



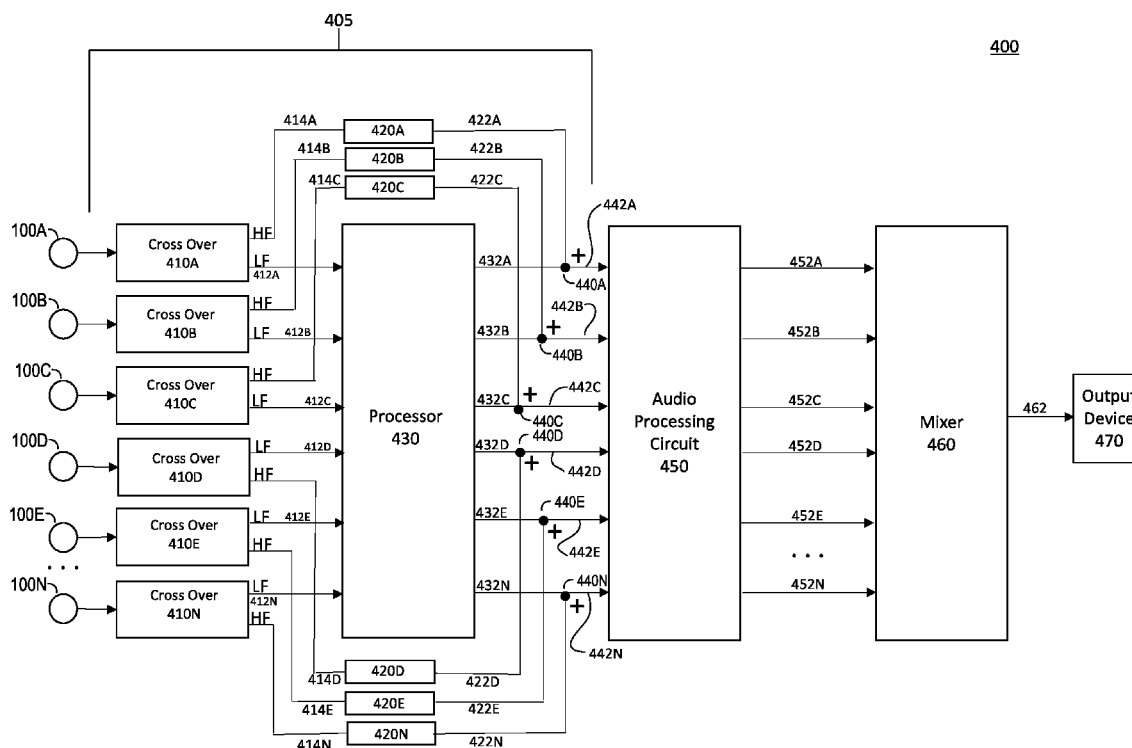
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(54) **HYBRID HORN MICROPHONE** (52) **U.S. Cl.**  
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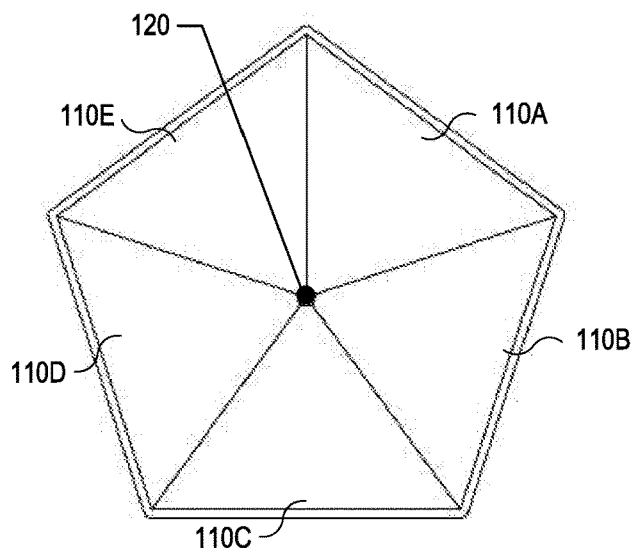
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**ABSTRACT**

The disclosed technology relates to a microphone array. The array comprises a plurality of microphones with each microphone having a horn portion. Each microphone of the array further comprises an instrument disposed at a distal end of the horn portion. Each instrument of the array is configured to convert sound waves into an electrical signal. The microphone array further comprises a beamforming signal processing circuit electrically coupled to each instrument and configured to create a plurality of beam signals based on respective electrical signals.

