CON-FMC API based on LIBUSB

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Abstract

This document addresses user level API (Application Programming Interface) of CON-FMC. This API utilized LIBUSB.

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1 Overview

As shown in Figure 1, this is about CON-FMC API (**conapi**) on top of LIBUSB. The LIBUSB is a C library providing generic access to USB device through usbfs or WinUSB.

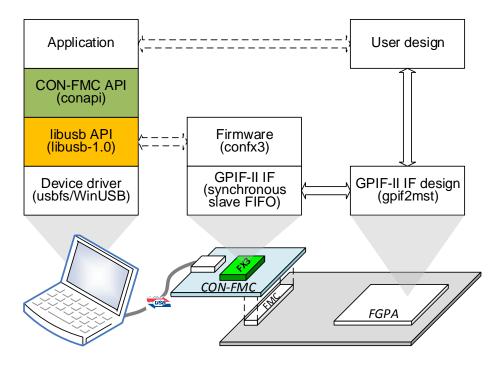


Figure 1: Overview

Licensing issues:

 'libusb' is released under version 2.1 of the GNU Lesser General Public License (LGPL).

2 Getting started

As shown in code below, 'conapi.h' should be included to use CON-FMC API and its basic steps are as follows.

- 1. Include API header, i.e., 'conapi.h'.
- 2. Get handler by calling 'conlnit' with proper arguments, which include card-id, operation-mode, and log-level.
- 3. Do some operation using the handler such as assert reset, get CID, and
- 4. Release all resource by calling 'conRelease().

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```
#include "conapi.h"

int main(int argc, char *argv[])
{
    unsigned int cid=0;
    unsigned int mode=CON_MODE_CMD;
    unsigned int loglevel=CONAPI_LOG_LEVEL_INFO;

    con_Handle_t handle=conInit(cid, mode, loglevel);
    conReset(handle, 1);
    cid=conGetCID(handle);
    conRelease(handle);

return 0;
}
```

3 API convention

Most API returns zero or non-NULL pointer on successful completion. Otherwise, it returns non-zero number and error number is stored in the internal variable. The error code is returned by 'conGetErrorConapi()' and the error message can be got by 'conGetErrorMsg()'.

4 Macros, data types, and enumerations

4.1 API version

#define CONAPI_VERSION 0x20180420

4.2 CON-FMC handler

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```
struct _con_Handle {
    unsigned int mode;
    unsigned int cid;
    struct _usb usb;
};
typedef struct _con_Handle *con_Handle_t;
```

4.3 USB related

```
struct _usb {
    struct libusb_context
                             *ctx;
    struct libusb_device
                             *dev:
    struct libusb_device_handle *handle;
                       interface:
    int
                       kernelDriverDetached;
                      // 0: initial value
                      // 1: dettached
    int speed; // x0.1-Mbps
        bulk_max_pkt_size_out; // in bytes
    int
    int bulk_max_pkt_size_in; // in bytes
    int iso_max_pkt_size_out; // in bytes
    int iso_max_pkt_size_in; // in bytes
typedef struct _usb usb_t;
```

'speed' reflects the device speed:

- 15: 1.5Mbps for USB1.0
- 120: 12Mbps for USB1.1
- 4,800: 480Mbps for USB2.0
- 50,000: 5Gbps for USB3.0
- 100,000: 10Gbps for USB3.2

'bulk_max_pkt_size_out/in' reflects the number of bytes for bulk operation.

- 512: for USB2.0
- 1024: for USB 3.0

4.4 USB vendor requests

These codes are used to request vendor specific functions to the firmware (i.e, confxe) through USB control transfer conUsbControlTransfer().

```
enum conapi_vendor_req {
    CON_CID_READ =0xC0
    , CON_RST_DRIVE =0xC1
    , CON_MODE_DRIVE=0xC2
    , CON_FX3_INFO_READ=0xC3
    , CON_LED_DRIVE =0xC4
    , CON_I2C_WRITE =0xBA
    , CON_I2C_READ =0xBB
    , CON_FX3_RESET =0xE2
```

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```
, CON_EP_RESET = 0xE1 };
```

4.5 USB vendor ID and Product ID

It is fixed value to identify USB device.

```
enum conapi_vid_pid {
    CON_USB_VID=0x04B4
    , CON_USB_PID=0x00F3
};
```

4.6 USB endpoint address

It is fixed value to identify USB endpoint. For CON-FMC, ENDPOINT 1 is used for read and write.

