

Deep Learning Library - Philipp Bock

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Chapter 1

Hierarchical Index

1.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

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Chapter 2

Class Index

2.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

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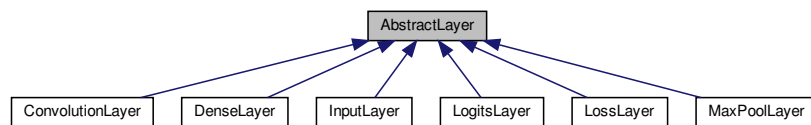
Chapter 3

Class Documentation

3.1 AbstractLayer Class Reference

```
#include <AbstractLayer.hpp>
```

Inheritance diagram for AbstractLayer:



Public Member Functions

- [AbstractLayer](#) (std::shared_ptr< [AbstractLayer](#) > input, std::shared_ptr< [Graph](#) > computeGraph)
- [AbstractLayer](#) (std::shared_ptr< [Graph](#) > computeGraph)
- const std::shared_ptr< [Node](#) > & [getInputNode](#) () const
the computational graph
- const std::shared_ptr< [Node](#) > & [getOutputNode](#) () const
- void [setOutputNode](#) (const std::shared_ptr< [Node](#) > &outputNode)
- int [getOutputChannels](#) () const
- void [setOutputChannels](#) (int outputChannels)
- int [getInputChannels](#) () const
- int [getOutputSize](#) () const
- void [setOutputSize](#) (int outputSize)
- int [getBatchSize](#) () const
- void [setBatchSize](#) (int batchSize)
- int [getInputSize](#) ()
- const std::shared_ptr< [Graph](#) > & [getComputeGraph](#) () const

3.1.1 Detailed Description

Layer Base class, defines what each Layer needs to implement. The main concept is, that each layer has an output node. this way we can connect all nodes of the computational graph by taking the outputNode of the previous Layer as an input node

3.1.2 Constructor & Destructor Documentation

3.1.2.1 AbstractLayer() [1/2]

```
AbstractLayer::AbstractLayer (
    std::shared_ptr< AbstractLayer > input,
    std::shared_ptr< Graph > computeGraph )
```

Creates a new Layer storing the input Layer and the computeGraph using the inputLayer, the input [Node](#), Channels and Batch Size are evaluated

Parameters

<i>input</i>	
<i>computeGraph</i>	

3.1.2.2 AbstractLayer() [2/2]

```
AbstractLayer::AbstractLayer (
    std::shared_ptr< Graph > computeGraph ) [explicit]
```

Creates a new Layer only storing the computeGraph

Parameters

<i>computeGraph</i>	
---------------------	--

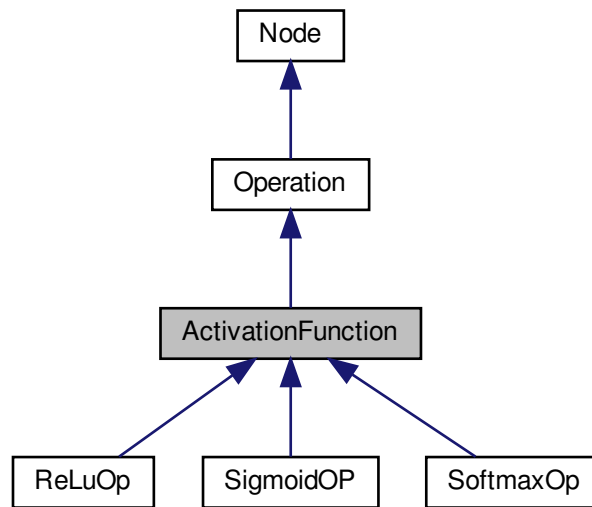
The documentation for this class was generated from the following files:

- /home/pbo/CLionProjects/libdl/library/NeuralNetwork/LayerFactory/include/AbstractLayer.hpp
- /home/pbo/CLionProjects/libdl/library/NeuralNetwork/LayerFactory/src/AbstractLayer.cpp

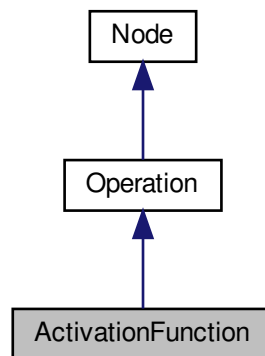
3.2 ActivationFunction Class Reference

```
#include <ActivationFunction.hpp>
```


Inheritance diagram for ActivationFunction:



Collaboration diagram for ActivationFunction:



Public Member Functions

- [ActivationFunction](#) (std::shared_ptr< [Node](#) > X)

3.2.1 Detailed Description

An [ActivationFunction](#) operation object introduces non linearity into the computational graph

3.2.2 Constructor & Destructor Documentation

3.2.2.1 ActivationFunction()

```
ActivationFunction::ActivationFunction (
    std::shared_ptr< Node > X )
```

- creates the operation Object from the input [Node](#)
- the channels are simply forwarded from the input [Node](#)

Parameters

X	input Node
---	----------------------------

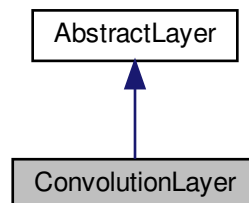
The documentation for this class was generated from the following files:

- /home/pbo/CLionProjects/libdl/library/ComputationalGraph/Operations/include/ActivationFunction.hpp
- /home/pbo/CLionProjects/libdl/library/ComputationalGraph/Operations/src/ActivationFunction.cpp

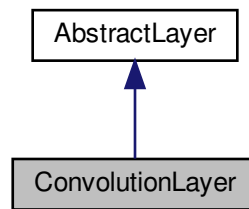
3.3 ConvolutionLayer Class Reference

```
#include <ConvolutionLayer.hpp>
```

Inheritance diagram for ConvolutionLayer:



Collaboration diagram for ConvolutionLayer:



Public Member Functions

- [ConvolutionLayer](#) (std::shared_ptr< [AbstractLayer](#) > input, std::shared_ptr< [Graph](#) > computeGraph, ActivationType activationFunction, int amountFilters, int kernelDim, int stride=1, InitializationType initializationType=InitializationType::Xavier)

3.3.1 Detailed Description

Creates a Convolutional Layer

3.3.2 Constructor & Destructor Documentation

3.3.2.1 ConvolutionLayer()

```

ConvolutionLayer::ConvolutionLayer (
    std::shared_ptr< AbstractLayer > input,
    std::shared_ptr< Graph > computeGraph,
    ActivationType activationFunction,
    int amountFilters,
    int kernelDim,
    int stride = 1,
    InitializationType initializationType = InitializationType::Xavier )
  
```

Creates the layer

Parameters

<i>input</i>	the previous Layer
<i>computeGraph</i>	
<i>activationFunction</i>	check commonDatatypes.h for possibilities
<i>amountFilters</i>	
<i>kernelDim</i>	
<i>stride</i>	
<i>initializationType</i>	check commonDatatypes.h for possibilities

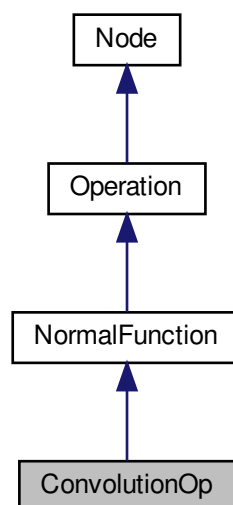
The documentation for this class was generated from the following files:

- /home/pbo/CLionProjects/libdl/library/NeuralNetwork/LayerFactory/include/ConvolutionLayer.hpp
- /home/pbo/CLionProjects/libdl/library/NeuralNetwork/LayerFactory/src/ConvolutionLayer.cpp

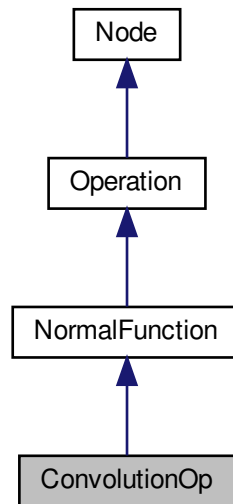
3.4 ConvolutionOp Class Reference

```
#include <ConvolutionOp.hpp>
```

Inheritance diagram for ConvolutionOp:



Collaboration diagram for ConvolutionOp:



Public Member Functions

- [ConvolutionOp](#) (std::shared_ptr< [Node](#) > X, std::shared_ptr< [Parameter](#) > filter, int stride=1)
- void [forwardPass](#) () override
default destructor
- void [backwardPass](#) () override
- const Matrix & [getIm2Col](#) () const
caches the calculated _im2Col matrix
- void [setIm2Col](#) (const Matrix &im2Col)

Static Public Member Functions

- static void [forwardsConvolution](#) (const Matrix &miniBatch, const Matrix &filter, Matrix &im2Col, Matrix &outputMatrix, const int stride, const int channels)
- static void [backwardsConvolution](#) (Matrix &dX, Matrix &dFilter, const Matrix &filter, const Matrix &dout, const Matrix &im2ColM, int batchSize, int inputDimX, int stride, int channels)
- static void [im2col](#) (Matrix &output, const Matrix &input, int kernelSize, int stride, int channel, int batchSize)
- static void [col2im](#) (Matrix &output, const Matrix &input, int kernelSize, int origDim, int stride, int channel, int batchSize)

3.4.1 Detailed Description

Implements a Convolution [Operation](#)

3.4.2 Constructor & Destructor Documentation

3.4.2.1 ConvolutionOp()

```
ConvolutionOp::ConvolutionOp (
    std::shared_ptr< Node > X,
    std::shared_ptr< Parameter > filter,
    int stride = 1 )
```

- creates a Normal Function and sets the outputChannel to the amount of Filters passed
- checks whether X and filter do have the same amount of channels if not a exception is thrown

Parameters

<i>X</i>	input Noode
<i>filter</i>	all kernels that should be applied. Each row of the forward pass represents one kernel
<i>stride</i>	stride

3.4.3 Member Function Documentation

3.4.3.1 backwardPass()

```
void ConvolutionOp::backwardPass ( ) [override], [virtual]
```

- calculates the gradients of the convolution using getPreviousGradients() and the previous calculated im2Col Matrix

Reimplemented from [Operation](#).

