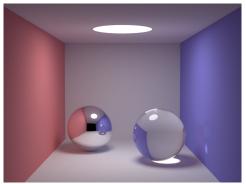
Optimizing smallpt

Davean Scies, Siddharth Bhat

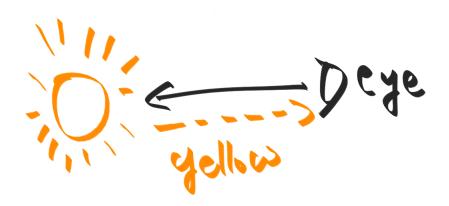
Haskell Exchange

November 4th, 2020

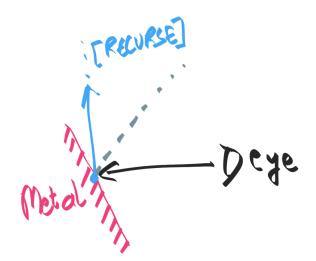


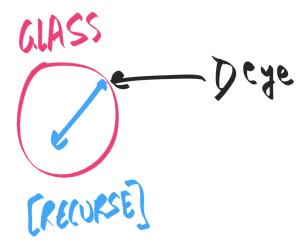
- ▶ 99 LoC C++: small path tracer.
- Ported to many languages, including Haskell! (Thanks to Vo Minh Thu/noteed).
- Start from noteed's original source; SHA the output image from the Haskell source for baseline.

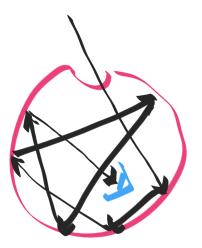












- When to end recursion?
- Choose to end recursion randomly after some large number of rounds
- "Russian Roulette"

- ► Recursive (recursively send more light rays)
- ▶ Branching (hit an object? is it a light source? what material?)
- ▶ Number crunching (reflection, refraction, sphere-ray-intersection)
- Randomness (when do we stop a light ray)

```
struct Vec {
 double x, y, z; // position, also color (r,q,b)
  ... methods...
}:
struct Ray { Vec o, d; Ray(Vec o_, Vec d_) : o(o_), d(d_) {} };
enum Refl_t { DIFF, SPEC, REFR }; // material types, used in radiance()
struct Sphere {
 double rad; // radius
 Vec p, e, c; // position, emission, color
 Refl_t refl; // reflection type (DIFFuse, SPECular, REFRactive)
  ... methods ...
 double intersect(const Ray &r) const // returns distance, 0 if nohit
};
Sphere spheres[] = {//Scene: radius, position, emission, color, material
  Sphere(1e5, Vec(1e5+1,40.8,81.6), Vec(), Vec(.75,.25,.25), DIFF), //Left
  ... initialization ...
};
```

```
Vec radiance(const Ray &r, int depth, unsigned short *Xi){
```

```
Vec radiance(const Ray &r, int depth, unsigned short *Xi){
                          radiance
                          radiance
                          radiance
    radiance
                                  radiance
    radiance
                                  radiance
```

```
Vec radiance(const Ray &r, int depth, unsigned short *Xi){
 if ( ) if (
                                            else
 if (
                    ){
                        radiance
 } else if (
                        radiance
 if (
                                   )
                        radiance
   radiance
                                radiance
   radiance
                                radiance
```

```
Vec radiance(const Ray &r, int depth, unsigned short *Xi){
 Vec x=r.o+r.d*t, n=(x-obj.p).norm(), nl=n.dot(r.d)<0?n:n*-1, f=obj.c;</pre>
 if ( ) if (
                                           else
 if (
                 ) {
                        radiance
 } else if (
                        radiance
  if ((cos2t=1-nnt*nnt*(1-ddn*ddn))<0)
                        radiance
   radiance
                                radiance
   radiance
                                radiance
```

```
Vec radiance(const Ray &r, int depth, unsigned short *Xi){
 Vec x=r.o+r.d*t, n=(x-obj.p).norm(), nl=n.dot(r.d)<0?n:n*-1, f=obj.c;
 if (
              ) if (erand48(Xi) )
                                             else
 if (
                     ) {
                    erand48(Xi) erand48(Xi)
                         radiance
 } else if (
                         radiance
  if ((cos2t=1-nnt*nnt*(1-ddn*ddn))<0)
                         radiance
                                  erand48(Xi)
   radiance
                                 radiance
   radiance
                                 radiance
```

```
Vec radiance(const Ray &r, int depth, unsigned short *Xi){
 double t;
                                         // distance to intersection
 int id=0:
                                         // id of intersected object
 if (!intersect(r, t, id)) return Vec(); // if miss, return black
 const Sphere &obi = spheres[id]:
                                    // the hit object
 Vec x=r.o+r.d*t, n=(x-obj.p).norm(), nl=n.dot(r.d)<0?n:n*-1, f=obj.c;
 double p = f.x > f.y && f.x > f.z ? f.x : f.y > f.z ? f.y : f.z : // max refl
 if (++depth>5) if (erand48(Xi)<p) f=f*(1/p); else return obj.e; //R.R.
 if (obj.refl == DIFF){
                                         // Ideal DIFFUSE reflection
   double r1=2*M PI*erand48(Xi), r2=erand48(Xi), r2s=sqrt(r2);
   Vec w=n1, u=((fabs(w.x)>.1?Vec(0,1):Vec(1))\%w).norm(), v=w\%u;
   Vec d = (u*cos(r1)*r2s + v*sin(r1)*r2s + w*sgrt(1-r2)).norm();
   return obj.e + f.mult(radiance(Ray(x,d),depth,Xi));
 } else if (obi.refl == SPEC)
                                 // Ideal SPECULAR reflection
   return obj.e + f.mult(radiance(Ray(x,r.d-n*2*n.dot(r.d)),depth,Xi));
 Ray reflRay(x, r.d-n*2*n.dot(r.d)): // Ideal dielectric REFRACTION
 bool into = n.dot(n1)>0;
                                        // Ray from outside going in?
 double nc=1, nt=1.5, nnt=into?nc/nt:nt/nc, ddn=r,d,dot(n1), cos2t;
 if ((cos2t=1-nnt*nnt*(1-ddn*ddn))<0)
                                       // Total internal reflection
   return obj.e + f.mult(radiance(reflRav.depth.Xi));
 Vec tdir = (r.d*nnt - n*((into?1:-1)*(ddn*nnt+sqrt(cos2t)))).norm();
 double a=nt-nc, b=nt+nc, R0=a*a/(b*b), c = 1-(into?-ddn:tdir.dot(n));
 double Re=R0+(1-R0)*c*c*c*c*c*.Tr=1-Re.P=.25+.5*Re.RP=Re/P.TP=Tr/(1-P):
 return obj.e + f.mult(depth>2 ? (erand48(Xi) < P ? // Russian roulette
   radiance(reflRav.depth.Xi)*RP:radiance(Rav(x,tdir),depth,Xi)*TP) :
   radiance(reflRay,depth,Xi)*Re+radiance(Ray(x,tdir),depth,Xi)*Tr);
}
```