```
enum conapi_ep_num {
    CON_EP_OUT_DOWN=0x01 // ENDPOINT 1 DownStream (i.e, OUT, write)
    , CON_EP_IN_UP =0x81 // ENDPOINT 1 UpStream (i.e., IN, read)
};
```

4.7 CON-FMC operation mode

CON-FMC operation mode.

```
enum conapi_mode {
        CON_MODE_CMD =0x0 // command mode
        , CON_MODE_SU2F =0x1 // stream-out (USB-to-FPGA) mode
        , CON_MODE_SF2U =0x2 // stream-in (USB-from-FPGA) mode
        , CON_MODE_SLOOP=0x3 // CON_MODE_SU2F|CON_MODE_SF2U // stream-in/out mode
};
```

4.8 FX3 information

FX3 firmware information.

```
struct _con_Fx3Info {
    uint32_t version;
};
typedef struct _con_Fx3Info con_Fx3Info_t;
```

4.9 Board information

CON-FMC board information

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```
struct
         MagicID[4];
    char
    uint32 t FormatVersion;
    uint32_t Length;
         Name[32];
    char
    uint32 t PcbVersion;
    uint32 t PcbSerial;
          MajorInfo[32];
    char
          MajorPart[32];
    char
    uint32 t CRC;
typedef struct _con_BoardInfo con_BoardInfo_t;
```

- MagicID[4]: null terminated string for "FPI"
- FormatVersion: Little-endian BCD (binary coded decimal), e.g., 0x2018 04 25
- Length: num of bytes from the beginning to the end (CRC included)
- Name[32]: null terminated string for board name, e.g., "CON-FMC-FX3"
- PcbVersion: Little-endian BCD, e.g., 0x1810_0101
- PcbSerial: Little-endian binary (not BCD)
- MajorInfo[32]: null terminated string for major part, e.g., "Cypress FX3"
- MajorPart[32]: null terminated string for board name, e.g., "CYUSB3014-BZXI
- CRC: formula 0x04C11DB7 (0xED888320/reversed) use not inverted

4.10 Gpif2mst information

Gpif2mst RTL information.

```
struct _con_MasterInfo {
    uint32_t version;
    uint16_t depth_cmd; // num of entries (i.e., words)
    uint16_t depth_u2f; // num of entries (i.e., words)
    uint16_t depth_f2u; // num of entries (i.e., words)
    uint8_t clk_mhz; // frequency in Mhz
    uint8_t clk_inv; // inverted when 1
};
typedef struct _con_MasterInfo con_MasterInfo_t;
```

5 API

5.1 Initialize and release

5.1.1 Initialize: conlnit()

'conInit()' prepares CON-FMC USB device through libusb APIs and returns a handler when there is a CON-FMC with the given 'con_cid'.

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Function prototype:

con_Handle_t conInit (unsigned int con_cid , unsigned int con_mode , unsigned int conapi_log_level);

Arguments:

- → con_mode: gpif2mst operation mode and bitwise or of followings
 - CON_MODE_CMD: pseudo-DMA mode
 - CON_MODE_SU2F: stream output, i.e., stream to FPGA through FX3
 - CON_MODE_SF2U: stream input, i.e., stream from FPGA through FX3
 - CON_MODE_SLOOP: both CON_MODE_SU2F and CON_MODE_SF2U
- - CONAPI_LOG_LEVEL_NONE,
 - CONAPI_LOG_LEVEL_ERROR,
 - CONAPI_LOG_LEVEL_WARNING,
 - CONAPI_LOG_LEVEL_INFO,
 - > CONAPI LOG LEVEL DEBUG

Return value:

- non-NULL pointer to con_Handle_t on success
- ♦ NULL pointer on failure

5.1.2 Release: conRelease()

'conRelease()' releases CON-FMC USB device for the given 'con cid'.