3.4.3.2 backwardsConvolution()

```
void ConvolutionOp::backwardsConvolution (
    Matrix & dX,
    Matrix & dFilter,
    const Matrix & filter,
    const Matrix & dout,
    const Matrix & im2ColM,
    int batchSize,
    int inputDimX,
    int stride,
    int channels ) [static]
```

- calculates the gradients w.r.t X and filter
- $dX = \text{filter.transpose()} * \text{dout}$;
- $d\text{Filter} = \text{dout} * \text{im2ColM.transpose()};$

Parameters

<i>dX</i>	reference to Matrix which should store the gradients w.r.t X
<i>dFilter</i>	reference to Matrix which should store the gradients w.r.t filter
<i>filter</i>	the original filter
<i>dout</i>	reference to Matrix which holds the previously calculated forwardpass
<i>im2ColM</i>	reference to Matrix which holds the previously calculated im2Col Matrix
<i>batchSize</i>	batchSize of X
<i>inputDimX</i>	the dimensions of one sample of the input Node X
<i>stride</i>	original stride
<i>channels</i>	the original channels of X and filter

3.4.3.3 col2im()

```
void ConvolutionOp::col2im (
    Matrix & output,
    const Matrix & input,
    int kernelSize,
    int origDim,
    int stride,
    int channel,
    int batchSize ) [static]
```

Implements the col2Im function see also https://leonardoaraujosantos.gitbooks.io/artificial-inteligen_faster.html

Parameters

<i>output</i>	reference to Matrix which should store the calculated col2Im matrix
<i>input</i>	a im2Col matrix
<i>kernelSize</i>	
<i>origDim</i>	the original Dimensions of a sample of the im2Col inputMatrix
<i>stride</i>	
<i>channel</i>	
<i>batchSize</i>	

3.4.3.4 forwardPass()

```
void ConvolutionOp::forwardPass ( ) [override], [virtual]
```

default destructor

- executes a convolution of the input Nodes X and filter

Reimplemented from [Operation](#).

3.4.3.5 forwardsConvolution()

```
void ConvolutionOp::forwardsConvolution (
    const Matrix & miniBatch,
    const Matrix & filter,
    Matrix & im2Col,
    Matrix & outputMatrix,
    const int stride,
    const int channels ) [static]
```

/

- calculates the dimensions of each sample of the minibatch and each kernel of the filter with the amount of channels
- transforms the miniBatch into the im2Col format and stores it in im2Col
- executes a convolution by multiplying the filter with im2Col and stores it in outputMatrix

Parameters

<i>miniBatch</i>	reference to miniBatch matrix where each row corresponds to one sample, channels are stored consecutively , miniBatch.row(i)=sample = [channel 0]...[channel 1]
<i>filter</i>	reference to miniBatch matrix where each row corresponds to one kernel, channels are stored consecutively filter.row(i) = kernel = [channel 0]...[channel 1]
<i>im2Col</i>	reference to Matrix which should store the im2Col output
<i>outputMatrix</i>	reference to Matrix which should store the convolution output of miniBatch with filter
<i>stride</i>	stride
<i>channels</i>	input channels of filter /miniBatch

3.4.3.6 im2col()

```
void ConvolutionOp::im2col (
    Matrix & output,
    const Matrix & input,
    int kernelSize,
    int stride,
    int channel,
    int batchSize ) [static]
```

Implements the im2Col function see also <https://leonardoaraujosantos.gitbooks.io/artificial-inteligence-faster.html>

Parameters

<i>output</i>	reference to Matrix which should store the calculated im2Col matrix
<i>input</i>	the matrix that should be transformed
<i>kernelSize</i>	
<i>stride</i>	
<i>channel</i>	
<i>batchSize</i>	

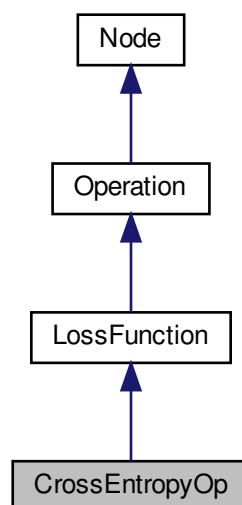
The documentation for this class was generated from the following files:

- /home/pbo/CLionProjects/libdl/library/ComputationalGraph/Operations/include/ConvolutionOp.hpp
- /home/pbo/CLionProjects/libdl/library/ComputationalGraph/Operations/src/ConvolutionOp.cpp

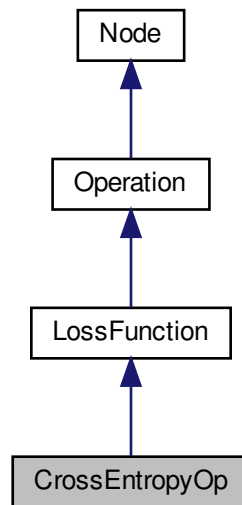
3.5 CrossEntropyOp Class Reference

```
#include <CrossEntropyOp.hpp>
```

Inheritance diagram for CrossEntropyOp:



Collaboration diagram for CrossEntropyOp:



Public Member Functions

- [CrossEntropyOp](#) (std::shared_ptr< [Node](#) > X, std::shared_ptr< [Placeholder](#) > labels)
- void [forwardPass](#) () override
default destructor
- void [backwardPass](#) () override

3.5.1 Detailed Description

Implements the CrossEntropy Loss

3.5.2 Constructor & Destructor Documentation

3.5.2.1 CrossEntropyOp()

```

CrossEntropyOp::CrossEntropyOp (
    std::shared_ptr< Node > X,
    std::shared_ptr< Placeholder > labels )

```

creates an [LossFunction](#) object stores the labels which are need to calculate the loss

Parameters

<i>X</i>	softmax classified samples
<i>labels</i>	groundTruth for initial samples

3.5.3 Member Function Documentation

3.5.3.1 backwardPass()

```
void CrossEntropyOp::backwardPass ( ) [override], [virtual]
```

calculates the softmax-crossEntropy-classifier gradient and passes it further to its input [Node](#) which must be a Softmax operation see also: <https://deepnotes.io/softmax-crossentropy>

Reimplemented from [Operation](#).

3.5.3.2 forwardPass()

```
void CrossEntropyOp::forwardPass ( ) [override], [virtual]
```

default destructor

calculates the cross-entropy loss and set the output as forward pass value

Reimplemented from [Operation](#).

The documentation for this class was generated from the following files:

- /home/pbo/CLionProjects/libdl/library/ComputationalGraph/Operations/include/CrossEntropyOp.hpp
- /home/pbo/CLionProjects/libdl/library/ComputationalGraph/Operations/src/CrossEntropyOp.cpp

3.6 DataInitialization Class Reference

Static Public Member Functions

- static Eigen::MatrixXf **generateRandomMatrix** (int rows, int cols)
- static Eigen::MatrixXf **generateRandomMatrixNormalDistribution** (float mean, float stdev, int rows, int cols)

The documentation for this class was generated from the following files:

- /home/pbo/CLionProjects/libdl/library/Utils/include/DataInitialization.hpp
- /home/pbo/CLionProjects/libdl/library/Utils/src/DataInitialization.cpp

3.7 DataSet Struct Reference

```
#include <commonDatatypes.hpp>
```

Public Member Functions

- **DataSet** (std::vector< Matrix > trainingSamples, std::vector< Matrix > trainingLabels)
- **DataSet** (std::vector< Matrix > trainingSamples, std::vector< Matrix > trainingLabels, std::vector< Matrix > validationSamples, std::vector< Matrix > validationLabels)

Public Attributes

- std::vector< Matrix > **_trainingSamples** {}
- std::vector< Matrix > **_trainingLabels** {}
- std::vector< Matrix > **_validationSamples** {}
- std::vector< Matrix > **_validationLabels** {}

3.7.1 Detailed Description

This struct holds four vectors. The first two holding the data and labels of the training set The second two hold the data and labels of the validation set

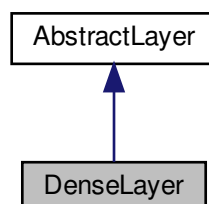
The documentation for this struct was generated from the following file:

- /home/pbo/CLionProjects/libdl/library/Utils/include/commonDatatypes.hpp

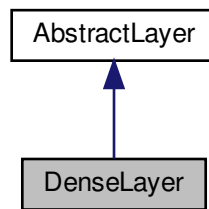
3.8 DenseLayer Class Reference

```
#include <DenseLayer.hpp>
```

Inheritance diagram for DenseLayer:



Collaboration diagram for DenseLayer:



Public Member Functions

- [DenseLayer](#) (std::shared_ptr< [AbstractLayer](#) > input, std::shared_ptr< [Graph](#) > computeGraph, ActivationType activationFunction, int amountNeurons, InitializationType initializationType=InitializationType::Xavier)

3.8.1 Detailed Description

Creates a [DenseLayer](#)

3.8.2 Constructor & Destructor Documentation

3.8.2.1 DenseLayer()

```

DenseLayer::DenseLayer (
    std::shared_ptr< AbstractLayer > input,
    std::shared_ptr< Graph > computeGraph,
    ActivationType activationFunction,
    int amountNeurons,
    InitializationType initializationType = InitializationType::Xavier )
  