Initial Haskell Code: radiance $(1\times)$

```
radiance :: Ray -> CInt -> Ptr CUShort -> IO Vec
radiance ray@(Ray o d) depth xi = case intersects ray of
  (Nothing,_) -> return zerov
  (Just t, Sphere _r p e c refl) -> do
        continue f = case refl of - BRANCHING
          DIFF -> do
            r1 <- ((2*pi)*) 'fmap' erand48 xi -- RNG
                   radiance
          SPEC -> do
            rad <- radiance -- RECURSION
          REFR -> do
            if
              then do
                rad <- radiance
```

Initial Haskell Code: Data structures

```
data Vec = Vec {-# UNPACK #-} !Double {-# UNPACK #-} !Double

cross :: Vec -> Vec -> Vec
(.*) :: Vec -> Double -> Vec
infixl 7 .*
len :: Vec -> Double
norm :: Vec -> Vec
norm v = v .* recip (len v)
dot :: Vec -> Vec -> Double
maxv :: Vec -> Double
data Ray = Ray Vec Vec -- origin, direction
data Refl = DIFF | SPEC | REFR -- material types, used in radiance
-- / radius, position, emission, color, reflection
data Sphere = Sphere Double Vec Vec Refl
```

Initial Haskell Code: scene data

Initial Haskell code: Sphere intersection

```
intersect :: Ray -> Sphere -> Maybe Double
intersect (Ray o d) (Sphere r p _e _c _refl) =
  if det<0 then Nothing else f (b-sdet) (b+sdet)
  where op = p - o -- Numeric
        eps = 1e-4
        b = dot op d
        det = b*b - dot op op + r*r -- Numeric
        sdet = sqrt det
        f a s = if a>eps then Just a else if s>eps then Just s else Nothing
intersects :: Ray -> (Maybe Double, Sphere)
intersects ray = (k, s)
  where (k,s) = foldl' f (Nothing, undefined) spheres -- Spheres iterated over
        f(k',sp) s' = case(k',intersect ray s') of
                  (Nothing, Just x) -> (Just x,s')
                  (Just y, Just x) \mid x < y \rightarrow (Just x,s')
                  _ -> (k',sp)
```

Initial Haskell Code: radiance $(1\times)$

```
radiance :: Ray -> CInt -> Ptr CUShort -> IO Vec
radiance ray@(Ray o d) depth xi = case intersects ray of
  (Nothing,_) -> return zerov
 (Just t, Sphere _r p e c refl) -> do
    let x = o 'addv' (d 'mulvs' t)
       n = norm $ x `subv` p
       nl = if n 'dot' d < 0 then n else n 'mulvs' (-1)
       pr = maxv c
        depth' = depth + 1
        continue f = case refl of
         DIFF -> do
           r1 <- ((2*pi)*) 'fmap' erand48 xi
            r2 <- erand48 xi
            let r2s = sqrt r2
                w@(Vec wx _ _ ) = n1
               u = norm $ (if abs wx > 0.1 then (Vec 0 1 0) else (Vec 1 0 0)) `cross` w
                v = w 'cross' n
                d' = norm $ (u'mulvs'(cos r1*r2s)) 'addv' (v'mulvs'(sin r1*r2s)) 'addv' (w'mulvs'sqrt (1-r2))
            rad <- radiance (Ray x d') depth' xi
            return $ e 'addy' (f 'muly' rad)
          SPEC -> do
            let d' = d `subv` (n `mulvs` (2 * (n`dot`d)))
            rad <- radiance (Rav x d') depth' xi
            return $ e 'addv' (f 'mulv' rad)
          REFR -> do
           let reflRay = Ray x (d `subv` (n `mulvs` (2* n`dot`d)))
                into = n'dot'n1 > 0
                nc = 1
                nt = 1.5
                nnt = if into then nc/nt else nt/nc
               ddn= d'dot'nl
                cos2t = 1-nnt*nnt*(1-ddn*ddn)
            if cos2t<0
              then do
                rad <- radiance reflRav depth' xi
```

