

User Manual

Quanser Controls Board for NI ELVIS III



Setup and Configuration

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# Safety Information

The following symbols and definitions are interchangeably used throughout the User Manual:

|  |  |
| --- | --- |
| Symbol | Description |
| **https://lh3.googleusercontent.com/uALLqA_1-o-BxRnTR40rPmJYJD4TqUSRTidN5-eYAncLaD54onoXck7oPGl5kpmYa-NZu1XkpF3uaHX_6qxBaRyhkBJGgges0bbRZzjjjbIQ9DnysRRfKnZdH35VWtl4W-plVzea** | Caution: consult documentation for additional information |
| https://lh6.googleusercontent.com/ay0jGKpt4TB7uxlm6ZAYgsewYgKAy5UimB2xyeXymTpFciMA-RfN3WCM-nUlerduvaUGDBhqF9FSHvItKMcHF6kEDl5ZHqQxJdzofTLIA3NID6YozXqFbzCt0LljsxTR0g3bEsFY | Attention: Observe precautions for handling electrostatic sensitive devices |

# The Quanser Controls Board

The Quanser Controls board, pictured in Figure 1 is a complete platform for investigating almost all aspects of modern control theory from system modeling and PID control to stability and digital control design. The system consists of a deterministic DC motor with a high-resolution encoder, as well as a pendulum attachment for balance control. Complete courseware and software is provided for a large compliment of typical control challenges.

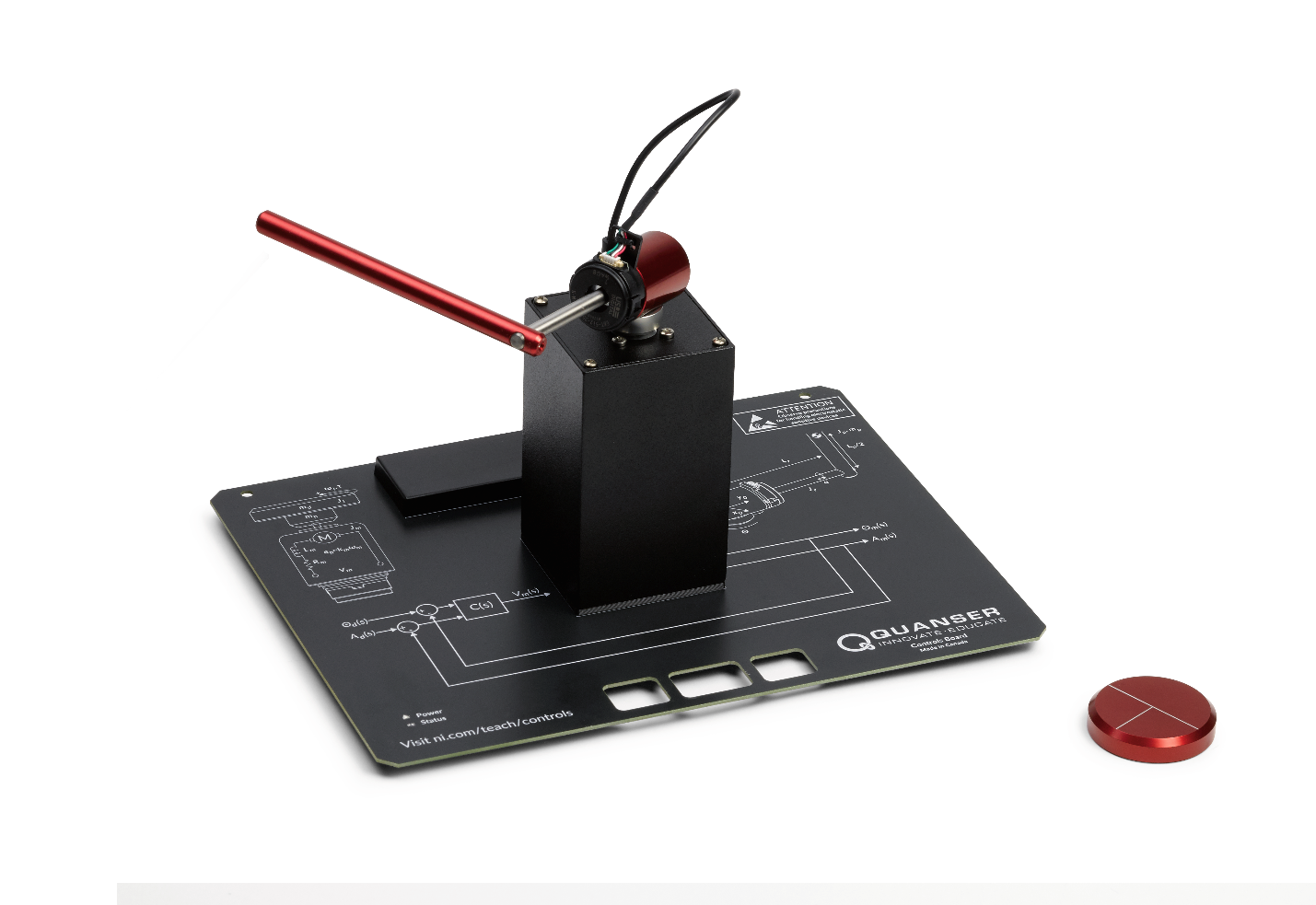


Figure 1: The Quanser Controls board

## Main Features

* Direct-drive brushed DC motor
* 512 count encoder mounted on the motor (giving 2048 count granularity with quadrature decoding), and on the pendulum arm
* Built in deterministic PWM amplifier mapped to theoretical motor models
* DC motor current sense