```

Create the Layer

Parameters

<i>input</i>	
<i>computeGraph</i>	
<i>activationFunction</i>	check commonDatatypes.h for possibilities
<i>amountNeurons</i>	
<i>initializationType</i>	check commonDatatypes.h for possibilities

The documentation for this class was generated from the following files:

- /home/pbo/CLionProjects/libdl/library/NeuralNetwork/LayerFactory/include/DenseLayer.hpp
- /home/pbo/CLionProjects/libdl/library/NeuralNetwork/LayerFactory/src/DenseLayer.cpp

3.9 Graph Class Reference

```
#include <Graph.hpp>
```

Public Member Functions

- void **addParameter** (std::shared_ptr< [Parameter](#) > parameters)
- void **addOperation** (std::shared_ptr< [Operation](#) > operation)
- void **computeForward** ()
- void **computeBackwards** ()
- void **updateParameters** ([HyperParameters](#) params=[HyperParameters](#)())
- bool **writeParameters** (std::string dir)
- bool **readParameters** (std::string dir)
- const std::shared_ptr< [Placeholder](#) > & **getInput** () const
contains all operations of the graph ordered according to their position in the graph
- void **setInput** (const std::shared_ptr< [Placeholder](#) > &input)
- const std::shared_ptr< [Placeholder](#) > & **getLabels** () const
- void **setLabels** (const std::shared_ptr< [Placeholder](#) > &labels)

3.9.1 Detailed Description

This class controls the Behaviour of our list of Nodes aka Computational [Graph](#).

3.9.2 Member Function Documentation

3.9.2.1 addOperation()

```
void Graph::addOperation (
    std::shared_ptr< Operation > operation )
```

Adds an parameter to the list of parameters ! the input [Node](#) of the passed operation must already be in _operations List or stored as label. Otherwise an exception is thrown!

Parameters

<i>operation</i>	
------------------	--

3.9.2.2 addParameter()

```
void Graph::addParameter (
    std::shared_ptr< Parameter > parameters )
```

Adds an parameter to the list of parameters

Parameters

<i>variable</i>	
-----------------	--

3.9.2.3 computeBackwards()

```
void Graph::computeBackwards ( )
```

First sets the previousGradient for the last [Operation](#) to One. Second it iterates through the reversed list of Operations and executes backwardsPass() on each. !this expects that each following [Operation](#) holds the previous [Operation](#) as input!

3.9.2.4 computeForward()

```
void Graph::computeForward ( )
```

iterates through the list of Operations and executes forwardPass() on each. !this expects that each following [Operation](#) holds the previous [Operation](#) as input!

3.9.2.5 readParameters()

```
bool Graph::readParameters (
    std::string dir )
```

Reads all Parameters from path dir

Parameters

<i>dir</i>	path/to/Parameter/files/Networkname
------------	-------------------------------------

Returns

SUCCESS

3.9.2.6 updateParameters()

```
void Graph::updateParameters (
    HyperParameters params = HyperParameters() )
```

This function may first be called after execution of the Backward Pass It uses the gradients of computation w.r.t [Parameter](#) to update its forward pass value.

Parameters

<i>params</i>	a HyperParameters object, specifying things like learningRate, BatchSize and which Optimizer should be used
---------------	---

3.9.2.7 writeParameters()

```
bool Graph::writeParameters (
    std::string dir )
```

Writes all Parameters to path dir

Parameters

<i>dir</i>	path/to/Parameter/files/Networkname
------------	-------------------------------------

Returns

success

The documentation for this class was generated from the following files:

- /home/pbo/CLionProjects/libdl/library/ComputationalGraph/include/Graph.hpp
- /home/pbo/CLionProjects/libdl/library/ComputationalGraph/src/Graph.cpp

3.10 HyperParameters Struct Reference

```
#include <commonDatatypes.hpp>
```

Public Member Functions

- **HyperParameters** (int epochs=10, int batchSize=8, float learningRate=0.01, Optimizer optimizer=Optimizer↔::Adam, float beta1=0.9, float beta2=0.999)
- std::string **toString** ()

Public Attributes

- float **_learningRate**
- float **_beta1**
- float **_beta2**
- int **_batchSize**
- int **_epochs**
- Optimizer **_optimizer**

3.10.1 Detailed Description

This struct holds all kind of possible Hyper parameters, that may be used to update an [Parameter](#) during training

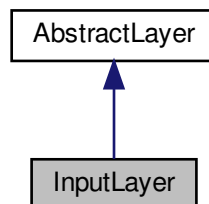
The documentation for this struct was generated from the following file:

- `/home/pbo/CLionProjects/libdl/library/Utils/include/commonDatatypes.hpp`

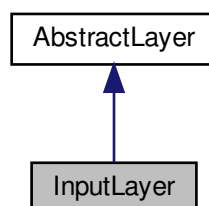
3.11 InputLayer Class Reference

```
#include <InputLayer.hpp>
```

Inheritance diagram for InputLayer:



Collaboration diagram for InputLayer:



Public Member Functions

- [InputLayer](#) (std::shared_ptr< [Graph](#) > computeGraph, int batchSize, int dataPoints, int channel)
- void [updateX](#) (Matrix &newMiniBatch)
- *default destructor*

3.11.1 Detailed Description

Creates an [InputLayer](#) this is the only Layer that does not take an input Layer as it is the starting Point

3.11.2 Constructor & Destructor Documentation

3.11.2.1 InputLayer()

```
InputLayer::InputLayer (
    std::shared_ptr< Graph > computeGraph,
    int batchSize,
    int dataPoints,
    int channel )
```

Parameters

<i>computeGraph</i>	
<i>batchSize</i>	
<i>dataPoints</i>	amount of data one sample has
<i>channel</i>	channels of the input

3.11.3 Member Function Documentation

3.11.3.1 updateX()

```
void InputLayer::updateX (
    Matrix & newMiniBatch )
```

default destructor

During Training or Prediction this method should be used to set a batch for calculation

Parameters

<i>newMiniBatch</i>	the batch to be predicted, to be trained on
---------------------	---

The documentation for this class was generated from the following files:

- /home/pbo/CLionProjects/libdl/library/NeuralNetwork/LayerFactory/include/InputLayer.hpp
- /home/pbo/CLionProjects/libdl/library/NeuralNetwork/LayerFactory/src/InputLayer.cpp

3.12 LegoDataLoader Class Reference

Static Public Member Functions

- static void **getData** (int samples, std::vector< std::pair< std::string, int >> shuffledFiles, [DataSet](#) &data)
- static std::vector< std::pair< std::string, int >> **shuffleData** (const std::string &dataDir)

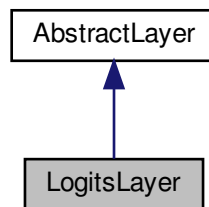
The documentation for this class was generated from the following files:

- /home/pbo/CLionProjects/libdl/library/Utils/include/LegoDataLoader.hpp
- /home/pbo/CLionProjects/libdl/library/Utils/src/LegoDataLoader.cpp

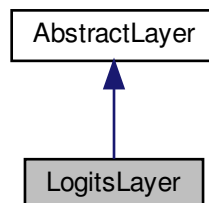
3.13 LogitsLayer Class Reference

```
#include <LogitsLayer.hpp>
```

Inheritance diagram for LogitsLayer:



Collaboration diagram for LogitsLayer:



Public Member Functions

- [LogitsLayer](#) (std::shared_ptr< [AbstractLayer](#) > input, std::shared_ptr< [Graph](#) > computeGraph, int output↔
Classes)

3.13.1 Detailed Description

Creates a Softmax Classification Layer

3.13.2 Constructor & Destructor Documentation

3.13.2.1 LogitsLayer()

```
LogitsLayer::LogitsLayer (
    std::shared_ptr< AbstractLayer > input,
    std::shared_ptr< Graph > computeGraph,
    int outputClasses )
```

Creates a Logits Layer using the softmax classifier

Parameters

<i>input</i>	
<i>computeGraph</i>	
<i>outputClasses</i>	the number of labels

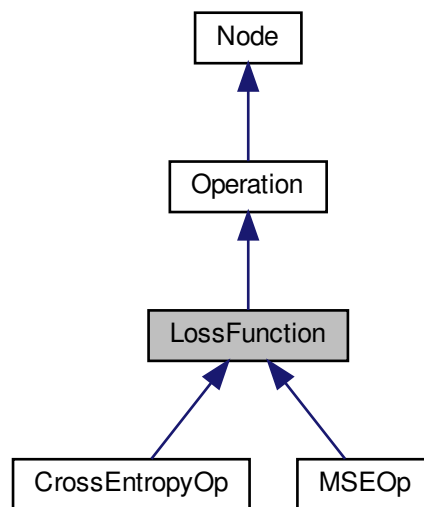
The documentation for this class was generated from the following files:

- /home/pbo/CLionProjects/libdl/library/NeuralNetwork/LayerFactory/include/LogitsLayer.hpp
- /home/pbo/CLionProjects/libdl/library/NeuralNetwork/LayerFactory/src/LogitsLayer.cpp

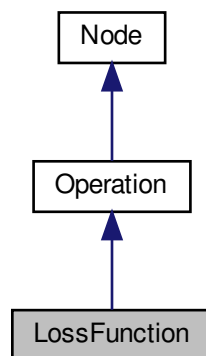
3.14 LossFunction Class Reference

```
#include <LossFunction.hpp>
```

Inheritance diagram for LossFunction:



Collaboration diagram for LossFunction:



Public Member Functions

- `LossFunction` (std::shared_ptr< [Node](#) > X, std::shared_ptr< [Placeholder](#) > labels)
- `const std::shared_ptr< Placeholder > & getLabels () const`
the ground truth to the input samples
- `const Matrix getPrediction () const`
- `const float getLoss () const`
returns the forward pass of the input [Node](#) aka the prediction

3.14.1 Detailed Description

A [LossFunction](#) operation object represents operation to calculate the loss of a sample computation compared to its ground truth

3.14.2 Constructor & Destructor Documentation

3.14.2.1 LossFunction()

```
LossFunction::LossFunction (
    std::shared_ptr< Node > X,
    std::shared_ptr< Placeholder > labels )
```

- creates the operation Object using the the obligatory Input [Node](#).
- stores the labels for this operation
- sets the output Channel of the operation Object to a random Value, as at this point channels do not matter anymore

Parameters

<i>X</i>	the input Node
<i>labels</i>	the ground truth to the input samples

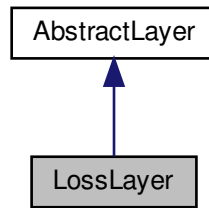
The documentation for this class was generated from the following files:

- /home/pbo/CLionProjects/libdl/library/ComputationalGraph/Operations/include/LossFunction.hpp
- /home/pbo/CLionProjects/libdl/library/ComputationalGraph/Operations/src/LossFunction.cpp

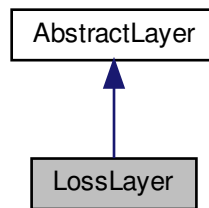
3.15 LossLayer Class Reference

```
#include <LossLayer.hpp>
```

Inheritance diagram for LossLayer:



Collaboration diagram for LossLayer:



Public Member Functions

- [LossLayer](#) (std::shared_ptr< [AbstractLayer](#) > input, std::shared_ptr< [Graph](#) > computeGraph, LossType losstype)
- void [updateLabels](#) (Matrix &newLabels)
- *default destructor*
- const Matrix [getPrediction](#) () const
- float [getLoss](#) ()

3.15.1 Detailed Description

Creates an Layer for the loss calculation

3.15.2 Constructor & Destructor Documentation

3.15.2.1 LossLayer()

```
LossLayer::LossLayer (
    std::shared_ptr< AbstractLayer > input,
    std::shared_ptr< Graph > computeGraph,
    LossType losstype )
```

Creates the selected loss function and sets it as outputNode

Parameters

<i>input</i>	
<i>computeGraph</i>	
<i>losstype</i>	

3.15.3 Member Function Documentation

3.15.3.1 getLoss()

```
float LossLayer::getLoss ( )
```

throws a runtime_error if no training or prediction has yet been done

Returns

the current Loss

3.15.3.2 getPrediction()

```
const Matrix LossLayer::getPrediction ( ) const
```

throws a runtime_error if no computation has yet been done

Returns

the current Prediciton

3.15.3.3 updateLabels()

```
void LossLayer::updateLabels (
    Matrix & newLabels )
```

default destructor

During Training this method should be used to set the labels for the loss calculation

Parameters

<i>the</i>	Labels that should be used for training
------------	---

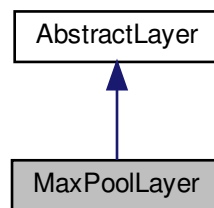
The documentation for this class was generated from the following files:

- /home/pbo/CLionProjects/libdl/library/NeuralNetwork/LayerFactory/include/LossLayer.hpp
- /home/pbo/CLionProjects/libdl/library/NeuralNetwork/LayerFactory/src/LossLayer.cpp

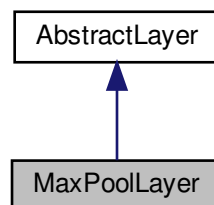
3.16 MaxPoolLayer Class Reference

```
#include <MaxPoolLayer.hpp>
```

Inheritance diagram for MaxPoolLayer:



Collaboration diagram for MaxPoolLayer:



Public Member Functions

- [MaxPoolLayer](#) (const std::shared_ptr< [AbstractLayer](#) > &input, std::shared_ptr< [Graph](#) > computeGraph, int kernelDim, int stride)

3.16.1 Detailed Description

Creates a max pooling layer

3.16.2 Constructor & Destructor Documentation

3.16.2.1 MaxPoolLayer()

```
MaxPoolLayer::MaxPoolLayer (
    const std::shared_ptr< AbstractLayer > & input,
    std::shared_ptr< Graph > computeGraph,
    int kernelDim,
    int stride )
```

Parameters

<i>input</i>	
<i>computeGraph</i>	
<i>kernelDim</i>	
<i>stride</i>	

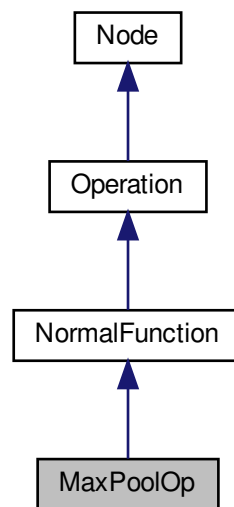
The documentation for this class was generated from the following files:

- /home/pbo/CLionProjects/libdl/library/NeuralNetwork/LayerFactory/include/MaxPoolLayer.hpp
- /home/pbo/CLionProjects/libdl/library/NeuralNetwork/LayerFactory/src/MaxPoolLayer.cpp

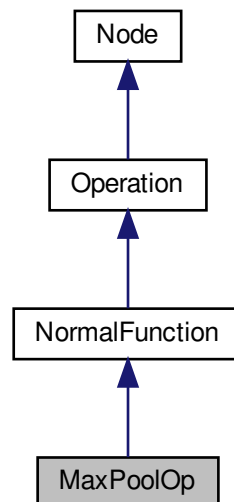
3.17 MaxPoolOp Class Reference

```
#include <MaxPoolOp.hpp>
```

Inheritance diagram for MaxPoolOp:



Collaboration diagram for MaxPoolOp:



Public Member Functions

- [MaxPoolOp](#) (std::shared_ptr< [Node](#) > X, int windowDim, int stride=1)

- void [forwardPass](#) () override
default destructor
- void [backwardPass](#) () override
- const Eigen::MatrixXf & [getMaxIndexMatrix](#) () const
stores the indices of the max Values
- void **setMaxIndexMatrix** (const Eigen::MatrixXf &maxIndexMatrix)

3.17.1 Detailed Description

Implements a MaxPooling operation

3.17.2 Constructor & Destructor Documentation

3.17.2.1 MaxPoolOp()

```
MaxPoolOp::MaxPoolOp (
    std::shared_ptr< Node > X,
    int windowDim,
    int stride = 1 )
```

- creates a Normal Function and sets the outputChannel to the number of channels of the input [Node](#)

Parameters

<i>X</i>	input Noode
<i>windowDim</i>	dimensions of the square window that is sliding over the samples taking the max value
<i>stride</i>	stride

3.17.3 Member Function Documentation

3.17.3.1 backwardPass()

```
void MaxPoolOp::backwardPass ( ) [override], [virtual]
```

calculates the gradient w.r.t the input isung the index Matrix

Reimplemented from [Operation](#).

3.17.3.2 forwardPass()

```
void MaxPoolOp::forwardPass ( ) [override], [virtual]
```

default destructor

applies Maxpooling to input X usig the window dimension stores additionally an index matrix of dim(X) containing at the index of the Max Values a one

Reimplemented from [Operation](#).

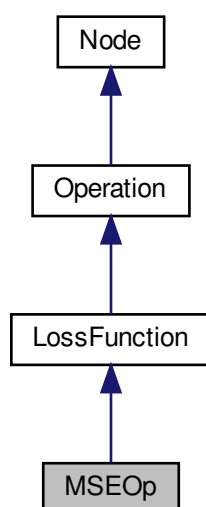
The documentation for this class was generated from the following files:

- /home/pbo/CLionProjects/libdl/library/ComputationalGraph/Operations/include/MaxPoolOp.hpp
- /home/pbo/CLionProjects/libdl/library/ComputationalGraph/Operations/src/MaxPoolOp.cpp

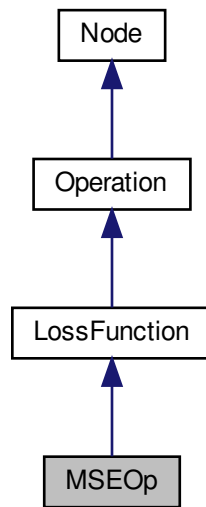
3.18 MSEOp Class Reference

```
#include <MSEOp.hpp>
```

Inheritance diagram for MSEOp:



Collaboration diagram for MSEOp:



Public Member Functions

- [MSEOp](#) (std::shared_ptr< [Node](#) > X, std::shared_ptr< [Placeholder](#) > labels)
- void [forwardPass](#) () override
- *default destructor*
- void [backwardPass](#) () override

3.18.1 Detailed Description

Implements the Mean Square Error

3.18.2 Constructor & Destructor Documentation

3.18.2.1 MSEOp()

```
MSEOp::MSEOp (
    std::shared_ptr< Node > X,
    std::shared_ptr< Placeholder > labels )
```

creates an [LossFunction](#) object stores the labels which are need to calculate the loss

Parameters

<i>X</i>	softmax classified samples
<i>labels</i>	groundTruth for initial samples

3.18.3 Member Function Documentation

3.18.3.1 backwardPass()

```
void MSEOp::backwardPass ( ) [override], [virtual]
```

calculates the gradient w.r.t to X

Reimplemented from [Operation](#).

