



System Jitter Test

For the Impatient

- Run a pre-compiled binary: `bin/<Platform>/sjtest`
- Or build from source and run: `cd src; make; ./sjtest`
- The output should be pretty self explanatory.
- Put your right ear on your shoulder to see the histogram.
- See [Output Explanation](#) below for details.
- See [Command Line Options](#) below for fine tuning and features.
- See [Example Output](#) below for example output and analysis.
- Browse code by [functions](#), [variables](#), [defines](#), [enums](#), and [typedefs](#).

Warning

This is a beta release. The code and doc will improve with time, but should be useful even now thanks to alpha testers. Please send all comments to BVan@Informatica.Com.

Introduction

Ultra Messaging customers use our software to build complicated systems that often process millions of messages per second. Common goals are low latency and high throughput, but many customers also value freedom from latency jitter. A system with no latency jitter would show exactly the same latency for every message passing through it. Consistency is the hallmark of low-jitter systems.

It's hard to be consistent in doing repetitive work when you're being interrupted all the time. For humans, consistency in performing a repeated task requires freedom from interruptions.

Roughly the same idea applies to computer systems. SJ Test measures the ability of a system to provide a CPU core that is able to consistently execute a repetitive task. The emphasis is *not* on the average time taken to do a task but rather on the *variance* in time between repetitions of the task.

We will define system jitter more thoroughly [below](#), but for now we can think of it as the jitter measured by an application that introduces no jitter of its own. System jitter will be present in any application run by the system. It represents the lower bound for jitter that might be expected of any application running on the system.

SJ Test measures system jitter and provides a simple but effective visualization of it for analysis.

Running a system jitter benchmark under different conditions can provide insight into the causes of system jitter. Here are some test ideas:

- Compare results with other CPU cores idle and with them working
- Compare the same OS running on different server hardware
- Compare different OSes running on the same server hardware
- Compare an OS running native to an OS running on a Hypervisor
- Compare BIOS settings for their jitter impact
- Compare single-user mode to multi-user mode
- Compare short test runs to long test runs
- Compare a sleeping thread to a hot thread burning CPU time
- Compare various CPU cores to each other
- Compare hyperthreaded shared cores to unshared cores
- Compare benefits of cset, taskset, etc.

Design

The design of SJ Test was motivated by goals, but bounded by constraints.

Design Goals

Two key design goals drove the development of SJ Test:

- Make measurements to quantify system jitter. These measurements can be used as benchmarks for performance comparisons between systems or to guide tuning efforts.
- Provide a visualization of collected data that aids in analysis and characterization of system jitter. The visualization can help drive jitter tuning efforts.

Design Constraints

The above goals had to be met within several design constraints.

- *Test Speed* Often in our experience, reducing jitter is a process of test, hunch, tune, and retest. It is sometimes possible to quickly find and remove a source of jitter, but more often, repeated tuning and testing are required. Hence SJ Test was designed to produce quick results so that the effect of tuning changes could be tested quickly.
- *Simplicity* Benchmarking and tuning opportunities are often fleeting, so it's important to get accurate results and actionable information simply. SJ Test combines data collection, analysis, and visualization in a single tool that is easy to operate.
- *Portability* It is useful to be able to compare results across a variety of operating systems. SJ Test is a small code base that uses few system libraries for good portability. It

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requires an x86 processor for access to the RDTSC instruction. It comes with pre-compiled binaries for Linux, Solaris, Mac OS X, and FreeBSD.

- *Information Density* Even a 1-second test run produces tens of millions of data points. Visualization of these data points can be key to forming strategies for jitter reduction. The range of data values can easily span 6 orders of magnitude, so they can be difficult to represent on even a high-resolution display. The constraints of simplicity and portability are best met with a character interface rather than a graphical one. So SJ Test aims to analyze and visualize all the data using easily portable character graphics.

Time Measurement Methodology

The CPU's [Time Stamp Counter](#) (TSC) is useful for measuring how long tasks take, especially when very short times are involved. It's usually counting at a rate of 3 or 4 billion counts per second. That gives it a resolution of 333 to 250 picoseconds.

