



# Airoha IoT SDK for RTOS Bluetooth Developer's Guide

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## Document Revision History

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Revision	Date	Description
1.0	2 September 2016	Initial release
1.1	4 November 2016	Added description for multi-advertising support, see section 4.1.8, "Multiple advertising".
1.2	13 January 2017	Added description for AWS, see section 3.8, "AWS" Added Bluetooth panic mechanism, see section 5.4, "Bluetooth panic mechanism"
1.3	5 May 2017	Refine the issues in table of contents (TOC).
1.4	30 June 2017	<ul style="list-style-type: none"><li>• Updated description for AWS, see section 3.8 "AWS".</li><li>• Updated AVRCP version from 1.3 to 1.6, added section 3.5.2.4, "Absolute volume".</li></ul>
1.5	15 September 2017	<ul style="list-style-type: none"><li>• Added description to get play status, added section 3.5.2.7, "Get play status".</li><li>• Added description for get capabilities, see section 3.5.2.8, "Get capabilities".</li><li>• Added description for A2DP source and sink, see section 3.4, "A2DP"</li></ul>

## Table of Contents

---

<b>1.</b>	<b>Overview .....</b>	<b>1</b>
1.1.	Bluetooth protocol stack .....	1
<b>2.</b>	<b>Support for Bluetooth.....</b>	<b>4</b>
2.1.	Airoha IoT SDK library.....	4
<b>3.</b>	<b>The Bluetooth BR/EDR Protocol and Profiles .....</b>	<b>7</b>
3.1.	GAP .....	7
3.2.	SDP.....	16
3.3.	HFP.....	20
3.4.	A2DP .....	34
3.5.	AVRCP .....	44
3.6.	PBAP .....	52
3.7.	SPP .....	58
3.8.	AWS .....	61
<b>4.</b>	<b>The Bluetooth Low Energy Protocol or Profiles.....</b>	<b>69</b>
4.1.	GAP .....	69
4.2.	SM.....	81
4.3.	GATT .....	91
<b>5.</b>	<b>Creating a Custom Bluetooth Application .....</b>	<b>112</b>
5.1.	Memory management.....	112
5.2.	Create an application task.....	115
5.3.	Interaction with the Bluetooth host stack.....	116
5.4.	Bluetooth panic mechanism .....	118
<b>6.</b>	<b>Debugging and Porting Layer .....</b>	<b>120</b>
6.1.	Debugging.....	120
6.2.	Porting layer .....	120
<b>7.</b>	<b>Appendix A: Acronyms and Abbreviations.....</b>	<b>121</b>

## Lists of Tables and Figures

---

Table 1. Airoha IoT SDK library support for Bluetooth.....	4
Table 2. Player application settings and values .....	48
Table 3. Media element attributes .....	48
Table 4. List of notification events .....	49
Table 5. Fixed size control blocks .....	112
Table 6. Acronyms and abbreviations .....	121
Figure 1. BR/EDR protocol stack .....	1
Figure 2. Bluetooth Low Energy protocol stack .....	3
Figure 3. The GAP abstraction layout.....	7
Figure 4. Set the scan mode message sequence.....	8
Figure 5. GAP inquiry message sequence .....	8
Figure 6. Bonding using auto-confirmation message sequence .....	9
Figure 7. Bonding using numeric comparison message sequence.....	10
Figure 8. Bonding using passkey entry message sequence.....	11
Figure 9. Bonding using pin code message sequence .....	11
Figure 10. GAP disconnect message sequence .....	12
Figure 11. SDP abstraction layout .....	16
Figure 12. SDP client-server architecture .....	16
Figure 13. SDP service record .....	17
Figure 14. SDP server role .....	17
Figure 15. HFP abstraction layout .....	21
Figure 16. HFP connection establishment message sequence .....	22
Figure 17. HFP connection release message sequence .....	23
Figure 18. Initiate an outgoing voice call message sequence .....	24
Figure 19. Audio connection setup message sequence .....	25
Figure 20. Audio connection release message sequence .....	26
Figure 21. Enable or disable the voice recognition message sequence.....	27
Figure 22. The actions of an incoming call message sequence.....	28
Figure 23. The three way call handling message sequence .....	29
Figure 24. The remote speaker volume control message sequence .....	30
Figure 25. The remote microphone volume control message sequence.....	31
Figure 26. Transmit DTMF codes message sequence .....	32
Figure 27. Query a list of current calls message sequence .....	33
Figure 28. The A2DP state diagram.....	35
Figure 29. The A2DP abstraction layout.....	35
Figure 30. The A2DP connection establishment message sequence .....	36
Figure 31. The A2DP connection release message sequence .....	37
Figure 32. The A2DP start streaming message sequence .....	38
Figure 33. The A2DP suspend streaming message sequence .....	38
Figure 34. The A2DP reconfiguration message sequence.....	39

Figure 35. The A2DP codec operation message sequence (Sink) .....	40
Figure 36. The A2DP codec operation message sequence (Source) .....	41
Figure 37. The AVRCP abstraction layout.....	44
Figure 38. AVRCP connection establishment.....	45
Figure 39. AVRCP connection release .....	46
Figure 40. AV/C command procedure.....	47
Figure 41. PBAPC abstraction layout.....	52
Figure 42. PBAPC connection establishment without authentication message sequence.....	53
Figure 43. PBAPC get phone book object message sequence .....	53
Figure 44. PBAPC get the number of phonebook objects message sequence.....	54
Figure 45. PBAPC get caller name by number message sequence .....	55
Figure 46. PBAPC PullvCardEntry message sequence .....	56
Figure 47. Disconnect message sequence .....	56
Figure 48. SPP abstraction layout .....	58
Figure 49. SPP connection establishment message sequence.....	59
Figure 50. SPP connection release message sequence .....	59
Figure 51. SPP data transfer message sequence.....	60
Figure 52. The AWS abstraction layout.....	61
Figure 53. The AWS connection establishment message sequence .....	62
Figure 54. The AWS connection release message sequence .....	63
Figure 55. The AWS start streaming message sequence .....	64
Figure 56. The AWS suspend streaming message sequence .....	65
Figure 57. The AWS voice message synchronization sequence.....	66
Figure 58. GAP state diagram.....	69
Figure 59. GAP abstraction layout .....	70
Figure 60. Powering on the Bluetooth message sequence.....	71
Figure 61. GAP active scan message sequence.....	72
Figure 62. GAP passive scan message sequence.....	72
Figure 63. GAP general connection message sequence.....	73
Figure 64. GAP auto connection message sequence .....	74
Figure 65. Connection interval and event.....	76
Figure 66. Slave latency .....	76
Figure 67. Connection timeout error occurred (error code -0x08).....	77
Figure 68. Connection timeout error occurred (error code -0x3E).....	77
Figure 69. SM abstraction layout .....	83
Figure 70. Just Works (central role) .....	84
Figure 71. Just Works (peripheral role).....	84
Figure 72. Numeric Comparison (central role).....	85
Figure 73. Numeric Comparison (peripheral role) .....	86
Figure 74. Passkey entry (central role).....	87
Figure 75. Passkey entry (peripheral role) .....	88
Figure 76. Encryption (central role) .....	88
Figure 77. Encryption (peripheral role).....	89
Figure 78. GATT Client and Server .....	91

Figure 79. GATT profile hierarchy .....	92
Figure 80. Logical representation of the attribute.....	92
Figure 81. Exchange MTU event sequence .....	98
Figure 82. Primary service discovery event sequence .....	99
Figure 83. Find included services event sequence.....	101
Figure 84. Discover characteristic event sequence.....	102
Figure 85. Characteristic descriptor discovery event sequence .....	103
Figure 86. Characteristic value read event sequence .....	105
Figure 87. Read characteristic value using UUID event sequence .....	106
Figure 88. Read multiple characteristic value event sequence.....	107
Figure 89. Characteristic value write event sequence .....	108
Figure 90. Long value write event sequence .....	109
Figure 91. Characteristic value indication event sequence.....	110
Figure 92. Application interaction with the Bluetooth API .....	117

## 1. Overview

Airoha IoT development platform for RTOS provides Bluetooth and Bluetooth Low Energy (LE) connectivity support for IoT and Wearable's applications. Bluetooth standard offers basic rate (BR) or enhanced data rate (EDR) and Bluetooth Low Energy (LE) support. Devices that can support [BR/EDR](#) and [Bluetooth LE](#) are referred to as dual-mode devices. Typically, in a Bluetooth system, a mobile phone or laptop computer acts as a dual-mode device. Devices that only support Bluetooth LE are referred to as single-mode devices where the low power consumption is the primary concern for application development, such as those that run on coin cell batteries.

This document guides you through:

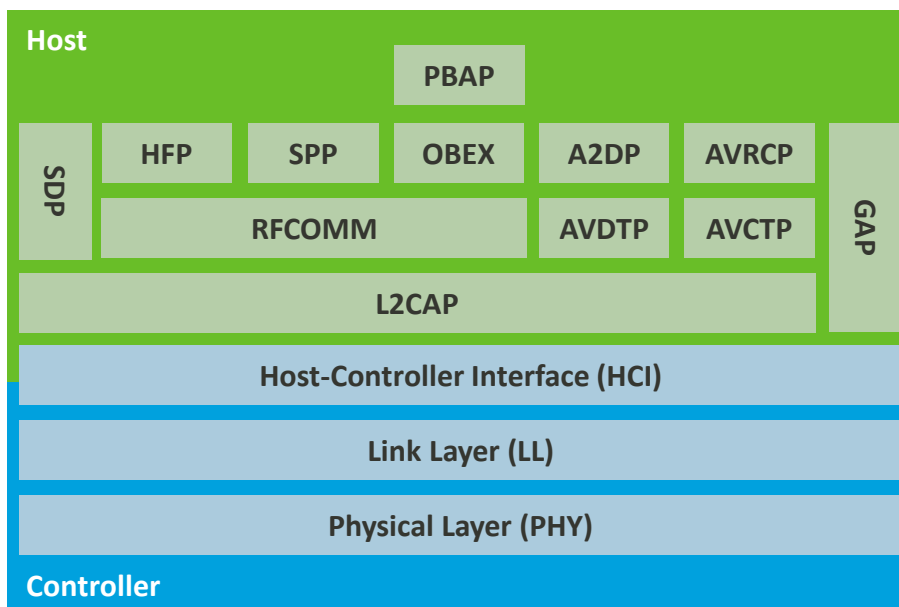
- Support for Bluetooth with the library description and supported reference examples.
- Detailed description of the BR/EDR profiles.
- Bluetooth LE profiles.
- Custom application development and debugging logs.

### 1.1. Bluetooth protocol stack

The Bluetooth protocol stack consists of two sections, the controller and the host, derived from the original Bluetooth core specification where the two sections were often implemented separately.

#### 1.1.1. BR/EDR protocol stack

The BR/EDR protocol stack architecture is illustrated in Figure 1.



**Figure 1. BR/EDR protocol stack**

The controller section includes the Physical Layer (PHY), Link Layer (LL) and Host-Controller Interface (HCI).

- 1) The physical layer (PHY) is the lowest layer of the Bluetooth protocol stack to manage physical channels and links.

- 2) The link layer (LL) is used to control the radio link between two devices, handling matters such as link establishment, querying device abilities and providing power control.
- 3) The host control interface (HCI) provides a means of communication between the host and controller using a standardized interface.

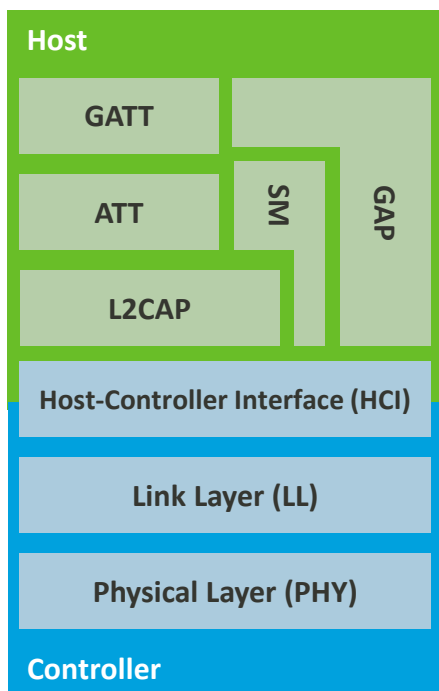
The host includes various communication protocols, as described below.

- 1) The logical link control and adaption protocol (L2CAP) provides data encapsulation services to the upper layers that enable logical end-to-end data communication.
- 2) The radio frequency communication (RFCOMM) is a set of transport protocols on top of the L2CAP protocol, providing emulated RS-232 serial ports.
- 3) The generic access profile (GAP) defines the generic procedures related to discovery of Bluetooth devices and link management aspects of connecting to Bluetooth devices.
- 4) The service discovery protocol (SDP) is used to allow devices to discover the supported services, and parameters to use to connect to them.
- 5) The hands-free profile (HFP) allows hands-free kits to control the mobile phone of calling functions and provide the voice connection between devices.
- 6) The object exchange (OBEX) is a communications protocol that facilitates the exchange of binary objects between devices.
- 7) The phonebook access profile (PBAP) defines the procedures and protocols to exchange phonebook objects between devices.
- 8) The Advanced Audio Distribution Profile (A2DP) defines how multimedia audio is streamed from one device to another via Bluetooth connection
- 9) The audio/video distribution transport protocol (AVDTP) is used by the advanced audio distribution profile to stream music to stereo headsets over the L2CAP channel intended for video distribution profile in the Bluetooth transmission.
- 10) The audio/video control transport protocol (AVCTP) is used to transport the command/response messages exchanged for the control of distant A/V devices over point-to-point connections.
- 11) The audio/video remote control profile (AVRCP) defines the features and procedures required in order to ensure interoperability between Bluetooth devices with audio/video control functions in the audio/video distribution scenarios.
- 12) The serial port profile (SPP) emulates a serial cable to provide a simple substitute for existing RS-232.

### **1.1.2. Bluetooth LE protocol stack**

The Bluetooth LE protocol stack architecture is shown in Figure 2.





**Figure 2. Bluetooth Low Energy protocol stack**

## 2. Support for Bluetooth

The platform includes Airoha IoT SDK v4 that can be extended to develop Bluetooth applications. The controller, host and application are implemented as a true single chip solution to enable cost effective and application development with low power consumption.

The SDK is designed to support custom Bluetooth application development with protocol-layer access to the following:

- GAP
- SDP
- HFP
- A2DP
- AVRCP
- PBAP
- SPP
- GAP LE
- SM
- GATT

For more information on the protocol specifications, refer to the Bluetooth Special Interest Group [website](#).

The SDK includes the following content along with this document:

- Binary libraries
- C header files
- Example applications
- API reference guides

### 2.1. Airoha IoT SDK library

The SDK provides a library file interface to the Bluetooth with C source and header files related to the platform, as shown in Table 1.

**Table 1. Airoha IoT SDK library support for Bluetooth**

Module	File Name	Location	Function
Bluetooth	libbt.a	/middleware/bluetooth/lib/	BR/EDR and Bluetooth LE stack library
	libbtdriver_[chip].a		Bluetooth driver library
	libbt_hfp.a		HFP library
	libbt_a2dp.a		A2DP library
	libbt_avrcp.a		AVRCP library, including the PASS

Module	File Name	Location	Function
			THROUGH command.
	libbt_avrcp_enhance.a		AVRCP library, including all VENDOR DEPENDENT commands.
	libbt_pbapc.a		PBAP library
	libbt_spp.a		SPP library
	bt_platform.h		Interface for Bluetooth tasks
	bt_type.h		Common data types
	bt_system.h		Interface for the system, such as power on or off, memory initiation and callback APIs for event handling.
	bt_uuid.h		Interface for the UUID
	bt_spp.h		Interface for the SPP
	bt_a2dp.h		Interface for the A2DP
	bt_codec.h		Interface for the codec
	bt_hfp.h		Interface for the HFP
	bt_avrcp.h		Interface for the AVRCP
	bt_pbapc.h		Interface for the PBAP client
	bt_gap.h		Interface for the GAP
	bt_sdp.h	/middleware/bluetooth/inc/	Interface for the SDP
	bt_gap_le.h		Interface for the GAP for Bluetooth LE support
	bt_hci_le.h		HCI structures and events for Bluetooth LE support
	bt_gatt.h		GATT UUID
	bt_gattc.h		Interface for the GATT client
	bt_gatts.h		Interface for the GATT server
	bt_att.h		Interface for the Attribute protocol
	bt_os_layer_api.h		Wrapper APIs for RTOS, memory, advanced encryption standard (AES) and rand
	bt_debug.h		Encapsulated debugging interface
	bt_hci_log.h		Encapsulated interface for the HCI logging
	bt_os_layer_api.c		Encapsulated interface for system, memory or AES. Developers can replace the implementation when porting to other platforms.
	bt_debug.c	/middleware/bluetooth/src/	Encapsulated debugging interface. Developers can replace the implementation when porting to other platforms.

Module	File Name	Location	Function
	bt_hci.c		Encapsulated interface for the HCI logging. Developers can replace the implementation when porting to other platforms.
	bt_task.c		The default Bluetooth task entry function.

### 3. The Bluetooth BR/EDR Protocol and Profiles

The Bluetooth support is provided as a collection of binary library files. This section provides details on the GAP, SDP, HFP, A2DP, AVRCP, SPP and PBAP profiles for which application has direct access to the APIs.

#### 3.1. GAP

GAP services include device discovery, connection modes, security, authentication, association models and service discovery. Implement a user-defined API `bt_gap_get_local_configuration()` in your application when turning the Bluetooth on. The GAP profile then calls the function `bt_gap_get_local_configuration()` to get the local configuration from the application.

The purpose of the inquiry is to discover other Bluetooth-enabled devices in general or limited discoverable modes. The purpose of the bonding procedure is to create a connection between two Bluetooth-enabled devices based on a common link key. The link key will be used for future authentication.

The GAP profile provides a user interface, sends related commands to the controller and receives events from the controller, as shown in Figure 3.

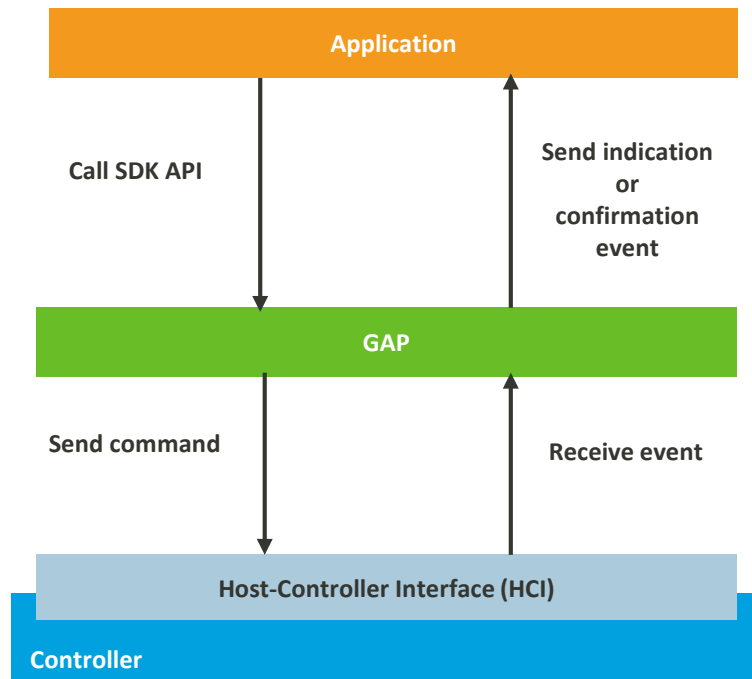


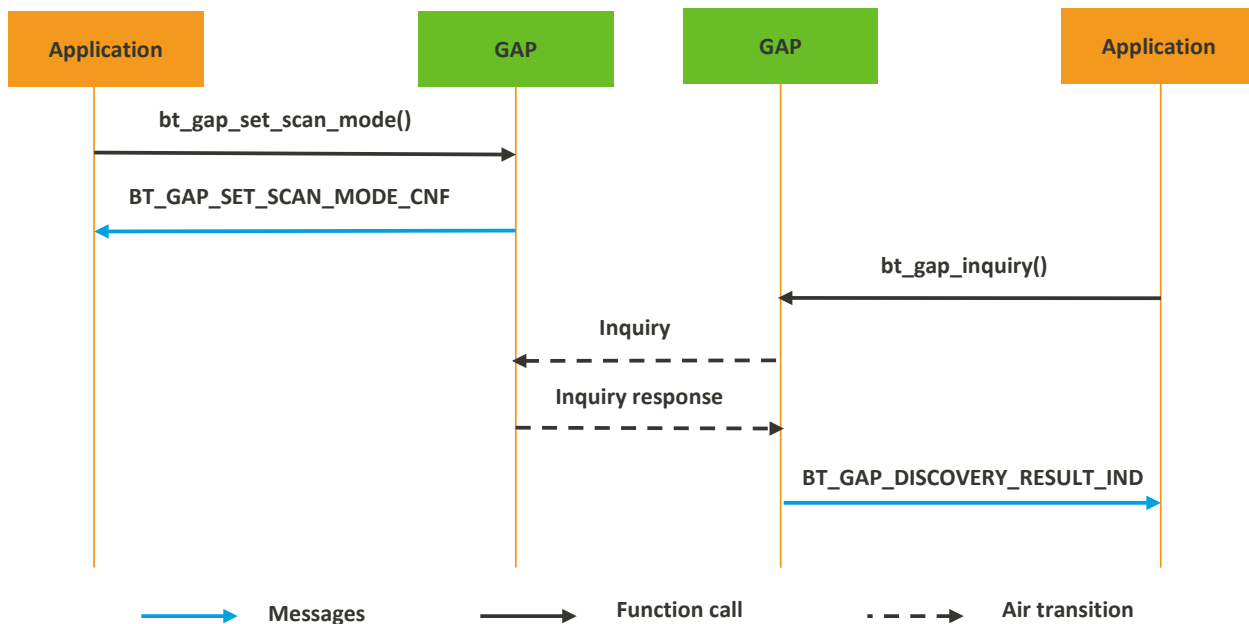
Figure 3. The GAP abstraction layout

#### 3.1.1. The GAP message sequences

This section introduces typical message sequences to provide more details about the events and procedures. For more details, refer to the `bt_gap.h`.

##### 3.1.1.1. Set the scan mode

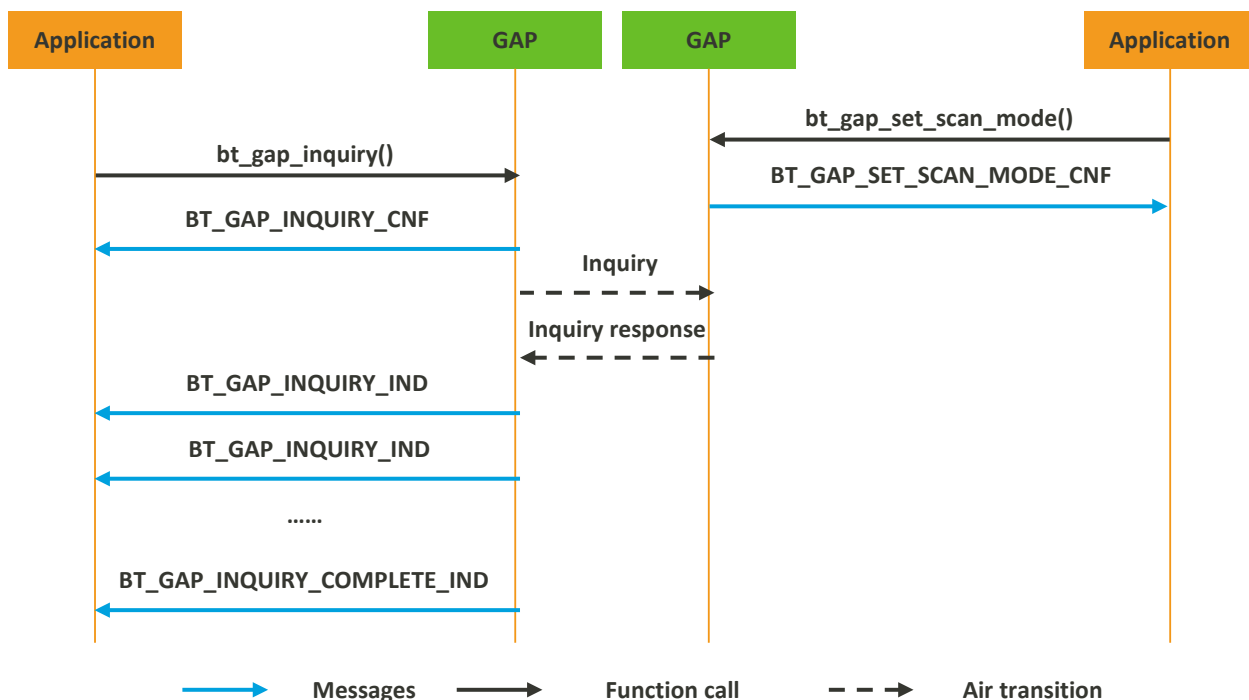
The scan mode controls whether the device can be discovered or connected by other Bluetooth-enabled devices, as shown in Figure 4. If set the scan mode is enabled, the device can be discovered by other Bluetooth devices. If the page scan is enabled, the device can be connected by other Bluetooth devices.



**Figure 4. Set the scan mode message sequence**

### 3.1.1.2. Inquiry

The purpose of the inquiry is to discover other Bluetooth devices in general or limited discoverable mode, as shown in Figure 5.



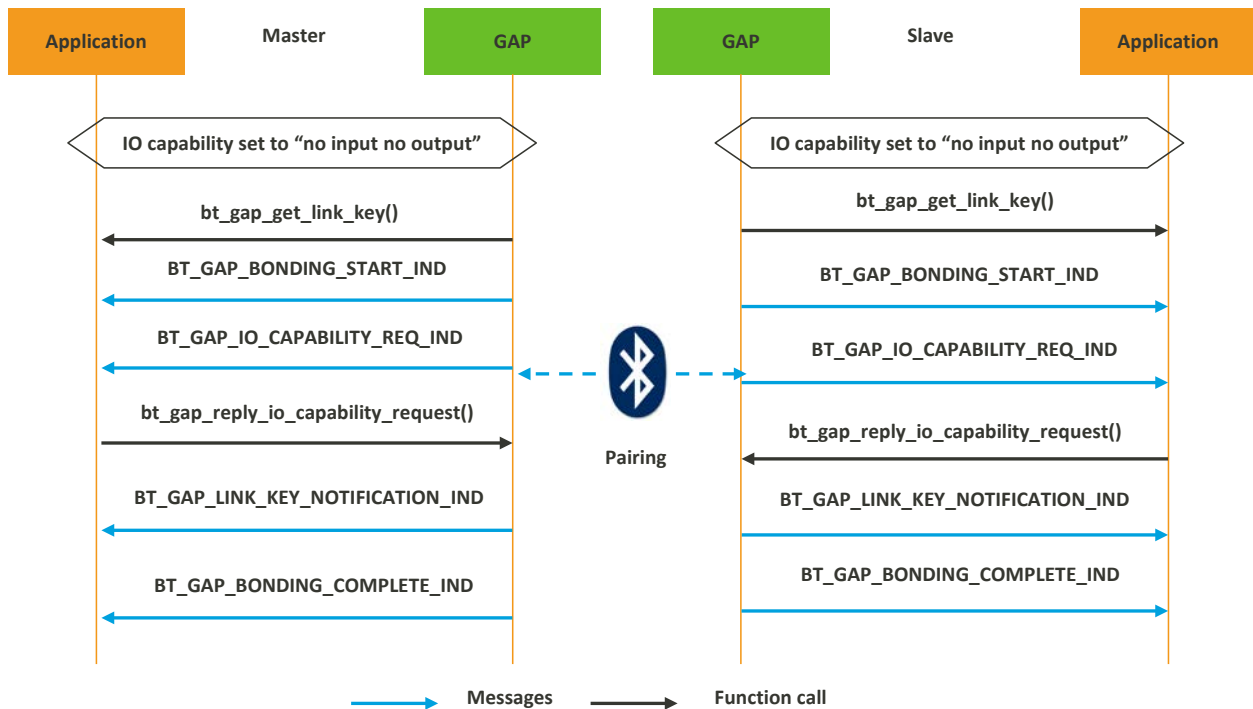
**Figure 5. GAP inquiry message sequence**

### 3.1.1.3. Bonding

The purpose of bonding procedure is to create a connection between two Bluetooth-enabled devices based on a common link key. The application should implement the user-defined API `bt_gap_get_link_key()`. After the

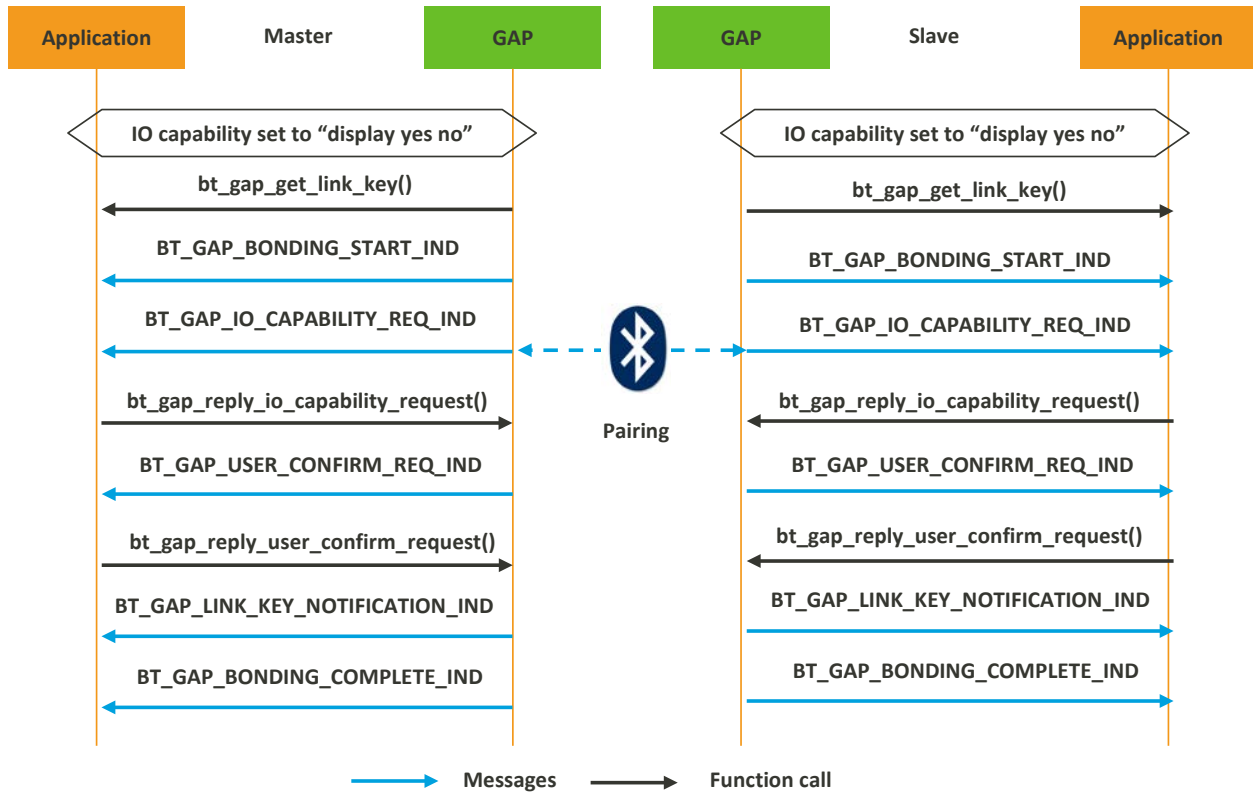
bonding procedure starts, the GAP profile calls the function `bt_gap_get_link_key()` to get the link key from the application. If the link key already exists, proceed to authentication. Otherwise, the application receives `BT_GAP_BONDING_START_IND` event and begins the pairing. After the pairing is complete, the application can store the link key by handling the `BT_GAP_LINK_KEY_NOTIFICATION_IND` event, and `BT_GAP_BONDING_COMPLETE_IND` event will be sent to notify the bonding result. There is no bonding API to start a bonding procedure, it starts when connecting devices with authentication requirement. There are four bonding modes: auto-confirmation, numeric comparison, passkey entry and pin code.

- 1) The auto-confirmation model is applied where the local I/O capability is either `BT_GAP_IO_CAPABILITY_NO_INPUT_NO_OUTPUT` or `BT_GAP_IO_CAPABILITY_DISPLAY_ONLY` and the remote I/O capability isn't `BT_GAP_IO_CAPABILITY_KEYBOARD_ONLY`, as shown in Figure 6.



**Figure 6. Bonding using auto-confirmation message sequence**

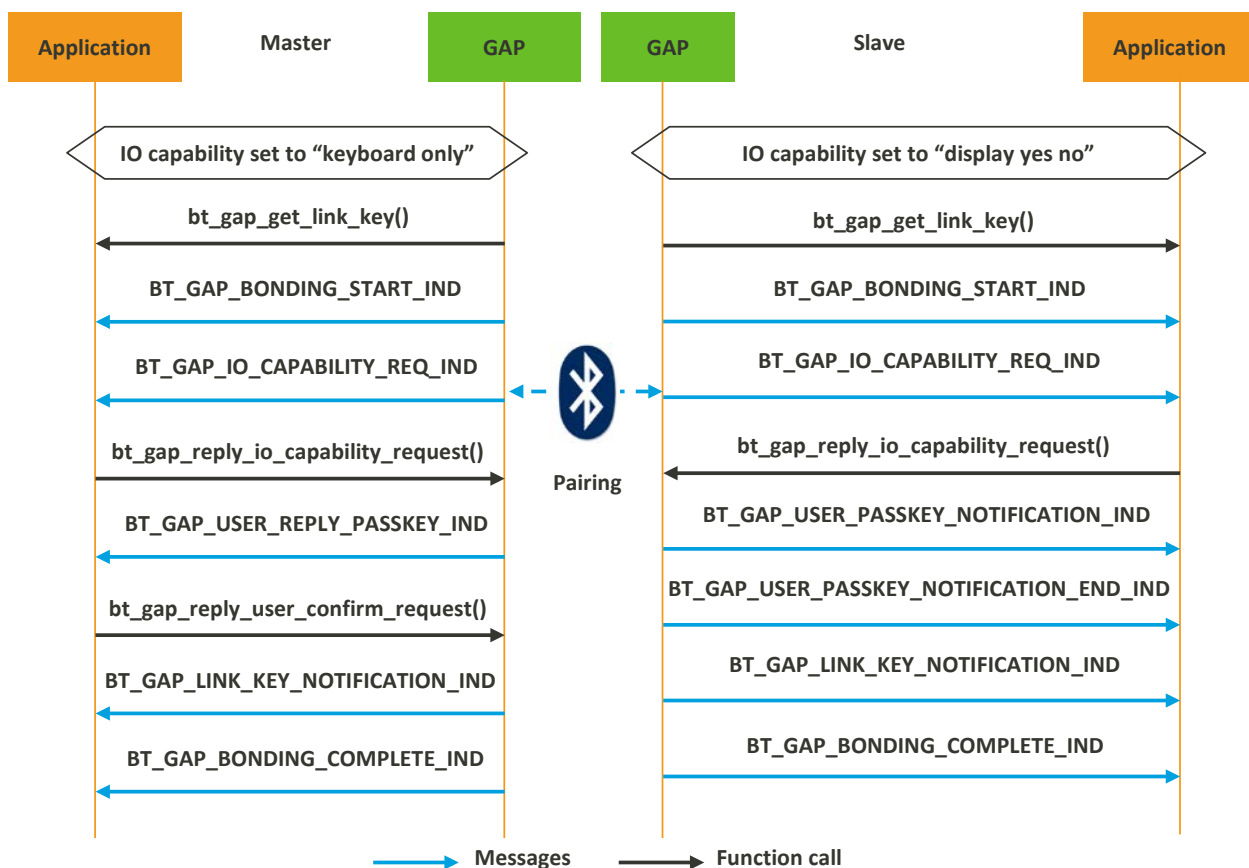
- 2) The numeric comparison model is applied when the local I/O capability is `BT_GAP_IO_CAPABILITY_DISPLAY_YES_NO`, as shown in Figure 7.



**Figure 7. Bonding using numeric comparison message sequence**

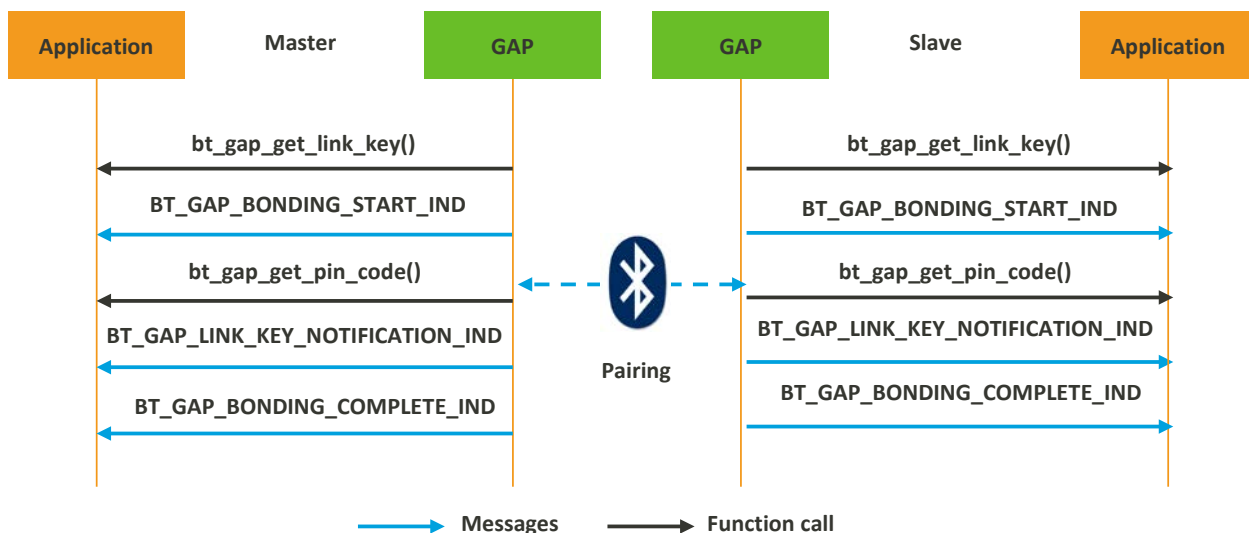
- 3) The passkey entry model is used when one device has input capability but does not have the capability to display six digits and the other device has output capabilities, as shown in Figure 8.





**Figure 8. Bonding using passkey entry message sequence**

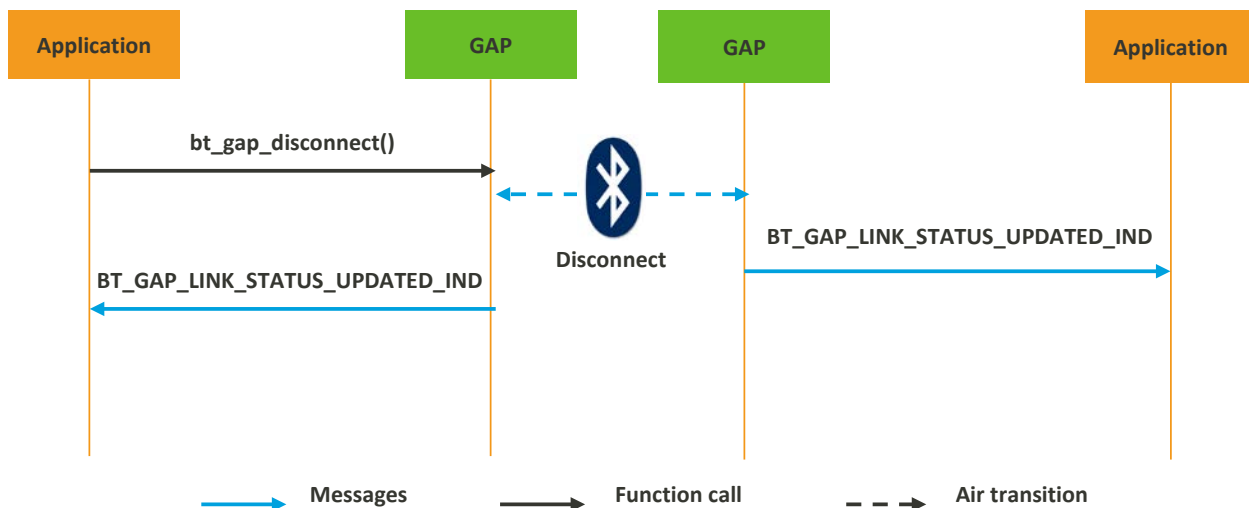
- 4) The pin code model is used when one of the devices doesn't support SSP. The default pin code is "0000", this value can be modified by calling a user-defined API `bt_gap_get_pin_code()`, as shown in Figure 9.



**Figure 9. Bonding using pin code message sequence**

### 3.1.1.4. Disconnect

The disconnect procedure terminates an existing ACL link, as shown in Figure 10.



**Figure 10. GAP disconnect message sequence**

## 3.1.2. Using the GAP APIs

This section describes how to use the GAP profile APIs. An example implementation is shown below.

- 1) Implement the required `bt_app_event_callback()` function to handle the GAP events, see section 3.1.2.1, "Full source code for `bt_app_event_callback()`".
- 2) Implement the required user-defined API `bt_gap_get_link_key()` to provide the link key stored during the last pairing procedure.

```

// The application may store the key in RAM, NVDM or permanent storage.
bt_gap_link_key_notification_ind_t edr_key;
void bt_gap_get_link_key(bt_gap_link_key_notification_ind_t*
key_information)
{
    if (memcmp(key_information->address, edr_key.address, 6) == 0) {
        memcpy(key_information, &edr_key,
sizeof(bt_gap_link_key_notification_ind_t));
    } else {
        // No link key, Do nothing
    }
}
    
```

- 3) Implement the required user-defined API `bt_gap_get_local_configuration()` to provide the GAP profile configuration.

```

static const bt_gap_config_t bt_config_default = {
    .inquiry_mode = 2, // Inquiry result with RSSI format or Extended
Inquiry Result (EIR) format.
    .io_capability = BT_GAP_IO_CAPABILITY_NO_INPUT_NO_OUTPUT,
    .cod = 0x240404, // Audio device type.
    .device_name = {"HB Duo device"},
};

// Define GAP configuration callback, it's invoked when Bluetooth is
powered on.
const bt_gap_config_t* bt_gap_get_local_configuration(void)
{
    return &bt_config_default; // Must return a global variable address.
}
    
```

- 4) Optional, implement the required user-defined API `bt_gap_get_pin_code()` to provide the pin code (default value is "0000").

```
// If local or remote device doesn't support SSP, the pin code pairing is
used.
// Default pin code is "0000", to replace it, implement the function
bt_gap_get_pin_code().
static const bt_gap_pin_code_information_t bt_gap_my_pin_code =
{
    .pin_len = 4,
    .pin_code = {"1234"},
};

const bt_gap_pin_code_information_t* bt_gap_get_pin_code(void)
{
    return &bt_gap_my_pin_code; // Change the pin code from "0000" to
"1234".
}
```

- 5) Call the function `bt_gap_set_scan_mode()` to set the device's scan mode in order to let other devices to discover it.

```
bt_gap_set_scan_mode(BT_GAP_MODE_GENERAL_ACCESSIBLE);
```

- 6) Call the function `bt_gap_inquiry()` to set the device in the inquiry mode to discover the nearby devices.

```
bt_gap_inquiry(10, 0);
```

- 7) Call the function `bt_gap_cancel_inquiry()` to cancel and exit the inquiry mode.

```
bt_gap_cancel_inquiry();
```

- 8) After the link is established, call related `bt_gap_get_remote_address()` to get the address.

```
const bt_bd_addr_t* address = bt_gap_get_remote_address(link_handle);
```

- 9) Call the function `bt_gap_read_remote_name()` to get the name of the remote device.

```
const bt_bd_addr_t address = {0xF1,0x24,0x0,0x22,0x48,0xFE};
bt_gap_read_remote_name(&address);
```

- 10) Call the function `bt_gap_disconnect()` to disconnect the link.

```
bt_gap_disconnect(link_handle);
```

### 3.1.2.1. Full source code for `bt_app_event_callback()`

```
void bt_app_event_callback(bt_msg_type_t msg, bt_status_t status, void
*buff)
{
    switch (msg) {
        case BT_GAP_INQUIRY_CNF:
        {
            if (status == BT_STATUS_SUCCESS) {
                // Inquiry command executes successfully.
            } else {
                // Inquiry command failed.
            }
            break;
        }
    }
}
```

```

case BT_GAP_INQUIRY_IND:
{
    // Find a nearby device.
    bt_gap_inquiry_ind_t* device = (bt_gap_inquiry_ind_t*) buff;
    // Handle the event, example connecting to the device.
    break;
}
case BT_GAP_INQUIRY_COMPLETE_IND:
{
    // Inquiry is complete.
    break;
}
case BT_GAP_SET_SCAN_MODE_CNF:
{
    if (status == BT_STATUS_SUCCESS) {
        // bt_gap_set_scan_mode() executes successfully, it
should be found by nearby devices.
    } else {
        // Setting the scan mode has failed.
    }
    break;
}
case BT_GAP_LINK_STATUS_UPDATED_IND:
{
    bt_gap_link_status_updated_ind_t* param =
(bt_gap_link_status_updated_ind_t*) buff;
    // Handle link status update event.
    if (param->link_status == BT_GAP_LINK_STATUS_DISCONNECTED) {
        // The link is disconnected and it cannot re-connect in
this function callstack.
    } elseif (param->link_status >=
BT_GAP_LINK_STATUS_CONNECTED_0) {
        // The link is connected.
    }
    break;
}
case BT_GAP_BONDING_START_IND:
{
    bt_gap_connection_handle_t* link_handle =
(bt_gap_connection_handle_t*) buff;
    // link_handle is going to bond.
    break;
}
case BT_GAP_IO_CAPABILITY_REQ_IND:
{
    // This event will be received after BT_GAP_BONDING_START_IND
and both devices are support SSP.
    bt_gap_connection_handle_t handle;
    handle = (bt_gap_connection_handle_t)buff;
    // Call bt_gap_reply_io_capability_request() to accept
bonding, or call bt_gap_reject_io_capability_request() to terminate
bonding.
    break;
}
case BT_GAP_USER_CONFIRM_REQ_IND:
{
    // This event will be received after
BT_GAP_IO_CAPABILITY_REQ_IND and IO Capability of both devices are
BT_GAP_IO_CAPABILITY_DISPLAY_YES_NO.