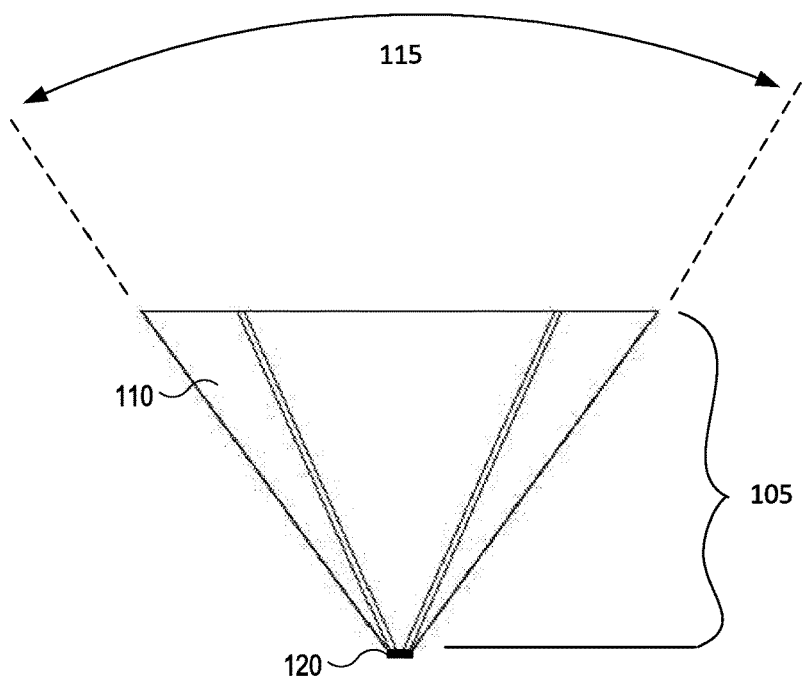


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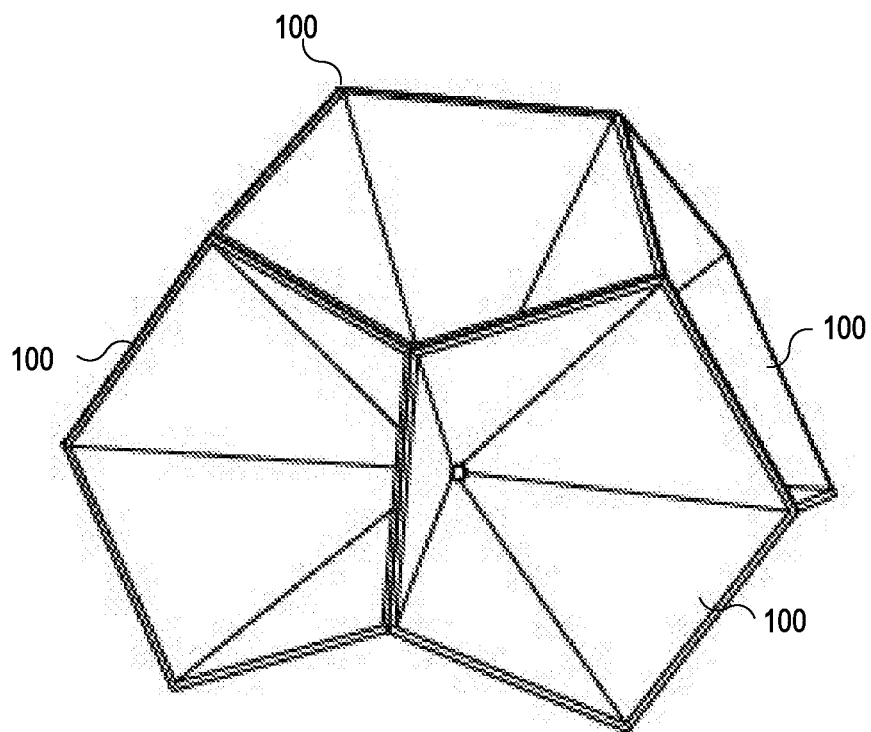
**FIG. 1**

100



**FIG. 2**

300



**FIG. 3**

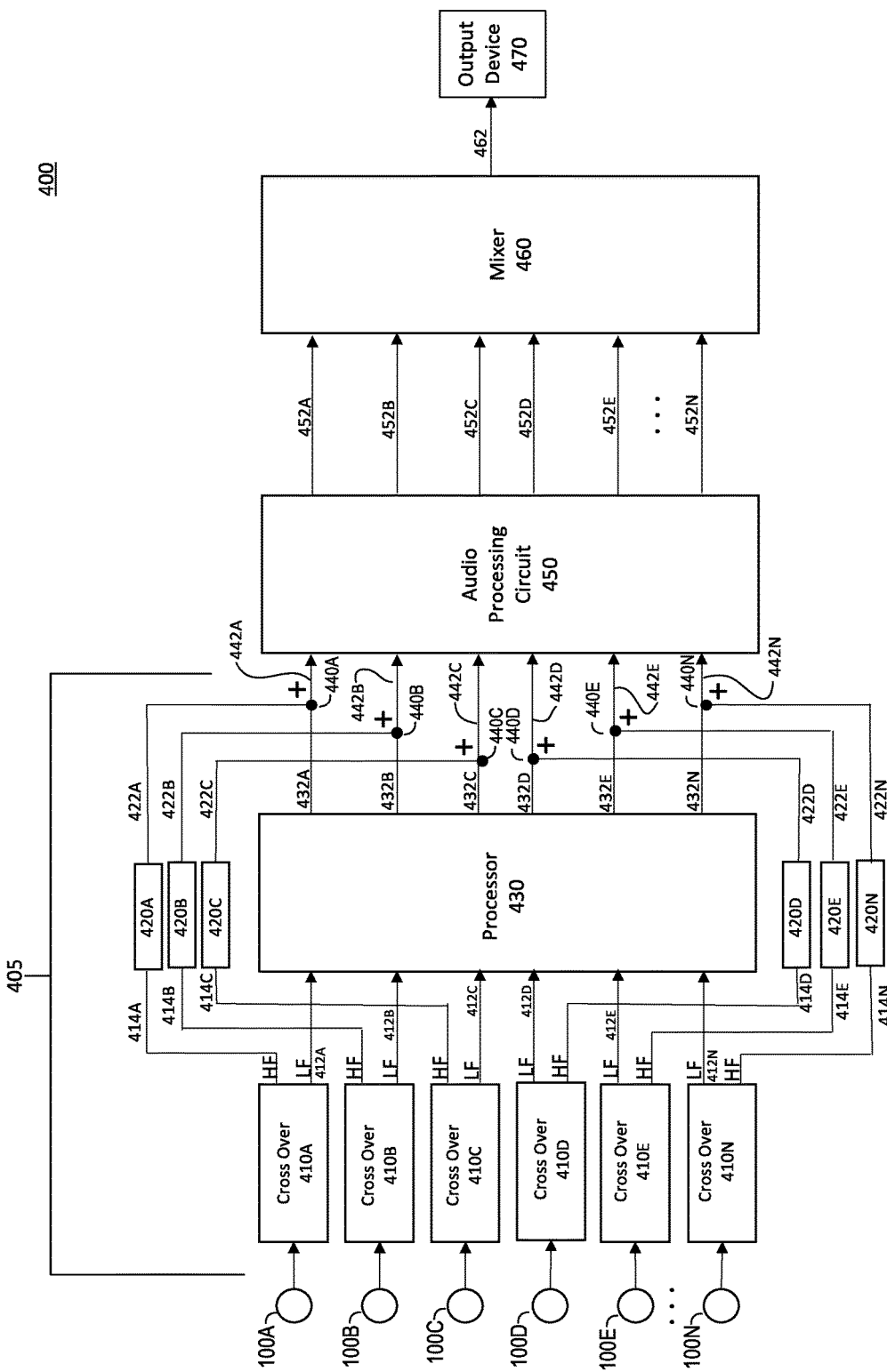
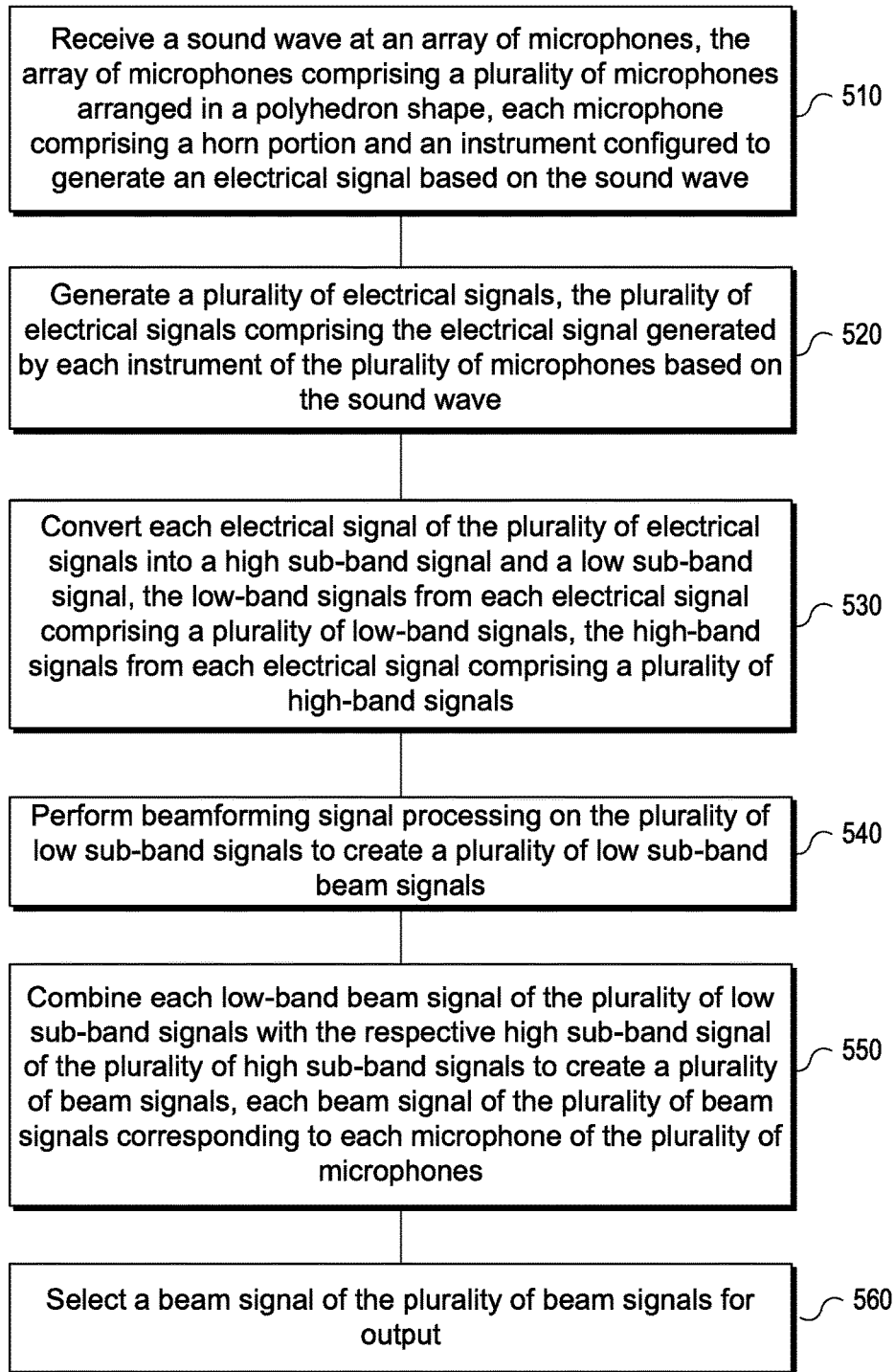


