

CS229-Cheatsheet

Supervised Learning

- **Gradient Descent:** to minimize $J(\theta)$, we perform

$$\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta} J(\theta)$$
- $\nabla_A AB = B^T$, $\nabla_{A^T} f(A) = (\nabla_A f(A))^T$,
 $\nabla_A \text{tr} ABA^T C = CAB + C^T AB^T$, $\nabla_A |A| = |A|(A^{-1})^T$
- **Normal Equations and Least Squares**

$$J(\theta) = \frac{1}{2} \sum_{i=1}^m (h_\theta(x^i) - y^i)^2 \rightarrow \nabla_\theta J(\theta) =$$

$$\nabla_\theta \frac{1}{2} (X\theta - y)^T (X\theta - y) = X^T X\theta - X^T y = 0 \rightarrow$$

$$X^T X\theta = X^T y \rightarrow \theta = (X^T X)^{-1} X^T y.$$
- **Locally Weighted Regression** Fit θ to minimize

$$\sum_{i=0}^m (y^i - \theta^T x^i)^2$$
 where $w^i = e^{-\frac{(x^i - x)^2}{2\tau^2}}$
- **Logistic Regression:** $h_\theta(x) = g(\theta^T x) = \frac{1}{1 + e^{-\theta^T x}}$,

$$g(z) = \frac{1}{1 + e^{-z}}, g'(z) = \frac{d}{dz} \frac{1}{1 + e^{-z}} = g(z)(1 - g(z)),$$

$$p(y|x; \theta) = (h_\theta(x))^y (1 - h_\theta(x))^{1-y}.$$

$$l(\theta) = \log L(\theta) = \sum_{i=1}^m y^i \log h(x^i) + (1 - y^i) \log(1 - h(x^i)),$$

$$\frac{\partial}{\partial \theta_j} l(\theta) = (y - h_\theta(x)) x_j$$
- **Perceptron Learning Algorithm**

$$\theta_j := \theta_j + \alpha (y^i - h_\theta(x^i)) x_j^i$$
- **Newton's Method:** $\theta := \theta - \frac{f(\theta)}{f'(\theta)}$, we want the first
derivative to be zero, then $\theta := \theta - \frac{l'(\theta)}{l''(\theta)}$, if θ is a
vector then $\theta := \theta - H^{-1} \nabla_\theta l(\theta)$ where $H_{ij} = \frac{\partial^2 l(\theta)}{\partial \theta_i \partial \theta_j}$
- **Exponential Family** $p(y; \eta) = b(y) \exp(\eta^T T(y) - a(\eta))$
- **General Linear Model Assumptions:** 1.
 $y|x; \eta \sim \text{ExponentialFamily}(\eta)$. 2. Given x our goal is
to predict the expected value of $T(y)$ which is usually
just y , so we would like our hypothesis to satisfy
 $h(x) = E(y|x)$. 3. The natural parameter η and inputs
 x are related linearly. $\eta = \theta^T x$.
- **Canonical response function:** the distribution's
mean as a function of the natural parameter
 $g(\eta) = E(T(y); \eta)$.

Generative Learning Algorithm

Gaussian Discriminant Analysis

- $y \sim \text{Bernoulli}(\phi)$, $x|y = 0 \sim N(\mu_0, \Sigma)$, $x|y = 1 \sim N(\mu_1, \Sigma)$.

- $p(y) = \phi^y (1 - \phi)^{1-y}$
- $p(x|y = 0) = \frac{1}{(2\pi)^{n/2} |\Sigma|^{1/2}} \exp(-\frac{1}{2} (x - \mu_0)^T \Sigma^{-1} (x - \mu_0))$
- $p(x|y = 1) = \frac{1}{(2\pi)^{n/2} |\Sigma|^{1/2}} \exp(-\frac{1}{2} (x - \mu_1)^T \Sigma^{-1} (x - \mu_1))$
- $l(\phi, \mu_0, \mu_1, \Sigma) = \log \prod_{i=1}^m p(x^i, y^i; \phi, \mu_0, \mu_1, \Sigma) =$

$$\log \prod_{i=1}^m p(x^i | y^i; \phi, \mu_0, \mu_1, \Sigma) p(y^i, \phi).$$
- By maximizing l with respect to the parameters, we
find the maximum likelihood of the parameters to be:

