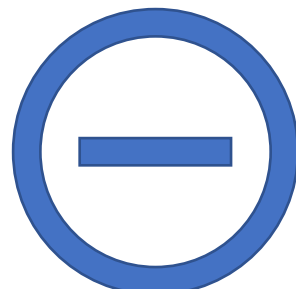
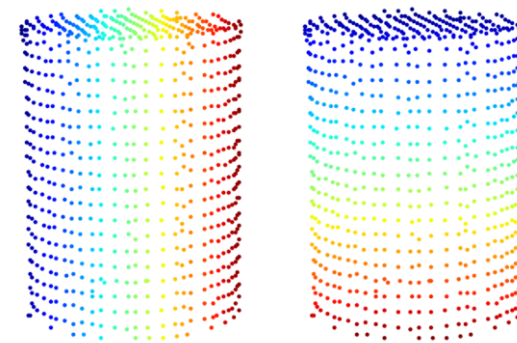


Observation I

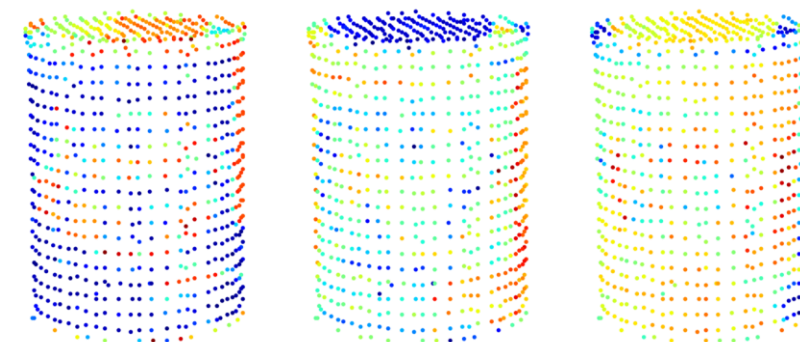
Difference function f



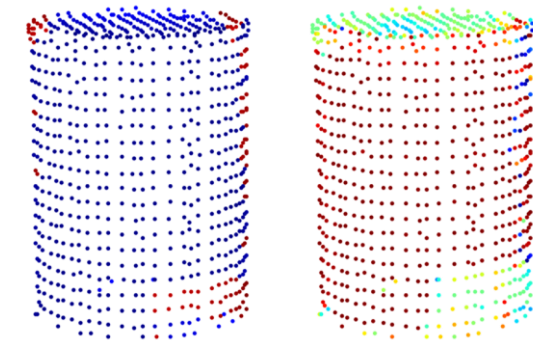
Normalized coordinates



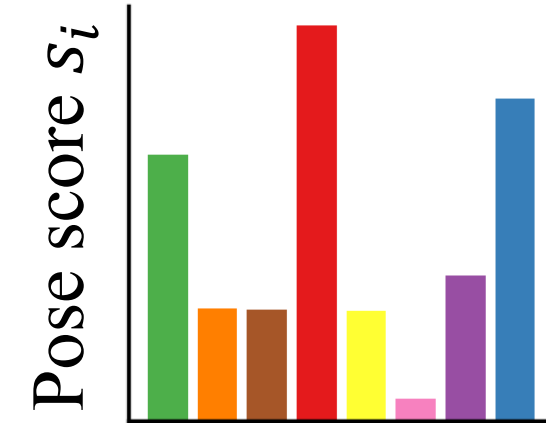
Color difference



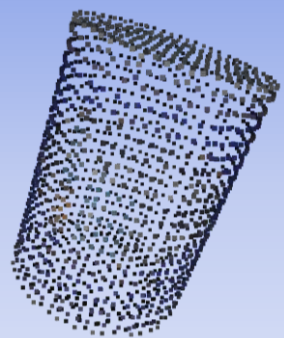
Geometry difference



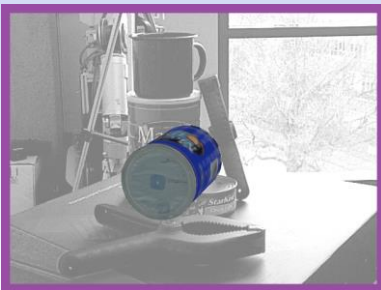
Scoring
Network



Hypothesis h_i



Object model \mathcal{M}



Pose hypotheses \mathcal{H}

Point difference D_i