Classification & Regression Trees

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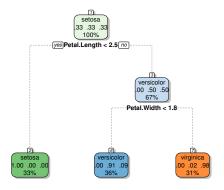
Introduction

- Today, we will take a first look at classification and regression trees.
- The definitive source for material pertaining to classification trees is probably (still) the famous text by Breiman et al. (1984).^a
- Conceptually, classification trees are quite simple.
- However, there are some subtleties.

^aBreiman L., Friedman J.H., Olshen R.A. and Stone, C.J. (1984). *Classification and Regression Trees.* Chapman & Hall/CRC.

Iris Data: Classification Tree

Classification Tree for Iris Data



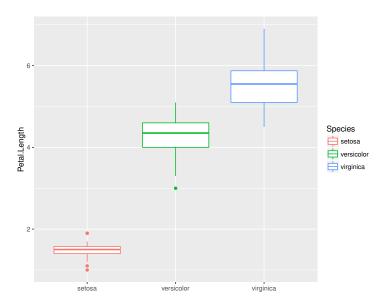
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Iris Data: Box Plot



A Classification Tree

- Starts at the top (root) and recursively partitions data based on the best splitter.
- As we saw with the iris tree, a splitter is a variable (together with a rule).
- What it means to be the "best" splitter will be discussed, inter alia, shortly.
- I think that going in-depth on pruning is not as helpful but you can consult Hastie et al. (2009).^a
- A classification tree is also called a decision tree.
 - ^aHastie, T., Tibshirani, R. and Friedman, J. (2009). *The Elements of Statistical Learning*. Second Edition. Springer: New York.

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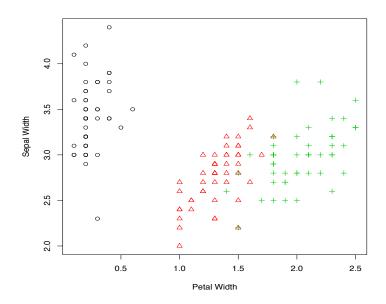
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Splitting: Notation

- Consider the notation of Hastie et al. (2009) so that a node m represents a region R_m with N_m observations.
- When one considers the relationship between a tree and the space of observations, this is natural.
- Before proceeding, consider a tree built using two variables from the iris data — two variables so that we can visualize the partitioning of the space of observations.

Iris: Sepal Width and Petal Width

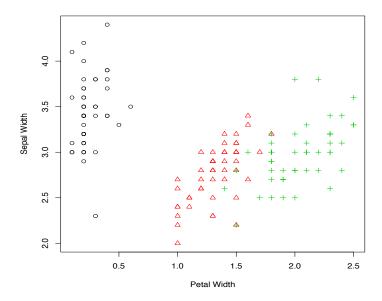


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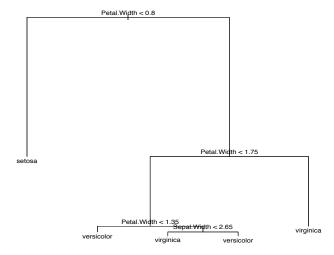
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Iris: Sepal Width and Petal Width



Iris: Sepal Width and Petal Width



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Returning to Notation

- ullet Recall that a node m represents a region R_m with N_m observations.
- Again, remaining with the notation of Hastie et al. (2009), the proportion of observations from class g in node m is

$$\hat{p}_{mg} = \frac{1}{N_m} \sum_{\mathbf{x}_i \in R_m} \mathbb{I}(y_i = g).$$

- All observations in node m are classified into the class with the largest proportion of observations; in other words, the majority class; or, in mathematical language, class $g^* = \arg\max_k \hat{p}_{mq}$.
- This is all just a formalization of what we discussed when we looked at the tree.

Growing the Tree

- We need to decide how to come up with splits (or splitters).
- We could think about the misclassification error, i.e.,

$$1 - \hat{p}_{mq^*}$$
.