```

```

        // Call bt_gap_reply_user_confirm_request(true) to accept
        bonding, or call bt_gap_reply_user_confirm_request(false) to terminate
        bonding.
        break;
    }
    case BT_GAP_USER_PASKEY_NOTIFICATION_IND:
    {
        // This event will be received after
        BT_GAP_IO_CAPABILITY_REQ_IND, and local IO Capability is
        BT_GAP_IO_CAPABILITY_DISPLAY_ONLY or BT_GAP_IO_CAPABILITY_DISPLAY_YES_NO
        and remote IO Capability is BT_GAP_IO_CAPABILITY_KEYBOARD_ONLY
        // User should display the passkey on the screen.
        uint32_t* passkey = (uint32_t*) buff;
        // Call GDI APIs to show the passkey.
        break;
    }
    case BT_GAP_USER_PASKEY_NOTIFICATION_END_IND:
    {
        // This event will be received after
        BT_GAP_USER_PASKEY_NOTIFICATION_IND.
        // User should stop showing the passkey.
        break;
    }
    case BT_GAP_USER_REPLY_PASKEY_IND:
    {
        // This event will be received after
        BT_GAP_IO_CAPABILITY_REQ_IND, and remote IO Capability is
        BT_GAP_IO_CAPABILITY_DISPLAY_ONLY or BT_GAP_IO_CAPABILITY_DISPLAY_YES_NO
        and local IO Capability is BT_GAP_IO_CAPABILITY_KEYBOARD_ONLY
        // Call bt_gap_reply_passkey_request() to replay the passkey
        before passkey timeout (25 seconds).
        break;
    }
    case BT_GAP_LINK_KEY_NOTIFICATION_IND:
    {
        // This event will be received before
        BT_GAP_BONDING_COMPLETE_IND and bonding success, or the old link key is
        phased out.
        bt_gap_link_key_notification_ind_t * key_info =
        (bt_gap_link_key_notification_ind_t *) buff;
        if (key_info->key_type == BT_GAP_LINK_KEY_TYPE_INVALID) {
            // The old link key is phased out, delete it from
            link key database.
        } else {
            // Save the new link key, and key_type to link key data
            base.
        }
        break;
    }
    case BT_GAP_BONDING_COMPLETE_IND:
    {
        // Bonding is complete.
        if (status == BT_STATUS_SUCCESS) {
            // Bonding completed successfully.
        } else {
            // An error occurred.
        }
        break;
    }
}

```

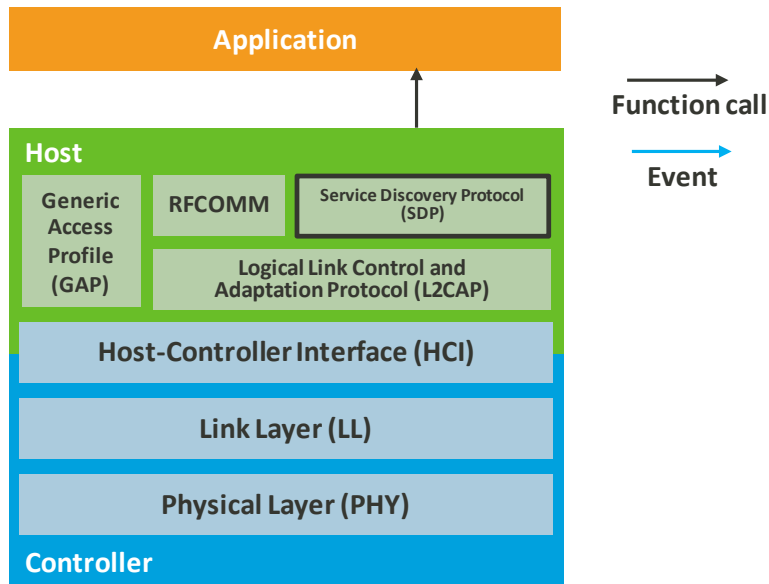
```

    default:
    break;
}

```

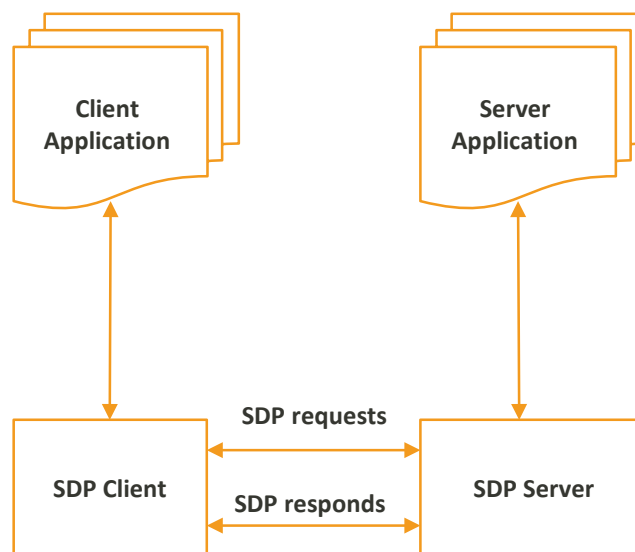
### 3.2. SDP

Service Discovery Protocol is used to locate the available services of the remote device and manage the local available services, as shown in Figure 11.



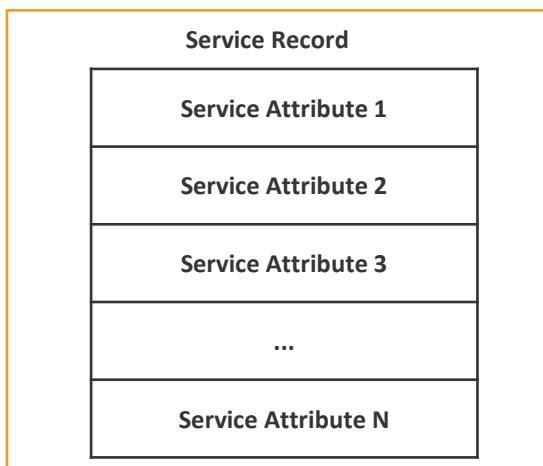
**Figure 11. SDP abstraction layout**

SDP is a client-server architecture shown in Figure 12. The client implementation is included in the profiles in the Bluetooth stack and it's not available to the user. On the other hand, the user can customize service records on the server.



**Figure 12. SDP client-server architecture**

A service record in the SDP server contains a list of service attributes, as shown in Figure 13.

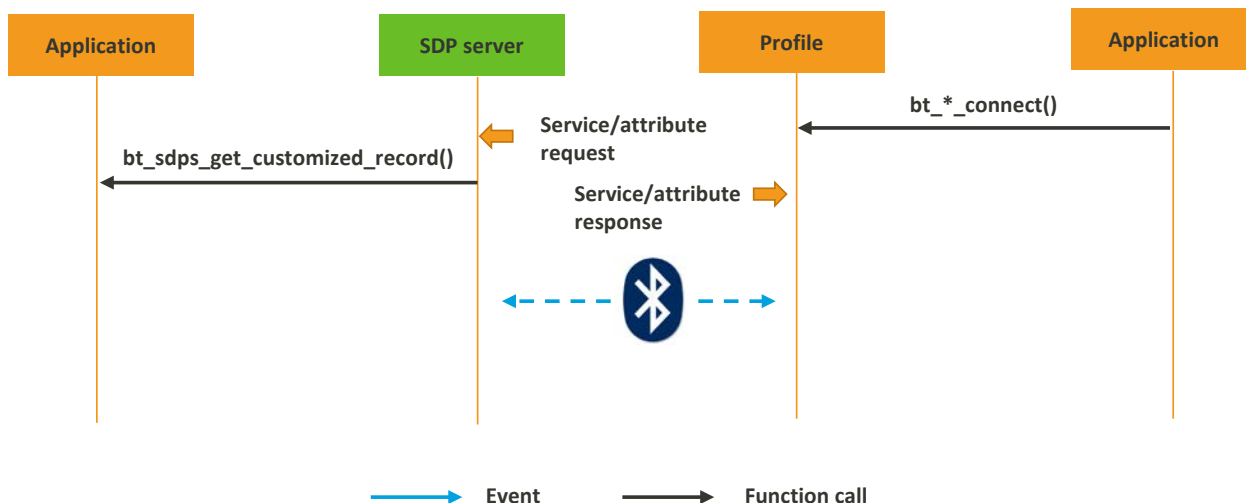


**Figure 13. SDP service record**

### 3.2.1. The SDP message sequences

The SDP API headers can be found in the `bt_sdp.h` header file with only one interface API `bt_sdps_get_customized_record()`. It's mandatory to implement this function if any customized service record needs to be discovered by a remote device.

The application on the remote device usually checks if the specific profile is supported on a peer device by sending an SDP query before it connects. In this case, the SDP acts as a server and calls `bt_sdps_get_customized_record()` from the Bluetooth stack to check if there is any customized record, as shown in Figure 14.



**Figure 14. SDP server role**

### 3.2.2. Add a customized record

Here is an example (see section 3.2.2.1, “Full source code to add a custom record”) to add a custom record that contains the service name, language list, service class ID list and protocol description list for a sample profile. Add your own record according to the SDP profile specification. For more information about the service attributes, refer to the [Bluetooth core specifications version 4.2](#) [VOL 3, part B, chapter 5]. More details about the API can be found in the header file `bt_sdp.h`.

Details of an example are explained below.

- 1) Define a service name with a given length.

```
static const uint8_t bt_sample_service_name[] =
{
    BT_SDP_TEXT_8BIT(7), // The string length of the service name.
    'S', 'a', 'm', 'p', 'l', 'e', '\0'
};
```

- 2) Define a sample language for the profile.

- a) In this example, each item is 3 bytes and the total length of the list items is 9 bytes.
- b) The language is defined as "en". A language identifier represents natural language. Please refer to the ISO 639:1988 (E/F): "Code for the representation of names of languages" and [ISO 639 Codes \(Names of Languages\)](#).
- c) The encoding is defined as UTF-8, a character encoding identifier that can be found in IANA'S database and the [Character Sets](#).
- d) Define a base attribute ID for the natural language in the service record.

```
static const uint8_t bt_sample_language_list[] =
{
    BT_SDP_ATTRIBUTE_HEADER_8BIT(9),
    BT_SDP_UINT_16BIT(0x656E),
    BT_SDP_UINT_16BIT(0x006A),
    BT_SDP_UINT_16BIT(0x0100)
};
```

- 3) Define the service class ID. In this example, each item is 3 bytes and the total length of the following list items is 6 bytes (see BT\_SDP\_ATTRIBUTE\_HEADER\_8BIT(6)).

```
static const uint8_t bt_sample_service_class_id_list[] =
{
    BT_SDP_ATTRIBUTE_HEADER_8BIT(6),
    BT_SDP_UUID_16BIT(BT_SDP_SERVICE_CLASS_HANDSFREE),
    BT_SDP_UUID_16BIT(BT_SDP_SERVICE_CLASS_GENERIC_AUDIO)
};
```

- 4) Define the attribute header for a protocol RFCOMM.

```
static const uint8_t bt_sample_protocol_description_list[] =
{
    BT_SDP_ATTRIBUTE_HEADER_8BIT(12), // The total length of all list items
    // is 12 bytes.

    BT_SDP_ATTRIBUTE_HEADER_8BIT(3), // The total length of the following
    // list item is 3 bytes.
    BT_SDP_UUID_16BIT(BT_SDP_PROTOCOL_L2CAP),

    BT_SDP_ATTRIBUTE_HEADER_8BIT(5), // The total length of the following
    // two list items is 5 bytes.
    BT_SDP_UUID_16BIT(BT_SDP_PROTOCOL_RFCOMM),
    BT_SDP_UINT_8BIT(0x01)
};
```

- 5) Define the SDP protocol attributes.



In this example the service name must add a base attribute ID, default value is 0x0100 (see `BT_SDP_ATTRIBUTE(BT_SDP_ATTRIBUTE_ID_SERVICE_NAME+0x0100, bt_sample_service_name)` depending on your profile.

```
static const bt_sdps_attribute_t bt_sample_sdp_attributes[] =
{
    BT_SDP_ATTRIBUTE(BT_SDP_ATTRIBUTE_ID_SERVICE_CLASS_ID_LIST,
bt_sample_service_class_id_list),
    BT_SDP_ATTRIBUTE(BT_SDP_ATTRIBUTE_ID_PROTOCOL_DESC_LIST,
bt_sample_protocol_description_list),
    BT_SDP_ATTRIBUTE(BT_SDP_ATTRIBUTE_ID_LANG_BASE_ID_LIST,
bt_sample_language_list),
    BT_SDP_ATTRIBUTE(BT_SDP_ATTRIBUTE_ID_SERVICE_NAME+0x0100,
bt_sample_service_name)
};
```

6) Create an attribute list with records.

```
static const bt_sdps_record_t bt_sample_sdp_record =
{
    .attribute_list_length = sizeof(bt_sample_sdp_attributes),
    .attribute_list = bt_sample_sdp_attributes,
};
```

7) Define an SDP sample record.

```
static const bt_sdps_record_t *sdps_sample_record[] = {
    &bt_sample_sdp_record,
};
```

8) Get a customized record.

This API invoked by the SDK process should be implemented by the application. If no records to be found by the remote device, set the `record_list` to NULL and return 0.

```
uint8_t bt_sdps_get_customized_record(const bt_sdps_record_t ***
record_list)
{
    *record_list = &sdps_sample_record;
    return sizeof(sdps_sample_record)/sizeof(bt_sdps_record_t*);
}
```

### 3.2.2.1. Full source code to add a custom record

```
static const uint8_t bt_sample_service_name[] =
{
    BT_SDP_TEXT_8BIT(7), // The string length of the service name.
    'S', 'a', 'm', 'p', 'l', 'e', '\0'
};

static const uint8_t bt_sample_language_list[] =
{
    BT_SDP_ATTRIBUTE_HEADER_8BIT(9),
    BT_SDP_UINT_16BIT(0x656E),
    BT_SDP_UINT_16BIT(0x006A),
    BT_SDP_UINT_16BIT(0x0100)
};
```

```
static const uint8_t bt_sample_service_class_id_list[] =
{
    BT_SDP_ATTRIBUTE_HEADER_8BIT(6),
    BT_SDP_UUID_16BIT(BT_SDP_SERVICE_CLASS_HANDSFREE),
    BT_SDP_UUID_16BIT(BT_SDP_SERVICE_CLASS_GENERIC_AUDIO)
};

static const uint8_t bt_sample_protocol_description_list[] =
{
    BT_SDP_ATTRIBUTE_HEADER_8BIT(12),
    BT_SDP_ATTRIBUTE_HEADER_8BIT(3),
    BT_SDP_UUID_16BIT(BT_SDP_PROTOCOL_L2CAP),
    BT_SDP_ATTRIBUTE_HEADER_8BIT(5),
    BT_SDP_UUID_16BIT(BT_SDP_PROTOCOL_RFCOMM),
    BT_SDP_UINT_8BIT(0x01)
};

static const bt_sdps_attribute_t bt_sample_sdp_attributes[] =
{
    BT_SDP_ATTRIBUTE(BT_SDP_ATTRIBUTE_ID_SERVICE_CLASS_ID_LIST,
bt_sample_service_class_id_list),
    BT_SDP_ATTRIBUTE(BT_SDP_ATTRIBUTE_ID_PROTOCOL_DESC_LIST,
bt_sample_protocol_description_list),
    BT_SDP_ATTRIBUTE(BT_SDP_ATTRIBUTE_ID_LANG_BASE_ID_LIST,
bt_sample_language_list),

    BT_SDP_ATTRIBUTE(BT_SDP_ATTRIBUTE_ID_SERVICE_NAME+0x0100,
bt_sample_service_name)
};

static const bt_sdps_record_t bt_sample_sdp_record =
{
    .attribute_list_length = sizeof(bt_sample_sdp_attributes),
    .attribute_list = bt_sample_sdp_attributes,
};

static const bt_sdps_record_t *sdps_sample_record[] = {
    &bt_sample_sdp_record,
};

uint8_t bt_sdps_get_customized_record(const bt_sdps_record_t ***
record_list)
{
    *record_list = &sdps_sample_record;
    return sizeof(sdps_sample_record)/sizeof(bt_sdps_record_t*);
}
```

### 3.3. HFP

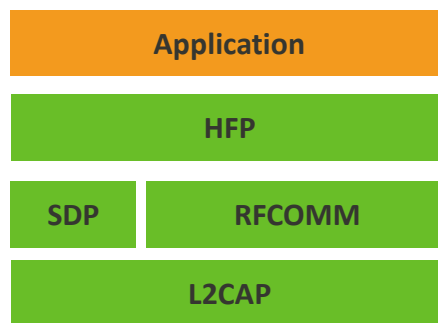
The profile defines details on how two devices supporting HFP interact on a point-to-point basis. An implementation of the HFP typically enables a headset or an embedded hands-free unit to connect wirelessly to a cellular phone for the purposes of acting as the cellular phone's audio input and output and allowing typical telephony functions to be performed without access to the actual phone.

The following roles are defined for this profile:

- **Audio Gateway (AG)** — a device that acts as input and output gateway of the audio. Typical devices acting as AG are cellular phones.
- **Hands-Free unit (HF)** — a device that acts as the AG's remote audio input and output. It also provides remote control capabilities.



Note: Only the HF role is supported in the Airoha IoT SDK v4.



**Figure 15. HFP abstraction layout**

The HFP depends on RFCOMM, which defines procedures required to send and receive files between two Bluetooth-enabled devices. HFP APIs are called in the **Application** to implement the features related to the HFP.

The HF is responsible for HFP connection management, audio connection management and call related action handling.

### 3.3.1. HFP message sequences

The HFP procedure can be established using the message sequence. The message sequence for each process is described below.

- Connection establishment
- Connection release
- Initiate an outgoing voice call
- Audio connection setup
- Audio connection release
- Enable or disable the voice recognition
- Incoming call actions
- Three way call handling
- Remote speaker volume control
- Remote microphone volume control
- Transmit DTMF codes
- Remote speaker volume control

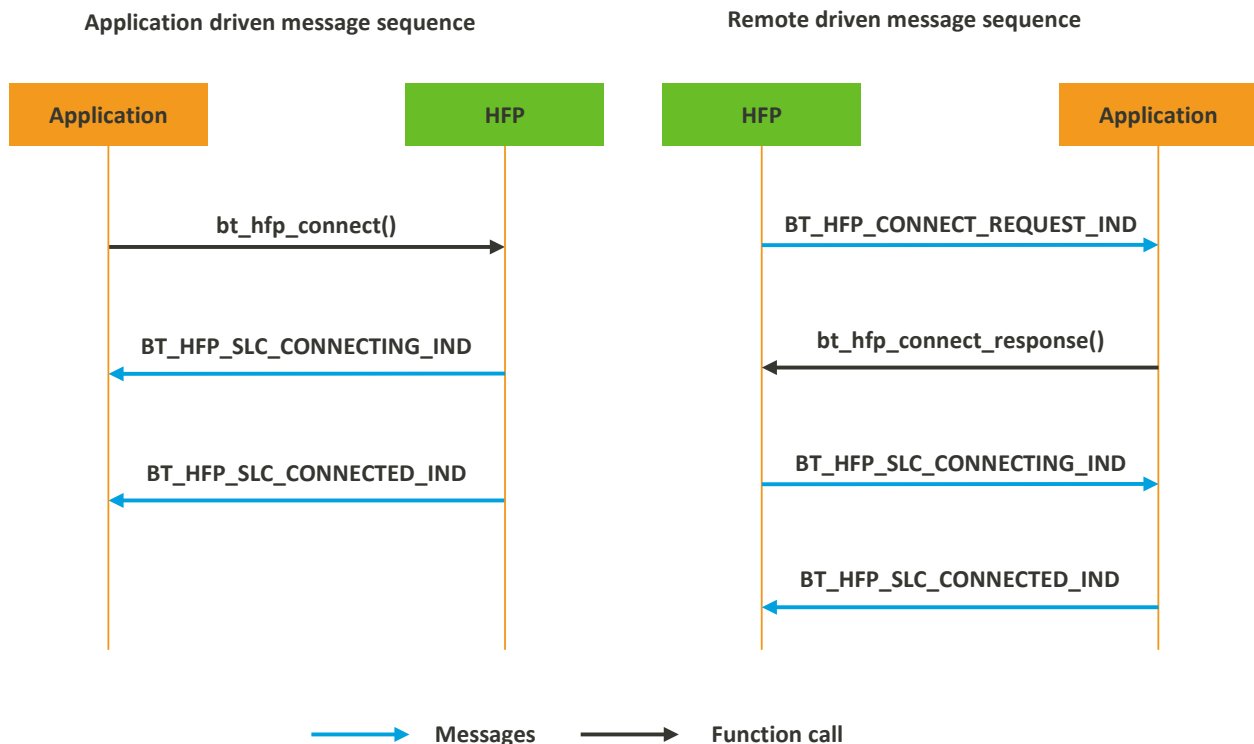
## 3.3.1.1. Connection establishment

Apply this process to establish HFP connection between devices, as shown in Figure 16. The SDK provides two different message sequences; either application driven or remote device driven. For more details, refer to the header file `bt_hfp.h`.

```
bt_status_t status;
uint32_t hfp_handle;

status = bt_hfp_connect(&hfp_handle, bt_addr);

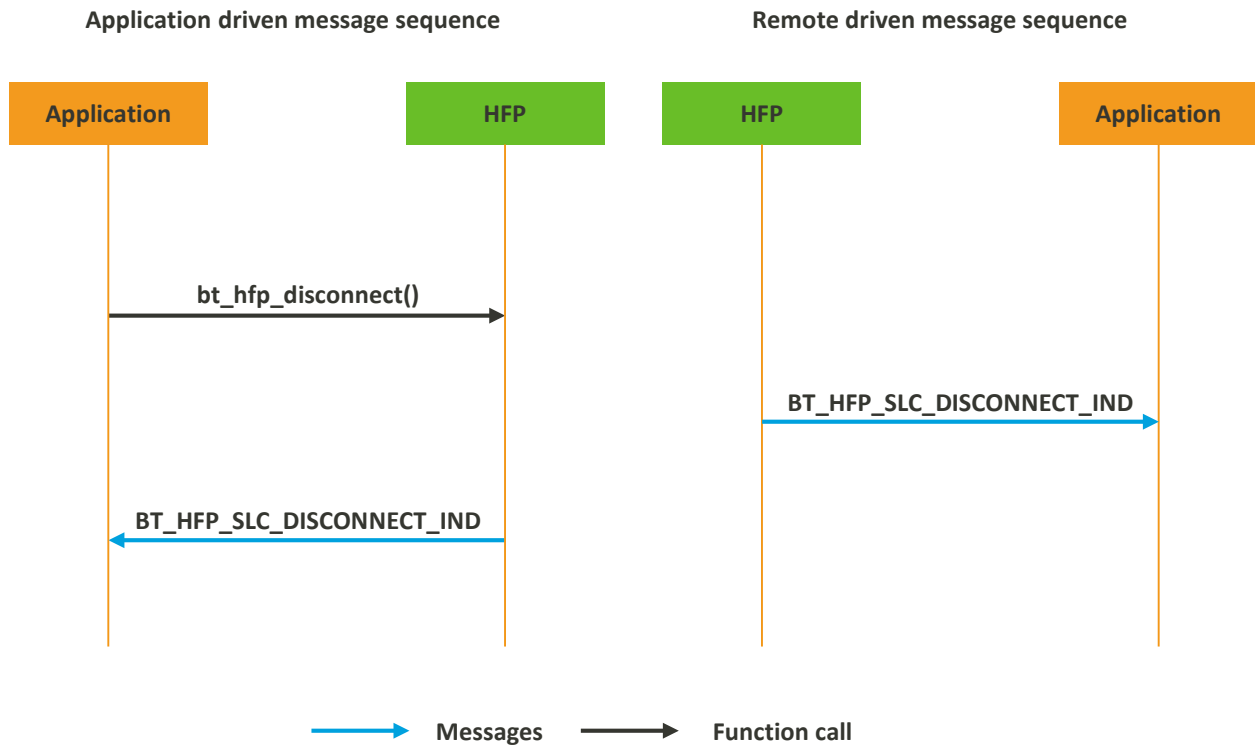
bt_status_t bt_app_event_callback(bt_msg_type_t msg, bt_status_t status,
void *buff)
{
    switch (msg) {
        case BT_HFP_SLC_CONNECTING_IND:
        {
            break;
        }
        case BT_HFP_SLC_CONNECTED_IND:
        {
            break;
        }
    }
    return BT_STATUS_SUCCESS;
}
```



**Figure 16. HFP connection establishment message sequence**

## 3.3.1.2. Connection release

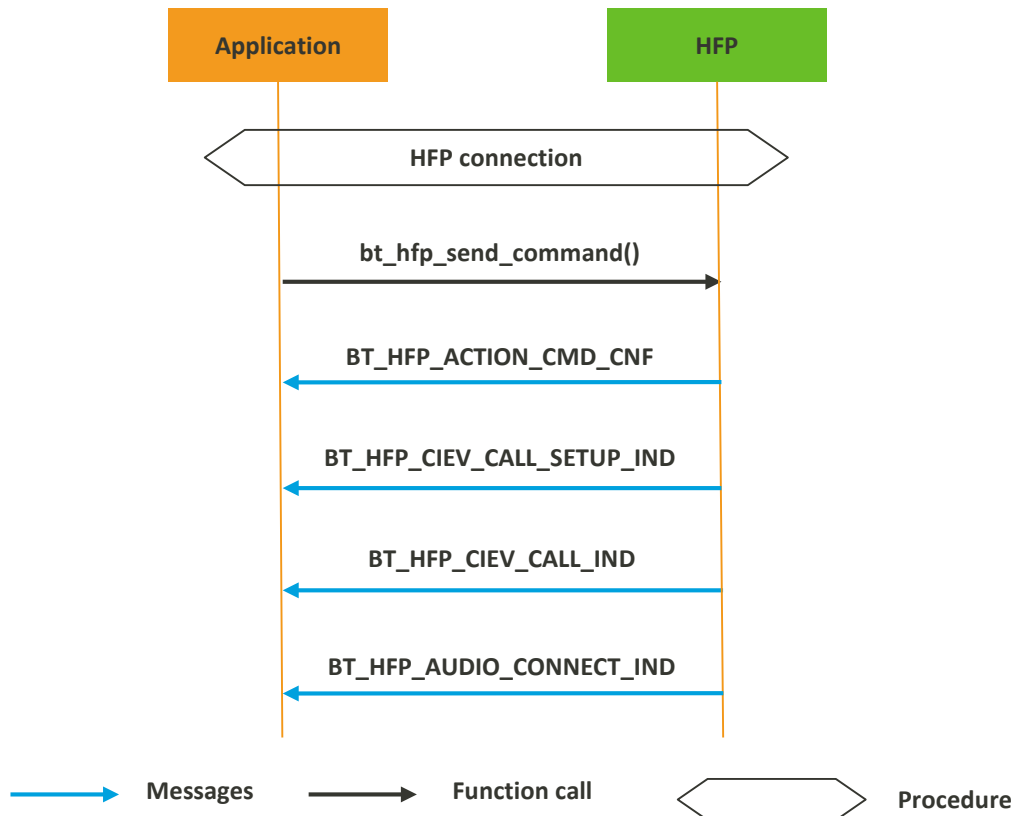
Apply this procedure to release the HFP connection, as shown in Figure 17. The SDK provides two different message sequences; either application driven or remote device driven. For more details, refer to the `bt_hfp.h`.



**Figure 17. HFP connection release message sequence**

## 3.3.1.3. Initiate an outgoing voice call

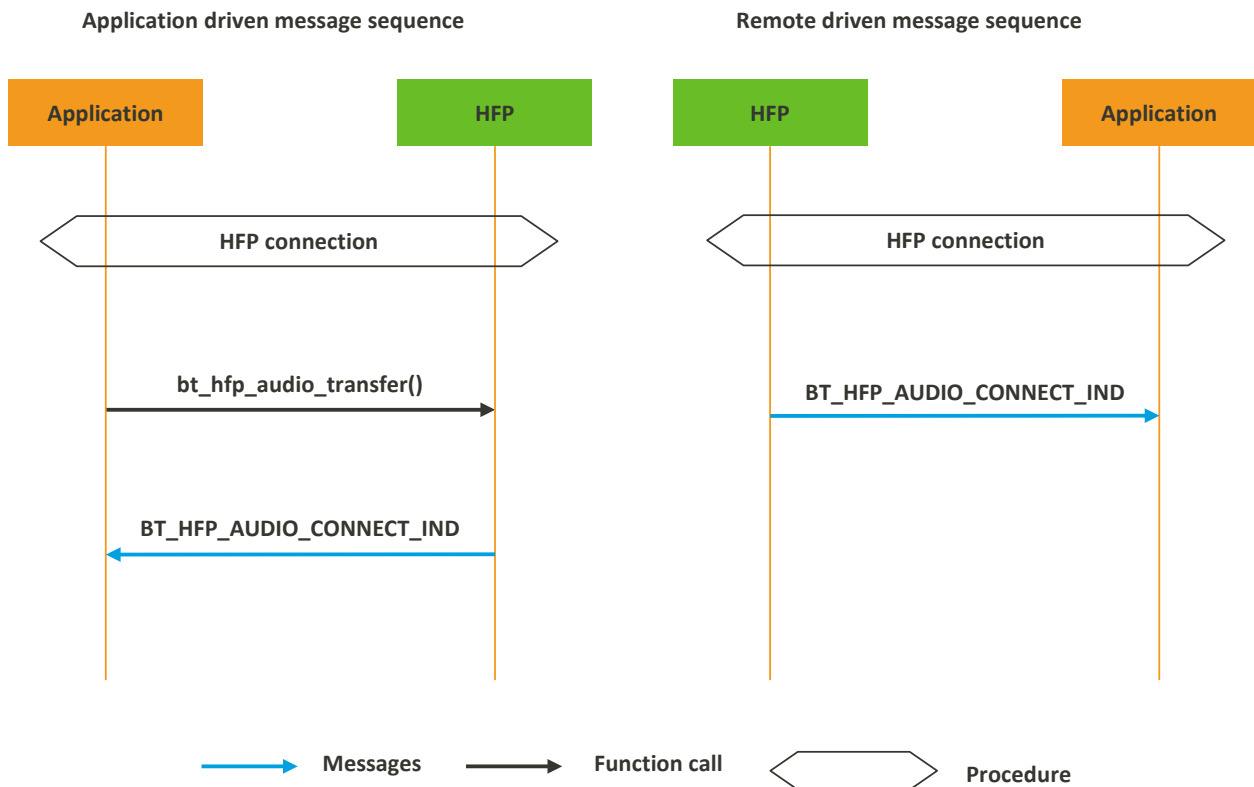
Apply this procedure to initiate an outgoing voice call from the HF. Application uses the API `bt_hfp_send_command()` and passes the command "ATDnnn", (where nnn is the phone number to dial) to make an outgoing call, as shown in Figure 18. For more details, refer to the `bt_hfp.h` and HFP specification version 1.6.



**Figure 18. Initiate an outgoing voice call message sequence**

#### 3.3.1.4. Audio connection setup

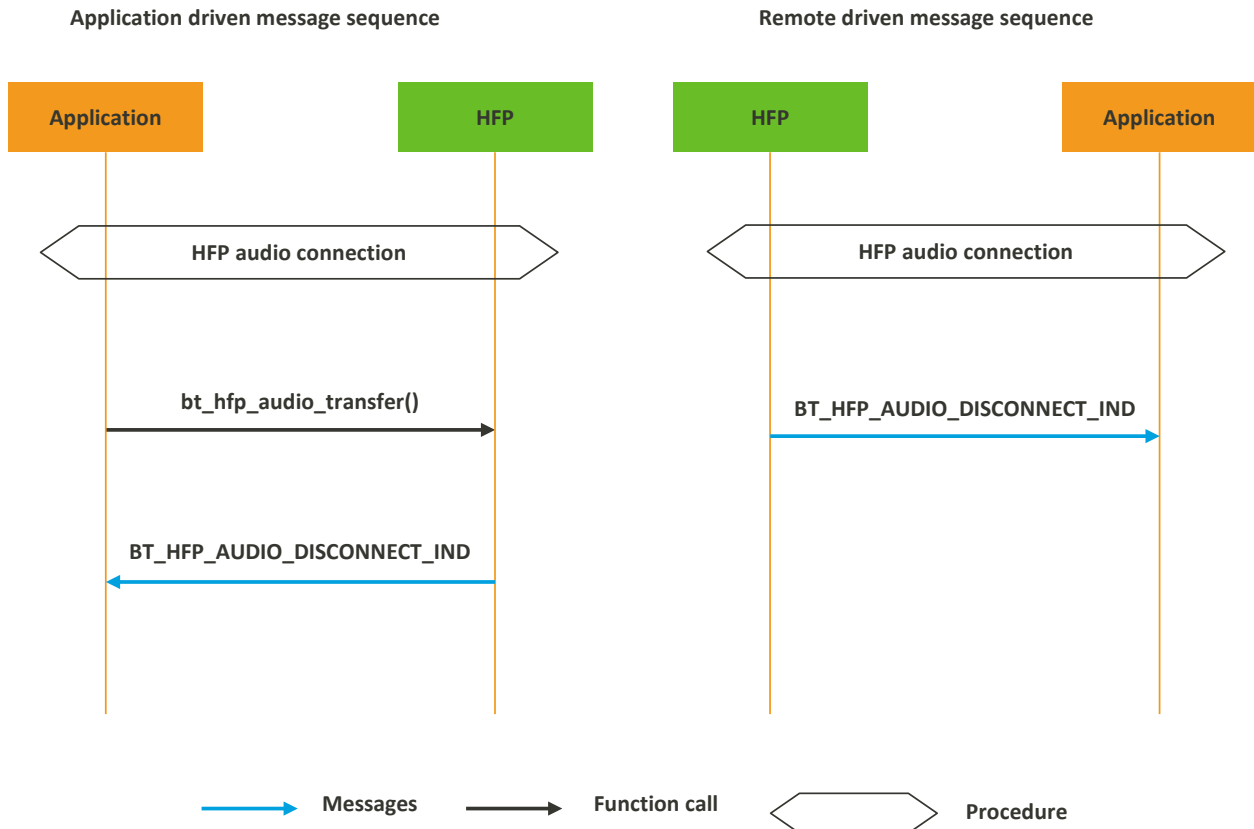
Apply this procedure to create an SCO link, as shown in Figure 19. The SDK provides two different message sequences; either application driven or remote device driven. The application driven message sequence uses the API `bt_hfp_audio_transfer()` and passes the director parameter of "BT\_HFP\_AUDIO\_TO\_HF" to create audio connection. For more details, refer to the `bt_hfp.h` and HFP specification version 1.6.



**Figure 19. Audio connection setup message sequence**

### 3.3.1.5. Audio connection release

Apply this process to release the SCO link, as shown in Figure 20. The SDK provides two different message sequences; either application driven or remote device driven. The application driven message sequence uses the API `bt_hfp_audio_transfer()` and passes the director parameter of "BT\_HFP\_AUDIO\_TO\_AG" to release the audio connection. For more details, refer to the `bt_hfp.h` and HFP specification version 1.6.

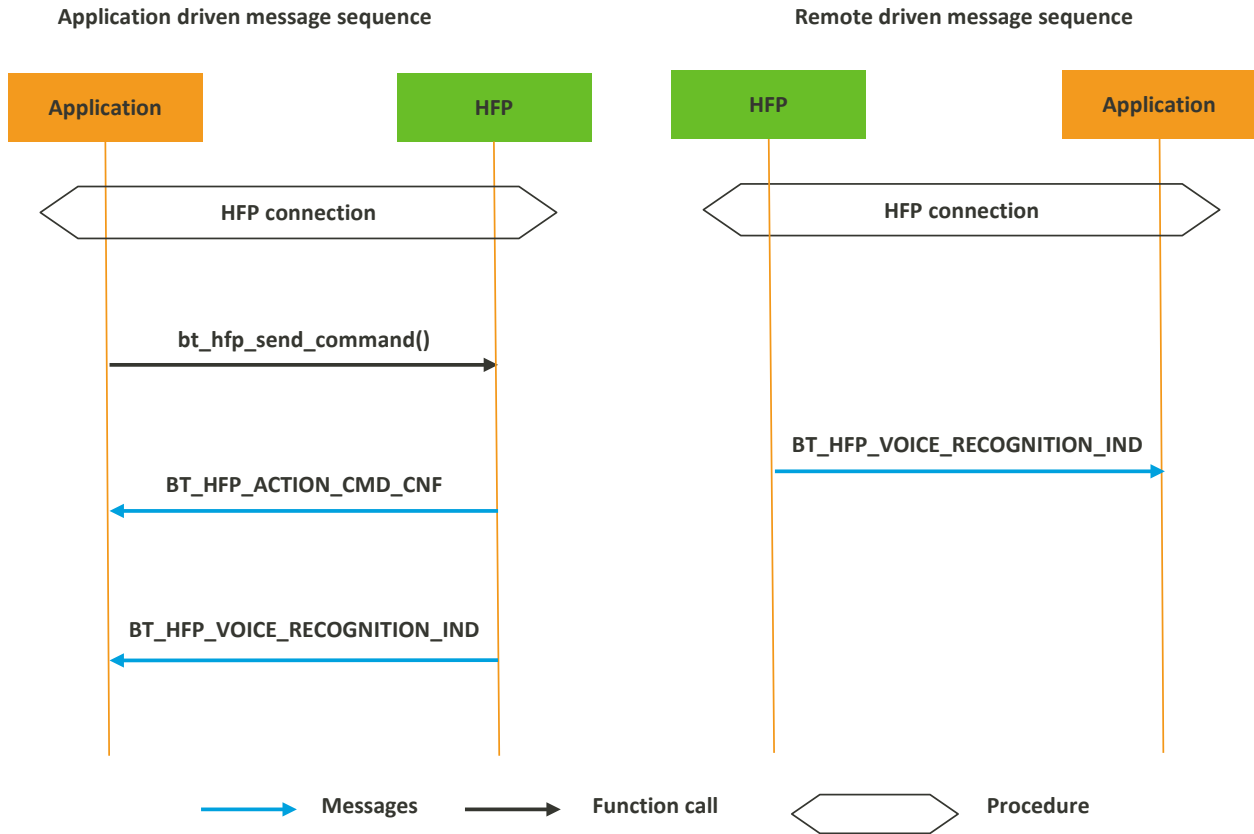


**Figure 20. Audio connection release message sequence**

### 3.3.1.6. Enable or disable the voice recognition

Apply this process to enable or disable voice recognition, as shown in Figure 21. The SDK provides two different message sequences; either application driven or remote device driven. The application driven message sequence uses the API `bt_hfp_send_command()` and passes the command "AT+BVRA=1" or "AT+BVRA=0" to enable or disable the voice recognition. For more details, refer to the `bt_hfp.h` and HFP specification version 1.6.

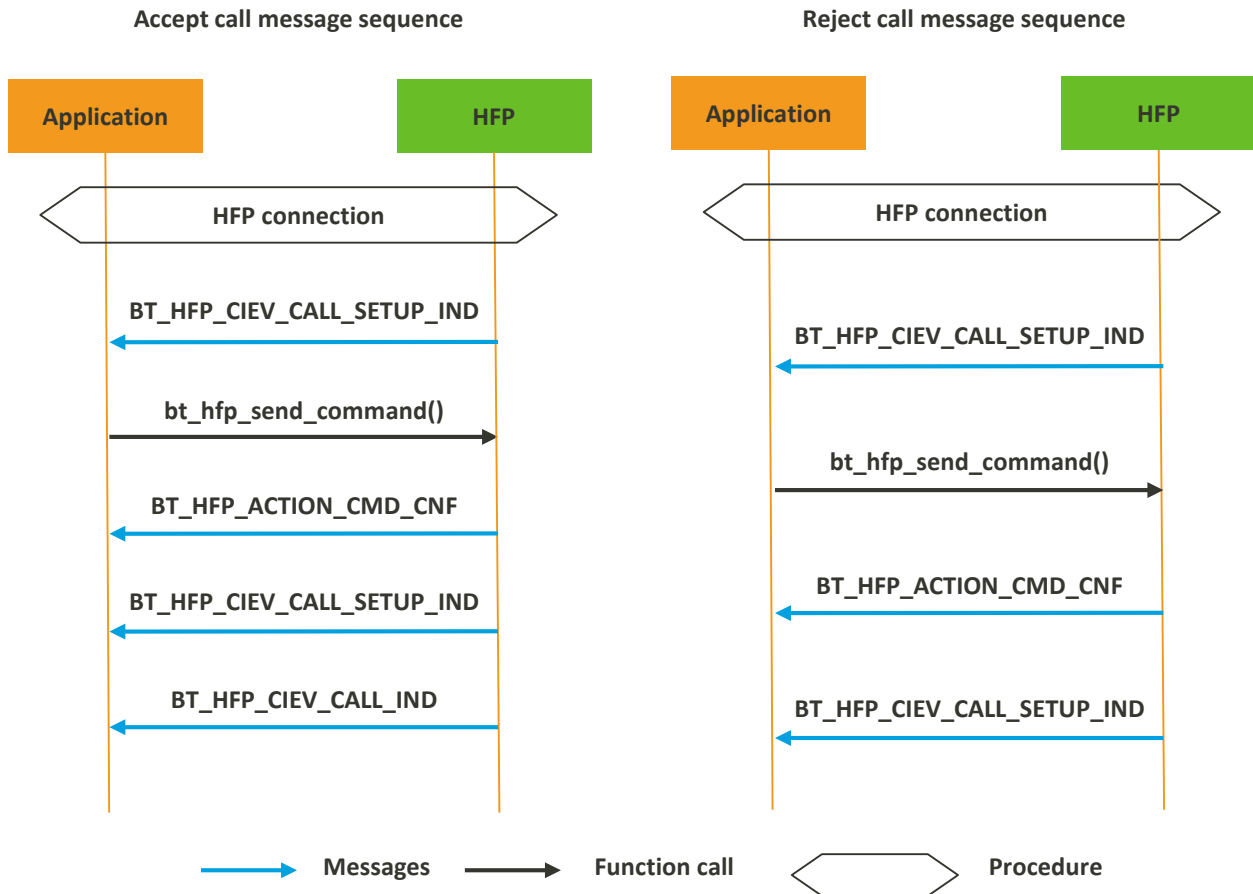




**Figure 21. Enable or disable the voice recognition message sequence**

### 3.3.1.7. Incoming call actions

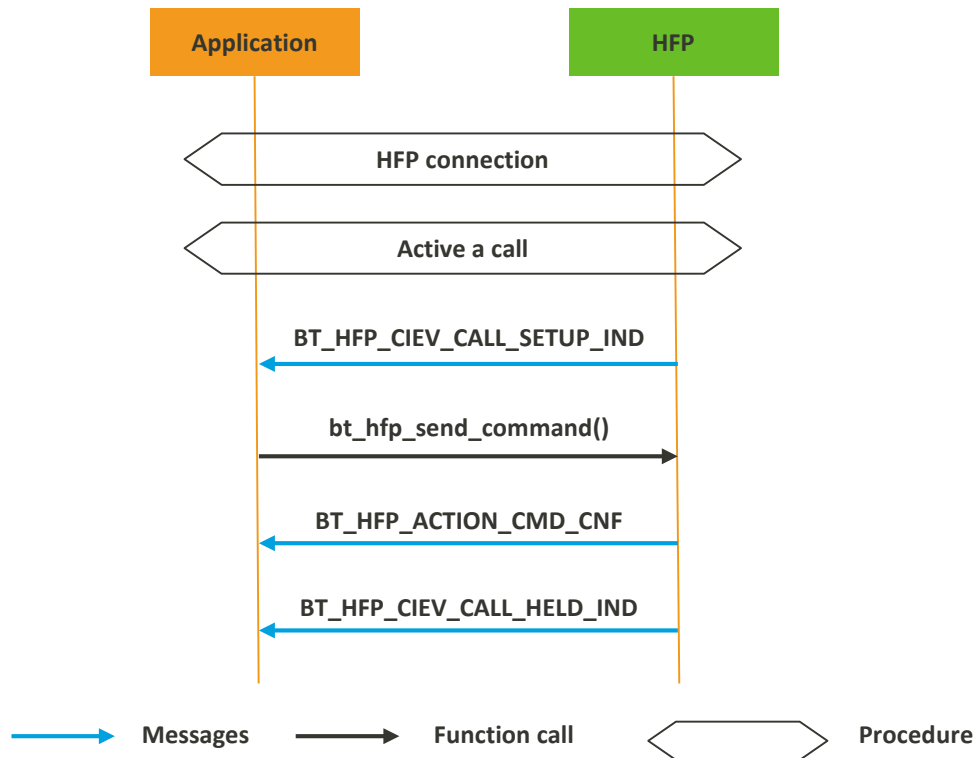
Apply this procedure to accept or reject an incoming call, as shown in Figure 22. Application uses the API `bt_hfp_send_command()` and passes the command "ATA" or "AT+CHUP" to accept or reject the incoming call. For more details, refer to the `bt_hfp.h` and HFP specification version 1.6.



**Figure 22. The actions of an incoming call message sequence**

### 3.3.1.8. Three way call handling

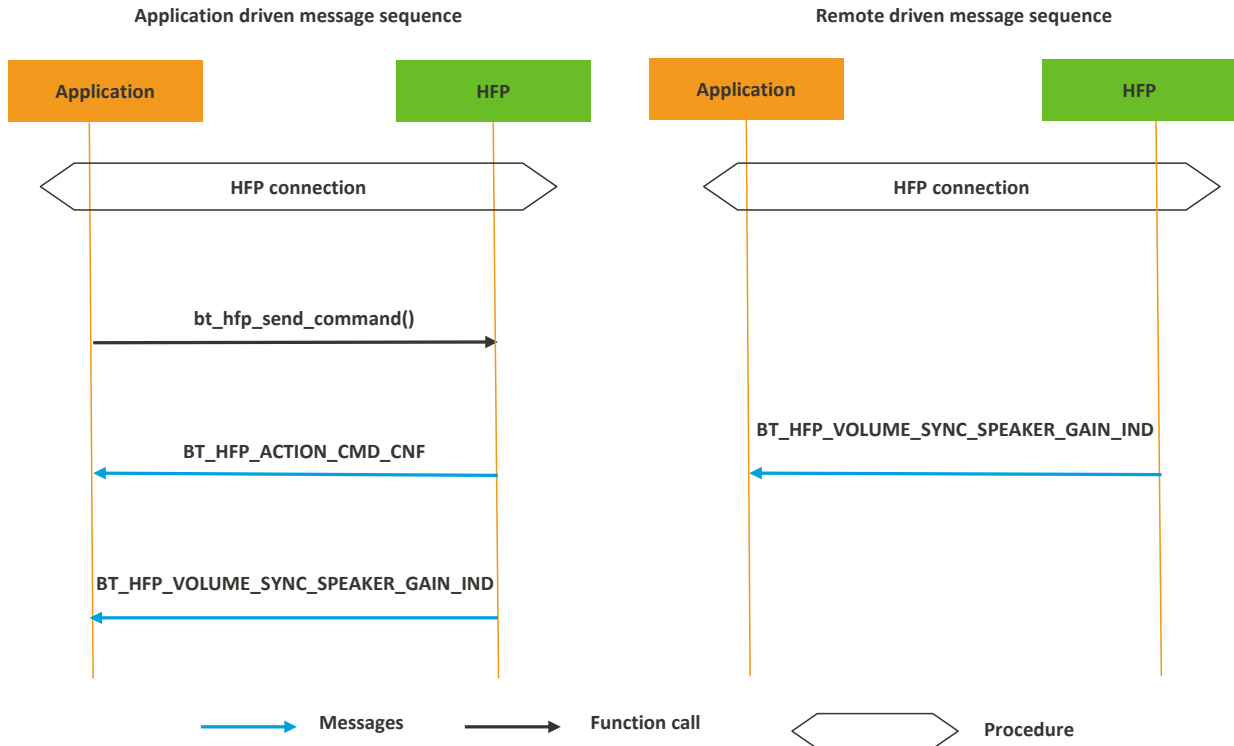
Apply this process to hold the call, as shown in Figure 23. The application calls `bt_hfp_send_command()` and passes the command "AT+CHLD=0" or "AT+CHLD=1" or any other command to make the call hold actions. For more details, refer to the `bt_hfp.h` and HFP specification version 1.6.



