#### **REGISTERS!**

Registers are **quickly** accessible memory locations available to the processor. The size of the register depends on the CPU architecture. Common sizes are 16 bits, 32 bits and 64 bits but they can be **larger**. The size of registers on a machine is called the **word** size

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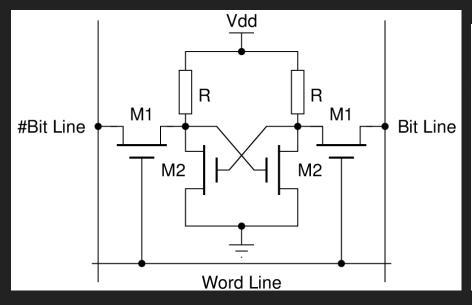
But isn't RAM enough?

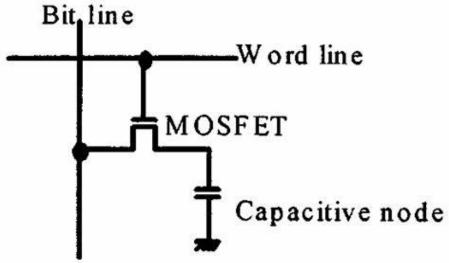
- Relative to the processor's clock speed, reading from and writing to RAM is slow
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But that's a presentation for another day

#### Just for your information. Static RAM technology vs Dynamic RAM technology





#### TYPES OF REGISTERS

The two types of registers we will be looking at are the general purpose registers and the special purpose registers

#### GENERAL PURPOSE REGISTERS

Essentially just variables for the processor. They can be used to store anything that the ALU is working on and even the results

e.g The accumulator

# SPECIAL PURPOSE REGISTERS

These registers are used to aid in the execution of instructions and keep track of the state of the processor

e.g the program counter

# THE PROGRAM COUNTER

Simply put the program counter stores the address of the next instruction to be fetched, decoded and executed. Used to facilitate iteration

# THE MEMORY DATA REGISTER

This special register stores the data fetched from main memory and the data which will be written to the main memory. Acts as a **buffer** 

### Example of the program counter using an actual program

#### Let's look at a simple program

```
Dim i as Integer = 10
Dim j as Integer = 1
j = j + i
```

#### Jumps

```
For i = 0 To 5
j = j + 5
Next
```

```
1 0x00005555555555125 <+0>: push rbp
2 0x00005555555555126 <+1>: mov rbp,rsp
3 0x00005555555555129 <+4>: mov DWORD PTR [rbp-0x4],0x0
4 0x00005555555555130 <+11>: mov DWORD PTR [rbp-0x8],0x0
5 0x00005555555555137 <+18>: jmp 0x555555555141
6 0x00005555555555139 <+20>: add DWORD PTR [rbp-0x8],0x5
7 0x0000555555555513d <+24>: add DWORD PTR [rbp-0x4],0x1
8 0x00005555555555141 <+28>: cmp DWORD PTR [rbp-0x4],0x4
9 0x00005555555555145 <+32>: jle 0x55555555139
10 0x00005555555555147 <+34>: mov eax,DWORD PTR [rbp-0x8]
11 0x00005555555555146 <+37>: pop rbp
12 0x0000555555555514b <+38>: ret
13
```

```
4 0 \times 00005555555555130 < +11 > :
                                                DWORD PTR [rbp-0x8], 0x0
                                       mov
```

```
0 \times 000005555555555137 < +18 > :
                                           jmp
                                                      0 \times 555555555141
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1 0x000055555555555125 <+0>: push rbp
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10 0x00005555555555144 <+34>: mov eax,DWORD PTR [rbp-0x8]
11 0x00005555555555146 <+33>: ret
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```

```
0 \times 0000055555555555139 < +20 > :
                                      add
                                               DWORD PTR [rbp-0x8], 0x5
```

```
0 \times 000005555555555533d < +24 > :
                                               DWORD PTR [rbp-0x4], 0x1
                                      add
```

### QUESTIONS

1. During the decode and execute stages of the fetch-execute cycle the instruction that is being processed is stored in the CIR[Current Instruction Register]. Explain why the instruction could not be processed directly from the MDR.

2. Are there any advantages of having a small number of registers?

#### ANSWERS

 To execute the instruction other data may be fetched which would overwrite the MDR and overwrite the instruction recently fetched

- Instruction encoding The more registers you have, the more bits you need in your instruction to specify each register. If you had only 4 registers, you would only need 2 bits to uniquely identify each register while 256 would need 8 bits.
- Space Registers are on the physical board so there's a limited amount of realestate to house them