OnFlight Hub UDP Broadcast Description

Firmware v1.0

Document Revision 1.0



Bolder Flight Systems

UDP Broadcast Description

Table of Contents

1	Technical Documentation	3
2	Support	2
	Introduction	
3	Introduction	J
4	Status Bit Field	

1 Technical Documentation

The following documentation and support software are included with OnFlight and available from our website:

- User Manual: describes the OnFlight Hub, specifications, and operations.
- CSV Data Log Description: describes the fields available in the CSV formatted data logs.
- **Binary Data Log Description:** describes the binary data log format that OnFlight Hub uses to write data. This is useful for application developers who would like to natively read and use these data logs.
- **UDP Broadcast Description (this document):** describes the real-time UDP broadcast packet format that is sent by OnFlight Hub.
- External Air Data Interface: describes the interface to send OnFlight Hub data from an external air data system.
- External AGL Altimeter Interface: describes the interface to send OnFlight Hub data from an external Above Ground Level (AGL) altimeter.
- Data Converter: application for Windows or MacOS, which converts the data from OnFlight to CSV format.

2 Support

If you have technical problems or cannot find the information you need in the provided documents, please contact our technical support team by email at: support@bolderflight.com. Our team is committed to providing the support necessary to ensure that you are successful using our products.

3 Introduction

OnFlight Hub broadcasts real-time data using UDP over port 2000. This message is sent at a rate of 50 Hz. The message structure is described below. Data is formatted as little endian.

Byte Offset	Туре	Name	Scale	Unit	Description
0	U1	version	-	-	Version number, currently 0.
1	U1[6]	status			Status, see Section 4 for bit field
			-	-	description.
7	l1	cpu_die_temp_c	1	С	CPU die temperature.
8	l1	imu_die_temp_c	1	С	IMU die temperature.
9	l1	mag_die_temp_c	1	С	Magnetometer die temperature.
10	11	pres_die_temp_c	1	С	Static pressure die temperature.
11	l1	airdata_die_temp_c	1	С	External airdata module die temperature.
12	11	agl_alt_die_temp_c	1	С	External AGL altimeter module die
			1	C	temperature.
13	U1	horz_pos_acc_ft	1 / 10	ft	Horizontal position accuracy estimate from
					the GNSS receiver.
14	U1	U1 vert_pos_acc_ft	1 / 10	ft	Vertical position accuracy estimate from
					the GNSS receiver.
15	U1	U1 vel_acc_kts	1/10	kts	Velocity accuracy estimate from the GNSS
			1710		receiver.
16	U1	gnss_fix_num_sv			The lower 3 bits encode the GNSS fix (0 =
					no fix, 2 = 2D fix, 3 = 3D fix, 4 = differential
	-	-	-	GNSS fix). The upper 5 bits encode the	
					number of satellite vehicles used in the
					GNSS solution.
17	U1	utc_year	_	_	UTC year from the GNSS receiver from
			_	_	1970 (i.e. year = utc_year + 1970).

