Exploring Parameter Estimation Techniques for HIV Modeling: From Simulation Data to Real-world Applications

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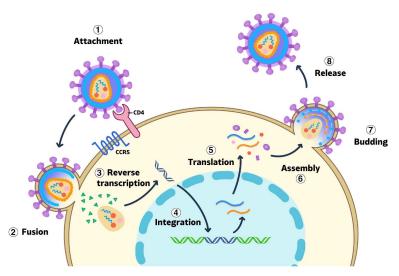
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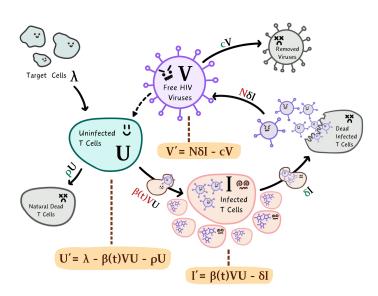
Introduction

- The role of CD4+T cells is to activate immune cells.
- HIV replicates in CD4+T and continually infects others.
- We evaluate the activity status of virus by monitoring the quantity of CD4+T.

Action Process



Schematic



Basic model

$$\begin{split} \frac{\mathrm{d}\mathbf{U}}{\mathrm{d}\mathbf{t}} &= \lambda - \beta(\mathbf{t})\mathbf{V}\mathbf{U} - \rho\mathbf{U}, \\ \frac{\mathrm{d}\mathbf{I}}{\mathrm{d}\mathbf{t}} &= \beta(\mathbf{t})\mathbf{V}\mathbf{U} - \delta\mathbf{I}, \\ \frac{\mathrm{d}\mathbf{V}}{\mathrm{d}\mathbf{t}} &= \mathbf{N}\delta\mathbf{I} - \mathbf{c}\mathbf{V}. \end{split}$$

Symbol	Description	Initial Value
U	Density of susceptible target cells	$U_0 = 600 \text{ cells } \cdot \mu L^{-1}$
I	Density of cells infected by the virus	$I_0 = 30 \text{ cells } \cdot \mu L^{-1}$
V	Density of free viruses	$V_0 = 10^5 \text{ copies } \cdot \text{mL}^{-1}$
β	Infection rate of target cells by free viruses	$\beta_0 = 9 \times 10^{-6} \text{mL} \cdot \text{copies}^{-1} \cdot \text{day}^{-1}$
λ	Production rate of target cells	36 cells $\cdot \mu L^{-1} \cdot day^{-1}$
ρ	Death rate of uninfected target cells	0.108 day^{-1}
δ	Death rate of target cells	$0.5 \mathrm{day^{-1}}$
N	Number of virions produced from each infected cell	$10^3 \text{ copies } \cdot \mu \text{L} \cdot \text{cell}^{-1} \cdot \text{mL}^{-1}$
c	Clearance rate of virus	3 day^{-1}

Nonautonomous system

$$\begin{split} \frac{\mathrm{d}\mathbf{U}}{\mathrm{d}\mathbf{t}} &= \lambda - \beta(\mathbf{t})\mathbf{V}\mathbf{U} - \rho\mathbf{U}, \\ \frac{\mathrm{d}\mathbf{I}}{\mathrm{d}\mathbf{t}} &= \beta(\mathbf{t})\mathbf{V}\mathbf{U} - \delta\mathbf{I}, \\ \frac{\mathrm{d}\mathbf{V}}{\mathrm{d}\mathbf{t}} &= \mathbf{N}\delta\mathbf{I} - \mathbf{c}\mathbf{V}. \end{split}$$

Equilibria

$$E^* = (U^*, I^*, V^*) = \left(\frac{c}{\beta N}, (\mathcal{R}_0 - 1) \frac{\rho c}{\beta \delta N}, (\mathcal{R}_0 - 1) \frac{\rho}{\beta}\right), \text{ where } \mathcal{R}_0 = \frac{\beta \lambda N}{\rho c}$$

[Perelson et al., 1996]



β system

$$\beta(t) = a(1 - d\cos(bt)), \quad a = 9 \times 10^{-5}, \quad b = \frac{\pi}{1000}, \quad d = 0.9$$

$$\beta'(t) = abd * \sin(bt)$$

$$\beta''(t) = ab^2 d(\cos(bt)) = ab^2 d(1 - \frac{\beta(t)}{a})$$

β system change to ω system

$$\omega_1(t) = \beta(t) = a(1 - d * \cos(bt)),$$
 $\omega_1(0) = 9 \times 10^{-6}$
 $\omega'_1 = \omega_2 = \beta'(t) = abd * \sin(bt),$ $\omega_2(0) = 0$
 $\omega'_2 = \beta''(t) = ab^2d(1 - \frac{\omega_1}{a})$

