

I2C Two-wire serial communication protocol

I2S Electrical serial bus for connecting digital audio devices

PWM Pulse-Width Modulation

RP1 Input Output Controller Chip for Raspberry Pi Model 5 peripherals

SPI Serial Peripheral Interface – Interface us between digital components

USB Universal Serial Bus