18	U1	uta manth			LITC month from the CNSS receiver
		utc_month	-	-	UTC month from the GNSS receiver.
19	U1	utc_day	-	-	UTC day from the GNSS receiver.
20	U1	utc_hour	-	-	UTC hour from the GNSS receiver.
21	U1	utc_min	-	-	UTC minute from the GNSS receiver.
22	U1	utc_sec	-	-	UTC second from the GNSS receiver.
23	12	pitch_deg	1/100	deg	Pitch angle (+up).
25	12	roll_deg	1/100	deg	Roll angle (+right).
27	12	mag_var_deg	1/100	deg	Magnetic variation (+east).
29	U2	true_heading_deg	1/100	deg	Heading angle, true, 0 – 360.
31	U2	gnd_spd_kts	1/100	kts	Ground speed.
33	U2	gnd_track_deg	1/100	kts	Ground track, true, 0 – 360.
35	12	flt_path_deg	1/100	kts	Flight path angle.
37	12	climb_rate_ftpm	1	ft/min	Climb rate.
39	12	load_factor	1/1000	G	Load factor.
41	12	pitch_rate_dps	1/10	deg/s	Pitch rate (+pitch up).
43	12	roll_rate_dps	1/10	deg/s	Roll rate (+roll right).
45	12	yaw_rate_dps	1 / 10	deg/s	Yaw rate (+yaw right).
47	12	accel_x_g	1/1000	G	Acceleration (+forward out the nose).
49	12	accel_y_g	1/1000	G	Acceleration (+right).
51	12	accel_z_g	1/1000	G	Acceleration (+down).
53	U2	alt_wgs84_ft			Altitude above the WGS84 ellipsoid, biased
			-	ft	by +10,000 ft (i.e. alt = alt_wgs84_ft -
					10000).
55	U2	alt_msl_ft			Altitude above Mean Sea Level (MSL),
			-	ft	biased by +10,000 ft (i.e. alt = alt_msl_ft -
					10000).
57	U2	cabin_pres_alt_ft			Cabin pressure altitude, biased by +10,000
			-	ft	ft (i.e. pres_alt = cabin_pres_alt_ft -
					10000).
59	U2	cabin_pres_pa	2	Pa	Cabin pressure.
61	U2	airdata_static_pres_pa	2	Pa	External airdata module static pressure.
63	U2	airdata_diff_pres_pa			External airdata module differential
			1	Pa	pressure.
65	U2	J2 airdata_oat_c	1/100	_	External airdata module Outside Air
				С	Temperature (OAT).
67	U2	U2 airdata_ias_kts	1/100		External airdata module Indicated Air
				kts	Speed (IAS).
69	U2	airdata_tas_kts	1 / 100	kts	External airdata module True Air Speed
			1 / 100		(TAS).
71	U2	airdata_pres_alt_ft	-		External airdata pressure altitude, biased
				ft	by +10,000 ft (pres alt =
					airdata_pres_alt_ft - 10000).
73	U2	airdata_density_alt_ft			External airdata density altitude, biased by
			_	ft	+10,000 ft (density_alt =
					airdata_density_alt_ft - 10000).
75	12	airdata_aoa	1/100	-	External airdata angle of attack, either in
-					degrees or a pressure ratio depending on
			'		the status bit set, described in Section 4.
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Bolder Flight Systems

77	12	agl_alt_in	1	in	External AGL altimeter altitude.
79	14	lat_deg	1e-7	deg	Latitude.
83	14	lon_deg	1e-7	deg	Longitude.
87	U4	sys_time_ms	-	ms	Time since boot.

4 Status Bit Field

Status bytes are used to efficiently encode data, below is the description and bit masking of these bytes. The description describes the case if a bit occupies that position.

Byte	Mask	Description			
0	0x01	Filtered input voltage between configured low and warning voltages.			
0	0x02	Filtered input voltage below configured low voltage.			
0	0x04	System die temperatures (CPU, IMU, magnetometer, and static pressure sensor) all			
U	0x04	reporting ok.			
0	0x08	CPU die temperature between -30C and +70C.			
0	0x10	INS initialized.			
0	0x20	INS healthy.			
1	0x01	New IMU data received.			
1	0x02	IMU healthy.			
1	0x04	IMU die temperature between -30C and +70C.			
1	0x08	New magnetometer data received.			
1	0x10	Magnetometer healthy.			
1	0x20	Magnetometer die temperature between -30C and +70C.			
1	0x40	New GNSS data received.			
1	0x80	GNSS healthy.			
2	0x01	New static pressure data received.			
2	0x02	Static pressure healthy.			
2	0x04	Static pressure die temperature between -30C and +70C.			
3	0x01	New external airdata message received.			
3	0x02	External airdata module connected.			
3	0x04	External airdata battery status warning.			
3	0x08	External airdata battery status critically low.			
3	0x10	External airdata board die temperature ok.			
3	0x20	External airdata OAT measurement available.			
3	0x40	External airdata AOA measurement available.			
3	0x80	External airdata new static pressure data received.			
4	0x01	External airdata static pressure healthy.			
4	0x02	External airdata new differential pressure data received.			
4	0x04	External airdata differential pressure healthy.			
4	0x08	External airdata new OAT data received.			
4	0x10	External airdata OAT healthy.			
4	0x20	External airdata new AOA data received.			
4	0x40	External airdata AOA healthy.			
4	0x80	External airdata AOA data type is angle in degrees, otherwise data type is pressure ratio.			
5	0x01	New external AGL altimeter message received.			
5	0x02	External AGL altimeter module connected.			
5	0x04	External AGL altimeter battery status warning.			

5	0x08	External AGL altimeter battery status critically low.	
5	0x10	External AGL altimeter board die temperature ok.	
5	0x20	External AGL altimeter new sensor data received.	
5	0x40	External AGL altimeter sensor healthy.	
5	0x80	External AGL altimeter sensor in range.	