

# Automated vessel detection for fetal surgery

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*Bachelor Thesis, Final presentation*

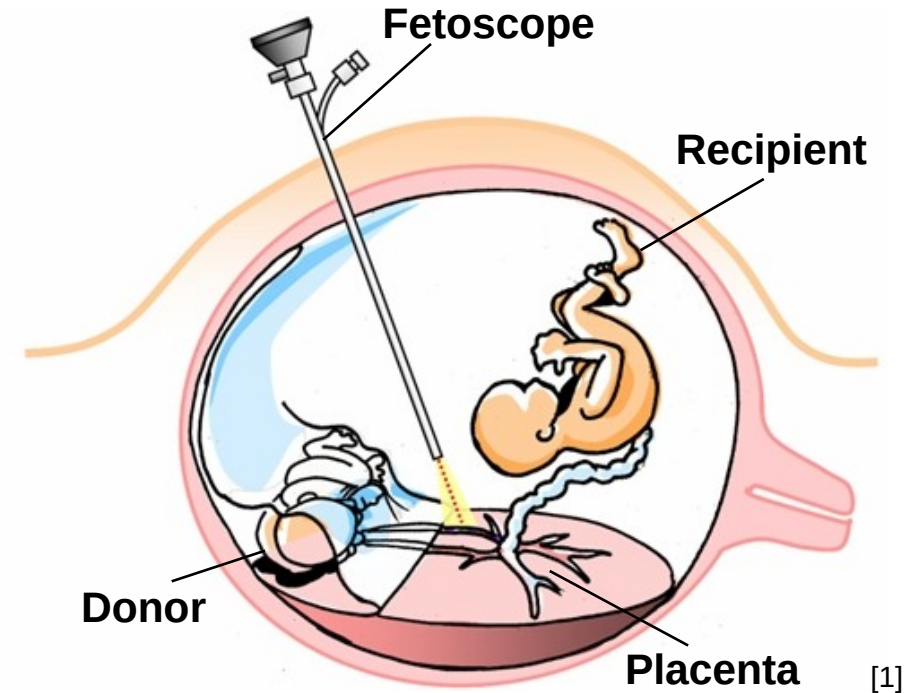
*Multi-Scale Robotics Lab, ETH Zurich*

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Supervisors: Jonas Lussi, Simone Gervasoni

# Medical Background

- Twin to Twin Transfusion Syndrome (TTTS)
- 10 to 15% of monochorionic twins affected
- Imbalance of blood flow
- Risk of death of both twins
- Fetoscopic laser coagulation

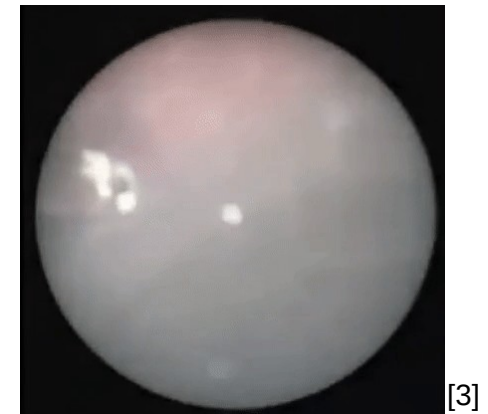
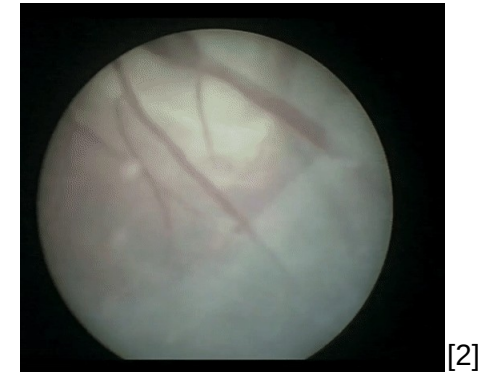


# Fetoscopic Laser Coagulation

- Visually explore placenta with camera
- Revisit anastomoses and ablate them with laser