Elapsed ticks can be measured by reading the TSC before and after doing a task, then subtracting the timestamps. This gives the number of ticks taken by the task, plus the time taken to read the TSC once.

```
uint64_t start, stop, elapsed_ticks;

rdtsc(start);
// Do some task
rdtsc(stop);
elapsed_ticks = stop - start;
```

When elapsed ticks for an interval are known, the elapsed time in seconds can be computed by dividing elapsed ticks by the CPU frequency in Hertz.

When elapsed time for an interval is known, CPU frequency in Hertz can be computed by dividing the elapsed ticks by the elapsed time.

If a task is repeated many times while measuring elapsed ticks, there will undoubtedly be some variation (jitter) in the number of ticks taken to do the task, even though the work should be the same each time for tasks with no conditional logic.

Jitter Measurement Strategy

Jitter is most apparent when we measure the elapsed time taken to do quick tasks. The limiting case is to measure the time needed to just read the TSC. Measuring the delta between two adjacent readings of the TSC does this. It is equivalent to measuring the elapsed time taken by a null task, plus the time to read the TSC.

We want to avoid conditional logic since it may cause jitter by varying CPU cache hit rates. We want to quickly take as many timestamp pairs as possible to maximize jitter detection opportunities. Both these goals are met by using manual [loop unwinding](#) to collect the timestamps. Analysis work on the collected timestamps is never done while collecting, but only after completion of the unwound loop.

```
uint64_t deltas[10], *dp;

do {
    dp = deltas;

    register uint64_t t0, t1, t2, t3, t4, t5, t6, t7, t8, t9, t10;

    // Take a block of 11 timestamps and compute their differences into
    // a 10-element array.
    //
    // Do an "unwound loop" so there's no branching or other work

    rdtsc(t0);
    rdtsc(t1);
    rdtsc(t2);
    . . .
    rdtsc(t9);
    rdtsc(t10);

    *dp++ = t1 - t0;
    *dp++ = t2 - t1;
    . . .
    *dp++ = t10 - t9;

    // Now that we're out of the timing loop, we can take all the
    // CPU time that we need for analysis.

    for (dp=deltas; dp<deltas+ARRAY_SIZE(deltas); dp++) {
        // Analysis as needed
    }
} while (collecting);
```

Jitter Sources and Categorization

It's true that each repeated test would run at the minimum elapsed time if there were no jitter. Any test repetition that takes longer than the minimum was delayed by waiting for some system resource. It had to wait because there was contention for a resource that was already in use elsewhere and could not be shared. Examples of shared resources might be data paths on the CPU chip, hyperthreaded execution units, shared caches, memory busses, CPU cores, kernel data structures and critical sections. So it's correct but simplistic to say that all jitter comes from contention.

We can make better progress at reducing jitter if we identify discrete sources of jitter and categorize them for discussion and measurement.

The CPU scheduler in the OS can be a source of jitter if a thread is moved between CPU cores since cache misses in the new core will initially slow execution compared to the old core. Virtual machine hypervisors may prevent a thread from holding the attention of a CPU core indefinitely. Even things at the CPU hardware level like shared cache contention and hyperthreading can add jitter.

Jitter in elapsed time measurements for doing identical tasks is also a measure of things distracting a CPU core from running a thread. Some runs of a task may take longer than others because a CPU core is not able to finish the task without first doing additional work. Hardware interrupts are one possible source of such additional work, but it's best to think of interruptions more broadly. Anything that keeps a CPU core from executing at full speed is a distraction that hurts performance and adds jitter.