**Figure 23. The three way call handling message sequence**

### 3.3.1.9. Remote speaker volume control

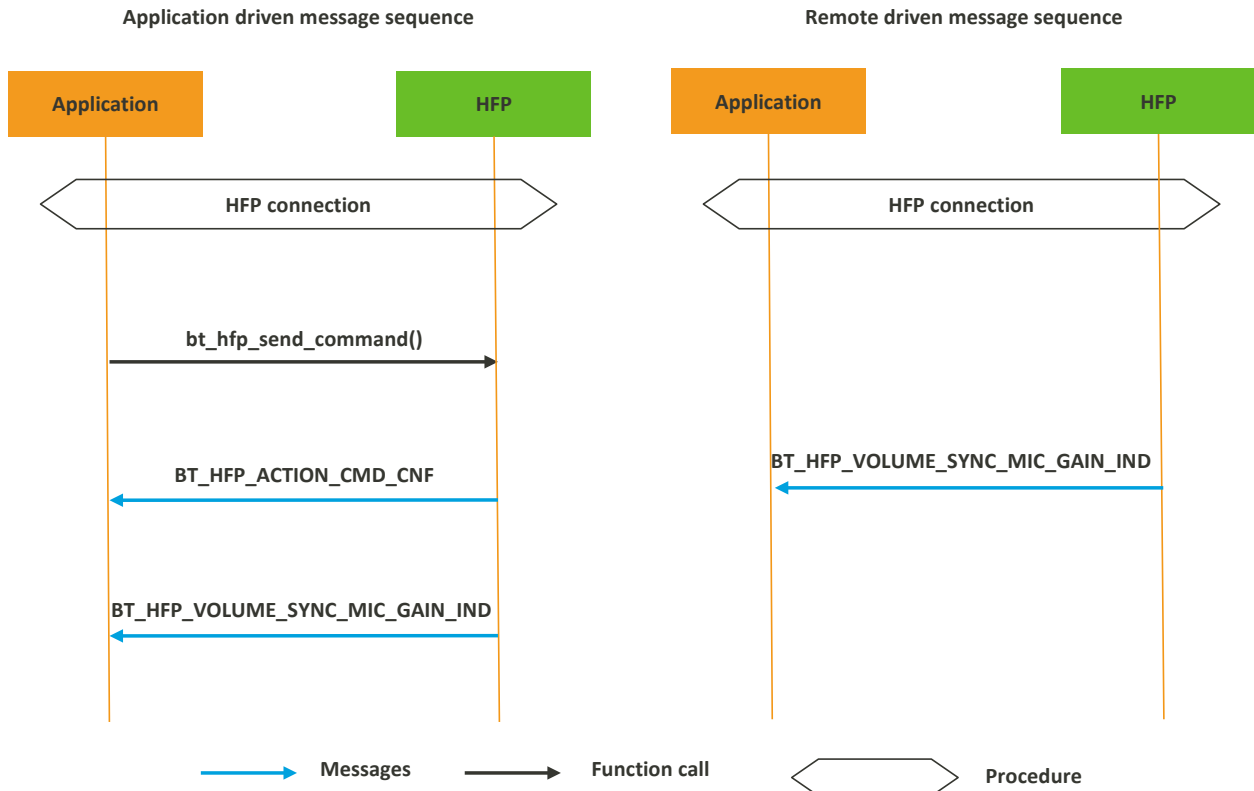
Apply this procedure to synchronize the speaker volume on a remote device, as shown in Figure 24. There are two different message sequences; either application driven or remote device driven. The application driven message sequence calls `bt_hfp_send_command()` and passes the command "AT+VGS=XX" (XX is the volume value to set) to synchronize the speaker volume. For more details, refer to the `bt_hfp.h` and HFP specification version 1.6.



**Figure 24. The remote speaker volume control message sequence**

### 3.3.1.10. Remote microphone volume control

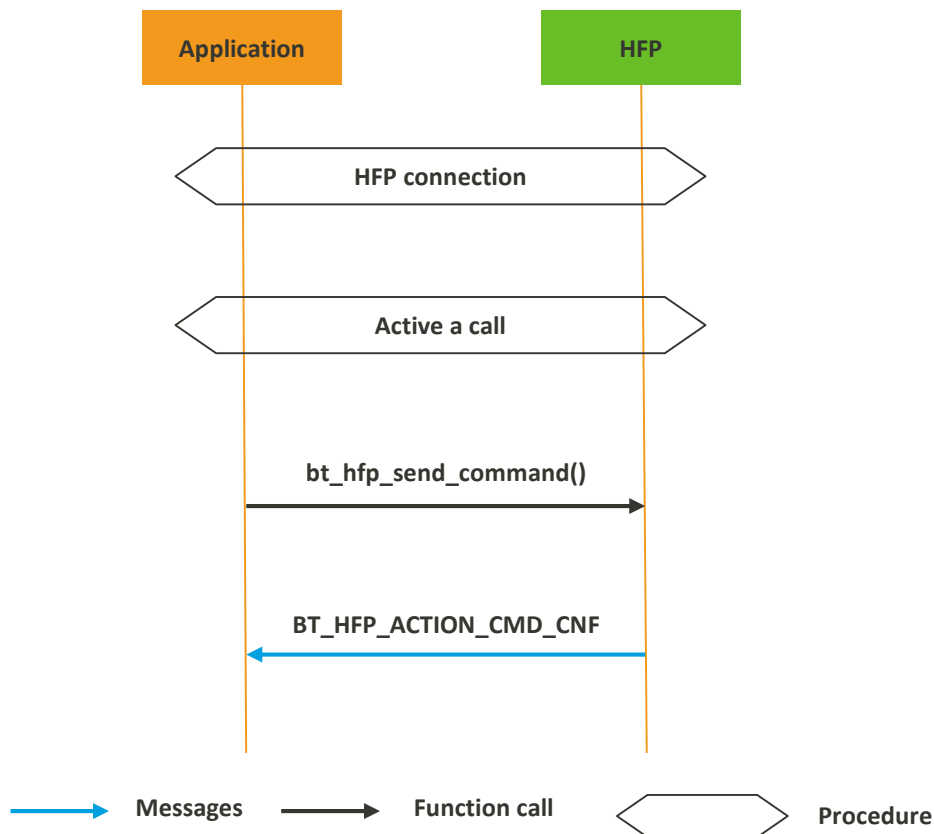
Apply this process to synchronize the microphone volume with a remote device, as shown in Figure 25. There are two different message sequences; either application driven or remote device driven. The application driven message sequence calls `bt_hfp_send_command()` and passes the command "AT+VGM=XX" (XX is the volume value to set) to synchronize the microphone volume. For more details, refer to the `bt_hfp.h` and HFP specification version 1.6.



**Figure 25. The remote microphone volume control message sequence**

### 3.3.1.11. Transmit DTMF codes

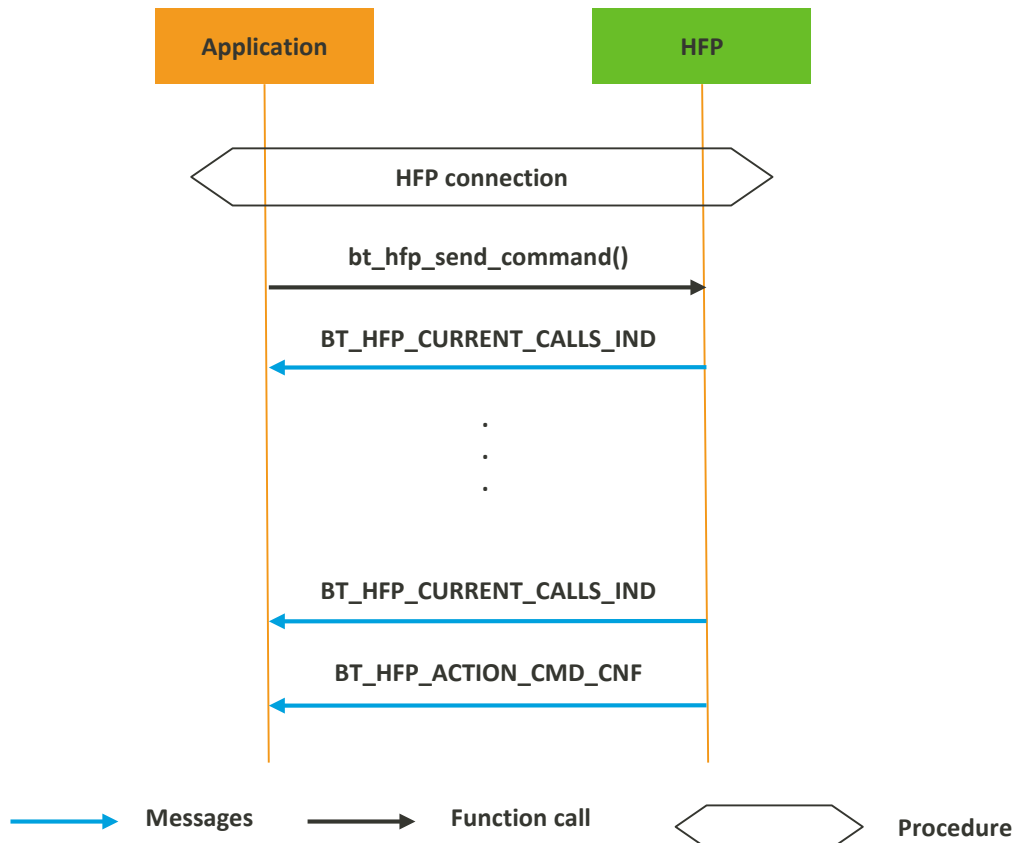
Apply this process to transmit DTMF codes through AG using the HDK, as shown in Figure 26. Application uses the API `bt_hfp_send_command()` and passes the command "AT+VTS=X" (X is the DTMF code to send) to send the DTMF code. For more details, refer to the `bt_hfp.h` and HFP specification version 1.6.



**Figure 26. Transmit DTMF codes message sequence**

### 3.3.1.12. Query a list of current calls

Apply this process to query the calls' detailed information, as shown in Figure 27. Application uses the API `bt_hfp_send_command()` and passes the command "AT+CLCC" to fetch current calls' detailed information. For more details, refer to the `bt_hfp.h` and HFP specification version 1.6.



**Figure 27. Query a list of current calls message sequence**

### 3.3.2. Using the HFP APIs

This section describes how to use the HFP APIs for an application development. The source code of the HFP API is implemented in a binary library code but the headers can be found in `bt_hfp.h`.

To use the HFP APIs:

- 1) Implement the API `bt_hfp_get_init_params()`. This function is called when the HFP channel is initialized and the HFP will create SLC connection with a remote device according to the initialization parameters. If this function is not implemented or the API's return value is not `BT_STATUS_SUCCESS`, the HFP channel cannot be created.

```
bt_status_t bt_hfp_get_init_params(bt_hfp_init_params_t *param);
```

- 2) Implement the API `bt_app_event_callback()`. This function is called to provide notifications to the application. If a remote device sent a connection request to the HDK, this function will be called with event ID `BT_HFP_CONNECT_REQUEST_IND`, and the application should call `bt_hfp_connect_response()` API to accept or reject the connection.

```
void bt_app_event_callback(bt_event_t event_id, const void *param);
```

- Call `bt_hfp_connect()` to connect to a remote device, the return value is the connection result:
  - `BT_STATUS_SUCCESS`, the command is successfully sent.
  - `BT_STATUS_FAIL`, the connection request has failed.

- BT\_STATUS\_OUT\_OF\_MEMORY, the connection request has failed as there is not enough memory to complete the operation. To solve the out of memory issue, refer to section 5.1.2, “Out of Memory (OOM)”.
- If the connection is complete, the application will receive BT\_HFP\_SLC\_CONNECTED\_IND with the connection result.

To send the HFP command to a remote device:

- 3) Connect the HFP to a remote device and wait until connection is established, get the event ID BT\_HFP\_SLC\_CONNECTED\_IND.
- 4) Use the API `bt_hfp_send_command()` to send an HFP command to a remote device. The return value is the result of sending a command.
  - a) BT\_STATUS\_SUCCESS, the command is successfully sent.
  - b) BT\_STATUS\_FAIL, sending a command has failed.
  - c) BT\_STATUS\_OUT\_OF\_MEMORY, sending a command has failed, as there is not enough memory to complete the operation. To solve the out of memory issue, refer to section 5.1.2, “Out of Memory (OOM)”.
- 5) Application gets the event ID BT\_HFP\_ACTION\_CMD\_CNF to get the response from a remote device.
- 6) Call `bt_hfp_disconnect()` to disconnect from a remote device and then get the event BT\_HFP\_DISCONNECT\_IND with the disconnect result. If the remote device initiates the disconnection, the application will directly get the event BT\_HFP\_DISCONNECT\_IND result.

## 3.4. A2DP

The A2DP provides protocols and procedures to implement distribution of high-quality audio content on ACL channels. For more information about this profile, refer to the A2DP specification version 1.2.

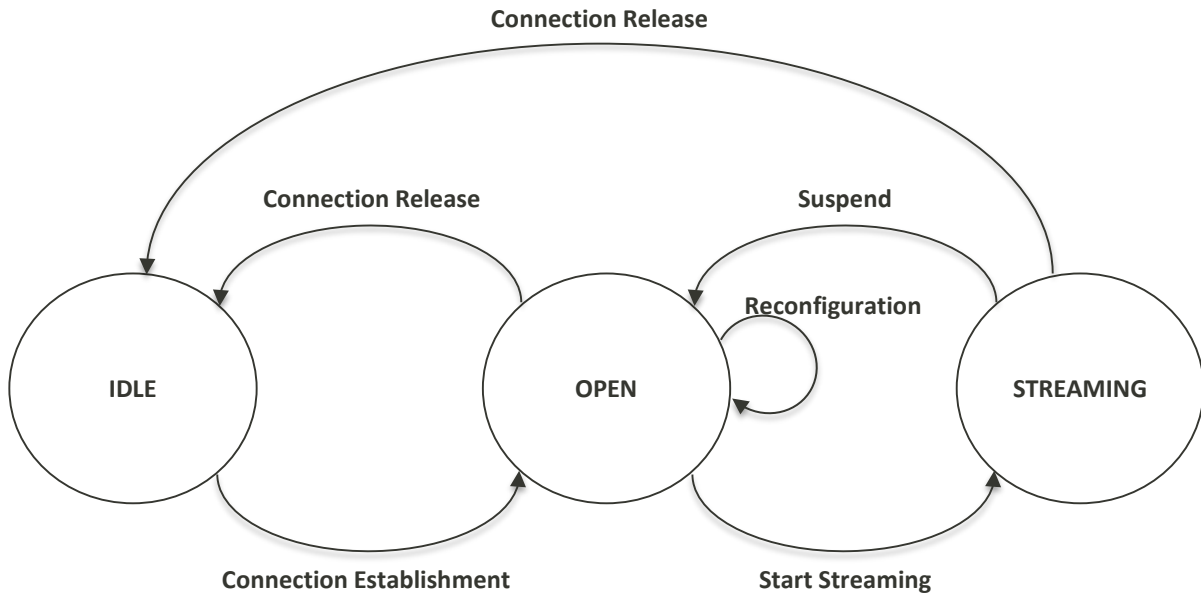
According to the A2DP specification, there are two roles (Sink and Source) defined for smart devices. The Source (SRC) acts as a digital audio streaming source that is delivered to the Sink (SNK) of the piconet. The SNK acts as a sink of a digital audio streaming delivered from the SRC on the same piconet.



Note: Only SNK is supported on the Airoha IoT SDK v4.

Whichever role the device is configured for, there are certain states to operate on, as described in the state machine diagram shown in Figure 28.



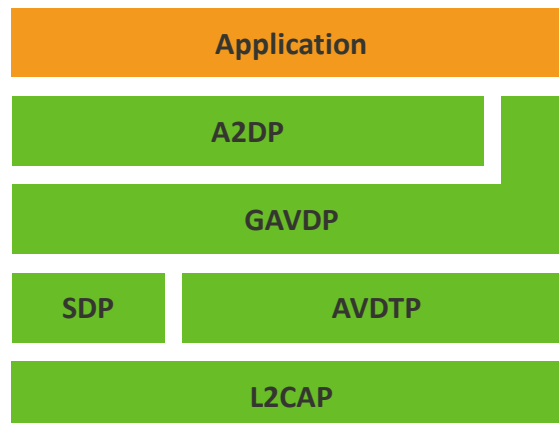


**Figure 28. The A2DP state diagram**

- **IDLE** — the initial state where the A2DP is not connected with or A2DP is disconnected from a remote device.
- **OPEN** — the A2DP is connected with a remote device, but both devices are not ready for streaming.
- **STREAMING** — both devices are ready for streaming.

The SDK supports two types of A2DP audio codecs, SBC and AAC. If Bluetooth is enabled and powered on, the application is requested to configure the codec information with `bt_a2dp_get_init_params()`.

The A2DP stack architecture layout is shown in Figure 29.



**Figure 29. The A2DP abstraction layout**

The A2DP depends on the Generic Audio/Video Distribution Profile (GAVDP), which defines procedures required to set up an audio/video streaming. Compared to GAVDP, there are fewer procedures involved in the application, and messages are simplified.

## 3.4.1. The A2DP message sequences

There are five operations available for the A2DP; connection establishment, connection release, start streaming, suspend steaming and reconfiguration. The message sequence for each procedure is described in the following sections.

### 3.4.1.1. Connection establishment

Apply this process to establish a streaming connection with another device. The initial state of both devices is **IDLE**, and it becomes **Open** after connection is established, as shown in Figure 30. The SDK provides two different message sequences for application from a different initiator that initiates a signaling procedure. For more details, refer to the `bt_a2dp.h`.

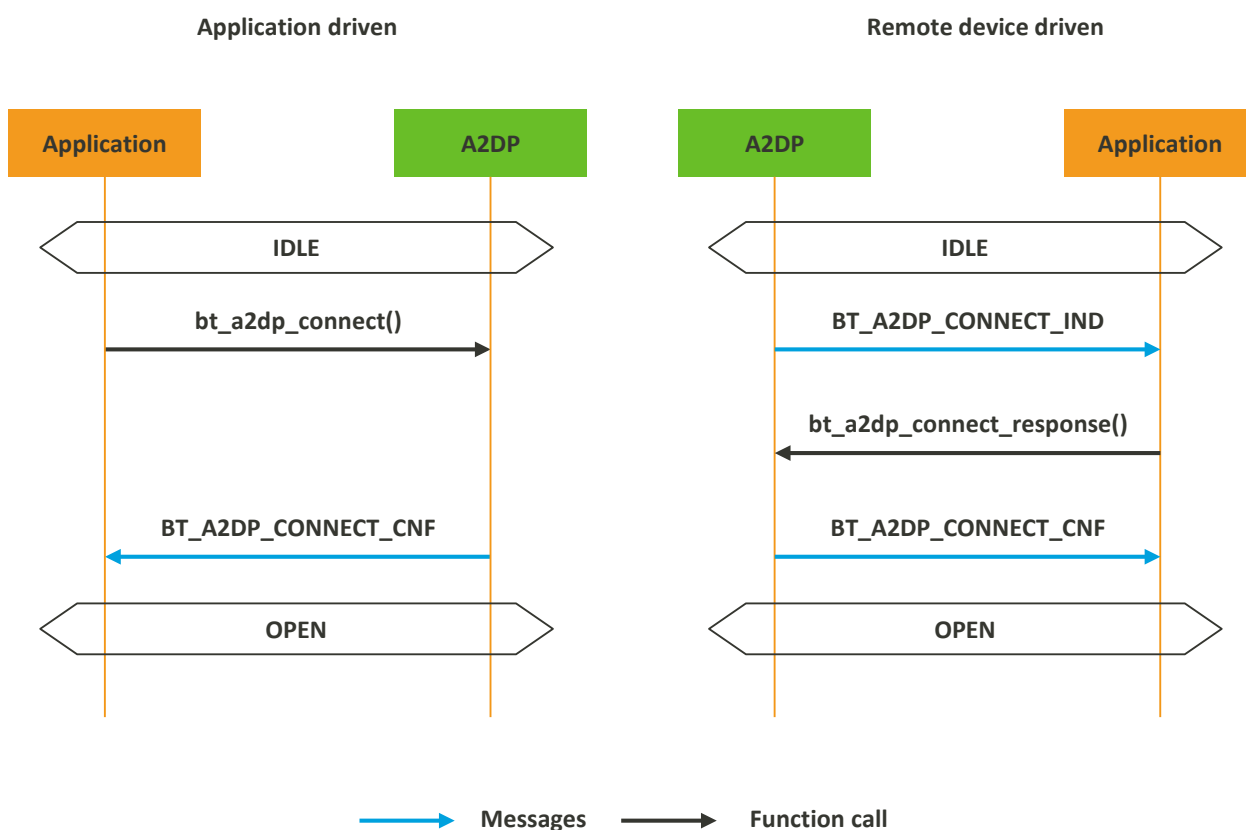
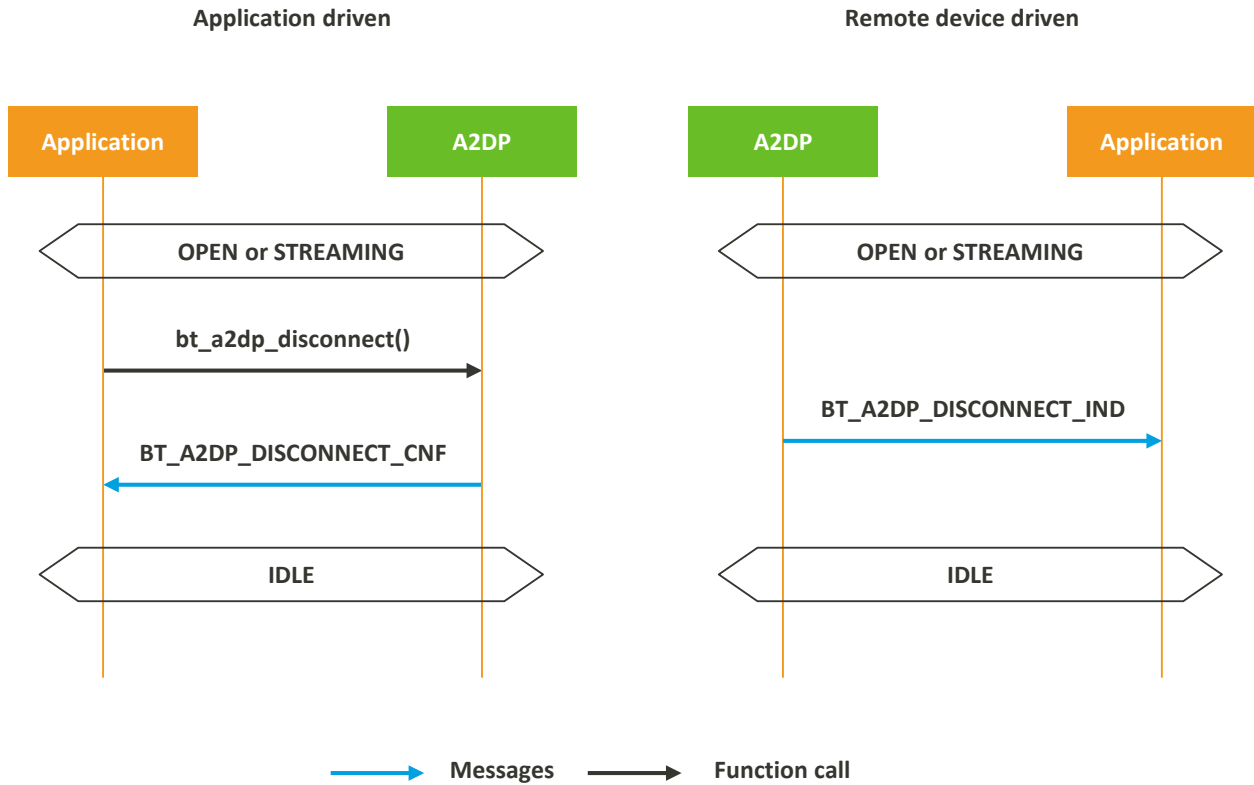


Figure 30. The A2DP connection establishment message sequence

### 3.4.1.2. Connection release

The A2DP connection is disconnected if a connection is released. It could be applied to **OPEN** and **STREAMING** states. The current state is set to **IDLE** for both devices, as shown in Figure 31. The HDK can initiate A2DP disconnection and accept the remote device's request to release the connection. For more details, refer to the `bt_a2dp.h`.

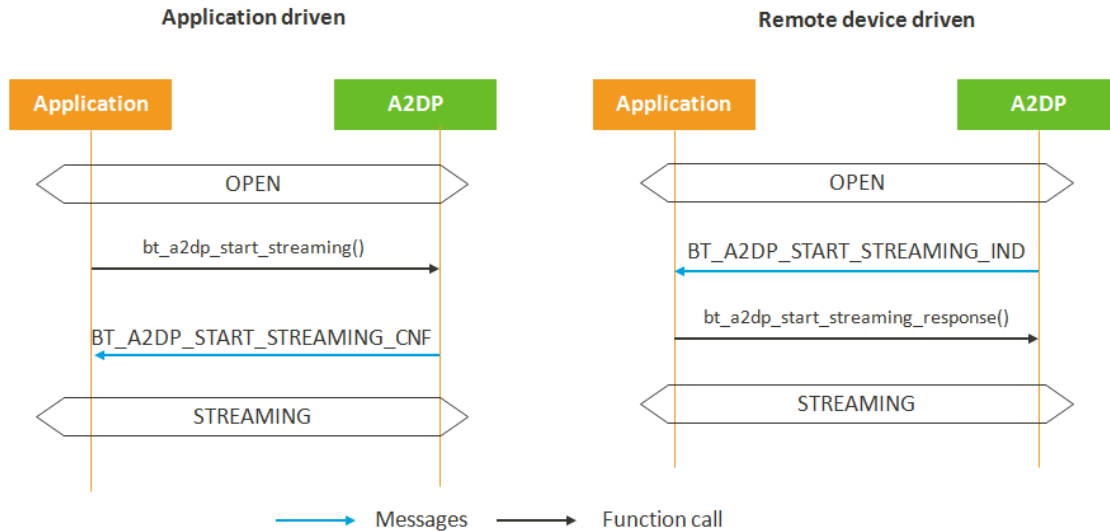


**Figure 31. The A2DP connection release message sequence**

### 3.4.1.3. Start streaming

To start or resume the audio streaming, initiate start streaming to change the state from **OPEN** to **STREAMING**, as shown in Figure 32. The device plays both acceptor and initiator role to accept the start streaming request and initiate the streaming. For more details, refer to the `bt_a2dp.h`.

In the **STREAMING** state, the application interacts with audio module to open the codec configured previously and send streaming data to audio or send SBC encoded data to the A2DP. For more details, see section 3.4.2, "Interaction with audio".

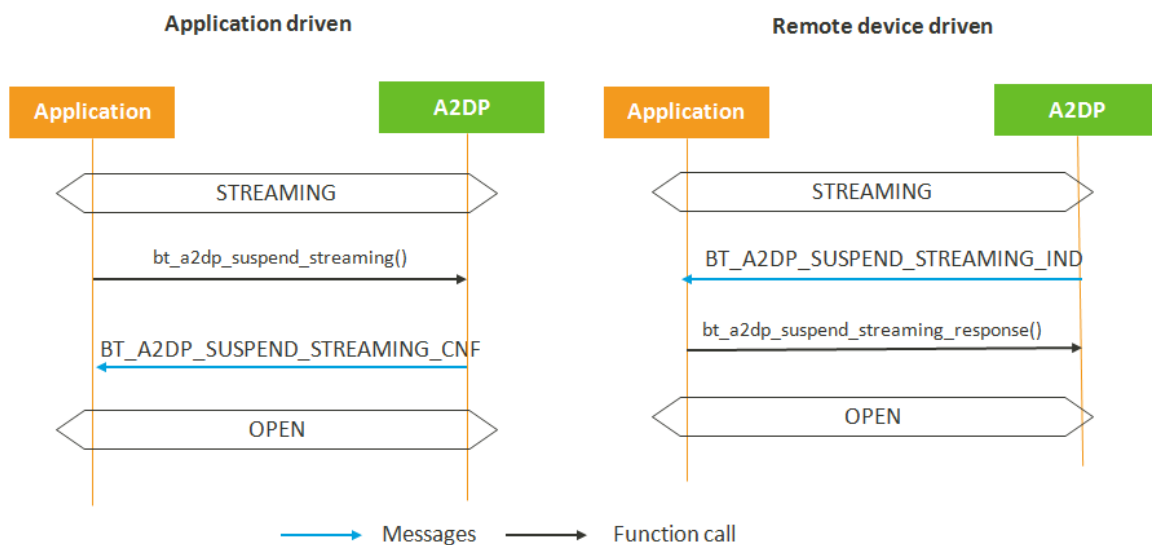


**Figure 32. The A2DP start streaming message sequence**

### 3.4.1.4. Suspend streaming

Apply this process to suspend the audio streaming and change the state from **STREAMING** to **OPEN**, as shown in Figure 33. In the meantime, the application notifies the audio module to close the codec and pause the audio so that the audio resource is released. For more details, refer to the `bt_a2dp.h`.

The SRC initiates streaming suspend by a user initiated action or an internal event.

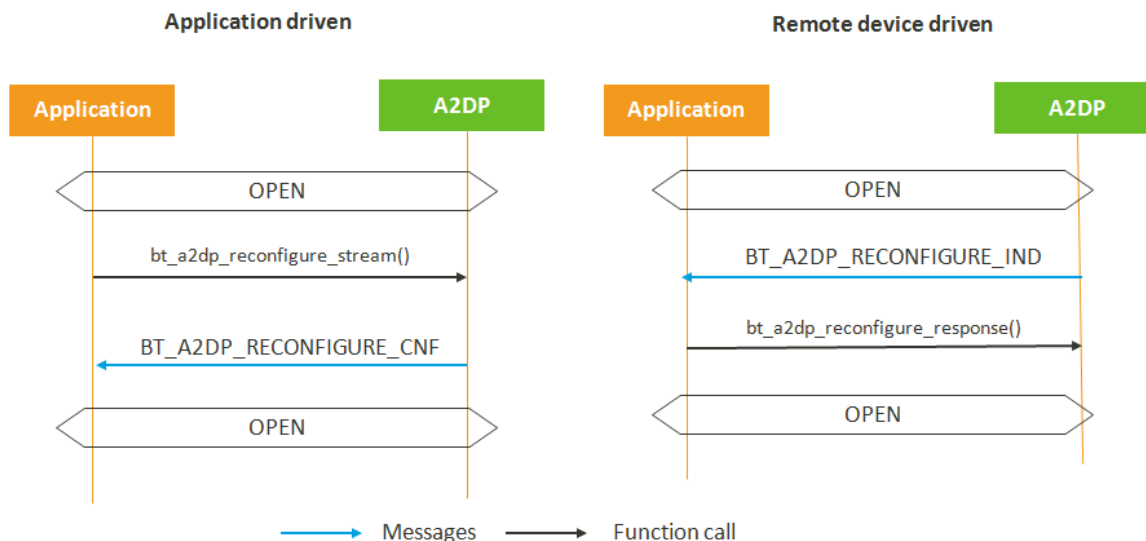


**Figure 33. The A2DP suspend streaming message sequence**

### 3.4.1.5. Reconfiguration

Apply this process, if the codec information is changed for a special audio streaming at SRC, before the streaming is sent to SNK. To process the reconfiguration, both devices should be in **OPEN** state. Execute suspend operation, if the state is **STREAMING** and change the state to **OPEN** for both devices, as shown in Figure 34. For more details, refer to the `bt_a2dp.h`.

At the end of this process, the device's state remains **OPEN**. Initiate Start streaming procedure to resume the streaming see section 3.4.2, "Interaction with audio".



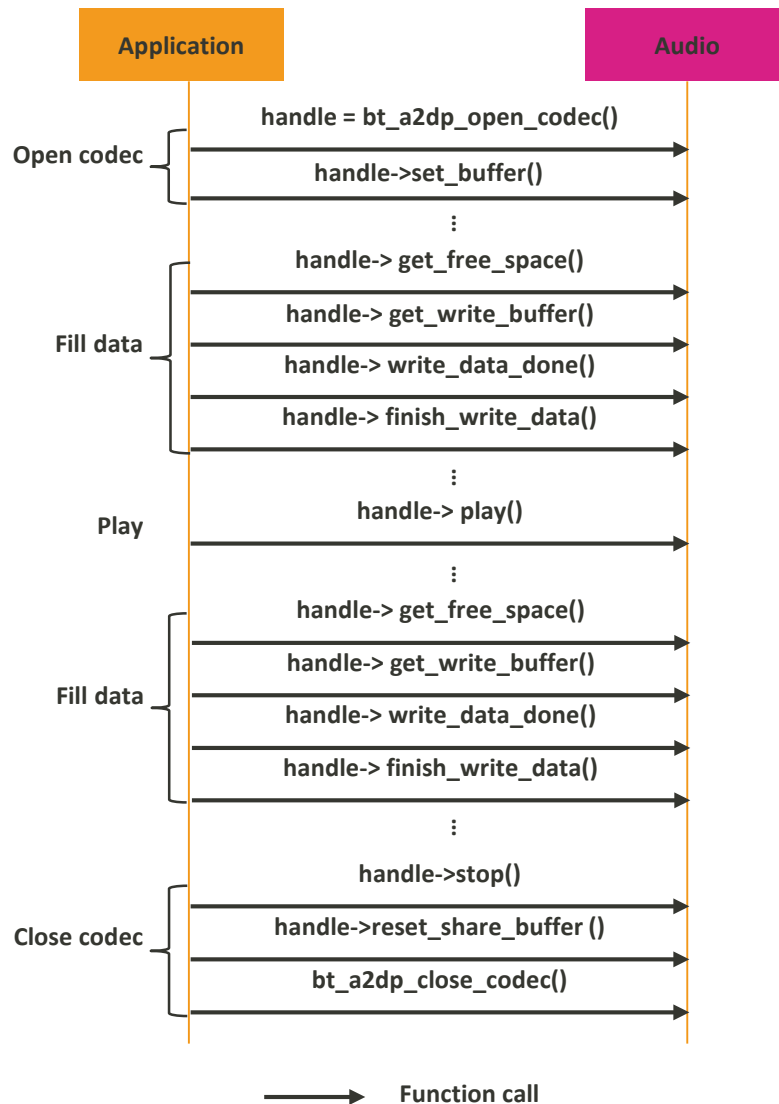
**Figure 34. The A2DP reconfiguration message sequence**

You've now successfully processed the A2DP message sequences.

### 3.4.2. Interaction with audio

To establish A2DP connection, both SRC and SNK devices need to negotiate and configure service parameters, such as the media transport, and the A2DP audio codec. The media codec enables to encode or decode digital data stream using Bluetooth protocol. The received data is decoded and passed through digital-to-analog converter (DAC).

Once the A2DP connection is established and Start streaming procedure is executed, the SRC and SNK switch to **STREAMING** state. At the SRC, the audio module encodes the raw audio data with a codec. This data is then passed to the SNK using A2DP over Bluetooth. At the SNK, the received data passes through the audio module and the raw data is decoded using the same codec. The A2DP audio codec must be opened before media data is streaming, and be closed after suspended. There are four main operations during the interaction between A2DP streaming and the audio codec; open codec, play, get data, close codec. For more details, refer to the `bt_codec.h`.



**Figure 35. The A2DP codec operation message sequence (Sink)**

### 3.4.2.1. Open codec

Bluetooth parameters, such as callback function and codec related parameters must be sent to configure the codec properties during open codec operation. If requested capability is available, a handle is returned and functions to share the buffer are provided. The Get data function sets the A2DP codec driver after opening the codec.

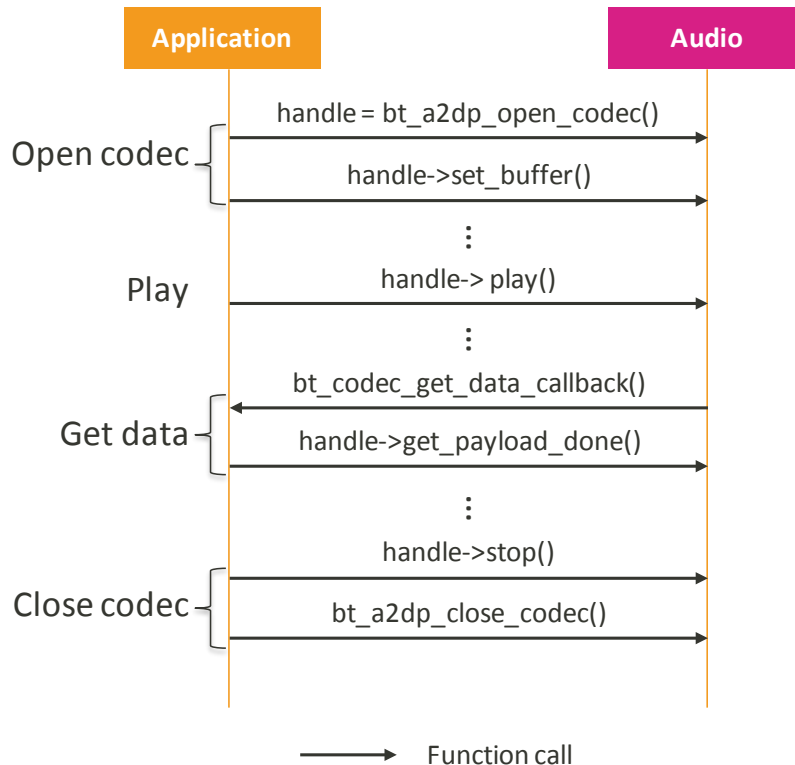
For A2DP sink operation, Bluetooth data is held before it is consumed. Codec driver fetches Bluetooth data with get data function for decoding (see Figure 35).

For A2DP source operation, the audio data is encoded with encoder, wrapped with Bluetooth header and then sent to the remote device (see Figure 36).

### 3.4.2.2. Play and Get data

For A2DP sink, it's recommended to keep enough Bluetooth data before playing the audio. The application will provide a callback function to fetch the data. To start the Bluetooth audio, call the play function (see Figure 35).

For A2DP source, application will be notified to get audio data after codec play is called, and the function `get_payload_done()` should be called after application gets and sends audio data.



**Figure 36. The A2DP codec operation message sequence (Source)**

### 3.4.2.3. Stop and Close the codec

Apply this operation if the audio is close to an end or an error occurred during playback. If the Bluetooth audio link is no longer needed, the codec can be closed (see Figure 35).

### 3.4.3. Using the A2DP APIs

This section describes how to use the A2DP APIs in your application. The functionality of the A2DP APIs is implemented in the library code but header functions can be found in `bt_a2dp.h`.

- 1) Implement `bt_a2dp_get_init_params()` to configure the codec information and role when the Bluetooth is powered on by calling `bt_gap_power_on()`.

```

bt_a2dp_codec_capability_t cap[2]; // Support 2 codec.
int32_t bt_a2dp_get_init_params(bt_a2dp_init_params_t* params) {
    (A2DP SINK)
    params->codec_number = 2;
    // Fill supported audio codec capability in init_codec, and then pass
    to params-> codec_list.
    params->codec_list = &init_codec;
    (A2DP SOURCE)
    params->codec_number = 1;
    // Fill supported audio codec capability in init_codec, and then pass
    to params-> codec_list.
    params->codec_list = &init_codec;

    return Bluetooth_STATUS_A2DP_OK;
}
    
```

```
}
```

- 2) The application connects to a remote device by calling the `bt_a2dp_connect()` function, and then the event `BT_A2DP_CONNECT_CNF` is expected to be received, as shown in `bt_app_event_callback(bt_msg_type_t msg_id, bt_status_t status, void *buff)`.

```
(A2DP SINK)
ret = bt_a2dp_connect(&a2dp_handle, address, BT_A2DP_SINK);
(A2DP SOURCE)
ret = bt_a2dp_connect(&a2dp_handle, address, BT_A2DP_SOURCE);
```

- 3) The HDK disconnects from a remote device using the following API and then the event `BT_A2DP_DISCONNECT_CNF` is expected to be received, as shown in `bt_app_event_callback(bt_msg_type_t msg_id, bt_status_t status, void *buff)`.

```
bt_a2dp_disconnect(a2dp_handle);
```

- 4) (A2DP SINK and A2DP Media Payload)

- A2DP SINK

Implement a utility function to hold the media data node and fetch data callback. If media data is received from the A2DP SDK layer when playing music, the data node is needed to keep in a buffer and locate the valid media data. Fetch data callback is called to fill the media data from data node in the buffer when the codec driver starts decoding. Remember to release the data node if the media data is fully copied.

- a) Hold the media data node.

```
#define MEDIA_PKT_HEADER_LEN 12 // Media packet header 12 Bytes.
typedef struct _bt_media_packet_node{
    _bt_media_packet_node *node;
    uint16_t packet_length;
    uint16_t offset;
} bt_media_packet_node_t;
void bt_a2dp_keep_media_data_node(bt_media_packet_node_t *data_node,
int16_t offset, int16_t total_len)
{
    void* p_payload = data_node + offset + MEDIA_PKT_HEADER_LEN;
    *payload_len = total_len - offset - MEDIA_PKT_HEADER_LEN;
    // Search the payload start pointer for AAC.
    if (g_a2dp_codec.type == BT_A2DP_CODEC_AAC) {
        uint8_t payload_offset = 9;
        uint8_t media_start_pos = 0;
        do {
            media_start_pos = ((uint8_t *) p_payload)[payload_offset];
            payload_offset++;
        } while (media_start_pos != 0xFF);
        *payload_len -= payload_offset;
        p_payload += payload_offset;
    }
    data_node->offset = p_payload - (void *)data_node;
    data_node->packet_length = total_len;
    // Insert the data_node at the end of data node buffer list.
    bt_a2dp_hold_media_data_node(data_node);
}
```

- b) Implement fetch data callback.

Fetch the data node from the data buffer list to `data_node` and copy the media data to `dsp_buff`. If the media data length in data node is less than `dsp_buff` length, then

- i) Remove the data node from the list and release it;



- ii) Fetch the data node and copy again, till the buffer is empty or the dsp\_buffer is full.

If the media length is larger than dsp\_buff length, then

- i) Do not remove data\_node before it's filled with received data.
- ii) Modify the remaining media offset only.

```
int32_t bt_sink_codec_get_data_callback(volatile uint16_t *dsp_buff,
uint32_t len)
{
    bt_media_packet_node_t *data_node = NULL;
    int16_t media_len;
    uint32_t filled_length;
    // Fetch the bt media packet node and fill the received data in the
    node to dsp_buffer.
    // Note: The data should be filled in units of Word.
    return filled_length;
}
```

- A2DP SOURCE

5) Implement bt\_app\_event\_callback() in your application.

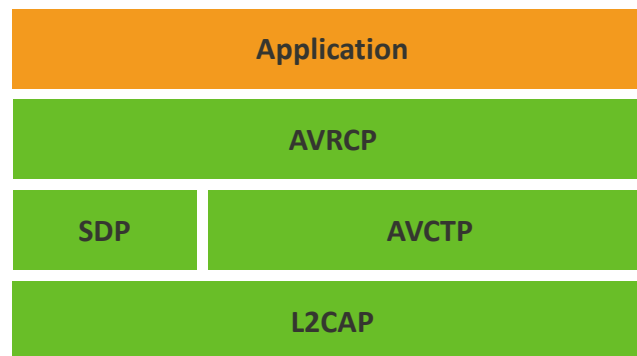
```
bt_status_t bt_app_event_callback (bt_msg_type_t msg_id, bt_status_t
status, void *buff)
{
    switch (msg_id) {
        case BT_A2DP_START_STREAMING_IND: {
            // Open a2dp codec according to the specified codec, and
            then set the fetch data function callback for codec driver.
            g_media_handle = bt_codec_a2dp_open(bt_audio_callback,
            &a2dp_codec);
            g_media_handle->
            set_get_data_function(handle, bt_sink_codec_get_data_callback);
            bt_a2dp_start_streaming_response(params->conn_id, true);
        }
        break;
        case BT_A2DP_SUSPEND_STREAMING_IND: {
            // Stop music, close codec.
            g_media_handle->stop(g_media_handle);
            bt_a2dp_close_codec(g_media_handle);
            bt_a2dp_suspend_streaming_response(params->conn_id, true);
        }
        break;
        case BT_A2DP_STREAMING_RECEIVED_IND: {
            bt_a2dp_keep_media_data_node(params->data_node, params->
            media_offset, params->total_length);
            // Call g_media_handle->play(); if this is the streaming
            data received first time after BT_A2DP_START_STREAMING_IND.
        }
        break;
    }
}
```

## 3.5. AVRCP

The AVRCP defines the features and procedures to ensure interoperability between Bluetooth devices with audio/video control functions. For more information about this profile, refer to the [AVRCP specification version 1.6.1](#).

In the AVRCP, there are two roles configured, controller (CT) and target (TG). The CT transmits AV/C (the AV/C Digital Interface Command Set) command to a remote Bluetooth device (TG). Hence, the CT should initiate a transaction by sending a command frame to a TG while the TG should receive a command frame and generate a corresponding response frame.

AVRCP does not handle A/V streaming, to handle streaming, refer to the [A2DP profile](#). Note, smartphone may not support connect AVRCP without A2DP. It's recommended to connect both profiles.



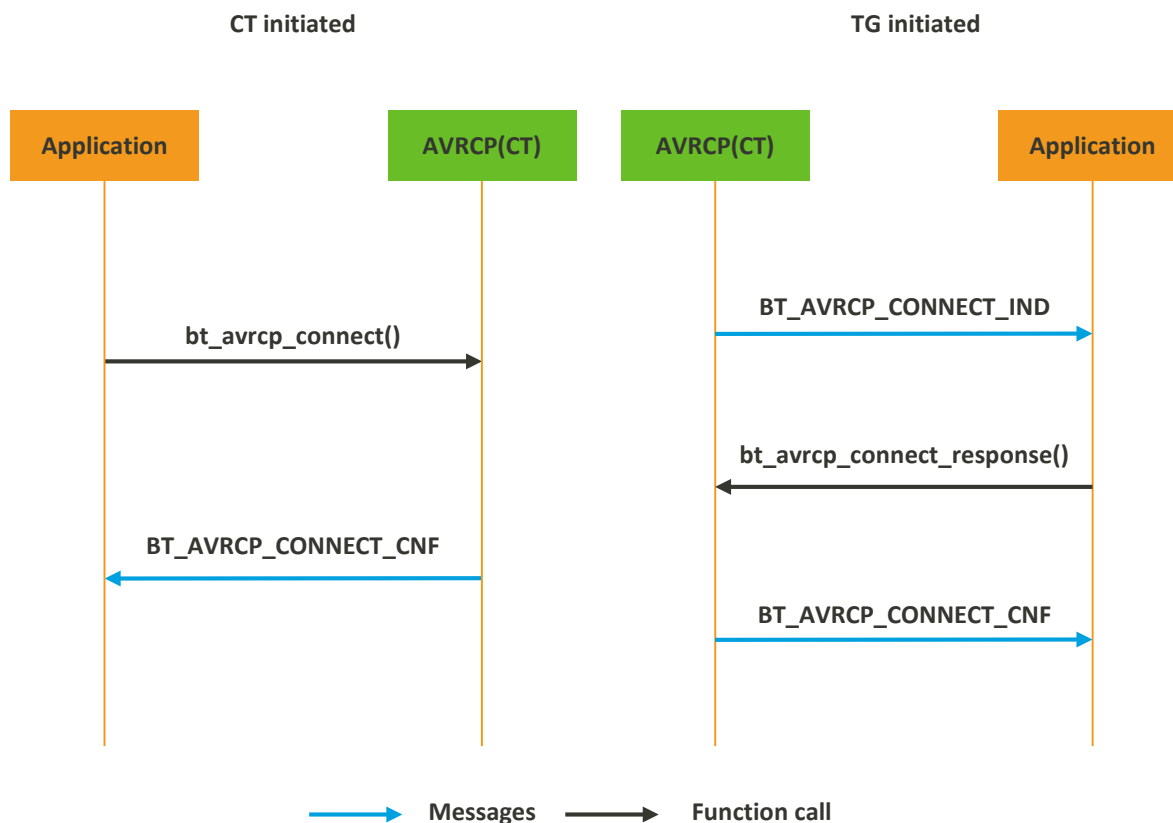
**Figure 37. The AVRCP abstraction layout**

The packets between CT and TG are transported by the Audio/Video Control Transport Protocol (AVCTP), as shown in Figure 37.

