Optimization Methods - Duality

Bolei Zhang

December 1, 2024

1 Solutions

Problem 1: Get the Lagrange function and dual function of the following problem:

$$\min x^T x
\text{s.t. } Ax = b$$
(1)

Solution: This problem has no inequality constraints and p (linear) equality constraints. The Lagrangian is $L(x,\nu) = x^T x + \nu^T (Ax - b)$, with domain $\mathbb{R}^n \times \mathbb{R}^p$. The dual function is given by $g(\nu) = \inf_x L(x,\nu)$. Since $L(x,\nu)$ is a convex quadratic function of x, we can find the minimizing x from the optimality condition

$$\nabla_x L(x, \nu) = 2x + A^T \nu = 0,$$

which yields $x = -(1/2)A^T\nu$. Therefore, the dual function is

$$g(\nu) = L(-(1/2)A^T\nu, \nu) = -(1/4)\nu^T AA^T\nu - b^T\nu,$$

which is a concave quadratic function, with domain \mathbb{R}^p . The lower bound property states that for any $\nu \in \mathbb{R}^p$, we have

$$-(1/4)\nu^T A A^T \nu - b^T \nu \le \inf\{x^T x | Ax = b\}$$

.

Problem 2: Get the Lagrange function and dual function of the following problem:

$$\min c^T x$$
s.t. $Ax = b, x > 0$. (2)

Solution: To form the Lagrangian we introduce multipliers λ_i for the *n* inequality constraints and multiplier ν_i for the equality constraints, and obtain

$$L(x, \lambda, \nu) = c^{T}x - \sum_{i=1}^{n} \lambda_{i}x_{i} + \nu^{T}(Ax - b) = -b^{T}\nu + (c + A^{T}\nu - \lambda)^{T}x$$

The dual function is

$$g(\lambda, \nu) = \inf L(x, \lambda, \nu) = -b^T \nu + \inf (c + A^T \nu - \lambda)^T$$

which is easily determined analytically, since a linear function is bounded below only when it is identically zero. Thus, $g(\lambda, \nu) = -\infty$ except when $c + A^T \nu - \lambda = 0$, in which case it is $-b^T \nu$:

$$g(\lambda, \nu) = \begin{cases} -b^T \nu & A^T \nu - \lambda + c = 0, \\ -\infty & otherwise. \end{cases}$$
 (3)

Note that the dual function g is finite only on a proper affine subset of $\mathbb{R}^m \times \mathbb{R}^p$. We will see that this is a common occurrence. The lower bound property (5.2) is nontrivial only when λ and ν satisfy $\lambda \geq 0$ and $A^T \nu - \lambda + c = 0$. When this occurs, $-b^T \nu$ is a lower bound on the optimal value of the LP.

Problem 3: Get the optimal value of the following problem via KKT conditions:

$$\min (1/2)x^T P x + q^T x + r$$
s.t. $Ax = b, P \in S_+^n$ (4)

Solution: The KKT conditions for this problem are

$$Ax^* = b, Px^* + q + A^T \nu^* = 0,$$

which we can write as

$$\left[\begin{array}{cc} P & A^T \\ A & 0 \end{array}\right] \left[\begin{array}{c} x^* \\ \nu^* \end{array}\right] = \left[\begin{array}{c} -q \\ b \end{array}\right]$$

Solving this set of m+n equations in the m+n variables x^*, ν^* gives the optimal primal and dual variables.

Problem 4: Get the optimal value of the max entropy problem via KKT conditions:

$$\min \sum_{i=1}^{n} x_i \log x_i$$
s.t. $Ax \le b, \mathbf{1}^T x = 1$ (5)

Solution: The Lagrange function is

$$L(x, \lambda, \nu) = \sum_{i=1}^{n} x_i \log x_i + \lambda^{T} (Ax - b) + \nu (\mathbf{1}^{T} x - 1)$$

By taking the derivative and setting it to zero:

$$\frac{\partial L}{\partial x_i} = \log x_i + 1 + a_i^T \lambda + \nu = 0$$

Therefore, $x_i = e^{-1-a_i^T \lambda - \nu}$. Substitute x_i in $g(\lambda, \nu)$

$$g(\lambda, \nu) = \sum_{i=1}^{n} (x_i(-\lambda^T a_i - \nu - 1) + \lambda^T (a_i^T x_i - b_i) + \nu x_i) - \nu$$

$$= -b^T \lambda - \nu - e^{-\nu - 1} \sum_{i=1}^{n} e^{-a_i^T \lambda}$$
(6)