Initial Haskell Code: Entry point $(1\times)$

```
smallpt :: Int -> Int -> Int -> IO ()
smallpt w h nsamps = do
  c <- VM.replicate (w * h) 0
  allocaArray 3 \xi -> -- Create mutable memory
    flip mapM_ [0..h-1] $ \y -> do -- Loop
      writeXi xi y
      for_ [0..w-1] \ x \rightarrow do -- Loop
        let i = (h-v-1) * w + x
        for_ [0..1] \sy -> do -- Loop
          for_ [0..1] \sx -> do -- Loop
            r <- newIORef 0 -- Create mutable memory
            for_ [0..samps-1] \_s -> do -- Loops, Loops
              r1 <- (2*) <$> erand48 xi
              . . .
              rad <- radiance (Ray (org+d.*140) (norm d)) 0 xi -- Crunch
              modifyIORef r (+ rad .* recip (fromIntegral samps)) -- Write
            ci <- VM.unsafeRead c i
            Vec rr rg rb <- readIORef r
            VM.unsafeWrite c i $
                ci + Vec (clamp rr) (clamp rg) (clamp rb) .* 0.25 -- Write
```

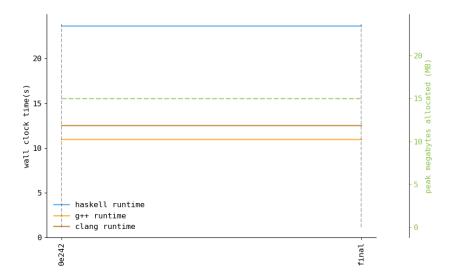
Initial Haskell Code: File I/O $(1\times)$

```
withFile "image.ppm" WriteMode $ \hdl -> do
hPrintf hdl "P3\n%d %d\n%d\n" w h (255::Int)
flip mapM_ [0..w*h-1] \i -> do
    Vec r g b <- VM.unsafeRead c i
    hPrintf hdl "%d %d %d " (toInt r) (toInt g) (toInt b)</pre>
```

Initial Haskell Code: RNG $(1\times)$

```
foreign import ccall unsafe "erand48"
  erand48 :: Ptr CUShort -> IO Double
```

Performance: Initial Haskell Code



Restrict export list to main $(1.13\times)$

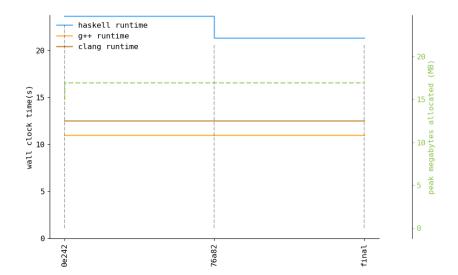
-module Main where +module Main (main) where

Restrict export list to main $(1.13\times)$

```
-module Main where
+module Main (main) where
```

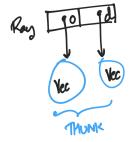
- Exported functions could be used by something unknown.
- Original versions must be available.

Performance: Restrict export list to main $(1.13\times)$



Mark entries of Ray and Sphere as UNPACK and Strict $(1.07 \times)$

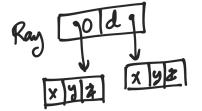
data Ray = Ray Vec Vec

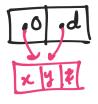


- By default, all fields are thunks to rest of computation
- Pure, allow equational reasoning.

Mark entries of Ray and Sphere as UNPACK and Strict $(1.07 \times)$

data Ray = Ray !Vec !Vec





- ▶ When strict, elements are *pointers* to known structures
- pointers enable sharing!

Mark entries of Ray and Sphere as UNPACK and Strict $(1.07\times)$

data Ray = Ray
$$\{-\#\ UNPACK\ \#-\}\ !Vec\ \{-\#\ UNPACK\ \#-\}\ !Vec$$

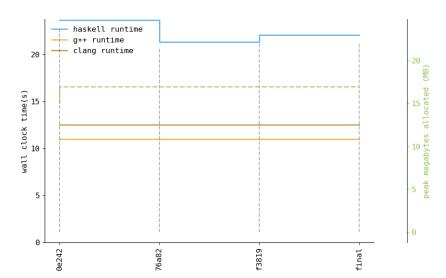


- ▶ When unpacked, elements are *members* of the parent.
- Larger, but eliminate pointer chasing.