Function prototype:

int conRelease (con_Handle_t con_handle);

Arguments:

Return value:

- ♦ 0 on success
- ♦ !=0 on failure, which will be

5.2 Core functions

5.2.1 USB device initialize: conUsbInit()

'conUsbInit()' finds a device with a particular CON-FMC card id by using 'conOpenDevWithVidPidCid()'

Function prototype:

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```
struct libusb_device_handle *conUsbInit (
, unsigned int card_id
, unsigned int conapi_log_level
, struct _usb *pusb );
```

Arguments:

- - CONAPI_LOG_LEVEL_NONE,
 - CONAPI_LOG_LEVEL_ERROR,
 - CONAPI_LOG_LEVEL_WARNING,
 - CONAPI_LOG_LEVEL_INFO,
 - CONAPI_LOG_LEVEL_DEBUG
- → pusb: pointer to 'struct usb'; it can be NULL

Return value:

- ♦ Pointer of a USB device handler, i.e., not NULL on success
- ♦ NULL on failure

5.2.2 Release: conUsbRelease()

'conUsbRelease()' releases USB device.

Function prototype:

```
int conUsbRelease ( usb_t *pusb );
```

Arguments:

Return value:

- ♦ 0 on success
- ♦ !=0 on failure, which will be

5.2.3 USB device open: conOpenUsbWithVidPidCid()

'conOpenUsbWithVidPidCid()' finds a device with a particular Vendor ID (0x04B4), Product ID (0x00F3), and Card ID.

Function prototype:

Arguments:

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Return value:

- ♦ Pointer of a USB device handler, i.e., not NULL on success
- ♦ NULL on failure

It first gathers USB device list and tries to get devices with the given vendor ID and product ID. And then it checks if there is a device with the given card ID. If a device exists, it opens the device.

5.2.4 USB control transfer: conUsbControlTransfer()

'conUsbControlTransfer()' generates USB control transfer to read and write resources in the USB controller, i.e., FX3.

Function prototype:

Arguments:

- type: direction of the transfer
 - LIBUSB ENDPOINT IN for read
 - ➤ LIBUSB ENDPOINT OUT for write
- → value: fills wValue and its meaning depends on 'cmd'
- ♦ cmd: Vendor Specific Requests and see 'enum conapi vendor reg'.
 - CON CID READ
 - CON_RST_DRIVE
 - CON_MODE_DRIVE
 - CON_LED_DRIVE
 - > CON I2C WRITE
 - CON I2C READ
- data: pointer to the buffer carrying data if any depending on 'cmd'
- → length: the number of bytes to carry through 'data' buffer

Return value:

- ♦ the number of bytes actually transferred (>=0) on success
- ♦ <0 on failure, which will be
 </p>

5.2.5 USB bulk transfer: conUsbBulkTransfer()

'conUsbBulkTransfer()' generates USB data transfer to push or pop data from FPGA through FX3.

Function prototype:

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```
int conUsbBulkTransfer( struct libusb_device_handle *dev_handle
, uint8_t ep_addr
, uint8_t *pData
, int toTransfer
, int *pTransferred );
```

Arguments:

- → dev_handle: USB device handler.
- → ep_addr: USB ENDPOINT address for downstream or upstream
 - CON_EP_OUT_DOWN
 - CON_EP_IN_UP
- ♦ pData: pointer to the buffer for data if any
- ♦ toTransfer: the number of bytes to be transferred
- ♦ pTransferred: the actual number of bytes have been transferred.

Return value:

- ♦ 0 on success
- ♦ !=0 on failure, which will be

5.2.6 Board I2C transfer: conUsbFx3I2cTransfer()

'conUsbFx3I2cTransfer()' generates I2C transactions on FX3. Note that I2C device address is fixed and dealt with the firmware (confx3).

Function prototype:

Arguments:

- type: direction of the transfer
 - LIBUSB_ENDPOINT_IN for read
 - > LIBUSB ENDPOINT OUT for write
- ♦ byte addr: I2C byte address
- → buffer: pointer to the data to be used
- ♦ byte_count: the number of bytes to be transferred

Return value:

- ♦ 0 on success
- ♦ !=0 on failure, which will be

5.3 Utility

5.3.1 Read CID: conGetCID()

'conGetCID()' reads CID.

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Function prototype:

int conGetCID(con_Handle_t con_handle);

Arguments:

Return value:

- ♦ 0~7 on success
- ♦ <0 on failure
 </p>

5.3.2 Read CID: conUsbGetCID()

'conUsbGetCID()' reads CID.

Function prototype:

int conUsbGetCID(struct libusb_device_handle *dev_handle);

Arguments:

Return value:

- ♦ 0~7 on success
- ♦ <0 on failure
 </p>

5.3.3 Reset: conReset()

'conReset()' asserts reset signals (i.e., SL_RST_N) and then de-asserts it.