3.18.3.2 forwardPass()

```
void MSEOp::forwardPass ( ) [override], [virtual]
```

default destructor

calculates the Mean Square Error of Input X with corresponding labels and sets the output as forward pass value

Reimplemented from [Operation](#).

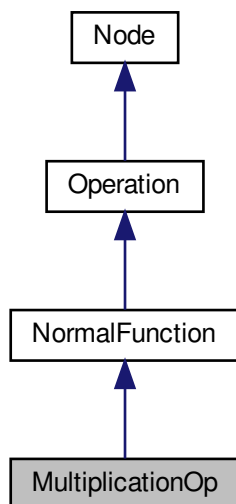
The documentation for this class was generated from the following files:

- /home/pbo/CLionProjects/libdl/library/ComputationalGraph/Operations/include/MSEOp.hpp
- /home/pbo/CLionProjects/libdl/library/ComputationalGraph/Operations/src/MSEOp.cpp

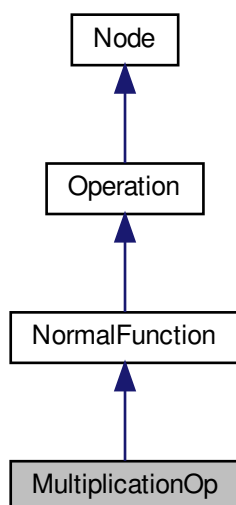
3.19 MultiplicationOp Class Reference

```
#include <MultiplicationOp.hpp>
```

Inheritance diagram for MultiplicationOp:



Collaboration diagram for MultiplicationOp:



Public Member Functions

- [MultiplicationOp](#) (std::shared_ptr< [Node](#) > X, std::shared_ptr< [Parameter](#) > weights)
- void [forwardPass](#) () override
- void [backwardPass](#) () override

3.19.1 Detailed Description

Implements the Matrix multiplication that simulates Neurons

3.19.2 Constructor & Destructor Documentation

3.19.2.1 MultiplicationOp()

```
MultiplicationOp::MultiplicationOp (
    std::shared_ptr< Node > X,
    std::shared_ptr< Parameter > weights )
```

creates [NormalFunction](#) object and passes the input outputChannels through stores a node Containing the weights for the multiplication

Parameters

<i>X</i>	input Batch
<i>weights</i>	the amount of cols of the forward pass corresponds to the number of Neurons, the amount of rows must equal the size of one sample of X

3.19.3 Member Function Documentation

3.19.3.1 backwardPass()

```
void MultiplicationOp::backwardPass ( ) [override], [virtual]
```

calculates the gradients w.r.t to X and weights

Reimplemented from [Operation](#).

3.19.3.2 forwardPass()

```
void MultiplicationOp::forwardPass ( ) [override], [virtual]
```

executes the Matrix multiplication and stores the output as forward pass value

Reimplemented from [Operation](#).

The documentation for this class was generated from the following files:

- /home/pbo/CLionProjects/libdl/library/ComputationalGraph/Operations/include/MultiplicationOp.hpp
- /home/pbo/CLionProjects/libdl/library/ComputationalGraph/Operations/src/MultiplicationOp.cpp

3.20 NeuralNetwork Class Reference

```
#include <NeuralNetwork.hpp>
```

Public Member Functions

- [NeuralNetwork](#) (std::shared_ptr< [Graph](#) > computeGraph, std::shared_ptr< [InputLayer](#) > inputLayer, std::shared_ptr< [LossLayer](#) > lossLayer)
- float [train](#) ([DataSet](#) &data, [HyperParameters](#) params, float trainingLossThreshold=1)
- [TrainingEvaluation](#) [trainAndValidate](#) ([DataSet](#) &data, [HyperParameters](#) params, float trainingLossThreshold=1)
- void [trainBatch](#) (Matrix &miniBatch, Matrix &labels, [HyperParameters](#) ¶ms)
- Matrix [predictBatch](#) (Matrix &miniBatch, Matrix &labels)
- bool [writeParameters](#) (std::string dir, std::string networkName)
- bool [readParameters](#) (std::string dir, std::string networkName)
- float [getLoss](#) ()

Static Public Member Functions

- static void [testAccuracy](#) (Matrix &results, Matrix &labels, float &correct, float &total)
- static std::vector< Matrix > [extractBatchList](#) (std::vector< Matrix > &dataset, int batchSize)

3.20.1 Detailed Description

This class implements the DeepLearning logic to run a training or prediction on a set of Layers/operations, specified by a inputLayer, a lossLayer and a computational graph

3.20.2 Constructor & Destructor Documentation

3.20.2.1 NeuralNetwork()

```
NeuralNetwork::NeuralNetwork (
    std::shared_ptr< Graph > computeGraph,
    std::shared_ptr< InputLayer > inputLayer,
    std::shared_ptr< LossLayer > lossLayer )
```

simple construction and initialization of the member variables with provided Parameters

Parameters

<i>computeGraph</i>	
<i>inputLayer</i>	
<i>lossLayer</i>	

3.20.3 Member Function Documentation

3.20.3.1 extractBatchList()

```
std::vector< Matrix > NeuralNetwork::extractBatchList (
    std::vector< Matrix > & dataset,
    int batchSize ) [static]
```

Parameters

<i>dataset</i>	a list of samples
<i>batchSize</i>	

Returns

a list of batches

3.20.3.2 getLoss()

```
float NeuralNetwork::getLoss ( )
```

Returns

the current Loss

3.20.3.3 predictBatch()

```
Matrix NeuralNetwork::predictBatch (
    Matrix & miniBatch,
    Matrix & labels )
```

this executes a simple prediction and returns the predicted labels

Parameters

<i>miniBatch</i>	
<i>labels</i>	this should be removed in Future, but is still needed as the Loss operation needs an label input

Returns

the Predictions: one row per sample, one collum for each label. if e.g. sample zero has label one label.↔
row(0)={0,1,0,0,...,0}

3.20.3.4 readParameters()

```
bool NeuralNetwork::readParameters (
    std::string dir,
    std::string networkName )
```

Initializes the Network with prestored Parameters stored in dir

Parameters

<i>dir</i>	
<i>networkName</i>	

Returns

if succeeded

3.20.3.5 testAccuracy()

```
void NeuralNetwork::testAccuracy (
    Matrix & results,
    Matrix & labels,
    float & correct,
    float & total ) [static]
```

Adds to the variable correct the number of correct predictions Adds to the variable total the number of samples that where predicted accuracy can then be calculated with correct/total

Parameters

<i>results</i>	
<i>labels</i>	
<i>correct</i>	
<i>total</i>	

3.20.3.6 train()

```
float NeuralNetwork::train (
    DataSet & data,
    HyperParameters params,
    float trainingLossThreshold = 1 )
```

Trains the Network on the trainingData stored in data

Parameters

<i>data</i>	
<i>params</i>	
<i>trainingLossThreshold</i>	

Returns

the final Loss

3.20.3.7 trainAndValidate()

```
TrainingEvaluation NeuralNetwork::trainAndValidate (
    DataSet & data,
    HyperParameters params,
    float trainingLossThreshold = 1 )
```

Trains the Network on the trainingData stored in data After each epoch the loss and accuracy is evaluated for both trainingSet and Validation Set the results are stored in an [TrainingEvaluation](#) object

Parameters

<i>data</i>	
<i>params</i>	
<i>trainingLossThreshold</i>	this can be used to tell at which cost the training should stop

Returns

Training results

3.20.3.8 trainBatch()

```
void NeuralNetwork::trainBatch (
    Matrix & miniBatch,
```

```
Matrix & labels,
HyperParameters & params )
```

Trains the network on a specific batch and the corresponding Labels

Parameters

<i>miniBatch</i>	one row per sample
<i>labels</i>	one row per sample, one collum for each label. if e.g. sample zero has label one label.row(0)={0,1,0,0,...,0}
<i>params</i>	the HyperParameter object contains everything need to update the Weights, Biases and Filters

3.20.3.9 writeParameters()

```
bool NeuralNetwork::writeParameters (
    std::string dir,
    std::string networkName )
```

Writes the parameter of the current Network

Parameters

<i>dir</i>	
<i>networkName</i>	

Returns

if succeeded

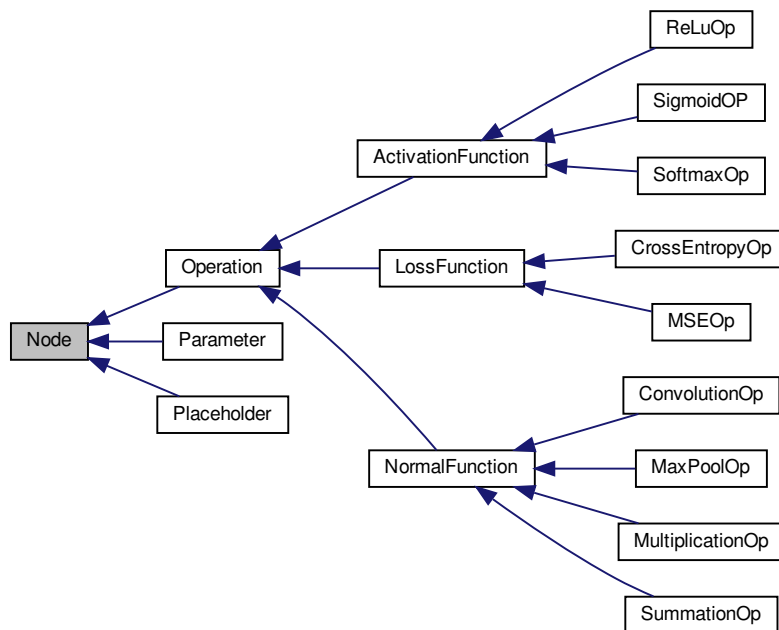
The documentation for this class was generated from the following files:

- /home/pbo/CLionProjects/libdl/library/NeuralNetwork/include/NeuralNetwork.hpp
- /home/pbo/CLionProjects/libdl/library/NeuralNetwork/src/NeuralNetwork.cpp

3.21 Node Class Reference

```
#include <Node.hpp>
```

Inheritance diagram for Node:



Public Member Functions

- const Matrix & **getForward** () const
- void **setForward** (const Matrix &forward)
- const Matrix & **getPreviousGradients** () const
- void **setPreviousGradients** (const Matrix &previousGradients)
- void **setOutputChannels** (int outputChannels)
- int **getOutputChannels** () const

3.21.1 Detailed Description

This class represents the Base Class of all Nodes of the Computational [Graph](#).