Autonomous system

$$U' = \lambda - \omega_1 VU - \rho U,$$

$$I' = \omega_1 VU - \delta I,$$

$$I' = \lambda VU - \delta I,$$

$$V' = N\delta I - cV,$$

$$\omega'_1 = \omega_2,$$

 $\omega'_2 = \omega''_1 = ab^2 d \left(1 - \frac{\omega_1}{a}\right),$

$$U(0) = 600,$$

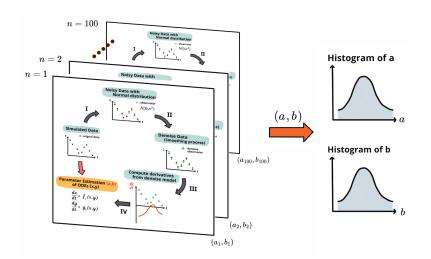
$$I(0) = 30,$$

$$V(0) = 10^5,$$

$$\omega_1(0) = 9 \times 10^{-6},$$

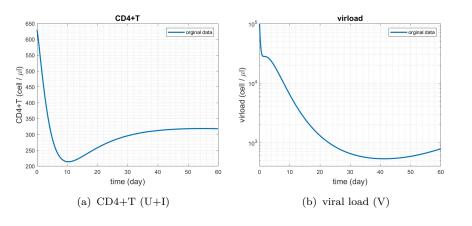
$$\omega_2(0)=0.$$

Flow Chart

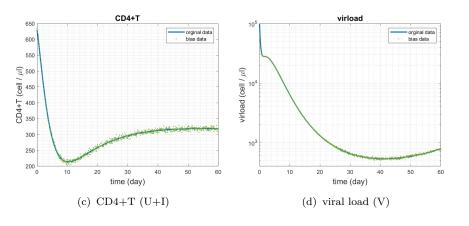


Flow chart with $N(0, \sigma^2)$.

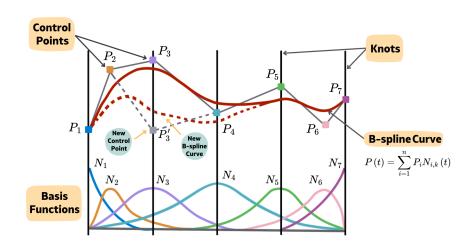
Simulation (original data)



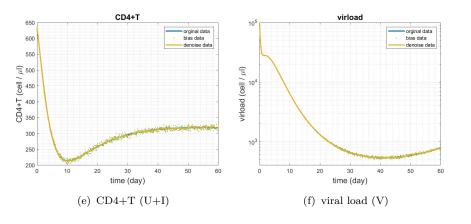
Simulation (bias data)



B-spline



Simulation (denoise data)



Parameter Estimation

Least Square Method

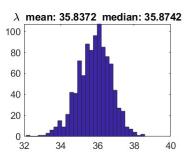
$$\begin{split} \frac{dT}{dt} &= \lambda - \rho(T-I) - \delta I, \\ \frac{dV}{dt} &= a_0 + a_1 T(t) + a_2 T'(t) - cV(t), \end{split}$$

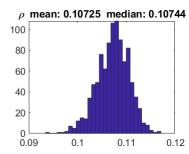
where
$$a_0 = -\frac{N\delta\lambda}{\rho - \delta}$$
, $a_1 = \frac{N\delta\rho}{\rho - \delta}$, $a_2 = \frac{N\delta}{\rho - \delta}$.

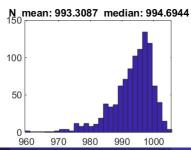
$$\frac{\mathrm{d} U}{\mathrm{d} t} = \lambda - \beta(t) V U - \rho U, \ \frac{\mathrm{d} I}{\mathrm{d} t} = \beta(t) V U - \delta, \ \frac{\mathrm{d} V}{\mathrm{d} t} = N \delta I - c V.$$

$$\begin{bmatrix} \vdots & \vdots & \vdots \\ 1 & T & T' \\ \vdots & \vdots & \vdots \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} \vdots \\ V' + CV \\ \vdots \end{bmatrix}$$

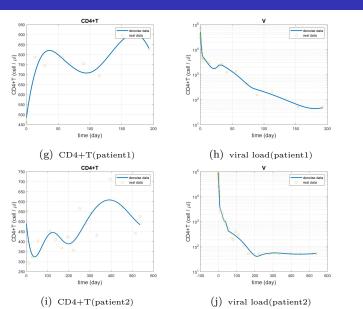
Histogram of Parameter Estimations







Real data



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Thank you for listening!