Since jitter sources exist at many layers of a system, we can envision a stack of jitter sources by layer as shown below:

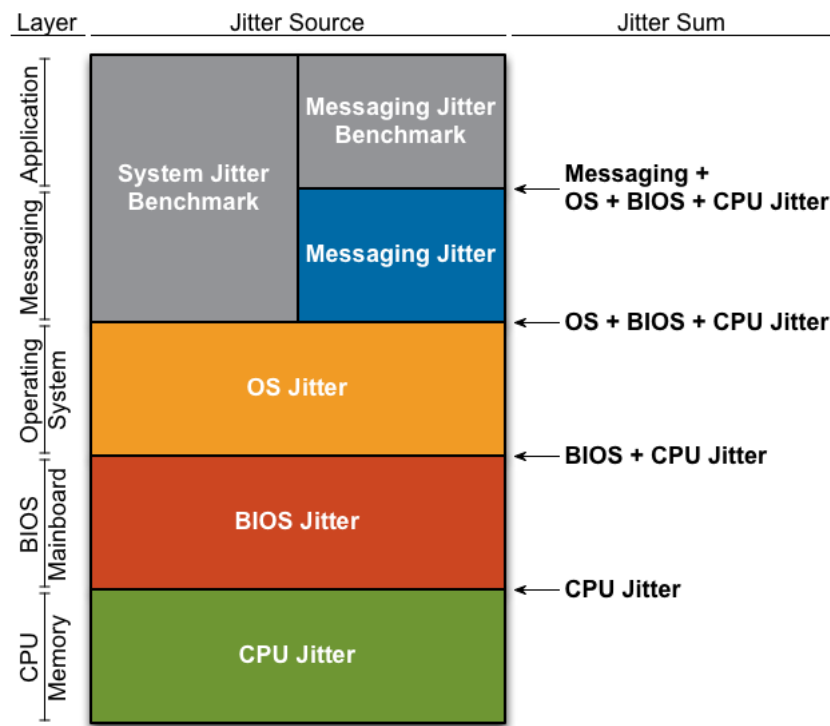


Figure 1: Jitter by layers and sources, showing sums.

Note that jitter measurements from lower layers propagate to higher layers.

Defining System Jitter

This code aims to measure system jitter so that a system can be tuned to minimize it. Reducing jitter in elapsed time measurements made with the TSC minimizes jitter throughout the system. Reading the TSC value is a very low-level operation. It is independent of higher-level languages and libraries like Ultra Messaging.

We define system jitter as the jitter measured at the lowest-possible level at which messaging or application software can be written. Applications are the likely source of any jitter measured in excess of the system jitter.

SJ Test uses no network I/O, no messaging library, no memory-managed language, or abstraction layers. It's measuring jitter as close to the machine hardware as we know how to get with C and in-line assembler. Said differently, jitter measured by SJ Test is coming from server hardware, BIOS, CPU, VM, and OS sources.

Contrast with Application Jitter

Applications doing repetitive tasks may introduce their own jitter by slightly varying the task. Conditional execution in the form of branches and loops is an obvious source of jitter because of cache misses and other effects. Even when code paths appear to be free from branches and loops, jitter can be caused by library calls like `malloc()` and `free()` that necessarily contain their own conditional code paths. We categorize all such jitter as application jitter.

Adding networking, messaging libraries, memory-managed language wrappers, and/or abstraction layers will only magnify the effects of system jitter. One microsecond of jitter on each step of a 1000-step task can turn into one millisecond of jitter for the whole task.

Note that we use the term "jitter" here in the general sense meaning variation from an expected norm. The system jitter discussed here is just one component of the latency variation observed in application-level tests like repeated message round-trip time tests. The standard deviation of latency measured in message round-trip times is often loosely called "jitter," but we are making a distinction here between that and system jitter. System jitter is that component that can never be removed from an application jitter measurement because it is present in all applications running on the system.

Jitter Visualization

Even a short system jitter test produces many millions of data points, so a concise visualization of the data is required to quickly interpret the results. Specifically, a good visualization of the data would allow quick and meaningful comparisons with other test runs.

A [histogram](#) is the natural choice for visualizing system jitter test data. Histograms are commonly used in applications like displaying the variance in adult height among a population. However, inherent differences in system jitter data and display constraints suggest we make some changes from common histograms. Specifically, we use non-uniform bin spacing, logarithmic value display, and rotated axes. Details are presented in following sections.

Jitter Data Characteristics

Although many natural processes follow a normal distribution, the elapsed times measured in system jitter tests are not expected to follow a normal distribution. One reason is that there is a hard lower bound on the time required to read the TSC so we shouldn't expect a symmetric or uniform distribution around the mean. Indeed in most cases, the mean and at least one mode are quite close to the lower bound with a very long tail of outliers. Another reason is that the different processes that introduce jitter often produce multimodal distributions.