• Or the Gini index, i.e.,

$$\sum_{g=1}^{G} \hat{p}_{mg} (1 - \hat{p}_{mg}).$$

• Or the information (also called deviance or cross-entropy), i.e.,

$$-\sum_{g=1}^{G} \hat{p}_{mg} \log \hat{p}_{mg}.$$

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Growing the Tree contd.

- Note that when used in this way, misclassification error, Gini index, and information are referred to as impurity measures.
- In this vernacular, we want nodes that are pure (or as pure as possible).
- The classification rate is generally not the impurity measure of choice.
- We can think a little about why.
- The Gini index has appealing interpretations.

Regression Trees

- Now, we will look at regression trees.
- They proceed in an analogous fashion to classification trees.
- However, we now have a regression problem as opposed to a classification problem, i.e., we want to predict Y based on X_1, \ldots, X_p .
- Following James et al. (2013), let's start with an example on Major League Baseball (MLB) data.

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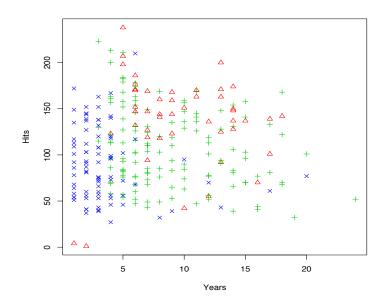
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The Hitters Data

- MLB data from the 1986 and 1987 seasons.
- Suppose we are interested in predicting Salary based on Hits and Years.
- After looking at the data, it seems clear that logSalary is a better option.
- Here is a scatter plot, coloured by logSalary, of Years versus Hits.

Hitters: Hits and Years

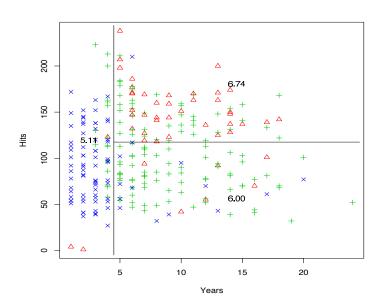


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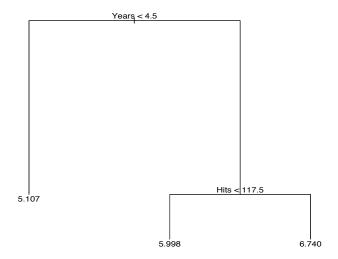
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Hitters: Hits and Years



Hitters: Hits and Years



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Interpretation

- Like before, we have a partitioning of the data into regions.
- But how do we interpret the number associated with each region?
- Having seen this example and we will return to it later we will now see how the tree is grown.
- As with classification trees, we need a splitter at each step.

Growing the Tree

• Borrowing the notation of James et al. (2013), we need to choose a value s and a variable X_j to split data into the regions

$$R_1(j,s) = \{ \mathbf{X} \mid X_j < s \} \text{ and } R_2(j,s) = \{ \mathbf{X} \mid X_j \ge s \}.$$

This choice (i.e., the choice of j and s) is made to minimize

$$\sum_{i:\mathbf{x}_i \in R_1(j,s)} (y_i - \hat{y}_{R_1})^2 + \sum_{i:\mathbf{x}_i \in R_2(j,s)} (y_i - \hat{y}_{R_2})^2,$$

where \hat{y}_{R_k} is the mean of (training) observations in R_k , for k=1,2.

• Further splits continue in this fashion.

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Comments

- Trees have lots of advantages.
- For one, they are very easy to understand.
- They mimic decision processes, e.g., of a physician perhaps.
- They are very easy (natural, even) to visualize.
- But they are not as good as some other methods.

Comments cont.

- Ensembles of trees, however, can lead to markedly improved performance.
- I want to do boosting, bagging, and random forests next.
- But I think some of you probably do not know what the bootstrap is.
- So we are going to spend some time learning about the bootstrap.
- Then, in the next class, we will move on to boosting, bagging, and random forests.
- Now, some more examples in R.

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