Digital Image Fundamentals

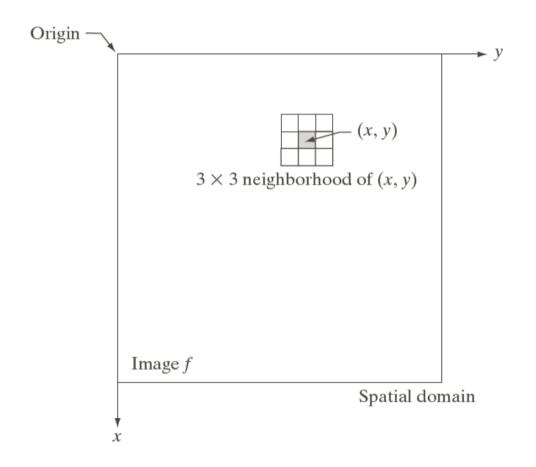
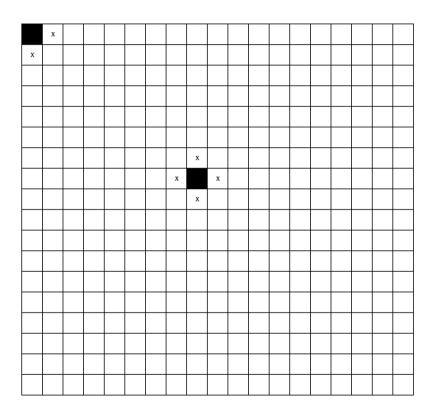


FIGURE 3.1

A 3×3 neighborhood about a point (x, y) in an image in the spatial domain. The neighborhood is moved from pixel to pixel in the image to generate an output image.

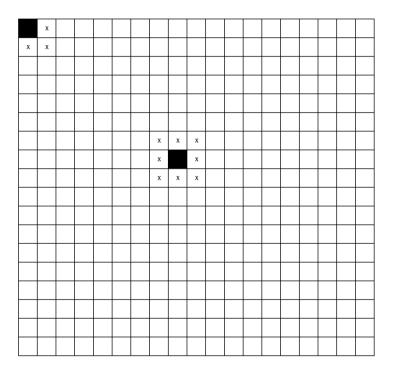
Neighborhood

4-Neighborhood



	(x,y-1)	
(x-1,y)	p (x, y)	(x+1,y)
	(x,y+1)	

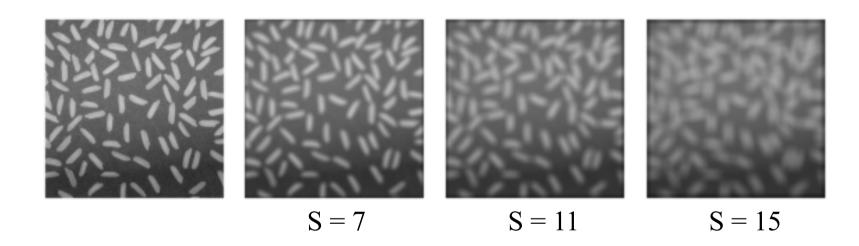
8-Neighborhood



(x-1,y-1)	(x, y - 1)	(x+1,y-1)
(x-1,y)	p (x, y)	(x+1,y)
(x-1,y+1)	(x, y + 1)	(x+1,y+1)

Average filter

For each pixel (x,y), the intensity is the average value of its 7,11,15-neighborhood.



Affine Transformation

[x y 1] = [v w 1] * T

TABLE 2.2 Affine transformations based on Eq. (2.6.–23).

Transformation Name	Affine Matrix, T	Coordinate Equations	Example
Identity	$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$	x = v $y = w$	y x
Scaling	$\begin{bmatrix} c_x & 0 & 0 \\ 0 & c_y & 0 \\ 0 & 0 & 1 \end{bmatrix}$	$x = c_x v$ $y = c_y w$	
Rotation	$\begin{bmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$	$x = v \cos \theta - w \sin \theta$ $y = v \cos \theta + w \sin \theta$	
Translation	$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ t_x & t_y & 1 \end{bmatrix}$	$x = v + t_x$ $y = w + t_y$	
Shear (vertical)	$\begin{bmatrix} 1 & 0 & 0 \\ s_v & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$	$x = v + s_v w$ $y = w$	
Shear (horizontal)	$\begin{bmatrix} 1 & s_h & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$	$x = v$ $y = s_h v + w$	