Kelvin Le

Brisbane/QLD | Email: kelvin.minhle1002@gmail.com | Phone: 0423 686 585 | Website: yourwebsite.com

LinkedIn: Kelvin Le | GitHub: bocho0600

Summary

Kelvin is an **undergraduate Mechatronics Engineer**, pursuing the bachelor degree at **Queensland University of Technology**. He has a strong passion on addressing real-world challenges with an engineering mindset, particularly through the application of robotics.

Technical Skills

- Robotics & Control System: ROS2 (Docker, ros2 control framework, ...), MATLAB & Simulink (Control).
- Embedded Systems: STM32, ESP32, IOT systems, AVR Series, Raspberry Pi, Linux-based Embedded System.
- Hardware Design: CAD Design (SolidWorks, Inventor), Circuit & PCB Design (Altium Designer, LTSpice)
- Machine Learning & Computer Vision: Computer Vision with OpenCV, LLM and Machine Learning on AWS & Google Colab.
- **Programming Languages: Python** (ROS2, Machine Learning, Embedded), **C/C++** (Embedded systems, ROS2 integration, System Programming), **C/C++** (OOP), **HTML/CSS/JavaScript** (Web Development).

Education

Queensland University of Technology, BS in Mechatronics/Aerospace

Jan 2023 - Dec 2026

- GPA: 6.7/7.0 (Academic Transcipt)
- Coursework: Computer Architecture, Comparison of Learning Algorithms, Computational Theory
- Achivements & Certifications: QUT Dean's Scholar, Executive Deans' Commendation for Academic Excellence (2023-Now), Virtual Peer Learning Leader (2023-Now)

Qualifications & Certifications

Generative AI with Large Language Models

issued by DeepLearning.AI

• Coursework & Skills: Computer Architecture, Comparison of Learning Algorithms, Computational Theory

Introduction to Machine Learning on AWS

issued by AWS

• Coursework & Skills: Artificial Intelligence, Machine Learning, AWS SageMaker, Large Language Models

Experience

Robotics Engineer Intern, QUT Motorsport Design Internship – Brisbane, QLD

Nov 2024 - Feb 2025

- Improved vehicle (QEV-3D) performance by **20**% by replacing the custom ROS2 controller component with built-in controllers from the ros2_control framework.
- Migrated and optimized the existing ROS2 Humble base to the lattest base.
- Ensured 70% effective of LiDAR point cloud by tuning the ground segmenter & refined LiDAR cone detection.
- Implemented CANBUS package for the vehicle to communicate with the Hardware, ECUs.

CAD/PCB Designer, AAA Salon Supply – Brisbane, QLD

Jan 2023 - Nov 2023

- Designed and finalized CAD models for salon equipment, including UV lamps and tools, ensuring functionality.
- Validated prototypes and final products, providing design enhancements for improved performance.
- Developed and manufactured PCBs for prototypes using 3D printing and advanced PCB design techniques.

Robotics/STEM Instructor, Junior Engineers – Brisbane, QLD

Nov 2023 - Now

- Cooperating with the team to develop a curriculum for the program in (AI, Robotics, web programmming).
- Leading classes with < 20 students in varying age groups (7-14) to teach about robotics and programming
- Designed and manufactured PCBs and 3D-printable, assemblable robot parts for teaching materials.

STEM Lead Instructor, CodeCamp - Brisbane, QLD

Nov 2023 - Now

- Working closely with the team to deliver a drones programming 3-day camp with < 20 students.
- Managing after-school classess of Scratch programming for kids aged 7-14.

Projects

Multi-User Drawing Tool

github.com/name/repo

- Developed an electronic classroom where multiple users can simultaneously view and draw on a "chalkboard" with each person's edits synchronized
- Tools Used: C++, MFC

Synchronized Desktop Calendar

github.com/name/repo

- Developed a desktop calendar with globally shared and synchronized calendars, allowing users to schedule meetings with other users
- Tools Used: C#, .NET, SQL, XML

Custom Operating System

2002

- Built a UNIX-style OS with a scheduler, file system, text editor, and calculator
- Tools Used: C

Technologies

Languages: C++, C, Java, Objective-C, C#, SQL, JavaScript

Technologies: .NET, Microsoft SQL Server, XCode, Interface Builder