$$\phi = \frac{1}{m} \mathbb{1}\{y^i = 1\}$$

$$\mu_0 = \frac{\sum_{i=1}^m \{y^i = 0\} x^i}{\sum_{i=1}^m \{y^i = 0\}}$$

$$\mu_1 = \frac{\sum_{i=1}^m \{y^i = 1\} x^i}{\sum_{i=1}^m \{y^i = 1\}}$$

$$\Sigma = \frac{1}{m} \sum_{i=1}^m (x^i - \mu_{y^i})^T (x^i - \mu_{y^i})$$

Naive Bayes

- **Naive Assumption:**

$$p(x_1, x_2, \dots | y) = p(x_1 | y) p(x_2 | y) \dots = \prod_{i=1}^n p(x_i | y)$$
- **Laplace Smoothing**

$$\phi_j = \frac{\sum_{i=1}^m \mathbb{1}\{z^i = j\}}{m} \rightarrow \frac{\sum_{i=1}^m \mathbb{1}\{z^i = j + 1\}}{m + k},$$
 where k
represent the number of possible outcomes for z .
- **Event Driven Text Classification:**

$$\phi_{k|y=1} = \frac{\sum_{i=1}^m \sum_{j=1}^{n_i} \mathbb{1}\{x_j^i = k \wedge y^i = 1\}}{\sum_{i=1}^m \sum_{j=1}^{n_i} \mathbb{1}\{y^i = 1\} n_i}$$

$$\phi_{k|y=0} = \frac{\sum_{i=1}^m \sum_{j=1}^{n_i} \mathbb{1}\{x_j^i = k \wedge y^i = 0\}}{\sum_{i=1}^m \sum_{j=1}^{n_i} \mathbb{1}\{y^i = 0\} n_i}$$

$$\phi_y = \frac{\sum_{i=1}^m \mathbb{1}\{y^i = 1\}}{m}$$

Support Vector Machines

- **Classifier:** $h_{w,b}(x) = g(w^T x + b)$ where $g(z) = 1$ if
 $z > 0$ and $g(z) = -1$ otherwise.
- **Functional Margins:** $\hat{\gamma}^i = y^i (w^T x^i + b)$, the smallest
functional margin in the training set is called:
 $\hat{\gamma} = \min_{i=1,2,\dots,m} \hat{\gamma}^i$
- **Geometric Margins:** $\gamma^i = y^i ((\frac{w}{\|w\|})^T x^i + \frac{b}{\|w\|})$, the
smallest geometric margin in a training set is
 $\gamma = \min_{i=1,\dots,m} \gamma^i$
- **Optimal Margin Classifier:** $\min_{\gamma, w, b} \frac{1}{2} \|w\|^2$
s.t $y^i (w^T x^i + b) \geq 1, i = 1, 2, \dots, m$

• Lagrangian

$$L(w, b, \alpha) = \frac{1}{2} \|w\|^2 - \sum_{i=1}^m \alpha_i (y^i (w^T x^i + b) - 1)$$

• The dual problem

$$\max_{\alpha} W(\alpha) = \sum_{i=1}^m \alpha_i - \frac{1}{2} \sum_{i,j=1}^m y^i y^j \alpha_i \alpha_j (x^i)^T x^j$$

$$\text{s.t } \sum_{i=1}^m \alpha_i y^i = 0$$

$$\alpha_i \geq 0 \text{ for } i = 1, \dots, m$$

• Observations:

$$1. \text{ Most of the } \alpha_i \text{ s will be zero}$$

$$w^T x + b = (\sum_{i=1}^m \alpha_i y^i x^i)^T x + b$$

• KKT Conditions:

$$\frac{\partial}{\partial w_i} L(w^*, \alpha^*, \beta^*) = 0, i = 1, \dots, n$$

$$\frac{\partial}{\partial \beta_i} L(w^*, \alpha^*, \beta^*) = 0, i = 1, \dots, l$$

$$\alpha^* g_i(w^*) = 0, i = 1, \dots, k$$

$$g_i(w^*) \leq 0, i = 1, \dots, k$$

$$\alpha^* \geq 0, i = 1, \dots, k$$

- **Mercer Theorem:** Let $K: \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}$ be given,
then for K to be a valid kernel, it is necessary and
sufficient that for any $\{x_1, x_2, \dots, x^m\}$, the
corresponding kernel matrix is symmetric positive
semi-definite.