FIG. 4

500**FIG. 5**

## HYBRID HORN MICROPHONE

### TECHNICAL FIELD

**[0001]** This present disclosure relates generally to microphones, and more particularly to a horn microphone utilizing beamforming signal processing.

### BACKGROUND

**[0002]** A Microphone converts air pressure variations of a sound wave into an electrical signal. A variety of methods may be used to convert a sound wave into an electrical signal, such as use of a coil of wire with a diaphragm suspended in a magnetic field, use of a vibrating diaphragm as a capacitor plate, use of a crystal of piezoelectric material, or use of a permanently charged material. Conventional microphones may sense sound waves from all directions (e.g. omni microphone), in a 3D axis symmetric figure of eight pattern (e.g. dipole microphone), or primarily in one direction with a fairly large pickup pattern (e.g. cardioid, super cardioid and hyper cardioid microphones).

**[0003]** In audio and video conferencing applications involving multiple participants in a given location, uni-directional microphones are undesired. In addition, participants desire speech intelligibility and sound quality without requiring a multitude of microphones placed throughout a conference room. Placing a plurality of microphones in varying locations within a room requires among other things, lengthy cables, cable management, and additional hardware.

**[0004]** Further, conventional microphone arrays require sophisticated and costly hardware, significant computing performance, complex processing, and may nonetheless lack adequate sound quality when compared to use of multiple microphones placed throughout a room. Moreover, conventional microphone arrays may experience processing artifacts caused by high-frequency spatial aliasing issues.

### BRIEF DESCRIPTION OF THE DRAWINGS

**[0005]** The embodiments herein may be better understood by referring to the following description in conjunction with the accompanying drawings in which like reference numerals indicate identical or functionally similar elements. Understanding that these drawings depict only exemplary embodiments of the disclosure and are not therefore to be considered to be limiting of its scope, the principles herein are described and explained with additional specificity and detail through the use of the accompanying drawings in which:

**[0006]** FIG. 1 is a top view of a hybrid horn microphone, in accordance with various aspects of the subject technology.

**[0007]** FIG. 2 is a front view of a hybrid horn microphone, in accordance with various aspects of the subject technology.

**[0008]** FIG. 3 is a perspective view of a hybrid horn microphone array, in accordance with various aspects of the subject technology.

**[0009]** FIG. 4 depicts a hybrid horn microphone array processing block diagram, in accordance with various aspects of the subject technology.

**[0010]** FIG. 5 depicts an example method for processing signals representing sound waves, in accordance with various aspects of the subject technology.

### DESCRIPTION OF EXAMPLE EMBODIMENTS

**[0011]** The detailed description set forth below is intended as a description of various configurations of embodiments and is not intended to represent the only configurations in which the subject matter of this disclosure can be practiced. The appended drawings are incorporated herein and constitute a part of the detailed description. The detailed description includes specific details for the purpose of providing a more thorough understanding of the subject matter of this disclosure. However, it will be clear and apparent that the subject matter of this disclosure is not limited to the specific details set forth herein and may be practiced without these details. In some instances, structures and components are shown in block diagram form in order to avoid obscuring the concepts of the subject matter of this disclosure.