The dual problem is

$$\max - b^T \lambda - \nu - e^{-\nu - 1} \sum_{i=1}^n e^{-a_i^T \lambda}$$
s.t. $\lambda > 0$ (7)

where a_i are the columns of A. We assume that the weak form of Slater's condition holds, i.e., there exists an x > 0 with $Ax \le b$ and $\mathbf{1}^T x = 1$, so strong duality holds and an optimal solution (λ^*, ν^*) exists. Suppose we have solved the dual problem. The Lagrangian at (λ^*, ν^*) is

$$L(x, \lambda^*, \nu^*) = \sum_{i=1}^{n} x_i \log x_i + \lambda^{*T} (Ax - b) + \nu^* (\mathbf{1}^T x - 1)$$

which is strictly convex on D and bounded below, so it has a unique solution x^* , given by

$$x_i^* = 1/\exp(a_i^T \lambda^* + \nu^* + 1), i = 1, ..., n.$$

If x^* is primal feasible, it must be the optimal solution of the primal problem. If x^* is not primal feasible, then we can conclude that the primal optimum is not attained.

Problem 5: Get the optimal value of the water filling problem via KKT conditions:

$$\min -\sum_{i=1}^{n} \log(\alpha_i + x_i)$$
s.t. $x > 0, \mathbf{1}^T x = 1$ (8)

Solution: This problem arises in information theory, in allocating power to a set of n communication channels. The variable x_i represents the transmitter power allocated to the *i*th channel, and $\log(\alpha_i + x_i)$ gives the capacity or communication rate of the channel, so the problem is to allocate a total power of one to the channels, in order to maximize the total communication rate.

Introducing Lagrange multipliers $\lambda^* \in \mathbb{R}^n$ for the inequality constraints $x^* \geq 0$, and a multiplier $\nu^* \in \mathbb{R}$ for the equality constraint $\mathbf{1}^T x = 1$, we obtain the KKT conditions

$$x^* \ge 0, \mathbf{1}^T x^* = 1, \lambda^* \ge 0, \lambda_i^* x_i^* = 0, i = 1, ..., n, -1/(\alpha_i + x_i^*) - \lambda_i^* + \nu^* = 0, i = 1, ..., n.$$

We can directly solve these equations to find x^*, λ^* , and ν^* . We start by noting that λ^* acts as a slack variable in the last equation, so it can be eliminated, leaving

$$x^* \ge 0, \mathbf{1}^T x^* = 1, x_i^* (\nu^* - 1/(\alpha_i + x_i^*)) = 0, i = 1, ..., n, \nu^* \ge 1/(\alpha_i + x_i^*), i = 1, ..., n.$$

If $\nu^* < 1/\alpha_i$, this last condition can only hold if $x_i^* > 0$, which by the third condition implies that $\nu^* = 1/(\alpha_i + x_i^*)$. Solving for x_i^* , we conclude that $x_{\equiv}^* 1/\nu^* - \alpha_i$ if $\nu^* < 1/\alpha_i$. If $\nu^* \ge 1/\alpha_i$, then $x_i^* > 0$ is impossible, because it would imply $\nu^* \ge 1/\alpha_i > 1/(\alpha_i + x_i^*)$, which violates the complementary slackness condition. Therefore, $x_i^* = 0$ if $\nu^* \ge 1/\alpha_i$. Thus we have

$$x_i^* = \begin{cases} 1/\nu^* - \alpha_i & \nu^* < 1/\alpha_i, \\ 0 & otherwise. \end{cases}$$
 (9)

or, put more simply, $x_i^* = \max\{0, 1/\nu^* - \alpha_i\}$. Substituting this expression for x_i^* into the condition $\mathbf{1}^T x^* = 1$ we obtain

$$\sum_{i=1}^{n} \max\{0, 1/\nu^* - \alpha_i\} = 1.$$

The lefthand side is a piecewise-linear increasing function of $1/\nu^*$, with breakpoints at α_i , so the equation has a unique solution which is readily determined.

This solution method is called water-filling for the following reason. We think of α_i as the ground level above patch i, and then flood the region with water to a depth $1/\nu$. The total amount of water used is then $\sum_{i=1}^{n} \max\{0, 1/\nu^* - \alpha - i\}$. We then increase the flood level until we have used a total amount of water equal to one. The depth of water above patch i is then the optimal value x_i^* .