• Regularization (revised optimal margin classifier)

$$\min_{\gamma, w, b} \frac{1}{2} \|w\|^2 + C \sum_{i=1}^m \xi_i$$

$$\text{s.t } y^i (w^T x^i + b) \geq 1 - \xi_i, i = 1, 2, \dots, m$$

$$\xi_i \geq 0, i = 1, \dots, m$$

• Dual of Regularization

$$\max_{\alpha} W(\alpha) = \sum_{i=1}^m \alpha_i - \frac{1}{2} \sum_{i,j=1}^m y^i y^j \alpha_i \alpha_j (x^i)^T x^j$$

$$\text{s.t } \sum_{i=1}^m \alpha_i y^i = 0$$

$$C \geq \alpha_i \geq 0 \text{ for } i = 1, \dots, m$$

Learning Theory

- **Union Bound:** Let A_1, A_2, \dots, A_k be k different
events (that may not be independent). Then

$$P(A_1 \cup A_2 \dots A_k) \leq P(A_1) + P(A_2) + \dots P(A_k)$$
- **Hoeffding inequality** Let Z_1, Z_2, \dots, Z_m be m
independent and identically distributed random
variables drawn from Bernoulli(ϕ) distribution. Let

$$\hat{\phi} = \frac{1}{m} \sum_{i=1}^m Z_i$$
 be the mean of these random variables
and let any $\gamma > 0$ be fixed. Then

$$P(|\phi - \hat{\phi}| > \gamma) \leq 2 \exp(-2\gamma m)$$

- **Generational Error Bound:**
 $P(|\epsilon(h_i) - \hat{\epsilon}(h_i)| > \gamma) \leq 2\exp(-2\gamma^2 m)$
- **Uniform Convergence:**

$$\begin{aligned} P(\neg \exists h \in H. |\epsilon(h_i) - \hat{\epsilon}(h_i)| > \gamma) \\ = P(\forall h \in H. |\epsilon(h_i) - \hat{\epsilon}(h_i)| \leq \gamma) \\ \geq 1 - 2k\exp(-2\gamma^2 m) \end{aligned}$$

- **Solving m, γ, δ** We just need to use the equation $\delta = 2k\exp(-2\gamma^2 m)$ to solve for one variable given the other two.
- Let $|H| = k$, and let any m, δ , be fixed. Then with probability at least $1 - \delta$, we have that

$$\epsilon(\hat{h}) \leq (\min_{h \in H} \epsilon(h)) + 2\sqrt{\frac{1}{2m} \log(\frac{2k}{\delta})}$$

- Let H be given, and let $d = VC(H)$, then with probability at least $1 - \delta$, we have that for all $h \in H$,

$$|\epsilon(h) - \hat{\epsilon}(h)| \leq O\left(\sqrt{\frac{d}{m} \log \frac{m}{d}} + \frac{1}{m} \log \frac{1}{\delta}\right)$$

we also have

$$|\hat{\epsilon}(h) - \epsilon(h^*)| \leq O\left(\sqrt{\frac{d}{m} \log \frac{m}{d}} + \frac{1}{m} \log \frac{1}{\delta}\right)$$

Regularization and Model Selection

Cross Validation

- **Simple Cross Validation:** 1. Randomly split S into S_{train} (say 70 percent of the data) and S_{cv} . Here, S_{cv} is called the hold-out cross validation set. 2. Train each model M_i on S_{train} only, to get some hypothesis h_i . 3.

Select and output the hypothesis h_i that had the smallest error $\hat{\epsilon}(h_i)$ on the hold out cross validation set.

- **k -fold cross validation** 1. Randomly split S into k disjoint subsets of m/k training examples each. Lets call these subsets S_1, \dots, S_k . 3. For each model M_i , we evaluate it as follows: For $j = 1, \dots, k$ Train the model M_i on $S_1 \cup \dots \cup S_{j-1} \cup S_{j+1} \cup \dots \cup S_k$ (i.e., train on all the data except S_j) to get some hypothesis h_{ij} . Test the hypothesis h_{ij} on S_j , to get $\epsilon_{S_j}(h_{ij})$. The estimated generalization error of model M_i is then calculated as the average of the $\epsilon_{S_j}(h_{ij})$ s (averaged over j).

Feature Selection
