

Performance Metrics github

How messages are formed

- all info ~~can~~ is passed through abstraction (Ros-bags collect these messages)
- 15 megs for 82 min of small robot
- Need to truncate data [8 gigs]

LRB compliance
Flash key

Main keys

LRB → currently written
Organizing ROS bags
Documentation

Multiple threads at a time

Metrics

LRB

- Removable Identity
- Easy to use
 - Auto population
 - Easy to pull out
 - Look good (GitHub)
 - Python preferred
- Web page okay → good even
- Easy to train

ROS bags

- Organized logically
- See all data & roll

Documentation

- Hardware & Software

github

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- Everything that is not commotial & \$
- ~~all~~ Matterhuman (no punctuation or caps)