Mark entries of Ray and Sphere as UNPACK and Strict $(1.07 \times)$

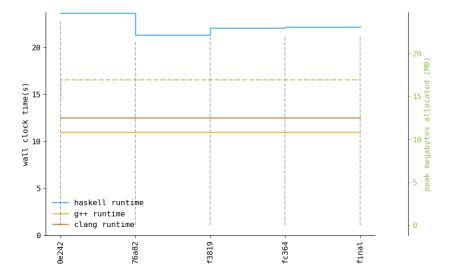
```
data Vec = Vec {-# UNPACK #-} !Double
              {-# UNPACK #-} !Double
              {-# UNPACK #-} !Double
-data Ray = Ray Vec Vec -- origin, direction
+data Rav = Rav !Vec !Vec -- origin, direction
data Refl = DIFF | SPEC | REFR -- material types, used in radiance
-- radius, position, emission, color, reflection
-data Sphere = Sphere Double Vec Vec !Refl
+data Sphere = Sphere {-# UNPACK #-} !Double
                     {-# UNPACK #-} !Vec
                     {-# UNPACK #-} !Vec
                      {-# UNPACK #-} !Vec !Refl
struct Vec { double x, y, z; }
struct Ray { std::function<Vec()> v; std::function<Vec()> w; };
struct RayUnpack { double xv, yv, int zv;
                  double xw, yw, zw; };
```

Performance: Mark entries of Ray and Sphere as UNPACK and Strict $(1.07\times)$



Use a pattern synonym to unpack Refl in Sphere $(1.07\times)$

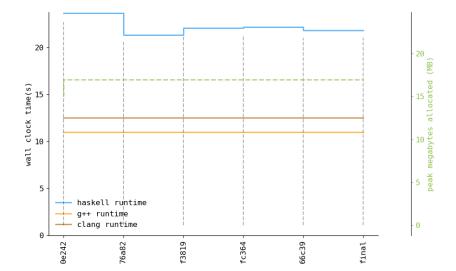
Performance: Use a pattern synonym to unpack Refl in Sphere $(1.07 \times)$



Change from maximum on a list to max $(1.08\times)$

```
-maxv (Vec a b c) = maximum [a,b,c]
+maxv (Vec a b c) = max a (max b c)
     let x = o `addv` (d `mulvs` t)
         n = norm $ x `subv` p
         nl = if n `dot` d < 0 then n else n `mulvs` (-1)</pre>
         pr = maxv c
         depth' = depth + 1
         continue f = case refl of
           DIFF -> do
. . .
     if depth'>5
       then do
         er <- erand48 xi
        let !pr = maxv c
```

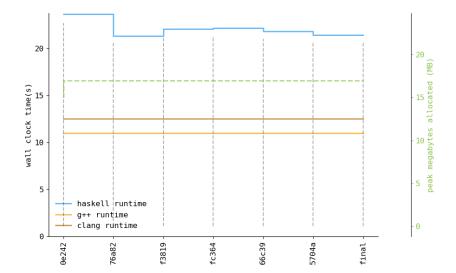
Performance: Change from maximum on a list to max $(1.08 \times)$



Convert erand48 to pure Haskell $(1.10\times)$

```
-foreign import ccall unsafe "erand48"
- erand48 :: Ptr CUShort -> IO Double
+erand48 :: IORef Word64 -> IO Double
+erand48 !t = do -- | Some number crunchy thing.
+ r <- readIORef t
+ let x' = 0x5deece66d * r + 0xb
      d_word = 0x3ff000000000000 .|. ((x' .&. 0xfffffffffff) `unsafeShiftL` 4)
      d = castWord64ToDouble d word - 1.0
+ writeIORef t x'
+ pure d
-radiance :: Ray -> CInt -> Ptr CUShort -> IO Vec
+radiance :: Ray -> Int -> IORef Word64 -> IO Vec -- IORef with state
radiance ray@(Ray o d) depth xi = case intersects ray of
   . . .
  c <- VM.replicate (w * h) zerov
- allocaArray 3 $ \xi -> -- Old RNG state
      flip mapM [0..h-1] $ \v -> do
+ xi <- newTORef O -- New RNG state
+ flip mapM_ [0..h-1] $ \y -> do
      writeXi xi y
```

Performance:Convert erand48 to pure Haskell (1.10×)