Problem 6: Get the optimal value of the following problem via KKT conditions:

min
$$x_1$$

s.t. $16 - (x_1 - 4)^2 - x_2^2 \ge 0$
 $x_1^2 + (x_2 - 2)^2 - 4 = 0$ (10)

Solution: The Lagrange function is

$$L(x,\lambda,\nu) = x_1 + \nu(x_1^2 + (x_2 - 2)^2 - 4) - \lambda(16 - (x_1 - 4)^2 - x_2^2),$$

Get the stationary condition:

$$1 + 2\nu x_1 + 2\lambda(x_1 - 4) = 0, 2\nu(x_2 - 2) + 2\lambda x_2 = 0.$$

Consider the complementary slackness $\lambda = 0$ or $16 - (x_1 - 4)^2 - x_2^2 = 0$. If $\lambda = 0$, the stationary becomes

$$1 + 2\nu x_1 = 0, 2\nu(x_2 - 2) = 0. (11)$$

From the first line, we can get $\nu \neq 0$, and therefore $x_2 = 2$. Taking the equality constraint that:

$$x_1^2 + (x_2 - 2)^2 - 4 = 0$$

We can get x1 = 2. The KKT point is $(x_1, x_2, \lambda, \nu) = (2, 2, 0, -1/4)$.

If $16 - (x_1 - 4)^2 - x_2^2 = 0$ holds for the complementary slackness, combining $x_1^2 + (x_2 - 2)^2 - 4 = 0$, we can get two solutions (0,0) and (8,16) for (x_1, x_2) . Therefore, the KKT points can be (0,0,1/8,0) and (8/5, 16/5, 3/40, -1/5).

Considering the above KKT points, the optimal solution is (0, 0, 1/8, 0).

Problem 7: Get the optimal value of the following problem via KKT conditions:

$$\min_{x \in \mathbb{R}, y > 0} e^{-x}$$
s.t.
$$\frac{x^2}{y} \le 0$$
(12)

Solution: According to the constraints, it is easy to convert the origin problem as

$$\min_{x \in \mathbb{R}} e^{-x}$$
s.t. $x = 0$ (13)

The Lagrange function is then

$$L(x,\nu) = e^{-x} + \nu x$$

And the dual function is

$$g(\nu) = \inf_{x} (e^{-x} + \nu x) = \begin{cases} \nu - \nu \ln \nu & \nu > 0, \\ 0, & \nu = 0, \\ -\infty & otherwise. \end{cases}$$

Therefore, the dual problem is

$$\max_{\nu} \left\{ \begin{array}{ll} \nu - \nu \ln \nu & \nu > 0, \\ 0, & \nu = 0, \end{array} \right.$$

The optimal solution is achieved when $\nu = 1$. The duality gap is 0.

Problem 8: Get the dual problem of

min
$$x^T W x$$

s.t. $x_i^2 = 1, i = 1, ..., n$ (14)

Solution: The Lagrange function is

$$L(x,\nu) = x^T W x + \sum_{i=1}^n \nu_i (x_i^2 - 1) = x^T (W + \text{diag}(\nu)) x - 1^T \nu$$

The dual function is

$$g(\nu) = \inf_{x} x^{T} (W + \operatorname{diag}(\nu)) x - 1^{T} \nu$$

$$= \begin{cases} -1^{T} \nu & W + \operatorname{diag}(\nu) \succeq 0, \\ -\infty & otherwise. \end{cases}$$
(15)

where we use the fact that the infimum of a quadratic form is either zero (if the form is positive semidefinite) or $-\inf$ (if the form is not positive semidefinite).

This dual function provides lower bounds on the optimal value. For example, we can take the specific value of the dual variable $\nu = -\lambda_{\min}(W)1$, which is dual feasible, since $W + \operatorname{diag}(\nu) = W - \lambda_{\min}(W)I \succeq 0$. This yields the bound on the optimal value p^* : $p^* \geq -1^T \nu = n\lambda_{\min}(W)$.

Problem 9: Get the conjugate function of

$$\min_{x \in \mathcal{L}} f(x) \\
\text{s.t. } x = 0$$
(16)

Solution: This problem has Lagrangian $L(x,\nu)=f(x)+\nu^T x$, and dual function

$$g(\nu) = \inf_{x} (f(x) + \nu^{T} x) = -\sup_{x} ((-\nu)^{T} x - f(x)) = -f^{*}(-\nu).$$

•

Problem 10: Get the dual problem of

$$\min_{s.t.} f_0(x)
s.t. Ax \le b, Cx = d$$
(17)

Solution: Using the conjugate of f_0 we can write the dual function for the problem as

$$g(\lambda, \nu) = \inf_{x} (f_0(x) + \lambda^T (Ax - b) + \nu^T (Cx - d))$$

= $-b^T \lambda - d^T \nu + \inf_{x} (f_0(x) + (A^T \lambda + C^T \nu)^T x)$
= $-b^T \lambda - d^T \nu - f_0^* (-A^T \lambda - C^T \nu).$ (18)

The domain of g follows in from the domain of f_0^* :

$$dom g = \{(\lambda, \nu) | -A^T \lambda - C^T \nu \in dom f_0^* \}.$$