# ODEs for Sci/Eng. Math 331 Syllabus

Textbook: Advanced Engineering Mathematics by Erwin Kreyszig, 10th Edition.

Spring 2013

#### Chapter 1. First Order ODEs

- Section 1.1: Basic Concepts, Modeling.
- Section 1.2: Geometric Meaning. Direction Fields. Euler's Method.
- Section 1.3: Separable ODEs. Modeling.
- Section 1.5: Linear ODEs (integrating factors). Bernoulli Eq., Population Dyn.
- Section 1.4: Exact ODEs. More on Integrating Factors.

### Chapter 2. Second Order Linear ODEs

- Section 2.1: Homogeneous Linear ODEs of Second Order.
- Section 2.2: Homogeneous Linear ODEs with Constant Coefficients.
- Section 2.4: Modeling: Free Oscillations. Mass Spring System
- Section 2.6: Existence and Uniqueness of Solutions. Wronskian.
- Section 2.7: Non-homogeneous ODEs
- Section 2.8: Modeling: Forced Oscillations. Resonance
- Section 2.9: (Optional) Solution by Variation of Parameters.

#### Chapter 4. Systems of ODEs. Phase Plane. Qualitative Methods

- Section 4.0: Basics of Matrices and Vectors.
- Section 4.1: Systems of ODEs as Models.
- Section 4.2: Basic Theory of Systems of ODEs
- Section 4.3: Constant coefficient systems. Phase Plane method.
- Section 4.4: Criteria for Critical Points. Stability.

## Chapter 6. Laplace Transforms

- Section 6.1: Laplace Transform. Inverse transform. Linearity. s-Shifting
- Section 6.2: Transforms of Derivatives and Integrals.
- Section 6.3: Unit Step Function. t-Shifting.
- Section 6.4: Short Impulses. Dirac's Delta Function. Partial Fractions.
- Section 6.8: Laplace Transforms. general Formulas.
- Section 6.9: Table of Laplace Transforms.