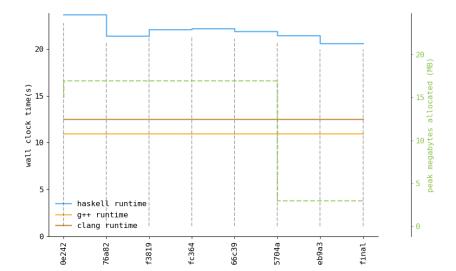
Remove mutability: Erand48 Monad $(1.15\times)$

```
-erand48 :: IORef Word64 -> IO Double
-erand48 !t = do
- r <- readIORef t
+data ET a = ET !Word64 !a deriving Functor
+newtype Erand48 a = Erand48 { runErand48' :: Word64 -> ET a } deriving Functor
+instance Applicative Erand48 where
+instance Monad Erand48 where
+runWithErand48 :: Int -> Erand48 a -> a
+erand48 :: Erand48 Double
-radiance :: Ray -> Int -> IORef Word64 -> IO Vec
-radiance ray@(Ray o d) depth xi = case intersects ray of
+radiance :: Ray -> Int -> Erand48 Vec
+radiance rav@(Rav o d) depth = case intersects rav of
. . .
            r1 <- (2*pi*) <$> erand48 xi
           r2 <- erand48 xi
            r1 <- (2*pi*) <$> erand48
            r2 <- erand48
                               then (.* rp) <$> radiance reflRay depth' xi
                               else (.* tp) <$> radiance (Ray x tdir) depth' xi
                               then (.* rp) <$> radiance reflRav depth'
                               else (.* tp) <$> radiance (Ray x tdir) depth'
```

Remove mutability: eliminate IORef and Data. Vector. Mutable $(1.15\times)$

```
- c <- VM.replicate (w * h) 0
- xi <- newIORef 0
   flip mapM_ [0..h-1] $ \y -> do
       writeXi xi y
       for_ [0..w-1] \x -> do
         let i = (h-y-1) * w + x
         for_ [0..1] \sy -> do
           for_ [0..1] \sx -> do
             r <- newINRef 0
             for [0..samps-1] \setminus s \rightarrow do
               r1 <- (2*) <$> erand48 xi
       img = (`concatMap` [(h-1), (h-2)..0]) $\y -> runWithErand48 y do
+
         for [0..w-1] \ x \rightarrow do
           (pf -> foldlM pf 0 [(sy, sx) | sy <- [0,1], sx <- [0,1]]) \ci (sy, sx) -> do
+
             Vec rr rg rb <- (\f -> foldlM f 0 [0..samps-1]) \ !r _s -> do
               r1 <- (2*) < $> erand 48
. . .
               modifyIORef r (+ rad .* recip (fromIntegral samps))
             ci <- VM.unsafeRead c i
             Vec rr rg rb <- readIORef r
             VM.unsafeWrite c i $ ci + Vec (clamp rr) (clamp rg) (clamp rb) .* 0.25
               pure (r + rad .* recip (fromIntegral samps))
             pure (ci + Vec (clamp rr) (clamp rg) (clamp rb) .* 0.25)
. . .
```

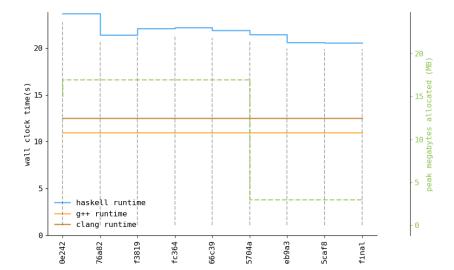
Performance: Remove mutability $(1.15 \times)$



Set everything in smallpt to be strict $(1.15\times)$

```
smallpt :: Int -> Int -> Int -> IO ()
smallpt w h nsamps = do
- let samps = nsamps `div` 4
      org = Vec 50 52 295.6
      dir = norm \$ Vec 0 (-0.042612) (-1)
      cx = Vec (fromIntegral w * 0.5135 / fromIntegral h) 0 0
      cy = norm (cx `cross` dir) `mulvs` 0.5135
  let !samps = nsamps `div` 4
       !org = Vec 50 52 295.6
       !dir = norm \$ Vec 0 (-0.042612) (-1)
+
       !cx = Vec (fromIntegral w * 0.5135 / fromIntegral h) 0 0
       !cv = norm (cx `cross` dir) `mulvs` 0.5135
- r1 <- (2*) `fmap` erand48 xi
- let dx = if r1<1 then sqrt r1-1 else 1-sqrt(2-r1)
- r2 <- (2*) `fmap` erand48 xi
- let dy = if r2<1 then sqrt r2-1 else 1-sqrt(2-r2)
      d = ...
- rad <- radiance (Ray (org'addv'(d'mulvs'140)) (norm d)) 0 xi
+ !r1 <- (2*) `fmap` erand48 xi
+ let !dx = if r1<1 then sqrt r1-1 else 1-sqrt(2-r1)
+ !r2 <- (2*) `fmap` erand48 xi
+ let !dv = if r2<1 then sart r2-1 else 1-sart(2-r2)
+ !d = ...
. . .
               pure $! r + rad .* recip (fromIntegral samps)
             pure $! ci + Vec (clamp rr) (clamp rg) (clamp rb) .* 0.25
```

Performance: Set everything in smallpt to be strict $(1.15\times)$



Why strictness may be bad

```
let foo = let x = error "ERR" in \y -> y let foo0pt = \y -> y
```

Why strictness may be bad

```
let foo = let x = error "ERR" in \y -> y
let fooOpt = \y -> y
let foo' = let !x = error "ERR" in \y -> y
```