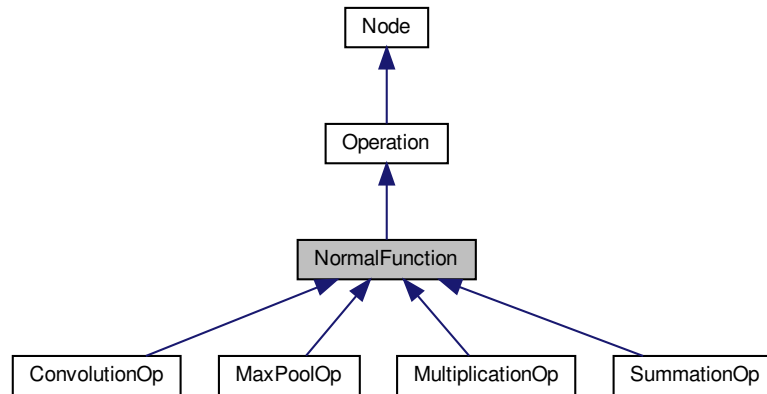
The documentation for this class was generated from the following files:

- /home/pbo/CLionProjects/libdl/library/ComputationalGraph/include/Node.hpp
- /home/pbo/CLionProjects/libdl/library/ComputationalGraph/src/Node.cpp

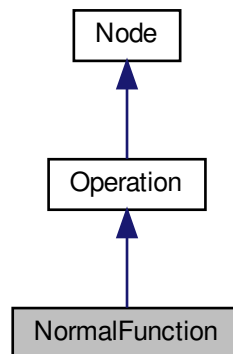
3.22 NormalFunction Class Reference

```
#include <NormalFunction.hpp>
```

Inheritance diagram for NormalFunction:



Collaboration diagram for NormalFunction:



Public Member Functions

- [NormalFunction](#) (std::shared_ptr< [Node](#) > X, std::shared_ptr< [Parameter](#) > parameter, int outputChannels)
- [NormalFunction](#) (std::shared_ptr< [Node](#) > X, int outputChannels)
- const std::shared_ptr< [Parameter](#) > & [getParameter](#) () const
arameters such as weights, biases, filters

3.22.1 Detailed Description

A [NormalFunction](#) operation represents typical operations that take a Weight or Bias Right now this also counts for the MaxPool Layer, however in future it should get its own Base class as MaxPool does not hold Weights or Biases

3.22.2 Constructor & Destructor Documentation

3.22.2.1 NormalFunction() [1/2]

```
NormalFunction::NormalFunction (
    std::shared_ptr< Node > X,
    std::shared_ptr< Parameter > parameter,
    int outputChannels )
```

- creates the operation Object using the the obligatory Input [Node](#) and the outputChannels.
- stores the parameters for this operation

Parameters

<i>X</i>	input Node
<i>parameter</i>	parameters such as weights, biases, filters
<i>outputChannels</i>	the expected outputChannels for this operation

3.22.2.2 NormalFunction() [2/2]

```
NormalFunction::NormalFunction (
    std::shared_ptr< Node > X,
    int outputChannels )
```

- creates the operation Object using the the obligatory Input [Node](#) and the outputChannels.

Parameters

<i>X</i>	input Node
<i>outputChannels</i>	the expected outputChannels for this operation

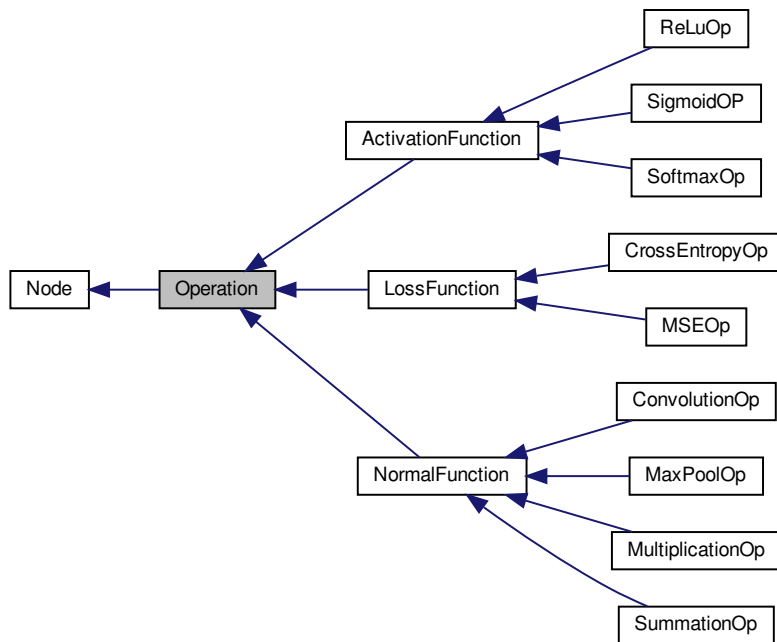
The documentation for this class was generated from the following files:

- /home/pbo/CLionProjects/libdl/library/ComputationalGraph/Operations/include/NormalFunction.hpp
- /home/pbo/CLionProjects/libdl/library/ComputationalGraph/Operations/src/NormalFunction.cpp

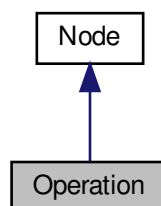
3.23 Operation Class Reference

```
#include <Operation.hpp>
```

Inheritance diagram for Operation:



Collaboration diagram for Operation:



Public Member Functions

- `Operation` (`std::shared_ptr< Node >` input, `int` outputChannel)
- `~Operation` () override=default
- `virtual void forwardPass` ()

- virtual void [backwardPass](#) ()
- int [forwardPassWithMeasurement](#) ()
- int [backwardPassWithMeasurement](#) ()
- int [getForwardTime](#) () const
- int [getBackwardsTime](#) () const
- const std::shared_ptr< [Node](#) > & [getInput](#) () const
- int [getInputChannels](#) () const

3.23.1 Detailed Description

This class defines the interface each [Operation](#) of the Computational [Graph](#) has to implement

3.23.2 Constructor & Destructor Documentation

3.23.2.1 Operation()

```
Operation::Operation (
    std::shared_ptr< Node > input,
    int outputChannel )
```

stores the obligatory Input [Node](#) for a operation and sets the `_outputChannel` for this [Operation](#). Further it stores the `_outputChannel` of the input [Node](#) as `_inputChannel`

Parameters

<i>input</i>	the inputNode which might be an Placeholder or an Operation
<i>outputChannel</i>	the #outputChannel of this Operation

3.23.2.2 ~Operation()

```
Operation::~~Operation ( ) [override], [default]
```

Default destructor

3.23.3 Member Function Documentation

3.23.3.1 backwardPass()

```
virtual void Operation::backwardPass ( ) [inline], [virtual]
```

calculates the gradients for the operation inputs w.r.t. the last [Node](#) in the Computational Grpah. In order to do so it uses the member variable `_previousGradients` of Class [Node](#), which contains the Gradients of the previous operation.

Each implementation must set the member variable `_previousGradients` of the operations Inputs by calling `[All←InputNodes]->setPreviousGradients(Matrix calculatedGradients)`

Reimplemented in [MaxPoolOp](#), [SigmoidOP](#), [ConvolutionOp](#), [SoftmaxOp](#), [CrossEntropyOp](#), [MSEOp](#), [Multiplication←Op](#), [ReLuOp](#), and [SummationOp](#).

3.23.3.2 backwardPassWithMeasurement()

```
int Operation::backwardPassWithMeasurement ( )
```

executes the backwardPass and stores the computation time

Returns

the computation Time

3.23.3.3 forwardPass()

```
virtual void Operation::forwardPass ( ) [inline], [virtual]
```

calculates the outputValue of this [Operation](#) using the Input Nodes.

Each implementation must set the member variable `_forward` by calling `setForward(Matrix calculatedOutputValue)`

Reimplemented in [MaxPoolOp](#), [ConvolutionOp](#), [SoftmaxOp](#), [CrossEntropyOp](#), [MSEOp](#), [MultiplicationOp](#), [ReLuOp](#), [SigmoidOP](#), and [SummationOp](#).