## Challenges:

- Limited field-of-view
- Occlusions
- Poor visibility



# Motivation

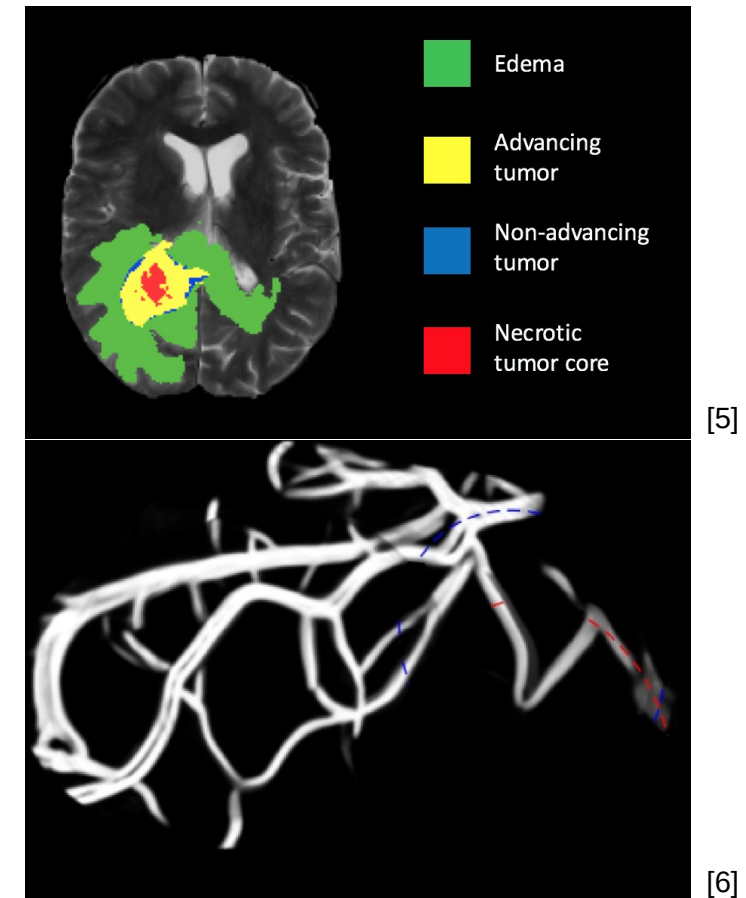
- Robust detection of blood vessels
- Enhance the surgeon view
- Minimize complications after surgery
- Segmentation



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# State of the art

- Deep Learning outperforms other
- Convolutional Networks
- Segmented placental vessel maps
- Limited data





# Datasets

## UCL dataset:

- 482 video frames
- 6 in vivo procedures
- Verified by expert

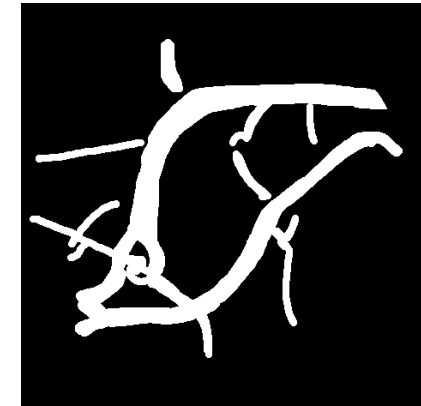
## MSRL dataset:

- 269 video frames
- Ex vivo

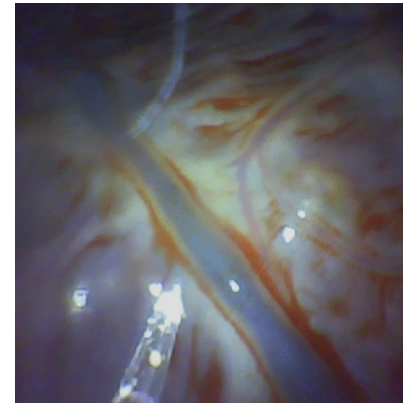
Input image



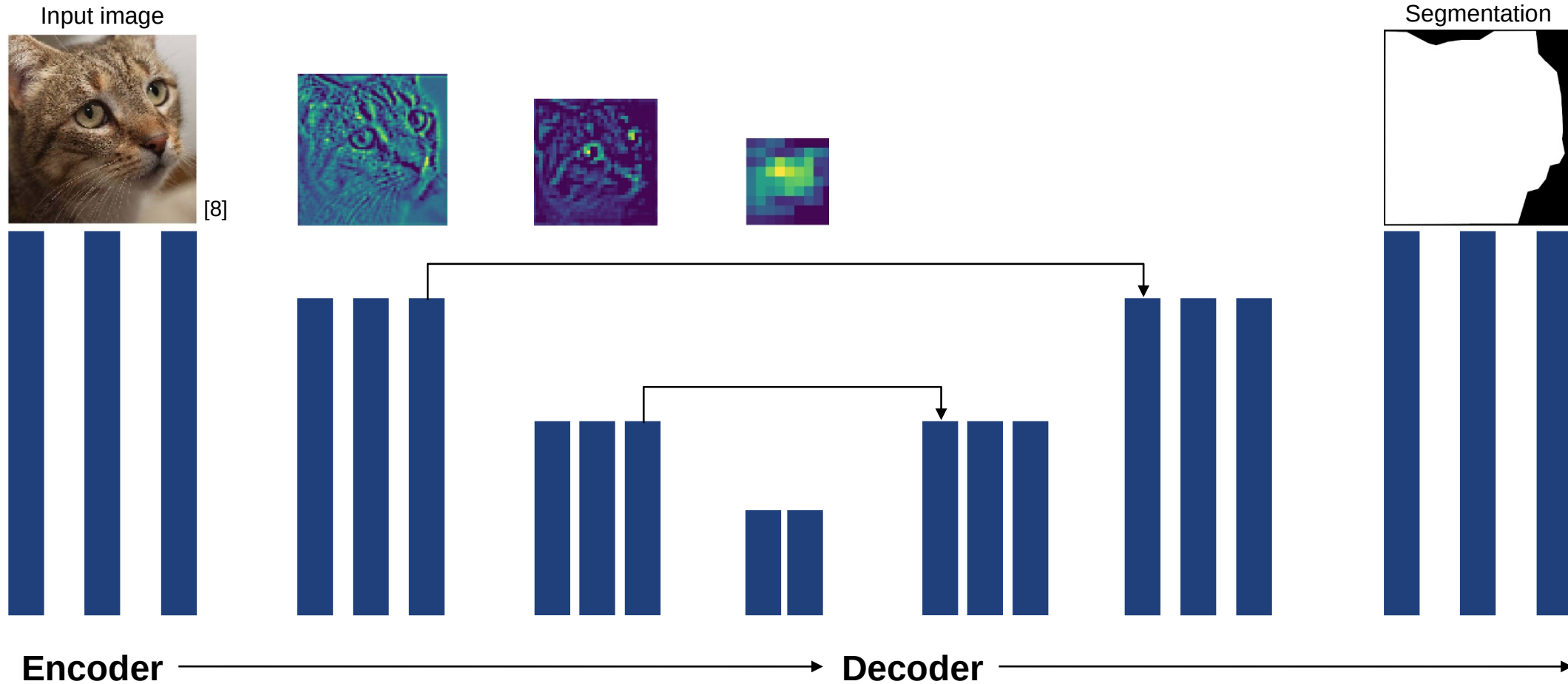
Ground truth



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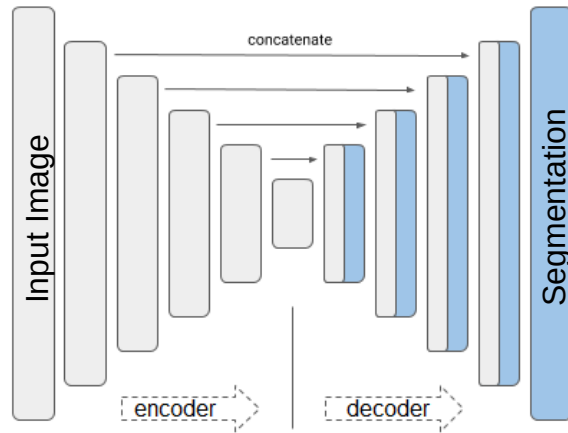