Function prototype:

Arguments:

- → duration: the number of 'nop()' instruction between driving 0 and 1.

Return value:

- ♦ 0 on success
- ♦ !=0 on failure, which will be

5.3.4 Mode: conSetMode()

'conSetMode()' sets CON-FMC operation mode. It asserts reset, drives mode, and then de-assert reset.

Function prototype:

```
int conSetMode ( con_Handle_t con_handle , unsigned int con_mode );
```

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Arguments:

- - CON_MODE_CMD
 - > CON MODE SU2F
 - ➤ CON_MODE_SF2U
 - CON_MODE_SLOOP

Return value:

- ♦ 0 on success
- ♦ !=0 on failure, which will be

It should be noted that the upstream buffers may be full when CON_MODE_SF2U or CON_MODE_SLOOP is set. As a result, access in CON_MODE_CMD may not work after CON_MODE_SF2U or CON_MODE_SLOOP.

5.3.5 Master information: conGetMasterInfo()

'conGetMasterInfo()' reads gpif2mst related information. It can be used when the operation mode is CON_MODE_CMD.

Function prototype:

```
int conGetMasterInfo(con_Handle_t con_handle
, con_MasterInfo_t *pInfo);
```

Arguments:

- plnfo: pointer to structure to store command FIFO depth; its structure is given in section 4.10 Gpif2mst information.

Return value:

- ♦ 0 on success
- ♦ !=0 on failure, which will be

5.3.6 Board information: conGetBoardInfo()

'conGetBoardInfo()' reads board information form I2C EEPROM.

Function prototype:

```
int conGetBoardInfo(con_Handle_t con_handle
, con_BoardInfo_t *pInfo
, unsigned int length
, unsigned int crc_check);
```

Arguments:

- plnfo: pointer to the board information data structure; its structure is given in section 4.9 Board information.
- ♦ length: the number of byte of the structure pointed by plnfo

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Return value:

- ♦ 0 on success
- ♦ !=0 on failure, which will be

There is 'conSetBoardInfo()' that writes board information to the I2C EEPROM.

5.3.7 Get API version: conGetVersionApi()

'conGetVersionApi()' returns CONAPI version.

Function prototype:

unsigned int conGetVersionApi(void);

Arguments:

Return value:

- ♦ 4-byte version on success
- ♦ <0 on failure, which will be
 </p>

5.3.8 FX3 information: conGetFx3Info()

'conGetFx3Info()' returns FX3 firmware version.

Function prototype:

```
int conGetFx3Info( con_Handle_t con_handle , con_Fx3Info_t *pInfo )
```

Arguments:

- ♦ pInfo: pointer to the structure

Return value:

- ♦ 0 on success
- ♦ <0 on failure, which will be
 </p>

5.3.9 FX3 information: conUsbGetFx3Info()

'conUsbGetFx3Info()' returns FX3 firmware version.

Function prototype:

Arguments:

- ♦ pVersion: pointer to the variable to return version.

Return value:

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- ♦ 0 on success
- ♦ <0 on failure, which will be
 </p>

5.3.10 Get GPIF2MST version: conGetVersionMst()

'conGetVersionMst()' returns GPIF2MST RTL version.

Function prototype:

```
int conGetVersionMst( con_Handle_t con_handle
, unsigned int *pVersion );
```

Arguments:

- → pVersion: pointer to the variable to return version.

Return value:

- ♦ 0 on success
- ♦ <0 on failure, which will be
 </p>

5.3.11 Reset FX3: conResetFx3()

'conResetFx3()' resets USB device.

Function prototype:

Arguments:

- → warm_reset: make USB device reset
 - > 0: cold-reset
 - ➤ 1: warm-reset

Return value:

- ♦ 0 on success
- ♦ !=0 on failure, which will be

This requests to reset the FX3 device and the device will disappears and establishes the USB connection again without loading the firmware.

5.3.12 Reset Endpoint: conResetEp()

'conResetEp()' requests to flush and reset the endpoint.

Function prototype:

```
int conResetEp ( struct libusb_device_handle *dev_handle
    , unsigned int ep_flag );
```

Arguments:

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- - > 1: OUT/down-stream endpoint
 - > 2: IN/up-stream endpoint
 - > 3: Both endpoints.