3.23.3.4 forwardPassWithMeasurement()

```
int Operation::forwardPassWithMeasurement ( )
```

executes the forwardPass and stores the computation time

Returns

the computation Time

3.23.3.5 getBackwardsTime()

```
int Operation::getBackwardsTime ( ) const
```

this does only work if [backwardPassWithMeasurement\(\)](#) is called

Returns

computation Time of backwardPass

3.23.3.6 getForwardTime()

```
int Operation::getForwardTime ( ) const
```

this does only work if [forwardPassWithMeasurement\(\)](#) is called

Returns

computation Time of forwardPass

The documentation for this class was generated from the following files:

- /home/pbo/CLionProjects/libdl/library/ComputationalGraph/include/Operation.hpp
- /home/pbo/CLionProjects/libdl/library/ComputationalGraph/src/Operation.cpp

3.24 OperationsFactory Class Reference

```
#include <OperationsFactory.hpp>
```

Static Public Member Functions

- static std::shared_ptr< [ConvolutionOp](#) > **createConvolutionOp** (std::shared_ptr< [Graph](#) > graph, const std::shared_ptr< [Node](#) > input, Matrix filterMatrix, int channels, int stride)
- static std::shared_ptr< [SummationOp](#) > **createSummationOp** (std::shared_ptr< [Graph](#) > graph, const std::shared_ptr< [Node](#) > input, Matrix biasMatrix, int channel)
- static std::shared_ptr< [MultiplicationOp](#) > **createMultiplicationOp** (std::shared_ptr< [Graph](#) > graph, const std::shared_ptr< [Node](#) > input, Matrix weightMatrix)
- static std::shared_ptr< [MaxPoolOp](#) > **createMaxpoolOp** (std::shared_ptr< [Graph](#) > graph, const std::shared_ptr< [Node](#) > input, int kernelDim, int stride)
- static std::shared_ptr< [MSEOp](#) > **createMSEOp** (std::shared_ptr< [Graph](#) > graph, const std::shared_ptr< [Node](#) > input, Matrix labelMatrix)
- static std::shared_ptr< [CrossEntropyOp](#) > **createCrossEntropyOp** (std::shared_ptr< [Graph](#) > graph, const std::shared_ptr< [Node](#) > input, Matrix labelMatrix)
- static std::shared_ptr< [ReLuOp](#) > **createReLuOp** (std::shared_ptr< [Graph](#) > graph, const std::shared_ptr< [Node](#) > input)
- static std::shared_ptr< [SigmoidOp](#) > **createSigmoidOp** (std::shared_ptr< [Graph](#) > graph, const std::shared_ptr< [Node](#) > input)
- static std::shared_ptr< [SoftmaxOp](#) > **createSoftmaxOp** (std::shared_ptr< [Graph](#) > graph, const std::shared_ptr< [Node](#) > input, int amountClasses)

3.24.1 Detailed Description

This class implements the Factory Pattern in a functional way. Each creation function assures that an [Operation](#) is not only created but also added to the compute graph if the input [Node](#) is not already in the [Graph](#) this will fail with an `runtime_error` cause by the [Graph](#) class

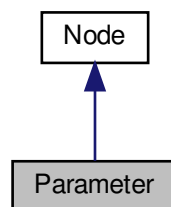
The documentation for this class was generated from the following files:

- `/home/pbo/CLionProjects/libdl/library/ComputationalGraph/Operations/include/OperationsFactory.hpp`
- `/home/pbo/CLionProjects/libdl/library/ComputationalGraph/Operations/src/OperationsFactory.cpp`

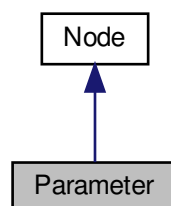
3.25 Parameter Class Reference

```
#include <Parameter.hpp>
```

Inheritance diagram for Parameter:



Collaboration diagram for Parameter:



Public Member Functions

- [Parameter](#) (Matrix &filter, int channel)
- [Parameter](#) (Matrix &input)
- [~Parameter](#) () override=default
- void [updateParameter](#) (const [HyperParameters](#) &hyperParameters)

3.25.1 Detailed Description

This [Node](#) holds the Parameters that define the function of the Computational [Graph](#). In terms of a Neural Networks, this class holds the functionality for Filters, Weights and Biases, which may be updated during Backpropagation

3.25.2 Constructor & Destructor Documentation

3.25.2.1 `Parameter()` [1/2]

```
Parameter::Parameter (
    Matrix & filter,
    int channel )
```

Constructs a Filter and sets the Output to the filterMatrix. Further it initializes the momentum and RMSprob for possible future Updates using the ADAM optimizer

Parameters

<i>filter</i>	each Row corresponds to one Kernel, the size of one Kernel equals <code>std::pow(KernelDim,2)*channel</code>
<i>channel</i>	the Amount of Channels each Kernel has

3.25.2.2 `Parameter()` [2/2]

```
Parameter::Parameter (
    Matrix & input ) [explicit]
```

Constructs a Weight or Bias and sets the Output to the inputMatrix. Further it initializes the momentum and RMSprob for possible future Updates using the ADAM optimizer

Parameters

<i>input</i>	
--------------	--

3.25.2.3 `~Parameter()`

```
Parameter::~~Parameter ( ) [override], [default]
```

Default Destructor

3.25.3 Member Function Documentation

3.25.3.1 updateParameter()

```
void Parameter::updateParameter (
    const HyperParameters & hyperParameters )
```

updates the output of the Variable according to the Optimizer and Hyperparameters that are passed.

Parameters

<i>hyperParameters</i>	Object containing all hyperParameters for Neural Networks
------------------------	---

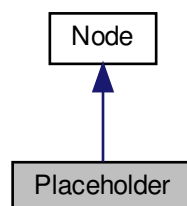
The documentation for this class was generated from the following files:

- /home/pbo/CLionProjects/libdl/library/ComputationalGraph/include/Parameter.hpp
- /home/pbo/CLionProjects/libdl/library/ComputationalGraph/src/Parameter.cpp

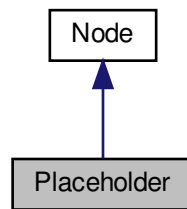
3.26 Placeholder Class Reference

```
#include <Placeholder.hpp>
```

Inheritance diagram for Placeholder:



Collaboration diagram for Placeholder:



Public Member Functions

- [Placeholder](#) (Matrix &batch, int channel)
- [Placeholder](#) (Matrix &labels)
- [~Placeholder](#) () override=default

3.26.1 Detailed Description

This [Node](#) represents a [Placeholder](#) for a fixed Input into the Computational [Graph](#). In terms of a Neural Networks, this class holds the functionality for inputting Samples or Labels to corresponding Samples.

3.26.2 Constructor & Destructor Documentation

3.26.2.1 Placeholder() [1/2]

```
Placeholder::Placeholder (
    Matrix & batch,
    int channel )
```

constructs a mini-batch and sets the output to batch. Further the number of output channels is set to the number of channels of each sample.

Parameters

<i>batch</i>	a whole mini-batch, each row contains one sample
<i>channel</i>	number of channels of each sample

3.26.2.2 Placeholder() [2/2]

```
Placeholder::Placeholder (
    Matrix & labels ) [explicit]
```

constructs a [Placeholder](#) that contains the labels to a previously created mini-batch.

Parameters

<i>labels</i>	each row corresponds to the label of one sample, while the Dimension of each row is the #labels, this way the corresponding label is identified by the column that holds a "1"
---------------	--

3.26.2.3 ~Placeholder()

```
Placeholder::~~Placeholder ( ) [override], [default]
```

Default Destructor

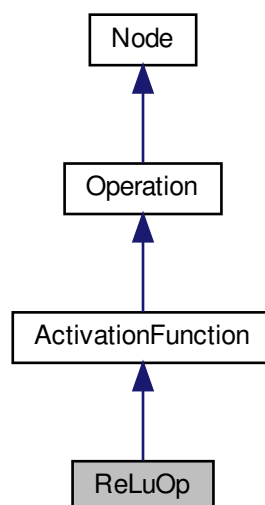
The documentation for this class was generated from the following files:

- /home/pbo/CLionProjects/libdl/library/ComputationalGraph/include/Placeholder.hpp
- /home/pbo/CLionProjects/libdl/library/ComputationalGraph/src/Placeholder.cpp

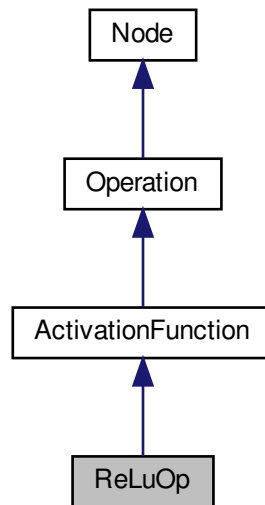
3.27 ReLuOp Class Reference

```
#include <ReLuOp.hpp>
```

Inheritance diagram for ReLuOp:



Collaboration diagram for ReLuOp:



Public Member Functions

- [ReLuOp](#) (std::shared_ptr< [Node](#) > X)
- void [forwardPass](#) () override
- *default destructor*
- void [backwardPass](#) () override

Static Public Member Functions

- static float [deriveReLu](#) (float element)

3.27.1 Detailed Description

Implements the ReLu activation function

3.27.2 Constructor & Destructor Documentation

3.27.2.1 ReLuOp()

```
ReLuOp::ReLuOp (
    std::shared_ptr< Node > X ) [explicit]
```

creates an [ActivationFunction](#) object using the input node X

Parameters

X	
---	--

3.27.3 Member Function Documentation

3.27.3.1 backwardPass()

```
void ReLuOp::backwardPass ( ) [override], [virtual]
```

calculates the sigmoid gradients w.r.t to input X using function deriveReLu

Reimplemented from [Operation](#).

3.27.3.2 deriveReLu()

```
float ReLuOp::deriveReLu (
    float element ) [static]
```

calculates the derivative of the ReLu function for a given element

Parameters

<i>element</i>	
----------------	--

Returns

dReLu(element)

3.27.3.3 forwardPass()

```
void ReLuOp::forwardPass ( ) [override], [virtual]
```

default destructor

calculates ReLu for the whole input X and set the output value as forward pass value

Reimplemented from [Operation](#).