We often see two or more closely-spaced modes near the lower bound and then several more widely-spaced modes that are perhaps orders of magnitude greater. Conventional linear

histogram bin spacing would not visualize this data well. Small numbers of bins would combine nearby modes that have distinct causes. Large numbers of bins leave many bins empty and make it difficult to see patterns.

A high-resolution display might be able to distinctly show both closely- and widely-spaced modes with consistent scaling, but it's hard to write portable code for high-resolution displays.

Observing a Knee in the Data

A graph of the cumulative percentage of all samples always rises from 0 to 100% as we move across the histogram bins. With system jitter data, we often see the cumulative percentage rise quickly from 0 to >90% in just a few bins, but then rise much more slowly after that. Thus a graph of the cumulative percentage often shows a *knee* range where the growth per bin slows.

Histogram Bin Spacing

We make it easier for modes to be seen by using two different bin spacings in the same histogram. The number of bins in the histogram is divided into two halves. The lower half of the bins are linearly spaced while the upper half are exponentially spaced. This provides detail near the lower bound where modes are closely spaced, while preserving the range needed to show modes that occur 5 or more orders of magnitude above the mean. For linguistic convenience, the bins in the lower half of the histogram are said to be "below the knee," while those in the upper half are above.

The hard lower bound mentioned above means that bins near 0 will likely be empty. We define a minimum expected value that improves the resolution below the knee. Any values below the expected minimum are accumulated in the first bin.

Command line options allow setting the number of bins, the knee value, and a minimum value which is the lower bound of the first bin. Here is an example for 20 histogram bins with a minimum value of 10% of the knee value:

Bin	Range
0	min + 0- 10% * (knee-min)
1	min + 10- 20% * (knee-min)
2	min + 20- 30% * (knee-min)
3	min + 30- 40% * (knee-min)
4	min + 40- 50% * (knee-min)
5	min + 50- 60% * (knee-min)
6	min + 60- 70% * (knee-min)
7	min + 70- 80% * (knee-min)
8	min + 80- 90% * (knee-min)
9	min + 90-100% * (knee-min)
-	-----
10	1-2 * knee
11	2-10 * knee
12	10-20 * knee
13	20-100 * knee
14	100-200 * knee
15	200-1000 * knee
16	1000-2000 * knee
17	2000-10000 * knee
18	10000-20000 * knee
19	20000-100000 * knee

Output Explanation

Default values produce output that is 28 lines by no more than 80 characters. This small space contains areas with many statistics and a compact visualization of system jitter.

The following figure gives a quick overview of the 5 output areas while following sections give detail on each.

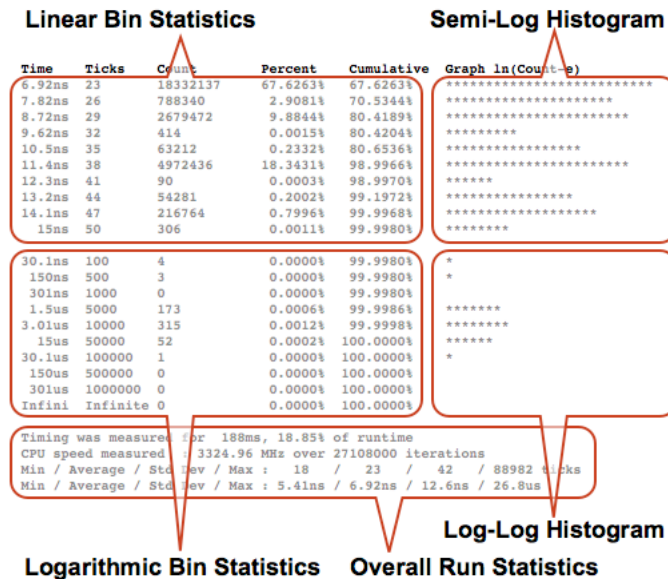


Figure 2: Output Explanation.