# Encoder-Decoder Network

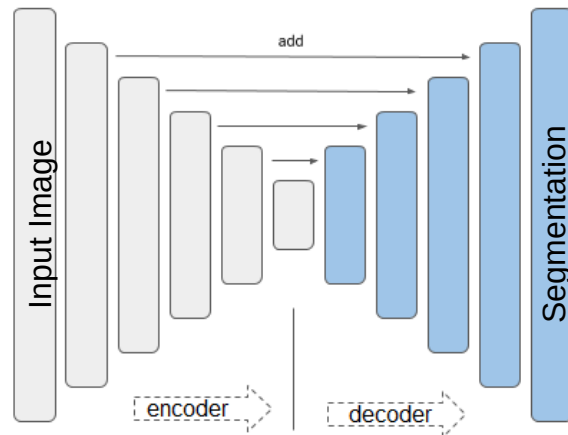


# Architectures

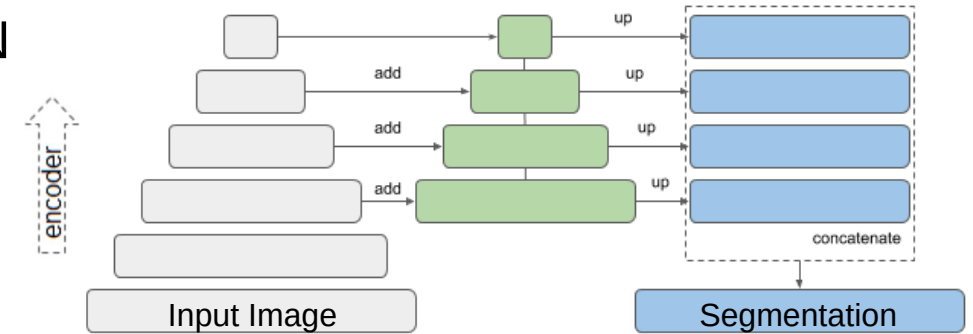
## U-Net



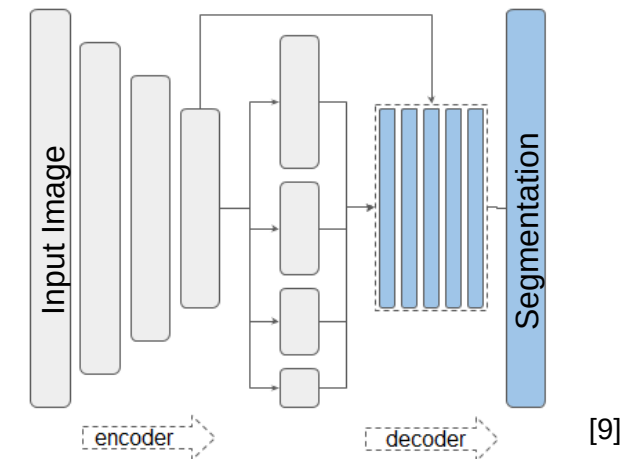
## LinkNet



## FPN



## PSPNet



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# Experimental Setup

- 6-fold crossvalidation
- 26 networks
- Data augmentation

U-Net		Fold 1
No. Train images		1526
No. validation images		52
Vanilla	Dice	0.69 (+/- 0.13)
	IoU	0.55 (+/- 0.15)
VGG16	Dice	0.70 (+/- 0.12)
	IoU	0.56 (+/- 0.14)
DenseNet201	Dice	0.58 (+/- 0.22)
	IoU	0.44 (+/- 0.21)
EfficientNetB5	Dice	0.67 (+/- 0.19)
	IoU	0.53 (+/- 0.20)
InceptionResNetV2	Dice	0.68 (+/- 0.17)
	IoU	0.53 (+/- 0.18)
InceptionV3	Dice	<b>0.73 (+/- 0.13)</b>
	IoU	<b>0.59 (+/- 0.16)</b>
ResNet101	Dice	0.58 (+/- 0.23)
	IoU	0.45 (+/- 0.23)

