

It's a process & a signpost

graf → Find a time to work as
a team

ROS bag accumulation of
sensor data

Replay sensor data validate data

Storing ROS bags & replay

POM-DP

Rviz → Encoders on wheels & Lidar
Point cloud

System setup & interface know

• Access to chairs

not

How to collect data & anonymize
data (unique ~~ideas~~ idea)

This site has example of documentation
Useful on getting things documented

1-5 Tuesday

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