Return value:

- ♦ 0 on success
- ♦ !=0 on failure, which will be

5.3.13 Timeout: conUsbTimeout()

'conUsbTimeout()' requests to flush and reset the endpoint.

Function prototype:

int conUsbTimeout (int millisecond);

Arguments:

- → millisecond: timeout in millisecond for bulk and control
 - positive value: timeout value to set
 - negative value: returns current timeout value without modification
 - o: non-blocking access

Return value:

- ♦ >0 on success
- ♦ <0 on failure
 </p>

5.4 Pseudo-DMA functions

This functions are used under CON_MODE_CMD mode, which uses command to control gpif2mst, in which the command is fed through thread 0 FIFO to cmd-FIFO.

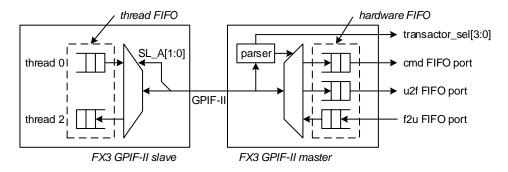


Figure 2: Pseudo-DMA mode

There are three types of communication as follows.

- Pushing cmd FIFO in the GPIF-II master (Command FIFO)
- Pushing u2f FIFO in the GPIF-II master (USB-to-FPGA data FIFO)

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Popping f2u FIFO in the GPIF-II mater (FPGA-to-USB data FIFO)

As shown in

Figure 3, all communication packet starts with 'control flit', which is fed through thread 0 FIFO and then followed by data flits if required. Especially, the communication packet to get data from F2U FIFO starts with 'control flit' and then gets 'data flits' through thread 2 FIFO instead of thread 0 FIFO. It should be noted that control flits never shown to beyond gpif2mst.

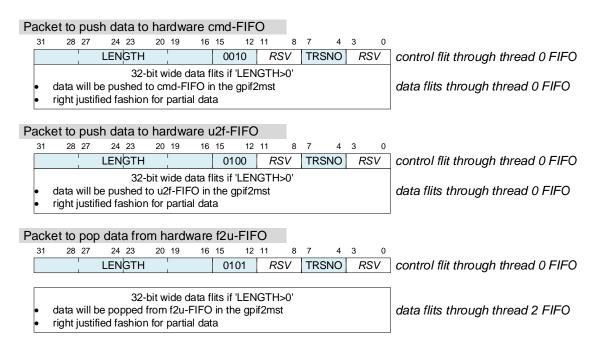


Figure 3: Communication packet formats

The meaning of field shown in Figure 3 is as follows.

- control command (bit 15-12 of control flit) specifies type of control
 - ♦ 0x2: command packet
 - ♦ 0x4: u2f packet (USB-to-FPGA)
 - ♦ 0x5: f2u packet (FPGA-to-USB)
- 'TRSNO[3:0]' (bit 7-4 of control flit) specifies transactor
 - ♦ It simply driven to 'transactor sel' pins of gpif2mst.
 - ♦ This can be used to select further interface beyond gpif2mst.
- 'LENGTH[15:0]' (bit 31-16) specifies the number of data flits to be followed
 - ♦ It reflects the number of payload in 32-bit units (i.e., word length).
- data flits
 - ♦ This is user payload.

When GPIF-II interface only uses 16-bit SL_DT[15:0], the lower 16-bit of packet is transferred first as little-endian fashion. This is why bit 15-12 is used for

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control command and as a result meaning of control flit can be parsed using first arriving information.

5.4.1 Communication scenario

Here is a rough scenario to send or receive data in terms of software.

In order to put data into hardware cmd-FIFO

- 1. make and send a control flit through thread 0 FIFO
 - ♦ With 0x2' control command along with corresponding data flit length
- 2. make and send data flits through thread 0 FIFO

In order to put data into hardware u2f-FIFO.

- 1. make and send a control flit through thread 0 FIFO
 - ♦ With 0x4' control command along with corresponding data flit length
- 2. make and send data flits through thread 0 FIFO

In order to get data from hardware f2u-FIFO.

- 1. make and send a control flit through thread 0 FIFO
 - ♦ With 0x5' control command along with corresponding data flit length
- 2. get data flits through thread 2 FIFO

5.4.2 Command write: conCmdWrite()

'conCmdWrite()' pushes command FIFO. It can be used when the operation mode is CON_MODE_CMD. It adds 32-bit control flit at the beginning of data.