# Segmentation Results

Input Image



Ground truth



Prediction

Baseline



UNet-EffNetB5



PSP-InceptionV3



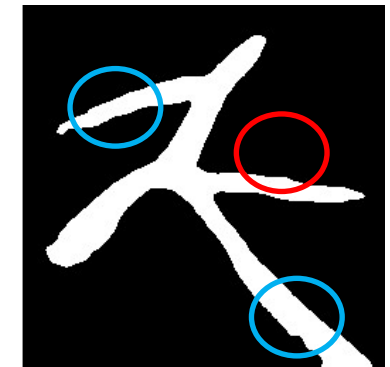
LinkNet-EffNetB5



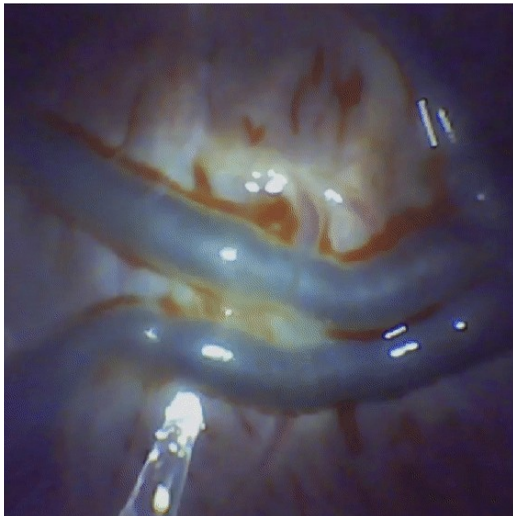
FPN-DenseNet201



FPN-EffNetB5



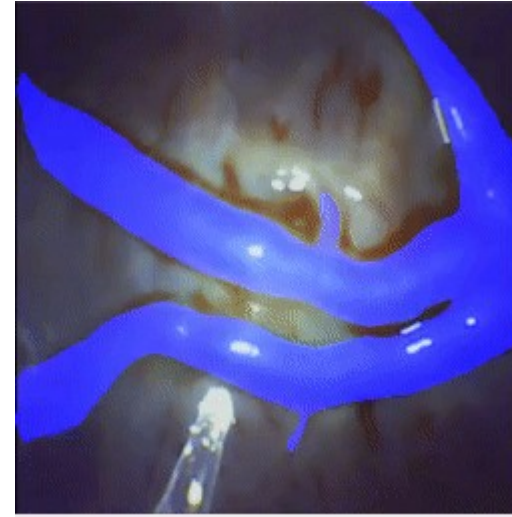
# Real time segmentation



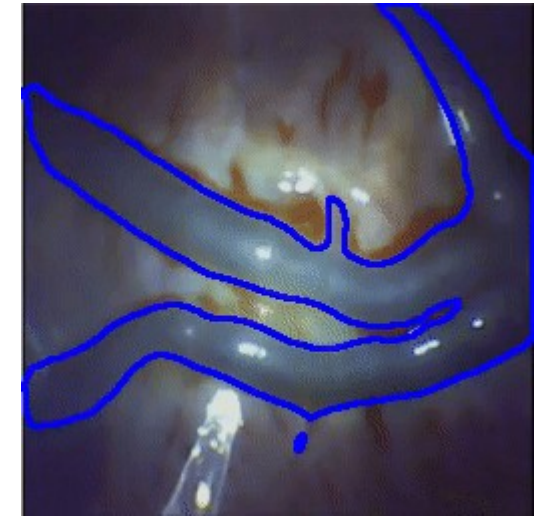
Original video



Predicted  
segmentation



Overlay

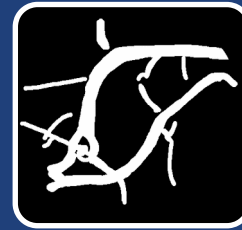
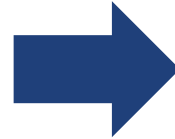