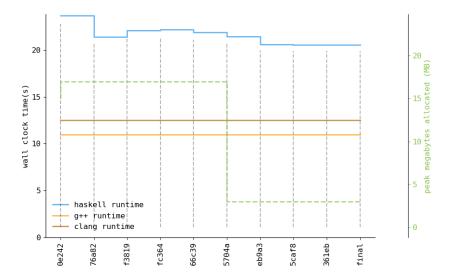
Why strictness may be bad

```
let foo = let x = error "ERR" in \y -> y
let fooOpt = \y -> y
let foo' = let !x = error "ERR" in \y -> y
let foo'Opt = \y -> y -- ERROR! forcing foo'=foo'Opt should give "ERR"
```

Reduce to only useful strictnesses in smallpt $(1.15\times)$

```
let !samps = nsamps `div` 4
       !org = Vec 50 52 295.6
       !dir = norm \$ Vec 0 (-0.042612) (-1)
       !cx = Vec (fromIntegral w * 0.5135 / fromIntegral h) 0 0
       !cy = norm (cx `cross` dir) .* 0.5135
   let samps = nsamps `div` 4
       org = Vec 50 52 295.6
+
       dir = norm \$ Vec 0 (-0.042612) (-1)
       cx = Vec (fromIntegral w * 0.5135 / fromIntegral h) 0 0
+
       cv = norm (cx `cross` dir) .* 0.5135
+
. . .
               !r1 <- (2*) <$> erand48
               r1 <- (2*) < $> erand 48
. . .
               !r2 <- (2*) < $> erand 48
               r2 <- (2*) <$> erand48
. . .
               !rad <- radiance (Ray (org+d.*140) (norm d)) 0
               rad <- radiance (Ray (org+d.*140) (norm d)) 0
. . .
               pure $! r + rad .* recip (fromIntegral samps)
             pure $! ci + Vec (clamp rr) (clamp rg) (clamp rb) .* 0.25
               pure (r + rad .* recip (fromIntegral samps))
             pure (ci + Vec (clamp rr) (clamp rg) (clamp rb) .* 0.25)
                                                      4□ > 4個 > 4 = > 4 = > = 900
```

Performance: Reduce to only useful strictnesses in smallpt $(1.15\times)$

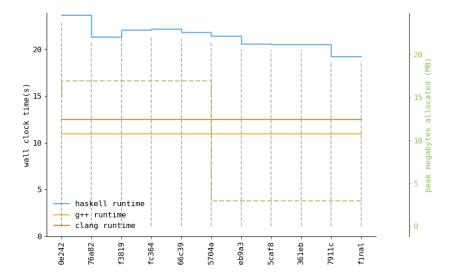


Strategic application of strictness in entire project $(1.23\times)$

```
. . .
- if det<0 then Nothing else f (b-sdet) (b+sdet)
- where op = p - o
    eps = 1e-4
  b = dot op d
 det = b*b - dot op op + r*r
 sdet = sqrt det
        f a s = if a>eps then Just a else if s>eps then Just s else Nothing
+ if det<0
+ then Nothing
  else
    let !eps = 1e-4
      !sdet = sgrt det
     !a = b-sdet
       !s = b+sdet
   in if a>eps then Just a else if s>eps then Just s else Nothing
```

. . .

Performance: Strategic application of strictness in entire project $(1.23\times)$

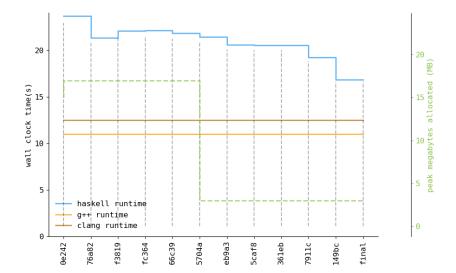


Remove Maybe from intersect(s) $(1.40\times)$

```
| Old: Use Maybe Double to represent (was-hit?:bool, hit-distance: Double)
| New: use (1/0) to represent not (was-hit?)
-intersect :: Ray -> Sphere -> Maybe Double
+intersect :: Rav -> Sphere -> Double
intersect (Ray o d) (Sphere r p _e _c _refl) =
- if det<0 then Nothing else f (b-sdet) (b+sdet)
+ if det<0 then (1/0.0) else f (b-sdet) (b+sdet)
   where op = p `subv` o
         f a s = if a>eps then Just a else if s>eps then Just s else Nothing
        f a s = if a>eps then a else if s>eps then s else (1/0.0)
-intersects :: Ray -> (Maybe Double, Sphere)
+intersects :: Ray -> (Double, Sphere)
 intersects ray = (k, s)
- where (k,s) = foldl' f (Nothing, undefined) spheres
         f (k',sp) s' = case (k',intersect ray s') of
                   (Nothing, Just x) -> (Just x,s')
                   (Just y, Just x) \mid x < y \rightarrow (Just x,s')
                   _ -> (k',sp)
+ where (k,s) = foldl' f (1/0.0,undefined) spheres
         f (k', sp) s' = let !x = intersect ray s' in if x < k' then (x, s') else (k', sp)
 radiance :: Ray -> Int -> STRefU s Word64 -> ST s Vec
 radiance ray@(Ray o d) depth xi = case intersects ray of
- (Nothing, ) -> return zerov
- (Just t,Sphere _r p e c refl) -> do
+ (t,_) | t == (1/0.0) -> return zerov
+ (t,Sphere _r p e c refl) -> do
```