Function prototype:

```
int conCmdWrite ( con_Handle_t con_handle
, void *pBuffer
, unsigned int nNumberOfItemsToWrite
, unsigned int *pNumberOfItemsWritten
, unsigned int transactor );
```

Arguments:

- → pBuffer: pointer to the buffer carrying command data
- ♦ nNumberOfItemsToWrite: the number of words (4-byte unit) in 'pBuffer'
- ♦ pNumberOfItemsWritten: the number of words actually written.
- transactor: 4-bit transactor id.

Return value:

- ♦ 0 on success
- ♦ !=0 on failure, which will be

It calls 'conUsbBulkTransfer()' twice internally.

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5.4.3 Data write: conDataWrite()

'conDataWrite()' pushes data FIFO. It can be used when the operation mode is CON MODE CMD. It sends control flit first and the sends data.

Function prototype:

```
int conDataWrite( con_Handle_t con_handle
, void *pBuffer
, unsigned int nNumberOfItemsToWrite
, unsigned int *pNumberOfItemsWritten
, unsigned int transactor );
```

Arguments:

- ♦ pBuffer: pointer to the buffer carrying data
- ♦ nNumberOfItemsToWrite: the number of words (4-byte unit) in 'pBuffer'
- ♦ pNumberOfItemsWritten: the number of words actually written

Return value:

- ♦ 0 on success
- ♦ !=0 on failure, which will be

It calls 'conUsbBulkTransfer()' twice internally.

5.4.4 Data read: conDataRead()

'conDataRead()' pops data FIFO. It can be used when the operation mode is CON MODE CMD. It sends control flit first and then receives data.

Function prototype:

```
int conDataRead ( con_Handle_t con_handle
, void *pBuffer
, unsigned int nNumberOfItemsToRead
, unsigned int *pNumberOfItemsRead
, unsigned int transactor );
```

Arguments:

- → pBuffer: pointer to the buffer to be filled
- ♦ nNumberOfItemsToRead: the number of words (4-byte unit) to read
- ♦ pNumberOfItemsRead: the number of words actually read.
- transactor: 4-bit transactor id.

Return value:

- ♦ 0 on success
- ♦ !=0 on failure, which will be

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It calls 'conUsbBulkTransfer()' twice internally; one for write and the other for read.

5.5 Stream functions

This mode does not use cmd-FIFO. It simply pushes or pops data in stream fashion.

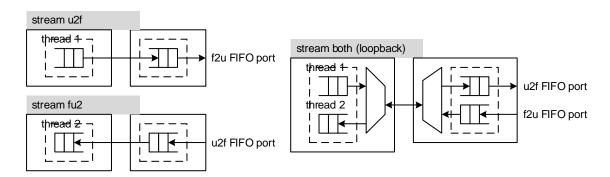


Figure 4: Stream modes

5.5.1 Stream write: conStreamWrite()

'conStreamWrite()' pushes data FIFO. It can be used when the operation mode is CON_MODE_SU2F or CON_MODE_SLOOP.

Function prototype:

```
int conStreamWrite( con_Handle_t con_handle
, void *pBuffer
, unsigned int nNumberOfItemsToWrite
, unsigned int *pNumberOfItemsWritten
, unsigned int zlp );
```

Arguments:

- → pBuffer: pointer to the buffer carrying data
- ♦ nNumberOfItemsToWrite: the number of words (4-byte unit) in 'pBuffer'
- ♦ pNumberOfItemsWritten: the number of words actually written

Return value:

- ♦ 0 on success
- ♦ !=0 on failure, which will be

It calls 'conUsbBulkTransfer()' once internally.

A multiple of wMaxPacketSize (Endpoint Descriptor) byte may not appear at one, so a ZLP (zero length packet) may be required to deal with this. The ZLP

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packet can be issued by submitting a transfer of zero length. Following is a good practice to deal with ZLP.

```
unsigned int zlp = (nNumberOfItemsToWrite%BulkMaxPktSizeOut) ? 0 : 1;
conStreamWrite(con_handle, pBuffer, nNumberOfItemsToWrite
, pNumberOfItemsWritten, zlp);
```

5.5.2 Stream read: conStreamRead()

'conStreamRead()' pops data FIFO. It can be used when the operation mode is CON_MODE_SF2U or CON_MODE_SLOOP.