#### Overview

**[0012]** Conventional microphones may sense sound waves from all directions (e.g. omni microphone), in a 3D axis symmetric figure of eight pattern (e.g. dipole microphone), or primarily in one direction with a fairly large pickup pattern (e.g. cardioid, super cardioid and hyper cardioid microphones). In applications where sensing of sound from various locations may be required, an array of microphones may be positioned in a central location, such as on the middle of a table in a room. Conventional microphone arrays require sophisticated and costly hardware, significant computing performance, complex processing, and may lack adequate sound quality when compared to use of multiple microphones placed throughout a room or assigned to individual participants or users. In addition, conventional microphone arrays may have a shorter critical distance, that is, the distance in which the microphone array may adequately sense sound due to the sound pressure level of the direct sound and the reverberant sound being equal when dealing with a directional source, when compared to the hybrid horn microphone of the subject technology. Moreover, a conventional microphone array may experience processing artifacts caused by high-frequency spatial aliasing issues.

**[0013]** The disclosed technology addresses the need in the art for providing a high-sensitive and anti-aliasing microphone by combining horn technology and beamforming signal processing. In an array configuration, the hybrid horn microphone of the subject technology requires less processing power compared to conventional microphone arrays. In addition, the hybrid microphone of the subject technology has a higher signal to noise ratio and less high frequency spatial-aliasing issues than other implementations. The hybrid horn microphone array of the subject technology also has a longer critical distance and increased sound quality compared to conventional microphone arrays.

**[0014]** In addition, the hybrid horn microphone array of the subject technology does not require multiple arrays, may utilize a single output cable, and may be installed in a single location in a room, such as on or near the ceiling. There is no need for multiple microphones to be located, installed and wired throughout a room. Further, users do not need to reposition table microphones to improve sound quality as the subject technology is capable of processing audio signals to create high quality sound.

### DETAILED DESCRIPTION

**[0015]** Various aspects of the disclosure are discussed in detail below. While specific implementations are discussed,

it should be understood that this is done for illustration purposes only. A person skilled in the relevant art will recognize that other components and configurations may be used without parting from the spirit and scope of the disclosure.

**[0016]** FIG. 1 is a top view of a hybrid horn microphone 100, in accordance with various aspects of the subject technology. Microphone 100 comprises a horn portion that is formed by a plurality of planar surfaces 110A-E. The planar surfaces 110A-E are arranged in a converging orientation to form a shape having a first opening on a proximal end and a second opening on a distal end, the second opening at the distal end being smaller in area than the first opening at the proximal end.

**[0017]** The plurality of planar surfaces 110 may be substantially planar and devoid of curvature such that a cross-sectional area of the horn portion from the proximal end to the distal end decreases at a constant rate. In some aspects, the planar surfaces may include curvature such that the cross-sectional area of the horn portion from the proximal end to the distal end decreases with varying rates.

**[0018]** The plurality of planar surfaces 110 may be made of polymer, composite, metal, alloys, or a combination thereof. It is understood that other materials may be used to form the horn portion without deviating from the scope of the subject technology.

**[0019]** Each planar surface 110 of the plurality of planar surfaces 110A-E may have substantially the same thickness. The thickness of each planar surface 110 may be 0.13", 0.25", 0.38", or 0.5". It is understood that the planar surfaces 110 may have other values for thickness without departing from the scope of the subject technology.

**[0020]** In some aspects, the length of the planar surface 110 may range from 4-6 inches, 6-8 inches, 8-10 inches, 10-12 inches or 12-14 inches. It is understood that the planar surface 110 may have a longer length without departing from the scope of the subject technology. In one aspect, a width of the planar surface is similar to the length of the planar surface.

**[0021]** In one aspect, the horn portion may be formed by a single component, folded, cast, or molded into the desired shape. For example, the horn portion may comprise sheet metal folded into a pentagonal pyramid having five planar surfaces 110A-E. In another aspect, the horn portion may be assembled from multiple components with each component comprising the planar surface 110.

**[0022]** FIG. 2 is a front view of the hybrid horn microphone 100, in accordance with various aspects of the subject technology. The microphone 100 includes an instrument 120 disposed at the distal end of the horn portion 105. The distal end is located where the planar surfaces 110A-E converge to form a narrow opening. The instrument 120 is configured to detect sound waves and convert air pressure variations of a sound wave into an electrical signal. The instrument 120 may comprise an electret microphone. An electret microphone is a type of electrostatic capacitor-based microphone.

**[0023]** Sound waves emitted by a source, such as a user speaking at a telephonic or video conference, are directed or reflected towards the horn portion 105 and are directed to the instrument 120 by the shape of the planar surfaces 110A-E. In one aspect, the size and shape of the horn portion 105 correlates to a frequency range or bandwidth of the sound waves desired for detection.

**[0024]** In another aspect, by utilizing the horn portion 105, the microphone 100 detects and senses sound waves directionally. That is, the microphone 100 is capable of detecting sound waves from a source located within a detection range 115, while minimizing detection of sound waves from other sources that may be located at different locations from the source, outside of the detection range 115. By utilizing the horn portion 105, the microphone 100 is also able to prevent detection of ambient noise (typically greater than 10 dB) coming from sources located outside of the detection range. In one aspect, the horn portion 105 of the microphone 100 significantly reduces detection of sound waves coming from angles outside of the direction of the microphone 100 because the sound waves from outside the direction of the microphone 100 are reflected away from the instrument 120 by the horn portion 105. In another aspect, for sound waves coming from a source located within the detection range 115 of the microphone 100, a Signal to Noise Ratio (SNR) of the sound wave is significantly higher (generally 9 dB or more) than conventional microphones resulting in increased sound quality. In one aspect, for sound waves coming from a source within the detection range 115, the microphone 100 has a very high directivity at frequencies above 2 kHz.

**[0025]** In some aspects, the horn portion 105 may have various shapes formed by the planar surfaces 110. For example, the shape of the horn portion 105 formed by the plurality of planar surfaces 110 may comprise a triangular pyramid having three interior faces. In another example, the shape of the horn portion 105 formed by the plurality of planar surfaces 110 may comprise a square pyramid having four interior faces. In yet another example, the shape of the horn portion 105 formed by the plurality of planar surfaces 110 may comprise a pentagonal pyramid having five interior faces. In another example, the shape of the horn portion 105 formed by the plurality of planar surfaces 110 may comprise a hexagonal pyramid having six interior faces. In yet another example, the shape of the horn portion 105 formed by the plurality of planar surfaces 110 may comprise a heptagonal pyramid having seven interior faces. In another example, the shape of the horn portion 105 formed by the plurality of planar surfaces 110 may comprise an octagonal pyramid having eight interior faces. It is further understood that other shapes may be formed by the plurality of planar surfaces 110 as desired by a person of ordinary skill in the art.