Contour

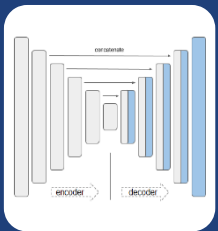
# Conclusion & Future Work



New dataset



Increase data quality



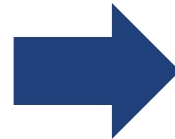
Compared networks



Integrate network to system



Automated detection

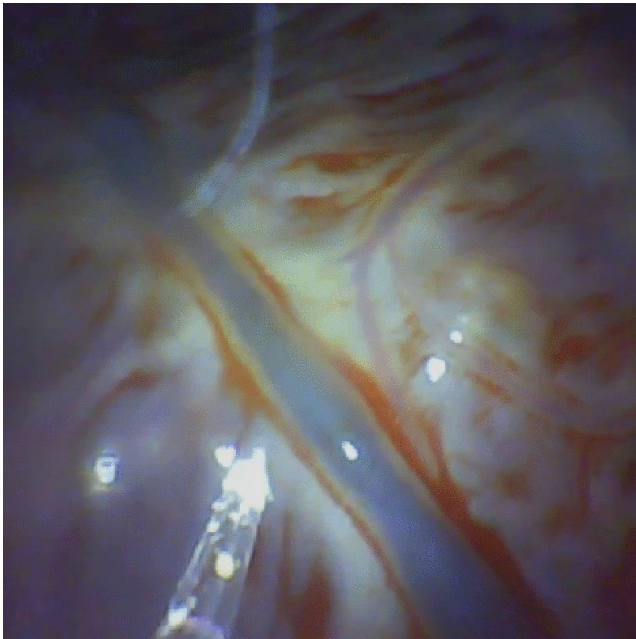


Vessel maps

# Acknowledgements

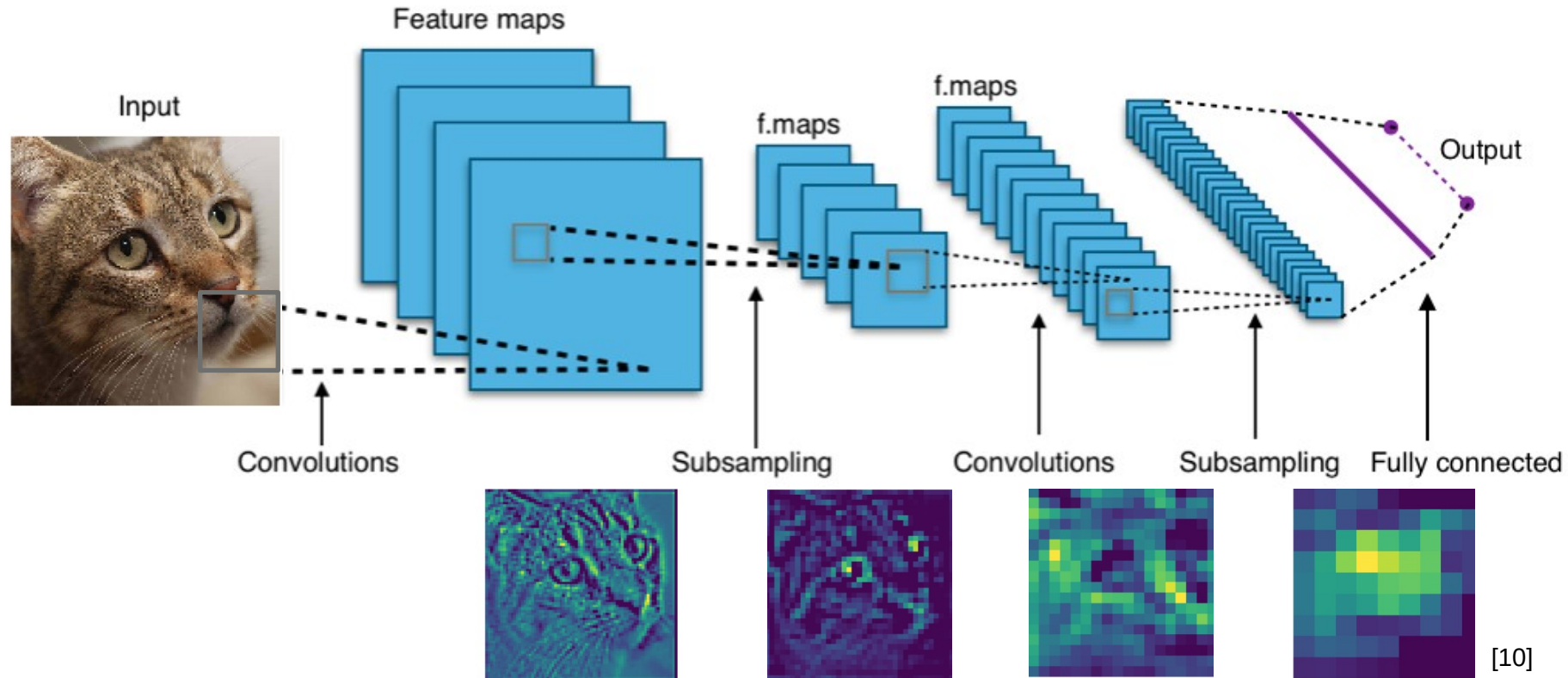
- Prof. Dr. Bradley Nelson
- Jonas Lussi
- Simone Gervasoni