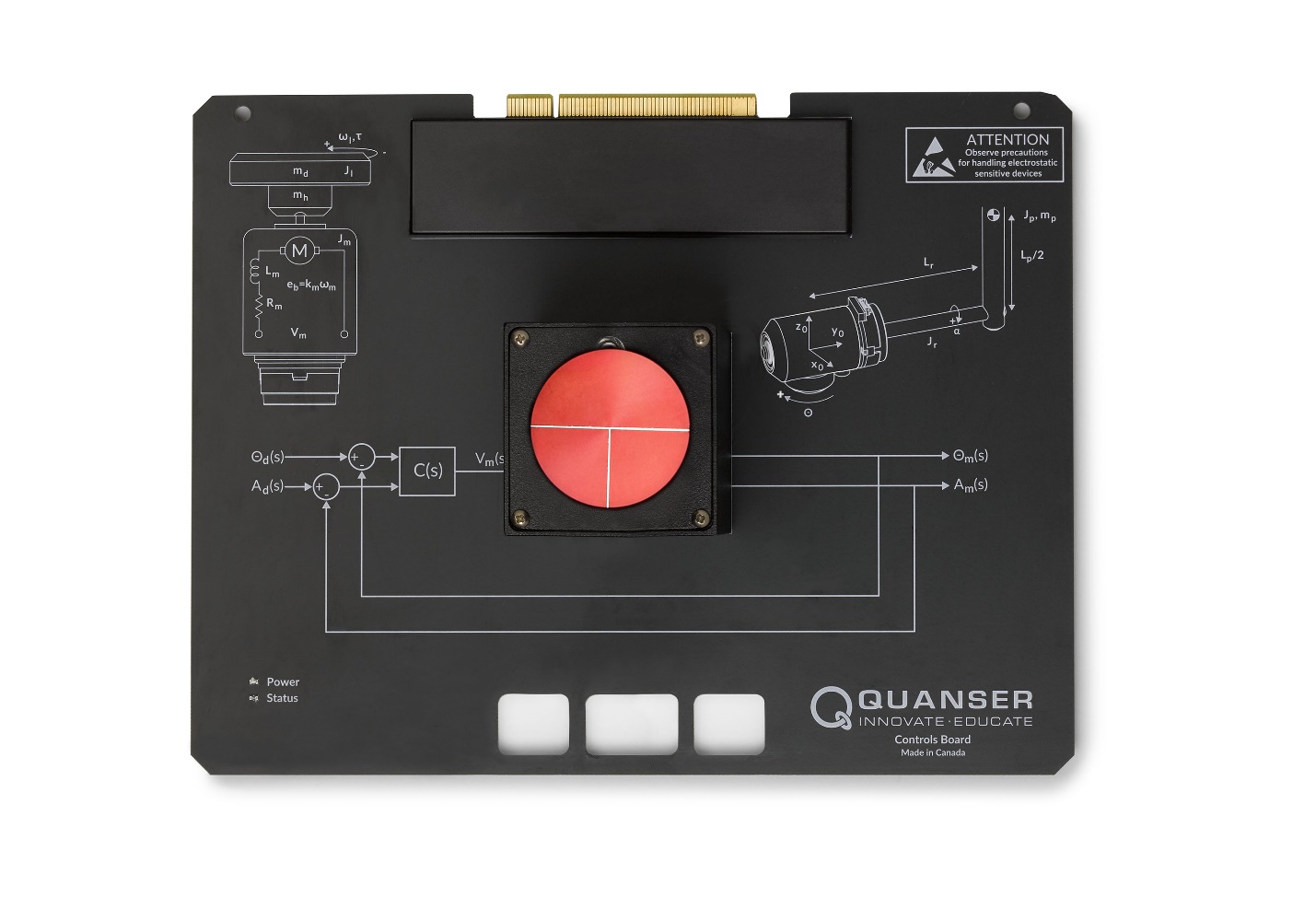
|  |  |
| --- | --- |
| Caution | This equipment is designed to be used for educational and research purposes and is not intended for use by the general public. The user is responsible to ensure that the equipment will be used by technically qualified personnel only. |

## System Hardware Components

The major components of the application board are identified in Figure 3.