**[0026]** FIG. 3 is a perspective view of a hybrid horn microphone array 300, in accordance with various aspects of the subject technology. In some aspects, the horn microphone 100 may be arranged in an array 300 to receive sound waves from one or more sources located within an area, such as a conference room. For example, the array 300 of microphones 100 may be arranged to form a polyhedron shape, such as a full dodecahedron that may be formed by arranging twelve microphones 100 into a full sphere dodecahedron arrangement. In another example, the polyhedron shape may comprise a half dodecahedron that may be formed by arranging six microphones 100 into a half dodecahedron arrangement (as shown in FIG. 3). In yet another example, the polyhedron shape may comprise a quarter dodecahedron formed by arranging three microphones 100 into a quarter dodecahedron arrangement. It is understood that the array 300 may comprise other shapes and may be formed of a multitude of microphones 100, including up to 120 microphones 100. In one aspect, the

higher the number of microphones 100 comprising the array, the narrower the detection of sound waves from the source.

[0027] Each microphone 100 of the array 300 is pointed at a different direction, as shown in FIG. 3. In some aspects, by forming the array 300 with the plurality of microphones 100 arranged so that each microphone 100 is pointed at a different direction, each microphone 100 is configured to detect sound waves from the direction the microphone is pointed.

[0028] FIG. 4 depicts a hybrid horn microphone array processing block diagram 400, in accordance with various aspects of the subject technology. The microphone array 300 (shown in FIG. 3) may further comprise the hybrid horn microphone array processing block diagram 400 to process the electrical signals generated by the instrument 120 (shown in FIGS. 1 and 2) of each microphone 100. In one aspect, the functions and operations depicted in the hybrid horn microphone array processing block diagram 400 may be performed by components mounted to the array 300, components located at a remote location, or at an output device as discussed further below.

[0029] The hybrid horn microphone array processing block diagram 400 comprises a beamforming signal processing circuit 405 for creating a high-sensitivity and anti-aliasing microphone array 300. The beamforming signal processing circuit 405 is electrically coupled to each microphone 100 and is configured to receive the electrical signals from each instrument 120. The beamforming signal processing circuit 405 is further configured to create beam signals corresponding to each microphone 100 based on the respective electrical signals. In some aspects, the beam signals are indicative of a location of a source of the sound waves detected by each microphone 100.

[0030] The beamforming signal processing circuit 405 comprises a crossover filter 410, a delaying circuit 420, a processor 430, and a mixer 440. Each electrical signal from the microphones 100A-N passes through respective cross over filters 410A-N. Each crossover filter 410A-N is configured to convert the respective electrical signals from the microphone 100A-N to a first signal 412 and a second signal 414, with the first and second signals, 412 and 414 respectively, having different frequencies or sub-bands. For example, the frequency of each respective first signal 412 may be below 2 kHz and the frequency of each respective second signal 414 may be above 2 kHz. In one aspect, the crossover frequency can be adapted to the size of the horn portion 105 (as shown in FIG. 2) of the microphone 100 in the array 300.

[0031] For example, with reference to a first microphone 100A, the electrical signal from the microphone 100A is received by the cross over filter 410A. The cross over filter 410A converts the electrical signal from the microphone 100A into a first signal 412A (Low Frequency or LF) and a second signal 414A (High Frequency or HF). With reference to a second microphone 100B, the electrical signal from the microphone 100B is received by the cross over filter 410B. The cross over filter 410B converts the electrical signal from the microphone 100B into a first signal 412B (Low Frequency or LF) and a second signal 414B (High Frequency or HF). With reference to a third microphone 100C, the electrical signal from the microphone 100C is received by the cross over filter 410C. The cross over filter 410C converts the electrical signal from the microphone 100C into a first signal 412C (Low Frequency or LF) and a second signal

414C (High Frequency or HF). With reference to a fourth microphone 100D, the electrical signal from the microphone 100D is received by the cross over filter 410D. The cross over filter 410D converts the electrical signal from the microphone 100D into a first signal 412D (Low Frequency or LF) and a second signal 414D (High Frequency or HF). With reference to a fifth microphone 100E, the electrical signal from the microphone 100E is received by the cross over filter 410E. The cross over filter 410E converts the electrical signal from the microphone 100E into a first signal 412E (Low Frequency or LF) and a second signal 414E (High Frequency or HF). In some aspects, any number of microphones 100N may be connected to the beamforming signal processing circuit 405, including the cross over filter 410N to convert the electrical signal from the microphone 100N into a first signal 412N and a second signal 414N, without departing from the scope of the subject technology.

[0032] The delaying circuit 420 is configured to delay the second signal 414 from the crossover filter 410 to create a delayed second signal 422. In some aspects, the delaying circuit is configured to sufficiently delay the second signal 414 so that upon mixing by the mixer 440, as discussed further below, the mixed signal is sufficiently aligned. Each second signal 414A-N from the respective cross over filters 410A-N is received by corresponding delaying circuits 420A-N to create respective delayed second signals 422A-N.

[0033] For example, with reference to the first microphone 100A, the second signal 414A from the cross over filter 410A is received by the delaying circuit 420A. The delaying circuit 420A delays the second signal 414A to create a delayed second signal 422A. With reference to the second microphone 100B, the second signal 414B from the cross over filter 410B is received by the delaying circuit 420B. The delaying circuit 420B delays the second signal 414B to create a delayed second signal 422B. With reference to the third microphone 100C, the second signal 414C from the cross over filter 410C is received by the delaying circuit 420C. The delaying circuit 420C delays the second signal 414C to create a delayed second signal 422C. With reference to the fourth microphone 100D, the second signal 414D from the cross over filter 410D is received by the delaying circuit 420D. The delaying circuit 420D delays the second signal 414D to create a delayed second signal 422D. With reference to the fifth microphone 100E, the second signal 414E from the cross over filter 410E is received by the delaying circuit 420E. The delaying circuit 420E delays the second signal 414E to create a delayed second signal 422E. In some aspects, any number of microphones 100N may be connected to the beamforming signal processing circuit 405, including the delaying circuit 420N to delay the second signal 414N and create a delayed second signal 422N, without departing from the scope of the subject technology.