Histogram Display

The histogram is displayed rotated 90 degrees clockwise from a conventional display to keep the code portable across operating systems and avoid the requirement for a high-resolution graphical display. The histogram bins are separated by elapsed time and are displayed vertically one bin per line instead of the more conventional horizontal display. The count of the samples in each bin are displayed horizontally instead of the more conventional vertical display.

Note that the number of counts per bin is displayed on a logarithmic scale so that it will fit on low-resolution screens. The magnitude (width) of all bins is scaled so that the bin with the largest count uses the full line width (default 80).

The first half of the bins below the knee setting are linearly spaced in the hope of catching the mode, the average, and the vast majority of the samples. The second half of the bins are spaced roughly by half orders of magnitude so that every pair of bins represents one order of magnitude.

So the top-half (left-half) of the histogram is a **semi-log plot** while the bottom-half (right-half) is a **log-log plot**.

Statistics

Each line of output contains statistics for the associated histogram bin and a visualization of the data. Column values are given in the table below.

Column	Contents
Time	The upper bound of this bin in terms of elapsed time between adjacent reads of the TSC.
Ticks	The same as above, but in ticks of the TSC.
Count	A count of the number of samples in this bin.
Percent	The percentage of all samples in this bin.
Cumulative	The cumulative percentage of all samples in this bin and lower.
Graph	A graph of the Count column.

If you want to see more detail in the histogram and have a window with many rows, try increasing the number of bins. Or try increasing the output line width if you have a window with more than 80 columns.

After per-bin statistics and histogram lines, there is a section of statistics for the overall test run. While the histogram is useful for characterizing a system's jitter and tuning, the overall statistics may be more useful for making benchmark comparisons between systems. In particular, the maximum and standard deviation in units of time are probably the two most important numbers for most Ultra Messaging customers.

Recommended Test Parameters

Design goals and constraints drove the decision to combine data collection and visualization into a single step. This creates a bit of a chicken-and-egg problem because minimum and knee values must be set before data collection yet the optimal values cannot be known until after data collection and often visualization. The default minimum and knee values may be good enough for a quick analysis, but tuning these values away from the defaults often provides sharper insight.

There are heuristics built into SJ Test that check the minimum and knee values for reasonability after data collection. You'll see this recommendation if the minimum data sample is less than 80% of the configured expected minimum.

Recommend min setting of x ticks

Where x is 80% of the minimum data sample seen.

Similarly you'll see this recommendation if the cumulative sample count at the middle histogram bin is less than 90% the total samples.

Recommend increasing knee setting from x ticks

Where x is the configured knee value.

Finally you'll see this recommendation if the cumulative sample count at the middle histogram bin is greater than 99% of the total samples.

Recommend decreasing knee setting from x ticks

Where x is the configured knee value.

Logging and Plotting Outliers

An outlier is defined as any TSC delta greater than the knee. The `-f` option names a file where outliers will be written. The format is x, y where x is the time of the outlier in ms relative to the start of the test and y is the size of the outlier in us. Note the different units between axes.

The expectation is that you'll give this data to the graphing software of your choice and request an x, y scatter plot. Visual analysis of the plot may help you spot any periodic patterns in the jitter. The period may give you clues to the source of the jitter.