4 D > 4 P > 4 B > 4 B > B 9 Q P

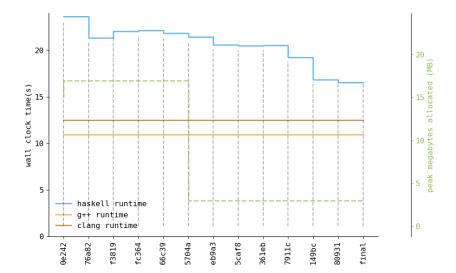
Performance: Remove Maybe from intersect(s) $(1.40\times)$



Hand unroll the fold in intersects $(1.43\times)$

```
intersects :: Ray -> (Double, Sphere)
-intersects ray = (k, s)
- where (k,s) = foldl' f (1/0.0, undefined) spheres
+intersects ray =
+ f (... (f (f (intersect ray sphLeft, sphLeft) sphRight) ...)
+ where
    f(k', sp) s' = let !x = intersect ray s' in if <math>x < k' then (x, s') else (k', sp)
-spheres :: [Sphere]
-spheres = let s = Sphere ; z = zerov ; (.*) = mulvs ; v = Vec in
- [ s 1e5 (v (1e5+1) 40.8 81.6) z (v 0.75 0.25 0.25) DIFF --Left
- , s 1e5 (v (-1e5+99) 40.8 81.6) z (v 0.25 0.25 0.75) DIFF --Rght
. . .
+sphLeft, sphRight, ... :: Sphere
+sphLeft = Sphere 1e5 (Vec (1e5+1) 40.8 81.6) zerov (Vec 0.75 0.25 0.25) DIFF
+sphRight = Sphere 1e5 (Vec (-1e5+99) 40.8 81.6) zerov (Vec 0.25 0.25 0.75) DIFF
. . .
```

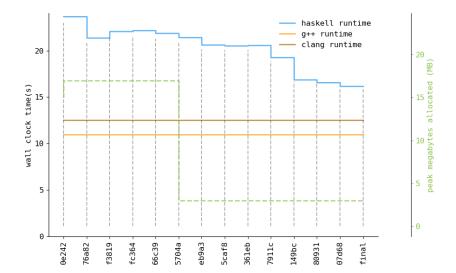
Performance: Hand unroll the fold in intersects (1.43×)



Custom datatype for intersects parameter passing $(1.46\times)$

```
Old: Tuple with possibly-uenevaluated Double and Sphere
New: Reference to a guaranteed-to-be-evaluated Double and Sphere
-intersects :: Ray -> (Double, Sphere)
+data T = T !Double !Sphere
+intersects :: Rav -> T
intersects rav =
- f ( ... f (intersect ray sphLeft, sphLeft) sphRight) ... sphLite
+ f ( ... f (T (intersect ray sphLeft) sphRight) ... sphLite
   where
- f(k', sp) s' =
        let !x = intersect ray s' in if x < k' then (x, s') else (k', sp)</pre>
+ f !(T k' sp) !s' =
        let !x = intersect ray s' in if x < k' then T x s' else T k' sp</pre>
radiance :: Ray -> Int -> Erand48 Vec
radiance ray@(Ray o d) depth = case intersects ray of
- (!t,_) \mid t == 1/0.0 \rightarrow return 0
- (!t,!Sphere _r p e c refl) -> do
+ (T t_{-}) | t == 1/0.0 -> return 0
+ (T t (Sphere _r p e c refl)) -> do
     let !x = o + d .* t
         !n = norm \$ x - p
         !nl = if dot n d < 0 then n else negate n
                                                     4 D > 4 P > 4 B > 4 B > B 9 Q P
```

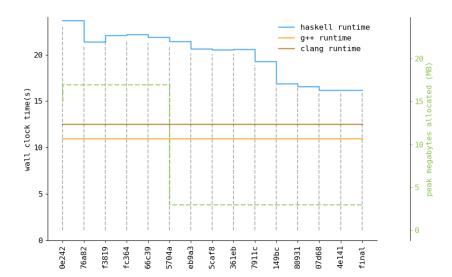
Performance: Custom datatype for intersects parameter passing $(1.46\times)$



Optimize file writing: $(1.46 \times)$

```
build-depends:
       base >= 4.12 \&\& < 4.15
+ , bytestring ^>= 0.11
-toInt :: Double -> Int
-toInt x = floor $ clamp x ** recip 2.2 * 255 + 0.5
+toInt :: Double -> BB.Builder -- O(1) concatenation
+toInt x = BB.intDec (floor (clamp x ** recip 2.2 * 255 + 0.5)) <> BB.char8 ' '
. . .
   withFile "image.ppm" WriteMode $ \hdl -> do
         hPrintf hdl "P3\n%d %d\n%d\n" w h (255::Int)
         for_ img \(Vec r g b) -> do
          hPrintf hdl "%d %d %d " (toInt r) (toInt g) (toInt b)
        BB.hPutBuilder hdl $
          BB.string8 "P3\n" <> -- efficient builders for ASCII
          BB.intDec w <> BB.char8 ' ' <> BB.intDec h <> BB.char8 '\n' <>
          BB.intDec 255 <> BB.char8 '\n' <>
           (mconcat $ fmap (\(Vec r g b) -> toInt r <> toInt g <> toInt b) img)
```

