# Machine Learning from Data Assignment 5

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## Exercise 2.8

(a) Show that if H is closed under linear combination, then  $\overline{g} \in H$ . The definition of of  $\overline{g}(x)$  is

$$\overline{g}(x) = \frac{1}{K} \sum_{k=1}^{K} g_k(x).$$

This means that every value of  $\overline{g}$  is a multiple of of the values of g in H. In other words, it is a linear combination of the  $g_k \in H$ . Since H is closed under linear combination,  $\overline{g}$  must also be in H.

- (b) Give a model for which the average function  $\overline{g}$  is not in the model's hypothesis set. If  $H = \emptyset$ , then  $\overline{g}$  cannot be in H.
- (c) For binary classification, do you expect  $\overline{g}$  to be a binary function? No, this is unlikely.

## Problem 2.14

Let  $H_1, H_2, \ldots, H_K$  be K hypothesis sets with finite VC dimension  $d_{VC}$ . Let  $H = H_1 \cup H_2 \cup \cdots \cup H_K$  be the union of these models.

(a) Show that  $d_{VC}(H) < K(d_{VC} + 1)$ .

The hypothesis sets have VC dimension  $d_{VC}$ , meaning they have break point  $k^* = d_{VC} + 1$ . Recall that the first break point is the sample size for which not all dichotomies can be given by the hypothesis set. So, given K hypothesis sets with this break point, if every hypothesis set can fill out dichotomies that others can't we end up with a largest possible breakpoint of

$$k^*(H) = Kk^*.$$

Since the breakpoint is related to the VC dimension and this is the largest value, we can rewrite this as

$$d_{VC}(H) < K(d_{VC} + 1)$$

since the VC dimension is strictly less than k\*.

(b) Suppose that l satisfies  $2^l > 2Kl^{d_{VC}}$ . Show that  $d_{VC}(H) \le l$ . This is a straight proof by calculation.

$$\begin{aligned} 2^{l} &> 2K l^{d_{VC}} \\ 2^{l-1} &> K l^{d_{VC}} \\ (l-1) \log_2 2 &> K d_{VC} \log_2 l \\ d_{VC} &< (l-1) \frac{1}{K \log_2 l} \\ &\leq \frac{l-1}{K} \end{aligned}$$

And as we can add this together K times for  $d_{VC}(H)$ , we get

$$d_{VC}(H) \le K \frac{l-1}{K} = l-1$$

which implies

$$d_{VC}(H) \le l$$
.

(c) Hence, show that

$$d_{VC}(H) \le \min(K(d_{VC} + 1), 7(d_{VC} + K) \log_2(d_{VC}K)).$$

That is,  $d_{VC} = O(\max(d_{VC}, K) \log_2 \max(d_{VC}, K))$  is not too bad.

Obviously, if the bound from (a) is the lower of the two, the inequality above holds.

To show the second term in the min is a bound, we set l to it and substitute into the inequality from (b).

$$2^{7(d_{VC}+K)\log_2(d_{VC}K)} > 2K(7(d_{VC}+K)\log_2(d_{VC}K))^{d_{VC}}$$
$$(d_{VC}K)^{7(d_{VC}+K)} > 2K(7(d_{VC}+K)d_{VC}\log_2(d_{VC}K))$$
$$(d_{VC}K)^{7(d_{VC}+K)-1} > 2(7(d_{VC}+K)\log_2(d_{VC}K))$$

This inequality, ugly as it is, holds for K > 1, so we have shown the previous inequality is true.

#### Problem 2.15

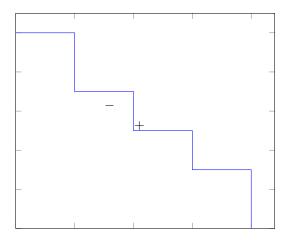
The monotonically increasing hypothesis set is

$$H = \{ h \mid x_1 \ge x_2 \implies h(x_1) \ge h(x_2) \},$$

where  $x_1 \geq x_2$  if and only if the inequality is satisfied for every component.