### 3.5.1. The AVRCP procedure and message sequences

#### 3.5.1.1. Connection establishment

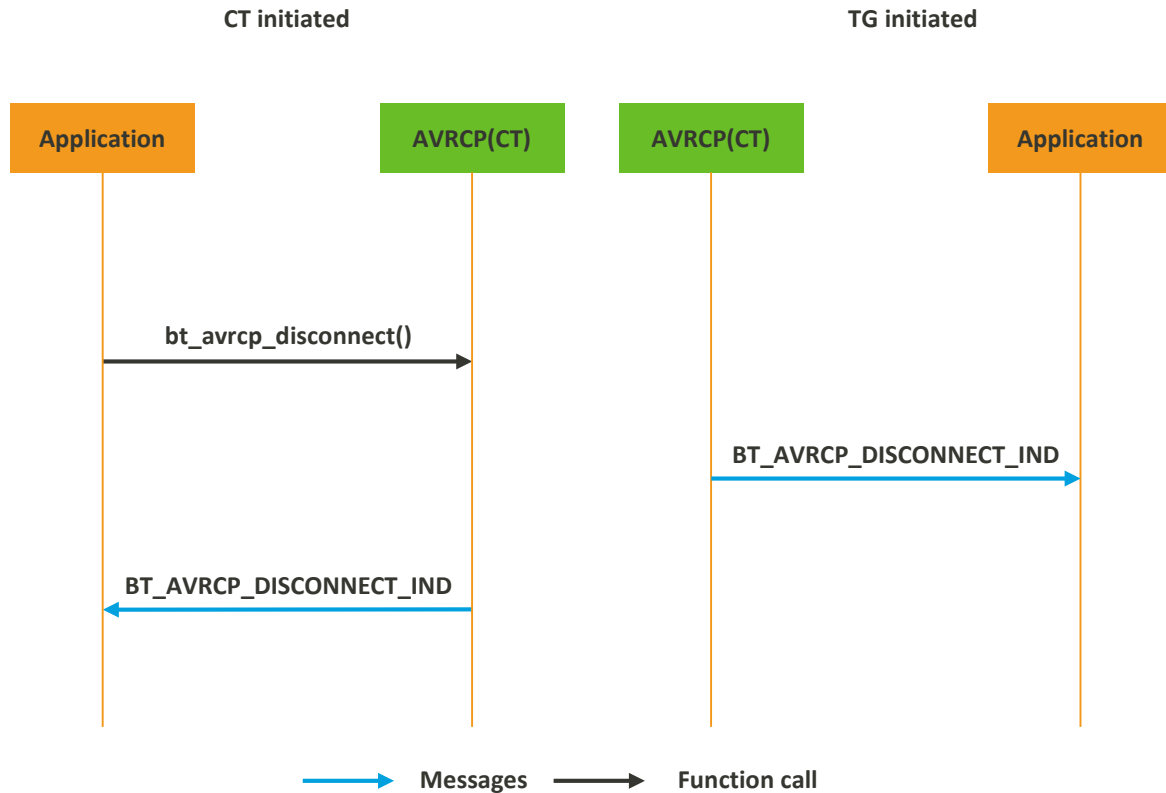
The AVRCP establishes an L2CAP connection for AVCTP channel that can be initiated by CT or TG. At the same time, there should be only one AVCTP channel per ACL link. If the channel already exists, the new connections will be rejected. This process is shown in Figure 38.



**Figure 38. AVRCP connection establishment**

### 3.5.1.2. Connection release

The CT or the TG can both initiate the process to release AVCTP connection. The process is shown in Figure 39.



**Figure 39. AVRCP connection release**

### 3.5.1.3. AV/C command procedure

The CT can send AV/C command once the connection is established. The process is shown in Figure 40. The AVRCP supports two types of commands; PASS THROUGH and VENDOR DEPENDENT. Each command should receive a response from TG. Only VENDOR DEPENDENT commands may receive an interim response. Note, the application should only send one command and wait for its response. The AVRCP returns a busy status, if a command is sent without waiting for the arrival of the previous command's response.

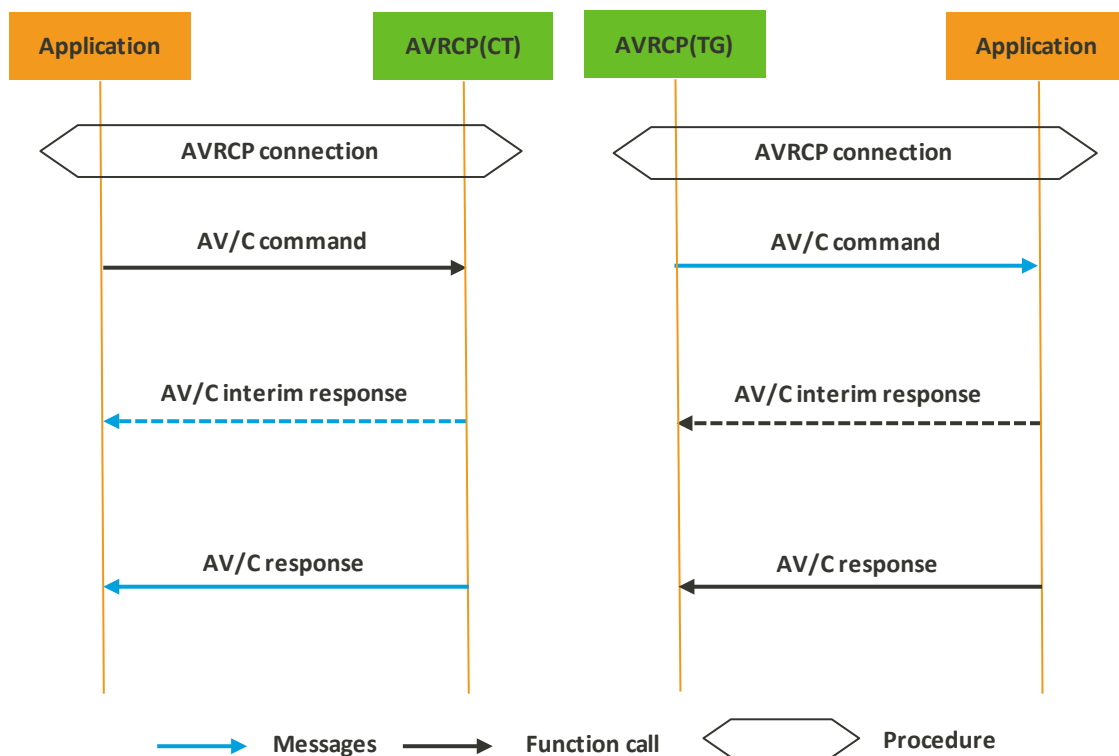


Figure 40. AV/C command procedure

## 3.5.2. AV/C commands

This section specifies two types of commands: PASS THROUGH and VENDOR DEPENDENT. The library `libbt_avrcp.a` provides only PASS THROUGH type of functions. To use VENDOR DEPENDENT type of commands, include `libbt_avrcp_enhance.a` library in your application. VENDOR DEPENDENT commands are mainly used for metadata transfer, for example, to get TG player application settings or metadata attributes.

### 3.5.2.1. PASS THROUGH

The PASS THROUGH command is mainly used to transfer a user operation from CT device to a TG device. To send a user operation from CT device, application can call `bt_avrcp_send_pass_through_command()` with operation ID and state. The operation ID specifies the given operation and the state defines the operation key status (see `bt_avrcp.h`). Since the TG may reject the PASS THROUGH command, application should check the response of the command. On TG device, the application receives the event `BT_AVRCP_PASS_THROUGH_COMMAND_IND` with operation ID and state from CT. Application should call `bt_avrcp_send_pass_through_response()` immediately after receiving the event, to send a response to the CT device (accepted or rejected).



Note, when sending the key, the key status can be either push or release and the TG device may respond to either one of them. It's recommended that application tries both push and release when sending the PASS THROUGH command.

### 3.5.2.2. Player application settings

CT provides commands for application to query player application attribute settings and get and set attribute values according to the attributes on the TG. All available settings on the TG are in `<attribute, value>` pair. That means each setting has a unique attribute ID and a corresponding value.



Note, the TG may accept the application attribute value setting commands sent from the CT, but it might not take any action with the attribute values depending on the implementation of TG.

The related attributes and values are listed in Table 2. For more details, please refer to Appendix F of [AVRCP specification version 1.6.1](#).

**Table 2. Player application settings and values**

Attribute ID	Attribute Description	Supported Value	Value Description
BT_AVRCP_SETTING_ATTRIBUTE_EQUALIZER	Equalizer status	0x01	OFF
		0x02	ON
BT_AVRCP_SETTING_ATTRIBUTE_REPEAT_MODE	Repeat status	0x01	OFF
		0x02	Single track repeat
		0x03	All tracks repeat
		0x04	Group repeat
BT_AVRCP_SETTING_ATTRIBUTE_SHUFFLE_MODE	Shuffle status	0x01	OFF
		0x02	All tracks shuffle
		0x03	Group shuffle
BT_AVRCP_SETTING_ATTRIBUTE_SCAN_MODE	Scan status	0x01	OFF
		0x02	All tracks scan
		0x03	Group Scan

### 3.5.2.3. Metadata attributes

CT enables access to metadata attributes for current media track by calling the Get Element attribute API. TG responds back with attribute values when receiving a request from the CT.

The related media attributes are listed in Table 3. For more details, please refer to Appendix E of [AVRCP specification version 1.6.1](#).

**Table 3. Media element attributes**

Attribute ID	Value	Description
BT_AVRCP_MEDIA_ATTRIBUTE_TITLE	0x01	Title
BT_AVRCP_MEDIA_ATTRIBUTE_ARTIST_NAME	0x02	Artist Name
BT_AVRCP_MEDIA_ATTRIBUTE_ALBUM_NAME	0x03	Album Name
BT_AVRCP_MEDIA_ATTRIBUTE_MEDIA_NUMBER	0x04	Current media number
BT_AVRCP_MEDIA_ATTRIBUTE_TOTAL_MEDIA_NUMBER	0x05	Total number of media
BT_AVRCP_MEDIA_ATTRIBUTE_GENRE	0x06	Genre category
BT_AVRCP_MEDIA_ATTRIBUTE_PLAYING_TIME	0x07	Length of the audio file in milliseconds

### 3.5.2.4. Absolute volume

The absolute audio volume is applied to adjust the volume (in percentage) between CT and TG devices. The application uses `bt_avrcp_set_absolute_volume()` to set TG volume from CT. Meanwhile, the application should call an event notification function to register the absolute volume change at TG device.

The TG device should use `bt_avrcp_send_set_absolute_volume_response()` after receiving the event `BT_AVRCP_SET_ABSOLUTE_VOLUME_CNF`. And also the event notification response API with absolute volume change event if local volume in TG device changes.



Note, the AVRCP CT role is along with A2DP sink role, while TG is with A2DP source role. However, the CT role of absolute volume is with A2DP source role, while TG is along with A2DP sink role.

### 3.5.2.5. Event notification

CT enables the application to register for an event to detect whether the attribute value on TG has changed. CT receives an interim response from TG to get the current value of the attribute. If the value has changed, the CT will receive the final response from TG for the updated value. For CT device, the application should register for additional events (see Table 4), after the last event receives an interim response. If the application needs to listen to the same attribute repeatedly, it can register for the same event again after receiving the final response. For TG device, the application should send an interim response with the current value for which the CT device is registered. TG device should send the updated value to CT device anytime the value changes.

The related event IDs are listed in Table 4. For more details, please refer to Appendix H of [the AVRCP specification version 1.6.1](#).

**Table 4. List of notification events**

Event ID	Description
BT_AVRCP_EVENT_PLAYBACK_STATUS_CHANGED	Change in the playback status of the current track
BT_AVRCP_EVENT_TRACK_CHANGED	Change of current track
BT_AVRCP_EVENT_TRACK_REACHED_END	Reached end of a track
BT_AVRCP_EVENT_TRACK_REACHED_START	Reached start of a track
BT_AVRCP_EVENT_PLAYBACK_POS_CHANGED	Change in playback position. Return the playback position after a specified playback interval in seconds.
BT_AVRCP_EVENT_BATT_STATUS_CHANGED	Change in the battery status
BT_AVRCP_EVENT_SYSTEM_STATUS_CHANGED	Change in the system status
BT_AVRCP_EVENT_PLAYER_APP_SETTING_CHANGED	Change in the player application setting
BT_AVRCP_EVENT_VOLUME_CHANGED	Change the absolute volume

### 3.5.2.6. Continuation packets

All metadata transfers related to VENDOR DEPENDENT commands support continuation packets. That means CT may receive more than one packet for a command to avoid sending large packets. Each response for these commands has a packet type parameter, which indicates whether the packet is continuation.

On the CT device, application should continue calling `bt_avrcp_request_continuing_response()` to get more packets until the data transfer is complete or call `bt_avrcp_abort_continuing_response()` to abort this operation.

Note, TG does not allow CT to send another metadata transfer command while still receiving continuation packets.

### 3.5.2.7. Get play status

CT provides commands to get the status of currently playing media. TG device responds with the corresponding status when receiving a request from the CT.

### 3.5.2.8. Get capabilities

CT provides commands to get the capabilities supported by TG device. There are two capabilities to query; company and event supported. TG responds back with its capability.

## 3.5.3. Using the AVRCP APIs

This section describes details on using the AVRCP APIs for application development. The AVRCP APIs are implemented in the library code but header functions can be found in `bt_avrcp.h`.

- 1) Initiate a connection to a TG device. The `BT_AVRCP_CONNECT_CNF` event is sent to `bt_app_event_callback()` to indicate the connection result.

```
bt_status_t bt_avrcp_connect(uint32_t *handle, const bt_bd_addr_t
*address);
```

- 2) Release a connection to a TG device. The `BT_AVRCP_DISCONNECT_IND` event is sent to `bt_app_event_callback()`.

```
bt_status_t bt_avrcp_disconnect(uint32_t *handle);
```

- 3) Send a pass through command to a TG device. Call this API after connection is established. The `BT_AVRCP_PASS_THROUGH_CNF` event is sent to `bt_app_event_callback()` to indicate the result of the command.

```
bt_status_t bt_avrcp_send_pass_through_command(
uint32_t handle,
bt_avrcp_operation_id_t op_id,
t_avrcp_operation_state_t op_state);
```

- 4) Respond the pass through to CT device. Call this API after receiving `BT_AVRCP_PASS_THROUGH_COMMAND_IND`.

```
bt_status_t bt_avrcp_send_pass_through_response(
uint32_t handle,
bt_avrcp_response_t response,
bt_avrcp_operation_id_t op_id,
t_avrcp_operation_state_t op_state);
```

- 5) List player application setting attribute IDs of a TG device. Call this API after connection is established. The `BT_AVRCP_LIST_APP_SETTING_ATTRIBUTES_CNF` event is sent to `bt_app_event_callback()` to indicate the result of the command.

```
bt_status_t bt_avrcp_list_app_setting_attributes(uint32_t handle);
```

- 6) Get player application setting attribute value for a specified value ID. Call this API after connection is established. The `BT_AVRCP_GET_APP_SETTING_VALUE_CNF` event is sent to `bt_app_event_callback()` to indicate the result of the command.

```
bt_status_t bt_avrcp_get_app_setting_value(
uint32_t handle,
uint16_t attribute_size,
bt_avrcp_get_app_setting_value_t *attribute_list);
```



- 7) Set player application setting attribute value for a specified value ID. Call this API after connection is established. The `BT_AVRCP_SET_APP_SETTING_VALUE_CNF` event is sent to `bt_app_event_callback()` to indicate the result of the command.

```
bt_status_t bt_avrcp_set_app_setting_value(
    uint32_t handle,
    uint16_t attribute_size,
    bt_avrcp_app_setting_value_t *attribute_value_list);
```

- 8) Get metadata attribute of a TG device. Call this API after connection is established. The `BT_AVRCP_GET_ELEMENT_ATTRIBUTES_CNF` event is sent to `bt_app_event_callback()` to indicate the result of the command.

```
bt_status_t bt_avrcp_get_element_attributes(
    uint32_t handle,
    uint16_t attribute_size,
    bt_avrcp_get_element_attributes_t *attribute_list);
```

- 9) Set absolute volume to a TG device. Call this API at volume change in CT device. The `BT_AVRCP_SET_ABSOLUTE_VOLUME_CNF` event is sent to `bt_app_event_callback()` to indicate the result of the command.

```
bt_status_t bt_avrcp_set_absolute_volume(
    uint32_t handle,
    uint8_t volume);
```

- 10) Send the set absolute volume to a CT device. Call this API after receiving `BT_AVRCP_SET_ABSOLUTE_VOLUME_COMMAND_IND`.

```
bt_status_t bt_avrcp_set_absolute_volume_response(
    uint32_t handle,
    uint8_t volume);
```

- 11) Register a notification event of a TG device. Call this API after connection is established. The `BT_AVRCP_EVENT_NOTIFICATION_IND` event is sent to `bt_app_event_callback()` to indicate the result of the command.

```
bt_status_t bt_avrcp_register_notification(
    uint32_t handle,
    bt_avrcp_event_t event_id,
    uint32_t play_back_interval);
```

- 12) Request a TG device to send next packet when received metadata response indicates the packet is not complete. Call this API after connection is established and if the received packet is not the last one. The corresponding metadata event is sent to `bt_app_event_callback()` to indicate the result of the next packet.

```
bt_status_t bt_avrcp_request_continuing_response(
    uint32_t handle,
    bt_avrcp_pdu_id_t pdu_id);
```

- 13) Abort a TG device to send next packet when received metadata response indicates the packet is not complete. Call this API after connection is established and if the received packet is not the last one. The `BT_AVRCP_ABORT_CONTINUING_CNF` event is sent to `bt_app_event_callback()` to indicate the result of the command.

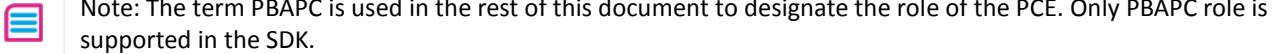
```
bt_status_t bt_avrcp_abort_continuing_response(
    uint32_t handle,
    bt_avrcp_pdu_id_t pdu_id);
```

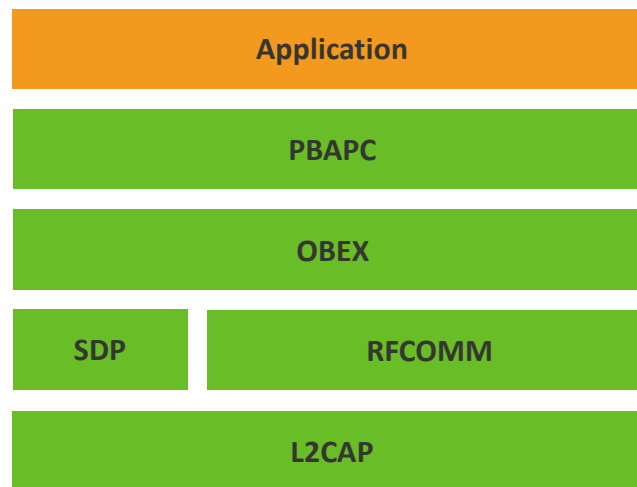
## 3.6. PBAP

The PBAP defines the protocols and procedures to retrieve phonebook objects on smart devices. For more information about this profile, refer to PBAP specification.

The following roles are defined for this profile:

- **PBAP Server (PBAPS)** — provides the source phone book objects.
- **PBAP Client (PBAPC)** — pulls the phone book objects.

 Note: The term PBAPC is used in the rest of this document to designate the role of the PCE. Only PBAPC role is supported in the SDK.



**Figure 41. PBAPC abstraction layout**

The PBAPC depends on OBEX, as shown Figure 41. It defines procedures required to send and receive files between two Bluetooth-enabled devices. Similar features are shared between these two profiles, such as connect, get (download and browsing) and disconnect.

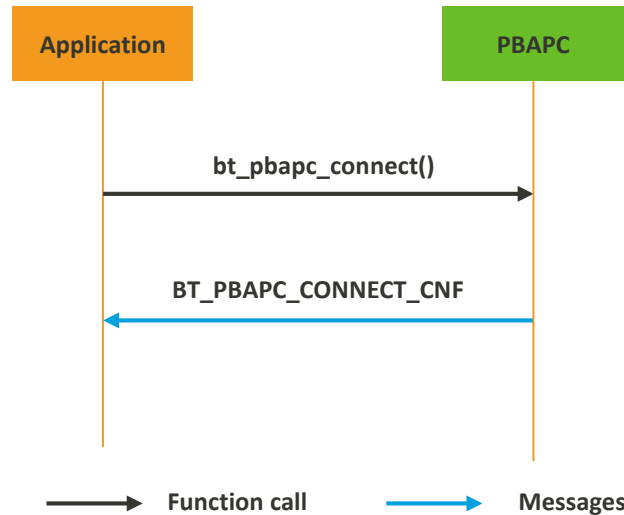
### 3.6.1. The PBAPC features and message sequences

#### 3.6.1.1. PBAP connection

This feature establishes PBAP connection with or without authentication using PBAP Client as an initiator.

- 1) Establish connection without authentication.

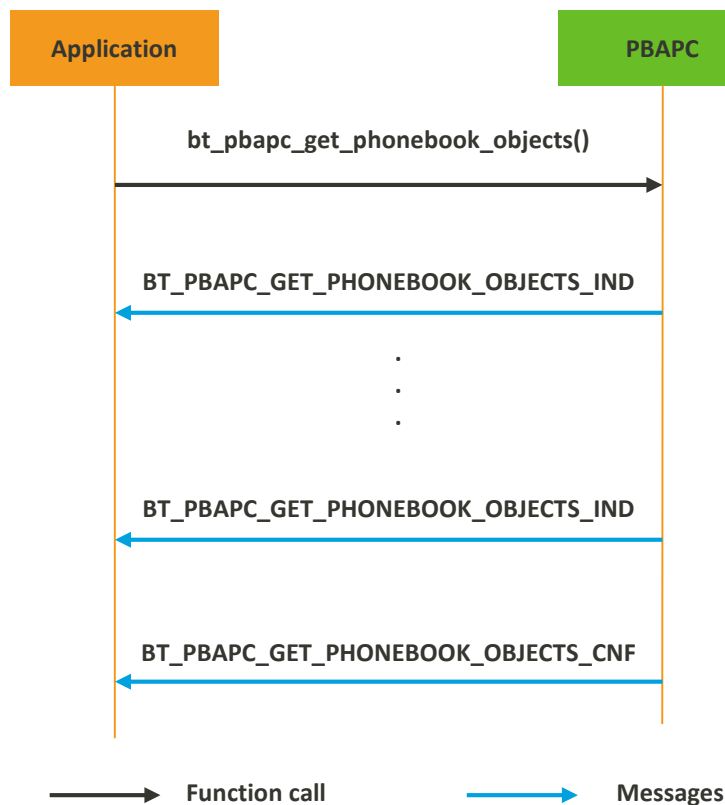
The message sequence is shown in Figure 42. For more details, see `bt_pbapc.h`.



**Figure 42. PBAPC connection establishment without authentication message sequence**

### 3.6.1.2. Get phonebook objects

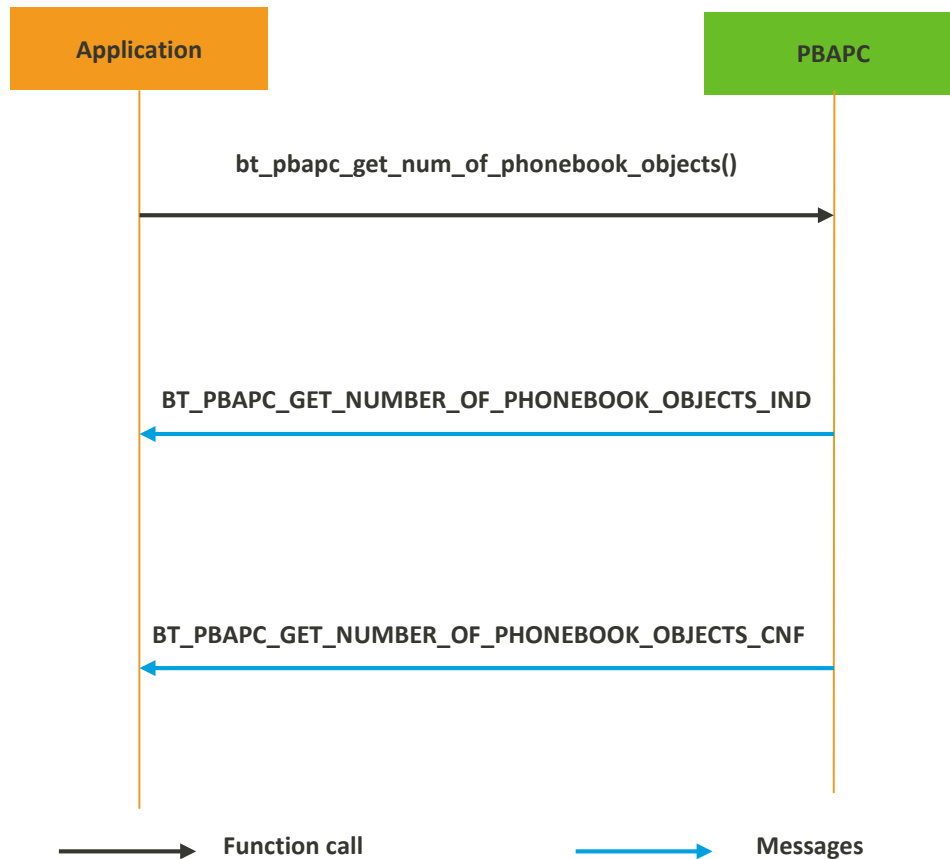
This feature is used to pull phonebook object's content. The data is in vCard format and the attribute of vCard depends on the PBAP Client's request parameter, such as the version number of the vCard (2.1 or 3.0) or the offset in the vCard. vCard 3.0 is used in Airoha IoT SDK v4.0.0 for RTOS. The message sequence is shown in Figure 43 . For more details, see `bt_pbapc.h`.



**Figure 43. PBAPC get phone book object message sequence**

## 3.6.1.3. Get the number of phonebook objects by PullPhonebook

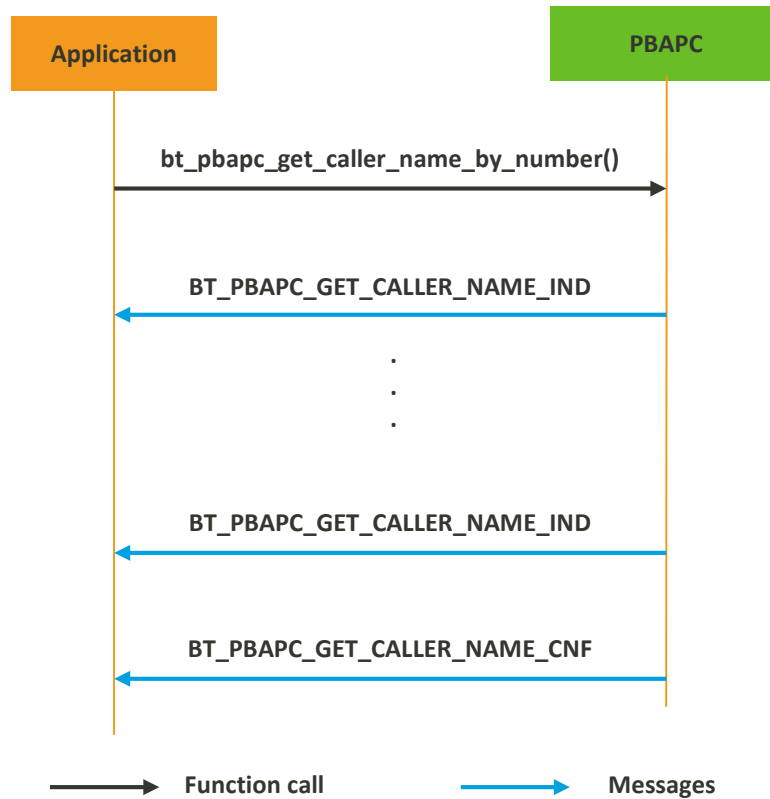
This feature is used to obtain the number of phonebook objects of type “Missed Calls History” or “Main Phone Book” from the PBAP Server by calling the PullPhonebook function after connection is established. For more information about this feature, refer to PBAP specification. The message sequence is shown in Figure 44. For more details, see `bt_pbapc.h`.



**Figure 44. PBAPC get the number of phonebook objects message sequence**

## 3.6.1.4. Get the caller name by number

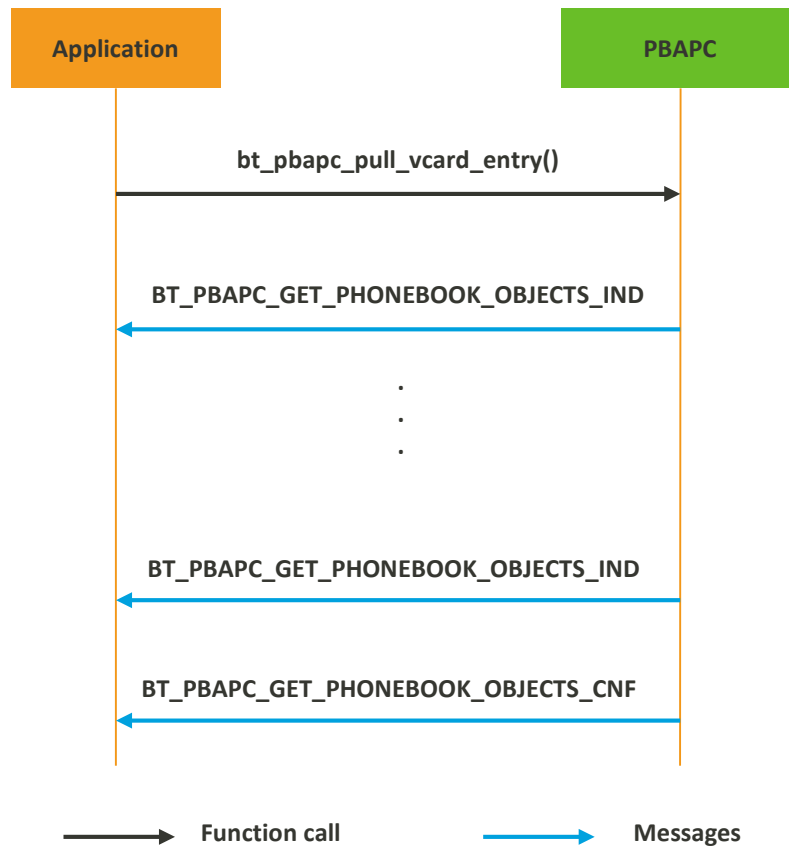
This feature is used to get the caller name by number by calling the PullvCardListing function. First, get the phonebook listing object from the PBAP Server. Then get the name field by parsing an XML file. The sequence is shown in Figure 45. For more details, see `bt_pbapc.h`.



**Figure 45. PBAPC get caller name by number message sequence**

### 3.6.1.5. PullvCardEntry Function

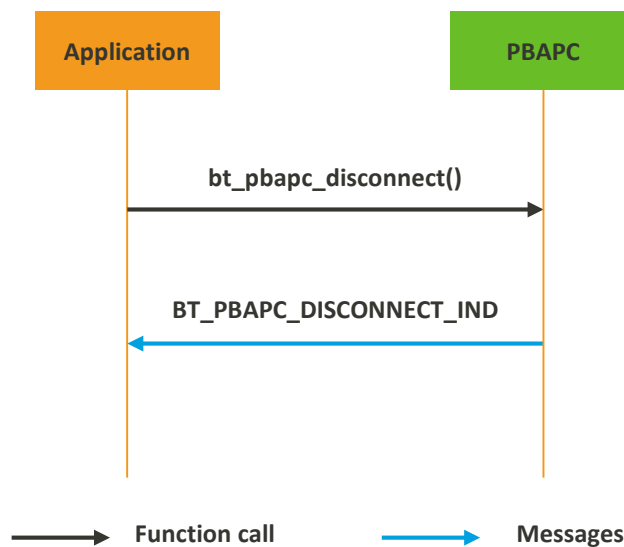
This function is used to retrieve a specific vCard from the PBAP Server. The sequence is shown in Figure 46. For more details, refer to `bt_pbapc.h`.



**Figure 46. PBAPC PullVCardEntry message sequence**

### 3.6.1.6. Connection release

This feature disconnects the PBAPC connection (see Figure 47). For more details, refer to `bt_pbapc.h`.



**Figure 47. Disconnect message sequence**

## 3.6.2. Using the PBAPC APIs

This section describes the PBAPC API usage for your application development. The source code of the PBAPC APIs is implemented in the library code but header functions can be found in `bt_pbapc.h`.

- 1) Initiate a connection to PBAP server from the PBAPC, call the APIs as follows:
  - a) Call `bt_pbapc_connect()` API to send a connect request.
  - b) The application gets the event `BT_PBAPC_CONNECT_CNF` to indicate the connection request result.
- 2) Implement the `bt_app_event_callback()` API. The API is called for events to notify the application or perform a task in this callback.

```
void bt_app_event_callback(bt_msg_type_t event_id, bt_status_t status,
    const void *param);
```

- 3) Get the number of phonebook objects by calling the following function.

```
bt_status_t bt_pbapc_get_num_of_phonebook_objects(uint32_t handle,
    bt_pbapc_phonebook_type_t type);
```

- a) The `BT_PBAPC_GET_NUMBER_OF_PHONEBOOK_OBJECTS_IND` event will notify application callback function with the data including the number of phonebook objects received from the remote device.
- b) The `BT_PBAPC_GET_NUMBER_OF_PHONEBOOK_OBJECTS_CNF` event will notify the application callback function to indicate the result of the request.

- 4) Retrieve vCard objects from the remote device by calling the following function.

```
bt_status_t bt_pbapc_get_phonebook_objects(uint32_t handle, uint16_t
    offset, bt_pbapc_phonebook_type_t type);
```

- a) The `BT_PBAPC_GET_PHONEBOOK_OBJECTS_IND` event will notify application callback function to indicate there is data received from a remote device. It will include name field, name length, number field and number length.
- b) The `BT_PBAPC_GET_PHONEBOOK_OBJECTS_CNF` event will notify the application callback function to indicate the result of the request.

- 5) Get caller name by number with the following function.

```
bt_status_t bt_pbapc_get_phonebook_objects(uint32_t handle,
    uint8_t*number);
```

- a) The `BT_PBAPC_GET_CALLER_NAME_IND` event will notify application callback function to indicate there is data received from the remote device, it will include name field, name length.
- b) The `BT_PBAPC_GET_CALLER_NAME_CNF` event will notify the application callback function to indicate the result of the request.

- 6) Pull the specific vCard with the following function.

```
bt_status_t bt_pbapc_pull_vcard_entry(uint32_t handle, uint8_t index);
```

- a) The `BT_PBAPC_GET_PHONEBOOK_OBJECTS_IND` event will notify application callback function to indicate there is data received from a remote device, it will include name field, name length, number field and number length.
- b) The `BT_PBAPC_GET_PHONEBOOK_OBJECTS_CNF` event will notify the application callback function to indicate the result of the request.

- 7) To disconnect the current connection, call this function in the application.

```
bt_status_t bt_pbapc_disconnect(uint32_t handle);
```

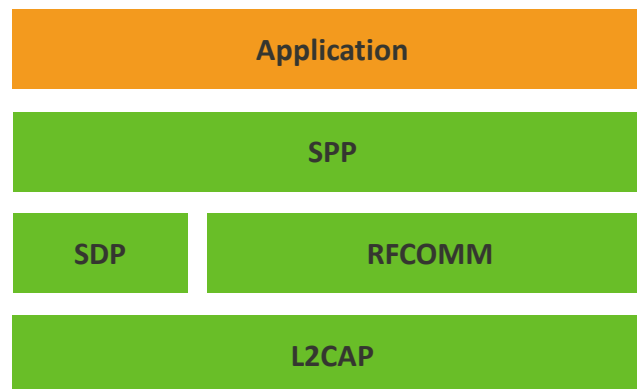
- a) The BT\_PBAPC\_DISCONNECT\_IND event will notify the application callback function to indicate the result of the request.

## 3.7. SPP

The SPP provides protocols and procedures for devices using Bluetooth for RS232 (or similar) serial cable emulation.

The SPP defines two roles, SPP client (Device A) and SPP server (Device B).

- **SPP client** — a device that takes the initiates connection with another device.
- **SPP server** — a device that waits for another device to take the initiative to connect.



**Figure 48. SPP abstraction layout**

The SPP is dependent upon the RFCOMM and SDP, as shown in Figure 48. RFCOMM is the Bluetooth adaptation of GSM TS 07.10, providing a transport protocol for serial port emulation. SDP is the Bluetooth Service Discovery Protocol.

### 3.7.1. The SPP message sequences

SPP enables the following functionality.

- 1) Connection establishment
- 2) Connection release
- 3) Data transfer

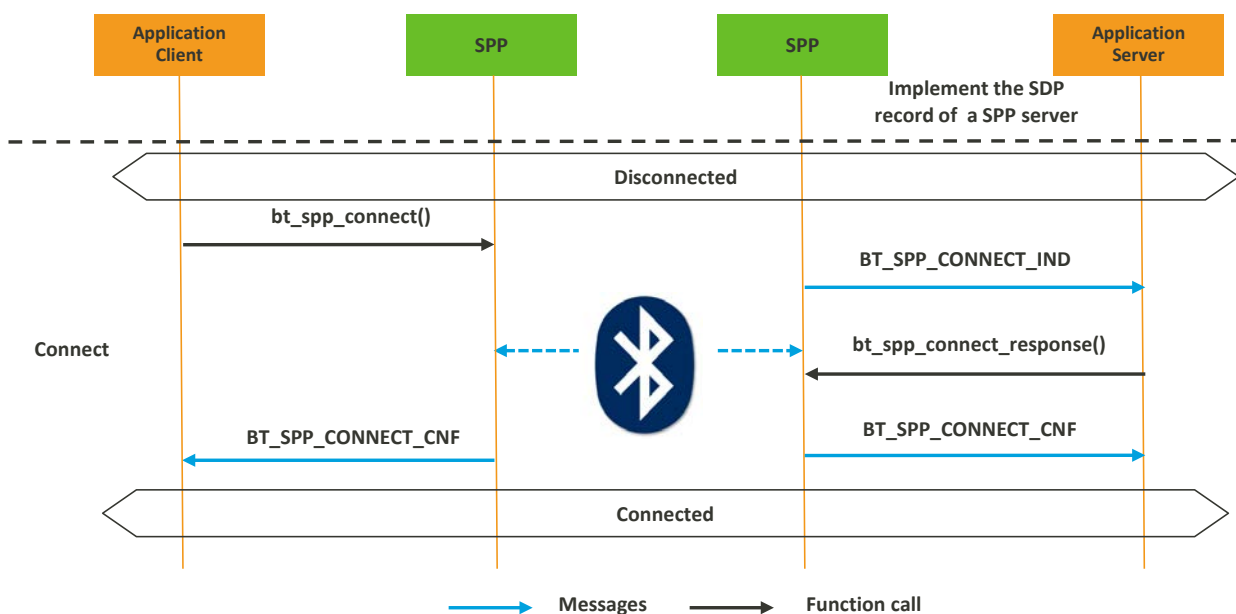
The message sequence for each procedure will be described in the upcoming sections.

#### 3.7.1.1. Connection establishment

According to the SPP specification, SPP connection is initiated by the SPP client. The SPP server must implement an SDP record for an emulated serial port before the connection is initiated. For more details about SPP record implementation, refer to `bt_spp.h`.

The connection establishment procedure between the SPP client and the SPP server is shown in Figure 49. For more details, refer to `bt_spp.h`.

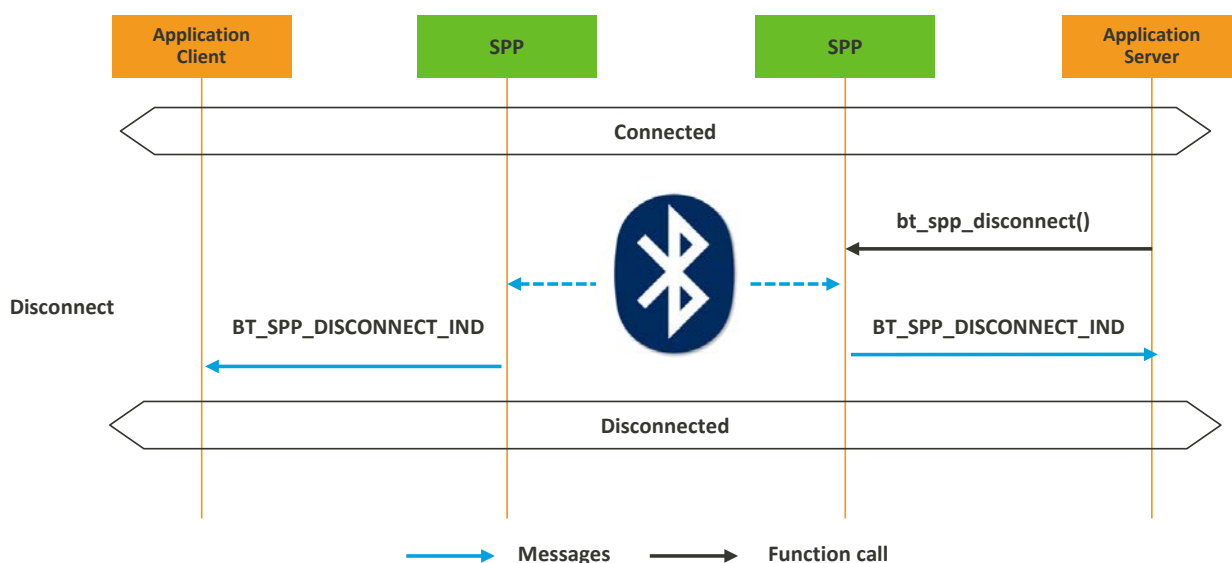




**Figure 49. SPP connection establishment message sequence**

### 3.7.1.2. Connection release

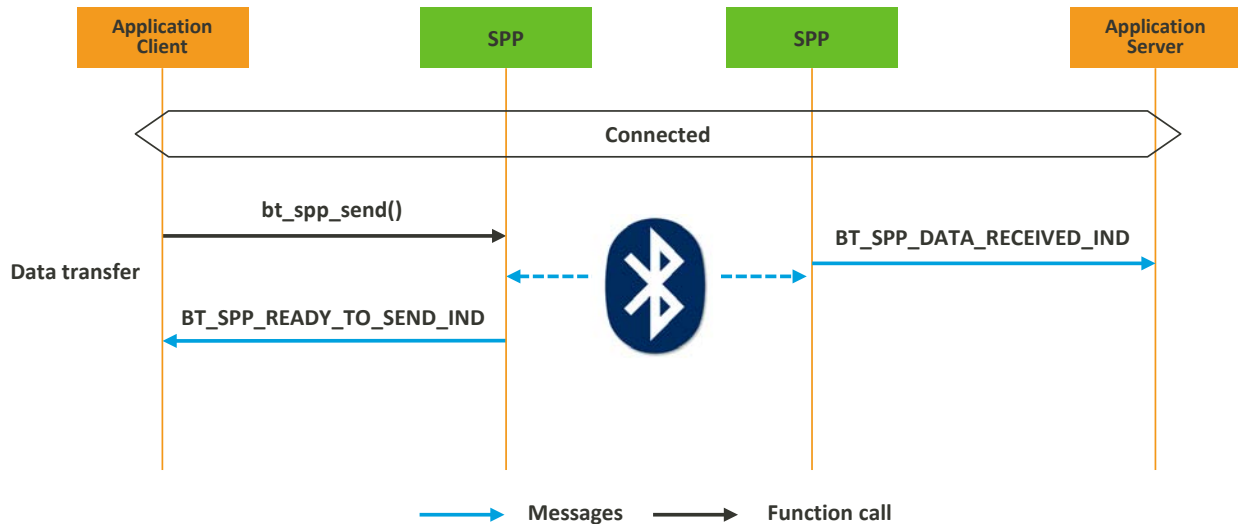
The SPP connection release can be initiated by both the SPP client and the SPP server, as shown in Figure 50. More details can be found in the header file `bt_spp.h`.



**Figure 50. SPP connection release message sequence**

### 3.7.1.3. Data transfer

During the SPP connection, the application data can be transferred between the SPP server and the SPP client, as shown in Figure 51. There is no restriction, both the SPP server and the SPP client are able to initiate to send and receive data. More details can be found in the header file `bt_spp.h`.



**Figure 51. SPP data transfer message sequence**

## 3.7.2. Using the SPP APIs

This section describes how to use the SPP APIs for the application development. The source code of the SPP APIs is implemented in the binary library code but the headers can be found in `bt_spp.h`.

The SDK supports client and server roles and all SPP APIs can be classified into three categories.

- 1) Common APIs
- 2) Server-specific APIs
- 3) Client-specific APIs

### 3.7.2.1. Common APIs

- 1) Implement the API `bt_app_event_callback()`. All SPP events will be generated to trigger this function to notify the application.

```
void bt_app_event_callback(bt_event_t event_id, const void *param);
```

- 2) Disconnect the SPP connection from the SPP server or client. The `BT_SPP_DISCONNECT_IND` event notifies `bt_app_event_callback()` to indicate the result of the disconnection.

```
bt_status_t bt_spp_disconnect(uint32_t handle);
```

- 3) Application can send data to the remote device using the SPP connection.

```
bt_status_t bt_spp_send(
uint32_t handle,
uint8_t *packet,
uint16_t packet_length);
```

- 4) Application call hold the SPP data to the Bluetooth RX buffer if it is no free buffer to save the SPP data from the `BT_SPP_DATA_RECEIVED_IND`.

```
void bt_spp_hold_data(uint8_t *data);
```

- 5) Call this function to release the data once it's saved in the application.

```
void bt_spp_release_data(uint8_t *data);
```

## 3.7.2.2. Server-specific APIs

- 1) Implement the API `bt_sdps_get_customized_record()` to provide the SPP record and record number. More details can be found in the header file `bt_sdp.h`. More details about SPP record implementation can be found in the header file `bt_spp.h`.

```
uint8_t bt_sdps_get_customized_record(const bt_sdps_record***
record_list);
```

- 2) If the `BT_SPP_CONNECT_IND` event is generated to trigger `bt_app_event_callback()`, that means the remote SPP client has initiated a connection request to the SPP server. Then the SPP server can respond (accept or reject) this connection request. Finally, the `BT_SPP_CONNECT_CNF` event is generated to trigger `bt_app_event_callback()`. It then notifies the application with the result of this SPP connection establishment.

```
bt_status_t bt_spp_connect_response(uint32_t handle, bool accept);
```

## 3.7.2.3. Client-specific APIs

Initiate a connection to a remote SPP server using the SPP client. The `BT_SPP_CONNECT_CNF` event is generated to trigger `bt_app_event_callback()`. Then it notifies the application with the result of this SPP connection establishment.