[0034] The processor 430 may be configured to down-sample the first signal 412 from the crossover filter 410 to create a downsampled first signal, process the downsampled first signal to create a processed first signal that is indicative of the location of the source of the sound waves detected by the microphone 100, and upsample the processed first signal to create an upsampled first signal 432. Each first signal 412A-N from the respective cross over filters 410A-N is received by the processor 430 to create the processed first signal 432A-N.



[0035] In some aspects, the processor 430 utilizes beam-forming signal processing techniques to process the first signals 412A-N. Beam forming signal processing may be used to extract sound sources in an area or room. This may be achieved by combining elements in a phased array in such a way that signals at particular angles experience constructive interference while others experience destructive interference.

[0036] In one aspect, because the horn portion 105 (as shown in FIG. 2) of the microphone 100 significantly reduces detection of sound waves coming from angles outside of the direction of the microphone 100, provides a high SNR for sound waves coming from a source located within the detection range 115 (as shown in FIG. 2), and provides a very high directivity at frequencies above 2 kHz; no processing is required by the processor 430 for the second signals 414A-N. In one aspect, because no processing is required for the second signals 414A-N, spatial aliasing issues are avoided.

[0037] The processor 430 may downsample each of the first signals 412A-N to a lower sampling rate such as from 48 kHz to 4 kHz, which may significantly reduce computational complexity by 90%. The processor 430 may then filter and sum (or weight and sum in the frequency domain) each of the first signals 412A-N to create respective processed first signals representing acoustic beams pointing in the direction of each respective microphone. In another example, the processor 430 may use spherical harmonics theory or sound field models to create respective processed first signals representing acoustic beams pointing in the direction of each respective microphone. In one aspect, the processor 430 may measure the array response vectors for various sound arrival angles in an anechoic chamber. In another aspect, the processor 430 may implement various types of beam pattern synthesis/optimization or machine learning. The processor 430 may then upsample the processed first signals to obtain respective upsampled first signals 432 with a desired sampling rate.

[0038] For example, with reference to the first microphone 100A, the first signal 412A from the cross over filter 410A is received by the processor 430. The processor 430 may downsample the first signal 412A to create a first downsampled first signal. The processor 430 may then filter and sum (or weight and sum in the frequency domain) the first downsampled first signal to create a first processed first signal representing an acoustic beam pointing in the direction of microphone 100A. The first processed first signal indicative of the location of the source of the sound waves detected by the microphone 100A. The processor 430 may then upsample the first processed first signal to obtain an upsampled first signal 432A. With respect to the second microphone 100B, the first signal 412B from the cross over filter 410B is received by the processor 430. The processor 430 may downsample the first signal 412B to create a second downsampled first signal. The processor 430 may then filter and sum (or weight and sum in the frequency domain) the second downsampled first signal to create a second processed first signal representing an acoustic beam pointing in the direction of microphone 100B. The second processed first signal indicative of the location of the source of the sound waves detected by the microphone 100B. The processor 430 may then upsample the second processed first signal to obtain an upsampled first signal 432B. With respect to the third microphone 100C, the first signal 412C from the

cross over filter 410C is received by the processor 430. The processor 430 may downsample the first signal 412C to create a third downsampled first signal. The processor 430 may then filter and sum (or weight and sum in the frequency domain) the third downsampled first signal to create a third processed first signal representing an acoustic beam pointing in the direction of microphone 100C. The third processed first signal indicative of the location of the source of the sound waves detected by the microphone 100C. The processor 430 may then upsample the third processed first signal to obtain an upsampled first signal 432C. With respect to the fourth microphone 100D, the first signal 412D from the cross over filter 410D is received by the processor 430. The processor 430 may downsample the first signal 412D to create a fourth downsampled first signal. The processor 430 may then filter and sum (or weight and sum in the frequency domain) the fourth downsampled first signal to create a fourth processed first signal representing an acoustic beam pointing in the direction of microphone 100D. The fourth processed first signal indicative of the location of the source of the sound waves detected by the microphone 100D. The processor 430 may then upsample the fourth processed first signal to obtain an upsampled first signal 432D. With respect to the fifth microphone 100E, the first signal 412E from the cross over filter 410E is received by the processor 430. The processor 430 may downsample the first signal 412E to create a fifth downsampled first signal. The processor 430 may then filter and sum (or weight and sum in the frequency domain) the fifth downsampled first signal to create a fifth processed first signal representing an acoustic beam pointing in the direction of microphone 100E. The fifth processed first signal indicative of the location of the source of the sound waves detected by the microphone 100E. The processor 430 may then upsample the fifth processed first signal to obtain an upsampled first signal 432E. In some aspects, any number of microphones 100N may be connected to the beamforming signal processing circuit 405, including the processor 430 to downsample, process and upsample the first signal 412N and create an upsampled first signal 432N, without departing from the scope of the subject technology.

[0039] The mixer 440 is configured to combine the upsampled first signal 432 from the processor 430 and the delayed second signal 422 from the delaying circuit 420 to create a full-band beam signal 442. Each upsampled first signal 432A-N and delayed second signal 422A-N from the respective delaying circuits 420A-N is received by corresponding mixers 440A-N to create respective full-band beam signals 442A-N.

[0040] For example, with reference to the first microphone 100A, the upsampled first signal 432A from the processor 430 and the delayed second signal 422A from the delaying circuit 420A is received by the mixer 440A. The mixer 440A combines the upsampled first signal 432A and the delayed second signal 422A to create a beam signal 442A. With reference to the second microphone 100B, the upsampled first signal 432B from the processor 430 and the delayed second signal 422B from the delaying circuit 420B is received by the mixer 440B. The mixer 440B combines the upsampled first signal 432B and the delayed second signal 422B to create a beam signal 442B. With reference to the third microphone 100C, the upsampled first signal 432C from the processor 430 and the delayed second signal 422C from the delaying circuit 420C is received by the mixer 440C. The mixer 440C combines the upsampled first signal

**432C** and the delayed second signal **422C** to create a beam signal **442C**. With reference to the fourth microphone **100D**, the upsampled first signal **432D** from the processor **430** and the delayed second signal **422D** from the delaying circuit **420D** is received by the mixer **440D**. The mixer **440D** combines the upsampled first signal **432D** and the delayed second signal **422D** to create a beam signal **442D**. With reference to the second microphone **100E**, the upsampled first signal **432E** from the processor **430** and the delayed second signal **422E** from the delaying circuit **420E** is received by the mixer **440E**. The mixer **440E** combines the upsampled first signal **432E** and the delayed second signal **422E** to create a beam signal **442E**. In some aspects, any number of microphones **100N** may be connected to the beamforming signal processing circuit **405**, including the mixer **440N** to combine the upsampled first signal **432N** and delayed second signal **422N** to create the beam signal **442N**, without departing from the scope of the subject technology.