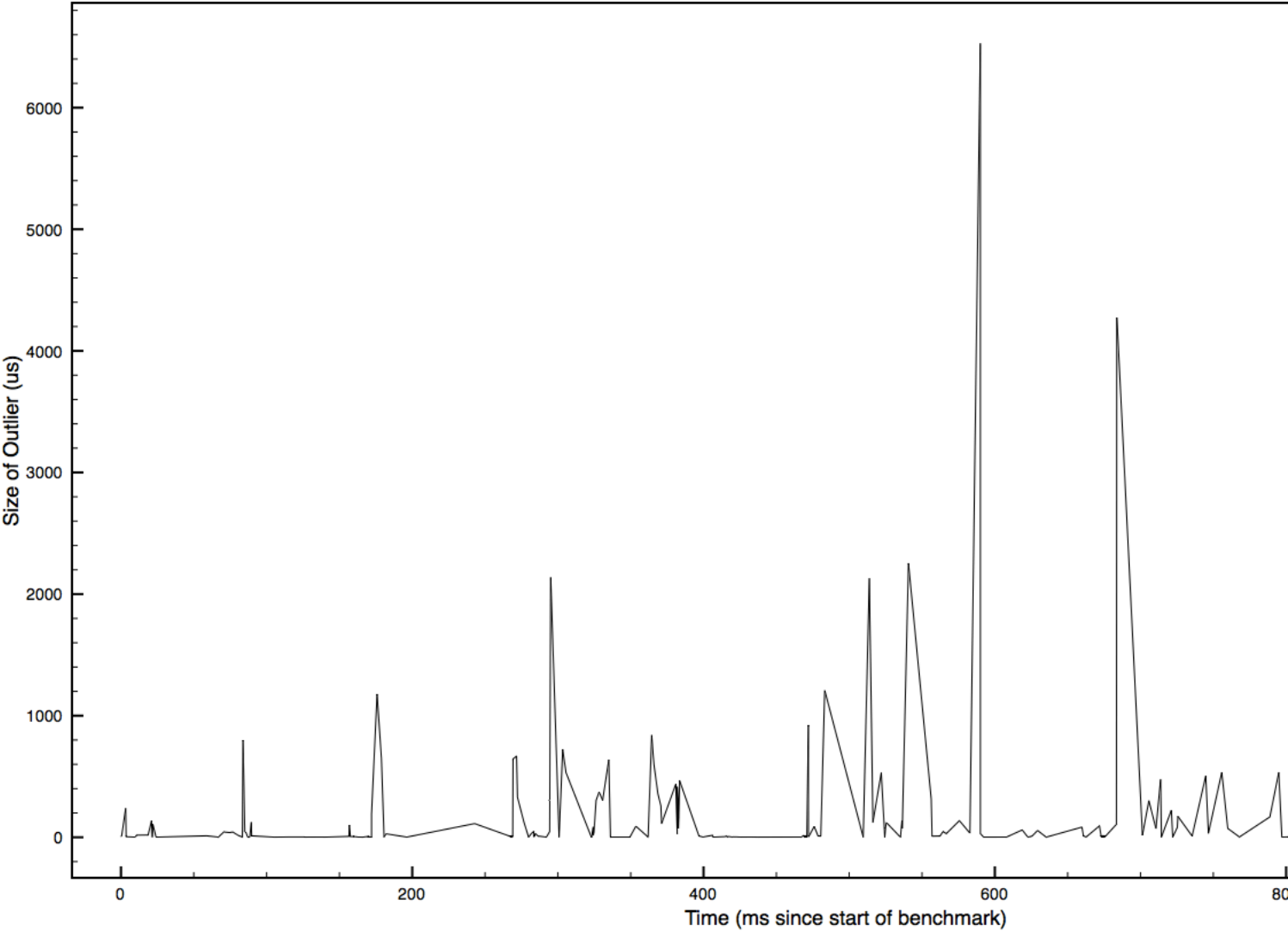


Figure 3: Outliers with no apparent time correlation.

Better yet, do an FFT on the data to move it from the time domain to the frequency domain.

Note that x may not be near zero if the outlier buffer wraps around. If you're worried about the outlier buffer wrapping around, my advice is to increase the knee to classify fewer deltas as outliers rather than making the buffer bigger. The default size is probably big enough for you to spot any periodic patterns.

Command Line Options

<code>-b bins</code>	Set the number of Bins in the histogram (20)
<code>-f outfile</code>	Name of file for outlier data to be written (no file written)
<code>-h</code>	Print Help
<code>-k knee</code>	Set the histogram Knee value in TSC ticks (50)

-m min	Set the Minimum expected value in TSC ticks (10)
-o outbuf	Size of outlier buffer in outliers (10000)
-p pause	Pause msec just before starting jitter test loop (0)
-r runtime	Run jitter testing loops until seconds pass (1)
-w width	Output line Width in characters (80)

Example Output

Following sections show data collected on various systems under various conditions with comments.

Low-Jitter Server

This output came from a server in our lab that had been tuned for low jitter.