(a) Give an example of a monotonic classifier in two dimensions, clearly showing the +1 and -1 regions.

The monotonic classifier will appear as a sort of decreasing step function, with the upper right side being the +1 region and the -1 region being the bottom left side.



(b) Compute  $m_H(N)$  and hence the VC dimension.

Consider the case of N monotonically decreasing points in the Cartesian plane. With the monotonically increasing hypothesis set, all dichotomies are possible. Thus,

$$m_H(N) = 2^n$$
 and  $d_{VC} = \infty$ .

#### Problem 2.24

Assume input dimension 1. Assume input variable x is uniformly distributed in the interval [-1,1]. Data set consists of 2 points,  $\{x_1, x_2\}$ . Assume target function is  $f(x) = x^2$ . Full data set is  $D = \{(x_1, x_1^2), (x_2, x_2^2)\}$ . Learning algorithm returns line fitting these two points as g. We are interested in the test performance  $E_{out}$  of the learning system w.r.t. the squared error measure, the bias and the variance.

(a) Give the analytic expression for the average function  $\overline{g}(x)$ .

$$\overline{g}(x) \approx \frac{1}{K} \sum_{k=1}^{K} g_k(x) = \mathbb{E}[ax+b]$$

a is the slope of the line obtained from the points, and b the intercept, so we get

$$\overline{g}(x) = \mathbb{E}[(x_1 + x_2)x - x_1x_2]$$

$$= \mathbb{E}[x_1] + \mathbb{E}[x_2])x - \mathbb{E}[x_1]\mathbb{E}[x_2]$$

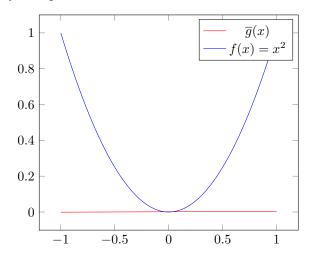
$$= 0$$

- (b) Describe an experiment that you could run to determine numerically  $\overline{g}(x)$ ,  $E_{out}$ , bias, and var.
  - Generate a large number (e.g. 10,000) of 2-point datasets  $D = \{(x_1, x_1^2), (x_2, x_2^2)\}$  and generate the set of final hypotheses for all these data sets. Since each  $g_i$  is just a line, we can simply store the coefficients a, b of g = ax + b, then average the sets of each coefficient to obtain  $\overline{g}(x)$ . The typical formula for  $E_{out}$  can be used for each iteration, then averaged. Bias and variance can both be calculated using  $\overline{g}$ .
- (c) Run your experiment and report the results. Compare  $E_{out}$  with bias+var. Provide a plot of your  $\overline{g}(x)$  and f(x).

Running the experiment for N = 10000 gives

$$\overline{g}(x) = 0.00244x + 0.00143$$
 
$$E_{out} = 0.537$$
 
$$\mathbb{E}[bias(x)] = 0.204$$
 
$$\mathbb{E}[var(x)] = 0.331$$

So for bias + var we get 0.535, only two thousands from the value first obtained for  $E_{out}$ . These values are extremely close, exactly as expected.



(d) Compute analytically what  $E_{out}$ , bias, and var should be.

For bias we have

$$bias = \mathbb{E}_x[\overline{g}(x) - f(x))^2]$$
$$= \frac{1}{2} \int_{-1}^1 x^4 dx$$
$$= \frac{1}{5}$$

and for variance we get

$$var = \mathbb{E}_x [\mathbb{E}_D[(g_D(X) - \overline{g}(x))^2]]$$

$$= \frac{1}{4} \int_{-1}^1 \int_{-1,1} \int_{-1}^1 ((y+z)x - yz)^2 dy dz dx$$

$$= \frac{1}{3}$$

so for  $E_{out}$  we get

$$\begin{split} \mathbb{E}[E_{out}] &= bias + var \\ &= \frac{1}{5} + \frac{1}{3} \\ &= \frac{8}{15} \approx .533 \end{split}$$

All of these values agree well with the numerically obtained values.