**[0041]** The hybrid horn microphone array processing block diagram **400** may further comprise an audio processing circuit **450**. The audio processing circuit **450** may be configured to receive each of the beam signals **442A-N** and perform at least one of an echo control filter, a reverberation filter, or a noise reduction filter, to improve the quality of the beam signals **442A-N** and create pre-mixed beam signals **452A-N**.

**[0042]** For example, with reference to the first microphone **100A**, the beam signal **442A** from the mixer **440A** is received by the audio processing circuit **450**. The audio processing circuit **450** performs operations such as echo modification, reverberation adjustment, or noise reduction, to improve the quality of the beam signal **442A**, and thereby create a pre-mixed beam signal **452A**. With reference to the second microphone **100B**, the beam signal **442B** from the mixer **440B** is received by the audio processing circuit **450**. The audio processing circuit **450** performs operations such as echo modification, reverberation adjustment, or noise reduction, to improve the quality of the beam signal **442B**, and thereby create a pre-mixed beam signal **452B**. With reference to the third microphone **100C**, the beam signal **442C** from the mixer **440C** is received by the audio processing circuit **450**. The audio processing circuit **450** performs operations such as echo modification, reverberation adjustment, or noise reduction, to improve the quality of the beam signal **442C**, and thereby create a pre-mixed beam signal **452C**. With reference to the fourth microphone **100D**, the beam signal **442D** from the mixer **440D** is received by the audio processing circuit **450**. The audio processing circuit **450** performs operations such as echo modification, reverberation adjustment, or noise reduction, to improve the quality of the beam signal **442D**, and thereby create a pre-mixed beam signal **452D**. With reference to the fifth microphone **100E**, the beam signal **442E** from the mixer **440E** is received by the audio processing circuit **450**. The audio processing circuit **450** performs operations such as echo modification, reverberation adjustment, or noise reduction, to improve the quality of the beam signal **442E**, and thereby create a pre-mixed beam signal **452E**. In some aspects, any number of microphones **100N** may be connected to the audio processing circuit **450** to improve the quality of the beam signal **442N** and create pre-mixed beam signal **452N**, without departing from the scope of the subject technology.

**[0043]** The hybrid horn microphone array processing block diagram **400** may further comprise an automatic mixer **460**. The automatic mixer **460** may be configured to receive the plurality of pre-mixed beam signals **452A-N** and identify one or more beam signals from the plurality of beam signals **452A-N** to output to an output device **470** based on a characteristic of the beam signal **452A-N**. The characteristic of the beam signal **452A-N** may include, for example, quality, level, clarity, strength, SNR, signal to reverberation ratio, amplitude, wavelength, frequency, or phase. In some aspects, the mixer **460** may be configured to review each incoming pre-mix beam signal **452A-N**, identify one or more beam signals **452A-N** based on one or more characteristic of the beam signals **452A-N**, select the one or more beam signals **452A-N**, isolate signals representing speech, filter low signals that may not represent speech, and transmit an output signal **462** to the output device **470**. In one aspect, the mixer **460** may utilize audio selection techniques to generate the desired audio output signal **462** (e.g., mono, stereo, surround).

**[0044]** The output device **470** is configured to receive the output signal **462** from the mixer and may comprise a set top box, console, visual output device (e.g., monitor, television, display), or audio output device (e.g., speaker).

**[0045]** FIG. 5 depicts an example method **500** for processing signals representing sound waves, in accordance with various aspects of the subject technology. It should be understood that, for any process discussed herein, there can be additional, fewer, or alternative steps performed in similar or alternative orders, or in parallel, within the scope of the various embodiments unless otherwise stated.

**[0046]** At operation **510**, a sound wave is received at an array of microphones. The array of microphones comprise a plurality of microphones arranged in a polyhedron shape, as shown for example, in FIG. 3. Each microphone may comprise a horn portion and an instrument, the instrument configured to generate an electrical signal based on the sound wave. The horn portion may comprise a plurality of planar surfaces that are arranged to form the polyhedron shape.

**[0047]** At operation **520**, a plurality of electrical signals are generated based on the received sound wave. The plurality of electrical signals comprise the electrical signal generated by each instrument of the plurality of microphones.

**[0048]** At operation **530**, each electrical signal of the plurality of electrical signals is converted into a high sub-band signal and a low sub-band signal. The electrical signal generated by each instrument and microphone, is thus converted to two signals, the high sub-band signal and the low sub-band signal. Each of the low-band signals, together, comprise a plurality of low-band signals. Similarly, each of the high-band signals, together, comprise a plurality of high-band signals.

**[0049]** At operation **540**, beamforming signal processing is performed on the plurality of low sub-band signals to create a plurality of low sub-band beam signals. Stated differently, each of the low-band signals undergoes beamforming signal processing to thereby create a low sub-band beam signal. As described above, beamforming signal processing may comprise use of spherical harmonics theory or sound field models, use of array response vectors for various

sound arrival angles in an anechoic chamber, and/or use of various types of beam pattern synthesis/optimization or machine learning.

**[0050]** At operation **550**, each low-band beam signal of the plurality of low sub-band signals is combined with the respective high sub-band signal of the plurality of high sub-band signals to create a plurality of beam signals. Each beam signal of the plurality of beam signals corresponds to each microphone of the plurality of microphones of the array.

**[0051]** At operation **560**, one or more beam signals of the plurality of beam signals is elected for output to an output device.

**[0052]** The functions described above can be implemented using computer-executable instructions that are stored or otherwise available from computer readable media. Such instructions can comprise, for example, instructions and data which cause or otherwise configure a general purpose computer, special purpose computer, or special purpose processing device to perform a certain function or group of functions. The computer executable instructions may be, for example, binaries, intermediate format instructions such as assembly language, firmware, or source code. Examples of computer-readable media that may be used to store instructions, information used, and/or information created during methods according to described examples include magnetic or optical disks, flash memory, USB devices provided with non-volatile memory, networked storage devices, and so on.

**[0053]** Devices implementing the functions and operations according to these disclosures may comprise hardware, firmware and/or software, and can take any of a variety of form factors. Typical examples of such form factors include laptops, smart phones, small form factor personal computers, personal digital assistants, rackmount devices, stand-alone devices, and so on. Functionality described herein also can be embodied in peripherals or add-in cards. Such functionality can also be implemented on a circuit board among different chips or different processes executing in a single device, by way of further example.