# Thanks for listening





# Further explanation CNN

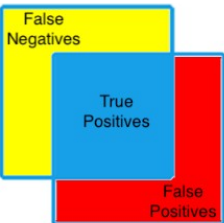


More  
information on  
image

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information on  
class

# Further explanation Crossvalidation

U-Net		Fold 1	...	Fold 5	Fold 6	Overall
No. Train images		1526		1631	1575	
No. validation images		52		36	44	270
Vanilla	Dice	0.69 (+/- 0.13)		0.58 (+/- 0.20)	0.67 (+/- 0.16)	0.70 (+/- 0.17)
	IoU	0.55 (+/- 0.15)		0.44 (+/- 0.19)	0.53 (+/- 0.18)	0.58 (+/- 0.18)
VGG16	Dice	0.70 (+/- 0.12)		0.57 (+/- 0.20)	0.67 (+/- 0.18)	0.70 (+/- 0.17)
	IoU	0.56 (+/- 0.14)		0.42 (+/- 0.19)	0.53 (+/- 0.18)	0.58 (+/- 0.18)
DenseNet201	Dice	0.58 (+/- 0.22)		0.58 (+/- 0.26)	<b>0.73 (+/- 0.12)</b>	0.71 (+/- 0.18)
	IoU	0.44 (+/- 0.21)		0.46 (+/- 0.25)	<b>0.59 (+/- 0.14)</b>	0.58 (+/- 0.19)
EfficientNetB5	Dice	0.67 (+/- 0.19)		<b>0.66 (+/- 0.16)</b>	0.73 (+/- 0.14)	<b>0.73 (+/- 0.15)</b>
	IoU	0.53 (+/- 0.20)		<b>0.51 (+/- 0.17)</b>	0.59 (+/- 0.16)	<b>0.61 (+/- 0.17)</b>
InceptionResNetV2	Dice	0.68 (+/- 0.17)		0.56 (+/- 0.23)	0.70 (+/- 0.13)	0.70 (+/- 0.17)
	IoU	0.53 (+/- 0.18)		0.42 (+/- 0.21)	0.55 (+/- 0.15)	0.58 (+/- 0.18)
InceptionV3	Dice	<b>0.73 (+/- 0.13)</b>		0.59 (+/- 0.22)	0.72 (+/- 0.13)	0.73 (+/- 0.16)
	IoU	<b>0.59 (+/- 0.16)</b>		0.45 (+/- 0.20)	0.58 (+/- 0.15)	0.61 (+/- 0.17)
ResNet101	Dice	0.58 (+/- 0.23)		0.55 (+/- 0.23)	0.70 (+/- 0.16)	0.69 (+/- 0.19)
	IoU	0.45 (+/- 0.23)		0.42 (+/- 0.20)	0.55 (+/- 0.18)	0.57 (+/- 0.20)



$$IoU = \frac{\text{Area of Overlap}}{\text{Area of Union}}$$

$$Dice = \frac{2 \times TP}{(TP + FP) + (TP + FN)}$$