RDMA Deadlock Analysis

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Analysis 1

See Figure 1 for the network topology and flow setup.

Assume a fluid model. Assume XON and XOFF threshold values are the same θ . Assume unit link capacity. Assume FIFO scheduling.

We can get the following equations for flow f.

$$\frac{S_f^1(t)}{dt} = \begin{cases} 1, & \text{if } S_f^1(t) - S_f^2(t) < \theta. \\ 0, & \text{if } S_f^1(t) - S_f^2(t) \ge \theta. \end{cases}$$
(1)

$$\frac{S_f^2(t)}{dt} = \begin{cases}
\frac{S_f^1(t) - S_f^2(t)}{S_f^1(t) - S_f^2(t) + S_g^3(t) - S_g^4(t)}, & \text{if } S_f^2(t) - S_f^3(t) < \theta. \\
0, & \text{if } S_f^2(t) - S_f^3(t) \ge \theta.
\end{cases}$$
(2)

$$\frac{S_f^3(t)}{dt} = \begin{cases} 1, & \text{if } S_f^3(t) - S_f^4(t) < \theta \text{ and } S_f^2(t) - S_f^3(t) > 0. \\ 0, & \text{otherwise.} \end{cases}$$
(3)

Similarly, we can get $\frac{S_g^1(t)}{dt}$, $\frac{S_g^2(t)}{dt}$, $\frac{S_g^3(t)}{dt}$. Additionally, we can have the following two equations.

$$\frac{S_f^2(t)}{dt} + \frac{S_g^4(t)}{dt} = \begin{cases} 1, & \text{if } S_f^2(t) - S_f^3(t) < \theta \text{ and } S_g^3(t) - S_g^4(t) > 0 \text{ and } S_f^1(t) - S_f^2(t) > 0. \\ \frac{S_f^2(t)}{dt}, & \text{if } S_f^2(t) - S_f^3(t) < \theta \text{ and } S_g^3(t) - S_g^4(t) = 0 \text{ and } S_f^1(t) - S_f^2(t) > 0. \\ \frac{S_g^4(t)}{dt}, & \text{if } S_f^2(t) - S_f^3(t) < \theta \text{ and } S_g^3(t) - S_g^4(t) > 0 \text{ and } S_f^1(t) - S_f^2(t) = 0. \\ 0, & \text{otherwise.} \end{cases}$$

$$\frac{S_g^2(t)}{dt} + \frac{S_f^4(t)}{dt} = \begin{cases} 1, & \text{if } S_g^2(t) - S_g^3(t) < \theta \text{ and } S_f^3(t) - S_f^4(t) > 0 \text{ and } S_g^1(t) - S_g^2(t) > 0. \\ \frac{S_g^2(t)}{dt}, & \text{if } S_g^2(t) - S_g^3(t) < \theta \text{ and } S_f^3(t) - S_f^4(t) = 0 \text{ and } S_g^1(t) - S_g^2(t) > 0. \\ \frac{S_f^4(t)}{dt}, & \text{if } S_g^2(t) - S_g^3(t) < \theta \text{ and } S_f^3(t) - S_f^4(t) > 0 \text{ and } S_g^1(t) - S_g^2(t) = 0. \\ 0, & \text{otherwise.} \end{cases}$$

(5)

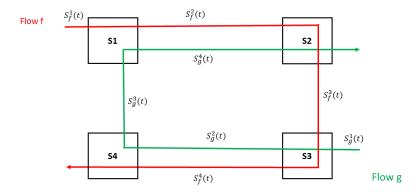


Figure 1: The scenario of four switches and two flows.

The initial conditions are $S_f^i(t) = 0$ for $i \in [0,3]$ and $S_g^j(t)$ for $j \in [0,3]$.

With the initial conditions, and 8 variables and 8 equations, in theory we

should be able to calculate all the service curves. Deadlock can occur if $\exists t_0 < \infty, \frac{S_f^i(t)}{dt} = 0$ and $\frac{S_g^j(t)}{dt} = 0$ for $t > t_0$. Deadlock cannot occur if no such t_0 exists.

A simple case for matlab study $\mathbf{2}$

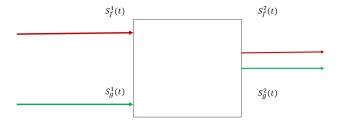
$$\frac{S_f^1(t)}{dt} = \begin{cases} 1, & \text{if } S_f^1(t) - S_f^2(t) < \theta. \\ 0, & \text{if } S_f^1(t) - S_f^2(t) \ge \theta. \end{cases}$$
(6)

$$\frac{d(S_g^1(t))}{dt} = \begin{cases} 1, & \text{if } S_g^1(t) - S_g^2(t) < \theta. \\ 0, & \text{if } S_g^1(t) - S_g^2(t) \ge \theta. \end{cases}$$
 (7)

$$\frac{d(S_f^2(t))}{dt} + \frac{d(S_g^2(t))}{dt} = 1$$
 (8)

$$\frac{d(S_f^2(t))}{dt} = \frac{S_f^1(t) - S_f^2(t)}{S_f^1(t) - S_f^2(t) + S_g^1(t) - S_g^2(t)}$$
(9)

Initial condition: $S_f^i(t) = 0$ and $S_g^i(t) = 0$.



Two input ports, one output port

Figure 2: A simple case for matlab study.