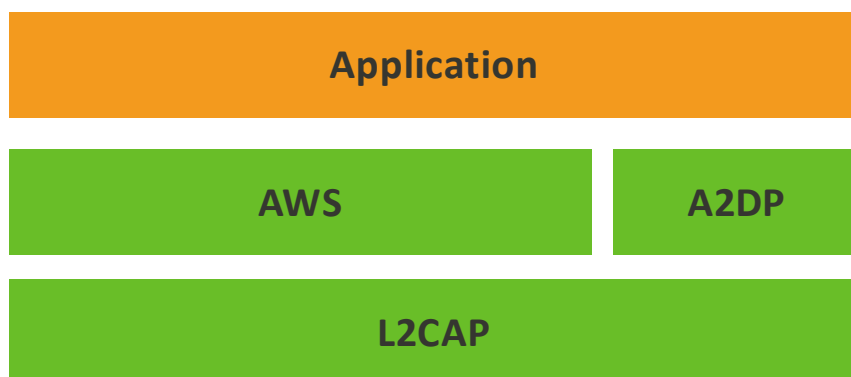
```
bt_status_t bt_spp_connect(
    uint32_t *handle,
    const bt_bd_addr_t *address,
    const uint8_t *uuid128);
```

## 3.8. AWS

The Advanced Wireless Stereo (AWS) is Airoha proprietary profile that defines the minimum set of functions such that two devices can transfer audio data and synchronize the audio status.

The AWS has two roles (Sink and Source) defined for smart devices. The Source (SRC) acts as a digital audio streaming source that is delivered to the Sink (SNK) of the piconet. The SNK acts as a sink of a digital audio streaming delivered from the SRC on the same piconet.

The AWS stack architecture layout is shown in Figure 52.



**Figure 52. The AWS abstraction layout**

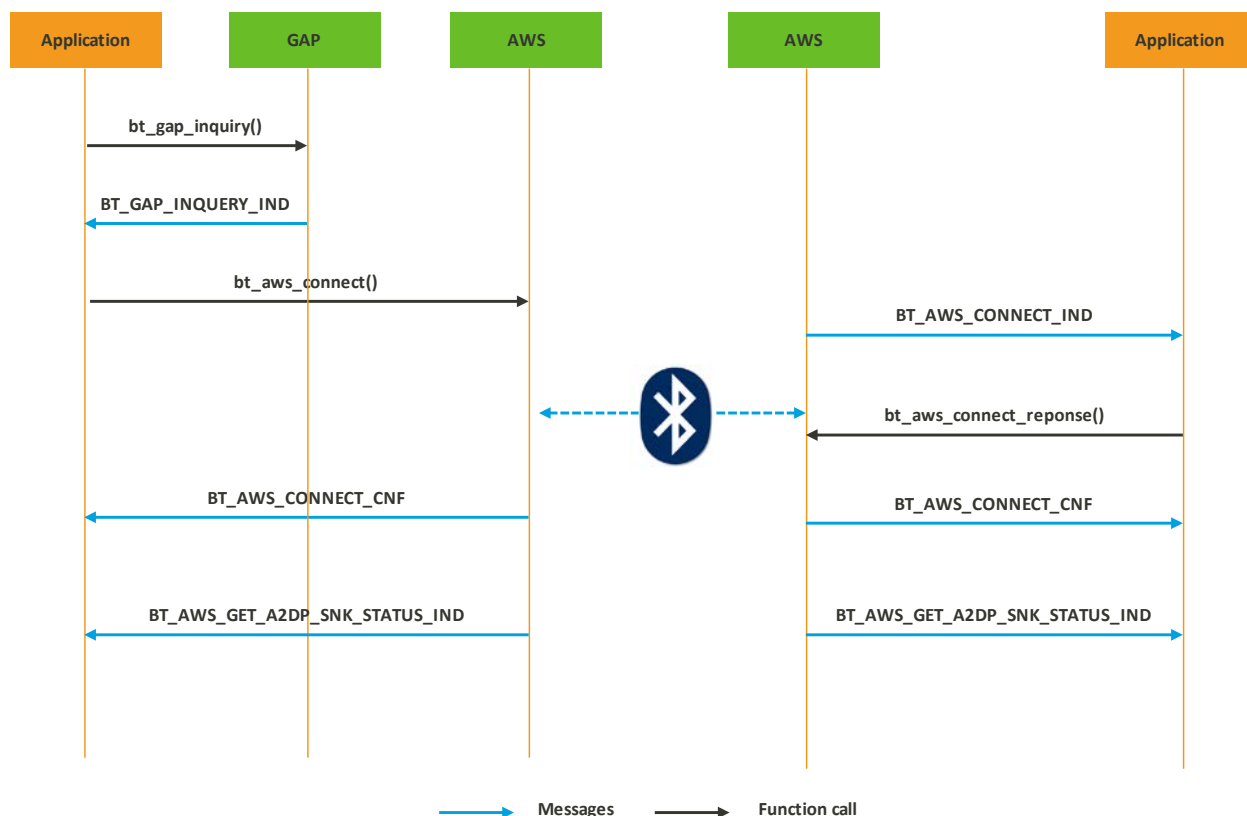
The AWS relies on the L2CAP, which defines procedures to transfer data..

## 3.8.1. The AWS message sequences

There are five operations available for the AWS: connection establishment, connection release, start streaming, suspend steaming and reconfiguration. The message sequence for each procedure is described in the following sections.

### 3.8.1.1. Connection establishment

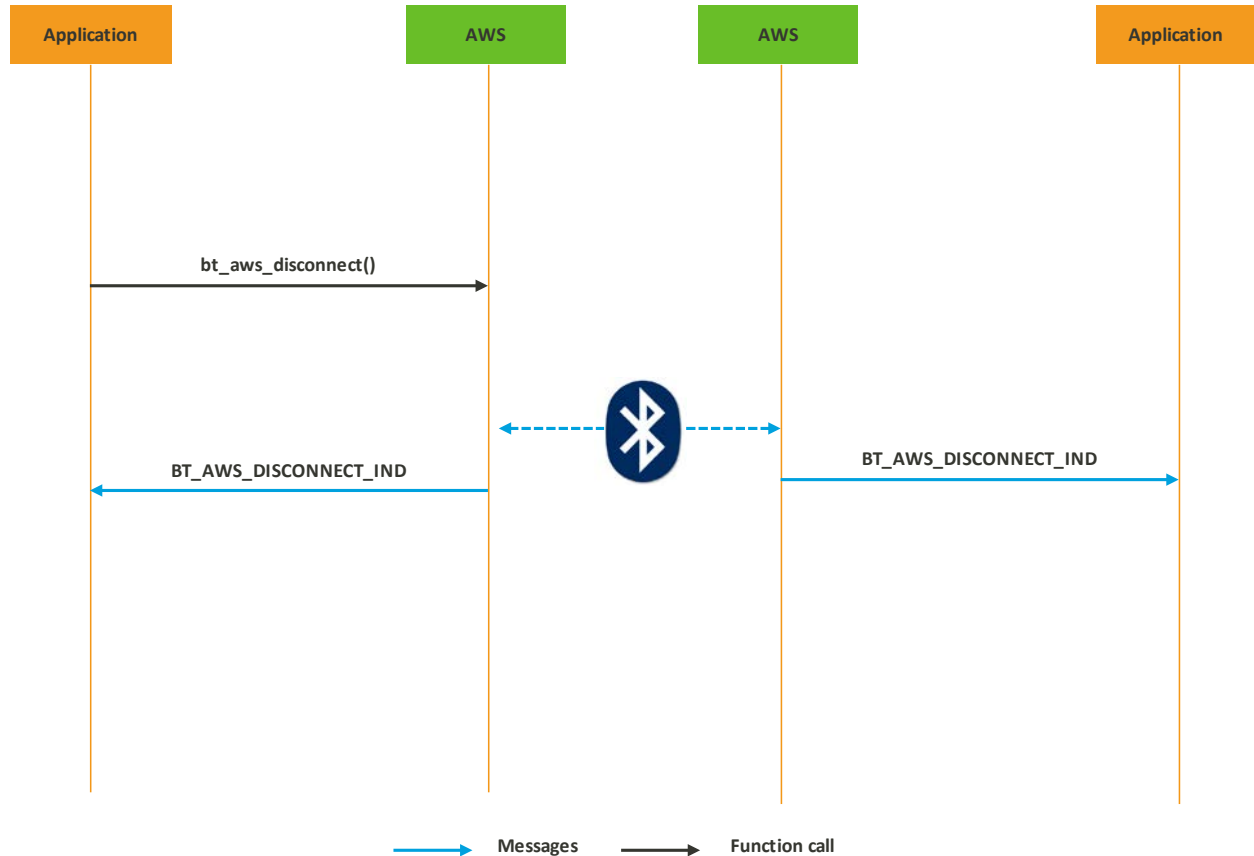
Apply this process to establish a streaming connection with both devices, as shown in Figure 53. The SDK provides two different message sequences, one for initiator (left) and another for acceptor (right). For more details, refer to `bt_aws.h`.



**Figure 53. The AWS connection establishment message sequence**

### 3.8.1.2. Connection release

Connection release procedure disconnects the AWS connection, as shown in Figure 31. Both devices can initiate AWS disconnection and accept the remote device's request to release the connection. For more details, refer to `bt_aws.h`.

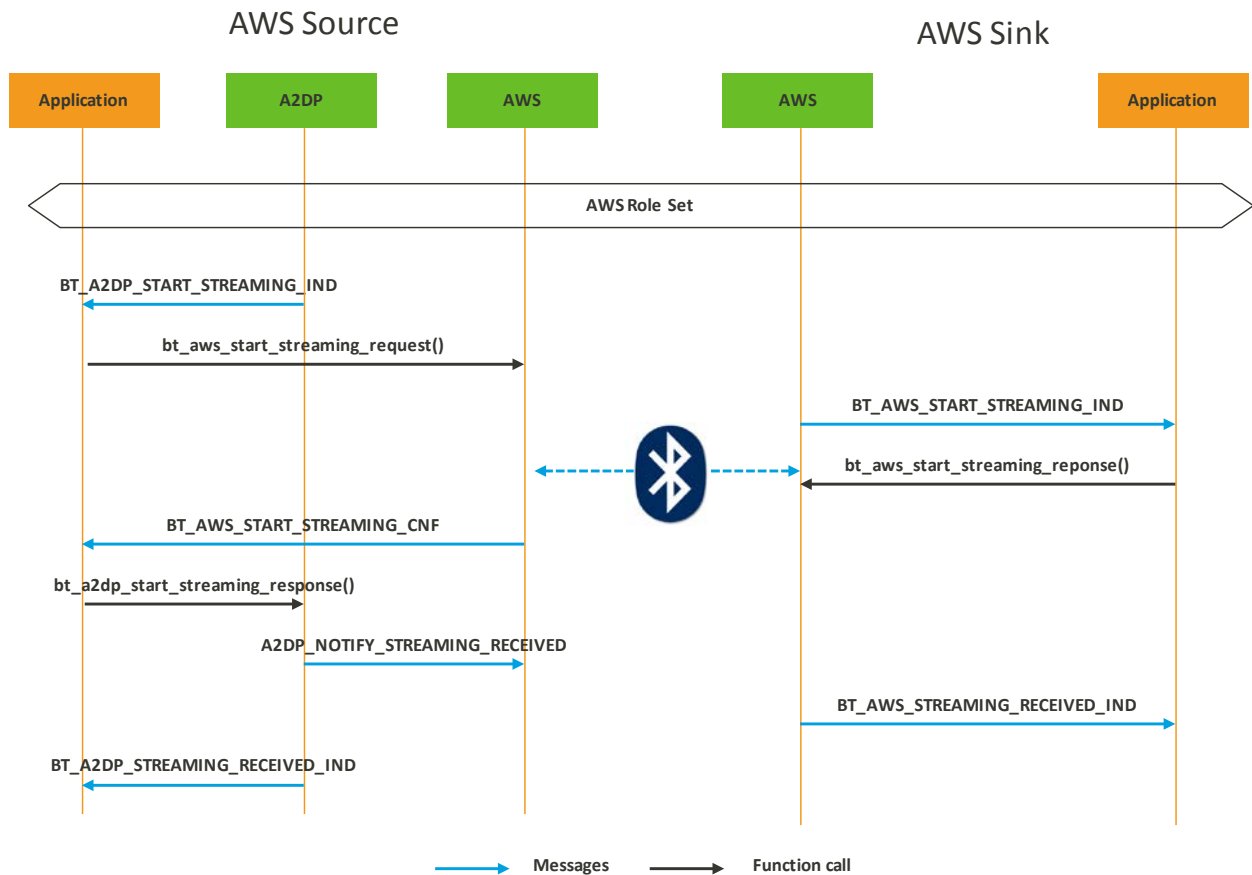


**Figure 54. The AWS connection release message sequence**

### 3.8.1.3. Start streaming

The sequence to start or resume the audio streaming is shown in Figure 55. The AWS SRC device plays an acceptor role that responds to an incoming request from the initiator, such as smartphone. The AWS SNK device plays an acceptor role that responds to an incoming request from the AWS SRC. For more details, refer to `bt_aws.h`.

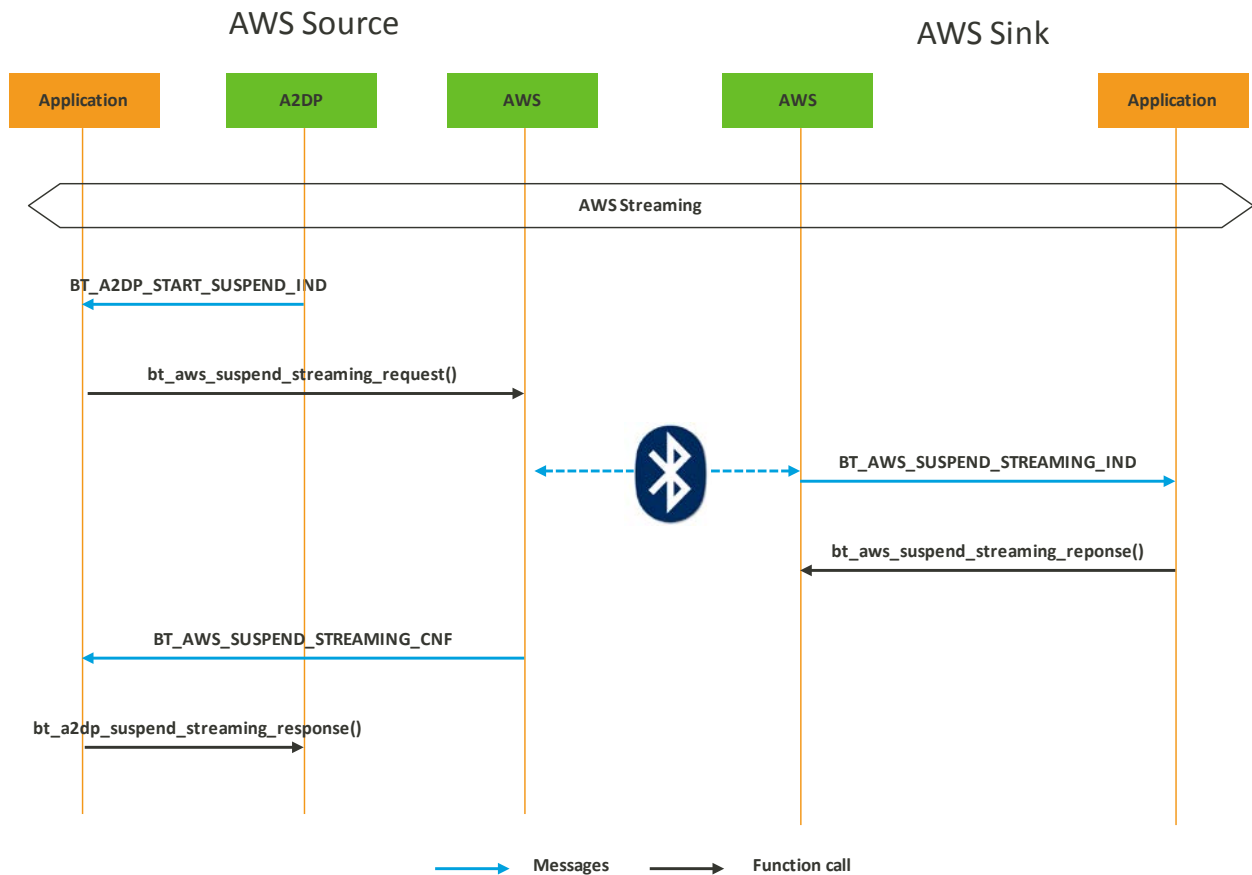
Once the streaming starts, the application interacts with audio module to open the codec configured previously and send streaming data to audio module. For more details, see section 3.8.2, “Interaction with audio”.



**Figure 55. The AWS start streaming message sequence**

### 3.8.1.4. Suspend streaming

The sequence to suspend the audio streaming is shown in Figure 56. In the meantime, the application notifies the audio module to close the codec and pause the audio so that the audio resource is released. For more details, refer to `bt_aws.h`.



**Figure 56. The AWS suspend streaming message sequence**

## 3.8.2. Interaction with audio

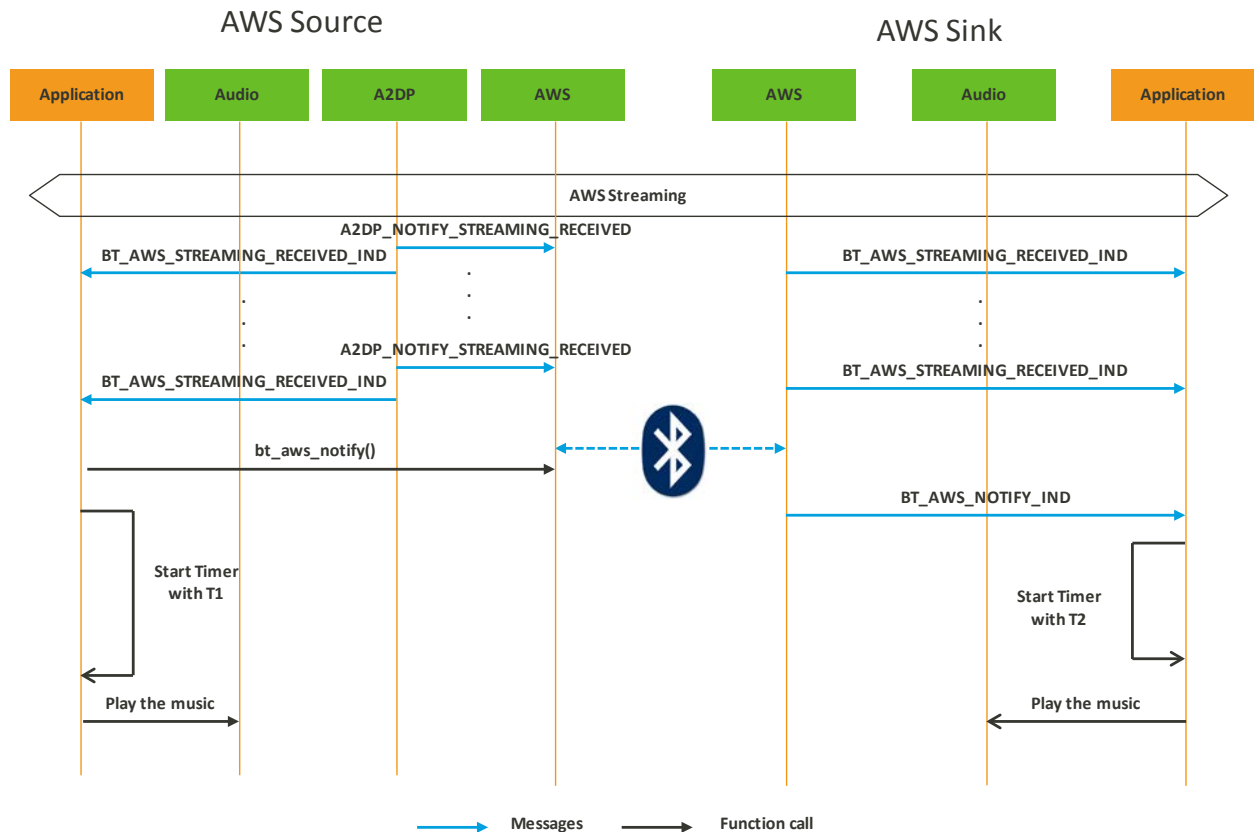
To play the audio, both SRC and SNK devices need to negotiate and configure the A2DP audio codec. The audio codec type is the same as for A2DP streaming. The application needs to handle the AWS audio packet with audio manager.

### 3.8.2.1. Open and close the codec

The format of the AWS streaming data is the same as for A2DP. To learn more on how to open and close the codec, refer to section 3.4.2, "Interaction with audio".

### 3.8.2.2. Synchronize the voice

In order to synchronize the voice between two AWS devices, it's recommended to buffer enough audio data and set a delay play time before playing the audio. The AWS provides a notification ID `BT_AWS_NOTIFY_ID_READY_TO_PLAY` to calculate how long the AWS SNK needs to start playing the music (see Figure 57).



**Figure 57. The AWS voice message synchronization sequence**

### 3.8.3. Using the AWS APIs

This section describes how to use the AWS APIs in your application. The functionality of the AWS APIs is implemented in the library code but header functions can be found in `bt_aws.h`.

- 1) Call the `bt_aws_connect()` function to connect to a remote device and then expect to receive the event `BT_AWS_CONNECT_CNF`, as shown in `bt_app_event_callback(bt_msg_type_t msg_id, bt_status_t status, void *buff)`.

```
ret = bt_aws_connect(&aws_handle, address);
```

- 2) Call the following API to disconnect from a remote device and then expect to receive the event `BT_AWS_DISCONNECT_IND`, as shown in `bt_app_event_callback(bt_msg_type_t msg_id, bt_status_t status, void *buff)`.

```
bt_aws_disconnect(aws_handle);
```

- 3) Both of the AWS devices need to play the first packet at the same time. The SRC needs to pass the current Bluetooth clock and play time to SNK and start a timer to play. The SNK needs to start a timer to play after receiving the notification ID `BT_AWS_NOTIFY_ID_READY_TO_PLAY`.

```
//Device SRC
//get current bt clock.
bt_aws_get_bt_local_time(&sink_loc_play_nclk, &sink_loc_play_nclk_intra);
aws_notify.op_id = BT_AWS_NOTIFY_ID_READY_TO_PLAY;
aws_notify.play_time.play_time = time_dur;
aws_notify.play_time.loc_play_nclk = sink_loc_play_nclk;
aws_notify.play_time.loc_play_nclk_intra = sink_loc_play_nclk_intra;
//notify remote device ready to play
```



```
err = bt_aws_notify(aws_dev->aws_hd, &aws_notify);
//start timer to wait to play
hal_gpt_start_timer_us(cntx->gpt_port, time_dur,
HAL_GPT_TIMER_TYPE_ONE_SHOT);
//play the music when the time is up.
//-----
// Device SNK
// after receiving the notify ID BT_AWS_NOTIFY_ID_READY_TO_PLAY, start a
timer to play the music.
time_dur = notify_ind->param->play_time.play_time;
hal_gpt_register_callback(cntx->gpt_port,
                        bt_sink_srv_aws_gpt_cb, (void *)dev);
gpt_ret = hal_gpt_start_timer_us(cntx->gpt_port, time_dur,
HAL_GPT_TIMER_TYPE_ONE_SHOT);
//play the music when the time is up
```

- 4) The application needs to implement a utility function to hold the media data node and fetch data callback. If media data is received from the A2DP or AWS, the data node serves as a buffer to store the received data to later identify and locate it. Fetch data callback is called to fill the media data from data node in a buffer when the codec driver starts decoding. Remember to release the data node if the media data is fully copied.

- a) Hold the media data node.

```
#define MEDIA_PKT_HEADER_LEN 12 // Media packet header 12 Bytes.
typedef struct _bt_media_packet_node{
    _bt_media_packet_node *node;
    uint16_t packet_length;
    uint16_t offset;
} bt_media_packet_node_t;
void bt_a2dp_keep_media_data_node(bt_media_packet_node_t *data_node,
int16_t offset, int16_t total_len)
{
    void* p_payload = data_node + offset + MEDIA_PKT_HEADER_LEN;
    *payload_len = total_len - offset - MEDIA_PKT_HEADER_LEN;
    // Search the payload start pointer for AAC.
    if (g_a2dp_codec.type == BT_A2DP_CODEC_AAC) {
        uint8_t payload_offset = 9;
        uint8_t media_start_pos = 0;
        do {
            media_start_pos = ((uint8_t *) p_payload)[payload_offset];
            payload_offset++;
        } while (media_start_pos != 0xFF);
        *payload_len -= payload_offset;
        p_payload += payload_offset;
    }
    data_node->offset = p_payload - (void *)data_node;
    data_node->packet_length = total_len;
    // Insert the data_node at the end of data node buffer list.
    bt_a2dp_hold_media_data_node(data_node);
}
```

- b) Implement fetch data callback.

Fetch the data node from data buffer list to `data_node` and copy the media data to `dsp_buff`. If the media data length in data node is less than `dsp_buff` length, then

- i) Remove the data node from the list and release it;
- ii) Fetch the data node and copy again, until the buffer is empty or the `dsp_buffer` is full.

If the media length is more than dsp\_buff length, then

- iii) Do not remove data\_node before it's filled with received data.
- iv) Modify the remaining media offset only.

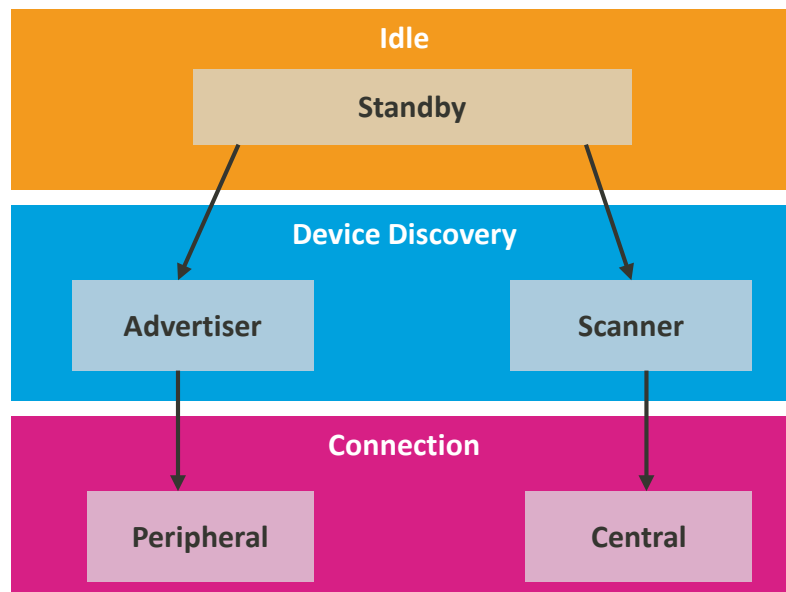
```
int32_t bt_sink_codec_get_data_callback(volatile uint16_t *dsp_buff,
uint32_t len)
{
    bt_media_packet_node_t *data_node = NULL;
    int16_t media_len;
    uint32_t filled_length;
    // Fetch the bt media packet node and fill the received data in the
node to dsp_buffer.
    // Note: The data should be filled in units of Word.
    return filled_length;
}
```

## 4. The Bluetooth Low Energy Protocol or Profiles

The addition to the Airoha IoT SDK for Bluetooth support is provided as a collection of binary library files. This section provides details on the GAP, SM and GATT profiles.

### 4.1. GAP

The Bluetooth LE GAP is responsible for connection and device management, including device configuration, device discovery, and connection establishment and termination, as shown in Figure 15.



**Figure 58. GAP state diagram**

- **Standby** — initial idle state when the Bluetooth powers on.
- **Advertiser** — the device is advertising with specific data to provide information to nearby devices about the advertiser, including the device address, advertising type and advertising data.
- **Scanner** — the device searches for nearby devices, based on the type of scanning and advertisement, it may send a scan request to the advertiser. The scanner can get more information in the scan response from the advertiser. Once the discovery is complete, the scanner can initiate a connection or not with the advertiser based on the advertising type.
- **Peripheral/Central** — once the scanner initiates a connection to the advertiser, the advertiser device will function as a peripheral device and the scanner device will be a central device.

The application and profiles can directly invoke Bluetooth LE GAP API functions to perform Bluetooth LE related functions, such as scan or connect, as shown in Figure 59. More details can be found in the header file `bt_gap_le.h`.

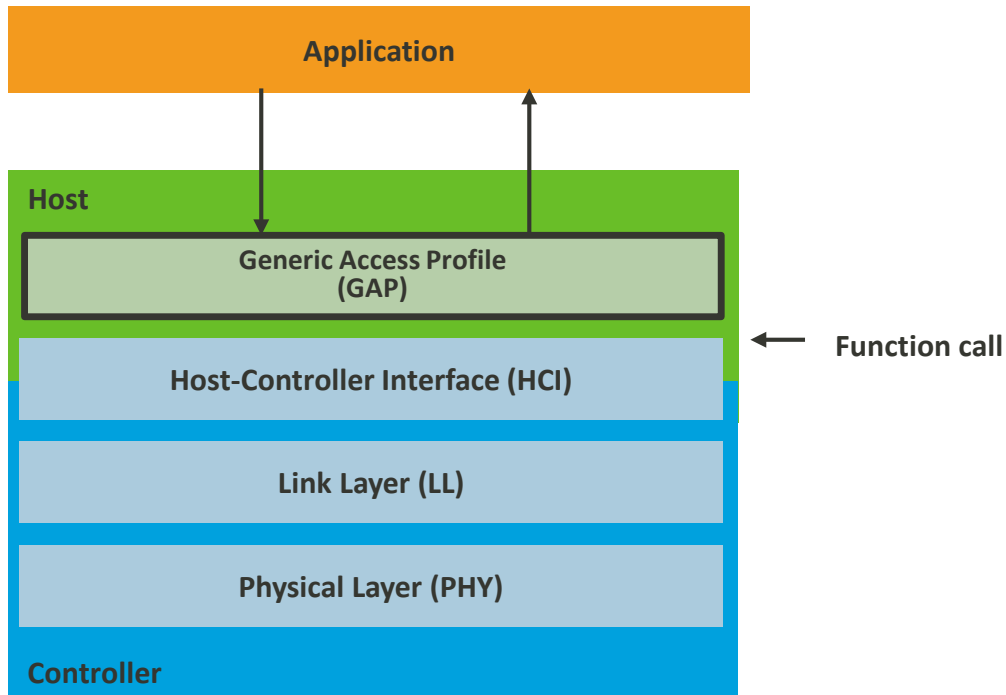
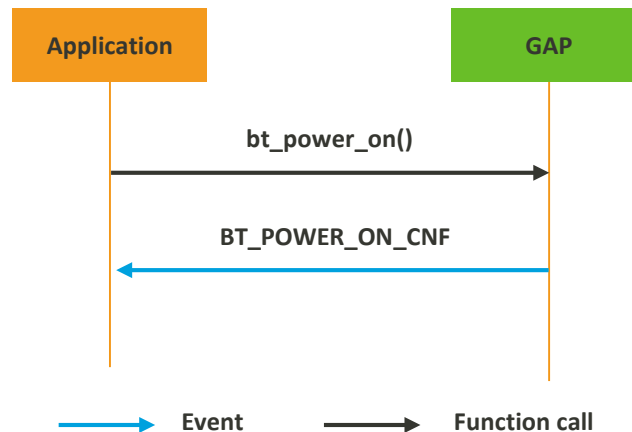


Figure 59. GAP abstraction layout

#### 4.1.1. Power on

Call the `bt_power_on()` function in the `main()` function to enable the Bluetooth. The `BT_POWER_ON_CNF` event is received after successful completion, as shown in Figure 16. More details can be found in the header file `bt_system.h`.

```
bt_status_t bt_app_event_callback(bt_msg_type_t msg, bt_status_t status,
void *buff)
{
    switch (msg) {
        case BT_POWER_ON_CNF:
        {
            break;
        }
    }
    return BT_STATUS_SUCCESS;
}
```



**Figure 60. Powering on the Bluetooth message sequence**

#### 4.1.2. Start advertising

Start advertising to enable device discovery and connectivity, as shown below.

```

void app_fun(void)
{
    bt_hci_cmd_le_set_advertising_enable_t adv_enable = {
        .advertising_enable = BT_HCI_ENABLE,
    };
    bt_hci_cmd_le_set_advertising_parameters_t adv_para = {
        .advertising_interval_min = 0x0800,
        .advertising_interval_max = 0x0800,
        .advertising_type = BT_HCI_ADV_TYPE_CONNECTABLE_UNDIRECTED,
        .advertising_channel_map = 7,
        .advertising_filter_policy = 0
    };
    bt_hci_cmd_le_set_advertising_data_t adv_data = {0};
    char dev_name[] = "My Device";

    adv_data.advertising_data_length = strlen(dev_name) + 2;
    adv_data.advertising_data[0] = strlen(dev_name) + 1;
    adv_data.advertising_data[1] = BT_GAP_LE_AD_TYPE_NAME_COMPLETE;
    memcpy(adv_data.advertising_data + 2, dev_name, strlen(dev_name));

    bt_gap_le_set_advertising(&adv_enable, &adv_para, &adv_data, NULL);

    return;
}

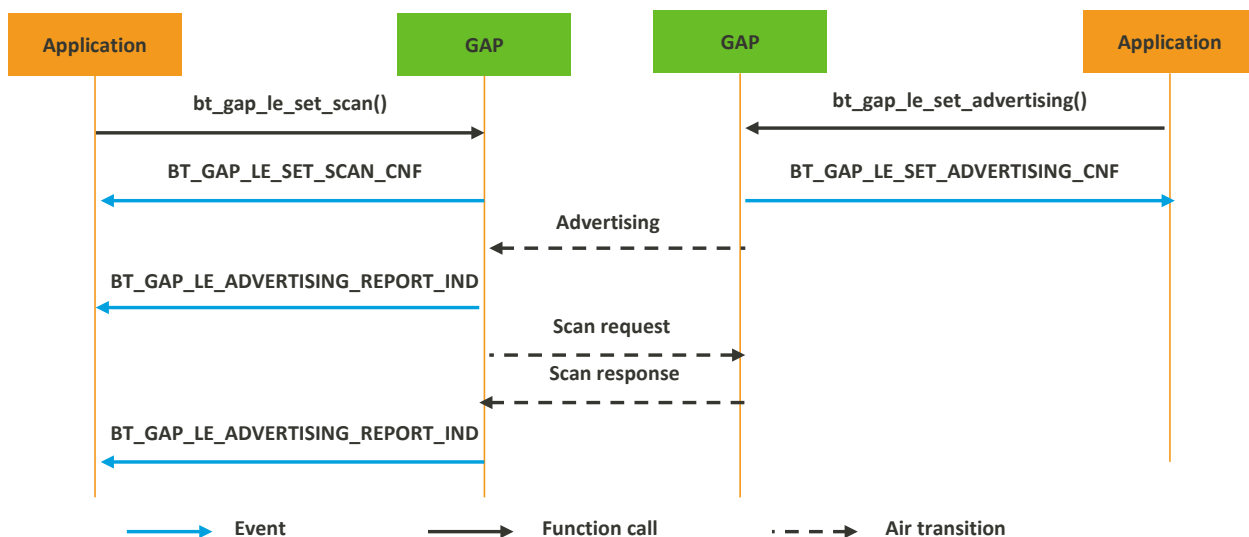
```

##### 4.1.2.1. Advertising and scan response data format

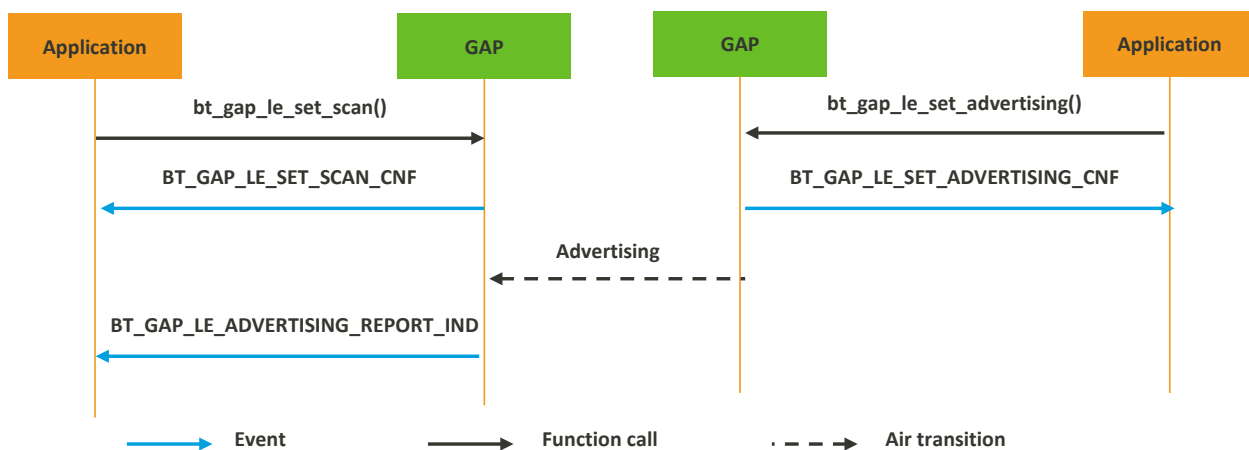
The format of advertising data can be found in the Bluetooth Core Specifications version 4.2 [VOL 3, Part C, 11], Bluetooth GAP and in the Specification of the Bluetooth system.

#### 4.1.3. Searching the nearby devices

The device scans for the nearby devices, as shown in Figure 61 and Figure 62. More details can be found in the header file `bt_gap_le.h`.



**Figure 61. GAP active scan message sequence**



**Figure 62. GAP passive scan message sequence**

An example code to provide GAP active scan (see Figure 61) is shown below:

```

void app_fun(void)
{
    bt_hci_cmd_le_set_scan_parameters_t scan_params;

    //Set scan parameters.
    scan_params.le_scan_type = BT_HCI_SCAN_TYPE_PASSIVE;
    scan_params.own_address_type = BT_HCI_SCAN_ADDR_PUBLIC;
    scan_params.le_scan_interval = 0x0024;
    scan_params.le_scan_window = 0x0011;
    scan_params.scanning_filter_policy = 0x00;

    bt_hci_cmd_le_set_scan_enable_t enable;
    enable.le_scan_enable = BT_HCI_ENABLE;
    enable.filter_duplicates = BT_HCI_ENABLE;

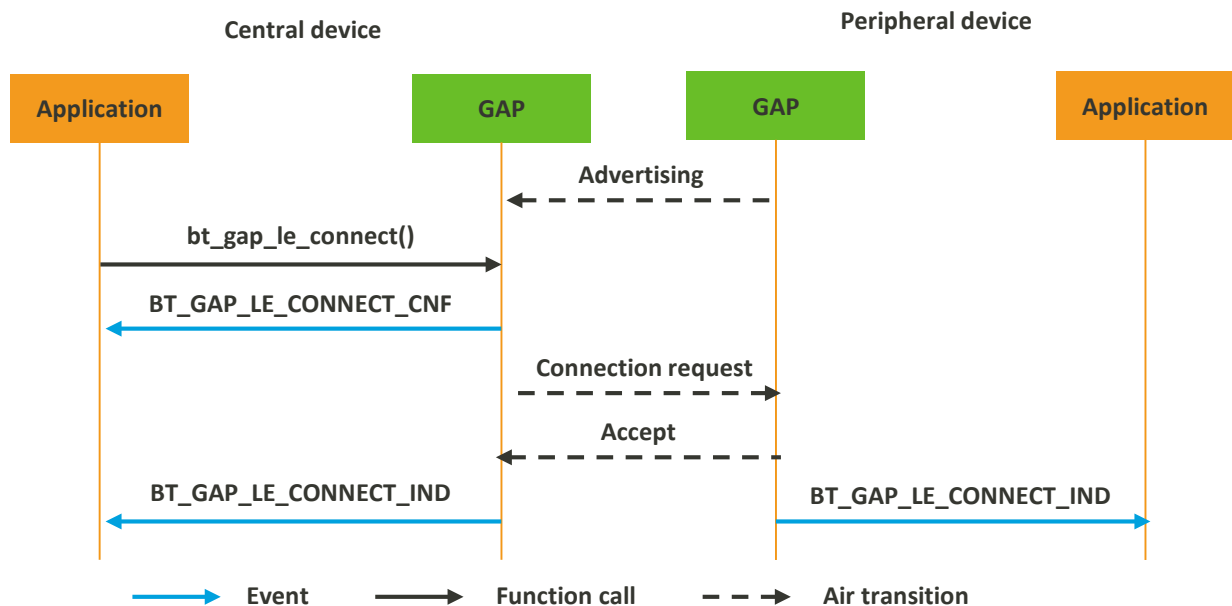
    //Start the scanner.
    bt_gap_set_scan(&enable, &param);
}
    
```

```
bt_status_t bt_app_event_callback(bt_msg_type_t msg, bt_status_t status,
void *buff)
{
    switch (msg) {
        case BT_GAP_LE_ADVERTISING_REPORT_IND:
        {
            const bt_gap_le_advertising_report_ind_t *report =
                (bt_gap_le_advertising_report_ind_t *)buff;
            // Log advertising report information.
        }
    }
    return BT_STATUS_SUCCESS;
}
```

## 4.1.4. Connecting

There are two ways to create a Bluetooth LE connection, a general connection and auto connection.

- 1) General connection. It enables the host to establish a connection with a specified device, as shown in Figure 63. More details can be found in the header file `bt_gap_le.h`.



**Figure 63. GAP general connection message sequence**

An example code to provide general connection (see Figure 63) is shown below.

```
void app_fun(void)
{
    bt_hci_cmd_le_create_connection_t conn_params;
    uint8_t addr[6] = {0xC0, 0x74, 0x3A, 0x2A, 0x09, 0xFF};

    //Set connection parameters.
    conn_params.le_scan_interval = 0x0060;
    conn_params.le_scan_window = 0x0030;
    conn_params.initiator_filter_policy =
BT_HCI_CONN_FILTER_ASSIGNED_ADDRESS;
    conn_params.peer_address.type = 0x00;
    memcpy(conn_params.peer_address.addr, addr, sizeof(addr));
}
```

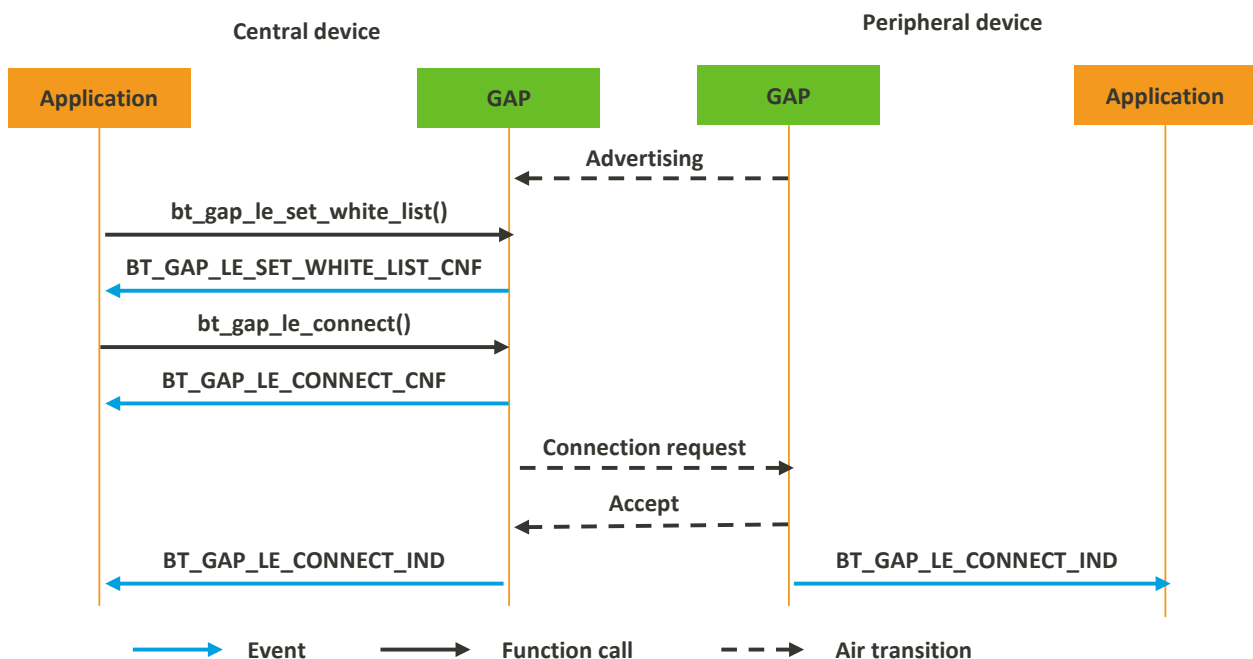
```

conn_params.own_address_type = BT_ADDR_RANDOM;
conn_params.conn_interval_min = 0x0018;
conn_params.conn_interval_max = 0x0028;
conn_params.conn_latency = 0x0000;
conn_params.supervision_timeout = 0x0C80;
conn_params.minimum_ce_length = 0x0060;
conn_params.maximum_ce_length = 0x0140;
//Start connecting.
bt_gap_le_connect(&conn_params);

return;
}

```

- 2) Auto-connection. It enables the host to configure the controller to establish a connection automatically with one or more devices. A white list in the controller stores device addresses. The controller automatically establishes a connection with devices in the white list, as shown in Figure 64. More details can be found in the header file `bt_gap_le.h`.



**Figure 64. GAP auto connection message sequence**

```

void app_fun(void)
{
    uint8_t addr[6] = {0xC0, 0x74, 0x3A, 0x2A, 0x09, 0xFF};
    bt_addr_t device;

    device.type = 0x00;
    memcpy(device.addr, addr, sizeof(addr));

    //Add the device to the white list
    bt_gap_le_set_white_list(BT_GAP_LE_ADD_TO_WHITE_LIST, &device);
    return;
}

bt_status_t bt_app_event_callback(bt_msg_type_t msg, bt_status_t status,
void *buff)
{
    switch (msg) {

```



```

        case BT_GAP_LE_ADVERTISING_REPORT_IND:
        {
            bt_hci_cmd_le_create_connection_t conn_params;

            //Set connection parameters.
            conn_params.le_scan_interval = 0x0060;
            conn_params.le_scan_window = 0x0030;
            conn_params.initiator_filter_policy =
                BT_HCI_CONN_FILTER_WHITE_LIST_ONLY;
            conn_params.own_address_type = BT_ADDR_RANDOM;
            conn_params.conn_interval_min = 0x0018;
            conn_params.conn_interval_max = 0x0028;
            conn_params.conn_latency = 0x0000;
            conn_params.supervision_timeout = 0x0C80;
            conn_params.minimum_ce_length = 0x0060;
            conn_params.maximum_ce_length = 0x0140;
            //Start connecting.
            bt_gap_le_connect(&conn_params);

            break;
        }
    }

    return BT_STATUS_SUCCESS;
}

```

Calling the `bt_gap_le_connect()` function again, while the GAP is connecting, will result in failure (`BT_STATUS_FAIL`). In this case, the application should call `bt_gap_le_cancel_connection()` to cancel the connection and then call `bt_gap_le_connect()` to re-connect.