Table 1: Application board hardware components

|  |  |  |  |
| --- | --- | --- | --- |
| ID | Component | ID | Component |
| 1 | Inertia Load | 4 | PCI Connector for interfacing with NI ELVIS III |
| 2 | DC motor and encoder | 5 | Pendulum encoder (optional) |
| 3 | Pendulum encoder connector  **1**  **2**  **3**  **4** | 6 | Pendulum encoder data cable (optional) |



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Figure 3: Quanser mechatronic systems board components

### DC Motor

The application board includes a direct-drive brushed DC motors to drive either the inertia load or pendulum arm. The motor specifications are given in Table 2.

The included motor is a Premotec CL40 Series Coreless DC Motors. The complete

specification sheet for the motor is available from [Allied Motion](https://www.alliedmotion.com/dc-motors/coreless-dc-motors/cl-series-coreless-dc-motors/).

|  |  |
| --- | --- |
| Caution | Exposed moving parts. |

### Encoder

The encoders used to measure the angular position of the motor and pendulum are single-ended, optical shaft encoders. They output 2048 counts per revolution in quadrature mode (512 lines per revolution).

The included encoders are the US Digital E8P-512-118 single-ended optical shaft encoder. The complete specification sheet of the encoders is available from [US Digital](http://cdn.usdigital.com/assets/datasheets/E8P_datasheet.pdf?k=634748881615955589).

**Environmental**

The QNET Mechatronic Systems is designed to function under the following environmental conditions:

* Standard rating
* Indoor use only
* Temperature 5◦C to 40◦C
* Altitude up to 2000 m
* Maximum relative humidity of 80% up to 31◦C decreasing linearly to 50% relative humidity at 40◦C
* Pollution Degree 2
* Maximum transient overvoltage 2500 V
* Marked degree of protection to IEC 60529: Ordinary Equipment (IPX0)

## System Parameters

Table 2: Application board system parameters

|  |  |  |
| --- | --- | --- |
| Symbol | Description | Value |
| DC Motor | | |
| Vnom | Nominal motor voltage | 18.0 V |
| τnom | Nominal motor torque | 22.0 Nmm |
| ωnom | Nominal speed | 3050 RPM |
| Inom | Nominal current | 0.540 A |
| Rm | Terminal resistance | 8.4 Ω |
| kt | Torque constant | 0.042 Nm/A |
| km | Motor back-emf constant | 0.042 V/(rad/s) |
| Jm | Rotor inertia | 4.0 x 10-6 kgm2 |
| Lm | Rotor inductance | 1.16 mH |
| ϴE | Encoder count angle (in quadrature) | 0.176 deg |
| mh | Module attachment hub mass | 0.0106 kg |
| rh | Module attachment hub radius | 0.0111 m |
| Jh | Module attachment moment of inertia | 0.6 x 10-6 kg-m2 |
| Inertia Disc | | |
| md | Disc mass | 0.053 kg |
| rd | Disc radius | 0.0248 m |
| Rotary Pendulum Module (Optional) | | |
| mr | Rotary arm mass | 0.095 kg |
| Lr | Rotary arm length | 0.085 m |
| mp | Pendulum link mass | 0.024 kg |
| Lp | Pendulum link length | 0.129 m |

## System Setup

The procedure to set up the Quanser Controls board on the NI ELVIS III module is detailed in this section.

|  |  |
| --- | --- |
| Caution | If the equipment is used in a manner not specified by the manufacturer, the protection provided by the equipment may be impaired. |
| ESD Warning | The electrical components on the Quanser Mechatronic Systems board are sensitive to electrostatic discharge (ESD). Before handling the board ensure that you have been properly grounded. |



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Figure 3: Components of the NI ELVIS III

|  |  |  |  |
| --- | --- | --- | --- |
| ID | Component | ID | Component |
| 1 | Antenna connector | 6 | Connection data screen |
| 2 | Ethernet connector | 7 | PCI connector |
| 3 | USB C connector | 8 | Handle latching hooks |
| 4 | Power cable | 9 | Status LEDs |
| 5 | Power switch | 10 | Application board power button |

|  |  |
| --- | --- |
| Caution | Do NOT make the following connections while power is supplied to the application board! |

Follow these instructions to setup the application board on the NI ELVIS III:

1. Power on the ELVIS III
2. Connect the ELVIS III to the network or to your computer via USB C
3. Ensure the LED on the application board power button is NOT lit
4. Position the handle of the application board over the handle latching hooks
5. Position the PCI connector on the application board so that it aligns with the PCI connector on the ELVIS III
6. Push the application board upward until the PCI connector is firmly seated
7. Press the application board power button and ensure the LED on the button is lit

## Troubleshooting

Please review the following before contacting technical support.

1. Verify the board is properly seated on the ELVIS III and that it has power.
2. Verify that the ELVIS III is correctly set up as outlined in the NI product documentation.

### You are getting 'VI Missing' messages

Make sure the required LabVIEW add-ons listed in the Quick-Start Guide are installed.

Verify that the correct LabVIEW version is installed (The ELVIS III is only compatible with LabVIEW 2018 or later).

### Board does not respond

Check that the source distribution has been deployed as outlined above.