Time	Ticks	Count	Percent	Cumulative	Graph ln(Count-e)
10.7ns	32	0	0.0000%	0.0000%	
11.4ns	34	0	0.0000%	0.0000%	
12ns	36	6997631	42.0733%	42.0733%	*****
12.7ns	38	0	0.0000%	42.0733%	
13.4ns	40	0	0.0000%	42.0733%	
14ns	42	0	0.0000%	42.0733%	
14.7ns	44	0	0.0000%	42.0733%	
15.4ns	46	9634329	57.9265%	99.9998%	*****
16ns	48	0	0.0000%	99.9998%	
16.7ns	50	0	0.0000%	99.9998%	
33.4ns	100	0	0.0000%	99.9998%	
167ns	500	0	0.0000%	99.9998%	
334ns	1000	2	0.0000%	99.9998%	*
1.67us	5000	36	0.0002%	100.0000%	*****
3.34us	10000	2	0.0000%	100.0000%	*
16.7us	50000	0	0.0000%	100.0000%	
33.4us	100000	0	0.0000%	100.0000%	
167us	500000	0	0.0000%	100.0000%	
334us	1000000	0	0.0000%	100.0000%	
Infini	Infinite	0	0.0000%	100.0000%	
Timing was measured for 229ms, 22.91% of runtime					
CPU speed measured : 2992.58 MHz over 16632000 iterations					
Min / Average / Std Dev / Max : 36 / 41 / 6 / 6984 ticks					
Min / Average / Std Dev / Max : 12ns / 13.7ns / 1.67ns / 2.33us					

42% of the samples were in the 12 ns bin and almost 58% were in the 15.4 ns bin. Together, 99.9998% of all samples were in these two bins. There were zero samples in the 4 bins between these two, producing a nice bi-modal histogram. The outlier samples were just 36 out of 16.6 million.

Busy Server

This output came from a busy server in our lab.

Time	Ticks	Count	Percent	Cumulative	Graph ln(Count-e)
6.92ns	23	18332137	67.6263%	67.6263%	*****
7.82ns	26	788340	2.9081%	70.5344%	*****
8.72ns	29	2679472	9.8844%	80.4189%	*****
9.62ns	32	414	0.0015%	80.4204%	*****
10.5ns	35	63212	0.2332%	80.6536%	*****
11.4ns	38	4972436	18.3431%	98.9966%	*****
12.3ns	41	90	0.0003%	98.9970%	*****
13.2ns	44	54281	0.2002%	99.1972%	*****
14.1ns	47	216764	0.7996%	99.9968%	*****
15ns	50	306	0.0011%	99.9980%	*****
30.1ns	100	4	0.0000%	99.9980%	*
150ns	500	3	0.0000%	99.9980%	*
301ns	1000	0	0.0000%	99.9980%	
1.5us	5000	173	0.0006%	99.9986%	*****
3.01us	10000	315	0.0012%	99.9998%	*****
15us	50000	52	0.0002%	100.0000%	*****
30.1us	100000	1	0.0000%	100.0000%	*
150us	500000	0	0.0000%	100.0000%	
301us	1000000	0	0.0000%	100.0000%	
Infini	Infinite	0	0.0000%	100.0000%	
Timing was measured for 188ms, 18.85% of runtime					
CPU speed measured : 3324.96 MHz over 27108000 iterations					
Min / Average / Std Dev / Max : 18 / 23 / 42 / 88982 ticks					
Min / Average / Std Dev / Max : 5.41ns / 6.92ns / 12.6ns / 26.8us					

It shows a much faster average time than the [low-jitter server](#) above, but the standard deviation is over 7 times larger while the maximum is over 11 times larger.

Availability

Informatica makes the binary and source code for SJ Test freely available so that our customers can use it to work with their hardware and software vendors to reduce jitter. We pioneered this idea with our [mtools](#) software for testing multicast UDP performance. Many customers have used mtools to work with their NIC, driver, OS, and server vendors to improve UDP multicast performance. We hope that this code can be used between our customers and their other vendors to reduce system jitter.

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Acknowledgement

Inspired by David Riddoch of Solarflare

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