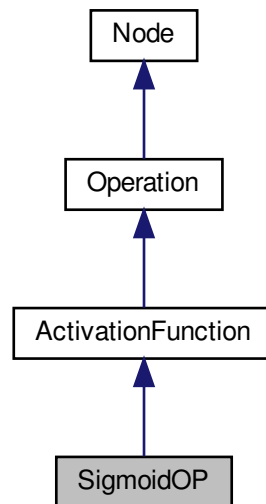
The documentation for this class was generated from the following files:

- /home/pbo/CLionProjects/libdl/library/ComputationalGraph/Operations/include/ReLuOp.hpp
- /home/pbo/CLionProjects/libdl/library/ComputationalGraph/Operations/src/ReLuOp.cpp

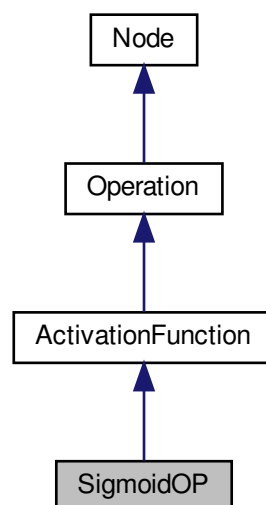
3.28 SigmoidOP Class Reference

```
#include <SigmoidOP.hpp>
```

Inheritance diagram for SigmoidOP:



Collaboration diagram for SigmoidOP:



Public Member Functions

- [SigmoidOP](#) (std::shared_ptr< [Node](#) > X)
- void [forwardPass](#) () override
default destructor
- void [backwardPass](#) () override

Static Public Member Functions

- static float [sigmoid](#) (float a)

3.28.1 Detailed Description

Implements the Sigmoid activation function

3.28.2 Constructor & Destructor Documentation

3.28.2.1 SigmoidOP()

```
SigmoidOP::SigmoidOP (
    std::shared_ptr< Node > X ) [explicit]
```

creates an [ActivationFunction](#) object using the input node X

Parameters

X	
---	--

3.28.3 Member Function Documentation

3.28.3.1 backwardPass()

```
void SigmoidOP::backwardPass ( ) [override], [virtual]
```

calculates the sigmoid gradients w.r.t to input X

Reimplemented from [Operation](#).

3.28.3.2 forwardPass()

```
void SigmoidOP::forwardPass ( ) [override], [virtual]
```

default destructor

calculates sigmoid for the whole input X and set the output value as forward pass value

Reimplemented from [Operation](#).

3.28.3.3 sigmoid()

```
float SigmoidOP::sigmoid (
    float a ) [static]
```

calculates the sigmoid function

Parameters

<i>a</i>	
----------	--

Returns

sigmoid(a)

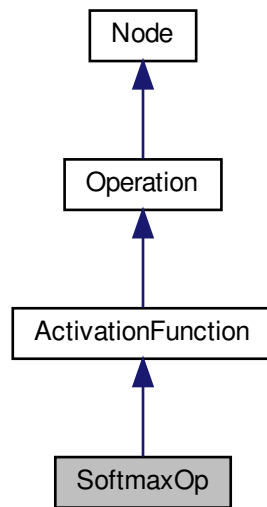
The documentation for this class was generated from the following files:

- /home/pbo/CLionProjects/libdl/library/ComputationalGraph/Operations/include/SigmoidOP.hpp
- /home/pbo/CLionProjects/libdl/library/ComputationalGraph/Operations/src/SigmoidOP.cpp

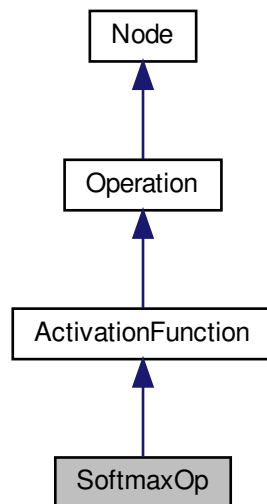
3.29 SoftmaxOp Class Reference

```
#include <SoftmaxOp.hpp>
```

Inheritance diagram for SoftmaxOp:



Collaboration diagram for SoftmaxOp:



Public Member Functions

- [SoftmaxOp](#) (std::shared_ptr< [Node](#) > X, int numberClasses)

- void [forwardPass](#) () override
default destructor
- void [backwardPass](#) () override

3.29.1 Detailed Description

Implements the Softmax Classifier Right Now Softmax does only work in combination with [CrossEntropyOp](#), as the gradient of both together is calculated there and then just passed backwards

3.29.2 Constructor & Destructor Documentation

3.29.2.1 SoftmaxOp()

```
SoftmaxOp::SoftmaxOp (
    std::shared_ptr< Node > X,
    int numberClasses )
```

creates an [ActivationFunction](#) object stores the number of classes that need to be predicted

Parameters

<i>X</i>	input to be transformed
<i>numberClasses</i>	#predictionClasses

3.29.3 Member Function Documentation

3.29.3.1 backwardPass()

```
void SoftmaxOp::backwardPass ( ) [override], [virtual]
```

passes the softmax-crossEntropy-classifier gradient calculated in CrossEntropyLoss further backwards to the input [Node X](#) see also: <https://deepnotes.io/softmax-crossentropy>

Reimplemented from [Operation](#).

3.29.3.2 forwardPass()

```
void SoftmaxOp::forwardPass ( ) [override], [virtual]
```

default destructor

performs softmax classification

Reimplemented from [Operation](#).

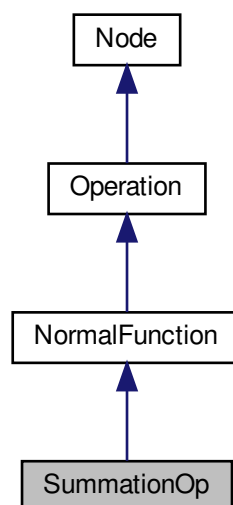
The documentation for this class was generated from the following files:

- /home/pbo/CLionProjects/libdl/library/ComputationalGraph/Operations/include/SoftmaxOp.hpp
- /home/pbo/CLionProjects/libdl/library/ComputationalGraph/Operations/src/SoftmaxOp.cpp

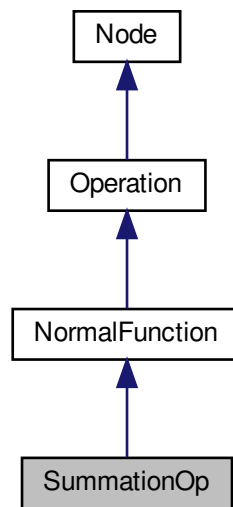
3.30 SummationOp Class Reference

```
#include <SummationOp.hpp>
```

Inheritance diagram for SummationOp:



Collaboration diagram for SummationOp:



Public Member Functions

- [SummationOp](#) (std::shared_ptr< [Node](#) > X, std::shared_ptr< [Parameter](#) > biases)
- void [forwardPass](#) () override
default destructor
- void [backwardPass](#) () override

3.30.1 Detailed Description

Implements the Matrix summation that is mainly used for adding a Bias to a previous calculated forward pass of a Neuron/MultiplicationOP

3.30.2 Constructor & Destructor Documentation

3.30.2.1 SummationOp()

```
SummationOp::SummationOp (
    std::shared_ptr< Node > X,
    std::shared_ptr< Parameter > biases )
```

creates [NormalFunction](#) object and passes the input outputChannels through stores a node Containing the biases for the summation

Parameters

<i>X</i>	input Batch
<i>biases</i>	the shape of biases should completely equal X

3.30.3 Member Function Documentation

3.30.3.1 backwardPass()

```
void SummationOp::backwardPass ( ) [override], [virtual]
```

calculates the gradients w.r.t to X and biases

Reimplemented from [Operation](#).

3.30.3.2 forwardPass()

```
void SummationOp::forwardPass ( ) [override], [virtual]
```

default destructor

executes the matrix summation and stores the output as forward pass value

Reimplemented from [Operation](#).

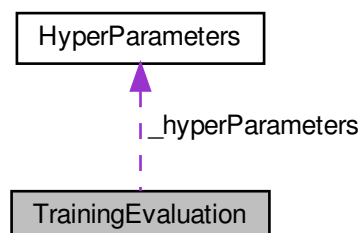
The documentation for this class was generated from the following files:

- /home/pbo/CLionProjects/libdl/library/ComputationalGraph/Operations/include/SummationOp.hpp
- /home/pbo/CLionProjects/libdl/library/ComputationalGraph/Operations/src/SummationOp.cpp

3.31 TrainingEvaluation Struct Reference

```
#include <commonDatatypes.hpp>
```

Collaboration diagram for TrainingEvaluation:



Public Member Functions

- **TrainingEvaluation** ([HyperParameters](#) hyperParameters)
- **TrainingEvaluation** (std::vector< float > trainingLoss, std::vector< float > trainingAccuracy, [HyperParameters](#) hyperParameters)
- **TrainingEvaluation** (std::vector< float > trainingLoss, std::vector< float > trainingAccuracy, std::vector< float > validationLoss, std::vector< float > validationAccuracy, [HyperParameters](#) hyperParameters)

Public Attributes

- std::vector< float > **_trainingLoss**
- std::vector< float > **_validationLoss**
- std::vector< float > **_trainingAccuracy**
- std::vector< float > **_validationAccuracy**
- [HyperParameters](#) **_hyperParameters**

3.31.1 Detailed Description

This struct holds the results of a training, storing in each field of a vector, the value for one epoch

The documentation for this struct was generated from the following file:

- /home/pbo/CLionProjects/libdl/library/Utils/include/commonDatatypes.hpp

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- ~Parameter
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