Function prototype:

```
int conStreamRead ( con_Handle_t con_handle
, void *pBuffer
, unsigned int nNumberOfItemsToRead
, unsigned int *pNumberOfItemsRead );
```

Arguments:

- → pBuffer: pointer to the buffer to be filled
- ♦ nNumberOfItemsToRead: the number of words (4-byte unit) to read; it should be a multiple of BulkMaxPktSizeIn/4 words.
- ♦ pNumberOfItemsRead: the number of words actually read

Return value:

- ♦ 0 on success
- ♦ !=0 on failure, which will be

It calls 'conUsbBulkTransfer()' once internally.

It should be noted that this function reports packet overflow when there is more data than the requested in the buffer. So this function should be called with wMaxPacketSize at least.

6 Troubleshooting

6.1 Permission problem

Symptom:

When following message appears, check you udev file in '/etc/udev/rules.d' directory.

libusb: 0.000000 error [op_open] libusb couldn't open USB device

/dev/bus/usb/006/002: Permission denied.

libusb: 0.000020 error [op open] libusb requires write access to USB device nodes.

cannot initialize CON-FMC

Solution:

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Make a file named '51-fds-rule.rules' in '/etc/udev/rules.d' directory. The file looks like below, which consists of two lines.

SUBSYSTEM=="usb", ENV{DEVTYPE}=="usb_device", ATTRS{idVendor}=="04b4", ATTRS{idProduct}=="00f3", MODE=="0666" SUBSYSTEM=="usb_device", ATTRS{idVendor}=="04b4", ATTRS{idProduct}=="00f3", MODE=="0666"

Do not forget to run followings or reboot your system.

\$ sudo udevadm control --reload-rules

\$ sudo service udev restart

\$ sudo udevadm trigger

6.2 LibUsb problem

Symptom:

When LibUsb header is not found by the compiler.

Solution:

Use 'pkg-config --cflags libusg-1.0' to figure out '-l/path-to-libusb.h'

\$ gcc source.c `pkg-config --cflags libub-1.0`

Symptom:

When LibUsb library is not found by the compiler.

Solution:

Use 'pkg-config --libs libusg-1.0' to figure out '-lusb-1.0'

\$ gcc source.c `pkg-config --libs libub-1.0`

Symptom:

When LibUsb header and library are not found by the compiler.

Solution:

Use 'pkg-config --libs --cflags libusg-1.0' to figure out '-l/path-to-libusb.h' and '-lusb-1.0

\$ gcc source.c `pkg-config --libs --cflags libub-1.0`

6.3 libconapi problem

Symptom:

When 'conapi.h' header is not found by the compiler.

Solution 1:

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Add the directory 'conapi.h' residing to 'C_INCLUDE_PATH' and 'CPLUS_INCLUDE_PATH' environment variable or simply run 'settings.sh' in the CON-FMC installation directory

\$ source /opt/confmc/2019.02/settings.sh

where '/opt/confmc/2019.02' is an example and it should be the directory where CON-FMC package is installed.

Solution 2:

Specify the directory 'conapi.h' residing with '-l' option of compiler

\$ gcc ... -I /opt/confmc/2019.02/include ...

where '/opt/confmc/2019.02' is an example and it should be the directory where CON-FMC package is installed.

Symptom:

When 'libconapi' library is not found by the compiler.

error while loading shared libraries: libconapi.so: cannot open shared object file: No such file or directory

Solution 1:

Add the directory 'libconapi.so' residing to 'LD_LIBRARY_PATH' environment variable or simply run 'settings.sh' in the CON-FMC installation directory

\$ source /opt/confmc/2019.02/settings.sh

where '/opt/confmc/2019.02' is an example and it should be the directory where CON-FMC package is installed.

Solution 2::

Specify the directory 'libconapi.so' residing using '-L' and '-l' options of compiler whiling linking stage

\$ gcc ... -L /opt/confmc/2019.02/lib/linux_x86_64 -lconapi

where '/opt/confmc/2019.02/lib/linux_x86_64' is an example and it should be the directory where CON-FMC package is installed.

6.4 Problems while connection or using CON-FMC

Refer to 'Trouble shooting' section in the reference [3].

7 References

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Revision history

- $\hfill\square$ 2019.04.10: Adding more cases in the 'Trouble shooting' section.
- ☐ 2019.02.09: Updated
- □ 2018.03.10: Started by Ando Ki (adki@future-ds.com)
- End of document -