`BT_GAP_LE_CONNECT_IND` event is received, when connecting or being connected successfully.

```

bt_status_t bt_app_event_callback(bt_msg_type_t msg, bt_status_t status,
void *buff)
{
    switch (msg) {
        case BT_GAP_LE_CONNECT_IND:
        {
            bt_gap_le_connect_ind_t *event;
            event = (bt_gap_le_connect_ind_t *)buff;
            //Handle connected event.
            break;
        }
    }
    return;
}

```

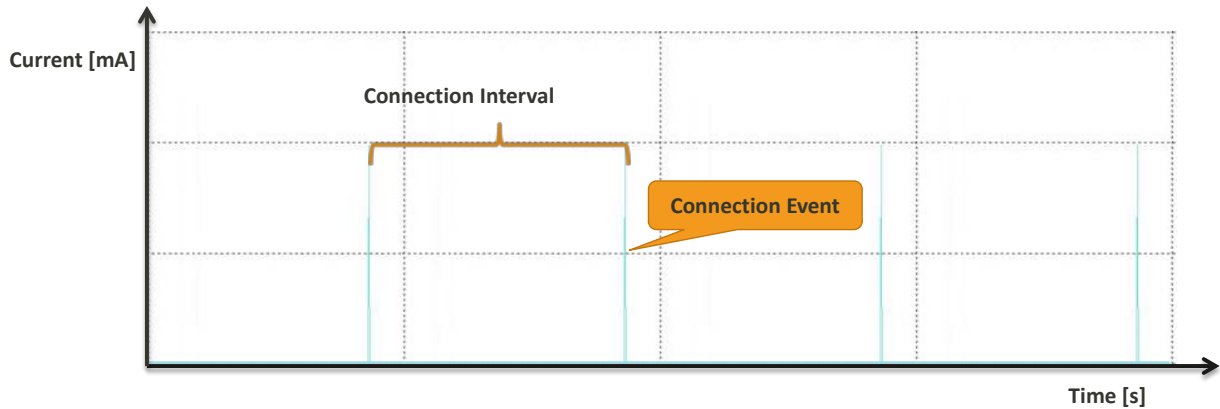
#### 4.1.4.1. Connection parameters

The connection parameters in this section affect the power consumption and performance. They are sent by the central device with the connection request and can be modified by a peripheral device, once the connection is established.

- 1) **Connection Interval.** During the connection interval, the two devices send and receive data only in Bluetooth LE connection state. If there is no data to send, the two devices will still keep sending link layer data to notify the peer device that it is still alive. The current increases if there is data to send in the connection event, as shown in Figure 65. The range of connection interval is from 7.5ms to 4s. The larger

the connection interval, the lower the power consumption and the throughput are. The ideal throughput is defined as  $\frac{(\text{conn\_interval}/0.625\text{ms}-3)\text{slot} * 23 \text{ bytes}/1.1\text{slot}}{\text{conn\_interval}}$ , where 23 bytes are useful bytes in the PDU. Three slots deducted in the expression are reserved in each connection interval and 23 bytes per 1.1 slot is the maximum BLE baseband capacity for Bluetooth 4.1.

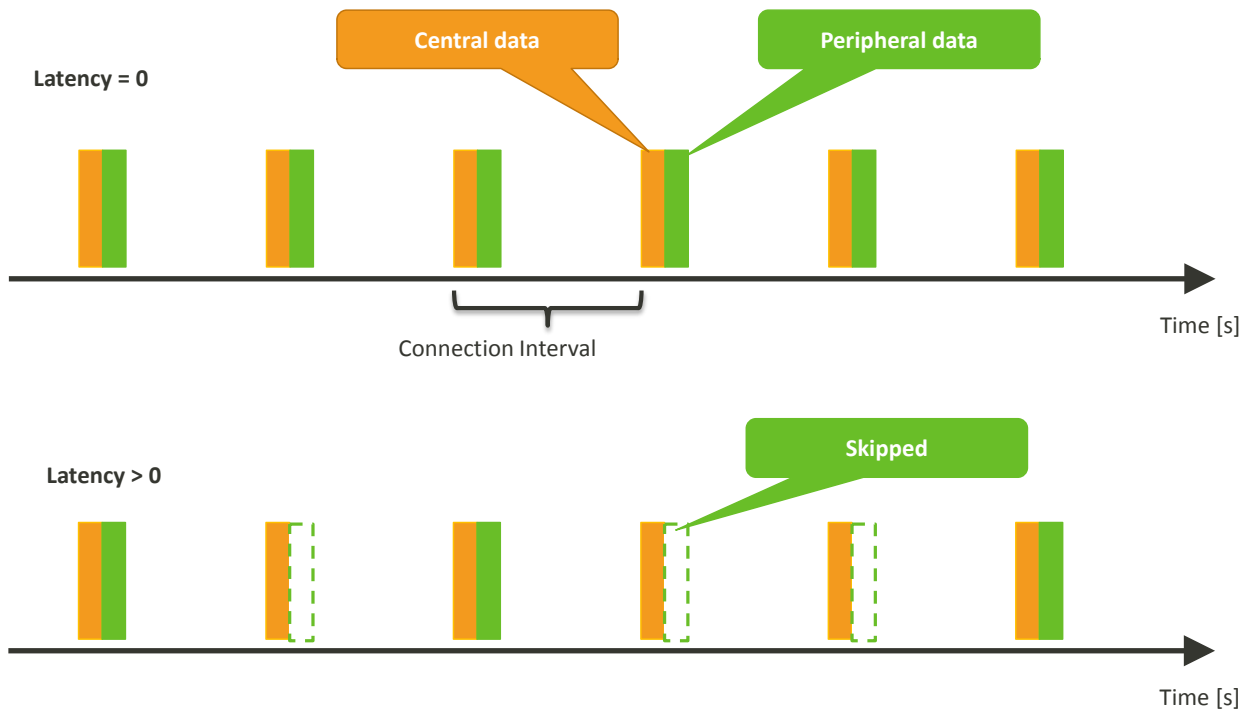
More details can be found in the header file `bt_hci_le.h`.



**Figure 65. Connection interval and event**

- 2) Connection Latency. Enables the peripheral device to skip a number of connection events. If the peripheral device has no data to send. It can skip no more than connection latency of connection events and stay asleep, as shown in Figure 66. The range of connection latency is from 0 to  $\frac{\text{conn\_timeout}}{2 * \text{conn\_interval}} - 1$ . The value of the latency should be less than 311.875ms.

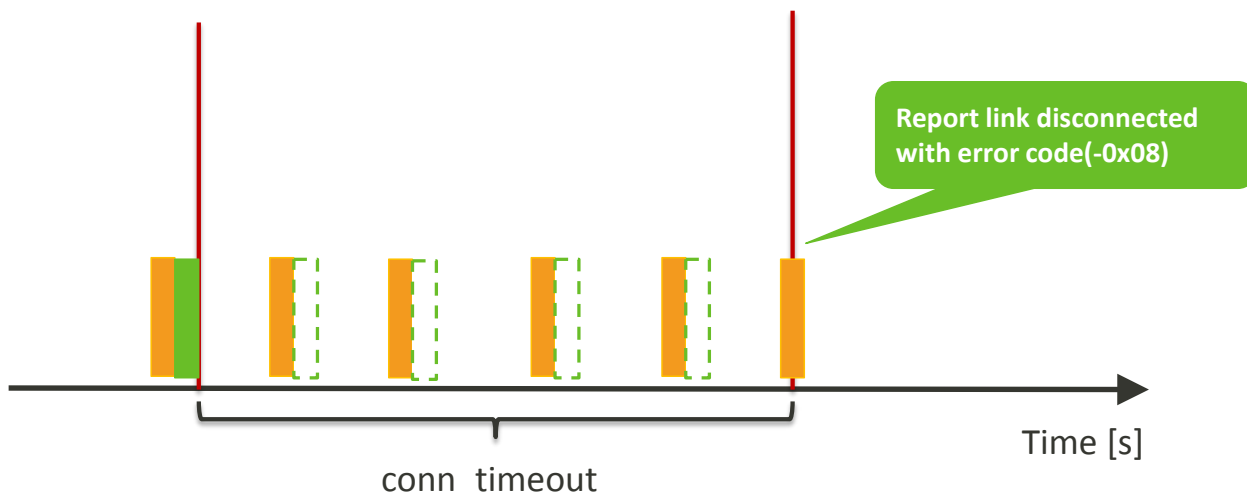
More details can be found in the header file `bt_hci_le.h`.



**Figure 66. Slave latency**

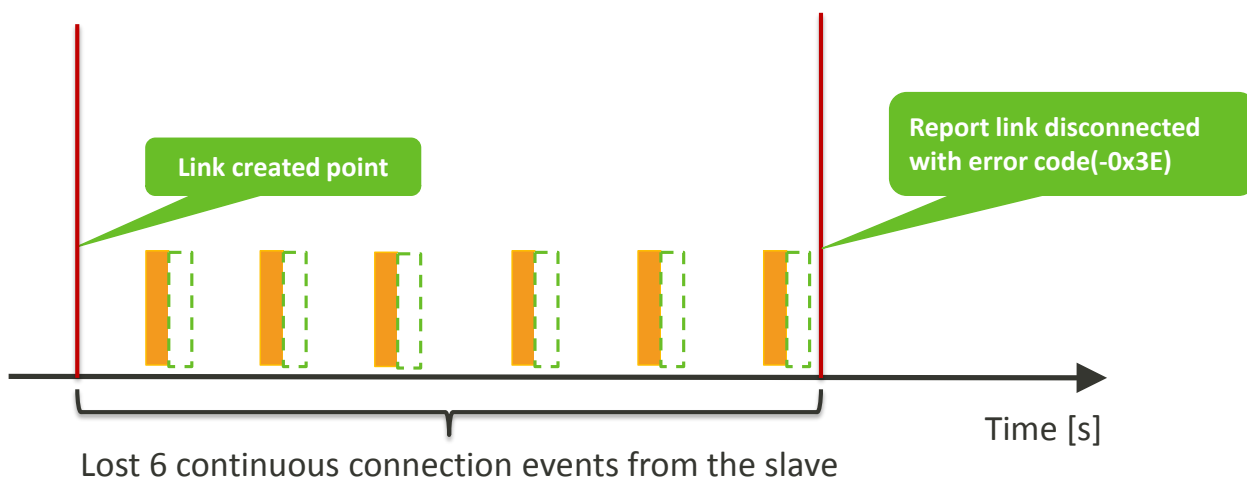
- 3) Connection Timeout. A connection might fail with an error code of `-0x08` due to not getting connection event data from the peer device before the connection times out. The range of the connection timeout is from 100ms to 32s. It defines the maximum time between two received connection data events before the connection is considered as failed, as shown in Figure 67.

More details can be found in the header file `bt_hci_le.h`.



**Figure 67. Connection timeout error occurred (error code -0x08)**

If the master fails to receive six continuous packet data units (PDU) after the connection is created, the connection is considered lost. This enables fast termination of connections that fail to establish, as shown in Figure 68.



**Figure 68. Connection timeout error occurred (error code -0x3E)**

## 4.1.5. Resolvable private address resolution

This feature makes it more difficult for an attacker to track a device over a certain period of time. The user should enable address resolution and add the device to the resolving list in the controller.

### 4.1.5.1. Enable address resolution

Call the function `bt_gap_le_set_address_resolution_enable()` to enable the resolution of the resolvable private addresses in the controller.

#### 4.1.5.2. Set resolvable private address timeout

Call the function `bt_gap_le_set_resolvable_private_address_timeout()` to set the resolvable private address timeout in the controller. The controller will generate a new resolvable private address and use it at timeout.

#### 4.1.5.3. Set resolving list

Call the function `bt_gap_le_set_resolving_list()` to add a device identity to the resolving list, remove a device identity from the resolving list or clear the resolving list. The device identity contains the peer's identity address and local and peer's IRK pair.

```
bt_status_t app_add_dev_to_resolving_list(const bt_gap_le_bonding_info_t
*bonded_info)
{
    bt_status_t st = BT_STATUS_SUCCESS;
    if (BT_ADDR_TYPE_UNKNOW != bonded_info->identity_addr.address.type) {
        bt_hci_cmd_le_add_device_to_resolving_list_t dev;
        dev.peer_identity_address = bonded_info->identity_addr.address;
        memcpy(dev.peer_irk, &(bonded_info->identity_info),
            sizeof(dev.peer_irk));
        memcpy(dev.local_irk, &(local_key_req.identity_info),
            sizeof(dev.local_irk));
        st =
        bt_gap_le_set_resolving_list(BT_GAP_LE_ADD_TO_RESOLVING_LIST,
            (void*)&dev);
    }
    return st;
}

bt_status_t app_delete_dev_from_resolving_list(const
bt_gap_le_bonding_info_t *bonded_info)
{
    bt_status_t st = BT_STATUS_SUCCESS;
    if (BT_ADDR_TYPE_UNKNOW != bonded_info->identity_addr.address.type) {
        bt_hci_cmd_le_remove_device_from_resolving_list_t dev;
        dev.peer_identity_address = bonded_info->identity_addr.address;
        st =
        bt_gap_le_set_resolving_list(BT_GAP_LE_REMOVE_FROM_RESOLVING_LIST,
            (void*)&dev);
    }
    return st;
}

bt_status_t app_clear_resolving_list()
{
    bt_status_t st = BT_STATUS_SUCCESS;
    st = bt_gap_le_set_resolving_list(BT_GAP_LE_CLEAR_RESOLVING_LIST,
    NULL);
    return st;
}
```

#### 4.1.6. Read the RSSI

Call the function `bt_gap_le_read_rssi()` to read the Received Signal Strength Indication (RSSI) of a given connection. More details can be found in the Bluetooth Core Specifications version 4.2 [vol2, Part E, 7.5.4], Bluetooth GAP.

## 4.1.7. Update data length

Call the function `bt_gap_le_update_data_length()` to suggest data length for a given connection. More details can be found in the Bluetooth Core Specifications version 4.2 [vol2, Part E, 7.8.33], [Bluetooth GAP](#).

## 4.1.8. Multiple advertising

The multiple advertising is supported on the MT7697 chip only; the objectives of multiple advertising are the following:

- Ability to support multiple non-connectable advertising
- Different advertising content and address
- An individualized response for each advertising
- Configurable transmission power (the range is from -70 dBm to 20 dBm)
- Ability to perform single (connectable) and multi-advertising (non-connectable), simultaneously, by calling the functions `bt_gap_le_set_advertising()` and `bt_gap_le_start_multiple_advertising()`, respectively.

With multiple advertising, different applications can start advertising without frequent modification of the advertising content. After it starts, the host can remain in sleep mode to save power. It requires adding the library “libble\_multi\_adv.a” to the project’s makefile. The application can start multiple advertising by using the multiple advertising APIs.

### 4.1.8.1. Limitations

- Multiple advertising does not support connectable type advertising.
- After adding the library “libble\_multi\_adv.a” to the project makefile, the `BT_HCI_ADV_TYPE_CONNECTABLE_DIRECTED_HIGH` and `BT_HCI_ADV_TYPE_CONNECTABLE_DIRECTED_HIGH` types of advertising are no longer supported by `bt_gap_le_set_advertising()`.

### 4.1.8.2. Get maximum advertising instances

Call the function `bt_gap_le_get_max_multiple_advertising_instances()` to get the maximum number of supported advertising instances, as shown below.

```
uint8_t max_instances =
bt_gap_le_get_max_multiple_advertising_instances();
```

### 4.1.8.3. Start multiple advertising

Set different advertising parameters and data for each advertising instance and start multiple advertising, as shown below. Multiple instances can start concurrently.

```
void app_start_instance_1(void)
{
    bt_bd_addr_t adv_addr = {0x13, 0x71, 0xDA, 0x7D, 0x1A, 0x0};
    bt_hci_cmd_le_set_advertising_parameters_t adv_para = {
        .advertising_interval_min = 0x0800,
        .advertising_interval_max = 0x0800,
        .advertising_type = BT_HCI_ADV_TYPE_SCANNABLE_UNDIRECTED,
        .advertising_channel_map = 7,
        .advertising_filter_policy = 0
    };
};
```

```

    bt_hci_cmd_le_set_advertising_data_t adv_data = {
        .advertising_data = {2, 1, 0x1A, 8, 9, 'a', 'd', 'v', 'o', 'n',
        'e', 0},
        .advertising_data_length = 12,
    };
    bt_hci_cmd_le_set_scan_response_data_t scan_res_data = {
        .scan_response_data = {2, 1, 0x1A},
        .scan_response_data_length = 3,
    };

    // Start advertising on instance 1. Each advertising instance needs to
    start individually.
    bt_gap_le_start_multiple_advertising(
        1, /* Instance 1. The range is from 1 to (max_instance - 1). */
        5,
        (bt_bd_addr_ptr_t)adv_addr,
        &adv_para,
        &adv_data,
        &scan_res_data
    );
    return;
}

void app_start_instance_2(void)
{
    bt_bd_addr_t adv_addr = {0x11, 0x11, 0x11, 0x11, 0x11, 0x11};
    bt_hci_cmd_le_set_advertising_parameters_t adv_para = {
        .advertising_interval_min = 0x0800,
        .advertising_interval_max = 0x0800,
        .advertising_type = BT_HCI_ADV_TYPE_SCANNABLE_UNDIRECTED,
        .advertising_channel_map = 7,
        .advertising_filter_policy = 0
    };
    bt_hci_cmd_le_set_advertising_data_t adv_data = {
        .advertising_data = {2, 1, 0x1A, 8, 9, 'a', 'd', 'v',
        't', 'w', '0', 0},
        .advertising_data_length = 12,
    };
    bt_hci_cmd_le_set_scan_response_data_t scan_res_data = {
        .scan_response_data = {2, 1, 0x1A},
        .scan_response_data_length = 3,
    };

    // Start advertising on instance 2. Each advertising instance needs to
    start individually.
    bt_gap_le_start_multiple_advertising(
        2, // Instance 2. The range is from 1 to (max_instance - 1).
        5,
        (bt_bd_addr_ptr_t)adv_addr,
        &adv_para,
        &adv_data,
        &scan_res_data
    );
    return;
}

bt_status_t bt_app_event_callback(bt_msg_type_t msg, bt_status_t status,
void *buff)
{

```

```

switch (msg) {
    case BT_GAP_LE_START_MULTIPLE_ADVERTISING_CNF:
    {
        bt_gap_le_start_multiple_advertising_cnf_t *event;
        event = (bt_gap_le_start_multiple_advertising_cnf_t *)buff;
        //Check the result of starting multi-advertising instance.
        break;
    }
}
return;
}

```

#### 4.1.8.4. Stop multiple advertising

Call the function `bt_gap_le_stop_multiple_advertising()` to stop the advertising instance, as shown below. Multiple instances can stop concurrently.

```

void app_stop_instance(void)
{
    // Stop advertising instance 1. Each advertising instance needs to be
    stopped individually.
    bt_gap_le_stop_multiple_advertising(1);
    return;
}

bt_status_t bt_app_event_callback(bt_msg_type_t msg, bt_status_t status,
void *buff)
{
    switch (msg) {
        case BT_GAP_LE_START_MULTIPLE_ADVERTISING_CNF:
        {
            bt_gap_le_stop_multiple_advertising_cnf_t *event;
            event = (bt_gap_le_stop_multiple_advertising_cnf_t *)buff;
            //Check the result of stopping multi-advertising instance.
            break;
        }
    }
    return;
}

```

## 4.2. SM

The SM manages pairing, authentication and encryption between Bluetooth LE devices.

Pairing process has three phases. The first two are mandatory while the third one is optional.

- 1) Pairing Feature Exchange. Pairing feature includes I/O capability, Out-of-Band data flag, authentication requirements (bonding flag, man-in-the-middle (MITM) flag and Secure Connections (SC) flag), maximum encryption key size, initiator key distribution and responder key distribution. At this phase, only the I/O capability, Out-of-Band data flag and authentication requirements are configurable.
  - a) The Bonding flag is set to false to delete the keys (described in step (d)), after disconnecting. If it's set to true, store the keys to the NAND flash so that they can be used again, when the two devices reconnect.
  - b) The MITM flag and the SC flag are used to determine whether to use the MITM protection and LE SC Pairing separately or not.
  - c) Maximum encryption key size is set to be 16 octets.

- d) The key distribution in the pairing request from the initiator can be one of the following:
  - i) LTK, EDIV, and Rand (only for legacy pairing)
  - ii) IRK
  - iii) CSRK

The responder will set the key distribution to be the minimum subset of Central and Peripheral devices.

- i) Short Term Key (STK) Generation for LE legacy pairing or LTK Generation for LE SC. The devices determine which of the following methods to use after exchanging I/O capabilities.
  - ii) Just Works
  - iii) Numeric Comparison (only for LE SC)
- 2) Passkey Entry. It varies depending on the I/O capability. One device displays the passkey and the other inputs the passkey. The passkey is generated randomly but can be modified to be fixed or variable before display.
  - 3) Out-of-Band. The keys are not exchanged over the air, but rather over some other source such as serial port or near field communication (NFC). For more information about how to determine the method, refer to the [Bluetooth core specifications version 4.2](#) [VOL 3, part H, 2.3.5.1].
  - 4) Transport Specific Key Distribution. Phase 3 is optional to distribute specific keys, such as the Identity Address information and IRK. Phase 1 and Phase 3 are identical regardless of the method used in Phase 2.

Phase 3 is only performed on an encrypted link using the STK or LTK generated in Phase 2. Phase 1 and Phase 2 can be performed on a link with no encryption.

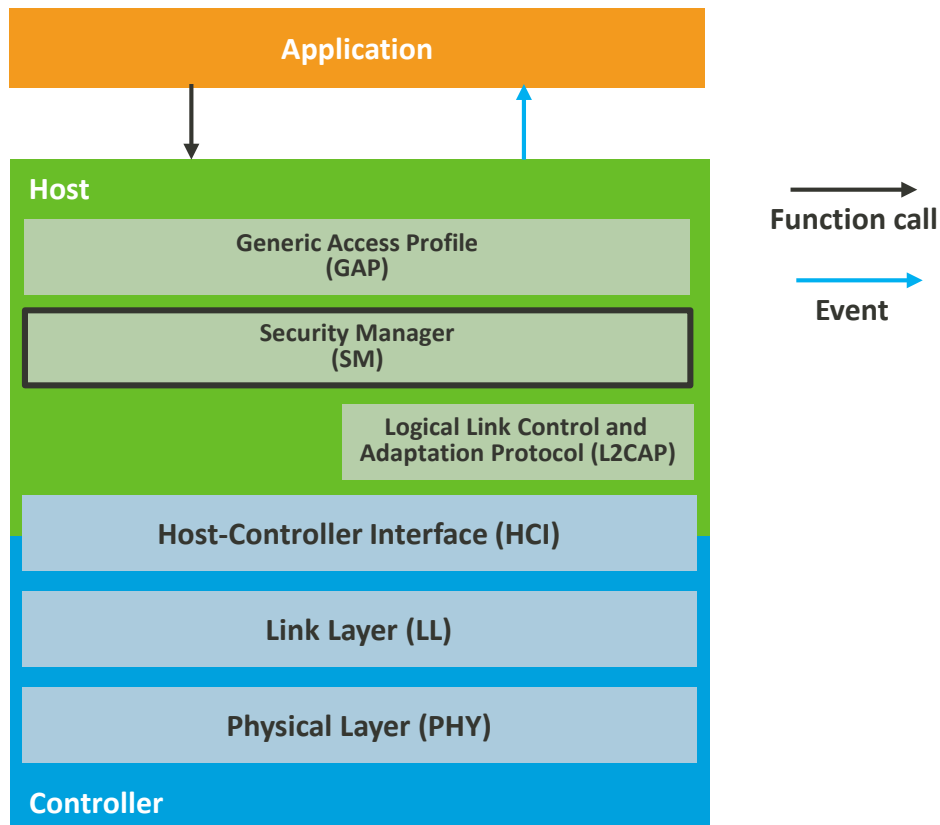
The keys distributed in Phase 3 need to be stored in the application. If the keys aren't stored, the pairing starts, otherwise the pairing is skipped and only the encryption is performed. Once the keys are stored for each device, the resolvable address needs to be considered when searching for the keys for that device. The resolvable address can be modified at any time. Keys are stored for a remote device with their resolvable addresses. The keys might change when the two devices are reconnected. In that case, during the search for keys, if both resolvable addresses can be resolved to the same identity address, the keys are found and can be used to encrypt the link so that the pairing process can be skipped.



**Note.** The Out-of-Band method is only supported in the LE legacy pairing, but not in the LE SC.

Encryption is implemented when the STK or LTK is generated. Usually the link is encrypted with the LTK again when reconnecting to the paired remote device. If the local device only initiates the encryption but the LTK doesn't exist on the remote device, then it's suggested to apply the pairing again.





**Figure 69. SM abstraction layout**

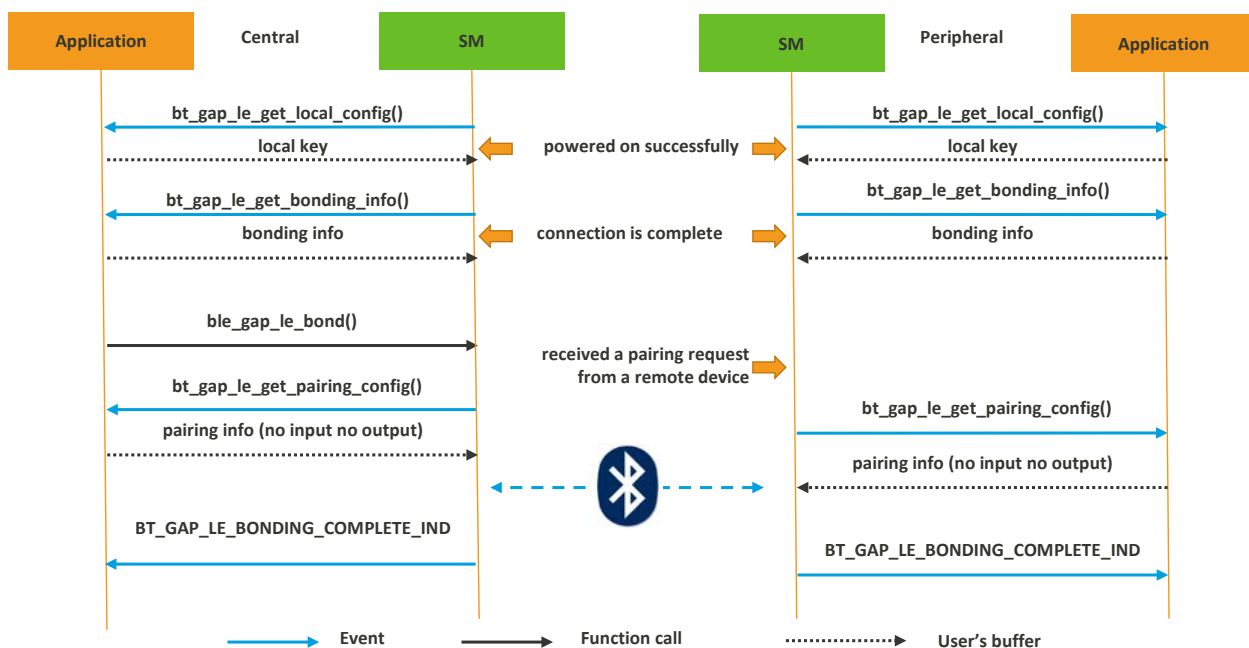
It's possible for the application and profiles to directly call GAP API functions to perform authentication and encryption after connection is established. GAP is based on SM, and the SM is based on L2CAP and HCI. GAP manages links and encapsulates the SM code, and the SM uses an L2CAP channel to send data to the remote device and receive data from the remote device, as shown in Figure 69.

## 4.2.1. The SM message sequences

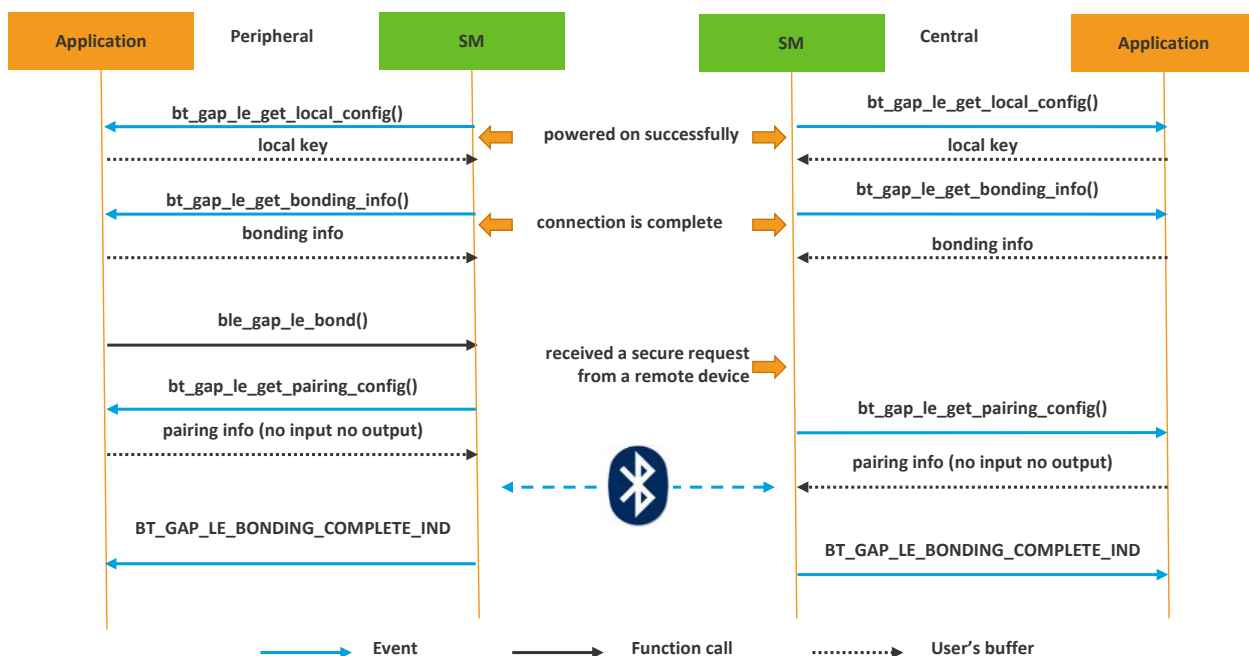
This section introduces typical message sequences to provide more details about the events and procedures of the SM.

### 4.2.1.1. Just Works

The central role can initiate the pairing by calling the function `bt_gap_le_bond()`, and Just Works is used if the Out-of-Band flag of both devices is "OOB not present" and the I/O capability of one of these two devices is "no input no output" or the MITM flag of both devices is "non-MITM". An example where the I/O capabilities of both devices are "no input no output" is shown in Figure 70.

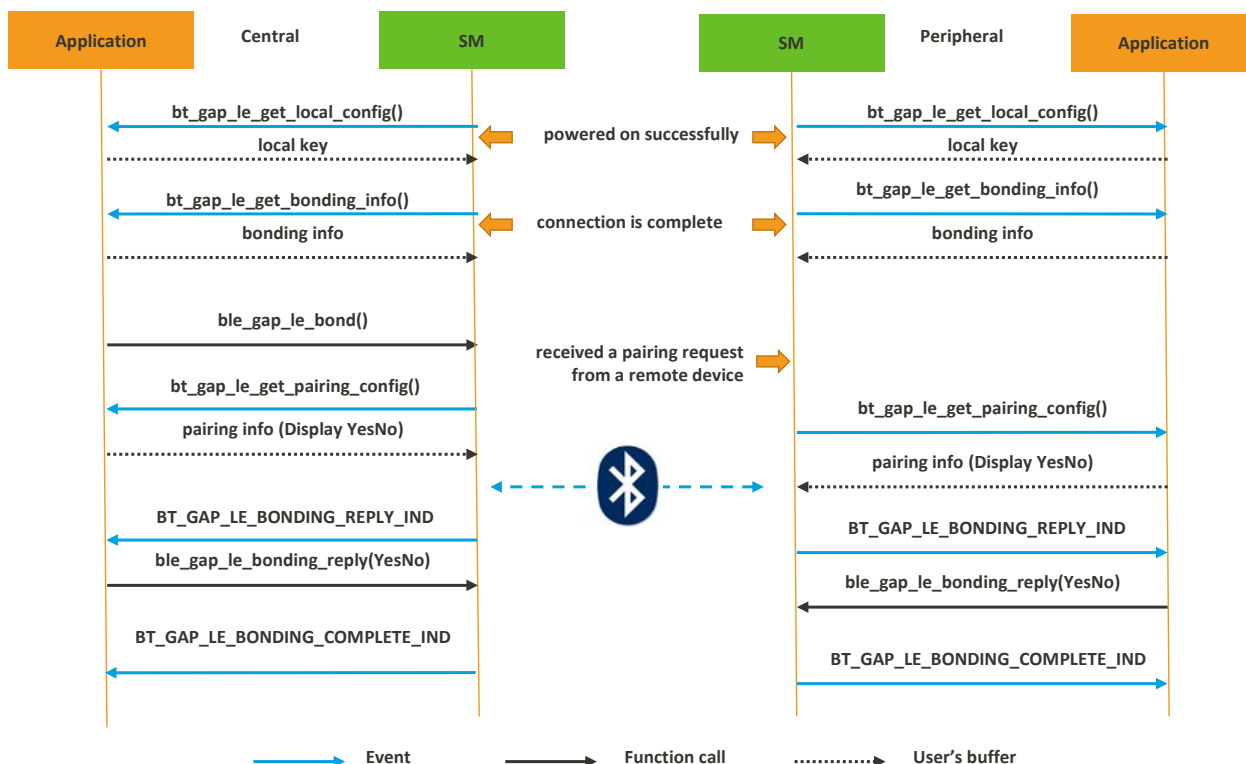


- 1) The peripheral role can request the central role to initiate pairing by calling the function `bt_gap_le_bond()`, and Just Works is used if the Out-of-Band flag of both devices is "OOB not present" and the I/O capability of one of these two devices is "no input no output" or the MITM flag of both devices is "non-MITM". An example where the I/O capabilities of both devices are "no input no output" is shown in Figure 71.



## 4.2.1.2. Numeric Comparison (only for LE SC)

The central role can initiate the pairing by calling the function `bt_gap_le_bond()`, and passkey entry is used if the Out-of-Band flag of both devices is “OOB not present”, the MITM flag of at least one device is “has MITM” and the I/O capability of one of these two devices is “Display Yes No”. An example is shown in.



**Figure 72. Numeric Comparison (central role)**

The peripheral role can request the central role to initiate the pairing by calling the function `bt_gap_le_bond()` and passkey entry is used if the Out-of-Band flag of both devices is “OOB not present”, the MITM flag of at least one of the devices is “has MITM”, the I/O capability of one of these two devices is “Display Yes No”.

An example is shown in Figure 73.

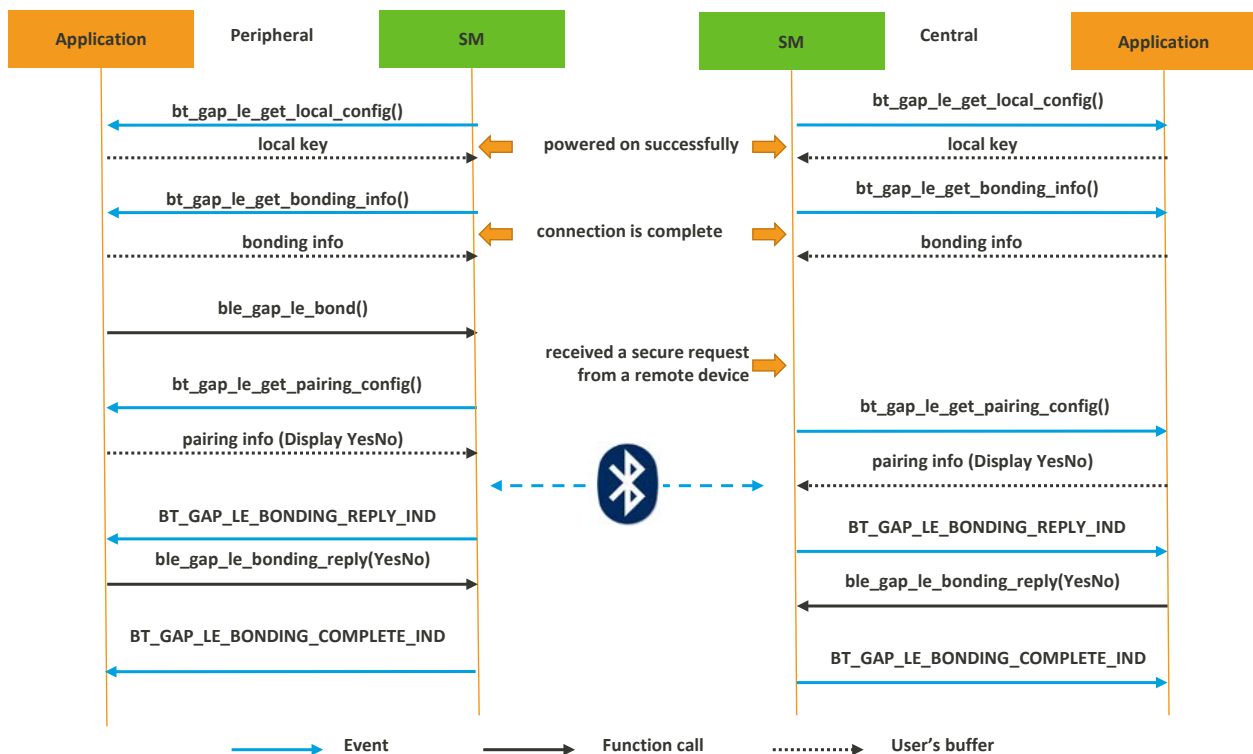
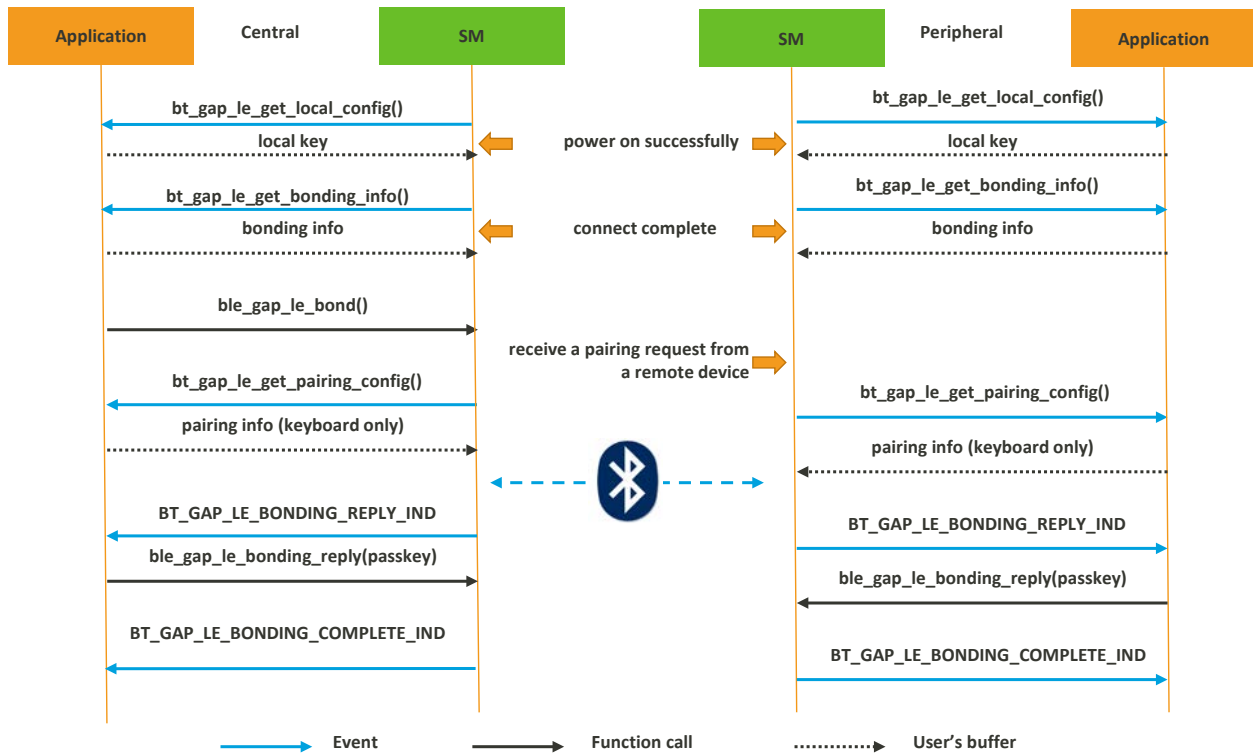


Figure 73. Numeric Comparison (peripheral role)

### 4.2.1.3. Passkey entry

- 1) The central role can initiate the pairing by calling the function `bt_gap_le_bond()`, and passkey entry is used if the Out-of-Band flag of both devices is "OOB not present", the MITM flag of at least one device is "has MITM" and the I/O capabilities of these two devices are any except "no input no output" and "display only". An example where the I/O capabilities of both devices are "keyboard only" is shown in Figure 74.



**Figure 74. Passkey entry (central role)**

- 2) The peripheral role can request the central role to initiate pairing by calling the function `bt_gap_le_bond()` and passkey entry is used if the Out-of-Band flag of both devices is "OOB not present", the MITM flag of at least one of the devices is "has MITM", the I/O capabilities of these two devices are anything except "no input no output" and "display only". An example where the I/O capabilities of both devices are "keyboard only" is shown in Figure 75.

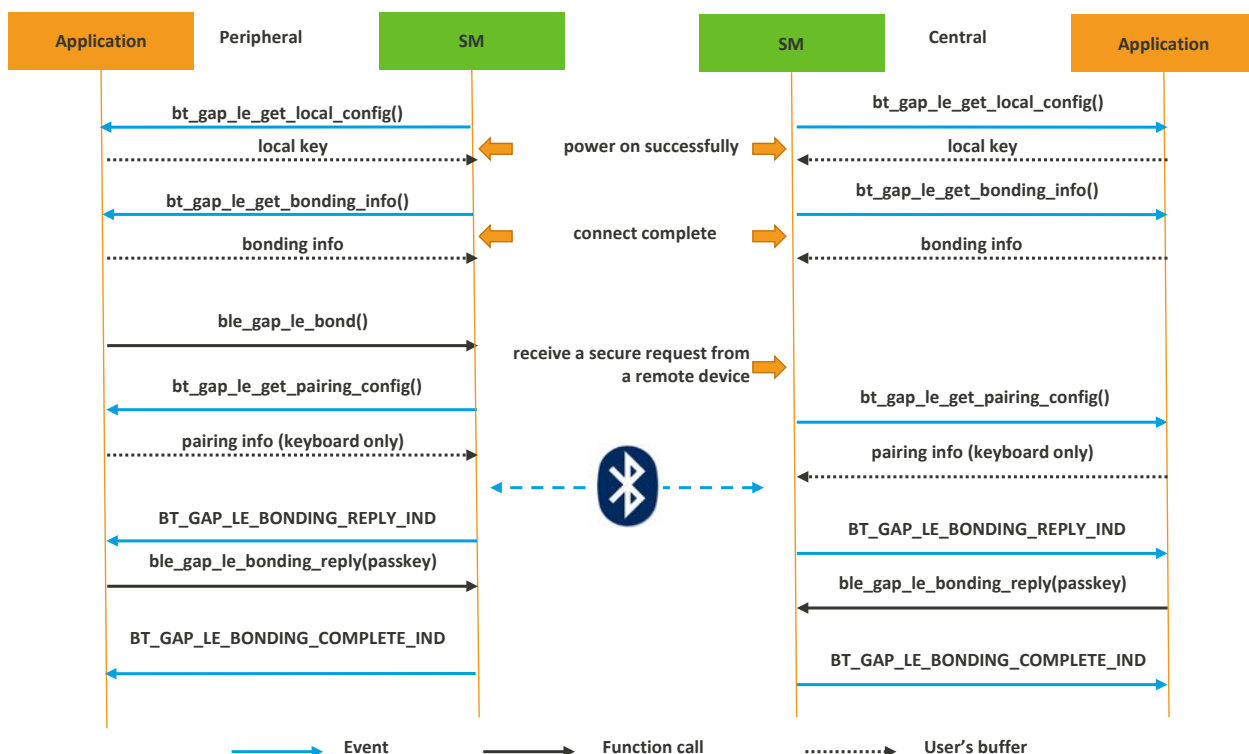


Figure 75. Passkey entry (peripheral role)

## 4.2.1.4. Encryption

- 1) The central role requests to initiate the encryption by calling the function `bt_gap_le_bond()`. After the pairing is complete, the link is already encrypted with the STK in LE legacy pairing or LTK in LE S C pairing. Usually the encryption with the LTK is performed if higher security level is required or after reconnecting. An example where the LTK is used to encrypt the link is shown in Figure 76.

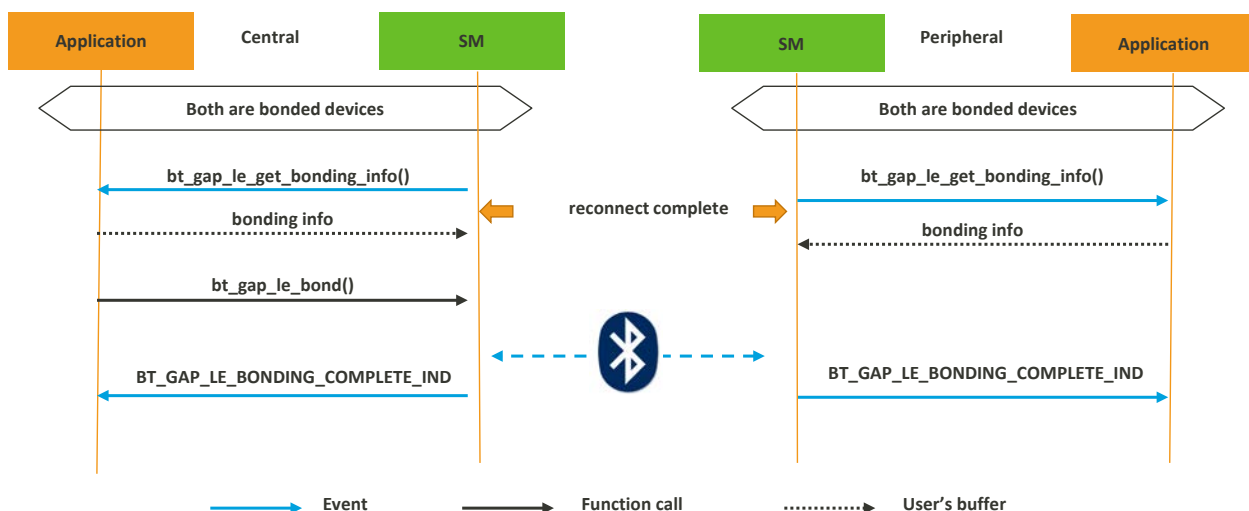


Figure 76. Encryption (central role)

- 2) The peripheral role initiates the encryption by calling the function `bt_gap_le_bond()`. After the pairing is complete, the link is already encrypted with STK in LE legacy pairing or LTK in LE SC pairing. Usually the

encryption with the LTK is performed if higher security level is required or after reconnecting. An example where the LTK is used for link encryption is shown in Figure 77.