**[0054]** The instructions, media for conveying such instructions, computing resources for executing them, and other structures for supporting such computing resources are means for providing the functions described in these disclosures.

**[0055]** Although a variety of examples and other information was used to explain aspects within the scope of the appended claims, no limitation of the claims should be implied based on particular features or arrangements in such examples, as one of ordinary skill would be able to use these examples to derive a wide variety of implementations. Further and although some subject matter may have been described in language specific to examples of structural features and/or method steps, it is to be understood that the subject matter defined in the appended claims is not necessarily limited to these described features or acts. For example, such functionality can be distributed differently or performed in components other than those identified herein. Rather, the described features and steps are disclosed as examples of components of systems and methods within the scope of the appended claims.

1. A system for converting sound waves, the system comprising:

an array of microphones, the array comprising a plurality of microphones, each microphone of the plurality of microphones comprising:

a horn portion comprising a plurality of surfaces, the surfaces arranged in a converging orientation to form a shape having a first opening at a proximal end and a second opening at a distal end, the second opening at the distal end being smaller in area than the first opening at the proximal end; and

an instrument disposed at the distal end of the horn portion, the instrument configured to convert sound waves into an electrical signal;

the microphones of the array are radially disposed around a central point and oriented to direct received sound waves to that central point; and

a beamforming signal processing circuit electrically coupled to each instrument of the plurality of microphones and configured to create a plurality of beam signals based on the respective electrical signals of each instrument.

2. The system of claim 1, wherein the beamforming signal processing circuit comprises a crossover filter, a processor, a delaying circuit, and a mixer.

3. The system of claim 2, wherein the crossover filter is configured to convert the electrical signal from each instrument of the plurality of microphones to respective first signals and second signals.

4. The system of claim 3, wherein the processor is configured to:

downsample each of the first signals from the crossover filter to create respective downsampled first signals;

process each of the downsampled first signals to create respective processed first signals, the processed first signals indicative of a location of the source of the sound waves detected by the respective instrument; and

upsample each of the processed first signals to create respective upsampled first signals.

5. The system of claim 4, wherein the delaying circuit is configured to delay each of the second signals from the crossover filter to create respective delayed second signals.

6. The system of claim 5, wherein the mixer is configured to combine each of the upsampled first signals from the processor with corresponding delayed second signals from the delaying circuit to create the plurality of beam signals.

7. The system of claim 1, further comprising an audio processing circuit, the audio processing circuit configured to perform at least one of an echo control filter, a reverberation filter, or a noise reduction filter, to the plurality of beam signals from the beamforming signal processing circuit.

8. The system of claim 1, wherein the shape of the horn portion formed by the plurality of surfaces comprises a square pyramid having four interior faces.

9. The system of claim 1, wherein the shape of the horn portion formed by the plurality of surfaces comprises a pentagonal pyramid having five interior faces.

10. The system of claim 1, wherein the shape of the horn portion formed by the plurality of surfaces comprises a hexagonal pyramid having six interior faces.

11. The system of claim 1, wherein each beam signal of the plurality of beam signals is indicative of a location of a source of the sound waves detected by each respective instrument.

- 12.** A microphone array comprising:  
 a plurality of microphones arranged to form an array, the microphones of the array being radially disposed around a central point and oriented to direct received sound waves to that central point, each microphone of the plurality of microphones comprising:  
 a horn portion comprising a plurality of planar surfaces, the planar surfaces arranged in a converging orientation to form a shape having a first opening on a proximal end and a second opening on a distal end, the second opening on the distal end being smaller in area than the first opening on the proximal end; and  
 an instrument disposed on the distal end of the horn portion, the instrument configured to detect sound waves and convert sound waves into an electrical signal;  
 a beamforming signal processing circuit electrically coupled to each instrument of plurality of microphones, the beamforming signal processing circuit configured to:  
 receive a plurality of electrical signals, the plurality of electrical signals comprising the electrical signal from each microphone of the plurality of microphones; and  
 create a plurality of beam signals based on the plurality of electric signals each beam signal of the plurality of beam signals corresponding to the electrical signal from each microphone of the plurality of microphones.
- 13.** The microphone array of claim **12**, wherein the beamforming signal processing circuit comprises a cross-over filter, a processor, a delaying circuit, and a mixer.
- 14.** The microphone array of claim **12**, further comprising an audio processing circuit, the audio processing circuit configured to perform at least one of an echo control filter, a reverberation filter, or a noise reduction filter, to the plurality of beam signals from the beamforming signal processing circuit.
- 15.** The microphone array of claim **12**, further comprising an automatic mixer, the automatic mixer configured to receive the plurality of beam signals and identify a beam signal from the plurality of beam signals based on a characteristic of the beam signal.
- 16.** The microphone array of claim **12**, wherein the shape of the horn portion of each microphone of the plurality of microphones comprises a pentagonal pyramid having five interior faces.
- 17.** The microphone array of claim **12**, wherein the array comprises a polyhedron shape.
- 18.** The microphone array of claim **17**, wherein the polyhedron shape comprises a half dodecahedron.
- 19.** The microphone array of claim **12**, wherein each beam signal is indicative of a location of a source of the sound waves detected by each microphone of the plurality of microphones.
- 20.** A method for creating a plurality of beam signals, the method comprising:  
 receiving a sound wave at an array of microphones, the array of microphones comprising a plurality of microphones radially disposed around a central point and oriented to direct received sound waves to that central point; each microphone comprising a horn portion and an instrument, the instrument configured to generate an electrical signal based on the sound wave;  
 generating a plurality of electrical signals based on the received sound wave, the plurality of electrical signals comprising the electrical signal generated by each instrument of the plurality of microphones;  
 converting each electrical signal of the plurality of electrical signals into a high sub-band signal and a low sub-band signal, the low sub-band signals from each electrical signal comprising a plurality of low sub-band signals, the high sub-band signals from each electrical signal comprising a plurality of high sub-band signals;  
 performing beamforming signal processing on the plurality of low sub-band signals to create a plurality of low sub-band beam signals;  
 combining each low-band beam signal of the plurality of low sub-band signals with the respective high sub-band signal of the plurality of high sub-band signals to create a plurality of beam signals, each beam signal of the plurality of beam signals corresponding to each microphone of the plurality of microphones of the array; and  
 selecting an output beam signal from the plurality of beam signals for output to an output device.
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