Performance: Optimize file writing $(1.46 \times)$

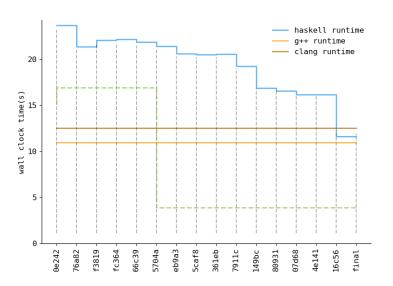


Use LLVM backend $(2.04\times)$

```
+package smallpt-opt
```

+ ghc-options: -fllvm

The view from the mountaintop $(2.04\times)$





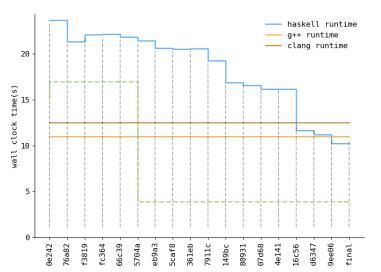
Avoid CPU ieee754 slow paths $(2.12\times)$

```
intersect :: Ray -> Sphere -> Double
 intersect (Ray o d) (Sphere r p _e _c _refl) =
   if det<0
- then 1/0.0
+ then 1e20
  else
    in if a>eps then a else if s>eps then s else 1/0.0
    in if a>eps then a else if s>eps then s else 1e20
radiance :: Ray -> Int -> Erand48 Vec
radiance ray@(Ray o d) depth = case intersects ray of
- (T t ) | t == 1/0.0 -> return 0
+ (T 1e20 ) -> return 0
   . . .
```

Fix differences with C++ version $(2.32\times)$

```
- if depth>2
+ if depth'>2 -- depth' = depth + 1
...
```

A second view from the mountaintop





Takeaways

- ▶ The unrolling in 'intersects' is ugly.
- ▶ (We feel) the maintainability of this code hasn't been significantly harmed.
- ▶ We're faster than clang++ and within 6% of g++
- ▶ Haven't exhausted the optimization opportunities.
- ▶ GHC could learn to do several of these optimizations for us.
- Others are just good Haskell style.
- Clean Haskell is often performant Haskell.
- Repository stepping through each optimization is available at ...

Raw data

▶ All test were on an otherwise idle Equinix Metal c3.small.x86 (Intel Xeon E-2278G with 32GiB RAM, Ubuntu 20.04).

0e242	23.6586	23.658	23.7251	23.6954	23.676	23.656	23.673	23.7139	23.6598	23.7641
76a82	21.3573	21.384	21.3516	21.3304	21.3658	21.3776	21.3564	21.3843	21.3401	21.3683
f3819	22.1036	22.0754	22.1034	22.0864	22.0692	22.1004	22.0584	22.1181	22.0728	22.0972
fc364	22.1211	22.114	22.1205	22.1101	23.0621	22.1101	22.1163	22.133	22.1491	22.1464
66c39	21.8626	21.8684	21.8977	21.9043	21.893	21.8483	21.8335	21.8869	21.8848	21.8335
5704a	21.4682	21.4692	21.4411	21.473	21.4783	21.4613	21.4818	21.4507	21.4388	21.4933
eb9a3	20.6134	20.6014	20.6527	20.596	20.6034	20.6174	20.5965	20.594	20.5967	20.5892
5caf8	20.5209	20.535	20.5312	20.5289	20.5338	20.5717	20.5387	20.5386	20.5262	20.5488
361eb	20.5551	20.5485	20.5602	20.552	20.5668	20.555	20.5573	20.5564	20.5599	20.5823
7911c	19.2532	19.2664	19.2955	19.2565	19.2517	19.2722	19.3284	19.2611	19.2623	19.2596
149bc	16.8551	16.8551	16.8788	16.9067	16.8683	16.8685	16.8651	16.9186	16.8589	16.8604
80931	16.5752	16.5739	16.5831	16.5918	16.5678	16.5785	16.6128	16.5682	16.5816	16.577
07d68	16.1819	16.1672	16.1829	16.2267	16.1716	16.1854	16.1806	16.1949	16.1917	16.1784
4e141	16.2206	16.1816	16.2002	16.1799	16.1813	16.1781	16.1929	16.243	16.1705	16.1877
16c56	11.6334	11.6166	11.6837	11.6504	11.6227	11.6135	11.5949	11.5966	11.6013	11.64
d6347	11.1632	11.218	11.1741	11.1802	11.1849	11.1755	11.1729	11.2155	11.1718	11.2089
9ee06	10.2131	10.2154	10.1994	10.2105	10.2028	10.2344	10.2008	10.2497	10.2226	10.3042
gcc	10.97	10.97	10.97	10.99	10.98	10.97	10.97	10.98	10.98	10.98
clang	12.53	12.51	12.5	12.53	12.51	12.5	12.52	12.48	12.53	12.52