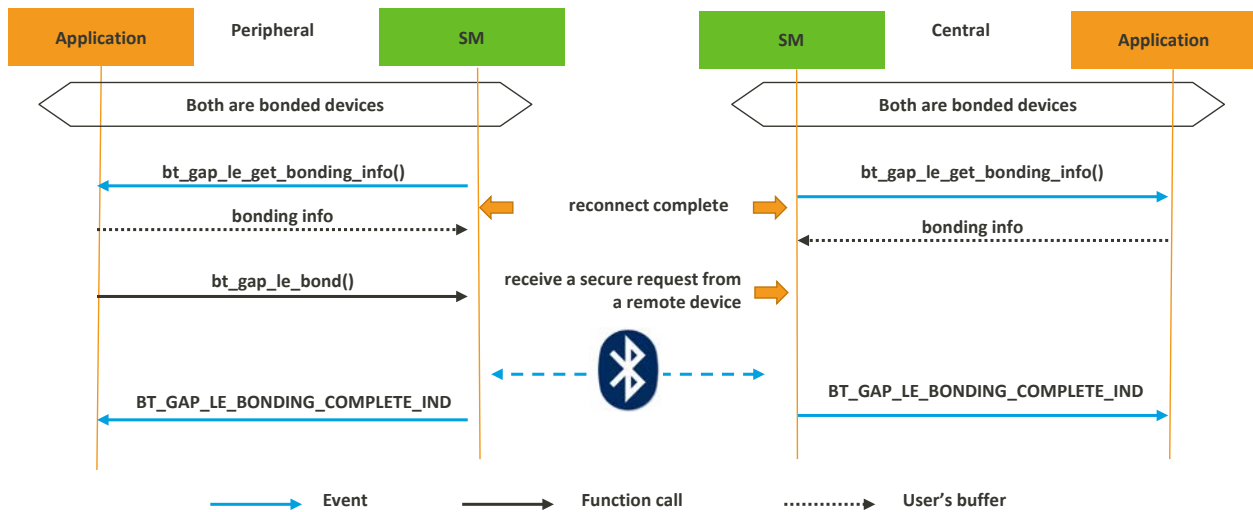


Figure 77. Encryption (peripheral role)

## 4.2.2. Using the SM APIs

The SM API headers can be found in the `bt_gap_le.h` header file with only two interface APIs for pairing, `bt_gap_le_bond()` and `bt_gap_le_bonding_reply()`. Apply the following function calls to use the SM in your application development.

- Optional, call the `bt_gap_le_bond()` API to pair with a remote device and perform the encryption once the pairing is finished. Also call the `bt_gap_le_bond()` API to encrypt only, if these two devices are still bonded, which is usually performed after reconnecting with the bonded remote device.

```

bt_status_t status;
bt_smp_pairing_config_t pairing_config = { //mitm, bond, oob
    .maximum_encryption_key_size = 16,
    .io_capability = BT_SMP_DISPLAY_YES_NO,
    .auth_req = BT_SMP_AUTH_REQ_MITM | BT_SMP_AUTH_REQ_SECURE_CONNECTION,
};
uint32_t connection_handle = 0x0200;
status = bt_gap_le_bond(connection_handle, & pairing_config);
    
```

- Optional, call the `bt_gap_le_bonding_reply()` API to send the Out-of-Band data for the Out-of-Band pairing method or passkey for the Passkey Input pairing method (see 4.2.1.3, "Passkey entry"), or Numeric Comparison result (see 4.2.1.2, "Numeric Comparison (only for LE SC)"), when `BT_GAP_LE_BONDING_REPLY` event is received.

```

bt_status_t status;
bt_gap_le_bonding_reply_t rsp = {.passkey = 123456};
uint32_t connection_handle = 0x0200;
status = bt_gap_le_bonding_reply(connection_handle, &rsp);
    
```

- Mandatory, implement the `bt_app_event_callback()` API to handle the events sent by the stack.

```

bt_status_t bt_app_event_callback(bt_msg_type_t msg, bt_status_t status,
void *buff)
{
    bt_status_t status;
    
```

```
switch (msg) {
    case BT_GAP_LE_BONDING_REPLY_IND: {
        //Reply OOB data or Passkey or Numeric Comparison result, call
        bt_gap_le_bonding_reply() API.
    }
    case BT_GAP_LE_BONDING_COMPLETE_IND: {
        // indicates a pairing procedure has finished.
    }

    default:
        break;
}
return status;
}
```

- 4) Mandatory, implement the `bt_gap_le_get_local_config()` API to return the local configuration field to stack. All configuration fields must be a global buffer.

```
static bt_gap_le_local_config_req_ind_t g_app_local_config;
bt_gap_le_local_key_t local_key_req = {
    .encryption_info = {0};
    .master_id = {0};
    .identity_info =
{0x12,0x34,0x56,0x78,0x9a,0xbc,0xde,0xf0,0x19,0x28,0x55,0x33,0x68,0x33,0x5
6,0xde};
    .signing.info = {0};
};
Bool sc_only = false;
bt_gap_le_local_config_req_ind_t bt_gap_le_get_local_config(void)
{
    g_app_local_config.local_key_req = &local_key_req;
    g_app_local_config.sc_only_mode_req = sc_only;

    return &g_app_local_config;
}
```

- 5) Mandatory, implement the `bt_gap_le_get_bonding_info()` API to return the bonding info field to stack. Bonding info field must be a global buffer.

```
static bt_gap_le_bonding_info_t bongding_info = {0};
bt_gap_le_bonding_info_t bt_gap_le_get_bonding_info(const bt_addr_t
remote_addr)
{
    return &bongding_info;
}
```

- 6) Mandatory, implement the `bt_gap_le_get_pairing_config()` API to return the pairing info field to stack. Pairing info field must be a global buffer.

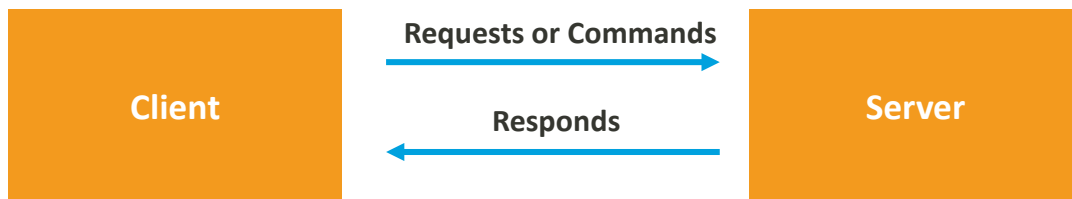
```
static bt_gap_le_smp_pairing_config_req = {
    .auth_req = BT_GAP_LE_SMP_AUTH_REQ_BONDING,
    .maximum_encryption_key_size = 16,
    .io_capability = BT_GAP_LE_SMP_NO_INPUT_NO_OUTPUT,
};
bt_status_t bt_gap_le_get_pairing_config(bt_gap_le_bonding_start_ind_t
*ind)
{
    ind->pairing_config_req = pairing_config_req;
    return BT_STATUS_SUCCESS;
}
```



### 4.3. GATT

GATT describes a service framework using the Attribute Protocol (ATT) to discover, read, write, notify and indicate characteristics, as well as to configure the broadcast of characteristics. GATT is designed for an application or another profile to communicate with a peer device. There are two roles defined for devices that implement this profile, as shown in Figure 78.

- **Client** — the device that sends commands and requests to the server and can receive responds, indications and notifications from the server.
- **Server** — the device that accepts commands and requests from the client and sends responds, indications and notifications to a client.



*Figure 78. GATT Client and Server*

The ATT request-response or indication-confirmation pair is considered as a single transaction. The two roles are not fixed to the device, but are determined when a device initiates a transaction, and are released when the transaction ends. A device can act in both roles at the same time.

A profile should have one or more services. The service is composed of one or more characteristics or included services. Each characteristic contains a value and may contain optional information known as descriptors of the value, as shown in Figure 79. All information (service, characteristic and the components of the characteristic) is stored in **Attributes** on the **Server**.

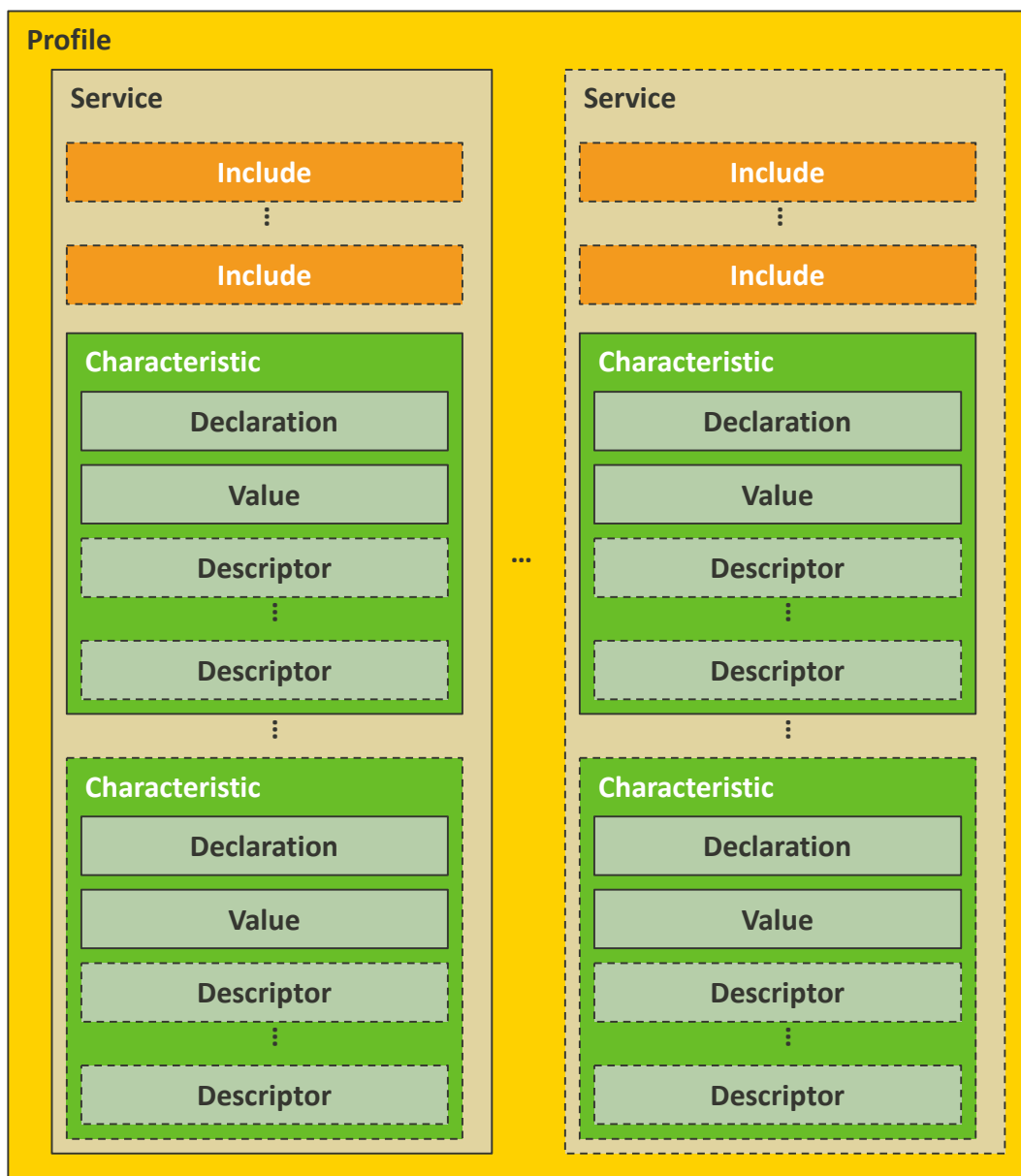


Figure 79. GATT profile hierarchy

The **Attribute** consists of: **Attribute Handle**, **Attribute Type**, **Attribute Value** and **Attribute Permissions**, as shown in Figure 80.

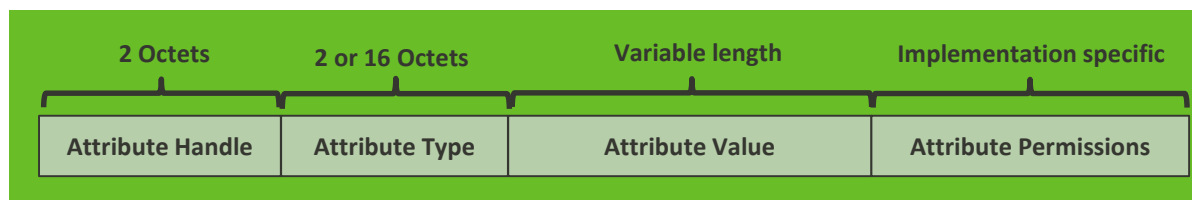


Figure 80. Logical representation of the attribute

The **Attribute Handle** is an index corresponding to a specific **Attribute**. The **Attribute Type** is a UUID that describes the **Attribute Value**. The **Attribute Value** is the data described by the **Attribute Type** and indexed by the **Attribute Handle**. The **Attributes** are ordered by ascending **Attribute Handle** values. The **Attribute Handle** values are in a range from 0x0001 to 0xFFFF. **Attribute Permissions** are part of the **Attribute** that

cannot be read from or written to using ATT. The permissions are used by the **Server** to determine whether read or write access is permitted for a given **Attribute**.

### 4.3.1. Create a GATT Server

The GATT Server stores and manages an application-wide attribute table. This section describes the process to create a user-defined GATT Server.

GATT Server's database is divided into three levels, from top to bottom, the server, the service and the record. Each server can have more than one service. Each service can have more than one record.

An example of a GATT Server that has two services, `bt_if_gap_service` with four records and `bt_if_gatt_service` with five records, is shown below.

```
|server
|  service
|    |handle|record|
|bt_if_gatt_server
|  |bt_if_gap_service
|    |0x0001|bt_if_gap_primary_service|
|    |0x0002|bt_if_gap_included_manufacturer_service|
|    |0x0003|bt_if_gap_char4_dev_name|
|    |0x0004|bt_if_gap_dev_name|
|  |bt_if_gatt_service
|    |0x0011|bt_if_gatt_primary_service|
|    |0x0012|bt_if_gatt_char4_service_changed|
|    |0x0013|bt_if_gatt_service_changed|
|    |0x0014|bt_if_gatt_client_config|
|    |0x0015|bt_if_gatt_server_config|
```

Follow the steps below to implement GATT Server with the defined services and records.

- 1) Implement a callback is required to handle the device name read and write requests when creating a device name characteristic, as shown below.

```
char gatts_device_name[256]={ "MTKHB" };
static uint32_t bt_if_gap_dev_name_callback (const uint8_t rw, uint16_t
handle, void *data, uint16_t size, uint16_t offset)
{
    uint32_t str_size = strlen(gatts_device_name);
    uint32_t buf_size = sizeof(gatts_device_name);
    uint32_t copy_size;
    switch (rw) {
        case BT_GATTS_CALLBACK_READ:
            /* To handle read request. */
            copy_size = (str_size> offset)?(str_size-offset):0;
            if (size==0){
                return str_size;
            }
            copy_size = (size > copy_size)? copy_size:size;
            memcpy(data, gatts_device_name+offset, copy_size);
            return copy_size;
        case BT_GATTS_CALLBACK_WRITE:
            /* To handle write request. */
            copy_size = (size > buf_size)? buf_size:size;
            memcpy(gatts_device_name, data, copy_size);
            return copy_size;
        default:
```

```
        return BT_STATUS_SUCCESS;
    }
}
```

- 2) Create the four (4) records of the GAP service and store them in the `bt_if_gap_service_rec`, as shown below.

```
/* To create records of GAP primary service. */
enum {
    GAP_HANDLE_START = 0x0001,
    GAP_HANDLE_PRIMARY_SERVICE = GAP_HANDLE_START,
    GAP_HANDLE_INCLUDED_MANUFACTURER_SERVICE,
    GAP_HANDLE_CHAR4_DEV_NAME,
    GAP_HANDLE_DEV_NAME,
    GAP_HANDLE_END
};
/* The record of primary service. */
BT_GATTS_NEW_PRIMARY_SERVICE_16(bt_if_gap_primary_service,
    BT_GATT_UUID16_GAP_SERVICE);
/* The record of included service. */
BT_GATTS_NEW_INCLUDED_SERVICE_128(bt_if_gap_included_manufacturer_service,
    0x0500, 0x0522);
/* The record of device name characteristic declaration. */
BT_GATTS_NEW_CHARC_16_WRITABLE(bt_if_gap_char4_dev_name,
    BT_GATT_CHARC_PROP_READ, GAP_HANDLE_DEV_NAME,
    BT_SIG_UUID16_DEVICE_NAME);
/* The record of device name characteristic value. */
BT_GATTS_NEW_CHARC_VALUE_CALLBACK(bt_if_gap_dev_name,
    BT_SIG_UUID_DEVICE_NAME,
    BT_GATTS_REC_PERM_READABLE|BT_GATTS_REC_PERM_WRITABLE,
    bt_if_gap_dev_name_callback);
/* The bt_if_gap_service_rec to hold all records of GAP service. */
static const bt_gatts_service_rec_t *bt_if_gap_service_rec[] = {
    (const bt_gatts_service_rec_t*) &bt_if_gap_primary_service,
    (const bt_gatts_service_rec_t*)
    &bt_if_gap_include_manufacturer_service,
    (const bt_gatts_service_rec_t*) &bt_if_gap_char4_dev_name,
    (const bt_gatts_service_rec_t*) &bt_if_gap_dev_name
};
```

- 3) Create a GAP service named as `bt_if_gap_service` and stored in `bt_if_gatt_server`, as shown below.

```
/* The value of the starting_handle is assigned to the first record:
bt_if_gap_primary_service.
The value of the ending_handle is assigned to the last record:
bt_if_gap_dev_name.
(ending_handle - starting_handle + 1) should equal to the number of
records.
The required_encryption_key_size defines the encryption key size this
service requires. If record's perm is set as
BT_GATTS_REC_PERM_READABLE_ENCRYPTION or
BT_GATTS_REC_PERM_WRITABLE_ENCRYPTION, GATTS will check if the channel is
encrypted and the encryption key size is greater than or equal to
required_encryption_key_size. */
static const bt_gatts_service_t bt_if_gap_service = {
    .starting_handle = GAP_HANDLE_START,
    .ending_handle = GAP_HANDLE_END - 1,
    .required_encryption_key_size = 7,
    /* If record needs channel encryption, the size of encryption key
```

```
should be equal to or greater than 7. */
.records = bt_if_gap_service_rec
};
```

- 4) Implement a callback is required to handle the client characteristic configuration read and write requests when creating the client characteristic configuration descriptor.

```
static uint16_t bt_if_gatt_notify=0; //Client Characteristic Configuration
static uint32_t bt_if_gatt_client_config_callback (const uint8_t rw,
                                                    uint16_t handle, void *data, uint16_t size, uint16_t
offset)
{
    if (rw == BT_GATTS_CALLBACK_WRITE){
        /* To handle write request. */
        if (size != sizeof(bt_if_gatt_notify)){ //Size check
            return 0;
        }
        bt_if_gatt_notify = *(uint16_t*)data;
    } else {
        /* To handle read request. */
        if (size!=0){
            uint16_t *buf = (uint16_t*) data;
            *buf = bt_if_gatt_notify;
        }
    }
    return sizeof(bt_if_gatt_notify);
}
```

- 5) Create five (5) records of the GATT service stored in `bt_if_gatt_service_rec`, as shown below.

```
/* To create records of GATT primary service. */
enum {
    GATT_HANDLE_START = 0x0011,
    GATT_HANDLE_PRIMARY_SERVICE = GATT_HANDLE_START,
    GATT_HANDLE_CHAR4_SERVICE_CHANGED,
    GATT_HANDLE_SERVICE_CHANGED,
    GATT_HANDLE_CLIENT_CONFIG,
    GATT_HANDLE_END
};
BT_GATTS_NEW_PRIMARY_SERVICE_16(bt_if_gatt_primary_service,
    BT_GATT_UUID16_GATT_SERVICE);
/* The record of service changed characteristic declaration. */
BT_GATTS_NEW_CHARC_16(bt_if_gatt_char4_service_changed,
    BT_GATT_CHARC_PROP_READ|BT_GATT_CHARC_PROP_NOTIFY|
    BT_GATT_CHARC_PROP_INDICATE,GATT_HANDLE_SERVICE_CHANGED,
    BT_SIG_UUID16_SERVICE_CHANGED);
/* The record of service changed characteristic value. */
BT_GATTS_NEW_CHARC_VALUE_UINT32_WRITABLE(bt_if_gatt_service_changed,
    BT_SIG_UUID_SERVICE_CHANGED, 0x2, 0x0001050F);
/* The record of client configuration descriptor. */
BT_GATTS_NEW_CLIENT_CHARC_CONFIG(bt_if_gatt_client_config,
    BT_GATTS_REC_PERM_READABLE|BT_GATTS_REC_PERM_WRITABLE,
    bt_if_gatt_client_config_callback);

static const bt_gatts_service_rec_t *bt_if_gatt_service_rec[] = {
    (const bt_gatts_service_rec_t*) &bt_if_gatt_primary_service,
    (const bt_gatts_service_rec_t*) &bt_if_gatt_char4_service_changed,
    (const bt_gatts_service_rec_t*) &bt_if_gatt_service_changed,
    (const bt_gatts_service_rec_t*) &bt_if_gatt_client_config
};
```

- 6) Create a GATT service named as `bt_if_gatt_service` and store it in `bt_if_gatt_server`, as shown below.

```
/* Value of starting_handle will be assigned to first record:
bt_if_gatt_primary_service.
Value of ending_handle will be assigned to end record:
bt_if_gatt_client_config.
(ending_handle - starting_handle + 1) should equal to number of records.
The required_encryption_key_size is used to define encryption key size
this service requires. If record's perm was setted with
BT_GATTS_REC_PERM_READABLE_ENCRYPTION or
BT_GATTS_REC_PERM_WRITABLE_ENCRYPTION, GATTS will check if the channel is
encrypted and the encryption key size is greater than or equal to
required_encryption_key_size. */

static const bt_gatts_service_t bt_if_gatt_service = {
    .starting_handle = GATT_HANDLE_START,
    .ending_handle = GATT_HANDLE_END - 1,
    .required_encryption_key_size = 9,
    /* If record need channel encryption, the size of encryption key
    should be equal to or greater than 9. */
    .records = bt_if_gatt_service_rec
};
```

- 7) Create a GATT Server named as `bt_if_gatt_server` to collect all services and implement

```
/* - Create bt_if_gatt_server and collect all services. */
// Server collects all service.
const bt_gatts_service_t * bt_if_gatt_server[] = {
    &bt_if_gap_service,
    &bt_if_gatt_service_ro,
    NULL
};
/* This server should be provided to GATTS via bt_get_gatt_server(). */
const bt_gatts_service_t** bt_get_gatt_server()
{
    return bt_if_gatt_server;
}
```

`bt_get_gatt_server()` to return the final constructed server.

- 8) If service or characteristic want to use 128 bit UUID, please refer to the following sample code.

```
/* - How to Add characteristic with 128 bit UUID. */
/* If uuid is 16 bit, convert it as 128 bit. */
bt_uuid_t uuid128_xxx = BT_UUID_INIT_WITH_UUID16(uuid16_xxx);
/* Define 128 UUID characteristic, and add to service as before. */
BT_GATTS_NEW_CHARC_128(name, prop, _handle, uuid128_xxx);

/* - How to add a secondary service with 128bit UUID. */
/* Define a secondary service with 128 bit UUID, and some characteristic
for this service */
#define BT_SIG_UUID_VENDOR_SERVICE
{{0x12,0x34,0x56,0x78,0x90,0x13,0x57,0x91,0x24,0x68,0x82,0x11,0x22,0x33,0x44,0x55}}
BT_GATTS_NEW_SECONDARY_SERVICE_128(bt_if_vendor_secondary_service,BT_SIG_U
UID_VENDOR_SERVICE);
BT_GATTS_NEW_CHARC_16(bt_if_vendor_char1_manufacture_name, ...) ;
.....
/* Add service records array into gatt server "bt_if_gatt_server[]" */
```

```
static const bt_gatts_service_rec_t *bt_if_vendor_service_rec[] = {
    (const bt_gatts_service_rec_t*) &bt_if_vendor_secondary_service,
    (const bt_gatts_service_rec_t*) &bt_if_vendor_char1_manufacture_name,
    .....
};
static const bt_gatts_service_t bt_if_vendor_service = {
    .starting_handle = 0x0500,
    .ending_handle = 0x0522,
    .required_encryption_key_size = 16,
    .records = bt_if_vendor_service_rec
};
const bt_gatts_service_t * bt_if_gatt_server[] = {
    &bt_if_gap_service, //0x0001
    &bt_if_gatt_service_ro, //0x0010
    &bt_if_bas_service, //0x0020
    &bt_if_vendor_service, //0x500
    NULL
};
/* Define include service which start/end handle same with secondary
service, and add include service into primary service. */
BT_GATTS_NEW_INCLUDED_SERVICE_128(bt_if_included_vendor_secondary_service,
0x0500, 0x0522);
static const bt_gatts_service_rec_t *bt_if_bas_service_rec[] = {
    (const bt_gatts_service_rec_t*) &bt_if_bas_primary_service,
    (const bt_gatts_service_rec_t*)&bt_if_included_vendor_secondary_service,
    .....
};
```

#### 4.3.1.1. GATT Server callbacks

- Implement the `bt_gatts_get_authorization_check_result()` API, if the GATT Server requires to check for an attribute authorization. The API confirms with a user whether to give authorization to a specified attribute. If the server accepts peer access to this attribute, the returned value is `BT_STATUS_SUCCESS`; otherwise, the returned value is `BT_STATUS_UNSUPPORTED`.
- If the GATT server has a long attribute, `bt_gatts_get_execute_write_result()` should be implemented, to confirm with the server whether execute write request completed successfully. If the execute write request completed successfully, the returned value is `BT_STATUS_SUCCESS`; otherwise, the returned value is `BT_ATT_ERRCODE_XXX`.

#### 4.3.2. Using the GATT APIs

This section describes how to use the GATT APIs in your application development. The APIs can be found in `bt_gattc.h` and `bt_gatts.h` header files.

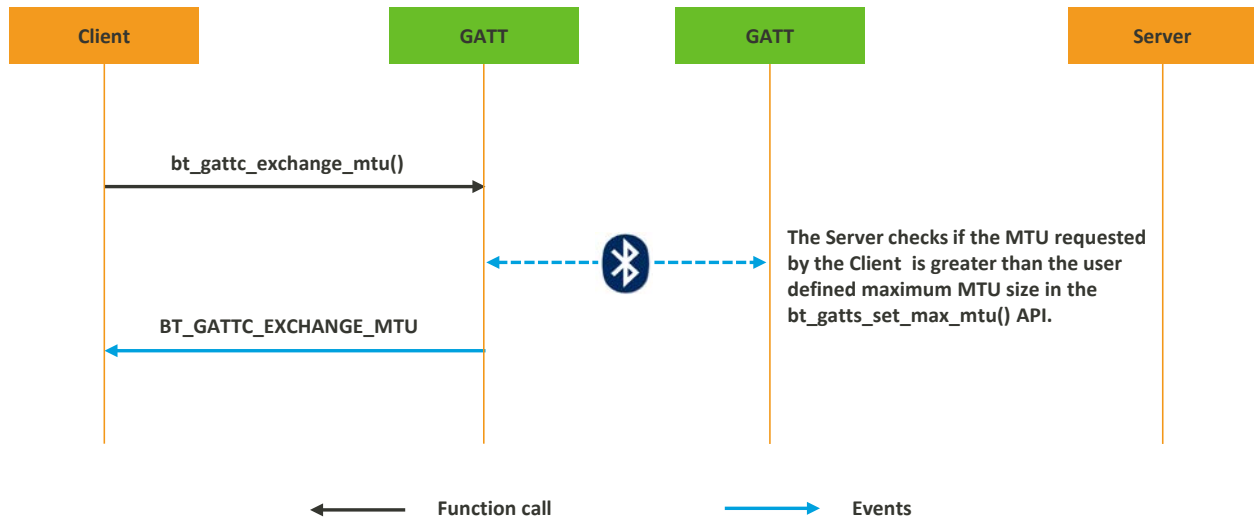
Most of the GATT APIs require a connection handle as the first parameter obtained from listening to the `BLE_GAP_CONNECT_IND` event from the `bt_app_event_callback()` callback function.

##### 4.3.2.1. Exchanging MTU

Initialize the Exchange MTU only once during a connection. The message flow for Exchange MTU is shown in Figure 81. More details can be found in the `bt_gattc.h` header file.

The default MTU size is 23. Neither client nor server should use MTU size of less than 23. When the client supports a value greater than the default MTU, the client should inform the server of the client's maximum receive MTU size by calling the function `bt_gattc_exchange_mtu()`.

The server can set the maximum MTU size it can support by calling `bt_gatts_set_max_mtu()`. Once the messages are exchanged, the final MTU between the two devices is set to the minimum of the client receive MTU and server receive MTU values. The GATT client or server can call the function `bt_gattc_get_mtu()` to get the current MTU.



**Figure 81. Exchange MTU event sequence**

An example implementation to Exchange MTU:

```

/* BLE devices is connected, and conn_handle has been obtained from
BLE_GAP. */
BT_GATTC_NEW_EXCHANGE_MTU_REQ(req);
bt_gattc_exchange_mtu(conn_handle, &req);

void bt_app_event_callback(bt_msg_type_t msg, bt_status_t status, void
*buff)
{
    switch (msg) {
        case BT_GATTC_EXCHANGE_MTU: {
            if (status != BT_STATUS_SUCCESS) {
                printf ("BT_GATTC_EXCHANGE_MTU FINISHED!!");
                break;
            }
            bt_gatt_exchange_mtu_rsp_t *rsp = (bt_gatt_exchange_mtu_rsp_t *)buff;
            printf("mtu=%d", rsp->server_rx_mtu);
            break;
        }
    }
}

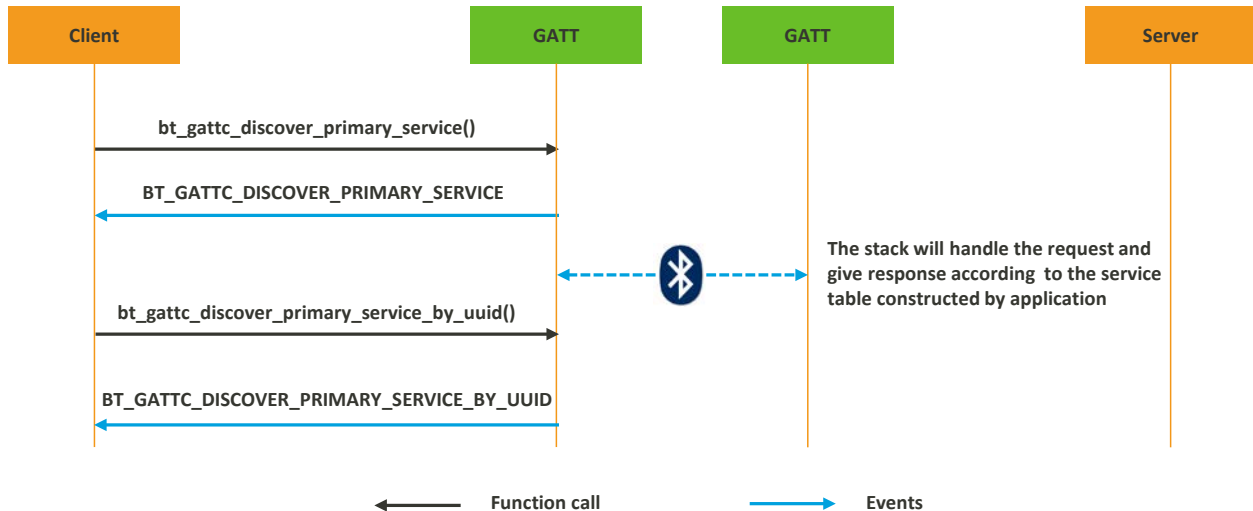
```

### 4.3.2.2. Primary service discovery

The Primary service discovery message flow is shown in Figure 82. More details can be found in the `bt_gattc.h` header file.

There are two APIs `bt_gattc_discover_primary_service()` and `bt_gattc_discover_primary_service_by_uuid()` used by a client to discover primary services on a server. Once the primary services are discovered, additional information about the primary services can be accessed using other APIs.





**Figure 82. Primary service discovery event sequence**

These two APIs will discover all primary services between the given starting handle and ending handle and then notify the upper layer about each received response.

An example implementation to discover a primary service:

```

/* BLE devices is connected, and conn_handle has been obtained from
BLE_GAP. */
BT_GATTC_NEW_DISCOVER_PRIMARY_SERVICE_REQ(req);
bt_gattc_discover_primary_service(conn_handle, &req);

void bt_app_event_callback(bt_msg_type_t msg, bt_status_t status, void
*buff)
{
    switch (msg) {
        case BT_GATTC_DISCOVER_PRIMARY_SERVICE: {
            if (status != BT_STATUS_SUCCESS && status != BT_ATT_ERRCODE_CONTINUE)
            {
                printf("BT_GATTC_DISCOVER_PRIMARY_SERVICE FINISHED!!");
                break;
            }
            bt_gattc_read_by_group_type_rsp_t *rsp =
(bt_gattc_read_by_group_type_rsp_t *)buff;
            uint16_t end_group_handle = 0, starting_handle = 0, uuid = 0;
            bt_uuid_t uuid128;
            uint8_t *attribute_data_list = rsp->att_rsp->attribute_data_list;
            uint8_t num_of_data = (rsp->length - 2) / rsp->att_rsp->length;
            int i, j;
            for (i = 0; i < num_of_data; i++) {
                memcpy(&starting_handle,
                    attribute_data_list + i * rsp->att_rsp->length, 2);
                memcpy(&end_group_handle,
                    attribute_data_list + i * rsp->att_rsp->length + 2, 2);
                if (rsp->att_rsp->length == 6) {
                    memcpy(&uuid, attribute_data_list + i * rsp->att_rsp->length + 4,
                        rsp->att_rsp->length - 4);
                } else {
                    memcpy(&uuid128.uuid, attribute_data_list+i*rsp->att_rsp->length +
4,
                        rsp->att_rsp->length - 4);
                }
            }
        }
    }
}
    
```

```

    }
  }
  break;
}
}

```

To discover a primary service by the UUID:

```

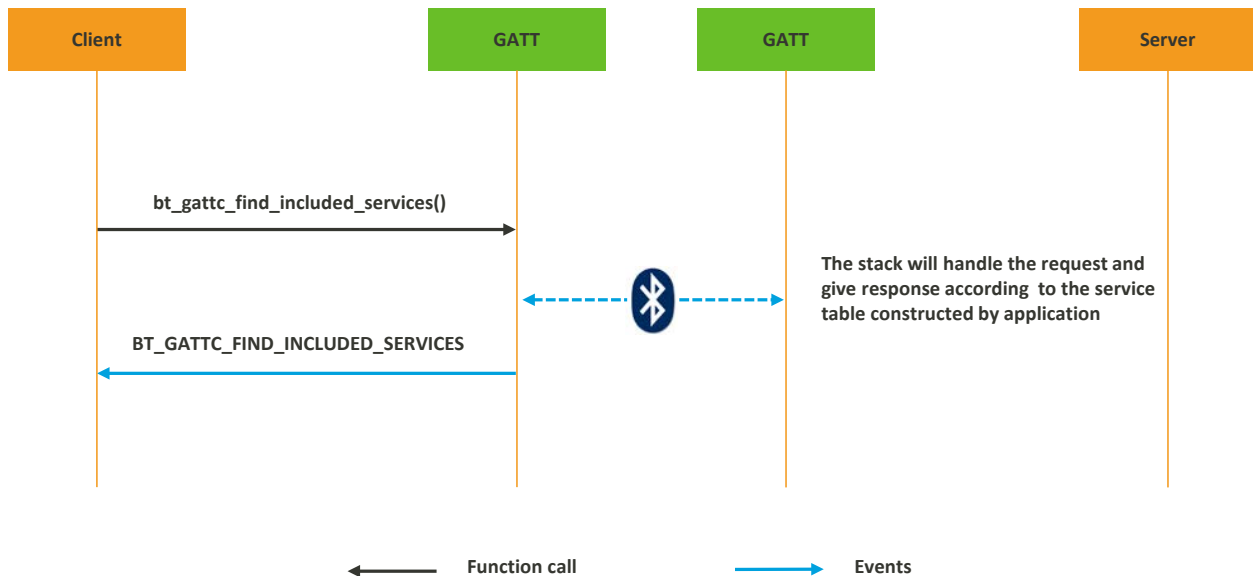
/* BLE devices is connected, and conn_handle has been obtained from
BLE_GAP. */
BT_GATTC_NEW_DISCOVER_PRIMARY_SERVICE_BY_UUID16_REQ(req, 0xABCD);
bt_gattc_discover_primary_service_by_uuid(conn_handle, &req);

void bt_app_event_callback(bt_msg_type_t msg, bt_status_t status, void
*buff)
{
  switch (msg) {
  case BT_GATTC_DISCOVER_PRIMARY_SERVICE_BY_UUID: {
    if (status != BT_STATUS_SUCCESS && status != BT_ATT_ERRCODE_CONTINUE)
    {
      printf("BT_GATTC_DISCOVER_PRIMARY_SERVICE BY UUID FINISHED!!");
      break;
    }
    bt_gattc_find_by_type_value_rsp_t *rsp =
      (bt_gattc_find_by_type_value_rsp_t *)buff;
    uint16_t attribute_handle = 0, end_group_handle = 0;
    uint8_t *handles_info_list = rsp->att_rsp->handles_info_list;
    uint8_t num_of_info = (rsp->length - 1) / 4;
    int i;
    for (i = 0 ; i < num_of_info; i++) {
      memcpy(&attribute_handle, handles_info_list + 4 * i, 2);
      memcpy(&end_group_handle, handles_info_list + 4 * i + 2, 2);
    }
    break;
  }
}
}

```

When the server receives a Primary service discovery request, the stack handles this message and sends a response to the client. The server only constructs a profile as described in section 4.3.1, "Create a GATT Server".

## 4.3.2.3. Find included services



**Figure 83. Find included services event sequence**

The Find included services message flow is shown in Figure 83. More details can be found in the `bt_gattc.h` header file.

Call the function `bt_gattc_find_included_services()` to find the included services. The response is in `BT_GATTC_FIND_INCLUDED_SERVICES`.

An example implementation to find included services:

```

/* BLE devices is connected, and conn_handle has been obtained from
BLE_GAP. */
BT_GATTC_NEW_FIND_INCLUDED_SERVICE_REQ(req, 0x0001, 0x0010);
bt_gattc_find_included_services(conn_handle, &req);

void bt_app_event_callback(bt_msg_type_t msg, bt_status_t status, void
*buff)
{
    switch (msg) {
        case BT_GATTC_FIND_INCLUDED_SERVICES: {
            if (status != BT_STATUS_SUCCESS && status != BT_ATT_ERRCODE_CONTINUE)
            {
                printf("BT_GATTC_FIND_INCLUDED_SERVICES FINISHED!!");
                break;
            }
            bt_gattc_read_by_type_rsp_t *rsp = (bt_gattc_read_by_type_rsp_t
*)buff;
            uint8_t *attribute_data_list = rsp->att_rsp->attribute_data_list;
            uint16_t attribute_handle = 0, starting_handle = 0, ending_handle = 0;
            uint16_t uuid = 0;
            bt_uuid_t uuid128;
            int i;

            if (rsp->att_rsp->length <= 8) {
                uint8_t num_of_data = (rsp->length - 2) / rsp->att_rsp->length;
                for (i = 0 ; i < num_of_data; i++) {
                    memcpy(&attribute_handle,

```

```

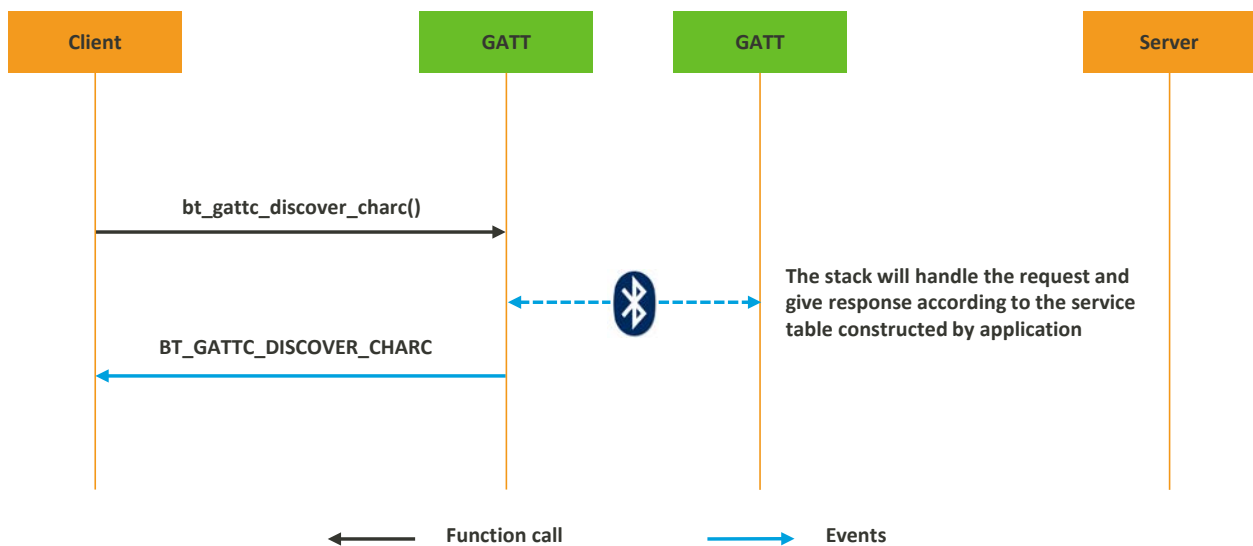
        attribute_data_list + rsp->att_rsp->length*i, 2);
memcpy(&starting_handle,
        attribute_data_list + rsp->att_rsp->length*i + 2, 2);
memcpy(&ending_handle,
        attribute_data_list + rsp->att_rsp->length*i + 4, 2);
memcpy(&uuid, attribute_data_list + rsp->att_rsp->length*i + 6,
2);
    }
} else {
    memcpy(&attribute_handle, attribute_data_list, 2);
    memcpy(&starting_handle, attribute_data_list + 2, 2);
    memcpy(&ending_handle, attribute_data_list + 4, 2);
    memcpy(&uuid128.uuid, attribute_data_list + 6, 16);
}
break;
}
}

```

When the server receives Find included services request, the stack handles this message and responds to the client according to the profile constructed by the application, as described in section 4.3.1, “Create a GATT Server”.

#### 4.3.2.4. Characteristic discovery

The Characteristic discovery message flow is shown in Figure 84. More details can be found in the `bt_gattc.h` header file.



**Figure 84. Discover characteristic event sequence**

Call the function `bt_gattc_discover_charc()` for characteristic discovery. The response is in the `BT_GATTC_DISCOVER_CHARC`.

An example implementation for the Characteristic discovery:

```

/* BLE devices is connected, and conn_handle has been obtained from
BLE_GAP. */
BT_GATTC_NEW_DISCOVER_CHARC_REQ(req, 0x0001, 0x0010);
bt_gattc_discover_charc(conn_handle, &req);

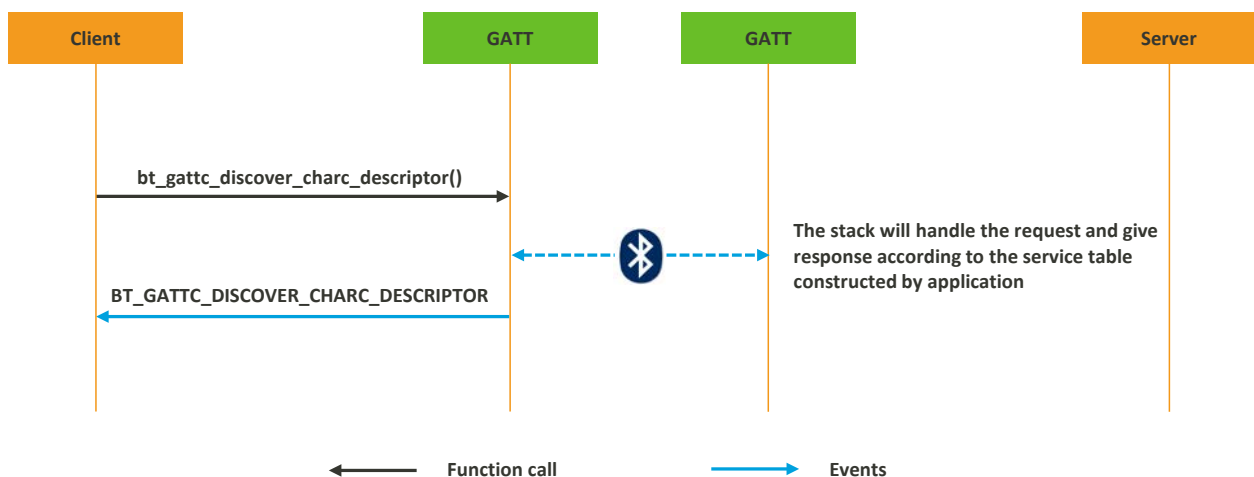
void bt_app_event_callback(bt_msg_type_t msg, bt_status_t status, void
*buff)
{

```

```
switch (msg) {
case BT_GATTC_DISCOVER_CHARC: {
    if (status != BT_STATUS_SUCCESS && status != BT_ATT_ERRCODE_CONTINUE)
    {
        printf("BT_GATTC_DISCOVER_CHARC FINISHED!!");
        break;
    }
    bt_gattc_read_by_type_rsp_t *rsp = (bt_gattc_read_by_type_rsp_t
*)buff;
    uint8_t *attribute_data_list = rsp->att_rsp->attribute_data_list;
    uint16_t attribute_handle = 0;
    uint8_t attribute_value[30] = {0};
    uint8_t num_of_data = (rsp->length - 2) / rsp->att_rsp->length;
    bt_uuid_t uuid128;
    int i, j;
    if (rsp->att_rsp->length < 20) {
        for (i = 0 ; i < num_of_data; i++) {
            memcpy(&attribute_handle,
                attribute_data_list + i * rsp->att_rsp->length, 2);
            memcpy(&attribute_value, attribute_data_list+i*rsp->att_rsp-
>length+2,
                rsp->att_rsp->length - 2);
        }
    } else {
        memcpy(&attribute_handle, attribute_data_list, 2);
        memcpy(&attribute_value, attribute_data_list + 3, 2);
        memcpy(&uuid128.uuid, attribute_data_list + 5, 16);
    }
    break;
}
}
```

When the server receives a Characteristic discovery request, the stack handles this message and responds to the client according to the profile constructed by the application, as described in section 4.3.1, "Create a GATT Server".

#### 4.3.2.5. Characteristic descriptor discovery



**Figure 85. Characteristic descriptor discovery event sequence**

The Characteristic descriptor discovery message flow is shown in Figure 85. More details can be found in the header file `bt_gattc.h`.

`bt_gattc_discover_charc_descriptor()` is used by a client to find all the characteristic descriptors'

**Attribute Handles** and **Attribute Types** within a characteristic definition when only the characteristic handle range is known. The start handle should be set to the handle of the specified characteristic value + 1, and the end handle should be set to the ending handle of the specified characteristic or service. The response will be stored in `BT_GATTC_DISCOVER_CHARC_DESCRIPTOR`.

An example implementation for the Characteristic descriptor discovery:

```
/* BLE devices is connected, and conn_handle has been obtained from
BLE_GAP. */
BT_GATTC_NEW_DISCOVER_CHARC_DESCRIPTOR_REQ(req, 0x0003, 0x0005);
bt_gattc_discover_charc_descriptor(conn_handle, &req);

void bt_app_event_callback(bt_msg_type_t msg, bt_status_t status, void
*buff)
{
    switch (msg) {
    case BT_GATTC_DISCOVER_CHARC_DESCRIPTOR: {
        if (status != BT_STATUS_SUCCESS && status != BT_ATT_ERRCODE_CONTINUE)
        {
            printf("BT_GATTC_DISCOVER_CHARC_DESCRIPTOR FINISHED!!");
            break;
        }
        bt_gattc_find_info_rsp_t *rsp = (bt_gattc_find_info_rsp_t *)buff;
        uint8_t format = rsp->att_rsp->format;
        uint16_t attribute_handle = 0, attribute_value = 0;
        uint8_t attribute_length = 0;
        uint8_t num_of_attribute;
        bt_uuid_t uuid128;
        int i, j;
        if ( format == 0x02 ) {
            /* 128-bit UUID. */
            attribute_length = 18;
            num_of_attribute = (rsp->length - 2) / attribute_length;
            for (i = 0; i < num_of_attribute; ++i) {
                memcpy(&attribute_handle,
                    rsp->att_rsp->info_data + i * attribute_length, 2);
                memcpy(&uuid128,
                    rsp->att_rsp->info_data + i * attribute_length + 2, 16);
            }
        } else {
            /* 16-bit UUID. */
            attribute_length = 4;
            num_of_attribute = (rsp->length - 2) / attribute_length;
            memcpy(&attribute_handle,
                rsp->att_rsp->info_data+(num_of_attribute-
1)*attribute_length, 2);
            memcpy(&attribute_value,
                rsp->att_rsp->info_data+(num_of_attribute-
1)*attribute_length+2, 2);
        }
        break;
    }
}
```

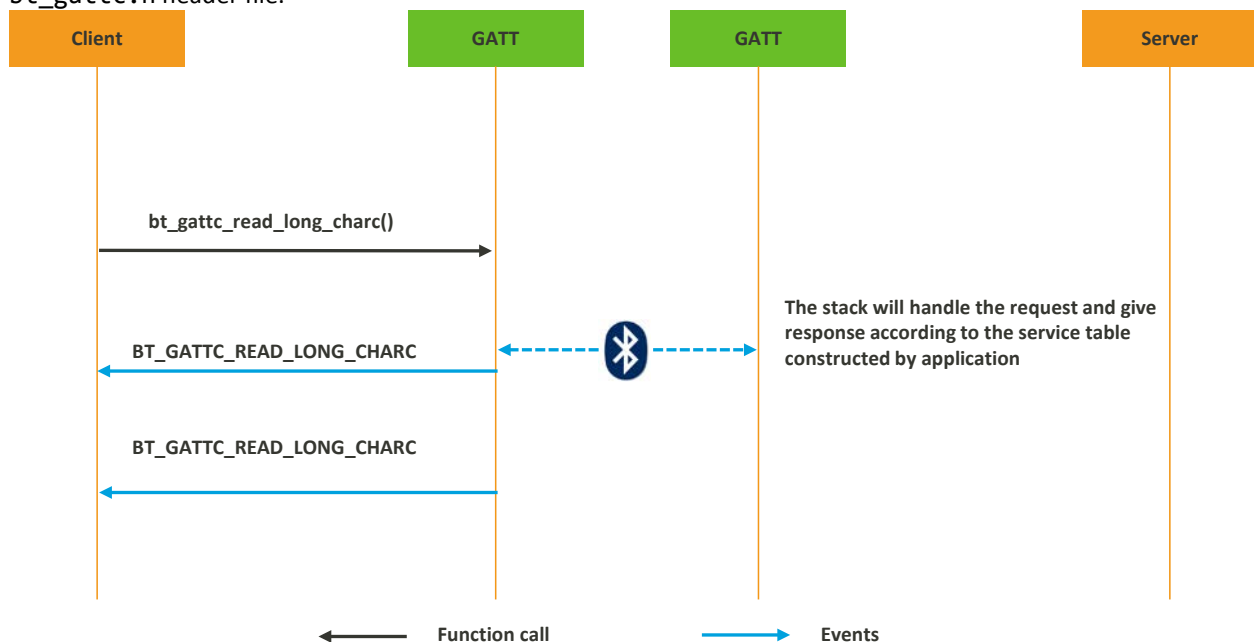
When the server receives the Characteristic descriptor discovery request, the stack handles this message and sends a response to the client according to the profile constructed by the application, as described in section 4.3.1, "Create a GATT Server".

## 4.3.2.6. Read the characteristic value

There are four APIs to read a characteristic value, `bt_gattc_read_charc()`, `bt_gattc_read_long_charc()`, `bt_gattc_read_using_charc_uuid()` and `bt_gattc_read_multi_charc_values()`.

- 1) Call the function `bt_gattc_read_charc()` to read a characteristic value from the server, if the client knows the characteristic value handle only. The handle parameter should be set to the characteristic value handle. The `BT_GATTC_READ_CHARC` returns the characteristic value.
- 2) Call the function `bt_gattc_read_long_charc()` to read the characteristic value, if the client knows the characteristic value handle and the length of the characteristic value is more than `MTU - 1`. The Bluetooth stack will continuously send read blob request until all the values of the characteristic are read. It will provide a response in `BT_GATTC_READ_LONG_CHARC` one by one, user is responsible to merge them together.
- 3) Call the function `bt_gattc_read_using_charc_uuid()` to read a characteristic value, if the client knows only the characteristic UUID and does not know the handle of the characteristic.
- 4) Call the function `bt_gattc_read_multi_charc_values()` to read multiple characteristic values in one request, if the handle parameter is set to the characteristic value handles.

The message flow to read the characteristic value is shown in Figure 86. More details can be found in the `bt_gattc.h` header file.



**Figure 86. Characteristic value read event sequence**

An example implementation to apply the function `bt_gattc_read_long_charc()`:

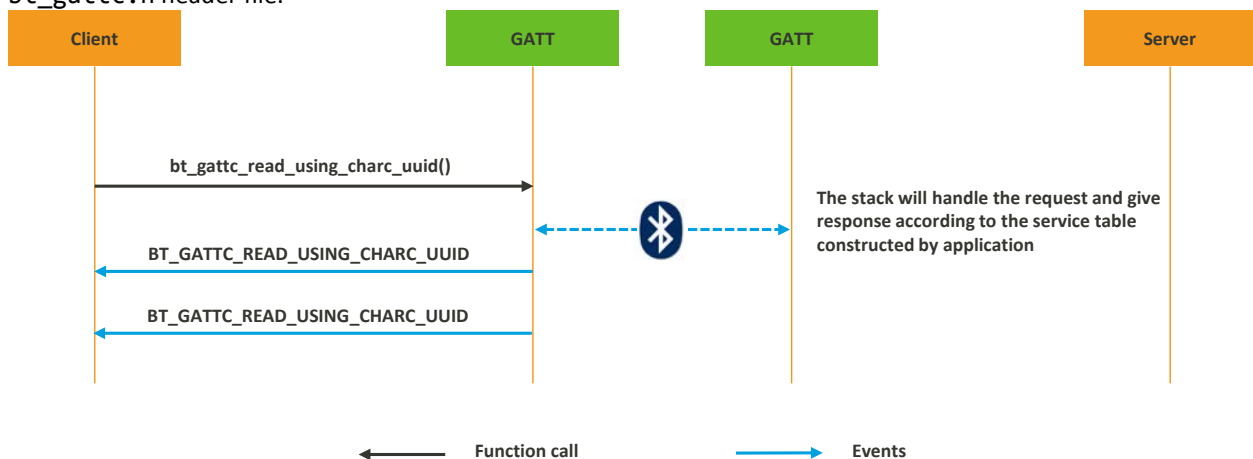
```

/* BLE devices is connected, and conn_handle has been obtained from
BLE_GAP. */
BT_GATTC_NEW_READ_LONG_CHARC_REQ(req, 0x0008, 0);
bt_gattc_read_long_charc(conn_handle, &req);
void bt_app_event_callback(bt_msg_type_t msg, bt_status_t status, void
*buff)

```

```
{
    switch (msg) {
    case BT_GATTC_READ_LONG_CHARC: {
        if (status != BT_STATUS_SUCCESS) {
            printf("BT_GATTC_READ_LONG_CHARC FINISHED!!");
            break;
        }
        bt_gattc_read_blob_rsp_t *rsp = (bt_gattc_read_blob_rsp_t*)buff;
        uint8_t length = rsp->length - 1;
        int i;
        for (i = 0; i < length ; i++)
            printf("0x%02x ", rsp->att_rsp->attribute_value[i]);
        break;
    }
    }
}
```

The message flow to read the characteristic value by UUID is shown in Figure 87. More details can be found in the `bt_gattc.h` header file.



**Figure 87. Read characteristic value using UUID event sequence**

An example implementation to apply the function `bt_gattc_read_using_charc_uuid()`:

```
/* BLE devices is connected, and conn_handle has been obtained from
BLE_GAP. */
uint8_t uuid16[2] = {0x2A, 0x01};
BT_GATTC_NEW_READ_USING_CHARC_UUID_REQ(req, 0x0001, 0xFFFF, uuid16, 2);
bt_gattc_read_using_charc_uuid(conn_handle, &req);

void bt_app_event_callback(bt_msg_type_t msg, bt_status_t status, void
*buff)
{
    switch (msg) {
    case BT_GATTC_READ_USING_CHARC_UUID: {
        if (status != BT_STATUS_SUCCESS) {
            printf("BT_GATTC_READ_USING_CHARC_UUID FINISHED!!");
            break;
        }
        bt_gattc_read_by_type_rsp_t *rsp = (bt_gattc_read_by_type_rsp_t
*)buff;
        uint8_t *attribute_data_list = rsp->att_rsp->attribute_data_list;
        uint16_t attribute_handle = 0;
        uint8_t attribute_value[30] = {0};
        int i, j;
        uint8_t num_of_data = (rsp->length - 2) / rsp->att_rsp->length;
```

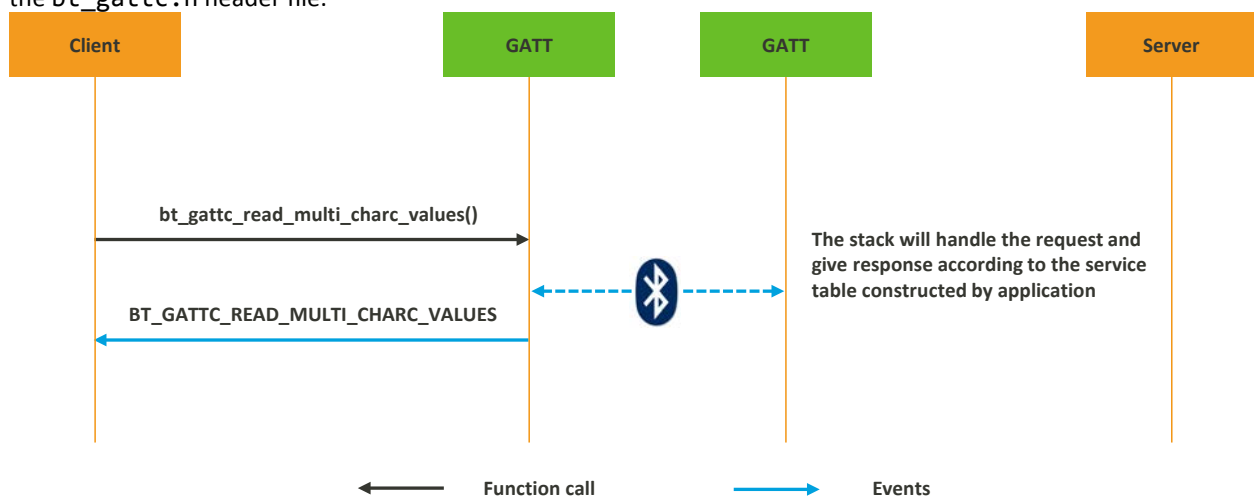


```

for (i = 0 ; i < num_of_data; i++) {
    memcpy(&attribute_handle,
           attribute_data_list + i * rsp->att_rsp->length, 2);
    memcpy(&attribute_value, attribute_data_list + i*rsp->att_rsp-
>length + 2,
           rsp->att_rsp->length - 2);
    for (j = 0; j < rsp->att_rsp->length - 2; j++) {
        printf("0x%02x ", attribute_value[j]);
    }
}
break;
}
}

```

The message sequence to read multiple characteristic values is shown in Figure 88. More details can be found in the `bt_gattc.h` header file.



**Figure 88. Read multiple characteristic value event sequence**

An example implementation to apply the function `bt_gattc_read_multi_charc_values()`:

```

/* BLE devices is connected, and conn_handle has been obtained from
BLE_GAP. */
bt_gattc_read_multi_charc_values_req_t req;
req.handle_length = 4; /* The length of value handles. 4 means there
are two handles. */
uint8_t buffer[5] = {0}; /* Buffer length = 1 + handle_length. */
req.att_req = (bt_att_read_multiple_req_t *)buffer;
req.att_req->opcode = BT_ATT_OPCODE_READ_MULTIPLE_REQUEST;
req.att_req->set_of_handles[0] = 0x0003;
req.att_req->set_of_handles[1] = 0x0005;
bt_gattc_read_multi_charc_values(conn_handle, &req);

void bt_app_event_callback(bt_msg_type_t msg, bt_status_t status, void
*buff)
{
    switch (msg) {
    case BT_GATTC_READ_MULTI_CHARC_VALUES: {
        if (status != BT_STATUS_SUCCESS) {
            printf("BT_GATTC_READ_MULTI_CHARC_VALUES FINISHED!!");
            break;
        }
        bt_gattc_read_multiple_rsp_t *rsp = (bt_gattc_read_multiple_rsp_t

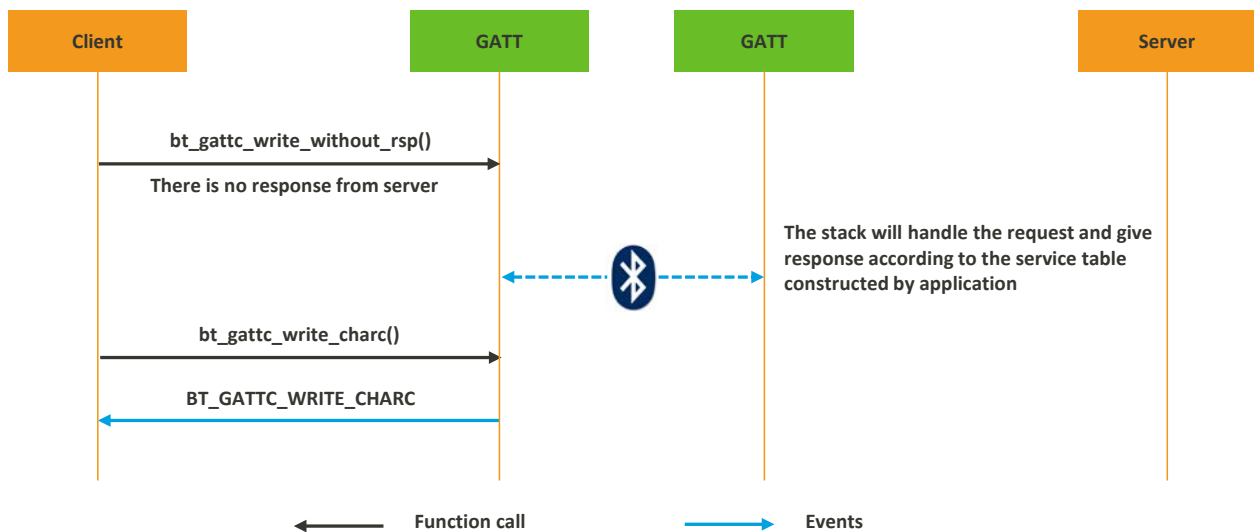
```

```

*)buff;
uint8_t op_code = rsp->att_rsp->opcode;
uint8_t length = rsp->length - 1;
int i;
for (i = 0; i < length; i++) {
    printf("0x%02x ", rsp->att_rsp->set_of_values[i]);
}
break;
}
}
}

```

#### 4.3.2.7. Characteristic value write



**Figure 89. Characteristic value write event sequence**

There are two types for write characteristic value requests to write a characteristic value no longer than the MTU, as shown in Figure 89. More details can be found in the `bt_gattc.h` header file.

- 1) Call the function `bt_gattc_wrote_without_rsp()`, if the client knows the characteristic value handle and does not need an acknowledgement that the write was successfully performed.
- 2) Call the function `bt_gattc_write_charc()`, if the client requires the status of a write request.

An example implementation of these two APIs:

```

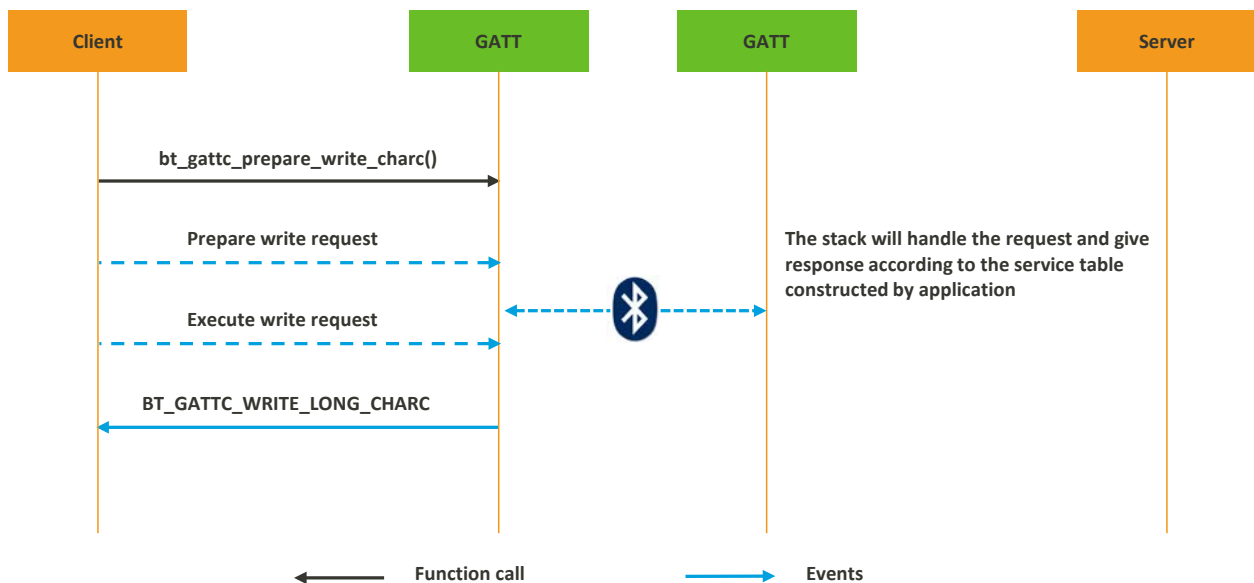
/* BLE devices is connected, and conn_handle has been obtained from
BLE_GAP. */
static uint8_t buff[40] = {0};
static uint8_t *value = "TestWriteCmd";
BT_GATTC_NEW_WRITE_WITHOUT_RSP_REQ(req, buff, 0, 0x0008, value,
strlen(value));
/* 0 means it is WRITE_COMMAND, 1 means SIGNED_WRITE_COMMAND. */
bt_gattc_write_without_rsp(conn_handle, 0, &req);
/* There is no response to handle for this request. */

static uint8_t buff2[40] = {0};
BT_GATTC_NEW_WRITE_CHARC_REQ(wreq, buff2, 0x0011, value, strlen(value));
bt_gattc_write_charc(conn_handle, &wreq);

```

```
void bt_app_event_callback(bt_msg_type_t msg, bt_status_t status, void
*buff)
{
    switch (msg) {
        case BT_GATTC_WRITE_CHARC: {
            printf("bt_gattc_write_charc, status = %d!!", status);
            break;
        }
    }
}
```

#### 4.3.2.8. Long characteristic value or descriptor write



**Figure 90. Long value write event sequence**

Apply the function `bt_gattc_prepare_write_charc()`, if the length of a characteristic value or descriptor is greater than the MTU size, as shown in Figure 90. More details can be found in the `bt_gattc.h` header file.

To write the complete characteristic value or descriptor, the offset should be set to 0. The Bluetooth stack will update the offset and send a subsequent **Prepare write** request. The **Prepare write** request is repeated until the characteristic value or descriptor is completely transferred, after which the **Execute write** request is used to write the complete value.

The second parameter of `bt_gattc_prepare_write_charc()` is to decide whether it is a reliable write or not. If set to 1, the Bluetooth stack will check if the value in the **Prepare write** response is the same as **Prepare write** request, if so, it will send a subsequent **Prepare write** request, else, it will send **Cancel the execute write request** to abort the write long procedure.

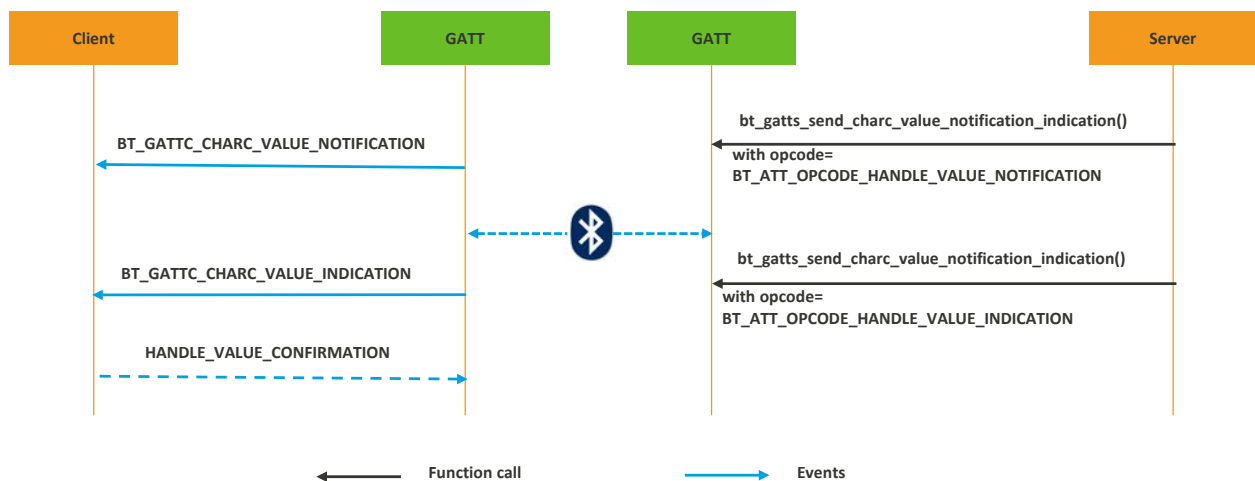
An example implementation is shown below:

```
/* BLE devices is connected, and conn_handle has been obtained from
BLE_GAP. */
static uint8_t *gatt_long_charc =
"ABCDEF1234567890FEDCBA098765432104134545563535";
BT_GATTC_NEW_PREPARE_WRITE_REQ(req, 0x0022, 0, gatt_long_charc,
strlen(gatt_long_charc));
bt_gattc_prepare_write_charc(conn_handle, 0, 0, &req);
```

```
void bt_app_event_callback(bt_msg_type_t msg, bt_status_t status, void
*buff)
{
    switch (msg) {
        case BT_GATTC_WRITE_LONG_CHARC:
        case BT_GATTC_RELIABLE_WRITE_CHARC: {
            printf("bt_gattc_prepare_write_charc, status = %d!!", status);
            break;
        }
    }
}
```

### 4.3.2.9. Characteristic value indication

Call the function `bt_gatts_send_charc_value_notification_indication()`, if the server requires to indicate a characteristic value to a client and expects an acknowledgement. The message flow is shown in Figure 91. More details can be found in the `bt_gatts.h` header file.



**Figure 91. Characteristic value indication event sequence**

An example implementation for the server to notify and indicate a characteristic value:

```
/* BLE devices is connected, and conn_handle has been obtained from
BLE_GAP. */
static uint8_t buf[64] = {0};
static uint8_t *noti_value = "notification"; /* The value to notify. */
bt_gattc_charc_value_notification_indication_t *bas_noti =
(bt_gattc_charc_value_notification_indication_t *)buf;
bas_noti->att_req.opcode = BT_ATT_OPCODE_HANDLE_VALUNE_NOTIFICATION;
bas_noti->att_req.handle = 0x0013; /* The value handle to notify. */
bas_noti->attribute_value_length = strlen(noti_value);
memcpy((void *) (bas_noti->att_req.attribute_value), noti_value,
strlen(noti_value));
bt_gatts_send_charc_value_notification_indication(conn_handle, bas_noti);
static uint8_t *ind_value = "indication"; /* The value to indicate. */
bt_gattc_charc_value_notification_indication_t *bas_ind =
(bt_gattc_charc_value_notification_indication_t *)buf;
bas_ind->att_req.opcode = BT_ATT_OPCODE_HANDLE_VALUNE_INDICATION;
bas_ind->att_req.handle = 0x0015; /* The value handle to indicate. */
bas_ind->attribute_value_length = strlen(ind_value);
memcpy((void *) (bas_ind->att_req.attribute_value), ind_value,
strlen(ind_value));
```

```
bt_gatts_send_charc_value_notification_indication(conn_handle, bas_ind);
```

An example implementation for the client to handle a characteristic value notification and indication:

```
void bt_app_event_callback(bt_msg_type_t msg, bt_status_t status, void
*buff)
{
    switch (msg) {
        case BT_GATTC_CHARC_VALUE_NOTIFICATION:
        case BT_GATTC_CHARC_VALUE_INDICATION: {
            bt_gatt_handle_value_notification_t *rsp =
                (bt_gatt_handle_value_notification_t
            *)buff;
            uint8_t op_code = rsp->att_rsp->opcode;
            uint16_t attribute_handle = rsp->att_rsp->handle;
            uint8_t length = rsp->length - 3;
            int i;
            printf("op_code = 0x%08x", op_code);
            printf("attribute_handle = 0x%08x", attribute_handle);
            for (i = 0; i < length ; i++)
                printf("0x%02x ", rsp->att_rsp->attribute_value[i]);
            printf("\n");
            break;
        }
    }
}
```

## 5. Creating a Custom Bluetooth Application

This section guides you through creating your own Bluetooth project including:

- Memory management for the SDK according to the application requirements.
- Creating a task. The task provides access to the system resources such as CPU and queues. The application can adjust task priorities to optimize the CPU usage.
- How to interact with the SDK stack task — a special, high priority task.
- Bluetooth panic mechanism for restoring Bluetooth function when Bluetooth works no normal.

### 5.1. Memory management

#### 5.1.1. Memory configuration

Memory configuration of the application should be applied before the Bluetooth powers on. There are two types of memory resources:

- 1) TX/RX buffer.
  - BT\_MEMORY\_TX\_BUFFER — Bluetooth transmit buffer. The buffer size determines the transmit speed and probability of out of memory (OOM) occurrence.
  - BT\_MEMORY\_RX\_BUFFER — Bluetooth receive buffer. The buffer size determines the speed and probability of the OOM occurrence.
- 2) Fixed size control blocks are shown in Table 5.

**Table 5. Fixed size control blocks**

Control block	Description
BT_MEMORY_CONTROL_BLOCK_TIMER	Control block for the timer. The maximum allocated timer value is ACL Link number added with 3 and normally it's the same as the value for BT_MEMORY_CONTROL_BLOCK_LE_CONNECTION and BT_MEMORY_CONTROL_BLOCK_EDR_CONNECTION
BT_MEMORY_CONTROL_BLOCK_LE_CONNECTION	Control block for LE connection. Each ACL link allocates a portion of this memory.
BT_MEMORY_CONTROL_BLOCK_EDR_CONNECTION	Control block for EDR connection. Each ACL link allocates a portion of this memory.
BT_MEMORY_CONTROL_BLOCK_RFCOMM	Control block for RFCOMM
BT_MEMORY_CONTROL_BLOCK_AVRCP	Control block for AVRCP
BT_MEMORY_CONTROL_BLOCK_PBAPC	Control block for PBAPC
BT_MEMORY_CONTROL_BLOCK_A2DP_SEP	Control block for A2DP SEP
BT_MEMORY_CONTROL_BLOCK_A2DP	Control block for A2DP
BT_MEMORY_CONTROL_BLOCK_HFP	Control block for HFP
BT_MEMORY_CONTROL_BLOCK_SPP	Control block for SPP

The application should configure the memory for the control block, if the module is enabled. To improve memory utilization, the SDK enables an OOM mechanism. If OOM occurs, the device operation may fail or the throughput may slow down. To increase the performance of Bluetooth stack, application should ensure there is enough memory allocated in TX/RX buffers.

An example implementation to configure the memory size for each memory block is shown below.

```
/*To configure the max EDR ACL link number, please refer to the datasheet
chapter 1.3 for the maximum link number.*/
#define BT_CONNECTION_MAX 2
#define BT_CONNECTION_BUF_SIZE \
    (BT_CONNECTION_MAX *
BT_CONTROL_BLOCK_SIZE_OF_EDR_CONNECTION)
static char bt_connection_cb_buf[BT_CONNECTION_BUF_SIZE];

/*To configure the timer, the suggested value is between BT_MAX_ACL_LINK
to
    BT_MAX_ACL_LINK+3 */
#define BT_TIMER_NUM 5
#define BT_TIMER_BUF_SIZE (BT_TIMER_NUM * BT_CONTROL_BLOCK_SIZE_OF_TIMER)
static char timer_cb_buf[BT_TIMER_BUF_SIZE];

/*To configure the transmit packet buffer, the value depends on the ACL
link and the GATT MTU size. Usually it's difficult to send data in all ACL
links. The suggested TX buffer size is about 2~3 times the MTU size.*/
#define BT_TX_BUFFER_SIZE 256 * BT_MAX_ACL_LINK
static tx_buf[BT_TX_BUFFER_SIZE];

/*To configure the receive packet buffer, the value depends on the ACL
link and the GATT MTU size. Receive buffer may receive data from all ACL
links and advertising data. The suggested RX buffer size is more than
1Kbytes or ACL link num * MTU size) */
#define BT_RX_BUFFER_SIZE 1024 * BT_MAX_ACL_LINK
static rx_buf[BT_RX_BUFFER_SIZE];

/*To configure the max LE link number, please refer to the datasheet
chapter 1.3 for the maximum link number. */
#define BT_LE_CONNECTION_MAX 10
#define BT_LE_CONNECTION_BUF_SIZE \
    (BT_LE_CONNECTION_MAX * BT_CONTROL_BLOCK_SIZE_OF_LE_CONNECTION)
static char le_conn_cb_buf[BT_LE_CONNECTION_BUF_SIZE];

/*To configure the rfcomm buffer size, the value of
BT_RFCOMM_TOTAL_LINK_NUM is the supported rfcomm link number*/
#define BT_RFCOMM_TOTAL_LINK_NUM 2
#define BT_RFCOMM_BUF_SIZE \
    (BT_RFCOMM_TOTAL_LINK_NUM *
BT_CONTROL_BLOCK_SIZE_OF_RFCOMM)
static char bt_rfcomm_cb_buf[BT_RFCOMM_BUF_SIZE];

/*To configure the hfp buffer size, the value of BT_HFP_TOTAL_LINK_NUM is
the supported hfp link number*/
#define BT_HFP_TOTAL_LINK_NUM 2
#define BT_HFP_BUF_SIZE \
    (BT_HFP_TOTAL_LINK_NUM * BT_CONTROL_BLOCK_SIZE_OF_HFP)
static char bt_hfp_cb_buf[BT_HFP_BUF_SIZE];

/*To configure the avrctp buffer size, the value of BT_AVRCP_TOTAL_LINK_NUM
is the supported avrctp link number*/
```

```
#define BT_AVRCP_TOTAL_LINK_NUM 2
#define BT_AVRCP_BUF_SIZE \
    (BT_AVRCP_TOTAL_LINK_NUM *
BT_CONTROL_BLOCK_SIZE_OF_AVRCP)
static char bt_avrcp_cb_buf[BT_AVRCP_BUF_SIZE];

/* To configure the a2dp streaming end point(sep) buffer size, the value
of BT_A2DP_SINK_CODEC_NUM is the supported sink codec number. The value of
BT_A2DP_SEP_TOTAL_NUM is the supported a2dp link number */
#define BT_A2DP_SINK_CODEC_NUM 2
#define BT_A2DP_SEP_TOTAL_NUM (2 * BT_A2DP_SINK_CODEC_NUM)
#define BT_A2DP_SEP_BUF_SIZE (BT_A2DP_SEP_TOTAL_NUM *
BT_CONTROL_BLOCK_SIZE_OF_A2DP_SEP) static char
bt_a2dp_sep_cb_buf[BT_A2DP_SEP_BUF_SIZE];

/*To configure the a2dp buffer size, the value of BT_A2DP_TOTAL_LINK_NUM
is the supported a2dp link number*/
#define BT_A2DP_TOTAL_LINK_NUM 2
#define BT_A2DP_BUF_SIZE \
    (BT_A2DP_TOTAL_LINK_NUM *
BT_CONTROL_BLOCK_SIZE_OF_A2DP)
static char bt_a2dp_cb_buf[BT_A2DP_BUF_SIZE];

/*To configure the spp buffer size, the value of
BT_SPP_TOTAL_CONNECTION_NUM is the supported spp total connection number*/
#define BT_SPP_TOTAL_CONNECTION_NUM 5
#define BT_SPP_BUF_SIZE \
    (BT_SPP_TOTAL_CONNECTION_NUM *
BT_CONTROL_BLOCK_SIZE_OF_SPP)
static char bt_spp_cb_buf[BT_SPP_BUF_SIZE];

/*To configure the pbapc buffer size, the value of
BT_PBAPC_TOTAL_CONNECTION_NUM is the supported pbapc link number*/
#define BT_PBAPC_TOTAL_CONNECTION_NUM 2
#define BT_PBAPC_BUF_SIZE \
    (BT_PBAPC_TOTAL_CONNECTION_NUM *
BT_CONTROL_BLOCK_SIZE_OF_PBAPC)
static char bt_pbapc_cb_buf[BT_PBAPC_BUF_SIZE];

void bt_mm_init(void)
{
    bt_memory_init_packet(BT_MEMORY_TX_BUFFER, tx_buf, BT_TX_BUFFER_SIZE);
    bt_memory_init_packet(BT_MEMORY_TX_BUFFER, tx_buf, BT_TX_BUFFER_SIZE);
    bt_memory_init_control_block(BT_MEMORY_CONTROL_BLOCK_TIMER,
timer_cb_buf,
                                BT_TIMER_BUF_SIZE);
    bt_memory_init_control_block(BT_MEMORY_CONTROL_BLOCK_LE_CONNECTION,
                                le_conn_cb_buf,
BT_LE_CONNECTION_BUF_SIZE);
    bt_memory_init_control_block(BT_MEMORY_CONTROL_BLOCK_EDR_CONNECTION,
                                bt_connection_cb_buf,
BT_CONNECTION_BUF_SIZE);
    bt_memory_init_control_block(BT_MEMORY_CONTROL_BLOCK_RFCOMM,
                                bt_rfcomm_cb_buf, BT_RFCOMM_BUF_SIZE);
    bt_memory_init_control_block(BT_MEMORY_CONTROL_BLOCK_HFP,
                                bt_hfp_cb_buf, BT_HFP_BUF_SIZE);
    bt_memory_init_control_block(BT_MEMORY_CONTROL_BLOCK_AVRCP,
                                bt_avrcp_cb_buf, BT_AVRCP_BUF_SIZE);
}
```



```

        bt_memory_init_control_block(BT_MEMORY_CONTROL_BLOCK_A2DP_SEP,
                                     bt_a2dp_sep_cb_buf,
BT_A2DP_SEP_BUF_SIZE);
        bt_memory_init_control_block(BT_MEMORY_CONTROL_BLOCK_A2DP,
                                     bt_a2dp_cb_buf, BT_A2DP_BUF_SIZE);
        bt_memory_init_control_block(BT_MEMORY_CONTROL_BLOCK_SPP,
                                     bt_spp_cb_buf, BT_SPP_BUF_SIZE);
        bt_memory_init_control_block(BT_MEMORY_CONTROL_BLOCK_PBAPC,
                                     bt_pbapc_cb_buf, BT_PBAPC_BUF_SIZE);
    }

int main(void)
{
    /*Configure the system */

    /*Configure memory of the SDK.*/
    bt_mm_init();

}

```

## 5.1.2. Out of Memory (OOM) handle

Reasons OOM occurs:

- The control block memory is not enough. If the connect request API returns OOM, there may be not enough memory allocated for the control block memory. The application should enlarge the control block memory.
- The TX memory is not enough. User can check the system log for a message, such as <TX OOM: "[MM]should not come here, please enlarge TX memory. ">. If TX OOM occurs rarely, the application can delay for a while and retry the TX request. If the error message persists, the application should enlarge the TX buffer.
- The RX memory is not enough. User can check the system log for a message, such as <RX OOM: "[MM]should not come here, please enlarge Rx memory.">. If the RX performance is poor due to RX OOM, the application should enlarge the RX buffer.

## 5.2. Create an application task

Airoha IoT SDK for RTOS enables to create a task at runtime. The application can create a queue or semaphore to communicate with other tasks, as shown below.

```

void app_task(void *arg)
{
    /*Application can implment its code here */
}

void bt_task(void * arg)
{
    uint32_t i;
    bt_bd_addr_t random_addr;
    for(i = 0; i < 6; i++) {
        * (((uint8_t*)random_addr) + i) =
(uint8_t)(bt_os_layer_generate_random() & 0xFF);
    }
    * (((uint8_t*)random_addr) + 5) |= 0xC0;
}

```

```

    bt_task_semaphore = bt_os_layer_create_semaphore();
    //bt_os_layer_sleep_task(500);
    if (arg != NULL) {
        // If arg is NULL means user does not want to power on BT
        bt_power_on((bt_bd_addr_ptr_t)arg,
(bt_bd_addr_ptr_t)&random_addr);
    }

    /* main loop */
    do {
        bt_os_layer_take_semaphore(bt_task_semaphore);

        /* handle events */
        if (BT_STATUS_SUCCESS != bt_handle_interrupt()) {
            break;
        }
    } while (1);
}

int main(void)
{
    /*first need configure hardware and system*/

    /*Task API usage please refer RTOS dev guider*/
    xTaskCreate(app_task, "app_t", 512, NULL, 1, NULL);

    /*bt_task is the main function implmented in SDK that application need
use it
as entry function. After bt task running, bt will power on
automaticlly. */
    xTaskCreate(bt_task, "bt_task", 1024, local_public_addr, 5, NULL);

    /*All task will truely construtor after this function executed*/
    vTaskStartScheduler();

}

```

The default implementation of Bluetooth task entry function `bt_task()` is provided in `bt_platform.c`. A user-defined entry function implementation can also be provided in that source file. Call the function `bt_task()` in the `bt_platform.h` as a task entry function to create a stack task. The stack size of `bt_task()` should be no less than 1024 words. Call the API `bt_handle_interrupt()` to handle the Bluetooth stack interrupt, such as timer and events in stack task.

### 5.3. Interaction with the Bluetooth host stack

The application task can call Bluetooth APIs directly. Callback functions are invoked in the Bluetooth host stack to process the events that are input as parameter to the callback (see Figure 92). Note, that the stack task needs to be created by the application and the entry function should handle the Bluetooth stack interrupt.

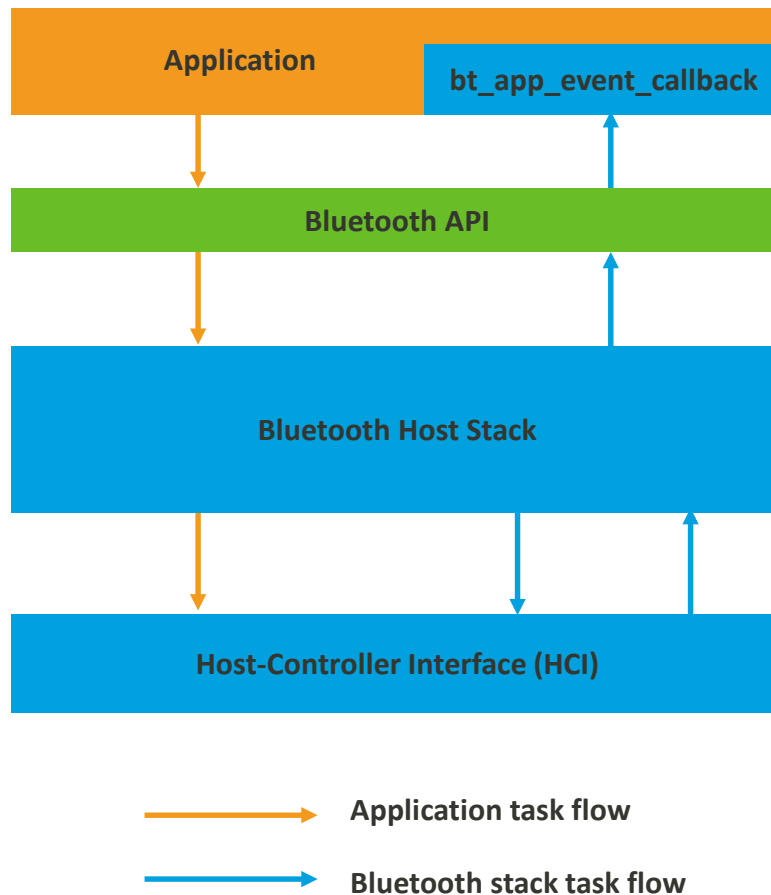


Figure 92. Application interaction with the Bluetooth API

### 5.3.1. Calling the APIs

The Airoha IoT SDK provides a set of thread-safe APIs for the application task. The application can call the SDK APIs in any task even including the stack task self. Note, that the SDK APIs run in the caller task.

```

void app_task(void *arg)
{
    /*Application can implement the code here */
    while(1) {
        /*Application should make task non-block, like receive queue here*/
        {
            bt_bd_addr_t addr[] = {0xC3,0x01,0x02,0x03,0x05,0x11};
            /*set random address API run in app task*/
            bt_gap_le_set_random_address(addr);
        }
    }
}
    
```

### 5.3.2. Processing the events

The SDK will send an event to `bt_app_event_callback()` which needs to be implemented in the application. The callback will be called in the SDK task, so the application has to consider which task will process the event. It's recommended to send the event to its own task. Note, that if processing an event in the stack task takes too long,

it may cause Bluetooth connection failure or reduce the data transmission rate. The application can use queue or semaphore in RTOS to switch task from stack to its own task.

An example implementation on getting the event from Bluetooth stack task is shown below.

```
typedef struct {
    uint16_t event_id;
    void *parameter;
} bt_app_event_t;

PRIVILEGED_DATA static QueueHandle_t bt_app_queue_p;

bt_status_t bt_app_event_callback(bt_msg_type_t msg, bt_status_t status,
void *buff){
    bt_app_event_t event;
    switch(msg) {
        /*Handle event and convert to message sending to application
task*/
        xQueueSend(bt_app_queue_p, &event, 0);
    }
}

void app_task(void *arg)
{
    /*Application can implment its code here */
    bt_app_queue_p = xQueueCreate(20, sizeof(bt_app_event_t));

    while(1) {
        /*Application should make task non-block, like receive queue*/

        if (xQueueReceive(bt_app_queue_p, &queue_event, portMAX_DELAY) ==
pdPASS){
            /*Handle message here*/
        }
    }
}
```

## 5.4. Bluetooth panic mechanism

The application will receive Bluetooth panic event from `bt_app_event_callback()`, in case Bluetooth host or controller malfunction. The application should reboot the Bluetooth with the `bt_power_off()` and `bt_power_on()` APIs to run the module successfully, as shown in the code below. It's also required to clear unused data or reset the state machine of the application to release all resources and reset the system to the default state.

An example implementation to restore Bluetooth when Bluetooth panic event is received is shown below.

```
bool is_panic = false;
bt_status_t bt_app_event_callback(bt_msg_type_t msg, bt_status_t status,
void *buff){
    switch(msg) {
        case BT_PANIC: {
            is_panic = true;
            if (((bt_panic_t *)buff)->source == BT_PANIC_SOURCE_HOST) {
                /* The panic event source is Bluetooth host */
            }
        }
    }
}
```

```

        /* The application should */
        /* clear unused data or reset state machine of the
application, and reboot Bluetooth (or reboot device). */
        bt_power_off();
    } else {
        /* The panic event source is Bluetooth controller */
        /* The application should */
        /* clear unused data or reset state machine of the
application, and reboot Bluetooth (or reboot device). */
        bt_power_off();
    }
}
case BT_POWER_OFF_CNF: {
    if (is_panic == true) {
        bt_power_on(NULL, NULL);
    }
}
case BT_POWER_ON_CNF: {
    if (is_panic == true) {
        is_panic = false;
        /*reboot Bluetooth success, start to run application again.*/
    }
}
}
}

```

## **6. Debugging and Porting Layer**

---

### **6.1. Debugging**

The Airoha IoT SDK provides two ways to debug the application:

- System log — provides the host information.
- HCI log — provides the HCI communication log between host and controller.

#### **6.1.1. System log**

The Bluetooth stack calls `bt_debug_log()` in the `bt_debug.c` source file to provide the host information. Application can set a filter or disable logging in this function. The application can also output these logs to any UART or USB port.

#### **6.1.2. HCI log**

The Airoha IoT SDK provides HCI information by calling the `bt_hci_log()` function in the `bt_hci_log.c` source file. The HCI information follows the standard HCI data format in Bluetooth core specification. The application can receive this information in the `bt_hci_log()` function and then send the output to UART. Users can analyze the data using standard HCI data or parse these data to a file that commercial tools like [Frontline](#) can recognize.

### **6.2. Porting layer**

The Bluetooth stack has flexibility to integrate with third-party RTOS APIs. These APIs can be implemented in the source file `bt_os_layer_api.c`.

## 7. Appendix A: Acronyms and Abbreviations

The acronyms and abbreviations used in this developer's guide are listed in Table 6.

**Table 6. Acronyms and abbreviations**

Abbreviation/Term	Expansion/Definition
GAP	Generic Access Profile defines the generic procedures related to the discovery of Bluetooth devices and link management aspects of connecting to Bluetooth devices. It also defines procedures related to use of different security levels.
SM	<a href="#">Security Manager</a>
GATT	Generic Attribute Profile defines a service framework using the Attribute Protocol for discovering services and for reading and writing characteristic value on a remote device.
MTU	The Maximum Transmission Unit (MTU) is the size of the largest protocol data unit that the communications layer can pass onwards.
LTK	Long Term Key, is a 128-bit key used to generate the contributory session key for an encrypted connection.
MITM	Man-in-the-middle attack is an attack where the attacker secretly relays and possibly alters the communication between two parties who believe they are directly communicating with each other.
STK	Short Term Key, is a 128-bit key used to encrypt a connection following pairing.
EDIV	Encrypted Diversifier is a 16-bit stored value used to identify the LTK distributed during the low energy legacy pairing.
IRK	Identity Resolving Key is a 128-bit key used to generate and resolve random addresses.
CSRK	Connection Signature Resolving Key is a 128-bit key that signs data and verifies signatures on the receiving device.
Out-Of-Band	The model is primarily designed for scenarios where an Out of Band mechanism is used to discover the devices and to exchange or transfer cryptographic numbers used in the pairing process.
AES	Advanced Encryption Standard